

DELAYED GRONWALL INEQUALITY WITH WEAKLY THE SINGULAR KERNEL

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ABSTRACT. Delay Gronwall inequality with a weakly singular kernel has been a subject of interest in various mathematical studies. In this article, we will delve into the consideration of this inequality and its application in the study continuity of the state trajectory for a Volterra integral equation with delay. Using delay Gronwall inequality with a singular kernel, we investigate the behavior and properties of the state trajectory if there are delays. This analysis aims to improve our understanding of the dynamics associated in del Volterra integral equations with delay. In addition, we present a comprehensive example demonstrating the practical significance of our results.

1. INTRODUCTION

The delay Gronwall inequality with a singular kernel is a fundamental result in the field of mathematical analysis and is widely used in various areas of mathematics, physics, and engineering. The inequality provides a powerful tool for estimating the growth and behavior of functions and has applications in diverse fields such as differential equations, delay systems, mathematical modeling, control theory, and stochastic processes.

The Gronwall inequality, named after American mathematician Thomas H. Gronwall, establishes an upper bound for the growth of a function based on its integral and the behavior of a singular kernel. The inequality has proven to be an indispensable tool for studying the properties of solutions to differential equations and integral equations.

The delay Gronwall inequality with a singular kernel offers a rigorous mathematical framework to analyze the growth and stability of functions subject to delays and singular influences. By considering the integral of a function multiplied by the singular kernel, the inequality provides an upper bound on the growth rate of delayed functions, enabling researchers to derive essential bounds and estimates. This inequality is indispensable for studying the stability and convergence properties of delayed differential equations, integral equations, and time-delay systems.

Furthermore, the delay Gronwall inequality with a singular kernel has profound implications in various scientific fields. In control theory, it plays a vital role in analyzing the stability and performance of control systems subjected to delays, ensuring robustness and preventing undesired behaviors. In signal processing and communication systems, it assists in understanding the impact of time delays on signal transmission and reception, contributing to the design of efficient and reliable communication

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1 networks. Its versatility and broad applicability make the delay Gronwall inequality with a singular
2 kernel a valuable asset in both theoretical and applied mathematics.

3 In this paper, we aim to provide a comprehensive overview of the delay Gronwall inequality with a
4 singular kernel. We will explore its mathematical formulation, discuss its properties, and examine its
5 applications in different areas of mathematics and science. By understanding the intricacies of this
6 inequality, researchers and practitioners can employ it effectively to tackle various problems and gain
7 insights into the behavior of complex systems.

8 In recent research [1]-[15], different generalizations of the Gronwall inequalities have been de-
9 veloped. In particular, Ping Lin and Jiongmin Yong [1] derived a notable inequality under certain
10 conditions.

11 We will denote the following necessary theorem, which we use it for proof of the delayed Gronwall's
12 inequality for singular integral.

13 **Lemma 1.** ([1]) Let $\beta \in (0, 1)$ and $q > 1/\beta$. Let $L(\cdot)$, $a(\cdot)$, $y(\cdot)$ be nonnegative functions with
14 $L(\cdot) \in L^q(0, T)$ and $a(\cdot), y(\cdot) \in L^{\frac{q}{q-1}}(0, T)$. Suppose

$$17 \quad (1.1) \quad y(t) \leq a(t) + \int_0^t \frac{L(s)y(s)}{(t-s)^{1-\beta}} ds, \quad a.e. \quad t \in [0, T].$$

19 Then there exists a constant $K > 0$ such that

$$21 \quad y(t) \leq a(t) + K \int_0^t \frac{L(s)a(s)}{(t-s)^{1-\beta}} ds, \quad a.e. \quad t \in [0, T].$$

24 Another interesting scenario, if we replace assumption (1.1) with the following condition:

$$27 \quad (1.2) \quad \xi(t) \leq \vartheta(t) + \int_0^t \frac{L(s)\xi(s)}{(t-s)^{1-\nu}} ds + \int_0^t \frac{L(s)\xi(s-h)}{(t-s)^{1-\nu}} ds, \quad a.e., \quad t \in [0, T].$$

29 Then, there exists a constant $K > 0$ such that

$$32 \quad (1.3) \quad \xi(t) \leq \vartheta_n(t) + K \int_0^t \frac{L(s)\vartheta(s)}{(t-s)^{1-\nu}} ds, \quad t \in [0, T].$$

34 Where

$$36 \quad \vartheta_n(t) = \vartheta(t) + K \sum_{k=1}^n \int_0^{t-kh} \frac{L(s)\vartheta(s)}{(t-kh-s)^{1-\nu}} ds + K \sum_{k=0}^{n-1} \int_h^{t-kh} \frac{L(s)\vartheta(s-h)}{(t-kh-s)^{1-\nu}} ds.$$

39 The assumption (1.2) is considered natural and plays a crucial role in investigating the well-posedness
40 problem discussed in Section 4. These results highlight the significant advancements in understanding
41 the properties and generalizations of Gronwall inequalities, paving the way for further exploration and
42 applications in various mathematical analyses.

2. Preliminaries

In the forthcoming section, we will provide initial findings that will prove beneficial in subsequent analysis. To begin, consider a predetermined time horizon denoted as $T > 0$. We will now define the subsequent spaces:

$$L^p(0, T; \mathbb{R}^n) = \left\{ \phi : [0, T] \rightarrow \mathbb{R}^n \mid \phi(\cdot) \text{ is measurable,} \right. \\ \left. \|\phi(\cdot)\|_p \equiv \left(\int_0^T |\phi(t)|^p dt \right)^{1/p} < \infty \right\}, 1 \leq p < \infty,$$

$$L^\infty(0, T; \mathbb{R}^n) = \left\{ \phi : [0, T] \rightarrow \mathbb{R}^n \mid \phi(\cdot) \text{ is measurable, } \|\phi(\cdot)\|_\infty \equiv \operatorname{ess\,sup}_{t \in [0, T]} |\phi(t)| < \infty \right\}.$$

Also, we define

$$L^{p+}(0, T; \mathbb{R}^n) = \bigcup_{r > p} L^r(0, T; \mathbb{R}^n), \quad 1 \leq p < \infty, \\ L^{p-}(0, T; \mathbb{R}^n) = \bigcap_{r < p} L^r(0, T; \mathbb{R}^n), \quad 1 < p < \infty.$$

In the subsequent analysis, we utilize the notation $\Delta = \{(t, s) \in [0, T]^2 \mid 0 \leq s < t \leq T\}$. It is important to note that the "diagonal line" represented by $\{(t, t) \mid t \in [0, T]\}$ does not belong to Δ . Consequently, if we consider a continuous mapping $\phi : \Delta \rightarrow \mathbb{R}^n$ where $(t, s) \mapsto \phi(t, s)$, the function $\phi(\cdot, \cdot)$ may become unbounded as the difference $|t - s| \rightarrow 0$.

