

NOTE ON (ϕ, ξ, η) -STRUCTURE

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Prof. Sasaki has recently investigated a structure called (ϕ, ξ, η) -structure [1]²⁾ which is closely related to the almost contact structure studied by W. Gray and W. M. Boothby-H. C. Wang, and may also be considered as an analogue of almost complex structure for odd dimensional manifolds.

Let M^{2n+1} be a $(2n + 1)$ -dimensional differentiable manifold of class C^∞ . M^{2n+1} is said to have a (ϕ, ξ, η) -structure if there exists a tensor field ϕ_j^i , a contravariant vector field ξ^i and a covariant vector field η_j (each is of class C^∞) over M^{2n+1} such that the following conditions are satisfied:

$$(0.1) \quad \xi^i \eta_i = 1, \quad (i, j, k = 1, 2, \dots, 2n + 1)$$

$$(0.2) \quad \text{rank } |\phi_j^i| = 2n,$$

$$(0.3) \quad \phi_j^i \xi^j = 0,$$

$$(0.4) \quad \phi_j^i \eta_i = 0,$$

$$(0.5) \quad \phi_j^i \phi_k^j = -\delta_k^i + \xi^i \eta_k.$$

In this note we intend to show that starting from a differentiable manifold M^{2n+1} having (ϕ, ξ, η) -structure one can construct by a natural way a manifold with 3π -structure [2] in the sense of the present author, and by applying the theory of 3π -structure we can obtain a tensor analogous to the Nijenhuis tensor in the case of almost complex structure. Moreover, canonic connections for the considered structure are also obtained by the use of the results of π -structure.

1. Associated 3π -structure. From (0.2) and (0.3) it is evident that ξ^i is a proper vector corresponding to the proper value 0 of ϕ_j^i and the proper subspace of the proper value 0 is spanned only by ξ^i .

Let v^j be any proper vector corresponding to a non-zero proper value λ of ϕ_j^i , then

$$(1.1) \quad \phi_j^i v^j = \lambda v^i.$$

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2) Number in bracket refers to the reference at the end of paper.

Multiply η_i and sum with respect to i , we have

$$(1.2) \quad \phi_j^i \eta_i v^j = \lambda v^i \eta_i.$$

By (0.4) we get $\lambda v^i \eta_i = 0$, therefore

$$(1.3) \quad v^i \eta_i = 0.$$

If we contract (1.1) with ϕ_i^k we have

$$\phi_i^k \phi_j^i v^j = \lambda \phi_i^k v^i.$$

From this we have by (0.5) and (1.1)

$$(-\delta_j^k + \xi^k \eta_j) v^j = \lambda^2 v^k.$$

which gives by (1.3)

$$\lambda^2 v^k = -v^k \text{ and } \lambda^2 = -1.$$

Thus the only non-zero proper values of ϕ_j^i are i and $-i$. As ϕ_j^i is real, it follows that each of the proper values has the multiplicity n , and the corresponding proper subspace T_P and S_P of the tangent space M_P at point P of M^{2n+1} are both of dimension n . So, over the differentiable manifold M^{2n+1} we have three distributions X, T and S which assign each point P of M^{2n+1} three subspaces X_P, T_P, S_P of the complexification M_P^c of the tangent space M_P . Moreover, $M_P^c = X_P^c + T_P + S_P$ (direct sum) for every point P of M^{2n+1} . Thus the differentiable manifold M^{2n+1} is endowed with a $3\text{-}\pi$ -structure defined by three distributions X, T and S .

Let v^j be any vector field contained in the distribution $T + S$, then by (0.1) and (1.3) we have

$$(1.4) \quad (\xi^i \eta_j) \xi^j = \xi^i \text{ and } (\xi^i \eta_j) v^j = 0.$$

So, $\xi^i \eta_j$ is the projection tensor field for the distribution X .

