ESTIMATION AND TESTING FOR PARTIALLY LINEAR SINGLE-INDEX MODELS

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In partially linear single-index models, we obtain the semiparametrically efficient profile least-squares estimators of regression coefficients. We also employ the smoothly clipped absolute deviation penalty (SCAD) approach to simultaneously select variables and estimate regression coefficients. We show that the resulting SCAD estimators are consistent and possess the oracle property. Subsequently, we demonstrate that a proposed tuning parameter selector, BIC, identifies the true model consistently. Finally, we develop a linear hypothesis test for the parametric coefficients and a goodness-of-fit test for the nonparametric component, respectively. Monte Carlo studies are also presented.

1. Introduction. Regression analysis is commonly used to explore the relationship between a response variable Y and its covariates Z. For the sake of convenience, one often employs a linear regression model $E(Y|Z) = Z^T\boldsymbol{\alpha}$ to assess the impact of the covariates on the response, where $\boldsymbol{\alpha}$ is an unknown vector and E stands for "expectation." In practice, however, the linear assumption may not be valid. Hence, it is natural to consider a single-index model $E(Y|Z) = \eta(Z^T\boldsymbol{\alpha})$, in which the link function η is unknown. Accordingly, various parameter estimators of single-index models have been proposed [e.g., Powell, Stock and Stocker (1989); Duan and Li (1991); Härdle, Hall and Ichimura (1993); Ichimura (1993); Horowitz and Härdle (1996); Liang and Wang (2005)]. Detailed discussion and illustration of the usefulness of this model can be found in Horowitz (1998). Although the single-index model plays an important role in data analysis, it may not be sufficient to explain the variation of responses via covariates Z. Therefore, Carroll et al. (1997) augmented the single-index model in a linear form with additional covariates X, which yields a partially linear single-index model (PLSIM),

$E(Y|Z, X) = \eta(Z^T\boldsymbol{\alpha}) + X^T\boldsymbol{\beta}$. When Z is scalar and $\boldsymbol{\alpha} = 1$, the PLSIM reduces to the partially linear model, $E(Y|Z, X) = \eta(Z) + X^T\boldsymbol{\beta}$ [see Speckman (1988)]. A comprehensive review of partially linear models can be found in Härdle, Liang and Gao (2000).

To estimate parameters in partially linear single-index models, Carroll et al. (1997) proposed the backfitting algorithm. However, the resulting estimators may be unstable [see Yu and Ruppert (2002)] and undersmoothing the nonparametric function is necessary to reduce the bias of the parametric estimators. Accordingly, Yu and Ruppert (2002) proposed the penalized spline estimation procedure, while Xia and Härdle (2006) applied the minimum average variance estimation (MAVE) method, which was originally introduced by Xia et al. (2002) for dimension reduction. Although Yu and Ruppert's procedure is useful, it may not yield efficient estimators; that is, the asymptotic covariance of their estimators does not reach the semiparametric efficiency bound [Carroll et al. (1997)]. In addition, these estimators need to be solved via an iterative procedure; that is, iteratively estimating the nonparametric component and the parametric component. We therefore propose the profile least-squares approach, which obtains efficient estimators and provides the efficient bound. Moreover, the resulting estimators can be found without using the iterative procedure mentioned above and hence may reduce the computational burden.

In data analysis, the true model is often unknown; this allows the possibility of selecting an underfitted (or overfitted) model, leading to biased (or inefficient) estimators and predictions. To address this problem, Tibshirani (1996) introduced the least absolute shrinkage and selection operator (LASSO) to shrink the estimated coefficients of superfluous variables to zero in linear regression models. Subsequently, Fan and Li (2001) proposed the smoothly clipped absolute deviation (SCAD) approach that not only selects important variables consistently, but also produces parameter estimators as efficiently as if the true model were known, a property not possessed by the LASSO. Because it is not a simple matter to formulate the penalized function via the MAVE's procedure, we employ the profile least-squares approach to obtain the SCAD estimators for both parameter vectors $\boldsymbol{\alpha}$ and $\boldsymbol{\beta}$. Furthermore, we establish the asymptotic results of the SCAD estimators, which include the consistency and oracle properties [see Fan and Li (2001)]. Simulation results are consistent with theoretical findings.

After estimating unknown parameters, it is natural to construct hypothesis tests to assess the appropriateness of the linear constraint hypothesis as well as the linearity of the nonparametric function. We demonstrate that the resulting test statistics are asymptotically chi-square distributed under the null hypothesis. In addition, simulation studies indicate that the test statistics perform well. The rest of this paper is organized as follows. Section 2 introduces the profile least-squares estimators and the penalized SCAD estimators. The asymptotic properties of these estimators are obtained. Section 3 presents hypothesis tests and their large-sample properties. Monte Carlo studies are presented in Section 4. Section 5 concludes the article with a brief discussion. All detailed proofs are deferred to the Appendix.

2. Profile least-squares procedure. Suppose that $\{(Y_i, Z_i, X_i), i = 1, \ldots, n\}$ is a random sample generated from the PLSIM

$$(2.1) \qquad Y = \eta(Z^T \boldsymbol{\alpha}) + X^T \boldsymbol{\beta} + \varepsilon,$$

where Z and X are p-dimensional and q-dimensional covariate vectors, respectively, $\boldsymbol{\alpha} = (\alpha_1, \ldots, \alpha_p)^T$, $\boldsymbol{\beta} = (\beta_1, \ldots, \beta_q)^T$, $\eta(\cdot)$ is an unknown differentiable function, ε is the random error with mean zero and finite variance σ^2, and $(Z^T, X^T)^T$ and ε are independent. Furthermore, we assume that $\|\boldsymbol{\alpha}\| = 1$ and that the first element of $\boldsymbol{\alpha}$ is positive, to ensure identifiability. We then employ the profile least-squares procedure to obtain efficient estimators and SCAD estimators in the following two subsections, respectively.

2.1. *Profile least-squares estimator.* In semiparametric models, Severini and Wong (1992) applied the profile likelihood approach to estimate the parametric component. We adapt this approach to estimate unknown parameters of partially linear single-index models. To begin, we re-express model (2.1) as

$$Y_i^* = \eta(\Lambda_i) + \varepsilon_i,$$

where $Y_i^* = Y_i - X_i^T \boldsymbol{\beta}$ and $\Lambda_i = Z_i^T \boldsymbol{\alpha}$. Then, for a given $\boldsymbol{\zeta} = (\boldsymbol{\alpha}^T, \boldsymbol{\beta}^T)^T$, we employ the local linear regression technique [Fan and Gijbels (1996)] to estimate η, that is, to minimize

$$(2.2) \qquad \sum_{i=1}^{n} \{a + b(\Lambda_i - u) + X_i^T \boldsymbol{\beta} - Y_i\}^2 K_h(\Lambda_i - u)$$

with respect to a, b, where $K_h(\cdot) = 1/h K(\cdot/h)$, $K(\cdot)$ is a kernel function and h is a bandwidth.

Let $(\hat{a}, \hat{b})$ be the minimizer of (2.2). Then,

$$(2.3) \qquad \hat{\eta}(u, \boldsymbol{\zeta}) = \hat{a} = \frac{K_{20}(u, \boldsymbol{\zeta}) K_{01}(u, \boldsymbol{\zeta}) - K_{10}(u, \boldsymbol{\zeta}) K_{11}(u, \boldsymbol{\zeta})}{K_{00}(u, \boldsymbol{\zeta}) K_{20}(u, \boldsymbol{\zeta}) - K_{10}^2(u, \boldsymbol{\zeta})},$$

where $K_{jl}(u, \boldsymbol{\zeta}) = \sum_{i=1}^{n} K_h(Z_i^T \boldsymbol{\alpha} - u)(Z_i^T \boldsymbol{\alpha} - u)^j (X_i^T \boldsymbol{\beta} - Y_i)^l$ for $j = 0, 1, 2$ and $l = 0, 1$. Subsequently, following Jennrich's (1969) assumption (a), there exists a profile least-squares estimator $\hat{\boldsymbol{\zeta}} = (\hat{\boldsymbol{\alpha}}^T, \hat{\boldsymbol{\beta}}^T)^T$ obtained by minimizing the following profile least-squares function:

$$(2.4) \qquad Q(\boldsymbol{\zeta}) = \sum_{i=1}^{n} \{Y_i - \hat{\eta}(Z_i^T \boldsymbol{\alpha}, \boldsymbol{\zeta}) - X_i^T \boldsymbol{\beta}\}^2.$$

It is noteworthy that we apply the Newton–Raphson iterative method to find the estimator $\hat{\boldsymbol{\zeta}}$; this technique is distinct from the more commonly used iterative procedure in partially single-index models which iteratively updates estimates of the

nonparametric component and the parametric component obtained from their corresponding objective functions. In addition, our proposed profile least-squares approach allows us to directly introduce the penalized function, as given in the next subsection.

To study the large-sample properties of parameter estimators, we consider the true model with an unknown parameter vector $\boldsymbol{\zeta}_0 = (\boldsymbol{\alpha}_0^{\mathrm{T}}, \boldsymbol{\beta}_0^{\mathrm{T}})^{\mathrm{T}}$. In addition, we assume that $\boldsymbol{\alpha}_0^{\mathrm{T}}$ and $\boldsymbol{\beta}_0^{\mathrm{T}}$ have the same dimensions as their corresponding parameter vectors $\boldsymbol{\alpha}^{\mathrm{T}}$ and $\boldsymbol{\beta}^{\mathrm{T}}$ in the candidate model of this subsection. Moreover, we introduce the following notation: $A^{\otimes 2} = AA^{\mathrm{T}}$ for a matrix A, $\Lambda = Z^{\mathrm{T}}\boldsymbol{\alpha}$, $\hat{\Lambda} = Z^{\mathrm{T}}\hat{\boldsymbol{\alpha}}$, $\Lambda_0 = Z^{\mathrm{T}}\boldsymbol{\alpha}_0$, $\widetilde{\xi} = \xi - E(\xi|\Lambda)$, $\widetilde{\xi}_0 = \xi - E(\xi|\Lambda_0)$ and $\hat{\xi} = \xi - \hat{E}(\xi|\Lambda)$ for any random variable (or vector) ξ, where $\hat{E}(\xi|\Lambda)$ is the local linear estimator of $E(\xi|\Lambda)$. For example, $\widetilde{Z} = Z - E(Z|\Lambda)$ and $\hat{X} = X - \hat{E}(X|\Lambda)$. We next present six conditions and then obtain the weak consistency and asymptotic normality of the profile least-squares estimators.

(i) The function $\eta(\cdot)$ is differentiable and not constant on the support $\mathcal{U}$ of $Z^{\mathrm{T}}\boldsymbol{\alpha}$.

(ii) The function $\eta(z^{\mathrm{T}}\boldsymbol{\alpha})$ and the density function of $Z^{\mathrm{T}}\boldsymbol{\alpha}$, $f_{\boldsymbol{\alpha}}(z)$, are both three times continuously differentiable with respect to z. The third derivatives are uniformly Lipschitz continuous over $\mathcal{A} \subset \mathcal{R}^p$ for all $u \in \{u = z^{\mathrm{T}}\boldsymbol{\alpha} : \boldsymbol{\alpha} \in \mathcal{A}, z \in \mathcal{Z} \subset \mathcal{R}^p\}$.

(iii) $E(|Y|^{m_1}) < \infty$ for some $m_1 \geq 3$. The conditional variance of Y given (X, Z) is bounded and bounded away from 0.

(iv) The kernel function $K(\cdot)$ is twice continuously differentiable with the support $(-1, 1)$. In addition, its second derivative is Lipschitz continuous. Moreover, $\int u^j K(u)\, du = 1$ if $j = 0$ and $= 0$ if $j = 1$.

(v) The bandwidth h satisfies $\{nh^{3+3/(m_1-1)}\}\log^{-1} n \to \infty$ and $nh^8 \to 0$ as $n \to \infty$.

(vi) $E(\widetilde{X}^{\otimes 2})$ and $E\{\widetilde{Z}\eta'(\Lambda)\}^{\otimes 2}$ are positive-definite, where η' is the first derivative of η.

THEOREM 1. *Under the regularity conditions* (i)–(vi), *with probability tending to one,* $\hat{\boldsymbol{\zeta}}$ *is a consistent estimator of* $\boldsymbol{\zeta}$. *Furthermore,* $\sqrt{n}(\hat{\boldsymbol{\zeta}} - \boldsymbol{\zeta}_0) \to N(0, \sigma^2\mathbf{D}^{-1})$ *in distribution, where* $\mathbf{D} = E[\{\eta'(\Lambda_0)\widetilde{Z}_0^{\mathrm{T}}, \widetilde{X}_0^{\mathrm{T}}\}^{\mathrm{T}}]^{\otimes 2}$. *Moreover,* $\hat{\boldsymbol{\zeta}}$ *is a semiparametrically efficient estimator.*

Because $(Z^{\mathrm{T}}, X^{\mathrm{T}})^{\mathrm{T}}$ is independent of ε, we are able to demonstrate that the asymptotic variance of Xia and Härdle's (2006) minimum average variance estimator is $\sigma^2\mathbf{D}^{-1}$, which indicates that MAVE is also an efficient estimator.

