

The Mumford Form and the Polyakov Measure in String Theory

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Abstract. An explicit formula is derived for the Mumford form on the moduli space of algebraic curves. According to the Belavin-Knizhnik theorem, this gives a formula for the Polyakov bosonic string measure.

Introduction

1. Polyakov's String

The quantum bosonic Polyakov string theory is defined by a path integral taken over random surfaces in the (Euclidean) d -dimensional space \mathbb{R}^d . The partition function of the closed string has a perturbation series expansion $Z = \sum_{g \geq 0} Z_g$:

$$Z_g = e^{\beta(2-2g)} \int e^{-J(x, \gamma)} D_x D_\gamma, \tag{1}$$

$$J(x, \gamma) = \int_N d^2z \sqrt{|\gamma|} \gamma^{ab} \partial_a x^\mu \partial_b x^\mu.$$

Here N is a fixed compact oriented surface of genus g (=“loop number”), z^a are local coordinates on it, $x = (x^\mu)$ is a map from N to \mathbb{R}^d , $\gamma_{ab} dz^a dz^b$ is a metric on N .

On the space of classical fields (x, γ) a gauge group $C \ltimes D$ acts, leaving the classical action $J(x, \gamma)$ invariant. It is a semidirect product of the diffeomorphism group D of N and of the conformal group C (= real-valued positive functions on N). Using this action, we can reduce (1) to a finite-dimensional integral in the following way. First, the integral over x 's is Gaussian, hence it equals $(\det' \Delta_{0\gamma})^{-d/2}$, where $\Delta_{0\gamma}$ is the Laplace operator on the functions on N , corresponding to γ , \det' its determinant without zero modes, regularized, say, by the formula $\det' \Delta_{0\gamma} = \exp(-\zeta'_\Delta(0))$. The remaining integration over the space $\text{Met } N$ of γ 's then reduces, via the Faddeev-Popov trick, to an integral over $\text{Met } N/C \ltimes D$, which is the same as the moduli space of Riemannian surfaces (or complex algebraic curves) of genus g . As is well known, this moduli space M_g is a complex variety of complex dimension 0 for $g=0$, 1 for $g=1$, $3g-3$ for $g \geq 2$.

Strictly speaking, this reduction is spoiled by the conformal anomaly: the regularization breaks the conformal invariance of the quantum effective action. But the anomaly cancels in the critical dimension $d = 26$ (cf. [2, 3]), and one has

$$Z_g = \text{const} \int_{M_g} dv \det' \Delta_{2\hat{\gamma}} (\det' \Delta_{0\hat{\gamma}})^{-13}, \quad g \geq 2, \tag{2}$$

where dv is the Petersson-Weil measure on the moduli space, $\Delta_{2\hat{\gamma}}$ is a Laplace operator on quadratic differentials, $\hat{\gamma}$ is a metric of constant curvature -1 in a given conformal class (for $g = 1$ the formula differs slightly).

2. Results

The main result of this paper (Theorem 6, Sect. 1) is an explicit formula for the Polyakov measure $d\pi_g$ on M_g , appearing in the right-hand side of (2). Here “explicit” means “written in terms of the complex geometry of the surface itself” and not in terms of its spectral invariants. Note that certain explicit formulae for the Laplace operator determinants were given by Ray and Singer [20]. In several papers, including [5, 21] they were applied to the string measure case. In this approach, $\log \det' \Delta$ is transformed into a sum over lengths of closed geodesics by means of the Selberg trace formula.

The formula of our paper looks very differently and is of a different nature since it utilizes the holomorphic invariants and not the metric ones.

One may consider this formula as a generalization to the genus $g \geq 2$ case of the well known genus 1 result:

$$\begin{aligned} Z_1 &= \int_{M_1} \frac{i}{2} d\tau \wedge d\bar{\tau} \frac{1}{(\text{Im} \tau)^4 |\Delta(\tau)|^2}, \\ \Delta(\tau) &= e^{2\pi i \tau} \prod_{n=1}^{\infty} (1 - e^{2\pi i n \tau})^{24}, \\ M_1 &= \{\tau \mid |\tau| \geq 1, |\text{Re} \tau| \leq \frac{1}{2}, \text{Im} \tau > 0\}. \end{aligned} \tag{3}$$

Observe that (3) may be expressed in terms of the theta function,

$$\theta(z, \tau) = \sum_{n=-\infty}^{\infty} e^{2\pi i n z + \pi i n^2 \tau},$$

since

$$2^8 \Delta(\tau) = e^{2\pi i \tau} (\theta(0, \tau) \theta(1/2, \tau) \theta(\tau/2, \tau))^8.$$

3. How to Compute Polyakov’s Measure

The computation presented here is based on the results of Mumford [8] and of Belavin and Knizhnik [7]. Here is a brief summary of their work.

The moduli space M_g is a complex algebraic variety. It has no convenient global coordinates. However, holomorphic 1-forms on M_g admit the following nice description: they correspond to the quadratic differentials on the complex curves, parametrized by the points of M_g . Let w_1, \dots, w_{3g-3} (here $g \geq 2$) be a basis of such differentials (depending holomorphically on parameters from M_g), and let

$\omega_1, \dots, \omega_g$ be a basis of differentials of the first kind. Mumford [8] shows, that there exists a unique, up to a constant multiple, holomorphic function F (depending on the choice of w_i, ω_j), such that

$$\mu_g = F \cdot \frac{w_1 \wedge \dots \wedge w_{3g-3}}{(\omega_1 \wedge \dots \wedge \omega_g)^{13}} \quad (4)$$

is a global section of the appropriate line bundle on M_g . This section is meromorphic at infinity (i.e., it is algebraic) and has a pole of order two; moreover, it has no zeroes on M_g . (Actually these properties are automatic for $g \geq 3$, and for $g=2$ they should be imposed additionally.)

We shall call μ_g a Mumford form.

Comparing this with (2), one is lead to believe that “13” in Mumford’s formula coincides with the half of the critical dimension. This was suggested by Yu. I. Manin and supported by certain evidence from the operator quantization approach.

In a remarkable paper [7] Belavin and Knizhnik pushed this much further. Namely, they proved that the Polyakov measure coincides with the modulus squared of the Mumford form. More precisely, let \bar{W}_i be a 1-form on M_g , corresponding to w_i , then one has

$$d\pi_g = \text{const} |F|^2 \cdot (-i)^g \frac{W_1 \wedge \bar{W}_1 \dots W_{3g-3} \wedge \bar{W}_{3g-3}}{|\det \int \omega_i \wedge \bar{\omega}_j|^{13}}. \quad (5)$$

Here bar means complex conjugate, and the integral is taken over the Riemann surface on which ω_i ’s are defined.

Hence to compute $d\pi_g$ it suffices to describe explicitly the Mumford form, a priori defined only by the implicit global conditions. This is the task we concentrate upon in what follows.

Note that in [14] $d\pi_g$ already was calculated in this way. This was done with the help of Faltings’ paper [9], which developed in turn the ideas of Arakelov, namely the Noether theorem for arithmetic surfaces. The formula presented below is shorter than the one in [14]. We hope also that its derivation clarifies somewhat the arguments of Faltings.

