

4 TWO-DIMENSIONAL NEUTRAL PARTIAL INTEGRO-DIFFERENTIAL EQUATIONS OF 5 FRACTIONAL ORDER AND ITS STABILITY: A NEW EXPLORATION

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10 ABSTRACT. Investigating the qualitative properties of two-dimensional neutral integro-differential equations of
11 fractional order is the primary goal of this article. To begin with, we consider some assumptions to establish the
12 theoretical results. Then, the existence and uniqueness of the solution of the considered two-dimensional neutral
13 integro-differential equation are established using Banach's and Krasnoselskii's fixed point theorems. Furthermore,
14 we analyze the stability of the solution by considering some suitable conditions for the initial data. Additionally, we
15 have obtained conditions for the existence of positive, maximal, and minimal solutions to the problem, followed by the
16 Continuation theorem. The paper concludes with a few numerical examples to illustrate and validate the theoretical
17 results.

18 19 20 1. Introduction

21 A branch of Mathematical analysis known as fractional calculus extends the idea of differentiation and integration
22 to non-integer levels. Fractional calculus, which deals with fractional orders of differentiation and integration rather
23 than just integer orders, finds applications in various fields such as modeling and simulating complex systems,
24 understanding dynamical systems, enhancing control theory, representing biological phenomena, studying heat
25 conduction, addressing non-local effects, and accounting for memory-related phenomena.

26 Differential and integral equations serve as highly effective tools for representing and describing physical
27 phenomena, finding widespread application in fields like physics, engineering, and applied mathematics. The
28 neutral differential equation is a type of differential equation that incorporates time delays in the derivatives. The
29 neutral-type differential has applications, such as infinite-dimensional neutral functional differential equations
30 employed in cell population model [1].

31 Integro-differential equations combine integral and derivative terms and are a powerful tool for describing a
32 wide range of physical phenomena as they have been employed to model Volterra's population dynamics [2] and
33 to model the emergence of cities and urban patterning [3].

34 Many researchers have established the existence and uniqueness results for differential equations, integral
35 equations, and integro-differential equations using different fixed point theorems like Banach's fixed point theorem,
36 which is the most popular theorem for determining uniqueness conditions for the solution [4], Krasnoselskii's,
37 Schauder's, and Schaefer's fixed point theorems are mainly used for establishing existence conditions [4, 5, 6].
38 Stability analysis is a crucial part of the discussion for differential equations, integral equations, and integro-
39 differential equations like Mittag-Leffler stability, Uniform stability, Ulam-Hyers stability, and Ulam-Hyers
40 Rassias's stability [4, 7, 8].

41 Recently, two-dimensional integral and integro-differential equations have collected significant interest due to
42 their applications in diverse fields like population dynamics, fluid mechanics, and image processing. Numerical
43 methods like the Triangular function operational matrix method, shifted Jacobi operational matrix method, and
44 Chebyshev integral operational matrix method have been developed to solve two-dimensional integro-differential
45 equations. However, theoretical exploration of these equations in the two-dimensional context is less extensive
46 than their one-dimensional counterparts. Building upon the well-established concepts in one dimension, we are
47 now extending our efforts to explore the theoretical aspects of two-dimensional integro-differential equations.
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52 Ulam Hyer stability, positive solution, maximal and minimal solution.

1 In this paper, we study a two-dimensional neutral integro-differential equation of fractional order of the
2 following form:

$$3 (1) \quad {}_0^C D_x^\gamma [\vartheta(\zeta, x) - h(\zeta, x, \vartheta(\zeta, x))] = f(\zeta, x, \vartheta(\zeta, x)) + {}_0 I_x^\alpha {}_0 I_\zeta^\beta K(\zeta, x, \varsigma, \rho) g(\zeta, \rho, \vartheta(\zeta, \rho)),$$

$$4 (2) \quad \vartheta(\zeta, 0) = \vartheta_0(\zeta),$$

5 with $\zeta \in I: [0, b]$, $x \in J: [0, T]$, $0 < \alpha, \beta, \gamma < 1$, and $\delta = \alpha + \gamma$ such that $0 < \delta < 1$, where ${}_0^C D_x^\gamma$ is Caputo
6 fractional derivative, ${}_0 I_x^\alpha$ and ${}_0 I_\zeta^\beta$ are left Riemann-Liouville fractional integral.

7 $\vartheta \in E$, $\vartheta_0 \in \mathbb{R}$, ${}_0^C D_x^\gamma [\vartheta(\zeta, x) - h(\zeta, x, \vartheta(\zeta, x))] \in E$, $K: G \rightarrow \mathbb{R}^+$, $h: I \times J \times \mathbb{R} \rightarrow \mathbb{R}$, $f: I \times J \times \mathbb{R} \rightarrow \mathbb{R}$,
8 and $g: I \times J \times \mathbb{R} \rightarrow \mathbb{R}$ are continuous functions, where $E =$ The set of all mappings from $C([0, b] \times [0, T])$ to \mathbb{R} , E
9 is a Banach space. Let $h(\zeta, 0, \vartheta(\zeta, 0)) = 0$.

10 The problem (1)-(2) we are investigating find its motivation from the following existing literature:
11 Freedman and Kuang [9] have established sufficient conditions for positive and bounded solutions and analyzed
12 local and global stability of the positive steady state of a class of nonlinear single species neutral differential
13 population model,

$$14 \frac{d}{dt}(x(t) + \rho x(t - \tau)) = x(t)G(x(t), x(t - \tau)),$$

$$15 x(\theta) = \phi(\theta) \geq 0, \theta \in [-\tau, 0],$$

16 where $r > 0$, $0 < \rho < 1$, $G(x, y)$ is continuously differentiable function, $\phi(\theta)$ is continuously differentiable on
17 $[-\tau, 0]$, and $\phi(0) > 0$.

18 Wu and Xia [10] studied neutral partial differential equations that appear in rotating waves,

$$19 \frac{d}{dt}(u(t, x) - bu(t - r, x)) = d\Delta[u(t, x) - bu(t - r, x)] - au(t, x) - abu(t - r, x) - g(u(t, x) - bu(t - r, x)).$$

20 Fu and Huang [11] studied the existence of solutions for semilinear neutral integro-differential equations of the
21 following form,

$$22 \frac{d}{dt}[x(t) + F(t, x_t)] = -Ax(t) + \int_0^t \gamma(t-s)x(s)ds + G(t, x_{\rho(t, x_t)}), t \in [0, T],$$

$$23 x_0 = \varphi \in \mathcal{B}_\alpha,$$

24 where $-A$ is the infinitesimal generator of an analytic semigroup on a Banach space X , $\gamma(t)$ is a closed linear
25 operator defined later, F, G , and ρ are given continuous functions to be specified below, and \mathcal{B}_α is an abstract
26 phase space endowed with a seminorm $\|\cdot\|_{\mathcal{B}_\alpha}$.

27 Andrade et al. [12] investigated the existence of mild solutions for fractional neutral integro-differential
28 equations, which arises from an evolutionary equation,

$$29 D_t^\alpha(x(t) + f(t, x_t)) = Ax(t) + \int_0^t B(t-s)x(s)ds + g(t, x_t), t > 0,$$

$$30 x_0 = \varphi, x'(0) = x_1,$$

31 where $\alpha \in (1, 2)$; $A, B(t)_{t \geq 0}$ are closed linear operators defined on a common domain which is dense in a Banach
32 space X , $D_t^\alpha h(t)$ represents the Caputo derivative of order $\alpha > 0$, and $g_\beta(t) := \frac{t^{\beta-1}}{\Gamma(\beta)}$, $t > 0$, $\beta \geq 0$. The history
33 $x_t: (-\infty, 0] \rightarrow X$ given by $x_t(\theta) = x(t + \theta)$ belongs to some abstract phase space \mathcal{B} defined axiomatically and
34 $f, g: I \times \mathcal{B} \rightarrow X$ are appropriate functions.

35 Yang et al. [13] have studied a class of neutral-type integral differential equations that arise in an epidemic
36 model, Santos et al. have established [14] the existence of mild solutions for a class of partial neutral integro-
37 differential equations, Vijayakumar and Udhayakumar [15] have explored the Sobolev-type Hilfer fractional
38

1 neutral integro-differential system. Various researchers study two-dimensional integro-differential equations to
 2 model population dynamics, heat conduction in materials of fading memory, etc., where the two independent
 3 variables are considered as time and space or time and temperature [16, 17]. Based on the literature review of
 4 two-dimensional neutral integro-differential equations, we have considered the problem (1)-(2), which we believed
 5 till now no one studied this type of equation.

7 Following are the sections of this article: We have covered basic results in the second section. The existence
 8 and uniqueness of the solution to the considered problem are discussed in the third section. Next, the Ulam-Hyers
 9 and Ulam-Hyers Rassias stability is analyzed in the fourth section. The continuation theorem, maximal solutions,
 10 minimal solutions, and positive solutions are all covered in the fifth section. In the sixth section, we have validated
 11 the results with a few examples.

2. Preliminaries

14 These are the basic concepts that we require to establish the results.

16 **Definition 1.** For $\alpha > 0$, the Riemann-Liouville fractional integral for two-dimensional function is defined as

$${}_0I_x^\alpha \vartheta(\zeta, x) = \frac{1}{\Gamma(\alpha)} \int_0^x (x-\rho)^{\alpha-1} \vartheta(\zeta, \rho) d\rho.$$

19 **Definition 2.** [18] For $0 < \alpha < 1$, the Caputo fractional derivative for two-dimensional function is defined as

$${}_0^C D_x^\alpha \vartheta(\zeta, x) = \frac{1}{\Gamma(1-\alpha)} \int_0^x (x-\rho)^{-\alpha} \frac{\partial}{\partial \rho} (\vartheta(\zeta, \rho)) d\rho.$$

23 **Lemma 1.** [19] $({}_0I_x^\alpha)({}_0^C D_x^\alpha) \vartheta(\zeta, x) = \vartheta(\zeta, x) - \vartheta(\zeta, 0)$, $0 < \alpha < 1$.

25 **Theorem 2.1.** [20] (Banach fixed point theorem) In a non-empty complete metric space $J = (J, d)$, if there exists a
 26 contraction mapping $H : J \rightarrow J$, then there is a unique fixed point for H .

27 **Theorem 2.2.** [21] (Arzela-Ascoli theorem) If Ω is a compact Hausdorff metric space, a subset $Y \subset C(\Omega)$ is said
 28 to be relatively compact if and only if it is both uniformly bounded and uniformly equicontinuous.

30 **Theorem 2.3.** [21] (Krasnoselskii fixed point theorem) Let N be a closed, bounded, and convex subset of a real
 31 Banach space J . Consider two operators, H_1 and H_2 , defined on N . The operators satisfy the following conditions:

- 32 (1) $H_1(N) + H_2(N) \subset N$,
- 33 (2) H_2 is continuous on N and $H_2(N)$ is relatively compact subset of J ,
- 34 (3) H_1 is a strict contraction on N , which means there exists a constant $\kappa \in [0, 1)$ such that
 35 $\|H_1(n_1) - H_1(n_2)\| \leq \kappa \|n_1 - n_2\| \forall n_1, n_2 \in N$. Under these conditions, there exists an element $n \in N$
 36 such that $H_1 n + H_2 n = n$.

3. Existence and uniqueness

39 In this section, we have established the conditions for the existence and uniqueness of the solution of the problem
 40 (1)-(2).

42 To establish the theoretical results for the problem (1)-(2), we are following these assumptions:

43 (A_{S1}) Let us assume that positive constants F_h and M_h exist for the continuous function $h : I \times J \times \mathbb{R} \rightarrow \mathbb{R}$
 44 such that $\|h(\zeta, x, \vartheta_1(\zeta, x)) - h(\zeta, x, \vartheta_2(\zeta, x))\| \leq F_h \|\vartheta_1 - \vartheta_2\|$ for each $(\zeta, x) \in I \times J$ and for all $\vartheta_1, \vartheta_2 \in E$
 45 also $M_h = \sup_{(\zeta, x) \in I \times J} \|h(\zeta, x, 0)\|$.

