ENTIRE SCALAR CURVATURE FLOW AND HYPERSURFACES OF CONSTANT SCALAR CURVATURE IN MINKOWSKI SPACE*

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Abstract. We prove existence in the Minkowski space of entire spacelike hypersurfaces with constant negative scalar curvature and given set of lightlike directions at infinity; we also construct the entire scalar curvature flow with prescribed set of lightlike directions at infinity, and prove that the flow converges to a spacelike hypersurface with constant scalar curvature. The proofs rely on barriers construction and a priori estimates.

Key words. Entire graphs, prescribed scalar curvature, scalar curvature flow, Minkowski space.

AMS subject classifications. 35J60, 35K55, 53C50

1. Introduction. The Minkowski space $\mathbb{R}^{n,1}$ is the space $\mathbb{R}^n \times \mathbb{R}$ endowed with the metric $dx_1^2 + \cdots + dx_n^2 - dx_{n+1}^2$. We say that a hypersurface of $\mathbb{R}^{n,1}$ is spacelike if the metric induced on it by the Minkowski metric is Riemannian, and that a function $u: \mathbb{R}^n \to \mathbb{R}$ of class C^1 is spacelike if its graph is a spacelike hypersurface, which equivalently means that |Du| < 1 on \mathbb{R}^n . The principal curvatures of a spacelike hypersurface are the eigenvalues of its curvature endomorphism dN, where N is the future oriented unit normal field. In the natural chart (x_1, \ldots, x_n) , the curvature endomorphism $(h_j^i)_{ij}$ of the graph of a spacelike function u is given by

$$h_j^i = \frac{1}{\sqrt{1 - |Du|^2}} \sum_{k=1}^n \left(\delta_{ik} + \frac{u_i u_k}{1 - |Du|^2} \right) u_{kj}.$$

Let us denote by $H_k[u]$ the k^{th} elementary symmetric function of the principal curvatures of the graph of u.

We are interested in the scalar curvature S[u] of the graph of u, which is linked to $H_2[u]$ by

$$S[u] = -2H_2[u].$$

We say that $u: \mathbb{R}^n \to \mathbb{R}$ of class C^2 is admissible, if u is spacelike and if $H_1[u] > 0$ and $H_2[u] > 0$ on \mathbb{R}^n . It is well known that the operator H_2 is elliptic on admissible functions, and that the Mac-Laurin inequality holds: on \mathbb{R}^n ,

$$H_2[u]^{\frac{1}{2}} \le \sqrt{\frac{n-1}{2n}} H_1[u].$$
 (1.1)

Let F be a closed subset of the unit sphere $S^{n-1} \subset \mathbb{R}^n$. We suppose that F is a union of arcs of circles on S^{n-1} . We first construct barriers whose set of lightlike directions at infinity is the set F. For definitions and examples, we refer to Sections 2 and 3.

PROPOSITION 1.1. Let F be as above, and consider $V_F : \mathbb{R}^n \to \mathbb{R}$ defined by $V_F(x) := \sup_{\lambda \in F} \langle x, \lambda \rangle$, where $\langle ., . \rangle$ stands for the canonical scalar product on \mathbb{R}^n . Let

^{*}Received September 13, 2008; accepted for publication January 22, 2009.

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h and k be two positive constants such that

$$h < \sqrt{\frac{2n}{n-1}} \text{ and } k \ge 1. \tag{1.2}$$

There exist two entire functions $\underline{u}, \overline{u}: \mathbb{R}^n \to \mathbb{R}$, such that

$$V_F < \underline{u} < \overline{u} < V_F + c \text{ on } \mathbb{R}^n$$
 (1.3)

for some constant c, where \overline{u} is smooth, spacelike, with constant mean curvature $H_1 = h$, and \underline{u} is the supremum of spacelike functions with constant scalar curvature $H_2 = k$. Moreover, for all $\xi \in F$,

$$\lim_{r \to +\infty} \underline{u}(r\xi) - r = \lim_{r \to +\infty} \overline{u}(r\xi) - r = 0, \tag{1.4}$$

and, from (1.3), for all $\xi \in S^{n-1} \backslash F$,

$$\lim_{r \to +\infty} \overline{u}(r\xi) - r = -\infty. \tag{1.5}$$

Solving a sequence of Dirichlet problems between the barriers \underline{u} and \overline{u} , and extracting a convergent subsequence thanks to local estimates [3, 4, 19], we will first construct an entire spacelike hypersurface of constant negative scalar curvature, and whose set of lightlike directions at infinity is F:

THEOREM 1.2. Let F be a closed subset of S^{n-1} as above. Then there exists $u: \mathbb{R}^n \to \mathbb{R}$, admissible, solution of

$$H_2[u] = 1 \ in \ \mathbb{R}^n \tag{1.6}$$

such that, for all $\xi \in F$,

$$\lim_{r \to +\infty} u(r\xi) - r = 0 \tag{1.7}$$

and

$$\sup_{\mathbb{R}^n} |u - V_F| < +\infty. \tag{1.8}$$

In particular, the set of lightlike directions at infinity of u is the set F.

Remark 1.3. Uniqueness of a solution of (1.6) satisfying (1.7) and (1.8) is still an open question.

We then study the entire scalar curvature flow. Starting with a smooth spacelike entire and strictly convex function between the barriers which has bounded scalar curvature, we prove that the entire scalar curvature flow is defined for all time and converges to a solution of the prescribed constant scalar curvature equation:

THEOREM 1.4. Let F be as above. We suppose that F is not included in any affine hyperplane of \mathbb{R}^n . Let h, k be two positive constants such that (1.2) holds, and let $\underline{u}, \overline{u}$ be the barriers given by Proposition 1.1. Let $u_0 : \mathbb{R}^n \to \mathbb{R}$ be a smooth spacelike and strictly convex function such that

$$\underline{u} < u_0 < \overline{u} \tag{1.9}$$

and

$$1 < H_2[u_0] < k$$
.

 $The\ parabolic\ problem$

$$\begin{cases}
-\frac{\dot{u}}{\sqrt{1-|Du|^2}} + H_2[u]^{\frac{1}{2}} = 1 & \text{in } \mathbb{R}^n \times (0, +\infty) \\
u(x, 0) = u_0(x) & \text{on } \mathbb{R}^n \times \{0\},
\end{cases}$$
(1.10)

has a smooth spacelike solution

$$u \in C^{\infty}(\mathbb{R}^n \times (0, +\infty)) \cap C^{1,1;0,1}(\mathbb{R}^n \times [0, +\infty)).$$

Moreover

$$u \le u \le \overline{u} \tag{1.11}$$

for all time, and u converges to a solution of (1.6) as the time t tends to infinity.

REMARK 1.5. Note that (1.10) describes hypersurfaces moving with normal velocity given by the square root of the scalar curvature,

$$\frac{d}{dt}X = \left(H_2[X]^{\frac{1}{2}} - 1\right)N,$$

where X is the embedding vector of the hypersurfaces.

Remark 1.6. If F is included in some affine hyperplane, condition (1.9) with u_0 strictly convex is not possible: suppose that $\xi \in \mathbb{R}^n$ belongs to F^{\perp} ; then $V_F(\xi) = 0$, and, by (1.3) and (1.9), $0 < u_0(\lambda \xi) < c$ for all $\lambda \in \mathbb{R}$, which is impossible if $\xi \neq 0$ and if u_0 is a strictly convex function. Note that the strict convexity of u_0 is a crucial hypothesis for the resolution of the parabolic Dirichlet problem, Section 6. See also [3, 19].

REMARK 1.7. If $u_0: \mathbb{R}^n \to \mathbb{R}$ is a spacelike and strictly convex function such that $1 \leq H_2[u_0] \leq k$ and $\lim_{|x| \to +\infty} u_0(x) - |x| = 0$, we get the following: taking for the lower barrier \underline{u} (resp. for the upper barrier \overline{u}) the hyperboloid asymptotic to the cone $x_{n+1} = |x|$ and of scalar curvature $H_2 = k' > k$ (resp. of mean curvature $H_1 = h < \sqrt{\frac{2n}{n-1}}$), by the maximum principle we have $\underline{u} < u_0 < \overline{u}$, and Theorem 1.4 shows that problem (1.10) has a (unique) solution u such that $\underline{u} \leq u \leq \overline{u}$ during the evolution. Moreover u converges to the hyperboloid of scalar curvature $H_2 = 1$, as t tends to infinity.

REMARK 1.8. By scaling u in Theorem 1.2, we obtain an admissible solution of $H_2[u] = \lambda^2$ in \mathbb{R}^n such that (1.7) and (1.8) hold. Moreover, by scaling the barriers $\underline{u}, \overline{u}$ in Proposition 1.1, we obtain a result similar to Theorem 1.4 for the parabolic problem

$$\begin{cases}
-\frac{\dot{u}}{\sqrt{1-|Du|^2}} + H_2[u]^{\frac{1}{2}} = \lambda & \text{in } \mathbb{R}^n \times (0, +\infty) \\
u(x, 0) = u_0(x) & \text{on } \mathbb{R}^n \times \{0\},
\end{cases}$$
(1.12)

if
$$\underline{u} < u_0 < \overline{u}$$
 and $\lambda^2 \le H_2[u_0] \le \lambda^2 k$ hold.

Let us quote some related papers: in Minkowski space, entire spacelike hypersurfaces of constant mean curvature are classified in [17] and entire hypersurfaces of constant Gauss curvature are studied in [12, 5]. In [3], we construct entire hypersurfaces with prescribed scalar curvature and given values at infinity which stay at a bounded distance of a lightcone.

The entire mean curvature flow in Minkowski space is studied in [8], and the entire Gauss curvature flow in [5]. The scalar curvature flow in globally hyperbolic Lorentzian manifolds having a compact Cauchy hypersurface is studied in [10, 11] and [9].

Finally, the parabolic Dirichlet problem for the scalar curvature operator in the euclidian space is solved in [14, 15].

The outline of the paper is as follows. We recall the definition of the set of lightlike directions at infinity of a spacelike and convex function in Section 2. In Section 3 we construct the barriers with given set of lightlike directions at infinity, and construct the auxiliary functions needed for the local estimates. The entire solutions of the prescribed constant scalar curvature equation are constructed Section 4. We introduce further notation and recall the evolution equations of various geometric quantities Section 5, and we study the parabolic Dirichlet problem Section 6. In Section 7 we construct the entire scalar curvature flow, once local C^1 and C^2 estimates are known, and we prove that the flow converges. We carry out the local estimates in Sections 8 and 9. A short appendix ends the paper.

2. The set of lightlike directions at infinity of an entire spacelike hypersurface of constant scalar curvature. Let $u: \mathbb{R}^n \to \mathbb{R}$ be a spacelike and convex function. Following Treibergs [17], its blow down $V_u: \mathbb{R}^n \to \mathbb{R}$ is defined by

$$V_u(x) = \lim_{r \to +\infty} \frac{u(rx)}{r}.$$

As in [17], we denote by Q the set of the convex homogeneous of degree one functions whose gradient has norm one whenever defined. The following holds:

Lemma 2.1. For every convex and spacelike solution u of the prescribed scalar curvature equation (1.6), the blow down V_u belongs to Q.

Proof. This result is proved in [17], Theorem 1 for the prescribed mean curvature equation, using a barrier construction. The same barrier can be used for the prescribed constant scalar curvature equation as well. \square

The set Q is in one-to-one correspondence with the set of closed subsets of S^{n-1} ; see [6], Lemma 4.3.

LEMMA 2.2. [6, 17]. If F is a closed non-empty subset of S^{n-1} ,

$$V_F(x) := \sup_{\lambda \in F} \langle x, \lambda \rangle$$

belongs to Q; the map $F \mapsto V_F$ is one-to-one, and its inverse is the map

$$w \in Q \mapsto F = \{x \in S^{n-1} \subset \mathbb{R}^n : w(x) = 1\}.$$

In particular, the blow down of a convex solution u of (1.6) is determined by the set of its *lightlike directions* at infinity

$$L_u := \{ x \in S^{n-1} : V_u(x) = 1 \}.$$

Note that here, and in contrast with [17, 5], it is not known if a spacelike entire function of constant negative scalar curvature is necessarily convex. Nevertheless, the solutions u constructed in this article are such that $V_F \leq u \leq V_F + c$, where F is a closed subset belonging to S^{n-1} and c is a constant. In that case, the blow down V_u and the set of lightlike directions L_u are well-defined, and satisfy

$$V_u = V_F$$
 and $L_u = F$.

We finally recall a useful formula. Denoting by d_S the canonical distance on the sphere S^{n-1} , we proved the following formula in [5], Lemma 4.6: for every $x \in S^{n-1}$,

$$V_F(x) = \cos(d_S(x, F)). \tag{2.1}$$

3. The construction of the barriers.

3.1. The semitrough. We first recall the properties of the *standard semitrough* of constant Gauss curvature in the Minkowski space $\mathbb{R}^{2,1}$, constructed in [13]: this is the unique spacelike function $\tilde{u}: \mathbb{R}^2 \to \mathbb{R}$ whose graph has constant Gauss curvature one, and which is such that

$$D\tilde{u}(\mathbb{R}^2) = \{(x_1, x_2) \in B_1 : x_1 > 0\},\$$

and

$$\lim_{|x| \to +\infty} \tilde{u}(x) - V_{S^{+}}(x) = 0. \tag{3.1}$$

Here B_1 is the unit ball in \mathbb{R}^2 centered at 0, and S^+ is the arc of the circle $S^1 = \partial B_1$ defined by $S^+ := \{(x_1, x_2) \in S^1 : x_1 \geq 0\}$. Let S be a closed arc of circle on the sphere S^{n-1} . This is a subset of the form $f(S^+ \times \{0\})$, where

$$S^{+} \times \{0\} = \{(x_1, x_2, 0, \dots, 0) \in S^{n-1} : x_1 \ge 0\}$$
(3.2)

and f is a conformal transformation of S^{n-1} . From the existence of the standard semitrough, we deduce the following

LEMMA 3.1. Let S be a closed arc of circle on S^{n-1} , and let k > 0. There exists a spacelike entire function u such that

$$H_2[u] = k \text{ and } \sup_{\mathbb{R}^n} |u - V_S| < +\infty.$$

Proof. Recall that a Lorentz transformation preserves H_2 , and acts as a conformal transformation of S^{n-1} on the sets of lightlike directions at infinity (S^{n-1} is identified with the projective lightcone). Thus, applying a Lorentz transformation, we may suppose that S is given by (3.2). The function u defined by

$$u(x_1, x_2, x_3, \dots, x_n) = \frac{1}{\sqrt{k}} \tilde{u}(\sqrt{k}(x_1, x_2)),$$

where \tilde{u} is the standard semitrough defined above, satisfies the required properties. \square

3.2. The barriers. Let h be a positive constant and F be a closed subset of S^{n-1} . From [17] p233, we know that there exists a smooth spacelike function $\overline{u}: \mathbb{R}^n \to \mathbb{R}$ whose graph has constant mean curvature $H_1 = h$ and which is such that

$$V_F \le \overline{u} \le V_F + \frac{n}{h} \text{ on } \mathbb{R}^n.$$
 (3.3)

The function \overline{u} satisfies the further properties:

$$\limsup_{|x| \to +\infty} \overline{u}(x) - |x| \le 0, \tag{3.4}$$

and, for all $\xi \in F$,

$$\lim_{r \to +\infty} \overline{u}(r\xi) - r = 0. \tag{3.5}$$

For these last properties, see the upper barrier z_2 used in [17] p233.

