

# involve

a journal of mathematics

Closed geodesics on doubled polygons

Ian M. Adelstein and Adam Y. W. Fong



# Closed geodesics on doubled polygons

Ian M. Adelstein and Adam Y. W. Fong

(Communicated by Frank Morgan)

We study  $1/k$ -geodesics, those closed geodesics that minimize on any subinterval of length  $L/k$ , where  $L$  is the length of the geodesic. We investigate the existence and behavior of these curves on doubled polygons and show that every doubled regular  $n$ -gon admits a  $1/(2n)$ -geodesic. For the doubled regular  $p$ -gons, with  $p$  an odd prime, we conjecture that  $k = 2p$  is the minimum value for  $k$  such that the space admits a  $1/k$ -geodesic.

## 1. Introduction

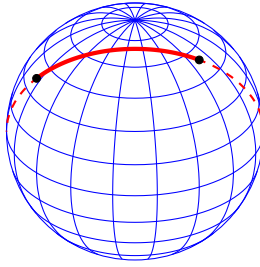
Traders and explorers have long sought shorter paths across our globe. Columbus in the fifteenth century thought it was possible to reach the East by sailing west. Alas, a continent stood in the way, and in the nineteenth century many explorers searched for the elusive Northwest Passage, a sea route connecting the Atlantic and Pacific via the Arctic Ocean. With the advent of air travel more direct routes became possible; planes often follow the shortest path between two points on the globe. In flat Euclidean space (like the  $xy$ -plane) the shortest path between any two points is a straight line. On a sphere the shortest paths are great circles, those curves of intersection between the surface of the sphere and a plane containing its center. This is why when you fly between cities in the northern hemisphere your route travels north towards the pole (see [Figure 1](#)).

A geodesic is a locally length-minimizing curve; it is the shortest path between any pair of sufficiently close points on the curve. In flat Euclidean space the geodesics are straight lines. We note that these geodesics are not only locally length-minimizing, but also globally length-minimizing; the straight line is the shortest path between any pair of points on the line, regardless of how close they are. In this paper we study geodesics that fail to minimize globally. As a first example of such a curve consider the geodesic in [Figure 2](#). Another important class of geodesics that fail to minimize globally are the closed geodesics, those geodesics that close up on themselves after finite time.

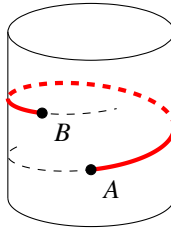
---

*MSC2010:* 53C20, 53C22.

*Keywords:* closed geodesics, regular polygons, billiard paths.



**Figure 1.** Great circle on a sphere showing the shortest path.



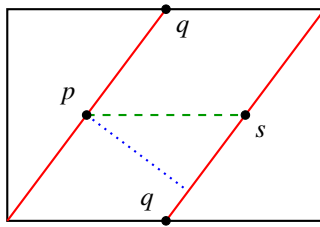
**Figure 2.** Geodesic on the cylinder that is not the shortest path between points  $A$  and  $B$ .

**Definition 1.1.** We use the symbol  $S^1$  to denote the circle. A closed geodesic is a map  $\gamma : S^1 \rightarrow M$  that is locally length-minimizing at every  $t \in S^1$ .

The great circles on the sphere are examples of closed geodesics. Fixing any point on the curve, the great circle is the shortest path to every other point on the circle up to its antipodal point, halfway along the length of the curve. If we traverse past the antipodal point, then a shorter path can be found by traversing the circle in the opposite direction, demonstrating that the great circles are not globally length-minimizing. Indeed, every closed geodesic fails to be globally length-minimizing, as traversing in the opposite direction always guarantees a shorter path to points beyond the halfway point.

It is not the case that a closed geodesic will always be the shortest path between pairs of points halfway along the curve. In [Figure 3](#) we see an example of a closed geodesic on a flat torus (the red curve) which does not minimize between pairs of points that are half the length apart. Indeed, the green (dashed) curve provides a shorter path between  $p$  and  $s$ . Logically, this poses the question of the largest interval on which a given closed geodesic minimizes. To examine this, Sormani [\[2007, Definition 3.1\]](#) introduced the notion of a  $1/k$ -geodesic.

