PROLONGATION OF CONNECTIONS TO BUNDLES OF INFINITELY NEAR POINTS

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Introduction

The purpose of this paper is to generalize the results of [5] to the bundles of infinitely near points of A-kinds in the sense of A. Weil [7], which generalizes the notions of p^r -jets in the sense of C. Ehresmann [1], [2]. Our results naturally generalizes the results of several authors, e.g., [4], [8], [10]. In fact, we have treated the same problem in the author's lecture notes (cf. [6, Part V]). However, in [6] we fully used the basis and structure constants of the local algebra A, and were obliged to consider (λ) -lifts of vector fields, 1-forms or tensor fields of type (p,q) with p=0 or 1, where $\lambda=0,1,2,\cdots,N$ and $N+1=\dim A$. Moreover, the geometric meaning of (λ) -lifts for $\lambda=1,2,\cdots,N$ are not so clear as that of (0)-lifts. In this paper, we shall essentially not use the basis and structure constants of the algebra A, and shall show that there exists essentially only one lift, which has a significant geometric meaning, and other (λ) -lifts can be derived naturally from that lift. Further, the proofs in [6] are much simplified, and some of results are somewhat sharpened (cf. [6, Theorem 6.6]).

In § 1, we explain the notion of local algebras and the infinitely near points of A-kind which will be simply called A-points. The covariant functor, which assigns to each manifold M its bundle M^A of infinitely near points, has many nice properties similar to the functor which assigns to M its tangent bundle T(M). In particular, if G is a Lie group (acting on a manifold M), then G^A is also a Lie group (acting on M^A).

- In § 2, by means of two different methods we define two A-module structures on the tangent space to M^A at each point of M^A , and we shall in fact show that these two A-module structures are essentially the same.
- In § 3, we shall define the lift of vector fields and establish some relations between the lift of functions and the bracket of vector fields.
- In § 4, § 5, we shall consider the lifting of covariant tensor fields and (1, 1)-tensor fields respectively. We shall prove that the lifting J^A of an almost complex structure J is integrable if and only if J is integrable.
- In § 6, we shall first construct the prolongation of affine connections (Theorem 6.1), and next show that the prolonged affine connection \mathcal{F}^A is locally

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affine symmetric if and only if Γ is.

In § 7, we shall give a proof for the fact that if M is an affine symmetric space then M^4 is also so. In such a manner, we obtain a method to construct a large number of affine symmetric spaces (resp. complex manifolds) from a given affine symmetric space (resp. complex manifold), (cf. [10, Introduction]).

In this paper, all manifolds and mappings (functions) are assumed to be differentiable of class C^{∞} , unless otherwise stated.

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1. Infinitely near points of A-kind

In this section we shall recall the notion of local algebras and infinitely near points of A-kind in the sense of A. Weil [7].

Definition 1.1. Let A be an associative algebra over the field R of real numbers with a unit (denoted by 1). We call A a local algebra if A is commutative and of finite dimension over R, admitting a unique maximal ideal m such that A/m is of dimension 1 over R and that $m^{h+1} = (0)$ for a nonnegative integer h. The smallest h such that $m^{h+1} = (0)$ will be called the height of A. We shall identify the field R with the subspace of A consisting of all scalar multiples of the unit 1. Clearly A is the direct sum of R and m as a vector space. If $a \in A$, the scalar $a_0 \in R$, defined by $a \equiv a_0 \mod m$, will be called the finite part of a. If A/m is identified with R, the map $a \to a_0$ is a homomorphism of A onto R.

Let $R[p] = R[[X_1, \dots, X_p]]$ be the algebra of all formal power series of p indeterminates X_1, \dots, X_p , and let \mathfrak{m}_p be the maximal ideal of R[p] consisting of all formal power series without constant terms. Let α be an ideal of R[p] such that dim $R[p]/\alpha < + \infty$. We see that $A = R[p]/\alpha$ is a local algebra with the maximal ideal $\mathfrak{m} = \mathfrak{m}_p/\alpha$. Conversely, we know that every local algebra is isomorphic to such a local algebra (cf. [7, p. 112]).

Let M be a manifold of dimension n, and let $C^{\infty}(M)$ be the algebra of all differentiable functions on M. Take a point $x \in M$.

Definition 1.2. Let A be a local algebra with the maximal ideal \mathfrak{m} . An algebra homomorphism $x': C^{\infty}(M) \to A$ will be called an A-point of M near to x (or *infinitely near point* to x on M of A-kind) if the finite part of x'(f) is equal to f(x), i.e.,

$$(1.1) x'(f) \equiv f(x) \text{mod } \mathfrak{m}$$

for every $f \in C^{\infty}(M)$. We denote by M_x^A the set of all A-points of M near to x and $M^A = \bigcup_{x \in M} M_x^A$, and define $\pi_A : M^A \to M$ by $\pi_A(M_x^A) = x$ for $x \in M$.

Remark 1.3. If $x' \in M_x^A$, and $f \in C^{\infty}(M)$ vanishes identically on a neighborhood of x, then we see that x'(f) = 0.

This remark shows that we can consider x'(f) for any differentiable function f defined on a neighborhood of x if $x' \in M_x^A$.

Remark 1.4. If we take $\alpha = (\mathfrak{m}_p)^{r-1}$, and $A = R[p]/\alpha$, then we see that the notion of A-points is nothing but the notion of p^r -jets (cf. [1], [2], [7]). In particular, if $\alpha = (\mathfrak{m}_1)^2$, $D = R[1]/\alpha$, then the notion of D-points is nothing but the notion of tangent vectors on M. We denote by $\tau = \pi(X_1)$, where X_1 is the indeterminate in R[1] and $\pi \colon R[1] \to D$ is the natural projection.

Let U be a coordinate neighborhood of x_0 in M with coordinate system $\{x_1, \dots, x_n\}$. Take a basis $\{1 = B^0, B^1, \dots, B^N\}$ of a local algebra A, where B^1, \dots, B^N span the maximal ideal \mathfrak{m} of A. We define $x_{i,\lambda} : \pi_A^{-1}(U) \to R$ by

$$\sum_{\lambda=0}^{N} x_{i,\lambda}(x')B^{\lambda} = x'(x_i) ,$$

for any $x' \in \pi_A^{-1}(U)$, where we have used Remark 1.3 for $f = x_i$ $(i = 1, \dots, n)$. We see readily that the set M^A becomes a differentiable manifold of dimension n(N+1) by the coordinate neighborhoods $\pi_A^{-1}(U)$ with coordinate system $\{x_{i,\lambda} | i = 1, \dots, n; \lambda = 0, 1, \dots, N\}$ induced by the coordinate system $\{x_1, \dots, x_n\}$ on U. Clearly this differentiable structure on M^A does not depend on the choice of the basis $\{B^0, \dots, B^N\}$ of A.

Definition 1.5. The differentiable manifold M^A defined above with the projection $\pi_A : M^A \to M$ will be called the *bundle of A-points* of M (or *bundle of infinitely near points* of M of A-kind).

Remark 1.6. The notion of bundle of *D*-kind is the same as that of tangent bundles. A tangent vector $X \in T_x M$ at x is identified with $x' \in M_x^D$ defined by $x'(f) = f(x) + (Xf) \cdot \tau$ for $f \in C^{\infty}(M)$.

Let $\Phi: M \to M'$ be a map of a manifold M into a manifold M'. Then the map $\Phi^A: M^A \to M'^A$ is defined by

$$(0.3) \qquad (\Phi^{A}(x'))g = x'(g \circ \Phi)$$

for $x' \in M^A$ and $g \in C^{\infty}(M')$. Clearly Φ^A is differentiable.

Lemma 1.7. Let $\pi_i: M_1 \times M_2 \to M_i$ (i = 1, 2) be the projections. Then $(M_1 \times M_2)^A$ can be identified with $M_1^A \times M_2^A$ by the following identification

$$(1.4) x' = (\pi_1^A(x'), \pi_2^A(x'))$$

for $x' \in (M_1 \times M_2)^A$.

Proof. Straightforward verification.

Lemma 1.8. Let $\Phi_1: M_1 \to M_1'$, $\Phi_2: M_2 \to M_2'$, $\Psi_1: M_1 \to M_1''$ and $\Phi_1: M_1' \to M$ be differentiable maps, $M_1, M_1', M_2, M_2', M_1''$, M being manifolds. Then we have the following equalities:

$$(\Phi_1' \circ \Phi_1)^A = \Phi_1'^A \circ \Phi_1^A , \qquad (\Phi_1 \times \Phi_2)^A = \Phi_1^A \times \Phi_2^A , (\Phi_1, \Psi_1)^A = (\Phi_1^A, \Psi_2^A) , \qquad (1_M)^A = 1_{M^A} ,$$

where 1_M stands for the identity map of M. Further, if we denote by π_i (resp. $\tilde{\pi}_i$) the projection of $M_1 \times M_2$ (resp. $M_1^A \times M_2^A$) onto M_i (resp. M_i^A) for i = 1, 2, then we have $\pi_i^A = \tilde{\pi}_i$ (i = 1, 2).

Proof. Straightforward verification by using (1.3) and (1.4).

