

K-ENERGY MAPS INTEGRATING FUTAKI INVARIANTS

Dedicated to the memory of the Professor Takehiko Miyata

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0. Introduction. One of the long-standing questions in complex differential geometry is the following: given a compact complex connected manifold V with $c_1(V) > 0$, can one find a simple criterion for the existence of an Einstein Kähler metric on V ? At present, there are no definitive answers, but in view of the partial results recently obtained by Sakane and Koiso, the following conjecture of Futaki [3] seems to be reasonable.

(I) **GENERALIZED CALABI'S CONJECTURE (FUTAKI).** *Suppose that the identity component $\text{Aut}^0(V)$ of the group of holomorphic automorphisms of V is a reductive algebraic group. If the Futaki invariant vanishes for each holomorphic vector field on V , then V admits an Einstein Kähler metric.*

On the other hand, as a characterization of Einstein Hermitian vector bundles on compact Kähler manifolds, S. Kobayashi [5] posed the following:

(II) **KOBAYASHI'S CONJECTURE.** *Let E be an indecomposable holomorphic vector bundle on a compact Kähler manifold W with Kähler metric g_0 . Then E admits an Einstein Hermitian metric if and only if E is stable (in the sense of Mumford-Takemoto) with respect to g_0 .*

Recently, Donaldson [2] solved (II) for the case where W is a projective algebraic surface. One crucial step in his proof is the construction of a non-linear functional λ from the set of all Hermitian metrics on E to the real numbers such that (1) any critical point of λ is exactly an Einstein Hermitian metric on E and that (2) λ is bounded from below if and only if E is semistable with respect to g_0 .

Although (I) and (II) look quite different, there is some link between these conjectures. Actually even for (I), the same procedure as in Donaldson's work can be carried out to a considerable degree as follows:

Fix a Kähler form $\omega_0 = \sqrt{-1} \sum g_{\alpha\bar{\beta}} dz^\alpha \wedge dz^{\bar{\beta}}$ on V . In this introduction, we assume for simplicity that ω_0 represents $2\pi c_1(V)_R$. We denote by \mathcal{X}

the set of all Kähler forms on V cohomologous to ω_0 . Let f_0 be a real-valued C^∞ -function on V which is uniquely determined, up to constant, by the equation

$$\bar{\partial}\partial \log \det(g_{\alpha\bar{\beta}}) - \sum g_{\alpha\bar{\beta}} dz^\alpha \wedge dz^{\bar{\beta}} = \partial\bar{\partial}f_0 .$$

The main purpose of this paper is to prove the following theorem announced earlier in [6].

THEOREM. *There exists a mapping $\mu: \mathcal{K} \rightarrow \mathbf{R}$ satisfying the following conditions:*

(i) *An element ω of \mathcal{K} is a critical point of μ if and only if ω is an Einstein Kähler form, (cf. §3).*

(ii) *Let Y be a holomorphic vector field on V , and ω be an element of \mathcal{K} . Put $Y_R := Y + \bar{Y}$ and $y_t := \exp tY_R$ for $t \in \mathbf{R}$. Then $\mu(y_t^*\omega)$ is a linear function in t . Namely for every t ,*

$$\frac{d}{dt}\mu(y_t^*\omega) = \int_V (Y_R f_0)\omega_0^n / \int_V \omega_0^n ,$$

where the right-hand side is the Futaki invariant of V corresponding to the holomorphic vector field Y , (cf. §5).

(iii) *If ω is a critical point of μ , then the inequality*

$$\frac{d^2}{dt^2}\mu(\theta_t)|_{t=0} \geq 0$$

holds for every smooth path $\{\theta_t \mid -\varepsilon \leq t \leq \varepsilon\}$ in \mathcal{K} such that $\theta_0 = \omega$, (cf. §6).

This $\mu: \mathcal{K} \rightarrow \mathbf{R}$ is called the *K-energy map* of the Kähler manifold (V, ω_0) . In view of (i) and (ii) above, one can easily see that if $\int_V (Y_R f_0)\omega_0^n \neq 0$ for some holomorphic vector field Y on V , then μ cannot have a critical point, i.e., X does not admit any Einstein Kähler metric, which gives another proof of a fundamental theorem of Futaki [3]. Furthermore, (i) and (iii) above give us some indication that Conjecture (I) can be weakened in the following more plausible form.

(III) **CONJECTURE.** *Suppose that $\text{Aut}^0(V)$ is a reductive algebraic group. If μ is bounded from below, then V admits an Einstein Kähler metric.*

Several supplements to this paper can be found in [7]. In a forthcoming paper (cf. Bando and Mabuchi [1]), we shall show the following theorem.

THEOREM. *Let \mathcal{E} be the set of all Einstein Kähler forms in \mathcal{K} , and*

\mathcal{K}^+ be the set of all $\omega \in \mathcal{K}$ with positive definite Ricci tensor. Assume that $\mathcal{E} \neq \emptyset$. Then

(i) the restriction $\mu|_{\mathcal{K}^+}: \mathcal{K}^+ \rightarrow \mathbf{R}$ is bounded from below, and $\mu|_{\mathcal{K}^+}$ takes its absolute minimum on \mathcal{E} .

(ii) For any ω_1 and ω_2 in \mathcal{E} , there exists an element g of $\text{Aut}^0(V)$ such that $g^*\omega_2 = \omega_1$.

We shall also give several generalizations of μ in the latter paper. I wish to thank all those people who encouraged me and gave me suggestions, in particular Professors S. Kobayashi and H. Ozeki, and Doctors S. Bando, I. Enoki and R. Kobayashi, who helped me again and again during the preparation of this paper. Thanks are due also to the Max-Planck-Institut für Mathematik for the hospitality and constant assistance all through my stay in Bonn.

ADDED IN PROOF. I am very grateful to the referee for several improvements of §5.

1. Notation and Convention. Throughout this paper we fix an arbitrary n -dimensional compact Kähler connected manifold X with Kähler form $\omega_0 = \sqrt{-1} \sum g_{\alpha\bar{\beta}} dz^\alpha \wedge dz^{\bar{\beta}}$ written in terms of holomorphic local coordinates (z^1, z^2, \dots, z^n) . Let

$$\mathcal{K} := \{\omega \mid \text{Kähler forms on } X \text{ which are cohomologous to } \omega_0 \text{ in } H^{1,1}(X, \mathbf{R})\}.$$

For each element $\omega = \sqrt{-1} \sum g(\omega)_{\alpha\bar{\beta}} dz^\alpha \wedge dz^{\bar{\beta}}$ of \mathcal{K} , we denote by $\sum R(\omega)_{\alpha\bar{\beta}} dz^\alpha \otimes dz^{\bar{\beta}}$ the corresponding Ricci tensor. We put $R(\omega) := \sqrt{-1} \sum R(\omega)_{\alpha\bar{\beta}} dz^\alpha \wedge dz^{\bar{\beta}}$. Then $R(\omega)/2\pi$ represents $c_1(X)_{\mathbf{R}}$ and we have $R(\omega) = \sqrt{-1} \partial\bar{\partial} \log \det(g(\omega)_{\alpha\bar{\beta}})$. Furthermore, let $\sigma(\omega)$ (resp. \square_ω) be the corresponding scalar curvature (resp. Laplacian on functions):

$$\sigma(\omega) := \sum g(\omega)^{\bar{\beta}\alpha} R(\omega)_{\alpha\bar{\beta}}, \quad \square_\omega := \sum g(\omega)^{\bar{\beta}\alpha} \partial^2 / \partial z^\alpha \partial z^{\bar{\beta}},$$

where $(g(\omega)^{\bar{\beta}\alpha})$ is the inverse matrix of $(g(\omega)_{\alpha\bar{\beta}})$. For each real valued C^∞ -function $\varphi \in C^\infty(X)_{\mathbf{R}}$ on X , we put $\omega_0(\varphi) = \omega_0 + \sqrt{-1} \partial\bar{\partial}\varphi$, and let

$$\mathcal{H} := \{\varphi \in C^\infty(X)_{\mathbf{R}} \mid \omega_0(\varphi) \in \mathcal{K}\}.$$

Note that the natural map

$$\mathcal{H} \rightarrow \mathcal{K}, \quad \varphi \mapsto \omega_0(\varphi)$$

is surjective. For each $\varphi \in \mathcal{H}$, the corresponding $\square_{\omega_0(\varphi)}$, $\sigma(\omega_0(\varphi))$, $R(\omega_0(\varphi))$, $R(\omega_0(\varphi))_{\alpha\bar{\beta}}$, $g(\omega_0(\varphi))_{\alpha\bar{\beta}}$, $g(\omega_0(\varphi))^{\bar{\beta}\alpha}$ will be denoted simply by \square_φ , $\sigma(\varphi)$, $R(\varphi)$, $R(\varphi)_{\alpha\bar{\beta}}$, $g(\varphi)_{\alpha\bar{\beta}}$, $g(\varphi)^{\bar{\beta}\alpha}$, respectively.

