

## ROTATIONAL SYMMETRY OF RICCI SOLITONS IN HIGHER DIMENSIONS

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### Abstract

Let  $(M, g)$  be a steady gradient Ricci soliton of dimension  $n \geq 4$  which has positive sectional curvature and is asymptotically cylindrical. Under these assumptions, we show that  $(M, g)$  is rotationally symmetric. In particular, our results apply to steady gradient Ricci solitons in dimension 4 which are  $\kappa$ -noncollapsed and have positive isotropic curvature.

### 1. Introduction

This is a sequel to our earlier paper [4], in which we proved a uniqueness theorem for the three-dimensional Bryant soliton. Recall that the Bryant soliton is the unique steady gradient Ricci soliton in dimension 3, which is rotationally symmetric (cf. [6]). In [4], it was shown that the three-dimensional Bryant soliton is unique in the class of  $\kappa$ -noncollapsed steady gradient Ricci solitons:

**Theorem 1.1** (Brendle [4]). *Let  $(M, g)$  be a three-dimensional complete steady gradient Ricci soliton which is non-flat and  $\kappa$ -noncollapsed. Then  $(M, g)$  is rotationally symmetric, and is therefore isometric to the Bryant soliton up to scaling.*

Theorem 1.1 resolves a problem mentioned in Perelman's first paper [16].

In this paper, we consider similar questions in higher dimensions. We will assume throughout that  $(M, g)$  is a steady gradient Ricci soliton of dimension  $n \geq 4$  with positive sectional curvature. We may write  $\text{Ric} = D^2f$  for some real-valued function  $f$ . As usual, we put  $X = \nabla f$ , and denote by  $\Phi_t$  the flow generated by the vector field  $-X$ .

**Definition.** We say that  $(M, g)$  is asymptotically cylindrical if the following holds:

- (i) The scalar curvature satisfies  $\frac{\Lambda_1}{d(p_0, p)} \leq R \leq \frac{\Lambda_2}{d(p_0, p)}$  at infinity, where  $\Lambda_1$  and  $\Lambda_2$  are positive constants.

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(ii) Let  $p_m$  be an arbitrary sequence of marked points going to infinity. Consider the rescaled metrics

$$\hat{g}^{(m)}(t) = r_m^{-1} \Phi_{r_m t}^*(g),$$

where  $r_m R(p_m) = \frac{n-1}{2} + o(1)$ . As  $m \rightarrow \infty$ , the flows  $(M, \hat{g}^{(m)}(t), p_m)$  converge in the Cheeger-Gromov sense to a family of shrinking cylinders  $(S^{n-1} \times \mathbb{R}, \bar{g}(t))$ ,  $t \in (0, 1)$ . The metric  $\bar{g}(t)$  is given by

$$(1) \quad \bar{g}(t) = (n-2)(2-2t)g_{S^{n-1}} + dz \otimes dz,$$

where  $g_{S^{n-1}}$  denotes the standard metric on  $S^{n-1}$  with constant sectional curvature 1.

We now state the main result of this paper. This result is motivated in part by the work of Simon and Solomon [17], which deals with uniqueness questions for minimal surfaces with prescribed tangent cones at infinity.

**Theorem 1.2.** *Let  $(M, g)$  be a steady gradient Ricci soliton of dimension  $n \geq 4$  which has positive sectional curvature and is asymptotically cylindrical. Then  $(M, g)$  is rotationally symmetric. In particular,  $(M, g)$  is isometric to the  $n$ -dimensional Bryant soliton up to scaling.*

In dimension 3, it follows from work of Perelman [16] that any complete steady gradient Ricci soliton which is non-flat and  $\kappa$ -noncollapsed is asymptotically cylindrical. Thus, Theorem 1.2 can be viewed as a higher dimensional version of Theorem 1.1.

Theorem 1.2 has an interesting implication in dimension 4. A four-dimensional manifold  $(M, g)$  has positive isotropic curvature if and only if  $a_1 + a_2 > 0$  and  $c_1 + c_2 > 0$ , where  $a_1, a_2, c_1, c_2$  are defined as in [12]. The notion of isotropic curvature was first introduced by Micallef and Moore [15] in their work on the index of minimal two-spheres. It also plays a central role in the convergence theory for the Ricci flow in higher dimensions (see e.g. [2], [3]).

**Theorem 1.3.** *Let  $(M, g)$  be a four-dimensional steady gradient Ricci soliton which is non-flat; is  $\kappa$ -noncollapsed; and satisfies the pointwise pinching condition*

$$0 \leq \max\{a_3, b_3, c_3\} \leq \Lambda \min\{a_1 + a_2, c_1 + c_2\},$$

where  $a_1, a_2, a_3, c_1, c_2, c_3, b_3$  are defined as in Hamilton's paper [12] and  $\Lambda \geq 1$  is a constant. Then  $(M, g)$  is rotationally symmetric.

We note that various authors have obtained uniqueness results for Ricci solitons in higher dimensions; see e.g. [7], [8], [9], and [11]. Moreover, Ivey [14] has constructed examples of Ricci solitons which are not rotationally symmetric.

In order to prove Theorem 1.2, we will adapt the arguments in [4]. While many arguments in [4] directly generalize to higher dimensions,

there are several crucial differences. In particular, the proof of the roundness estimate in Section 2 is very different than in the three-dimensional case. Moreover, the proof in [4] uses an estimate of Anderson and Chow [1] for the linearized Ricci flow system. This estimate uses special properties of the curvature tensor in dimension 3, so we require a different argument to handle the higher dimensional case. This will be discussed in Section 4.

Finally, to deduce Theorem 1.3 from Theorem 1.2, we show that a steady gradient Ricci soliton  $(M, g)$  which satisfies the assumptions of Theorem 1.3 must have positive curvature operator (cf. Corollary 6.4 below). The proof of this fact uses the pinching estimates of Hamilton (see [12], [13]). Using results from [10], we conclude that  $(M, g)$  is asymptotically cylindrical. Theorem 1.2 then implies that  $(M, g)$  is rotationally symmetric.

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## 2. The roundness estimate

By scaling, we may assume that  $R + |\nabla f|^2 = 1$ . Since  $R \rightarrow 0$  at infinity, we can find a point  $p_0$  where the scalar curvature attains its maximum. Since  $(M, g)$  has positive sectional curvature, the Hessian of  $f$  is strictly positive definite at each point in  $M$ . The identity  $\nabla R(p_0) = 0$  implies  $\nabla f(p_0) = 0$ . Since  $f$  is strictly convex, we conclude that  $\liminf_{p \rightarrow \infty} \frac{f(p)}{d(p_0, p)} > 0$ . On the other hand, since  $|\nabla f|^2 \leq 1$ , we have  $\limsup_{p \rightarrow \infty} \frac{f(p)}{d(p_0, p)} < \infty$ .

Using the fact that  $(M, g)$  is asymptotically cylindrical, we obtain the following result:

**Proposition 2.1.** *We have  $fR = \frac{n-1}{2} + o(1)$  and  $f\text{Ric} \leq (\frac{1}{2} + o(1))g$ . Moreover, we have  $f^2\text{Ric} \geq cg$  for some positive constant  $c$ .*

*Proof.* Since  $(M, g)$  is asymptotically cylindrical, we have  $\Delta R = o(r^{-2})$  and  $|\text{Ric}|^2 = \frac{1}{n-1}R^2 + o(r^{-2})$ . This implies

$$-\langle X, \nabla R \rangle = \Delta R + 2|\text{Ric}|^2 = \frac{2}{n-1}R^2 + o(r^{-2}),$$

hence

$$\left\langle X, \nabla \left( \frac{1}{R} - \frac{2}{n-1}f \right) \right\rangle = o(1).$$

Integrating this inequality along the integral curves of  $X$  gives

$$\frac{1}{R} - \frac{2}{n-1}f = o(r),$$

hence

$$fR = \frac{n-1}{2} + o(1).$$

Moreover, we have  $\text{Ric} \leq \left(\frac{1}{n-1} + o(1)\right) Rg$  since  $(M, g)$  is asymptotically cylindrical. Therefore,  $f \text{Ric} \leq \left(\frac{1}{2} + o(1)\right) g$ .

In order to verify the third statement, we choose an orthonormal frame  $\{e_1, \dots, e_n\}$  such that  $e_n = \frac{X}{|X|}$ . Since  $(M, g)$  is asymptotically cylindrical, we have

$$\text{Ric}(e_i, e_j) = \frac{1}{n-1} R \delta_{ij} + o(r^{-1})$$

for  $i, j \in \{1, \dots, n-1\}$  and

$$2 \text{Ric}(e_i, X) = -\langle e_i, \nabla R \rangle = o(r^{-\frac{3}{2}}).$$

Moreover, we have

$$2 \text{Ric}(X, X) = -\langle X, \nabla R \rangle = \Delta R + 2 |\text{Ric}|^2 = \frac{2}{n-1} R^2 + o(r^{-2}).$$

Putting these facts together, we conclude that  $\text{Ric} \geq cR^2 g$  for some positive constant  $c$ . From this, the assertion follows. q.e.d.

In the remainder of this section, we prove a roundness estimate. We begin with a lemma:

**Lemma 2.2.** *We have  $R_{ijkl} \partial^l f = O(r^{-\frac{3}{2}})$ .*

*Proof.* Using Shi's estimate, we obtain

$$R_{ijkl} \partial^l f = D_i \text{Ric}_{jk} - D_j \text{Ric}_{ik} = O(r^{-\frac{3}{2}}).$$

This proves the assertion. q.e.d.

