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Stein's method, smoothing and functional approximation

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Abstract

Stein's method for Gaussian process approximation can be used to bound the differences between the expectations of smooth functionals h of a càdlàg random process X of interest and the expectations of the same functionals of a well understood target random process Z with continuous paths. Unfortunately, the class of smooth functionals for which this is easily possible is very restricted. Here, we provide an infinite dimensional Gaussian smoothing inequality, which enables the class of functionals to be greatly expanded — examples are Lipschitz functionals with respect to the uniform metric, and indicators of arbitrary events — in exchange for a loss of precision in the bounds. Our inequalities are expressed in terms of the smooth test function bound, an expectation of a functional of X that is closely related to classical tightness criteria, a similar expectation for Z, and, for the indicator of a set K, the probability $\mathbb{P}(Z \in K^{\theta} \setminus K^{-\theta})$ that the target process is close to the boundary of K.

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1 Introduction

Stein's method [32, 33] is a powerful method of obtaining explicit bounds on the distance between a probability distribution $\mathcal{L}(X)$ of interest and a well-understood approximating distribution $\mathcal{L}(Z)$ on some metric space $(\mathcal{S}, \mathrm{dist})$. Here, $\mathcal{L}(X)$ denotes the distribution of the random variable X, and "distance" is represented by a bound on the differences $|\mathbb{E}h(X) - \mathbb{E}h(Z)|$, for all functions in some class \mathcal{H} of test functions:

$$d_{\mathcal{H}}(\mathcal{L}(X), \mathcal{L}(Z)) := \sup_{h \in \mathcal{H}} |\mathbb{E}[h(X)] - \mathbb{E}[h(Z)]|.$$

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For example, if \mathcal{H} is the class of Lipschitz functions h from \mathcal{S} to \mathbb{R} with

$$\sup_{\substack{x \neq y \\ x,y \in \mathcal{S}}} \frac{|h(x) - h(y)|}{\operatorname{dist}(x,y)} \leq 1,$$

the distance is the Wasserstein metric. The general method was treated in monograph form in [33], its application to approximation by the Poisson and normal distributions is described in the books [6] and [13], respectively, and its many uses in combination with the Malliavin calculus are presented in the monograph [26]. Stein's method is not restricted to approximating the distributions of real-valued random variables, but can be used for multivariate distributions, as introduced in [4] for the Poisson and [19] for the normal, as well as for entire processes, as developed by [4] and [1] for Poisson processes and [5] for Brownian motion.

A feature of Stein's method is that, in applications, there is often a class of functions $\mathcal H$ that is particularly well adapted for use with the method, resulting in a distance that is easily bounded. For normal approximation in one dimension, the family of (bounded) Lipschitz functions is typically amenable, leading to approximation with respect to a (bounded) Wasserstein distance. This distance is very natural in the context of weak convergence, but is not well suited for approximating tail probabilities, where the appropriate test functions are indicators of half lines, and hence are not Lipschitz. Nonetheless, by approximating the indicator functions above and below by Lipschitz functions with steep gradient, a (bounded) Wasserstein distance of ε easily implies an approximation bound of order $O(\varepsilon^{1/2})$ for the probability of a half line. Thus smoothing the indicator function, and then using the error bound for smooth functions, immediately results in bounds for the probabilities of half lines, albeit at the cost of an inferior rate of approximation. If better rates of approximation are required for tail probabilities, then (much) more work usually has to be done.

For process approximation by Brownian motion, the classes of 'smooth' test functions M_c^0 , c>0, used in [5] and [22, 21], and given in (1.2) and (1.5) below, are particularly well adapted for use with Stein's method. However, the classes are not rich enough to directly imply bounds for the distributions of functionals, such as the supremum, that have immediate practical application. This limits the usefulness of the results obtained. As an example, it would be advantageous to know that, if X belonged to the space $\mathbb D$ of càdlàg processes indexed by [0,T] equipped with the Skorokhod topology, and if

$$\kappa^Z_c(X) \; := \; \sup_{h \in M^0_c \colon \left\|h\right\|_{M^0} \leqslant 1} \left| \mathbb{E}h(X) - \mathbb{E}h(Z) \right|$$

were small (see (1.2), and (1.5)), then differences of the form

$$\Delta_Z(X,K) := |\mathbb{P}(X \in K) - \mathbb{P}(Z \in K)|, \tag{1.1}$$

for K with $\mathbb{P}(Z \in \partial K) = 0$, would also be small. Then, at least, if $(X_n)_{n\geqslant 1}$ were a sequence of processes in \mathbb{D} for which $\kappa_c^Z(X_n)$ converged to zero, this would imply that X_n converged weakly to Z, something that is shown only under some additional, mild assumptions in [5] and [22, 21].

The aim of this article is to show how to use smoothing to obtain error bounds for the distribution of rather general functionals of X, provided that a bound for functions in the class M_c^0 is available. In addition to the value of $\kappa_c^Z(X)$, the bounds involve some quantities that can be deduced from the properties of the limiting process Z, which, for $\Delta_Z(X,K)$, also involve the set K. In addition, they require an estimate of the uniform difference between X and a smoothed version X_ε of X (see (1.8)), which, in asymptotic settings, can be thought of as a quantitative version of tightness. The method is rather

broadly useful, being designed to give error bounds in situations that are not amenable to other more direct approaches. In the context of the general version of Stein's method for Gaussian (not necessarily Brownian) process approximation, introduced in [7], it has already proved successful in deriving bounds for the error in approximations to the distributions of useful functionals, based on those that can be established for functions in the class M_c^0 . The ideas are also fundamental to the Gaussian smoothing techniques recently derived in [2], and applied to the analysis of wide random neural networks.

1.1 Related approaches for process approximation

There is an enormous literature on process approximation in classical settings, such as random walks and martingales, with the best results using strong embeddings. As is typical for Stein's method, our focus is on non-classical settings where strong embeddings are not available, and so this literature is not relevant here. There are other general approaches to Gaussian process approximation in the Stein's method literature. These approaches either suffer from lack of applicability, or are developed in function spaces, such as $L^2[0,1]$, equipped with metrics that are too weak to see natural statistics of the process, such as the maximum, or the finite dimensional distributions. Even convergence for such statistics cannot be established by using such metrics. Regarding applicability, the approach of [5] is the most flexible, because it is a natural extension of the methods previously used for approximating the distributions of random variables using Stein's method, and many of the techniques that have found great success there can be adapted to it; see, for example, [18], [21, 22]. The results of this paper show that rates of convergence from the approach of [5] can be relatively easily adapted to imply rates of convergence for many natural statistics that are continuous with respect to Skorokhod topology.

In more detail, [31] develops an approach to Stein's method for Gaussian measures on separable Banach spaces. When approximating continuous processes, this setting is rich enough to include most natural statistics, because C[0,1] equipped with the sup norm is such a space. However, the bounds developed there are complicated, being expressed in terms of associated Hilbert norms and embeddings, and their evaluation in concrete settings seems to be too difficult to have been widely used. The next step was taken in [15]. Here, Stein's method is developed for Brownian motion, now viewed as an abstract Wiener measure on Hilbert space. The corresponding inner products are of integral type, and do not see finite dimensional distributions. Since the inner product determines the metric on the underlying space, the rates of convergence are not transferable to many natural statistics. Their approach has been further applied and refined in [8] and [11], to make it somewhat more applicable, but without removing the drawback inherent in the weak metric.

Finally, in a recent paper [16], a rate of convergence is derived that is expressed in terms of the bounded Wasserstein distance with respect to the fractional Sobolev norm, but only in the special setting of Donsker's theorem. This metric is much stronger. However, their technique involves applying Stein's method to a finite-dimensional discretization of the process, and then using bounds on maximal fluctuations to handle the error in the discretization. In the setting of Donsker's theorem, the growth of the error in dimension when applying Stein's method is well controlled, and sharp maximal inequalities are classically available. Both of these are crucial, if good bounds are to be obtained using their method. Its applicability in more general settings has not yet been established. Their bounds, in the limited context of Donsker's theorem, are better than ours, as discussed below in Example 1.8; both are rather worse than those obtained

 $^{^{1}}$ Due to the Sobolev embeddings (page 3 in [16]), one can derive the same rate of convergence, up to a multiplicative constant, in the bounded Wasserstein distance (1.18) with respect to the usual sup norm.

using strong approximation [23, 24]; see the discussion in Remark 1.9. As the highlight of this article, the bounds that we derive are applicable to functionals that need not be Lipschitz, the limiting process can be quite general, and the process to be approximated may have an arbitrary dependence structure. All of these features were needed for the queueing application in our companion paper [7, Theorem 1.2].

1.2 Test functions

In order to state the main result, we need some further definitions. Let $\mathbb{D}:=\mathbb{D}\left([0,T];\mathbb{R}^d\right)$ be the set of functions from [0,T] to \mathbb{R}^d that are right continuous with left limits. We assume, with little loss of functionality, that $T\geqslant 1$ to simplify forthcoming bounds. The space \mathbb{D} endowed with the sup norm $\|\cdot\|$ is a Banach space (though not separable), and we denote the Fréchet derivatives of functions $h\colon \mathbb{D}\to\mathbb{R}$ by Dh,D^2h,\ldots

As in [5] and [22], let M^0 be the set of functions $h \colon \mathbb{D} \to \mathbb{R}$ such that

$$||h||_{M^{0}} := \sup_{w \in \mathbb{D}} |h(w)| + \sup_{w \in \mathbb{D}} ||Dh(w)|| + \sup_{w \in \mathbb{D}} ||D^{2}h(w)|| + \sup_{\substack{w,v \in \mathbb{D} \\ v \neq 0}} \frac{||D^{2}h(w+v) - D^{2}h(w)||}{||v||}$$

$$(1.2)$$

is finite, where we write $||A|| := \sup_{w:||w||=1} |A[w,\ldots,w]|$ for any k-linear form A. Letting $I_t \in \mathbb{D}([0,T];\mathbb{R})$ be defined by

$$I_t(u) := \mathbb{I}[u \geqslant t],\tag{1.3}$$

we are interested in functions $h \in M^0$ such that for all $r, s, t \in [0, T]$ and $x_1, x_2 \in \mathbb{R}^d$,

$$\sup_{w \in \mathbb{D}} \left| D^2 h(w) [x_1 I_r, x_2 (I_s - I_t)] \right| \leqslant c |x_1| |x_2| |s - t|^{1/2}. \tag{1.4}$$

For c > 0, we define

$$M_c^0 = \{ h \in M^0 : (1.4) \text{ holds} \}.$$
 (1.5)

For $\theta>0$ and a Skorokhod–measurable set $K\subset\mathbb{D}$, we define the θ -enlargement and θ -shrinkage as follows:

$$K^{\theta} \; := \; \left\{ w : \operatorname{dist}(w,K) < \theta \right\} \; \supseteq \; K \quad \text{and} \quad K^{-\theta} \; := \; \left((K^{c})^{\theta} \right)^{c} \; \subseteq \; K,$$

where $dist(w, K) := \inf\{||w - v|| : v \in K\}.$

For $w \in \mathbb{D}$ with $\|w\| < \infty$, we can define the ε -regularized versions of w as follows: For $\varepsilon > 0$,

$$w_{\varepsilon}(s) := \mathbb{E}[w(s + \varepsilon U)],$$
 (1.6)

where U is uniformly distributed over the interval (-1,1), and we define w(t)=w(T) for t>T and w(t)=w(0) for t<0. In other words, we follow the convention that for a function $s\in[0,T]\mapsto w(s)$ and for any $x\in\mathbb{R}$, the function $w(\bullet+x)$ is understood as

$$s \in [0, T] \mapsto w([s + x]_0^T),$$
 (1.7)

where $[u]_0^T = \min\{\max\{0, u\}, T\}$. It is easy to see that the path w_{ε} , defined in (1.6), is absolutely continuous, so that by Rademacher's theorem, ∇w_{ε} is well defined almost everywhere.

Then, for $h\colon \mathbb{D}\to \mathbb{R}$ that is bounded and measurable with respect to the Skorokhod topology, and for any $\varepsilon,\delta>0$, we define an (ε,δ) -smoothed version of h by

$$h_{\varepsilon,\delta}(w) := \mathbb{E}[h(w_{\varepsilon} + \delta B + \delta \Theta)],$$
 (1.8)

where B is a standard d-dimensional Brownian motion on [0,T], Θ is a standard Gaussian vector on \mathbb{R}^d that is independent of B, and w_ε is defined as in (1.6). As is shown in Lemma 1.11 and Remark 1.12, if $\sup_{y\in\mathbb{D}}|h(y)|\leqslant 1$, then

$$h_{\varepsilon,\delta} \in M_{\mathfrak{c}_1}^0$$
, with $\mathfrak{c}_1 := \mathfrak{c}_1(\varepsilon,\delta) := \varepsilon^{-2} \delta^{-2} \sqrt{(1+\frac{\varepsilon}{2})(T+\varepsilon^2)}$ (1.9)

for any positive ε and δ , and if h is differentiable with $||Dh|| \leqslant 1$, then

$$h_{\varepsilon,\delta} \in M_{\mathfrak{c}_2}^0$$
, with $\mathfrak{c}_2 := \mathfrak{c}_2(\varepsilon,\delta) := \varepsilon^{-1}\delta^{-1}\sqrt{\frac{2+\varepsilon}{2\pi}}$. (1.10)

Our main result is as follows. For its statement, we define

$$c_0(v) := 1 + v + \sqrt{2}v^2 + \sqrt{\frac{50}{\pi}}v^3,$$

observing that $c_0(v) \leqslant 7.5v^3$ if $v \geqslant 1$, and set

$$C_0 := C_0(\varepsilon, \delta) := c_0(\sqrt{T + \varepsilon^2}/\varepsilon\delta).$$
 (1.11)

Note, in particular, that if $T \geqslant 1$, $0 < \varepsilon \leqslant \frac{1}{2}\sqrt{T}$ and $\delta \leqslant 2$, entailing $\sqrt{T + \varepsilon^2}/\varepsilon \delta \geqslant 1$, then

$$C_0(\varepsilon,\delta) \leqslant 10.5 \left(\sqrt{T}/\varepsilon\delta\right)^3$$
 and $\mathfrak{c}_1(\varepsilon,\delta) \leqslant \frac{5}{4} \left(\sqrt{T}/\varepsilon\delta\right)^2$. (1.12)

We also define \mathcal{H} to be the set of all $h \colon \mathbb{D} \to \mathbb{R}$ that are bounded, Skorokhod-measurable, and Lipschitz with respect to the sup-norm, satisfying $\sup\{|h(w)| \colon w \in \mathbb{D}\} \leqslant 1$ and $\|Dh\| \leqslant 1$.

