

## STOCHASTIC STABILITY OF ANOSOV DIFFEOMORPHISMS

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### § 0. Introduction

R. Bowen [1] introduced the notion of pseudo-orbit for a homeomorphism  $f$  of a metric space  $X$  as follows: A (double) sequence  $\{x_i\}_{i \in \mathbb{Z}}$  of points  $x_i$  in  $X$  is called a  $\delta$ -pseudo-orbit of  $f$  iff

$$d(fx_i, x_{i+1}) \leq \delta$$

for every  $i \in \mathbb{Z}$ , where  $d$  denotes the metric in  $X$ . We say  $f$  is stochastically stable if for every  $\varepsilon > 0$  there exists  $\delta > 0$  such that every  $\delta$ -pseudo-orbit  $\{x_i\}_{i \in \mathbb{Z}}$  of  $f$  is  $\varepsilon$ -traced by some  $x \in X$ , i.e.,

$$d(f^i x, x_i) \leq \varepsilon$$

for every  $i \in \mathbb{Z}$ . He proved in [1] that if a compact hyperbolic set  $A$  for a diffeomorphism  $f$  of a compact manifold  $M$  has local product structure then the restriction  $f|_A$  of  $f$  to  $A$  is stochastically stable, using stable and unstable manifolds.

In this paper we prove first that an Anosov diffeomorphism  $f$  of a compact manifold  $M$  is topologically stable, in the set of all continuous maps of  $M$  into  $M$ , in a sense (Theorem 1). Next, making use of Theorem 1 we give another proof for Bowen's result, in the case of  $f$  an Anosov diffeomorphism (Theorem 2). The idea of this paper is inspired by a result of A. Morimoto [2], which says that a topologically stable homeomorphism  $f$  of a manifold  $M$  with  $\dim M \geq 3$  is stochastically stable. The method of the proof follows that of P. Walters [3].

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### § 1. Preparatory lemmas

$M$  will always denote a compact  $C^\infty$  manifold without boundary.

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DEFINITION 1. A  $C^1$  diffeomorphism  $f$  of  $M$  is called an Anosov diffeomorphism if there exist a Riemannian metric  $\|\cdot\|$  on  $M$  and constants  $C > 0$ ,  $0 < \lambda < 1$  such that the tangent bundle of  $M$  can be written as the Whitney sum of two continuous subbundles,  $TM = E^s \oplus E^u$ , and the following conditions are satisfied:

$$(1.1) \quad Tf(E^\sigma) = E^\sigma \quad (\sigma = s, u) .$$

$$(1.2) \quad \begin{aligned} \|Tf^n(v)\| &\leq C\lambda^n \|v\|, & v \in E^s, n \geq 0, \\ \|Tf^{-n}(v)\| &\leq C\lambda^n \|v\|, & v \in E^u, n \geq 0. \end{aligned}$$

$f$  will always denote an Anosov diffeomorphism of  $M$ . We can find a Riemannian metric for which we can take  $C = 1$ , and fix it (cf. [3]). Let  $\mathfrak{X}(M)$  denote the Banach space of all continuous vector fields with the norm

$$\|v\| = \sup_{x \in M} \|v(x)\|, \quad v \in \mathfrak{X}(M) .$$

Let  $\mathfrak{X}^\sigma(M)$  denote the subspace of all  $v \in \mathfrak{X}(M)$  with  $v(x) \in E_x^\sigma$  for every  $x \in M$  ( $\sigma = s, u$ ). Clearly  $\mathfrak{X}(M) = \mathfrak{X}^s(M) \oplus \mathfrak{X}^u(M)$  (direct sum). We define a linear operator  $f_\# : \mathfrak{X}(M) \rightarrow \mathfrak{X}(M)$  by

$$f_\#(v) = Tf \circ v \circ f^{-1}, \quad v \in \mathfrak{X}(M) .$$

Let  $d(\cdot, \cdot)$  denote the metric on  $M$  induced by  $\|\cdot\|$ , and for each  $x \in M$   $\exp_x : TM_x \rightarrow M$  denote the exponential map with respect to  $\|\cdot\|$ . Let  $\text{Map}(M)$  denote the metric space of all continuous maps of  $M$  into  $M$  with the metric

$$d(\phi, \psi) = \sup_{x \in M} d(\phi x, \psi x), \quad \phi, \psi \in \text{Map}(M) .$$

For  $\delta > 0$  we put  $\text{Map}(M, \delta) = \{\phi \in \text{Map}(M) : d(\phi, \text{id}) \leq \delta\}$ , and  $\sum_\delta = \{(x, y) \in M \times M : d(x, y) \leq \delta\}$ .

