

On Three Theorems of Lees for Numerical Treatment of Semilinear Two-Point Boundary Value Problems

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Received December 20, 2005

Revised July 18, 2006

This paper is concerned with semilinear two-point boundary value problems of the form $-(p(x)u')' + f(x, u) = 0$, $a \leq x \leq b$, $\alpha_0 u(a) - \alpha_1 u'(a) = \alpha$, $\beta_0 u(b) + \beta_1 u'(b) = \beta$, $\alpha_i \geq 0$, $\beta_i \geq 0$, $i = 0, 1$, $\alpha_0 + \alpha_1 > 0$, $\beta_0 + \beta_1 > 0$, $\alpha_0 + \beta_0 > 0$. Under the assumption $\inf f_u > -\lambda_1$, where λ_1 is the smallest eigenvalue of $\mathcal{L}u = -(pu')'$ with the boundary conditions, unique existence theorems of solution for the continuous problem and a discretized system with not necessarily uniform nodes are given as well as error estimates. The results generalize three theorems of Lees for $u'' = f(x, u)$, $0 \leq x \leq 1$, $u(0) = \alpha$, $u(1) = \beta$.

Key words: two-point boundary value problems, discretization, existence of solution, error estimates, theorems of Lees

1. Introduction

We will be concerned with a mathematical theory for numerical treatment of semilinear boundary value problem

$$-\frac{d}{dx} \left(p(x) \frac{du}{dx} \right) + f(x, u) = 0, \quad a \leq x \leq b, \quad (1.1)$$

$$B_1(u) = \alpha_0 u(a) - \alpha_1 u'(a) = \alpha, \quad (1.2)$$

$$B_2(u) = \beta_0 u(b) + \beta_1 u'(b) = \beta, \quad (1.3)$$

where $p(x) \in C^1[a, b]$, $p(x) > 0$, $f(x, u) \in C([a, b] \times \mathbb{R})$ and α_i, β_i , $i = 0, 1$ are constants which satisfy

$$\alpha_0 \geq 0, \quad \alpha_1 \geq 0, \quad \alpha_0 + \alpha_1 > 0, \quad (1.4)$$

$$\beta_0 \geq 0, \quad \beta_1 \geq 0, \quad \beta_0 + \beta_1 > 0, \quad (1.5)$$

and

$$\alpha_0 + \beta_0 > 0. \quad (1.6)$$

Let $\mathcal{L}u = -(d/dx)(p(x)(du/dx))$ and put $\mathcal{D} = \{u \in C^2[a, b] \mid B_1(u) = B_2(u) = 0\}$. Then, as is easily verified, the Green function for $(\mathcal{L}, \mathcal{D})$ exists

under the conditions (1.4)–(1.6). It is known that if $f_u = \partial f / \partial u$ exists, is continuous on $[a, b] \times \mathbb{R}$ and $f_u \geq 0$, then the problem has a unique solution $u \in C^2[a, b]$ (cf. [8]; Remark 2.1). To find a numerical solution, we discretize (1.1)–(1.3) at not necessarily uniform nodes

$$\Delta: a = x_0 < x_1 < \dots < x_n < x_{n+1} = b, \tag{1.7}$$

and put

$$h_i = x_i - x_{i-1}, \quad h = \max_i h_i.$$

The discretized system we consider here is

$$HAU + \tilde{f}(U) = \mathbf{0} \tag{1.8}$$

where, if $\alpha_1\beta_1 \neq 0$, then

$$H = \begin{pmatrix} \omega_0^{-1} & & & & \\ & \omega_1^1 & & & \\ & & \ddots & & \\ & & & \ddots & \\ & & & & \omega_{n+1}^{-1} \end{pmatrix}, \quad \omega_i = \begin{cases} \frac{1}{2}h_1 & (i = 0) \\ \frac{1}{2}(h_i + h_{j+1}) & (1 \leq i \leq n) \\ \frac{1}{2}h_{n+1} & (i = n + 1), \end{cases}$$