47 (A_{S2}) Let us assume that positive constants F_f and M_f exist for the continuous function $f : I \times J \times \mathbb{R} \rightarrow \mathbb{R}$
 48 such that $\|f(\zeta, x, \vartheta_1(\zeta, x)) - f(\zeta, x, \vartheta_2(\zeta, x))\| \leq F_f \|\vartheta_1 - \vartheta_2\|$ for each $(\zeta, x) \in I \times J$ and for all $\vartheta_1, \vartheta_2 \in E$
 49 also $M_f = \sup_{(\zeta, x) \in I \times J} \|f(\zeta, x, 0)\|$.

51 (A_{S3}) Let us assume that positive constants F_g and M_g exist for the continuous function $g : I \times J \times \mathbb{R} \rightarrow \mathbb{R}$

1 such that $\|g(\zeta, x, \vartheta_1(\zeta, x)) - g(\zeta, x, \vartheta_2(\zeta, x))\| \leq F_g \|\vartheta_1 - \vartheta_2\|$ for each $(\zeta, x) \in I \times J$ and for all $\vartheta_1, \vartheta_2 \in E$
 2 also $M_g = \sup_{(\zeta, x) \in I \times J} \|g(\zeta, x, 0)\|$.

3
 4 (As_4) $K : G \rightarrow \mathbb{R}^+$ is continuous on D with $K_0 = \{\sup |K(\zeta, x, \varsigma, \rho)| : (\zeta, x, \varsigma, \rho) \in G\}$, where
 5 $G = \{(\zeta, x, \varsigma, \rho) : 0 \leq \varsigma \leq \zeta \leq b, 0 \leq \rho \leq x \leq T\}$.

6
 7 (As_5) Let there exists a positive constant M_ϑ such that $M_\vartheta = \sup_{(\zeta, x) \in I \times J} \|\vartheta(\zeta, 0)\|$.

8
 9 (As_6) Let $B_r = \{\vartheta \in E : \|\vartheta\| \leq r\}$, B_r is a closed, bounded, and convex subset of E , where $r \geq \frac{K_1}{1-K^*}$ with
 10 $K_1 = M_\vartheta + M_h + M_f \frac{T^\gamma}{\Gamma(\gamma+1)} + K_0 M_g \frac{T^\delta}{\Gamma(\delta+1)} \frac{b^\beta}{\Gamma(\beta+1)}$ and $K^* = F_h + F_f \frac{T^\gamma}{\Gamma(\gamma+1)} + K_0 F_g \frac{T^\delta}{\Gamma(\delta+1)} \frac{b^\beta}{\Gamma(\beta+1)}$.

11
 12 Firstly, we will transform the considered two-dimensional neutral integro-differential equation into the corre-
 13 sponding integral equation.

$$14 \quad \vartheta(\zeta, x) - h(\zeta, x, \vartheta(\zeta, x)) - \vartheta(\zeta, 0) + h(\zeta, 0, \vartheta(\zeta, 0)) = {}_0I_x^\gamma f(\zeta, \rho, \vartheta(\zeta, \rho))$$

$$15 \quad + {}_0I_x^{\gamma+\alpha} {}_0I_\zeta^\beta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)),$$

16
 17 this gives

$$18 \quad (3) \quad \vartheta(\zeta, x) = \vartheta_0(\zeta) + h(\zeta, x, \vartheta(\zeta, x)) + {}_0I_x^\gamma f(\zeta, \rho, \vartheta(\zeta, \rho)) + {}_0I_x^{\gamma+\alpha} {}_0I_\zeta^\beta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)).$$

19
 20 **Theorem 3.1.** Assume that assumptions $(As_1) - (As_6)$ are satisfied. If

$$21 \quad F_h + F_f \frac{T^\gamma}{\Gamma(\gamma+1)} < 1,$$

22
 23 then problem (1)-(2) has at least one solution.

24
 25 **Proof.** The operator Λ is defined as the sum of the two operators Λ_1 and Λ_2 according to the following
 26 equations:

$$27 \quad (4) \quad \Lambda \vartheta(\zeta, x) = \Lambda_1 \vartheta(\zeta, x) + \Lambda_2 \vartheta(\zeta, x),$$

28
 29 where

$$30 \quad (5) \quad \Lambda_1 \vartheta(\zeta, x) = \vartheta_0(\zeta) + h(\zeta, x, \vartheta(\zeta, x)) + \frac{1}{\Gamma(\gamma)} \int_0^x (x-\rho)^{\gamma-1} f(\zeta, \rho, \vartheta(\zeta, \rho)) d\rho$$

31
 32 and

$$33 \quad (6) \quad \Lambda_2 \vartheta(\zeta, x) = \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \int_0^x \int_0^\zeta (x-\rho)^{\delta-1} (\zeta-\varsigma)^{\beta-1} K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)) d\varsigma d\rho.$$

34
 35 **STEP 1:** We will show that $\Lambda_1 \vartheta + \Lambda_2 \mu \in B_r, \forall \vartheta, \mu \in B_r$.

$$36 \quad \|\Lambda_1 \vartheta(\zeta, x)\| \leq \|\vartheta_0(\zeta)\| + \|h(\zeta, x, \vartheta(\zeta, x))\| + \frac{1}{\Gamma(\gamma)} \int_0^x (x-\rho)^{\gamma-1} \|f(\zeta, \rho, \vartheta(\zeta, \rho))\| d\rho$$

$$37 \quad \leq M_\vartheta + F_h \|\vartheta(\zeta, x)\| + M_h + F_f \|\vartheta(\zeta, x)\| \frac{x^\gamma}{\Gamma(\gamma+1)} + M_f \frac{x^\gamma}{\Gamma(\gamma+1)}$$

38
 39 and

$$40 \quad \|\Lambda_2 \mu(\zeta, x)\| \leq \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \int_0^x \int_0^\zeta (x-\rho)^{\delta-1} (\zeta-\varsigma)^{\beta-1} \|K(\zeta, x, \varsigma, \rho)\| \|g(\varsigma, \rho, \mu(\varsigma, \rho))\| d\varsigma d\rho$$

$$41 \quad \leq K_0 F_g \frac{x^\delta}{\Gamma(\delta+1)} \frac{\zeta^\beta}{\Gamma(\beta+1)} \|\mu(\zeta, x)\| + K_0 M_g \frac{x^\delta}{\Gamma(\delta+1)} \frac{\zeta^\beta}{\Gamma(\beta+1)}.$$

1 Consequently,

$$\begin{aligned}
 & \|\Lambda_1 \vartheta(\zeta, x) + \Lambda_2 \mu(\zeta, x)\| \leq \|\Lambda_1 \vartheta(\zeta, x)\| + \|\Lambda_2 \mu(\zeta, x)\| \\
 & \leq M_\vartheta + F_h \|\vartheta(\zeta, x)\| + M_h + F_f \|\vartheta(\zeta, x)\| \frac{x^\gamma}{\Gamma(\gamma+1)} + M_f \frac{x^\gamma}{\Gamma(\gamma+1)} \\
 & \quad + K_0 F_g \frac{x^\delta}{\Gamma(\delta+1)} \frac{\zeta^\beta}{\Gamma(\beta+1)} \|\mu(\zeta, x)\| + K_0 M_g \frac{x^\delta}{\Gamma(\delta+1)} \frac{\zeta^\beta}{\Gamma(\beta+1)} \\
 & \leq M_\vartheta + F_h r + M_h + F_f \frac{T^\gamma}{\Gamma(\gamma+1)} r + M_f \frac{T^\gamma}{\Gamma(\gamma+1)} \\
 & \quad + K_0 F_g \frac{T^\delta}{\Gamma(\delta+1)} \frac{b^\beta}{\Gamma(\beta+1)} r + K_0 M_g \frac{T^\delta}{\Gamma(\delta+1)} \frac{b^\beta}{\Gamma(\beta+1)} \\
 & \leq \left[M_\vartheta + M_h + M_f \frac{T^\gamma}{\Gamma(\gamma+1)} + K_0 M_g \frac{T^\delta}{\Gamma(\delta+1)} \frac{b^\beta}{\Gamma(\beta+1)} \right] \\
 & \quad + \left[F_h + F_f \frac{T^\gamma}{\Gamma(\gamma+1)} + K_0 F_g \frac{T^\delta}{\Gamma(\delta+1)} \frac{b^\beta}{\Gamma(\beta+1)} \right] r \\
 & \leq K_1 + K^* r \\
 & \leq r.
 \end{aligned}$$

21 STEP 2: Λ_1 is a contraction mapping.

$$(7) \quad \Lambda_1 \vartheta(\zeta, x) = \vartheta_0(\zeta) + h(\zeta, x, \vartheta(\zeta, x)) + \frac{1}{\Gamma(\gamma)} \int_0^x (x-\rho)^{\gamma-1} f(\zeta, \rho, \vartheta(\zeta, \rho)) d\rho.$$

25 Consider $\vartheta_1, \vartheta_2 \in B_r$. Accordingly,

$$\begin{aligned}
 \|\Lambda_1 \vartheta_1(\zeta, x) - \Lambda_1 \vartheta_2(\zeta, x)\| & \leq F_h \|\vartheta_1 - \vartheta_2\| + \frac{1}{\Gamma(\gamma)} \int_0^x (x-\rho)^{\gamma-1} F_f \|\vartheta_1 - \vartheta_2\| d\rho \\
 & \leq F_h \|\vartheta_1 - \vartheta_2\| + F_f \frac{x^\gamma}{\Gamma(\gamma+1)} \|\vartheta_1 - \vartheta_2\| \\
 & \leq \left[F_h + F_f \frac{T^\gamma}{\Gamma(\gamma+1)} \right] \|\vartheta_1 - \vartheta_2\| \\
 & \leq K^{**} \|\vartheta_1 - \vartheta_2\|,
 \end{aligned}$$

35 where $K^{**} = \left[F_h + F_f \frac{T^\gamma}{\Gamma(\gamma+1)} \right] < 1$. This means Λ_1 exhibits the property of being a contraction mapping.

37 STEP 3: Λ_2 is a continuous function and the set $\Lambda_2 B_r$ is relatively compact within the space E .

39 (i) Λ_2 is continuous.

40 In the given argument, it is assumed that the sequence $\{\vartheta_i\}$ converges to ϑ , where $\vartheta_i \in B_r \forall i \in \mathbb{N}$ (the natural numbers). This implies that as n approaches infinity, the norm of the difference between ϑ_n and ϑ tends to zero, which means, $\lim_{n \rightarrow \infty} \|\vartheta_n - \vartheta\| = 0$. From this assumption, it is claimed that $\lim_{n \rightarrow \infty} \Lambda_2 \vartheta_n = \Lambda_2 \vartheta$. To prove this claim, the following inequality is derived:

$$\begin{aligned}
 \|\Lambda_2 \vartheta_n - \Lambda_2 \vartheta\| & \leq \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \int_0^x \int_0^\zeta (x-\rho)^{\delta-1} (\zeta-\varsigma)^{\beta-1} \|K(\zeta, x, \varsigma, \rho)\| \\
 & \quad \|g(\varsigma, \rho, \vartheta_n(\varsigma, \rho)) - g(\varsigma, \rho, \vartheta(\varsigma, \rho))\| d\varsigma d\rho \\
 & \leq \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \int_0^x \int_0^\zeta (x-\rho)^{\delta-1} (\zeta-\varsigma)^{\beta-1} K_0 F_g \|\vartheta_n - \vartheta\| d\varsigma d\rho.
 \end{aligned}$$

51 Finally, it is concluded that $\|\Lambda_2 \vartheta_n - \Lambda_2 \vartheta\| \rightarrow 0$ whenever $\vartheta_n \rightarrow \vartheta$.