The expression for the curvature form of the determinant of the Laplace operator on j -differentials, found by Belavin and Knizhnik and directly implying (5), appears to be a particular case of the similar formula for the determinants of Dirac operators on arbitrary compact manifolds, due to Bismut and Freed [17] (this was pointed out in [18]). The Bismut-Freed result (generalizing the earlier theorem of Quillen) in the context of complex Hermitian geometry may be viewed as an exact Riemann-Roch-Grothendieck formula for c_1 , valid on the level of forms, and not on the cohomology level only. A similar formula for higher c_i remains to be found. We are sure it will help to understand both anomalies in physics and arithmetic geometry, in the spirit advocated in [19].

4. Superstrings

The Polyakov string has a fermion analog, described in [2, 4]. The critical dimension for the superstring is $d = 10$. A computation of an analogue of $d\pi_g$ on the

corresponding moduli superspaces was done in [6] by means of a supervariant of the Selberg trace formula. However, the relation with the right Polyakov measure seems not quite clear, due to two circumstances. a. The supersversion of the Belavin-Knizhnik theorem is not available at the moment. b. One does not know how to sum up a Mumford superform over different spin structures before taking the modulus squared. We discuss this question briefly in Sect. 3.2.

5. *The Contents of the Paper*

Our basic result is, after some preliminaries, stated in Sect. 1.6. Its proof is presented in Sect. 2. The third section contains some remarks and complements.

Finally, the appendix deals with the following problem. Mumford forms μ_g are defined a priori only modulo multiplication by a constant, depending on the genus. We shall explain how one can normalize all μ_g 's canonically and simultaneously. Conjecturally, one should have $e^{\beta(2-2g)}|\mu_g|^2 = d\pi_g$ with this normalization.

1. **Notation and Statement of Results**

1. *Calculus on Riemann Surface*

Let X be a compact complex Riemann surface of genus $g \geq 1$, or, equivalently, a smooth projective algebraic curve over \mathbb{C} . Marking of X is a choice of a symplectic basis $(a_1, \dots, a_g; b_1, \dots, b_g)$ in $H_1(X, \mathbb{Z})$. This means that $(a_i, a_j) = (b_i, b_j) = 0$, $(a_i, b_j) = \delta_{ij}$. One can construct such a basis making a classical system of cuts, which turns X into a polygon with pairwise identified sides (see e.g. [12]).

The space of holomorphic 1-forms (or differentials of the first kind) on X has the Riemann basis $\omega_1, \dots, \omega_g$ uniquely determined by the conditions $\int_{a_i} \omega_j = \delta_{ij}$, $i, j = 1, \dots, g$. Put $\int_{b_i} \omega_j = \tau_{ij}$, $\tau = (\tau_{ij})$. One has $\tau_{ij} = \tau_{ji}$, $\text{Im } \tau > 0$, hence τ lies in the Siegel upper halfspace H_g . The curve X together with its marking can be reconstructed from τ up to unique isomorphism.

Let $T \subset \mathbb{C}^g$ be a lattice, generated by columns of τ and \mathbb{Z}^g . The Jacobian of X is the complex torus $J = \mathbb{C}^g/T$. For each $P_0 \in X$, $z_0 \in J$ there is a standard embedding $\psi: X \rightarrow J$, mapping P_0 to z_0 , defined by the formula $\psi(P) = \left(z_0 + \int_{P_0}^P \omega \right) \text{ mod } T$, $\omega = (\omega_i)$. If z_i is the i^{th} coordinate on \mathbb{C}^g , the T -invariant form dz_i on \mathbb{C}^g may be viewed as a holomorphic (translation invariant) form on J . Any standard embedding $\psi: X \rightarrow J$ induces the same isomorphism between the space of such forms on J and the space of the differentials of the first kind on $X: \psi^*(dz_i) = \omega_i$.

The Jacobian J classifies the divisor classes of degree zero on X , or, equivalently, the isomorphism classes of invertible sheaves L on X with $c_1(L) = 0$. Namely, a sheaf $\mathcal{O}_X(\sum a_i P_i)$ corresponds to a point $\sum a_i \psi(P_i)$, where ψ is any standard embedding.

2. *Theta Function*

The function $\theta: \mathbb{C}^g \times H_g \rightarrow \mathbb{C}$ is defined by the classical series

$$\theta(z, \tau) = \sum_{m \in \mathbb{Z}^g} \exp 2\pi i(m^t z + 1/2 m^t \tau m).$$

It has a kind of periodic behavior:

$$\begin{aligned} \theta(z + m, \tau) &= \theta(z, \tau), \\ \theta(z + \tau n, \tau) &= \theta(z, \tau) \exp 2\pi i(-n^t z - 1/2m^t \tau n). \end{aligned}$$

In particular, the zero divisor of $\theta(z, \tau)$ (as a function of z ; τ being fixed) is T -invariant and hence comes from a divisor Θ on J .

For $\alpha = \varepsilon + \tau\delta \in \mathbb{C}^g$, put

$$\theta[\alpha](z, \tau) = \exp 2\pi i(\delta^t(z + \varepsilon) + 1/2\delta^t \tau \delta) \theta(z + \varepsilon + \tau\delta, \tau).$$

If $\varepsilon, \delta \in 1/2\mathbb{Z}^g$, then the class $\alpha \bmod T \in J$ is called theta characteristics. The parity of such α is $4\varepsilon\delta \bmod 2$. The function $\theta[\alpha](z, \tau)$ is even or odd with respect to z according to the parity of α . The theta characteristics are the second order points on J . Their total number is 4^g , of which there are $2^g(2^g - 1)$ even ones and $2^g(2^g + 1)$ odd ones.

3. Moduli of Curves and Moduli of Abelian Varieties

The complex tori, corresponding to the points $\tau \in H_g$, are algebraic. They are called abelian varieties. The Siegel halfspace H_g of dimension $g(g + 1)/2$ parametrizes the pairs $(A, (a_i, b_j))$, where A is a principally polarized abelian variety and (a_i, b_j) is a symplectic basis in $H_1(A, \mathbb{Z})$. Those pairs that come from (Jacobians of) curves from a closed analytic subvariety $N_g \subset H_g$ of dimension 1 for $g = 1, 3g - 3$ for $g \geq 2$. Hence for $g \geq 4$ one has $\dim N_g < \dim H_g$.

To the same curve there corresponds many points of N_g , since we can change the marking. Such a change transforms τ by an element

$$\begin{pmatrix} A & B \\ C & D \end{pmatrix} \in \text{Sp}(2g, \mathbb{Z}) : \tau \mapsto (A\tau + B)(C\tau + D)^{-1}.$$

This action of $\text{Sp}(2g, \mathbb{Z})$ on H_g, N_g is discrete. The space $\text{Sp}(2g, \mathbb{Z}) \backslash N_g = M_g$ is called the (coarse) moduli space of curves of genus g , and $\text{Sp}(2g, \mathbb{Z}) \backslash H_g = A_g$ is the (coarse) moduli space of (principally polarized) abelian varieties.

The functions $\tau_{ij}, i \geq j$, are global holomorphic coordinates on H_g . Locally they are coordinates at any smooth point of A_g (or a covering space of A_g). And, although the the functions τ_{ij} being restricted to N_g , become dependent (for $g \geq 4$), at any point of N_g corresponding to a nonhyperelliptic curve X_x , one may choose $3g - 3$ of τ_{ij} 's that form local coordinates at x on N_g . To be more precise, let k be the Kodaira-Spencer map identifying the quadratic differentials on X_x with the fiber of $\Omega^1 N_g$ at x . Then one has $k(\omega_a \omega_b) = (2\pi i)^{-1} d\tau_{ab}$. Below we shall describe the Mumford form in terms of $(\omega_a), (\omega_a \omega_b)$. Processing it into the Polyakov measure one should replace $\omega_a \omega_b$ by $(2\pi i)^{-1} d\tau_{ab}|_{N_g}$.