Theorem 1.1. Let X,Z be random elements of $\mathbb D$ such that Z has almost surely continuous sample paths. Let $\mathfrak c_1$, $\mathfrak c_2$, and C_0 be as defined in (1.9), (1.10), and (1.11). Let $X_\varepsilon,Z_\varepsilon$ be defined according to (1.6). Suppose that there are $\kappa_1,\kappa_2\geqslant 0$ such that, for any $h\in M_c^0$, we have

$$|\mathbb{E}h(X) - \mathbb{E}h(Z)| \leqslant \kappa_1 ||h||_{M^0} + c \kappa_2. \tag{1.13}$$

Then, for any $K \subseteq \mathbb{D}$ that is measurable with respect to Skorokhod topology, and for any positive $\delta, \varepsilon, \theta, \gamma$, we have

$$\begin{aligned} \left| \mathbb{P}(X \in K) - \mathbb{P}(Z \in K) \right| \\ &\leqslant C_0(\varepsilon, \delta) \, \kappa_1 + \mathfrak{c}_1(\varepsilon, \delta) \kappa_2 + \mathbb{P}\left(\|X_{\varepsilon} - X\| \geqslant \theta \right) + \mathbb{P}\left(\|Z_{\varepsilon} - Z\| \geqslant \theta \right) \\ &+ 6de^{-\frac{\gamma^2}{8dT\delta^2}} + \mathbb{P}(Z \in K^{2(\theta + \gamma)} \setminus K^{-2(\theta + \gamma)}). \end{aligned} \tag{1.14}$$

Furthermore, for any $h \in \mathcal{H}$ and for any $\varepsilon, \delta \in (0, 1)$,

$$\left| \mathbb{E} \left[h(X) - h(Z) \right] \right| \leqslant \mathbb{E} \|X_{\varepsilon} - X\| + \mathbb{E} \|Z_{\varepsilon} - Z\| + 2T^{1/2} \delta \mathbb{E} \|B_{[0,1]}\| + 2\delta \sqrt{d} + 4(T+2)\varepsilon^{-2} \delta^{-2} \kappa_1 + \mathfrak{e}_2(\varepsilon, \delta) \kappa_2,$$

$$(1.15)$$

where $B_{[0,1]}$ denotes the standard d-dimensional Brownian motion on [0,1].

Remark 1.2. (i) The quantity $|\mathbb{E}h(X) - \mathbb{E}h(Z)|$ with $h \in M_c^0$ can frequently be bounded effectively in the form (1.13), using Stein's method. See e.g. [5], [7], [18], [22, 21].

(ii) The bound (1.14) fits in well with weak convergence. Suppose that $(X_n)_{n\geqslant 1}\subset \mathbb{D}$, for fixed T, is a sequence of processes for which (1.13) holds with $\kappa_i=\kappa_i^{(n)}\to 0$ as

 $n\to\infty$, i=1,2, and define $X_{n,\varepsilon}=(X_n)_\varepsilon$ according to (1.6). Then, letting $n\to\infty$ in (1.14), it follows that, for all $\varepsilon,\delta,\gamma,\theta>0$ and for all Skorokhod-measurable $K\subset\mathbb{D}$,

$$\limsup_{n \to \infty} \left| \mathbb{P}(X_n \in K) - \mathbb{P}(Z \in K) \right|$$

$$\leqslant \limsup_{n \to \infty} \mathbb{P}(\|X_{n,\varepsilon} - X_n\| \geqslant \theta) + \mathbb{P}(\|Z_{\varepsilon} - Z\| \geqslant \theta)$$

$$+ 6de^{-\frac{\gamma^2}{8dT\delta^2}} + \mathbb{P}(Z \in K^{2(\theta + \gamma)} \setminus K^{-2(\theta + \gamma)}).$$

Now, since Z has almost surely continuous sample paths, $\|Z_{\varepsilon} - Z\| \to 0$ almost surely, as $\varepsilon \to 0$. Hence, letting ε and δ tend to zero for fixed θ, γ , and then letting θ and γ tend to zero, it follows that

$$\begin{split} & \limsup_{n \to \infty} \left| \mathbb{P}(X_n \in K) - \mathbb{P}(Z \in K) \right| \\ & \leqslant \limsup_{\theta \to 0} \limsup_{\varepsilon \to 0} \limsup_{n \to \infty} \mathbb{P}\left(\|X_{n,\varepsilon} - X_n\| \geqslant \theta \right) + \mathbb{P}(Z \in \partial K). \end{split}$$

Thus $\limsup_{n\to\infty} \left| \mathbb{P}(X_n \in K) - \mathbb{P}(Z \in K) \right| = 0$ for all K with $\mathbb{P}(Z \in \partial K) = 0$, and hence X_n converges weakly to Z, provided that

$$\limsup_{\varepsilon \to 0} \limsup_{n \to \infty} \mathbb{P}(\|X_{n,\varepsilon} - X_n\| \geqslant \theta) = 0 \text{ for each } \theta > 0.$$
 (1.16)

Thus, with this condition in addition to $\kappa_i^{(n)} \to 0$, i=1,2, it follows that X_n converges weakly to Z. Now, by the definition of $X_{n,\varepsilon}$, we have $\|X_{n,\varepsilon}-X_n\| \leqslant \omega_{X_n}(\varepsilon)[0,T]$, where

$$\omega_x(\eta)[0,T] := \sup_{0 \le s < t \le T \colon t - s < \eta} |x(t) - x(s)| \tag{1.17}$$

denotes the uniform modulus of continuity of x on [0,T]. It is well known that any sequence $(X_n, n \in \mathbb{N}) \subset \mathbb{D}$ that converges weakly to a limit with continuous sample paths satisfies the tightness condition

$$\limsup_{\varepsilon \to 0} \limsup_n \mathbb{P} \big(\omega_{X_n}(\varepsilon)[0,T] \geqslant \theta \big) \ = \ 0 \ \text{ for all } \theta > 0.$$

Hence, given $\kappa_i^{(n)} \to 0$, i = 1, 2, the condition (1.16) is a necessary and sufficient condition for weak convergence to Z.

The Lévy-Prokhorov distance between X and Z can be defined as

$$d_{\mathrm{LP}}\big(\mathcal{L}(X),\mathcal{L}(Z)\big) \ := \ \inf\big\{\varepsilon > 0 \colon \mathbb{P}[X \in K] \leqslant \mathbb{P}[Z \in K^{\varepsilon}] + \varepsilon,$$
 for all Skorokhod measurable subsets $K\}$,

and the bounded Wasserstein distance by

$$d_{\mathrm{BW}}(\mathcal{L}(X), \mathcal{L}(Z)) := \sup_{h \in \mathcal{H}} |\mathbb{E}h(X) - \mathbb{E}h(Z)|, \tag{1.18}$$

for \mathcal{H} as defined before Theorem 1.1. Formula (2.41) in the proof of Theorem 1.1 and the bound (1.15) thus immediately imply the following corollary.

Corollary 1.3. Under the assumptions of Theorem 1.1, it follows that the Lévy–Prokhorov distance between the distributions of X and Z is bounded by

$$\max \left\{ 2(\theta + \gamma), C_0(\varepsilon, \delta) \, \kappa_1 + \mathfrak{c}_1(\varepsilon, \delta) \kappa_2 + \mathbb{P} \left(\|X_{\varepsilon} - X\| \geqslant \theta \right) + \mathbb{P} \left(\|Z_{\varepsilon} - Z\| \geqslant \theta \right) + 6de^{-\frac{\gamma^2}{8dT\delta^2}} \right\},$$

$$(1.19)$$

and the bounded Wasserstein distance by

$$\mathbb{E}||X_{\varepsilon} - X|| + \mathbb{E}||Z_{\varepsilon} - Z|| + 2T^{1/2}\delta \,\mathbb{E}||B_{[0,1]}|| + 2\delta\sqrt{d} + 4(T+2)\varepsilon^{-2}\delta^{-2}\kappa_1 + \mathfrak{c}_2(\varepsilon,\delta)\kappa_2,$$
(1.20)

for any positive $\delta, \varepsilon, \theta$ and γ , where $B_{[0,1]}$ denotes the standard d-dimensional Brownian motion on [0,1].

The main use for the bound given in Theorem 1.1 is to obtain explicit bounds on the error in approximating probabilities and expectations of functionals involving the process X by the corresponding values for the process Z. These follow from (1.14) and (1.15) by optimizing the choice of ε , δ , γ , θ . In the case of a sequence of processes indexed by n, rates of convergence can be deduced, as illustrated in Examples 1.8 and 1.10 below. The following lemma provides a useful bound for probabilities of the form $\mathbb{P}(\|Y_{\varepsilon} - Y\| \geqslant \theta)$. It is a quantitative version of the classical condition of [14].

Lemma 1.4. Suppose that $Y:=(Y^{(1)},\ldots,Y^{(d)})\in\mathbb{D}$ is a random process, and that, for some $\beta>1$ and $\gamma>0$,

$$\mathbb{P}\big[\min\{|Y^{(i)}(s)-Y^{(i)}(u)|,|Y^{(i)}(u)-Y^{(i)}(t)|\}>a\big] \leqslant K|s-t|^{\beta}/a^{\gamma}, \ 1\leqslant i\leqslant d, \quad \ \ (1.21)$$

for all s < u < t such that $\frac{1}{2}n^{-1} \leqslant t - s \leqslant 1$. Then, for $\varphi_n(\cdot)$ defined by

$$\varphi_n(\eta) := \max_{1 \leqslant i \leqslant d} \max_{1 \leqslant k \leqslant \lceil nT \rceil} n \mathbb{P} \Big[\sup_{(k-1)/n \leqslant s \leqslant k/n} |Y^{(i)}(s) - Y^{(i)}((k-1)/n)| > \eta \Big], \tag{1.22}$$

it holds that, for any $\varepsilon \in (n^{-1}, 1)$, we have

$$\mathbb{P}[\|Y_{\varepsilon} - Y\| > \sqrt{d\lambda}] \leqslant dT \left\{ 2\varphi_n \left(\frac{\lambda(1 - 2^{-(\beta - 1)/(2\gamma)})}{26} \right) + C'(K, \beta, \gamma, d) \frac{\varepsilon^{\beta - 1}}{\lambda^{\gamma}} \right\}, \quad (1.23)$$

where $C'(K, \beta, \gamma, d) > 0$ is a finite constant that does not depend on ε or λ .

Remark 1.5. (i) The condition (1.21) can be replaced by

$$\mathbb{P}[|Y^{(i)}(t) - Y^{(i)}(s)| > a] \le K|s - t|^{\beta}/a^{\gamma}, \quad 1 \le i \le d, \tag{1.24}$$

for all s < t such that $\frac{1}{2}n^{-1} \leqslant t - s \leqslant 1$.

(ii) If (1.21) is true for all t > s, then the function $\varphi_n(\eta)$ in (1.22) can be replaced by

$$\varphi(\eta) = \max_{1 \le i \le d} \frac{1}{T} \mathbb{P}[J_{Y^{(i)}}(T) > \eta], \tag{1.25}$$

where $J_X(T) := \sup_{0 \le t \le T} |X(t) - X(t-)|$.

(iii) If (1.24) is true for all t > s, then the term φ_n in the bound (1.23) can be dropped.

A standard setting in which the modulus of continuity can be bounded is that of normalized sums of mixing random variables. Suppose that $Y(t):=n^{-1/2}\sum_{j=1}^{\lfloor nt\rfloor}X_j$, where X_1,X_2,\ldots,X_N is a sequence of centred random variables such that, for some p>2, $\mathbb{E}[|X_j|^p]^{1/p}\leqslant c_p$ uniformly in $1\leqslant j\leqslant N$. Suppose also that the sequence is strongly mixing, with mixing coefficients satisfying

$$\sup \left\{ \left| \mathbb{P}[A \cap B] - \mathbb{P}[A]\mathbb{P}[B] \right| : A \in \mathcal{F}_{1,s}, B \in \mathcal{F}_{s+j,N}, \ 2 \leqslant s \leqslant N - j - 1 \right\}$$

$$\leqslant kj^{-b}, \quad j \geqslant 1,$$

for some k > 0 and b > p/(p-2), where, for $1 \le i < j \le N$, $\mathcal{F}_{i,j} := \sigma\{Y_i, \dots, Y_j\}$.

Lemma 1.6. Under the above mixing conditions, for $\varepsilon > \frac{1}{2n}$ and for $T \leqslant N/n$, with $\omega_Y(\varepsilon)[0,T]$ as defined in (1.17) and with $r:=1+\frac{(p-1)b}{p+b}>2$,

$$\mathbb{P}[\|Y_{\varepsilon} - Y\| \geqslant ac_{p}] \leqslant \mathbb{P}[\omega_{Y}(\varepsilon)[0, T] \geqslant ac_{p}] \leqslant C'Ta^{-r}\varepsilon^{\frac{r}{2} - 1}$$
(1.26)

for a suitable constant C' := C'(p, k, b).

For a process Y for which the differences $\sqrt{n}\{Y(j/n)-Y((j-1)/n)\}$ satisfy the same conditions as the X_j , but Y(t) may vary on intervals of the form ((j-1)/n,j/n], the bound (2.43) in the proof of Lemma 1.6 can be used to show that (1.21) in Lemma 1.4 is satisfied, with $\beta=r/2$ and $\gamma=r$. A pendant of (1.22) is then needed to control the variation on intervals of length 1/n.

Remark 1.7. If Z is a centred Gaussian process with

$$\mathbb{E}\left[\left(Z(v) - Z(u)\right)^2\right] \leqslant k|v - u|^{\tau},\tag{1.27}$$

for some positive constants k and τ , then, for any $\gamma \geqslant 2$,

$$\mathbb{P}[|Z(t)-Z(s)|>a] \ \leqslant \ k^{\gamma/2}\mathbb{E}\{|G|^{\gamma}\}a^{-\gamma}|t-s|^{\tau\gamma/2},$$

where $G \sim \mathcal{N}(0,1)$ is standard normal. Then Lemma 1.4 and Remark 1.5-(iii) imply that

$$\mathbb{P}(\|Z_{\varepsilon} - Z\| > \lambda) \leqslant T\hat{C}\varepsilon^{\frac{\tau\gamma}{2} - 1}\lambda^{-\gamma},\tag{1.28}$$

where $\hat{C} = \hat{C}(k, \tau, \gamma)$ is a suitable constant.