Lemma 1.9. \mathbb{R}^A can be identified with A by $\mathbb{R}^A \ni x' \to x'(t) \in A$, where t is the natural coordinates on \mathbb{R} .

Proof. Straightforward verification (cf. [7]).

Lemma 1.10. Let A and B be two local algebras. Then we can identify A^B with $A \otimes B$ (cf. [7]).

Lemma 1.11. A, B being as above, we can define canonically a diffeomorphism $\psi: (M^A)^B \to M^{A \otimes B}$.

Proof. Take $x'' \in (M^A)^B$ and $f \in C^{\infty}(M)$. Since $f: M \to R$ is a C^{∞} -map, we can consider the map $f^A: M^A \to R^A = A$ (cf. Lemma 1.9). Hence using the map $(f^A)^B: (M^A)^B \to A^B = A \otimes B$ we can consider the map $x': C^{\infty}(M) \to A \otimes B$ defined by $x'(f) = (f^A)^B(x'') \in A \otimes B$, which is easily seen to be an $A \otimes B$ -point on M. Thus we get a map $x'' \to x'$ from $(M^A)^B$ to $M^{A \otimes B}$, which can be verified to be a diffeomorphism (for detail, see [7]).

Corollary 1.12. A and B being as above, we can identify $x'' \in (M^A)^B$ with $x_1'' \in (M^B)^A$ for elements x'' and x_1'' characterized by

$$(f^A)^B(x'') = (f^B)^A(x_1'')$$

for every $f \in C^{\infty}(M)$, where we have identified $A \otimes B$ with $B \otimes A$.

Proof. Clear from the proof of Lemma 1.11.

Lemma 1.13. Let G be a Lie group with group multiplication μ . Then G^A becomes a Lie group with group multiplication $\mu^A : (G \times G)^A = G^A \times G^A$ $\to G^A$.

Proof. Omitted (cf. [7]).

2. A-module structures on the tangent spaces of M^A

In this section, we define canonically an A-module structure on the tangent space of M^A at every point of M^A .

Let $\mu: R \times M^D \to M^D$ be the scalar multiplication of the tangent vectors of M, i.e., $\mu(t, X) = t \cdot X$ for $t \in R$, $X \in M^D$. Since $R^A = A$ and $(M^D)^A = (M^A)^D$ by our identification (cf. Corollary 1.12), the map $\mu^A: (R \times M^D)^A = R^A \times (M^D)^A \to (M^D)^A$ can be considered as the map $\mu^A: A \times (M^A)^D \to (M^A)^D$.

Definition 2.1. Put $\mu^A(a, x'') = a \cdot x''$ for $a \in A$, $x'' \in (M^A)^D$. We denote by π_D (resp. $\tilde{\pi}_D$) the projection $M^D \to M$ (resp. $(M^A)^D \to M^A$).

Lemma 2.2. The notation being as above, we have

- (i) $\tilde{\pi}_D(a \cdot x'') = \tilde{\pi}_D(x'')$ for every $a \in A$ and $x'' \in (M^A)^D$,
- (ii) for any $x' \in M^A$, the tangent space $(M^A)_{x'}^D$ becomes an A-module by the multiplication $(a, x'') \to a \cdot x''$ for $(a, x'') \in A \times (M^A)_{x'}^D$.

Remark 2.3. In fact, in the next section (cf. Corollary 3.10) we shall show

that $(M^A)_{x'}^D$ is a free A-module for any $x' \in M^A$.

Proof of Lemma 2.2. (i) Consider the following diagram:

$$(2.1) \qquad \begin{array}{c} R^{A} \times (M^{A})^{D} \xrightarrow{1 \times j} R^{A} \times (M^{D})^{A} \xrightarrow{\mu^{A}} (M^{D})^{A} \xrightarrow{i} (M^{A})^{D} \\ \tilde{\pi}_{D} \circ \tilde{\pi}_{2} \downarrow \qquad (\pi_{D} \circ \pi_{2})^{A} \downarrow \qquad (\pi_{D})^{A} \downarrow \qquad \tilde{\pi}_{D} \downarrow \\ M^{A} \longrightarrow M^{A} \longrightarrow M^{A} \longrightarrow M^{A} \longrightarrow M^{A} \end{array}$$

where $\tilde{\pi}_2: \mathbb{R}^A \times (M^A)^D \to (M^A)^D$ (resp. $\pi_2: \mathbb{R} \times M^D \to M^D$) is the projection and $j^{-1} = i: (M^D)^A \to (M^A)^D$ is the identification map (cf. Corollary 1.12). Since $\pi_D \circ \mu = \pi_D \circ \pi_2$, the middle rectangle of (2.1) is commutative. It is now sufficient to verify the commutativity of the right rectangle of (2.1), because $a \cdot x'' = (i \circ \mu^A \circ (1 \times j))(a, x'')$ for $(a, x'') \in A \times (M^A)^D$, and the commutativity of the left rectangle is implied by that of the right one.

Take $x'' \in (M^D)^A$ and put $x_1'' = i(x'') \in (M^A)^D$. Then for any $f \in C^{\infty}(M)$, we have

$$(2.2) (f^D)^A(x'') = (f^A)^D(x_1'') ,$$

(cf. Corollary 1.12), where we have identified: $A \otimes D = D \otimes A$. To show that $(\pi_D)^A(x'') = \tilde{\pi}_D(x_1'')$, it suffices to show

$$(2.3) ((\pi_D)^A(x''))(f) = (\tilde{\pi}_D(x_1''))(f)$$

for $f \in C^{\infty}(M^A)$. (2.3) is equivalent to

(2.4)
$$x''(f \circ \pi_D) = f^A(\tilde{\pi}_D(x_1'')) .$$

Now, we know that $f^D \equiv f \circ \pi_D \pmod{R \cdot \tau}$, where $D = R \oplus R\tau$. Therefore we have $(f^A)^D \equiv f^A \circ \tilde{\pi}_D \pmod{A \otimes R\tau}$. Considering the A-components of (2.2) in $A \otimes D = A \oplus A \otimes R\tau$, we obtain (2.4), since $(f^D)^A(x'') = x''(f^D) \equiv x''(f \circ \pi_D) \pmod{A \otimes R \cdot \tau}$. Thus (i) is proved.

(ii) Let $\mu_0 \colon R \times R \to R$ and $\mu_A \colon A \times A \to A$ be the multiplication in R and A respectively. We see easily that $(\mu_0)^A = \mu_A$. The equality $(t \cdot s) \cdot X = t \cdot (s \cdot X)$ for $t, s \in R$ and $X \in M^D$ can be written as $\mu \circ (\mu_0 \circ \pi_{12}, \pi_3) = \mu \circ (\pi_1, \mu \circ \pi_{23})$, where $\pi_{12} \colon R \times R \times M \to R \times R$, $\pi_3 \colon R \times R \times M \to M$ etc. denote the natural projection. Then by the functoriality of $\mu \to \mu^A$, etc. (cf. Lemma 1.8) it follows that $\mu^A \circ (\mu_A \circ \tilde{\pi}_{12}, \tilde{\pi}_3) = \mu^A \circ (\tilde{\pi}_1, \mu^A \circ \tilde{\pi}_{23})$, where $\tilde{\pi}_{12} \colon A \times A \times M^A \to A \times A$ etc. denote the natural projection similar to π_{12} etc. Thus we get the associativity: $(a \cdot b) \cdot x'' = a \cdot (b \cdot x'')$ for $a, b \in A$, $x'' \in M^A$.

The distributivity $(a + b) \cdot x'' = a \cdot x'' + b \cdot x''$, $a \cdot (x' + x'') = a \cdot x' + a \cdot x''$ are similarly proved by using the addition $\alpha : M^D \oplus M^D \to M^D$ of tangent vectors, where $M^D \oplus M^D$ denotes the Whitney sum of the tangent bundles M^D with itself.

Remark 2.4. We can prove (ii) of Lemma 2.1 more quickly by using the local coordinate system around $x'' \in (M^D)^A$ and the local expression of μ^A by coordinates. In fact, taking a coordinate system $\{x_1, \dots, x_n\}$ around x, we see that

$$x_{i,\epsilon,\lambda}(a \cdot x'') = \begin{cases} \sum a_{\kappa} x_{i,\epsilon,\nu}(x'') C_{\lambda}^{\kappa,\nu} & (\varepsilon = 1) ,\\ x_{i,\epsilon,\lambda}(x'') & (\varepsilon = 0) \end{cases}$$

for $a = \sum a_{\kappa}B^{\kappa}$, $B^{\kappa} \cdot B^{\nu} = \sum C_{\lambda}^{\kappa,\nu}B^{\lambda}$ (cf. (1.2)).