(ii) $\Lambda_2 B_r$ is uniformly bounded.

$$\|\Lambda_2 \vartheta(\zeta, x)\| \leq r^*,$$

where $r^* = \frac{T^\delta}{\Gamma(\delta+1)} \frac{b^\beta}{\Gamma(\beta+1)} K_0 [F_g r + M_g]$. This implies $\Lambda_2 B_r \subset B_{r^*}$ for any $\vartheta \in B_r$.

(iii) $\Lambda_2 B_r$ is uniformly equicontinuous.

Let $(\zeta_1, x_1), (\zeta_2, x_2) \in I \times J$ and $\vartheta \in B_r$, then we have

$$\begin{aligned} & \left\| \Lambda_2 \vartheta(\zeta_1, x_1) - \Lambda_2 \vartheta(\zeta_2, x_2) \right\| \\ &= \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \left\| \int_0^{x_1} \int_0^{\zeta_1} (x_1 - \rho)^{\delta-1} (\zeta_1 - \varsigma)^{\beta-1} K(\zeta_1, x_1, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)) d\varsigma d\rho \right. \\ & \quad \left. - \int_0^{x_2} \int_0^{\zeta_2} (x_2 - \rho)^{\delta-1} (\zeta_2 - \varsigma)^{\beta-1} K(\zeta_2, x_2, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)) d\varsigma d\rho \right\| \\ &\leq \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \left\| \int_0^{\zeta_1} \int_0^{x_1} (x_1 - \rho)^{\delta-1} (\zeta_1 - \varsigma)^{\beta-1} K(\zeta_1, x_1, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)) d\rho d\varsigma \right. \\ & \quad \left. - \int_0^{\zeta_1} \int_0^{x_2} (x_2 - \rho)^{\delta-1} (\zeta_1 - \varsigma)^{\beta-1} K(\zeta_1, x_2, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)) d\rho d\varsigma \right\| \\ & \quad + \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \left\| \int_0^{x_2} \int_0^{\zeta_1} (x_2 - \rho)^{\delta-1} (\zeta_1 - \varsigma)^{\beta-1} K(\zeta_1, x_2, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)) d\varsigma d\rho \right. \\ & \quad \left. - \int_0^{x_2} \int_0^{\zeta_2} (x_2 - \rho)^{\delta-1} (\zeta_2 - \varsigma)^{\beta-1} K(\zeta_2, x_2, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)) d\varsigma d\rho \right\| \\ &\leq \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \int_0^{\zeta_1} (\zeta_1 - \varsigma)^{\beta-1} (K_0 F_g + M_g) \\ & \quad \left\{ \int_0^{x_1} \{(x_1 - \rho)^{\delta-1} - (x_2 - \rho)^{\delta-1}\} d\rho + \int_{x_1}^{x_2} (x_2 - \rho)^{\delta-1} d\rho \right\} d\varsigma \\ & \quad + \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \int_0^{x_2} (x_2 - \rho)^{\delta-1} (K_0 F_g + M_g) \\ & \quad \left\{ \int_0^{\zeta_1} \{(\zeta_1 - \varsigma)^{\beta-1} - (\zeta_2 - \varsigma)^{\beta-1}\} d\varsigma + \int_{\zeta_1}^{\zeta_2} (\zeta_2 - \varsigma)^{\beta-1} d\varsigma \right\} d\rho \\ &\leq \frac{\zeta_1^\beta}{\Gamma(\delta+1)} \frac{(K_0 F_g + M_g)}{\Gamma(\beta+1)} [2(x_2 - x_1)^\delta + x_1^\delta - x_2^\delta] \\ & \quad + \frac{x_2^\delta}{\Gamma(\delta+1)} \frac{(K_0 F_g + M_g)}{\Gamma(\beta+1)} [2(\zeta_2 - \zeta_1)^\beta + \zeta_1^\beta - \zeta_2^\beta], \end{aligned}$$

$\|\Lambda_2 \vartheta(\zeta_1, x_1) - \Lambda_2 \vartheta(\zeta_2, x_2)\| \rightarrow 0$ whenever $\zeta_1 \rightarrow \zeta_2, x_1 \rightarrow x_2$.

Thus, $\Lambda_2 B_r$ is uniformly equicontinuous. By the Theorem 2.2, $\Lambda_2 B_r$ becomes relatively compact.

Since each of the criteria of the Theorem 2.3 has been fulfilled, the problem (1)-(2) has at least one solution.

Theorem 3.2. Suppose that assumptions $(As_1) - (As_6)$ are satisfied. If

$$F_h + F_f \frac{T^\gamma}{\Gamma(\gamma+1)} + K_0 F_g \frac{T^\delta}{\Gamma(\delta+1)} \frac{b^\beta}{\Gamma(\beta+1)} < 1$$

then problem (1)-(2) has a unique solution.

1 **Proof.** Let us consider an operator $\Lambda : B_r \rightarrow B_r$, define as

$$\begin{aligned} 2 & \Lambda(\vartheta) = \vartheta, \\ 3 & (8) \\ 4 & \Lambda\vartheta(\zeta, x) = \vartheta_0(\zeta) + h(\zeta, x, \vartheta(\zeta, x)) + {}_0I_x^\gamma f(\zeta, \rho, \vartheta(\zeta, \rho)) \\ 5 & (9) \\ 6 & \quad + {}_0I_x^{\gamma+\alpha} {}_0I_\zeta^\beta K(\zeta, x, \varsigma, \rho)g(\varsigma, \rho, \vartheta(\varsigma, \rho)), \\ 7 & \\ 8 & \Lambda\vartheta(\zeta, x) = \vartheta_0(\zeta) + h(\zeta, x, \vartheta(\zeta, x)) + \frac{1}{\Gamma(\gamma)} \int_0^x (x-\rho)^{\gamma-1} f(\zeta, \rho, \vartheta(\zeta, \rho)) d\rho \\ 9 & (10) \\ 10 & \quad + \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \int_0^x \int_0^\zeta (x-\rho)^{\delta-1} (\zeta-\varsigma)^{\beta-1} K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)) d\varsigma d\rho, \\ 11 & \end{aligned}$$

12 where $\delta = \gamma + \alpha$. For $\vartheta \in B_r$, we have

$$\begin{aligned} 14 & \|\Lambda\vartheta\| \leq \|\vartheta_0(\zeta)\| + \|h(\zeta, x, \vartheta(\zeta, x))\| + \frac{1}{\Gamma(\gamma)} \int_0^x (x-\rho)^{\gamma-1} \|f(\zeta, \rho, \vartheta(\zeta, \rho))\| d\rho \\ 15 & \\ 16 & \quad + \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \int_0^x \int_0^\zeta (x-\rho)^{\delta-1} (\zeta-\varsigma)^{\beta-1} \|K(\zeta, x, \varsigma, \rho)\| \|g(\varsigma, \rho, \vartheta(\varsigma, \rho))\| d\varsigma d\rho \\ 17 & \\ 18 & \leq M_\vartheta + F_h \|\vartheta(\zeta, x)\| + M_h + F_f \|\vartheta(\zeta, x)\| \frac{x^\gamma}{\Gamma(\gamma+1)} + M_f \frac{x^\gamma}{\Gamma(\gamma+1)} \\ 19 & \\ 20 & \quad + K_0 F_g \frac{x^\delta}{\Gamma(\delta+1)} \frac{\zeta^\beta}{\Gamma(\beta+1)} \|\vartheta(\zeta, x)\| + K_0 M_g \frac{x^\delta}{\Gamma(\delta+1)} \frac{\zeta^\beta}{\Gamma(\beta+1)} \\ 21 & \\ 22 & \leq M_\vartheta + F_h r + M_h + F_f r \frac{T^\gamma}{\Gamma(\gamma+1)} + M_f \frac{T^\gamma}{\Gamma(\gamma+1)} + K_0 F_g \frac{T^\delta}{\Gamma(\delta+1)} \frac{b^\beta}{\Gamma(\beta+1)} r + K_0 M_g \frac{T^\delta}{\Gamma(\delta+1)} \frac{b^\beta}{\Gamma(\beta+1)} \\ 23 & \\ 24 & \leq \left[M_\vartheta + M_h + M_f \frac{T^\gamma}{\Gamma(\gamma+1)} + K_0 M_g \frac{T^\delta}{\Gamma(\delta+1)} \frac{b^\beta}{\Gamma(\beta+1)} \right] + \left[F_h + F_f \frac{T^\gamma}{\Gamma(\gamma+1)} + K_0 F_g \frac{T^\delta}{\Gamma(\delta+1)} \frac{b^\beta}{\Gamma(\beta+1)} \right] r \\ 25 & \\ 26 & \leq K_1 + K^* r \\ 27 & \\ 28 & \leq r. \\ 29 & \\ 30 & \end{aligned}$$

31 This concludes that $\Lambda B_r \subset B_r$.

32 Now, consider $\vartheta_1, \vartheta_2 \in B_r$ such that

$$\begin{aligned} 34 & \Lambda\vartheta_1(\zeta, x) = \vartheta_0(\zeta) + h(\zeta, x, \vartheta_1(\zeta, x)) + \frac{1}{\Gamma(\gamma)} \int_0^x (x-\rho)^{\gamma-1} f(\zeta, \rho, \vartheta_1(\zeta, \rho)) d\rho \\ 35 & (11) \\ 36 & \quad + \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \int_0^x \int_0^\zeta (x-\rho)^{\delta-1} (\zeta-\varsigma)^{\beta-1} K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta_1(\varsigma, \rho)) d\varsigma d\rho \\ 37 & \end{aligned}$$

38 and

$$\begin{aligned} 40 & \Lambda\vartheta_2(\zeta, x) = \vartheta_0(\zeta) + h(\zeta, x, \vartheta_2(\zeta, x)) + \frac{1}{\Gamma(\gamma)} \int_0^x (x-\rho)^{\gamma-1} f(\zeta, \rho, \vartheta_2(\zeta, \rho)) d\rho \\ 41 & (12) \\ 42 & \quad + \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \int_0^x \int_0^\zeta (x-\rho)^{\delta-1} (\zeta-\varsigma)^{\beta-1} K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta_2(\varsigma, \rho)) d\varsigma d\rho. \\ 43 & \end{aligned}$$

44 Then we have,

$$\begin{aligned} 46 & \|\Lambda\vartheta_1(\zeta, x) - \Lambda\vartheta_2(\zeta, x)\| \leq \|h(\zeta, x, \vartheta_1(\zeta, x)) - h(\zeta, x, \vartheta_2(\zeta, x))\| \\ 47 & \\ 48 & \quad + \frac{1}{\Gamma(\gamma)} \int_0^x (x-\rho)^{\gamma-1} \|f(\zeta, \rho, \vartheta_1(\zeta, \rho)) - f(\zeta, \rho, \vartheta_2(\zeta, \rho))\| d\rho \\ 49 & \\ 50 & \quad + \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \int_0^x \int_0^\zeta (x-\rho)^{\delta-1} (\zeta-\varsigma)^{\beta-1} K(\zeta, x, \varsigma, \rho) \\ 51 & \\ 52 & \quad \|g(\varsigma, \rho, \vartheta_1(\varsigma, \rho)) - g(\varsigma, \rho, \vartheta_2(\varsigma, \rho))\| d\varsigma d\rho \end{aligned}$$

$$\begin{aligned}
&\leq F_h \|\vartheta_1 - \vartheta_2\| + \frac{1}{\Gamma(\gamma)} \int_0^x (x-\rho)^{\gamma-1} F_f \|\vartheta_1 - \vartheta_2\| d\rho \\
&\quad + \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \int_0^x \int_0^\zeta (x-\rho)^{\delta-1} (\zeta-\varsigma)^{\beta-1} K_0 F_g \|\vartheta_1 - \vartheta_2\| d\varsigma d\rho \\
&\leq F_h \|\vartheta_1 - \vartheta_2\| + F_f \frac{x^\gamma}{\Gamma(\gamma+1)} \|\vartheta_1 - \vartheta_2\| + K_0 F_g \frac{x^\delta}{\Gamma(\delta+1)} \frac{\zeta^\beta}{\Gamma(\beta+1)} \|\vartheta_1 - \vartheta_2\| \\
&\leq \left[F_h + F_f \frac{T^\gamma}{\Gamma(\gamma+1)} + K_0 F_g \frac{T^\delta}{\Gamma(\delta+1)} \frac{b^\beta}{\Gamma(\beta+1)} \right] \|\vartheta_1 - \vartheta_2\| \\
&\leq K^* \|\vartheta_1 - \vartheta_2\|,
\end{aligned}$$

where

$$K^* = \left[F_h + F_f \frac{T^\gamma}{\Gamma(\gamma+1)} + K_0 F_g \frac{T^\delta}{\Gamma(\delta+1)} \frac{b^\beta}{\Gamma(\beta+1)} \right] < 1.$$

In consideration of the fact that Λ is a contraction mapping, the problem of (1)-(2) has a unique solution according to the Theorem 2.1.