After having estimated $\boldsymbol{\alpha}$ and $\boldsymbol{\beta}$, we obtain the following estimator of $\eta(u)$:

$$\hat{\eta}(u) = \hat{\eta}(u, \hat{\boldsymbol{\zeta}}) = \frac{K_{20}(u, \hat{\boldsymbol{\zeta}})K_{01}(u, \hat{\boldsymbol{\zeta}}) - K_{10}(u, \hat{\boldsymbol{\zeta}})K_{11}(u, \hat{\boldsymbol{\zeta}})}{K_{00}(u, \hat{\boldsymbol{\zeta}})K_{20}(u, \hat{\boldsymbol{\zeta}}) - K_{10}^2(u, \hat{\boldsymbol{\zeta}})}.$$

If the density function f_{Λ_0} of Λ_0 is positive and the derivative of $E(\varepsilon^2|\Lambda_0 = u)$ exists, then we can further demonstrate that $(nh)^{1/2}\{\hat{\eta}(u) - \eta(u) - 1/2k_2\eta''(u)h^2\}$ converges to a normal distribution $N(0, \sigma_{\eta,u}^2)$, where $\sigma_{\eta,u}^2 = f_{\Lambda_0}^{-1}(u)\int K^2(t)\,dt \times E(\varepsilon^2|\Lambda_0 = u)$, $k_2 = \int K(t)t^2\,dt$ and η'' is the second derivative of η. It is also noteworthy that one usually either introduces a trimming function or adds a ridge parameter [see Seifert and Gassert (1996)] when the denominator of $\hat{\eta}$ closes to zero.

REMARK 1. Condition (v) indicates that Theorem 1 is applicable for a reasonable range of bandwidths. Numerical studies confirm it; our results remain stable by employing various bandwidths around the optimal bandwidth selected by cross-validation, in particular when the sample size becomes large.

2.2. *Penalized profile least-squares estimator.* In practice, the true model is often unknown a priori. An underfitted model can yield biased estimates and predicted values, while an overfitted model can degrade the efficiency of the parameter estimates and predictions. This motivates us to apply the penalized least-squares approach to simultaneously estimate parameters and select important variables. To this end, we consider a penalized profile least-squares function

$$(2.5) \qquad \mathcal{L}_P(\zeta) = \frac{1}{2}Q(\zeta) + n\sum_{j=1}^{p} p_{\lambda_{1j}}(|\alpha_j|) + n\sum_{k=1}^{q} p_{\lambda_{2k}}(|\beta_k|),$$

where $p_\lambda(\cdot)$ is a penalty function with a regularization parameter λ. Throughout this paper, we allow different elements of $\boldsymbol{\alpha}$ and $\boldsymbol{\beta}$ to have different penalty functions with different regularization parameters. For the purpose of selecting X-variables only, we simply set $p_{\lambda_{1j}}(\cdot) = 0$ and the resulting penalized profile least-squares function becomes

$$(2.6) \qquad \mathcal{L}_P(\zeta) = \frac{1}{2}Q(\zeta) + n\sum_{k=1}^{q} p_{\lambda_{2k}}(|\beta_j|).$$

Similarly, if we are only interested in selecting Z-variables, then we set $p_{\lambda_{2k}}(\cdot) = 0$ so that

$$(2.7) \qquad \mathcal{L}_P(\zeta) = \frac{1}{2}Q(\zeta) + n\sum_{j=1}^{p} p_{\lambda_{1j}}(|\alpha_j|).$$

There are various penalty functions available in the literature. To obtain the oracle property of Fan and Li (2001), we adopt their SCAD penalty, whose first derivative is

$$p_\lambda'(\theta) = \lambda\left\{I(\theta \le \lambda) + \frac{(a\lambda - \theta)_+}{(a-1)\lambda}I(\theta > \lambda)\right\},$$

and where $p_\lambda(0) = 0$, $a = 3.7$ and $(t)_+ = tI\{t > 0\}$ is the hinge loss function. For the given tuning parameters, we obtain the penalized estimators by minimizing $\mathcal{L}_P(\boldsymbol{\alpha}, \boldsymbol{\beta})$ with respect to $\boldsymbol{\alpha}$ and $\boldsymbol{\beta}$. For the sake of simplicity, we denote the resulting estimators by $\hat{\boldsymbol{\alpha}}_{\lambda_1}$ and $\hat{\boldsymbol{\beta}}_{\lambda_2}$.

In what follows, we study the theoretical properties of the penalized profile least-squares estimators with the SCAD penalty. Without loss of generality, it is assumed that the correct model has regression coefficients $\boldsymbol{\alpha}_0 = (\boldsymbol{\alpha}_{10}^T, \boldsymbol{\alpha}_{20}^T)^T$ and $\boldsymbol{\beta}_0 = (\boldsymbol{\beta}_{10}^T, \boldsymbol{\beta}_{20}^T)^T$, where $\boldsymbol{\alpha}_{10}$ and $\boldsymbol{\beta}_{10}$ are $p_0 \times 1$ and $q_0 \times 1$ nonzero components of $\boldsymbol{\alpha}_0$ and $\boldsymbol{\beta}_0$, respectively, and $\boldsymbol{\alpha}_{20}$ and $\boldsymbol{\beta}_{20}$ are $(p - p_0) \times 1$ and $(q - q_0) \times 1$ vectors with zeros. In addition, we define Z_1 and X_1 in such a way that they consist of the first p_0 and q_0 elements of Z and X, respectively. We define $\widetilde{Z}_1$ and $\widetilde{X}_1$ analogously. Finally, we use the following notation for simplicity: $\Gamma_{\widetilde{X}_1\widetilde{X}_1} = E(\widetilde{X}_1^{\otimes 2})$, $\Gamma_{\widetilde{X}_1\widetilde{Z}_1} = E\{\widetilde{Z}_1 \widetilde{X}_1^T \eta'(\Lambda)\}$ and $\Gamma_{\widetilde{Z}_1\widetilde{Z}_1} = E\{\widetilde{Z}_1 \eta'(\Lambda)\}^{\otimes 2}$.

THEOREM 2. *Under the regularity conditions* (i)–(vi), *if, for all k and j, $\lambda_{1j} \to 0$, $\sqrt{n}\lambda_{1j} \to \infty$, $\lambda_{2k} \to 0$ and $\sqrt{n}\lambda_{2k} \to \infty$ as $n \to \infty$, with probability tending to one, then the penalized estimators $\hat{\boldsymbol{\alpha}}_{\lambda_1} = (\hat{\boldsymbol{\alpha}}_{1\lambda_1}^T, \hat{\boldsymbol{\alpha}}_{2\lambda_1}^T)^T$ and $\hat{\boldsymbol{\beta}}_{\lambda_2} = (\hat{\boldsymbol{\beta}}_{1\lambda_2}^T, \hat{\boldsymbol{\beta}}_{2\lambda_2}^T)^T$ satisfy*:

(a) $\hat{\boldsymbol{\alpha}}_{2\lambda_1} = 0$ *and* $\hat{\boldsymbol{\beta}}_{2\lambda_2} = 0$;
(b) $\sqrt{n}(\hat{\boldsymbol{\alpha}}_{1\lambda_1} - \boldsymbol{\alpha}_{10}) \to N\{0, \sigma^2(\Gamma_{\widetilde{Z}_1\widetilde{Z}_1} - \Gamma_{\widetilde{X}_1\widetilde{Z}_1}\Gamma_{\widetilde{X}_1\widetilde{X}_1}^{-1}\Gamma_{\widetilde{X}_1\widetilde{Z}_1}^T)^{-1}\}$ *and* $\sqrt{n}(\hat{\boldsymbol{\beta}}_{1\lambda_2} - \boldsymbol{\beta}_{10}) \to N\{0, \sigma^2(\Gamma_{\widetilde{X}_1\widetilde{X}_1} - \Gamma_{\widetilde{X}_1\widetilde{Z}_1}^T\Gamma_{\widetilde{Z}_1\widetilde{Z}_1}^{-1}\Gamma_{\widetilde{X}_1\widetilde{Z}_1})^{-1}\}$.

Analogous results can be established for those parameter estimators obtained via the penalized functions (2.6) or (2.7).

Kong and Xia (2007) developed a cross-validation-based variable selection procedure in single-index models and observed the difference between the popular leave-m-out cross-validation method in the variable selection of the linear model and the single-index model. It is noteworthy that we need two tuning parameters in (2.5), λ_1 and λ_2, imposed on the linear part and the single-index part, respectively. They can be in the same order in the large-sample sense, on the basis of the assumptions in Theorem 2, although the distinction between these two tuning parameters in practice is anticipated, as will be discussed below. Theorem 2 indicates that the proposed variable selection procedure possesses the oracle property. However, this attractive feature relies on the tuning parameters. To this end, we adopt Wang, Li and Tsai's (2007) BIC selector to choose the regularization parameters λ_{1j} and λ_{2k}. Because it is computationally expensive to minimize BIC, defined below, with respect to the $(p + q)$-dimensional regularization parameters, we follow the approach of Fan and Li (2004) to set $\lambda_{1j} = \lambda \, \mathrm{SE}(\hat{\alpha}_j^u)$ and $\lambda_{2k} = \lambda \, \mathrm{SE}(\hat{\beta}_k^u)$, where λ is the tuning parameter, and $\mathrm{SE}(\hat{\alpha}_j^u)$ and $\mathrm{SE}(\hat{\beta}_k^u)$ are the standard errors of the unpenalized profile least-squares estimators of α_j and β_k, respectively, for

$j = 1, \ldots, p$ and $k = 1, \ldots, q$. Let the resulting SCAD estimators be $\hat{\boldsymbol{\alpha}}_\lambda$ and $\hat{\boldsymbol{\beta}}_\lambda$. We then select λ by minimizing the objective function

$$\text{(2.8)} \qquad \text{BIC}(\lambda) = \log\{(\text{MSE}(\lambda)\} + \big(\log(n)/n\big)\text{DF}_\lambda,$$

where $\text{MSE}(\lambda) = n^{-1}\sum_{i=1}^{n}\{Y_i - \hat{\eta}(Z_i^{\text{T}}\hat{\boldsymbol{\alpha}}_\lambda) - X_i^{\text{T}}\hat{\boldsymbol{\beta}}_\lambda\}^2$ and DF_λ is the number of nonzero coefficients of both $\hat{\boldsymbol{\alpha}}_\lambda$ and $\hat{\boldsymbol{\beta}}_\lambda$. More specifically, we choose λ to be the minimizer among a set of grid points over bounded interval $[0, \lambda_{\max}]$, where $\lambda_{\max}/\sqrt{n} \to 0$ as $n \to \infty$. The resulting optimal tuning parameter is denoted by $\hat{\lambda}$. In practice, a plot of the $\text{BIC}(\lambda)$ against λ can be used to determine an appropriate $\lambda_{\max}$ to ensure that the $\text{BIC}(\lambda)$ reaches its minimum around the middle of the range of λ. The grid points for λ are then taken to be evenly distributed over $[0, \lambda_{\max}]$ so that they are chosen to be fine enough to avoid multiple minimizers of $\text{BIC}(\lambda)$. In our numerical studies, the range for λ and the number of grid points are set in the same manner as those in Wang, Li and Tsai (2007) and Zhang, Li and Tsai (2010). Based on our limited experience, the resulting estimate of λ is quite stable with respect to the number of grid points when they are sufficiently fine.

To investigate the theoretical properties of the BIC selector, we denote by $S = \{j_1, \ldots, j_d\}$ the set of the indices of the covariates in the given candidate model, which contains indices of both X and Z. In addition, let S_T be the true model, S_F be the full model and S_λ be the set of the indices of the covariates selected by the SCAD procedure with tuning parameter λ. For a given candidate model S with parameter vectors $\boldsymbol{\alpha}_s$ and $\boldsymbol{\beta}_s$, let $\hat{\boldsymbol{\alpha}}_s$ and $\hat{\boldsymbol{\beta}}_s$ be the corresponding profile least-squares estimators. Then, define $\sigma_n^2(S) = n^{-1}\sum_{i=1}^{n}\{Y_i - \hat{\eta}(Z_i^{\text{T}}\hat{\boldsymbol{\alpha}}_s) - X_i^{\text{T}}\hat{\boldsymbol{\beta}}_s\}^2$ and further assume that:

(A) for any $S \subset S_F$, $\sigma_n^2(S) \to \sigma^2(S)$ in probability for some $\sigma^2(S) > 0$;
(B) for any $S \not\supset S_T$, we have $\sigma^2(S) > \sigma^2(S_T)$.

It is noteworthy that (A) and (B) are the standard conditions for investigating parameter estimation under model misspecification [e.g., see Wang, Li and Tsai (2007)].