We want to give another interpretation of the A-module structure on the tangent space $T_{x'}(M^A)$ with $x' \in M^A$. Let $L \in T_{x'}(M^A)$ be a tangent vector at $x' \in M^A$. Then there exists a curve $t \to x'_t$ on M^A such that $x'_0 = x'$ and that

(2.5)
$$L\tilde{f} = \frac{d\tilde{f}(x_t')}{dt}\Big|_{t=0}$$

for $\tilde{f} \in C^{\infty}(M^A)$. We define $L': C^{\infty}(M) \to A$ by

(2.6)
$$L'f = \frac{d(x'_t(f))}{dt}\bigg|_{t=0}.$$

Lemma 2.5. The map $L': C^{\infty}(M) \to A$ is well-defined and linear, and has the property

$$(2.7) L'(f \cdot g) = L'f \cdot x'(g) + x'(f) \cdot L'g$$

for $f, g \in C^{\infty}(M)$.

Proof. Since $x'_t(f) = f^A(x'_t)$, $x'_t(f)$ is differentiable with respect to t and $\frac{dx'_t(f)}{dt}\Big|_{t=0} = L(f^A)$, (cf. (2.5)). If another curve x''_t on M^A satisfies $x''_0 = x'$

and
$$L\tilde{f} = \frac{d\tilde{f}(x_t'')}{dt}\Big|_{t=0}$$
, then we have $\frac{dx_t'(f)}{dt}\Big|_{t=0} = \frac{dx_t''(f)}{dt}\Big|_{t=0}$. Thus L' is well-defined.

(2.7) can be verified directly.

Definition 2.6. We denote by $T'_{x'}(M^A)$ the set of all linear map $L': C^{\infty}(M) \to A$ such that (2.7) holds for every $f, g \in C^{\infty}(M)$.

Remark 2.7. For $L' \in T'_{x'}M^A$, we can define L'h for any C^{∞} -function h around x.

Thus we have obtained a map $j: T_x M^A \to T_x' M^A$ by j(L) = L', (cf. (2.6)).

Lemma 2.8. The map j is a bijective linear map.

Proof. Let $L_1, L_2 \in T_x M^A$. For $f \in C^{\infty}(M)$ we have $(L_1 + L_2)'f = (L_1 + L_2)f^A = L_1f^A + L_2f^A = L_1'f + L_2'f = (L_1' + L_2')f$. Similarly $(\alpha L_1)'f = (\alpha L_1)f^A = \alpha(L_1f^A) = \alpha(L_1'f) = (\alpha L_1')f$ for $\alpha \in \mathbb{R}$. Thus f is linear.

To prove the bijectivity of j, we first prove

$$\dim T'_{x'}M^A \leq \dim M^A.$$

In fact, take a coordinate system $\{x_1, \dots, x_n\}$ around x, and consider the linear map $g: T'_xM^A \to A^n$ by $g(L') = (L'x_1, \dots, L'x_n)$. We show first that g is injective. Take L'_1 and $L'_2 \in T'_xM^A$ and assume $L'_1x_i = L'_2x_i$ for every $i = 1, \dots, n$. For any $f \in C^{\infty}(M)$ we can find a polynomials P, Q of x_1, \dots, x_n and $g \in C^{\infty}(M)$ such that

$$f = P + g \cdot Q$$

holds on some neighborhood of x, where Q is homogeneous and of degree \geq height of A. Then we have

$$L'_1f = L'_1(P) + L'_1(g)x'(Q) + x'(g)L'_1(Q)$$

= $L'_1(P) + x'(g)L'_1(Q) = L'_2(P) + x'(g)L'_2(Q) = L'_2f$,

where we have used the fact that $x'(f_1 \cdots f_h) = 0$ for $f_i \in C^{\infty}(M)$ with $f_i(x) = 0$. Thus $L'_1 = L'_2$, which proves the injectivity of g. Therefore we get (2.7).

To prove the injectivity of j, it suffices to show that L'f = 0 for every $f \in C^{\infty}(M)$ implies L = 0. Now $\sum L(x_{i,\lambda}) \cdot B^{\lambda} = L(x_i^A) = L'x_i = 0$, which implies $L(x_{i,\lambda}) = 0$ for any $i = 1, \dots, n$; $\lambda = 0, \dots, N$. Thus L = 0. The injectivity and the inequality (2.7) imply the bijectivity of j.

Remark 2.9. $T'_{x'}M^A$ becomes canonically an A-module, i.e., for $a \in A$ and $L' \in T'_{x'}(M^A)$ we define $a \cdot L' \in T'_{x'}(M^A)$ by

$$(a \cdot L')f = a \cdot (L'f)$$

for $f \in C^{\infty}(M)$.

Lemma 2.10. For any $a \in A$ and $L \in T_{x'}(M^A)$, we have

$$(2.8) (a \cdot L)' = a \cdot L'.$$

(Cf. Definition 2.1 for $a \cdot L$).

Proof. To make the several identifications more clear, we introduce the following notation. For $L \in T_x M^A$ the identified element in $(M^A)_{x'}^D$ will be denoted by L^* , and conversely for $K \in (M^A)_{x'}^D$ the corresponding element in $T_x M^A$ will be denoted by *K. Similarly for $S \in T_x' M^A$, we denote ' $S = j^{-1}(S)$. Further for $L^* \in (M^A)^D$ the corresponding element in $(M^D)^A$ will be denoted by L^* . Then (2.8) means more precisely

$$(2.8)' (*(a \cdot L^*))' = a \cdot L'.$$

Now (2.8)' is equivalent to

$$(2.8)^{\prime\prime} \qquad \qquad \mu^{A}(a, L_{1}^{*}) = ('(aL'))_{1}^{*},$$

which is equivalent to

$$(2.8)''' (f^{D})^{A}(\mu^{A}(a, L_{1}^{*})) = (f^{A})^{D}(('(aL'))^{*})$$

for $f \in C^{\infty}(M)$.

The left hand side of $(2.8)^{\prime\prime\prime}$ is equal to

$$(f^D \circ \mu)^A(a, L_1^*) = (a, L_1^*)(f^D \circ \mu),$$

while the right hand side of (2.8)" is equal to

$$('(aL'))^*(f^A) = f^A(x') + '(aL')f^A \cdot \tau$$

= $f^A(x') + (a \cdot L')f \cdot \tau = f^A(x') + a \cdot L'f \cdot \tau$.

Therefore it remains to verify

$$(2.9) (a, L_1^*)(f^D \circ \mu) = f^A(x') + a \cdot L' f \cdot \tau$$

for $f \in C^{\infty}(M)$.

Now, since L^* and L_1^* are corresponding elements in $(M^A)^D$ and $(M^D)^A$, we have

$$(2.10) (fD)A(L1*) = (fA)D(L*)$$

for $f \in C^{\infty}(M)$.

Put $K = (a, L_1^*)$. Then we have $K(g \circ \pi_1) = a(g)$, $K(g' \circ \pi_2) = L_1^*(g')$ for $g \in C^{\infty}(\mathbb{R})$, $g' \in C^{\infty}(M^D)$. Next, we have, for $(t, X) \in \mathbb{R} \times M^D$,

$$(f^{D} \circ \mu)(t, X) = f^{D}(tX) = f(\pi X) + (tX)f \cdot \tau$$

$$= (f \circ \pi) \circ \pi_{2}(t, X) + (1 \circ \pi_{1}(t, X)) \cdot \pi_{2}(t, X)f \cdot \tau$$

$$= (f \circ \pi) \circ \pi_{2}(t, X) + (1 \circ \pi_{1}) \cdot (f' \circ \pi_{2})(t, X) \cdot \tau.$$

where $f' \in C^{\infty}(M^D)$ is defined by f'(X) = Xf for $X \in M^D$. Hence we have

(2.11)
$$K(f^{D} \circ \mu) = K((f \circ \pi) \circ \pi_{2}) + K(1 \circ \pi_{1}) \cdot K(f' \circ \pi_{2}) \cdot \tau$$
$$= L_{1}^{*}(f \circ \pi) + a \cdot L_{1}^{*}f' \cdot \tau.$$

On the other hand, from (2.10) we get

$$(f^D)^A(L_1^*) = L_1^*(f^D) = L_1^*(f \circ \pi + f' \cdot \tau) = L_1^*(f \circ \pi) + L_1^* f' \cdot \tau ,$$

 $(f^A)^D(L^*) = L^*(f^A) = f^A(x') + L f^A \cdot \tau = f^A(x') + L' f \cdot \tau ,$

which imply

(2.12)
$$L_1^*(f \circ \pi) = f^A(x'), \qquad L_1^*f' = L'f.$$

Combining (2.10), (2.11) and (2.12), we get (2.9).

3. Lifting of vector fields

We denote by $\mathcal{F}_0^1(M)$ the set of all vector fields on M. Take $X \in \mathcal{F}_0^1(M)$. The corresponding $X': M \to M^D$ is defined by

$$(3.1) X'(x)f = f(x) + (X(x)f) \cdot \tau \in D$$

for $f \in C^{\infty}(M)$ and $x \in M$. The map X' induces a map $X'^A : M^A \to (M^D)^A$. Consider the map $\tilde{X} = i \circ X'^A : M^A \to (M^A)^D$, where $i : (M^D)^A \to (M^A)^D$ is the identification map. The commutativity of the right triangle of the diagram (2.1) implies that $\tilde{X}(x') \in (M^A)^D_x$ for every $x' \in M^A$. Hence by Remark 1.6 we obtain a tangent vector in $T_{x'}(M^A)$ corresponding to $\tilde{X}(x')$, which we denote by $X^A(x')$.

