

COHOMOLOGICALLY SYMPLECTIC SOLVMANIFOLDS ARE SYMPLECTIC

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We consider aspherical manifolds with torsion-free virtually polycyclic fundamental groups, constructed by Baues. We prove that if those manifolds are cohomologically symplectic then they are symplectic. As a corollary we show that cohomologically symplectic solvmanifolds are symplectic.

1. Introduction

A $2n$ -dimensional compact manifold M is called cohomologically symplectic (c-symplectic) if we have $\omega \in H^2(M, \mathbb{R})$ such that $\omega^n \neq 0$. A compact symplectic manifold is c-symplectic but the converse is not true in general. For example $\mathbb{C}P^2 \# \mathbb{C}P^2$ is c-symplectic but not symplectic. But for some class of manifolds these two conditions are equivalent. For examples, nilmanifolds, i.e., compact homogeneous spaces of nilpotent simply connected Lie groups. In [7], for a nilpotent simply connected Lie group G with a cocompact discrete subgroup Γ (such subgroup is called a lattice), Nomizu showed that the de Rham cohomology $H^*(G/\Gamma, \mathbb{R})$ of G/Γ is isomorphic to the cohomology $H^*(\mathfrak{g})$ of the Lie algebra of G . By the application of Nomizu's theorem, if G/Γ is c-symplectic then G/Γ is symplectic (see [3, p. 191]). Every nilmanifold can be represented by such G/Γ (see [6]).

Consider solvmanifolds, i.e., compact homogeneous spaces of solvable simply connected Lie groups. Let G be a solvable simply connected Lie group with a lattice Γ . We assume that for any $g \in G$ the all eigenvalues of the adjoint operator Ad_g are real. With this assumption, in [5] Hattori extended Nomizu's theorem. By Hattori's theorem, for such case, without difficulty, we can similarly show that if G/Γ is c-symplectic, then G/Γ is symplectic. But the isomorphism $H^*(G/\Gamma, \mathbb{R}) \cong H^*(\mathfrak{g})$ fails to hold for general solvable Lie groups, and not all solvmanifolds can be represented by G/Γ . Thus it is a considerable problem whether every c-symplectic solvmanifold is symplectic.

Let Γ be a torsion-free virtually polycyclic group. In [1] Baues constructed the compact aspherical manifold M_Γ with $\pi_1(M_\Gamma) = \Gamma$. Baues proved that every infra-solvmanifold (see [1] for the definition) is diffeomorphic to M_Γ . In particular, the class of such aspherical manifolds contains the class of solvmanifolds. We prove that if M_Γ is c-symplectic then M_Γ is symplectic. In other words, for a torsion-free virtually polycyclic group Γ with $2n = \text{rank } \Gamma$, if there exists $\omega \in H^2(\Gamma, \mathbb{R})$ such that $\omega^n \neq 0$ then we have a symplectic aspherical manifold with the fundamental group Γ .

2. Notation and conventions

A general reference here is [2]. Let k be a subfield of \mathbb{C} . A group \mathbf{G} is called a k -algebraic group if \mathbf{G} is a Zariski-closed subgroup of $GL_n(\mathbb{C})$ which is defined by polynomials with coefficients in k . Let $\mathbf{G}(k)$ denote the set of k -points of \mathbf{G} and $\mathbf{U}(\mathbf{G})$ the maximal Zariski-closed unipotent normal k -subgroup of \mathbf{G} called the unipotent radical of \mathbf{G} . Let $U_n(k)$ denote the $n \times n$ k -valued upper triangular unipotent matrix group.

3. Aspherical manifolds with torsion-free virtually polycyclic fundamental groups

Definition 3.1. A group Γ is polycyclic if it admits a sequence

$$\Gamma = \Gamma_0 \supset \Gamma_1 \supset \cdots \supset \Gamma_k = \{e\}$$

of subgroups such that each Γ_i is normal in Γ_{i-1} and Γ_{i-1}/Γ_i is cyclic. We denote $\text{rank } \Gamma = \sum_{i=1}^k \text{rank } \Gamma_{i-1}/\Gamma_i$.

Proposition 3.1 [8, Proposition 3.10]. The fundamental group of a solvmanifold is torsion-free polycyclic.

Let k be a subfield of \mathbb{C} . Let Γ be a torsion-free virtually polycyclic group. For a finite index polycyclic subgroup $\Delta \subset \Gamma$, we denote $\text{rank } \Gamma = \text{rank } \Delta$.

Definition 3.2. We call a k -algebraic group \mathbf{H}_Γ a k -algebraic hull of Γ if there exists an injective group homomorphism $\psi : \Gamma \rightarrow \mathbf{H}_\Gamma(k)$ and \mathbf{H}_Γ satisfies the following conditions:

- (1) $\psi(\Gamma)$ is Zariski-dense in \mathbf{H}_Γ .
- (2) $Z_{\mathbf{H}_\Gamma}(\mathbf{U}(\mathbf{H}_\Gamma)) \subset \mathbf{U}(\mathbf{H}_\Gamma)$ where $Z_{\mathbf{H}_\Gamma}(\mathbf{U}(\mathbf{H}_\Gamma))$ is the centralizer of $\mathbf{U}(\mathbf{H}_\Gamma)$.
- (3) $\dim \mathbf{U}(\mathbf{H}_\Gamma) = \text{rank } \Gamma$.