$$A = \begin{pmatrix} a_0 + a_1 & -a_1 & & & \\ -a_1 & a_1 + a_2 & -a_2 & & \\ & \ddots & \ddots & \ddots & \\ & & & -a_{n+1} & a_{n+1} + a_{n+2} \end{pmatrix}$$

$$a_i = \begin{cases} \frac{\alpha_0}{\alpha_1}p(a) & (i = 0) \\ \left(\int_{x_{i-1}}^{x_i} \frac{dt}{p(t)} \right)^{-1} & (1 \leq i \leq n + 1) \\ \frac{\beta_0}{\beta_1}p(b) & (i = n + 2), \end{cases}$$

$$U = (U_0, U_1, \dots, U_{n+1})^t$$

$$f(U) = (f(x_0, U_0), \dots, f(x_{n+1}, U_{n+1}))^t$$

$$\tilde{f}(U) = f(U) - \left(\frac{2}{h_1} \cdot \frac{\alpha}{\alpha_1}p(a), 0, \dots, 0, \frac{2}{h_{n+1}} \cdot \frac{\beta}{\beta_1}p(b) \right)^t.$$

If $\alpha_1\beta_1 = 0$, then (1.2) or (1.3) reduces to the Dirichlet condition $u(a) = 0$ or $u(b) = 0$ so that a modification of (1.8) is necessary. Namely, if $\alpha_1 = 0$ and $\beta_1 \neq 0$,

then $\alpha_0 \neq 0$ and we replace $H, A, \mathbf{U}, \mathbf{f}$, and $\tilde{\mathbf{f}}$ by

$$\begin{aligned}
 H &= \text{diag}(\omega_1^{-1}, \omega_2^{-1}, \dots, \omega_{n+1}^{-1}), \\
 A &= \begin{pmatrix} a_1 + a_2 & -a_2 & & & \\ -a_2 & a_2 + a_3 & -a_3 & & \\ & \ddots & \ddots & \ddots & \\ & & & -a_{n+1} & a_{n+1} + a_{n+2} \end{pmatrix} \\
 \mathbf{U} &= (U_1, U_2, \dots, U_{n+1})^t, \\
 \mathbf{f}(\mathbf{U}) &= (f(x_1, U_1), f(x_2, U_2), \dots, f(x_{n+1}, U_{n+1}))^t
 \end{aligned} \tag{1.9}$$

and

$$\tilde{\mathbf{f}}(\mathbf{U}) = \mathbf{f}(\mathbf{U}) - \left(\frac{2}{h_1 + h_2} \frac{\alpha}{\alpha_0} a_1, 0, \dots, 0, \frac{2}{h_{n+1}} \cdot \frac{\beta}{\beta_1} p(b) \right)^t.$$

If $a_1 \neq 0$ and $\beta_1 = 0$, then $\beta_0 \neq 0$ and $H, A, \mathbf{U}, \mathbf{f}$ and $\tilde{\mathbf{f}}$ in (1.8) are replaced by

$$\begin{aligned}
 H &= \text{diag}(\omega_0^{-1}, \omega_1^{-1}, \dots, \omega_n^{-1}), \\
 A &= \begin{pmatrix} a_0 + a_1 & -a_1 & & & \\ -a_1 & a_1 + a_2 & -a_2 & & \\ & \ddots & \ddots & \ddots & \\ & & & -a_n & a_n + a_{n+1} \end{pmatrix}, \\
 \mathbf{U} &= (U_0, U_1, \dots, U_n)^t, \\
 \mathbf{f}(\mathbf{U}) &= (f_0(x_0, U_0), f(x_1, U_1), \dots, f(x_n, U_n))^t
 \end{aligned}$$

and

$$\tilde{\mathbf{f}}(\mathbf{U}) = \mathbf{f}(\mathbf{U}) - \left(\frac{2}{h_1} \frac{\alpha}{\alpha_1} p(a), 0, \dots, 0, \frac{2}{h_n + h_{n+1}} \frac{\beta}{\beta_0} a_{n+1} \right)^t.$$