We next present the asymptotic property of the BIC-type tuning parameter selector.

THEOREM 3. *Under conditions* (A), (B) *and the regularity conditions* (i)–(vi), *we have*

$$\text{(2.9)} \qquad P(S_{\hat{\lambda}} = S_T) \to 1.$$

Theorem 3 demonstrates that the BIC tuning parameter selector enables us to select the true model consistently.

3. Hypothesis tests. Applying the estimation method described in the previous section, we propose two hypothesis tests. The first is for general hypothesis testing of regression parameters and the second is for testing the nonparametric function.

3.1. *Testing parametric components.* Consider the general linear hypothesis

$$(3.1) \qquad\qquad H_0 : \mathbf{A}\boldsymbol{\zeta} = \boldsymbol{\delta} \quad \text{versus} \quad H_1 : \mathbf{A}\boldsymbol{\zeta} \neq \boldsymbol{\delta},$$

where $\mathbf{A}$ is a known $m \times (p+q)$ full-rank matrix and $\boldsymbol{\delta}$ is an $m \times 1$ vector. A simple example of (3.1) is to test whether some elements of $\boldsymbol{\alpha}$ and $\boldsymbol{\beta}$ are zero; that is,

$$H_0 : \alpha_{i_1} = \cdots = \alpha_{i_k} = 0 \text{ and } \beta_{j_1} = \cdots = \beta_{j_l} = 0$$

versus

$$H_1 : \text{not all } \alpha_{i_1}, \ldots, \alpha_{i_k} \text{ and } \beta_{j_1}, \ldots, \beta_{j_l} \text{ are equal to } 0.$$

Under H_0 and H_1, let $\boldsymbol{\zeta}_0 = (\boldsymbol{\alpha}_0^{\mathrm{T}}, \boldsymbol{\beta}_0^{\mathrm{T}})^{\mathrm{T}}$ and $\boldsymbol{\zeta}_1 = (\boldsymbol{\alpha}_1^{\mathrm{T}}, \boldsymbol{\beta}_1^{\mathrm{T}})^{\mathrm{T}}$ be the corresponding parameter vectors, and let Ω_0 and Ω_1 be the parameter spaces of $\boldsymbol{\zeta}_0$ and $\boldsymbol{\zeta}_1$, respectively. It is noteworthy that this is a slight abuse of notation because $\boldsymbol{\zeta}_0$ was previously used to denote the true value of $\boldsymbol{\zeta}$ in Section 2.1. Furthermore, define

$$Q(H_0) = \inf_{\Omega_0} Q(\boldsymbol{\zeta}_0) = \sum_{i=1}^{n} \{Y_i - \mathbf{X}_i^{\mathrm{T}}\hat{\boldsymbol{\beta}}_0 - \hat{\eta}(Z_i^{\mathrm{T}}\hat{\boldsymbol{\alpha}}_0, \hat{\boldsymbol{\xi}}_0)\}^2$$

and

$$Q(H_1) = \inf_{\Omega_1} Q(\boldsymbol{\zeta}_1) = \sum_{i=1}^{n} \{Y_i - \mathbf{X}_i^{\mathrm{T}}\hat{\boldsymbol{\beta}}_1 - \hat{\eta}(Z_i^{\mathrm{T}}\hat{\boldsymbol{\alpha}}_1, \hat{\boldsymbol{\xi}}_1)\}^2,$$

where $\{\hat{\boldsymbol{\beta}}_0, \hat{\boldsymbol{\xi}}_0\}$ and $\{\hat{\boldsymbol{\beta}}_1, \hat{\boldsymbol{\xi}}_1\}$ are the profile least-squares estimators of $\{\boldsymbol{\beta}_0, \boldsymbol{\zeta}_0\}$ and $\{\boldsymbol{\beta}_1, \boldsymbol{\zeta}_1\}$, respectively, and $\hat{\eta}$ is the nonparametric estimator of η obtained via (2.3). Subsequently, we propose a test statistic,

$$T_1 = \frac{n\{Q(H_0) - Q(H_1)\}}{Q(H_1)},$$

and give its theoretical property below.

THEOREM 4. *Assume that the regularity conditions* (i)–(vi) *hold. Then*:

(a) *under H_0 in* (3.1), $T_1 \to \chi_m^2$;

(b) *under H_1 in* (3.1), T_1 *converges to a noncentral chi-squared distribution with m degrees of freedom and noncentrality parameter* $\phi = \lim_{n\to\infty} n\sigma^{-2}(\mathbf{A}\boldsymbol{\zeta} - \boldsymbol{\delta})^{\mathrm{T}}(\mathbf{A}\mathbf{D}^{-1}\mathbf{A}^{\mathrm{T}})^{-1}(\mathbf{A}\boldsymbol{\zeta} - \boldsymbol{\delta})$, *where $\mathbf{D}$ is defined as in Theorem* 1.

Analogously, we are able to construct the Wald test, $W_n = (\mathbf{A}\hat{\boldsymbol{\zeta}} - \boldsymbol{\delta})^{\mathrm{T}}(\mathbf{A}\hat{\mathbf{D}}^{-1} \times \mathbf{A}^{\mathrm{T}})^{-1}(\mathbf{A}\hat{\boldsymbol{\zeta}} - \boldsymbol{\delta})$, and demonstrate that W_n and T_1 have the same asymptotic distribution.

3.2. *Testing the nonparametric component.* The nonparametric estimate of $\eta(\cdot)$ provides us with descriptive and graphical information for exploratory data analysis. Using this information, it is possible to formulate a parametric model that takes into account the features that emerged from the preliminary analysis. To this end, we introduce a goodness-of-fit test to assess the appropriateness of a proposed parametric model. Without loss of generality, we consider a simple linear model under the null hypothesis. Accordingly, the null and alternative hypotheses are given as follows:

$$(3.2) \quad H_0 : \eta(u) = \theta_0 + \theta_1 u \quad \text{versus} \quad H_1 : \eta(u) \neq \theta_0 + \theta_1 u \qquad \text{for some } u,$$

where θ_0 and θ_1 are unknown constant parameters.

Under H_1, let $\hat{\boldsymbol{\alpha}}$, $\hat{\boldsymbol{\beta}}$ and $\hat{\eta}$ be the corresponding profile least-squares and non-parametric estimators of $\boldsymbol{\alpha}$, $\boldsymbol{\beta}$ and η, respectively. Under H_0, we use the same parametric estimators $\hat{\boldsymbol{\alpha}}$ and $\hat{\boldsymbol{\beta}}$ as those obtained under H_1, while the estimator of η is $\tilde{\eta}(u) = \hat{\theta}_0 + \hat{\theta}_1 u$, where $\hat{\theta}_0$ and $\hat{\theta}_1$ are the ordinary least-squares estimators of θ_0 and θ_1, respectively, by fitting $Y_i - X_i^{\mathrm{T}}\hat{\boldsymbol{\beta}}$ versus $Z_i^{\mathrm{T}}\hat{\boldsymbol{\alpha}}$. The resulting residual sums of squares under the null and alternative hypotheses are then

$$\mathrm{RSS}(H_0) = \sum_{i=1}^{n}\{Y_i - \tilde{\eta}(Z_i^{\mathrm{T}}\hat{\boldsymbol{\alpha}}) - X_i^{\mathrm{T}}\hat{\boldsymbol{\beta}}\}^2$$

and

$$\mathrm{RSS}(H_1) = \sum_{i=1}^{n}\{Y_i - \hat{\eta}(Z_i^{\mathrm{T}}\hat{\boldsymbol{\alpha}}) - X_i^{\mathrm{T}}\hat{\boldsymbol{\beta}}\}^2.$$

To test the null hypothesis, we consider the following generalized F-test:

$$T_2 = \frac{r_K}{2}\frac{n\{\mathrm{RSS}(H_0) - \mathrm{RSS}(H_1)\}}{\mathrm{RSS}(H_1)},$$

where $r_K = \{K(0) - 0.5\int K^2(u)\,du\}\{\int\{K(u) - 0.5K * K(u)\}\,du\}^{-1}$ and $K * K$ denotes the convolution of K. The theoretical property of T_2 is given below.

THEOREM 5. *Assume that the regularity conditions* (i)–(vi) *hold. Under* H_0 *in* (3.2), T_2 *has an asymptotic* χ^2 *distribution with* df_n *degrees of freedom, where* $df_n = r_K|\mathcal{U}|\{K(0) - 0.5\int K^2(u)\,du\}/h$, $|\mathcal{U}|$ *stands for the length of* $\mathcal{U}$ *and* $\mathcal{U}$ *is defined in regularity condition* (i).

The above theorem unveils the Wilks phenomenon for the partially linear single-index model. Furthermore, we can obtain an analogous result when the simple linear model under H_0 is replaced by a multiple regression model.

4. Simulation studies. In this section, we present four Monte Carlo studies which evaluate the finite-sample performance of the proposed estimation and testing methods. The first two examples illustrate the performance of the profile least-squares estimator and the SCAD-based variable selection procedure proposed in Sections 2.1 and 2.2, respectively. The next two examples explore the performance of the test statistics developed in Sections 3.1 and 3.2.

EXAMPLE 4.1. We generated 500 realizations, each consisting of $n = 50, 100$ and 200 observations, from each of the following models:

$$(4.1) \qquad y = 4\{(z_1 + z_2 - 1)/\sqrt{2}\}^2 + 4 + 0.2\varepsilon;$$

$$(4.2) \qquad y = \sin[\{(z_1 + z_2 + z_3)/\sqrt{3} - a\}\pi/(b - a)] + \beta X + 0.1\varepsilon,$$

where z_1, z_2, z_3 are independent and uniformly distributed on $[0, 1]$, $X = 0$ for the odd numbered observations and $X = 1$ for the even numbered observations, ε has the standard normal distribution, $a = 0.3912$ and $b = 1.3409$. The resulting parameters of models (4.1) and (4.2) are $\boldsymbol{\alpha} = (\alpha_1, \alpha_2)^{\mathrm{T}} = (0.7071, 0.7071)^{\mathrm{T}}$ and $(\boldsymbol{\alpha}, \beta) = (\alpha_1, \alpha_2, \alpha_3, \beta)^{\mathrm{T}} = (0.5774, 0.5774, 0.5774, 0.3)^{\mathrm{T}}$ with $\phi_0 = \arccos(\alpha_1) = 0.7854$ as in Xia and Härdle (2006) [or $\pi/4$ in Härdle, Hall and Ichimura (1993), page 165].

Model (4.1) was analyzed by Härdle, Hall and Ichimura (1993) and Xia and Härdle (2006), while model (4.2) was investigated by Carroll et al. (1997) and Xia and Härdle (2006). For both models, Xia and Härdle claimed that their MAVE approach outperforms those of Härdle, Hall and Ichimura (1993) and Carroll et al. (1997), respectively. It is therefore of interest to compare the profile least-squares (abbreviated to PrLS) method with MAVE. Tables 1 and 2 present the results for models (4.1) and (4.2), respectively. Both tables indicate that the profile least-squares method yields accurate estimates and that the mean squared error becomes smaller as the sample size gets larger, which is consistent with the theoretical finding. Furthermore, Table 1 shows that the mean squared errors of $\hat{\boldsymbol{\alpha}}$ and $\hat{\boldsymbol{\beta}}$ are smaller than those computed via the MAVE method [see Table 1 of Xia and Härdle (2006)]. Table 2 suggests that the biases and their associated mean squared

TABLE 1
Simulation results for Example 4.1: the profile least-squares estimates (PrLS) and their corresponding mean squared errors ($\times 10^{-4}$) for model (4.1)

n	$\alpha_1 \,(= 0.7071)$	$\alpha_2 \,(= 0.7071)$	$\phi_0 \,(= 0.7854)$
50	0.7053 (21.5274)	0.7059 (21.3398)	0.7859 (42.9158)
100	0.7054 (8.5874)	0.7076 (8.4175)	0.7869 (17.0116)
200	0.7067 (4.4636)	0.7069 (4.4287)	0.7856 (8.8942)

TABLE 2
Simulation results for Example 4.1: *the profile least-squares estimates* (*PrLS*) *and their corresponding mean squared errors* ($\times 10^{-4}$) *for model* (4.2)

n	$\alpha_1 (= 0.5774)$	$\alpha_2 (= 0.5774)$	$\alpha_3 (= 0.5774)$	$\beta (= 0.3)$
50	0.5753 (5.8336)	0.5771 (5.5685)	0.5782 (5.9245)	0.2923 (11.4582)
100	0.5776 (2.5009)	0.5774 (2.4606)	0.5764 (2.4770)	0.3000 (4.7030)
200	0.5782 (1.1533)	0.5771 (1.0852)	0.5764 (1.2483)	0.3004 (2.2026)

errors of $\hat{\boldsymbol{\alpha}}$ and $\hat{\boldsymbol{\beta}}$ are comparable to those calculated via MAVE. In summary, the Monte Carlo studies indicate that PrLS performs well. Because the penalized MAVE is not easy to obtain, we study only the penalized PrLS estimates in the following example.