4. Theta Characteristics and Differentials of Half-Integral Weight

For any integer d denote by J_d the variety, parametrizing the isomorphism classes of the invertible sheaves of degree d on X . This is a principal homogeneous space over J . For almost all sheaves L of degree $g - 1$ one has $h^0(L) = h^1(L) = 0$. More precisely, the sheaves with $h^0(L) > 0$ form a divisor $\Theta_{g-1} \subset J_{g-1}$. According to the

Riemann theorem, there exists a unique isomorphism $J \rightarrow J_{g-1}$, compatible with J -action, which maps Θ to Θ_{g-1} . It identifies $0 \in J$ with the Riemann point $\Delta \in J_{g-1}$. One has $2\Delta = \text{class of } \Omega^1 \text{ in } J_{2g-2}$, where Ω^1 is the sheaf of 1-forms on X (see [12, 15]). Note that Δ depends on the marking of X . In this way the set of theta characteristics transforms into the set of square roots of Ω^1 . Therefore below we shall indiscriminately call “theta characteristics” a point in J , or in J_{g-1} (a half of Ω^1), or else a sheaf L_α together with an isomorphism $L_\alpha^{\otimes 2} \xrightarrow{\sim} \Omega^1$.

For any curve X there exists such an odd α (the “typical” odd one), that $h^0(L_\alpha) = 1$. We choose one and fix it. We put $\Omega^{1/2} = L_\alpha$ and $\Omega^i = L_\alpha^{\otimes 2i}$ for $i \in 1/2\mathbb{Z}$.

5. Distinguished Bases

Using $\Omega^{1/2}$ we shall define now certain bases in the spaces of differentials and quadratic differentials on X . We assume that $g \geq 2$ and that X is not hyperelliptic, if $g \geq 3$.

a) The basis $(\varphi_0, \varphi_1, \dots, \varphi_{g-1})$ in $\Omega^1(X)$. Put

$$\varphi_0 = \sum_{j=1}^g (\partial/\partial z_j \theta[\alpha])(0, \tau) \omega_j. \tag{1}$$

This differential has double zeroes on X . Assume that $\text{div } \varphi_0 = \sum_{i=1}^{g-1} 2P_i$ with pairwise different P_i (this is true for an open dense subset in N_g). We have $\varphi_0 = v_\alpha^2$, where v_α is a certain 1/2-differential.

Choose local parameters t_j at P_j in such a way that $\varphi_0 = t_j^2 dt_j$. Clearly, $t_j(P) = \left(3 \int_{P_j}^P \varphi_0 \right)^{1/3}$, so that t_j are defined up to multiplication by $\sqrt[3]{1}$.

Now the conditions

$$\varphi_j = (\delta_{jk} + a_{jk} t_k) dt_k + O(t_k^3 dt_k) \text{ near } P_k; j, k = 1, \dots, g-1 \tag{2}$$

define the differentials φ_j uniquely. Put moreover

$$B = (B_{ij}) = \left(\int_{a_j} \varphi_{i-1} \right), \quad i, j = 1, \dots, g.$$

Clearly, $(\varphi)^t = B(\omega)^t$.

b) The basis (w_1, \dots, w_{3g-3}) in $\Omega^2(X)$. For $g=2$ or for non-hyperelliptic X ($g \geq 3$) put

$$(w_1, \dots, w_{3g-3}) = (\varphi_0^2, \varphi_0 \varphi_1, \dots, \varphi_0 \varphi_{g-1}; \varphi_1^2, \dots, \varphi_{g-1}^2; a_{1,g-1}^{-1} \varphi_1 \varphi_{g-1}, \dots, a_{g-2,g-1}^{-1} \varphi_{g-2} \varphi_{g-1}).$$

The last group of these differentials is defined on an open dense subset of N_g , where all $a_{i,g-1}$ are invertible. Off this subset one should change this choice as explained in Sect. 2. The only important thing is that

$$w_{2g-1+j} = \delta_{jk} t_k (dt_k)^2 + O(t_k^2 (dt_k)^2) \text{ near } P_k, \quad j, k = 1, \dots, g-2,$$

and also a possibility to explicitly present w_i as bilinear combinations of $\omega_a \omega_b$ for computation of the map k .

We can now write down formulae for μ_g and $d\pi_g$.

6.

Theorem. a) For $g \geq 2$ the Mumford form is

$$\mu_g = \text{const} (\det B)^4 \frac{w_1 \wedge \dots \wedge w_{3g-3}}{(\varphi_0 \wedge \dots \wedge \varphi_g)^{13}}.$$

b) In the same conditions the Polyakov measure is

$$d\pi_g = \text{const} |\det B|^{-18} (\det \text{Im} \tau)^{-13} W_1 \wedge \bar{W}_1 \wedge \dots \wedge W_{3g-3} \wedge \bar{W}_{3g-3},$$

where $W_i = k(w_i)$, $k(\omega_a \omega_b) = (2\pi i)^{-1} d\tau_{ab}$.

2. Proofs

1. $\det R\pi_*$ formalism

Let $\pi : X \rightarrow S$ be an algebraic family of projective varieties X_s , parametrized by points $s \in S$, or, as an algebraic geometer would say, just a projective flat morphism. Consider an (algebraic coherent) sheaf L on X , flat over S ; roughly speaking, this is a family of sheaves L_s on the fibers of π . If for a certain i the dimensions of the cohomology groups $H^i(X_s, L_s)$ do not depend on s , then they are fibers of the higher direct image sheaf $R^i\pi_*L$, and this sheaf is locally free. If this holds for all i , we may define a “multiplicative Euler characteristic”

$$d(L) := \bigotimes_i (\det R^i\pi_*L)^{(-1)^i} = \det R\pi_*L,$$

which is an invertible sheaf on S .

Knudsen and Mumford in [10] have shown how to define $d(L)$ with nice properties for any L flat over S , without assuming that $\dim H^i(X_s, L_s)$ does not jump. To be more precise, they proved the following result.

2.

Proposition. For any family of projective varieties $\pi : X \rightarrow S$, any flat sheaf L on X and any isomorphism of sheaves $f : L \rightarrow L'$ one can construct an invertible sheaf $d(L)$ on S and an isomorphism $d(f) : d(L) \rightarrow d(L')$ in such a way that d becomes a functor with the following properties. (Below equalities mean canonical isomorphisms.)

a) $d(L) = \det R\pi_*L$, if all $R^i\pi_*L$ are locally free.

b) $d(L)$ is compatible with base change (= change of parameter space S).

c) Let $E = (E^i, d^i)$ be a finite complex of locally free sheaves on S , whose cohomology is $R^i\pi_*L$ universally (i.e. after any base change). (See [13] for an explanation of this Grothendieck’s construction). Then $d(L) = \bigotimes_i (\det E^i)^{(-1)^i}$.

d) For any exact triple $0 \rightarrow L' \xrightarrow{i} L \xrightarrow{j} L'' \rightarrow 0$ one has a canonical isomorphism $d(L) = d(L') \otimes d(L'')$, compatible with exact triples of exact triples and base change.