We next define

$$T = (n-1) \text{Ric} - Rg + Rdf \otimes df.$$

Note that

$$\text{tr}(T) = -R^2 = O(r^{-2}),$$

$$T(\nabla f, \cdot) = (n-1) \text{Ric}(\nabla f, \cdot) - R^2 \nabla f = O(r^{-\frac{3}{2}}),$$

$$T(\nabla f, \nabla f) = (n-1) \text{Ric}(\nabla f, \nabla f) - R^2 |\nabla f|^2 = O(r^{-2}).$$

**Proposition 2.3.** *We have  $|T| \leq O(r^{-\frac{3}{2}})$ .*

*Proof.* The Ricci tensor of  $(M, g)$  satisfies the equation

$$\Delta \text{Ric}_{ik} + D_X \text{Ric}_{ik} = -2 \sum_{j,l=1}^n R_{ijkl} \text{Ric}^{jl}.$$

Moreover, using the identity  $\Delta X + D_X X = 0$ , we obtain

$$\begin{aligned} & \Delta(Rg_{ik} - R \partial_i f \partial_k f) + D_X(Rg_{ik} - R \partial_i f \partial_k f) \\ &= (\Delta R + \langle X, \nabla R \rangle) (g_{ik} - \partial_i f \partial_k f) + O(r^{-\frac{5}{2}}) \\ &= -2 |\text{Ric}|^2 (g_{ik} - \partial_i f \partial_k f) + O(r^{-\frac{5}{2}}). \end{aligned}$$

Using Lemma 2.2, we conclude that

$$\begin{aligned} \Delta T_{ik} + D_X T_{ik} &= -2 \sum_{j,l=1}^{n-1} R_{ijkl} T^{jl} - 2R \operatorname{Ric}_{ik} \\ &\quad + 2|\operatorname{Ric}|^2 (g_{ik} - \partial_i f \partial_k f) + O(r^{-\frac{5}{2}}), \end{aligned}$$

hence

$$\begin{aligned} &\Delta(|T|^2) + \langle X, \nabla(|T|^2) \rangle \\ &= 2|DT|^2 - 4 \sum_{j,l=1}^{n-1} R_{ijkl} T^{ik} T^{jl} - 4R \sum_{i,k=1}^n \operatorname{Ric}_{ik} T^{ik} \\ &\quad + 4|\operatorname{Ric}|^2 \sum_{i,k=1}^n (g_{ik} - \partial_i f \partial_k f) T^{ik} + O(r^{-\frac{5}{2}}) |T| \\ &= 2|DT|^2 - 4 \sum_{j,l=1}^{n-1} R_{ijkl} T^{ik} T^{jl} - \frac{4}{n-1} R |T|^2 \\ &\quad + 4 \left( |\operatorname{Ric}|^2 - \frac{1}{n-1} R^2 \right) \sum_{i,k=1}^n (g_{ik} - \partial_i f \partial_k f) T^{ik} + O(r^{-\frac{5}{2}}) |T|. \end{aligned}$$

Since  $\sum_{i,k=1}^n (g_{ik} - \partial_i f \partial_k f) T^{ik} = O(r^{-2})$ , we obtain

$$\begin{aligned} &\Delta(|T|^2) + \langle X, \nabla(|T|^2) \rangle \\ &\geq -4 \sum_{j,l=1}^{n-1} R_{ijkl} T^{ik} T^{jl} - \frac{4}{n-1} R |T|^2 - O(r^{-\frac{5}{2}}) |T| - O(r^{-4}). \end{aligned}$$

Moreover, since  $(M, g)$  is asymptotically cylindrical, we have

$$\begin{aligned} R_{ijkl} &= \frac{1}{(n-1)(n-2)} R (g_{ik} - \partial_i f \partial_k f) (g_{jl} - \partial_j f \partial_l f) \\ &\quad - \frac{1}{(n-1)(n-2)} R (g_{il} - \partial_i f \partial_l f) (g_{jk} - \partial_j f \partial_k f) \\ &\quad + o(r^{-1}) \end{aligned}$$

near infinity. This implies

$$\sum_{j,l=1}^{n-1} R_{ijkl} T^{ik} T^{jl} = -\frac{1}{(n-1)(n-2)} R |T|^2 + O(r^{-\frac{5}{2}}) |T| + o(r^{-1}) |T|^2,$$

hence

$$\begin{aligned} &\Delta(|T|^2) + \langle X, \nabla(|T|^2) \rangle \\ &\geq -\frac{4(n-3)}{(n-1)(n-2)} R |T|^2 - o(r^{-1}) |T|^2 - O(r^{-\frac{5}{2}}) |T| - O(r^{-4}). \end{aligned}$$

We next observe that  $|D_X \text{Ric}| \leq O(r^{-2})$  and  $|D_{X,X}^2 \text{Ric}| \leq O(r^{-\frac{5}{2}})$ . This implies  $|D_X T| \leq O(r^{-2})$  and  $|D_{X,X}^2 T| \leq O(r^{-\frac{5}{2}})$ . From this, we deduce that

$$\begin{aligned} & \Delta_\Sigma(|T|^2) + \langle X, \nabla(|T|^2) \rangle \\ & \geq -\frac{2(n-3)}{n-2} f^{-1} |T|^2 - o(r^{-1}) |T|^2 - O(r^{-\frac{5}{2}}) |T| - O(r^{-4}), \end{aligned}$$

where  $\Delta_\Sigma$  denotes the Laplacian on the level surfaces of  $f$ . Thus, we conclude that

$$\begin{aligned} & \Delta_\Sigma(f^2 |T|^2) + \langle X, \nabla(f^2 |T|^2) \rangle \\ & \geq \frac{2}{n-2} f |T|^2 - o(r) |T|^2 - O(r^{-\frac{1}{2}}) |T| - O(r^{-2}) \geq -O(r^{-2}) \end{aligned}$$

outside some compact set. Since  $f^2 |T|^2 \rightarrow 0$  at infinity, the parabolic maximum principle implies that  $f^2 |T|^2 \leq O(r^{-1})$ . This completes the proof. q.e.d.

In the following, we fix  $\varepsilon$  sufficiently small; for example,  $\varepsilon = \frac{1}{1000n}$  will work. By Proposition 2.3, we have  $|T| \leq O(r^{\frac{1}{2(n-2)} - \frac{3}{2} - 32\varepsilon})$ . Moreover, it follows from Shi's estimates that  $|D^m T| \leq O(r^{-\frac{m+2}{2}})$  for each  $m$ . Using standard interpolation inequalities, we obtain  $|DT| \leq O(r^{\frac{1}{2(n-2)} - 2 - 16\varepsilon})$ . Using the identity

$$\begin{aligned} D^k T_{ik} &= \frac{n-3}{2} \partial_i R + \langle \nabla f, \nabla R \rangle \partial_i f + R^2 \partial_i f + R \text{Ric}_i^k \partial_k f \\ &= \frac{n-3}{2} \partial_i R + O(r^{-2}), \end{aligned}$$

we conclude that  $|\nabla R| \leq O(r^{\frac{1}{2(n-2)} - 2 - 16\varepsilon})$ . This implies

$$|D \text{Ric}| \leq C |DT| + C |\nabla R| + C R |D^2 f| \leq O(r^{\frac{1}{2(n-2)} - 2 - 16\varepsilon}).$$

Using standard interpolation inequalities, we obtain

$$|D^2 \text{Ric}| \leq O(r^{\frac{1}{2(n-2)} - \frac{5}{2} - 8\varepsilon}).$$

**Proposition 2.4.** *We have  $f R = \frac{n-1}{2} + O(r^{\frac{1}{2(n-2)} - \frac{1}{2} - 8\varepsilon})$ .*

*Proof.* Using the inequality  $|T| \leq O(r^{-\frac{3}{2}})$ , we obtain

$$|\text{Ric}| = \frac{1}{n-1} R |g - df \otimes df| + O(r^{-\frac{3}{2}}) = \frac{1}{\sqrt{n-1}} R + O(r^{-\frac{3}{2}}),$$

hence

$$|\text{Ric}|^2 = \frac{1}{n-1} R^2 + O(r^{-\frac{5}{2}}).$$

This implies

$$-\langle X, \nabla R \rangle = \Delta R + 2 |\text{Ric}|^2 = \frac{2}{n-1} R^2 + O(r^{\frac{1}{2(n-2)} - \frac{5}{2} - 8\varepsilon}),$$

hence

$$\left\langle X, \nabla \left( \frac{1}{R} - \frac{2}{n-1} f \right) \right\rangle = O(r^{\frac{1}{2(n-2)} - \frac{1}{2} - 8\varepsilon}).$$

Integrating this identity along the integral curves of  $X$ , we obtain

$$\frac{1}{R} - \frac{2}{n-1} f = O(r^{\frac{1}{2(n-2)} + \frac{1}{2} - 8\varepsilon}).$$

From this, the assertion follows.

q.e.d.