We are not aware of any general theory for bounding the final term $\mathbb{P}(Z \in K^{\theta} \setminus K^{-\theta})$, even for restricted classes of sets and continuous Gaussian processes. For finite dimensional Gaussian measures and convex sets, such enlargements have order θ as $\theta \to 0$; see, for example, [3] and [20, Section 1.1.4]. For Gaussian processes with values in a Hilbert space, there are some results when K is an open ball [20]. That being said, for certain K and K0, it may nonetheless be possible to obtain quantitive results; see the following two examples.

(i) If $(Z_t:t\in[0,1])$ is a Brownian motion on \mathbb{R}^d and $g\colon\mathbb{D}([0,1];\mathbb{R}^d)\to\mathbb{R}$ is a measurable function that is Lipschitz on $C([0,1];\mathbb{R}^d)$ such that g(Z) has a bounded density, for example if d=1 and $g(w)=\sup_{0\leqslant s\leqslant 1}w(s)$, then for $K=\{w\in\mathbb{D}\colon g(w)\leqslant y\}$, it is easy to see that

$$\mathbb{P}(Z \in K^{\theta} \setminus K^{-\theta}) \leqslant c'\theta,$$

where c' is a constant depending on the density bound and the Lipschitz constant of g. In such an example, Theorem 1.1 can be used to provide bounds on the Kolmogorov distance between $\mathcal{L}(g(X))$ and $\mathcal{L}(g(Z))$.

(ii) We can also obtain quantitive results for finite-dimensional distributions as follows. Setting d=1, let $0 < t_1 < \cdots < t_k \le T$, \mathcal{K} be a convex set in \mathbb{R}^k , and

$$K = \{ w \in \mathbb{D} \colon (w(t_i))_{i=1}^k \in \mathcal{K} \}.$$

Noting $K^{\theta} \subseteq \left\{w \in \mathbb{D} \colon (w(t_i))_{i=1}^k \in \mathcal{K}^{\theta \sqrt{k}}\right\}$ and $K^{-\theta} \supseteq \left\{w \in \mathbb{D} \colon (w(t_i))_{i=1}^k \in \mathcal{K}^{-\theta \sqrt{k}}\right\}$, if Z is a Gaussian process and $(Z(t_i))_{i=1}^k$ has non-singular covariance, then Gaussian isoperimetry or anti-concentration (e.g., [3] and [20, Section 1.1.4]) implies

$$\mathbb{P}(Z \in K^{\theta} \setminus K^{-\theta}) \leqslant c_k \theta,$$

where c_k is a constant depending on the dimension k and on the covariance kernel of Z.

Theorem 1.1 and the discussion following should be compared to [5, Theorem 2] and [22, Proposition 2.3], which give criteria for weak convergence assuming a bound of the form

$$\left| \mathbb{E}[h(X_n)] - \mathbb{E}[h(Z)] \right| \le \|h\|_{M^0} \, \kappa^{(n)}$$

for all functions h in the larger class M^0 , which are not assumed to satisfy the smoothness condition (1.4) (the statement in [5, Theorem 2] is not correct, and the bound must hold for functions without the smoothness condition). For functions h such that $\|D^2h\| < \infty$, it is immediate that, for fixed $w, x \in \mathbb{D}$, $|D^2h(w)[x,y_r]| \to 0$ if $\|y_r\| \to 0$ as $r \to \infty$. Under the additional smoothness condition (1.4), $|D^2h(w)[x,y_r]| \to 0$ for some sequences y_r such that $\|y_r\| = 1$ for all r, in which the functions y_r become 'small' in the sense that $|\{u \in [0,T], y_r(u) \neq 0\}| \to 0$. A minor advantage of working with this smaller class of functions M_c^0 is that a discretization step can be avoided, which in turn can remove a log-term from the convergence rate; see [5, Remark 2 and (2.29)]. More importantly, applying Stein's method using only the test functions in the smaller class has wider applicability; for instance, [7, Theorem 1.2] gives a Gaussian process approximation to the $GI/GI/\infty$ queue, using condition (1.4) in the proof in an essential way.

Example 1.8. As a proof of concept, we explore the quality of result that can be obtained with Theorem 1.1 in the classical case, where

$$X_n(s) = n^{-1/2} \sum_{i=1}^{\lfloor ns \rfloor} W_i$$

with $(W_i)_{i\geqslant 1}$ real centred, i.i.d. random variables such that $\mathbb{E}[W_1^2]=1$ and $\mathbb{E}\big[|W_1|^p\big]<\infty$ for some $p\geqslant 3$. Donsker's theorem implies that the limiting process Z is a standard Brownian motion. First, [5, Theorem 1 and Remark 2] implies that, for $p\geqslant 3$, the bound (1.13) holds with

$$\kappa_1^{(n)} = CT n^{-1/2} \mathbb{E}|W_1|^3 \text{ and } \kappa_2^{(n)} = \frac{4}{3} T n^{-1/2},$$
(1.29)

for a universal constant C, and then the first two terms of (1.14) are bounded by

$$C_0 \kappa_1^{(n)} + \mathfrak{c}_1 \kappa_2^{(n)}, \tag{1.30}$$

where $C_0 = C_0(\varepsilon, \delta)$ and $\mathfrak{c}_1 = \mathfrak{c}_1(\varepsilon, \delta)$ are as in (1.11), (1.9), and (1.12). Note that, for the Brownian motion Z, we can deduce from Remark 1.7 that for any $l \geqslant 2$,

$$\mathbb{P}(\|Z_{\varepsilon} - Z\| \geqslant \theta) \leqslant K_Z T \varepsilon^{\frac{l}{2} - 1} \theta^{-l}$$
(1.31)

for some constant K_Z depending on $\mathcal{L}(Z)$ and l. Moving to $\mathbb{P}(\|X_{n,\varepsilon} - X_n\| \geqslant \theta)$, it is possible to use Doob's L^p -inequality and Rosenthal's inequality to bound

$$\mathbb{P}\left(\sup_{s\leqslant v\leqslant s+\varepsilon}|X_n(v)-X_n(s)|\geqslant\theta\right)\leqslant K_W\varepsilon^{p/2}\theta^{-p}$$

for some constant K_W depending on $\mathcal{L}(W_1)$ and p. From here, a standard argument, based on the inequality

$$\begin{split} |X_{n,\varepsilon}(s) - X_n(s)| &\leqslant \sup_{|h| \leqslant \varepsilon} |X_n(s+h) - X_n(s)| \\ &\leqslant 3 \max_{0 \leqslant k \leqslant \lfloor T/2\varepsilon \rfloor} \sup_{2k\varepsilon \leqslant v \leqslant 2(k+1)\varepsilon} |X_n(v) - X_n(2k\varepsilon)|, \end{split}$$

For example, we take $x=x_1I_v$ and $y_r=x_2(I_{v-r-1}-I_v)$ with $x_1,x_2\in\mathbb{R}^d$ and $v\in[0,T]$.

implies that $\mathbb{P}\left(\|X_{n,\varepsilon} - X_n\| \geqslant \theta\right)$ is upper bounded of order $T\varepsilon^{\frac{p}{2}-1}\theta^{-p}$. However, we can get a bound of a similar quality by applying Lemma 1.4 and Remark 1.5(2), which we do here to illustrate their use. We first verify (1.21) for all $0 < s < t \leqslant T$. If |t-s| < 1/n, then for s < u < t,

$$\min\{|X_n(t) - X_n(u)|, |X_n(s) - X_n(u)|\} = 0,$$

since at least one term in the minimum must be zero. If $|t - s| \ge 1/n$, then for p > 2, Rosenthal's inequality [30, Theorem 3] implies that

$$\mathbb{E}[|X_n(t) - X_n(u)|^p] \leqslant C_p \mathbb{E}\{|W_1|^p\} \left(\frac{\lceil n(t-s)\rceil}{n}\right)^{p/2}$$

$$\leqslant 2^{p/2} C_p \mathbb{E}\{|W_1|^p\} (t-s)^{p/2},$$

where C_p is a constant depending only on p, and (1.21) thus holds, for $\beta = \frac{p}{2} - 1 > 0$ and $\gamma = p$, by Markov's inequality. In order to use Remark 1.5-(ii), we also note that

$$\begin{split} \mathbb{P}(J_{X_n}(T) \geqslant \theta/2) &= \mathbb{P}\Big(\max_{1 \leqslant i \leqslant \lfloor nT \rfloor} W_i \geqslant (\theta/2) \sqrt{n} \Big) \\ &\leqslant \lfloor nT \rfloor \, \mathbb{P}\big(|W_1| \geqslant (\theta/2) \sqrt{n} \big) \\ &\leqslant \lfloor nT \rfloor \, \frac{\mathbb{E}\big(|W_1|^p\big)}{(\theta/2)^p n^{p/2}} \, \leqslant \, 2^{p+1} \mathbb{E}\big(|W_1|^p\big) T n^{1-\frac{p}{2}} \theta^{-p}. \end{split}$$

Altogether, we deduce from Lemma 1.4 with $\beta = \frac{p}{2} - 1 > 0$ and $\gamma = p$ that

$$\mathbb{P}(\|X_{n,\varepsilon} - X_n\| \geqslant \theta) \leqslant \widetilde{K}_W T \left(\varepsilon^{\frac{p}{2} - 1} \theta^{-p} + n^{1 - \frac{p}{2}} \theta^{-p}\right)$$
(1.32)

for some constant \widetilde{K}_W depending on $\mathcal{L}(W_1)$ and p.

Hence, in view of (1.30), (1.31), (1.32), (1.29), (1.12) and (1.14), it follows from Corollary 1.3 that, for $T \geqslant 1$, $0 < \varepsilon \leqslant \frac{1}{2} \sqrt{T}$ and $0 < \delta \leqslant 2$, we have

$$d_{\text{LP}}(\mathcal{L}(X_n), \mathcal{L}(Z)) \leqslant C\left(T^{5/2}(\varepsilon\delta)^{-3}n^{-1/2} + T\varepsilon^{\frac{p}{2}-1}\theta^{-p} + Tn^{1-\frac{p}{2}}\theta^{-p} + \theta + \gamma\right) + 6e^{-\frac{\gamma^2}{8T\delta^2}},$$

for some constant C. We first choose $\gamma=2\delta\sqrt{10T\log n}$ so that the exponential term is of order $\mathrm{O}(n^{-5})$, which is negligible compared to the first term $T^{5/2}(\varepsilon\delta)^{-3}n^{-1/2}$. Note also that we shall choose ε to be much bigger than 1/n and also choose $\theta=\sqrt{T}\delta$. In this way, we only need to balance three terms

$$T^{5/2}(\varepsilon\delta)^{-3}n^{-1/2}$$
, $T\varepsilon^{p/2-1}\theta^{-p}$ and θ .

Balancing θ and $T\varepsilon^{p/2-1}\theta^{-p}$ gives $\theta=T^{1/(p+1)}\varepsilon^{(p-2)/(2(p+1))}$ and then balancing the final two terms in ε and δ gives

$$\varepsilon = \left(\{ T^4 n^{-1/2} \}^{p+1} T^{-4} \right)^{1/(5p-1)} \quad \text{and} \quad \theta = \sqrt{T} \delta = \left(\{ T^4 n^{-1/2} \}^{\frac{p}{2}-1} T^3 \right)^{1/(5p-1)} .$$

As a result, we have established a rate of convergence in Lévy-Prokhorov distance:

$$d_{\mathrm{LP}}\big(\mathcal{L}(X_n),\mathcal{L}(Z)\big) \ = \ \mathrm{O}\Big[(\log n)^{1/2}\big(\{T^4n^{-1/2}\}^{\frac{p}{2}-1}T^3\big)^{1/(5p-1)}\Big].$$

Assuming finite third moments (p=3) and T=1, the rate is $O\left(n^{-\frac{1}{56}}\sqrt{\log n}\right)$, and we can obtain the rate $O\left(n^{-\frac{1}{20}+a}\right)$ for arbitrarily small a>0, if we assume that W_1 has all its moments.

Remark 1.9. Fix T=1. For the bounded Wasserstein distance, similar calculations can be carried through, based on the bound given in Corollary 1.3. From (1.32), it follows by integration that $\mathbb{E}\|X_{n,\varepsilon}-X_n\|=\mathrm{O}\big(\varepsilon^{(p-2)/(2p)}\big)$, so that the bound (1.20) is easily seen to be of order

$$O(\varepsilon^{\frac{p-2}{2p}} + \delta + \varepsilon^{-2}\delta^{-2}n^{-1/2}).$$

Balancing the terms by taking

$$\delta = \varepsilon^{-2/3} n^{-1/6} = \varepsilon^{(p-2)/(2p)}$$

gives $\varepsilon = n^{-\frac{p}{7p-6}}$, and hence a bound

$$d_{\text{BW}}(\mathcal{L}(X_n), \mathcal{L}(Z)) = O(n^{-\frac{1}{6} + \frac{2p}{3(7p-6)}}).$$

Thus, assuming finite third moments (p=3), the rate is $O\left(n^{-\frac{1}{30}}\right)$, and, if W_1 has all its moments, the rate is $O\left(n^{-\frac{1}{14}+a}\right)$, for any a>0. In this example, the approach of [16], discussed in Section 1.1, can also be applied. It gives the rates $O\left(n^{-\frac{1}{18}+a}\right)$ and $O\left(n^{-\frac{1}{6}+a}\right)$ for any a>0, respectively, for bounded Lipschitz functionals, which are better; however, no bounds are given by their method for the Lévy–Prokhorov distance. In the strong approximation theorems of [23, 24], copies of X_n and Z are constructed on the same probability space, in such a way that the distribution of the random variable $\|X_n-Z\|$ is tightly controlled. In particular, with the moment assumptions above, their bounds on $\mathbb{E}\|X_n-Z\|$ imply corresponding rates for bounded Lipschitz functionals of orders $O\left(n^{-\frac{1}{6}}\right)$ and $O\left(n^{-\frac{1}{2}+a}\right)$ for any a>0, respectively (see [17, Theorem 2.6.7]), and, if W_1 has a finite moment generating function, a rate of order $O\left(n^{-\frac{1}{2}}\log n\right)$ [24, Theorem 1]; these are much better still.