**Definition 1.2.** A  $1/k$ -geodesic is a constant-speed closed geodesic  $\gamma : S^1 \rightarrow M$  which minimizes on all subintervals of length  $L/k$ , where  $L$  is the length of the geodesic and  $k \in \mathbb{N}$ .



**Figure 3.** Closed geodesic on a flat torus.

Note that the great circles on the sphere are  $\frac{1}{2}$ -geodesics, or half-geodesics. The curve in Figure 3 is a  $\frac{1}{4}$ -geodesic, as it minimizes between all points at length  $L/4$  (for example, between the points  $p$  and  $q$ ). The curve does not minimize beyond points at length  $L/4$ , as is evidenced by the blue (dotted) curve between  $p$  and a point on the geodesic beyond  $q$ . See also [Adelstein 2016a; 2016b; Ho 2008; Sormani 2007] for more on  $1/k$ -geodesics. An important first fact about  $1/k$ -geodesics is that they are as ubiquitous as closed geodesics.

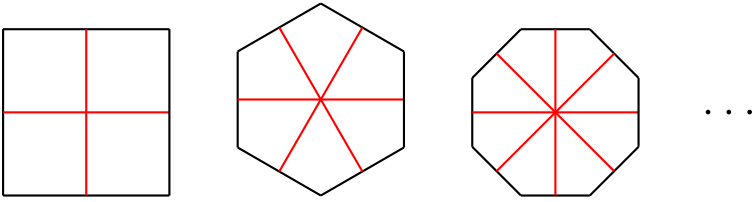
**Proposition 1.3** [Sormani 2007, Theorem 3.1]. *Every closed geodesic is a  $1/k$ -geodesic for some  $k \geq 2$ .*

*Proof.* Let  $\gamma : S^1 \rightarrow M$  be a constant-speed closed geodesic. Then by the local length-minimization property of  $\gamma$  we have for every  $t \in S^1 = [0, 2\pi]$  that there exists an  $\epsilon_t > 0$  such that  $\gamma$  minimizes on the interval  $(t - \epsilon_t, t + \epsilon_t)$ . These intervals form an open cover of  $S^1$  and by compactness of the circle we can choose a finite subcover. Let  $\epsilon$  be the Lebesgue number of the finite subcover, and by the Archimedean property choose  $k \geq 2\pi/\epsilon$ . Then  $\gamma$  minimizes on all parameter intervals  $(t - \pi/k, t + \pi/k)$  and hence  $\gamma$  minimizes on all subintervals of length  $L/k$ .  $\square$

## 2. The over-under curve on doubled polygons

We proceed by studying  $1/k$ -geodesics on doubled regular  $n$ -gons. We define a doubled regular  $n$ -gon, denoted by  $X_n$ , to be the metric space obtained by gluing two regular  $n$ -gons along their common edges. We think of the doubled regular  $n$ -gons as having a top face and bottom face, so that traversal from one face to the other is possible only by crossing through a point along the shared edges or vertices of the faces. The distance between any two points lying on the same face is the standard Euclidean distance, whereas the distance between two points  $x, y \in X_n$  lying on opposite faces is given by  $\min_z \{d(x, z) + d(z, y)\}$ , where  $d$  is the Euclidean distance function on each face and the minimum is taken over all edge points  $z \in X_n$ .

We next need to determine the behavior of geodesics on these doubled polygons. On any given face the space is Euclidean and the geodesics are straight lines; if two points are on the same face the straight line path between them is a geodesic.



**Figure 4.** The  $n/2$  half-geodesics on  $X_n$ ,  $n$  even. Note that we only depict one face of the doubled polygon, and that these geodesics are the concatenation of straight line paths on the top and bottom faces.

If two points are on opposite faces, a geodesic connecting them must consist of a straight line segment on each face, connected via a shared edge or vertex point. If this geodesic traverses an edge, we can reflect the doubled polygon over this edge, creating a Euclidean space, and conclude that the geodesic on this reflected space must be a straight line. Upon reflecting back over the edge, we see that the angle of incidence is equal to the angle of reflection, i.e., that the geodesics billiard around the edges of the doubled polygons; see [Veech 1992]. An application of Heron’s solution to the shortest path problem illuminates this billiard behavior. We also have the following lemma.