LEMMA 3.2. Let h and k be two positive constants such that $h < 2\sqrt{k}$. We assume that F is a union of closed arcs of circles on S^{n-1} ,

$$F = \bigcup_{i \in I} S_i. \tag{3.6}$$

Denoting by u_i the entire spacelike function of constant scalar curvature k associated to S_i by Lemma 3.1 (and its proof), the function $\underline{u} = \sup_{i \in I} u_i$ satisfies

$$V_F < u < \overline{u} \text{ on } \mathbb{R}^n.$$

REMARK 3.3. The closure of an open subset U of S^{n-1} with C^1 boundary is of the form (3.6). More generally, if U satisfies an interior cone condition at each boundary-point (i.e. all $\xi \in \partial U$ is a vertex of a (geodesic) cone $\subset \overline{U}$), \overline{U} is of the form (3.6). Of course, the set F in (3.6) might be much more complicated (e.g. without interior point).

Proof. We first prove that $V_F < \underline{u}$ on \mathbb{R}^n . Since $u_i > V_{S_i}$ for all $i \in I$, it is sufficient to prove that, for all $x \in \mathbb{R}^n$, $V_F(x) = V_{S_i}(x)$ for some index $i \in I$. Since these functions are homogeneous of degree one, we may suppose that $x \in S^{n-1} \subset \mathbb{R}^n$. By (2.1), this amounts to prove that $d_S(x, F) = d_S(x, S_i)$ for some index $i \in I$, where d_S is the natural distance on S^{n-1} . Let $x_0 \in F$ be such that $d_S(x, F) = d_S(x, x_0)$, and $i \in I$ be such that x_0 belongs to S_i . Since $S_i \subset F$, we have $d_S(x, F) \leq d_S(x, S_i)$, and since $x_0 \in S_i$ we have $d_S(x, x_0) \geq d_S(x, S_i)$ and thus $d_S(x, F) \geq d(x, S_i)$. Thus $d_S(x, F) = d_S(x, S_i)$, and the result follows.

We now prove that $\underline{u} \leq \overline{u}$. We fix $i \in I$ and we prove that $u_i \leq \overline{u}$: applying a Lorentz transformation, we may assume that

$$S_i = \{(x_1, x_2, 0, \dots, 0) \in S^{n-1} : x_1 \ge 0\}.$$

Let $x'_0 \in \mathbb{R}^{n-2}$, and set

$$\tilde{u}_i(x_1, x_2) := u_i(x_1, x_2, x_0') \text{ and } \tilde{\overline{u}}(x_1, x_2) := \overline{u}(x_1, x_2, x_0').$$

Recalling the proof of Lemma 3.1, we observe that \tilde{u}_i is the (scaled) semitrough defined Section 3.1. From Lemma A.1 we get $H_1[\tilde{u}] \leq h$. Since \tilde{u}_i is the semitrough

with Gauss curvature equal to k, from the geometric-arithmetic means inequality we get $H_1[\tilde{u}_i] \geq 2\sqrt{k}$. Thus $H_1[\tilde{u}] \leq H_1[\tilde{u}_i]$. We suppose by contradiction that there exists $x_0 = (x_1^0, x_2^0)$ such that $\tilde{u}_i(x_0) > \bar{u}(x_0)$, and we consider $\varepsilon > 0$ such that

$$\tilde{u}_i(x_0) > \frac{\tilde{u}}{u}(x_0) + \varepsilon.$$

Since S_i belongs to F, we have $V_F(., x_0') \geq V_{S_i}(., x_0') = V_{S^+}$, and we conclude from (3.1) and (3.3) that

$$\lim_{|x|\to+\infty}\inf(\tilde{\overline{u}}+\varepsilon)-\tilde{u}_i\geq\varepsilon.$$

Thus the non-empty open set

$$U = \{(x_1, x_2) \in \mathbb{R}^2 : \ \tilde{u}_i(x_1, x_2) > \frac{\tilde{u}}{u}(x_1, x_2) + \varepsilon \}$$

is bounded. Since $\tilde{u}_i = \overline{\tilde{u}} + \varepsilon$ on ∂U and $H_1[\tilde{u}_i] \geq H_1[\overline{\tilde{u}} + \varepsilon]$ in U, we get a contradiction with the maximum principle. The claim is proved.

We finally prove the strict inequality $\underline{u} < \overline{u}$: we set $\overline{u}_{\lambda}(x) := \frac{1}{\lambda} \overline{u}(\lambda x)$, with $\lambda > 1$ such that $\lambda h < 2\sqrt{k}$. Since $H_1[\overline{u}_{\lambda}] = \lambda h$ and $\overline{u}_{\lambda} > V_F$, the arguments given in the paragraph above (with \overline{u}_{λ} instead of \overline{u}) show that $\underline{u} \leq \overline{u}_{\lambda}$. Since $\overline{u}_{\lambda} < \overline{u}$, we obtain the result. \square

The useful properties of the barriers are gathered in Proposition 1.1.

Remark 3.4. By construction, it is clear that if the set F is contained in some affine subspace, in

$$\{(x', x'') \in \mathbb{R}^n = \mathbb{R}^k \times \mathbb{R}^{n-k} : x'' = 0\}$$

say, we may assume that the barriers $\underline{u}, \overline{u}$ satisfy: for all $(x', x'') \in \mathbb{R}^k \times \mathbb{R}^{n-k}$,

$$u(x', x'') = u(x', 0)$$
 and $\overline{u}(x', x'') = \overline{u}(x', 0)$.

3.3. Construction of two auxiliary functions. This section is devoted to the construction of auxiliary functions which are crucial for the local C^1 and C^2 estimates. The functions $\underline{u}, \overline{u}$ are the barriers constructed above. The following lemma is needed for the local C^1 estimate.

LEMMA 3.5. Let K be a compact subset of \mathbb{R}^n . There exists a smooth spacelike function $\psi : \mathbb{R}^n \to \mathbb{R}$ such that

$$\psi < u$$
 on K and $\psi > \overline{u}$ near infinity.

For the proof, we will need the following lemma:

LEMMA 3.6. Let F be a closed subset of S^{n-1} . Let $\varepsilon > 0$ and set

$$F_{\varepsilon} := \{ \xi \in S^{n-1} : d_S(\xi, F) \le \varepsilon \}.$$

The function $V_{F_{\varepsilon}} - V_F$ has the following properties:

$$\sup_{\xi \in S^{n-1}} |V_{F_{\varepsilon}}(\xi) - V_F(\xi)| \le \varepsilon, \tag{3.7}$$

and

$$\inf_{\xi \in S^{n-1} \setminus F_{\varepsilon}} V_{F_{\varepsilon}}(\xi) - V_{F}(\xi) \ge m_{\varepsilon}, \tag{3.8}$$

for some positive constant m_{ε} .

Proof. By (2.1), for all $\xi \in S^{n-1}$,

$$V_{F_{\varepsilon}}(\xi) - V_F(\xi) = \cos(d_S(\xi, F_{\varepsilon})) - \cos(d_S(\xi, F)). \tag{3.9}$$

We first prove (3.7): we observe that, for all $\xi \in S^{n-1}$,

$$|d_S(\xi, F_{\varepsilon}) - d_S(\xi, F)| < \varepsilon.$$

Since $|\cos(\alpha) - \cos(\beta)| \le |\alpha - \beta|$ for all $\alpha, \beta \in \mathbb{R}$, we obtain (3.7).

We now prove (3.8): we suppose that $\xi \notin F_{\varepsilon}$; since $F \subset F_{\varepsilon}$, we have

$$d_S(\xi, F) = d_S(\xi, F_{\varepsilon}) + \varepsilon. \tag{3.10}$$

This implies in particular that

$$d_S(\xi, F_{\varepsilon}) \in [0, \pi - \varepsilon].$$

Denoting $\alpha = d_S(\xi, F_{\varepsilon})$, we obtain from (3.9) and (3.10) that

$$V_{F_{\varepsilon}}(\xi) - V_{F}(\xi) = \cos \alpha - \cos(\alpha + \varepsilon) \ge m_{\varepsilon},$$

where $m_{\varepsilon} = \inf_{\alpha \in [0, \pi - \varepsilon]} \int_{\alpha}^{\alpha + \varepsilon} \sin(t) dt$ is positive, and we obtain (3.8). \square

Proof of Lemma 3.5. Let K be a compact subset of \mathbb{R}^n , and $R \geq 1$ be such that $K \subset \overline{B}_R$ (here and below B_R stands for the open ball of radius R in \mathbb{R}^n , centered at the origin). We fix $\delta_0 > 0$ such that

$$\inf_{B_R} (\underline{u} - V_F) \ge \delta_0. \tag{3.11}$$

Let $\varepsilon > 0$ and $F_{\varepsilon} := \{ \xi \in S^{n-1} | d(\xi, F) \le \varepsilon \}$. From (3.7) we get

$$\sup_{K} |V_{F_{\varepsilon}} - V_{F}| < \frac{\delta_{0}}{8} \tag{3.12}$$

if $\varepsilon < \frac{\delta_0}{8R}$. Thus, if $\varepsilon < \frac{\delta_0}{8R}$,

$$\sup_{K} |(V_{F_{\varepsilon}} + \varepsilon) - V_{F}| < \frac{\delta_{0}}{4}. \tag{3.13}$$

Let ψ be a spacelike function such that $\psi > V_{F_{\varepsilon}} + \varepsilon$ and

$$\sup_{K} |\psi - (V_{F_{\varepsilon}} + \varepsilon)| < \frac{\delta_0}{4}. \tag{3.14}$$

We may construct ψ as follows: we first consider a spacelike function v whose graph has constant mean curvature one and which is such that

$$V_{F_{\varepsilon}} < v < V_{F_{\varepsilon}} + c$$

given by [17] Theorem 2; here c is a positive constant. We then define

$$\psi(x) := \frac{1}{\lambda}v(\lambda x) + \varepsilon,$$

where λ is a positive parameter. We have

$$\sup_{x \in \mathbb{R}^n} |\psi(x) - (V_{F_{\varepsilon}} + \varepsilon)(x)| = \sup_{x \in \mathbb{R}^n} \left| \frac{1}{\lambda} v(\lambda x) - V_{F_{\varepsilon}}(x) \right|$$
$$= \frac{1}{\lambda} \sup_{x \in \mathbb{R}^n} |v(\lambda x) - V_{F_{\varepsilon}}(\lambda x)| \le \frac{c}{\lambda} < \frac{\delta_0}{4}$$

if λ is chosen sufficiently large. From (3.13) and (3.14) we get

$$\sup_{K} |\psi - V_F| < \frac{\delta_0}{2},\tag{3.15}$$

and, from (3.11), on K,

$$\underline{u} - \psi \ge \inf_{K} (\underline{u} - V_F) - \sup_{K} |\psi - V_F| \ge \frac{\delta_0}{2}.$$

We now prove that there exists $r_{\varepsilon} > 0$ such that

$$\inf_{\mathbb{R}^n \setminus B_{r_{\varepsilon}}} \left(V_{F_{\varepsilon}} + \varepsilon - \overline{u} \right) \ge \frac{\varepsilon}{2}. \tag{3.16}$$

Since $\psi > V_{F_{\varepsilon}} + \varepsilon$, this will prove the last claim of the Lemma. We consider $x = r\xi \in \mathbb{R}^n \setminus \{0\}$, with r > 0 and $\xi \in S^{n-1}$. We first suppose that $\xi \in F_{\varepsilon}$. By (3.4) there exists r_1 , independent of ξ , such that $\overline{u}(r\xi) \leq r + \frac{\varepsilon}{2}$ for all $r \geq r_1$. Thus, if $r \geq r_1$,

$$(V_{F_{\varepsilon}} + \varepsilon - \overline{u})(r\xi) \ge (r + \varepsilon) - \left(r + \frac{\varepsilon}{2}\right) \ge \frac{\varepsilon}{2}.$$

If we now suppose that $\xi \notin F_{\varepsilon}$, we have

$$(V_{F_{\varepsilon}} + \varepsilon - \overline{u})(r\xi) \ge (V_{F_{\varepsilon}} - V_F)(r\xi) + (V_F - \overline{u})(r\xi)$$

$$\ge (V_{F_{\varepsilon}} - V_F)(r\xi) - c,$$

where the constant c is given by (1.3). By (3.8), $(V_{F_{\varepsilon}} - V_F)(r\xi) \ge rm_{\varepsilon}$ where the constant m_{ε} is positive. Thus, there exists r_2 such that if $r \ge r_2$ and $\xi \notin F_{\varepsilon}$, we have

$$(V_{F_{\varepsilon}} + \varepsilon - \overline{u})(r\xi) \ge \frac{\varepsilon}{2}.$$

Taking $r_{\varepsilon} = \max(r_1, r_2)$ we obtain (3.16). \square

The following lemma is needed for the local C^2 estimate.