Thus we obtain a vector field $X^A \in \mathcal{F}_0^1(M^A)$.

Definition 3.1. The vector field X^A is called the *lift* of X to M^A .

Remark 3.2. Any $X \in \mathcal{F}_0^1(M^A)$ can be extended to a derivation of $C^{\infty}(M^A, A)$ by

$$X\tilde{f} = X(\sum f_i B^i) = \sum (Xf_i) \cdot B^i$$
,

where $\{1, B^1, \dots, B^N\}$ is a basis of A, and $\tilde{f} = \sum f_i B^i$ with $f_i \in C^{\infty}(M^A)$. **Lemma 3.3.** For any $X \in \mathcal{F}_0^1(M)$ and $f \in C^{\infty}(M)$, we have

$$(3.2) (Xf)^A = X^A f^A.$$

Proof. We have to show

$$(3.3) (Xf)^{A}(x') = (X^{A}f^{A})(x')$$

for $x' \in M^A$. Put $x'' = X'^A(x') \in (M^D)^A$. Then $x_1'' = (X^A(x'))'$ is the element corresponding to x'' in $(M^A)^D$ (for the notation ()' see Remark 1.6). Using Corollary 1.12 we have

(3.4)
$$(f^{D})^{A}(x'') = (f^{A})^{D}(x''_{1}) = x''_{1}(f^{A}) = (X^{A}(x'))'f^{A}$$

$$= f^{A}(x') + X^{A}(x')f^{A} \cdot \tau .$$

The left hand side of (3.3) is equal to

$$(3.5) ((f^D)^A \circ X'^A)(x') = (f^D \circ X')^A(x') = x'(f^D \circ X').$$

Since

$$(f^D \circ X')(x) = f^D(X'(x)) = X'(x)(f) = f(x) + (Xf)(x) \cdot \tau$$

= $(f + Xf \cdot \tau)(x)$,

(3.5) is equal to

(3.6)
$$x'(f) + x'(Xf) \cdot \tau = f^{A}(x') + (Xf)^{A}(x') \cdot \tau .$$

Comparing (3.4) and (3.6), we obtain (3.3).

Lemma 3.4. The map $X \to X^A$ is linear.

Proof. Take $f ∈ C^{\infty}(M)$ and $X, Y ∈ \mathcal{F}_0^1(M)$. Then by Lemma 3.3 we have $(X + Y)^A f^A = ((X + Y)f)^A = (Xf + Yf)^A = (Xf)^A + (Yf)^A = X^A f^A + Y^A f^A = (X^A + Y^A)f^A$, and therefore $((X + Y)^A)'f = (X + Y)^A f^A = (X^A + Y^A)'f$, which implies $((X + Y)^A)' = (X^A + Y^A)'$ (for the notation ()' see Lemme 2.8). Hence we get $(X + Y)^A = X^A + Y^A$. Similarly, $(\alpha \cdot X)^A = \alpha \cdot X^A$ for $\alpha \in R$.

Lemma 3.5. For any $f \in C^{\infty}(M)$ and $X \in \mathcal{F}_0^1(M)$, we have

$$(5.7) (f \cdot X)^A = f^A \cdot X^A ,$$

equivalently,

$$(fX)^A(x') = f^A(x')X^A(x')$$

for every $x' \in M^A$ (cf. Definition 2.1).

Proof. Let $\mu: \mathbb{R} \times M^D \to M^D$ be the scalar multiplication of tangent vectors. Identifying X with its corresponding $X': M \to M^D$ (cf. Definition 3.1), we have

$$(f \cdot X)^A = (\mu \circ (f, X))^A = \mu^A \circ (f, X)^A = \mu^A \circ (f^A, X^A) = f^A \cdot X^A$$
.

Definition 3.6. For $\tilde{X} \in \mathcal{F}_0^1(M^A)$, we define a map $\tilde{X}' : C^{\infty}(M) \to C^{\infty}(M^A, A)$ by

$$(\tilde{X}'f)(x') = (\tilde{X}(x'))'f = (j(\tilde{X}(x')))f$$

for $f \in C^{\infty}(M)$ and $x' \in M^A$ (cf. Remark 2.7).

Remark 3.7. By Lemma 2.8, we have

$$(g \cdot \tilde{X})' = g \cdot \tilde{X}'$$

for $g \in C^{\infty}(M^A, A)$, $\tilde{X} \in \mathcal{F}_0^1(M^A)$.

Lemma 3.8. For $a \in A$, $X \in \mathcal{F}_0^1(M)$ and $f \in C^{\infty}(M)$, we have

$$(3.8) (a \cdot X^A)f^A = a \cdot (Xf)^A.$$

Proof. We have

$$(a \cdot X^A)f^A = (a \cdot X^A)'f = a \cdot ((X^A)'f) = a \cdot (X^Af^A) = a \cdot (Xf)^A,$$

where we have used Lemma 2.5, Lemma 3.3 and Remark 3.7.

Lemma 3.9. Let $\{x_1, \dots, x_n\}$ be a coordinate system on some neighborhood of M. Then we have

$$(3.9) B^{\lambda} \cdot (\partial/\partial x_i)^A = \partial/\partial x_{i,\lambda}$$

for $i = 1, \dots, n$; $\lambda = 0, \dots, N$.

Proof. We have $(B^{\lambda}(\partial/\partial x_i)^A)(x_j)^A = B^{\lambda}(\partial x_j/\partial x_i)^A = B^{\lambda}(\delta_{ij})^A = B^{\lambda} \cdot \delta_{ij}$. On the other hand we have

$$(\partial/\partial x_{i,\lambda})(x_j)^A = (\partial/\partial x_{i,\lambda})\Big(\sum_{\nu} x_{j,\nu}B^{\nu}\Big) = \delta_{ij}B^{\lambda}$$
.

Hence we get (3.9).

Corollary 3.10. For any $x' \in M^A$, the A-module T_xM^A , is a free A-module. Proof. Take $X_i = (\partial/\partial x_i)_{x'}^A$ $(i = 1, \dots, n)$. Then $\{X_1, \dots, X_n\}$ is a free A-basis of $T_{x'}M^A$.

Lemma 3.11. For any $X, Y \in \mathcal{F}_0^1(M)$ we have

$$[X^A, Y^A] = [X, Y]^A$$
.

Proof. For any $f \in C^{\infty}(M)$, we have

$$[X^{A}, Y^{A}]f^{A} = X^{A}Y^{A}f^{A} - Y^{A}X^{A}f^{A} = (XYf - YXf)^{A}$$
$$= ([X, Y]f)^{A} = [X, Y]^{A}f^{A}.$$

Hence we have

$$[X^A, Y^A]'f = [X^A, Y^A]f^A = [X, Y]^Af^A = ([X, Y]^A)'f$$
,

which implies $[X^A, Y^A]' = ([X, Y]^A)'$ and hence we get $[X^A, Y^A] = [X, Y]^A$. **Lemma 3.12.** For any $a, b \in A$ and $X, Y \in \mathcal{F}_0^1(M)$ we have

$$[aX^{A}, bY^{A}] = (a \cdot b) \cdot [X, Y]^{A}.$$

Proof. We calculate as follows: for any $f \in C^{\infty}(M)$

$$[aX^{A}, bY^{A}]f^{A} = (aX^{A})(bY^{A})f^{A} - (bY^{A})(aX^{A})f^{A}$$

$$= (a \cdot X^{A})(b \cdot (Yf)^{A}) - bY^{A}(a \cdot (Xf)^{A})$$

$$= b \cdot (aX^{A}(Yf)^{A}) - a \cdot (bY^{A} \cdot (Xf)^{A})$$

$$= b \cdot a \cdot (XYf)^{A} - a \cdot b(YXf)^{A}$$

$$= (a \cdot b) \cdot ([X, Y]f)^{A} = (a \cdot b)([X, Y]^{A}f^{A})$$

$$= ((ab)[X, Y]^{A}f^{A}.$$

By the same argument as in Lemma 3.10 we get (3.10).

Remark 3.13. We can verify that if $\{\Phi^t\}$ is a one-parameter group of diffeomorphism on M generated by a vector field X, then the one-parameter group $\{(\Phi^t)^A\}$ induces the vector field X^A .

4. Lifting of covariant tensor fields

Take $f \in C^{\infty}(M)$. Since $f^A: M^A \to A$ is an A-valued function, we can consider $df^A: T(M^A) \to A$. On the other hand, since $df: M^D \to R$ is a function, we can consider $(df)^A: (M^D)^A \to R^A = A$.