Furthermore, if $\alpha_1 = \beta_1 = 0$, then $\alpha_0, \beta_0 \neq 0$ and $H, A, \mathbf{U}, \mathbf{f}$ and $\tilde{\mathbf{f}}$ are replaced by

$$\begin{aligned}
 H &= \text{diag}(\omega_1^{-1}, \omega_2^{-1}, \dots, \omega_n^{-1}), \\
 A &= \begin{pmatrix} a_1 + a_2 & -a_2 & & & \\ -a_2 & a_2 + a_3 & -a_3 & & \\ & \ddots & \ddots & \ddots & \\ & & & -a_n & a_n + a_{n+1} \end{pmatrix}, \\
 \mathbf{U} &= (U_1, \dots, U_n)^t, \\
 \mathbf{f}(\mathbf{U}) &= (f(x_1, U_1), \dots, f(x_n, U_n))^t
 \end{aligned}$$

and

$$\tilde{\mathbf{f}}(\mathbf{U}) = \mathbf{f}(\mathbf{U}) - \left(\frac{2}{h_1 + h_2} \frac{\alpha}{\alpha_0}, 0, \dots, 0, \frac{2}{h_n + h_{n+1}} \frac{\beta}{\beta_0} a_{n+1} \right)^t.$$

It should be remarked here that, in any case, we have $A^{-1} = (G(x_i, x_j))$ (cf. [8]), where $G(x, \xi)$ denotes the Green function for $(\mathcal{L}, \mathcal{D})$ with $\mathcal{L} = -(d/dx)(p(d/dx)[\])$.

Observe also that, if the nodes are uniform, i.e., $x_i = ih$, $h = (b - a)/(n + 1)$, $p(x) = 1$ and the boundary conditions are of Dirichlet's type $u(a) = \alpha$ and $u(b) = \beta$, then (1.8) reduces to a system of n equations

$$\frac{1}{h^2} \begin{pmatrix} 2 & -1 & & & \\ -1 & 2 & -1 & & \\ & \ddots & \ddots & \ddots & \\ & & & & -1 & 2 \end{pmatrix} \begin{pmatrix} U_1 \\ \vdots \\ U_n \end{pmatrix} + \begin{pmatrix} f(x_1, U_1) - \frac{\alpha}{h^2} \\ \vdots \\ f(x_n, U_n) - \frac{\beta}{h^2} \end{pmatrix} = \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix}. \tag{1.10}$$

In [4], M. Lees considered the problem

$$u'' = f(x, u), \quad x \in E = [0, 1], \tag{1.11}$$

$$u(0) = \alpha, \quad u(1) = \beta \tag{1.12}$$

and proved the following three theorems:

THEOREM 1.1. *If f_u exists, is continuous on $E \times \mathbb{R}$ and satisfies*

$$\inf_{E \times \mathbb{R}} f_u = -\eta > -\pi^2, \tag{1.13}$$

then the problem (1.11), (1.12) has a unique solution $u \in C^2[E]$.

THEOREM 1.2. *Assume that $u \in C^4[E]$. If f satisfies (1.13) and h is sufficiently small, i.e., if $h \leq h_0$, where h_0 is a constant satisfying*

$$\eta < \pi^2 \left[1 - \frac{h_0^2}{12} \pi^2 \right],$$

then (1.10) has a unique solution $\mathbf{U} = (U_1, \dots, U_n)^t \in \mathbb{R}^n$.