In the article, we adopt the notation $t_1 \vee t_2 = \max\{t_1, t_2\}$ and $t_1 \wedge t_2 = \min\{t_1, t_2\}$, for any $t_1, t_2 \in \mathbb{R}$. Notably, $t^+ = t \vee 0$.

Lemma 2. (Lemma 2.1, page 138, [1]) Let $p, q, r \geq 1$ satisfy $\frac{1}{p} + 1 = \frac{1}{q} + \frac{1}{r}$. Then for any $f(\cdot) \in L^q(\mathbb{R}^n), g(\cdot) \in L^r(\mathbb{R}^n)$,

$$(2.1) \quad \|f(\cdot) * g(\cdot)\|_{L^p(\mathbb{R}^n)} \leq \|f(\cdot)\|_{L^q(\mathbb{R}^n)} \|g(\cdot)\|_{L^r(\mathbb{R}^n)}.$$

Corollary 3. (Corollary 2.2, page 138, [1]) Let $\beta \in (0, 1)$, $1 \leq r < \frac{1}{1-\beta}$, and $\frac{1}{p} + 1 = \frac{1}{q} + \frac{1}{r}$, $p, q \geq 1$. Then for any $a < b$, $0 < \delta \leq b - a$, and $\varphi(\cdot) \in L^q(a, b)$,

$$(2.2) \quad \left(\int_a^{a+\delta} \left| \int_a^t \frac{\varphi(s) ds}{(t-s)^{1-\beta}} \right|^p dt \right)^{1/p} \leq \left(\frac{\delta^{1-r(1-\beta)}}{1-r(1-\beta)} \right)^{1/r} \|\varphi(\cdot)\|_{L^q(a, b)}.$$

3. Main result

In this section, we will present the following theorem that demonstrates the delay Gronwall inequality with a singular kernel.

Theorem 4. Let $v \in (0, 1)$, $h > 0$, and $q > \frac{1}{v}$. Suppose that $L(\cdot)$, $\vartheta(\cdot)$, $\xi(\cdot)$ be nonnegative functions with $\vartheta(t) = 0$, $L(t) = 0$ $t < 0$, where $L(\cdot) \in L^q(0, T)$ and $\vartheta(\cdot), \xi(\cdot) \in L^{\frac{q}{q-1}}[-h, T]$. Assume

$$(3.1) \quad \begin{cases} \xi(t) \leq \vartheta(t) + \int_0^t \frac{L(s)\xi(s)}{(t-s)^{1-v}} ds + \int_0^t \frac{L(s)\xi(s-h)}{(t-s)^{1-v}} ds, & a.e. \quad t \in [0, T], \\ \xi(t) = 0, & t < 0. \end{cases}$$

Then there is a constant $K > 0$ such that

$$(3.2) \quad \xi(t) \leq \vartheta_n(t) + K \int_0^t \frac{L(s)\vartheta(s)}{(t-s)^{1-v}} ds, \quad a.e. \quad t \in [0, T],$$

where

$$(3.3) \quad \vartheta_n(t) = \vartheta(t) + K \sum_{k=1}^n \int_0^{t-kh} \frac{L(s)\vartheta(s)}{(t-kh-s)^{1-v}} ds + K \sum_{k=0}^{n-1} \int_h^{t-kh} \frac{L(s)\vartheta(s-h)}{(t-kh-s)^{1-v}} ds.$$

Proof. Let's contemplate the partition of $[0, T]$ by intervals of length h , where there exists an integer n such that $0 < h < 2h < \dots < nh \leq T < (n+1)h$.

• **Step 1.** Consider (3.1) on the $0 < t \leq h$,

$$\xi(t) \leq \vartheta(t) + \int_0^t \frac{L(s)\xi(s)}{(t-s)^{1-v}} ds + \int_0^t \frac{L(s)\xi(s-h)}{(t-s)^{1-v}} ds.$$

Since $\xi(t) = 0$, $-h \leq t \leq 0$, it follows

$$\xi(t) \leq \vartheta(t) + \int_0^t \frac{L(s)\xi(s)}{(t-s)^{1-v}} ds.$$

By using Lemma 1, we obtain

$$(3.4) \quad \xi(t) \leq \vartheta_0(t) + K_0 \int_0^t \frac{L(s)\vartheta(s)}{(t-s)^{1-v}} ds, \quad t \in [0, h],$$

where $\vartheta_0(t) = \vartheta(t)$.

• **Step 2.** Now, employing the same principle, we take $h < t \leq 2h$,

$$\xi(t) \leq \vartheta(t) + \int_0^t \frac{L(s)\xi(s)}{(t-s)^{1-v}} ds + \int_h^t \frac{L(s)\xi(s-h)}{(t-s)^{1-v}} ds$$

Substituting (3.4) into the above

$$\xi(t) \leq \vartheta(t) + \int_0^t \frac{L(s)\xi(s)}{(t-s)^{1-v}} ds + \int_h^t \frac{L(s)}{(t-s)^{1-v}} \left[\vartheta(s-h) + K_0 \int_0^{s-h} \frac{L(\tau)\vartheta(\tau)}{(s-h-\tau)^{1-v}} d\tau \right] ds.$$

By applying the Fubini's theorem,

$$\int_h^t \frac{L(s)}{(t-s)^{1-v}} \int_0^{s-h} \frac{L(\tau)\vartheta(\tau)}{(s-h-\tau)^{1-v}} d\tau ds = \int_0^{t-h} L(\tau) \left[\int_{\tau+h}^t \frac{L(s) ds}{(t-s)^{1-v} (s-h-\tau)^{1-v}} \right] \vartheta(\tau) d\tau$$