**Proposition 2.5.** *We have*

$$\begin{aligned} f R_{ijkl} &= \frac{1}{2(n-2)} (g_{ik} - \partial_i f \partial_k f) (g_{ik} - \partial_i f \partial_k f) \\ &\quad - \frac{1}{2(n-2)} (g_{il} - \partial_i f \partial_l f) (g_{jk} - \partial_j f \partial_k f) \\ &\quad + O(r^{\frac{1}{2(n-2)} - \frac{1}{2} - 8\varepsilon}). \end{aligned}$$

*Proof.* It follows from Proposition 2.10 in [3] that

$$\begin{aligned} -D_X R_{ijkl} &= D_{i,k}^2 \text{Ric}_{jl} - D_{i,l}^2 \text{Ric}_{jk} - D_{j,k}^2 \text{Ric}_{il} + D_{j,l}^2 \text{Ric}_{ik} \\ &\quad + \sum_{m=1}^n \text{Ric}_i^m R_{mjkl} + \sum_{m=1}^n \text{Ric}_j^m R_{imkl}. \end{aligned}$$

Using Lemma 2.2 and Proposition 2.3, we obtain

$$\begin{aligned} \sum_{m=1}^n \text{Ric}_i^m R_{mjkl} &= \frac{1}{n-1} R \sum_{m=1}^n (\delta_i^m - \partial_i f \partial^m f) R_{mjkl} + O(r^{-\frac{5}{2}}) \\ &= \frac{1}{n-1} R R_{ijkl} + O(r^{-\frac{5}{2}}). \end{aligned}$$

Thus, we conclude that

$$\begin{aligned} -D_X R_{ijkl} &= \frac{2}{n-1} R R_{ijkl} + O(r^{\frac{1}{2(n-2)} - \frac{5}{2} - 8\varepsilon}) \\ &= f^{-1} R_{ijkl} + O(r^{\frac{1}{2(n-2)} - \frac{5}{2} - 8\varepsilon}), \end{aligned}$$

hence

$$|D_X(f R_{ijkl})| \leq O(r^{\frac{1}{2(n-2)} - \frac{3}{2} - 8\varepsilon}).$$

On the other hand, the tensor

$$\begin{aligned} S_{ijkl} &= \frac{1}{2(n-2)} (g_{ik} - \partial_i f \partial_k f) (g_{jl} - \partial_j f \partial_l f) \\ &\quad - \frac{1}{2(n-2)} (g_{il} - \partial_i f \partial_l f) (g_{jk} - \partial_j f \partial_k f) \end{aligned}$$

satisfies

$$|D_X S_{ijkl}| \leq O(r^{-\frac{3}{2}}).$$

Putting these facts together, we obtain

$$|D_X(f R_{ijkl} - S_{ijkl})| \leq O(r^{\frac{1}{2(n-2)} - \frac{3}{2} - 8\varepsilon}).$$

Moreover, we have  $|f R_{ijkl} - S_{ijkl}| \rightarrow 0$  at infinity. Integrating the preceding inequality along integral curves of  $X$  gives

$$|f R_{ijkl} - S_{ijkl}| \leq O(r^{\frac{1}{2(n-2)} - \frac{1}{2} - 8\varepsilon}),$$

as claimed.

q.e.d.

We next construct a collection of approximate Killing vector fields:

**Proposition 2.6.** *We can find a collection of vector fields  $U_a$ ,  $a \in \{1, \dots, \frac{n(n-1)}{2}\}$ , on  $(M, g)$  such that  $|\mathcal{L}_{U_a}(g)| \leq O(r^{\frac{1}{2(n-2)} - \frac{1}{2} - 2\varepsilon})$  and  $|\Delta U_a + D_X U_a| \leq O(r^{\frac{1}{2(n-2)} - 1 - 2\varepsilon})$ . Moreover, we have*

$$\sum_{a=1}^{\frac{n(n-1)}{2}} U_a \otimes U_a = r \left( \sum_{i=1}^{n-1} e_i \otimes e_i + O(r^{\frac{1}{2(n-2)} - \frac{1}{2} - 2\varepsilon}) \right),$$

where  $\{e_1, \dots, e_{n-1}\}$  is a local orthonormal frame on the level set  $\{f = r\}$ .

The proof of Proposition 2.6 is analogous to the arguments in [4], Section 3. We omit the details.

### 3. An elliptic PDE for vector fields

Let us fix a smooth vector field  $Q$  on  $M$  with the property that  $|Q| \leq O(r^{\frac{1}{2(n-2)} - 1 - 2\varepsilon})$ . We will show that there exists a vector field  $V$  on  $M$  such that  $\Delta V + D_X V = Q$  and  $|V| \leq O(r^{\frac{1}{2(n-2)} - \varepsilon})$ .

**Lemma 3.1.** *Consider the shrinking cylinders  $(S^{n-1} \times \mathbb{R}, \bar{g}(t))$ ,  $t \in (0, 1)$ , where  $\bar{g}(t)$  is given by (1). Let  $\bar{V}(t)$ ,  $t \in (0, 1)$ , be a one-parameter family of vector fields which satisfy the parabolic equation*

$$(2) \quad \frac{\partial}{\partial t} \bar{V}(t) = \Delta_{\bar{g}(t)} \bar{V}(t) + \text{Ric}_{\bar{g}(t)}(\bar{V}(t)).$$

Moreover, suppose that  $\bar{V}(t)$  is invariant under translations along the axis of the cylinder, and

$$(3) \quad |\bar{V}(t)|_{\bar{g}(t)} \leq 1$$

for all  $t \in (0, \frac{1}{2}]$ . Then

$$\inf_{\lambda \in \mathbb{R}} \sup_{S^{n-1} \times \mathbb{R}} \left| \bar{V}(t) - \lambda \frac{\partial}{\partial z} \right|_{\bar{g}(t)} \leq L (1-t)^{\frac{1}{2(n-2)}}$$

for all  $t \in [\frac{1}{2}, 1)$ , where  $L$  is a positive constant.

*Proof.* Since  $\bar{V}(t)$  is invariant under translations along the axis of the cylinder, we may write

$$\bar{V}(t) = \xi(t) + \eta(t) \frac{\partial}{\partial z}$$

for  $t \in (0, 1)$ , where  $\xi(t)$  is a vector field on  $S^{n-1}$  and  $\eta(t)$  is a real-valued function on  $S^{n-1}$ . The parabolic equation (2) implies the following system of equations for  $\xi(t)$  and  $\eta(t)$ :

$$(4) \quad \frac{\partial}{\partial t} \xi(t) = \frac{1}{(n-2)(2-2t)} (\Delta_{S^{n-1}} \xi(t) + (n-2) \xi(t)),$$

$$(5) \quad \frac{\partial}{\partial t} \eta(t) = \frac{1}{(n-2)(2-2t)} \Delta_{S^{n-1}} \eta(t).$$

Furthermore, the estimate (3) gives

$$(6) \quad \sup_{S^{n-1}} |\xi(t)|_{g_{S^{n-1}}} \leq L_1,$$

$$(7) \quad \sup_{S^{n-1}} |\eta(t)| \leq L_1$$

for each  $t \in (0, \frac{1}{2}]$ , where  $L_1$  is a positive constant.

Let us consider the operator  $\xi \mapsto -\Delta_{S^{n-1}} \xi - (n-2) \xi$ , acting on vector fields on  $S^{n-1}$ . By Proposition A.1, the first eigenvalue of this operator is at least  $-(n-3)$ . Using (4) and (6), we obtain

$$(8) \quad \sup_{S^{n-1}} |\xi(t)|_{g_{S^{n-1}}} \leq L_2 (1-t)^{-\frac{n-3}{2(n-2)}}$$

for all  $t \in [\frac{1}{2}, 1)$ , where  $L_2$  is a positive constant. Similarly, it follows from (5) and (7) that

$$(9) \quad \inf_{\lambda \in \mathbb{R}} \sup_{S^{n-1}} |\eta(t) - \lambda| \leq L_3 (1-t)^{\frac{n-1}{2(n-2)}}$$

for each  $t \in [\frac{1}{2}, 1)$ , where  $L_3$  is a positive constant. Combining (8) and (9), the assertion follows. q.e.d.

**Lemma 3.2** (cf. [4], Lemma 5.2). *Let  $V$  be a smooth vector field satisfying  $\Delta V + D_X V = Q$  in the region  $\{f \leq \rho\}$ . Then*

$$\sup_{\{f \leq \rho\}} |V| \leq \sup_{\{f = \rho\}} |V| + B \rho^{\frac{1}{2(n-2)} - 2\varepsilon}$$

for some uniform constant  $B \geq 1$ .

The proof of Lemma 3.2 is similar to the proof of Lemma 5.2 in [4]; we omit the details.

As in [4], we choose a sequence of real numbers  $\rho_m \rightarrow \infty$ . For each  $m$ , we can find a vector field  $V^{(m)}$  such that  $\Delta V^{(m)} + D_X V^{(m)} = Q$  in the region  $\{f \leq \rho_m\}$  and  $V^{(m)} = 0$  on the boundary  $\{f = \rho_m\}$ . We now define

$$A^{(m)}(r) = \inf_{\lambda \in \mathbb{R}} \sup_{\{f=r\}} |V^{(m)} - \lambda X|$$

for  $r \leq \rho_m$ .

**Lemma 3.3.** *Let us fix a real number  $\tau \in (0, \frac{1}{2})$  so that  $\tau^{-\varepsilon} > 2L$ , where  $L$  is the constant in Lemma 3.1. Then we can find a real number  $\rho_0$  and a positive integer  $m_0$  such that*

$$2\tau^{-\frac{1}{2(n-2)}+\varepsilon} A^{(m)}(\tau r) \leq A^{(m)}(r) + r^{\frac{1}{2(n-2)}-\varepsilon}$$

for all  $r \in [\rho_0, \rho_m]$  and all  $m \geq m_0$ .