THEOREM 1.3. *Let*

$$\|\mathbf{U}\|_D = \sqrt{h \sum_{j=1}^{n+1} \left(\frac{U_j - U_{j-1}}{h} \right)^2},$$

where $U_0 = \alpha$ and $U_{n+1} = \beta$. Then, under the assumption of Theorem 1.2,

$$\|\mathbf{u} - \mathbf{U}\|_\infty \leq \frac{1}{2} \|\mathbf{u} - \mathbf{U}\|_D \leq \frac{1}{12} K(h_0) h^2 \|u^{(4)}\|_E,$$

where $\mathbf{u} = (u(x_1), \dots, u(x_n))^t$, $K(h_0)$ is a constant and

$$\|u^{(4)}\|_E = \max_{x \in E} |u^{(4)}(x)|.$$

The purpose of this paper is to generalize these result to the problem (1.1)–(1.6) and its discretized system (1.8).

2. Existence of Solution for (1.1)–(1.6)

Observing that the number π^2 in (1.13) is the smallest eigenvalue for the operator $-(d^2/dx^2): \{u \in C^2[0, 1] \mid u(0) = u(1) = 0\} \rightarrow C[0, 1]$, we generalize Theorem 1.1 on the basis of the following three lemmas.

LEMMA 2.1. *Let $\mathcal{L}u = -(d/dx)(p(du/dx))$ and $\mathcal{D} = \{u \in C^2[a, b] \mid B_1(u) = B_2(u) = 0\}$. We denote by λ_1 the smallest eigenvalue of $(\mathcal{L}, \mathcal{D})$. Then λ_1 is positive and*

$$(\mathcal{L}u, u) \geq \lambda_1 \|u\|^2 \quad \forall u \in \mathcal{D},$$

where $\|\cdot\|$ denote the L_2 norm.

Proof. The proof is straightforward since $(\mathcal{L}, \mathcal{D})$ has a complete system of orthonormal eigenfunctinos in $L_2[a, b]$. \square

LEMMA 2.2. *Let $r(x), g(x) \in C[a, b]$ and*

$$\min_{a \leq x \leq b} r(x) = -\eta > -\lambda_1, \tag{2.1}$$

where λ_1 is as defined by Lemma 2.1. Then the boundary value problem

$$\begin{aligned} \mathcal{L}u + r(x)u &= g(x), & a \leq x \leq b \\ u &\in \mathcal{D} \end{aligned}$$

has a unique solution and

$$\|u\| \leq \frac{\|g\|}{\lambda_1 - \eta}.$$

Proof. Let $\mathcal{L}u + r(x)u = 0, u \in \mathcal{D}$. Then

$$\begin{aligned} 0 &= (\mathcal{L}u, u) + (ru, u) \\ &\geq \lambda_1(u, u) + (ru, u) = ((\lambda_1 + r)u, u) \geq (\lambda_1 - \eta)(u, u). \end{aligned}$$

Since $\lambda_1 - \eta > 0$, we obtain $\|u\| = 0$. Hence, $(\mathcal{L} + rI, \mathcal{D})$, where I is the identity, is injective and the problem

$$\mathcal{L}u + ru = g, \quad u \in \mathcal{D} \tag{2.2}$$

has a unique solution. We then have

$$(\lambda_1 - \eta)\|u\|^2 \leq (\mathcal{L}u, u) + (ru, u) = (g, u) \leq \|g\| \cdot \|u\|. \tag{2.3}$$

If $\|u\| > 0$, then (2.3) implies

$$(\lambda_1 - \eta)\|u\| \leq \|g\|$$

or

$$\|u\| \leq \frac{\|g\|}{\lambda_1 - \eta}.$$

This inequality holds for $\|u\| = 0$, too. \square

LEMMA 2.3. *Let $G(x, \xi)$ be the Green function for $(\mathcal{L}, \mathcal{D})$, where \mathcal{L} and \mathcal{D} are defined in Lemma 2.1. Then*

$$\begin{aligned} &G(x, \xi) \\ &= \begin{cases} \frac{1}{p(a)p(b)\delta} \left(\alpha_1 + \alpha_0 p(a) \int_a^x \frac{dt}{p(t)} \right) \left(\beta_1 + \beta_0 p(b) \int_\xi^b \frac{dt}{p(t)} \right) & (x \leq \xi) \\ \frac{1}{p(a)p(b)\delta} \left(\alpha_1 + \alpha_0 p(a) \int_a^\xi \frac{dt}{p(t)} \right) \left(\beta_1 + \beta_0 p(b) \int_x^b \frac{dt}{p(t)} \right) & (x \geq \xi) \end{cases} \\ &\leq G(x, x) \end{aligned}$$

where

$$\delta = \alpha_0 \left(\beta_0 \int_a^b \frac{dt}{p(t)} + \frac{\beta_1}{p(b)} \right) + \frac{\alpha_1 \beta_0}{p(a)} > 0. \tag{2.4}$$