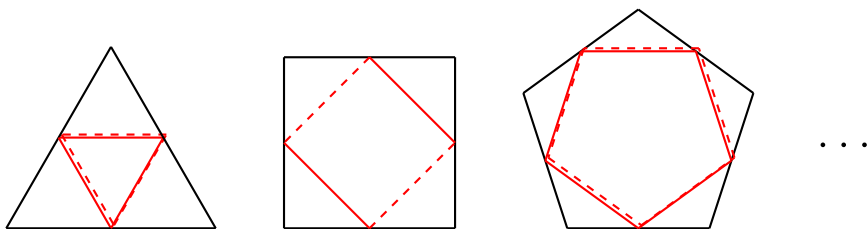
**Lemma 2.1** [Adelstein 2016a, Lemma 2.1]. *Geodesics on doubled regular  $n$ -gons do not contain vertices as interior points.*

*Proof.* By contradiction assume that the geodesic contains a vertex point. Because regular polygons are convex, we can always reflect the doubled polygon over one of the edges adjacent to the vertex (as in the paragraph above) such that the geodesic in the resulting Euclidean space is kinked with an acute angle. Choosing a pair of geodesic points on either side of the vertex, and considering the triangle formed in the resultant Euclidean space from these two points and the vertex, we conclude via the triangle inequality that there exists a shorter path connecting these points. This contradicts the local length-minimizing property of the geodesic at the vertex.  $\square$

The closed geodesics on the doubled regular polygons are interesting to study because of their simplicity. Our research is motivated by the following result:

**Proposition 2.2** [Adelstein 2016a, Proposition 2.5]. *Let  $X_n$  be a doubled regular  $n$ -gon:*

- (1) *If  $n$  is odd then  $X_n$  has no half-geodesics.*
- (2) *If  $n$  is even then  $X_n$  has exactly  $n/2$  half-geodesics: those curves which pass through the center of each face and perpendicularly through parallel edges; see Figure 4.*



**Figure 5.** Over-under curves on  $X_n$ . Note that we now depict as solid the segments of the geodesic on the top face, and as dashed the segments on the bottom face.

For  $n$  odd, the result states that  $X_n$  admits no half-geodesics. This naturally leads to the question of the smallest  $k \in \mathbb{N}$  such that  $X_n$  admits a  $1/k$ -geodesic. To examine this question we introduce the notion of an over-under curve on  $X_n$ .

**Definition 2.3.** Let  $\gamma : S^1 \rightarrow X_n$  be the closed geodesic on the doubled regular  $n$ -gon that passes through the midpoints of adjacent edges of  $X_n$ . We call  $\gamma$  an *over-under curve* between adjacent edges on  $X_n$ .

If  $\gamma$  is an over-under curve and  $\gamma(t_0)$ ,  $\gamma(t_1)$ , and  $\gamma(t_2)$  are edge points of  $X_n$  with the edge containing  $\gamma(t_1)$  adjacent to the edges containing  $\gamma(t_0)$  and  $\gamma(t_2)$  then the following facts are immediate:

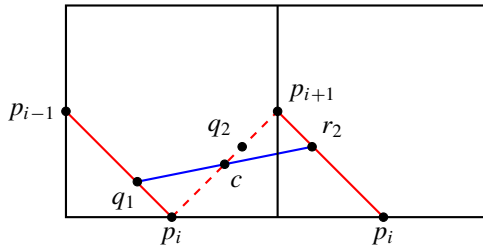
- (1)  $\gamma|_{(t_0,t_1)}$  and  $\gamma|_{(t_1,t_2)}$  are on opposite faces of  $X_n$ .
- (2) For every  $t \in (t_0, t_1)$  and  $s \in (t_1, t_2)$  the minimum path between  $\gamma(t)$  and  $\gamma(s)$  through the edge containing  $\gamma(t_1)$  passes through the point  $\gamma(t_1)$ .

The over-under curves on  $X_n$  exhibit distinct behavior depending on the parity of  $n$ . If  $n$  is even, the curves close smoothly after  $n$  segments. If  $n$  is odd, the curves close after  $n$  segments, but not smoothly. The first and  $n$ -th segments are on the same face of  $X_n$ , thus forming a corner when they meet at an edge. The curve needs  $2n$  segments before closing smoothly, so that the first and  $2n$ -th segments are on opposite faces (see Figure 5). The following theorem states that the minimizing index of the over-under curves equals the number of segments.