4. Stability analysis

In the current section, we have discussed the Ulam-Hyer and Ulam-Hyer Rassias stability for the problem (1)-(2).

Definition 3. The problem (1)-(2) is said to be Ulam-Hyers stable if, for any given positive ε , whenever there exists a function $\vartheta(\zeta, x)$ satisfies the inequality

$$(13) \quad \left| {}_0^C D_x^\gamma [\vartheta(\zeta, x) - h(\zeta, x, \vartheta(\zeta, x))] - f(\zeta, x, \vartheta(\zeta, x)) - {}_0 I_x^\alpha {}_0 I_\zeta^\beta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)) \right| < \varepsilon$$

then, there must exist a solution $\mu(\zeta, x)$ of problem (1)-(2), which satisfies

$$(14) \quad |\vartheta(\zeta, x) - \mu(\zeta, x)| < k_f \varepsilon, \quad k_f \in \mathbb{R}.$$

Definition 4. The problem (1)-(2) is said to be Ulam-Hyers Rassias stable if, for any given positive ε_ψ , whenever there exists a function $\vartheta(\zeta, x)$ satisfies the inequality

$$(15) \quad \left| {}_0^C D_x^\gamma [\vartheta(\zeta, x) - h(\zeta, x, \vartheta(\zeta, x))] - f(\zeta, x, \vartheta(\zeta, x)) - {}_0 I_x^\alpha {}_0 I_\zeta^\beta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)) \right| < \varepsilon_\psi \psi(\zeta, x)$$

then, there must exist a solution $\mu(\zeta, x)$ of problem (1)-(2), which satisfies

$$(16) \quad |\vartheta(\zeta, x) - \mu(\zeta, x)| < k_f \varepsilon_\psi \psi(\zeta, x), \quad k_f \in \mathbb{R}.$$

Theorem 4.1. Assume that assumptions $(As_1) - (As_6)$ are satisfied. If $T^\gamma F_f < (1 - F_h)\Gamma(\gamma+1)$ then the problem (1)-(2) is Ulam-Hyers stable.

Proof. For a given $\varepsilon > 0$, if the inequality (13) is satisfied, then there exist a function $\phi(\zeta, x)$ satisfying $|\phi(\zeta, x)| < \varepsilon$, which can be written as

$${}_0^C D_x^\gamma [\vartheta(\zeta, x) - h(\zeta, x, \vartheta(\zeta, x))] - f(\zeta, x, \vartheta(\zeta, x)) - {}_0 I_x^\alpha {}_0 I_\zeta^\beta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)) = \phi(\zeta, x).$$

Therefore, we have

$$\begin{aligned}
&|\vartheta(\zeta, x) - \vartheta_0(\zeta) - h(\zeta, x, \vartheta(\zeta, x)) - {}_0 I_x^\gamma f(\zeta, \rho, \vartheta(\zeta, \rho)) - {}_0 I_x^{\gamma+\alpha} {}_0 I_\zeta^\beta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho))| \\
&= |{}_0 I_x^\gamma \phi(\zeta, x)| \leq \frac{x^\gamma}{\Gamma(\gamma+1)} \varepsilon \leq \frac{T^\gamma}{\Gamma(\gamma+1)} \varepsilon.
\end{aligned}$$

1 Now, let $\mu(\zeta, x)$ be the solution of problem (1)-(2), satisfying $\mu(\zeta, 0) = \vartheta(\zeta, 0) = \vartheta_0(\zeta)$. We have,

$$\begin{aligned}
 & |\vartheta(\zeta, x) - \mu(\zeta, x)| = |\vartheta(\zeta, x) - \vartheta_0(\zeta) - h(\zeta, x, \mu(\zeta, x)) - {}_0I_x^\gamma f(\zeta, \rho, \mu(\zeta, \rho)) \\
 & \quad - {}_0I_x^{\gamma+\alpha} {}_0I_\zeta^\beta K(\zeta, x, \varsigma, \rho)g(\varsigma, \rho, \mu(\zeta, \rho))| \\
 & \leq |\vartheta(\zeta, x) - \vartheta_0(\zeta) - h(\zeta, x, \vartheta(\zeta, x)) - {}_0I_x^\gamma f(\zeta, \rho, \vartheta(\zeta, \rho)) \\
 & \quad - {}_0I_x^{\gamma+\alpha} {}_0I_\zeta^\beta K(\zeta, x, \varsigma, \rho)g(\varsigma, \rho, \vartheta(\zeta, \rho))| + |h(\zeta, x, \vartheta(\zeta, x)) - h(\zeta, x, \mu(\zeta, x))| \\
 & \quad + |{}_0I_x^\gamma f(\zeta, \rho, \vartheta(\zeta, \rho)) - {}_0I_x^\gamma f(\zeta, \rho, \mu(\zeta, \rho))| \\
 & \quad + |{}_0I_x^{\gamma+\alpha} {}_0I_\zeta^\beta K(\zeta, x, \varsigma, \rho)g(\varsigma, \rho, \vartheta(\zeta, \rho)) \\
 & \quad - {}_0I_x^{\gamma+\alpha} {}_0I_\zeta^\beta K(\zeta, x, \varsigma, \rho)g(\varsigma, \rho, \mu(\zeta, \rho))| \\
 & \leq \frac{T^\gamma}{\Gamma(\gamma+1)} \varepsilon + F_h |\vartheta(\zeta, x) - \mu(\zeta, x)| + {}_0I_x^\gamma F_f |\vartheta(\zeta, x) - \mu(\zeta, x)| + \\
 & \quad {}_0I_x^\delta {}_0I_\zeta^\beta K_0 F_g |\vartheta(\zeta, x) - \mu(\zeta, x)|.
 \end{aligned}$$

17 Thus,

$$\begin{aligned}
 & |\vartheta(\zeta, x) - \mu(\zeta, x)| [1 - F_h] \leq \frac{T^\gamma}{\Gamma(\gamma+1)} \varepsilon + {}_0I_x^\gamma F_f |\vartheta(\zeta, x) - \mu(\zeta, x)| + \\
 & \quad {}_0I_x^\delta {}_0I_\zeta^\beta K_0 F_g |\vartheta(\zeta, x) - \mu(\zeta, x)|
 \end{aligned}$$

$$\begin{aligned}
 & |\vartheta(\zeta, x) - \mu(\zeta, x)| [1 - F_h] \leq \frac{T^\gamma}{\Gamma(\gamma+1)} \varepsilon + \frac{T^\gamma}{\Gamma(\gamma+1)} F_f |\vartheta(\zeta, x) - \mu(\zeta, x)| \\
 & \quad + {}_0I_x^\delta {}_0I_\zeta^\beta K_0 F_g |\vartheta(\zeta, x) - \mu(\zeta, x)|
 \end{aligned}$$

$$|\vartheta(\zeta, x) - \mu(\zeta, x)| \left[1 - F_h - \frac{T^\gamma}{\Gamma(\gamma+1)} F_f \right] \leq \frac{T^\gamma}{\Gamma(\gamma+1)} \varepsilon + {}_0I_x^\delta \frac{b^\beta}{\Gamma(\beta+1)} K_0 F_g |\vartheta(\zeta, x) - \mu(\zeta, x)|$$

$$\begin{aligned}
 & |\vartheta(\zeta, x) - \mu(\zeta, x)| \leq \frac{T^\gamma}{[(1 - F_h)\Gamma(\gamma+1) - T^\gamma F_f]} \varepsilon \\
 & \quad + \frac{b^\beta K_0 F_g \Gamma(\gamma+1)}{\Gamma(\beta+1)[(1 - F_h)\Gamma(\gamma+1) - T^\gamma F_f]} {}_0I_x^\delta |\vartheta(\zeta, x) - \mu(\zeta, x)|.
 \end{aligned}$$

38 Now, by using Gronwall's inequality [22], we get

$$|\vartheta(\zeta, x) - \mu(\zeta, x)| \leq \frac{T^\gamma}{[(1 - F_h)\Gamma(\gamma+1) - T^\gamma F_f]} E_\delta \left(\frac{T^\delta b^\beta K_0 F_g \Gamma(\gamma+1)}{\Gamma(\beta+1)[(1 - F_h)\Gamma(\gamma+1) - T^\gamma F_f]} \right) \varepsilon,$$

41 where E_δ is the Mittag-Leffler function. Therefore, $|\vartheta(\zeta, x) - \mu(\zeta, x)| < k_f \varepsilon$ with

$$k_f = \frac{T^\gamma}{[(1 - F_h)\Gamma(\gamma+1) - T^\gamma F_f]} E_\delta \left(\frac{T^\delta b^\beta K_0 F_g \Gamma(\gamma+1)}{\Gamma(\beta+1)[(1 - F_h)\Gamma(\gamma+1) - T^\gamma F_f]} \right).$$

44 Hence, the problem (1)-(2) is Ulam-Hyers stable.

45 **Theorem 4.2.** Assume that assumptions $(As_1) - (As_6)$ are satisfied. If $T^\gamma F_f < (1 - F_h)\Gamma(\gamma+1)$ then the problem
46 (1)-(2) is Ulam-Hyers Rassias stable.