DEFINITION (1.1). A one-parameter family $\{\varphi_t \mid a \leq t \leq b\}$ of functions

in $C^\infty(X)_\mathbf{R}$ is said to be *smooth* (or a *smooth path*) if the mapping

$$[a, b] \times X \rightarrow \mathbf{R}, \quad (t, x) \mapsto \varphi_t(x)$$

is C^∞ . We then put $\dot{\varphi}_t := \partial\varphi_t/\partial t$ and $\ddot{\varphi}_t = \partial^2\varphi_t/\partial t^2$.

DEFINITION (1.2). We define the real constants λ and ν by

$$\lambda := 2n\pi \int_X c_1(X)\omega_0^{n-1} / \int_X \omega_0^n, \quad \nu := \lambda/n.$$

Furthermore, to each $\varphi \in C^\infty(X)_\mathbf{R}$, we associate an (n, n) -form $V_0(\varphi)$ on X as follows:

$$V_0(\varphi) := \omega_0(\varphi)^n / \int_X \omega_0^n.$$

This is so normalized that $\int_X V_0(\varphi) = 1$. Moreover, if ω_0 represents $2\pi c_1(X)_\mathbf{R}$, then $\lambda = n$.

DEFINITION (1.3). Let (z^1, z^2, \dots, z^n) be a system of holomorphic local coordinates on X . For every $f \in C^\infty(X)_\mathbf{R}$, we use the following notation:

$$\begin{aligned} f_\alpha &:= \partial_\alpha f, & f_{\bar{\alpha}} &:= \partial_{\bar{\alpha}} f, & f_{\alpha\beta} &:= \partial_\alpha \partial_\beta f, & f_{\bar{\alpha}\bar{\beta}} &:= \partial_{\bar{\alpha}} \partial_{\bar{\beta}} f, \\ f_{\alpha\bar{\beta}} &:= \partial_\alpha \partial_{\bar{\beta}} f, & f_{\alpha\beta\bar{\gamma}} &:= \partial_\alpha \partial_\beta \partial_{\bar{\gamma}} f, & \dots & & \end{aligned}$$

where we denote by ∂_α (resp. $\partial_{\bar{\alpha}}, \partial_\beta, \partial_{\bar{\beta}}, \partial_{\bar{\gamma}}$) the operator $\partial/\partial z^\alpha$ (resp. $\partial/\partial z^{\bar{\alpha}}, \partial/\partial z^\beta, \partial/\partial z^{\bar{\beta}}, \partial/\partial z^{\bar{\gamma}}$). Our notation is slightly different from the ordinary one, because for instance, $f_{\alpha\beta}$ is not $\nabla_\beta \nabla_\alpha f$.

2. Basic Constructions. This section is crucial in the construction of the K-energy map μ . We shall introduce the mappings

$$L: C^\infty(X)_\mathbf{R} \times C^\infty(X)_\mathbf{R} \rightarrow \mathbf{R}, \quad (\text{cf. (2.5)}),$$

$$M: \mathcal{H} \times \mathcal{H} \rightarrow \mathbf{R}, \quad (\text{cf. (2.4)}),$$

where the latter immediately defines μ , (cf. (2.7), (3.1)). Although the functional L is not essential in later sections, it none-the-less plays an important role in our forthcoming papers (cf. Mabuchi [7], Bando and Mabuchi [1]).

DEFINITION (2.1). Let \mathcal{S} be a non-empty set and A be an additive group. Then a mapping $N: \mathcal{S} \times \mathcal{S} \rightarrow A$ is said to satisfy the *1-cocycle condition* if

- (i) $N(\sigma_1, \sigma_2) + N(\sigma_2, \sigma_1) = 0$ and
- (ii) $N(\sigma_1, \sigma_2) + N(\sigma_2, \sigma_3) + N(\sigma_3, \sigma_1) = 0$

for all $\sigma_1, \sigma_2, \sigma_3 \in \mathcal{S}$.

DEFINITION (2.2). For every $(\varphi', \varphi'') \in \mathcal{H} \times \mathcal{H}$, we define real numbers $L(\varphi', \varphi'')$, $M(\varphi', \varphi'')$ by

$$(2.2.1) \quad L(\varphi', \varphi'') := \int_a^b \left(\int_X \dot{\varphi}_t V_0(\varphi_t) \right) dt$$

$$(2.2.2) \quad M(\varphi', \varphi'') := - \int_a^b \left\{ \int_X \dot{\varphi}_t (\sigma(\varphi_t) - \lambda) V_0(\varphi_t) \right\} dt,$$

where $\{\varphi_t | a \leq t \leq b\}$ is an arbitrary piecewise smooth path in \mathcal{H} such that $\varphi_a = \varphi'$ and $\varphi_b = \varphi''$.

THEOREM (2.3). $L(\varphi', \varphi'')$ above is independent of the choice of the path $\{\varphi_t | a \leq t \leq b\}$ and therefore well-defined. Moreover,

(2.3.1) L satisfies the 1-cocycle condition, and

(2.3.2) $L(\varphi_1, \varphi_2 + C) = L(\varphi_1, \varphi_2) + C$ for all φ_1, φ_2 and all $C \in \mathbf{R}$.

THEOREM (2.4). $M(\varphi', \varphi'')$ above is independent of the choice of the path $\{\varphi_t | a \leq t \leq b\}$ and therefore well-defined. Moreover,

(2.4.1) M satisfies the 1-cocycle condition, and

(2.4.2) $M(\varphi_1 + C_1, \varphi_2 + C_2) = M(\varphi_1, \varphi_2)$ for all φ_1, φ_2 and all $C_1, C_2 \in \mathbf{R}$.

PROOF OF (2.3). Let $\psi(s, t) := s\varphi_t$ for $(s, t) \in [0, 1] \times [a, b]$. Since $\{\varphi_t | a \leq t \leq b\}$ is piecewise smooth, there exists a partition $a = a_0 < a_1 < a_2 < \dots < a_r = b$ of the interval $[a, b]$ such that $\{\varphi_t | a_{i-1} \leq t \leq a_i\}$ is smooth for each $i \in \{1, 2, \dots, r\}$.

Step 1. We shall first show that

$$(*)_i \quad \int_{a_{i-1}}^{a_i} \left(\int_X \dot{\varphi}_t V_0(\varphi_t) \right) dt = \int_0^1 \left(\int_X \frac{\partial \psi}{\partial s} V_0(\psi) \right) ds \Big|_{t=a_{i-1}}^{t=a_i}.$$

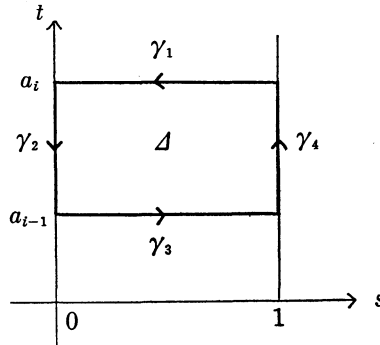


FIGURE 1.

Let $\Psi(s, t) := \left(\int_X (\partial\psi/\partial s) V_0(\psi) ds\right) + \left(\int_X (\partial\psi/\partial t) V_0(\psi)\right) dt$. Then in view of Figure 1, we have

$$\begin{aligned} \int_A d\Psi &= \int_{a_i} \Psi = \sum_{i=1}^4 \int_{\gamma_i} \Psi \\ &= -\int_0^1 \left(\int_X \frac{\partial\psi}{\partial s} V_0(\psi)\right) ds \Big|_{t=a_{i-1}}^{t=a_i} + \int_{a_{i-1}}^{a_i} \left(\int_X \dot{\varphi}_i V_0(\varphi_i)\right) dt. \end{aligned}$$

Therefore the proof of $(*)_i$ is reduced to showing $d\Psi = 0$. By routine computations, we have

$$\begin{aligned} d\Psi &= dt \wedge ds \int_X \left\{ \frac{\partial}{\partial t} \left(\frac{\partial\psi}{\partial s} V_0(\psi) \right) - \frac{\partial}{\partial s} \left(\frac{\partial\psi}{\partial t} V_0(\psi) \right) \right\} \\ &= \sqrt{-1} dt \wedge ds \int_X \left\{ \frac{\partial\psi}{\partial s} \bar{\partial} \bar{\partial} \left(\frac{\partial\psi}{\partial t} \right) + \frac{\partial\psi}{\partial t} \bar{\partial} \bar{\partial} \left(\frac{\partial\psi}{\partial s} \right) \right\} \wedge n\omega_0(\psi)^{n-1} / \int_X \omega_0^n \\ &= \sqrt{-1} dt \wedge ds \int_X \left\{ -\bar{\partial} \left(\frac{\partial\psi}{\partial s} \right) \wedge \bar{\partial} \left(\frac{\partial\psi}{\partial t} \right) - \bar{\partial} \left(\frac{\partial\psi}{\partial t} \right) \wedge \bar{\partial} \left(\frac{\partial\psi}{\partial s} \right) \right\} \\ &\quad \wedge n\omega_0(\psi)^{n-1} / \int_X \omega_0^n \\ &= 0. \end{aligned}$$