Example 1.10. In [18, Section 6], the joint distribution of the processes counting edges and two-stars in the Bernoulli random graph $\mathcal{G}(n,p)$ is shown, after appropriate centering and normalization, to converge weakly to a Gaussian limit. In this example, we complement Döbler and Kasprzak's result with a convergence rate, and we refer interested readers to their paper for an overview of relevant literature. The two-dimensional process that they considered was $X_n := (X_n^{(1)}, X_n^{(2)})$ defined by

$$X_{n}^{(1)}(t) := \frac{\lfloor nt \rfloor - 2}{n^{2}} \sum_{1 \leq i < j \leq \lfloor nt \rfloor} (E_{ij} - p) =: \frac{\lfloor nt \rfloor - 2}{n^{2}} V_{n}(t);$$

$$X_{n}^{(2)}(t) := \frac{1}{n^{2}} \sum_{1 \leq i < j < k \leq \lfloor nt \rfloor} \widetilde{E}_{ijk}, \quad 0 \leq t \leq 1,$$
(1.33)

where E_{ij} , $1 \leq i < j \leq n$, are independent indicator random variables with fixed expectation $p \in (0,1)$, and where

$$\widetilde{E}_{ijk} := E_{ij}E_{ik} + E_{ij}E_{jk} + E_{ik}E_{jk} - 3p^2, \quad i < j < k.$$

Letting

$$Y(t) := t\sqrt{p(1-p)} B(\frac{1}{2}t^2), \tag{1.34}$$

where ${\cal B}$ is a standard real Brownian motion, the limiting random process is the degenerate two-dimensional process³

$$Z := (Y, 2pY).$$
 (1.35)

 $[\]overline{\ }^3$ Here we take a different representation of the limiting process Z from that in [18, Theorem 6.4], and one can easily verify by checking the covariance structure of these two centred Gaussian processes that they are identical in law.

In [18, Theorem 6.4], it is shown that the condition (1.13) of Theorem 1.1 is satisfied. More precisely, for any $h \in M \supset M^0 \supset M_c^0$ (for all c > 0), the bound (1.13) holds with

$$\kappa_1 = 16422 \frac{\sqrt{\log n}}{\sqrt{n}} + \frac{138}{\sqrt{n}} = O\left(\frac{\sqrt{\log n}}{\sqrt{n}}\right) \text{ and } \kappa_2 = 0.$$

In this particular example, we obtain the following rates of functional convergence in the Lévy–Prokhorov distance and in the bounded Wasserstein distance:

claim:
$$d_{LP}(\mathcal{L}(X_n), \mathcal{L}(Z)) = O(n^{-\frac{1}{20}+a})$$
 and $d_{BW}(\mathcal{L}(X_n), \mathcal{L}(Z)) = O(n^{-\frac{1}{14}+a})$ (1.36)

for any a > 0.

To establish the claim by invoking Corollary 1.3, we need to bound probabilities like

$$\mathbb{P}[\|X_{n,\varepsilon} - X_n\| > \theta] \quad \text{and} \quad \mathbb{P}[\|Z_{\varepsilon} - Z\| > \theta]$$
 (1.37)

for any $\theta, \varepsilon > 0$ and for any $n \ge 2$. For this purpose, we use Lemma 1.4 together with Remark 1.5 (i) to bound the first term in (1.37), and Remark 1.7 to bound the second term in (1.37). For the latter, it is immediate from (1.34), (1.35), and independence of Brownian increments that, for $0 \le v < u \le 1$,

$$\begin{split} \mathbb{E}\big[|Y(u) - Y(v)|^2\big] &= p(1-p)\mathbb{E}\Big[\big|uB(\frac{1}{2}u^2) - vB(\frac{1}{2}v^2)\big|^2\Big] \\ &= p(1-p)\mathbb{E}\Big[\big|u\big\{B(\frac{1}{2}u^2) - B(\frac{1}{2}v^2)\big\} + (u-v)B(\frac{1}{2}v^2)\big|^2\Big] \\ &= p(1-p)\Big(\frac{u^2}{2}(u^2 - v^2) + (u-v)^2\frac{v^2}{2}\Big) \\ &\leqslant \frac{1}{4} \cdot \frac{3}{2}(u-v) = \frac{3}{8}(u-v), \end{split}$$

so that the bound (1.28) can be used with $T=\tau=1$ and with any choice of $\gamma\geqslant 2$. In other words, in view of (1.35), we have

$$\mathbb{P}\left[\|Z_{\varepsilon} - Z\| > \theta\right] \leqslant \mathbb{P}\left[\|Y_{\varepsilon} - Y\| > \frac{1}{2}\theta\right] + \mathbb{P}\left[2p\|Y_{\varepsilon} - Y\| > \frac{1}{2}\theta\right]
= O\left(\varepsilon^{\frac{\gamma}{2} - 1}\theta^{-\gamma}\right),$$
(1.38)

which is of the same order as the bound in (1.31). For $\mathbb{P}[\|X_{n,\varepsilon} - X_n\| > \theta]$, considering the first component, note that, for $0 \le s < t \le 1$,

$$X_n^{(1)}(t) - X_n^{(1)}(s) = \frac{\lfloor nt \rfloor - \lfloor ns \rfloor}{n^2} V_n(s) + \frac{\lfloor nt \rfloor - 2}{n^2} (V_n(t) - V_n(s))$$

=: $A_n(s,t) + A'_n(s,t)$,

say. Now, for $U \sim \operatorname{Binomial}(m,p)$, it follows that $\mathbb{E}\{(U-mp)^{2r}\} \leqslant C_r(p)m^r$, for a suitable constant $C_r(p)$, for any $r \in \mathbb{N}$. Hence it follows, after a little calculation, that, for $0 \leqslant s < t \leqslant 1$ such that $(t-s) \geqslant \frac{1}{2}n^{-1}$, we have

$$\mathbb{E}\{(A_n(s,t))^{2r}\} \leqslant \left(\frac{3(t-s)}{n}\right)^{2r} C_r(p) \left(\frac{(ns)^2}{2}\right)^r \leqslant K_1(t-s)^{2r};$$

$$\mathbb{E}\{(A'_n(s,t))^{2r}\} \leqslant \left(\frac{t}{n}\right)^{2r} C_r(p) \left(\binom{\lfloor nt \rfloor}{2} - \binom{\lfloor ns \rfloor}{2}\right)^r \leqslant K_2(t-s)^r,$$

where the constants K_1, K_2 , and K in (1.39) below do not depend on (t, s, n). Note that the lower bound on t - s is used to accommodate the rounding error:

$$\lfloor nt \rfloor - \lfloor ns \rfloor \leqslant nt - ns + 1 \leqslant 3n(t-s)$$
 when $(t-s) \geqslant \frac{1}{2}n^{-1}$.

It now follows easily that, in the same range of s and t, and for any $r \in \mathbb{N}$,

$$\mathbb{P}\left[|X_n^{(1)}(t) - X_n^{(1)}(s)| > \theta\right] \leqslant K(t-s)^r \theta^{-2r}. \tag{1.39}$$

For the second component, observe first that for $0 \leqslant s < t \leqslant 1$

$$X_n^{(2)}(t) - X_n^{(2)}(s) = \frac{1}{n^2} \sum_{1 \leqslant i < j < k \leqslant n} \mathbb{I}\{\lfloor ns \rfloor < k \leqslant \lfloor nt \rfloor\} \widetilde{E}_{ijk}.$$

Now, in computing $\mathbb{E}\{(X_n^{(2)}(t)-X_n^{(2)}(s))^{2r}\}$, the expectations $\mathbb{E}\Big\{\prod_{l=1}^{2r}\widetilde{E}_{i_l,j_l,k_l}\Big\}$ are zero unless each index set $\{i_l,j_l,k_l\}$ overlaps with another index set $\{i_{l'},j_{l'},k_{l'}\}$ in at least two elements. The dominant contribution to the sum making up $\mathbb{E}\{(X_n^{(2)}(t)-X_n^{(2)}(s))^{2r}\}$ is seen to come from collections of index sets consisting of r pairs that overlap in two elements. Each such pair has 4 distinct indices, the largest of which lies between $\lfloor ns \rfloor$ and $\lfloor nt \rfloor$, so that there are $O\big(\{n^4(t-s)\}^r\big)$ such collections of index sets (when $t-s\geqslant \frac{1}{2}n^{-1}$) and each gives a contribution of order $O\big(\{n^{-2}\}^{2r}\big)$. The contribution from all other arrangements of index set is of smaller order. Hence

$$\mathbb{E}\{(X_n^{(2)}(t) - X_n^{(2)}(s))^{2r}\} \leqslant K_3(t-s)^r,$$

for a suitable constant K_3 , and it follows that, for $0 \le s < t \le 1$ such that $(t-s) \ge \frac{1}{2}n^{-1}$ and for any $r \in \mathbb{N}$, we have

$$\mathbb{P}[|X_n^{(2)}(t) - X_n^{(2)}(s)| > \theta] \leqslant K_3(t-s)^r \theta^{-2r}. \tag{1.40}$$

Since the process X has only one jump in any interval of length 1/n, the bounds (1.39) and (1.40) can be used with t-s=1/n to bound $\varphi_n(\eta)$ defined at (1.22). That is, we can find a constant \widetilde{K}_3 such that

$$\varphi_n(\eta) \leqslant \widetilde{K}_3 n^{1-r} \eta^{-2r}.$$

Invoking Lemma 1.4, it now follows that, for any $r \in \mathbb{N}$,

$$\mathbb{P}[\|X_{n,\varepsilon} - X_n\| > \theta] \leqslant K_r' \theta^{-2r} (n^{1-r} + \varepsilon^{r-1}),$$

for a suitable constant K'_r . Note that the above bound is of exactly the same orders as (1.32) in the case of sums of i.i.d. random variables, so that the same choices of ε , δ , θ , and $\gamma = p = 2r$ (for any $r \geqslant 1$) can be made as in Example 1.8 and Remark 1.9 so as to verify our claim (1.36).

The example illustrates the strength of our approach, as is typical in Stein's method, that it applies in situations with non-trivial dependencies, where rates of convergence are not otherwise available; see [7] for another application where Theorem 1.1 is needed. Being able to explicitly incorporate a time interval of length T that may depend on n is also very useful. Note that the error estimates given above still converge to zero as $n \to \infty$, if $T = T_n$ grows like a small enough power of n.

The key to proving Theorem 1.1 is the following lemma on Gaussian smoothing, for which we need the (ε, δ) -smoothing of h, defined in (1.8). The lemma is an infinite-dimensional analog of finite-dimensional Gaussian smoothing inequalities found, for example, in [27, Section 4.2]. The result is closely related to [25, Theorem 6.2, Chapter II].

Lemma 1.11. Let $h: \mathbb{D} \to \mathbb{R}$ be bounded and measurable with respect to the Skorokhod topology, and let ε and δ be positive. Then the function $h_{\varepsilon,\delta}$, defined in (1.8), is also

Skorokhod-measurable, and has infinitely many bounded Fréchet derivatives (with respect to the uniform norm) satisfying

$$\sup_{w \in \mathbb{D}} \|D^k h_{\varepsilon,\delta}(w)\| \leqslant C_k \sup_{y \in \mathbb{D}} |h(y)| (T + \varepsilon^2)^{k/2} \frac{1}{\varepsilon^k \delta^k}, \tag{1.41}$$

where C_k is a constant⁴ depending only on k. Moreover, with $C_0(\varepsilon, \delta)$ bounded at (1.12), we have

$$||h_{\varepsilon,\delta}||_{M^0} \leqslant C_0(\varepsilon,\delta) \sup_{y\in\mathbb{D}} |h(y)|,$$
 (1.42)

and for $z, x \in \mathbb{D}$,

$$\left| D^{2}h_{\varepsilon,\delta}(w)[z,x] \right| \\
\leqslant \sqrt{2}\varepsilon^{-1}\delta^{-2} \left(T + \varepsilon^{2} \right)^{\frac{1}{2}} ||z|| \left(\sup_{y \in \mathbb{D}} |h(y)| \right) \left(\int_{0}^{T} |\nabla x_{\varepsilon}(s)|^{2} ds + |x_{\varepsilon}(0)|^{2} \right)^{1/2}.$$
(1.43)

If, in addition, h is such that $||D^n h|| < \infty$ for some integer $n \ge 1$, then, for any integer $k \ge 0$, we have

$$||D^{k+n}h_{\varepsilon,\delta}|| \leqslant ||D^nh|| C_k(T+\varepsilon^2)^{\frac{k}{2}} (\varepsilon\delta)^{-k}, \tag{1.44}$$

with the same C_k as in (1.41); and if $||Dh|| < \infty$, then for $z, x \in \mathbb{D}$,

$$\left| D^2 h_{\varepsilon,\delta}(w)[z,x] \right| \leqslant \sqrt{2/\pi} \|z\| \|Dh\| \frac{1}{\delta} \left(\int_0^T |\nabla x_{\varepsilon}(s)|^2 ds + |x_{\varepsilon}(0)|^2 \right)^{1/2}. \tag{1.45}$$

Remark 1.12. For $x_1, x_2 \in \mathbb{R}^d$ and for functions $z = x_1 I_r$ and $x = x_2 (I_s - I_t)$, as per (1.4) and assuming s < t, the inequality (1.43) implies the inequality

$$\begin{split} \left| D^2 h_{\varepsilon,\delta}(w) [x_1 I_r, x_2 (I_s - I_t)] \right| \\ &\leqslant |x_1| |x_2| \sup_{y \in \mathbb{D}} |h(y)| \sqrt{1 + \frac{\varepsilon}{2}} \left(T + \varepsilon^2 \right)^{\frac{1}{2}} \frac{1}{\varepsilon^2 \delta^2} |t - s|^{1/2}. \end{split}$$

This is because, with $x(u) = x_2(I_s(u) - I_t(u)) = x_2\mathbb{I}[s \leqslant u < t]$,

$$\begin{split} & \int_0^T |\nabla x_\varepsilon(u)|^2 \, du \ = \ \frac{|x_2|^2}{4\varepsilon^2} \int_0^T \left[\mathbb{I}[s \leqslant u + \varepsilon < t] - \mathbb{I}[s \leqslant u - \varepsilon < t] \right]^2 du \\ & \leqslant \ \frac{|x_2|^2}{4\varepsilon^2} \left(4\varepsilon \mathbb{I}[t - s > 2\varepsilon] + 2|t - s|\mathbb{I}[t - s \leqslant 2\varepsilon] \right) \\ & \leqslant \ |x_2|^2 \, \frac{(t - s)}{2\varepsilon^2}. \end{split}$$

and, with $U \sim \text{Uniform}(-1, 1)$,

$$|x_{\varepsilon}(0)| = |\mathbb{E}[x(\varepsilon U)]| = |x_{2}| \cdot \mathbb{P}(s \leqslant \varepsilon U < t)$$

$$\leqslant |x_{2}| \frac{\min\{t - s, \varepsilon\}}{2\varepsilon} \leqslant |x_{2}| \frac{\sqrt{t - s}}{2\sqrt{\varepsilon}}.$$

 $[\]overline{^4}$ For example, we can choose $C_1 = \sqrt{2/\pi} < 1$ and $C_2 = 3$.