LEMMA 3.7. We suppose that F is not included in any affine hyperplane of \mathbb{R}^n , and we consider K a compact subset of \mathbb{R}^n . There exist a ball B_R which contains K and a smooth and strictly convex function $\Phi : \overline{B}_R \to \mathbb{R}$ such that

$$\Phi > \overline{u} \text{ on } K \text{ and } \Phi \leq \underline{u} \text{ on } \partial B_R.$$

Proof. We first note that the upper barrier \overline{u} is strictly convex: this follows from the Splitting Theorem [6], Theorem 3.1, together with the assumption that F is not

included in any affine hyperplane of \mathbb{R}^n . Applying a affine Lorentz transformation if necessary, we may suppose that $\overline{u}(0) = 0$ and $d\overline{u}_0 = 0$. Since \overline{u} is strictly convex, we have

$$\lim_{|x| \to +\infty} \overline{u}(x) = +\infty. \tag{3.17}$$

We fix R' sufficiently large such that $K \subset \overline{B}_{R'}$. We set $\Phi_0 := \sup_{B_{R'}} \overline{u} + 1$. Recalling (1.3), $\underline{u} \geq \overline{u} - c$ on \mathbb{R}^n . We thus get from (3.17) the existence of R > R' such that

$$\inf_{\{x: |x| \ge R\}} \underline{u}(x) \ge \Phi_0 + 1. \tag{3.18}$$

We set, for all $x \in \mathbb{R}^n$,

$$\Phi(x) := \Phi_0 + \frac{1}{R^2} |x|^2. \tag{3.19}$$

The function Φ is strictly convex, $\Phi \geq \overline{u} + 1$ on $B_{R'}$ and $\Phi \leq \underline{u}$ on ∂B_R . \square

4. The construction of an entire solution of the elliptic problem. We assume that F, \underline{u} and \overline{u} are as in Proposition 1.1. The barriers \underline{u} , \overline{u} are constructed in the previous section.

We first suppose that F is not included in any affine hyperplane of \mathbb{R}^n . For any positive R, we set u_R for the admissible solution of

$$\begin{cases} H_2[u_R] = 1 \text{ in } B_R \\ u_R = \overline{u} \text{ on } \partial B_R. \end{cases}$$

This Dirichlet problem is solvable since \overline{u} is strictly convex (by the Splitting Principle [6], Theorem 3.1); see [3, 19]. From the Mac-Laurin inequality (1.1) we get $H_1[u_R] \ge \sqrt{\frac{2n}{n-1}}$. Thus, the comparison principle for the operator H_1 implies that $\overline{u} \ge u_R$. Since \underline{u} is defined as a supremum of admissible functions with scalar curvature $H_2 = 1$, we also have $u_R \ge \underline{u}$. Thus u_R lies between the barriers, for every R. The following local uniform estimates hold: for any $R_0 \ge 0$, there exist $R_1 = R_1(R_0)$ sufficiently large, $\vartheta \in (0,1)$, and $C \ge 0$ such that: for every $R \ge R_1$,

$$\sup_{B_{R_0}} |Du_R| \le 1 - \vartheta \text{ and } \sup_{B_{R_0}} |u_R| + \sup_{B_{R_0}} |D^2 u_R| \le C.$$

For the C^1 local estimate, we refer to [4], Proposition 4.1. The auxiliary function ψ needed for the estimate is given here by Lemma 3.5. For the local C^2 estimate, we refer to [4], Proposition 5.1.; here is needed the auxiliary function Φ given by Lemma 3.7. The proofs remain unchanged.

Evans-Krylov interior second derivative Hölder estimate, and Schauder interior regularity theory imply locally uniform estimates of higher derivatives. A diagonal process then yields a subsequence u_{R_k} , $R_k \to +\infty$, that locally converges to a smooth solution of (1.6). The properties (1.7) and (1.8) follow from the behavior at infinity of the barriers given by (1.3) and (1.4).

If F is included in some affine hyperplane of \mathbb{R}^n , applying a Lorentz transformation we may suppose that F belongs to

$$S^{k-1} \times \{0\} = \{(x_1, \dots, x_n) \in S^{n-1} : x_{k+1} = \dots = x_n = 0\}$$

and that F is not included in any affine hyperplane of $\mathbb{R}^k \times \{0\}$, where k belongs to $\{1,\ldots,n-1\}$. By Remark 3.4, the restrictions $\underline{u}_{|\mathbb{R}^k}$, $\overline{u}_{|\mathbb{R}^k}$ are barriers for the scalar curvature operator H_2 on \mathbb{R}^k , with $\overline{u}_{|\mathbb{R}^k}$ strictly convex, and are such that (1.3)-(1.4) hold on \mathbb{R}^k . Thus, there exists $\tilde{u}: \mathbb{R}^k \to \mathbb{R}$ such that $H_2[\tilde{u}] = 1$ and $\underline{u}_{|\mathbb{R}^k} \leq \tilde{u} \leq \overline{u}_{|\mathbb{R}^k}$. The function u defined on \mathbb{R}^n by

$$u(x_1,\ldots,x_n):=\tilde{u}(x_1,\ldots,x_k)$$

is an entire solution of (1.6) such that (1.7) and (1.8) hold.

5. Notation and evolution equations.

5.1. Notation. Let Σ_0 be a spacelike hypersurface of $\mathbb{R}^{n,1}$, and let $X:\Sigma_0\times [0,+\infty)\to\mathbb{R}^{n,1}$ be a family of spacelike embeddings of Σ_0 in $\mathbb{R}^{n,1}$: for every $t\geq 0$, $\Sigma_t:=X(\Sigma_0\times\{t\})$ is a spacelike hypersurface. We set N for the future oriented unit normal field of Σ_t . We denote by (g_{ij}) and (h_{ij}) the metric and the second fundamental form induced by the Minkowski metric on the embedded hypersurface Σ_t . We will use the Einstein summation convention, and raise or lower indices with respect to the metric (g_{ij}) . The components of the curvature endomorphism are thus denoted by h_j^i , and we will often write problem (1.10) in the equivalent form

$$\begin{cases} \dot{X} = (F((h_j^i)_{i,j}) - \hat{f}(X,t))N \text{ in } \Sigma_0 \times (0, +\infty) \\ X(.,0) = X_0 \text{ on } \Sigma_0, \end{cases}$$
 (5.1)

where X_0 is the canonical embedding of Σ_0 , F(A) is the square root of the sum of the principal minors of order 2 of the matrix A, and \hat{f} is a positive function on $\mathbb{R}^{n,1} \times [0,+\infty)$ (constant equal to one in (1.10)). Let

$$F_i^j := \frac{\partial F}{\partial h_j^i} \left((h_j^i)_{i,j} \right).$$

If $(h_j^i)_{i,j}$ is diagonal, so is $(F_i^j)_{i,j}$, and $F_i^i = \frac{1}{2F}\sigma_{1,i}$ for all i, where

$$\sigma_{1,i} = \sum_{k,k \neq i} \lambda_k.$$

Here and below we denote by $\lambda_1 \geq \cdots \geq \lambda_n$ the principal curvatures of Σ_t . $(F_i^j)_{i,j}$ defines a (1,1) tensor on Σ_t . Raising the index i we also will use the symmetric tensor $(F^{ij})_{i,j}$. Analogously we define

$$F^{ij,kl} := g^{ii'} g^{kk'} \frac{\partial^2 F}{\partial h_i^{i'} \partial h_l^{k'}} \left((h_j^i)_{i,j} \right).$$

We say that X solution of (5.1) is admissible if, for every $t \geq 0$, Σ_t is an admissible hypersurface, which means that $H_1(\Sigma_t) > 0$ and $H_2(\Sigma_t) > 0$. Admissibility of a solution of (1.10) is defined similarly. We denote by D the usual covariant derivative on $\mathbb{R}^{n,1}$ (or on \mathbb{R}^n), ∇ the covariant derivative induced on Σ_t , and use a semi-colon to denote the components of covariant derivatives on Σ_t . Finally, the Minkowski metric on $\mathbb{R}^{n,1}$ is denoted by $\langle ., . \rangle$, the Minkowski norm of spacelike vectors of $\mathbb{R}^{n,1}$ by |.|, and the usual euclidian norm by $|.|_{eucl}$.

5.2. Evolution equations. For a hypersurface moving according to

$$\dot{X} = (F(h_i^i) - \hat{f}(X, t))N,$$

we have

$$\frac{d}{dt}g_{ij} = 2(F - \hat{f})h_{ij},\tag{5.2}$$

$$\frac{d}{dt}(F - \hat{f}) - F^{ij}(F - \hat{f})_{ij} = -F^{ij}h_{ik}h_j^k(F - \hat{f}) - N^{\alpha}\hat{f}_{\alpha}(F - \hat{f}) - \hat{f}_t,$$
 (5.3)

$$\frac{d}{dt}h_{ij} - F^{kl}h_{ij;kl} = F(h_i^a h_{aj}) - h_{ij}F^{kl}(h_k^a h_{al})
+ F^{kl,pq}h_{kl;i}h_{pq;j} - \hat{f}_{ij} + (F - \hat{f})h_i^k h_{kj},$$
(5.4)

and, defining $u := -\langle e_{n+1}, X \rangle$ and $\nu := -\langle e_{n+1}, N \rangle$,

$$\dot{u} - F^{ij}u_{ij} = -\hat{f}\nu,\tag{5.5}$$

and

$$\dot{\nu} - F^{ij}\nu_{ij} = -\nu F^{ij}h_i^k h_{ki} + \hat{f}_j t^j, \tag{5.6}$$

where the t^{j} 's are the coordinates of the component tangential to Σ_{t} of e_{n+1} . For the proofs we refer to [10] and [5], where similar evolution equations are obtained.

6. The parabolic Dirichlet problem. The aim of this section is to prove the following

THEOREM 6.1. Let Ω be a uniformly convex bounded domain in \mathbb{R}^n with smooth boundary, let $u_0: \overline{\Omega} \to \mathbb{R}$ be a smooth, spacelike and strictly convex function, and let $\hat{f}: \overline{\Omega} \times \mathbb{R} \times [0, +\infty) \to (0, +\infty)$, $(x, u, t) \mapsto \hat{f}(x, u, t)$ be a smooth positive function such that $\hat{f}_t \leq 0$. We suppose that, for all $x \in \Omega$,

$$H_2[u_0]^{\frac{1}{2}}(x) - \hat{f}(x, u_0(x), 0) \ge 0.$$

Then the parabolic Dirichlet problem

$$\begin{cases}
-\frac{\dot{u}}{\sqrt{1-|Du|^2}} + H_2[u]^{\frac{1}{2}} &= \hat{f}(x, u, t) \text{ in } \Omega \times (0, +\infty) \\
u(x, t) &= u_0(x) \text{ on } \partial\Omega \times [0, +\infty) \cup \Omega \times \{0\},
\end{cases} (6.1)$$

has an admissible solution $u \in C^{\infty}(\overline{\Omega} \times [0, +\infty))$ if, on the corner of the parabolic domain, the compatibility conditions of any order are satisfied.

At the boundary, compatibility conditions of any order are fulfilled, so we get a smooth admissible solution for a short time interval.

We consider T maximal such that the parabolic Dirichlet problem (6.1) has an admissible solution on $\overline{\Omega} \times [0,T)$, and suppose by contradiction that $T<+\infty$. We need the following a priori estimates:

$$\sup_{\overline{\Omega} \times [0,T)} |Du| \le 1 - \vartheta, \quad \sup_{\overline{\Omega} \times [0,T)} |H_2[u]^{\frac{1}{2}} - \hat{f}| \le C_1, \quad \sup_{\overline{\Omega} \times [0,T)} |D^2 u| \le C_2, \tag{6.2}$$

and

$$\alpha_0 \le \inf_{\overline{\Omega} \times [0,T)} H_2[u]^{\frac{1}{2}}.\tag{6.3}$$

with $\vartheta \in (0,1]$, $C_1, C_2 \geq 0$, and $\alpha_0 > 0$. With these estimates at hand (and the obvious C^0 estimate), the estimates of Krylov and Safonov and the Schauder theory imply estimates of higher derivatives of u. We may thus extend u to a solution on [0,T]. Admissibility at the time T is guaranteed by (6.3) and Mac-Laurin inequality (1.1). The short time existence theory then yields a solution on $[0,T+\varepsilon)$, $\varepsilon > 0$, and thus a contradiction with the definition of T.

In the rest of the section we carry out estimates (6.2) and (6.3). Instead of (6.1) we will also consider the equivalent problem

$$\begin{cases}
\dot{X} = (F - \hat{f})N \text{ in } \Sigma_0 \times (0, T) \\
X = X_0 \text{ on } \partial \Sigma_0 \times [0, T) \cup \Sigma_0 \times \{0\},
\end{cases}$$
(6.4)

where $\Sigma_0 = \operatorname{graph} u_0$ and $X : \Sigma_0 \times [0, T) \to \mathbb{R}^{n,1}$ denotes the embedding vector in $\mathbb{R}^{n,1}$.

We will denote by D_0 the domain of dependence in $\mathbb{R}^{n,1}$ of the boundary data $\Sigma_0 = \operatorname{graph} u_0$ (a point p belongs to D_0 if every non-spacelike ray through p intersects Σ_0). D_0 is a compact subset of $\mathbb{R}^{n,1}$, and, since $X = X_0$ on $\partial \Sigma_0 \times [0,T)$ and X is spacelike, X(x,t) belongs to D_0 during the evolution.

6.1. The C^1 estimate.

6.1.1. The maximum principle for the first derivatives.

PROPOSITION 6.2. Let $X: \Sigma_0 \times [0,T) \to \mathbb{R}^{n,1}$ be a smooth solution of (6.4). Then

$$\sup_{\Sigma_0 \times [0,T)} \nu \le C,$$

where C depends on the C^0 estimate, on $\sup_{D_0 \times [0,T]} |D \log \hat{f}|_{eucl}$ and on an upper bound of ν on the parabolic boundary $\partial \Sigma_0 \times [0,T] \cup \Sigma_0 \times \{0\}$.