Proof. See [8]. \square

We are now in a position to prove the following:

THEOREM 2.1. *If $f(x, u)$ satisfies*

$$\inf_{[a,b] \times \mathbb{R}} f_u(x, u) = -\eta > -\lambda_1, \tag{2.5}$$

where λ_1 is defined in Lemma 2.1, then the problem (1.1)–(1.6) has a unique solution $u \in C^2[a, b]$.

Proof. Without loss of generality, we may assume $\alpha = \beta = 0$ (cf. [8]).

(i) EXISTENCE. Putting

$$r(x; u) = \int_0^1 f_u(x; \theta u) d\theta,$$

we have

$$f(x, u) = f_0(x) + r(x; u)u,$$

where $f_0(x) = f(x, 0)$. Then, by Lemma 2.2, given $u \in C[a, b]$, the linear boundary value problem

$$\mathcal{L}w + r(x; u)w = -f_0(x), \quad w \in \mathcal{D} \tag{2.6}$$

has a unique solution $w \in C^2[a, b]$, which satisfies

$$\|w\| \leq \frac{\|f_0\|}{\lambda_1 - \eta} \equiv \delta_0 \quad (\text{say}) \tag{2.7}$$

by Lemma 2.2. Furthermore, we have from (2.6)

$$\mathcal{L}w = -f_0(x) - r(x; u)w$$

and

$$w(x) = - \int_a^b G(x, \xi) \{f_0(\xi) + r(\xi; u(\xi))w(\xi)\} d\xi$$

so that, using Lemma 2.3, we obtain

$$\begin{aligned} \frac{dw(x)}{dx} &= - \int_a^x \frac{\partial G(x, \xi)}{\partial x} \{f_0(\xi) + r(\xi; u(\xi))w(\xi)\} d\xi \\ &\quad - \int_x^b \frac{\partial G(x, \xi)}{\partial x} \{f_0(\xi) + r(\xi; u(\xi))w(\xi)\} d\xi \\ &= - \int_a^x \frac{1}{\delta} \left(-\frac{\beta_0}{p(x)} \right) \left(\frac{\alpha}{p(a)} + \alpha_0 \int_a^\xi \frac{dt}{p(t)} \right) \{f_0(\xi) + r(\xi; u(\xi))w(\xi)\} d\xi \\ &\quad - \int_x^b \frac{1}{\delta} \left(\frac{\alpha_0}{p(x)} \right) \left(\frac{\beta_1}{p(b)} + \beta_0 \int_\xi^b \frac{dt}{p(t)} \right) \{f_0(\xi) + r(\xi; u(\xi))w(\xi)\} d\xi, \end{aligned}$$

where δ is as defined in (2.4).

Observing that

$$\delta = \beta_0 \left(\frac{\alpha_1}{p(a)} + \alpha_0 \int_a^b \frac{dt}{p(t)} \right) + \frac{\alpha_0 \beta_1}{p(b)} \geq \beta_0 \left(\frac{\alpha_1}{p(a)} + \alpha_0 \int_a^\xi \frac{dt}{p(t)} \right)$$

and similiary

$$\delta \geq \alpha_0 \left(\frac{\beta_1}{p(b)} + \beta_0 \int_\xi^b \frac{dt}{p(t)} \right),$$