*Proof.* We argue by contradiction. Suppose that the assertion is false. After passing to a subsequence, there exists a sequence of real numbers  $r_m \leq \rho_m$  such that  $r_m \rightarrow \infty$  and

$$A^{(m)}(r_m) + r_m^{\frac{1}{2(n-2)}-\varepsilon} \leq 2\tau^{-\frac{1}{2(n-2)}+\varepsilon} A^{(m)}(\tau r_m)$$

for all  $m$ . For each  $m$ , there exists a real number  $\lambda_m$  such that

$$\sup_{\{f=r_m\}} |V^{(m)} - \lambda_m X| = A^{(m)}(r_m).$$

Applying Lemma 3.2 to the vector field  $V^{(m)} - \lambda_m X$  gives

$$\begin{aligned} \sup_{\{f \leq r_m\}} |V^{(m)} - \lambda_m X| &\leq \sup_{\{f=r_m\}} |V^{(m)} - \lambda_m X| + B r_m^{\frac{1}{2(n-2)}-2\varepsilon} \\ &\leq A^{(m)}(r_m) + r_m^{\frac{1}{2(n-2)}-\varepsilon} \end{aligned}$$

if  $m$  is sufficiently large. We next consider the vector field

$$\tilde{V}^{(m)} = \frac{1}{A^{(m)}(r_m) + r_m^{\frac{1}{2(n-2)}-\varepsilon}} (V^{(m)} - \lambda_m X).$$

The vector field  $\tilde{V}^{(m)}$  satisfies

$$(10) \quad \sup_{\{f \leq r_m\}} |\tilde{V}^{(m)}| \leq 1.$$

Let

$$\hat{g}^{(m)}(t) = r_m^{-1} \Phi_{r_m t}^*(g)$$

and

$$\hat{V}^{(m)}(t) = r_m^{\frac{1}{2}} \Phi_{r_m t}^*(\tilde{V}^{(m)}).$$

Note that the metrics  $\hat{g}^{(m)}(t)$  evolve by the Ricci flow. Moreover, the vector fields  $\hat{V}^{(m)}(t)$  satisfy the parabolic equation

$$\frac{\partial}{\partial t} \hat{V}^{(m)}(t) = \Delta_{\hat{g}^{(m)}(t)} \hat{V}^{(m)}(t) + \text{Ric}_{\hat{g}^{(m)}(t)}(\hat{V}^{(m)}(t)) - \hat{Q}^{(m)}(t),$$

where

$$\hat{Q}^{(m)}(t) = \frac{r_m^{\frac{3}{2}}}{A^{(m)}(r_m) + r_m^{\frac{1}{2(n-2)}-\varepsilon}} \Phi_{r_m t}^*(Q).$$

Using (10), we obtain

$$\limsup_{m \rightarrow \infty} \sup_{t \in [\delta, 1-\delta]} \sup_{\{r_m - \delta^{-1} \sqrt{r_m} \leq f \leq r_m + \delta^{-1} \sqrt{r_m}\}} |\hat{V}^{(m)}(t)|_{\hat{g}^{(m)}(t)} < \infty$$

for any given  $\delta \in (0, \frac{1}{2})$ . Moreover, the estimate  $|Q| \leq O(r^{\frac{1}{2(n-2)}-1-2\varepsilon})$  implies that

$$\limsup_{m \rightarrow \infty} \sup_{t \in [\delta, 1-\delta]} \sup_{\{r_m - \delta^{-1} \sqrt{r_m} \leq f \leq r_m + \delta^{-1} \sqrt{r_m}\}} |\hat{Q}^{(m)}(t)|_{\hat{g}^{(m)}(t)} = 0$$

for any given  $\delta \in (0, \frac{1}{2})$ .

We now pass to the limit as  $m \rightarrow \infty$ . To that end, we choose a sequence of marked points  $p_m \in M$  such that  $f(p_m) = r_m$ . The manifolds  $(M, \hat{g}^{(m)}(t), p_m)$  converge in the Cheeger-Gromov sense to a one-parameter family of shrinking cylinders  $(S^{n-1} \times \mathbb{R}, \bar{g}(t))$ ,  $t \in (0, 1)$ , where  $\bar{g}(t)$  is given by (1). Furthermore, the rescaled vector fields  $r_m^{\frac{1}{2}} X$  converge to the axial vector field  $\frac{\partial}{\partial z}$  on  $S^{n-1} \times \mathbb{R}$ . Finally, the sequence  $\hat{V}^{(m)}(t)$  converges in  $C_{loc}^0$  to a one-parameter family of vector fields  $\bar{V}(t)$ ,  $t \in (0, 1)$ , which satisfy the parabolic equation

$$\frac{\partial}{\partial t} \bar{V}(t) = \Delta_{\bar{g}(t)} \bar{V}(t) + \text{Ric}_{\bar{g}(t)}(\bar{V}(t)).$$

As in [4], we can show that  $\bar{V}(t)$  is invariant under translations along the axis of the cylinder. Moreover, the estimate (10) implies that

$$|\bar{V}(t)|_{\bar{g}(t)} \leq 1$$

for all  $t \in (0, \frac{1}{2}]$ . Hence, it follows from Lemma 3.1 that

$$(11) \quad \inf_{\lambda \in \mathbb{R}} \sup_{S^{n-1} \times \mathbb{R}} \left| \bar{V}(t) - \lambda \frac{\partial}{\partial z} \right|_{\bar{g}(t)} \leq L(1-t)^{\frac{1}{2(n-2)}}$$

for all  $t \in (0, \frac{1}{2}]$ . Finally, we have

$$\begin{aligned} & \inf_{\lambda \in \mathbb{R}} \sup_{\Phi_{r_m(\tau-1)}(\{f=\tau r_m\})} \left| \hat{V}^{(m)}(1-\tau) - \lambda r_m^{\frac{1}{2}} X \right|_{\hat{g}^{(m)}(1-\tau)} \\ &= \inf_{\lambda \in \mathbb{R}} \sup_{\{f=\tau r_m\}} |\tilde{V}^{(m)} - \lambda X|_g \\ &= \frac{1}{A^{(m)}(r_m) + r_m^{\frac{1}{2(n-2)}-\varepsilon}} \inf_{\lambda \in \mathbb{R}} \sup_{\{f=\tau r_m\}} |V^{(m)} - \lambda X|_g \\ &= \frac{A^{(m)}(\tau r_m)}{A^{(m)}(r_m) + r_m^{\frac{1}{2(n-2)}-\varepsilon}} \\ &\geq \frac{1}{2} \tau^{\frac{1}{2(n-2)}-\varepsilon}. \end{aligned}$$

If we send  $m \rightarrow \infty$ , we obtain

$$(12) \quad \inf_{\lambda \in \mathbb{R}} \sup_{S^{n-1} \times \mathbb{R}} \left| \bar{V}(1-\tau) - \lambda \frac{\partial}{\partial z} \right|_{\bar{g}(1-\tau)} \geq \frac{1}{2} \tau^{\frac{1}{2(n-2)}-\varepsilon}.$$

Since  $\tau^{-\varepsilon} > 2L$ , the inequality (12) is in contradiction with (11). This completes the proof of Lemma 3.3. q.e.d.

If we iterate the estimate in Lemma 3.3, we obtain

$$\sup_m \sup_{\rho_0 \leq r \leq \rho_m} r^{-\frac{1}{2(n-2)} + \varepsilon} A^{(m)}(r) < \infty.$$

From this, we deduce the following result:

**Proposition 3.4.** *There exists a sequence of real numbers  $\lambda_m$  such that*

$$\sup_m \sup_{\{f \leq \rho_m\}} f^{-\frac{1}{2(n-2)} + \varepsilon} |V^{(m)} - \lambda_m X| < \infty.$$

The proof of Proposition 3.4 is analogous to the proof of Proposition 5.4 in [4]. We omit the details. By taking the limit as  $m \rightarrow \infty$  of the vector fields  $V^{(m)} - \lambda_m X$ , we obtain the following result:

**Theorem 3.5.** *There exists a smooth vector field  $V$  such that  $\Delta V + D_X V = Q$  and  $|V| \leq O(r^{\frac{1}{2(n-2)} - \varepsilon})$ . Moreover,  $|DV| \leq O(r^{\frac{1}{2(n-2)} - \frac{1}{2} - \varepsilon})$ .*

#### 4. Analysis of the Lichnerowicz equation

Throughout this section, we will denote by  $\Delta_L$  the Lichnerowicz Laplacian; that is,

$$\Delta_L h_{ik} = \Delta h_{ik} + 2 R_{ijkl} h^{jl} - \text{Ric}_i^l h_{kl} - \text{Ric}_k^l h_{il}.$$

**Lemma 4.1.** *Let us consider the shrinking cylinders  $(S^{n-1} \times \mathbb{R}, \bar{g}(t))$ ,  $t \in (0, 1)$ , where  $\bar{g}(t)$  is given by (1). Let  $\bar{h}(t)$ ,  $t \in (0, 1)$ , be a one-parameter family of  $(0, 2)$ -tensors which solve the parabolic equation*

$$(13) \quad \frac{\partial}{\partial t} \bar{h}(t) = \Delta_{L, \bar{g}(t)} \bar{h}(t).$$

Moreover, suppose that  $\bar{h}(t)$  is invariant under translations along the axis of the cylinder, and

$$(14) \quad |\bar{h}(t)|_{\bar{g}(t)} \leq (1-t)^{-2}$$

for all  $t \in (0, \frac{1}{2}]$ . Then

$$\inf_{\lambda \in \mathbb{R}} \sup_{S^{n-1} \times \mathbb{R}} |\bar{h}(t) - \lambda \text{Ric}_{\bar{g}(t)}|_{\bar{g}(t)} \leq N (1-t)^{\frac{1}{2(n-2)} - \frac{1}{2}}$$

for all  $t \in [\frac{1}{2}, 1)$ , where  $N$  is a positive constant.