Step 2. Adding up the equalities $(*)_i$ ($i = 1, 2, \dots, r$), we obtain

$$\int_a^b \left(\int_X \dot{\varphi}_i V_0(\varphi_i)\right) dt = \int_0^1 \left(\int_X \varphi V_0(s\varphi)\right) ds \Big|_{\varphi=\varphi'}^{\varphi=\varphi''}.$$

This shows that $\int_a^b \left(\int_X \dot{\varphi}_i V_0(\varphi_i)\right) dt$ is independent of the choice of the path $\{\varphi_t | a \leq t \leq b\}$. (2.3.1) is also immediate. For (2.3.2), let $\psi_t := \varphi_2 + tC$ ($t \in [0, 1]$). Then in view of (2.3.1),

$$L(\varphi_1, \varphi_2 + C) - L(\varphi_1, \varphi_2) = L(\varphi_2, \varphi_2 + C) = \int_0^1 \int_X C V_0(\psi_t) dt = C.$$

REMARK (2.5). The above proof is valid even in the case $(\varphi', \varphi'') \in C^\infty(X)_R \times C^\infty(X)_R$. Hence L naturally extends to a functional on $C^\infty(X)_R \times C^\infty(X)_R$. This extended functional (denoted by the same L) can still be defined by (2.2.1) and satisfies (2.3.1) and (2.3.2).

For the proof of (2.4), we need the following Lemma:

LEMMA (2.6). Suppose that a two-parameter family $\{\psi(s, t) | (s, t) \in [0, 1] \times [a, b]\}$ of functions in \mathcal{H} is smooth in the sense that the mapping

$$[0, 1] \times [a, b] \times X \rightarrow \mathbf{R}, \quad (s, t, x) \mapsto (\psi(s, t))(x)$$

is C^∞ . Then there exists a unique C^∞ -function $F = F(s, t, x) \in C^\infty([0, 1] \times$

$[a, b] \times X)_R$ such that

- (i) $\partial F/\partial s = -(\square_\psi + \nu)(\partial\psi/\partial s)$,
- (ii) $\partial F/\partial t = -(\square_\psi + \nu)(\partial\psi/\partial t)$,
- (iii) $F|_{(s,t)=(0,a)} = 0$ in $C^\infty(X)_R$, and
- (iv) $R(\psi) - \nu\omega_0(\psi) = R(\omega_1) - \nu\omega_1 + \sqrt{-1}\partial\bar{\partial}F$,

where we put $\omega_1 := \omega_0(\psi(0, a))$.

PROOF. Using the notation in (1.3), we have

$$\begin{aligned}
 (2.6.1) \quad & (\partial/\partial t)(\square_\psi(\partial\psi/\partial s)) - (\partial/\partial s)(\square_\psi(\partial\psi/\partial t)) \\
 &= (\partial/\partial t)(\sum g(\psi)^{\bar{\gamma}\tau}(\partial\psi/\partial s)_{\bar{\gamma}\bar{\delta}}) - (\partial/\partial s)(\sum g(\psi)^{\bar{\alpha}\beta}(\partial\psi/\partial t)_{\beta\bar{\alpha}}) \\
 &= -\sum \{g(\psi)^{\bar{\delta}\beta}(\partial\psi/\partial t)_{\beta\bar{\alpha}}g(\psi)^{\bar{\alpha}\tau}(\partial\psi/\partial s)_{\bar{\gamma}\bar{\delta}}\} \\
 &\quad + \sum \{g(\psi)^{\bar{\alpha}\tau}(\partial\psi/\partial s)_{\bar{\gamma}\bar{\delta}}g(\psi)^{\bar{\delta}\beta}(\partial\psi/\partial t)_{\beta\bar{\alpha}}\} \\
 &= 0.
 \end{aligned}$$

Hence $(\partial/\partial t)\{(\square_\psi + \nu)(\partial\psi/\partial s)\} = (\partial/\partial s)\{(\square_\psi + \nu)(\partial\psi/\partial t)\}$. Therefore there exists $F(s, t, x) \in C^\infty([0, 1] \times [a, b] \times X)$ satisfying (i), (ii) and (iii). For (iv), we first observe that it is true for $(s, t) = (0, a)$. We now have

$$\begin{aligned}
 & (\partial/\partial s)(R(\psi) - \nu\omega_0(\psi)) - (\partial/\partial s)(\sqrt{-1}\partial\bar{\partial}F) \\
 &= \sqrt{-1}\{\bar{\partial}\partial(\square_\psi(\partial\psi/\partial s)) - \partial\bar{\partial}(\nu\partial\psi/\partial s) - \partial\bar{\partial}(\partial F/\partial s)\} = 0.
 \end{aligned}$$

Similarly, $(\partial/\partial t)(R(\psi) - \nu\omega_0(\psi)) - (\partial/\partial t)(\sqrt{-1}\partial\bar{\partial}F) = 0$. Hence we obtain (iv).

PROOF OF (2.4). Let $\psi(s, t) := s\varphi_t$ for $(s, t) \in [0, 1] \times [a, b]$ and $\Psi(s, t)$ be the 1-form

$$\left(\int_x -\frac{\partial\psi}{\partial s}(\sigma(\psi) - \lambda)V_0(\psi)\right)ds + \left(\int_x -\frac{\partial\psi}{\partial t}(\sigma(\psi) - \lambda)V_0(\psi)\right)dt.$$

Then similar to the proof of (2.3), that of (2.4) except the equality (2.4.2) is reduced to showing $d\Psi = 0$.

Step 1. By Lemma (2.6) applied to our Ψ , there exists a function $F = F(s, t, x) \in C^\infty([0, 1] \times [a, b] \times X)_R$ satisfying the equalities (i)~(iv). First by (iv),

$$\begin{aligned}
 & n(R(\omega_0) - \nu\omega_0)\omega_0(\psi)^{n-1} / \int_x \omega_0^n \\
 &= n(R(\psi) - \nu\omega_0(\psi) - \sqrt{-1}\partial\bar{\partial}F)\omega_0(\psi)^{n-1} / \int_x \omega_0^n \\
 &= (\sigma(\psi) - \lambda - \square_\psi F)V_0(\psi).
 \end{aligned}$$

Therefore, introducing the 1-form Φ defined as

$$\left\{ ds \int_x n(R(\omega_0) - \nu\omega_0) \frac{\partial \psi}{\partial s} \omega_0(\psi)^{n-1} + dt \int_x n(R(\omega_0) - \nu\omega_0) \frac{\partial \psi}{\partial t} \omega_0(\psi)^{n-1} \right\} / \int_x \omega_0^n,$$

we obtain

$$\begin{aligned} \Psi &= -\Phi - \left(\int_x \frac{\partial \psi}{\partial s} (\square_\psi F) V_0(\psi) \right) ds - \left(\int_x \frac{\partial \psi}{\partial t} (\square_\psi F) V_0(\psi) \right) dt \\ &= -\Phi - \left(\int_x \left(\square_\psi \frac{\partial \psi}{\partial s} \right) F V_0(\psi) \right) ds - \left(\int_x \left(\square_\psi \frac{\partial \psi}{\partial t} \right) F V_0(\psi) \right) dt. \end{aligned}$$

Hence $d\Psi = -d\Phi + Ids \wedge dt$, where the coefficient I is

$$\int_x \frac{\partial}{\partial t} \left(\left(\square_\psi \frac{\partial \psi}{\partial s} \right) F V_0(\psi) \right) - \int_x \frac{\partial}{\partial s} \left(\left(\square_\psi \frac{\partial \psi}{\partial t} \right) F V_0(\psi) \right).$$

In view of the identities $\partial V_0(\psi)/\partial t = \square_\psi(\partial \psi/\partial t) V_0(\psi)$ and $\partial V_0(\psi)/\partial s = \square_\psi(\partial \psi/\partial s) V_0(\psi)$, (2.6.1) above combined with (i) and (ii) of (2.6) yields

$$\begin{aligned} I &= \int_x \left(\square_\psi \frac{\partial \psi}{\partial s} \right) \frac{\partial}{\partial t} (F V_0(\psi)) - \int_x \left(\square_\psi \frac{\partial \psi}{\partial t} \right) \frac{\partial}{\partial s} (F V_0(\psi)) \\ &= \int_x \left\{ \left(\square_\psi \frac{\partial \psi}{\partial s} \right) \left(-\square_\psi \frac{\partial \psi}{\partial t} - \nu \frac{\partial \psi}{\partial t} \right) + \left(\square_\psi \frac{\partial \psi}{\partial s} \right) F \left(\square_\psi \frac{\partial \psi}{\partial t} \right) \right\} V_0(\psi) \\ &\quad - \int_x \left\{ \left(\square_\psi \frac{\partial \psi}{\partial t} \right) \left(-\square_\psi \frac{\partial \psi}{\partial s} - \nu \frac{\partial \psi}{\partial s} \right) + \left(\square_\psi \frac{\partial \psi}{\partial t} \right) F \left(\square_\psi \frac{\partial \psi}{\partial s} \right) \right\} V_0(\psi) \\ &= 0. \end{aligned}$$