**Theorem 2.4.** Let  $\gamma : S^1 \rightarrow X_n$  be an over-under curve between adjacent edges on a doubled regular  $n$ -gon:

- (1) If  $n$  is even then  $\gamma$  is a  $1/n$ -geodesic.
- (2) If  $n$  is odd then  $\gamma$  is a  $1/(2n)$ -geodesic.

*Proof.* We prove the theorem for  $n$  even and note that the proof of the odd case is equivalent after a reparametrization of the curve. Start by parametrizing  $\gamma$  by a circle of length  $2\pi$  so that each edge point is given by  $p_i = \gamma(2\pi i/n)$ . To prove the theorem we show that  $\gamma$  is the minimizing path between any pair of points



**Figure 6.** The over-under curve on  $X_4$ .

$q_1 = \gamma(t)$  and  $q_2 = \gamma(t + 2\pi/n)$ . First note that if the  $q_j$  are edge points then  $\gamma$  is indeed the minimizing path, as  $\gamma$  is a straight line path on a single face of  $X_n$ . Otherwise the  $q_j$  are on opposite faces and the segment of  $\gamma$  connecting the pair contains an edge point  $p_i$ . Any shorter path between the  $q_j$  must cross an edge distinct from the edge containing  $p_i$ . It is only necessary to consider paths through the edges containing  $p_{i\pm 1}$  as we can easily provide a lower bound of  $l(\gamma)/n$  for the length of paths through other edges. Without loss of generality we consider only those paths through the edge containing  $p_{i+1}$ .

By reflecting the doubled polygon over the edge containing  $p_{i+1}$  and considering the top and bottom faces as part of the same plane, we are able to complete the proof in the Euclidean setting. Assume  $q_1$  is on the top face and let  $r_2$  denote the reflection of  $q_2$  through the edge containing  $p_{i+1}$  (see Figure 6). We show that the straight-line path between  $q_1$  and  $r_2$  has length at least  $l(\gamma)/n$ . Let  $c$  be the point of intersection between the line segments  $\overline{q_1 r_2}$  and  $\overline{p_i p_{i+1}}$ . Consider the pair of triangles  $\Delta q_1 c p_i$  and  $\Delta r_2 c p_{i+1}$ . By construction we have that the sides opposite  $\angle c$  in each triangle have equal length so that applying law of sines to both triangles yields

$$\frac{\sin(\angle q_1)}{Q_1} = \frac{\sin(\angle p_i)}{P_i} = \frac{\sin(\angle c)}{C} = \frac{\sin(\angle r_2)}{R_2} = \frac{\sin(\angle p_{i+1})}{P_{i+1}},$$

where we have used a capital letter to denote the length of the side opposite its angle. We note that  $\angle p_i = \pi - \angle p_{i+1}$  so that  $\angle r_2 = \angle p_i - \angle c$  and

$$\frac{\sin(\pi - \angle c - \angle p_i)}{Q_1} = \frac{\sin(\angle p_i)}{P_i} = \frac{\sin(\angle p_i - \angle c)}{R_2} = \frac{\sin(\pi - \angle p_i)}{P_{i+1}}.$$

Via the trigonometric identity  $\sin(\pi - x) = \sin(x)$  we have  $P_i = P_{i+1}$  and

$$\frac{Q_1 + R_2}{2P_i} = \frac{\sin(\angle p_i - \angle c) + \sin(\angle p_i + \angle c)}{2 \sin(\angle p_i)} = \frac{2 \sin(\angle p_i) \cos(\angle c)}{2 \sin(\angle p_i)} = \cos(\angle c) \leq 1.$$

We have therefore shown that  $2P_i = P_i + P_{i+1} \geq Q_1 + R_2 = l(\gamma)/n$  and conclude that  $\gamma$  minimizes on all subintervals of length  $l(\gamma)/n$ . □

### 3. Bounding the minimizing index

We have shown for  $n$  odd that  $X_n$  admits a  $1/(2n)$ -geodesic by explicitly constructing such curves. We now consider whether these curves realize the optimal minimizing property on  $X_n$ , i.e., if  $k = 2n$  is the smallest  $k \in \mathbb{N}$  for which  $X_n$  ( $n$  odd) admits a  $1/k$ -geodesic. To quantify this notion Sormani introduced the minimizing index.