The following lemma is due to P. Walters [3].

LEMMA 1. *There exist  $\delta_1 > 0$  and  $\tau_1 > 0$  satisfying the following conditions:*

(1.3) *For every  $(x, y) \in \sum_{\delta_1}$  there exists a linear isomorphism  $L_{(x,y)} : TM_x \rightarrow TM_y$  such that  $L_{(x,y)}(E_x^\sigma) = E_y^\sigma$  ( $\sigma = s, u$ ), and  $L_{(x,y)}$  is continuous with respect to  $(x, y) \in \sum_{\delta_1}$ .*

(1.4) *For every  $(x, y) \in \sum_{\delta_1}$  there exists a continuous map  $\gamma_{(x,y)} : TM_x(\tau_1) \rightarrow TM_y$  such that*

$$\exp_x(v) = \exp_y(L_{(x,y)}(v) + \gamma_{(x,y)}(v)), \quad v \in TM_x(\tau_1)$$

and  $\gamma_{(x,y)}$  is continuous with respect to  $(x, y) \in \Sigma_{\delta_1}$ , where  $TM_x(\tau_1) = \{v \in TM_x : \|v\| \leq \tau_1\}$ .

$$(1.5) \quad x = \exp_y(\gamma_{(x,y)}(0)), \quad (x, y) \in \Sigma_{\delta_1}.$$

$$(1.6) \quad \|L_{(x,y)}\| \text{ and } \|(L_{(x,y)})^{-1}\| \text{ converge uniformly to 1 as } d(x, y) \rightarrow 0.$$

(1.7) For every  $(x, y) \in \Sigma_{\delta_1}$  there exists  $K(x, y) \geq 0$  such that

$$\|\gamma_{(x,y)}(v) - \gamma_{(x,y)}(v')\| \leq K(x, y) \|v - v'\|, \quad v, v' \in TM_x(\tau_1)$$

and  $K(x, y)$  converges uniformly to 0 as  $d(x, y) \rightarrow 0$ .

*Proof.* See Lemma 1 [3].

**DEFINITION 2.** For  $\phi \in \text{Map}(M, \delta_1)$  we define continuous linear maps  $J_\phi, R_\phi: \mathfrak{X}(M) \rightarrow \mathfrak{X}(M)$ , a continuous map  $\gamma_\phi: \mathfrak{X}(M)(\tau_1) \rightarrow \mathfrak{X}(M)$ , and a constant  $K(\phi) \geq 0$  as follows: For  $v \in \mathfrak{X}(M)$  and  $x \in M$

$$J_\phi(v)(x) = L_{(\phi x, x)}(v(\phi x)),$$

$$R_\phi(v)(x) = (L_{(x, \phi x)})^{-1}(v(\phi x)).$$

For  $v \in \mathfrak{X}(M)(\tau_1)$  and  $x \in M$

$$\gamma_\phi(v)(x) = \gamma_{(\phi x, x)}(v(\phi x)),$$

where  $\mathfrak{X}(M)(\tau_1) = \{v \in \mathfrak{X}(M) : \|v\| \leq \tau_1\}$ .

$$K(\phi) = \sup_{x \in M} K(\phi x, x).$$

By Lemma 1 we have the following lemma:

**LEMMA 2.** For  $\phi \in \text{Map}(M, \delta_1)$ ,  $v, v' \in \mathfrak{X}(M)(\tau_1)$  and  $x \in M$

$$(1.8) \quad J_\phi(\mathfrak{X}^\sigma(M)) \subset \mathfrak{X}^\sigma(M), \quad R_\phi(\mathfrak{X}^\sigma(M)) \subset \mathfrak{X}^\sigma(M) \quad (\sigma = s, u),$$

$$(1.9) \quad \exp_{\phi x} v(\phi x) = \exp_x (J_\phi(v) + \gamma_\phi(v))(x),$$

$$(1.10) \quad \exp_x \gamma_\phi(0) = \phi(x),$$

$$(1.11) \quad \|\gamma_\phi(v) - \gamma_\phi(v')\| \leq K(\phi) \|v - v'\|, \\ K(\phi) \longrightarrow 0 \text{ as } d(\phi, \text{id}) \longrightarrow 0,$$

$$(1.12) \quad \|J_\phi\|, \|R_\phi\| \longrightarrow 1 \text{ as } d(\phi, \text{id}) \longrightarrow 0.$$

**LEMMA 3.** If  $\phi, \psi \in \text{Map}(M, \delta_1)$  and a subset  $S$  of  $M$  satisfy

$$\psi\phi(x) = x$$

for every  $x \in S$ , then

$$(1.13) \quad R_\psi J_\phi(v)(\phi x) = v(\phi x) ,$$

$$(1.14) \quad J_\phi R_\psi(v)(x) = v(x)$$

for every  $x \in S$  and  $v \in \mathfrak{X}(M)$ .

*Proof.* By Definition 2 we have

$$\begin{aligned} J_\phi R_\psi(v)(x) &= L_{(\phi x, x)}(R_\psi(v)(\phi x)) \\ &= L_{(\phi x, x)}(L_{(\phi x, \psi\phi x)})^{-1}(v(\psi\phi x)) \\ &= v(x) , \end{aligned}$$

which proves (1.14). Similarly, we have

$$\begin{aligned} R_\psi J_\phi(v)(\phi x) &= (L_{(\phi x, \psi\phi x)})^{-1}(J_\phi(v)(\psi\phi x)) \\ &= (L_{(\phi x, x)})^{-1}L_{(\phi x, x)}(v(\phi x)) \\ &= v(\phi x) , \end{aligned}$$

which proves (1.13).

LEMMA 4. *There exists  $\tau_2 > 0$  satisfying the following conditions: For every  $v \in \mathfrak{X}(M)(\tau_2)$  there exists  $s(v) \in \mathfrak{X}(M)$  such that*

$$(1.15) \quad \begin{aligned} f \exp_{f^{-1}x} v(f^{-1}x) &= \exp_x (f_\#(v) + s(v))(x) , \quad x \in M, \\ s(0) &= 0 , \end{aligned}$$

$$(1.16) \quad \|s(v) - s(v')\| \leq C(\tau_2) \|v - v'\|$$

for every  $v, v' \in \mathfrak{X}(M)(\tau_2)$ , where  $C(\tau_2) \rightarrow 0$  as  $\tau_2 \rightarrow 0$ .

*Proof.* See Lemma 2 [3].

LEMMA 5. *There exist constants  $0 < \delta_2 < \delta_1$  and  $\alpha > 0$  satisfying the following conditions: For every  $\phi, \psi \in \text{Map}(M, \delta_2)$  there exist a constant  $\mu(\phi, \psi) > 0$  and a continuous linear map  $P = P_{\phi, \psi}: \mathfrak{X}(M) \rightarrow \mathfrak{X}(M)$  such that if a subset  $S$  of  $M$  satisfies*

$$\psi\phi(x) = x$$

for every  $x \in S$ , then

$$(1.17) \quad (I - R_\psi f_\#)P(v)(\phi x) = v(\phi x)$$

for every  $x \in S$ , and

$$(1.18) \quad \|P\| \leq \frac{\alpha}{1 - \mu(\phi, \psi)\lambda},$$

$\mu(\phi, \psi) \longrightarrow 1$  as  $d(\phi, \text{id}), d(\psi, \text{id}) \longrightarrow 0$ .