Theorem 3.1 [1, Theorem A.1]. There exists a k -algebraic hull of Γ and a k -algebraic hull of Γ is unique up to k -algebraic group isomorphism.

Let Γ be a torsion-free virtually polycyclic group and \mathbf{H}_Γ the \mathbb{Q} -algebraic hull of Γ . Denote $H_\Gamma = \mathbf{H}_\Gamma(\mathbb{R})$. Let U_Γ be the unipotent radical of H_Γ

and T a maximal reductive subgroup. Then H_Γ decomposes as a semi-direct product $H_\Gamma = T \ltimes U_\Gamma$. Let \mathfrak{u} be the Lie algebra of U_Γ . Since the exponential map $\exp : \mathfrak{u} \rightarrow U_\Gamma$ is a diffeomorphism, U_Γ is diffeomorphic to \mathbb{R}^n such that $n = \text{rank } \Gamma$. For the semi-direct product $H_\Gamma = T \ltimes U_\Gamma$, we denote $\phi : T \rightarrow \text{Aut}(U_\Gamma)$ the action of T on U_Γ . Then we have the homomorphism $\alpha : H_\Gamma \rightarrow \text{Aut}(U_\Gamma) \ltimes U_\Gamma$ such that $\alpha(t, u) = (\phi(t), u)$ for $(t, u) \in T \ltimes U_\Gamma$. By the property (2) in Definition 3.2, ϕ is injective and hence α is injective.

In [1] Baues constructed a compact aspherical manifold $M_\Gamma = \alpha(\Gamma) \backslash U_\Gamma$ with $\pi_1(M_\Gamma) = \Gamma$. We call M_Γ a standard Γ -manifold.

Theorem 3.2 [1, Theorem 1.2, 1.4]. *A standard Γ -manifold is unique up to diffeomorphism. A solvmanifold with the fundamental group Γ is diffeomorphic to the standard Γ -manifold M_Γ .*

Let $A^*(M_\Gamma)$ be the de Rham complex of M_Γ . Then $A^*(M_\Gamma)$ is the set of the Γ -invariant differential forms $A^*(U_\Gamma)^\Gamma$ on U_Γ . Let $(\bigwedge \mathfrak{u}^*)^T$ be the left-invariant forms on U_Γ which are fixed by T . Since $\Gamma \subset H_\Gamma = T \ltimes U_\Gamma$, we have the inclusion

$$\left(\bigwedge \mathfrak{u}^*\right)^T = A^*(U_\Gamma)^{H_\Gamma} \subset A^*(U_\Gamma)^\Gamma = A^*(M_\Gamma).$$

Theorem 3.3 [1, Theorem 1.8]. *This inclusion induces an isomorphism on cohomology.*

By the application of the above facts, we prove the main theorem of this paper.

Theorem 3.4. *Suppose M_Γ is c -symplectic. Then M_Γ admits a symplectic structure. In particular, cohomologically symplectic solvmanifolds are symplectic.*

Proof. Since we have the isomorphism $H^*(M_\Gamma, \mathbb{R}) \cong H^*((\bigwedge \mathfrak{u}^*)^T)$, we have $\omega \in (\bigwedge^2 \mathfrak{u}^*)^T$ such that $0 \neq [\omega]^n \in H^{2n}((\bigwedge \mathfrak{u}^*)^T)$. This gives $0 \neq \omega^n \in (\bigwedge \mathfrak{u}^*)^T$ and hence $0 \neq \omega^n \in \bigwedge \mathfrak{u}^*$. Since ω^n is a non-zero invariant $2n$ -form on U_Γ , we have $(\omega^n)_p \neq 0$ for any $p \in U_\Gamma$. Hence by the inclusion $(\bigwedge \mathfrak{u}^*)^T \subset A^*(U_\Gamma)^T = A^*(M_\Gamma)$, we have $(\omega^n)_{\Gamma p} \neq 0$ for any $\Gamma p \in \Gamma \backslash U_\Gamma = M_\Gamma$. This implies that ω is a symplectic form on M_Γ . Hence, we have the theorem. \square

4. Remarks

Let $G = \mathbb{R} \ltimes_\phi U_3(\mathbb{C})$ such that

$$\phi(t) \cdot \begin{pmatrix} 1 & x & z \\ 0 & 1 & y \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & e^{i\pi t} \cdot x & z \\ 0 & 1 & e^{-i\pi t} \cdot y \\ 0 & 0 & 1 \end{pmatrix},$$

and $D = \mathbb{Z} \rtimes_{\phi} D'$ with

$$D' = \left\{ \begin{pmatrix} 1 & x_1 + ix_2 & z_1 + iz_2 \\ 0 & 1 & y_1 + iy_2 \\ 0 & 0 & 1 \end{pmatrix} : x_1, y_2, z_2 \in \mathbb{Z}, x_2, y_1, z_1 \in \mathbb{R} \right\}.$$