Lemma 4.1. Identifying $T(M^A) = (M^A)^D$ with $(M^D)^A$, we have

$$(4.1) (df)^A = df^A.$$

Proof. Let π (resp. $\tilde{\pi}$) be the projection $\pi: \mathbf{R}^D = \mathbf{R} \oplus \mathbf{R} \cdot \tau \to \mathbf{R} \cdot \tau = \mathbf{R}$ (resp. $\tilde{\pi}: A^D = A \oplus A \cdot \tau \to A \cdot \tau = A$). Then we have, by definition, $df = \pi \circ f^D$, $df^A = \tilde{\pi} \circ (f^A)^D$. Hence $(df)^A = \pi^A \circ (f^D)^A$. Then the commutative diagram

$$(M^{A})^{D} \xrightarrow{(f^{A})^{D}} A^{D} \xrightarrow{\tilde{\pi}} A$$

$$\downarrow \simeq \qquad \qquad \downarrow \simeq \qquad \downarrow 1$$

$$(M^{D})^{A} \xrightarrow{(f^{D})^{A}} D^{A} \xrightarrow{\pi^{A}} A$$

proves (4.1). q.e.d.

Take a 1-form $\theta \in \mathcal{F}_1^0(M)$. Then θ can be considered as a function $\theta \colon M^D \to R$. Hence $\theta^A \colon (M^D)^A \to A$ is an A-valued function on $(M^D)^A = (M^A)^D$. To prove that θ^A is in fact a 1-form on M^A , we shall first prove

Lemma 4.2. Take $\theta_1, \theta_2 \in \mathcal{F}_1^0(M)$. Then we have

$$(\theta_1 + \theta_2)^A = \theta_1^A + \theta_2^A.$$

Proof. Let $\alpha: \mathbb{R} \times \mathbb{R} \to \mathbb{R}$ (resp. $\alpha_A: A \times A \to A$) be the addition in \mathbb{R} (resp. A). Then we know that $\alpha_A = \alpha^A$, and therefore that

$$(\theta_1 + \theta_2)^A = (\alpha \circ (\theta_1, \theta_2))^A = \alpha^A \circ (\theta_1^A, \theta_2^A)$$
$$= \alpha_A(\theta_1^A, \theta_2^A) = \theta_1^A + \theta_2^A.$$

Lemma 4.3. For $f \in C^{\infty}(M)$ and $\theta \in \mathcal{F}_1^0(M)$, we have

$$(4.3) (f \cdot \theta)^A = f^A \cdot \theta^A .$$

Proof. Let $\mu_0: \mathbf{R} \times \mathbf{R} \to \mathbf{R}$ (resp. $\mu_A: A \times A \to A$) be the multiplication in \mathbf{R} (resp. in A). Then we know $(\mu_0)^A = \mu_A$, and therefore $(f \cdot \theta)^A = (\mu_0 \circ (f, \theta))^A = (\mu_0)^A \circ (f^A, \theta^A) = \mu_A \circ (f^A, \theta^A) = f^A \cdot \theta^A$.

Lemma 4.4. For any $\theta \in \mathcal{F}_1^0(M)$, we have $\theta^A \in \mathcal{F}_1^0(M^A)$.

Proof. Since the problem is local, we can assume that $\theta = \sum g_i df_i$ with $g_i, f_i \in C^{\infty}(M)$. By (4.1), (4.2), (4.3) we have $\theta^A = \sum g_i^A df_i^A$, which is a 1-form on M^A .

Lemma 4.5. For $\theta \in \mathcal{F}_1^0(M)$ and $X \in \mathcal{F}_0^1(M)$, we have

$$(\theta(X))^A = \theta^A(X^A) .$$

Proof. The function $\theta(X): M \to R$ can be written as $\theta(X) = \theta \circ X$, where $X: M \to M^D$ and $\theta: M^D \to R$. Hence we have $(\theta(X))^A = (\theta \circ X)^A = \theta^A \circ X^A = \theta^A(X^A)$.

Lemma 4.6. For $\theta \in \mathcal{F}_1^0(M)$, $a \in A$ and $\tilde{X} \in T_{x'}(M^A)$, we have

(4.5)
$$\theta^{A}(a \cdot \tilde{X}) = a \cdot \theta^{A}(\tilde{X}) .$$

Proof. Since $\theta(t \cdot X) = t\theta(X)$ for $t \in \mathbb{R}$ and $X \in T(M)$ we have $(\theta \circ \mu)(t, X) = \theta(tX) = \mu_0(t, \theta(X)) = \mu_0(1 \times \theta)(t, X)$. Hence $(\theta \circ \mu)^A = (\mu_0)^A \circ (1 \times \theta^A) = \mu_A \circ (1 \times \theta^A)$, which implies (4.5).

Since θ^A is an A-valued 1-form on M^A , we can consider it as $\theta^A \in \mathcal{F}_1^0(M^A)$ $\otimes A$. We can easily verify

Lemma 4.7. $\mathcal{F}^0_*(M^A) \otimes A$ becomes an associative graded algebra over A with the multiplication:

$$(K_1 \otimes a_1) \otimes (K_2 \otimes a_2) = K_1 \otimes K_2 \otimes (a_1 a_2)$$

for $K_1, K_2 \in \mathcal{F}^0_*(M^A) = \sum_q \mathcal{F}^0_q(M^A)$ and $a_1, a_2 \in A$.

Lemma 4.8. The map $L: \mathcal{F}^0_*(M) \to \mathcal{F}^0_*(M^A) \otimes A$ defined by $L(\theta_1 \otimes \cdots \otimes \theta_q) = \theta_1^A \otimes \cdots \otimes \theta_q^A$ for $\theta_i \in \mathcal{F}^0_1(M)$ is an algebra homomorphism.

Proof. Let $L: (\mathcal{F}_q^0(M))^q \to \mathcal{F}_q^0(M^A) \otimes A$ be defined by $L(\theta_1, \dots, \theta_q) = \theta_1^A \otimes \dots \otimes \theta_q^A$. It is easily checked that $L(f_1\theta_1, \dots, f_q\theta_q) = (f_1 \dots f_q)^A L(\theta_1, \dots, \theta_q)$ for $f_i \in \mathcal{F}_0^0(M)$, $\theta_i \in \mathcal{F}_1^0(M)$. Hence there exists a map $L: \mathcal{F}_q^0(M) \to \mathcal{F}_q^0(M^A) \otimes A$ such that $L(\theta_1 \otimes \dots \otimes \theta_q) = L(\theta_1, \dots, \theta_q)$. Now it is easy to see that L is an algebra homomorphism.

5. Lifting of (1, 1)-tensor fields

Let $K \in \mathcal{T}_1^1(M)$ be a (1, 1)-tensor field on M. Then K can be considered as a map $K: M^D \to M^D$ such that $\pi \circ K = \pi$. Then $K^A: (M^D)^A \to (M^D)^A$ can be considered as $K^A: (M^A)^D \to (M^A)^D$.

Lemma 5.1. K^A is a (1, 1)-tensor field on M^A .

Proof. Since the problem is local, we assume $K = \sum \theta_i \otimes Y^i$ with $\theta_i \in \mathcal{F}_1^0(M)$ and $Y^i \in \mathcal{F}_0^1(M)$. Then

$$K(X) = \sum \theta_i(X)Y^i = \sum \mu(\theta_i(X), (Y^i \circ \pi)(X))$$

= $(\alpha_r \circ (\mu \circ (\theta_1, Y^1 \circ \pi), \dots, \mu \circ (\theta_r, Y^r \circ \pi)))(X)$,

where $\alpha_r : \mathbf{R}^r \to \mathbf{R}$ is the addition $\alpha_r(a_1, \dots, a_r) = a_1 + \dots + a_r$ for $a_i \in \mathbf{R}$. Hence we have

$$K^A = (\alpha_r)^A \circ (\mu^A \circ (\theta_1^A, (Y^1)^A \circ \pi^A), \cdots, \mu^A \circ (\theta_r^A, (Y^r)^A \circ \pi^A)),$$

which implies

$$K^{A}(\tilde{X}) = \sum \theta_{i}^{A}(\tilde{X}) \cdot (Y^{i})^{A}$$

for $\tilde{X} \in (M^A)^D$. Thus $K^A \in \mathcal{T}_1^1(M^A)$.

Lemma 5.2. For $K \in \mathcal{F}_1^1(M)$, $X \in \mathcal{F}_0^1(M)$ and $a \in A$, we have

$$K^{A}(a\cdot X^{A})=a\cdot (K(X))^{A}.$$

Proof. As before, we can assume $K = \sum_{i} \theta_{i} \otimes Y_{i}$. Then

$$K^{A}(a \cdot X^{A}) = \sum \theta_{i}^{A}(aX^{A}) \cdot (Y^{i})^{A} = \sum a \cdot \theta_{i}^{A}(X^{A})(Y^{i})^{A}$$
$$= a \cdot \sum (\theta_{i}(X))^{A}(Y^{i})^{A} = a \cdot (\sum \theta_{i}(X)Y^{i})^{A} = a \cdot (K(X))^{A}.$$

Theorem 5.3. Let $J \in \mathcal{T}_1^1(M)$ be an almost complex structure on M. Then J^A is an almost complex structure on M^A . Moreover, J^A is integrable if and only if J is.