1 **Proof.** Let $\vartheta_1(\zeta, x)$ satisfy the problem (1)-(2). For a given $\varepsilon_\psi > 0$, if the inequality (15) holds, then there
2 exist a function $\psi(x, t)$ such that

$$\begin{aligned} & |\vartheta_1(\zeta, x) - \vartheta_0(\zeta) - h(\zeta, x, \vartheta_1(\zeta, x)) - {}_0I_x^\gamma f(\zeta, \rho, \vartheta_1(\zeta, \rho)) - {}_0I_x^{\gamma+\alpha} {}_0I_\zeta^\beta K(\zeta, x, \varsigma, \rho)g(\varsigma, \rho, \vartheta_1(\zeta, \rho))| \\ & \leq \frac{T^\gamma}{\Gamma(\gamma+1)} \varepsilon_\psi \psi(\zeta, x). \end{aligned}$$

7 Now, let $\mu_1(\zeta, x)$ be the solution of problem (1)-(2), satisfying $\mu_1(\zeta, 0) = \vartheta_1(\zeta, 0) = \vartheta_0(\zeta)$. We have,

$$\begin{aligned} & |\vartheta_1(\zeta, x) - \mu_1(\zeta, x)| = |\vartheta_1(\zeta, x) - \vartheta_0(\zeta) - h(\zeta, x, \mu_1(\zeta, x)) - {}_0I_x^\gamma f(\zeta, \rho, \mu_1(\zeta, \rho)) \\ & \quad - {}_0I_x^{\gamma+\alpha} {}_0I_\zeta^\beta K(\zeta, x, \varsigma, \rho)g(\varsigma, \rho, \mu_1(\zeta, \rho))| \\ & \leq |\vartheta_1(\zeta, x) - \vartheta_0(\zeta) - h(\zeta, x, \vartheta_1(\zeta, x)) - {}_0I_x^\gamma f(\zeta, \rho, \vartheta_1(\zeta, \rho)) \\ & \quad - {}_0I_x^{\gamma+\alpha} {}_0I_\zeta^\beta K(\zeta, x, \varsigma, \rho)g(\varsigma, \rho, \vartheta_1(\zeta, \rho))| + |h(\zeta, x, \vartheta_1(\zeta, x)) - h(\zeta, x, \mu_1(\zeta, x))| \\ & \quad + |{}_0I_x^\gamma f(\zeta, \rho, \vartheta_1(\zeta, \rho)) - {}_0I_x^\gamma f(\zeta, \rho, \mu_1(\zeta, \rho))| \\ & \quad + |{}_0I_x^{\gamma+\alpha} {}_0I_\zeta^\beta K(\zeta, x, \varsigma, \rho)g(\varsigma, \rho, \vartheta_1(\zeta, \rho)) - {}_0I_x^{\gamma+\alpha} {}_0I_\zeta^\beta K(\zeta, x, \varsigma, \rho)g(\varsigma, \rho, \mu_1(\zeta, \rho))| \\ & \leq \frac{T^\gamma}{\Gamma(\gamma+1)} \varepsilon_\psi \psi(\zeta, x) + F_h |\vartheta_1(\zeta, x) - \mu_1(\zeta, x)| + {}_0I_x^\gamma F_f |\vartheta_1(\zeta, x) - \mu_1(\zeta, x)| + \\ & \quad {}_0I_x^\delta {}_0I_\zeta^\beta K_0 F_g |\vartheta_1(\zeta, x) - \mu_1(\zeta, x)|. \end{aligned}$$

22 So,

$$\begin{aligned} & |\vartheta_1(\zeta, x) - \mu_1(\zeta, x)| [1 - F_h] \leq \frac{T^\gamma}{\Gamma(\gamma+1)} \varepsilon_\psi \psi(\zeta, x) + \frac{T^\gamma}{\Gamma(\gamma+1)} F_f |\vartheta_1(\zeta, x) - \mu_1(\zeta, x)| \\ & \quad + {}_0I_x^\delta {}_0I_\zeta^\beta K_0 F_g |\vartheta_1(\zeta, x) - \mu_1(\zeta, x)| \\ & |\vartheta_1(\zeta, x) - \mu_1(\zeta, x)| \left[1 - F_h - \frac{T^\gamma}{\Gamma(\gamma+1)} F_f \right] \leq \frac{T^\gamma}{\Gamma(\gamma+1)} \varepsilon_\psi \psi(\zeta, x) + {}_0I_x^\delta \frac{b^\beta}{\Gamma(\beta+1)} K_0 F_g |\vartheta_1(\zeta, x) - \mu_1(\zeta, x)| \\ & |\vartheta_1(\zeta, x) - \mu_1(\zeta, x)| \leq \frac{T^\gamma}{[(1 - F_h)\Gamma(\gamma+1) - T^\gamma F_f]} \varepsilon_\psi \psi(\zeta, x) \\ & \quad + \frac{b^\beta K_0 F_g \Gamma(\gamma+1)}{\Gamma(\beta+1)[(1 - F_h)\Gamma(\gamma+1) - T^\gamma F_f]} {}_0I_x^\delta |\vartheta_1(\zeta, x) - \mu_1(\zeta, x)|. \end{aligned}$$

38 Now, by using Gronwall's inequality [22], we get

$$|\vartheta_1(\zeta, x) - \mu_1(\zeta, x)| \leq \frac{T^\gamma}{[(1 - F_h)\Gamma(\gamma+1) - T^\gamma F_f]} E_\delta \left(\frac{T^\delta b^\beta K_0 F_g \Gamma(\gamma+1)}{\Gamma(\beta+1)[(1 - F_h)\Gamma(\gamma+1) - T^\gamma F_f]} \right) \varepsilon_\psi \psi(\zeta, x),$$

43 where E_δ is the Mittag-Leffler function. Therefore, $|\vartheta_1(\zeta, x) - \mu_1(\zeta, x)| < k_f \varepsilon_\psi \psi(\zeta, x)$ with

$$k_f = \frac{T^\gamma}{[(1 - F_h)\Gamma(\gamma+1) - T^\gamma F_f]} E_\delta \left(\frac{T^\delta b^\beta K_0 F_g \Gamma(\gamma+1)}{\Gamma(\beta+1)[(1 - F_h)\Gamma(\gamma+1) - T^\gamma F_f]} \right).$$

47 Thus, the problem (1)-(2) is Ulam-Hyers Rassias stable.

5. Positive solutions, maximal and minimal solutions, and continuation theorem

51 In the current section, we have established the conditions for the existence of positive solutions, maximal and
52 minimal solutions, and continuation theorem for the problem (1)-(2).

1 5.1. Positive solutions. Assumptions

2
3 **AP1:** The functions $h : I \times J \times \mathbb{R}^+ \rightarrow \mathbb{R}^+$, $f : I \times J \times \mathbb{R}^+ \rightarrow \mathbb{R}^+$, $g : I \times J \times \mathbb{R}^+ \rightarrow \mathbb{R}^+$ and $K : G \rightarrow \mathbb{R}^+$.

4 **AP2:** There exist $m_1, m_2, m_3, M_1, M_2, M_3 > 0$ such that $m_1 \leq h \leq M_1$, $m_2 \leq f \leq M_2$, and $m_3 \leq g \leq M_3$, for every
5 $(x, t) \in I \times J$. Let $m = \min\{m_1, m_2, m_3\}$ and $M = \max\{M_1, M_2, M_3\}$.

6
7 Let $D \subset E$ be a cone defined by $D = \{\vartheta \in E : \vartheta(\zeta, x) \geq 0, \|(\zeta, x)\| \leq p\}$. Then (E, D) forms an ordered
8 Banach space. We have the following theorem if we assume that $\Lambda : D \rightarrow D$ be the operator defined as in the
9 equation (10).

10 **Theorem 5.1.** Assume that assumptions AP1 and AP2 are satisfied. Then Λ is completely continuous.

11
12 **Proof.** According to Theorem 3.1, the operator Λ is bounded mapping. We will demonstrate the continuity of
13 $\Lambda : D \rightarrow D$. Let $\vartheta \in D$, where $\|\vartheta\| \leq r$. Let $\tilde{D} = \{\tilde{\vartheta} \in D : \|\vartheta - \tilde{\vartheta}\| \leq \tilde{r}\}$. Then $\|\tilde{\vartheta}\| \leq r + \tilde{r} := r_0, \forall \tilde{\vartheta} \in \tilde{D}$.

14 Since h, f, g , and k are continuous on $I \times J$, then it uniformly continuous there. Therefore, for given $\varepsilon > 0$,
15 there exist $r_1 > 0$ ($r_1 < \tilde{r}$) such that

$$16 \quad \|h(\zeta, x, \vartheta(\zeta, x)) - h(\zeta, x, \tilde{\vartheta}(\zeta, x))\| < \frac{\varepsilon}{\tilde{K}},$$

$$17 \quad \|f(\zeta, x, \vartheta(\zeta, x)) - f(\zeta, x, \tilde{\vartheta}(\zeta, x))\| < \frac{\varepsilon}{\tilde{K}},$$

18 and

$$19 \quad \|g(\zeta, x, \vartheta(\zeta, x)) - g(\zeta, x, \tilde{\vartheta}(\zeta, x))\| < \frac{\varepsilon}{\tilde{K}},$$

20
21 for $\|\vartheta - \tilde{\vartheta}\| < r_1, (\zeta, x) \in I \times J$. If $\|\vartheta - \tilde{\vartheta}\| < r_1$, then $\tilde{\vartheta} \in \tilde{D}$ and $\|\tilde{\vartheta}\| < r_0$. As $\tilde{\vartheta} \in \tilde{D} \subset D, \|\tilde{\vartheta}\| \leq r_0$.
22 Similarly $\|\vartheta\| \leq r_0$. Since we have $\|\Lambda\vartheta - \Lambda\tilde{\vartheta}\| < \varepsilon$, it follows that Λ is continuous. Consequently, Λ has a fixed
23 point.

24
25 **Theorem 5.2.** Assume that assumptions AP1 and AP2 are satisfied. Then the problem (1)-(2) has at least one
26 positive solution.

27
28 **Proof.** Let $D_1 = \{\vartheta \in E : \|\vartheta\| \leq K_1 + \tilde{K}rM\}$ and $D_2 = \{\vartheta \in E : \|\vartheta\| \leq K_1 + \tilde{K}rm\}$. For $\vartheta \in D \cap \partial D_2$,
29 we have $0 \leq \vartheta(\zeta, x) \leq K_1 + \tilde{K}rM, (\zeta, x) \in I \times J$. Since $h(\zeta, x, \vartheta(\zeta, x)) \leq M, f(\zeta, x, \vartheta(\zeta, x)) \leq M$, and
30 $g(\zeta, x, \vartheta(\zeta, x)) \leq M$, we have

$$31 \quad \Lambda\vartheta(\zeta, x) = \vartheta_0(\zeta) + h(\zeta, x, \vartheta(\zeta, x)) + \frac{1}{\Gamma(\gamma)} \int_0^x (x-\rho)^{\gamma-1} f(\zeta, x, \vartheta(\zeta, x)) d\rho$$

$$32 \quad + \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \int_0^x \int_0^\zeta (x-\rho)^{\delta-1} (\zeta-\varsigma)^{\beta-1} K(\zeta, x, \varsigma, \rho) g(\zeta, \rho, \vartheta(\zeta, \rho)) d\varsigma d\rho$$

$$33 \quad \|\Lambda\vartheta(\zeta, x)\| \leq \left[M_\vartheta + M_h + M_f \frac{T^\gamma}{\Gamma(\gamma+1)} + K_0 M_g \frac{T^\delta}{\Gamma(\delta+1)} \frac{b^\beta}{\Gamma(\beta+1)} \right]$$

$$34 \quad + \left[F_h + F_f \frac{T^\gamma}{\Gamma(\gamma+1)} + K_0 F_g \frac{T^\delta}{\Gamma(\delta+1)} \frac{b^\beta}{\Gamma(\beta+1)} \right] r$$

$$35 \quad \leq K_1 + \tilde{K}rM,$$

36 where $\tilde{K} = \left[1 + \frac{T^\gamma}{\Gamma(\gamma+1)} + K_0 \frac{T^\delta}{\Gamma(\delta+1)} \frac{b^\beta}{\Gamma(\beta+1)} \right]$.

37
38 Hence, $\|\Lambda\vartheta\| \leq \|\vartheta\|$. On the other hand, for $\vartheta \in D \cap \partial D_1$, we have $0 \leq \vartheta(\zeta, x) \leq K_1 + \tilde{K}rm, (\zeta, x) \in I \times J$.
39 As a result of the fact that $h(\zeta, x, \vartheta(\zeta, x)) \geq m, f(\zeta, x, \vartheta(\zeta, x)) \geq m$, and $g(\zeta, x, \vartheta(\zeta, x)) \geq m$, we have
40 $\|\Lambda\vartheta\| \geq K_1 + \tilde{K}rm = \|\vartheta\|$, (see Theorem 1.2 [23]).

41
42 Consequently, the operator Λ has a fixed point in $D \cap (\bar{D}_2 \setminus D_1)$. Thus the problem (1)-(2) has at least one
43 positive solution.

Theorem 5.3. Let $h : I \times J \times \mathbb{R}^+ \rightarrow \mathbb{R}^+$, $f : I \times J \times \mathbb{R}^+ \rightarrow \mathbb{R}^+$, and $g : I \times J \times \mathbb{R}^+ \rightarrow \mathbb{R}^+$ be continuous and increasing functions for each $(\zeta, x) \in I \times J$. Let there exist c_0 and d_0 satisfying ${}_0^C D_x^\gamma c_0 \leq c_0$, ${}_0^C D_x^\gamma d_0 \geq d_0$ and $0 \leq c_0 \leq d_0$, $(\zeta, x) \in I \times J$. Then problem (1)-(2) has a positive solution.