Similarly, if $||Dh|| < \infty$, then (1.45) implies

$$\left| D^2 h_{\varepsilon,\delta}(w) [x_1 I_r, x_2 (I_s - I_t)] \right| \leqslant \frac{|x_1| |x_2|}{\sqrt{\pi}} \|Dh\| \frac{|t - s|^{1/2}}{\varepsilon \delta} \sqrt{1 + \frac{\varepsilon}{2}}.$$

See also (1.9) and (1.10).

An expression for the Fréchet derivatives and bounds can be found at (2.11) and (2.24). They are not complicated, but require some set-partition notation, stemming from Faà di Bruno's formula for the derivatives of an exponential. The proof begins with the easy fact that w_{ε} belongs to the Cameron-Martin space of the sum of a d-dimensional Brownian motion and an independent Gaussian vector. (We must add the Gaussian vector because w_{ε} may not satisfy $w_{\varepsilon}(0)=0$, and thus we present a variant of the Cameron-Martin theorem in Theorem 2.1 below.) As a consequence, we can write $h_{\varepsilon,\delta}(w+x)-h_{\varepsilon,\delta}(w)$ as a single expectation with respect to the Gaussian process (Brownian motion plus an independent Gaussian vector). Roughly speaking, such a difference is smooth in x due to the change of measure formula.

2 Proofs

Let us first state a variant of the Cameron–Martin–Girsanov theorem [12], when the Gaussian process is the sum of a Brownian motion and an independent Gaussian random variable.

Theorem 2.1. Let $(B(t): t \in [0,T])$ be a standard d-dimensional Brownian motion and $g = (g^{(1)},...,g^{(d)}): [0,T] \to \mathbb{R}^d$ be a deterministic, absolutely continuous function such that

$$\int_0^T |\nabla g(t)|^2 dt = \int_0^T \sum_{i=1}^d \left(\frac{d}{dt} g^{(i)}(t)\right)^2 dt < \infty.$$
 (2.1)

Let Θ be a standard Gaussian random vector on \mathbb{R}^d that is independent of B. Then, for any bounded measurable function $\Phi: C([0,T];\mathbb{R}^d) \to \mathbb{R}$, we have

$$\mathbb{E}\left[\Phi(B+\Theta+g)\right] = \mathbb{E}\left(\Phi(B+\Theta)\exp\left[\langle g(0),\Theta\rangle - \frac{1}{2}|g(0)|^2 + \int_0^T \nabla g(t) \,dB(t) - \frac{1}{2}\int_0^T |\nabla g(t)|^2 \,dt\right]\right), \tag{2.2}$$

where $\langle \cdot \rangle$ denotes the inner product on \mathbb{R}^d .

Note that the Wiener integral

$$\int_0^T \nabla g(t) \, dB(t) \ := \ \sum_{i=1}^d \int_0^T \left(\frac{d}{dt} g^{(i)}(t) \right) \, dB^{(i)}(t) \tag{2.3}$$

is normally distributed with mean zero and variance $\int_0^T |\nabla g(t)|^2 dt$.

The usual Cameron-Martin theorem asserts that the probability measure induced by B+g on the path space $C([0,T];\mathbb{R}^d)$ is equivalent to that of B, when g satisfies the condition (2.1) and g(0)=0; see also pages 333-335 in [28]. For our purpose, we need a process that is absolutely continuous with its shift by w_{ε} from (1.6), which may not begin at zero, Since the law of $a+\Theta$ is equivalent to the law of Θ for any $a\in\mathbb{R}$, we use the additional Gaussian smoothing by Θ in (1.8).

Proof of Theorem 2.1. Given a bounded measurable function $\Phi: C([0,T];\mathbb{R}^d) \to \mathbb{R}$, we

have

$$\begin{split} \widetilde{\Phi}(v) &:= \mathbb{E} \big[\Phi(v + g(0) + \Theta) \big] \\ &= \frac{1}{(2\pi)^{d/2}} \int_{\mathbb{R}^d} \Phi(v + g(0) + z) e^{-\frac{|z|^2}{2}} dz \\ &= \frac{1}{(2\pi)^{d/2}} \int_{\mathbb{R}^d} \Phi(v + y) e^{-\frac{|y|^2}{2}} e^{\langle y, g(0) \rangle - \frac{1}{2} |g(0)|^2} dy \\ &= \mathbb{E} \bigg[\Phi(v + \Theta) \exp \Big(\langle \Theta, g(0) \rangle - \frac{1}{2} |g(0)|^2 \Big) \bigg] \quad \text{for } v \in C([0, T]; \mathbb{R}^d), \end{split}$$
(2.4)

where the third equality in (2.4) follows from a simple change of variable y=g(0)+z. It is clear that $\widetilde{\Phi}$ is also a real bounded measurable function on $C([0,T];\mathbb{R}^d)$. Then, we deduce from the independence between B and Θ , the Cameron-Martin theorem, and (2.4) that with $g^*=g-g(0)$,

$$\begin{split} & \mathbb{E} \big[\Phi(B + \Theta + g) \big] = \mathbb{E} \big[\widetilde{\Phi}(B + g^*) \big] \\ & = \mathbb{E} \left(\widetilde{\Phi}(B) \exp \left[\int_0^T \nabla g(t) \, dB(t) - \frac{1}{2} \int_0^T |\nabla g(t)|^2 \, dt \right] \right) \\ & = \mathbb{E} \left(\Phi(B + \Theta) \exp \left[\langle \Theta, g(0) \rangle - \frac{1}{2} |g(0)|^2 + \int_0^T \nabla g(t) \, dB(t) - \frac{1}{2} \int_0^T |\nabla g(t)|^2 \, dt \right] \right), \end{split}$$

which is exactly the equality (2.2).

With the above change of measure formula, we are ready to prove Lemma 1.11.

Proof of Lemma 1.11. To establish the measurability of $h_{\varepsilon,\delta}$, note that $x\mapsto x_\varepsilon$ is continuous (and hence measurable with respect to the Skorokhod topology) and then that $(x,y)\mapsto h(x_\varepsilon+\delta y)$ is measurable with respect to the product topology. Therefore, $h_{\varepsilon,\delta}$ is also measurable.

We first give a formal computation to indicate where the formulas below come from. Note that for $w \in \mathbb{D}$, w_{ε} is absolutely continuous from [0,T] to \mathbb{R}^d and

$$\|\nabla w_{\varepsilon}\| = \frac{1}{2\varepsilon} \|w(\bullet + \varepsilon) - w(\bullet - \varepsilon)\| \leqslant \frac{1}{\varepsilon} \|w\|, \tag{2.5}$$

where the function $w(\bullet + \varepsilon)$ is defined according to the convention (1.7). Thus, we can apply the formula (2.2) to write

$$h_{\varepsilon,\delta}(w) = \mathbb{E}\Big[h(\delta B + \delta \Theta) \exp(\Psi(w))\Big],$$
 (2.6)

where $\Psi(w) =: \Psi_{\Theta}(w) + \Psi_{B}(w)$ is a random element given by

$$\Psi(w) := \frac{1}{\delta} \langle \Theta, w_{\varepsilon}(0) \rangle - \frac{1}{2\delta^{2}} |w_{\varepsilon}(0)|^{2}
+ \frac{1}{\delta} \int_{0}^{T} \nabla w_{\varepsilon}(t) dB(t) - \frac{1}{2\delta^{2}} \int_{0}^{T} |\nabla w_{\varepsilon}(s)|^{2} ds,$$
(2.7)

such that the random variable $e^{\Psi(w)}$ has mean one and finite moments of all order, for any $w \in \mathbb{D}$. Now, formally, we ought to have

$$D^k h_{\varepsilon,\delta}(w)[x_1,\ldots,x_k] = \mathbb{E}\Big[h(\delta B + \delta \Theta)D^k \exp(\Psi(w))[x_1,\ldots,x_k]\Big],$$

and then $D^k \exp(\Psi(w))[x_1,\ldots,x_k]$ can be understood as $\exp(\Psi(w))$ times a polynomial of the derivatives of $\Psi(w)$, motivated by the Faà di Bruno's formula. Looking at the expression⁵

$$\Psi(w+v) - \Psi(w) = \frac{1}{\delta} \int_0^T \nabla v_{\varepsilon}(t) d(B - \delta^{-1} w_{\varepsilon})(t) - \frac{1}{2\delta^2} \int_0^T |\nabla v_{\varepsilon}(t)|^2 dt
+ \frac{1}{\delta} \langle \Theta - \delta^{-1} w_{\varepsilon}(0), v_{\varepsilon}(0) \rangle - \frac{1}{2\delta^2} |v_{\varepsilon}(0)|^2,$$
(2.8)

with v_{ε} defined according to (1.6), we can deduce from (2.5) that

$$D\Psi(w)[v] = \frac{1}{\delta} \int_0^T \nabla v_{\varepsilon}(s) d(B(s) - \delta^{-1} w_{\varepsilon}(s)) + \frac{1}{\delta} \langle \Theta - \delta^{-1} w_{\varepsilon}(0), v_{\varepsilon}(0) \rangle$$

=: $D\Psi_B(w)[v] + D\Psi_{\Theta}(w)[v].$ (2.9)

And, it is also easy to see that

$$D^{2}\Psi(w)[x,y] = -\frac{1}{\delta^{2}} \int_{0}^{T} \langle \nabla x_{\varepsilon}(s), \nabla y_{\varepsilon}(s) \rangle \, ds - \frac{1}{\delta^{2}} \langle x_{\varepsilon}(0), y_{\varepsilon}(0) \rangle,$$

$$D^{k}\Psi(w)[x_{1}, \dots, x_{k}] = 0, \quad k \geqslant 3,$$
(2.10)

and these higher derivatives are no longer random. The above discussion, together with the Faà di Bruno's formula, leads to the following claim:

$$D^{n}h_{\varepsilon,\delta}(w)[x_{1},...,x_{n}] = \mathbb{E}\left[h(\delta B + \delta \Theta)e^{\Psi(w)}\left(\sum_{\pi \in \mathcal{P}_{n,2}} \prod_{\mathfrak{b} \in \pi} D^{|\mathfrak{b}|}\Psi(w)[x_{\mathfrak{b}}]\right)\right], \qquad (2.11)$$

where

- $\mathcal{P}_{n,2}$ is the set of all partitions of $\{1,...,n\}$, whose blocks have at most 2 elements;
- $\mathfrak{b} \in \pi$ means that \mathfrak{b} is a block of π , whose cardinality is denoted by $|\mathfrak{b}|$;
- if $\mathfrak{b} = \{i_1,...,i_{|\mathfrak{b}|}\}$, the expression $D^{|\mathfrak{b}|}\Psi(w)[x_{\mathfrak{b}}]$ means $D^{|\mathfrak{b}|}\Psi(w)[x_{i_1},...,x_{i_{|\mathfrak{b}|}}]$; see (2.9) and (2.10).

Let us first verify the claim (2.11) for n = 1:

$$Dh_{\varepsilon,\delta}(w)[z] = \mathbb{E}\Big(h(\delta B + \delta \Theta)e^{\Psi(w)}D\Psi(w)[z]\Big). \tag{2.12}$$

By (1.8), (2.6), and (2.7), we can write for $w, z \in \mathbb{D}$,

$$h_{\varepsilon,\delta}(w+z) - h_{\varepsilon,\delta}(w) = \mathbb{E}\left[h(\delta B + \delta \Theta)\left(e^{\Psi(w+z)} - e^{\Psi(w)}\right)\right]. \tag{2.13}$$

Now, we deduce from (2.8), (2.9), and (2.5) that

$$|\Psi(w+z) - \Psi(w) - D\Psi(w)[z]| = \frac{1}{2\delta^2} \int_0^T |\nabla z_{\varepsilon}(s)|^2 ds + \frac{1}{2\delta^2} |z_{\varepsilon}(0)|^2$$

$$\leq \frac{T||z||^2}{2\delta^2 \varepsilon^2} + \frac{1}{2\delta^2} ||z||^2,$$

and

$$\int_0^T \nabla y(s) \, dB(s) \sim \mathcal{N}\left(0, \int_0^T |\nabla y(s)|^2 \, ds\right). \tag{2.14}$$

 $^{^5}$ For an absolutely continuous path g, d(B+g)(t)=d(B(t)+g(t)) is understood as $dB(t)+\dot{g}(t)dt$, where dB(t) is the Brownian integrator and $\dot{g}(t)dt$ is the usual Lebesgue integral with the derivative $\dot{g}(t)$ defined for almost every t.

It is thus straightforward to see from Taylor's expansion and simple Gaussian computations that

$$e^{\Psi(w+z)} - e^{\Psi(w)} = e^{\Psi(w)} D\Psi(w)[z] + \mathbf{O}(\|z\|^2),$$
 (2.15)

where the linear-in-z term $e^{\Psi(w)}D\Psi(w)[z] = \mathbf{O}(\|z\|)$. Here and in what follows, the big- \mathbf{O} is to be understood in the $L^p(\Omega)$ -sense; for example, $U(z) = \mathbf{O}(\|z\|)$ means that U(z) is a random variable that depends on z, and $(\mathbb{E}|U(z)|^p)^{1/p} = \mathrm{O}(\|z\|)$, in the usual sense of O , for any $p \in [2,\infty)$. Therefore, the equality in (2.12) follows from (2.13) and (2.15). That is, the claim (2.11) is verified for n=1.