Proof. Let K be a positive constant to be chosen later. At an interior maximum of $\psi = e^{Ku}\nu$, we have

$$\frac{d}{dt}(\log \psi) - F^{ij}(\log \psi)_{ij} \ge 0.$$

Thus, using (5.5),

$$\frac{d}{dt}(\log \nu) - F^{ij}(\log \nu)_{ij} - K\hat{f}\nu \ge 0. \tag{6.5}$$

Moreover, we have

$$\frac{d}{dt}(\log \nu) - F^{ij}(\log \nu)_{ij} = \frac{1}{\nu} \left(\dot{\nu} - F^{ij}\nu_{ij}\right) + \frac{1}{\nu^2} F^{ij}\nu_i\nu_j,$$

with

$$\dot{\nu} - F^{ij}\nu_{ij} = \hat{f}_j t^j - \nu F^{ij} h_j^k h_{ki}$$

$$\leq \nu |\nabla \hat{f}| - \nu \sum_{i=1}^n F^{ii} \lambda_i^2,$$

and $\nu_i = u_i \lambda_i$. Here the tensors are written in an orthonormal basis of principal directions, and we used that $g_{ij}t^it^j \leq \nu^2$. Thus, (6.5) implies

$$\left(\sum_{i=1}^n F^{ii}\lambda_i^2 - \sum_{i=1}^n F^{ii}\lambda_i^2 \frac{u_i^2}{\nu^2}\right) + K\hat{f}\nu \le |\nabla \hat{f}|.$$

Discarding the first term which is positive, and using $|\nabla \hat{f}| \leq \nu |D\hat{f}|_{eucl}$, we obtain $K\hat{f} \leq |D\hat{f}|_{eucl}$, which is impossible for K sufficiently large such that

$$K > \sup_{D_0 \times [0,T]} |D \log \hat{f}|_{eucl}. \tag{6.6}$$

Thus, if K satisfies (6.6), the function $\psi = e^{Ku}\nu$ reaches its maximum on the parabolic boundary of $\Sigma_0 \times [0, T)$, and the result follows. \square

6.1.2. The C^1 estimate at the boundary.

PROPOSITION 6.3. Let $u: \overline{\Omega} \times [0,T) \to \mathbb{R}$ be an admissible solution of (6.1). Then there exists $\theta \in (0,1]$ such that

$$\sup_{\partial \Omega \times [0,T)} |Du| \le 1 - \vartheta.$$

The number ϑ depends on $\inf_{D_0 \times [0,T]} \hat{f}$, $\sup_{D_0 \times [0,T]} \hat{f}$, and $\sup_{\overline{\Omega}} |Du_0|$.

Proof. We fix $x_0 \in \partial \Omega$, and we denote by n the inner normal of $\partial \Omega$ at x_0 . We define, for $c(n) = \sqrt{\frac{n-1}{2n}}$,

$$P_1[u] = -\frac{\dot{u}}{\sqrt{1-|Du|^2}} + c(n)H_1[u], \ P_2[u] = -\frac{\dot{u}}{\sqrt{1-|Du|^2}} + H_2[u]^{\frac{1}{2}}.$$
 (6.7)

The construction of the upper barrier. Let u_1 be a spacelike function such that $u_1 \geq u_0$ in $\overline{\Omega}$, $u_1 = u_0$ on $\partial \Omega$, and $c(n)H_1[u_1] \leq \inf_{D_0 \times [0,T]} \hat{f}$. We may take for u_1 the solution of $H_1[u_1] = c$ in Ω , $u_1 = u_0$ on $\partial \Omega$, where c is a small constant; this Dirichlet problem is solved in [2], Theorem 4.1. Defining $u_1(x,t) := u_1(x)$, we have $P_1[u_1] \leq P_1[u]$ (since $P_1[u] = \hat{f} + c(n)H_1[u] - H_2[u]^{\frac{1}{2}}$ and using (1.1)), $u_1 \geq u$ on the parabolic boundary, and thus, by the maximum principle, $u_1 \geq u$ on $\overline{\Omega} \times [0,T)$. Since $u_1(x_0,t) = u(x_0,t) = u_0(x_0)$ for all $t \in [0,T)$, we obtain

$$\partial_n u(x_0, t) \le \partial_n u_1(x_0), \ \forall t \in [0, T).$$

The construction of the lower barrier. Let u_2 be an admissible function such that $u_2 \leq u_0$ in $\overline{\Omega}$, $u_2 = u_0$ on $\partial \Omega$, and $H_2[u_2]^{\frac{1}{2}} \geq \sup_{D_0 \times [0,T]} \hat{f}$. We may take for u_2 the strictly convex and spacelike solution of $K[u_2] = c$ in Ω , $u_2 = u_0$ on $\partial \Omega$, where c is a large constant; $K[u_2]$ stands for the Gauss curvature of graph u_2 ; this Dirichlet problem is solved in [7]. Defining $u_2(x,t) := u_2(x)$, we have $P_2[u_2] \geq P_2[u]$ on $\Omega \times (0,T)$, $u_2 \leq u$ on the parabolic boundary, and thus, by the maximum principle, $u_2 \leq u$ on $\overline{\Omega} \times [0,T)$. Since $u_2(x_0,t) = u_0(x_0,t) = u_0(x_0)$ for all $t \in [0,T)$, we obtain

$$\partial_n u(x_0, t) \ge \partial_n u_2(x_0), \ \forall t \in [0, T).$$

Finally, since the tangential derivatives at the boundary of u, u_1 and u_2 coincide, we get

$$\sup_{\partial \Omega \times [0,T)} |Du| \le \max(\sup_{\partial \Omega} |Du_1|, \sup_{\partial \Omega} |Du_2|),$$

and the result follows. \square

6.2. The velocity estimate.

PROPOSITION 6.4. Let X be an admissible solution of the parabolic Dirichlet problem (6.4). We recall that $\hat{f}_t \leq 0$ and we suppose that C and K are two positive constants such that

$$|\hat{f}_t| \le C \text{ and } |N^{\alpha} \hat{f}_{\alpha}| \le K$$
 (6.8)

during the evolution. If $F - \hat{f} \ge 0$ at t = 0 then, for all $t \in [0, T)$.

$$0 \le F - \hat{f} \le e^{Kt} \sup_{t=0} (F - \hat{f}) + \frac{C}{K} (e^{Kt} - 1). \tag{6.9}$$

In particular, there exist two constants $\alpha_0, \beta_0 > 0$ such that

$$\alpha_0 \le F \le \beta_0 \tag{6.10}$$

on $\Sigma_0 \times [0,T)$. The constants α_0, β_0 depend on C, K, T, $\sup_{t=0} (F - \hat{f})$, and $\inf_{D_0 \times [0,T]} \hat{f}$.

REMARK 6.5. The constants C and K in (6.8) are controlled by $\sup_{D_0 \times [0,T]} |\hat{f}_t|$, $\sup_{D_0 \times [0,T]} |D\hat{f}|_{eucl}$, and by the C^1 estimate obtained Section 6.1.

Proof. We first consider $\Psi_1 := (F - \hat{f})e^{-Kt}$. The evolution equation of Ψ_1 is

$$\begin{split} \dot{\Psi}_1 - F^{ij} \Psi_{1ij} &= \left[\frac{d}{dt} (F - \hat{f}) - F^{ij} (F - \hat{f})_{ij} - K(F - \hat{f}) \right] e^{-Kt} \\ &= \left[-F^{ij} h_{ik} h_j^k (F - \hat{f}) - N^\alpha \hat{f}_\alpha (F - \hat{f}) - \hat{f}_t - K(F - \hat{f}) \right] e^{-Kt} \\ &\geq \left[-F^{ij} h_{ik} h_j^k - N^\alpha \hat{f}_\alpha - K \right] \Psi_1, \end{split}$$

since $\hat{f}_t \leq 0$. Let $T_1 \in (0,T)$. The function Ψ_1 on $\overline{\Omega} \times [0,T_1]$ reaches its minimum at some point (x_0,t_0) . Assume that $(x_0,t_0) \in \Omega \times (0,T_1]$ and that $\Psi_1(x_0,t_0) < 0$. At (x_0,t_0) , we have $\dot{\Psi}_1 - F^{ij}\Psi_{1ij} \leq 0$, which gives

$$-F^{ij}h_{ik}h_j^k - N^\alpha \hat{f}_\alpha - K \ge 0 \tag{6.11}$$

and a contradiction with (6.8). Since $\Psi_1 \geq 0$ on the parabolic boundary, we conclude that $\Psi_1 \geq 0$ on $\overline{\Omega} \times [0, T)$, and thus that $F - \hat{f} \geq 0$ on $\overline{\Omega} \times [0, T)$.

We now consider $\Psi_2 := \left(F - \hat{f} + \frac{C}{K}\right)e^{-Kt}$, whose evolution equation is

$$\dot{\Psi}_2 - F^{ij}\Psi_{2ij} = \left[-F^{ij}h_{ik}h_j^k(F - \hat{f}) - N^{\alpha}\hat{f}_{\alpha}(F - \hat{f}) - \hat{f}_t - K(F - \hat{f}) - C \right]e^{-Kt}.$$

Let $T_2 \in (0,T)$. The function Ψ_2 on $\overline{\Omega} \times [0,T_2]$ reaches its maximum at some point (x_0,t_0) . Assume that $(x_0,t_0) \in \Omega \times (0,T_2]$ and that $\Psi_2(x_0,t_0) > \frac{C}{K}$. The latter implies that $F - \hat{f} > 0$ at (x_0,t_0) . At (x_0,t_0) , $\dot{\Psi}_2 - F^{ij}\Psi_{2ij} \geq 0$, which gives

$$-F^{ij}h_{ik}h_{i}^{k}(F-\hat{f}) - N^{\alpha}\hat{f}_{\alpha}(F-\hat{f}) - \hat{f}_{t} - K(F-\hat{f}) - C \ge 0$$
 (6.12)

and a contradiction with (6.8). Since $\Psi_2 \leq \frac{C}{K}$ on $\partial\Omega \times [0,T)$ and $\Psi_2 \geq \frac{C}{K}$ on $\Omega \times \{0\}$, we conclude that, for all $(x,t) \in \overline{\Omega} \times [0,T)$,

$$\Psi_2(x,t) \le \sup_{x \in \overline{\Omega}} \Psi_2(x,0),$$

which proves the proposition. \square

6.3. The C^2 estimate.

6.3.1. The maximum principle for the second derivatives.

Proposition 6.6. Let $X: \Sigma_0 \times [0,T) \to \mathbb{R}^{n,1}$ be a solution of (6.4). Then

$$\sup_{\xi \in T\Sigma_t, |\xi|=1} h_{ij} \xi^i \xi^j \le C$$

during the evolution, for some constant C which depends on a bound of the second fundamental form on the parabolic boundary $\partial \Sigma_0 \times [0,T) \cup \Sigma_0 \times \{0\}$ and on estimates obtained before.

Proof. The estimate relies on J.Urbas C^2 estimate [19] for the elliptic Dirichlet problem. We fix $T_1 \in (0,T)$. For $t \in [0,T_1]$, $x \in \Sigma_0$, and $\xi \in T_{X(x,t)}\Sigma_t$ with $|\xi| = 1$, we consider

$$\tilde{W}(x,\xi,t) := \eta^{\beta}(X(x,t))h_{ij}\xi^{i}\xi^{j},$$

where η is a positive function on $\mathbb{R}^{n,1}$ and β is a positive constant, which will be defined later. We suppose that \tilde{W} reaches its maximum at (x_0, ξ_0, t_0) where $t_0 \in (0, T_1], x_0$ is an interior point of Σ_0 , and $\xi_0 \in T_{X(x_0,t_0)}\Sigma_{t_0}$, with $|\xi_0| = 1$. We choose e_1^0, \ldots, e_n^0 a local frame on Σ_0 which induces on Σ_{t_0} an orthonormal frame $\hat{e_1}, \ldots, \hat{e_n}$ such that

$$\hat{e}_1(X(x_0,t_0)) = \xi_0 \text{ and } \nabla_{\hat{e}_i}\hat{e}_j(X(x_0,t_0)) = 0.$$

Observe that $\hat{e_1}$ is a principal direction of Σ_{t_0} at $X(x_0, t_0)$, associated to the largest principal curvature. We still denote by $\hat{e_1}, \dots, \hat{e_n}$ the frame induced by e_1^0, \dots, e_n^0 on Σ_t , for every t. The function

$$W(x,t) := \eta^{\beta} II(\hat{e_1},\hat{e_1})/|\hat{e_1}|^2,$$

where II stands for the second fundamental form of Σ_t , reaches its maximum at (x_0, t_0) ; we get

$$\begin{array}{rcl} \frac{d}{dt} {\log W} - F^{ij} ({\log W})_{ij} & = & \beta \left(\dot{\log \eta} - F^{ij} ({\log \eta})_{ij} \right) + \frac{1}{h_{11}} \left(\dot{h}_{11} - F^{ij} h_{11;ij} \right) \\ & & + \frac{1}{h_{11}^2} F^{ij} h_{11;i} h_{11;j} - \frac{\dot{g}_{11}}{g_{11}} \geq 0. \end{array}$$