EXAMPLE 4.2. We simulated 500 realizations, each consisting of $n = 100$ and 200 random samples, from model (4.2) with $\sigma = 0.1$ and 0.25, respectively. The mean function has coefficients $\boldsymbol{\alpha} = (1, 3, 1.5, 0.5, 0, 0, 0, 0)^{\mathrm{T}}/\sqrt{12.5}$ and $\boldsymbol{\beta} = (3, 2, 0, 0, 0, 1.5, 0, 0.2, 0.3, 0.15, 0, 0)^{\mathrm{T}}$. To assess the robustness of estimates, we further generate the linear and nonlinear covariates from the following three scenarios: (i) the covariate vectors $\mathbf{X}$ and $\mathbf{Z}$ have 12 and 8 elements, respectively, which are independent and uniformly distributed on $[0, 1]$; (ii) the covariate vector $\mathbf{X}$ has 12 elements; the first 5 and last 5 elements are independent and standard normally distributed, while the 6th and 7th elements are independently Bernoulli distributed with success probability 0.5; the covariate vector $\mathbf{Z}$ has 8 elements, which are independent and standard normally distributed; (iii) a covariate vector W was generated from a 12-dimensional normal distribution with mean 0 and variance 0.25; the correlation between w_i and w_j is $\rho^{|i-j|}$ with $\rho = 0.4$; then the covariate vector $\mathbf{X} = W + \{1.5 \exp(1.5z_1), 5z_1, 5\sqrt{z_2}, 3z_1 + z_2^2, 0, 0, 0, 0, 0, 0, 0, 0\}^{\mathrm{T}}$; moreover, the covariate vector $\mathbf{Z}$ has 8 elements, which are independent and uniformly distributed on $[0, 1]$.

Based on the above model settings, we next explore the performance of the penalized profile least-squares approach via SCAD-BIC. Because the Akaike information criterion [Akaike (1973)] has been commonly used for classical variable selections, we also study SCAD-AIC by replacing $\log(n)$ in (2.8) with $2(p + q)$. To assess the performance, we consider Fan and Li's (2001) median of relative model error (MRME), where the relative model error is defined as $\mathrm{RME} = \mathrm{ME}/\mathrm{ME}_{S_F}$, ME is defined as $E(Z^{\mathrm{T}}\hat{\boldsymbol{\alpha}}_{\hat{\lambda}} - Z^{\mathrm{T}}\boldsymbol{\alpha})^2$ for $\hat{\boldsymbol{\alpha}}_{\hat{\lambda}}$ and $E(X^{\mathrm{T}}\hat{\boldsymbol{\beta}}_{\hat{\lambda}} - X^{\mathrm{T}}\boldsymbol{\beta})^2$ for $\hat{\boldsymbol{\beta}}_{\hat{\lambda}}$, and ME_{S_F} is the corresponding model error calculated by fitting the data with the full model via the unpenalized estimates. In addition, we calculate the average number of the true zero coefficients that were correctly set to zero and the average number of the truly nonzero coefficients that were incorrectly set to zero. Table 3 shows that

Simulation results for Example 4.2. S-AIC: SCAD(AIC); S-BIC: SCAD(BIC). MRME: median of relative model error; C: the average number of the true zero coefficients that were correctly set to zero; I: the average number of the truly nonzero coefficients that were incorrectly set to zero

| | | $\sigma = 0.1$ | | | | | | $\sigma = 0.25$ | | | | | |
| | | α | | | β | | | α | | | β | | |
n		MRME	C	I	MRME	C	I	MRME	C	I	MRME	C	I
							scenario (i)						
100	Oracle	0.26	4	0	0.28	6	0	0.2	4	0	0.27	6	0
	S-BIC	0.37	3.60	0.08	0.91	5.32	0.29	0.73	3.29	0.30	0.86	4.91	1.02
	S-AIC	0.66	3.08	0.05	0.97	4.12	0.15	0.75	2.70	0.11	0.91	4.02	0.68
200	Oracle	0.27	4	0	0.34	6	0	0.31	4	0	0.39	6	0
	S-BIC	0.33	3.89	0.02	0.85	5.55	0.02	0.36	3.86	0.03	0.94	5.50	0.57
	S-AIC	0.60	3.39	0.01	0.92	4.49	0.01	0.62	3.29	0.01	0.93	4.43	0.23
							scenario (ii)						
100	Oracle	0.29	4	0	0.35	6	0	0.24	4	0	0.24	6	0
	S-BIC	0.36	3.75	0.05	0.88	5.44	0.19	0.66	3.47	0.27	0.94	5.11	1.07
	S-AIC	0.65	3.26	0.02	0.91	4.35	0.07	0.70	2.86	0.09	0.96	4.04	0.67
200	Oracle	0.31	4	0	0.36	6	0	0.32	4	0	0.3	6	0
	S-BIC	0.36	3.91	0.01	0.79	5.64	0.01	0.40	3.87	0.03	0.85	5.53	0.50
	S-AIC	0.62	3.32	0	0.93	4.51	0.01	0.72	3.29	0.01	0.97	4.45	0.19
							scenario (iii)						
100	Oracle	0.28	4	0	0.15	6	0	0.19	4	0	0.18	6	0
	S-BIC	0.48	3.67	0.03	0.82	5.24	0.05	0.50	3.35	0.21	0.85	4.99	0.56
	S-AIC	0.74	3.09	0.02	0.94	4.35	0.03	0.71	2.70	0.12	0.98	4.17	0.32
200	Oracle	0.32	4	0	0.18	6	0	0.29	4	0	0.17	6	0
	S-BIC	0.39	3.89	0	0.73	5.52	0.01	0.39	3.80	0.04	0.83	5.29	0.12
	S-AIC	0.68	3.30	0	0.84	4.54	0	0.66	3.13	0.02	0.85	4.48	0.03

the SCAD-BIC outperforms SCAD-AIC in terms of model error measures. Moreover, SCAD-BIC has a much better rate of correctly identifying the true submodel than that of SCAD-AIC, although it sometimes shrinks small nonzero coefficients to zero. Unsurprisingly, SCAD-BIC improves as the signal gets stronger and the sample size becomes larger, which corroborates our theoretical findings.

EXAMPLE 4.3. To study the finite-sample performance of the test statistic T_1 in Section 3.1, we consider the same model as that of scenario (i) in Example 4.2. Due to the model's parameter setting, we naturally consider the following null and alternative hypotheses:

$$H_0 : \beta_3 = \beta_4 = \beta_5 = \beta_7 = 0 \quad \text{versus} \quad H_1 : \beta_3 = \beta_4 = \beta_5 = \beta_7 = c_1,$$
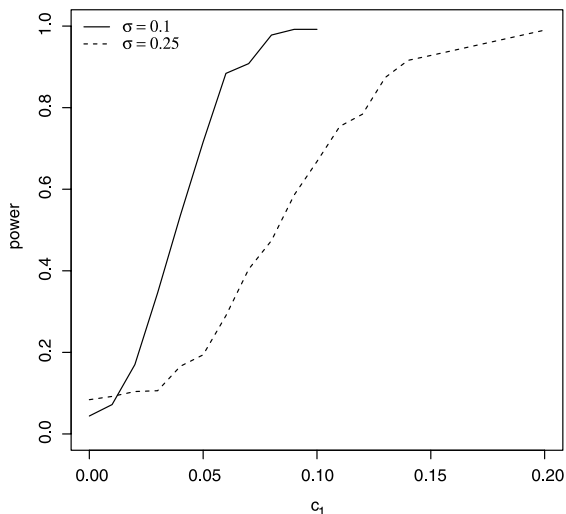
FIG. 1.   *Power function of the test statistic T_1.*

where c_1 ranges from 0 to 0.1 with increment 0.01 for $\sigma = 0.1$, whereas c_1 is the value from a set of $\{0, 0.01, 0.02, \ldots, 0.09, 0.15, 0.2\}$ for $\sigma = 0.25$. In addition, 500 realizations were generated with $n = 200$ to calculate the size and power of T_1. Figure 1 depicts the power function versus c_1. It shows that the empirical size at $c_1 = 0$ is very close to the nominal level 0.05. Furthermore, the power of the test is greater than 0.95 as c_1 increases to 0.05 and 0.15, respectively, when $\sigma = 0.1$ and $\sigma = 0.25$. It is not surprising that the power increases as the signal gets stronger. In summary, T_1 not only controls the size well, but is also a powerful test.

EXAMPLE 4.4.   To examine the performance of the test statistic T_2 in Section 3.2, we generated 500 realizations from the model given below with $n = 200$.

$$(4.3) \qquad y = \eta\{(z_1 + z_2 + z_3)/\sqrt{3}\} - 0.5x_1 + 0.3x_2 + \sigma\varepsilon,$$

where $\sigma = 0.1$ and $\sigma = 0.25$, respectively. We then consider the following hypotheses:

$$H_0 : \eta(u) = u \quad \text{versus} \quad H_1 : \eta(u) = c_2 \sin\{\pi(u - a)/(b - a)\} + u,$$

where c_2 ranges from 0 to 0.1 with increment 0.025 for $\sigma = 0.1$, while c_2 ranges from 0 to 0.2 with increment 0.05 for $\sigma = 0.25$. Figure 2 demonstrates that the empirical size at $c_2 = 0$ is very close to the nominal level 0.05. Furthermore, the power of the test is greater than 0.95 as c_2 increases to 0.075 and 0.2, respectively. As expected, the power increases when the signal becomes stronger. Although T_2 is slightly less powerful than T_1, it controls the size well and is a reliable test.

5. Discussion.   In partially linear single-index models, we propose using the SCAD approach to shrink parameters contained in both parametric and nonpara-
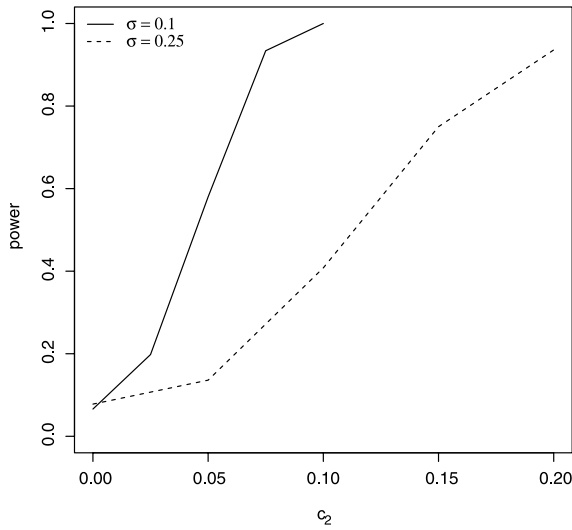
FIG. 2. *Power function of the test statistic T_2.*

metric components. The resulting estimators enjoy the oracle property when the regularization parameters satisfy the proper conditions. To further exploit SCAD, one could extend the current results to partially linear multiple-index models by allowing ε to be dependent on $(Z^T, X^T)^T$. In addition, one could obtain the SCAD estimator for generalized partially linear single-index models. Finally, an investigation of partially linear single-index model selection with error-prone covariates could also be of interest. We believe that these efforts would enhance the usefulness of SCAD in data analysis.

APPENDIX: PROOFS OF THEOREMS

A.1. Proof of Theorem 1. Under the conditions of Theorem 1, we follow similar arguments to those used by Ichimura (1993) and show that $\hat{\zeta} = (\hat{\alpha}^T, \hat{\beta}^T)^T$ is a root-n consistent estimator of ζ. Because the proof is straightforward, we do not present it here. We next demonstrate the asymptotic normality of $\hat{\zeta}$ by using a general result of Newey (1994).