*Proof.* Since  $\bar{h}(t)$  is invariant under translations along the axis of the cylinder, we may write

$$\bar{h}(t) = \chi(t) + dz \otimes \sigma(t) + \sigma(t) \otimes dz + \beta(t) dz \otimes dz$$

for  $t \in (0, 1)$ , where  $\chi(t)$  is a symmetric  $(0, 2)$  tensor on  $S^{n-1}$ ,  $\sigma(t)$  is a one-form on  $S^{n-1}$ , and  $\beta(t)$  is a real-valued function on  $S^{n-1}$ . The

parabolic Lichnerowicz equation (13) implies the following system of equations for  $\chi(t)$ ,  $\sigma(t)$ , and  $\beta(t)$ :

$$(15) \quad \frac{\partial}{\partial t} \chi(t) = \frac{1}{(n-2)(2-2t)} (\Delta_{S^{n-1}} \chi(t) - 2(n-1) \overset{\circ}{\chi}(t)),$$

$$(16) \quad \frac{\partial}{\partial t} \sigma(t) = \frac{1}{(n-2)(2-2t)} (\Delta_{S^{n-1}} \sigma(t) - (n-2) \sigma(t)),$$

$$(17) \quad \frac{\partial}{\partial t} \beta(t) = \frac{1}{(n-2)(2-2t)} \Delta_{S^{n-1}} \beta(t).$$

Here,  $\overset{\circ}{\chi}(t)$  denotes the trace-free part of  $\chi(t)$  with respect to the standard metric on  $S^{n-1}$ . Using the assumption (14), we obtain

$$(18) \quad \sup_{S^{n-1}} |\chi(t)|_{g_{S^{n-1}}} \leq N_1,$$

$$(19) \quad \sup_{S^{n-1}} |\sigma(t)|_{g_{S^{n-1}}} \leq N_1,$$

$$(20) \quad \sup_{S^{n-1}} |\beta(t)| \leq N_1$$

for each  $t \in (0, \frac{1}{2}]$ , where  $N_1$  is a positive constant.

We next analyze the operator  $\chi \mapsto -\Delta_{S^{n-1}} \chi + 2(n-1) \overset{\circ}{\chi}$ , acting on symmetric  $(0, 2)$ -tensors on  $S^{n-1}$ . The first eigenvalue of this operator is equal to 0, and the associated eigenspace is spanned by  $g_{S^{n-1}}$ . Moreover, the other eigenvalues of this operator are at least  $n-1$  (cf. Proposition A.2 below). Hence, it follows from (15) and (18) that

$$(21) \quad \inf_{\lambda \in \mathbb{R}} \sup_{S^{n-1}} |\chi(t) - \lambda g_{S^{n-1}}|_{g_{S^{n-1}}} \leq N_2 (1-t)^{\frac{n-1}{2(n-2)}}$$

for all  $t \in [\frac{1}{2}, 1)$ , where  $N_2$  is a positive constant. We now consider the operator  $\sigma \mapsto -\Delta_{S^{n-1}} \sigma + (n-2)\sigma$ , acting on one-forms on  $S^{n-1}$ . By Proposition A.1, the first eigenvalue of this operator is at least  $n-1$ . Using (16) and (19), we deduce that

$$(22) \quad \sup_{S^{n-1}} |\sigma(t)|_{g_{S^{n-1}}} \leq N_3 (1-t)^{\frac{n-1}{2(n-2)}}$$

for all  $t \in [\frac{1}{2}, 1)$ , where  $N_3$  is a positive constant. Finally, using (17) and (20), we obtain

$$(23) \quad \sup_{S^{n-1}} |\beta(t)| \leq N_4$$

for all  $t \in [\frac{1}{2}, 1)$ , where  $N_4$  is a positive constant. If we combine (21), (22), and (23), the assertion follows. q.e.d.

We now study the equation  $\Delta_L h + \mathcal{L}_X(h) = 0$  on  $(M, g)$ , where  $\Delta_L$  denotes the Lichnerowicz Laplacian defined above.

**Lemma 4.2.** *Let  $h$  be a solution of the Lichnerowicz-type equation*

$$\Delta_L h + \mathcal{L}_X(h) = 0$$

*on the region  $\{f \leq \rho\}$ . Then*

$$\sup_{\{f \leq \rho\}} |h| \leq C \rho^2 \sup_{\{f = \rho\}} |h|$$

*for some uniform constant  $C$  which is independent of  $\rho$ .*

*Proof.* It suffices to show that

$$(24) \quad h \leq C \rho^2 \left( \sup_{\{f = \rho\}} |h| \right) g$$

for some uniform constant  $C$ . Indeed, if (24) holds, the assertion follows by applying (24) to  $h$  and  $-h$ .

We now describe the proof of (24). By Proposition 2.1, we have  $f^2 \text{Ric} \geq c g$  for some positive constant  $c$ . Therefore, the tensor  $\text{Ric} - \frac{c}{2} \rho^{-2} g$  is positive definite in the region  $\{f \leq \rho\}$ . Let  $\theta$  be the smallest real number with the property that  $\theta (\text{Ric} - \frac{c}{2} \rho^{-2} g) - h$  is positive semi-definite at each point in the region  $\{f \leq \rho\}$ . There exists a point  $p_0 \in \{f \leq \rho\}$  and an orthonormal basis  $\{e_1, \dots, e_n\}$  of  $T_{p_0} M$  such that

$$\theta \text{Ric}(e_1, e_1) - \frac{\theta c}{2} \rho^{-2} - h(e_1, e_1) = 0$$

at the point  $p_0$ . We now distinguish two cases:

*Case 1:* Suppose that  $p_0 \in \{f < \rho\}$ . In this case, we have

$$\theta (\Delta \text{Ric})(e_1, e_1) - (\Delta h)(e_1, e_1) \geq 0$$

and

$$\theta (D_X \text{Ric})(e_1, e_1) - (D_X h)(e_1, e_1) = 0$$

at the point  $p_0$ . Using the identity  $\Delta_L h + \mathcal{L}_X(h) = 0$ , we obtain

$$\begin{aligned} 0 &= (\Delta h)(e_1, e_1) + (D_X h)(e_1, e_1) + 2 \sum_{i,k=1}^n R(e_1, e_i, e_1, e_k) h(e_i, e_k) \\ &\leq \theta (\Delta \text{Ric})(e_1, e_1) + \theta (D_X \text{Ric})(e_1, e_1) + 2 \sum_{i,k=1}^n R(e_1, e_i, e_1, e_k) h(e_i, e_k) \\ &= -2 \sum_{i,k=1}^n R(e_1, e_i, e_1, e_k) (\theta \text{Ric}(e_i, e_k) - h(e_i, e_k)) \\ &= -\theta c \rho^{-2} \text{Ric}(e_1, e_1) \\ &\quad - 2 \sum_{i,k=1}^n R(e_1, e_i, e_1, e_k) \left( \theta \text{Ric}(e_i, e_k) - \frac{\theta c}{2} \rho^{-2} g(e_i, e_k) - h(e_i, e_k) \right) \end{aligned}$$

at the point  $p_0$ . Since  $(M, g)$  has positive sectional curvature, we have

$$\sum_{i,k=1}^n R(e_1, e_i, e_1, e_k) \left( \theta \operatorname{Ric}(e_i, e_k) - \frac{\theta c}{2} \rho^{-2} g(e_i, e_k) - h(e_i, e_k) \right) \geq 0.$$

Consequently,  $\theta \leq 0$ . This implies  $h \leq 0$  at each point in the region  $\{f \leq \rho\}$ . Therefore, (24) is satisfied in this case.

*Case 2:* Suppose that  $p_0 \in \{f = \rho\}$ . Since  $f^2 \operatorname{Ric} \geq c g$ , we have

$$\frac{\theta c}{2} \leq \theta \rho^2 \operatorname{Ric}(e_1, e_1) - \frac{\theta c}{2} = \rho^2 h(e_1, e_1) \leq \rho^2 \sup_{\{f=\rho\}} |h|.$$

Since  $h \leq \theta (\operatorname{Ric} - \frac{c}{2} \rho^{-2} g)$ , we conclude that

$$h \leq C \rho^2 \left( \sup_{\{f=\rho\}} |h| \right) g$$

at each point in the region  $\{f \leq \rho\}$ . This proves (24). q.e.d.