we have

$$\begin{aligned} \left| \frac{dw(x)}{dx} \right| &\leq \int_a^x \frac{1}{p(x)} (|f_0(\xi)| + |r(\xi; u(\xi))| \cdot |w(\xi)|) d\xi \\ &\quad + \int_x^b \frac{1}{p(x)} (|f_0(\xi)| + |r(\xi; u(\xi))| \cdot |w(\xi)|) d\xi \\ &= \int_a^b \frac{1}{p(x)} (|f_0(\xi)| + |r(\xi; u(\xi))| \cdot |w(\xi)|) d\xi \\ &\leq \frac{1}{p_*} \int_a^b (\|f_0\|_{[a,b]} + |r(\xi; u(\xi))| \cdot \|w\|_{[a,b]}) d\xi, \end{aligned}$$

where $p_* = \min_{a \leq x \leq b} p(x) > 0$ and $\|\cdot\|_{[a,b]}$ denotes the maximum norm in $[a, b]$:

$$\|f_0\|_{[a,b]} = \max_{x \in [a,b]} |f_0(x)|, \quad \|w\|_{[a,b]} = \max_{x \in [a,b]} |w(x)|, \quad \text{etc.}$$

Hence, if $u \in C^2[a, b]$ and $\|u\|_{[a,b]} \leq \delta_0$, then, putting

$$\tilde{K} = \sup_{[a,b] \times [-\delta_0, \delta_0]} |f_u(x, u)|$$

we have

$$\begin{aligned} \|w'\|_{[a,b]} &\leq \frac{1}{p_*} \int_a^b (\|f_0\|_{[a,b]} + \tilde{K}\delta_0) d\xi \\ &= \frac{1}{p_*} (\|f_0\|_{[a,b]} + \tilde{K}\delta_0) (b - a) \equiv \delta_1 \quad (\text{say}). \end{aligned}$$

Consider a Banach space $X = C^1[a, b]$ equipped with the norm $\|u\|_{C^1} = \|u\|_{[a,b]} + \|u'\|_{[a,b]}$ for $u \in X$ and put

$$S = \{u \in X \mid \|u\|_{[a,b]} \leq \delta_0, \|u'\|_{[a,b]} \leq \delta_1, B_1(u) = B_2(u) = 0\}.$$

Then S is a bounded and closed convex set in X . The map $T: S \rightarrow S \cap C^2[a, b] \subset S$ defined by $Tu = w, u \in S$, is then continuous and it can be shown by Ascoli-Arzelà's theorem that $T(S)$ is relatively compact in X (cf. [8]). Hence, Schauder's theorem implies that T has a fixed point $u \in S$. It is clear that $u = Tu$ is a solution of (1.1)–(1.6).

(ii) UNIQUENESS. Let u and v be two solutions of the problem and set $\varphi = u - v$. Then

$$f(x, u) - f(x, v) = r(x; u, v)\varphi$$

where

$$r(x; u, v) = \int_0^1 f_u(x, v + \theta(u - v)) d\theta.$$

Therefore

$$\begin{aligned} \mathcal{L}\varphi + r(x; u, v)\varphi &= 0, \quad a \leq x \leq b \\ \varphi &\in \mathcal{D}, \end{aligned}$$

where

$$r(x; u, v) \geq -\eta > -\lambda_1.$$

Hence Lemma 2.2 applies to conclude that $\varphi \equiv 0$. □

REMARK 2.1. If $\alpha_1\beta_1 \neq 0$ and $\alpha = \beta = 0$, then the existence of solution for the problem (1.1)–(1.6) follows from the following result which is the one-dimensional version of Theorem 2.3.1 in Sattinger [5]. (Also see Amann [1], [2])

THEOREM 2.2. Let $\varphi(x)$ and $\psi(x)$ be upper and lower solutions for the problem (1.1)–(1.6) with $\alpha = \beta = 0$:

$$\begin{aligned} \mathcal{L}\varphi + f(x, \varphi) &\geq 0 \quad (a \leq x \leq b), & B_1(\varphi) &\geq 0, & B_2(\varphi) &\geq 0 \\ \mathcal{L}\psi + f(x, \psi) &\leq 0 \quad (a \leq x \leq b), & B_1(\psi) &\leq 0, & B_2(\psi) &\leq 0, \end{aligned}$$

where \mathcal{L} is as defined in Lemma 2.1. If $\psi \leq \varphi$ in $[a, b]$, then there exists a solution u for (1.1)–(1.6) with $\psi \leq u \leq \varphi$.