Let $m_x(\Lambda) = E(X|\Lambda)$, $m_z(\Lambda) = E(Z|\Lambda)$ and $\kappa = \eta'(\Lambda)\{Z - m_z(\Lambda)\}$. In addition, let

$$(A.1) \qquad \Psi(m_x, \eta, \kappa, \alpha, \beta, Y, Z, X) = (Y - \eta - X^T\beta) \left\{ \begin{array}{c} \kappa \\ X - m_x(\Lambda) \end{array} \right\}.$$

For any given m_x^*, η^* and κ^*, define

$$D(m_x^* - m_x, \eta^* - \eta, \kappa^* - \kappa, \alpha, \beta, Y, Z, X)$$
$$= \frac{\partial \Psi}{\partial m_x}(m_x^* - m_x) + \frac{\partial \Psi}{\partial \eta}(\eta^* - \eta) + \frac{\partial \Psi}{\partial \kappa}(\kappa^* - \kappa),$$

where the partial derivatives are the Frechet partial derivatives. After algebraic simplification, we have

$$\frac{\partial \Psi}{\partial m_x} = (Y - \eta - X^{\mathrm{T}} \boldsymbol{\beta}) \begin{pmatrix} 0 \\ -1 \end{pmatrix},$$

$$\frac{\partial \Psi}{\partial \eta} = - \left\{ \begin{matrix} \kappa \\ X - m_x(\Lambda) \end{matrix} \right\},$$

$$\frac{\partial \Psi}{\partial \kappa} = (Y - \eta - X^{\mathrm{T}} \boldsymbol{\beta}) \begin{pmatrix} 1 \\ 0 \end{pmatrix},$$

where the partial derivatives are zero. Accordingly,

$$\begin{aligned} \| \Psi(m_x^*, \eta^*, \kappa^*, \boldsymbol{\alpha}, \boldsymbol{\beta}, Y, Z, X) &- \Psi(m_x, \eta, \kappa, \boldsymbol{\alpha}, \boldsymbol{\beta}, Y, Z, X) \\ &- D(m_x^* - m_x, \eta^* - \eta, \kappa^* - \kappa, \boldsymbol{\alpha}, \boldsymbol{\beta}, Y, Z, X) \| \\ &= O(\|m_x^* - m_x\|^2 + \|\eta^* - \eta\|^2 + \|\kappa^* - \kappa\|^2), \end{aligned}$$
(A.2)

where $\| \cdot \|$ denotes the Sobolev norm, that is, the supremum norm of the function itself, as well as its derivatives. Equation (A.2) is Newey's Assumption 5.1(i). It is also noteworthy that his Assumption 5.2 holds by the expression of $D(\cdot, \cdot, \cdot, \boldsymbol{\alpha}, \boldsymbol{\beta}, Y, Z, X)$. Moreover, the result

$$E\{D(m_x^* - m_x, \eta^* - \eta, \kappa^* - \kappa, \boldsymbol{\alpha}, \boldsymbol{\beta}, Y, Z, X)\} = 0$$

leads to Newey's Assumption 5.3.

In addition to Newey's assumptions mentioned above, we need to verify one more assumption before employing his result. To this end, we re-express the solution of (2.2) as

$$\hat{\eta}(u) = \frac{1}{n} \sum_{i=1}^{n} \frac{\{\hat{s}_2(u, h) - \hat{s}_1(u, h)(\Lambda_i - u)\} K_h(\Lambda_i - u)(Y_i - X_i^{\mathrm{T}} \boldsymbol{\beta})}{\hat{s}_2(u, h)\hat{s}_0(u, h) - \hat{s}_1^2(u, h)},$$

where Λ_i is the ith row of Λ and

$$\hat{s}_r(u, h) = \frac{1}{n} \sum_{i=1}^{n} (\Lambda_i - u)^r K_h(\Lambda_i - u) \qquad \text{for } r = 0, 1, 2.$$

Then, let

$$\hat{m}_x(u) = \frac{1}{n} \sum_{i=1}^{n} \frac{\{\hat{s}_2(u, h) - \hat{s}_1(u, h)(\Lambda_i - u)\} K_h(\Lambda_i - u) X_i^{\mathrm{T}}}{\hat{s}_2(u, h)\hat{s}_0(u, h) - \hat{s}_1^2(u, h)},$$

$$\hat{m}_z(u) = \frac{1}{n} \sum_{i=1}^{n} \frac{\{\hat{s}_2(u, h) - \hat{s}_1(u, h)(\Lambda_i - u)\} K_h(\Lambda_i - u) Z_i^{\mathrm{T}}}{\hat{s}_2(u, h)\hat{s}_0(u, h) - \hat{s}_1^2(u, h)}.$$

Applying similar techniques to those used in Mack and Silverman (1982), we obtain the following equations, which hold uniformly in $u \in \mathcal{U}$:

$$\hat{\eta}(u) - \eta(u) = o_p(n^{-1/4}), \qquad \hat{\eta}'(u) - \eta'(u) = o_p(n^{-1/4}),$$

(A.3)

$$\hat{m}_x(u) - m_x(u) = o_p(n^{-1/4}) \quad \text{and} \quad \hat{m}_z(u) - m_z(u) = o_p(n^{-1/4}).$$

These results imply that $\hat{\kappa} - \kappa = o_p(n^{-1/4})$. Thus, Newey's Assumption 5.1(ii) holds.

After examining Newey's Assumptions 5.1–5.3, we apply his Lemma 5.1 and find that $\hat{\boldsymbol{\zeta}}$ has the same limit distribution as the solution to the equation

$$(A.4) \qquad 0 = \sum_{i=1}^{n} \Psi(m_x, \eta, \kappa, \boldsymbol{\alpha}, \boldsymbol{\beta}, Y_i, Z_i, X_i).$$

Furthermore, it is easy to show that the solution to (A.4) has the same limit distribution as described in the statement of Theorem 1. Hence, we complete the proof of asymptotic normality.

Finally, we show the efficiency of $\hat{\boldsymbol{\zeta}}$. Let $p_\varepsilon(\varepsilon)$ be the probability density function of ε and let $p_\varepsilon'(\varepsilon)$ be its first-order derivative with respect to ε. Then, the score function of $(\boldsymbol{\alpha}, \boldsymbol{\beta})$ is

$$S_{(\boldsymbol{\alpha}, \boldsymbol{\beta})} = -\sigma^2 \left\{ \begin{array}{c} \eta'(\Lambda)Z \\ X \end{array} \right\} \frac{p_\varepsilon'(\varepsilon)}{p_\varepsilon(\varepsilon)}.$$

For any given function g of (Z, X), it can be shown that the nuisance tangent space $\mathcal{P}$, for the three nuisance parameters, $g_{(Z,X)}(z, x)$, $p_\varepsilon(\varepsilon)$ and $\eta(\Lambda)$, is $\{g(Z, X) : E(g) = 0, E(\varepsilon g) \text{ is a function of } (Z, X) \text{ only}\}$. Furthermore, the orthogonal component of $\mathcal{P}$ is

$$\mathcal{P}^\perp = \{\varepsilon g(Z, X) : E(g|\Lambda) = 0\}.$$

Subsequently, we apply the approach of Bickel et al. (1993) and obtain the following semiparametric efficient score function via equation (2.4):

$$(A.5) \qquad S_{\text{eff}} = \varepsilon \left\{ \begin{array}{c} \eta'(\Lambda)\widetilde{Z} \\ \widetilde{X} \end{array} \right\}.$$

It can be seen that $S_{\text{eff}} \in \mathcal{P}^\perp$.

For any $\varepsilon g \in \mathcal{P}^\perp$, we have $E(g|\Lambda) = 0$. Accordingly,

$$E\{(S_{(\boldsymbol{\alpha}, \boldsymbol{\beta})} - S_{\text{eff}})^{\mathrm{T}} \varepsilon g(Z, X)\}$$

$$= E\left(-\sigma^2 \left\{ \begin{array}{c} \eta'(\Lambda)Z \\ X \end{array} \right\}^{\mathrm{T}} g E\left\{ \frac{\varepsilon p_\varepsilon'(\varepsilon)}{p_\varepsilon(\varepsilon)} \right\} \right.$$

$$\left. - E(\varepsilon^2) \left[\left\{ \begin{array}{c} \eta'(\Lambda)Z \\ X \end{array} \right\}^{\mathrm{T}} g - E\left\{ \begin{array}{c} \eta'(\Lambda)E(Z|\Lambda) \\ E(X|\Lambda) \end{array} \right\}^{\mathrm{T}} g \right] \right).$$

Because $E\{\varepsilon p'_\varepsilon(\varepsilon)/p_\varepsilon(\varepsilon)\} = -1$, it follows that

$$E\{(S_{(\boldsymbol{\alpha},\boldsymbol{\beta})} - S_{\mathrm{eff}})^{\mathrm{T}} \varepsilon g(Z, X)\} = E[\{\eta'(\Lambda)E(Z^{\mathrm{T}}|\Lambda), E(X^{\mathrm{T}}|\Lambda)\}E(g|\Lambda)] = 0.$$

That is, S_{eff} is the projection of $S_{(\boldsymbol{\alpha},\boldsymbol{\beta})}$ onto $\mathcal{P}^\perp$ and the estimator $\hat{\boldsymbol{\zeta}}$ is therefore efficient [see Bickel et al. (1993)]. We have thus completed the proof.

A.2. Proof of Theorem 2. To prove this theorem, we consider the following three steps: Step I establishes the order of the minimizer $(\hat{\boldsymbol{\alpha}}_{\lambda_1}^{\mathrm{T}}, \hat{\boldsymbol{\beta}}_{\lambda_2}^{\mathrm{T}})^{\mathrm{T}}$ of $\mathcal{L}_P(\boldsymbol{\alpha}, \boldsymbol{\beta})$; Step II shows that $(\hat{\boldsymbol{\alpha}}_{\lambda_1}^{\mathrm{T}}, \hat{\boldsymbol{\beta}}_{\lambda_2}^{\mathrm{T}})^{\mathrm{T}}$ attains sparsity; Step III derives the asymptotic distribution of the penalized estimators.

Step I. Let $\gamma_n = n^{-1/2} + a_n + c_n$, $\mathbf{v}_1 = (v_{11}, \dots, v_{1p})^{\mathrm{T}}$, $\mathbf{v}_2 = (v_{21}, \dots, v_{2q})^{\mathrm{T}}$ and $\|\mathbf{v}_1\| = \|\mathbf{v}_2\| = C$ for some positive constant C, where

$$a_n = \max_{1 \le j \le p} \{|p'_{\lambda_{1j}}(|\alpha_{0j}|)|, \alpha_{0j} \ne 0\},$$

$$c_n = \max_{1 \le k \le q} \{|p'_{\lambda_{2k}}(|\beta_{0k}|)|, \beta_{0k} \ne 0\},$$

and α_{0j} and β_{0k} are the jth and kth elements of $\boldsymbol{\alpha}_0$ and $\boldsymbol{\beta}_0$, respectively, for $j = 1, \dots, p$ and $k = 1, \dots, q$. Furthermore, define

$$D_{n,1} = \sum_{i=1}^n \{Y_i - \hat{\eta}(Z_i^{\mathrm{T}}(\boldsymbol{\alpha}_0 + \gamma_n \mathbf{v}_1), \boldsymbol{\alpha}_0 + \gamma_n \mathbf{v}_1, \boldsymbol{\beta}_0 + \gamma_n \mathbf{v}_2) - X_i^{\mathrm{T}}(\boldsymbol{\beta}_0 + \gamma_n \mathbf{v}_2)\}^2$$

$$- \sum_{i=1}^n \{Y_i - \hat{\eta}(X_i^{\mathrm{T}}\boldsymbol{\alpha}_0, \boldsymbol{\alpha}_0, \boldsymbol{\beta}_0) - X_i^{\mathrm{T}}\boldsymbol{\beta}_0\}^2$$

and

$$D_{n,2} = -n \sum_{j=1}^{p_0} \{p_{\lambda_{1j}}(|\alpha_{0j} + \gamma_n v_{1j}|) - p_{\lambda_{1j}}(|\alpha_{0j}|)\}$$

$$- n \sum_{k=1}^{q_0} \{p_{\lambda_{2k}}(|\beta_{0k} + \gamma_n v_{2k}|) - p_{\lambda_{2k}}(|\beta_{0k}|)\}.$$

After algebraic simplification, we have

(A.6)
$$D_{n,1} = \sum_{i=1}^n \{\hat{\eta}(Z_i^{\mathrm{T}}(\boldsymbol{\alpha}_0 + \gamma_n \mathbf{v}_1), \boldsymbol{\alpha}_0 + \gamma_n \mathbf{v}_1, \boldsymbol{\beta}_0 + \gamma_n \mathbf{v}_2)$$
$$- \hat{\eta}(Z_i^{\mathrm{T}}\boldsymbol{\alpha}_0, \boldsymbol{\alpha}_0, \boldsymbol{\beta}_0) + X_i^{\mathrm{T}}\gamma_n \mathbf{v}_2\}$$
$$\times \{\hat{\eta}(Z_i^{\mathrm{T}}(\boldsymbol{\alpha}_0 + \gamma_n \mathbf{v}_1), \boldsymbol{\alpha}_0 + \gamma_n \mathbf{v}_1, \boldsymbol{\beta}_0 + \gamma_n \mathbf{v}_2)$$
$$+ \hat{\eta}(Z_i^{\mathrm{T}}\boldsymbol{\alpha}_0, \boldsymbol{\alpha}_0, \boldsymbol{\beta}_0) + X_i^{\mathrm{T}}(\boldsymbol{\beta}_0 + \gamma_n \mathbf{v}_2) + X_i^{\mathrm{T}}\boldsymbol{\beta}_0 - 2Y_i\}$$

$$= \sum_{i=1}^{n} \{\widetilde{Z}_i^{\mathrm{T}} \eta'(\Lambda_i) \mathbf{v}_1 \gamma_n + \widetilde{X}_i^{\mathrm{T}} \mathbf{v}_2 \gamma_n\}^2$$

$$- \sum_{i=1}^{n} \{\widetilde{Z}_i^{\mathrm{T}} \eta'(\Lambda_i) \mathbf{v}_1 \gamma_n + \widetilde{X}_i^{\mathrm{T}} \mathbf{v}_2 \gamma_n\} \varepsilon_i + o_p(1).$$