Note that if $a : L \rightarrow L$ is multiplication by $a \in \mathbb{C}^*$, then $d(a)$ is multiplication by $a^{\chi(L)}$, where $\chi(L) = \sum (-1)^i \text{rk} R^i\pi_*L$. This explains the name “multiplicative Euler characteristics.”

We refer to [10] for further details. In concrete computations below we shall not use much more than the following particular case. Assume that $R^i\pi_*L=0$ for $i \geq 1$ and let $l=(l_1, \dots, l_a)$ denote some free generators of $R^0\pi_*L$. Then $d(L)$ is freely generated by

$$d(l)=l_1 \wedge \dots \wedge l_a \in \det R^0\pi_*L.$$

If the same holds for the terms L, L', L'' of an exact triple, as in d) above, and if the bases are chosen in such a way that

$$l'=(l'_1, \dots, l'_a), \quad l=(i(l'_1, \dots, l'_a); l_{a+1}, \dots, l_b), \quad l''=j(l_{a+1}, \dots, l_b),$$

then, under the canonical isomorphism $d(L)=d(L') \otimes d(L'')$ we have $d(l)=d(l') \otimes d(l'')$.

3. The Sheaves λ_i

Now let $\pi : X \rightarrow S$ be a flat family of smooth projective curves, $g = \text{genus}$, $\Omega = \Omega^1 X/S$ the sheaf of relative 1-forms. Put $\lambda_i = d(\Omega^{\otimes i})$. We have $\lambda_i = \lambda_{1-i}$ in a canonical way [since, by Serre's duality, $d(L) = d(L^{-1} \otimes \Omega)$ for any invertible L].

The sheaves λ_i play a crucial role in the Polyakov string measure theory due to the following facts.

a) Mumford's theorem [8]: there exists a universal isomorphism $\lambda_{i+1} = \lambda_1^{6i^2 + 6i + 1}$.

This means that we have such an isomorphism for any family of curves, and we can normalize them in a way compatible with base changes. Such a universal isomorphism is unique, up to multiplication by a constant, depending on g only, for $g \geq 3$ (for $g = 2$ the uniqueness also holds if certain assumptions on the behavior at infinity are added).

The uniqueness for $g \geq 3$ follows from the fact that every holomorphic function on M_g is constant. To see this, consider the closure of M_g in the Satake compactification of A_g . A holomorphic function can be extended from M_g to this closure by Hartogs' theorem, since at infinity lies a subset of codimension ≥ 2 . But the closure is compact, hence a holomorphic function on it is constant.

In the appendix we describe a canonical normalization for all g .

b) Theorem on modular families: if $\pi : X \rightarrow S$ is a locally universal family, then the Kodaira-Spencer map $R^0\pi_*\Omega^{\otimes 2}X/S \rightarrow \Omega^1S$ is an isomorphism. Passing to the determinants we get $\lambda_2 = \Omega^{3g-3}S$.

The combination of a) for $i=1$ and b) gives us a universal section $\mu_g \in \Omega^{3g-3}S \otimes \lambda_1^{-13}$, called earlier the Mumford form.

c) The Belavin-Knizhnik theorem: Polyakov's measure equals $\text{const}|\mu_g|^2$ in the sense explained in the Introduction.

Below we shall reprove the Mumford theorem by a method that does not use the Riemann-Roch-Grothendieck global type arguments, and allows us to trace out the behaviour of convenient generators in λ_i .

Essentially this type of argument can be found in the Faltings paper [9].

Before proceeding further we need one more algebraic-geometrical construction.

4. The Sheaves $\langle L, M \rangle$

Let X be a smooth projective curve; f, g meromorphic functions on it with disjoint divisors. Put

$$\langle f, g \rangle = f(\operatorname{div} g) = \prod_{x \in X} f(x)^{v_x(g)},$$

where $v_x(g)$ is the order of g at a point x . According to A. Weil, $\langle f, g \rangle = \langle g, f \rangle$: this generalizes the classical symmetry of the projective cross-ratio [look at the case $X = P^1$, $f = (z-a)(z-b)^{-1}$, $g = (z-b)(z-c)^{-1}$].

Assume now, that L, M are invertible sheaves on X , and s, t are their meromorphic sections with disjoint divisors. We can still define $\langle s, t \rangle = \prod_x s(x)^{v_x(t)}$ as an element of one dimensional vector space $\langle L, M \rangle_{s,t} = \bigotimes_x L_x^{\otimes v_x(t)}$, instead of the base field of complex numbers. But it appears, essentially due to the Weil symmetry, that these vector spaces admit a lot of canonical identifications. In particular, for a different couple of sections s', t' of L, M one has a canonical isomorphism $\langle L, M \rangle_{s,t} = \langle L, M \rangle_{s',t'}$. Hence we may omit the index s, t and deal with $\langle L, M \rangle$ depending on L, M only. If X, L, M depend on parameters S , then L, M form a line bundle or an invertible sheaf on S .

This formalism was developed by Deligne in [11]; here is a brief summary.

5.

Proposition. *Let $\pi: X \rightarrow S$ be a flat family of smooth projective curves. Then for each pair of invertible sheaves L, M on X and each pair of isomorphisms $\varphi: L \rightarrow L', \psi: M \rightarrow M'$, one can construct an invertible sheaf $\langle L, M \rangle$ on S and an isomorphism $\langle \varphi, \psi \rangle: \langle L, M \rangle \rightarrow \langle L', M' \rangle$ with the following properties.*

a) *This construction is a bimultiplicative symmetric bifunctor, i.e. there are natural identifications*

$$\begin{aligned} \langle L, \mathcal{O}_X \rangle &= \mathcal{O}_S, & \langle L_1 \otimes L_2, M \rangle &= \langle L_1, M \rangle \otimes \langle L_2, M \rangle, \\ \langle L, M \rangle &= \langle M, L \rangle, & \langle L, M^{-1} \rangle &= \langle L, M \rangle^{-1}. \end{aligned}$$

b) *For each pair of meromorphic sections s of L, t of M with disjoint divisors flat over S , an invertible section $\langle s, t \rangle$ of $\langle L, M \rangle$ can be defined in such a way that with respect to the identifications in a) we have*

$$\begin{aligned} \langle s, 1 \rangle &= 1, & \langle s_1 \otimes s_2, t \rangle &= \langle s_1, t \rangle \otimes \langle s_2, t \rangle, \\ \langle s, t \rangle &= (-1)^{\deg L \deg M} \langle t, s \rangle, & \langle s, t^{-1} \rangle &= \langle s, t \rangle^{-1}. \end{aligned}$$

Moreover, $\langle s, f \rangle = f(\operatorname{div} s)$, if f is a meromorphic function.

c) *Let $M = 0_X(D)$, where D is a relative positive divisor with structure sheaf 0_D , locally free over S . Then*

$$\begin{aligned} \langle L, 0_X(D) \rangle &= \det_{0_S}(L \otimes 0_D) \otimes (\det_{0_S} 0_D)^{-1} = d(L \otimes 0_D) \otimes d(0_D)^{-1}, \\ \langle s, t_D \rangle &= \text{determinant of the } 0_S\text{-morphism } 0_D \rightarrow L \otimes 0_D, \\ &\text{sending } 1 \text{ to } s \otimes 1. \end{aligned}$$

Here t_D is a canonical section of $0_X(D)$, equation of D .

This data is compatible with arbitrary base change and is determined in a unique way, up to a unique isomorphism.

A relation between $d(L)$ and $\langle L, M \rangle$ is established by following Deligne's result:

6.