In fact, if we put $F(x, u) = f(x, u) + \lambda_1 u$ where λ_1 is defined in Lemma 2.1, then

$$F_u(x, u) = f_u(x, u) + \lambda_1 \geq \lambda_1 - \eta > 0.$$

Hence, at each x fixed, F is monotonically increasing in u and $F(x, -\infty) = -\infty$, $F(x, +\infty) = +\infty$, $x \in [a, b]$, so that, by the implicit function theorem, there exists a unique $\Phi(x) \in C[a, b]$ satisfying $F(x, \Phi(x)) = 0$. Take a positive constant m with $-m \leq \Phi(x) \leq m \forall x \in [a, b]$ and an eigenfunction $v(x)$ corresponding to the eigenvalue λ_1 for $(\mathcal{L}, \mathcal{D})$. Then $v(x) > 0$ in $[a, b]$ since $\alpha_1 \beta_1 \neq 0$.

Furthermore, letting

$$\gamma = \min_{a \leq x \leq b} v(x) > 0,$$

we have

$$-\frac{m}{\gamma}v(x) \leq -m \leq \Phi(x) \leq m \leq \frac{m}{\gamma}v(x) \quad \forall x \in [a, b]$$

and it can be shown that $\varphi(x) = (m/\gamma)v(x)$ and $\psi(x) = -(m/\gamma)v(x)$ are upper and lower solutions with $\psi(x) \leq \varphi(x)$ in $[a, b]$.

In fact, we have

$$\begin{aligned} \mathcal{L}\varphi + f(x, \varphi) &= \mathcal{L}\varphi - \lambda_1\varphi + F(x, \varphi) \\ &= F(x, \varphi) \\ &\geq F(x, \Phi(x)) = 0 \end{aligned}$$

and

$$B_1(\varphi) = B_2(\varphi) = 0.$$

Similarly

$$\mathcal{L}\psi + f(x, \psi) = F(x, \psi) \leq F(x, \Phi(x)) = 0$$

and

$$B_1(\psi) = B_2(\psi) = 0.$$

Hence, by Theorem 2.2, the problem (1.1)–(1.6) has a solution u with $\psi \leq u \leq \varphi$.

3. Existence of Solution for the Discretized System

In this section, we shall show that (1.8) has a unique solution $\mathbf{U} \in \mathbb{R}^{n+2}$ for sufficiently small h . Before doing this, we prepare several lemmas. In the following, we assume $\alpha_1 \beta_1 \neq 0$ without loss of generality.

LEMMA 3.1. *Let $\widehat{U}(x)$ be the piecewise linear interpolant for the $n+2$ points (x_i, U_i) , $i = 0, 1, 2, \dots, n+1$. Then*

$$\frac{1}{3} (\mathbf{U}, H^{-1}\mathbf{U}) \leq \|\widehat{U}\|^2 \leq (\mathbf{U}, H^{-1}\mathbf{U}).$$

Proof. The trapezoidal rule for numerical integration implies that if $\varphi \in C^2[x_{j-1}, x_j]$, $1 \leq j \leq n+1$, then there exists $\xi_j \in (x_{j-1}, x_j)$ for each j such that

$$\int_{x_{j-1}}^{x_j} \varphi(x) dx = \frac{h_j}{2} (\varphi(x_j) + \varphi(x_{j-1})) - \frac{h_j^3}{12} \varphi''(\xi_j).$$