Let p_j^i and q_j^i be respectively the projection tensor field for the distributions T and S . Then if v_+^i and v_-^i are respectively contained in T and S , we have

$$(1.5) \quad \left\{ \begin{array}{l} p_j^i v_+^j = v_+^i, \quad p_j^i v_-^j = 0; \\ q_j^i v_+^j = 0, \quad q_j^i v_-^j = v_-^i; \\ p_j^i \xi^j = q_j^i \xi^j = 0. \end{array} \right.$$

Since, by definition

$$(1.6) \quad \left\{ \begin{array}{l} \phi_j^i v_+^j = i v_+^i, \quad \phi_j^i v_-^j = -i v_-^i, \\ \phi_j^i \xi^j = 0, \end{array} \right.$$

we have

$$(1.7) \quad \phi_j^i = i p_j^i - i q_j^i,$$

because both sides of the latter formula have the same effect for all vectors of the tangent space at every point of M^{2n+1} .

As M_P^c is the direct sum of X_P^c , T_P and S_P , we also have

$$(1.8) \quad \xi^i \eta_j + p_j^i + q_j^i = \delta_j^i.$$

Now we start to consider the inverse implication: Assume that we have a $(2n + 1)$ -dimensional differentiable manifold M^{2n+1} endowed with a $3\text{-}\pi$ -structure defined by the complete system [2] consists of three distributions X , T and S , of which the first one is a one dimensional real distribution and the latter two are n -dimensional conjugate complex distributions which together span the complexification of a $2n$ -dimensional real distribution. If ξ^i , v_+^i , v_-^i ($\alpha = 1, \dots, n$) respectively span X , T and S , then there exists a covariant vector field η_i such that

$$(1.9) \quad \left\{ \begin{array}{l} \eta_i v_+^i = 0, \quad \eta_i v_-^i = 0, \quad (\alpha = 1, \dots, n) \\ \xi^i \eta_i = 1. \end{array} \right.$$

Then it is evident that $\xi^i \eta_j$ is the projection tensor field for the distribution X . Let p_j^i and q_j^i be respectively the projection tensor field for T and S , then (1.5) holds for any vector field v_+^i and v_-^i contained respectively in T and S . It is also evident that (1.8) and the following relation hold:

$$(1.10) \quad \bar{p}_j^i = q_j^i.$$

Next, define ϕ_j^i by (1.7), then we have by (1.5)₃ that

$$(0.3) \quad \phi_j^i \xi^j = 0.$$

Moreover, by (1.5)₁ and (1.9)₁ we have

$$\eta_i p_j^i v_+^j = v_+^i \eta_i = 0.$$

Similarly, from (1.5)₁ and (0.3), we have

$$\eta_i p_j^i v_-^j = 0 \text{ and } \eta_i p_j^i \xi^j = 0.$$

So $\eta_i p_j^i u^j = 0$ holds for any vector u^j of the tangent space. Thus we have

$$(1.11) \quad \eta_i p_j^i = 0, \text{ and similarly, } \eta_i q_j^i = 0.$$

Consequently, we have (1.7)

$$(0.4) \quad \phi_j^i \eta_i = 0.$$

From (1.7) and (1.8) we have moreover

$$(0.5) \quad \begin{aligned} \phi_j^i \phi_k^j &= (ip_j^i - iq_j^i)(ip_k^j - iq_k^j) \\ &= -(p_k^i + q_k^i) = -\delta_k^i + \xi^i \eta_k. \end{aligned}$$

From (1.10) it follows that ϕ_j^i is real. And, from (1.7) and (1.5) it follows that ϕ_j^i satisfies (1.6), so the rank of $|\phi_j^i|$ is $2n$.