For later use, let us first recall from (2.9)-(2.10) that $D^2\Psi(w)[x,y]$ does not depend on w and that

$$D\Psi(w+z)[x] = D\Psi(w)[x] + D^2\Psi(w)[x,z],$$

$$D^2\Psi(w)[x,z] = O(||z||).$$
(2.16)

Next, we assume that the formula (2.11) holds for all $n \leq k$, and we want to show that (2.11) holds for n = k + 1. For $z \in \mathbb{D}([0,1]; \mathbb{R}^d)$,

$$D^k h_{\varepsilon,\delta}(w+z)[x_1,...,x_k] - D^k h_{\varepsilon,\delta}(w)[x_1,...,x_k]$$

$$= \sum_{\pi \in \mathcal{P}_{k,2}} \mathbb{E} \left[h(\delta B + \delta \Theta) \left(e^{\Psi(w+z)} - e^{\Psi(w)} \right) \prod_{\mathfrak{b} \in \pi} D^{|\mathfrak{b}|} \Psi(w+z) [x_{\mathfrak{b}}] \right]$$
(2.17)

$$+\sum_{\pi\in\mathcal{P}_{k,2}}\mathbb{E}\left[h(\delta B+\delta\Theta)e^{\Psi(w)}\left(\left\{\prod_{\mathfrak{b}\in\pi}D^{|\mathfrak{b}|}\Psi(w+z)[x_{\mathfrak{b}}]\right\}-\prod_{\mathfrak{b}\in\pi}D^{|\mathfrak{b}|}\Psi(w)[x_{\mathfrak{b}}]\right)\right]. \tag{2.18}$$

Let us deal with the above two sums now.

(i) The sum in (2.17) can be rewritten as

$$\sum_{\pi \in \mathcal{P}_{1,0}} \mathbb{E} \left[h(\delta B + \delta \Theta) e^{\Psi(w)} D\Psi(w)[z] \prod_{\mathfrak{b} \in \pi} D^{|\mathfrak{b}|} \Psi(w)[x_{\mathfrak{b}}] \right] + \mathcal{O}(\|z\|^{2}), \tag{2.19}$$

which is a consequence of (2.15), (2.16), and the fact that $D\Psi(w)[z] = \mathbf{O}(\|z\|)$.

(ii) In (2.18), the expectation vanishes if $\pi \in \mathcal{P}_{k,2}$ is a partition with all blocks having exactly 2 elements, since $D^2\Psi(y)$ does not depend on y. Suppose now that the partition $\pi \in \mathcal{P}_{k,2}$ contains ℓ blocks with exactly one element, for some $\ell \in \{1,...,k\}$ (say the blocks $\{1\},...,\{\ell\}$). Then, it follows from (2.16) that

$$\left\{ \prod_{\mathfrak{b}\in\pi} D^{|\mathfrak{b}|} \Psi(w+z)[x_{\mathfrak{b}}] \right\} - \prod_{\mathfrak{b}\in\pi} D^{|\mathfrak{b}|} \Psi(w)[x_{\mathfrak{b}}]$$

$$= \left(\prod_{\mathfrak{b}\in\pi} \left(D^{2} \Psi(w)[x_{\mathfrak{b}}] \right)^{\mathbb{I}_{\{|\mathfrak{b}|=2\}}} \right) \left(\sum_{j=1}^{\ell} D^{2} \Psi(w)[z,x_{j}] \prod_{i\in\{1,\dots,\ell\}\setminus\{j\}} D\Psi(w)[x_{i}] \right)$$

$$+ \mathbf{O}(\|z\|^{2}).$$

As a consequence, we can write the second sum (2.18) as

$$\sum_{\pi \in \mathcal{P}_{h+1,2}'} \mathbb{E}\left[h(\delta B + \delta \Theta) e^{\Psi(w)} \prod_{\mathfrak{b} \in \pi} D^{|\mathfrak{b}|} \Psi(w)[x_{\mathfrak{b}}]\right] + \mathcal{O}(\|z\|^2),$$

where $\mathcal{P}'_{k+1,2}$ is the set of all partitions of $\{1, ..., k, k+1\}$ $(x_{k+1} = z)$ whose blocks have at most 2 elements, and such that k+1 (that corresponds to z) belongs to a block of size 2. Since the first term (2.19) accounts for the partitions where k+1 is in a block of size 1, we have just established formula (2.11) for n=k+1,

Hence by mathematical induction, the formula (2.11) holds true for all $n \ge 1$. In particular, we prove that the function $h_{\varepsilon,\delta}$ has infinitely many bounded Fréchet derivatives.

It remains to prove the bounds on the derivatives given in (1.41), (1.42), (1.43), (1.44), and (1.45). Since the random variable $e^{\Psi(w)}$ in (2.11) is not uniformly bounded in $L^p(\Omega)$ for p>1, which makes a direct proof of the bounds more awkward, we undo the change of measure, and work with an equivalent version of (2.11):

$$D^{n}h_{\varepsilon,\delta}(w)[x_{1},...,x_{n}] = \mathbb{E}\left[h(w_{\varepsilon} + \delta B + \delta \Theta)\left(\sum_{\pi \in \mathcal{P}_{n,2}} \prod_{\mathfrak{b} \in \pi} \widehat{D}^{|\mathfrak{b}|} \Psi(w)[x_{\mathfrak{b}}]\right)\right], \qquad (2.20)$$

where

$$\widehat{D}\Psi(w)[x] = \frac{1}{\delta} \int_0^T \nabla x_{\varepsilon}(s) dB(s) + \frac{1}{\delta} \langle \Theta, x_{\varepsilon}(0) \rangle,$$

$$\widehat{D}^2 \Psi(w)[x, y] = D^2 \Psi(w)[x, y] \quad \text{as in (2.10)}.$$
(2.21)

The equivalence between (2.20) and (2.11) essentially follows from the Cameron-Martin formula. However, there is a stochastic integral with respect to $B-\delta^{-1}w_\varepsilon$ in $D\Psi$ (which should become an integral with respect to B under the change of measure, leading to $\widehat{D}\Psi$), and so some additional justification may be desired. We provide a proof in the Appendix A. Let us now apply the formula (2.20) to establish the bounds (1.41), (1.42), (1.43), (1.44), and (1.45). Without loss of generality, we assume that $|h(y)| \leqslant 1$ for any $y \in \mathbb{D}$. Let us first prove the bound (1.41). Using (2.14), (2.5), and (2.21), we have

$$\mathbb{E}\left[|\widehat{D}\Psi(w)[x]|^2\right] = \frac{1}{\delta^2} \int_0^T |\nabla x_{\varepsilon}(s)|^2 ds + \frac{1}{\delta^2} |x_{\varepsilon}(0)|^2$$

$$\leqslant (T + \varepsilon^2) \frac{1}{\varepsilon^2 \delta^2} ||x||^2,$$
(2.22)

and

$$|\widehat{D}^2\Psi(w)[x,y]| \leqslant (T+\varepsilon^2) \frac{1}{\varepsilon^2 \delta^2} ||x|| \cdot ||y||. \tag{2.23}$$

Therefore, we can deduce from (2.22), (2.23), and (2.20) that

$$\sup_{w \in \mathbb{D}} \|D^k h_{\varepsilon,\delta}(w)\| \leqslant (T + \varepsilon^2)^{k/2} \frac{1}{\varepsilon^k \delta^k} \mathbb{E}[|G|^k] \times \operatorname{card}(\mathcal{P}_{k,2}). \tag{2.24}$$

Thus, the bound (1.41) is proved, where we can choose the constant C_k to be $\mathbb{E}[|G|^k] \times \operatorname{card}(\mathcal{P}_{k,2})$ with $G \sim \mathcal{N}(0,1)$, and hence

$$C_1 = \sqrt{2/\pi}$$
, and $C_2 = 3$. (2.25)

Next, we prove the bound (1.42). Using (2.24) directly yields that

$$\sup_{w \in \mathbb{D}} \|Dh_{\varepsilon,\delta}(w)\| \leqslant \frac{1}{\varepsilon \delta} \sqrt{T + \varepsilon^2}. \tag{2.26}$$

For k = 2,3, we can do better than simply applying (2.24). We first deduce from the

formula (2.20) with n = 2, and (2.21) that

$$D^{2}h_{\varepsilon,\delta}(w)[x,y] = \mathbb{E}\Big[h(w_{\varepsilon} + \delta B + \delta \Theta)\widehat{D}\Psi(w)[x]\widehat{D}\Psi(w)[y]\Big] \\ + \mathbb{E}\Big[h(w_{\varepsilon} + \delta B + \delta \Theta)\widehat{D}^{2}\Psi(w)[x,y]\Big] \\ = \delta^{-2}\mathbb{E}\Big[h(w_{\varepsilon} + \delta B + \delta \Theta)\left(\int_{0}^{T}\nabla x_{\varepsilon}(s)\,dB(s) + \langle \Theta, x_{\varepsilon}(0)\rangle\right) \\ \times \left(\int_{0}^{T}\nabla y_{\varepsilon}(s)\,dB(s) + \langle \Theta, y_{\varepsilon}(0)\rangle\right)\Big] \\ - \delta^{-2}\mathbb{E}\Big[h(w_{\varepsilon} + \delta B + \delta \Theta)\Big]\left(\int_{0}^{T}\langle \nabla x_{\varepsilon}(s), \nabla y_{\varepsilon}(s)\rangle ds + \langle x_{\varepsilon}(0), y_{\varepsilon}(0)\rangle\right) \\ = \delta^{-2}\operatorname{Cov}\Big[h(w_{\varepsilon} + \delta B + \delta \Theta), \left(\int_{0}^{T}\nabla x_{\varepsilon}(s)\,dB(s) + \langle \Theta, x_{\varepsilon}(0)\rangle\right) \\ \times \left(\int_{0}^{T}\nabla y_{\varepsilon}(s)\,dB(s) + \langle \Theta, y_{\varepsilon}(0)\rangle\right)\Big].$$

From this, and because $|h(y)| \leqslant 1$ for all $y \in \mathbb{D}$, it easily follows from Cauchy–Schwarz that

$$\left| D^{2} h_{\varepsilon,\delta}(w)[x,y] \right| \\
\leqslant \frac{1}{\delta^{2}} \sqrt{\operatorname{Var} \left[\left(\int_{0}^{T} \nabla x_{\varepsilon}(s) \, dB(s) + \langle \Theta, x_{\varepsilon}(0) \rangle \right) \left(\int_{0}^{T} \nabla y_{\varepsilon}(s) \, dB(s) + \langle \Theta, y_{\varepsilon}(0) \rangle \right) \right]}.$$
(2.28)

Now, for (U,V) bivariate normal with mean zero, variance 1 and correlation ρ , $Var(UV) = 1 + \rho^2 \leq 2$. Hence, and since, from (2.14) and (2.5), for any $z \in \mathbb{D}$, we have

$$\sigma_{z,\varepsilon,T}^{2} := \operatorname{Var}\left(\int_{0}^{T} \nabla z_{\varepsilon}(s) dB(s) + \langle \Theta, z_{\varepsilon}(0) \rangle\right)$$

$$= \int_{0}^{T} \left| \nabla z_{\varepsilon}(s) \right|^{2} ds + |z_{\varepsilon}(0)|^{2} \leqslant \left(\frac{T}{\varepsilon^{2}} + 1\right) ||z||^{2}, \qquad (2.29)$$

it follows that

$$\left|D^2 h_{\varepsilon,\delta}(w)[x,y]\right|^2 \leqslant \frac{2}{\delta^4} \sigma_{x,\varepsilon,T}^2 \sigma_{y,\varepsilon,T}^2 \leqslant \frac{2}{\varepsilon^4 \delta^4} \left(T + \varepsilon^2\right)^2 \|x\|^2 \|y\|^2,$$

and hence that

$$\sup_{w \in \mathbb{D}} \|D^2 h_{\varepsilon,\delta}(w)\| \leqslant \frac{\sqrt{2}}{\varepsilon^2 \delta^2} (T + \varepsilon^2). \tag{2.30}$$

For the Lipschitz constant of the second derivative, we claim that

$$\sup_{w \in \mathbb{D}} \frac{\|D^2 h_{\varepsilon,\delta}(w+v) - D^2 h_{\varepsilon,\delta}(w)\|}{\|v\|} \leqslant \sqrt{50/\pi} \frac{1}{\varepsilon^3 \delta^3} (T + \varepsilon^2)^{\frac{3}{2}}.$$
 (2.31)

Using the definition of the derivative, (2.20) (in which $\widehat{D}\Psi(w)$ does not depend on

w), (2.22), and (2.23), we have

$$\begin{split} &\left|D^{2}h_{\varepsilon,\delta}(w+x_{3})[x_{1},x_{2}]-D^{2}h_{\varepsilon,\delta}(w)[x_{1},x_{2}]\right| \\ &\leqslant \int_{0}^{1}\left|D^{3}h_{\varepsilon,\delta}(w+tx_{3})[x_{1},x_{2},x_{3}]\right|dt \\ &\leqslant \sup_{w\in\mathbb{D}}\left(\mathbb{E}\left[\sum_{i=1}^{3}\left|\widehat{D}\Psi(w)[x_{i}]\widehat{D}^{2}\Psi(w)\left[(x_{j})_{j\neq i}\right]\right|\right]+\mathbb{E}\left[\prod_{j=1}^{3}\left|\widehat{D}\Psi(w)[x_{j}]\right|\right]\right) \\ &\leqslant \frac{1}{\delta^{3}}\left(\frac{T}{\varepsilon^{2}}+1\right)^{\frac{3}{2}}\left(3\mathbb{E}[|G|]+\mathbb{E}[|G|^{3}]\right)\prod_{i=1}^{3}\|x_{i}\| \quad \text{with } G\sim\mathcal{N}(0,1) \\ &= \sqrt{50/\pi}\,\frac{1}{\delta^{3}}\left(\frac{T}{\varepsilon^{2}}+1\right)^{\frac{3}{2}}\prod_{i=1}^{3}\|x_{i}\|. \end{split}$$

Then, the claim (2.31) follows immediately. Therefore, the bound (1.42) on $||h_{\varepsilon,\delta}||_{M^0}$ follows from (1.2), (2.26), (2.30), and (2.31). Now to see (1.43), it is enough to apply the Cauchy–Schwarz inequality and (2.27) in almost the same way as in the calculations leading to (2.28).