**Definition 3.1** [Sormani 2007, Definition 3.3]. The minimizing index of a metric space  $M$ , denoted by  $\text{minind}(M)$ , is the smallest  $k \in \mathbb{N}$  such that the metric space admits a  $1/k$ -geodesic.

For  $n$  odd the results of the previous section give an upper bound of  $2n$  on  $\text{minind}(X_n)$ . Furthermore, we have seen that such  $X_n$  do not admit half-geodesics and consequently that  $2 < \text{minind}(X_n) \leq 2n$ . A natural question is whether we can sharpen this bound on the minimizing index of  $X_n$ . Given a doubled prime-gon it is compelling to believe that its minimizing index is  $2p$ .

**Conjecture 3.2.** *If  $p$  is an odd prime, then  $\text{minind}(X_p) = 2p$ .*

Observe here that the primality of  $p$  is necessary, since if we have  $n = kp$  with  $k \geq 2$ , we can construct a  $1/(2p)$ -geodesic by creating an over-under curve between the midpoints of every  $k$ -th edge of  $X_n$ . Evidence towards this conjecture begins with the following:

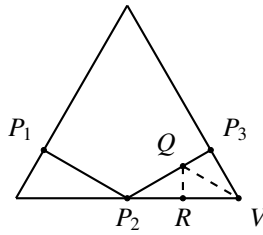
**Proposition 3.3.** *The conjecture is true for the case  $p = 3$ ; i.e., the minimizing index of the doubled regular triangle is 6.*

*Proof.* We first define the *period* of a closed geodesic on a doubled polygon to be its total number of segments. As these geodesics must close smoothly, we have that the period is always even. Also note because a geodesic on a doubled polygon will never minimize on an open segment that contains multiple edge points, the period provides a lower bound on the minimizing index of a geodesic (the smallest  $k \in \mathbb{N}$  such that it is a  $1/k$ -geodesic).

We have therefore reduced the problem to showing that those closed geodesics with period less than 6 have minimizing index at least 6. We have already established that  $X_3$  does not admit half-geodesics, and that the period must be even, so we need only consider those closed geodesics with period 4. Such curves can be classified: they must leave an edge with angle  $\frac{\pi}{6}$ , traverse an adjacent edge perpendicularly, return to the starting edge (at the same point, but not with the same velocity), traverse the remaining edge perpendicularly, and return to the starting point to close up smoothly (see [Figure 7](#)).

It remains to show that any period-4 geodesic on  $X_3$  has minimizing index at least 6. We first show that the period-4 geodesic from [Figure 7](#) has minimizing index





**Figure 7.** Closed geodesic on  $X_3$  with period 4 and minimizing index 6.

at least 6. In this figure  $QV$  is the bisector of angle  $V$  and  $QR$  is perpendicular to  $VP_2$ . Using properties of similar triangles we have

$$|QR| = |QP_3| = \frac{|P_2P_3|}{3} = \frac{L}{12}.$$

This demonstrates that there exist two equal-length paths between  $Q$  and its corresponding point on the bottom face: one along our geodesic through  $P_3$ , and another through  $R$ . The geodesic therefore cannot minimize beyond this segment of length  $L/6$ , and we conclude that the minimizing index must be at least 6. For a period-4 geodesic on  $X_3$  that does not contain the midpoint of an edge, a similar argument shows that the minimizing index must be strictly greater than 6.  $\square$

Please note that [Proposition 3.3](#) did not appear in the original version of this paper. The proof was sketched by the undergraduate research group [\[Adelstein et al. 2019\]](#) and independently by one of the referees (who also produced [Figure 7](#)). The original paper had an argument equivalent to the last paragraph of the proof showing that the minimizing index of the geodesic from [Figure 7](#) is at least 6, but did not classify all period-4 geodesics, and therefore did not determine the minimizing index of  $X_3$ .