Thus we have the following:

THEOREM 1.1. *A necessary and sufficient condition for a $(2n+1)$ -dimensional manifold M^{2n+1} to have a (ϕ, ξ, η) -structure is that the manifold be endowed with a 3π -structure defined by a complete system consists of three distributions X, T and S , of which the first one is a one dimensional real distribution, and the latter two are n -dimensional conjugate complex distributions which together span the complexification of a $2n$ -dimensional real distribution.*

2. Fundamental tensors and torsion tensors. From (1.7) and (1.8) we have

$$(2.1) \quad \begin{cases} p_j^i = \frac{1}{2} (\delta_j^i - \xi^i \eta_j - i\phi_j^i), \\ q_j^i = \frac{1}{2} (\delta_j^i - \xi^i \eta_j + i\phi_j^i), \end{cases}$$

so p_j^i and q_j^i are conjugate complex to each other.

Now the fundamental tensor for the associated 3π -structure is defined as follows:

$$(2.2) \quad F_j^i = \lambda(\xi^i \eta_j + \omega_1^2 p_j^i + \omega_1 q_j^i),$$

where ω_1 is a cubic root ($\neq 1$) of unity and λ is any non-zero complex number. Substitute (2.1) in (2.2) we have

$$(2.3) \quad \overset{1}{F}_j^i \equiv F_j^i = \frac{\lambda}{2} \{-\delta_j^i + 3\xi^i \eta_j + i\omega_1(1 - \omega_1)\phi_j^i\}.$$

From which it follows that

$$(2.4) \quad \overset{2}{F}_k^i \equiv F_j^i F_k^j = \frac{\lambda^2}{2} \{-\delta_k^i + 3\xi^i \eta_k - i\omega_1(1 - \omega_1)\phi_k^i\},$$

and

$$(2.5) \quad \overset{3}{F}_l^i \equiv F_j^i F_k^j F_l^k = \lambda^3 \delta_l^i.$$

We also can associate M^{2n+1} with three kinds of 2π -structure as follows:

$$(2.6) \quad \overset{1}{F}_j^i = \lambda_1 \{\xi^i \eta_j - (p_j^i + q_j^i)\},$$

$$(2.7) \quad \overset{2}{F}_j^i = \lambda_2 \{(\xi^i \eta_j + p_j^i) - q_j^i\},$$

$$(2.8) \quad \overset{3}{F}_j^i = \lambda_3 \{(\xi^i \eta_j + q_j^i) - p_j^i\}.$$

These three tensor fields satisfy the following relations:

$$(2.9) \quad F_1^i F_k^j = \lambda_1^2 \delta_k^i, \quad F_2^i F_k^j = \lambda_2^2 \delta_k^i, \quad F_3^i F_k^j = \lambda_3^2 \delta_k^i.$$

$$(2.10) \quad \left\{ \begin{aligned} F_1^i F_k^j = F_2^i F_k^j = \frac{\lambda_1 \lambda_2}{\lambda_3} F_3^i, \quad F_2^i F_k^j = F_3^i F_k^j = \frac{\lambda_2 \lambda_3}{\lambda_1} F_1^i, \\ F_3^i F_k^j = F_1^i F_k^j = \frac{\lambda_1 \lambda_3}{\lambda_2} F_2^i. \end{aligned} \right.$$

Substitute (2.1) in (2.6), (2.7) and (2.8) we have

$$(2.11) \quad \left\{ \begin{aligned} F_1^i &= \lambda_1(2\xi^i \eta_j - \delta_j^i), \\ F_2^i &= \lambda_2(\xi^i \eta_j - i\phi_j^i), \\ F_3^i &= \lambda_3(\xi^i \eta_j + i\phi_j^i). \end{aligned} \right.$$

It is known that the torsion tensor (analogue of the Nijenhuis tensor) for a 2π -structure is as follows [2].

$$(2.12) \quad t_a^i = -\frac{1}{4\lambda_a^2} (\delta_j^p F_a^q + \delta_k^q F_j^p)(\partial_p F_a^i - \partial_q F_p^i), \quad (a = 1, 2, 3).$$