Thus, we obtain

$$\begin{aligned} d\Psi &= -d\Phi = ds \wedge dt \int_x n(R(\omega_0) - \nu\omega_0) \left(\frac{\partial \psi}{\partial s} \frac{\partial}{\partial t} - \frac{\partial \psi}{\partial t} \frac{\partial}{\partial s} \right) (\omega_0(\psi)^{n-1}) / \int_x \omega_0^n \\ &= \sqrt{-1} ds \wedge dt \int_x n(n-1)(R(\omega_0) - \nu\omega_0) \left(-\frac{\partial \psi}{\partial s} \bar{\partial} \left(\frac{\partial \psi}{\partial t} \right) - \frac{\partial \psi}{\partial t} \bar{\partial} \left(\frac{\partial \psi}{\partial s} \right) \right) \omega_0(\psi)^{n-2} / \int_x \omega_0^n \\ &= \sqrt{-1} ds \wedge dt \int_x n(n-1)(R(\omega_0) - \nu\omega_0) \\ &\quad \times \left(\bar{\partial} \left(\frac{\partial \psi}{\partial s} \right) \wedge \partial \left(\frac{\partial \psi}{\partial t} \right) + \partial \left(\frac{\partial \psi}{\partial t} \right) \wedge \bar{\partial} \left(\frac{\partial \psi}{\partial s} \right) \right) \omega_0(\psi)^{n-2} / \int_x \omega_0^n \\ &= 0. \end{aligned}$$

Step 2. We shall finally show (2.4.2). Since $M(\varphi_1 + C_1, \varphi_2 + C_2) - M(\varphi_1, \varphi_2) = M(\varphi_2, \varphi_2 + C_2) - M(\varphi_1, \varphi_1 + C_1)$, it suffices to show $M(\varphi, \varphi + C) = 0$ for all φ and C . Let $\psi_t := \varphi + tC$, $t \in [0, 1]$. Then

$$M(\varphi, \varphi + C) = -\int_0^1 \left(\int_x C(\sigma(\psi_t) - \lambda) V_0(\psi_t) \right) dt = 0.$$

The proof of (2.4) is now complete.

(2.7) In view of (2.4.2) above, $M: \mathcal{H} \times \mathcal{H} \rightarrow \mathbf{R}$ factors through $\mathcal{H} \times \mathcal{H}$. Hence we can define a mapping $M: \mathcal{H} \times \mathcal{H} \rightarrow \mathbf{R}$ (denoted by the same M) satisfying the 1-cocycle condition by

$$(2.7.1) \quad M(\omega', \omega'') := M(\varphi', \varphi''), \quad \text{for all } \omega', \omega'' \in \mathcal{H},$$

where φ', φ'' are functions in \mathcal{H} such that $\omega_0(\varphi') = \omega'$ and $\omega_0(\varphi'') = \omega''$. We now put $\mathcal{H}_0 := \{\varphi \in \mathcal{H} \mid L(0, \varphi) = 0\}$. Then the restriction of the mapping $\varphi \in \mathcal{H} \mapsto \omega_0(\varphi) \in \mathcal{H}$ to \mathcal{H}_0 is an isomorphism:

$$\mathcal{H}_0 \cong \mathcal{H}, \quad \varphi \mapsto \omega_0(\varphi).$$

Hence we can regard \mathcal{H} as the subset \mathcal{H}_0 of \mathcal{H} . By this identification, the mapping $M: \mathcal{H} \times \mathcal{H} \rightarrow \mathbf{R}$ defined just above coincides with the restriction to $\mathcal{H}_0 \times \mathcal{H}_0$ of the original mapping $M: \mathcal{H} \times \mathcal{H} \rightarrow \mathbf{R}$.

A one-parameter family $\{\omega_t \mid a \leq t \leq b\}$ of Kähler forms in \mathcal{H} is said to be *smooth* (or a *smooth path*) if it forms a smooth path in $C^\infty(X)_\mathbf{R}$ via the identification $\mathcal{H} = \mathcal{H}_0$.

3. K-energy maps and their critical points.

DEFINITION (3.1). Let $\mu: \mathcal{H} \rightarrow \mathbf{R}$ be the mapping which associate, to each $\omega \in \mathcal{H}$, the real number $\mu(\omega) := M(\omega_0, \omega)$, (cf. (2.7)). This μ is called the K-energy map of the Kähler manifold (X, ω_0) . For every $\varphi \in \mathcal{H}$, $\mu(\omega_0(\varphi))$ will be denoted by $\mu(\varphi)$ for simplicity.

We write the above μ sometimes as μ_{ω_0} because it depends on the choice of ω_0 . If we replace the original ω_0 by another ω'_0 cohomologous to ω_0 , then the difference between μ_{ω_0} and $\mu_{\omega'_0}$ is just a constant. In fact, for all $\omega \in \mathcal{H}$

$$\mu_{\omega_0}(\omega) - \mu_{\omega'_0}(\omega) = M(\omega_0, \omega'_0)$$

which is independent of $\omega \in \mathcal{H}$. In particular every critical point of μ_{ω_0} is, at the same time, that of $\mu_{\omega'_0}$ and vice versa. Hence "critical points of μ " have an intrinsic meaning in the sense that they depend only on X and on the cohomology class of ω_0 in $H^{1,1}(X, \mathbf{R})$.

THEOREM (3.2). Let $\mu: \mathcal{H} \rightarrow \mathbf{R}$ be the K-energy map of the Kähler manifold (X, ω_0) . Then for an arbitrary element ω of \mathcal{H} , the following are equivalent:

- (i) ω is a critical point of μ ,
- (ii) ω has a constant scalar curvature,
- (iii) ω has the constant scalar curvature λ .

PROOF. Let $\{\varphi_t \mid -\varepsilon \leq t \leq \varepsilon\}$ be a smooth path in \mathcal{H} such that $\omega_0(\varphi_0) = \omega$. Then by (2.2.2) and (2.7.1),

$$\frac{d}{dt} \mu(\omega_0(\varphi_t))|_{t=0} = \int_X \dot{\varphi}_t|_{t=0} (\sigma(\omega) - \lambda)\omega^n / \int_X \omega_0^n,$$

which shows the equivalence of (i) and (iii). Thus the proof is reduced to showing that (ii) implies (iii). Since $\int_X (\sigma(\omega) - \lambda)\omega^n = 0$ for every $\omega \in \mathcal{H}$, the required implication is now immediate.

DEFINITION (3.3). A compact complex connected manifold with ample anticanonical bundle (or equivalently, with $c_1 > 0$) is called a *Fano manifold*. Differential-geometrically, a Fano manifold is a compact complex connected manifold which admits a Kähler metric with positive definite Ricci tensor, (cf. Yau [8]).

THEOREM (3.4). *Suppose that X is a Fano manifold and furthermore that ω_0 represents $2\pi c_1(X)_R$. Consider the K-energy map $\mu: \mathcal{H} \rightarrow R$ of the Kähler manifold (X, ω_0) . Then for an arbitrary element ω of \mathcal{H} , the following are equivalent:*

- (i) ω is a critical point of μ ,
- (ii) ω is an Einstein Kähler form,
- (iii) ω is an Einstein Kähler form with the constant scalar curvature n .

PROOF. Note that λ is n , (cf. (1.2)). Since X is a Fano manifold, every Kähler form of constant scalar curvature in the cohomology class $2\pi c_1(X)_R$ is an Einstein form. Then (3.4) is straightforward from Theorem (3.2).