**Lemma 4.3.** *Let  $h$  be a solution of the Lichnerowicz-type equation*

$$\Delta_L h + \mathcal{L}_X(h) = 0$$

*on the region  $\{f \leq \rho\}$ . Then*

$$\sup_{\{f \leq \rho\}} f^2 |h| \leq B \rho^2 \sup_{\{f=\rho\}} |h|,$$

*where  $B$  is a positive constant that does not depend on  $\rho$ .*

*Proof.* As above, it suffices to show that

$$(25) \quad f^2 h \leq C \rho^2 \left( \sup_{\{f=\rho\}} |h| \right) g$$

for some uniform constant  $C$ . We now describe the proof of (25). By Proposition 2.1, we can find a compact set  $K$  such that  $f \operatorname{Ric} < (1 - 3 f^{-1} |\nabla f|^2) g$  on  $M \setminus K$ . Let us consider the smallest real number  $\theta$  with the property that  $\theta f^{-2} g - h$  is positive semi-definite at each point in the region  $\{f \leq \rho\}$ . By definition of  $\theta$ , there exists a point  $p_0 \in \{f \leq \rho\}$  and an orthonormal basis  $\{e_1, \dots, e_n\}$  of  $T_{p_0} M$  such that

$$\theta f^{-2} - h(e_1, e_1) = 0$$

at the point  $p_0$ . Let us distinguish two cases:

*Case 1:* Suppose that  $p_0 \in \{f < \rho\} \setminus K$ . In this case, we have

$$\theta \Delta(f^{-2}) - (\Delta h)(e_1, e_1) \geq 0$$

and

$$\theta \langle X, \nabla(f^{-2}) \rangle - (D_X h)(e_1, e_1) = 0$$

at the point  $p_0$ . Using the identity  $\Delta_L h + \mathcal{L}_X(h) = 0$ , we obtain

$$\begin{aligned} 0 &= (\Delta h)(e_1, e_1) + (D_X h)(e_1, e_1) + 2 \sum_{i,k=1}^n R(e_1, e_i, e_1, e_k) h(e_i, e_k) \\ &\leq \theta \Delta(f^{-2}) + \theta \langle X, \nabla(f^{-2}) \rangle + 2 \sum_{i,k=1}^n R(e_1, e_i, e_1, e_k) h(e_i, e_k) \\ &= -2\theta f^{-3} (1 - 3f^{-1} |\nabla f|^2 - f \operatorname{Ric}(e_1, e_1)) \\ &\quad - 2 \sum_{i,k=1}^n R(e_1, e_i, e_1, e_k) (\theta f^{-2} g(e_i, e_k) - h(e_i, e_k)) \end{aligned}$$

at the point  $p_0$ . Since  $(M, g)$  has positive sectional curvature, we have

$$\sum_{i,k=1}^n R(e_1, e_i, e_1, e_k) (\theta f^{-2} g(e_i, e_k) - h(e_i, e_k)) \geq 0,$$

hence

$$0 \leq -2\theta f^{-3} (1 - 3f^{-1} |\nabla f|^2 - f \operatorname{Ric}(e_1, e_1)).$$

On the other hand, we have  $f \operatorname{Ric}(e_1, e_1) < 1 - 3f^{-1} |\nabla f|^2$  since  $p_0 \in M \setminus K$ . Consequently, we have  $\theta \leq 0$ . This implies that  $h \leq 0$  at each point in the region  $\{f \leq \rho\}$ , and (25) is trivially satisfied.

*Case 2:* We next assume that  $p_0 \in \{f = \rho\} \cup K$ . Using Lemma 4.2, we obtain

$$\theta = f^2 h(e_1, e_1) \leq \sup_{\{f=\rho\} \cup K} f^2 |h| \leq C \rho^2 \sup_{\{f=\rho\}} |h|.$$

Since  $f^2 h \leq \theta g$ , we conclude that

$$f^2 h \leq C \rho^2 \left( \sup_{\{f=\rho\}} |h| \right) g$$

at each point in the region  $\{f \leq \rho\}$ . This proves (25). q.e.d.

**Theorem 4.4.** *Suppose that  $h$  is a solution of the Lichnerowicz-type equation*

$$\Delta_L h + \mathcal{L}_X(h) = 0$$

*with the property that  $|h| \leq O(r^{\frac{1}{2(n-2)} - \frac{1}{2} - \varepsilon})$ . Then  $h = \lambda \operatorname{Ric}$  for some constant  $\lambda \in \mathbb{R}$ .*

*Proof.* Let us consider the function

$$A(r) = \inf_{\lambda \in \mathbb{R}} \sup_{\{f=r\}} |h - \lambda \operatorname{Ric}|.$$

Clearly,  $A(r) \leq \sup_{\{f=r\}} |h| \leq O(r^{\frac{1}{2(n-2)} - \frac{1}{2} - \varepsilon})$ . We consider two cases:

*Case 1:* Suppose that there exists a sequence of real numbers  $r_m \rightarrow \infty$  such that  $A(r_m) = 0$  for all  $m$ . In this case, we can find a sequence of

real numbers  $\lambda_m$  such that  $h - \lambda_m \text{Ric} = 0$  on the level surface  $\{f = r_m\}$ . Using Lemma 4.3, we conclude that  $h - \lambda_m \text{Ric} = 0$  in the region  $\{f \leq r_m\}$ . Therefore, the sequence  $\lambda_m$  is constant. Moreover,  $h$  is a constant multiple of the Ricci tensor.

*Case 2:* Suppose now that  $A(r) > 0$  when  $r$  is sufficiently large. Let us fix a real number  $\tau \in (0, \frac{1}{2})$  such that  $\tau^{-\varepsilon} > 2NB$ , where  $N$  and  $B$  are the constants in Lemma 4.1 and Lemma 4.3, respectively. Since  $A(r) \leq O(r^{\frac{1}{2(n-2)} - \frac{1}{2} - \varepsilon})$ , there exists a sequence of real numbers  $r_m \rightarrow \infty$  such that

$$A(r_m) \leq 2\tau^{\frac{1}{2} - \frac{1}{2(n-2)} + \varepsilon} A(\tau r_m)$$

for all  $m$ . For each  $m$ , we can find a real number  $\lambda_m$  such that

$$\sup_{\{f=r_m\}} |h - \lambda_m \text{Ric}| = A(r_m).$$

Applying Lemma 4.3 to the tensor

$$\tilde{h}^{(m)} = \frac{1}{A(r_m)} (h - \lambda_m \text{Ric})$$

gives

(26)

$$\sup_{\{f=r\}} |\tilde{h}^{(m)}| \leq \frac{B r_m^2}{r^2} \sup_{\{f=r_m\}} |\tilde{h}^{(m)}| = \frac{B r_m^2}{r^2 A(r_m)} \sup_{\{f=r_m\}} |h - \lambda_m \text{Ric}| = \frac{B r_m^2}{r^2}$$

for  $r \leq r_m$ .

At this point, we define

$$\hat{g}^{(m)}(t) = r_m^{-1} \Phi_{r_m t}^*(g)$$

and

$$\hat{h}^{(m)}(t) = r_m^{-1} \Phi_{r_m t}^*(\tilde{h}^{(m)}).$$

The metrics  $\hat{g}^{(m)}(t)$  evolve by the Ricci flow, and the tensors  $\hat{h}^{(m)}(t)$  satisfy the parabolic Lichnerowicz equation

$$\frac{\partial}{\partial t} \hat{h}^{(m)}(t) = \Delta_{L, \hat{g}^{(m)}(t)} \hat{h}^{(m)}(t).$$

Using (26), we obtain

$$\limsup_{m \rightarrow \infty} \sup_{t \in [\delta, 1-\delta]} \sup_{\{r_m - \delta^{-1} \sqrt{r_m} \leq f \leq r_m + \delta^{-1} \sqrt{r_m}\}} |\hat{h}^{(m)}(t)|_{\hat{g}^{(m)}(t)} < \infty$$

for any given  $\delta \in (0, \frac{1}{2})$ .

We now pass to the limit as  $m \rightarrow \infty$ . Let us choose a sequence of marked points  $p_m \in M$  satisfying  $f(p_m) = r_m$ . The manifolds  $(M, \hat{g}^{(m)}(t), p_m)$  converge in the Cheeger-Gromov sense to a one-parameter family of shrinking cylinders  $(S^{n-1} \times \mathbb{R}, \bar{g}(t))$ ,  $t \in (0, 1)$ , where  $\bar{g}(t)$  is given by (1). The vector fields  $r_m^{\frac{1}{2}} X$  converge to the axial vector field

$\frac{\partial}{\partial z}$  on  $S^{n-1} \times \mathbb{R}$ . Furthermore, the sequence  $\hat{h}^{(m)}(t)$  converges to a one-parameter family of tensors  $\bar{h}(t)$ ,  $t \in (0, 1)$ , which solve the parabolic Lichnerowicz equation

$$\frac{\partial}{\partial t} \bar{h}(t) = \Delta_{L, \bar{g}(t)} \bar{h}(t).$$

As in [4], we can show that  $\bar{h}(t)$  is invariant under translations along the axis of the cylinder. Using (26), we obtain

$$|\bar{h}(t)|_{\bar{g}(t)} \leq B(1-t)^{-2}$$

for all  $t \in (0, \frac{1}{2}]$ . Hence, Lemma 4.1 implies that

$$(27) \quad \inf_{\lambda \in \mathbb{R}} \sup_{S^{n-1} \times \mathbb{R}} |\bar{h}(t) - \lambda \text{Ric}_{\bar{g}(t)}|_{\bar{g}(t)} \leq NB(1-t)^{\frac{1}{2(n-2)} - \frac{1}{2}}$$

for all  $t \in [\frac{1}{2}, 1)$ . On the other hand, we have

$$\begin{aligned} & \inf_{\lambda \in \mathbb{R}} \sup_{\Phi_{r_m(\tau-1)}(\{f=\tau r_m\})} \left| \hat{h}^{(m)}(1-\tau) - \lambda \text{Ric}_{\hat{g}^{(m)}(1-\tau)} \right|_{\hat{g}^{(m)}(1-\tau)} \\ &= \inf_{\lambda \in \mathbb{R}} \sup_{\{f=\tau r_m\}} |\tilde{h}^{(m)} - \lambda \text{Ric}_g|_g \\ &= \frac{1}{A(r_m)} \inf_{\lambda \in \mathbb{R}} \sup_{\{f=\tau r_m\}} |h - \lambda \text{Ric}_g|_g \\ &= \frac{A(\tau r_m)}{A(r_m)} \\ &\geq \frac{1}{2} \tau^{\frac{1}{2(n-2)} - \frac{1}{2} - \varepsilon}. \end{aligned}$$

If we send  $m \rightarrow \infty$ , we obtain

$$(28) \quad \inf_{\lambda \in \mathbb{R}} \sup_{S^{n-1} \times \mathbb{R}} |\bar{h}(1-\tau) - \lambda \text{Ric}_{\bar{g}(1-\tau)}|_{\bar{g}(1-\tau)} \geq \frac{1}{2} \tau^{\frac{1}{2(n-2)} - \frac{1}{2} - \varepsilon}.$$

Since  $\tau^{-\varepsilon} > 2NB$ , the inequality (28) contradicts (27). This completes the proof of Theorem 4.4. q.e.d.