Thus for respective case of (2.11) we have

$$(2.13) \quad t_1^i = -\xi^i(-N_j \eta_k + N_k \eta_j + \eta_{j,k} - \eta_{k,j}),$$

$$(2.14) \quad \left\{ \begin{aligned} t_2^i &= -\frac{1}{4} P_{jk}^i - \frac{1}{4} iQ_{jk}^i, \\ t_3^i &= -\frac{1}{4} P_{jk}^i + \frac{1}{4} iQ_{jk}^i, \end{aligned} \right.$$

in which

$$(2.15) \quad \left\{ \begin{aligned} P_{jk}^i &= N_{jk}^i - t_{jk}^i - \xi^i(\eta_{j,k} - \eta_{k,j}), \\ Q_{jk}^i &= -N_j^i \eta_k + N_k^i \eta_j + \xi^i N_{jk}, \end{aligned} \right.$$

where $\eta_{j,k} \equiv \frac{\partial \eta_j}{\partial x^k} \equiv \partial_k \eta_j$, and the $N_{jk}^i, N_{jk}, N_j^i, N_j$ are tensors obtained by

Sasaki and Hatakeyama [3] and defined as follows:

$$(2.16) \quad \left\{ \begin{aligned} N_{jk}^i &= \phi_k^q(\phi_{j,q}^i - \phi_{q,j}^i) - \phi_j^p(\phi_{k,p}^i - \phi_{p,k}^i) - \eta_j \xi^i + \eta_k \xi^i, \\ N_{jk} &= \phi_k^q(\eta_{q,j} - \eta_{j,q}) - \phi_j^p(\eta_{p,k} - \eta_{k,p}), \\ N_j^i &= \xi^q(\phi_{j,q}^i - \phi_{q,j}^i) - \phi_j^q \xi^i, \\ N_j &= \xi^p(\eta_{j,p} - \eta_{p,j}). \end{aligned} \right.$$

For the torsion tensor of a 3π -structure we have [2]:

$$(2.17) \quad t_{jk}^i = \frac{1}{9\lambda^3} \left[\left\{ -2(\delta_j^p F_k^q + \delta_k^q F_j^p) + \frac{1}{\lambda^3} F_j^p F_k^q \right\} (\partial_p F_q^i - \partial_q F_p^i) \right]$$

$$+ \{-2(\delta_j^p F_k^q + \delta_k^q F_j^p) + F_j^p F_k^q\}(\partial_p F_q^i - \partial_q F_p^i).$$

Substituting (2.3) and (2.4), we have the following expression after some straightforward calculations:

$$(2.18) \quad t_{jk}^i = \frac{1}{4} \{-N_{jk}^i - 3\xi^i(\eta_{j,k} - \eta_{k,j}) + 2\xi^i(N_j \eta_k - N_k \eta_j) + \xi^i \phi_j^p \phi_k^q (\eta_{i,p} - \eta_{p,q}) - N_p^i (\phi_j^p \eta_k - \phi_k^p \eta_j)\}.$$

3. (ϕ, ξ, η) -connections. It is known [2] that if γ_{jk}^i is any linear connection of the manifold, and we define a connection l_{jk}^i by

$$(3.1) \quad l_{jk}^i = \gamma_{jk}^i + T_{jk}^i$$

with

$$(3.2) \quad T_{jk}^i = \frac{1}{3} \frac{1}{\lambda^3} \{(\nabla_k F_j^l) F_l^i + (\nabla_k F_j^l) F_l^i\},$$

where ∇ denotes the covariant derivative with respect to γ_{jk}^i , then l_{jk}^i is a π -connection of the differentiable manifold with a 3π -structure whose fundamental tensor is given by (2.3), that is, l_{jk}^i is a connection which leaves the fundamental tensor F_j^i covariant constant. Therefore F_j^i and $F_j^i = \lambda^3 \delta_j^i$ are also left covariant constant. Consequently l_{jk}^i leaves also $\xi^i \eta_j$ and ϕ_j^i covariant constant, i.e.,

$$(3.3) \quad \begin{cases} (\xi^i \eta_j)_{;k} = \xi^i_{;k} \eta_j + \xi^i \eta_{j;k} = 0, \\ \phi_{j;k}^i = 0, \end{cases}$$

as $\xi^i \eta_j$ and ϕ_j^i can respectively be expressed as linear combination of F_j^i , F_j^i and δ_j^i by (2.3) and (2.4). In (3.3); denotes the covariant derivative with respect to the π -connection l_{jk}^i induced by γ_{jk}^i .

