

ON COCOMPLEX STRUCTURES

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Introduction.

Let Γ be a pseudogroup of differentiable transformations of a manifold V and let M be a differentiable manifold. A Γ -atlas on M is a collection of local diffeomorphisms $\{\lambda_i; U_i\}$ of M into V which satisfies $\cup U_i = M$ and $\lambda_i \circ \lambda_j^{-1} \in \Gamma$ for all i and j such that $U_i \cap U_j \neq \emptyset$. Two Γ -atlases are said to be equivalent if their union is a Γ -atlas. An equivalence class of Γ -atlases is called a Γ -structure on M .

By an *almost* Γ -structure on a manifold M we mean, roughly speaking, a structure on M which is identified with a Γ -structure up to a certain order of contact at each point. It is a G -structure of a certain order.

We consider the following correspondences between structures on an even dimensional manifold and those on an odd dimensional one:

- (*) symplectic structure ———— (*) cosymplectic structure,
- (#) almost symplectic structure — (#) almost cosymplectic structure,
- (*) complex structure ———— (*) cocomplex structure,
- (#) almost complex structure — (#) almost cocomplex structure.

The (*)ed structures are Γ -structures for some Γ and the (#)ed structures are almost Γ -structures.

An almost cocomplex structure is defined by Sasaki [3] and called a (ϕ, ξ, η) -structure.

We shall give *modern foundations for cocomplex structures and almost cocomplex structures.*

§ 1. Preliminaries.

Let M be a differentiable manifold of dimension $2n+1$ and $F(M)$ the bundle of linear frames of M . Then $F(M)$ is a principal fibre bundle over M with structure group $GL(2n+1, \mathbb{R})$.

Let G be a subgroup of $GL(2n+1, \mathbb{R})$. A G -structure on M is a reduction of $F(M)$ to the group G .

Let $P_G(M)$ be a G -structure on M . We shall call a connection on $P_G(M)$ a G -connection.

Let \mathfrak{g} be the Lie algebra of G . The cohomology class c in $\text{Hom}(\mathbb{R}^{2n+1} \wedge \mathbb{R}^{2n+1}, \mathbb{R}^{2n+1}) / \partial \text{Hom}(\mathbb{R}^{2n+1}, \mathfrak{g})$ determined by the torsion form of a local G -connection is

Received June 19, 1967.

called the *first order structure tensor* of the G -structure $P_G(M)$.

§ 2. Cocomplex structures and almost cocomplex structures.

Suppose we are given in \mathbb{R}^{2n+1} an involutive differential system of codimension one and a complex structure on its integral manifolds. To fix our notations, let y^0, y^1, \dots, y^{2n} be the natural coordinate system of \mathbb{R}^{2n+1} and let

$$\alpha = dy^0$$

and

$$F = \sum_{i=1}^n \frac{\partial}{\partial y^i} \otimes dy^{i+n} - \sum_{i=1}^n \frac{\partial}{\partial y^{i+n}} \otimes dy^i.$$

Let \mathcal{L} be the sheaf of germs of all vector fields X on \mathbb{R}^{2n+1} which satisfy

$$L_X \alpha = 0$$

and

$$L_X F = 0,$$

where L_X denotes the Lie differentiation with respect to X .

Let $\mathcal{L}(0)$ be the stalk of \mathcal{L} at the origin 0 . Then $\mathcal{L}(0)$ is a *flat*, transitive filtered Lie algebra of infinite dimensions. The linear isotropy algebra \mathfrak{g} of $\mathcal{L}(0)$ is the linear Lie algebra

$$\left\{ \left(\begin{array}{c|c} 0 & 0 \dots 0 \\ \hline 0 & A \\ \vdots & \\ 0 & \end{array} \right) \mid A \in \mathfrak{gl}(n, \mathbb{C}) \right\}.$$

The Lie algebra \mathfrak{g} is involutive.