*Proof.* There exists  $\alpha > 0$  such that

$$(1.19) \quad \|v_s\| + \|v_u\| \leq \alpha \|v_s + v_u\|$$

for every  $v_\sigma \in \mathfrak{X}^\sigma(M)$  ( $\sigma = s, u$ ). For  $\phi, \psi \in \text{Map}(M, \delta_1)$  we put

$$(1.20) \quad \mu(\phi, \psi) = \text{Max} \{\|J_\phi\|, \|R_\psi\|\}.$$

Then, by (1.12) there exists  $0 < \delta_2 \leq \delta_1$  and  $\lambda_1$  such that

$$(1.21) \quad \mu(\phi, \psi)\lambda < \lambda_1 < 1$$

for every  $\phi, \psi \in \text{Map}(M, \delta_2)$ .

By (1.1) and (1.8) we can define as follows:  $f_\#^\sigma = f_\#|_{\mathfrak{X}^\sigma(M)}$ ,  $J_\phi^\sigma = J_\phi|_{\mathfrak{X}^\sigma(M)}$  and  $R_\psi^\sigma = R_\psi|_{\mathfrak{X}^\sigma(M)}$  ( $\sigma = s, u$ ). By (1.2), (1.20) and (1.21) we have

$$\|R_\psi^s f_\#^s\| \leq \|R_\psi^s\| \|f_\#^s\| \leq \mu(\phi, \psi)\lambda < 1.$$

Therefore, the Neumann series  $\sum_{n=0}^{\infty} (R_\psi^s f_\#^s)^n$  is convergent. Putting  $P_s = \sum_{n=0}^{\infty} (R_\psi^s f_\#^s)^n$  we have

$$(1.22) \quad \|P_s\| \leq \frac{1}{1 - \mu(\phi, \psi)\lambda}.$$

Similarly, since  $\|(f_\#^u)^{-1} J_\phi^u\| \leq \mu(\phi, \psi)\lambda < 1$  the Neumann series  $\sum_{n=1}^{\infty} ((f_\#^u)^{-1} J_\phi^u)^n$  is convergent. Putting  $P_u = -\sum_{n=1}^{\infty} ((f_\#^u)^{-1} J_\phi^u)^n$  we have

$$(1.23) \quad \|P_u\| \leq \frac{1}{1 - \mu(\phi, \psi)\lambda}.$$

Now we put  $P = P_s + P_u$ . By (1.19), (1.22) and (1.23) we get

$$\|P\| \leq \alpha \text{Max} \{\|P_s\|, \|P_u\|\} \leq \frac{\alpha}{1 - \mu(\phi, \psi)\lambda},$$

which proves (1.18). Next, we shall prove (1.17). By (1.13) and (1.14) we have

$$\begin{aligned} & (I - R_\psi^u f_\#^u) P_u(v)(\phi x) \\ &= P_u(v)(\phi x) + R_\psi^u f_\#^u (f_\#^u)^{-1} J_\phi^u \left[ \sum_{n=0}^{\infty} ((f_\#^u)^{-1} J_\phi^u)^n(v) \right] (\phi x) \\ &= P_u(v)(\phi x) + \sum_{n=0}^{\infty} ((f_\#^u)^{-1} J_\phi^u)^n(v)(\phi x) \\ &= v(\phi x) \end{aligned}$$

for  $v \in \mathfrak{X}^u(M)$  and  $x \in S$ . Clearly,  $(I - R_{\psi}^* f_{\frac{\delta}{2}}^*)P_s = I$ .

Thus, we have proved (1.17).

## §2. Proof of Theorem 1

**THEOREM 1.** *An Anosov diffeomorphism  $f$  of  $M$  is topologically stable in the following sense: For every  $\varepsilon > 0$  there exists  $\delta = \delta(\varepsilon) > 0$  satisfying the following conditions: If  $g, \tilde{g} \in \text{Map}(M)$  with  $d(f, g), d(f\tilde{g}, \text{id}) \leq \delta$  and a subset  $S$  of  $M$  satisfy*

$$\tilde{g}g(x) = x$$

for every  $x \in S$ , then there exists  $h \in \text{Map}(M)$  such that

$$(2.1) \quad hg(x) = fh(x)$$

for every  $x \in S$ , and

$$(2.2) \quad d(h, \text{id}) \leq \varepsilon .$$

*Proof.* First, take  $\varepsilon_0 \leq \text{Min}\{\tau_1, \tau_2, \varepsilon\}$  so small that for every  $\phi, \psi \in \text{Map}(M, \delta_2)$

$$(2.3) \quad \frac{\alpha\mu(\phi, \psi)}{1 - \mu(\phi, \psi)\lambda} C(\varepsilon_0) \leq \frac{1}{4} .$$