## 5. Proof of Theorem 1.2

Combining Theorems 3.5 and 4.4, we obtain the following symmetry principle:

**Theorem 5.1.** *Suppose that  $U$  is a vector field on  $(M, g)$  such that  $|\mathcal{L}_U(g)| \leq O(r^{\frac{1}{2(n-2)} - \frac{1}{2} - 2\varepsilon})$  and  $|\Delta U + D_X U| \leq O(r^{\frac{1}{2(n-2)} - 1 - 2\varepsilon})$  for some small constant  $\varepsilon > 0$ . Then there exists a vector field  $\hat{U}$  on  $(M, g)$  such that  $\mathcal{L}_{\hat{U}}(g) = 0$ ,  $[\hat{U}, X] = 0$ ,  $\langle \hat{U}, X \rangle = 0$ , and  $|\hat{U} - U| \leq O(r^{\frac{1}{2(n-2)} - \varepsilon})$ .*

*Proof.* In view of Theorem 3.5, the equation

$$\Delta V + D_X V = \Delta U + D_X U$$

has a smooth solution which satisfies the bounds  $|V| \leq O(r^{\frac{1}{2(n-2)}-\varepsilon})$  and  $|DV| \leq O(r^{\frac{1}{2(n-2)}-\frac{1}{2}-\varepsilon})$ . Hence, the vector field  $W = U - V$  satisfies  $\Delta W + D_X W = 0$ . Using Theorem 4.1 in [4], we conclude that the Lie derivative  $h = \mathcal{L}_W(g)$  satisfies the Lichnerowicz-type equation

$$\Delta_L h + \mathcal{L}_X(h) = 0.$$

Since  $|h| \leq O(r^{\frac{1}{2(n-2)}-\frac{1}{2}-\varepsilon})$ , Theorem 4.4 implies that  $h = \lambda \text{Ric}$  for some constant  $\lambda \in \mathbb{R}$ . Consequently, the vector field  $\hat{U} := U - V - \frac{1}{2} \lambda X$  must be a Killing vector field. The identities  $[\hat{U}, X] = 0$  and  $\langle \hat{U}, X \rangle = 0$  follow as in [4]. q.e.d.

To complete the proof of Theorem 1.2, we apply Theorem 5.1 to the vector fields  $U_a$  constructed in Proposition 2.6. Consequently, there exist vector fields  $\hat{U}_a, a \in \{1, \dots, \frac{n(n-1)}{2}\}$ , on  $(M, g)$  such that  $\mathcal{L}_{\hat{U}_a}(g) = 0, [\hat{U}_a, X] = 0$ , and  $\langle \hat{U}_a, X \rangle = 0$ . Moreover, we have

$$\sum_{a=1}^{\frac{n(n-1)}{2}} \hat{U}_a \otimes \hat{U}_a = r \left( \sum_{i=1}^{n-1} e_i \otimes e_i + O(r^{\frac{1}{2(n-2)}-\frac{1}{2}-\varepsilon}) \right),$$

where  $\{e_1, \dots, e_{n-1}\}$  is a local orthonormal frame on the level set  $\{f = r\}$ . This shows that  $(M, g)$  is rotationally symmetric.

### 6. Proof of Theorem 1.3

We now describe how Theorem 1.3 follows from Theorem 1.2. Let  $(M, g)$  be a four-dimensional steady gradient Ricci soliton which is non-flat; is  $\kappa$ -noncollapsed; and satisfies the pointwise pinching condition

$$0 \leq \max\{a_3, b_3, c_3\} \leq \Lambda \min\{a_1 + a_2, c_1 + c_2\}$$

for some constant  $\Lambda \geq 1$ . In particular,  $(M, g)$  has nonnegative isotropic curvature. Moreover, since the sum  $R + |\nabla f|^2$  is constant, the scalar curvature of  $(M, g)$  is bounded from above; consequently,  $(M, g)$  has bounded curvature.

We next show that  $(M, g)$  has positive curvature operator. To that end, we adapt the arguments in [12] and [13]. We note that pinching estimates for ancient solutions to the Ricci flow were established in [5].

**Lemma 6.1.** *We have  $a_3 \leq (6\Lambda^2 + 1) a_1$  and  $c_3 \leq (6\Lambda^2 + 1) a_1$ .*

*Proof.* Using the inequalities

$$\Delta a_1 + \langle X, \nabla a_1 \rangle \leq -2a_2 a_3$$

and

$$\Delta a_3 + \langle X, \nabla a_3 \rangle \geq -a_3^2 - 2a_1 a_2 - b_3^2,$$

we obtain

$$\begin{aligned} & \Delta((6\Lambda^2 + 1)a_1 - a_3) + \langle X, \nabla((6\Lambda^2 + 1)a_1 - a_3) \rangle \\ & \leq a_3^2 + 2a_1 a_2 + b_3^2 - (12\Lambda^2 + 2)a_2 a_3 \\ & \leq a_3^2 + b_3^2 - 12\Lambda^2 a_2 a_3 \\ & \leq a_3^2 + b_3^2 - 3\Lambda^2 (a_1 + a_2)^2 \\ & \leq -a_3^2. \end{aligned}$$

Hence, the Omori-Yau maximum principle implies that  $(6\Lambda^2 + 1)a_1 - a_3 \geq 0$ . The inequality  $(6\Lambda^2 + 1)c_1 - c_3 \geq 0$  follows similarly.  $\square$  q.e.d.

**Lemma 6.2.** *We have  $4b_3^2 \leq (a_1 + a_2)(c_1 + c_2)$ .*

*Proof.* Suppose that  $\gamma = \sup_M \frac{2b_3}{\sqrt{(a_1 + a_2)(c_1 + c_2)}} > 1$ . The function  $u = \frac{1}{2} \sqrt{(a_1 + a_2)(c_1 + c_2)}$  satisfies

$$\begin{aligned} & \Delta u + \langle X, \nabla u \rangle \\ & \leq -u \left[ a_3 + c_3 + \frac{a_1^2 + a_2^2 + b_1^2 + b_2^2}{2(a_1 + a_2)} + \frac{c_1^2 + c_2^2 + b_1^2 + b_2^2}{2(c_1 + c_2)} \right]. \end{aligned}$$

On the other hand, we have

$$\Delta b_3 + \langle X, \nabla b_3 \rangle \geq -b_3(a_3 + c_3) - 2b_1 b_2.$$

Putting these facts together, we obtain

$$\begin{aligned} & \Delta(\gamma u - b_3) + \langle X, \nabla(\gamma u - b_3) \rangle \\ & \leq -\gamma u \left[ a_3 + c_3 + \frac{a_1^2 + a_2^2 + b_1^2 + b_2^2}{2(a_1 + a_2)} + \frac{c_1^2 + c_2^2 + b_1^2 + b_2^2}{2(c_1 + c_2)} \right] \\ & \quad + b_3(a_3 + c_3) + 2b_1 b_2 \\ & = -\gamma u \frac{(a_1 - b_1)^2 + (a_2 - b_2)^2 + 2a_2(b_2 - b_1)}{2(a_1 + a_2)} \\ & \quad - \gamma u \frac{(c_1 - b_1)^2 + (c_2 - b_2)^2 + 2c_2(b_2 - b_1)}{2(c_1 + c_2)} \\ & \quad - (\gamma u - b_3)(a_3 + c_3 + 2b_1) - 2b_1(b_3 - b_2). \end{aligned}$$

Note that  $\gamma u - b_3 \geq 0$  by definition of  $\gamma$ . Since  $\gamma > 1$ , we can find a positive constant  $\delta$  such that

$$\begin{aligned} 3\delta |\text{Ric}|^2 & \leq \gamma u \frac{(a_1 - b_1)^2 + (a_2 - b_2)^2 + 2a_2(b_2 - b_1)}{2(a_1 + a_2)} \\ & \quad + \gamma u \frac{(c_1 - b_1)^2 + (c_2 - b_2)^2 + 2c_2(b_2 - b_1)}{2(c_1 + c_2)} \\ & \quad + (\gamma u - b_3)(a_3 + c_3 + 2b_1) + 2b_1(b_3 - b_2). \end{aligned}$$

This implies

$$\Delta(\gamma u - b_3) + \langle X, \nabla(\gamma u - b_3) \rangle \leq -3\delta |\text{Ric}|^2,$$

hence

$$\Delta(\gamma u - b_3 - \delta R) + \langle X, \nabla(\gamma u - b_3 - \delta R) \rangle \leq -\delta |\text{Ric}|^2.$$

Using the Omori-Yau maximum principle, we conclude that  $\gamma u - b_3 - \delta R \geq 0$ . This contradicts the definition of  $\gamma$ . Thus,  $\gamma \leq 1$ , as claimed. q.e.d.