A diffeomorphism $f: U \rightarrow U'$, where U and U' are open subsets of \mathbb{R}^{2n+1} , is called a *cocomplex transformation* if it satisfies

$$f^* \alpha = \alpha$$

and

$$f_* \circ F = F \circ f_*.$$

The collection, Γ , of all such cocomplex transformations forms an infinite, continuous pseudogroup.

Let M be a differentiable manifold of dimension $2n+1$. A Γ -structure on M is called a *cocomplex structure*.

A cocomplex structure is the same as a $2n$ -dimensional involutive *complex* differential system. In other words, giving a cocomplex structure on M is the same as giving a closed 1-form ω and a tensor field J of type $(1, 1)$ on M which satisfy

$$\begin{aligned} \omega \circ J &= 0, \\ J^2 &= -I + Z \otimes \omega \end{aligned}$$

where Z is a unique vector field on M defined by

$$\omega(Z) = 1 \quad \text{and} \quad J(Z) = 0,$$

and

$$[JX, JY] - J[JX, Y] - J[X, JY] + J^2[X, Y] = 0$$

for any vector fields X and Y which satisfy $\omega(X) = \omega(Y) = 0$.

ω , J and Z can locally be written as

$$\begin{aligned} \omega &= dx^0, \\ J &= \sum_{i=1}^n \frac{\partial}{\partial x^i} \otimes dx^{i+n} - \sum_{i=1}^n \frac{\partial}{\partial x^{i+n}} \otimes dx^i, \\ Z &= \frac{\partial}{\partial x^0}. \end{aligned}$$

A local coordinate system in which ω , J and Z are written as above will be called an *admissible* coordinate.

Let Γ_0 be the subset of Γ consisting of the elements which leave the origin 0 invariant. Let $j: \Gamma_0 \rightarrow GL(2n+1, \mathbb{R})$ be defined as follows: for $f \in \Gamma_0$, $j(f)$ is the 1-jet determined by f . Let $G = j(\Gamma_0)$. Then G is a subgroup of $GL(2n+1, \mathbb{R})$ whose Lie algebra is \mathfrak{g} , the linear isotropy algebra of $\mathcal{L}(0)$. G is isomorphic with $GL(n, \mathbb{C})$.

Let M be a differentiable manifold of dimension $2n+1$. An *almost cocomplex structure* on M is, by definition, a reduction of the bundle of linear frames $F(M)$ to G , that is, a G -structure $P_G(M)$ on M .

Given a G -structure $P_G(M)$ on M , we can define a 1-form η and a tensor field ϕ of type $(1, 1)$ on M which satisfy

$$(1) \quad \eta \circ \phi = 0$$

and

$$(2) \quad \phi^2 = -I + \xi \otimes \eta,$$

where ξ is a unique vector field on M defined by

$$\eta(\xi) = 1 \quad \text{and} \quad \phi(\xi) = 0.$$

In fact, for each $x \in M$, let u be a point of $P_G(M)$ with $\pi(u) = x$, where $\pi: P_G(M) \rightarrow M$ is the projection. For any tangent vector X at x , we set

$$(3) \quad \eta_x(X) = \alpha(u^{-1}X)$$

and

$$(4) \quad \phi_x(X) = u(F(u^{-1}X)),$$

where we regard a frame u as a linear isomorphism of \mathbb{R}^{2n+1} onto $T_x(M)$.

From the properties of G , this definition is independent of the choice of u .

Conversely, given a pair of a 1-form η and a tensor field ϕ of type (1, 1) on M , let $P_G(M)$ be the set of all linear frames u which satisfy (3) and (4) for any tangent vector X at $x = \pi(u)$. Then $P_G(M)$ is a G -structure on M .

Thus giving a G -structure on M is the same as giving a pair of a 1-form η and a tensor field ϕ of type (1, 1) which satisfy (1) and (2).

Let M_0 be a manifold with a cocomplex structure. Since every Γ -structure gives rise canonically to an almost Γ -structure, M_0 has an almost cocomplex structure.