Next, we show the bound (1.44), under the additional assumption that $||D^n h|| < \infty$. First, we note that the sum inside the expectation in (2.20)

$$\mathcal{T}_n := \sum_{\pi \in \mathcal{P}_{n,2}} \prod_{\mathfrak{b} \in \pi} \widehat{D}^{|\mathfrak{b}|} \Psi(w)[x_{\mathfrak{b}}]$$
 (2.33)

does not depend on w. We now show by induction that, for $0 \le r \le n$,

$$D^{k+r}h_{\varepsilon,\delta}(w)[x_1,\ldots,x_k,z_1,\ldots,z_r] = \mathbb{E}\Big[D^rh(w_\varepsilon+\delta B+\delta\Theta)[z_{1,\varepsilon},\ldots,z_{r,\varepsilon}]\mathcal{T}_k\Big], \quad (2.34)$$

where $z_{j,\varepsilon}=(z_j)_{\varepsilon}$ is defined according to (1.6), the case r=0 being just (2.20). Then, assuming that (2.34) is true for r,

$$D^{k+r+1}h_{\varepsilon,\delta}(w)[x_1,\ldots,x_k,z_1,\ldots,z_r,v]$$

$$= \frac{d}{dt}\Big|_{t=0}D^{k+r}h_{\varepsilon,\delta}(w+tv)[x_1,\ldots,x_k,z_1,\ldots,z_r]$$

$$= \frac{d}{dt}\Big|_{t=0}\mathbb{E}\Big[D^rh(w_{\varepsilon}+tv_{\varepsilon}+\delta B+\delta\Theta)[z_{1,\varepsilon},\ldots,z_{r,\varepsilon}]\mathcal{T}_k\Big].$$
(2.35)

For r < n, since $||D^n h|| < \infty$,

$$\sup_{y:||y||\leqslant 1} ||D^{r+1}h(w_{\varepsilon} + y + \delta B + \delta \Theta)||$$

is bounded by a polynomial of degree n-r-1 in $\delta \|B+\Theta\|$, and hence its product with $|\mathcal{T}_k|$ is integrable⁶, by Fernique's theorem (see [10, Theorem 2.8.5]). Hence, we deduce from the dominated convergence theorem that

$$\frac{d}{dt}\Big|_{t=0} \mathbb{E} \left[D^r h(w_{\varepsilon} + tv_{\varepsilon} + \delta B + \delta \Theta)[z_{1,\varepsilon}, \dots, z_{r,\varepsilon}] \mathcal{T}_k \right]
= \mathbb{E} \left[D^{r+1} h(w_{\varepsilon} + \delta B + \delta \Theta)[z_{1,\varepsilon}, \dots, z_{r,\varepsilon}, v_{\varepsilon}] \mathcal{T}_k \right],$$
(2.36)

⁶Fernique's theorem applied to the Gaussian process $B+\Theta$ yields exponential integrability of $\|B+\Theta\|$, while the term \mathcal{T}_k lives in the first two Wiener chaoses and thus admits finite moments of any order (see Section 2.8 of [26]). These two observations imply the integrability of $\delta \|B+\Theta\| \cdot |\mathcal{T}_k|$.

establishing (2.34) for r+1 also. The bound (1.44) follows from (2.34) with r=n, using (2.14) and (2.5), as in proving (2.24). Finally, we point out that the inequality (1.45) follows from (2.34) with k=r=1, (2.22), and the fact that $\widehat{D}\Psi(w)[x]$ is Gaussian:

$$\begin{aligned} \left| D^2 h_{\varepsilon,\delta}(w)[z,x] \right| &\leqslant \|Dh\| \|z\| \mathbb{E} \left| \widehat{D} \Psi(w)[x] \right| \\ &\leqslant \mathbb{E}[|G|] \frac{1}{\delta} \|Dh\| \|z\| \left(\int_0^T |\nabla x_{\varepsilon}(s)|^2 ds + |x_{\varepsilon}(0)|^2 \right)^{\frac{1}{2}}, \end{aligned}$$

with $G \sim \mathcal{N}(0,1)$, which concludes our proof.

Now we present the proof of Theorem 1.1.

Proof of Theorem 1.1. First note that, if $h \colon \mathbb{D} \to \mathbb{R}$ is the indicator of a measurable set and ε, δ are positive, then Lemma 1.11 and Remark 1.12 imply that $h_{\varepsilon,\delta} \in M^0_{\mathfrak{c}_1}$, with \mathfrak{c}_1 given in (1.9), and that

$$||h_{\varepsilon,\delta}||_{M^0} \leqslant C_0, \tag{2.37}$$

with $C_0 = C_0(\varepsilon, \delta)$ as in (1.11) and (1.12). Next, we upper and lower bound $\mathbb{P}(X \in K) - P(Z \in K)$ for K a measurable subset of \mathbb{D} . For any $\theta, \gamma > 0$, we have

$$\mathbb{P}(X \in K) \leqslant \mathbb{P}(X_{\varepsilon} + \delta B + \delta \Theta \in K^{\theta + \gamma}, ||X_{\varepsilon} + \delta B + \delta \Theta - X|| < \theta + \gamma)
+ \mathbb{P}(||X_{\varepsilon} + \delta B + \delta \Theta - X|| \ge \theta + \gamma)
\leqslant \mathbb{P}(X_{\varepsilon} + \delta B + \delta \Theta \in K^{\theta + \gamma}) - \mathbb{P}(Z_{\varepsilon} + \delta B + \delta \Theta \in K^{\theta + \gamma})
+ \mathbb{P}(||X_{\varepsilon} + \delta B + \delta \Theta - X|| \ge \theta + \gamma) + \mathbb{P}(Z_{\varepsilon} + \delta B + \delta \Theta \in K^{\theta + \gamma}).$$
(2.38)

The first term (2.38) is of the form $\mathbb{E}[h_{\varepsilon,\delta}(X)] - \mathbb{E}[h_{\varepsilon,\delta}(Z)]$ for h as above, and is thus upper bounded by $C_{\varepsilon,\delta,T}\kappa_1 + \sqrt{(1+\frac{\varepsilon}{2})(T+\varepsilon^2)}(\varepsilon\delta)^{-2}\kappa_2$. The first part of the second term (2.39) is upper bounded by

$$\begin{split} & \mathbb{P}(\|X_{\varepsilon} + \delta B + \delta \Theta - X\| \geqslant \theta + \gamma) \\ & \leqslant & \mathbb{P}(\|X_{\varepsilon} - X\| \geqslant \theta) + \mathbb{P}(\|\delta B + \delta \Theta\| \geqslant \gamma) \\ & \leqslant & \mathbb{P}(\|X_{\varepsilon} - X\| \geqslant \theta) + \mathbb{P}(\|\delta B\| \geqslant \gamma/2) + \mathbb{P}(|\delta \Theta| \geqslant \gamma/2) \\ & \leqslant & \mathbb{P}(\|X_{\varepsilon} - X\| \geqslant \theta) + 2de^{-\gamma^2/(8dT\delta^2)} + de^{-\gamma^2/(4d\delta^2)}; \end{split}$$

in the third inequality we have used the bound

$$\mathbb{P}(\|B\| \geqslant z) \leqslant \mathbb{P}\left(\bigcup_{i=1}^{d} \left\{ \|B^{(i)}\| \geqslant \frac{z}{\sqrt{d}} \right\} \right) \leqslant d\mathbb{P}\left(\|B^{(1)}\| \geqslant \frac{z}{\sqrt{d}}\right)
\leqslant 2d\mathbb{P}\left(\max_{0 \leqslant t \leqslant T} B^{(1)}(t) \geqslant zd^{-1/2}\right) \leqslant 4d\mathbb{P}\left(B^{(1)}(T) \geqslant zd^{-1/2}\right)
\leqslant 2d\exp\left(-\frac{z^2}{2dT}\right),$$

for any z>0, which follows from well known facts about Brownian motion. For the second term of (2.39), we have

$$\mathbb{P}(Z_{\varepsilon} + \delta B + \delta \Theta \in K^{\theta + \gamma})
\leqslant \mathbb{P}(\|Z_{\varepsilon} + \delta B + \delta \Theta - Z\| \geqslant \theta + \gamma) + \mathbb{P}(Z \in K^{2(\theta + \gamma)})
\leqslant \mathbb{P}(\|Z_{\varepsilon} - Z\| \geqslant \theta) + \mathbb{P}(\|\delta B + \delta \Theta\| \geqslant \gamma) + \mathbb{P}(Z \in K^{2(\theta + \gamma)})
\leqslant \mathbb{P}(\|Z_{\varepsilon} - Z\| \geqslant \theta) + \mathbb{P}(Z \in K^{2(\theta + \gamma)}) + 2de^{-\gamma^{2}/(8dT\delta^{2})} + de^{-\gamma^{2}/(4d\delta^{2})}.$$
(2.40)

Combining the last displays and using that $T \geqslant 1$, we find that

$$\mathbb{P}(X \in K) \leqslant C_0 \kappa_1 + \mathfrak{c}_1 \kappa_2 + \mathbb{P}(\|X_{\varepsilon} - X\| \geqslant \theta) + \mathbb{P}(\|Z_{\varepsilon} - Z\| \geqslant \theta) + \mathbb{P}(Z_{\varepsilon} - Z\| \geqslant \theta) + \mathbb{P}(Z_{\varepsilon} +$$

Subtracting $\mathbb{P}(Z \in K)$ from both sides gives an upper bound on $\mathbb{P}(X \in K) - \mathbb{P}(Z \in K)$ of the form (1.14), with $\mathbb{P}(Z \in K^{2(\theta+\gamma)} \setminus K)$ in place of $\mathbb{P}(Z \in K^{2(\theta+\gamma)} \setminus K^{-2(\theta+\gamma)})$. A lower bound of the same magnitude follows in analogous fashion.

Finally, suppose that $h\colon \mathbb{D}\to \mathbb{R}$ is bounded and Lipschitz with $\sup\{|h(w)|: w\in \mathbb{D}\}\leqslant 1$ and $\|Dh\|\leqslant 1$. Then for any $\varepsilon,\delta>0$, Lemma 1.11 and Remark 1.12 imply that $h_{\varepsilon,\delta}\in M^0_{\mathfrak{c}_2}$ with \mathfrak{c}_2 given as in (1.10), and we also have

$$\mathbb{E}[h(X) - h(Z)] = \mathbb{E}[h(X) - h(X_{\varepsilon} + \delta B + \delta \Theta)] + \mathbb{E}[h_{\varepsilon,\delta}(X) - h_{\varepsilon,\delta}(Z)] + \mathbb{E}[h(Z_{\varepsilon} + \delta B + \delta \Theta) - h(Z)].$$

The first expectation is bounded by $\mathbb{E}(\|X - X_{\varepsilon}\| + \delta \|B + \Theta\|)$, and the third by $\mathbb{E}(\|Z - Z_{\varepsilon}\| + \delta \|B + \Theta\|)$; the second is bounded by $\kappa_1 \|h_{\varepsilon,\delta}\|_{M^0} + \mathfrak{c}_2 \kappa_2$, by assumption (1.13). Now we claim that the following bounds hold when $\sup\{|h(w)| : w \in \mathbb{D}\} \leq 1$ and $\|Dh\| \leq 1$:

- (i) $||h_{\varepsilon,\delta}|| \leq 1$,
- (ii) $||Dh_{\varepsilon,\delta}|| \leq 1$,
- (iii) $||D^2 h_{\varepsilon,\delta}|| \leq (T + \varepsilon^2)^{\frac{1}{2}} (\varepsilon \delta)^{-1}$.

Claim (i) is trivial, and to verify claim (ii), we begin by writing

$$Dh_{\varepsilon,\delta}(w)[v] = \frac{d}{dt}\Big|_{t=0} h_{\varepsilon,\delta}(w+tv)$$

$$= \frac{d}{dt}\Big|_{t=0} \mathbb{E}\big[h(w_{\varepsilon}+tv_{\varepsilon}+\delta B+\delta \Theta)\big]$$

$$= \mathbb{E}\Big(Dh(w_{\varepsilon}+\delta B+\delta \Theta)[v_{\varepsilon}]\Big),$$

which follows from the same reasoning as in (2.35)-(2.36). Then, claim (ii) follows from $||Dh|| \le 1$ and $||v_{\varepsilon}|| \le ||v||$. Note that claim (iii) follows from (1.44).

Note that we can deduce from (2.32) and (1.44) that

$$\begin{split} & \left| D^{2}h_{\varepsilon,\delta}(w+x_{3})[x_{1},x_{2}] - D^{2}h_{\varepsilon,\delta}(w)[x_{1},x_{2}] \right| \\ & \leqslant \|D^{3}h_{\varepsilon,\delta}\| \cdot \prod_{j=1}^{3} \|x_{j}\| \leqslant \|Dh\|C_{2}(T+\varepsilon^{2})\varepsilon^{-2}\delta^{-2} \cdot \prod_{j=1}^{3} \|x_{j}\| \\ & \leqslant 3(T+\varepsilon^{2})\varepsilon^{-2}\delta^{-2} \cdot \prod_{j=1}^{3} \|x_{j}\|. \end{split}$$

See (2.25) for the choice of C_2 . Thus, if $\varepsilon, \delta \in (0,1)$, we see that

$$||h_{\varepsilon,\delta}||_{M^0} \leqslant 1 + 1 + (T+1)^{1/2} \varepsilon^{-1} \delta^{-1} + 3(T+1) \varepsilon^{-2} \delta^{-2}$$

 $\leqslant 2 + 4(T+1)(\varepsilon \delta)^{-2} \leqslant 4(T+2) \varepsilon^{-2} \delta^{-2}.$

Since $\mathbb{E}\|B_{[0,T]}\| \leqslant T^{1/2}\mathbb{E}\|B_{[0,1]}\|$ and $\mathbb{E}|\Theta| \leqslant \sqrt{d}$, the above bounds lead us to the desired estimate (1.15). Hence, the proof is completed.

The rest of this section is devoted to the proofs of Lemma 1.4 and Lemma 1.6.

Proof of Lemma 1.4. The proof uses the standard dyadic techniques from, for example, [9, Chapter 3]. Letting $\omega_x(\varepsilon)[0,T]$ be as in (1.17), we can bound

$$\mathbb{P}(\|Y_{\varepsilon} - Y\| \geqslant \sqrt{d}\lambda) \leqslant \mathbb{P}\left(\bigcup_{i=1}^{d} \left\{\|Y_{\varepsilon}^{(i)} - Y^{(i)}\| \geqslant \lambda\right\}\right)$$
$$\leqslant \sum_{i=1}^{d} \mathbb{P}(\omega_{Y^{(i)}}(\varepsilon)[0, T] \geqslant \lambda).$$

Thus it suffices to bound $\mathbb{P}(\omega_Y(\varepsilon)[0,T] \geqslant \lambda)$ for a one-dimensional process Y satisfying the assumption (1.21) of Lemma 1.4.