Lemma. *There is a canonical isomorphism*

$$\langle L, M \rangle = d(L \otimes M) \otimes d(0_X) \otimes d(L)^{-1} \otimes d(M)^{-1}.$$

The essence of this lemma is that the functor d behaves in a (non-homogeneous) quadratic way with respect to the tensor product, and \langle, \rangle is the associated bimultiplicative functor.

For our purposes we need an explicit construction of the last isomorphism. Take $M = 0_X(-D)$. Then the exact triples

$$\begin{aligned} 0 \rightarrow M \xrightarrow{t_D} 0_X \rightarrow 0_D \rightarrow 0, \\ 0 \rightarrow L \otimes M \rightarrow L \rightarrow L \otimes 0_D \rightarrow 0 \end{aligned}$$

together with Proposition 2d give

$$\begin{aligned} d(0_D) &= d(0_X) \otimes d(M)^{-1}, \\ d(L \otimes 0_D) &= d(L) \otimes d(L \otimes M)^{-1}. \end{aligned}$$

Hence, by Proposition 5c we get

$$\begin{aligned} \langle L, M \rangle &= \langle L, M^{-1} \rangle^{-1} = d(0_D) \otimes d(L \otimes 0_D)^{-1} \\ &= d(L \otimes M) \otimes d(0_X) \otimes d(L)^{-1} \otimes d(M)^{-1}. \end{aligned}$$

7. Proof of Mumford's Theorem

We shall proceed in three steps.

a)
$$\lambda_{i+1} = \lambda_1 \langle \Omega, \Omega \rangle^{i(i+1)/2}.$$

In fact, according to Lemma 6 and using $d(0_X) = \lambda_1$, we have

$$\langle \Omega, \Omega \rangle^i = \langle \Omega^i, \Omega \rangle = d(\Omega^{i+1})d(0_X)d(\Omega^i)^{-1}d(\Omega)^{-1} = \lambda_{i+1}\lambda_i^{-1}.$$

Now induction by i shows what we want. (From now on we sometimes omit \otimes in notation.)

b) Assume that on the family $\pi : X \rightarrow S$ a relative theta characteristic is given, utilizing which we define $\lambda_i = d(\Omega^{1/2 \otimes 2i})$ for half-integral i 's. Then

$$\langle \Omega, \Omega \rangle = \lambda_1^8 \lambda_{1/2}^{-8}.$$

In fact,

$$\langle \Omega, \Omega \rangle = \langle \Omega^{1/2}, \Omega^{1/2} \rangle^4$$

and, by Lemma 6,

$$\langle \Omega^{1/2}, \Omega^{1/2} \rangle = d(\Omega)d(0_X)d(\Omega^{1/2})^{-2} = \lambda_1^2 \lambda_{1/2}^{-2}.$$

c) Under the same assumptions, $\lambda_1^4 \lambda_{1/2}^8 = 0_S$. Unfortunately, we could not find a proof local by S and are bound to reproduce a global and analytic argument due to Faltings.¹ It consists in a reinterpretation of λ_1 and $\lambda_{1/2}$ in terms of Jacobian and in the subsequent proof of the corresponding fact for a universal family of all abelian varieties.

To do the first reduction, denote by $\Theta_{g-1} \subset J_{g-1}$ the relative theta divisor of the family and let $\alpha: S \rightarrow J_{g-1}$ be the relative theta characteristics, corresponding to $\Omega^{1/2}$. Finally, let $e: S \rightarrow J$ be the identity section. Then

$$\lambda_{1/2} = \alpha^* 0(-\Theta_{g-1}), \quad \lambda_1 = e^*(\Omega^g J/S).$$

For the second step recall a classical result on the behaviour of $\theta(z, \tau)$ under the simultaneous action of $\text{Sp}(2g, \mathbb{Z})$ upon z and τ . The group $\text{Sp}(2g, \mathbb{Z})$ consists of integral matrices $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ conserving the form $a(x_1, x_2; y_1, y_2) = x_1^t y_2 - x_2^t y_1$; $x_i, y_j \in \mathbb{Z}^g$. Let $\Gamma_{1,2}$ be the subgroup, conserving also $x_1^t x_2 \pmod{2}$ (this means that the diagonal elements of $A^t C, B^t D$ are even).

Then for all $T = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in \Gamma_{1,2}$ one has

$$\begin{aligned} &\theta(((C\tau + D)^t)^{-1} z, (A\tau + B)(C\tau + D)^{-1}) \\ &= \zeta \det(C\tau + D)^{1/2} \exp(iz^t(C\tau + D)^{-1} Cz) \theta(z, \tau), \end{aligned}$$

where ζ is a 8th root of unity, depending on T .

The proof, given in [12], consists of two steps. First, one checks this relation for a simple generator system of $\Gamma_{1,2}$; to do this, one needs only periodicity and Poisson formula. Second, one establishes a group property of the transformation formula.

Namely, the transformation formula is equivalent to the $\Gamma_{1,2}$ -invariance of certain expressions involving theta constants, in particular

$$\exp(2\pi i n^t \tau n) \theta^8(z - 1/2(m + \tau n), \tau) (dz_1 \wedge \dots \wedge dz_g)^4|_{z=0}. \tag{3}$$

This invariance can be restated in geometric terms.

Let τ vary in the Siegel half-space H_g . Instead of $A_g = \text{Sp}(2g, \mathbb{Z}) \backslash H_g$ consider a space A'_g , parametrizing pairs (abelian variety, degree one symmetric ample line bundle). Every such pair essentially is $(A, \mathcal{O}(-\Theta_\alpha))$, where α is a point of second order on A . Let $\mathcal{A} \rightarrow A'_g$ be the universal family of such pairs, $e: A'_g \rightarrow \mathcal{A}$ its identity section. Then the expression (3) defines a canonical invertible section of the sheaf

$$e^*(\mathcal{O}(-\Theta_\alpha)^8 \otimes (\Omega^g \mathcal{A}/A'_g)^4),$$

i.e. an isomorphism of this sheaf with $0_{A'_g}$.

Restricting this isomorphism to M'_g , parametrizing pairs $(J, \mathcal{O}(-\Theta_\alpha))$, we get finally $\lambda_{1/2}^8 \lambda_1^4 = 0_{M'_g}$.

d) End of proof.

Putting together a), b), c), we obtain

$$\lambda_{i+1} = \lambda_1 \langle \Omega, \Omega \rangle^{i(i+1)/2} = \lambda_1 (\lambda_1^2)^{i(i+1)/2} = \lambda_1^{6i^2 + 6i + 1}.$$

¹ A similar argument may also be found in [7]

The independence of this isomorphism of the choice of $\Omega^{1/2}$ follows for $g \geq 3$ from global topological considerations. For a precise statement see the appendix.