THEOREM 2.1. *Let $P_G(M_0)$ be the almost cocomplex structure associated with a cocomplex structure on M_0 . Then the first order structure tensor c vanishes.*

Proof. A representative of c is given by the torsion tensor of a G -connection. Let Π be a linear connection and ∇ the covariant differentiation with respect to Π . Let (ω, J) be the associated pair as before. Then Π is a G -connection if and only if

$$\nabla\omega = 0 \quad \text{and} \quad \nabla J = 0.$$

Using the local expressions

$$\omega = (1, 0, \dots, 0)$$

and

$$J = \left(\begin{array}{c|cc} 0 & 0 \cdots \cdots 0 & \\ \hline 0 & 0 & I_n \\ \vdots & & \\ 0 & -I_n & 0 \end{array} \right)$$

with respect to an admissible coordinate system $(x^0, x^1, \dots, x^{2n})$, we can easily see that there exists a G -connection without torsion.

Since the first order structure tensor c is independent of the choice of a G -connection, our assertion is now clear. (Q.E.D.)

§ 3. The integrability problem for almost cocomplex structures.

Let M be a differentiable manifold of dimension $2n+1$ and $P_G(M)$ a G -structure, an almost cocomplex structure, on M .

$P_G(M)$ is said to be *integrable* if it determines a cocomplex structure on M .

Then the answer to the integrability problem for an almost cocomplex structure is the following

THEOREM 3.1. *An almost cocomplex structure whose structure tensor of the first order vanishes is cocomplex.*

Proof. Let $P_G(M)$ be an almost cocomplex structure on M and (ϕ, η) the associated pair.

Let Π be a linear connection and ∇ the covariant differentiation with respect to Π . Then Π is a G -connection if and only if

$$\nabla\eta=0 \quad \text{and} \quad \nabla\phi=0.$$

Since the first order structure tensor of $P_G(M)$ vanishes, there exists a torsionfree G -connection.

In general, let Π be a torsionfree linear connection and α a differential form. Then

$$d\alpha = \mathcal{A}(\nabla\alpha),$$

where \mathcal{A} is the alternation operator. Hence, let Π be a torsionfree G -connection. Then we have

$$d\eta=0.$$

Hence the differential system defined by η is involutive.

We have to prove that ϕ gives rise to a complex structure on each integral manifold of η .

The equation (2) implies that ϕ is an almost complex structure on each integral manifold of η . Let N be the *Nijenhuis torsion tensor field* of ϕ and let X and Y be vector fields on an integral manifold. Then

$$\begin{aligned} N(X, Y) &= [\phi X, \phi Y] - \phi[\phi X, Y] - \phi[X, \phi Y] + \phi^2[X, Y] \\ &= [\phi X, \phi Y] - \phi[\phi X, Y] - \phi[X, \phi Y] - [X, Y], \end{aligned}$$

since $\eta([X, Y])=0$.

On the other hand, since Π is a torsionfree G -connection, we have

$$\nabla\phi=0$$

and

$$[X, Y] = \nabla_X Y - \nabla_Y X$$

for any X and Y . Therefore

$$\begin{aligned} N(X, Y) &= \nabla_{\phi X}(\phi Y) - \nabla_{\phi Y}(\phi X) - \phi(\nabla_{\phi X} Y - \nabla_Y(\phi X)) - \phi(\nabla_X(\phi Y) - \nabla_{\phi Y} X) - \nabla_X Y + \nabla_Y X \\ &= \phi^2(\nabla_Y X - \nabla_X Y) - (\nabla_X Y - \nabla_Y X) \\ &= -[Y, X] + \eta([Y, X]) \cdot \xi - [X, Y] \\ &= 0. \end{aligned}$$

This implies that ϕ defines a complex structure on each integral manifold of η . Hence (ϕ, η) determines a cocomplex structure. (Q.E.D.)

Let S be the *Sasakian torsion tensor* of ϕ [4]. Then

$$S = N + 2\xi \otimes d\eta.$$

Hence we have

COROLLARY. *If $d\eta=0$ and $S=0$, then the almost cocomplex structure is cocomplex.*

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