Then D is not discrete and G/D is compact. We have $D/D_0 \cong \mathbb{Z} \rtimes_{\varphi} U_3(\mathbb{Z})$ such that

$$\varphi(t) \cdot \begin{pmatrix} 1 & x & z \\ 0 & 1 & y \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & (-1)^t x & z \\ 0 & 1 & (-1)^{-t} y \\ 0 & 0 & 1 \end{pmatrix},$$

where D_0 is the identity component of D . Denote $\Gamma = D/D_0$. We have the algebraic hull $H_{\Gamma} = \{\pm 1\} \rtimes_{\psi} (U_3(\mathbb{R}) \times \mathbb{R})$ such that

$$\psi(-1) \cdot \left(\begin{pmatrix} 1 & x & z \\ 0 & 1 & y \\ 0 & 0 & 1 \end{pmatrix}, t \right) = \left(\begin{pmatrix} 1 & -x & z \\ 0 & 1 & -y \\ 0 & 0 & 1 \end{pmatrix}, t \right).$$

The dual of the Lie algebra \mathfrak{u} of $U_3(\mathbb{R}) \times \mathbb{R}$ is given by $\mathfrak{u}^* = \langle \alpha, \beta, \gamma, \delta \rangle$ such that the differential is given by

$$\begin{aligned} d\alpha &= d\beta = d\delta = 0, \\ d\gamma &= -\alpha \wedge \beta, \end{aligned}$$

and the action of $\{\pm 1\}$ is given by

$$\begin{aligned} (-1) \cdot \alpha &= -\alpha, (-1) \cdot \beta = -\beta, \\ (-1) \cdot \gamma &= \gamma, (-1) \cdot \delta = \delta. \end{aligned}$$

Then we have a diffeomorphism $M_{\Gamma} \cong G/D$ and an isomorphism $H^*(M_{\Gamma}, \mathbb{R}) \cong H^*((\bigwedge \mathfrak{u}^*)^{\{\pm 1\}})$. By simple computations, $H^2((\bigwedge \mathfrak{u}^*)^{\{\pm 1\}}) = 0$ and hence the solvmanifold G/D is not symplectic.

Remark 1. The proof of the Theorem 3.4 contains a proof of the following proposition.

Proposition 4.1. *If M_{Γ} admits a symplectic structure, then U_{Γ} has an invariant symplectic form.*

Otherwise for the above example, $U_{\Gamma} = U_3(\mathbb{R}) \times \mathbb{R}$ has an invariant symplectic form but M_{Γ} is not symplectic. Thus the converse of this proposition is not true. If Γ is nilpotent, then T is trivial and any invariant symplectic form on U_{Γ} induces the symplectic form on M_{Γ} . Hence for nilmanifolds, the converse of Proposition 4.1 is true.

Remark 2. Γ is a finite extension of a lattice of $U_{\Gamma} = U_3(\mathbb{R}) \times \mathbb{R}$. Hence M_{Γ} is finitely covered by a Kodaira–Thurston manifold (see [9], [3, p. 192]). M_{Γ} is an example of a non-symplectic manifold finitely covered by a symplectic manifold.

Let $H = G \times \mathbb{R}$. Then the dual of the Lie algebra \mathfrak{h} of H is given by $\mathfrak{h}^* = \langle \sigma, \tau, \zeta_1, \zeta_2, \eta_1, \eta_2, \theta_1, \theta_2 \rangle$ such that the differential is given by

$$\begin{aligned} d\sigma &= d\tau = 0, \\ d\zeta_1 &= \tau \wedge \zeta_2, \quad d\zeta_2 = -\tau \wedge \zeta_1, \\ d\eta_1 &= \tau \wedge \eta_2, \quad d\eta_2 = -\tau \wedge \eta_1, \\ d\theta_1 &= -\zeta_1 \wedge \eta_1 + \zeta_2 \wedge \eta_2, \quad d\theta_2 = -\zeta_1 \wedge \eta_2 - \zeta_2 \wedge \eta_1. \end{aligned}$$

By simple computations, any closed invariant 2-form $\omega \in \bigwedge^2 \mathfrak{h}^*$ satisfies $\omega^4 = 0$. Hence H has no invariant symplectic form. Otherwise we have a lattice $\Delta = 2\mathbb{Z} \times U_3(\mathbb{Z} + i\mathbb{Z}) \times \mathbb{Z}$ which is also a lattice of $\mathbb{R}^2 \times U_3(\mathbb{C})$. Thus H/Δ is diffeomorphic to a direct product of a two-dimensional torus and an Iwasawa manifold (see [4]). Since an Iwasawa manifold is symplectic (see [4]), H/Δ is also symplectic. By this example we can say:

Remark 3. For a simply connected nilpotent Lie group G with a lattice Γ , if the nilmanifold G/Γ is symplectic then G has an invariant symplectic form. But suppose G is solvable we have an example of a symplectic solvmanifold G/Γ such that G has no invariant symplectic form.

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