8. *Distinguished Bases*

The only advantage of this proof with respect to Mumford's original one (Riemann-Roch-Grothendieck plus global topological arguments) is that it gives rise to explicit formulae. To derive them, we shall now construct distinguished bases in the sheaves $R^k \pi_* \Omega^{i/2}$, hence in $\lambda_{i/2}$, compatible with various canonical identifications. In this subsection we deal with the family $\pi : X \rightarrow M_g^-$, where M_g^- is a subspace of M_g , parametrizing pairs (curve, odd theta characteristics L_α with $h^0(L_\alpha) = 1$). The base M_g^- projects onto M_g ; $\Omega^{1/2}$ is, by definition, L_α .

a) A basis in $\lambda_{1/2}$. The section $v_\alpha = \varphi_0^{1/2}$, defined by (1), Sect. 1, generates $\pi_* \Omega^{1/2}$. Serre's duality identifies $(R^1 \pi_* \Omega^{1/2})^{-1}$ with $\pi_* \Omega^{1/2}$. Hence $\lambda_{1/2} = (\pi_* \Omega^{1/2})^2$ acquires a generator $d_{1/2} = v_\alpha^2$.

b) A basis in λ_1 . Choose a basis $(\varphi_0, \dots, \varphi_{g-1})$ in $\pi_* \Omega^1$ according to (2), Sect. 1. Identify $R^1 \pi_* \Omega^1$ with $0_{M_g^-}$ by the Serre duality. The distinguished generator of λ_1 is $d_1 = \varphi_0 \wedge \dots \wedge \varphi_{g-1}$.

Recall that B is a matrix, transforming ω into φ (Sect. 1, N° . 5).

We assert now that the isomorphism $0_{M_g^-} = \lambda_{1/2}^8 \lambda_1^4$ maps the unit section of $0_{M_g^-}$ to

$$(v_\alpha^2)^8 (\omega_1 \wedge \dots \wedge \omega_g)^4 = d_{1/2}^8 d_1^4 (\det B)^{-4}. \tag{4}$$

To see this, denote by $p : X \times J_{g-1} \rightarrow J_{g-1}$ the projection, by L the universal sheaf of degree $g-1$ on $X \times J_{g-1}$. Then $d(L)$, constructed with respect to p , is canonically isomorphic to $O(-\Theta_{g-1})$. In fact, on the complement $J_{g-1} \setminus \Theta_{g-1}$ we have $d(L) = 0_J$, and the unit section t of this sheaf has a pole of the first order at Θ_{g-1} . At a simple point $\alpha \in \Theta_{g-1}$ this isomorphism is given by the formula $t_\alpha \mapsto (ss')_\alpha$, where $s \in H^0(X, L_\alpha)$, $s' \in H^1(X, L_\alpha)^* = H^0(X, \Omega^1 \otimes L^{-1})$ are such that $(ss')_\alpha = (dt)_\alpha$. In particular, if α is a theta characteristic, t_α goes into $(\sqrt{dt_\alpha})^2$. But this is precisely v_α^2 from (1), Sect. 1.

c) A basis in $\lambda_{3/2}$. The sheaf $\pi_* \Omega^{3/2}$ has the distinguished basis

$$(v_\alpha \varphi_0, v_\alpha \varphi_1, \dots, v_\alpha \varphi_{g-1}; \psi_1, \dots, \psi_{g-2}),$$

where ψ_j fulfill the conditions

$$\psi_j = \delta_{jk} (dt_k)^{3/2} + O(t_k (dt_k)^{3/2}) \text{ near } P_k, \tag{5}$$

$j, k = 1, \dots, g-2$. Observe that the principal part of ψ_j near P_{g-1} is determined from the equation $\sum_1^{g-1} \text{res}_{P_k} (v_\alpha^{-1} \psi_j) = 0$. Clearly (5) determines ψ_j up to differentials vanishing at all P_k , but one normalizes ψ_j in a unique way, as in (2), Sect. 1, if one demands the vanishing of the term $v_\alpha^{3/2} = t_k^3 (dt_k)^{3/2}$ in the expansion of ψ_j near P_k . The other choices below can be normalized similarly.

The distinguished generator of $\lambda_{3/2}$ is

$$d_{3/2} = v_\alpha \varphi_0 \wedge v_\alpha \varphi_1 \wedge \dots \wedge \psi_{g-2}.$$

d) A basis in $\lambda_{(i+1)/2}$, $i \geq 3$. Since one has $R^1 \pi_* \Omega^{i/2} = 0$ for $i \geq 3$, the above game may be continued further inductively. One declares that the distinguished basis in $\pi_* \Omega^{(i+1)/2}$ is one in $\pi_* \Omega^{i/2}$, multiplied by v_α , plus the differentials with principal parts $\delta_{jk} (dt_k)^{(i+1)/2}$ at P_k , $j, k = 1, \dots, g-1$.

The distinguished generator of $\lambda_{(i+1)/2}$ is

$$d_{(i+1)/2} = \text{the wedge product of the elements} \\ \text{of the distinguished basis of } \pi_{\ast} \Omega^{(i+1)/2}.$$

e) A basis in $\langle \Omega^{1/2}, \Omega^{1/2} \rangle$. Put $D = \sum_1^{g-1} P_k$. According to Proposition 5c, we have $\langle \Omega^{1/2}, O(D) \rangle = \bigotimes_1^{g-1} \Omega_{P_i}^{1/2}$, and $\langle v_{\alpha}, 1 \rangle$ under this isomorphism maps into $\bigotimes_1^{g-1} v_{P_i}$, where v_{P_i} is $v_{\alpha} \bmod t_i v$, i.e. $t_i dt_i^{1/2} \bmod t_i^2$. The isomorphism $O(D) \xrightarrow{v_{\alpha}} \Omega^{1/2}$, $1 \mapsto v_{\alpha}$, sends this class into the distinguished generator of $\langle \Omega^{1/2}, \Omega^{1/2} \rangle$, which we denote

$$\langle \text{id}, v_{\alpha} \rangle \left(\bigotimes_1^{g-1} v_{P_i} \right) = \prod_1^{g-1} \langle v_{P_i}, v \rangle = v.$$

Now the formal properties of the functors d and \langle , \rangle imply, that

$$d_{i+1} = d_i v^{4i} \text{ via identification } \lambda_{i+1} = \lambda_i \langle \Omega, \Omega \rangle^i \\ (\mathbb{N}^{\circ}. 7a) \tag{6}$$

$$d_1^2 = d_{1/2}^2 v \text{ via identification } \lambda_1^2 = \lambda_{1/2}^2 \langle \Omega^{1/2}, \Omega^{1/2} \rangle \\ (\mathbb{N}^{\circ}. 7b) \tag{7}$$

9. Proof of Theorem 6, Sect. 1

Putting together (6), (7), and (4), we get formally

$$d_2 = d_1 v^4 = d_1^9 d_{1/2}^{-8} = d_1^{13} (\det B)^{-4},$$

which implies the statement a) of the theorem. To deduce b), note that

$$\det \left(\frac{i}{2} \int_X \omega_a \wedge \bar{\omega}_b \right) = \det \text{Im } \tau,$$

hence

$$\det \left(\frac{i}{2} \int_X \varphi_a \wedge \bar{\varphi}_b \right) = \det |B|^2 \det \text{Im } \tau.$$

3. Remarks and Complements

1. Admissible Metrics

The formula for the Polyakov measure, given in [14], was derived by almost the same method as the one above. The difference between two formulae owes partly to a different choice of distinguished bases, but mainly to the fact in [14] the machine of special hermitian metrics on invertible sheaves was systematically used. Since it may have a wider use in various contexts, we add here some hints on the derivation of the formula in [14].