1 Utilizing the Holder inequality, and letting $r = \frac{s-h-\tau}{t-h-\tau}$ implies

$$\begin{aligned}
 & \int_{\tau+h}^t \frac{L(s)ds}{(t-s)^{1-\nu}(s-h-\tau)^{1-\nu}} \leq \left(\int_{\tau+h}^t L(s)^q ds \right)^{\frac{1}{q}} \left(\int_{\tau+h}^t \frac{ds}{(t-s)^{(1-\nu)\frac{q}{q-1}}(s-h-\tau)^{(1-\nu)\frac{q}{q-1}}} \right)^{\frac{q-1}{q}} \\
 & \leq \|L(\cdot)\|_q \frac{1}{(t-h-\tau)^{2(1-\nu)-\frac{q-1}{q}}} \left(\int_0^1 \frac{dr}{(1-r)^{(1-\nu)\frac{q}{q-1}}r^{(1-\nu)\frac{q}{q-1}}} \right)^{\frac{q-1}{q}}.
 \end{aligned}$$

8 Since $q > \frac{1}{\nu}$ that is equivalent to

$$(3.5) \quad 0 < 1 - \frac{(1-\nu)q}{q-1} = \frac{\nu q - 1}{q-1},$$

12 we get

$$\int_{\tau+h}^t \frac{L(s)ds}{(t-s)^{1-\nu}(s-h-\tau)^{1-\nu}} \leq \frac{\|L(\cdot)\|_q}{(t-h-\tau)^{2(1-\nu)-\frac{q-1}{q}}} B\left(\frac{\nu q - 1}{q-1}, \frac{\nu q - 1}{q-1}\right)^{\frac{q-1}{q}} \equiv \frac{K_1}{(t-h-\tau)^{1-\nu_1}},$$

17 where, $B(\cdot, \cdot)$ is the well-known Beta function.

18 Therefore,

$$(3.6) \quad \xi(t) \leq \vartheta(t) + \int_0^t \frac{L(s)\xi(s)}{(t-s)^{1-\nu}} ds + \int_h^t \frac{L(s)\vartheta(s-h)}{(t-s)^{1-\nu}} ds + K_1 \int_0^{t-h} \frac{L(s)\vartheta(s)}{(t-h-s)^{1-\nu_1}} ds,$$

21 such as

$$\begin{aligned}
 K_1 &= \|L(\cdot)\|_q B\left(\frac{\nu q - 1}{q-1}, \frac{\nu q - 1}{q-1}\right)^{\frac{q-1}{q}}, \\
 \nu_1 &= 1 - \left(2(1-\nu) - \frac{q-1}{q}\right) = \nu + \left(\nu - \frac{1}{q}\right) > \nu.
 \end{aligned}$$

27 By using the following inequality in (3.6)

$$(3.7) \quad \frac{1}{(t-s)^{1-\nu_1}} \leq \frac{C}{(t-s)^{1-\nu}}, \quad 0 \leq s < t \leq T,$$

31 we receive

$$\xi(t) \leq \vartheta(t) + \int_0^t \frac{L(s)\xi(s)}{(t-s)^{1-\nu}} ds + \int_h^t \frac{L(s)\vartheta(s-h)}{(t-s)^{1-\nu}} ds + K_1 \int_0^{t-h} \frac{L(s)\vartheta(s)}{(t-h-s)^{1-\nu}} ds.$$

35 By using Lemma 1, we achieve

$$(3.8) \quad \xi(t) \leq \vartheta_1(t) + K_1 \int_0^t \frac{L(s)\vartheta(s)}{(t-s)^{1-\nu}} ds,$$

39 where

$$\vartheta_1(t) = \vartheta(t) + K_1 \int_h^t \frac{L(s)\vartheta(s-h)}{(t-s)^{1-\nu}} ds + K_2 \int_0^{t-h} \frac{L(s)\vartheta(s)}{(t-h-s)^{1-\nu}} ds.$$

1 • **Step 3.** Subsequently, we examine the range where $2h \leq t \leq 3h$,

$$2 \quad \xi(t) \leq \vartheta(t) + \int_0^t \frac{L(s)\xi(s)}{(t-s)^{1-\nu}} ds + \int_h^t \frac{L(s)\xi(s-h)}{(t-s)^{1-\nu}} ds$$

4 Again substituting (3.8) into the last expression

$$5 \quad \xi(t) \leq \vartheta(t) + \int_0^t \frac{L(s)\xi(s)}{(t-s)^{1-\nu}} ds + \int_h^t \frac{L(s)}{(t-s)^{1-\nu}} \left[\vartheta_1(s-h) + K_1 \int_0^{s-h} \frac{L(\tau)\vartheta(s)}{(s-h-\tau)^{1-\nu}} d\tau \right] ds$$

8 By using the Fubini's theorem and inequality (3.7)

$$9 \quad = \vartheta(t) + K_3 \int_0^t \frac{L(s)\xi(s)}{(t-s)^{1-\nu}} ds + K_3 \int_h^t \frac{L(s)\vartheta(s-h)}{(t-s)^{1-\nu}} ds + K_3 \int_0^{t-h} \frac{L(s)\vartheta(s)}{(t-h-s)^{1-\nu}} ds$$

$$10 \quad + K_3 \int_h^{t-h} \frac{L(s)\vartheta(s-h)}{(t-h-s)^{1-\nu}} ds + K_3 \int_0^{t-2h} \frac{L(s)\vartheta(s)}{(t-2h-s)^{1-\nu}} ds$$

15 Applying Lemma 1, we get

$$16 \quad (3.9) \quad \xi(t) \leq \vartheta_3(t) + K_4 \int_0^t \frac{L(s)\vartheta(s)}{(t-s)^{1-\nu}} ds,$$

18 where

$$19 \quad \vartheta_3(t) = \vartheta(t) + K_4 \int_0^{t-h} \frac{L(s)\vartheta(s)}{(t-h-s)^{1-\nu}} ds + K_4 \int_0^{t-2h} \frac{L(s)\vartheta(s)}{(t-2h-s)^{1-\nu}} ds$$

$$20 \quad + K_4 \int_h^t \frac{L(s)\vartheta(s-h)}{(t-s)^{1-\nu}} ds + K_4 \int_h^{t-h} \frac{L(s)\vartheta(s-h)}{(t-h-s)^{1-\nu}} ds.$$

24 As T is finite, there exists $n \in \mathbb{N}$ such that $T < (n+1)h$. Continuing the given recursive relationship in
25 the same manner for $nh \leq t \leq (n+1)h$, we obtain the following inequality:

$$26 \quad \xi(t) \leq \vartheta_n(t) + K \int_0^t \frac{L(s)\vartheta(s)}{(t-s)^{1-\nu}} ds, \quad a.e. \quad t \in [0, T],$$

28 where, K is the maximum value of K_i for $i \in \mathbb{N}$, and

$$29 \quad \vartheta_n(t) = \vartheta(t) + K \sum_{k=1}^n \int_0^{t-kh} \frac{L(s)\vartheta(s)}{(t-kh-s)^{1-\nu}} ds + K \sum_{k=0}^{n-1} \int_h^{t-kh} \frac{L(s)\vartheta(s-h)}{(t-kh-s)^{1-\nu}} ds.$$

33 □

34 4. Well-posedness in L^p space and continuity of the state trajectory.