This is possible since  $C(\varepsilon_0) \rightarrow 0$  as  $\varepsilon_0 \rightarrow 0$ . Next, take  $0 < \delta \leq \delta_2$  so small that for every  $\phi, \psi \in \text{Map}(M, \delta)$

$$(2.4) \quad \frac{\alpha\mu(\phi, \psi)}{1 - \mu(\phi, \psi)\lambda} \delta \leq \frac{1}{2} \varepsilon_0$$

and

$$(2.5) \quad \frac{\alpha\mu(\phi, \psi)}{1 - \mu(\phi, \psi)\lambda} K(\phi) \leq \frac{1}{4} .$$

This is possible since  $K(\phi) \rightarrow 0$  as  $d(\phi, \text{id}) \rightarrow 0$ .

For  $\phi, \psi \in \text{Map}(M, \delta)$  we define a continuous map  $\Phi : \mathfrak{X}(M)(\varepsilon_0) \rightarrow \mathfrak{X}(M)$  by

$$\Phi(v) = P_{\phi, \psi} R_{\psi}(s(v) - \gamma_{\phi}(v)) , \quad v \in \mathfrak{X}(M)(\varepsilon_0) .$$

To find a fixed point of  $\Phi$  we shall first show that the Lipschitz constant of  $\Phi \leq \frac{1}{2}$ . Take two elements  $v, v' \in \mathfrak{X}(M)(\varepsilon_0)$ . By (1.11), (1.16), (1.18), (1.20), (2.3) and (2.5) we have

$$\begin{aligned}
& \|\Phi(v) - \Phi(v')\| \\
& \leq \|P\| \|R_\psi\| (\|s(v) - s(v')\| + \|\gamma_\phi(v) - \gamma_\phi(v')\|) \\
& \leq \frac{\alpha\mu(\phi, \psi)}{1 - \mu(\phi, \psi)\lambda} (C(\varepsilon_0) \|v - v'\| + K(\phi) \|v - v'\|) \\
& \leq (\tfrac{1}{4} + \tfrac{1}{4}) \|v - v'\| = \tfrac{1}{2} \|v - v'\|.
\end{aligned}$$

Next, we shall show  $\Phi(\mathfrak{X}(M)(\varepsilon_0)) \subset \mathfrak{X}(M)(\varepsilon_0)$ . By (1.10), (1.15), (1.18), (1.20) and (2.4) we have

$$\begin{aligned}
\|\Phi(v)\| & \leq \|\Phi(0)\| + \|\Phi(v) - \Phi(0)\| \\
& \leq \|P\| \|R_\psi\| \delta + \tfrac{1}{2} \|v\| \\
& \leq \frac{\alpha\mu(\phi, \psi)}{1 - \mu(\phi, \psi)\lambda} \delta + \frac{1}{2} \varepsilon_0 \\
& \leq \tfrac{1}{2} \varepsilon_0 + \tfrac{1}{2} \varepsilon_0 = \varepsilon_0
\end{aligned}$$

for  $v \in \mathfrak{X}(M)(\varepsilon_0)$ . Thus,  $\Phi$  is a contraction of a complete metric space  $\mathfrak{X}(M)(\varepsilon_0)$ . Therefore,  $\Phi$  has a unique fixed point  $v_0 = v_0(\phi, \psi) \in \mathfrak{X}(M)(\varepsilon_0)$ , i.e.

$$(2.6) \quad v_0 = P_{\phi, \psi} R_\psi (s(v_0) - \gamma_\phi(v_0)).$$

We put  $h (= h_{\phi, \psi}) = \exp v_0$ .