Let $(L, | |)$ be an invertible sheaf with hermitian metrics on the complex variety of M . Its curvature form is the C^{∞} (1, 1)-form $\partial \bar{\partial} \log |s|^2$, where s is an arbitrary local

invertible section of L . This form is closed, and its cohomology class equals $2\pi i c_1(L)$. If M is compact, one gets in this way a bijection

$$\left[\begin{array}{l} (1, 1)\text{-forms} \\ \text{in the class } c_1(L) \end{array} \right] \leftrightarrow \left[\begin{array}{l} \text{metrics on } L \\ \text{up to proportionality} \end{array} \right].$$

On a Riemann surface X of genus $g \geq 1$ there is a canonical $(1, 1)$ -form

$$\varrho_X = i/2g \omega^i (\text{Im } \tau)^{-1} \wedge \omega,$$

where ω is the Riemann basis. Therefore any invertible sheaf L admits metrics with the curvature form proportional to ϱ_X . Such metrics are called admissible. For example, the sheaf $\mathcal{O}(P)$ has a canonical admissible metric, defined by $|t_P|(\mathcal{Q}) = G(P, \mathcal{Q})$, where G is the exponentiated Green function of the Laplace operator $\Delta = -\frac{i}{\pi \varrho_X} \partial \bar{\partial}$. To be more precise,

$$f(P) = -\int_X \log G(P, \mathcal{Q}) \Delta f(\mathcal{Q}) \varrho_X(\mathcal{Q}) \quad \text{for} \quad \int_X f \varrho_X = 0,$$

$$\int_X \log G(P, \mathcal{Q}) \varrho_X(\mathcal{Q}) = 0.$$

Faltings [9] has shown, that if an admissible metric on a sheaf L is given, then $d(L)$ can be endowed with a canonical metric that transforms in an explicit way under the canonical isomorphisms of Sect. 2. One can then use it instead of distinguished bases to compute $|\mu_X|^2 = d\pi_g$ (but not μ_X itself).

For example, the isomorphism

$$d(L) = d(L(-\sum P_i)) \otimes \left(\bigotimes_i L_{P_i} \right),$$

which we used constantly, becomes an isometry, if $d(L)$ and $d(L(-\sum P_i))$ are endowed with Faltings' metrics, while $\bigotimes L_{P_i}$ gets the metrics

$$\otimes (\text{induced metrics on } L_{P_i}) \otimes \prod_{i < j} G(P_i, P_j)^{-1}.$$

Such arguments, together with another result of Faltings on the metric change via $\lambda_1^{13} \rightarrow \lambda_2$ give the formula of [14].

2. The Problem of Measure for Superstrings

One hopes that Polyakov's measure for the superstring in the critical dimension 10 should also be computable in the same vein, through an intermediary Mumford-Berezin form on a superalgebraic moduli space M_g^s of dimension $3g - 3|2g - 2$ (for $g \geq 2$). At the moment, however, only some parts of the whole picture are on a mathematically sound base.

a) It is unknown (at least, to the authors), whether an analogue of the Belavin-Knizhnik theorem is true.

b) The supervariety M_g^s , or rather an infinite covering of it, was constructed by one of us (Yu. I. M.) by means of Schottky's superuniformization, but not all techniques needed for transposition of calculations of Sect. 2 are worked out yet.

At our present level of knowledge, we can calculate at least the analog of the Mumford form on the “component” version of the superspace M_g^s , which parametrizes certain (1|1)-dimensional superalgebraic curves with superconformal structure in the sense of [6], having odd typical structural theta characteristics. By definition, the underlying space of this superspace is M_g^- (see Sect. 2, N^o. 8), and the sheaf of holomorphic superfunctions is $\mathcal{A}'(\pi_*\Omega^{3/2})$, where $\pi: X \rightarrow M_g^-$ is the universal family.

Denote this supervariety by \tilde{M}_g^s and consider the family of supercurves $\tilde{\pi}: \tilde{X} \rightarrow M_g^s$, where odd superfunctions on \tilde{X} are generated by the functions, lifted from $M_{g_2}^s$ and the sections of $\Omega^{1/2}$, lifted from X .

On \tilde{M}_g^s there are analogs of Mumford’s sheaves

$$A_i = \text{Ber } R\tilde{\pi}_*((\Omega^s)^{i/2}),$$

where $(\Omega^s)^{1/2}$ comes from $\Omega^{1/2}$. The results of Sect. 2 give us a canonical isomorphism on M_g^- , $(\lambda_1\lambda_{1/2}^{-1})^5 = \lambda_2\lambda_{1/2}^{-1}$, which after lifting to M_g^s becomes an isomorphism $A_1^5 = A_3$.

The section of $A_1^{-5}A_3$, corresponding to 1, is a component analogue of a “true” Mumford’s form. The second formula of [14] gives its modulus squared. The computations of Sect. 2 give an explicit formula for this section itself in terms of distinguished bases.

3. Distinguished Bases and Canonical Models of Algebraic Curves

If a curve X of genus $g \geq 3$ is not hyperelliptic, then the distinguished basis $(\varphi_0, \dots, \varphi_{g-1})$ embeds it into a coordinatized projective space P^{g-1} .

An advantage of this choice over Petri’s one (see [16, pp. 123–135]) is that this embedding is defined only up to finite ambiguity. In fact, to define it, one fixes a typical odd theta characteristic and $g - 1$ cubic roots of unity. The formula for φ_0 in terms of the theta function seems to introduce a transcendental element into this construction, but one may well avoid it. E.g. we can leave φ_0 defined up to multiplication by c , and $\varphi_j, j \geq 1$, up to multiplication by $c^{-1/3}$ [the normalization (2), Sect. 1] is crucial here).

The ideal of equations for X in this embedding is generated for $g \geq 4$ by quadratic relations between φ_j ’s. (excepting plane quintics and trigonal curves).

The basic quadratic relations can be written in the form

$$\varphi_k\varphi_l = \sum_{i=1}^{3g-3} a_{kl}^i w_i, \quad k, l = 0, \dots, g-1.$$

Here (w_i) is the distinguished basis of quadratic differentials, and coefficients a_{kl}^i can be calculated through the expansion coefficients of φ_i by v_α near P_k .

This refinement of the Petri method may be of independent algebro-geometric interest.

Appendix. Simultaneous Normalization of Mumford’s Forms

In the main body of the paper Mumford’s forms μ_g were defined only up to multiplication by a constant, depending on g . In this appendix we shall show how

to normalize μ_g in a canonical coherent way by purely algebraic means. Hopefully, in this normalization $d\pi_g = e^{\beta(2-2g)}|\mu_g|^2$ for a certain (zero?) value of β . This conjecture is equivalent to a factorization property of $d\pi_g$.

To achieve this goal, we need to fix the behaviour of μ_g when a curve acquires a singularity. Let us first introduce some notation. Below “curve” means “projective algebraic curve, possibly reducible or even disconnected, with quadratic singularities only.” For a curve X , let $\Omega^1 X$ be the sheaf of 1-forms on it and ω_X the dualizing sheaf (which is always invertible). They are related by a canonical morphism $i: \Omega^1 X \rightarrow \omega_X$, which is an isomorphism off singular points. The image of i coincides with $\pi_* \Omega^1 \tilde{X}$, where $\pi: \tilde{X} \rightarrow X$ is the normalization map, pulling apart the double points. Now let α be such a double point; x_1, x_2 parameters of two branches, crossing at α . The one-dimensional fibers of $\text{Ker } i$, $\text{Coker } i$ at α are generated by $x_1 dx_2, x_1^{-1} dx_1 - x_2^{-1} dx_2$ respectively. Put

$$\lambda_j(X) = \det R\Gamma(X, \omega_X^{\otimes j}), j \in \mathbb{Z}; \quad \tilde{\lambda}(X) = \det R\Gamma(X, \Omega^1 X),$$

$$\delta(X) = \lambda_1(X) \tilde{\lambda}(X)^{-1}.$$

These are one-dimensional vector spaces with the following properties.

i) They vary in a holomorphic way, when X varies. The symmetries of X act upon them.

ii) There is a canonical element $\det i \in \delta(X)$, vanishing iff X is singular.

iii) (Serre’s duality). $\lambda_j(X) = \lambda_{1-j}(X)$.

iv) (Disjoint sums). If $X = X_1 \sqcup X_2$, then there are canonical identifications $\lambda_j(X) = \lambda_j(X_1) \otimes \lambda_j(X_2)$, and similarly for $\tilde{\lambda}, \delta$.