From the evolution equation (5.4), we get:

$$\dot{h}_{11} - F^{ij} h_{11;ij} = F h_{11}^2 - h_{11} F^{kl} (h_k^a h_{al})
+ F^{kl,pq} h_{kl;1} h_{pq;1} - \hat{f}_{11} + (F - \hat{f}) h_{11}^2,$$

and thus:

$$\beta \left(\log \eta - F^{ij} (\log \eta)_{ij} \right) + F h_{11} - F^{kl} (h_k^a h_{al})$$

$$+ \frac{1}{h_{11}} F^{kl,pq} h_{kl;1} h_{pq;1} - \frac{\hat{f}_{11}}{h_{11}} + (F - \hat{f}) h_{11}$$

$$+ \frac{1}{h_{11}^2} F^{ij} h_{11;i} h_{11;j} - \frac{\hat{g}_{11}}{g_{11}} \ge 0.$$

$$(6.13)$$

Recalling (6.10), $|F - \hat{f}|$ is under control, and we have the following estimates (where the largest principal curvature is denoted by λ_1 , and C_1, C_2, C_3 are constants under control):

$$Fh_{11} + (F - \hat{f})h_{11} \le C_1(1 + \lambda_1),$$

$$|\hat{f}_{11}| \le C_2(1+\lambda_1),\tag{6.14}$$

and, from (5.2),

$$\left|\frac{\dot{g}_{11}}{g_{11}}\right| \le C_3 \lambda_1.$$

For estimate (6.14), we refer to [19] p312-313. Thus

$$0 \geq -\beta \left(\log \eta - F^{ij} (\log \eta)_{ij} \right) + F^{kl} (h_k^a h_{al}) - C_4 (1 + \lambda_1) - \frac{1}{h_{11}} F^{kl,pq} h_{kl;1} h_{pq;1} - \frac{1}{h_{11}^2} F^{ij} h_{11;i} h_{11;j},$$

$$(6.15)$$

for some constant C_4 . We choose $\log \eta = \Phi$, with

$$\Phi(x_1,\ldots,x_n,x_{n+1}) := \varphi(x_1,\ldots,x_n),$$

where φ is some strictly convex function on \mathbb{R}^n . Note that

$$\dot{\log \eta} = (F - \hat{f}) d\Phi_{X(x_0, t_0)}(N)$$
(6.16)

is under control. Moreover, following J.Urbas [19], page 313,

$$F^{ij}(\log \eta)_{ij} \ge C_0 \tau - C$$

where $\tau = \sum_{i} F^{ii}$, and C_0, C are constants under control. Finally,

$$0 \geq \beta(C_0\tau - C') + F^{kl}(h_k^a h_{al}) - C_4(1 + \lambda_1) - \frac{1}{\lambda_1} F^{kl,pq} h_{kl;1} h_{pq;1} - \frac{1}{\lambda_1^2} F^{ij} h_{11;i} h_{11;j},$$

where C' is under control, which is analogous to inequality (2.8) obtained by J.Urbas in [19] page 312. We then obtain the estimate of λ_1 following the arguments used in [19] p. 314-315, without any modification. This gives the C^2 estimate if the C^2 estimate at the parabolic boundary is known. \square

6.3.2. The C^2 estimate at the boundary.

PROPOSITION 6.7. Let $u: \overline{\Omega} \times [0,T) \to \mathbb{R}$ be a smooth solution of the parabolic Dirichlet problem (6.1). Then

$$\sup_{(x,t)\in\partial\Omega\times(0,T)}|D^2u(x,t)|\leq C,$$

for some constant C under control (which depends on the estimates obtained Sections 6.1 and 6.2).

We fix $(x_0, t_0) \in \partial\Omega \times (0, T)$. Following [15], we write the evolution equation (6.1) on the form

$$-\dot{u} + \tilde{F}(Du, D^2u) = \hat{f}(x, u, t) \times \gamma(Du),$$

where $\gamma(Du) = \sqrt{1 - |Du|^2}$, and $\tilde{F}(Du, D^2u)$ is the square root of the second elementary symmetric function of the principal values of the $n \times n$ matrix whose coefficient (i, j) is given by

$$\sum_{k=1}^{n} \left(\delta_{ik} + \frac{u_i u_k}{1 - |Du|^2} \right) u_{kj}. \tag{6.17}$$

Let us consider the linear operator

$$LW := -\dot{W} + \tilde{F}^{ij}W_{ij},$$

where $\tilde{F}^{ij} = \frac{\partial \tilde{F}}{\partial q_{ij}}(Du, D^2u)$. We suppose that (e_1, \ldots, e_n) is a basis such that (e_1, \ldots, e_{n-1}) is an orthonormal basis made of principal vectors of $\partial \Omega$ at x_0 and e_n is the unit inner normal of Ω at x_0 . Let

$$W(x,t) := g(x,Du(x,t)) - \frac{K}{2} \sum_{k=1}^{n-1} (u_k(x,t) - u_k(x_0,t_0))^2,$$

where $g: \overline{\Omega} \times B(0,1) \to \mathbb{R}$ is a given smooth function and K is a constant.

The following key inequality is a lorentzian analog of (2.4) in [15]:

Lemma 6.8. If K is sufficiently large under control, W satisfies

$$LW \le C_1(1 + |DW| + \sum_{ij} \tilde{F}^{ij} W_i W_j + \sum_i \tilde{F}^{ii}),$$
 (6.18)

where C_1 depends on the C^1 estimate and on the constants α_0, β_0 in (6.10).

Sketch of the proof. Following the lines of [15] Section 3, we obtain the following expression for LW, which is analogous to (3.13) in [15]:

$$LW = -K \sum_{\alpha=1}^{n} \tilde{\sigma}_{1,\alpha} u_{\alpha\alpha}^{2} \left(\sum_{k=1}^{n-1} \eta_{k}^{\alpha^{2}} \right) + j_{1} + j_{2} + j_{3}, \tag{6.19}$$

with

$$j_1 = -2\sum_{\alpha=1}^n \tilde{\sigma}_{1,\alpha} u_\alpha u_{\alpha\alpha} W_\alpha,$$

$$|j_2| \le C \left(\sum_{\alpha=1}^n \tilde{\sigma}_{1,\alpha} |u_{\alpha\alpha}| + \sum_{\alpha=1}^n \tilde{\sigma}_{1,\alpha} \right) \text{ and } |j_3| \le C \left(1 + |DW| \right),$$

where C is a constant under control. Here we use the letter α for derivatives in a basis (τ_{α}) of \mathbb{R}^n which induces by the map $x \mapsto (x, u(x, t))$ an orthonormal basis of principal vectors of graph u at (x, u(x, t)); moreover $\tilde{\sigma}_{1,\alpha}$ denotes a sum of principal values of (6.17), and the numbers η_k^{α} are such that $e_k = \sum_{\alpha} \eta_k^{\alpha} \tau_{\alpha}$, for $k = 1, \ldots, n$. Expression (6.19) is also analogous to (26) in [3]. We then follow the arguments in [3], from page 19 to page 23, without modification, and obtain (6.18).

Setting

$$\tilde{W}(x,t) := \exp\left(-C_1 g(x_0, Du(x_0, t_0))\right) - \exp(-C_1 W) - b|x - x_0|^2,$$

the following holds (see [15], inequality (2.5)):

Lemma 6.9. If b is sufficiently large,

$$L\tilde{W} \leq C_2(1 + |D\tilde{W}|),$$

where C_2 is some constant under control.

We first estimate the mixed second derivatives. Let e_s be a unit vector tangent to $\partial\Omega$ at x_0 , and let ξ be the local vector field tangent to the boundary, and spanned by the vector e_s : for all $x \in \overline{\Omega} \cap \overline{B_r}(x_0)$,

$$\xi(x) := e_s + \rho_s(x')e_n,$$

where e_n is the inner normal vector of Ω at x_0 , and where, in the splitting $\mathbb{R}^n = T_{x_0}\partial\Omega \oplus \mathbb{R}.e_n$, $x - x_0 = (x', x_n)$ and $\partial\Omega$ is locally the graph of ρ .

As in [3], we take $g(x,p) = \langle p, \xi(x) \rangle$, and we define the barrier function

$$v = -a_0|x - x_0|^2 - h(d) + \psi(x'),$$

with $h(d) = c_0(1 - e^{-b_0 d})$ and

$$\psi(x') = \exp(-C_1 u_{0\xi}(x_0)) - \exp(-C_1 u_{0\xi}(x')) \exp\left(C_1 K \sum_{k=1}^{n-1} (u_{0k}(x') - u_{0k}(x_0))^2 + 2C_1 K(|u_{0n}(x')|^2 + 1)|D\rho(x')|^2\right).$$

Here d denotes the distance function to the boundary-point x_0 , $u_{0\xi}(x)$ denotes $\langle Du_0(x), \xi(x) \rangle$, and, for a function f defined on \mathbb{R}^n , an expression like f(x') stands for $f(x', \rho(x'))$.

We first verify that $v \leq \tilde{W}$ on the parabolic boundary of $\overline{\Omega} \cap \overline{B_r}(x_0) \times [0,T)$:
- on $\partial(\overline{\Omega} \cap \overline{B_r}) \times [0,T) : v \leq \tilde{W}$ on $\partial\Omega \cap \overline{B_r} \times [0,T)$ by the very definition of ψ , and on $\overline{\Omega} \cap \partial \overline{B_r} \times [0,T)$ if $a_0 = a_0(r,\sup |\psi|,\sup |\tilde{W}|)$ is chosen sufficiently large.
- on $(\overline{\Omega} \cap \overline{B_r}) \times \{0\}$: we suppose that $x_0 = 0$, we fix $x \in \overline{\Omega} \cap \overline{B_r}$, and we consider $\omega(s) = \tilde{W}(sx,0) - v(sx)$, $s \in [0,1]$ (Ω is convex). We have $\omega(0) \geq 0$. Setting

$$C = \sup_{\overline{\Omega} \cap \overline{B_r} \times \{0\}} |D\tilde{W}| + \sup_{\overline{\Omega} \cap \overline{B_r} \times \{0\}} |D\psi|,$$

we see by a direct computation that, for all $s \in [0, 1]$,

$$\omega'(s) > |x| \{b_0 c_0 e^{-b_0 r} - C\}.$$

We thus obtain the property if $c_0 = c_0(b_0)$ is chosen large such that

$$b_0 c_0 e^{-b_0 r} \ge C. (6.20)$$

From the proof of Lemma 4.6. in [3], we see that

$$Lv > C_2(1+|Dv|)$$

on $\Omega \cap B_r(x_0) \times (0,T)$, if $h' = b_0 c_0 e^{-b_0 d}$, $-\frac{h''}{h'} = b_0$ are large, which is compatible with (6.20). The comparison principle implies that $v \leq \tilde{W}$ on the parabolic domain, and, since $v(x_0) = \tilde{W}(x_0,t_0) = 0$, we get

$$v_n(x_0) \le \tilde{W}_n(x_0, t_0),$$

which gives the estimate

$$u_{sn}(x_0, t_0) > C_3$$

where C_3 is a controlled constant. As in [3], to estimate $u_{sn}(x_0, t_0)$ from above we do the same with $g(x, p) = -\langle p, \xi(x) \rangle = -p_s - \rho_s(x')e_n$.

We now estimate the double normal derivatives. A lower bound follows from $H_1[u] > 0$ and from the estimates of tangential and mixed second derivatives. To obtain an upper bound, we use a technique of N.S.Trudinger [18, 16]. We used this method in [3] for the elliptic Dirichlet problem. We define, for $p' \in B(0,1) \subset \mathbb{R}^{n-1}$ and q' a $(n-1) \times (n-1)$ symmetric matrix

$$\tilde{F}_1(p',q') = \sum_{i,j=1}^{n-1} \left(\delta_{ij} + \frac{p'_i p'_j}{1 - |p'|^2} \right) q'_{ij}.$$

We denote by γ the outward unit normal to $\partial\Omega$ in \mathbb{R}^n , and by ∂ the tangential differential operator on $\partial\Omega$. We fix $T_1 \in (0,T)$, and $(y,t_1) \in \partial\Omega \times [0,T_1]$ such that $\tilde{F}_1(\partial u_0, \partial^2 u_0 + u_\gamma \partial \gamma)$ reaches its minimum at (y,t_1) . As in [3] page 27, an upper bound of u_{nn} on $\partial\Omega \times [0,T_1]$ follows from an upper bound of $u_{nn}(y,t_1)$. We keep the notation introduced above, but here adapted to the boundary-point y. We set

$$g(x,p) = \tilde{F}_1(\partial u_0(x'), \partial^2 u_0(x') + \langle p, \gamma(x') \rangle \partial \gamma(x')),$$

and

$$\begin{split} \tilde{W}(x,t) &= \exp[-C_1 g(y,Du(y,t_1))] \left\{ 1 - \exp\left[-C_1 (g(x,Du(x,t)) - g(y,Du(y,t_1)))\right] \right. \\ &\times \exp\left(C_1 \frac{K}{2} \sum_{k=1}^{n-1} (u_k(x,t) - u_k(y,t_1))^2\right) \right\} - b|x-y|^2. \end{split}$$

We consider the barrier function

$$v = -a_0|x - y|^2 - h(d) + \psi(x')$$

with $h(d) = c_0(1 - e^{-b_0 d})$ and

$$\psi(x') = \exp(-C_1 g(y, Du(y, t_1))) \left\{ 1 - \exp\left(C_1 K \sum_{k=1}^{n-1} (u_{0k}(x') - u_{0k}(y))^2 + 2C_1 K(|u_{0n}(x')|^2 + 1)|D\rho(x')|^2\right) \right\}.$$

For suitable constants a_0, b_0, c_0 under control, we have $v \leq \tilde{W}$ on the parabolic boundary of $\overline{\Omega} \cap \overline{B_r} \times [0, T_1)$, and $Lv > C_2(1+|Dv|)$ in $\overline{\Omega} \cap \overline{B_r} \times [0, T_1)$ (see above the estimate of the mixed derivatives). By the comparison principle and since $v(y) = \tilde{W}(y, t_1) = 0$, we obtain that $v_n(y) \leq \tilde{W}_n(y, t_1)$, which gives

$$u_{nn}(y,t_1) \leq C_4$$

where C_4 is a constant under control. We finally observe that the bound is independent of T_1 .

7. Existence of the entire flow reduced to obtaining local C^1 and C^2 estimates, and convergence. We suppose here that $F, \underline{u}, \overline{u}$ and u_0 satisfy the hypotheses of Theorem 1.4: $\underline{u}, \overline{u} : \mathbb{R}^n \to \mathbb{R}$ are the barriers constructed Section 3 (\overline{u} is a smooth spacelike and strictly convex function with constant mean curvature h and \underline{u} is the supremum of spacelike functions with constant scalar curvature $H_2 = k$) and $u_0 : \mathbb{R}^n \to \mathbb{R}$ is some smooth spacelike and strictly convex function such that

$$\underline{u} < u_0 < \overline{u} \text{ and } 1 \le H_2[u_0] \le k.$$
 (7.1)

To construct the entire flow, we solve a family of parabolic Dirichlet problems with parabolic boundary data u_0 on a growing sequence of balls. We modify slightly the equations near the boundary of the balls such that the problems are compatible on the corner of the parabolic domains. This is done in such a way that the normal velocities are uniformly bounded in terms of $H_2[u_0]$. Moreover the functions u, \overline{u} are still barriers for the modified evolution equations. This theorem is analogous to Theorem B.4 in [5] for the logarithmic Gauss curvature flow.