Moreover, applying the Taylor expansion and the Cauchy–Schwarz inequality, we are able to show that $n^{-1} D_{n,2}$ is bounded by

$$\sqrt{p_0} \gamma_n a_n \|\mathbf{v}_1\| + \gamma_n^2 b_n \|\mathbf{v}_1\|^2 + \sqrt{q_0} \gamma_n c_n \|\mathbf{v}_2\| + \gamma_n^2 d_n \|\mathbf{v}_2\|^2$$

$$\leq C \gamma_n^2 (\sqrt{p_0} + b_n C + \sqrt{q_0} + d_n C),$$

where

$$b_n = \max_{1 \leq j \leq p} \{|p''_{\lambda_{1j}}(|\alpha_{0j}|)|, \alpha_{0j} \neq 0\}, \qquad d_n = \max_{1 \leq k \leq q} \{|p''_{\lambda_{2k}}(|\beta_{0k}|)|, \beta_{0k} \neq 0\}.$$

When b_n and d_n tend to 0 and C is sufficiently large, the first term on the right-hand side of (A.6) dominates the second term on the right-hand side of (A.6) and $D_{n,2}$. As a result, for any given $\nu > 0$, there exists a large constant C such that

$$P\left\{\inf_{\mathcal{V}_{12}} \mathcal{L}_P(\boldsymbol{\alpha}_0 + \gamma_n \mathbf{v}_1, \boldsymbol{\beta}_0 + \gamma_n \mathbf{v}_2) > \mathcal{L}_P(\boldsymbol{\alpha}_0, \boldsymbol{\beta}_0)\right\} \geq 1 - \nu,$$

where $\mathcal{V}_{12} = \{(\mathbf{v}_1, \mathbf{v}_2) : \|\mathbf{v}_1\| = C, \|\mathbf{v}_2\| = C\}$. We therefore conclude that the rate of convergence of $(\hat{\boldsymbol{\alpha}}_{\lambda_1}^{\mathrm{T}}, \hat{\boldsymbol{\beta}}_{\lambda_2}^{\mathrm{T}})^{\mathrm{T}}$ is $O_P(n^{-1/2} + a_n + c_n)$.

Step II. Let $\boldsymbol{\alpha}_1$ and $\boldsymbol{\beta}_1$ satisfy $\|\boldsymbol{\alpha}_1 - \boldsymbol{\alpha}_{10}\| = O_P(n^{-1/2})$ and $\|\boldsymbol{\beta}_1 - \boldsymbol{\beta}_{10}\| = O_P(n^{-1/2})$, respectively. We next show that

$$(A.7) \qquad \mathcal{L}_P\left\{\begin{pmatrix} \boldsymbol{\alpha}_1 \\ \mathbf{0} \end{pmatrix}, \begin{pmatrix} \boldsymbol{\beta}_1 \\ \mathbf{0} \end{pmatrix}\right\} = \min_{\mathcal{C}} \mathcal{L}_P\left\{\begin{pmatrix} \boldsymbol{\alpha}_1 \\ \boldsymbol{\alpha}_2 \end{pmatrix}, \begin{pmatrix} \boldsymbol{\beta}_1 \\ \boldsymbol{\beta}_2 \end{pmatrix}\right\},$$

where $\mathcal{C} = \{\|\boldsymbol{\alpha}_2\| \leq C^* n^{-1/2}, \|\boldsymbol{\beta}_2\| \leq C^* n^{-1/2}\}$ and C^* is a positive constant.

Consider $\beta_k \in (-C^* n^{-1/2}, C^* n^{-1/2})$ for $k = q_0 + 1, \ldots, q$. When $\beta_k \neq 0$, we have $\partial \mathcal{L}_P(\boldsymbol{\alpha}, \boldsymbol{\beta}) / \partial \beta_k = \ell_k(\boldsymbol{\alpha}, \boldsymbol{\beta}) + n p'_{\lambda_{2k}}(|\beta_k|) \operatorname{sgn}(\beta_k)$, where

$$\ell_k(\boldsymbol{\alpha}, \boldsymbol{\beta}) = \frac{1}{n} \sum_{i=1}^{n} \{Y_i - \hat{\eta}(Z_i^{\mathrm{T}} \boldsymbol{\alpha}, \boldsymbol{\alpha}, \boldsymbol{\beta}) + X_i^{\mathrm{T}} \boldsymbol{\beta}\} \left\{X_{ik} + \frac{\partial \hat{\eta}(Z_i^{\mathrm{T}} \boldsymbol{\alpha}, \boldsymbol{\alpha}, \boldsymbol{\beta})}{\partial \beta_k}\right\}$$

$$= \frac{1}{n} \sum_{i=1}^{n} \{\hat{\eta}(Z_i^{\mathrm{T}} \boldsymbol{\alpha}, \boldsymbol{\alpha}, \boldsymbol{\beta}) - \eta(Z_i^{\mathrm{T}} \boldsymbol{\alpha}_0) + X_i^{\mathrm{T}} (\boldsymbol{\beta} - \boldsymbol{\beta}_0) - \varepsilon_i\}$$

$$\times \left\{X_{ik} + \frac{\partial \hat{\eta}(Z_i^{\mathrm{T}} \boldsymbol{\alpha}, \boldsymbol{\alpha}, \boldsymbol{\beta})}{\partial \beta_k}\right\}.$$

Applying arguments similar to those used in the proof of Theorem 5.2 of Ichimura (1993), together with algebraic simplifications, the above term can be

expressed as

$$\frac{1}{n}\sum_{i=1}^{n}(\boldsymbol{\alpha}-\boldsymbol{\alpha}_0)^{\mathrm{T}}\widetilde{Z}_i\eta'(\Lambda_i)\widetilde{X}_{ik} + \frac{1}{n}\sum_{i=1}^{n}(\boldsymbol{\beta}-\boldsymbol{\beta}_0)^{\mathrm{T}}\widetilde{X}_i\widetilde{X}_{ik} + o_p(n^{-1/2}).$$

Using the assumptions that $\|\boldsymbol{\alpha}-\boldsymbol{\alpha}_0\| = O_P(n^{-1/2})$ and $\|\boldsymbol{\beta}-\boldsymbol{\beta}_0\| = O_P(n^{-1/2})$, we have that $n^{-1}\ell_k(\boldsymbol{\alpha},\boldsymbol{\beta})$ is of the order $O_P(n^{-1/2})$. Therefore,

$$\frac{\partial\mathcal{L}_P(\boldsymbol{\alpha},\boldsymbol{\beta})}{\partial\beta_k} = -n\lambda_{2k}\{\lambda_{2k}^{-1}p_{\lambda_{2k}}'(|\beta_k|)\operatorname{sgn}(\beta_k) + O_P(n^{-1/2}\lambda_{2k}^{-1})\}.$$

Because $\liminf_{n\to\infty}\liminf_{\beta_j\to 0^+}\lambda_{2k}^{-1}p_{\lambda_{2k}}'(|\beta_k|) > 0$ and $n^{-1/2}/\lambda_{2k} \to 0$, $\partial\mathcal{L}_P(\boldsymbol{\alpha},\boldsymbol{\beta})/\partial\beta_k$ and β_k have different signs for $\beta_k \in (-C^*n^{-1/2}, C^*n^{-1/2})$. Analogously, we can show that $\partial\mathcal{L}_P(\boldsymbol{\alpha},\boldsymbol{\beta})/\partial\alpha_j$ and α_j have different signs when $\alpha_j \in (-C^*n^{-1/2}, C^*n^{-1/2})$ for $j = p_0+1,\ldots,p$. Consequently, the minimum is attained at $\boldsymbol{\alpha}_2 = 0$ and $\boldsymbol{\beta}_2 = 0$. This completes the proof of (A.7).

Step III. Finally, we demonstrate the asymptotic normality of $\hat{\boldsymbol{\alpha}}_{\lambda_1 1}$ and $\hat{\boldsymbol{\beta}}_{\lambda_2 1}$. For the sake of simplicity, we define

$$\mathbf{R}_{\lambda_1} = \{p_{\lambda_{11}}'(|\alpha_{01}|)\operatorname{sgn}(\alpha_{01}),\ldots,p_{\lambda_{1p_0}}'(|\alpha_{0p_0}|)\operatorname{sgn}(\alpha_{0p_0})\}^{\mathrm{T}},$$

$$\Sigma_{\lambda_1} = \operatorname{diag}\{p_{\lambda_{11}}''(|\alpha_{01}|),\ldots,p_{\lambda_{1p_0}}''(|\alpha_{0p_0}|)\},$$

$$\mathbf{R}_{\lambda_2} = \{p_{\lambda_{21}}'(|\beta_{01}|)\operatorname{sgn}(\beta_{01}),\ldots,p_{\lambda_{2q_0}}'(|\beta_{0q_0}|)\operatorname{sgn}(\beta_{0q_0})\}^{\mathrm{T}},$$

$$\Sigma_{\lambda_2} = \operatorname{diag}\{p_{\lambda_{21}}''(|\beta_{01}|),\ldots,p_{\lambda_{2q_0}}''(|\beta_{0q_0}|)\},$$

where α_{0j} and β_{0k} are the jth and kth elements of $\boldsymbol{\alpha}_{10}$ and $\boldsymbol{\beta}_{10}$, respectively, for $j = 1,\ldots,p_0$ and $k = 1,\ldots,q_0$. It follows from (2.5) that $\hat{\boldsymbol{\alpha}}_{\lambda_1 1}$ and $\hat{\boldsymbol{\beta}}_{\lambda_2 1}$ satisfy

(A.8)
$$\mathbf{0} = \left\{\begin{array}{c}\dfrac{\partial\mathcal{L}_P(\hat{\boldsymbol{\alpha}}_{\lambda_1 1},\hat{\boldsymbol{\beta}}_{\lambda_2 1})}{\partial\boldsymbol{\alpha}_1} \\[2mm] \dfrac{\partial\mathcal{L}_P(\hat{\boldsymbol{\alpha}}_{\lambda_1 1},\hat{\boldsymbol{\beta}}_{\lambda_2 1})}{\partial\boldsymbol{\beta}_1}\end{array}\right\}$$
$$= l(\hat{\boldsymbol{\alpha}}_{\lambda_1 1},\hat{\boldsymbol{\beta}}_{\lambda_2 1}) + \left\{\begin{array}{c}\mathbf{R}_{\lambda_1} - \Sigma_{\lambda_1}(\hat{\boldsymbol{\alpha}}_{\lambda_1 1}-\boldsymbol{\alpha}_{10}) \\ \mathbf{R}_{\lambda_2} - \Sigma_{\lambda_2}(\hat{\boldsymbol{\beta}}_{\lambda_2 1}-\boldsymbol{\beta}_{10})\end{array}\right\},$$

where

$$l(\hat{\boldsymbol{\alpha}}_{\lambda_1 1},\hat{\boldsymbol{\beta}}_{\lambda_2 1}) = \frac{1}{n}\sum_{i=1}^{n}\{Y_i - \hat{\eta}(\Lambda_i,\hat{\boldsymbol{\zeta}}_{\lambda_1}) - X_{i,1}^{\mathrm{T}}\hat{\boldsymbol{\beta}}_{\lambda_2 1}\}\left\{\begin{array}{c}\dfrac{\partial\hat{\eta}(\hat{\Lambda}_i,\hat{\boldsymbol{\zeta}}_{\lambda_1})}{\partial\boldsymbol{\alpha}} \\[2mm] \dfrac{\partial\hat{\eta}(\hat{\Lambda}_i,\hat{\boldsymbol{\zeta}}_{\lambda_1})}{\partial\boldsymbol{\beta}} + X_{i,1}\end{array}\right\},$$

$\hat{\Lambda}_i$ and $X_{i,1}$ here being the ith rows of $\hat{\Lambda}$ and X_1, respectively, and $\hat{\boldsymbol{\zeta}}_{\lambda_1} = (\hat{\boldsymbol{\alpha}}_{\lambda_1 1}^{\mathrm{T}},\hat{\boldsymbol{\beta}}_{\lambda_2 1}^{\mathrm{T}})^{\mathrm{T}}$ being the penalized least-squares estimator of $\boldsymbol{\zeta}_1 = (\boldsymbol{\alpha}_1^{\mathrm{T}},\boldsymbol{\beta}_1^{\mathrm{T}})^{\mathrm{T}}$.