If we substitute (2.3) and (2.4) into (3.2) we have

$$(3.4) \quad T_{jk}^i = \frac{1}{2} \{- (\nabla_k \xi^i) \eta_j + 3\xi^i \eta_l (\nabla_k \xi^l) \eta_j + 2\xi^i (\nabla_k \eta_j) - (\nabla_k \phi_j^l) \phi_l^i\}.$$

Now by simple calculation, we have

$$(3.5) \quad \xi^i_{;k} = \nabla_k \xi^i + T_{jk}^i \xi^j = \xi^i \eta_l (\nabla_k \xi^l).$$

Since Ishihara and Obata [4] have shown that there is a symmetric affine connection which leaves ξ^i covariant constant, if we take γ_{jk}^i in (3.1) as such a connection $\tilde{\gamma}_{jk}^i$, then it follows from (3.5) that the induced π -connection leaves ξ^i covariant constant, and consequently also leaves η_j covariant constant by

(3.3)₁. Thus if we define connection $\overset{\circ}{l}_{jk}{}^i$ by

$$(3.6) \quad \overset{\circ}{l}_{jk}{}^i = \overset{\circ}{\gamma}_{jk}{}^i + \overset{\circ}{T}_{jk}{}^i$$

with

$$(3.7) \quad \overset{\circ}{T}_{jk}{}^i = \frac{1}{2} \{2\xi^i(\overset{\circ}{\nabla}_k\eta_j) - (\overset{\circ}{\nabla}_k\phi_j^i)\phi_l^i\},$$

where $\overset{\circ}{\nabla}$ denotes the covariant derivative with respect to $\overset{\circ}{\gamma}_{jk}{}^i$, then it leaves ϕ_j^i , ξ^i and η_j covariant, that is, $\overset{\circ}{l}_{jk}{}^i$ is a (ϕ, ξ, η) -connection in the sense of Sasaki and Hatakeyama. Thus we have

THEOREM 3.1. *On a manifold with a (ϕ, ξ, η) -structure we can find an affine (ϕ, ξ, η) -connection.*

By the way we note that the torsion tensor of the connection $\overset{\circ}{l}_{jk}{}^i$ is as follows.

$$(3.8) \quad \begin{aligned} \overset{\circ}{S}_{jk}{}^i &= \frac{1}{2} (\overset{\circ}{T}_{jk}{}^i - \overset{\circ}{T}_{kj}{}^i) \\ &= \frac{1}{2} \left[\{\xi^i(\overset{\circ}{\nabla}_k\eta_j) - \xi^i(\overset{\circ}{\nabla}_j\eta_k)\} - \frac{1}{2} \{(\overset{\circ}{\nabla}_k\phi_j^i)\phi_l^i - (\overset{\circ}{\nabla}_j\phi_k^i)\phi_l^i\} \right]. \end{aligned}$$

Moreover, it is also known that $l_{jk}{}^i$ is a π -connection if and only if it can be expressed as

$$(3.9) \quad \left\{ \begin{aligned} l_{jk}{}^i &= \overset{\circ}{l}_{jk}{}^i + U_{jk}{}^i, \text{ where} \\ U_{jk}{}^i &= \frac{1}{3} \{ \sigma_{jk}{}^i + \frac{1}{\lambda^3} (F_j^d \sigma_{dk}{}^c F_c^i + F_j^d \sigma_{dk}{}^c F_c^j) \} \end{aligned} \right.$$

with some tensor $\sigma_{jk}{}^i$.