THEOREM 7.1. Let R > 1 and the ball of \mathbb{R}^n , $B_R := \{x \in \mathbb{R}^n : |x| < R\}$. We choose a smooth function $\eta: \overline{B_R} \times \mathbb{R} \to [0,1]$ such that $\eta = 0$ on $(B_{R-1} \times \mathbb{R}) \cup$ $\operatorname{graph} \underline{u} \cup \operatorname{graph} \overline{u}$, and $\eta = 1$ near $\operatorname{graph} u_{0|\partial B_R}$. We also choose a smooth function $\zeta:[0,+\infty)\to[0,1]$ such that $\zeta(t)=1$ near t=0, $\zeta(t)=0$ for $t\geq 1,$ and $\zeta'\leq 0.$ We

$$\hat{f}(x, u, t) := \eta(x, u) \zeta\left(\frac{t}{\varepsilon}\right) \left[H_2[u_0]^{\frac{1}{2}} - 1\right] + 1. \tag{7.2}$$

If $\varepsilon > 0$ is chosen sufficiently small, the parabolic Dirichlet problem

$$\begin{cases} -\frac{\dot{u}}{\sqrt{1-|Du|^2}} + H_2[u]^{\frac{1}{2}} &= \hat{f}(x,u,t) \text{ in } B_R \times (0,+\infty) \\ u(x,t) &= u_0(x) \text{ on } \partial B_R \times [0,+\infty) \cup B_R \times \{0\}, \end{cases}$$
(7.3)

has an admissible solution $u: \overline{B_R} \times [0, +\infty) \to \mathbb{R}$ such that the normal velocity $\frac{\dot{u}}{\sqrt{1-|Du|^2}}$ is uniformly bounded in terms of $H_2[u_0]$. Moreover

$$\underline{u} \le u \le \overline{u} \tag{7.4}$$

for all time.

Observe that u solution of (7.3) is also solution of (1.10) on $B_{R-1} \times [0, +\infty)$. We also write problem (7.3) in the equivalent form:

$$\begin{cases}
\dot{X} = (F - \hat{f})N \\
X = X_0 \text{ on } \partial \Sigma_0^R \times [0, +\infty) \cup \Sigma_0^R \times \{0\},
\end{cases}$$
(7.5)

where \hat{f} is given by (7.2), $\Sigma_0^R = \operatorname{graph}_{\overline{B}_R} u_0$ and $X : \Sigma_0^R \times [0, +\infty) \to \mathbb{R}^{n,1}$ is the embedding function.

Proof. The existence of a solution follows from Theorem 6.1: $\hat{f}_t \leq 0$ holds, the compatibility conditions are fulfilled on the corner of the parabolic domain, and, observing that

$$\hat{f}_{|t=0} = \eta H_2[u_0]^{\frac{1}{2}} + (1-\eta)1 \le H_2[u_0]^{\frac{1}{2}},\tag{7.6}$$

we get $(H_2^{\frac{1}{2}} - \hat{f})_{|t=0} \ge 0$. We now prove (7.4). We consider the operators P_1, P_2 defined in (6.7). We recall that \underline{u} is of the form $\underline{u} = \sup_{i \in I} u_i$, where for all $i \in I$ the function u_i is spacelike with $H_2[u_i] = k$. Defining $u_i(x,t) := u_i(x)$, we have $P_2[u_i] = H_2[u_i]^{\frac{1}{2}} = k^{\frac{1}{2}}$. Moreover, from (7.2)-(7.1), we have $P_2[u] = \hat{f} \leq k^{\frac{1}{2}}$. Thus, since $u \geq u_i$ on the parabolic boundary, we get by the maximum principle that $u \geq u_i$ during the evolution, and finally that $u \geq u$. Now, setting $\overline{u}(x,t) := \overline{u}(x)$, we get

$$P_1[\overline{u}] = c(n)h. \tag{7.7}$$

Moreover, since $\hat{f} \geq 1$ and recalling (1.1), we have

$$P_1[u] = \hat{f} + c(n)H_1[u] - H_2[u]^{\frac{1}{2}} \ge 1.$$
 (7.8)

Since $c(n)h \leq 1$ (see Proposition 1.1), (7.7) and (7.8) imply that $P_1[u] \geq P_1[\overline{u}]$, and thus that $u \leq \overline{u}$ since this inequality also holds on the parabolic boundary.

We now estimate the normal velocity. We consider $X: \Sigma_0^R \times [0, +\infty) \to \mathbb{R}^{n,1}$ solution of (7.5). We first suppose that $t \in [0, \varepsilon]$. We note that $|\hat{f}_t| \leq \frac{C_0}{\varepsilon}$ where C_0 is a constant controlled in terms of $H_2[u_0]$; recalling inequality (6.9) in Proposition 6.4, we get

$$0 \le F - \hat{f} \le e^{Kt} \sup_{t=0} (F - \hat{f}) + \frac{C_0}{\varepsilon K} (e^{Kt} - 1),$$

where K is a bound of $|N^{\alpha}\hat{f}_{\alpha}|$. Observe that K may grow with R but is independent of ε (see Propositions 6.2 and 6.3). Taking $\varepsilon = \frac{1}{K}$, we get the estimate: for all $t \in [0, \varepsilon]$,

$$0 \le F - \hat{f} \le C\left(\sup_{t=0} (F - \hat{f}), C_0\right),$$
 (7.9)

where the right-hand side term is a constant bounded in terms of $H_2[u_0]$. For $t \geq \varepsilon$ the normal velocity fulfills

$$\frac{d}{dt}(F - \hat{f}) - F^{ij}(F - \hat{f})_{ij} = -(F - \hat{f})F^{ij}h_{ik}h^{k}j,$$

and the maximum principle implies that

$$0 \le F - \hat{f} \le \sup_{t=\varepsilon} (F - \hat{f}). \tag{7.10}$$

Estimates (7.9) and (7.10) imply the estimate of the normal velocity during the evolution in terms of the curvature $H_2[u_0]$ only. \square

We set u_R for a solution of the parabolic Dirichlet problem (7.3) on $\overline{B}_R \times [0, +\infty)$, R > 1. By construction, the normal velocity of the solution u_R is bounded by a constant which is independent of R. Suppose that the following estimates hold: for any $R_0 \geq 0$, there exists $R_1 = R_1(R_0)$ larger than R_0 , $\vartheta \in (0,1)$ and $C \geq 0$ such that, for every $R \geq R_1$,

$$\sup_{\overline{B}_{R_0} \times [0, +\infty)} |Du_R| \le 1 - \vartheta, \quad \sup_{\overline{B}_{R_0} \times [0, +\infty)} |u_R| + |D^2 u_R| \le C. \tag{7.11}$$

Then, higher order derivative estimates (due to Krylov, Safonov, and Schauder for positive times) imply that a subsequence converges in

$$C^{\infty}(\mathbb{R}^n\times(0,+\infty))\cap C^{1,\alpha;0,\frac{\alpha}{2}}(\mathbb{R}^n\times[0,+\infty))$$

for every $0 < \alpha < 1$ to a solution $u \in C^{\infty}(\mathbb{R}^n \times (0, +\infty)) \cap C^{1,1;0,1}(\mathbb{R}^n \times [0, +\infty))$ of (1.10).

We now prove the convergence of the entire flow u, following [10, 9]. We first note that $H_2[u]^{\frac{1}{2}} \geq 1$ during the evolution, since this property holds for the solutions of the Dirichlet problems (7.3). We deduce that $\dot{u} \geq 0$. Thus, for every $x \in \mathbb{R}^n$, $t \mapsto u(x,t)$ is an increasing function, bounded above by $\overline{u}(x)$, and

$$u_{\infty}(x) := \lim_{t \to +\infty} u(x,t)$$

is well defined. The a priori estimates, locally uniform in space and uniform in time, show that u_{∞} is a smooth and spacelike function, and that u(.,t) smoothly converges to u_{∞} as t tends to $+\infty$. We now fix $x \in \mathbb{R}^n$. Since $\dot{u} \geq 0$ and $\sup_{t \in [0,+\infty)} |Du(x,t)| < 1$, we get from (1.10) that

$$0 \le H_2[u]^{\frac{1}{2}}(x,t) - 1 \le c(x)\dot{u}(x,t),$$

where $c(x) \in \mathbb{R}$ does not depend on t. Thus

$$\int_0^{+\infty} [H_2[u]^{\frac{1}{2}}(x,t) - 1]dt < +\infty,$$

and there exists a sequence (t_n) such that $t_n \to +\infty$ and $H_2[u](x,t_n) \to 1$ as n tends to infinity. Thus u_∞ is a solution of (1.6).

In the rest of the article, we prove the local estimates (7.11).

- **8. The local** C^1 **estimate.** We obtain here the local C^1 estimate in the spirit of R.Bartnik's estimate concerning hypersurfaces of prescribed mean curvature. See e.g. [1].
- **8.1.** The estimate with a general time function. We suppose that X: $\Sigma_0 \times [0, +\infty) \to \mathbb{R}$ is a solution of (5.1) with $\hat{f} \equiv 1$. Let $\tau: \mathbb{R}^{n,1} \to \mathbb{R}$ be a smooth function whose lorentzian gradient $D\tau$ is a timelike and past oriented field (τ is a time function on $\mathbb{R}^{n,1}$). We set $\alpha^{-2} = -\langle D\tau, D\tau \rangle$ and $T = -\alpha D\tau$. Using the timelike vector field T, we define a Riemannian metric on $\mathbb{R}^{n,1}$ by

$$|Y|_T^2 := \langle Y, Y \rangle + 2\langle Y, T \rangle^2.$$

If S is a tensor field on $\mathbb{R}^{n,1}$, we denote by $|S|_T$ its norm with respect to the metric $|.|_T$. For instance, if Y is a vector field on $\mathbb{R}^{n,1}$,

$$|DY|_T = \left(\sum_{i,j=1}^{n+1} \langle D_{u_i} Y, u_j \rangle^2\right)^{\frac{1}{2}}$$

where $(u_1, \ldots, u_n, u_{n+1})$ is an orthonormal basis of $\mathbb{R}^{n,1}$ such that $u_{n+1} = T$. We fix $\tau_0 > 0$, and we suppose that, for every $t \geq 0$,

$$\Sigma_{t,\tau > \tau_0} := \{ X(x,t) : \ x \in \Sigma_0, \ \tau(X(x,t)) \ge \tau_0 \}$$
(8.1)

is a compact (spacelike) hypersurface such that $\tau = \tau_0$ on its boundary, and that the set $\Sigma_{t,\tau \geq 2\tau_0}$ is non-empty. We moreover suppose that τ,α,α^{-1} , $|D\alpha|_T$, $|DT|_T$ and $|D^2T|_T$ are bounded on the region

$$D_{\tau_0} := \bigcup_{t>0} \Sigma_{t,\tau \ge \tau_0} \tag{8.2}$$

of $\mathbb{R}^{n,1}$, and we fix τ_1 such that $\tau_1 \geq \tau$ on D_{τ_0} . Finally, we assume that F has positive lower and upper bounds on D_{τ_0} . Setting here $\nu := -\langle T, N \rangle$, we prove the following estimate:

THEOREM 8.1. There exists a constant C such that, for every $t \geq 0$,

$$\sup_{\Sigma_{t,\tau} > 2\tau_0} \nu \le C. \tag{8.3}$$

The constant C depends on τ_0, τ_1 , upper bounds of $\alpha, \alpha^{-1}, |D\alpha|_T, |DT|_T$ and $|D^2T|_T$ on the set D_{τ_0} , on lower and upper bounds of F on D_{τ_0} , and on $\sup_{\Sigma_0, \tau > \tau_0} \nu$.

This estimate relies on the maximum principle applied to the function $\varphi = \eta \nu$, where $\eta = (\tau - \tau_0)^K$ with K a large constant. We fix $T_1 \in (0, +\infty)$, and we consider φ on the compact set

$$J = \{(x,t) \in \Sigma_0 \times [0,T_1] : \tau(X(x,t)) \ge \tau_0\}.$$

The function φ reaches its maximum at a point $(x_0, t_0) \in J$. Our purpose is to estimate $\varphi(x_0, t_0)$ by a constant under control which does not depend on T_1 ; such an estimate clearly implies (8.3). If $t_0 = 0$, we readily get that $\varphi(x_0, t_0) \leq C'$ where $C' = C'(K, \tau_0, \tau_1, \Sigma_{0, \tau \geq \tau_0})$ is a constant, and the result follows. We thus suppose that $t_0 > 0$, and we prove the following proposition, which implies the estimate of $\varphi(x_0, t_0)$, and the theorem:

Proposition 8.2. Let $\nu_0 > 1$. If K is sufficiently large,

$$\nu(x_0,t_0) < \nu_0.$$

The constant K depends on ν_0 , τ_0 , τ_1 , and on bounds on α , α^{-1} , $|DT|_T$, $|D^2T|_T$ and F on the region D_{τ_0} .

In the following, we suppose that $\nu(x_0, t_0) > \nu_0$, and we will obtain a contradiction if K is large under control. Let us denote by $T^{||}$ the orthogonal projection of T on the tangent space of Σ_{t_0} . By definition of T, we have $T^{||} = -\alpha \nabla \tau$, and

$$\nu^2 - 1 = |T^{||}|^2 = \alpha^2 |\nabla \tau|^2. \tag{8.4}$$

Let Z be the tangent vector field of Σ_{t_0} such that $\langle Z, h \rangle = \langle N, D_h T \rangle$, for all tangent vector h. By a direct computation,

$$\nabla \nu = -S(T^{||}) - Z = \alpha S(\nabla \tau) - Z. \tag{8.5}$$

Here S stands for the curvature endomorphism of Σ_{t_0} . We first estimate |Z|:

Lemma 8.3. We have

$$|Z| \le C_0 \nu^2,\tag{8.6}$$

where C_0 only depends on an upper bound of $|DT|_T$.