Proof. Let $c, d \in D$ such that $c < d$, then we have

$$\begin{aligned} \Lambda c(\vartheta, x) &= \vartheta_0(\zeta) + h(\zeta, x, c(\zeta, x)) + \frac{1}{\Gamma(\gamma)} \int_0^x (x-\rho)^{\gamma-1} f(\zeta, x, c(\zeta, \rho)) d\rho \\ &\quad + \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \int_0^x \int_0^\zeta (x-\rho)^{\delta-1} (\zeta-\varsigma)^{\beta-1} K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, c(\varsigma, \rho)) d\varsigma d\rho \\ &\leq \vartheta_0(\zeta) + h(\zeta, x, d(\zeta, x)) + \frac{1}{\Gamma(\gamma)} \int_0^x (x-\rho)^{\gamma-1} f(\zeta, x, d(\zeta, \rho)) d\rho \\ &\quad + \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \int_0^x \int_0^\zeta (x-\rho)^{\delta-1} (\zeta-\varsigma)^{\beta-1} K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, d(\varsigma, \rho)) d\varsigma d\rho \\ &= \Lambda d(\zeta, x). \end{aligned}$$

Therefore $\Lambda c(\zeta, x) \leq \Lambda d(\zeta, x)$, $\forall (\zeta, x) \in I \times J$, which gives $\Lambda c \leq \Lambda d$. As there exist c_0, d_0 such that $0 \leq c_0 \leq d_0$, with $\Lambda c_0 \leq c_0$, $\Lambda d_0 \geq d_0$, (see Theorem 1.3 [23]) Λ is compact and has a fixed point in $\langle c, d \rangle$.

Therefore, according to Theorem 1.3 [23] $\Lambda : \langle c_0, d_0 \rangle \rightarrow \langle c_0, d_0 \rangle$ is compact. Hence Λ has a fixed point $e \in \langle c, d \rangle$, which is the positive solution. This supports the argument.

5.2. Maximal and minimal solutions theorems for the problem (1)-(2). In the current section, we investigate the existence of both maximal and minimal solutions for the problem (1)-(2).

Definition 5. Let $l(\zeta, x)$ be a solution of problem (1)-(2) in $I \times J$. If the inequality $\vartheta(\zeta, x) \leq l(\zeta, x)$, $(\zeta, x) \in I \times J$, holds for every solution of problem (1)-(2) define on $(\zeta, x) \in I \times J$, then $l(\zeta, x)$ is said to be a maximal solution of problem (1)-(2).

Definition 6. Let $\tilde{l}(\zeta, x)$ be a solution of problem (1)-(2) in $I \times J$. If the inequality $\vartheta(\zeta, x) \geq \tilde{l}(\zeta, x)$, $(\zeta, x) \in I \times J$, holds for every solution of problem (1)-(2) define on $(\zeta, x) \in I \times J$, then $\tilde{l}(\zeta, x)$ is said to be a minimal solution of problem (1)-(2).

Theorem 5.4. Suppose $h : I \times J \times \mathbb{R}^+ \rightarrow \mathbb{R}^+$, $f : I \times J \times \mathbb{R}^+ \rightarrow \mathbb{R}^+$, $g : I \times J \times \mathbb{R}^+ \rightarrow \mathbb{R}^+$, and $K : G \rightarrow \mathbb{R}^+$ are continuous and non-decreasing functions defined on the set E . Let q_1 and q_2 be two positive constants such that $q_1 < q_2$. If the following inequalities hold:

$$\frac{q_1}{\varepsilon + \vartheta_0(\zeta) + h(\zeta, x, q_1) + {}_0 I_x^\gamma f(\zeta, \rho, q_1) + {}_0 I_x^\delta {}_0 I_\zeta^\beta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, q_1)} < 1 < \frac{q_2}{\varepsilon + \vartheta_0(\zeta) + h(\zeta, x, q_2) + {}_0 I_x^\gamma f(\zeta, \rho, q_2) + {}_0 I_x^\delta {}_0 I_\zeta^\beta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, q_2)}.$$

Then there exists a maximal and minimal solution of problem (1)-(2) on $I \times J$.

Proof. The fractional integral equation of the problem (1)-(2) is

$$\vartheta(\zeta, x) = \vartheta_0(\zeta) + h(\zeta, x, \vartheta(\zeta, x)) + {}_0 I_x^\gamma f(\zeta, \rho, \vartheta(\zeta, \rho)) + {}_0 I_x^\delta {}_0 I_\zeta^\beta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)).$$

Consider the fractional integral equation

$$(17) \quad \vartheta(\zeta, x) = \varepsilon + \vartheta_0(\zeta) + h(\zeta, x, \vartheta(\zeta, x)) + {}_0 I_x^\gamma f(\zeta, \rho, \vartheta(\zeta, \rho)) + {}_0 I_x^\delta {}_0 I_\zeta^\beta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)),$$

where $\varepsilon > 0$. Then $\vartheta(\zeta, x)$ given by equation (17) is solution of problem (1)-(2) in (q_1, q_2) , $(\zeta, x) \in I \times J$, for some constants $q_1, q_2 > 0$ such that

$$\frac{q_1}{\varepsilon + \vartheta_0(\zeta) + h(\zeta, x, q_1) + {}_0 I_x^\gamma f(\zeta, \rho, q_1) + {}_0 I_x^\delta {}_0 I_\zeta^\beta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, q_1)} < 1 < \frac{q_2}{\varepsilon + \vartheta_0(\zeta) + h(\zeta, x, q_2) + {}_0 I_x^\gamma f(\zeta, \rho, q_2) + {}_0 I_x^\delta {}_0 I_\zeta^\beta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, q_2)}.$$

1 Now, let $0 < \varepsilon_2 < \varepsilon_1 \leq \varepsilon$. Then we have $\vartheta_{\varepsilon_2}(0, 0) < \vartheta_{\varepsilon_1}(0, 0)$. Thus we have to show that

$$2$$

$$3$$

$$4 \quad (18) \quad \vartheta_{\varepsilon_2}(\zeta, x) < \vartheta_{\varepsilon_1}(\zeta, x), \quad \forall (\zeta, x) \in I \times J.$$

5 Consider it to be false. Then there exist a (ζ_1, x_1) such that $\vartheta_{\varepsilon_2}(\zeta_1, x_1) = \vartheta_{\varepsilon_1}(\zeta_1, x_1)$ and $\vartheta_{\varepsilon_2}(\zeta, x) < \vartheta_{\varepsilon_1}(\zeta, x)$,
6 $\forall (\zeta, x) \in I \times J$. Since h, f, g are monotonic non-decreasing function in ϑ , it follows that

$$7$$

$$8 \quad h(\zeta, x, \vartheta_{\varepsilon_2}(\zeta, x)) \leq h(\zeta, x, \vartheta_{\varepsilon_1}(\zeta, x)),$$

$$9$$

$$10 \quad f(\zeta, x, \vartheta_{\varepsilon_2}(\zeta, x)) \leq f(\zeta, x, \vartheta_{\varepsilon_1}(\zeta, x)),$$

11 and

$$12$$

$$13 \quad g(\zeta, x, \vartheta_{\varepsilon_2}(\zeta, x)) \leq g(\zeta, x, \vartheta_{\varepsilon_1}(\zeta, x)).$$

14 Consequently, using equation (17), we get

$$15$$

$$16 \quad \vartheta_{\varepsilon_2}(\zeta_1, x_1) = \varepsilon_2 + \vartheta_0(\zeta_1) + h(\zeta_1, x_1, \vartheta_{\varepsilon_2}(\zeta_1, x_1)) + {}_0I_{x_1}^{\gamma} f(\zeta_1, \rho, \vartheta_{\varepsilon_2}(\zeta_1, \rho))$$

$$17 \quad + {}_0I_{x_1}^{\delta} {}_0I_{\zeta_1}^{\beta} K(\zeta_1, x_1, \varsigma, \rho) g(\varsigma, \rho, \vartheta_{\varepsilon_2}(\varsigma, \rho))$$

$$18 \quad < \varepsilon_1 + \vartheta_0(\zeta_1) + h(\zeta_1, x_1, \vartheta_{\varepsilon_1}(\zeta_1, x_1)) + {}_0I_{x_1}^{\gamma} f(\zeta_1, \rho, \vartheta_{\varepsilon_1}(\zeta_1, \rho))$$

$$19 \quad + {}_0I_{x_1}^{\delta} {}_0I_{\zeta_1}^{\beta} K(\zeta_1, x_1, \varsigma, \rho) g(\varsigma, \rho, \vartheta_{\varepsilon_1}(\varsigma, \rho))$$

$$20 \quad = \vartheta_{\varepsilon_1}(\zeta_1, x_1),$$

21 which defies the fact that $\vartheta_{\varepsilon_2}(\zeta_1, x_1) = \vartheta_{\varepsilon_1}(\zeta_1, x_1)$. As a result inequality (18) is true. That is, there exists a
22 decreasing sequence ε_n such that $\varepsilon_n \rightarrow 0$ as $n \rightarrow \infty$ and $\lim_{n \rightarrow \infty} \vartheta_{\varepsilon_n}(\zeta, x)$ exists uniformly in $(\zeta, x) \in I \times J$. We write
23 this limiting value by $l(\zeta, x)$. Evidently, by the uniform continuity of h, f , and g , the equation

$$24$$

$$25 \quad \vartheta_{\varepsilon_n}(\zeta_1, x_1) = \varepsilon_n + \vartheta_0(\zeta_1) + h(\zeta_1, x_1, \vartheta_{\varepsilon_n}(\zeta_1, x_1)) + {}_0I_{x_1}^{\gamma} f(\zeta_1, \rho, \vartheta_{\varepsilon_n}(\zeta_1, \rho))$$

$$26 \quad + {}_0I_{x_1}^{\delta} {}_0I_{\zeta_1}^{\beta} K(\zeta_1, x_1, \varsigma, \rho) g(\varsigma, \rho, \vartheta_{\varepsilon_n}(\varsigma, \rho)),$$

27 yields that $l(\zeta, x)$ is a solution of problem (1)-(2), let $\vartheta(\zeta, x)$ be any solution of problem (1)-(2) in $(\zeta, x) \in I \times J$.
28 Then

$$29$$

$$30 \quad \vartheta(\zeta, x) < \varepsilon + \vartheta_0(\zeta) + h(\zeta, x, \vartheta(\zeta, x)) + {}_0I_x^{\gamma} f(\zeta, \rho, \vartheta(\zeta, \rho))$$

$$31 \quad + {}_0I_x^{\delta} {}_0I_{\zeta}^{\beta} K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)),$$

$$32 \quad = \vartheta_{\varepsilon}(\zeta, x).$$

33 Since the maximal solution is unique, it is clear that $\vartheta_{\varepsilon}(\zeta, x)$ tends to $l(\zeta, x)$ uniformly in $(\zeta, x) \in I \times J$ as
34 $\varepsilon \rightarrow 0$, which indicates the existence of maximal solution for the problem (1)-(2). Similarly, we can demonstrate
35 the existence of the minimum solution.