36 In this section, we consider the continuity of the state trajectory for the delayed Volterra integral
37 equation with initial condition, and we will show the application of the delayed Gronwall inequality.

$$38 \quad (4.1) \quad \begin{cases} \xi(t) = \zeta(t) + \int_0^t \frac{\kappa(t,s,\xi(s),\xi(s-h),\vartheta(s))}{(t-s)^{1-\nu}} ds, & a.e. \quad t \in [0, T] \\ \xi(t) = 0, & -h \leq t \leq 0, \quad h \geq 0. \end{cases}$$

41 We present a set of the following conditions that apply to the generator function $\kappa(\cdot, \cdot, \cdot, \cdot, \cdot)$ used in
42 our state equation. Let U be a separable metric space with the metric d , which could be a nonempty

1 bounded or unbounded set in R^n with the metric induced by the usual Euclidean norm. With the Borel
2 σ -field, U is regarded as a measurable space. Let $u_0 \in U$ be fixed. For any $p \geq 1$, we define

$$3 \quad \mathcal{U}_p[0, T] = \{u : [0, T] \rightarrow U \mid u(\cdot) \text{ is measurable, } d(u(\cdot), u_0) \in L^p(0, T)\}.$$

4 (H): Let $\kappa : [0, T] \times [0, T] \times R^n \times R^n \times U \rightarrow R^n$ be a transformation with $(t, s) \mapsto \kappa(t, s, \xi, \xi_h, v)$ being
5 measurable, $(\xi, \xi_h) \mapsto \kappa(t, s, \xi, \xi_h, v)$ being continuously differentiable, $(\xi, \xi_h, v) \mapsto \kappa(t, s, \xi, \xi_h, v)$
6 , $(\xi, \xi_h, v) \mapsto \kappa_\xi(t, s, \xi, \xi_h, v)$ and $(\xi, \xi_h, v) \mapsto \kappa_{\xi_h}(t, s, \xi, \xi_h, v)$ being continuous. There exist non-
7 negative functions. $L_0(\cdot), L(\cdot)$ with
8

$$9 \quad (4.2) \quad L_0(\cdot) \in L^{\frac{1}{v}+}(0, T), \quad L(\cdot) \in L^{\frac{p}{pv-1}+}(0, T)$$

10 for some $p > \frac{1}{v}$ and $v \in (0, 1), v_0 \in U$.

$$11 \quad (4.3) \quad |\kappa(t, s, 0, 0, v_0)| \leq L_0(s), \quad t \in [0, T],$$

$$12 \quad (4.4) \quad |\kappa(t, s, \xi, \xi_h, v) - \kappa(t, s, \xi', \xi'_h, v')| \leq L(s)[|\xi - \xi'| + |\xi_h - \xi'_h| + d(v, v')],$$

13
14 for $(t, s) \in \Delta, \quad \xi, \xi', \xi_h, \xi'_h \in R^n, \quad v, v' \in U$.

15 We point out (4.3)-(4.4) declare

$$16 \quad (4.5) \quad |\kappa(t, s, \xi, \xi_h, v)| \leq L_0(s) + L(s)[|\xi| + |\xi_h| + d(v, v_0)], \quad (t, \xi, \xi_h, v) \in [0, T] \times R^n \times R^n \times U.$$

$$17 \quad (4.6)$$

$$18 \quad |\kappa(t, s, \xi, \xi_h, v) - \kappa(t', s, \xi, \xi_h, v)| \leq K\omega(|t - t'|)(1 + |\xi| + |\xi_h|), \quad t, t' \in [0, T], \quad \xi, \xi_h \in R^n, \quad v \in U,$$

19 for some modulus of continuity $\omega(\cdot)$. Moreover, it is evident that L is included in a smaller space,
20 compared to the space to which L_0 belongs.

21 We will now demonstrate the well-posedness of the state equation (4.1) when considering L^p spaces.

22 **Theorem 5.** Assume that (H) satisfies with some $p \geq 1$ and $v \in (0, 1)$. Hence for each $\zeta(\cdot) \in$
23 $L^p(-h, T; R^n)$ and $v \in \mathcal{U}^p[0, T]$, (4.1) admits a unique solution $\xi(\cdot) \equiv \xi(\cdot, \zeta(\cdot), v(\cdot)) \in L^p(-h, T; R^n)$,
24 and the following estimate satisfies:

$$25 \quad (4.7) \quad \|\xi(\cdot)\|_p \leq \|\zeta(\cdot)\|_p + K\left(1 + \|d(v(\cdot), v_0)\|_{L^p(0, T)}\right).$$

26 If $(\zeta_1(\cdot), v_1(\cdot)), (\zeta_2(\cdot), v_2(\cdot)) \in L^p(-h, T; R^n) \times \mathcal{U}^p[0, T]$ and $\xi_1(\cdot), \xi_2(\cdot)$ are the solutions of (4.1)
27 corresponding to $(\zeta_1(\cdot), v_1(\cdot))$, and $(\zeta_2(\cdot), v_2(\cdot))$, accordingly, then

$$28 \quad \|\xi_1(\cdot) - \xi_2(\cdot)\|_p \leq K \left\{ \|\zeta_1(\cdot) - \zeta_2(\cdot)\|_p \right. \\ 29 \quad \left. + \left[\int_0^T \left(\int_0^t \frac{|\kappa(t, s, \xi_1(s), \xi_1(s-h), v_1(s)) - \kappa(t, s, \xi_2(s), \xi_2(s-h), v_2(s))|}{(t-s)^{1-v}} ds \right)^p dt \right]^{1/p} \right\}.$$

30 *Proof.* Assuming a fixed function $\zeta(\cdot)$ in the space $L^p(-h, S; R^n)$, and a control function v belonging
31 to the set $\mathcal{U}^p[0, T]$. For each $z(\cdot) \in L^p(-h, S; R^n)$ with $0 < S \leq T$, such that $z(t) = 0, -h \leq t \leq 0$.