Proof. Let $u_1, \ldots, u_n, u_{n+1}$ be an orthonormal basis such that $u_{n+1} = T$. Writing $N = \sum_{j=1}^n \alpha_j u_j + \nu T$, we have $\sum_{j \le n} \alpha_j^2 = \nu^2 - 1$. Let $h := \sum_{i=1}^{n+1} h_i u_i$ be a vector tangent to Σ_{t_0} . Since $\langle T, D_h T \rangle = 0$,

$$|\langle N, D_h T \rangle| \le \sum_{i=1}^{n+1} \sum_{j=1}^{n} |h_i \alpha_j \langle u_j, D_{u_i} T \rangle| \le \nu |h|_T |DT|_T.$$
(8.7)

Observe that inequality

$$|h|_T \le \sqrt{2}\nu|h| \tag{8.8}$$

holds for all tangent vector h. To prove this, suppose that $h \neq 0$, and define $\delta := \frac{h_{n+1}^2}{\sum_{i=1}^n h_i^2}$. By a straightforward computation,

$$|h|_T^2 = \left(\frac{1+\delta}{1-\delta}\right)|h|^2. \tag{8.9}$$

Since h is a tangent vector, $\langle h, N \rangle = \sum_{i=1}^n h_i \alpha_i - h_{n+1} \nu = 0$, and the Schwarz inequality readily gives that $\delta \leq \frac{\nu^2 - 1}{\nu^2}$; inequality (8.8) then follows from (8.9). Finally, inequalities (8.7) and (8.8) imply that $|\langle Z, h \rangle| \leq \sqrt{2} \nu^2 |h| |DT|_T$, and the lemma. \square

We need the evolution equation of ν :

Lemma 8.4. During the evolution

$$\dot{\nu} - F^{ij}\nu_{ij} = \langle D_N T, N \rangle + F^{ij} \langle D_{e_i, e_j}^2 T, N \rangle + 2F^{ij} \langle D_{e_i} T, D_{e_j} N \rangle$$
$$-\nu F^{ij} h_i^k h_{ki}. \tag{8.10}$$

Here (e_i) is a basis of $T\Sigma_t$ at X(x,t).

Proof. By Lemma 3.3 in [10], the normal evolves according to $\dot{N}=\nabla F$ (recall that $\hat{f}\equiv 1$ here) and thus

$$\langle T, \dot{N} \rangle = g^{ij} F_{;i} t_j = g^{ij} F^{kl} h_{kl;i} t_j.$$

Thus

$$\dot{\nu} = -\langle \dot{T}, N \rangle - \langle T, \dot{N} \rangle$$

$$= -(F - \hat{f})\langle D_N T, N \rangle - g^{ij} F^{kl} h_{kl:i} t_i. \tag{8.11}$$

We fix $(x,t) \in \Sigma_0 \times [0,+\infty)$. Let (e_i) be a local frame of Σ_t such that $\nabla_{e_i} e_j(X(x,t)) = 0$. Thus $D_{e_i} e_j(X(x,t)) = h_{ij}N$, and we have

$$D_{e_j}(D_{e_i}T) = D_{e_i,e_j}^2 T + h_{ij} D_N T$$

and

$$D_{e_i}(D_{e_i}N) = D_{e_i}(h_i^k e_k) = h_{i:j}^k e_k + h_i^k h_{kj} N.$$

Thus

$$F^{ij}\nu_{ij} = -F^{ij}\langle D_{e_i,e_j}^2 T, N \rangle - F\langle D_N T, N \rangle - 2F^{ij}\langle D_{e_i} T, D_{e_j} N \rangle$$
$$-F^{ij}h_{i;j}^k \langle T, e_k \rangle + F^{ij}h_i^k h_{kj}\nu. \tag{8.12}$$

Equations (8.11) and (8.12), together with the symmetry of $h_{ij;k}$ in the three indices (the Codazzi equations), imply (8.10). \square

Thus, the maximum condition $\frac{d}{dt}(\log \varphi) - F^{ij}(\log \varphi)_{ij} \ge 0$ reads

$$\left(F^{ij}h_{j}^{k}h_{ki} - \frac{1}{\nu^{2}}F^{ij}\nu_{i}\nu_{j}\right) - \left(\frac{d}{dt}\log\eta - F^{ij}\left(\log\eta\right)_{ij}\right) \\
\leq \frac{1}{\nu}\left(\langle D_{N}T, N\rangle + F^{ij}\langle D_{e_{i},e_{j}}^{2}T, N\rangle + 2F^{ij}\langle D_{e_{i}}T, D_{e_{j}}N\rangle\right).$$
(8.13)

Moreover, since $\nu_i = -h_i^k t_k - Z_i$ (see (8.5)), we get:

$$F^{ij}h_{j}^{k}h_{ki} - \frac{1}{\nu^{2}}F^{ij}\nu_{i}\nu_{j} = \left(F^{ij}h_{j}^{k}h_{ki} - \frac{1}{\nu^{2}}F^{ij}h_{i}^{k}t_{k}h_{j}^{l}t_{l}\right) - \frac{1}{\nu^{2}}F^{ij}Z_{i}Z_{j} - \frac{2}{\nu^{2}}F^{ij}h_{i}^{k}t_{k}Z_{j}.$$
(8.14)

We now estimate the terms in the expressions above:

LEMMA 8.5. There exist constants C_1, C_2, C_3 such that

$$|\langle D_N T, N \rangle| \le C_1 \nu^2, \tag{8.15}$$

$$\left| F^{ij} \langle D_{e_i, e_j}^2 T, N \rangle + \frac{1}{\nu} F^{ij} Z_i Z_j \right| \le C_2 \sigma_1 \nu^3, \tag{8.16}$$

and
$$\left| \frac{2}{\nu} F^{ij} h_i^k t_k Z_j + 2F^{ij} \langle D_{e_i} T, D_{e_j} N \rangle \right| \le C_3 \nu^2 \sum_i \sigma_{1,i} |\lambda_i|.$$
 (8.17)

The constants C_1, C_2, C_3 only depend on bounds on $|DT|_T$, $|D^2T|_T$ and F.

Proof. Let $(u_i)_{1 \leq i \leq n+1}$ be an orthonormal basis of $\mathbb{R}^{n,1}$ such that $u_{n+1} = T$. We suppose that e_1, \ldots, e_n is an orthonormal basis of principal directions of Σ_{t_0} at x_0 , and we define $(\alpha_{ij})_{1 \leq i,j \leq n+1}$ such that

$$e_i = \sum_{j=1}^{n+1} \alpha_{ij} u_j$$
 and $N = \sum_{j=1}^{n+1} \alpha_{n+1,j} u_j$.

The following estimates hold: for all i = 1, ..., n + 1, $\sum_{j=1}^{n+1} \alpha_{ij}^2 \le 2\nu^2$ (see (8.8) for i < n+1, and use $\langle N, N \rangle = -1$ for i = n+1).

We first prove (8.15): using the Schwarz inequality,

$$|\langle N, D_N T \rangle| \le \sum_{i,j=1}^{n+1} |\alpha_{n+1,i}| |\alpha_{n+1,j}| |\langle u_i, D_{u_j} T \rangle| \le 2\nu^2 |DT|_T,$$

and we get (8.15).

We estimate the first term in (8.16):

$$\left| \sum_{ij} F^{ij} \langle N, D_{e_i, e_j}^2 T \rangle \right| \leq \frac{1}{2F} \sum_i \sigma_{1,i} \sum_{jkl} |\alpha_{n+1,j}| |\alpha_{ik}| |\alpha_{il}| \left| \langle u_j, D_{u_k, u_l}^2 T \rangle \right|$$

$$\leq \frac{1}{2F} (n-1) 2^{3/2} \sigma_1 \nu^3 |D^2 T|_T.$$

For the second term in (8.16), we readily get: $F^{ij}Z_iZ_j \leq \frac{n-1}{2F}\sigma_1|Z|^2$, and we obtain the estimate from (8.6).

We finally prove (8.17):

$$\left| \frac{2}{\nu} F^{ij} h_i^k t_k Z_j + 2 F^{ij} \langle D_{e_i} T, D_{e_j} N \rangle \right| \leq \frac{1}{F} \sum_i \sigma_{1,i} |\lambda_i| \left(\frac{1}{\nu} |t_i| |Z_i| + |\langle D_{e_i} T, e_i \rangle| \right);$$

using $|T^{||}| \le \nu$, $|Z| \le C_0 \nu^2$ (Lemma 8.3) and $|\langle D_{e_i}T, e_i \rangle| \le 2\nu^2 |DT|_T$ we obtain (8.17). \square

We now prove that the smallest principal curvature of Σ_{t_0} at x_0 is negative, with absolute value arbitrarily large, if the constant K is chosen sufficiently large:

Lemma 8.6. If

$$K \ge 2C_0\alpha(\tau_1 - \tau_0)\frac{\nu_0^2}{\nu_0^2 - 1},$$
 (8.18)

the smallest principal curvature λ_n is negative and is estimated by

$$\lambda_n \le -\frac{1}{2} \frac{\alpha^{-1} K}{\tau - \tau_0} \nu. \tag{8.19}$$

Note that since φ vanishes if $\tau = \tau_0$ and is positive if $\tau > \tau_0$, we have $\tau > \tau_0$ at (x_0, t_0) .

Proof. By (8.5),

$$S(\nabla \tau) = \frac{1}{\alpha} (\nabla \nu + Z);$$

moreover, the extremum condition $\nabla \varphi(x_0, t_0) = 0$ reads

$$\frac{\nabla \nu}{\nu} = -\frac{K}{\tau - \tau_0} \nabla \tau.$$

Thus

$$\left\langle S\left(\frac{\nabla \tau}{|\nabla \tau|}\right), \frac{\nabla \tau}{|\nabla \tau|} \right\rangle = -\nu \alpha^{-1} \frac{K}{\tau - \tau_0} + \frac{\alpha^{-1}}{|\nabla \tau|^2} \langle Z, \nabla \tau \rangle. \tag{8.20}$$

By Lemma 8.3 and expression (8.4), we estimate

$$\frac{\alpha^{-1}}{|\nabla \tau|^2} |\langle Z, \nabla \tau \rangle| \le \alpha^{-1} \frac{|Z|}{|\nabla \tau|} \le C_0 \frac{\nu^3}{\nu^2 - 1}.$$

Since $\nu > \nu_0 > 1$, we have $\frac{\nu^2}{\nu^2 - 1} \le \frac{\nu_0^2}{\nu_0^2 - 1}$, and thus

$$-\nu\alpha^{-1}\frac{K}{\tau - \tau_0} + C_0 \frac{\nu^3}{\nu^2 - 1} \le \nu \left(-\alpha^{-1} \frac{K}{\tau - \tau_0} + C_0 \frac{\nu_0^2}{\nu_0^2 - 1} \right)$$
$$\le -\frac{1}{2}\alpha^{-1} \frac{K}{\tau - \tau_0} \nu$$

if $\frac{1}{2}\alpha^{-1}\frac{K}{\tau-\tau_0} \geq C_0\frac{\nu_0^2}{\nu_0^2-1}$, which follows from the hypothesis (8.18). Thus expression (8.20) is bounded by $-\frac{1}{2}\alpha^{-1}\frac{K}{\tau-\tau_0}\nu$, and the result follows. \square

As in Lemma 4.6. of [4], we obtain the key inequality:

LEMMA 8.7. If $\lambda_n \leq 0$,

$$F^{ij}h_j^k h_{ki} - \frac{1}{\nu^2} F^{ij}h_i^k t_k h_j^l t_l \ge \varepsilon \sigma_{1,n} \lambda_n^2,$$

where ε is a positive constant which only depends on an upper bound of F.

Proof. Just follow the lines of the proof of Lemma 4.6. in [4], with λ_n instead of λ_{i_0} and t_i instead of u_i , using here identity (8.4). \square

Inequality (8.13) and Lemmas 8.5 and 8.7 thus imply that

$$\varepsilon \sigma_{1,n} \lambda_n^2 - \left(\frac{d}{dt} \log \eta - F^{ij} (\log \eta)_{ij}\right) \le C_1 \nu + C_2 \sigma_1 \nu^2 + C_3 \nu \sum_i \sigma_{1,i} |\lambda_i|. \tag{8.21}$$

The next lemma permits to balance the last term in (8.21):

LEMMA 8.8. If $\lambda_n \leq 0$, then, for all i,

$$|\sigma_{1,i}|\lambda_i| \le \sigma_2 + \frac{\beta}{\nu}\sigma_{1,n}\lambda_n^2,$$

where β is a constant arbitrarily small, if $K = K(\alpha, \beta, \tau_0, \tau_1)$ is chosen sufficiently large.