It is reasonable to believe that a similar argument could be used to show that  $\text{minind}(X_5) = 10$ . It need only be shown that closed geodesics of period 4, 6, or 8 have minimizing index at least 10. One quickly realizes that this direction of reasoning will prove untenable for resolving the conjecture; as  $p$  grows it becomes prohibitively difficult to complete such an analysis. As a partial solution to the conjecture we present the following:

**Theorem 3.4** [\[Adelstein et al. 2019, Theorem 2\]](#). *For  $p$  prime, as  $p \rightarrow \infty$ , the minimizing index of  $X_p$  grows without bound.*

This theorem was proved after the completion of this paper by a subsequent undergraduate research group [\[Adelstein et al. 2019\]](#). The proof involves a careful study of the closed geodesics on doubled polygons, developing new techniques to study their minimizing properties. To the best of our knowledge [Conjecture 3.2](#) remains open, and we invite the reader to pursue their own investigations.

## Acknowledgements

The authors would like to thank the Faculty Research Committee at Trinity College for funding Fong’s on-campus research with Adelstein through the Student Research Program. We also acknowledge the wonderful work of Brett C. Smith who recreated all the figures in this paper for publication.

## References

- [Adelstein 2016a] I. M. Adelstein, “Existence and nonexistence of half-geodesics on  $S^2$ ”, *Proc. Amer. Math. Soc.* **144**:7 (2016), 3085–3091. [MR](#) [Zbl](#)
- [Adelstein 2016b] I. M. Adelstein, “Minimizing closed geodesics via critical points of the uniform energy”, *Math. Res. Lett.* **23**:4 (2016), 953–972. [MR](#) [Zbl](#)
- [Adelstein et al. 2019] I. Adelstein, A. Azvolinsky, J. Hinman, and A. Schlesinger, “Minimizing closed geodesics on polygons and disks”, preprint, 2019. [arXiv](#)
- [Ho 2008] W. K. Ho, “Manifolds without  $1/k$ -geodesics”, *Israel J. Math.* **168** (2008), 189–200. [MR](#) [Zbl](#)
- [Sormani 2007] C. Sormani, “Convergence and the length spectrum”, *Adv. Math.* **213**:1 (2007), 405–439. [MR](#) [Zbl](#)
- [Veech 1992] W. A. Veech, “The billiard in a regular polygon”, *Geom. Funct. Anal.* **2**:3 (1992), 341–379. [MR](#) [Zbl](#)

Received: 2019-01-24

Revised: 2019-02-07

Accepted: 2019-02-18

[iadelstein@gmail.com](mailto:iadelstein@gmail.com)

*Department of Mathematics, Yale University,  
New Haven, CT, United States*

[adam.y.w.fong@gmail.com](mailto:adam.y.w.fong@gmail.com)

*Department of Mathematics, Trinity College, Hartford, CT,  
United States*

## INVOLVE YOUR STUDENTS IN RESEARCH

*Involve* showcases and encourages high-quality mathematical research involving students from all academic levels. The editorial board consists of mathematical scientists committed to nurturing student participation in research. Bridging the gap between the extremes of purely undergraduate research journals and mainstream research journals, *Involve* provides a venue to mathematicians wishing to encourage the creative involvement of students.