32 Define

$$33 \quad \mathcal{T}[z(\cdot)](t) = \zeta(t) + \int_0^t \frac{\kappa(t, s, z(s), z(s-h), v(s))}{(t-s)^{1-v}} ds, \quad a.e. \quad t \in [0, S].$$

1 Hence by Corollary 3, for each $q \geq 1, 0 \leq \varepsilon < \frac{\nu}{1-\nu}$, with $\frac{1}{p} + 1 = \frac{1}{q} + \frac{1}{1+\varepsilon}$,

$$\begin{aligned}
 & \|\mathcal{F}[z(\cdot)]\|_{L^p(-h, S; \mathbb{R}^n)} \leq \|\zeta(\cdot)\|_{L^p(-h, S; \mathbb{R}^n)} + \left[\int_0^S \left| \int_0^t \frac{\kappa(t, s, z(s), z(s-h), \mathbf{v}(s))}{(t-s)^{1-\nu}} ds \right|^p dt \right]^{1/p} \\
 & \leq \|\zeta(\cdot)\|_p + \left[\int_0^S \left(\int_0^t \frac{|\kappa(t, s, z(s), z(s-h), \mathbf{v}(s))|}{(t-s)^{1-\nu}} ds \right)^p dt \right]^{1/p} \\
 & \leq \|\zeta(\cdot)\|_p + \left[\int_0^S \left(\int_0^t \frac{L_0(s) + L(s)[|z(s)| + |z(s-h)| + d(\mathbf{v}(s), \mathbf{v}_0)]}{(t-s)^{1-\nu}} ds \right)^p dt \right]^{1/p} \\
 (4.9) \quad & \leq \|\zeta(\cdot)\|_p + \left(\frac{S^{1-(1+\varepsilon)(1-\nu)}}{1-(1+\varepsilon)(1-\nu)} \right)^{\frac{1}{1+\varepsilon}} \|L_0(\cdot) + L(\cdot)[|z(\cdot)| + |z(\cdot-h)| + d(\mathbf{v}(\cdot), \mathbf{v}_0)]\|_{L^q(0, S)}.
 \end{aligned}$$

13 We will examine three cases.

14 **Case 1.** $p > \frac{1}{1-\nu}$. In this part, $\frac{1}{\nu} > \frac{p}{p-1}$ and $\frac{p}{1+\nu p} > 1$. For every $\varepsilon \in (0, \frac{\nu}{1-\nu})$, that is equivalent to
 15 $(1-\nu)(1+\varepsilon) < 1$, we obtain (without any constraint on $p > \frac{1}{1-\nu}$ for the current case)

$$\frac{1}{q} = \frac{1}{p} + 1 - \frac{1}{1+\varepsilon} < \frac{1}{p} + 1 - \frac{1}{1+\frac{\nu}{1-\nu}} = \frac{1}{p} + \nu < 1, \quad \frac{1}{q} - \frac{1}{p} = 1 - \frac{1}{1+\varepsilon} < \nu.$$

19 Therefore,

$$q \searrow \frac{p}{1+\nu p} > 1, \quad \frac{pq}{p-q} \searrow \frac{1}{\nu}, \quad \text{as } \varepsilon \nearrow \frac{\nu}{1-\nu}.$$

23 As $L_0(\cdot)$ belongs to $L^{\frac{p}{1+\nu p}+}(0, T)$ and $L(\cdot)$ belongs to $L^{\frac{1}{\nu}+}(0, T)$, we was able to find ε close enough
 24 to $\frac{\nu}{1-\nu}$ such that $L_0(\cdot)$ belongs to $L^q(0, T)$ and $L(\cdot)$ belongs to $L^{\frac{pq}{p-q}}(0, T)$. Hence

$$\begin{aligned}
 & \|L_0(\cdot) + L(\cdot)[|z(\cdot)| + |z(\cdot-h)| + d(\mathbf{v}(\cdot), \mathbf{v}_0)]\|_{L^q(0, S)} \leq \|L_0(\cdot)\|_{L^q(0, T)} \\
 (4.10) \quad & + \|L(\cdot)\|_{L^{\frac{pq}{p-q}}(0, T)} \| |z(\cdot)| + |z(\cdot-h)| + d(\mathbf{v}(\cdot), \mathbf{v}_0) \|_{L^p(0, S)}.
 \end{aligned}$$

29 which yields

$$\begin{aligned}
 & \|\mathcal{F}[z(\cdot)]\|_{L^p(-h, S; \mathbb{R}^n)} \leq \|\zeta(\cdot)\|_p + \left(\frac{S^{1-(1+\varepsilon)(1-\nu)}}{1-(1+\varepsilon)(1-\nu)} \right)^{\frac{1}{1+\varepsilon}} \left\{ \|L_0(\cdot)\|_{L^q(0, T)} \right. \\
 (4.11) \quad & \left. + \|L(\cdot)\|_{L^{\frac{pq}{p-q}}(0, T)} \| |z(\cdot)| + |z(\cdot-h)| + d(\mathbf{v}(\cdot), \mathbf{v}_0) \|_{L^p(0, S)} \right\} \\
 & \leq \|\zeta(\cdot)\|_p + \left(\frac{S^{1-(1+\varepsilon)(1-\nu)}}{1-(1+\varepsilon)(1-\nu)} \right)^{\frac{1}{1+\varepsilon}} \left\{ \|L_0(\cdot)\|_{L^q(0, T)} \right. \\
 & \left. + \|L(\cdot)\|_{L^{\frac{pq}{p-q}}(0, T)} (2\|z(\cdot)\|_p + \|d(\mathbf{v}(\cdot), \mathbf{v}_0)\|_{L^p(0, T)}) \right\}
 \end{aligned}$$

40 Hence, we can conclude that the operator \mathcal{F} maps functions in $L^p(-h, S; \mathbb{R}^n)$ to functions in $L^p(-h, S; \mathbb{R}^n)$
 41 for all S belonging to the interval $(0, T]$. Moving forward, suppose $\delta \in (0, T]$ be undetermined, and
 42 consider two functions $z_1(\cdot)$ and $z_2(\cdot)$ belonging to $L^p(-h, \delta; \mathbb{R}^n)$. We will investigate the following

1 expression (using Corollary 3):