36
37 **5.3. Continuation theorem.** This section examines the continuation of the solution to the problem (1)-(2) for the
38 particular case $0 < \gamma \leq 1$, $\alpha = 0$, and $\beta = 1$, then the corresponding integral equation of problem (1)-(2) reduces
39 to

$$40$$

$$41 \quad \vartheta(\zeta, x) = \vartheta_0(\zeta) + h(\zeta, x, \vartheta(\zeta, x)) + {}_0I_x^{\gamma} f(\zeta, \rho, \vartheta(\zeta, \rho))$$

$$42 \quad + {}_0I_x^{\gamma} \int_0^{\zeta} K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)) d\varsigma.$$

43
44 **Theorem 5.5.** Let $h(\zeta, x, \vartheta(\zeta, x)), f(\zeta, x, \vartheta(\zeta, x)), g(\zeta, x, \vartheta(\zeta, x))$ and $K(\zeta, x, \varsigma, \rho)$ are continuous functions
45 on E , then

$$46$$

$$47 \quad \lim_{\gamma \rightarrow 0} {}_0I_x^{\gamma} \left\{ f(\zeta, \rho, \vartheta(\zeta, \rho)) + \int_0^{\zeta} K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)) d\varsigma \right\}$$

$$48 \quad = {}_0I_x^{\zeta} \left\{ f(\zeta, \rho, \vartheta(\zeta, \rho)) + \int_0^{\zeta} K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)) d\rho \right\}.$$

Proof. We have

$$\begin{aligned}
 & \left| {}_0I_x^\gamma \left\{ f(\zeta, \rho, \vartheta(\zeta, \rho)) + \int_0^\zeta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)) d\varsigma \right\} \right. \\
 & \quad \left. - {}_0I_x^z \left\{ f(\zeta, \rho, \vartheta(\zeta, \rho)) + \int_0^\zeta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)) d\varsigma \right\} \right| \\
 & \leq \left| \frac{1}{\Gamma(\gamma)} \int_0^x (x-\rho)^{\gamma-1} f(\zeta, \rho, \vartheta(\zeta, \rho)) d\rho - \frac{1}{\Gamma(z)} \int_0^x (x-\rho)^{z-1} f(\zeta, \rho, \vartheta(\zeta, \rho)) d\rho \right| \\
 & \quad + \left| \frac{1}{\Gamma(\gamma)} \int_0^x \int_0^\zeta (x-\rho)^{\gamma-1} K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)) d\varsigma d\rho \right. \\
 & \quad \left. - \frac{1}{\Gamma(z)} \int_0^x \int_0^\zeta (x-\rho)^{z-1} K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)) d\varsigma d\rho \right| \\
 & = \left| \left(\frac{1}{\Gamma(\gamma)} \int_0^x (x-\rho)^{\gamma-1} - \frac{1}{\Gamma(z)} \int_0^x (x-\rho)^{z-1} \right) f(\zeta, \rho, \vartheta(\zeta, \rho)) d\rho \right| \\
 & \quad + \left| \left(\frac{1}{\Gamma(\gamma)} \int_0^x (x-\rho)^{\gamma-1} - \frac{1}{\Gamma(z)} \int_0^x (x-\rho)^{z-1} \right) \int_0^\zeta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta(\varsigma, \rho)) d\varsigma d\rho \right|.
 \end{aligned}$$

Since $\frac{1}{\Gamma(\gamma)} \int_0^x (x-\rho)^{\gamma-1} \rightarrow \frac{1}{\Gamma(z)} \int_0^x (x-\rho)^{z-1}$, as $\gamma \rightarrow z$, $z = 1, 2, 3, \dots$
we get the result.

Theorem 5.6. If the solution $\vartheta_1(\zeta, x)$ of eq. (19) exists, and if $\vartheta_\gamma(\zeta, x)$ is the solution of problem (1)-(2), then

$$\lim_{\gamma \rightarrow 1} \vartheta_\gamma(\zeta, x) = \vartheta_1(\zeta, x)$$

Proof. We have

$$\begin{aligned}
 (20) \quad \vartheta_\gamma(\zeta, x) &= \vartheta_0(\zeta) + h(\zeta, x, \vartheta_\gamma(\zeta, x)) + {}_0I_x^\gamma f(\zeta, \rho, \vartheta_\gamma(\zeta, \rho)) \\
 & \quad + {}_0I_x^\gamma \int_0^\zeta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta_\gamma(\varsigma, \rho)) d\varsigma
 \end{aligned}$$

and

$$\begin{aligned}
 (21) \quad \vartheta_1(\zeta, x) &= \vartheta_0(\zeta) + h(\zeta, x, \vartheta_1(\zeta, x)) + {}_0I_x^1 f(\zeta, \rho, \vartheta_1(\zeta, \rho)) \\
 & \quad + {}_0I_x^1 \int_0^\zeta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta_1(\varsigma, \rho)) d\varsigma.
 \end{aligned}$$

Then

$$\begin{aligned}
 & \| \vartheta_\gamma(\zeta, x) - \vartheta_1(\zeta, x) \| \\
 & \leq \| h(\zeta, x, \vartheta_\gamma(\zeta, x)) - h(\zeta, x, \vartheta_1(\zeta, x)) \| + \| {}_0I_x^\gamma f(\zeta, \rho, \vartheta_\gamma(\zeta, \rho)) - {}_0I_x^1 f(\zeta, \rho, \vartheta_1(\zeta, \rho)) \| \\
 & \quad + \left\| {}_0I_x^\gamma \int_0^\zeta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta_\gamma(\varsigma, \rho)) d\varsigma - {}_0I_x^1 \int_0^\zeta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta_1(\varsigma, \rho)) d\varsigma \right\| \\
 & \leq F_h \| \vartheta_\gamma(\zeta, x) - \vartheta_1(\zeta, x) \| + \frac{T^\gamma}{\Gamma(\gamma+1)} F_f \| \vartheta_\gamma(\zeta, x) - \vartheta_1(\zeta, x) \| \\
 & \quad + \| {}_0I_x^\gamma f(\zeta, \rho, \vartheta_1(\zeta, \rho)) - {}_0I_x^1 f(\zeta, \rho, \vartheta_1(\zeta, \rho)) \| + \frac{T^\gamma}{\Gamma(\gamma+1)} F_g K_0 \| \vartheta_\gamma(\zeta, x) - \vartheta_1(\zeta, x) \| \\
 & \quad + \left\| {}_0I_x^\gamma \int_0^\zeta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta_1(\varsigma, \rho)) d\varsigma - {}_0I_x^1 \int_0^\zeta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta_1(\varsigma, \rho)) d\varsigma \right\|.
 \end{aligned}$$

1 Thus,

$$\begin{aligned} 2 & \\ 3 & \|\vartheta_\gamma - \vartheta_1\| \leq \left[1 - F_h - \frac{T^\gamma}{\Gamma(\gamma+1)} F_f - \frac{T^\gamma}{\Gamma(\gamma+1)} F_g K_0 \right]^{-1} \left\{ \left\| {}_0 I_x^\gamma f(\zeta, \rho, \vartheta_1(\zeta, \rho)) - {}_0 I_x^1 f(\zeta, \rho, \vartheta_1(\zeta, \rho)) \right\| \right. \\ 4 & \\ 5 & \quad \left. + \left\| {}_0 I_x^\gamma \int_0^\zeta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta_1(\varsigma, \rho)) d\varsigma - {}_0 I_x^1 \int_0^\zeta K(\zeta, x, \varsigma, \rho) g(\varsigma, \rho, \vartheta_1(\varsigma, \rho)) d\varsigma \right\| \right\}, \\ 6 & \\ 7 & \end{aligned}$$

8 where $F_h + \frac{T^\gamma}{\Gamma(\gamma+1)} F_f + \frac{T^\gamma}{\Gamma(\gamma+1)} F_g K_0 < 1$ (from the uniqueness theorem). The proof is complete as we have
9 $\|\vartheta_\gamma - \vartheta_1\| \rightarrow 0$ as $\gamma \rightarrow 1$, which is in accordance with Theorem 5.5.

11 6. Numerical examples

12 **Exmample 1.** Consider the problem

$$14 \quad (22) \quad {}_0^C D_x^\gamma \left[\vartheta(\zeta, x) - \cos \pi \zeta \frac{x^2}{4} \sin \vartheta(\zeta, x) \right] = \frac{e^{-\zeta^2 x}}{10} \vartheta(\zeta, x) + {}_0 I_x^\alpha {}_0 I_\zeta^\beta \frac{x \zeta^2 e^\zeta (1 + \rho^2)}{8} \frac{\zeta^4 \rho^2}{16} \vartheta(\zeta, \rho)$$

16 with the initial condition $\vartheta(\zeta, 0) = \vartheta_0(\zeta) = \frac{\zeta}{16}$, and $(\zeta, x) \in [0, 1] \times [0, 1]$.

17 Here we have,

$$19 \quad h(\zeta, x, \vartheta(\zeta, x)) = \cos \pi \zeta \frac{x^2}{4} \sin \vartheta(\zeta, x),$$

$$21 \quad f(\zeta, x, \vartheta(\zeta, x)) = \frac{e^{-\zeta^2 x}}{10} \vartheta(\zeta, x),$$

$$23 \quad K(\zeta, x, \varsigma, \rho) = \frac{x \zeta^2 e^\zeta (1 + \rho^2)}{8}$$

24 and

$$26 \quad g(\zeta, x, \vartheta(\zeta, x)) = \frac{\zeta^4 x^2}{16} \vartheta(\zeta, x).$$

27 As all the assumptions are satisfying for the functions h , f , K , and g , therefore the values are given as $F_h = \frac{1}{4}$,
28 $F_f = \frac{1}{10}$, $K_0 = \frac{e}{4}$, and $F_g = \frac{1}{16}$.

29 This leads to

$$31 \quad K^* = \frac{1}{4} + \left(\frac{1}{10} \right) \frac{1}{\Gamma(\gamma+1)} + \left(\frac{e}{4} \right) \left(\frac{1}{16} \right) \frac{1}{\Gamma(\delta+1)\Gamma(\beta+1)}$$

32 Case I: For a particular value of $\alpha = \frac{1}{8}$, $\beta = \frac{1}{4}$, and $\gamma = \frac{1}{8}$, this gives

$$\begin{aligned} 34 \quad K^* &= \frac{1}{4} + \left(\frac{1}{10} \right) \frac{1}{\Gamma(9/8)} + \left(\frac{e}{4} \right) \left(\frac{1}{16} \right) \frac{1}{\Gamma(5/4)\Gamma(5/4)}. \\ 35 & \\ 36 & = 0.45958 < 1. \end{aligned}$$

37 Consequently, the problem has a unique solution.

38 Case II: For a particular value of $\alpha = \frac{1}{4}$, $\beta = \frac{1}{2}$, and $\gamma = \frac{1}{3}$, this gives

$$\begin{aligned} 40 \quad K^* &= \frac{1}{4} + \left(\frac{1}{10} \right) \frac{1}{\Gamma(4/3)} + \left(\frac{e}{4} \right) \left(\frac{1}{16} \right) \frac{1}{\Gamma(19/12)\Gamma(3/2)} \\ 41 & \\ 42 & = 0.41573 < 1. \end{aligned}$$

43 Consequently, the problem has a unique solution.

44 The approximate solution to the problem (23) is given by

$$\begin{aligned} 46 \quad \vartheta_n(\zeta, x) &= \frac{\zeta}{16} + \cos \pi \zeta \frac{x^2}{4} \sin \vartheta_{n-1}(\zeta, x) + \frac{1}{\Gamma(\gamma)} \int_0^x (x-\rho)^{\gamma-1} \frac{e^{-\zeta^2 \rho}}{10} \vartheta_{n-1}(\zeta, \rho) d\rho \\ 47 & \\ 48 & \quad + \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \int_0^x \int_0^\zeta (x-\rho)^{\delta-1} (\zeta-\varsigma)^{\beta-1} \frac{x \zeta^2 e^\zeta (1 + \rho^2)}{8} \frac{\zeta^4 \rho^2}{16} \vartheta_{n-1}(\varsigma, \rho) d\varsigma d\rho. \end{aligned}$$

49 For $n = 1$, we have the approximate solution ϑ_1 for Case I and II as shown in Figures 1 and 2, respectively.

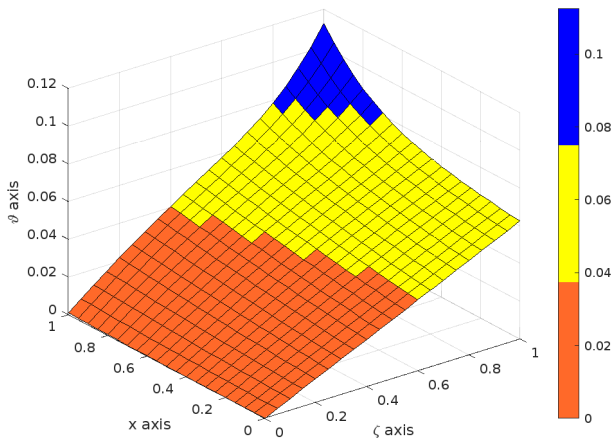


Figure 1: Graph for the approximate solution ϑ_1 of problem (22), where $\alpha = \frac{1}{8}$, $\beta = \frac{1}{4}$, $\gamma = \frac{1}{8}$.