4. Another interpretation for the K-energy map. Recall that \mathcal{H} is naturally identified with the subset \mathcal{H}_0 of \mathcal{H} , (cf. (2.7)). In this section, another interpretation for the K-energy map $\mu: \mathcal{H}_0 (= \mathcal{H}) \rightarrow R$ of (X, ω_0) , (cf. (3.1)), will be given. We shall actually show the following:

THEOREM (4.1). *For each $\varphi \in \mathcal{H}$, there exists a unique function $f_\varphi \in C^\infty(X)_R$ (depending smoothly on φ) such that*

$$(4.1.1) \quad \sigma(\varphi) - \lambda = \square_\varphi f_\varphi,$$

$$(4.1.2) \quad \int_X f_\varphi V_0(\varphi) = 0 \text{ if } \varphi = 0 \text{ in } C^\infty(X)_R, \text{ and}$$

$$(4.1.3) \quad \frac{\partial}{\partial t} (f_{\varphi_t} - k_{\varphi_t}) = -(\square_{\varphi_t} + \nu)\dot{\varphi}_t \text{ for every smooth path } \{\varphi_t | a \leq t \leq b\} \text{ in } \mathcal{H},$$

where for each $\psi \in \mathcal{H}$, we denote by k_ψ the function in $C^\infty(X)_R$ defined

by

$$\square_{\psi} k_{\psi} = (R(\omega_0) - \nu\omega_0) \wedge n\omega_0(\psi)^{n-1}/\omega_0(\psi)^n \quad \text{and}$$

$$\int_X k_{\psi} \omega_0^n = 0 .$$

COROLLARY (4.2). *Suppose that X is a Fano manifold and furthermore that ω_0 represents $2\pi c_1(X)_R$. Then to each $\varphi \in \mathcal{H}_0$, we can uniquely associate a function $f_{\varphi} \in C^{\infty}(X)_R$ (which is the same one as in (4.1)) such that*

$$(4.2.1) \quad \sigma(\varphi) - n = \square_{\varphi} f_{\varphi}, \text{ i.e., } R(\varphi) - \omega_0(\varphi) = \sqrt{-1} \partial\bar{\partial} f_{\varphi},$$

$$(4.2.2) \quad \mu(\varphi) = -\int_X f_{\varphi} V_0(\varphi), \text{ and}$$

$$(4.2.3) \quad \frac{\partial}{\partial t} f_{\varphi_t} = -(\square_{\varphi_t} + 1)\dot{\varphi}_t \text{ for every smooth path } \{\varphi_t | a \leq t \leq b\} \text{ in } \mathcal{H}_0.$$

In view of (4.2.2), the construction of f_{φ} is crucial to our approach. The key in the definition of f_{φ} is the following:

DEFINITION (4.3). For each pair $(\varphi', \varphi'') \in \mathcal{H} \times \mathcal{H}$, we define a function $H(\varphi', \varphi'') \in C^{\infty}(X)_R$ by

$$(4.3.1) \quad H(\varphi', \varphi'') := -\int_a^b (\square_{\varphi_t} + \nu)\dot{\varphi}_t dt ,$$

where $\{\varphi_t | a \leq t \leq b\}$ is an arbitrary piecewise smooth path in \mathcal{H} such that $\varphi_a = \varphi'$ and $\varphi_b = \varphi''$.

THEOREM (4.4). $H(\varphi', \varphi'')$ above is independent of the choice of the path $\{\varphi_t | a \leq t \leq b\}$ and therefore well-defined. Moreover,

$$(4.4.1) \quad H: \mathcal{H} \times \mathcal{H} \rightarrow C^{\infty}(X)_R \text{ satisfies the 1-cocycle condition, and}$$

$$(4.4.2) \quad \{R(\varphi) - \nu\omega_0(\varphi)\}_{\varphi=\varphi'}^{\varphi=\varphi''} = \sqrt{-1} \partial\bar{\partial} H(\varphi', \varphi'') .$$

PROOF. In view of the proof of (2.3), we may assume that $\{\varphi_t | a \leq t \leq b\}$ is a smooth path. Let $\psi(s, t) := s\varphi_t$ for $(s, t) \in [0, 1] \times [a, b]$. Then by Lemma (2.6), we obtain a C^{∞} -function $F(s, t, x) \in C^{\infty}([0, 1] \times [a, b] \times X)_R$ with the properties (i)~(iv) of (2.6). For each $(\sigma, \tau) \in [0, 1] \times [a, b]$, we set $F_{\sigma, \tau} := F|_{(s,t)=(\sigma,\tau)}$. Then by (i),

$$F_{1,t} - F_{0,t} = -\int_0^1 (\square_{\psi(s,t)} + \nu)\varphi_t ds .$$

On the other hand, by (ii) applied to the cases $s = 0$ and $s = 1$,

$$F_{0,b} = F_{0,a},$$

$$F_{1,b} - F_{1,a} = -\int_a^b (\square_{\varphi_t} + \nu)\dot{\varphi}_t dt.$$

Combining the three equalities obtained just above, we have

$$-\int_a^b (\square_{\varphi_t} + \nu)\dot{\varphi}_t dt = (F_{1,t} - F_{0,t})|_{t=a}^{t=b} = -\int_0^1 (\square_{\psi(s,t)} + \nu)\varphi_t ds |_{t=a}^{t=b}.$$

The proof, except that for (4.4.2), is then straightforward. For (4.4.2), applying (iv) of (2.6) to the cases $(s, t) = (1, a), (1, b)$, we now conclude that

$$\{R(\varphi) - \nu\omega_0(\varphi)\}|_{\varphi=a}^{\varphi=b} = \sqrt{-1}\partial\bar{\partial}(F_{1,b} - F_{1,a}) = \sqrt{-1}\partial\bar{\partial}H(\varphi', \varphi').$$

We shall now define f_φ for each $\varphi \in \mathcal{H}$ and then proceed to the proof of (4.1) and (4.2).

DEFINITION (4.5). (i) For each $\varphi \in \mathcal{H}$, we define $f_\varphi \in C^\infty(X)_R$ by $f_\varphi := k_\varphi + H(0, \varphi)$.

(ii) For each $\omega \in \mathcal{H}$, let $f_\omega \in C^\infty(X)_R$ denote the function f_{φ_ω} , where φ_ω is the unique element of \mathcal{H}_0 such that $\omega = \omega_0(\varphi_\omega)$.

PROOF OF (4.1). Since the uniqueness is easy, it suffices to show that f_φ defined in (4.5) satisfies (4.1.1)~(4.1.3). First, (4.1.2) is obvious from our definition of f_φ . We next observe that (4.1.3) is an immediate consequence of (4.3.1). For (4.1.1), we apply (4.4.2):

$$R(\varphi) - \nu\omega_0(\varphi) = R(\omega_0) - \nu\omega_0 + \sqrt{-1}\partial\bar{\partial}H(0, \varphi).$$

Taking the wedge product with $n\omega_0(\varphi)^{n-1}$, and then dividing both sides by $\omega_0(\varphi)^n$, we finally obtain

$$\sigma(\varphi) - \lambda = \square_\varphi(k_\varphi + H(0, \varphi)) = \square_\varphi f_\varphi.$$

PROOF OF (4.2). Since $R(\omega_0)$ and ω_0 are cohomologous, we have $k_\varphi = f_0$ for every $\varphi \in \mathcal{H}_0$, where $f_0 \in C^\infty(X)_R$ is the function defined by the conditions $\int_X f_0 \omega_0^n = 0$ and $R(\omega_0) - \omega_0 = \sqrt{-1}\partial\bar{\partial}f_0$. Since (4.2.3) is then obvious from (4.1.3), the proof is reduced to showing (4.2.2) for f_φ defined in (4.5). Fix an arbitrary $\varphi \in \mathcal{H}_0$, and we put $\psi_t := t\varphi - L(0, t\varphi)$, $t \in [0, 1]$. Note that $\{\psi_t | 0 \leq t \leq 1\}$ is a smooth path in \mathcal{H}_0 connecting 0 with φ . In view of (4.1.2), the proof is further reduced to showing

$$\frac{d}{dt}\mu(\psi_t) = -\frac{d}{dt}\int_X f_{\psi_t} V_0(\psi_t)$$

for every $t \in [0, 1]$. We can now finish the proof by the following

computation:

$$\begin{aligned}
 -\frac{d}{dt} \int_X f_{\psi_t} V_0(\psi_t) &= \int_X (\square_{\psi_t} + \nu) \dot{\psi}_t V_0(\psi_t) - \int_X f_{\psi_t} (\square_{\psi_t} \dot{\psi}_t) V_0(\psi_t) \\
 &= -\int_X f_{\psi_t} (\square_{\psi_t} \dot{\psi}_t) V_0(\psi_t) = -\int_X (\sigma(\psi_t) - \lambda) \dot{\psi}_t V_0(\psi_t) = \frac{d}{dt} \mu(\psi_t) .
 \end{aligned}$$

5. Futaki invariants as derivatives of the K-energy map. Let $\text{Aut}(X)$ be the group of holomorphic automorphisms of X , and let $\text{Aut}^0(X)$ be its identity component. For each holomorphic vector field $Y \in \Gamma(X, \mathcal{O}(T(X)))$ on X , we put

$$Y_R := Y + \bar{Y} ,$$

and we later consider the corresponding one-parameter group $y_t := \exp t Y_R$, ($t \in \mathbf{R}$). For each $\omega \in \mathcal{K}$, let $f_\omega \in C^\infty(X)_\mathbf{R}$ be the function defined in (4.5). Recall that

$$\sigma(\omega) - \lambda = \square_\omega f_\omega , \quad (\text{cf. (4.1.1)}) .$$

Then a fundamental theorem of Futaki [4] states the following:

(5.1) *For every $Y \in \Gamma(X, \mathcal{O}(T(X)))$, the real number $C_{Y,\omega} := \int_X (Y_R f_\omega) \omega^n / \int_X \omega^n$ does not depend on the choice of ω in \mathcal{K} but depends possibly on the Kähler class \mathcal{K} . (Therefore $C_{Y,\omega}$ will be denoted by $C_{Y,\mathcal{K}}$.)*

(5.2) *If there exists a $\tilde{\omega} \in \mathcal{K}$ such that $(X, \tilde{\omega})$ is a Kähler manifold of constant scalar curvature, then $C_{Y,\mathcal{K}} = 0$ for all $Y \in \Gamma(X, \mathcal{O}(T(X)))$.*

The main purpose of this section is to show that the first derivative of the K-energy map $\mu: \mathcal{K} \rightarrow \mathbf{R}$ along each orbit $\{y_t^* \omega \mid t \in \mathbf{R}\}$ of the one-parameter group $\{y_t\}_{t \in \mathbf{R}}$ is nothing but $C_{Y,\mathcal{K}}$. Using this fact, we shall give another proof for both (5.1) and (5.2). In a subsequent paper (cf. Bando and Mabuchi [1]), a thorough study of these properties will be given in a more general situation.