Applying the Taylor expansion, we obtain

$$
l(\hat{\boldsymbol{\alpha}}_{\lambda_1 1}, \hat{\boldsymbol{\beta}}_{\lambda_2 1}) = \frac{1}{n} \sum_{i=1}^{n} \{Y_i - \hat{\eta}(\Lambda_i, \boldsymbol{\zeta}_1) - X_{i,1}^{\mathrm{T}} \boldsymbol{\beta}_1\}
\left\{
\begin{array}{c}
\dfrac{\partial \hat{\eta}(\Lambda_i, \boldsymbol{\zeta}_1)}{\partial \boldsymbol{\alpha}_1} \\[2mm]
\dfrac{\partial \hat{\eta}(\Lambda_i, \boldsymbol{\zeta}_1)}{\partial \boldsymbol{\beta}_1} + X_{i,1}
\end{array}
\right\}
$$

$$
- \frac{1}{n} \sum_{i=1}^{n}
\left\{
\begin{array}{c}
\dfrac{\partial \hat{\eta}(\bar{\Lambda}_i, \bar{\boldsymbol{\zeta}}_1)}{\partial \boldsymbol{\alpha}_1} \\[2mm]
\dfrac{\partial \hat{\eta}(\bar{\Lambda}_i, \bar{\boldsymbol{\zeta}}_1)}{\partial \boldsymbol{\beta}_1} + X_{i,1}
\end{array}
\right\}^{\otimes 2}
(\hat{\boldsymbol{\zeta}}_{\lambda 1} - \boldsymbol{\zeta}_1)
$$

$$
- \frac{1}{n} \sum_{i=1}^{n} \{Y_i - \hat{\eta}(\bar{\Lambda}_i, \bar{\boldsymbol{\zeta}}_1) - X_{i,1}^{\mathrm{T}} \bar{\boldsymbol{\beta}}_1\} \frac{\partial^2 \hat{\eta}(\bar{\Lambda}_i, \bar{\boldsymbol{\zeta}}_1)}{\partial \boldsymbol{\zeta}_1 \partial \boldsymbol{\zeta}_1^{\mathrm{T}}} (\hat{\boldsymbol{\zeta}}_{\lambda 1} - \boldsymbol{\zeta}_1),
$$

where $\bar{\boldsymbol{\beta}}_1$, $\bar{\Lambda}_i$ and $\bar{\boldsymbol{\zeta}}_1$ are the interior points between $\boldsymbol{\beta}_1$ and $\hat{\boldsymbol{\beta}}_{\lambda_2 1}$, Λ_i and $\hat{\Lambda}_i$, and $\boldsymbol{\zeta}_1$ and $\hat{\boldsymbol{\zeta}}_{\lambda 1}$, respectively. Furthermore, using arguments similar to those used in the proof of Theorem 1, we have that

$$
l(\hat{\boldsymbol{\alpha}}_{\lambda_1 1}, \hat{\boldsymbol{\beta}}_{\lambda_2 1}) = \frac{1}{\sqrt{n}} \sum_{i=1}^{n}
\left\{
\begin{array}{c}
\widetilde{Z}_{i,1} \eta'(\Lambda_i) \\
\widetilde{X}_{i,1}
\end{array}
\right\} \varepsilon_i
$$

$$
- \frac{1}{n} \sum_{i=1}^{n}
\left\{
\begin{array}{c}
\widetilde{Z}_{i,1} \eta'(\Lambda_i) \\
\widetilde{X}_{i,1}
\end{array}
\right\}^{\otimes 2}
\sqrt{n}
\begin{pmatrix}
\hat{\boldsymbol{\alpha}}_{\lambda_1 1} - \boldsymbol{\alpha}_{10} \\
\hat{\boldsymbol{\beta}}_{\lambda_2 1} - \boldsymbol{\beta}_{10}
\end{pmatrix} + o_p(1).
$$

Moreover, the summand of the matrix over n in the second term of the above equation converges to $\begin{pmatrix} \Gamma_{\widetilde{Z}_1 \widetilde{Z}_1} & \Gamma_{\widetilde{X}_1 \widetilde{Z}_1} \\ \Gamma_{\widetilde{X}_1 \widetilde{Z}_1}^{\mathrm{T}} & \Gamma_{\widetilde{X}_1 \widetilde{X}_1} \end{pmatrix}$. These results, together with (A.8), lead to

$$
n^{1/2}
\begin{pmatrix}
\Gamma_{\widetilde{Z}_1 \widetilde{Z}_1} + \Sigma_{\lambda_1} & \Gamma_{\widetilde{X}_1 \widetilde{Z}_1} \\
\Gamma_{\widetilde{X}_1 \widetilde{Z}_1}^{\mathrm{T}} & \Gamma_{\widetilde{X}_1 \widetilde{X}_1} + \Sigma_{\lambda_2}
\end{pmatrix}
\begin{pmatrix}
\hat{\boldsymbol{\alpha}}_{\lambda_1 1} - \boldsymbol{\alpha}_{10} \\
\hat{\boldsymbol{\beta}}_{\lambda_2 1} - \boldsymbol{\beta}_{10}
\end{pmatrix} - n^{1/2}
\begin{pmatrix}
\mathbf{R}_{\lambda_1} \\
\mathbf{R}_{\lambda_2}
\end{pmatrix}
$$

$$
= \frac{1}{\sqrt{n}} \sum_{i=1}^{n}
\left\{
\begin{array}{c}
\widetilde{Z}_{i,1} \eta'(\Lambda_i) \varepsilon_i \\
\widetilde{X}_{i,1} \varepsilon_i
\end{array}
\right\} + o_p(1).
$$

It follows that

$$
n^{1/2}(\Gamma_{\widetilde{Z}_1 \widetilde{Z}_1} + \Sigma_{\lambda_1})(\hat{\boldsymbol{\alpha}}_{\lambda_1 1} - \boldsymbol{\alpha}_{10}) + n^{1/2} \Gamma_{\widetilde{X}_1 \widetilde{Z}_1}(\hat{\boldsymbol{\beta}}_{\lambda_2 1} - \boldsymbol{\beta}_{10}) - n^{1/2} \mathbf{R}_{\lambda_1}
$$

$$
= \frac{1}{\sqrt{n}} \sum_{i=1}^{n} \widetilde{Z}_{i,1} \eta'(\Lambda_i) \varepsilon_i + o_p(1)
$$

and

$$
n^{1/2} \Gamma_{\widetilde{X}_1 \widetilde{Z}_1}^{\mathrm{T}} (\hat{\boldsymbol{\alpha}}_{\lambda_1 1} - \boldsymbol{\alpha}_{10}) + n^{1/2}(\Gamma_{\widetilde{X}_1 \widetilde{X}_1} + \Sigma_{\lambda_2})(\hat{\boldsymbol{\beta}}_{\lambda_2 1} - \boldsymbol{\beta}_{10}) - n^{1/2} \mathbf{R}_{\lambda_2}
$$

$$
= \frac{1}{\sqrt{n}} \sum_{i=1}^{n} \widetilde{X}_{i,1} \varepsilon_i + o_p(1).
$$

After simplification, we have

$$\sqrt{n}\{(\Gamma_{\widetilde{Z}_1 \widetilde{Z}_1} + \Sigma_{\lambda_1}) - \Gamma_{\widetilde{X}_1 \widetilde{Z}_1}(\Gamma_{\widetilde{X}_1 \widetilde{X}_1} + \Sigma_{\lambda_2})^{-1}\Gamma_{\widetilde{X}_1 \widetilde{Z}_1}^{\mathrm{T}}\}(\hat{\boldsymbol{\alpha}}_{\lambda_1 1} - \boldsymbol{\alpha}_{10})$$

$$\text{(A.9)} \quad + n^{1/2}\{\Gamma_{\widetilde{X}_1 \widetilde{Z}_1}(\Gamma_{\widetilde{X}_1 \widetilde{X}_1} + \Sigma_{\lambda_1})^{-1}\mathbf{R}_{\lambda_1} - \mathbf{R}_{\lambda_2}\}$$

$$= \frac{1}{\sqrt{n}}\sum_{i=1}^{n}\{\widetilde{Z}_{i,1}\eta'(\Lambda_i) - \Gamma_{\widetilde{X}_1 \widetilde{Z}_1}(\Gamma_{\widetilde{X}_1 \widetilde{X}_1} + \Sigma_{\lambda_2})^{-1}\widetilde{X}_{i,1}\}\varepsilon_i + o_p(1)$$

and

$$\sqrt{n}\{(\Gamma_{\widetilde{X}_1 \widetilde{X}_1} + \Sigma_{\lambda_2}) - \Gamma_{\widetilde{X}_1 \widetilde{Z}_1}^{\mathrm{T}}(\Gamma_{\widetilde{Z}_1 \widetilde{Z}_1} + \Sigma_{\lambda_1})^{-1}\Gamma_{\widetilde{X}_1 \widetilde{Z}_1}\}(\hat{\boldsymbol{\beta}}_{\lambda_2 1} - \boldsymbol{\beta}_{10})$$

$$\text{(A.10)} \quad + n^{1/2}\{\Gamma_{\widetilde{X}_1 \widetilde{Z}_1}^{\mathrm{T}}(\Gamma_{\widetilde{Z}_1 \widetilde{Z}_1} + \Sigma_{\lambda_1})^{-1}\mathbf{R}_{\lambda_2} - \mathbf{R}_{\lambda_1}\}$$

$$= \frac{1}{\sqrt{n}}\sum_{i=1}^{n}\{\widetilde{X}_{i,1} - \Gamma_{\widetilde{X}_1 \widetilde{Z}_1}^{\mathrm{T}}(\Gamma_{\widetilde{Z}_1 \widetilde{Z}_1} + \Sigma_{\lambda_1})^{-1}\widetilde{Z}_{i,1}\eta'(\Lambda_i)\}\varepsilon_i + o_p(1).$$

Equations (A.9) and (A.10), together with the central limit theorem, yield that

$$\sqrt{n}\{\Gamma_{\widetilde{Z}_1 \widetilde{Z}_1} + \Sigma_{\lambda_1} - \Gamma_{\widetilde{X}_1 \widetilde{Z}_1}(\Gamma_{\widetilde{X}_1 \widetilde{X}_1} + \Sigma_{\lambda_2})^{-1}\Gamma_{\widetilde{X}_1 \widetilde{Z}_1}^{\mathrm{T}}\}(\hat{\boldsymbol{\alpha}}_{\lambda_1 1} - \boldsymbol{\alpha}_{10})$$

$$+ n^{1/2}\{\Gamma_{\widetilde{X}_1 \widetilde{Z}_1}(\Gamma_{\widetilde{X}_1 \widetilde{X}_1} + \Sigma_{\lambda_2})^{-1}\mathbf{R}_{\lambda_1} - \mathbf{R}_{\lambda_2}\} \to N(0, \Sigma_{\boldsymbol{\alpha}_1})$$

and

$$\sqrt{n}\{\Gamma_{\widetilde{X}_1 \widetilde{X}_1} + \Sigma_{\lambda_2} - \Gamma_{\widetilde{X}_1 \widetilde{Z}_1}^{\mathrm{T}}(\Gamma_{\widetilde{Z}_1 \widetilde{Z}_1} + \Sigma_{\lambda_1})^{-1}\Gamma_{\widetilde{X}_1 \widetilde{Z}_1}\}(\hat{\boldsymbol{\beta}}_{\lambda_2 1} - \boldsymbol{\beta}_{10})$$

$$+ n^{1/2}\{\Gamma_{\widetilde{X}_1 \widetilde{Z}_1}^{\mathrm{T}}(\Gamma_{\widetilde{Z}_1 \widetilde{Z}_1} + \Sigma_{\lambda_1})^{-1}\mathbf{R}_{\lambda_2} - \mathbf{R}_{\lambda_1}\} \to N(0, \Sigma_{\boldsymbol{\beta}_1}),$$

where

$$\Sigma_{\boldsymbol{\alpha}_1} = \{\Gamma_{\widetilde{Z}_1 \widetilde{Z}_1} - 2\Gamma_{\widetilde{X}_1 \widetilde{Z}_1}(\Gamma_{\widetilde{X}_1 \widetilde{X}_1} + \Sigma_{\lambda_2})^{-1}\Gamma_{\widetilde{X}_1 \widetilde{Z}_1}^{\mathrm{T}}$$

$$+ \Gamma_{\widetilde{X}_1 \widetilde{Z}_1}(\Gamma_{\widetilde{X}_1 \widetilde{X}_1} + \Sigma_{\lambda_2})^{-1}\Gamma_{\widetilde{X}_1 \widetilde{X}_1}(\Gamma_{\widetilde{X}_1 \widetilde{X}_1} + \Sigma_{\lambda_2})^{-1}\Gamma_{\widetilde{X}_1 \widetilde{Z}_1}^{\mathrm{T}}\}\sigma^2$$

and

$$\Sigma_{\boldsymbol{\beta}_1} = \{\Gamma_{\widetilde{X}_1 \widetilde{X}_1} - 2\Gamma_{\widetilde{X}_1 \widetilde{Z}_1}^{\mathrm{T}}(\Gamma_{\widetilde{Z}_1 \widetilde{Z}_1} + \Sigma_{\lambda_1})^{-1}\Gamma_{\widetilde{X}_1 \widetilde{Z}_1}$$

$$+ \Gamma_{\widetilde{X}_1 \widetilde{Z}_1}^{\mathrm{T}}(\Gamma_{\widetilde{Z}_1 \widetilde{Z}_1} + \Sigma_{\lambda_1})^{-1}\Gamma_{\widetilde{Z}_1 \widetilde{Z}_1}(\Gamma_{\widetilde{Z}_1 \widetilde{Z}_1} + \Sigma_{\lambda_1})^{-1}\Gamma_{\widetilde{X}_1 \widetilde{Z}_1}\}\sigma^2.$$

Because each element of $n^{1/2}\Sigma_{\lambda_1}$, $n^{1/2}\Sigma_{\lambda_2}$, $n^{1/2}\mathbf{R}_{\lambda_1}$ and $n^{1/2}\mathbf{R}_{\lambda_2}$ tends to zero, we complete the proof.