Let $\xi_{|k}^i$ and $\xi_{;k}^i$ be respectively the covariant derivative of ξ^i with respect to $l_{jk}{}^i$ and $\overset{\circ}{l}_{jk}{}^i$, then

$$(3.10) \quad \xi_{|k}^i = \xi_{;k}^i + U_{jk}{}^i \xi^j.$$

So the condition for $l_{jk}{}^i$ in (3.9) to be a (ϕ, ξ, η) -connection is that $U_{jk}{}^i \xi^j = 0$. Substitute (3.9), (2.3) and (2.4) into this relation we have the following condition after some simple calculation:

$$(3.11) \quad \xi^j \sigma_{jk}{}^i \eta_i = 0.$$

Thus we have

THEOREM 3.2. *A connection $l_{jk}{}^i$ is a (ϕ, ξ, η) -connection if and only if it can be expressed as (3.9) with some tensor $\sigma_{jk}{}^i$ satisfying (3.11).*

4. Symmetric (ϕ, ξ, η) -connections. As $\overset{\circ}{l}_{jk}{}^i$ in (3.6) is a π -connection

induced by a symmetric connection, it follows from the general theory of π -structure [2] that the connection defined by

$$(4.1) \quad \hat{l}_{jk}{}^t = \overset{\circ}{l}_{jk}{}^t - \frac{2}{3} \{ \overset{\circ}{S}_{jk}{}^t + \frac{1}{\lambda^3} (F_j^a \overset{\circ}{S}_{ak}{}^c F_c^t + F_j^a \overset{\circ}{S}_{ak}{}^c F_c^t) \}$$

is a distinguished π -connection, that is a π -connection having the torsion tensor $t_{jk}{}^t$ in (2.18) of the considered 3- π -structure as its torsion tensor. In (4.1), $\overset{\circ}{S}_{jk}{}^t$ is the torsion tensor of the connection $\overset{\circ}{l}_{jk}{}^t$ and can be expressed as in (3.8).

On the other hand, since $\overset{\circ}{l}_{jk}{}^t$ is a (ϕ, ξ, η) -connection, we see by Theorem 3.2 that $\hat{l}_{jk}{}^t$ is also a (ϕ, ξ, η) -connection if and only if the following condition is satisfied:

$$(4.2) \quad 2\xi^j \overset{\circ}{S}_{jk}{}^t \eta_t = 0.$$

Substitute from (3.8), we have

$$(4.3) \quad \xi^j \{ (\overset{\circ}{\nabla}_k \eta_j) - (\overset{\circ}{\nabla}_j \eta_k) \} = 0.$$

Since $\overset{\circ}{\nabla}$ denote the covariant derivative with respect to a symmetric connection specified above, (4.3) is equivalent to the following

$$(4.4) \quad N_k \equiv \xi^j (\eta_{k,j} - \eta_{j,k}) = 0.$$

Thus we have

THEOREM 4.1. *Let M^{2n+1} be a manifold with a (ϕ, ξ, η) -structure. If $N_j = 0$, then we can find a (ϕ, ξ, η) -connection whose torsion tensor is equal to the tensor $t_{jk}{}^t$ in (2.18).*

If η_j is a gradient and $N_j^t = 0$, then $t_{jk}{}^t$ in (2.18) turns out to be

$$(4.5) \quad t_{jk}{}^t = -\frac{1}{4} N_{jk}{}^t.$$

Thus we have the following theorem of Sasaki and Hatakeyama[3]:

THEOREM 4.2. *Let M^{2n+1} be a manifold with a (ϕ, ξ, η) -structure. If η_j is a gradient and $N_j^t = 0$, then we can find (ϕ, ξ, η) -connection whose torsion tensor is equal to $-\frac{1}{4} N_{jk}{}^t$.*

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