THEOREM (5.3). *Let Y be an arbitrary holomorphic vector field on X . Then for all $t \in \mathbf{R}$ and $\omega \in \mathcal{K}$*

$$\mu(y_t^* \omega) = \mu(\omega) + t C_{Y,\mathcal{K}} .$$

PROOF. For each $t \in \mathbf{R}$, there exists a unique function $\varphi_t \in \mathcal{H}_0$ such that $y_t^* \omega = \omega_0(\varphi_t)$. For simplicity, we write $y_t^* \omega$ and $f_{y_t^* \omega}$ as ω_t and f_t , respectively. We furthermore put $V := \int_X \omega_0^n / n!$. Note that

$$L_{Y_R}\omega_t = \frac{\partial}{\partial t}\omega_t = \sqrt{-1}\partial\bar{\partial}\dot{\varphi}_t.$$

Since $0 = \int_X L_{Y_R}(f_t\omega_t^n) = \int_X (Y_R f_t)\omega_t^n + n\sqrt{-1} \int_X f_t\omega_t^{n-1} \wedge \partial\bar{\partial}\dot{\varphi}_t$, we have, for every $t \in \mathbf{R}$,

$$\begin{aligned} C_{Y,\mathcal{X}} &= \int_X (Y_R f_t)\omega_t^n / (n! V) = -n\sqrt{-1} \int_X f_t\omega_t^{n-1} \wedge \partial\bar{\partial}\dot{\varphi}_t / (n! V) \\ &= \sqrt{-1} \int_X \partial f_t \wedge \bar{\partial}\dot{\varphi}_t \wedge \omega_t^{n-1} / ((n-1)! V) = (1/V)(\partial f_t, \bar{\partial}\dot{\varphi}_t)_{L^2(X,\omega_t)} \\ &= -(1/V)(\square_{\omega_t} f_t, \dot{\varphi}_t)_{L^2(X,\omega_t)} = - \int_X \dot{\varphi}_t(\sigma(\varphi_t) - \lambda) V_0(\varphi_t) \\ &= d\mu(\omega_t)/dt, \end{aligned}$$

from which the required equality immediately follows.

PROOF FOR (5.2) IN FUTAKI'S THEOREM WITH (5.1) TAKEN FOR GRANTED:
By Theorem (3.2), $\mu: \mathcal{X} \rightarrow \mathbf{R}$ has a critical point at $\tilde{\omega}$. Hence, for an arbitrary $Y \in H^0(X, \mathcal{O}(T(X)))$,

$$C_{Y,\mathcal{X}} = \frac{d}{dt}\mu(y_t^* \tilde{\omega})|_{t=0} = 0.$$

DEFINITION (5.4). To our Kähler class \mathcal{X} , we associate the closed subgroup $G_{\mathcal{X}}$ of $\text{Aut}(X)$ as follows:

$$G_{\mathcal{X}} := \{g \in \text{Aut}(X) \mid g^* \mathcal{X} = \mathcal{X}\} \quad (\supset \text{Aut}^0(X)).$$

LEMMA (5.4.1). If $g \in G_{\mathcal{X}}$, then $M(g^*\omega_1, g^*\omega_2) = M(\omega_1, \omega_2)$ for all $\omega_1, \omega_2 \in \mathcal{X}$.

PROOF. Let $\{\varphi_t \mid a \leq t \leq b\}$ be a smooth path in \mathcal{X} such that $\omega_1 = \omega_0(\varphi_a)$ and $\omega_2 = \omega_0(\varphi_b)$. Note that, by $g \in G_{\mathcal{X}}$, we can write $g^*\omega_0$ as $\omega_0(\psi_g)$ for some $\psi_g \in \mathcal{X}$. In view of the identities $g^*\omega_0(\varphi_t) = \omega_0(\psi_g + g^*\varphi_t)$ and $\sigma(g^*\omega_0(\varphi_t)) = g^*\sigma(\varphi_t)$, we obtain

$$\begin{aligned} M(g^*\omega_1, g^*\omega_2) &= - \int_a^b \left\{ \int_X g^*\dot{\varphi}_t(\sigma(g^*\omega_0(\varphi_t)) - \lambda) g^* V_0(\varphi_t) \right\} dt \\ &= - \int_a^b \left\{ \int_X \dot{\varphi}_t(\sigma(\varphi_t) - \lambda) V_0(\varphi_t) \right\} dt = M(\omega_1, \omega_2). \end{aligned}$$

DEFINITION (5.5). We define the mapping $m_{\mathcal{X}}: G_{\mathcal{X}} \rightarrow \mathbf{R}_+$ by

$$m_{\mathcal{X}}(g) := \exp(M(\omega, g^*\omega)), \quad (\omega \in \mathcal{X}),$$

where \mathbf{R}_+ denotes the multiplicative group of positive real numbers. Since M satisfies the 1-cocycle condition, Lemma (5.4.1) above assures

that $m_{\mathcal{X}}(g)$ is independent of the choice of ω . (This independence obviously gives us a very simple proof of (5.1).)

For $g_1, g_2 \in G_{\mathcal{X}}$ and $\omega \in \mathcal{K}$, we have

$$\begin{aligned} \log(m_{\mathcal{X}}(g_1 g_2)) &= M(\omega, (g_1 g_2)^* \omega) = M(\omega, g_1^* \omega) + M(g_1^* \omega, g_2^* g_1^* \omega) \\ &= \log(m_{\mathcal{X}}(g_1)) + \log(m_{\mathcal{X}}(g_2)), \quad \text{i.e.,} \quad m_{\mathcal{X}}(g_1 g_2) = m_{\mathcal{X}}(g_1) m_{\mathcal{X}}(g_2). \end{aligned}$$

Recall that the identity component of $G_{\mathcal{X}}$ is $\text{Aut}^0(X)$, and hence $H^0(X, \mathcal{O}(T(X)))$ is naturally regarded as the Lie algebra of $G_{\mathcal{X}}$. We can now interpret Theorem (5.3) as follows:

THEOREM (5.6). $m_{\mathcal{X}}: G_{\mathcal{X}} \rightarrow \mathbf{R}_+$ is a Lie group homomorphism. Moreover the corresponding Lie algebra homomorphism $(m_{\mathcal{X}})_*: H^0(X, \mathcal{O}(T(X))) \rightarrow \mathbf{R}$ is the “Futaki invariant” of \mathcal{K} , i.e., $(m_{\mathcal{X}})_*(Y) = C_{Y, \mathcal{X}}$ for all $Y \in H^0(X, \mathcal{O}(T(X)))$.

COROLLARY (5.6.1) (cf. Futaki [3; (2.2)]). $m_{\mathcal{X}}$ is trivial on $[G_{\mathcal{X}}, G_{\mathcal{X}}]$.

We conclude this section by showing the following group-theoretic analogue of (5.2).

THEOREM (5.7). (i) Suppose that the “Futaki invariant” of \mathcal{K} vanishes (i.e., $(m_{\mathcal{X}})_* = 0$). Then $m_{\mathcal{X}}$ is trivial, whenever $\pi_0(G_{\mathcal{X}}) := G_{\mathcal{X}}/\text{Aut}^0(X)$ is finite.

(ii) Assume that X is a Fano manifold (where it is not necessary to assume that ω_0 represents a specific class such as $2\pi c_1(X)_{\mathbf{R}}$). Suppose furthermore that there exists a Kähler form $\tilde{\omega} \in \mathcal{K}$ of constant scalar curvature. Then $m_{\mathcal{X}}$ is trivial.