Fix $y \in \mathbb{D}([0,T];\mathbb{R})$ and $(s,\varepsilon) \in [0,T] \times (0,\infty)$, we set

$$x_{j,r} := x_{j,r}(s,\varepsilon) := s + j2^{-r}\varepsilon$$
, for $0 \le j \le 2^r$ and $1 \le r \le R$

and define $\delta_{jn}^* := \delta_{jn}^*(y)$ and $\delta_{jr} := \delta_{jr}(y, s, \varepsilon)$ by

$$\begin{split} \delta_{jn}^* &:= \sup_{j/n \leqslant v \leqslant (j+1)/n} |y(v) - y(jn^{-1})|, \quad 0 \leqslant j < nT; \\ \delta_{jr} &:= \min \left\{ |y(x_{j,r}) - y(x_{j,r} - 2^{-r}\varepsilon)|, |y(x_{j,r}) - y(x_{j,r} + 2^{-r}\varepsilon)| \right\}, \quad j \text{ odd}, 1 \leqslant j < 2^r, \end{split}$$

with $\delta_{jr} = 0$ if j is even (set y(v) := y(T) for v > T); note that, for j odd,

$$x_{j,r} - 2^{-r}\varepsilon = x_{\lfloor j/2 \rfloor, r-1}$$
 and $x_{j,r} + 2^{-r}\varepsilon = x_{\lfloor j/2 \rfloor + 1, r-1}$.

Then, defining $R := R_{n,\varepsilon} := \lceil \log_2(n\varepsilon) \rceil$, we first establish that, for $s \leqslant u \leqslant s + \varepsilon$,

$$|y(u) - y(s)| \le 3 \left\{ \left(\sum_{r=1}^{R} \max_{1 \le j < 2^r} \delta_{jr} \right) + 2 \max_{0 \le j < nT} \delta_{jn}^* \right\}.$$
 (2.42)

The argument to show (2.42) is based on the following two observations. First, the triangle inequality can be used to bound the *minimal change* in the value of y when going from an argument of the form $x_{j,r}$ to one of the form $x_{j',r-1}$, which is no more than $\max_{1 \le j < 2^r} \delta_{jr}$. Secondly, the change when going from any value in $[s, s + \varepsilon]$ to the next smaller value $s+j2^{-R}\varepsilon$ is bounded by $2\max_{0 \le j < nT} \delta_{jn}^*$.

As a result of these observations, for any $s \leqslant u \leqslant s + \varepsilon$, there is a path from u to $x_{j_0,0}$ of the form $(u,x_{j_R,R},x_{j_{R-1},R-1},\ldots,x_{j_1,1},x_{j_0,0})$, where $x_{j_0,0} \in \{s,s+\varepsilon\}$, along which the value of y changes in total by no more than

$$\mathcal{K} := \left(\sum_{r=1}^{R} \max_{1 \leqslant j < 2^r} \delta_{jr}\right) + 2 \max_{0 \leqslant j < nT} \delta_{jn}^*.$$

We call such a path $(u,x_{j_R,R},\ldots,x_{j_1,1},x_{j_0,0})$ admissible. Then, if J denotes the maximal value of j such that there is an admissible path from $x_{j,R}$ to s with $|y(x_{j,R})-y(s)|\leqslant \mathcal{K}$, it is immediate that $|y(x_{j,R})-y(s)|\leqslant 2\mathcal{K}$ for all $0\leqslant j\leqslant J$, because an admissible path from $x_{j,R}$ to $s+\varepsilon$ has to cross an admissible path from $x_{J,R}$ to s in this case and can be modified to follow the admissible path from $x_{J,R}$ to s thereafter. For each j>J, we can find an admissible path Γ_j from $x_{j,R}$ to $s+\varepsilon$.

• If Γ_j crosses the admissible path from $x_{J,R}$ to s, then from the triangle inequality it follows immediately that

$$|y(x_{j,R}) - y(s)| \leq 2\mathcal{K}.$$

• If Γ_j does not intersect with the admissible path from $x_{J,R}$ to s, we deduce from the triangle inequality that

$$|y(x_{j,R}) - y(s)| \leq |y(x_{j,R}) - y(s+\varepsilon)| + |y(x_{J+1,R}) - y(s+\varepsilon)| + |y(x_{J+1,R}) - y(x_{J,R})| + |y(x_{J,R}) - y(s)|$$

$$\leq 3 \left(\sum_{r=1}^{R} \max_{1 \leq j < 2^{r}} \delta_{jr} \right) + 2 \max_{0 \leq j < nT} \delta_{jn}^{*},$$

where we also used the bound $|y(x_{J,R}) - y(x_{J+1,R})| \leq 2 \max_{0 \leq j < nT} \delta_{in}^*$

This verifies (2.42) by noting that $|y(u)-y(s)| \leq |y(u)-y(x_{j,R})| + |y(x_{j,R})-y(s)|$, where $x_{j,R}$ is the smaller value next to u such that $|y(u)-y(x_{j,R})| \leq 2 \max_{0 \leq j < nT} \delta_{jn}^*$.

Now, returning to the process Y, note that

$$\{\omega_Y(\varepsilon)[0,T]\geqslant \lambda\} \ := \ \left\{ \sup_{0\leqslant s,t\leqslant T\colon |s-t|\leqslant \varepsilon} |Y(s)-Y(t)| \ \geqslant \ \lambda \right\} \subset \bigcup_{k=1}^{\lceil T/\varepsilon\rceil} A_k(\varepsilon,\lambda),$$

where

$$A_k(\varepsilon,\lambda) := \left\{ \sup_{(k-1)\varepsilon \leqslant u \leqslant k\varepsilon} |Y(u) - Y((k-1)\varepsilon)| \geqslant \lambda/3 \right\}.$$

Then, for $0 < \psi < 1$, because of (2.42) with $s = (k-1)\varepsilon$, we can write

$$A_k(\varepsilon,\lambda) \subset B(n,T,\lambda) \cup \bigcup_{r=1}^{R_{n,\varepsilon}} \bigcup_{j=1}^{2^r} A_{k,r,j,\varepsilon,\lambda},$$

where

$$A_{k,r,j,\varepsilon,\lambda} := \left\{ \delta_{jr}(Y,(k-1)\varepsilon,\varepsilon) \geqslant \lambda \psi^r (1-\psi)/9 \right\}$$

and

$$B(n,T,\lambda) := \bigcup_{j=1}^{\lceil nT \rceil} \left\{ 2\delta_{jn}^*(Y) \geqslant \lambda (1-\psi)/9 \right\},\,$$

for some $\psi \in (0,1)$ to be fixed later such that

$$\lambda/9 > \lambda(1-\psi)/9 + \sum_{r=1}^{R_{n,\varepsilon}} \lambda \psi^r (1-\psi)/9.$$

Computing probabilities using (1.21) gives

$$\mathbb{P}[A_{k,r,j,\varepsilon,\lambda}] \leqslant \frac{K(2^{-r+1}\varepsilon)^{\beta}}{(\lambda\psi^r(1-\psi)/9)^{\gamma}} = K\left(\frac{9}{1-\psi}\right)^{\gamma} \frac{(2\varepsilon)^{\beta}}{\lambda^{\gamma}} (2^{\beta}\psi^{\gamma})^{-r},$$

and

$$\mathbb{P}[B(n,T,\lambda)] \leq 2T\varphi_n(\lambda(1-\psi)/18).$$

Hence

$$\begin{split} \mathbb{P}[\omega_Y(\varepsilon)[0,T] \geqslant \lambda] \leqslant & \ \mathbb{P}[B(n,T,\lambda)] + \sum_{k=1}^{\lceil T/\varepsilon \rceil} \sum_{r=1}^{R_{n,\varepsilon}} \sum_{j=1}^{2^r} \mathbb{P}[A_{k,r,j,\varepsilon,\lambda}] \\ \leqslant & 2T\varphi_n(\lambda(1-\psi)/18) + KC(\psi,\beta,\gamma)\lceil T/\varepsilon \rceil \frac{\varepsilon^\beta}{\lambda^\gamma} \,, \end{split}$$

where $C(\psi, \beta, \gamma) < \infty$ provided that $\psi \in (0, 1)$ is chosen so that $2^{\beta - 1} \psi^{\gamma} > 1$. The result follows by choosing $\psi = 2^{-(\beta - 1)/(2\gamma)}$.

Proof of Lemma 1.6. Using [29, (1.12b)], for $1 \leq m_1 < m_2 \leq N$, we have

$$s_{m_1,m_2}^2 := \sum_{i=m_1+1}^{m_2} \sum_{j=m_1+1}^{m_2} |\text{Cov}(Y_i, Y_j)| \leqslant Kc_p^2(m_2 - m_1),$$

where

$$K := 2\left\{1 + 2\sum_{j \geqslant 1} (kj^{-b})^{(p-2)/p}\right\} < \infty.$$

It now follows from [29, Theorem 6.2], with r = 1 + (p-1)b/(p+b), that, for $0 \le s < t \le N/n$,

$$\mathbb{P}\left[\sup_{s\leqslant u\leqslant t} |X(u) - X(s)| \geqslant 4\lambda c_p\right] \\
\leqslant 4\left\{ \left(\frac{Kr(t-s)}{\lambda^2}\right)^{r/2} + \frac{\lceil n(t-s)\rceil}{\lambda\sqrt{n}} \left(\frac{rk^{1/b}}{\lambda\sqrt{n}}\right)^{r-1} \right\} \\
\leqslant C \frac{(t-s)^{r/2}}{\lambda^r}, \tag{2.43}$$

with the last line uniformly in $n(t-s) \ge 1/2$, for a suitable constant C := C(p,k,b). This in turn implies (1.26), by a standard argument.

A Equivalence between (2.20) and (2.11)

In this appendix, we prove the equivalence between (2.20) and (2.11).

Proof. First, recalling the definitions of the derivatives of Ψ in (2.9) and (2.10), we write

RHS of (2.11) =
$$\sum_{\pi \in \mathcal{P}_{n,2}} \mathbb{E} \left[h(\delta B + \delta \Theta) \prod_{\mathfrak{b} \in \pi} \left(D^{|\mathfrak{b}|} \Psi(w)[x_{\mathfrak{b}}] \right)^{\mathbb{I}[|\mathfrak{b}| = 1]} \right] \times \prod_{\mathfrak{b} \in \pi} \left(D^{|\mathfrak{b}|} \Psi(w)[x_{\mathfrak{b}}] \right)^{\mathbb{I}[|\mathfrak{b}| = 2]},$$
(A.1)

where we used the fact that $D^2\Psi(w)[x,y]$ is deterministic. Suppose $\mathfrak{b}=\{i_1,i_2,...,i_\ell\}$. Note that the Wiener integral is not pathwise defined, so it prevents us from applying the change of measure for $h(\delta B+\delta\Theta)D\Psi(w)[x]$. However, we can proceed by an approximation argument.

- (i) For each $j \in \{1,...,\ell\}$, one can find a sequence of uniformly bounded piecewise constant functions $\{F_{j,n}: n \geqslant 1\}$ such that $\|F_{j,n} \delta^{-1}\nabla(x_{i_j})_{\varepsilon}\| \to 0$ as n tends to infinity; denote the time instants at which the function $F_{j,n}$ jumps by $t_k^{j,n}$, $1 \leqslant k \leqslant N_{j,n}$.
- (ii) By dominated convergence and Ito isometry for Wiener integral, the following $L^p(\Omega)$ -convergence of Gaussians holds:

$$\sum_{k=1}^{N_{j,n}} F_{j,n}(t_k^{j,n}) \left[B\left(t_{k+1}^{j,n}\right) - B\left(t_k^{j,n}\right) \right] \xrightarrow[n \to \infty]{L^p(\Omega)} \frac{1}{\delta} \int_0^T \nabla(x_{i_j})_{\varepsilon}(s) dB(s)$$

for any finite $p \geqslant 1$.

Then, defining $w_{\varepsilon}^*(s) := w_{\varepsilon}(s) - w_{\varepsilon}(0)$ and writing $\Pi_t v = v(t)$ for the canonical evaluation map of $v \in C([0,T];\mathbb{R}^d)$ at time t, and recalling the definitions of $\Psi_B(w)$

and $\Psi_{\Theta}(w)$ in (2.7), the expectation in (A.1) can be rewritten (noting that $\Psi_{B}(w)=\Psi_{B}(w^{*})$) as

$$\begin{split} &\mathbb{E}\left[h(\delta B + \delta \Theta)e^{\Psi_B(w) + \Psi_{\Theta}(w)} \prod_{j=1}^{\ell} D\Psi(w)[x_{i_j}]\right] \\ &= \lim_{n \to \infty} \mathbb{E}\bigg\{h(\delta B + \delta \Theta)e^{\Psi_B(w^*) + \Psi_{\Theta}(w)} \prod_{j=1}^{\ell} \left[\left(\sum_{k=1}^{N_{j,n}} F_{j,n}(t_k^{j,n}) \times \left[\Pi_{t_{k+1}^{j,n}}(B - \delta^{-1}w_{\varepsilon}^*) - \Pi_{t_k^{j,n}}(B - \delta^{-1}w_{\varepsilon}^*)\right]\right) - \frac{1}{\delta} \left\langle \Theta - \delta^{-1}w_{\varepsilon}(0), (x_{i_j})_{\varepsilon}(0) \right\rangle\right]\bigg\} \\ &= \lim_{n \to \infty} \mathbb{E}\bigg\{h(w_{\varepsilon}^* + \delta B + \delta \Theta)e^{\Psi_{\Theta}(w)} \prod_{j=1}^{\ell} \left[\left(\sum_{k=1}^{N_{j,n}} F_{j,n}(t_k^{j,n}) \left[\Pi_{t_{k+1}^{j,n}} B - \Pi_{t_k^{j,n}} B\right]\right) - \frac{1}{\delta} \left\langle \Theta - \delta^{-1}w_{\varepsilon}(0), (x_{i_j})_{\varepsilon}(0) \right\rangle\right]\bigg\} \\ &= \mathbb{E}\bigg\{h(w_{\varepsilon}^* + \delta B + \delta \Theta)e^{\Psi_{\Theta}(w)} \prod_{j=1}^{\ell} \left[\frac{1}{\delta} \int_{0}^{T} \nabla(x_{i_j})_{\varepsilon}(s)dB(s) - \frac{1}{\delta} \left\langle \Theta - \delta^{-1}w_{\varepsilon}(0), (x_{i_j})_{\varepsilon}(0) \right\rangle\right]\bigg\} \\ &= \mathbb{E}\bigg\{h(w_{\varepsilon} + \delta B + \delta \Theta) \prod_{j=1}^{\ell} \widehat{D}\Psi(w)[x_{i_j}]\bigg\}, \end{split}$$

The first and third equalities in (A.2) follow from (ii), and the second follows by applying the Cameron–Martin change of measure formula for the Brownian motion B with respect to $B + \delta^{-1} w_{\varepsilon}^*$. The final equality in (A.2) follows from the same change of measure as in (2.4).

Therefore, we have verified the equivalence between (2.20) and (2.11).

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