**Proposition 6.3.** *We have  $b_3^2 \leq a_1 c_1$ .*

*Proof.* Suppose that  $\gamma = \sup_M \frac{b_3}{\sqrt{a_1 c_1}} > 1$ . The function  $v = \sqrt{a_1 c_1}$  satisfies

$$\Delta v + \langle X, \nabla v \rangle \leq -v \left[ \frac{a_1^2 + 2a_2 a_3 + b_1^2}{2a_1} + \frac{c_1^2 + 2c_2 c_3 + b_1^2}{2c_1} \right].$$

This implies

$$\begin{aligned} & \Delta(\gamma v - b_3) + \langle X, \nabla(\gamma v - b_3) \rangle \\ & \leq -\gamma v \left[ \frac{a_1^2 + 2a_2 a_3 + b_1^2}{2a_1} + \frac{c_1^2 + 2c_2 c_3 + b_1^2}{2c_1} \right] \\ & \quad + b_3(a_3 + c_3) + 2b_1 b_2 \\ & = -\gamma v \left[ \frac{(a_1 - b_1)^2 + 2(a_2 - a_1)a_3}{2a_1} + \frac{(c_1 - b_1)^2 + 2(c_2 - c_1)c_3}{2c_1} \right] \\ & \quad - (\gamma v - b_3)(a_3 + c_3 + 2b_1) - 2b_1(b_3 - b_2). \end{aligned}$$

Note that  $\gamma v - b_3 \geq 0$  by definition of  $\gamma$ . Using Lemma 6.2 and the inequality  $\gamma > 1$ , we obtain an estimate of the form

$$\begin{aligned} 3\delta |\text{Ric}|^2 & \leq \gamma v \left[ \frac{(a_1 - b_1)^2 + 2(a_2 - a_1)a_3}{2a_1} + \frac{(c_1 - b_1)^2 + 2(c_2 - c_1)c_3}{2c_1} \right] \\ & \quad + (\gamma v - b_3)(a_3 + c_3 + 2b_1) + 2b_1(b_3 - b_2) \end{aligned}$$

for some positive constant  $\delta$ . From this, we deduce that

$$\Delta(\gamma v - b_3) + \langle X, \nabla(\gamma v - b_3) \rangle \leq -3\delta |\text{Ric}|^2,$$

hence

$$\Delta(\gamma v - b_3 - \delta R) + \langle X, \nabla(\gamma v - b_3 - \delta R) \rangle \leq -\delta |\text{Ric}|^2.$$

As above, the Omori-Yau maximum principle implies that  $\gamma v - b_3 - \delta R \geq 0$ . This contradicts the definition of  $\gamma$ . Consequently,  $\gamma \leq 1$ , which proves the assertion. q.e.d.

**Corollary 6.4.** *The manifold  $(M, g)$  has positive curvature operator.*

*Proof.* The inequality  $b_3^2 \leq a_1 c_1$  implies that  $(M, g)$  has nonnegative curvature operator. If  $(M, g)$  has generic holonomy group, then the strict maximum principle (cf. [12]) implies that  $(M, g)$  has positive curvature operator. On the other hand, if  $(M, g)$  has non-generic holonomy group, then  $(M, g)$  locally splits as a product. In this case, we can deduce from Proposition 6.3 that  $(M, g)$  is isometric to a cylinder. This contradicts the fact that  $(M, g)$  is a steady soliton. q.e.d.

Note that  $(M, g)$  satisfies restricted isotropic curvature pinching condition in [10]. Using the compactness theorem for ancient  $\kappa$ -solutions in [10], we obtain:

**Proposition 6.5** (Chen and Zhu [10]). *Let  $p_m$  be a sequence of points going to infinity. Then  $|\langle X, \nabla R \rangle| \leq O(1) R^2$  at the point  $p_m$ . Moreover, if  $d(p_0, p_m)^2 R(p_m) \rightarrow \infty$ , then we have  $|\nabla R| \leq o(1) R^{\frac{3}{2}}$  and  $|\langle X, \nabla R \rangle + \frac{2}{3} R^2| \leq o(1) R^2$  at the point  $p_m$ .*

*Proof.* The first statement follows immediately from Proposition 3.3 in [10]. To prove the second statement, we consider a sequence of points  $p_m$  such that  $d(p_0, p_m)^2 R(p_m) \rightarrow \infty$ . Combining the compactness theorem for ancient solutions (cf. [10, Corollary 3.7]) with the splitting theorem (cf. [10, Lemma 3.1]), we conclude that  $|\nabla R| \leq o(1) R^{\frac{3}{2}}$ ,  $|\Delta R| \leq o(1) R^2$ , and  $3|\text{Ric}|^2 = (1 + o(1)) R^2$ . From this, we deduce that  $-\langle X, \nabla R \rangle = \Delta R + 2|\text{Ric}|^2 = (\frac{2}{3} + o(1)) R^2$ , as claimed. q.e.d.

Using Proposition 6.5, it is not difficult to show that  $R \rightarrow 0$  at infinity. Consequently, there exists a unique point  $p_0 \in M$  where the scalar curvature attains its maximum. The point  $p_0$  must be a critical point of the function  $f$ . Since  $f$  is strictly convex, we conclude that  $f$  grows linearly near infinity. If we integrate the inequality  $|\langle X, \nabla R \rangle| \leq O(1) R^2$  along integral curves of  $X$ , we obtain  $R \geq \frac{\Lambda_1}{d(p_0, p)}$  outside a compact set, where  $\Lambda_1$  is a positive constant. Hence, Proposition 6.5 gives  $|\langle X, \nabla R \rangle + \frac{2}{3} R^2| \leq o(1) R^2$ . Integrating this inequality along integral curves of  $X$ , we obtain  $R \leq \frac{\Lambda_2}{d(p_0, p)}$  outside a compact set. Using Lemma 3.1 in [10] again, we conclude that  $(M, g)$  is asymptotically cylindrical. Hence,  $(M, g)$  must be rotationally symmetric by Theorem 1.2.

### Appendix A. The eigenvalues of some elliptic operators on $S^{n-1}$

In this section, we analyze the eigenvalues of certain elliptic operators on  $S^{n-1}$ . In the following,  $g_{S^{n-1}}$  will denote the standard metric on  $S^{n-1}$  with constant sectional curvature 1.

**Proposition A.1.** *Let  $\sigma$  be a one-form on  $S^{n-1}$  satisfying*

$$\Delta_{S^{n-1}} \sigma + \mu \sigma = 0,$$

where  $\Delta_{S^{n-1}}$  denotes the rough Laplacian and  $\mu \in (-\infty, 1)$  is a constant. Then  $\sigma = 0$ .

*Proof.* For any smooth function  $u$ , we have

$$\begin{aligned} \int_{S^{n-1}} u \Delta_{S^{n-1}}(d^* \sigma) &= \int_{S^{n-1}} \langle d(\Delta_{S^{n-1}} u), \sigma \rangle \\ &= \int_{S^{n-1}} \langle \Delta_{S^{n-1}}(du), \sigma \rangle - (n-2) \int_{S^{n-1}} \langle du, \sigma \rangle \\ &= -(n-2+\mu) \int_{S^{n-1}} \langle du, \sigma \rangle \\ &= -(n-2+\mu) \int_{S^{n-1}} u d^* \sigma. \end{aligned}$$

Since  $u$  is arbitrary, we conclude that

$$\Delta_{S^{n-1}}(d^* \sigma) + (n-2+\mu) d^* \sigma = 0.$$

Since  $n-2+\mu < n-1$ , it follows that  $d^* \sigma$  is constant. Consequently,  $d^* \sigma = 0$  by the divergence theorem.

We next consider the tensor  $S_{ik} = D_i \sigma_k + D_k \sigma_i$ . Then

$$(n-2-\mu) \sigma_i = \Delta_{S^{n-1}} \sigma_i + (n-2) \sigma_i = D^k S_{ik} - \frac{1}{2} D_i(\text{tr } S).$$

Using the identity  $d^* \sigma = 0$ , we obtain

$$(n-2-\mu) \int_{S^{n-1}} |\sigma|^2 = \int_{S^{n-1}} \left( D^k S_{ik} - \frac{1}{2} D_i(\text{tr } S) \right) \sigma^i = -\frac{1}{2} \int_{S^{n-1}} |S|^2.$$

Since  $n-2-\mu > 0$ , we conclude that  $\sigma = 0$ , as claimed. q.e.d.

**Proposition A.2.** *Let  $\chi$  be a symmetric  $(0, 2)$ -tensor on  $S^{n-1}$  satisfying*

$$\Delta_{S^{n-1}} \chi - 2(n-1) \overset{\circ}{\chi} + \mu \chi = 0,$$

where  $\overset{\circ}{\chi}$  denotes the trace-free part of  $\chi$  and  $\mu \in (-\infty, n-1)$  is a constant. Then  $\chi$  is a constant multiple of  $g_{S^{n-1}}$ .

*Proof.* The trace of  $\chi$  satisfies

$$\Delta_{S^{n-1}}(\text{tr } \chi) + \mu(\text{tr } \chi) = 0.$$

Since  $\mu < n-1$ , we conclude that  $\text{tr } \chi$  is constant. Moreover, the trace-free part of  $\chi$  satisfies

$$\Delta_{S^{n-1}} \overset{\circ}{\chi} + (\mu - 2(n-1)) \overset{\circ}{\chi} = 0.$$

Since  $\mu - 2(n-1) < 0$ , it follows that  $\overset{\circ}{\chi} = 0$ . Putting these facts together, the assertion follows. q.e.d.

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