PROOF. (i) Since $\pi_0(G_{\mathcal{X}})$ is finite, each $g \in G_{\mathcal{X}}$ satisfies $g^\alpha \in \text{Aut}^0(X)$ for some positive integer $\alpha = \alpha(g)$. On the other hand, $(m_{\mathcal{X}})_* = 0$ implies $\text{Aut}^0(X) \subset \text{Ker } m_{\mathcal{X}}$ by Theorem (5.6). We now have $m_{\mathcal{X}}(g)^\alpha = 1$, from which $m_{\mathcal{X}}(g) = 1$ immediately follows.

(ii) Since X is a Fano manifold, there exists an $r \in \mathbf{Z}$ ($r \gg 1$) such that the line bundle $K_{\bar{X}}^r$ is very ample. In particular, $\text{Aut}(X)$ is regarded as a closed (algebraic) subgroup of $\text{PGL}(N; \mathbf{C}) = \text{Aut}(\mathbf{P}(H^0(X, \mathcal{O}(K_{\bar{X}}^r))))$, where $N = h^0(X, \mathcal{O}(K_{\bar{X}}^r))$. Hence the subset $\pi_0(G_{\mathcal{X}})$ of the finite set $\pi_0(\text{Aut}(X))$ is also finite. Furthermore, by (5.2), we have $(m_{\mathcal{X}})_* = 0$. Applying (i) above, we conclude that $m_{\mathcal{X}}$ is trivial.

6. The second variation formula for K-energy maps. Throughout this section, for simplicity, we assume that X is a Fano manifold with a Kähler form $\omega_0 = \sqrt{-1} \sum g_{\alpha\bar{\beta}} dz^\alpha \wedge d\bar{z}^\beta$ representing $2\pi c_1(X)_{\mathbf{R}}$, (cf. §1). We furthermore fix a smooth path $\{\varphi_t \mid a \leq t \leq b\}$ in \mathcal{K} .

We denote by ∇^t the covariant derivative on the space of 1-forms of the Kähler manifold $(X, \omega_0(\varphi_t))$, and let A_t be the A -operator

$$A_t(\sum_{\alpha, \bar{\beta}} a_{\alpha \bar{\beta}} dz^\alpha \wedge d\bar{z}^{\bar{\beta}}) := \frac{1}{\sqrt{-1}} \sum_{\alpha, \bar{\beta}} g(\varphi_t)^{\bar{\beta} \alpha} a_{\alpha \bar{\beta}}$$

of $(X, \omega_0(\varphi_t))$. Let $f_{\varphi_t} \in C^\infty(X)_R$ be the function defined in (4.5), and denote this function simply by f_t . Then

$$\dot{f}_t = -(\square_{\varphi_t} + 1)\dot{\varphi}_t, \quad \text{and}$$

$$R(\varphi_t) - \omega_0(\varphi_t) = \sqrt{-1} \partial \bar{\partial} f_t, \quad \text{i.e.,} \quad \sigma(\varphi_t) - n = \square_{\varphi_t} f_t,$$

for every $t \in [a, b]$, (cf. (4.2)). We shall first prove:

LEMMA (6.1). *Let $Y (= \sum_{\alpha} y^\alpha \partial / \partial z^\alpha)$ be an arbitrary complex valued global C^∞ -vector field of type $(1, 0)$ on X . Then for every $\psi \in C^\infty(X)_R$,*

$$(6.1.1) \quad \sqrt{-1} A_t \bar{\partial} \{ -(Yf_t) \partial \psi + \nabla_Y^t \partial \psi \} + \sqrt{-1} A_t \{ (\bar{\partial} Y)(f_t) \wedge \partial \psi - \nabla_{\bar{\partial} Y}^t \partial \psi \} \\ = Y(-\square_{\varphi_t} \psi - \psi) + (Yf_t) \square_{\varphi_t} \psi,$$

where $(\bar{\partial} Y)(f_t) := \sum_{\alpha, \bar{\beta}} y_{\bar{\beta}}^\alpha (f_t)_\alpha d\bar{z}^{\bar{\beta}}$ and $\nabla_{\bar{\partial} Y}^t \partial \psi := \sum_{\alpha, \bar{\beta}} (y_{\bar{\beta}}^\alpha dz^{\bar{\beta}} \wedge \nabla_{\partial / \partial z^\alpha}^t \partial \psi)$. (We use such notation $y_{\bar{\beta}}^\alpha = \partial y^\alpha / \partial \bar{z}^{\bar{\beta}}$, $(f_t)_\alpha := \partial f_t / \partial z^\alpha, \dots$ as explained in (1.3).)

PROOF. Fix an arbitrary pair $(t, p) \in R \times X$. We then choose a system $z = (z^1, z^2, \dots, z^n)$ of holomorphic local coordinates of X centered at p such that

$$g(\varphi_t)_{\alpha \bar{\beta}}(p) = \delta_{\alpha \bar{\beta}} \quad \text{and} \quad d(g(\varphi_t)_{\alpha \bar{\beta}})(p) = 0$$

for all α and β . Since there is no fear of confusion, the following $g(\varphi_t)_{\alpha \bar{\beta}}$, $g(\varphi_t)^{\bar{\beta} \alpha}$, $R(\varphi_t)_{\alpha \bar{\beta}}$, f_t , ∇^t , A_t , \square_{φ_t} will be denoted simply by $G_{\alpha \bar{\beta}}$, $G^{\bar{\beta} \alpha}$, $R_{\alpha \bar{\beta}}$, f , ∇ , A , \square , respectively. Then at the point $(t, p) \in R \times X$,

$$(6.1.2) \quad \sqrt{-1} A \bar{\partial} \{ -(Yf) \partial \psi + \nabla_Y \partial \psi \} \\ = \sum_{\alpha, \bar{\beta}} (y_{\bar{\beta}}^\alpha f_\alpha \psi_\beta + y^\alpha f_{\alpha \bar{\beta}} \psi_\beta + y^\alpha f_\alpha \psi_{\bar{\beta} \bar{\beta}}) \\ + \sum_{\alpha, \bar{\beta}} \{ -y_{\bar{\beta}}^\alpha \psi_{\beta \alpha} - y^\alpha \psi_{\beta \alpha \bar{\beta}} + y^\alpha \sum_{\delta} \psi_\delta (\partial^2 G_{\bar{\beta} \delta} / \partial z^\alpha \partial \bar{z}^{\bar{\beta}}) \} \\ = \sum_{\alpha, \bar{\beta}} \{ y_{\bar{\beta}}^\alpha f_\alpha \psi_\beta + y^\alpha (R_{\alpha \bar{\beta}} - \delta_{\alpha \bar{\beta}}) \psi_\beta \} + (Yf) \square \psi \\ + \sum_{\alpha, \bar{\beta}} (-y_{\bar{\beta}}^\alpha \psi_{\beta \alpha} - y^\alpha \psi_{\bar{\beta} \bar{\beta} \alpha}) - \sum_{\alpha, \bar{\beta}} y^\alpha R_{\alpha \bar{\beta}} \psi_\beta \\ = \sum_{\alpha, \bar{\beta}} (y_{\bar{\beta}}^\alpha f_\alpha \psi_\beta - y_{\bar{\beta}}^\alpha \psi_{\beta \alpha}) + Y(-\psi - \square \psi) + (Yf) \square \psi.$$

On the other hand, at the same point (t, p) ,

$$(6.1.3) \quad \sqrt{-1} A \{ (\bar{\partial} Y)(f) \wedge \partial \psi - \nabla_{\bar{\partial} Y} \partial \psi \} = -\sum_{\alpha, \bar{\beta}} (y_{\bar{\beta}}^\alpha f_\alpha \psi_\beta - y_{\bar{\beta}}^\alpha \psi_{\beta \alpha}).$$

Adding up (6.1.2) and (6.1.3), we obtain (6.1.1).