Now assume that  $g, \tilde{g} \in \text{Map}(M)$  with  $d(f, g), d(f\tilde{g}, \text{id}) \leq \delta$  and a subset  $S$  of  $M$  satisfy that  $\tilde{g}g(x) = x$  for every  $x \in S$ . Putting  $\phi = gf^{-1}$  and  $\psi = f\tilde{g}$  we see that  $\phi, \psi \in \text{Map}(M, \delta)$  and  $\psi\phi(fx) = f(x)$  for every  $x \in S$ . By Definition 2, (1.14), (1.17) and (2.6) we obtain

$$\begin{aligned}
& J_\phi(v_0)(fx) - f_\#(v_0)(fx) \\
& = J_\phi(v_0)(fx) - J_\phi R_\psi f_\#(v_0)(fx) \\
& = J_\phi(I - R_\psi f_\#)(v_0)(fx) \\
& = J_\phi(I - R_\psi f_\#) P R_\psi (s(v_0) - \gamma_\phi(v_0))(fx) \\
& = L_{(\phi fx, fx)} [(I - R_\psi f_\#) P R_\psi (s(v_0) - \gamma_\phi(v_0))(\phi fx)] \\
& = L_{(\phi fx, fx)} [R_\psi (s(v_0) - \gamma_\phi(v_0))(\phi fx)] \\
& = L_{(\phi fx, fx)} (L_{(\phi fx, \psi\phi fx)})^{-1} ((s(v_0) - \gamma_\phi(v_0))(\psi\phi fx)) \\
& = s(v_0)(fx) - \gamma_\phi(v_0)(fx)
\end{aligned}$$

for every  $x \in S$ . Thus we have

$$(2.7) \quad (J_\phi(v_0) + \gamma_\phi(v_0))(fx) = (f_\#(v_0) + s(v_0))(fx)$$

for every  $x \in S$ . By (1.9), (1.15) and (2.7), for every  $x \in S$  we have

$$\begin{aligned}
hg(x) &= \exp_{\phi, fx} v_0(\phi fx) \\
&= \exp_{fx} (J_{\phi}(v_0) + \gamma_{\phi}(v_0))(fx) \\
&= \exp_{fx} (f_{\#}(v_0) + s(v_0))(fx) \\
&= f \exp_{f^{-1}fx} v_0(f^{-1}fx) \\
&= fh(x) ,
\end{aligned}$$

which proves (2.1). Clearly,  $d(h, \text{id}) = \|v_0\| \leq \varepsilon_0 \leq \varepsilon$ , which proves (2.2).

This completes the proof of Theorem 1.

*Remark.* Let  $g \in \text{Map}(M)$  be a homeomorphism of  $M$  with  $d(f, g) \leq \delta$ . Clearly, we see that  $d(fg^{-1}, \text{id}) \leq \delta$  and  $g^{-1}g(x) = x$  for every  $x \in M$ . By Theorem 1 there exists  $h \in \text{Map}(M, \varepsilon)$  such that

$$hg(x) = fh(x)$$

for every  $x \in M$ . Thus, Theorem 1 is a generalization of P. Walters' result (Theorem 1 [3]), except the uniqueness of the semiconjugacy  $h$  with  $d(h, \text{id}) \leq \varepsilon$ .

### §3. Proof of Theorem 2

**THEOREM 2.** *An Anosov diffeomorphism  $f$  of  $M$  is stochastically stable.*

*Proof.* For  $\varepsilon > 0$  we put  $\delta_0 = \delta(\varepsilon/2)$ , where  $\delta(\varepsilon/2)$  is as in Theorem 1, and  $\delta = \delta_0/3$ . For every  $\delta$ -pseudo-orbit  $\{x_i\}_{i \in \mathbf{Z}}$  of  $f$ , we shall find  $x \in M$  such that

$$(3.1) \quad d(f^i x, x_i) \leq \varepsilon, \quad i \in \mathbf{Z}.$$

**CLAIM 1.** *For every positive integer  $k$  and  $\delta$ -pseudo-orbit  $\{x_i\}_{i \in \mathbf{Z}}$  of  $f$ , there exists  $z \in M$  such that*