Proof. We first suppose that $\lambda_i \leq 0$: we thus have $|\lambda_i| \leq |\lambda_n|$, and, since $\sigma_{1,n} \geq \sigma_{1,i}$,

$$\sigma_{1,i}|\lambda_i| \leq \sigma_{1,n}|\lambda_n|.$$

By estimate (8.19) in Lemma 8.6, $\frac{\nu}{\beta} \leq |\lambda_n|$, if $K = K(\tau_0, \tau_1, \alpha, \nu_0, \beta)$ is sufficiently large. This implies

$$|\sigma_{1,i}|\lambda_i| \leq \frac{\beta}{\nu} \sigma_{1,n} \lambda_n^2,$$

and the estimate. We now suppose that $\lambda_i \geq 0$: the proof relies on the following inequality:

$$\lambda_i \sigma_{1,i} < \sigma_2 + \gamma_n \sigma_{1,n} |\lambda_n|, \tag{8.22}$$

where γ_n is a positive constant which only depends on n. With this inequality at hand, taking as above K sufficiently large such that $\frac{\gamma_n \nu}{\beta} \leq |\lambda_n|$, we obtain the lemma. To finish the proof we thus focus on the proof of (8.22): first,

$$\lambda_i \sigma_{1,i} = \sigma_2 - \sigma_{2,in} - \sigma_{1,ni} \lambda_n,$$

where $-\sigma_{2,in}$ is a sum of terms of the form $-\lambda_j\lambda_k$, with $j\neq k$, and $j,k\notin\{i,n\}$. We observe that $-\sigma_{1,ni}\lambda_n=\sigma_{1,ni}|\lambda_n|\leq\sigma_{1,n}|\lambda_n|$, since $\lambda_i\geq 0$. It thus remains to bound the positive terms appearing in $-\sigma_{2,in}$: let $j,k\notin\{i,n\}$ be such that $-\lambda_j\lambda_k>0$. We suppose that $\lambda_k<0$, and thus that $\lambda_j>0$. We have $\lambda_j\leq\sigma_{1,n}$ since $\sigma_{1,n}=\lambda_j+\sigma_{1,j}-\lambda_n$ with $\sigma_{1,j}$ and $-\lambda_n$ positive. Moreover $|\lambda_k|\leq |\lambda_n|$ since $\lambda_n\leq\lambda_k\leq 0$. Thus $-\lambda_j\lambda_k\leq\sigma_{1,n}|\lambda_n|$, which concludes the proof of (8.22). \square

From (8.21) and Lemma 8.8 we obtain the inequality

$$\varepsilon \sigma_{1,n} \lambda_n^2 - \left(\frac{d}{dt} \log \eta - F^{ij} \left(\log \eta\right)_{ij}\right) \le C_1 \nu + C_2 \sigma_1 \nu^2 + nC_3 \nu \left(\sigma_2 + \frac{\beta}{\nu} \sigma_{1,n} \lambda_n^2\right). \tag{8.23}$$

Choosing β small such that $\varepsilon - nC_3\beta \geq \frac{\varepsilon}{2}$, we obtain

$$\frac{\varepsilon}{2}\sigma_{1,n}\lambda_n^2 - \left(\frac{d}{dt}\log\eta - F^{ij}\left(\log\eta\right)_{ij}\right) \le C_1\nu + C_2\sigma_1\nu^2 + nC_3\nu\sigma_2. \tag{8.24}$$

We now estimate the contribution of the cut-off function:

Lemma 8.9. There exists a constant C_4 such that

$$\frac{d}{dt}(\log \eta) - F^{ij}(\log \eta)_{ij} \le C_4 K \nu^2 \frac{\sigma_1}{\tau - \tau_0} \left(1 + \frac{1}{\tau - \tau_0}\right).$$

The constant C_4 depends on bounds on α^{-1} , $|D\alpha|_T$, $|DT|_T$ and F.

Proof. By a direct computation,

$$\frac{d}{dt}(\log \eta) = (F - \hat{f})\frac{K}{\tau - \tau_0}D\tau(N).$$

Since $|D\tau(N)| = \nu \alpha^{-1}$, we get

$$\frac{d}{dt}(\log \eta) \le C \frac{K}{\tau - \tau_0} \nu,\tag{8.25}$$

where C depends on bounds on α^{-1} and $F - \hat{f}$. Moreover

$$\sum_{i} \sigma_{1,i} (\log \eta)_{ii} = K \left(\sum_{i} \sigma_{1,i} \frac{\tau_{ii}}{\tau - \tau_0} - \sum_{i} \sigma_{1,i} \frac{\tau_i^2}{(\tau - \tau_0)^2} \right). \tag{8.26}$$

Using (8.4), the last term is directly estimated by

$$\sum_{i} \sigma_{1,i} \frac{\tau_i^2}{(\tau - \tau_0)^2} \le (n - 1)\alpha^{-2} \nu^2 \frac{\sigma_1}{(\tau - \tau_0)^2}.$$
 (8.27)

To estimate the first term in (8.26), we extend e_1, \ldots, e_n to vector fields of Σ_{t_0} such that $\nabla_{e_i} e_i(x_0) = 0$. Since $\tau_i = -\langle \alpha^{-1} T, e_i \rangle$ and $D_{e_i} e_i = \lambda_i N$, we get

$$\tau_{ii} = -\langle D_{e_i}(\alpha^{-1}T), e_i \rangle + \alpha^{-1}\nu\lambda_i.$$

Since $\langle D_{e_i}(\alpha^{-1}T), e_i \rangle = (\alpha^{-1})_i \langle T, e_i \rangle + \alpha^{-1} \langle D_{e_i}T, e_i \rangle$, and since

$$|\langle T, e_i \rangle| \le \nu$$
, $|\langle D_{e_i} T, e_i \rangle| \le 2\nu^2 |DT|_T$, and $|(\alpha^{-1})_i| \le \sqrt{2\nu} |D\alpha^{-1}|_T$

(see the proof of Lemma 8.5), we obtain

$$\left| \sum_{i} \sigma_{1,i} \frac{\tau_{ii}}{\tau - \tau_0} \right| \le \frac{\alpha^{-1}}{\tau - \tau_0} \left(2(n-1)\sigma_1 \nu^2 \left\{ \frac{1}{\alpha^{-1}} |D\alpha^{-1}|_T + |DT|_T \right\} + 2\nu\sigma_2 \right).$$

Observing moreover that σ_1 is bounded below by a positive constant (Mac-Laurin inequality), this last estimate together with (8.26) and (8.27) imply that

$$-F^{ij} (\log \eta)_{ij} \le CK\nu^2 \frac{\sigma_1}{\tau - \tau_0} \left(1 + \frac{1}{\tau - \tau_0} \right)$$
 (8.28)

where C only depends on bounds on α^{-1} , $|D\alpha|_T$, $|DT|_T$, and F. Finally, estimates (8.25) and (8.28) give the result. \square

Using the lower bound $\frac{\varepsilon}{2}\sigma_{1,n}\lambda_n^2 \geq \frac{\varepsilon}{2}\sigma_1\frac{\alpha^{-2}K^2}{4(\tau-\tau_0)^2}\nu^2$ given by Lemma 8.6, we finally obtain

$$\frac{\varepsilon}{2}\sigma_1 \frac{1}{4}K^2 \nu^2 - C_4 K \nu^2 \alpha^2 \sigma_1((\tau - \tau_0) + 1) \le \left(C_1 \nu + C_2 \sigma_1 \nu^2 + nC_3 \nu \sigma_2\right) \alpha^2 (\tau - \tau_0)^2,$$

which is impossible if K is sufficiently large under control.

8.2. The construction of the adapted time function. We suppose that \underline{u} and \overline{u} are the barriers constructed Section 3. Let $R_0 > 0$, and consider $\Psi : \mathbb{R}^n \to \mathbb{R}$ such that $\Psi < \underline{u}$ on \overline{B}_{R_0} , and $\Psi \geq \overline{u}$ near infinity, given by Lemma 3.5. We define

$$\tau(x_1,\ldots,x_n,x_{n+1}) := x_{n+1} - \Psi(x_1,\ldots,x_n).$$

The function τ is a time function since ψ is spacelike. We fix $\tau_0 > 0$ such that $\Psi + 2\tau_0 \leq \underline{u}$ on \overline{B}_{R_0} . We also fix R_1 such that $\psi(x) \geq \overline{u}(x)$ if $|x| \geq R_1$, and, for $R \geq R_1 + 1$, we consider $X^R : \Sigma_0^R \times [0, +\infty) \to \mathbb{R}^{n,1}$ solution of (7.5). We set K for the compact set $\{\psi(x_1, \ldots, x_n) \leq x_{n+1} \leq \overline{u}(x_1, \ldots, x_n)\}$. Note that $\hat{f} \equiv 1$ on K, and that the normal velocity F is bounded from above and from below during the evolution, uniformly in R. For all $t \in [0, +\infty)$, the set $\Sigma_{t,\tau \geq \tau_0}^R$ defined by (8.1) is compact, and is such that $\tau = \tau_0$ on its boundary. Moreover, since the set D_{τ_0} defined by (8.2) belongs to the compact set K, the time function τ satisfies all the requirements of the previous section. Thus Theorem 8.1 applies and gives the gradient estimate on the set

$$\{(x,t) \in \Sigma_0^R \times [0,+\infty) : \tau(X^R(x,t)) \ge 2\tau_0\}.$$

We deduce the required local gradient estimate (7.11) since

$$\operatorname{graph}_{\overline{B}_{R_0}} u_R \subset \{X \in \mathbb{R}^{n,1} : \ \tau(X) \ge 2\tau_0\}.$$

9. The local C^2 **estimate.** We suppose that $\underline{u}, \overline{u}$ are the barriers constructed Section 3.

THEOREM 9.1. Let $R_0 \geq 0$, and let $R_0' \geq R_0$ and $\Phi : \overline{B}_{R_0'} \to \mathbb{R}$ be such that

$$\Phi > \overline{u} \text{ on } \overline{B}_{R_0}, \ \Phi \leq \underline{u} \text{ on } \partial B_{R_0},$$

given by Lemma 3.7. We fix $\delta_0 > 0$ such that $\Phi \geq \overline{u} + \delta_0$ on \overline{B}_{R_0} , and we set, for all $X = (x_1, \dots, x_{n+1}) \in \overline{B}_{R_0'} \times \mathbb{R} \subset \mathbb{R}^{n,1}$,

$$\eta(X) := \Phi(x_1, \dots, x_n) - x_{n+1}.$$

Then, there exists $R_1 \ge {R_0}'$ such that, for all $R \ge R_1$, the solution X^R of (7.5) satisfies the following local C^2 estimate:

$$\sup_{\{(x,t):\ \eta(X^R(x,t))\geq\delta_0\}}|II^R_{(x,t)}|\leq C.$$

Here $|II_{(x,t)}^R|$ stands for the norm of the second fundamental form of Σ_t^R at $X^R(x,t)$, and C is a constant controlled by the local C^1 estimate on the set where $\eta \geq 0$.

Proof. We fix $R_1 \ge R_0'$ such that for all $R \ge R_1$ the local C^1 estimate holds on the set where $\underline{u} \le x_{n+1} \le \Phi$. For $T_1 > 0$ we define

$$\Gamma_{T_1} = \{(x,t) \in \Sigma_0^R \times [0,T_1] : \eta(X^R(x,t)) \ge 0\}.$$

Following J.Urbas [19], we suppose that the function

$$\tilde{W}(x,t,\xi) := \eta^{\beta}(X^R(x,t))h_{ij}\xi^i\xi^j, \tag{9.1}$$

defined for all $(x,t) \in \Gamma_{T_1}$ and all unit $\xi \in T_{X^R(x,t)}\Sigma_t$, reaches its maximum at a point (x_0,t_0,ξ_0) , with $t_0 > 0$. Arguing as in Paragraph 6.3.1, we also get here inequality (6.15) at (x_0,t_0) . Moreover, using the evolution equation (5.5) of $u = x_{n+1}$, we obtain

$$\frac{d}{dt}\log\eta - F^{ij}\left(\log\eta\right)_{ij} = \frac{\nu\hat{f}}{\eta} + \frac{1}{\eta}\left(\dot{\Phi} - F^{ij}\Phi_{ij}\right) + F^{ij}\frac{\eta_i\eta_j}{\eta^2}.$$
 (9.2)

The following estimates hold: $F^{ij}\Phi_{ij} \geq c_0 \sum_i F_i^i - c$, $\dot{\Phi} \leq c$, and $\nu \hat{f} \leq c$ where c_0 and c are controlled constants; for the first estimate we refer to [19] p.313, and for the second estimate to (6.16). Thus

$$-\beta \left(\frac{d}{dt}\log \eta - F^{ij} \left(\log \eta\right)_{ij}\right) \ge \frac{\beta}{\eta} \left(c_0 \sum_{i} F_i^i - c'\right) - \beta F^{ij} \frac{\eta_i \eta_j}{\eta^2}.$$
 (9.3)

Inequalities (6.15) and (9.3) give inequality (2.8) obtained by J.Urbas in [19] p. 312 (where the first term in (2.8) is moreover estimated by (2.12) [19] p. 313). We then follow the arguments in [19], and obtain an upper bound of $\tilde{W}(x_0, t_0, \xi_0)$, if β is chosen sufficiently large (under control). The bound is independent of T_1 and R. This gives an upper bound of the second fundamental form during the evolution, on the set where $\eta \geq \delta_0$. \square

This estimate implies the local C^2 estimate (7.11) since

$$\operatorname{graph}_{\overline{B}_{R_0}} u_R \subset \{X \in \mathbb{R}^{n,1} : \eta(X) \ge \delta_0\},\$$

and thus completes the proof of Theorem 1.4.

Appendix A.

LEMMA A.1. Let u be a spacelike and convex function defined on \mathbb{R}^n , and let $x'_0 \in \mathbb{R}^{n-2}$. Setting

$$\tilde{u}(x_1, x_2) := u(x_1, x_2, x'_0),$$

we have, for all $(x_1, x_2) \in \mathbb{R}^2$,

$$H_1[\tilde{u}](x_1, x_2) \leq H_1[u](x_1, x_2, x'_0).$$

Proof. The second fundamental form of the graph of \tilde{u} in the chart (x_1, x_2) is

$$\tilde{II} = \frac{1}{\sqrt{1 - |D\tilde{u}|^2}} D^2 \tilde{u}.$$

Since $|Du| \ge |D\tilde{u}|$ and $D^2\tilde{u} = D^2u_{|_{\mathbb{R}^2 \times \{0\}}}$, we obtain

$$\frac{1}{\sqrt{1-|D\tilde{u}|^2}}D^2\tilde{u} \leq \frac{1}{\sqrt{1-|Du|^2}}D^2u_{|_{\mathbb{R}^2\times\{0\}}}.$$

The right-hand side term is the second fundamental form II of the graph of u, in the chart (x_1, \ldots, x_n) , restricted to the plane $x_3 = \cdots = x_n = 0$. Let us fix (e_1, e_2, \ldots, e_n) a basis in the chart (x_1, \ldots, x_n) which induces an orthonormal basis $(\hat{e}_1, \ldots, \hat{e}_n)$ of the tangent space of graph u at (x_1, x_2, x'_0) . We suppose moreover that e_1, e_2 belong to the plane $x_3 = \cdots = x_n = 0$. Thus \hat{e}_1, \hat{e}_2 are tangent to graph \tilde{u} , and we get:

$$H_1[\tilde{u}](x_1, x_2) = \tilde{I}I(\hat{e}_1) + \tilde{I}I(\hat{e}_2) \le II(\hat{e}_1) + II(\hat{e}_2)$$

$$\le \sum_{i=1}^n II(\hat{e}_i) \le H_1[u](x_1, x_2, x'_0),$$

where the second inequality follows from the convexity of u. \square

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