Proof. Let I be the (1, 1)-tensor field of identity maps of T_xM for $x \in M$. Since $I = \sum dx_i \otimes \partial/\partial x_i$ locally, we get, for $\tilde{X} \in (M^A)^D$,

$$I^{A}(\tilde{X}) = \sum (dx_{i})^{A}(\tilde{X}) \otimes \left(\frac{\partial}{\partial x_{i}}\right)^{A} = \sum dx_{i}^{A}(\tilde{X}) \cdot \frac{\partial}{\partial x_{i,0}}$$
$$= \sum dx_{i,\lambda}(\tilde{X})B^{\lambda}\frac{\partial}{\partial x_{i,0}} = \sum dx_{i,\lambda(\tilde{X})} \cdot \frac{\partial}{\partial x_{i,\lambda}} = \tilde{X},$$

where we have used (3.9) and (4.5). Thus we have $J^A \circ J^A = (J \circ J)^A = (-I)^A = -I^A = -\tilde{I}$, where \tilde{I} is the (1, 1)-tensor field of identity maps of M^A . Hence J^A is an almost complex structure on M^A .

Next, J is integrable if and only if

$$(5.1) J[X,Y] = [JX,Y] + [X,JY] + J[JX,JY]$$

for every $X, Y \in \mathcal{F}_0^1(M)$. Using Lemmas 3.12 and 5.2 we have

$$J^{A}[ax^{A}, bY^{A}] = J^{A}(ab[X, Y]^{A}) = (ab)(J[X, Y])^{A}$$

$$= (ab)\{[J^{A}X^{A}, Y^{A}] + [X^{A}, J^{A}Y^{A}] + J^{A}[J^{A}X^{A}, J^{A}Y^{A}]\}$$

$$= [J^{A}(aX^{A}), bY^{A}] + [aX^{A}, J^{A}(bY^{A})] + J^{A}[J^{A}(aX^{A}), J^{A}(bY^{A})]$$

for $a, b \in A$. Since T_xM^A is a free A-module (Corollary 3.10), we conclude that J^A is integrable. Conversely, if J^A is integrable, we get

$$(J[X,Y])^A = ([JX,Y] + [X,JY] + J[JX,JY])^A$$

for $X, Y \in \mathcal{F}_0^1(M)$, which implies (5.1), and hence J is integrable.

6. Prolongations of affine connections

Let ∇ be the covariant differentiation defined by an affine connection of M. In the sequel, for the sake of convenience of notation, we shall denote by $\nabla(X, K)$ the covariant differentiation of a tensor field K on M with respect to $X \in \mathcal{F}_0^1(M)$, i.e.,

$$V(X,K) = V_X K$$
.

Theorem 6.1. There exists one and only one affine connection on M^A whose covariant differentiation \tilde{V} satisfies the following condition

$$\tilde{\mathcal{V}}_{aXA}bY^A = (ab)(\mathcal{V}_XY)^A$$

for every $X, Y \in \mathcal{F}_0^1(M)$ and $a, b \in A$.

Proof. Take a coordinate neighborhood U with coordinate system $\{x_1, \dots, x_n\}$ and let Γ_{ij}^k be the connection components of V with respect to $\{x_1, \dots, x_n\}$, i.e.,

(6.2)
$$V\left(\frac{\partial}{\partial x_i}, \frac{\partial}{\partial x_j}\right) = \sum \Gamma_i{}^k{}_j \frac{\partial}{\partial x_k}$$

for $i, j = 1, \dots, n$. Let $\Gamma'_{ij}{}^k$ be the connection components of Γ with respect to another coordinate system $\{y_1, \dots, y_n\}$ on U. Then we have the following equalities:

(6.3)
$$\Gamma_{i \ j}^{\prime k} = \sum \frac{\partial x_b}{\partial y_i} \frac{\partial x_c}{\partial y_j} \frac{\partial y_k}{\partial x_a} \Gamma_b{}^a{}_c + \sum \frac{\partial^2 x_a}{\partial y_i \partial y_j} \frac{\partial y_k}{\partial x_a}$$

for $i, j = 1, 2, \dots, n$ (cf. for instance [3, p. 27]). Let $\{x_{i,\lambda} | i = 1, \dots, n; \lambda = 0, 1, \dots, N\}$ (resp. $\{y_{i,\lambda}\}$) be the induced coordinate system on $\pi_A^{-1}(U)$. Define $\tilde{\Gamma}_{(i,\lambda)}^{(k,\nu)}(j,\mu)$ by

(6.4)
$$\sum \tilde{\Gamma}_{(i,\lambda)}^{(k,\nu)}{}_{(j,\mu)}B^{\nu} = B^{\lambda}B^{\mu}(\Gamma_{ij}{}^{k})^{A}$$

for $i, j, k = 1, \dots, n$; $\lambda, \mu, \nu = 0, 1, \dots, N$, where $\{B^0 = 1, B^1, \dots, B^N\}$ is a basis of A as in § 1.

We shall now prove that there exists a connection \tilde{V} whose connection components with respect to $\{x_{i,\lambda}\}$ are given by (6.4). To prove this we have to prove the following equalities (6.5) similar to (6.3):

(6.5)
$$\tilde{\Gamma}'_{(i,\nu)}{}^{(k,\lambda)}_{(j,\mu)} = \sum_{\alpha} \frac{\partial x_{b,\beta}}{\partial y_{i,\nu}} \frac{\partial x_{c,\gamma}}{\partial y_{j,\mu}} \frac{\partial y_{k,\lambda}}{\partial x_{a,\alpha}} \tilde{\Gamma}_{(b,\beta)}{}^{(a,\alpha)}_{(c,\gamma)} + \sum_{\alpha} \frac{\partial^2 x_{a,\alpha}}{\partial y_{i,\nu}\partial y_{j,\mu}} \frac{\partial y_{k,\lambda}}{\partial x_{a,\alpha}}$$

for $i, j, k = 1, \dots, n$; $\lambda, \mu, \nu = 0, 1, \dots, N$, where $\tilde{\Gamma}'_{(i,\nu)}^{(k,\lambda)}(j,\mu)$ denote the connection components of \tilde{V} with respect to the coordinate system $\{y_{i,\lambda}\}$. Denoting the right hand side of (6.5) by $\tilde{\Gamma}^*_{(i,\nu)}^{(k,\lambda)}(j,\mu)$ and using Lemmas 3.8 and 3.9, we calculate as follows:

$$\begin{split} & \sum \tilde{\Gamma}_{(t,\nu)}^{*}{}^{(k,\lambda)}{}_{(j,\mu)}B^{\lambda} \\ & = \frac{\partial x_{b,\beta}}{\partial y_{i,\nu}} \frac{\partial x_{c,\tau}}{\partial y_{j,\mu}} \left(\frac{\partial y_k}{\partial x_a} \right)^A B^{\alpha} \tilde{\Gamma}_{(b,\beta)}{}^{(a,\alpha)}{}_{(c,\tau)} + \frac{\partial^2 x_{a,\alpha}}{\partial y_{i,\nu}\partial y_{j,\mu}} \left(\frac{\partial y_k}{\partial x_a} \right)^A B^{\alpha} \\ & = \frac{\partial x_{b,\beta}}{\partial y_{i,\nu}} \frac{\partial x_{c,\tau}}{\partial y_{j,\mu}} \left(\frac{\partial y_k}{\partial x_a} \right)^A B^{\beta} B^{\tau} (\Gamma_b{}^a{}_c)^A + \frac{\partial}{\partial y_{i,\nu}} \left(\frac{\partial x_{a,\alpha}}{\partial y_{j,\mu}} B^{\alpha} \right) \left(\frac{\partial y_k}{\partial x_a} \right)^A \\ & = \left(\frac{\partial x_b}{\partial y_i} \right)^A B^{\nu} \left(\frac{\partial x_c}{\partial y_j} \right)^A B^{\mu} \left(\frac{\partial y_k}{\partial x_a} \right)^A (\Gamma_b{}^a{}_c)^A + \frac{\partial}{\partial y_{i,\nu}} \left(\frac{\partial x_a}{\partial y_j} \right)^A B^{\mu} \left(\frac{\partial y_k}{\partial x_a} \right)^A \\ & = \left(\frac{\partial x_b}{\partial y_i} \right)^A B^{\nu} \left(\frac{\partial x_c}{\partial y_j} \right)^A B^{\mu} \left(\frac{\partial y_k}{\partial x_a} \right)^A (\Gamma_b{}^a{}_c)^A + \left(\frac{\partial^2 x_a}{\partial y_i \partial y_j} \right)^A B^{\nu} B^{\mu} \left(\frac{\partial y_k}{\partial x_a} \right)^A \\ & = B^{\nu} B^{\mu} (\Gamma_i^{\prime k}{}_j)^A = \tilde{\Gamma}_{(i,\nu)}^{\prime \prime}{}^{(k,k)}{}^{(j,\mu)} B^{\lambda} , \end{split}$$

which implies (6.5).

Thus we have proved the existence of $\tilde{\mathcal{V}}$ whose connection components with respect to $\{x_{i,\lambda}\}$ are given by (6.4).