$$(3.2) \quad d(f^i z, x_i) \leq \varepsilon, \quad i = 0, 1, \dots, k.$$

*Proof.* There exists a  $(\frac{2}{3}\delta_0)$ -pseudo-orbit  $\{x'_i\}_{i \in \mathbf{Z}}$  such that

$$(3.3) \quad \begin{aligned} d(x'_i, x_i) &\leq \varepsilon/2, & i = 0, 1, \dots, k, \\ x'_i &\neq x'_j, & 0 \leq i \neq j \leq k+1. \end{aligned}$$

Since  $f(x'_i) \neq f(x'_j)$  ( $0 \leq i \neq j \leq k+1$ ) and  $d(fx'_i, x'_{i+1}) \leq \frac{2}{3}\delta_0$ , we can find  $\phi, \psi \in \text{Map}(M, \delta_0)$  such that

$$\phi f(x'_i) = x'_{i+1}, \quad \psi(x'_{i+1}) = f(x'_i), \quad i = 0, 1, \dots, k.$$



Put  $S = \{x'_0, \dots, x'_k\}$ ,  $g = \phi f$  and  $\bar{g} = f^{-1}\psi$ . Then we see that  $d(f, g) = d(\phi, \text{id})$ ,  $d(f\bar{g}, \text{id}) = d(\psi, \text{id}) \leq \delta_0$ , and  $\bar{g}g(x'_i) = f^{-1}\psi\phi f(x'_i) = x'_i$ ,  $i = 0, 1, \dots, k$ . By Theorem 1, there exists  $h \in \text{Map}(M, \varepsilon/2)$  such that  $hg(x'_i) = fh(x'_i)$ , for  $i = 0, 1, \dots, k$ . Therefore, we have

$$(3.4) \quad f^i h(x'_0) = h(x'_i), \quad i = 0, 1, \dots, k.$$

Putting  $z = h(x'_0)$ , by (3.3) and (3.4) we obtain

$$\begin{aligned} d(f^i z, x_i) &\leq d(f^i h(x'_0), x'_i) + d(x'_i, x_i) \\ &\leq d(h(x'_i), x'_i) + \varepsilon/2 \\ &\leq d(h, \text{id}) + \varepsilon/2 \\ &\leq \varepsilon/2 + \varepsilon/2 = \varepsilon, \end{aligned}$$

which proves (3.2).

**CLAIM 2.** *Let  $\{x_i\}_{i \in \mathbb{Z}}$  be a  $\delta$ -pseudo-orbit of  $f$ . For every positive integer  $k$  there exists  $z = z_k \in M$  such that*

$$(3.5) \quad d(f^i z, x_i) \leq \varepsilon, \quad |i| \leq k.$$

*Proof.* Take a positive integer  $k$  and fix it. Putting  $y_i = x_{-k+i}$  we see that  $\{y_i\}_{i \in \mathbb{Z}}$  is a  $\delta$ -pseudo-orbit. By Claim 1 there exists  $z' \in M$  such that  $d(f^i z', y_i) \leq \varepsilon$ , for  $i = 0, 1, \dots, 2k$ . Putting  $z = f^k(z')$  we get  $d(f^i z, x_i) = d(f^{i+k} z', y_{i+k}) \leq \varepsilon$ ,  $|i| \leq k$ , which proves (3.5).

By the compactness of  $M$  we can find a subsequence  $\{z_{k_\nu}\}$  of  $\{z_k\}$  such that  $\lim_{\nu \rightarrow \infty} z_{k_\nu} = x$  for some  $x \in M$ . Take  $i \in \mathbb{Z}$  and fix it. By (3.5) we have that  $d(f^i z_{k_\nu}, x_i) \leq \varepsilon$  for every  $\nu$  with  $|i| \leq k_\nu$ . Therefore we obtain  $d(f^i x, x_i) = \lim_{\nu \rightarrow \infty} d(f^i z_{k_\nu}, x_i) \leq \varepsilon$ , which proves (3.1).

This completes the proof of Theorem 2.

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