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$$\begin{aligned}
 & \left\| \mathcal{I}[z_1(\cdot)](t) - \mathcal{I}[z_2(\cdot)](t) \right\|_{L^p(-h, \delta; \mathbb{R}^n)} \equiv \left[\int_0^\delta \left| \mathcal{I}[z_1(\cdot)](t) - \mathcal{I}[z_2(\cdot)](t) \right|^p dt \right]^{1/p} \\
 &= \left[\int_0^\delta \left| \int_0^t \frac{\kappa(t, s, z_1(s), z_1(s-h), \mathbf{v}(s)) - \kappa(t, s, z_2(s), z_2(s-h), \mathbf{v}(s))}{(t-s)^{1-\nu}} ds \right|^p dt \right]^{1/p} \\
 &\leq \left[\int_0^\delta \left(\int_0^t \frac{|\kappa(t, s, z_1(s), z_1(s-h), \mathbf{v}(s)) - \kappa(t, s, z_2(s), z_2(s-h), \mathbf{v}(s))|}{(t-s)^{1-\nu}} ds \right)^p dt \right]^{1/p} \\
 &\leq \left(\frac{\delta^{1-(1+\varepsilon)(1-\nu)}}{1-(1+\varepsilon)(1-\nu)} \right)^{\frac{1}{1+\varepsilon}} \|L(\cdot)\|_{L^{\frac{pq}{p-q}}(0, T)} \left(\|z_1(\cdot) - z_2(\cdot)\|_{L^p(-h, \delta; \mathbb{R}^n)} \right. \\
 &\quad \left. + \|z_1(\cdot - h) - z_2(\cdot - h)\|_{L^p(-h, \delta; \mathbb{R}^n)} \right) \\
 &\leq 2 \left(\frac{\delta^{1-(1+\varepsilon)(1-\nu)}}{1-(1+\varepsilon)(1-\nu)} \right)^{\frac{1}{1+\varepsilon}} \|L(\cdot)\|_{L^{\frac{pq}{p-q}}(0, T)} \|z_1(\cdot) - z_2(\cdot)\|_{L^p(-h, \delta; \mathbb{R}^n)}.
 \end{aligned}$$

29 Consider choosing a value of δ from the interval $(0, T]$ such that $2 \left(\frac{\delta^{1-(1+\varepsilon)(1-\nu)}}{1-(1+\varepsilon)(1-\nu)} \right)^{\frac{1}{1+\varepsilon}} \|L(\cdot)\|_{L^{\frac{pq}{p-q}}(0, T)} <$

30 1. This choice of δ ensures that the operator $\mathcal{I} : L^p(-h, \delta; \mathbb{R}^n) \rightarrow L^p(-h, \delta; \mathbb{R}^n)$ is a contraction, and
 31 therefore has a unique fixed point $\xi(\cdot)$ in $L^p(-h, \delta; \mathbb{R}^n)$. This fixed point is the unique solution of the
 32 state equation (4.1) on the interval $[0, \delta]$, with $\xi(t) = 0$, $-h \leq t \leq 0$.

33 Next, we focus on the state equation (4.1) over the interval $[0, 2\delta]$. Let $z(\cdot)$ be any function belonging
 34 to $L^p(\delta, 2\delta; \mathbb{R}^n)$, and define the following expression:

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$$\mathcal{I}[z(\cdot)](t) = \zeta(t) + \int_0^\delta \frac{\kappa(t, s, \xi(s), \xi(s-h), \mathbf{v}(s))}{(t-s)^{1-\nu}} ds + \int_\delta^t \frac{\kappa(t, s, z(s), z(s-h), \mathbf{v}(s))}{(t-s)^{1-\nu}} ds, \quad a.e \quad t \in [\delta, 2\delta].$$

1 Denote $\bar{z}(\cdot) = \xi(\cdot)\chi_{[0,\delta]}(\cdot) + z(\cdot)\chi_{[\delta,2\delta]}(\cdot) \in L^p(-h, 2\delta; \mathbb{R}^n)$, $\bar{z}(\cdot - h) = \xi(\cdot - h)\chi_{[0,\delta]}(\cdot) + z(\cdot - h)\chi_{[\delta,2\delta]}(\cdot) \in L^p(-h, 2\delta; \mathbb{R}^n)$. Hence similarly to (4.9) - (4.11)(with $S = 2\delta$)

$$\begin{aligned}
 & \left\| \zeta(\cdot) + \int_0^\delta \frac{\kappa(t, s, \xi(s), \xi(s-h), \mathbf{v}(s))}{(\cdot - s)^{1-\nu}} ds \right\|_{L^p(\delta, 2\delta; \mathbb{R}^n)} \\
 &= \left[\int_\delta^{2\delta} \left| \zeta(t) + \int_0^\delta \frac{\kappa(t, s, \xi(s), \xi(s-h), \mathbf{v}(s))}{(t-s)^{1-\nu}} ds \right|^p dt \right]^{1/p} \\
 &\leq \left(\int_\delta^{2\delta} |\zeta(t)|^p dt \right)^{1/p} + \left[\int_\delta^{2\delta} \left(\int_0^\delta \frac{|\kappa(t, s, \xi(s), \xi(s-h), \mathbf{v}(s))|}{(t-s)^{1-\nu}} ds \right)^p dt \right]^{1/p} \\
 &\leq \|\zeta(\cdot)\|_p + \left[\int_\delta^{2\delta} \left(\int_0^\delta \frac{L_0(s) + L(s) [|\xi(s)| + |\xi(s-h)| + d(\mathbf{v}(s), \mathbf{v}_0)]}{(t-s)^{1-\nu}} ds \right)^p dt \right]^{1/p} \\
 &\leq \|\zeta(\cdot)\|_p + \left[\int_0^{2\delta} \left(\int_0^\delta \frac{L_0(s)}{(t-s)^{1-\nu}} ds \right)^p dt \right]^{1/p} \\
 &+ \left[\int_0^{2\delta} \left(\int_0^\delta \frac{L(s) [|\bar{z}(s)| + |\bar{z}(s-h)| + d(\mathbf{v}(s), \mathbf{v}_0)]}{(t-s)^{1-\nu}} ds \right)^p dt \right]^{1/p} \\
 &\leq \|\zeta(\cdot)\|_p + K \left[1 + 2\|\xi(\cdot)\|_{L^p(-h, \delta; \mathbb{R}^n)} + 2\|z(\cdot)\|_{L^p(\delta, 2\delta; \mathbb{R}^n)} + \|d(\mathbf{v}(\cdot), \mathbf{v}_0)\|_p \right]
 \end{aligned}$$