### MANAGING EDITOR

Kenneth S. Berenhaut Wake Forest University, USA

### BOARD OF EDITORS

Colin Adams	Williams College, USA	Robert B. Lund	Clemson University, USA
Arthur T. Benjamin	Harvey Mudd College, USA	Gaven J. Martin	Massey University, New Zealand
Martin Bohner	Missouri U of Science and Technology, USA	Mary Meyer	Colorado State University, USA
Amarjit S. Budhiraja	U of N Carolina, Chapel Hill, USA	Frank Morgan	Williams College, USA
Pietro Cerone	La Trobe University, Australia	Mohammad Sal Moslehian	Ferdowsi University of Mashhad, Iran
Scott Chapman	Sam Houston State University, USA	Zuhair Nashed	University of Central Florida, USA
Joshua N. Cooper	University of South Carolina, USA	Ken Ono	Univ. of Virginia, Charlottesville
Jem N. Corcoran	University of Colorado, USA	Yuval Peres	Microsoft Research, USA
Toka Diagana	Howard University, USA	Y.-F. S. Pétermann	Université de Genève, Switzerland
Michael Dorff	Brigham Young University, USA	Jonathon Peterson	Purdue University, USA
Sever S. Dragomir	Victoria University, Australia	Robert J. Plemmons	Wake Forest University, USA
Joel Foisy	SUNY Potsdam, USA	Carl B. Pomerance	Dartmouth College, USA
Erin W. Fulp	Wake Forest University, USA	Vadim Ponomarenko	San Diego State University, USA
Joseph Gallian	University of Minnesota Duluth, USA	Bjorn Poonen	UC Berkeley, USA
Stephan R. Garcia	Pomona College, USA	József H. Przytycki	George Washington University, USA
Anant Godbole	East Tennessee State University, USA	Richard Rebarber	University of Nebraska, USA
Ron Gould	Emory University, USA	Robert W. Robinson	University of Georgia, USA
Sat Gupta	U of North Carolina, Greensboro, USA	Javier Rojo	Oregon State University, USA
Jim Haglund	University of Pennsylvania, USA	Filip Saidak	U of North Carolina, Greensboro, USA
Johnny Henderson	Baylor University, USA	Hari Mohan Srivastava	University of Victoria, Canada
Glenn H. Hurlbert	Virginia Commonwealth University, USA	Andrew J. Sterge	Honorary Editor
Charles R. Johnson	College of William and Mary, USA	Ann Trenk	Wellesley College, USA
K. B. Kulasekera	Clemson University, USA	Ravi Vakil	Stanford University, USA
Gerry Ladas	University of Rhode Island, USA	Antonia Vecchio	Consiglio Nazionale delle Ricerche, Italy
David Larson	Texas A&M University, USA	John C. Wierman	Johns Hopkins University, USA
Suzanne Lenhart	University of Tennessee, USA	Michael E. Zieve	University of Michigan, USA
Chi-Kwong Li	College of William and Mary, USA		

### PRODUCTION

Silvio Levy, Scientific Editor

Cover: Alex Scorpan

See inside back cover or [msp.org/involve](http://msp.org/involve) for submission instructions. The subscription price for 2019 is US \$195/year for the electronic version, and \$260/year (+\$35, if shipping outside the US) for print and electronic. Subscriptions, requests for back issues and changes of subscriber address should be sent to MSP.

Involve (ISSN 1944-4184 electronic, 1944-4176 printed) at Mathematical Sciences Publishers, 798 Evans Hall #3840, c/o University of California, Berkeley, CA 94720-3840, is published continuously online. Periodical rate postage paid at Berkeley, CA 94704, and additional mailing offices.

Involve peer review and production are managed by EditFlow® from Mathematical Sciences Publishers.

PUBLISHED BY

 **mathematical sciences publishers**

nonprofit scientific publishing

<http://msp.org/>

© 2019 Mathematical Sciences Publishers

# involve

2019

vol. 12

no. 7

Asymptotic expansion of Warlimont functions on Wright semigroups MARCO ALDI AND HANQIU TAN	1081
A systematic development of Jeans' criterion with rotation for gravitational instabilities KOHL GILL, DAVID J. WOLLKIND AND BONNI J. DICHONE	1099
The linking-unlinking game ADAM GIAMBRONE AND JAKE MURPHY	1109
On generalizing happy numbers to fractional-base number systems ENRIQUE TREVIÑO AND MIKITA ZHYLINSKI	1143
On the Hadwiger number of Kneser graphs and their random subgraphs ARRAN HAMM AND KRISTEN MELTON	1153
A binary unrelated-question RRT model accounting for untruthful responding AMBER YOUNG, SAT GUPTA AND RYAN PARKS	1163
Toward a Nordhaus–Gaddum inequality for the number of dominating sets LAUREN KEOUGH AND DAVID SHANE	1175
On some obstructions of flag vector pairs $(f_1, f_{04})$ of 5-polytopes HYE BIN CHO AND JIN HONG KIM	1183
Benford's law beyond independence: tracking Benford behavior in copula models REBECCA F. DURST AND STEVEN J. MILLER	1193
Closed geodesics on doubled polygons IAN M. ADELSTEIN AND ADAM Y. W. FONG	1219
Sign pattern matrices that allow inertia $\mathbb{S}_n$ ADAM H. BERLINER, DEREK DEBLIECK AND DEEPAK SHAH	1229
Some combinatorics from Zeckendorf representations TYLER BALL, RACHEL CHAISER, DEAN DUSTIN, TOM EDGAR AND PAUL LAGARDE	1241