THEOREM (6.2). (Second variation formula). *For every $t \in [a, b]$, we have*

$$(6.2.1) \quad \frac{d^2}{dt^2} \mu(\varphi_t) = \frac{1}{V} \|\bar{\partial} Y_t\|_{L^2(X, \omega_0(\varphi_t))}^2 - \int_X \{ \ddot{\varphi}_t - \sum_{\alpha, \beta} g(\varphi_t)^{\bar{\beta}\alpha}(\dot{\varphi}_t)_\alpha(\dot{\varphi}_t)_{\bar{\beta}} \} (\sigma(\varphi_t) - n) V_0(\varphi_t),$$

where

$$V := \int_X \omega_0^n / n! \quad \text{and} \quad Y_t := \sum_{\alpha, \beta} g(\varphi_t)^{\bar{\beta}\alpha}(\dot{\varphi}_t)_{\bar{\beta}} \partial / \partial z^\alpha.$$

PROOF. We integrate, on X , the equality (6.1.1) applied to $(\psi, Y) = (\dot{\varphi}_t, Y_t)$. Then by $\int_X \sqrt{-1} A_t \bar{\partial} \{ \dots \} V_0(\varphi_t) = 0$, we obtain

$$(6.2.2) \quad \int_X \sqrt{-1} A_t \{ (\bar{\partial} Y_t)(f_t) \wedge \partial \dot{\varphi}_t - \nabla_{\dot{\varphi}_t}^t \partial \dot{\varphi}_t \} V_0(\varphi_t) = \int_X Y_t (-\square_{\varphi_t} \dot{\varphi}_t - \dot{\varphi}_t) V_0(\varphi_t) + \int_X (Y_t f_t) (\square_{\varphi_t} \dot{\varphi}_t) V_0(\varphi_t).$$

On the other hand,

$$(6.2.3) \quad \begin{aligned} \frac{d^2}{dt^2} \mu(\varphi_t) &= \frac{d}{dt} \int_X -\dot{\varphi}_t (\square_{\varphi_t} f_t) V_0(\varphi_t) \\ &= \frac{d}{dt} \{ (1/V) (\bar{\partial} \dot{\varphi}_t, \bar{\partial} f_t)_{L^2(X, \omega_0(\varphi_t))} \} \\ &= \int_X \frac{\partial}{\partial t} \{ \sum_{\alpha, \beta} g(\varphi_t)^{\bar{\beta}\alpha}(\dot{\varphi}_t)_{\bar{\beta}}(f_t)_\alpha V_0(\varphi_t) \} \\ &= - \int_X \sum_{\alpha, \beta, \gamma, \delta} g(\varphi_t)^{\bar{\beta}\gamma}(\dot{\varphi}_t)_{\bar{\gamma}} \bar{g}(\varphi_t)^{\bar{\delta}\alpha}(\dot{\varphi}_t)_{\bar{\delta}}(f_t)_\alpha V_0(\varphi_t) \\ &\quad + \int_X \sum_{\alpha, \beta} g(\varphi_t)^{\bar{\beta}\alpha}(\ddot{\varphi}_t)_{\bar{\beta}}(f_t)_\alpha V_0(\varphi_t) \\ &\quad + \int_X Y_t(\dot{f}_t) V_0(\varphi_t) + \int_X (Y_t f_t) (\square_{\varphi_t} \dot{\varphi}_t) V_0(\varphi_t). \end{aligned}$$

Since $\dot{f}_t = -(\square_{\varphi_t} + 1)\dot{\varphi}_t$, the right-hand side of (6.2.2) coincides with the sum of the last two integrals of (6.2.3). Hence

$$(6.2.4) \quad \begin{aligned} \frac{d^2}{dt^2} \mu(\varphi_t) &= - \int_X \sum_{\alpha, \beta, \gamma, \delta} g(\varphi_t)^{\bar{\beta}\gamma}(\dot{\varphi}_t)_{\bar{\gamma}} \bar{g}(\varphi_t)^{\bar{\delta}\alpha}(\dot{\varphi}_t)_{\bar{\delta}}(f_t)_\alpha V_0(\varphi_t) \\ &\quad + \int_X \sum_{\alpha, \beta} g(\varphi_t)^{\bar{\beta}\alpha}(\ddot{\varphi}_t)_{\bar{\beta}}(f_t)_\alpha V_0(\varphi_t) \end{aligned}$$

$$+ \int_X \sqrt{-1} \Lambda_t \{ (\bar{\partial} Y_t)(f_t) \wedge \partial \dot{\varphi}_t - \nabla_{\bar{\partial} Y_t}^t \partial \dot{\varphi}_t \} V_0(\varphi_t) .$$

Note the following identities:

$$(6.2.5) \quad 0 = \int_X -\sqrt{-1} \Lambda_t \bar{\partial} \left(\sum_{\alpha, \beta} g(\varphi_t)^{\bar{\beta}\alpha} (\dot{\varphi}_t)_{\bar{\beta}} (\dot{\varphi}_t)_{\alpha} \partial f_t \right) V_0(\varphi_t) ;$$

$$(6.2.6) \quad \int_X \sum_{\alpha, \beta} g(\varphi_t)^{\bar{\beta}\alpha} (\ddot{\varphi}_t)_{\bar{\beta}} (f_t)_{\alpha} V_0(\varphi_t) = (1/V) (\bar{\partial} \ddot{\varphi}_t, \partial f_t)_{L^2(X, \omega_0(\varphi_t))} \\ = (1/V) (\ddot{\varphi}_t, -\square_{\varphi_t} f_t)_{L^2(X, \omega_0(\varphi_t))} = -\int_X \ddot{\varphi}_t (\sigma(\varphi_t) - n) V_0(\varphi_t) .$$

Adding up (6.2.4), (6.2.5) and (6.2.6), we obtain

$$\frac{d^2}{dt^2} \mu(\varphi_t) = \int_X h V_0(\varphi_t) ,$$

where $h = h(t, x) \in C^\infty([a, b] \times X)$ is the function defined by

$$h := - \sum_{\alpha, \beta, \gamma, \delta} \{ g(\varphi_t)^{\bar{\beta}\gamma} (\dot{\varphi}_t)_{\bar{\beta}} \bar{\gamma} g(\varphi_t)^{\bar{\delta}\alpha} (\dot{\varphi}_t)_{\bar{\delta}} (f_t)_{\alpha} \} - \ddot{\varphi}_t (\sigma(\varphi_t) - n) \\ + \sqrt{-1} \Lambda_t \{ (\bar{\partial} Y_t)(f_t) \wedge \partial \dot{\varphi}_t - \nabla_{\bar{\partial} Y_t}^t \partial \dot{\varphi}_t - \bar{\partial} \left(\sum_{\alpha, \beta} g(\varphi_t)^{\bar{\beta}\alpha} (\dot{\varphi}_t)_{\bar{\beta}} (\dot{\varphi}_t)_{\alpha} \partial f_t \right) \} .$$

On the other hand, writing Y_t as $\sum_{\alpha} y^\alpha \partial / \partial z^\alpha$ (in which we put $y^\alpha := \sum_{\beta} g(\varphi_t)^{\bar{\beta}\alpha} (\dot{\varphi}_t)_{\bar{\beta}}$), we have

$$\text{(Right-hand side of (6.2.1))} = \int_X k V_0(\varphi_t) ,$$

where $k = k(t, x) \in C^\infty([a, b] \times X)$ is the function defined by

$$k := \{ \sum g(\varphi_t)_{\alpha \bar{\beta}} g(\varphi_t)_{\bar{\gamma} \delta} (y^\alpha)_{\bar{\gamma}} (\bar{y}^\beta)_{\delta} \} - (\ddot{\varphi}_t - \sum g(\varphi_t)^{\bar{\beta}\alpha} (\dot{\varphi}_t)_{\alpha} (\dot{\varphi}_t)_{\bar{\beta}}) (\sigma(\varphi_t) - n) .$$

We fix an arbitrary pair $(t, p) \in [a, b] \times X$ and choose a system (z^1, z^2, \dots, z^n) of holomorphic local coordinates of X centered at p such that

$$g(\varphi_t)_{\alpha \bar{\beta}}(p) = \delta_{\alpha\beta} \quad \text{and} \quad d(g(\varphi_t)_{\alpha \bar{\beta}})(p) = 0$$

for all α and β . Then at the point $(t, p) \in [a, b] \times X$,

$$h = \{ \sum_{\alpha, \bar{\gamma}} (\dot{\varphi}_t)_{\bar{\gamma} \alpha} (\dot{\varphi}_t)_{\bar{\gamma} \alpha} \} - \ddot{\varphi}_t (\sigma(\varphi_t) - n) + \sum_{\alpha, \bar{\gamma}} (\dot{\varphi}_t)_{\alpha} (\dot{\varphi}_t)_{\bar{\gamma} \alpha} \bar{\alpha} f_{\bar{\gamma} \bar{\gamma}} \\ = \{ \sum_{\alpha, \bar{\gamma}} (\dot{\varphi}_t)_{\bar{\gamma} \alpha} (\dot{\varphi}_t)_{\bar{\gamma} \alpha} \} - (\ddot{\varphi}_t - \sum_{\alpha} (\dot{\varphi}_t)_{\alpha} (\dot{\varphi}_t)_{\bar{\alpha}}) (\sigma(\varphi_t) - n) = k$$

as required.

COROLLARY (6.3). *If ω is a critical point of $\mu: \mathcal{K} \rightarrow \mathbf{R}$, then the inequality*

$$\frac{d^2}{dt^2} \mu(\theta_t) |_{t=0} \geq 0$$

holds for every smooth path $\{\theta_t \mid -\varepsilon \leq t \leq \varepsilon\}$ in \mathcal{K} such that $\theta_0 = \omega$.

REMARK (6.4). Another interpretation for (6.2.1) will be given in a forthcoming paper [7].

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Note added in proof. The author recently received a preprint: A. Futaki, On a character of the automorphism group of a compact complex manifold (to appear in Invent. Math.), which gives a very explicit formula for the Lie group homomorphism in Theorem (5.6) under the assumption that \mathcal{K} is the Kähler class in $2\pi c_1(X)_R$.

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