For λ_j this comes from the exact sequence $0 \rightarrow \omega_1^{\otimes j} \rightarrow \omega_X^{\otimes j} \rightarrow \omega_{X_2}^{\otimes j} \rightarrow 0$; similarly for $\tilde{\lambda}$; and δ expresses through $\lambda_1, \tilde{\lambda}$. Observe that this isomorphism for $\lambda_j, \tilde{\lambda}$ multiplies by $(-1)^{x(0_{x_1})x(0_{x_2})}$, if one changes the order of X_1, X_2 ; while one for δ does not depend on this order.

v) (Glueing points). Let X be a curve, α_1, α_2 smooth points on it. Denote by \bar{X} a curve, obtained from X by glueing these points together into a point α . Put $l_i = (\Omega^1 X)_{\alpha_i}$. Then there are canonical identifications

$$\lambda_j(\bar{X}) = \lambda_j(X) (l_1 l_2)^{-j(j-1)/2}, \quad \tilde{\lambda}(\bar{X}) = \tilde{\lambda}(X) l_1 l_2,$$

$$\delta(\bar{X}) = \delta(X) (l_1 l_2)^{-1}.$$

To see this, consider the glueing map $\pi: X \rightarrow \bar{X}$, and let x_1, x_2 be parameters at α_1, α_2 . This data defines the following exact sequences:

a) $0 \rightarrow \omega_X^{\otimes j} \rightarrow \pi_*(\omega_X(\alpha_1 + \alpha_2))^{\otimes j} \xrightarrow{\varphi} \mathbb{C}_\alpha \rightarrow 0.$

b) $0 \rightarrow \omega_X^{\otimes j} \rightarrow (\omega_X(\alpha_1 + \alpha_2))^{\otimes j} \rightarrow 0_X/m_{\alpha_1}^j \oplus 0_X/m_{\alpha_2}^j \rightarrow 0.$

c) $0 \rightarrow (l_1 l_2)_\alpha \xrightarrow{\psi} \Omega^1 \bar{X} \rightarrow \pi_* \Omega^1 X \rightarrow 0.$

Here the maps φ and ψ are defined by

$$\varphi(f_1(x_1^{-1} dx_1)^j + f_2(x_2^{-1} dx_2)^j) = f_1(\alpha_1) + (-1)^{j-1} f_2(\alpha_2),$$

$$\psi(c(dx_1)_{\alpha_1}(dx_2)_{\alpha_2}) = cx_1 dx_2.$$

Applying to these exact sequences $\det R\Gamma$, we get:

$$\begin{aligned} \lambda_j(\bar{X}) &\stackrel{(a)}{=} \det R\Gamma(X, \omega_X(\alpha_1 + \alpha_2)^{\otimes j}) \stackrel{(b)}{=} \lambda_j(X) \det(0_X/m_{\alpha_1}^j \oplus 0_X/m_{\alpha_2}^j) \\ &= \lambda_j(X) \bigotimes_{a=j}^0 \det(m_{\alpha_1}^{a-1}/m_{\alpha_1}^a \oplus m_{\alpha_2}^{a-1}/m_{\alpha_2}^a) = \lambda_j(X) (l_1 l_2)^{j(j-1)/2}, \\ \tilde{\lambda}(\bar{X}) &\stackrel{(c)}{=} \tilde{\lambda}(X) l_1 l_2. \end{aligned}$$

The isomorphism for δ comes from ones for $\lambda_1, \tilde{\lambda}$. Again, the isomorphisms for $\lambda_j, \tilde{\lambda}$ change sign, when the order of α_1, α_2 is reversed.

vi) (Projective line). If X is a smooth curve of genus zero, then $\lambda_j(X) = \tilde{\lambda}(X) = \delta(X) = \mathbf{C}$ canonically.

Indeed, by ii), iii) it suffices to look at the case $\lambda_j, j \geq 0$. Choose a point $x \in X$. Consider an exact sequence

$$0 \rightarrow \omega_X^{\otimes j} \rightarrow \omega_X^{\otimes j}((2j-1)x) \rightarrow F \rightarrow 0,$$

where $F = \omega_X^{\otimes j}((2j-1)x)/\omega_X^{\otimes j}$. The middle sheaf is acyclic, being isomorphic to $0_X(-1)$, hence $\lambda_j(X) = (\det F)^{-1}$. But $\det F = \mathbf{C}$, under the isomorphism, mapping 1 to $t^{-1}(dt)^j \wedge \dots \wedge t^{-2j+1}(dt)^j$, where t is an arbitrary parameter at x . This isomorphism does not depend on choices made to construct it.

Now put

$$\bar{\lambda}_j = \lambda_j \delta^{-j(j-1)/2}, \quad v_j = \bar{\lambda}_j \bar{\lambda}_1^{-6j^2+6j-1}.$$

Clearly, the above implies

vii) The properties i), iii), iv), vi) hold for $\bar{\lambda}_j, v_j$. In the situation v) we have $\bar{\lambda}_j(\bar{X}) = \bar{\lambda}_j(X), v_j(\bar{X}) = v_j(X)$ (“factorization property”).

We can state now the main result of this appendix.

Proposition. *There is a unique identification $v_j(X) \in \mathbf{C}$ compatible with i), iv), and v). It is then automatically compatible with iii) and for $X = P^1$ coincides with vi). The element $\mu^{(j)}(X) \in v_j(X)$ is the normalized Mumford form (or, rather, its value at X).*

Sketch of Proof. Assume first that such μ exists. According to iv), v) it is defined by its values on smooth connected X . But any such X is a member of a family of curves with compact connected parameter space, in which P^1 with a number of double points also occurs. (Take, e.g. the Deligne-Mumford modular family.) This shows that $\mu(P^1)$, together with i), v), determines μ uniquely. It remains to see that $\mu(P^1)$ coincides with 1 in normalization vi). Consider a constant family $P^1 \times A^1$ and blow up a point in a fiber over $0 \in A^1$. In this new family the fiber over 0 is $P^1 \sqcup P^1$ with two points glued together, i.e. $P^1 \vee P^1$. We have $\mu(P^1 \vee P^1) = \mu(P^1) \cdot \mu(P^1)$, and $\mu(P^1 \vee P^1) = \lim_{t \rightarrow 0} \mu(P_t^1)$. This forces $\mu(P^1)$ to be 1.

As for existence of μ , one can prove it by a simple induction on genus, using the structure of Deligne-Mumford moduli space at infinity, together with iv), v) to normalize the Mumford forms.

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Note added in proof. Since this paper was written we became aware of a very interesting letter by P. Deligne to D. Quillen, dated back to 20 June 1985, where a refinement of the Grothendieck-Riemann-Roch for c_1 of direct images of rank 0 virtual vector bundles over Riemann surfaces was given and the normalized Mumford forms were defined.