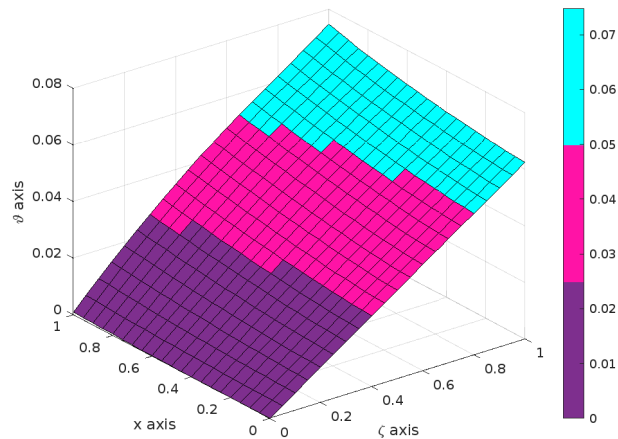


Figure 2: Graph for the approximate solution ϑ_1 of problem (22), where $\alpha = \frac{1}{4}$, $\beta = \frac{1}{2}$, $\gamma = \frac{1}{3}$.

Figure 1 and Figure 2 represent the approximate solution ϑ_1 for the problem (22), but they correspond to different fractional order values. For the particular values of α , β , and γ , the first figure covers a broader range than the second figure.

Exmample 2. Consider the problem

$$(23) \quad {}_0^C D_x^\gamma \left[\vartheta(\zeta, x) - \sin 2x \frac{e^{-\zeta x}}{10} (2 + \vartheta(\zeta, x)) \right] = \frac{x\zeta^3}{4} (1 + \vartheta(\zeta, x)) \\ + {}_0 I_x^\alpha {}_0 I_\zeta^\beta \rho \zeta^2 \frac{(\zeta^2 + 3)}{16} \left(x\zeta + \frac{e^{(\rho^2 + \zeta)}}{12} \vartheta(\zeta, \rho) \right)$$

with the initial condition $\vartheta(\zeta, 0) = \vartheta_0(\zeta) = 0$. and $(\zeta, x) \in [0, 1] \times [0, 1]$.

Here we have,

$$h(\zeta, x, \vartheta(\zeta, x)) = \sin 2x \frac{e^{-\zeta x}}{10} (2 + \vartheta(\zeta, x)),$$

$$f(\zeta, x, \vartheta(\zeta, x)) = \frac{x\zeta^3}{4} (1 + \vartheta(\zeta, x)),$$

$$K(\zeta, x, \zeta, \rho) = \rho \zeta^2 \frac{(\zeta^2 + \zeta x + 3)}{16},$$

and

$$g(\zeta, x, \vartheta(\zeta, x)) = x\zeta + \frac{e^{(x^2 + \zeta)}}{12} \vartheta(\zeta, x).$$

As all the assumptions are satisfying for the functions h , f , K , and g , therefore the values are given as $F_h = \frac{1}{10}$,

$F_f = \frac{1}{4}$, $K_0 = \frac{5}{16}$, and $F_g = \frac{e^2}{12}$.

This leads to

$$K^* = \frac{1}{10} + \left(\frac{1}{4}\right) \frac{1}{\Gamma(\gamma+1)} + \left(\frac{5}{16}\right) \left(\frac{e^2}{12}\right) \frac{1}{\Gamma(\delta+1)\Gamma(\beta+1)}$$

Case I: For a particular value of $\alpha = \frac{1}{10}$, $\beta = \frac{1}{4}$, and $\gamma = \frac{1}{5}$, it gives

$$K^* = \frac{1}{10} + \left(\frac{1}{4}\right) \frac{1}{\Gamma(6/5)} + \left(\frac{5}{16}\right) \left(\frac{e^2}{12}\right) \frac{1}{\Gamma(13/10)\Gamma(5/4)} \\ = 0.608828 < 1.$$

Consequently, the problem has a unique solution.

Case II: For a particular value of $\alpha = \frac{1}{2}$, $\beta = \frac{1}{7}$, and $\gamma = \frac{1}{3}$, it gives

$$K^* = \frac{1}{10} + \left(\frac{1}{4}\right) \frac{1}{\Gamma(1/3)} + \left(\frac{5}{16}\right) \left(\frac{e^2}{12}\right) \frac{1}{\Gamma(11/6)\Gamma(8/7)}$$

$$= 0.455738 < 1.$$

Consequently, the problem has a unique solution.

The approximate solution to the problem (23) is given by

$$\begin{aligned} \vartheta_n(\zeta, x) = & \sin 2x \frac{e^{-\zeta x}}{10} (2 + \vartheta_{n-1}(\zeta, x)) + \frac{1}{\Gamma(\gamma)} \int_0^x (x-\rho)^{\gamma-1} \frac{\rho \zeta^3}{4} (1 + \vartheta_{n-1}(\zeta, \rho)) d\rho \\ & + \frac{1}{\Gamma(\delta)} \frac{1}{\Gamma(\beta)} \int_0^x \int_0^\zeta (x-\rho)^{\delta-1} (\zeta-\varsigma)^{\beta-1} \rho \varsigma^2 \frac{(\zeta^2 + \varsigma^2)}{16} \left(\rho \varsigma + \frac{e^{(\rho^2 + \varsigma^2)}}{12} \vartheta_{n-1}(\zeta, \rho) \right) d\varsigma d\rho. \end{aligned}$$

For $n = 1$, we have the approximate solution ϑ_1 for Case I and II, as shown in Figures 3 and 4, respectively.

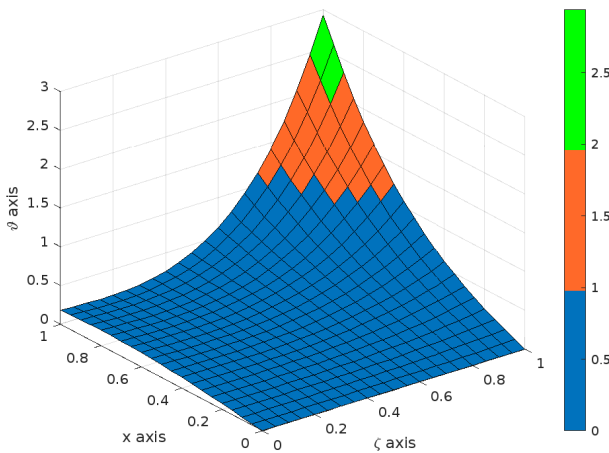


Figure 3: Graph for the approximate solution ϑ_1 of problem (23), where $\alpha = \frac{1}{10}$, $\beta = \frac{1}{4}$, $\gamma = \frac{1}{5}$.

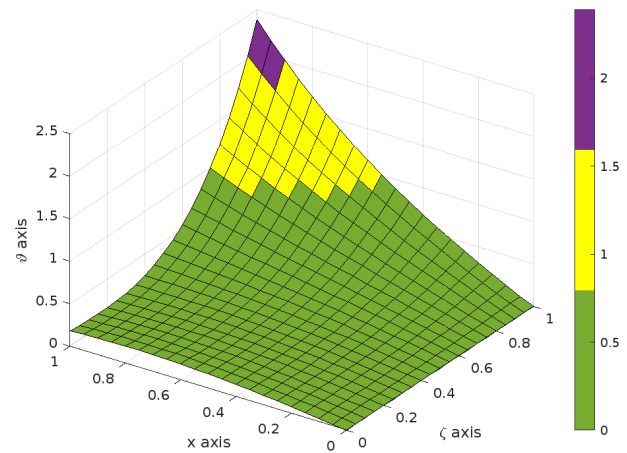


Figure 4: Graph for the approximate solution ϑ_1 of problem (23), where $\alpha = \frac{1}{2}$, $\beta = \frac{1}{7}$, $\gamma = \frac{1}{3}$.

Figure 3 and Figure 4 represent the approximate solution ϑ_1 for the problem (23), but they correspond to different fractional order values. For the particular values of α , β , and γ , the third figure covers a broader range compared to the fourth figure.

7. Conclusion

Two-dimensional IDEs have indeed attracted a lot of research interest in recent years due to their significance in various fields of science and engineering. Theoretical results and analytical and numerical solutions for these types of problems are of great interest to researchers. Several numerical methods have been developed for solving two-dimensional IDEs, including two-dimensional Triangular function, Haar wavelet, Tau method, and meshless methods.

In this paper, we have discussed the existence and uniqueness of the solution of the considered two-dimensional neutral integro-differential equation of fractional order by using Banach's and Krasnoselskii's fixed point theorems and then we have discussed Ulam-Hyers and Ulam-Hyers Rassias's stability of the considered problem. Additionally, we obtained a positive solution, maximal and minimal solution, and Continuation theorem. Validated our results with a few examples. In future work, we can find the numerical solution to the considered problem and establish qualitative properties for various types of two-dimensional integro-differential equations.

Appendix A. Coding for examples.

```

46 Figure 1. [X,Y] = meshgrid(0:0.05:1,0:0.05:1);
47 Z = 0.0625.*X + cos(pi.*X). * 0.015625.*Y.^2.*sin(0.0625.*Y) + 0.04444.*X.*exp(-X.^2). * Y.^1.125 +
48 0.017651.*X.^6.*25.*exp(-X). * Y.^3.*25.*(2.8444 + Y.^2.*2.471191);
49 surf(X,Y,Z)
50 colorbar
51 mycolors = [1 0 0; 1 1 0; 0 0 1];
52 colormap(mycolors);

```

```

1 Figure 2. [X,Y] = meshgrid(0:0.05:1,0:0.05:1);
2 Z = 0.0625.*X + cos(pi.*X). * 0.015625.*Y.^2.*sin(0.0625.*Y) + 0.028125.*X.*exp(-X.^2). * Y.^1.*.3333 +
3 0.005328.*X.^6.*.5.*exp(-X). * Y.^3.*.5833.* (0.83822 + Y.^2.*0.61245);
4 surf(X,Y,Z)
5 colorbar
6 mycolors = [1 0 0; 1 1 0; 0 0 1];
7 colormap(mycolors);

```

```

8
9 Figure 3. [X,Y] = meshgrid(0:0.05:1,0:0.05:1);
10 Z = 0.2.*exp(-X.*Y). * sin(2.*Y) + 1.04166667.* (X.^3). * Y.^1.*.14285714 + 0.36589.* (X.^2 + X.*Y + 3). *
11 X.^3.*.14285714.*Y.^2.*.833333;
12 surf(X,Y,Z)
13 colorbar
14 mycolors = [1 0 0; 1 1 0; 0 0 1];
15 colormap(mycolors);

```

```

16
17 Figure 4. [X,Y] = meshgrid(0:0.05:1,0:0.05:1);
18 Z = 0.2.*exp(-X.*Y). * sin(2.*Y) + 1.53125.* (X.^3). * Y.^1.*.14285714 + 0.157576569.* (X.^2 + X.*Y + 3). *
19 X.^3.*.14285714.*Y.^2.*.833333;
20 surf(X,Y,Z)
21 colorbar
22 mycolors = [1 0 0; 1 1 0; 0 0 1];
23 colormap(mycolors);

```

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