23 Following a similar argument to the proof of (4.11), we can conclude that the operator \mathcal{T} maps
 24 functions from $L^p(\delta, 2\delta; \mathbb{R}^n)$ to $L^p(\delta, 2\delta; \mathbb{R}^n)$. Suppose we have two functions, $z_1(\cdot)$ and $z_2(\cdot)$, both
 25 belonging to $L^p(\delta, 2\delta; \mathbb{R}^n)$. By using Corollary 3, we obtain

$$\begin{aligned}
 & \left\| \mathcal{T}[z_1(\cdot)](t) - \mathcal{T}[z_2(\cdot)](t) \right\|_{L^p(\delta, 2\delta; \mathbb{R}^n)} \equiv \left[\int_\delta^{2\delta} \left| \mathcal{T}[z_1(\cdot)](t) - \mathcal{T}[z_2(\cdot)](t) \right|^p dt \right]^{1/p} \\
 &= \left[\int_\delta^{2\delta} \left| \int_\delta^t \frac{\kappa(t, s, z_1(s), z_1(s-h), \mathbf{v}(s)) - \kappa(t, s, z_2(s), z_2(s-h), \mathbf{v}(s))}{(t-s)^{1-\nu}} ds \right|^p dt \right]^{1/p} \\
 &\leq \left[\int_\delta^{2\delta} \left(\int_\delta^t \frac{L(s) [|z_1(s) - z_2(s)| + |z_1(s-h) - z_2(s-h)|]}{(t-s)^{1-\nu}} ds \right)^p dt \right]^{1/p} \\
 &\leq \left(\frac{\delta^{1-(1+\varepsilon)(1-\nu)}}{1 - (1+\varepsilon)(1-\nu)} \right)^{\frac{1}{1+\varepsilon}} \|L(\cdot)\|_{L^{\frac{pq}{p-q}}(0, T)} \left[\|z_1(\cdot) - z_2(\cdot)\|_{L^p(\delta, 2\delta; \mathbb{R}^n)} \right. \\
 &+ \left. \|z_1(\cdot - h) - z_2(\cdot - h)\|_{L^p(\delta, 2\delta; \mathbb{R}^n)} \right] \\
 &\leq 2 \left(\frac{\delta^{1-(1+\varepsilon)(1-\nu)}}{1 - (1+\varepsilon)(1-\nu)} \right)^{\frac{1}{1+\varepsilon}} \|L(\cdot)\|_{L^{\frac{pq}{p-q}}(0, T)} \|z_1(\cdot) - z_2(\cdot)\|_{L^p(\delta, 2\delta; \mathbb{R}^n)}
 \end{aligned}$$

41 Hence we get the existence and uniqueness of the solution to the state equation on $[\delta, 2\delta]$. Using the
 42 induction, we can obtain the solution $\xi(\cdot) \in [-h, \delta], [\delta, 2\delta], \dots, [(\frac{T}{\delta})\delta, T]$.

Now, suppose $\zeta_1(\cdot), \nu_1(\cdot), (\zeta_2(\cdot), \nu_2(\cdot)) \in L^p(-h, T; \mathbb{R}^n) \times \mathcal{U}^p[0, T]$ and $\xi_1(\cdot), \xi_2(\cdot)$ become the corresponding solutions. Hence

$$\begin{aligned} |\xi_1(t) - \xi_2(t)| &\leq |\zeta_1(t) - \zeta_2(t)| + \int_0^t \frac{|\kappa(t, s, \xi_1(s), \xi_1(s-h), \nu_1(s)) - \kappa(t, s, \xi_2(s), \xi_2(s-h), \nu_2(s))|}{(t-s)^{1-\nu}} ds \\ &\quad + \int_0^t \frac{|\kappa(t, s, \xi_1(s), \xi_1(s-h), \nu_2(s)) - \kappa(t, s, \xi_2(s), \xi_2(s-h), \nu_2(s))|}{(t-s)^{1-\nu}} ds \\ &\leq |\zeta_1(t) - \zeta_2(t)| + \int_0^t \frac{|\kappa(t, s, \xi_1(s), \xi_1(s-h), \nu_1(s)) - \kappa(t, s, \xi_2(s), \xi_2(s-h), \nu_2(s))|}{(t-s)^{1-\nu}} ds \\ &\quad + \int_0^t \frac{L(s) \left[|\xi_1(s) - \xi_2(s)| + |\xi_1(s-h) - \xi_2(s-h)| \right]}{(t-s)^{1-\nu}} ds \\ &\equiv \vartheta(t) + \int_0^t \frac{L(s) |\xi_1(s) - \xi_2(s)|}{(t-s)^{1-\nu}} ds + \int_0^t \frac{L(s) |\xi_1(s-h) - \xi_2(s-h)|}{(t-s)^{1-\nu}} ds \end{aligned}$$

Then, by using Theorem 4, we will get

(4.12)

$$|\xi_1(t) - \xi_2(t)| \leq \vartheta(t) + K \sum_{k=0}^n \int_0^{t-kh} \frac{L(s) \vartheta(s)}{(t-kh-s)^{1-\nu}} ds + K \sum_{k=0}^{n-1} \int_h^{t-kh} \frac{L(s) \vartheta(s-h)}{(t-kh-s)^{1-\nu}} ds, \quad a.e. \quad t \in [0, T],$$

for some constant $K > 0$. As a result,

$$\begin{aligned} \|\xi_1(\cdot) - \xi_2(\cdot)\|_p &\leq K \left[\int_0^T \left(\vartheta(t) + K \sum_{k=0}^n \int_0^{t-kh} \frac{L(s) \vartheta(s)}{(t-kh-s)^{1-\nu}} ds + K \sum_{k=0}^{n-1} \int_h^{t-kh} \frac{L(s) \vartheta(s-h)}{(t-kh-s)^{1-\nu}} ds \right)^p dt \right]^{1/p} \\ &\leq K \left(\int_0^T (\vartheta(t))^p dt \right)^{1/p} \leq K \left\{ \|\zeta_1(t) - \zeta_2(t)\|_p \right. \\ &\quad \left. + \left[\int_0^T \left(\int_0^t \frac{|\kappa(s, \xi_1(s), \xi_1(s-h), \nu_1(s)) - \kappa(s, \xi_2(s), \xi_2(s-h), \nu_2(s))|}{(t-s)^{1-\nu}} ds \right)^p dt \right]^{1/p} \right\}. \end{aligned}$$

proving the stability estimate. We are able to the similar argument to prove (4.7).