Next, we shall prove (6.1) for $X = \partial/\partial x_i$, $Y = \partial/\partial x_j$, and $a = B^2$, $b = B^\mu$. We calculate as follows:

$$\begin{split} \tilde{V}\Big(B^{\lambda}\Big(\frac{\partial}{\partial x_{i}}\Big)^{A}, B^{\mu}\Big(\frac{\partial}{\partial x_{j}}\Big)^{A}\Big) &= \tilde{V}\Big(\frac{\partial}{\partial x_{i,\lambda}}, \frac{\partial}{\partial x_{j,\mu}}\Big) = \tilde{\Gamma}_{(i,\lambda)}{}^{(k,\nu)}{}_{(j,\mu)} \frac{\partial}{\partial x_{k,\nu}} \\ &= \tilde{\Gamma}_{(i,\lambda)}{}^{(k,\nu)}{}_{(j,\mu)} B^{\nu}\Big(\frac{\partial}{\partial x_{k}}\Big)^{A} = B^{\lambda}B^{\mu}(\Gamma_{i}{}^{k}{}_{j})^{A}\Big(\frac{\partial}{\partial x_{k}}\Big)^{A} \\ &= B^{\lambda}B^{\mu}\Big(\Gamma_{i}{}^{k}{}_{j} \frac{\partial}{\partial x_{\nu}}\Big)^{A} = B^{\lambda}B^{\mu}\Big(V\Big(\frac{\partial}{\partial x_{i}}, \frac{\partial}{\partial x_{i}}\Big)\Big)^{A}, \end{split}$$

which proves (6.1) for $X = \partial/\partial x_i$, $Y = \partial/\partial x_j$ and $a = B^{\lambda}$, $b = B^{\mu}$ and hence for arbitrary $a, b \in A$.

Now put $X_i = \partial/\partial x_i$ for $i = 1, \dots, n$. We shall prove (6.1) for $X = fX_i$, $Y = X_j$ with $f \in \mathcal{F}_0^0(U)$. We calculate as follows:

$$\tilde{V}(aX^A, bY^A) = \tilde{V}(a(f \cdot X_i)^A, b \cdot X_j^A)\tilde{V}(af^A \cdot X_i^A, b \cdot X_j^A)
= af^A\tilde{V}(X_i^A, bX_j^A) = abf^A(\tilde{V}(X_i, X_j))^A
= ab(fV(X_i, X_i))^A = ab(V(fX_i, X_j))^A = ab(V(X, Y))^A,$$

which proves our assertion. Therefore we see that (6.1) holds for $X \in \mathcal{F}_0^1(M)$ and $Y = X_j$ with $j = 1, \dots, n$. Next we prove that (6.1) holds for $X \in \mathcal{F}_0^1(M)$ and $Y = f \cdot X_j$ with $f \in \mathcal{F}_0^0(U)$ and $j = 1, \dots, n$. We calculate as follows:

$$\begin{split} \tilde{V}(a\cdot X^A,b\cdot Y^A) &= \tilde{V}(a\cdot X^A,b(f\cdot X_j)^A) = \tilde{V}(aX^A,bf^A\cdot X_j^A) \\ &= f^A \tilde{V}_{aX^A} bX_j^A + aX^A (bf^A)X_j^A = f^A ab(\tilde{V}_X Y_j)^A + ab(Xf)^A X_j^A \\ &= ab(f\tilde{V}_X Y_j + Xf\cdot X_j)^A = ab(\tilde{V}_X fY_j)^A = ab(\tilde{V}(X,Y))^A \;, \end{split}$$

where we have used Lemmas 3.5 and 3.8.

Thus we have proved (6.1) for any $X, Y \in \mathcal{F}_0^1(M)$ and $a, b \in A$. The uniqueness of such $\tilde{\mathcal{V}}$ follows from Lemma 3.9.

Definition 6.2. The unique affine connection $\tilde{\mathcal{V}}$ in Theorem 6.1 will be called the *prolongation* of \mathcal{V} to M^{Δ} and will be denoted by $\tilde{\mathcal{V}} = \mathcal{V}^{\Delta}$.

Theorem 6.3. Let T and R (resp. \tilde{T} and \tilde{R}) be the torsion and curvature tensor fields of V (resp. $\tilde{V} = V^A$). Then according as T = 0, VT = 0, R = 0 or VR = 0, we have $\tilde{T} = 0$, $\tilde{V}\tilde{T} = 0$, $\tilde{R} = 0$ or $\tilde{V}\tilde{R} = 0$ and vice versa. In particular, if M is locally affine symmetric with respect to V, so is M^A with respect to $\tilde{V} = V^A$.

Proof. First we prove

$$\tilde{T}(aX^A, bY^A) = ab(T(X, Y))^A$$

for $X, Y \in \mathcal{F}_0^1(M)$ and $a, b \in A$.

In fact, by the definition of \tilde{T} , Lemma 3.12 and (6.1) we get

$$\tilde{T}(aX^{A}, bY^{A}) = \tilde{V}_{aX^{A}} bY^{A} - \tilde{V}_{bY^{A}} aX^{A} - [aX^{A}, bY^{A}]
= (ab)(V_{X}Y - V_{Y}X - [X, Y])^{A} = ab(T(X, Y))^{A}.$$

Thus we see that T=0 if and only if $\tilde{T}=0$ (cf. Corollary 3.10).

Similarly we know that $\tilde{R}(aX^A, bY^A, cZ^A) = (abc)(R(X, Y, Z))^A$ for $X, Y, Z \in \mathcal{F}_0^1(M)$ and $a, b, c \in A$, from which we see that R = 0 if and only if $\tilde{R} = 0$. The proof for the case VT and VR is similar.

7. Affine symmetric spaces

Lemma 7.1. Let Φ be a diffeomorphism of M onto M', and let $X \in \mathcal{F}_0^1(M)$ and $a \in A$. Then we have

$$(7.1) (T\Phi^{A})(aX^{A}) = a((T\Phi)X)^{A}.$$

Proof. Take $f \in C^{\infty}(M)$. We have

$$(\Phi^{A})^{D}(aX^{A})f^{A} = (aX^{A})(f^{A} \circ \Phi^{A}) = (aX^{A})(f \circ \Phi)^{A} = a \cdot X^{A}(f \circ \Phi)^{A}$$
$$= a \cdot (X(f \circ \Phi))^{A} = a \cdot ((\Phi^{D}X)f)^{A} = a \cdot ((\Phi^{D}X)^{A}f^{A})$$
$$= (a(\Phi^{D}X)^{A})f^{A},$$

from which follows (7.1).

Lemma 7.2. Let V (resp. V') be an affine connection on M (resp. on M')

and let Φ be a diffeomorphism of M onto M' transforming ∇ onto ∇' . Then Φ^A transforms ∇^A onto ∇'^A .

Proof. Take $X, Y \in \mathcal{F}_0^1(M)$. Then we have, for $a, b \in A$,

$$T\Phi^{A}(\mathcal{V}_{aX^{A}}^{A}bY^{A}) = T\Phi^{A}(ab\mathcal{V}_{X}Y)^{A} = ab(T\Phi(\mathcal{V}_{X}Y))^{A} = ab(\mathcal{V}_{T\phi_{X}}^{\prime}T\Phi Y)^{A}$$
$$= \mathcal{V}_{a(T\phi_{X})^{A}}^{\prime A}b(T\Phi Y)^{A} = \mathcal{V}_{T\phi^{A}(aX^{A})}^{\prime}T\Phi^{A}(bY^{A}) ,$$

where we have used Lemma 7.1. Since X, Y, a, b are arbitrary, Lemma 7.2 follows.

Lemma 7.3. Let $X \in \mathcal{F}_0^1(M)$, and $x_0 \in M$. Assume $X_{x_0} = 0$. Then $(X^A)_{\tilde{x}_0} = 0$, where $\tilde{x}_0 \in M^A$ is defined by $\tilde{x}_0(f) = f(x_0)$ for $f \in C^{\infty}(M)$.

Proof. Let Φ^t be a local one-parameter group of local diffeomorphisms around x_0 generated by X. Then X^A generates the local group $(\Phi^t)^A$ around \tilde{x}_0 (cf. Remark 3.13). Since $\Phi^t(x_0) = x_0$, we get $(\Phi^t)^A(\tilde{x}_0) = \tilde{x}_0$ and therefore $(X^A)_{\tilde{x}_0} = 0$.

Lemma 7.4. Let $\Phi: M \to M$ be a diffeomorphism such that there exist $x_0 \in M$ and $\alpha \in R$ with $\Phi(x_0) = x_0$ and $T_{x_0}\Phi = \alpha \cdot 1_{T_{x_0}M}$. Then $T_{\bar{x}_0}\Phi^A = \alpha \cdot 1_{T_{\bar{x}_0}M}$.