A.3. Proof of Theorem 3. Let $\tau_n = \log(n)$, $\lambda_{n1j} = \tau_n \, \mathrm{SE}(\hat{\alpha}_j^u)$, $\lambda_{n2k} = \tau_n \, \mathrm{SE}(\hat{\beta}_k^u)$ and

$$\mathrm{BIC}(S_T) = \log\{\sigma_n^2(S_T)\} + \{\log(n)/n\} \, \mathrm{DF}(S_T),$$

where $\mathrm{DF}(S_T)$ stands for the degrees of freedom of the true model S_T. $\mathrm{SE}(\hat{\alpha}_k^u) = O(1/\sqrt{n})$ and $\mathrm{SE}(\hat{\beta}_j^u) = O(1/\sqrt{n})$. Thus, $\lambda_{n1j} = O_P(\log(n)/\sqrt{n})$ and $\lambda_{n2k} = O_P(\log(n)/\sqrt{n})$. Then, employing techniques similar to those used in Wang, Li and Tsai (2007), we obtain that

$$(A.11) \qquad P\{\mathrm{BIC}(\tau_n) = \mathrm{BIC}(S_T)\} = 1.$$

Therefore, to prove the theorem, it suffices to show that

$$(A.12) \qquad P\left\{ \inf_{\lambda \in \Omega_- \cup \Omega_+} \mathrm{BIC}(\lambda) > \mathrm{BIC}(\tau_n) \right\} \to 1,$$

where

$$\Omega_- = \{\lambda : S_\lambda \not\supset S_T\} \quad \text{and} \quad \Omega_+ = \{\lambda : S_\lambda \supset S_T\}$$

represent the underfitted and overfitted models, respectively.

To demonstrate (A.12), we consider two separate cases given below.

Case 1: Underfitted model (i.e., the model misses at least one covariate from the true model). For any $\lambda \in \Omega_-$, (A.11). together with assumptions (A) and (B), implies that, with probability tending to one,

$$\begin{aligned}
\mathrm{BIC}(\lambda) - \mathrm{BIC}(\tau_n) &= \log\{\mathrm{MSE}(\lambda)\} + \{\log(n)/n\} \, \mathrm{DF}_\lambda - \mathrm{BIC}(S_T) \\
&\geq \log\{\mathrm{MSE}(\lambda)\} - \mathrm{BIC}(S_T) \\
&\geq \log\{\sigma_n^2(S_\lambda)\} - \mathrm{BIC}(S_T) \\
&\geq \inf_{\lambda \in \Omega_-} \log\{\sigma_n^2(S_\lambda)\} - \mathrm{BIC}(S_T) \\
&\geq \min_{S \not\supset S_T} \log\{\sigma_n^2(S)\} - \log\{\sigma_n^2(S_T)\} - \{\log(n)/n\} \, \mathrm{DF}(S_T) \\
&\to \min_{S \not\supset S_T} \log\{\sigma^2(S)/\sigma^2(S_T)\} \geq 0.
\end{aligned}$$

Case 2: Overfitted model (i.e., the model contains all of the covariates in the true model and includes at least one covariate that does not belong to the true model). For any $\lambda \in \Omega_+$, it follows by (A.11) that, with probability tending to one,

$$\begin{aligned}
n\{\mathrm{BIC}(\lambda) - \mathrm{BIC}(\tau_n)\} &= n\{\mathrm{BIC}(\lambda) - \mathrm{BIC}(S_T)\} \\
&= n \log\{\mathrm{MSE}(\lambda)/\sigma_n^2(S_T)\} + (\mathrm{DF}_\lambda - \mathrm{DF}_{S_T}) \log(n) \\
&\geq n \log\{\sigma_n^2(S_\lambda)/\sigma_n^2(S_T)\} + (\mathrm{DF}_\lambda - \mathrm{DF}_{S_T}) \log(n) \\
&= \frac{n\{\sigma_n^2(S_\lambda) - \sigma_n^2(S_T)\}}{\sigma_n^2(S_T)}\{1 + o_P(1)\} \\
&\quad + (\mathrm{DF}_\lambda - \mathrm{DF}_{S_T}) \log(n).
\end{aligned}$$

Applying the result of Theorem 4, we know that $n\{\sigma_n^2(S_\lambda) - \sigma_n^2(S_T)\}/\sigma_n^2(S_T)$ is an asymptotically chi-squared distribution with $\mathrm{DF}_\lambda - \mathrm{DF}_{S_T}$ degrees of freedom. Accordingly, we obtain that $n\{\sigma_n^2(S_\lambda) - \sigma_n^2(S_T)\}/\sigma_n^2(S_T) = O_P(1)$. Moreover, for any $\lambda \in \Omega_+$, $\mathrm{DF}_\lambda - \mathrm{DF}_{S_T} \geq 1$, and hence $(\mathrm{DF}_\lambda - \mathrm{DF}_{S_T})\log(n)$ diverges to $+\infty$ as $n \to \infty$. Consequently,

$$P\Big\{\inf_{\lambda \in \Omega_+} n\{\mathrm{BIC}(\lambda) - \mathrm{BIC}(\tau_n)\} > 0\Big\} = P\Big\{\inf_{\lambda \in \Omega_+} \mathrm{BIC}(\lambda) - \mathrm{BIC}(\tau_n) > 0\Big\} \to 1.$$

The results of Cases 1 and 2 complete the proof.

A.4. Proof of Theorem 4. We apply techniques similar to those used in the proofs of Theorems 3.1 and 3.2 in Fan and Huang (2005) to show this theorem. Accordingly, we only provide a sketch of a proof here; detailed derivations can be obtained from the authors upon request.

Let

$$B_n = \left[\sum_{i=1}^n \left\{ \begin{matrix} \eta'(\Lambda_i)\hat{Z}_i \\ \hat{X}_i \end{matrix} \right\}^{\otimes 2}\right]^{-1} \mathbf{A}^{\mathrm{T}} \left(\mathbf{A}\left[\sum_{i=1}^n \left\{ \begin{matrix} \eta'(\Lambda_i)\hat{Z}_i \\ \hat{X}_i \end{matrix} \right\}^{\otimes 2}\right]^{-1} \mathbf{A}^{\mathrm{T}}\right)^{-1} \mathbf{A}.$$

The difference $Q(H_0) - Q(H_1)$ can be expressed as

$$\sum_{i=1}^n \{Y_i - X_i^{\mathrm{T}}\hat{\boldsymbol{\beta}}_0 - \hat{\eta}(Z_i^{\mathrm{T}}\hat{\boldsymbol{\alpha}}_0, \hat{\boldsymbol{\xi}}_0)\}^2 - \sum_{i=1}^n \{Y_i - X_i^{\mathrm{T}}\hat{\boldsymbol{\beta}}_1 - \hat{\eta}(Z_i^{\mathrm{T}}\hat{\boldsymbol{\alpha}}_1, \hat{\boldsymbol{\xi}}_1)\}^2$$

$$= \sum_{i=1}^n \{\hat{\eta}(Z_i^{\mathrm{T}}\hat{\boldsymbol{\alpha}}_1, \hat{\boldsymbol{\xi}}_1) - \hat{\eta}(Z_i^{\mathrm{T}}\hat{\boldsymbol{\alpha}}_0, \hat{\boldsymbol{\xi}}_0) + X_i^{\mathrm{T}}(\hat{\boldsymbol{\beta}}_1 - \hat{\boldsymbol{\beta}}_0)\}^2$$

(A.13)
$$+ 2\sum_{i=1}^n \{Y_i - X_i^{\mathrm{T}}\hat{\boldsymbol{\beta}}_1 - \hat{\eta}(Z_i^{\mathrm{T}}\hat{\boldsymbol{\alpha}}_1, \hat{\boldsymbol{\xi}}_1)\}$$

$$\times \{\hat{\eta}_1(Z_i^{\mathrm{T}}\hat{\boldsymbol{\alpha}}_1, \hat{\boldsymbol{\xi}}_1) - \hat{\eta}(Z_i^{\mathrm{T}}\hat{\boldsymbol{\alpha}}_0, \hat{\boldsymbol{\xi}}_0) + X_i^{\mathrm{T}}(\hat{\boldsymbol{\beta}}_1 - \hat{\boldsymbol{\beta}}_0)\}$$

$$\stackrel{\mathrm{def}}{=} Q_1 + Q_2.$$

It can be shown that Q_2 is asymptotically negligible in probability. Furthermore, Q_1 can be simplified as

$$Q_1 = (\hat{\boldsymbol{\xi}}_1 - \hat{\boldsymbol{\xi}}_0)^{\mathrm{T}} \sum_{i=1}^n \left\{ \begin{matrix} \eta'(Z_i^{\mathrm{T}}\hat{\boldsymbol{\alpha}}_0, \hat{\boldsymbol{\xi}}_0)\hat{Z}_i \\ \hat{X}_i \end{matrix} \right\}^{\otimes 2} (\hat{\boldsymbol{\xi}}_1 - \hat{\boldsymbol{\xi}}_0) + o_p(1).$$

A direct calculation yields that $\hat{\boldsymbol{\xi}}_0 = \hat{\boldsymbol{\xi}}_1 - B_n\hat{\boldsymbol{\xi}}_1$. This, together with the asymptotic normality and consistency of $\hat{\boldsymbol{\xi}}_1$ obtained from Theorem 1, implies that $\sigma^{-2}Q_1 \to$

χ_m^2 in distribution under H_0. Moreover, under H_1, $\sigma^{-2} Q_1$ asymptotically follows a noncentral chi-squared distribution with m degrees of freedom and noncentrality parameter ϕ. This completes the proof.

A.5. Proof of Theorem 5.   It is noteworthy that

$$
\begin{aligned}
\text{RSS}(H_0) &= \sum_{i=1}^{n} \{Y_i - X_i^{\mathrm{T}} \boldsymbol{\beta} - \widetilde{\eta}(Z_i^{\mathrm{T}} \hat{\boldsymbol{\alpha}})\}^2 \\
&\quad + \sum_{i=1}^{n} [\{Y_i - X_i^{\mathrm{T}} \hat{\boldsymbol{\beta}} - \hat{\eta}(Z_i^{\mathrm{T}} \hat{\boldsymbol{\alpha}})\}^2 - \{Y_i - X_i^{\mathrm{T}} \boldsymbol{\beta} - \widetilde{\eta}(Z_i^{\mathrm{T}} \hat{\boldsymbol{\alpha}})\}^2] \\
&\stackrel{\text{def}}{=} \text{RSS}^*(H_0) + I_{n0}
\end{aligned}
$$

and

$$
\begin{aligned}
\text{RSS}(H_1) &= \sum_{i=1}^{n} \{Y_i - X_i^{\mathrm{T}} \boldsymbol{\beta} - \hat{\eta}(Z_i^{\mathrm{T}} \hat{\boldsymbol{\alpha}})\}^2 \\
&\quad + \sum_{i=1}^{n} [\{Y_i - X_i^{\mathrm{T}} \hat{\boldsymbol{\beta}} - \hat{\eta}(Z_i^{\mathrm{T}} \hat{\boldsymbol{\alpha}})\}^2 - \{Y_i - X_i^{\mathrm{T}} \boldsymbol{\beta} - \hat{\eta}(Z_i^{\mathrm{T}} \hat{\boldsymbol{\alpha}})\}^2] \\
&\stackrel{\text{def}}{=} \text{RSS}^*(H_1) + I_{n1}.
\end{aligned}
$$

Applying similar arguments to those in the proof of Theorem 5 in Fan, Zhang and Zhang (2001), under H_0, we have

$$
\frac{n r_K}{2} \frac{\text{RSS}^*(H_0) - \text{RSS}^*(H_1)}{\text{RSS}^*(H_1)} \sim \chi_{df_n}^2,
$$

where df_n is defined as in Theorem 5 and it approaches infinity as $n \to \infty$. Furthermore, it can be straightforwardly shown that $n^{-1} I_{n0} = \sigma^2 \{1 + o_P(1)\}$ and $n^{-1} I_{n1} = \sigma^2 \{1 + o_P(1)\}$. These results complete the proof.

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