Case 2. $1 < p \leq \frac{1}{1-\nu}$. In this case,

$$\frac{1}{\nu} \leq \frac{p}{p-1}, \quad \frac{p}{1+\nu p} \leq 1.$$

Also, since $1-\nu \leq \frac{1}{p} < 1$ for each $\varepsilon \in (0, p-1)$, the following satisfies:

$$1-\nu \leq \frac{1}{p} < \frac{1}{1+\varepsilon}.$$

This imply $(1-\nu)(1+\varepsilon) < 1$. Hence

$$\frac{1}{p} < \frac{1}{q} = \frac{1}{p} + 1 - \frac{1}{1+\varepsilon} \nearrow 1, \quad \frac{p-q}{pq} = \frac{1}{p} - \frac{1}{q} = 1 - \frac{1}{1+\varepsilon} \nearrow \frac{p-1}{p}, \quad \text{as } \varepsilon \nearrow p-1.$$

Therefore, we can choose a value for ε close to $p - 1$, given that $L_0(\cdot) \in L^{1+}(0, T)$ and $L(\cdot) \in L^{\frac{p}{p-1}+}(0, T)$. This will ensure that $L_0(\cdot) \in L^q(0, T)$ and $L(\cdot) \in L^{\frac{pq}{p-q}}(0, T)$. The remaining steps of the proof will be identical to Case 1.

Case 3. $p = 1$. In this part, the condition reads $L_0(\cdot) \in L^{1+}(0, T)$ and $L(\cdot) \in L^\infty(0, T)$. Hence we take $\varepsilon = 0$, and (4.11) reads

(4.13)

$$\|\mathcal{T}[z(\cdot)]\|_{L^1(-h, S; R^n)} \leq \|\zeta(\cdot)\|_1 + \frac{S^\nu}{\nu} \{ \|L_0(\cdot)\|_{L^1(0, T)} + \|L(\cdot)\|_{L^\infty(0, T)} (2\|z(\cdot)\| + \|d(v(\cdot), v_0)\|_{L^1(0, S)}) \}.$$

The remainder of the proof is comparable to that of Case 1. □

Example 6. Let

$$\kappa(t, s, \xi(s), \xi(s-h), v) = \frac{\sqrt{|s-1|^{2\delta-2}|t+1|^{2-2\gamma} + |\xi(s)| + |\xi(s-h)|}}{|s-1|^{1-\nu}|t+1|^{1-\gamma}},$$

$$\forall (t, s, \xi, \xi_{s-h}, v) \in \Delta \times R^2 \times U, \quad \gamma < 1, \quad s \neq 1.$$

Consider the following Volterra integral equation

$$(4.14) \quad \xi(t) = \frac{1}{|t-1|^{1-\sigma}} + \int_0^t \frac{\sqrt{|s-1|^{2\delta-2}|t+1|^{2-2\gamma} + |\xi(s)| + |\xi(s-h)|}}{|s-1|^{1-\nu}|t+1|^{1-\gamma}(t-s)^{1-\beta}} ds, \quad a.e., \quad t \in [0, T]$$

for some $\nu, \beta \in (0, 1)$, $\sigma, \delta \in (0, 1]$, and $\gamma > 1$. We can take

$$\zeta(t) = \frac{1}{|t-1|^{1-\sigma}}, \quad L_0(s) = \frac{1}{|s-1|^{2-\nu-\delta}}, \quad L(s) = \frac{1}{|s-1|^{1-\nu}}, \quad t \neq 1, \quad s \neq 1.$$

We see that

$$\zeta(\cdot) \in L^p(0, 1) \leftarrow p(1-\sigma) < 1 \iff p < \frac{1}{1-\sigma} \quad \left(\frac{1}{0} = \infty\right),$$

$$\left\{ \begin{array}{l} (2-\nu-\delta) \frac{p}{1+\beta p} < 1 \iff 2-\nu-\beta-\delta < \frac{1}{p} \\ \iff p < \frac{1}{(2-\nu-\beta-\delta)_+}, \\ 2-\nu-\delta < 1 \iff \nu+\beta > 1. \end{array} \right.$$

$$\implies L(\cdot) \in L^{(\frac{1}{\beta} \vee 1)^+}(0, T),$$

$$\left\{ \begin{array}{l} \frac{1-\nu}{\beta} < 1 \iff \nu+\beta > 1, \\ (1-\nu) \frac{p}{p-1} < 1 \iff 1-\nu < 1-\frac{1}{p} \iff p > \frac{1}{\nu} \end{array} \right.$$

$$L(\cdot) \in L^{(\frac{1}{\beta} \vee \frac{p}{p-1})^+}(0, T).$$

1 Then, (4.14) has a unique solution $\xi(\cdot) \in L^p(0, T)$ for any

$$2 \quad p \in \left(\frac{1}{v}, \frac{1}{(1-\sigma) \vee (2-v-\beta-\delta)_+} \right),$$

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4 supplied

$$5 \quad (4.15) \quad v + \beta > 1, \quad v + \delta > 1.$$

6
7 Let us highlight that the solution $\xi(\cdot)$ of equation (4.10) does not have to be continuous in general,
8 even if the free term $\zeta(\cdot)$ is continuous. Specifically, when we set σ to 1 and consider $\zeta(t)$ as a constant
9 function equal to 1, which is continuous, we observe that the solution $\xi(\cdot)$ is positive. This positivity
10 can be determined by applying the Picard iteration method. Thus,

$$11 \quad (4.16) \quad \lim_{t \rightarrow 1} \xi(t) \geq 1 + \lim_{t \rightarrow 1} \int_0^t \frac{ds}{|s-1|^{2-v-\delta}(t-s)^{1-\beta}} = \int_0^1 \frac{ds}{(1-s)^{3-v-\beta-\delta}} = \infty,$$

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13 supplied

$$14 \quad (4.17) \quad 3 - v - \beta - \delta > 1 \iff v + \beta + \delta < 2.$$

15
16 This will be the case if we take

$$17 \quad v = \frac{2}{3}, \quad \beta = \delta = \frac{1}{2}.$$

18
19 In this scenario, there is a solution $\xi(\cdot) \in L^p(0, T)$ where $p \in (\frac{3}{2}, 3)$. However, it should be noted that
20 the solution is not continuous at $t = 1$.
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