Proof. Let $\{x_1, \dots, x_n\}$ be a local coordinate system around x_0 . By Lemma 7.1 we have $T\Phi^A(\partial/\partial x_i)^A = (T\Phi(\partial/\partial x_i))^A$ for $i = 1, \dots, n$. Hence we get

$$T\Phi^A((\partial/\partial x_i)_{\bar{x}_0}^A) = (T\Phi^A(\partial/\partial x_i)_{\bar{x}_0}^A)_{\bar{x}_0} = (T\Phi(\partial/\partial x_i)_{\bar{x}_0}^A)_{\bar{x}_0}^A$$

Put $X = T\Phi(\partial/\partial x_i) - \alpha(\partial/\partial x_i)$. Then X is a vector field around x_0 on M with $X_{x_0} = 0$. Therefore by Lemma 7.3 we get $(X^A)_{\bar{x}_0} = 0$, which implies

$$(T\Phi(\partial/\partial x_i))_{\bar{x}_0}^A = (\alpha(\partial/\partial x_i))_{\bar{x}_0}^A = \alpha \cdot (\partial/\partial x_i)_{\bar{x}_0}^A.$$

Take an arbitrary $a \in A$. Then we have

$$T\Phi^{A}(a(\partial/\partial x_{i}))_{\bar{x}_{0}}^{A} = a \cdot (T\Phi(\partial/\partial x_{i}))_{\bar{x}_{0}}^{A} = a \cdot \alpha(\partial/\partial x_{i})_{\bar{x}_{0}}^{A} = \alpha \cdot (a(\partial/\partial x_{i})_{\bar{x}_{0}}^{A}).$$

Since $\{a(\partial/\partial x_i)^A \mid a \in A\}$ span the tangent space $T_{\bar{x}_0}M^A$ (cf. Lemma 3.9), we get $T_{\bar{x}_0}\Phi^A = \alpha \cdot 1_{T_{\bar{x}_0}M^A}$.

Corollary 7.5. Let Φ be the affine symmetry at a point $x_0 \in M$ with respect to an affine connection ∇ on M. Then Φ^A is the affine symmetry of M^A at \tilde{x}_0 with respect to ∇^A .

Proof. Since Φ leaves ∇ invariant, Φ^A leaves ∇^A invariant by Lemma 7.2. Next, since Φ is the affine symmetry we see that $T_{x_0}\Phi = -1_{T_{x_0}M}$. Thus by Lemma 7.4 we get $T_{\tilde{x}_0}\Phi^A = -1_{T_{\tilde{x}_0}M^A}$, which means that Φ^A is the affine symmetry at \tilde{x}_0 .

Proposition 7.6. Let V be an affine connection on M and let $X \in T_0^1(M)$ be an infinitesimal affine transformation of V. Then, for any $a \in A$, aX^A is also an infinitesimal affine transformation of V^A .

Proof. A necessary and sufficient condition for X to be an infinitesimal affine transformation of M is that

$$L_X \circ V_Y - V_Y \circ L_X = V_{\lceil X,Y \rceil}$$

for every $Y \in \mathcal{F}_0^1(M)$, where L_X (or L(X)) denotes the Lie derivation with respect to X. Therefore we have to prove

$$(7.2) L(a \cdot X^{A})(\overline{V}^{A}(\tilde{Y}, K)) - \overline{V}^{A}(\tilde{Y}, L(aX^{A})K) = \overline{V}^{A}([aX^{A}, \tilde{Y}], K)$$

for every $K \in \mathcal{F}(M^A)$ and $\tilde{Y} \in \mathcal{F}_0^1(M^A)$. To prove (7.2) it suffices to prove (7.2) for the special cases, where $\tilde{Y} = bY^A$ with $Y \in \mathcal{F}_0^1(M)$, $b \in A$, and $K = c \cdot Z^A$ or θ^A with $Z \in \mathcal{F}_0^1(M)$, $\theta \in \mathcal{F}_0^1(M)$ and $c \in A$. Moreover, to prove (7.2) for $K = \theta^A$, it suffices to prove it for $\theta = df$ with $f \in \mathcal{F}_0^0(M)$.

If $K = cZ^A$, we calculate as follows:

$$\begin{split} L_{aX^A} \tilde{\mathcal{V}}_{bY^A} \, cZ^A &- \tilde{\mathcal{V}}_{bY^A} \, L_{aX^A} \, cZ^A = \left[aX^A, bc(\mathcal{V}_YZ)^A \right] - \tilde{\mathcal{V}}_{bY^A} [aX^A, cZ^A] \\ &= abc[X, \mathcal{V}_YZ]^A - bac(\mathcal{V}_Y[X, Z])^A \\ &= abc((L_X\mathcal{V}_Y - \mathcal{V}_YL_X)Z)^A = abc(\mathcal{V}_{[X,Y]}Z)^A \\ &= \tilde{\mathcal{V}}_{[aX^A,bY^A]} \, cZ^A \; . \end{split}$$

If $K = df^A$, we have

$$\begin{split} L_{aX^A} \tilde{\mathcal{V}}_{bY^A}(df^A) &- \tilde{\mathcal{V}}_{bY^A} L_{aX^A}(df^A)(cZ^A) \\ &= (aX^A)(\tilde{\mathcal{V}}_{bY^A} \, df^A)(cZ^A) - (\tilde{\mathcal{V}}_{bY^A} \, df^A)(aX^A, cZ^A) - (\tilde{\mathcal{V}}_{bY^A} \, d(aX^Af^A))(cZ^A) \\ &= (aX^A)\{(bY^A)(cZ^A)(f^A) - (\tilde{\mathcal{V}}_{bY^A} \, cZ^A)f^A\} \\ &- \{bY^A[aX^A, cZ^A]f^A - (\tilde{\mathcal{V}}_{bY^A}[aX^A, cZ^A])f^A\} \\ &- \{bY^A(cZ^A)(aX^A)f^A - (\tilde{\mathcal{V}}_{bY^A} \, cZ^A)(aX^A)f^A\} \\ &= abc(\{L_X \circ \mathcal{V}_Y - \mathcal{V}_Y \circ L_X\}(df)(Z))^A = abc((\mathcal{V}_{[X,Y]}(df))Z)^A \\ &= abc([X,Y]Zf - (\mathcal{V}_{[X,Y]}Z)f)^A \\ &= [aX^A, bY^A](cZ^A)f^A - (\tilde{\mathcal{V}}_{[aX^A,bY^A]} \, cZ^A)f^A \\ &= (\tilde{\mathcal{V}}_{[aX^A,bY^A]}(df)^A)(cZ^A) \; . \end{split}$$

Theorem 7.7. Let M be an affine symmetric space with connection ∇ . Then M^A is also an affine symmetric space with connection ∇^A .

Proof. Let G be the connected component of the group of all affine transformations of M. Then G operates transitively on M. Let X_1, \dots, X_m be a basis of the Lie algebra g of G. We denote by $X^* \in \mathcal{F}_0^1(M)$ the vector field induced by the one-parameter group of affine transformations generated by $X \in g$. Now we can show that aX^A is a left invariant vector field on the Lie group G^A and that $(a \cdot X^A)^* = a \cdot (X^*)^A$ holds for $a \in A$ (the detail will be omitted), which implies that $a \cdot (X^*)^A$ is complete, i.e., generates a global one-parameter group of affine transformations of M^A (cf. Proposition 7.6). Hence

we see that any element of G^A is an affine transformation of M^A . The transitivity of G shows that dim $(\{X_x^* | X \in g\}) = \dim M$ for any $x \in M$, which implies

$$\dim (\{(a \cdot (X^*)^A)_{x'} | a \in A, X \in g\}) = \dim M^A$$

for any $x' \in M^A$ and hence the transitivity of G^A on M^A follows. On the other hand, by Corollary 7.5 we have an affine symmetry at \tilde{x}_0 of M^A for $x_0 \in M$. Hence M^A is affinely symmetric.

Proposition 7.8. Let ∇ be an affine connection on M. If M^{Δ} is affinely symmetric with respect to ∇^{Δ} , then M is also so with respect to ∇ .

Proof. Consider the map $\zeta: M \to M^A$ defined by $(\zeta(x))f = f(x)$ for $x \in M$, $f \in C^{\infty}(M)$. Let $\gamma: I \to M$ be a curve on M, where I is an open interval in R. Put $\tilde{\gamma} = \zeta \circ \gamma$. From (6.4), we see that

$$\tilde{\Gamma}_{(j,0)}^{(i,\lambda)}(\xi(x)) = \delta_0^{\lambda} \Gamma_j^{i}{}_{k}(x)$$

for $i, j, k = 1, \dots, n$; $\lambda = 0, 1, \dots, N$, from which we can verify that γ is a geodesic on M if and only if $\tilde{\gamma}$ is so on M^A . Further, we can conclude that the submanifold $\tilde{M} = \zeta(M)$ is a totally geodesic submanifold of M^A with respect to Γ^A and that the induced affine connection Γ' on M is isomorphic with Γ by the diffeomorphism $\zeta: M \to \tilde{M}$.

Now, take an arbitrary point $x \in M$ and consider $\tilde{x} = \zeta(x) \in M^A$. Since M^A is affinely symmetric, there exists an affine symmetry Φ of M^A at \tilde{x} . Since $T_{\tilde{x}}\Phi = -1_{T_{\tilde{x}}M^A}$, and \tilde{M} is totally geodesic, we see that $\Phi(\tilde{M}) = \tilde{M}$ and that $\Phi|_{\tilde{M}} : \tilde{M} \to \tilde{M}$ is an affine transformation of Γ' . Then $\Phi|_{\tilde{M}}$ induces the affine symmetry $\Psi: M \to M$ of M at x.

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