Hence

$$\begin{aligned} \int_a^b \varphi(x) dx &= \sum_{j=1}^{n+1} \frac{h_j}{2} (\varphi(x_j) + \varphi(x_{j-1})) - \frac{1}{12} \sum_{j=1}^{n+1} h_j^3 \varphi''(\xi_j) \\ &= \sum_{j=0}^{n+1} \omega_j \varphi(x_j) - \frac{1}{12} \sum_{j=1}^{n+1} h_j^3 \varphi''(\xi_j), \end{aligned}$$

or

$$\sum_{j=0}^{n+1} \omega_j \varphi(x_j) = \int_a^b \varphi(x) dx + \frac{1}{12} \sum_{j=1}^{n+1} h_j^3 \varphi''(\xi_j).$$

An application of this formula to $\varphi(x) = \{\widehat{U}(x)\}^2$ yields

$$\begin{aligned} (\mathbf{U}, H^{-1}\mathbf{U}) &= \sum_{j=0}^{n+1} \omega_j U_j^2 = \sum_{j=0}^{n+1} \omega_j \{\widehat{U}(x_j)\}^2 \\ &= \int_a^b \widehat{U}(x)^2 dx + \frac{1}{6} \sum_{j=1}^{n+1} h_j^3 \left(\frac{U_j - U_{j-1}}{h_j} \right)^2 \\ &= \|\widehat{U}\|^2 + \frac{1}{6} \sum_{j=1}^{n+1} h_j (U_j - U_{j-1})^2 \\ &\geq \|\widehat{U}\|^2, \end{aligned}$$

where we have used the fact that

$$\widehat{U}(x) = \frac{U_j - U_{j-1}}{h_j} (x - x_{j-1}) + U_{j-1}, \quad x \in [x_{j-1}, x_j]$$

and

$$\frac{d^2}{dx^2} \{\widehat{U}(x)^2\} = \frac{2(U_j - U_{j-1})^2}{h_j^2} \quad (\text{constant}), \quad x \in [x_{j-1}, x_j].$$

On the other hand

$$\begin{aligned}
 \int_a^b \widehat{U}(x)^2 dx &= \sum_{j=1}^{n+1} \int_{x_{j-1}}^{x_j} \left\{ \frac{U_j - U_{j-1}}{h_j} (x - x_{j-1}) + U_{j-1} \right\}^2 dx \\
 &= \sum_{j=1}^{n+1} \left\{ (U_j - U_{j-1})^2 \frac{h_j}{3} + 2(U_j - U_{j-1})U_{j-1} \frac{h_j}{2} + U_{j-1}^2 h_j \right\} \\
 &= \frac{1}{3} \sum_{j=1}^{n+1} h_j (U_j^2 + U_j U_{j-1} + U_{j-1}^2) \\
 &\geq \frac{1}{3} \sum_{j=1}^{n+1} \frac{h_j}{2} (U_j^2 + U_{j-1}^2) \\
 &= \frac{1}{3} \sum_{j=0}^{n+1} \omega_j U_j^2 = \frac{1}{3} (\mathbf{U}, H^{-1} \mathbf{U}).
 \end{aligned}$$

This proves Lemma 3.1. \square

LEMMA 3.2. *The following inequalities hold.*

- (i) $\sum_{j=1}^{n+1} h_j |U_j - U_{j-1}|^2 \leq 4(\mathbf{U}, H^{-1} \mathbf{U})$
- (ii) $\sum_{j=1}^{n+1} h_j |U_j - U_{j-1}| \leq 2\sqrt{b-a} \sqrt{(\mathbf{U}, H^{-1} \mathbf{U})}$
- (iii) $\sum_{j=1}^{n+1} h_j |U_{j-1}|^2 \leq 2(\mathbf{U}, H^{-1} \mathbf{U})$
- (iv) $\sum_{j=1}^{n+1} h_j |U_{j-1}| \leq \sqrt{2(b-a)} \sqrt{(\mathbf{U}, H^{-1} \mathbf{U})}$
- (v) $\sum_{j=1}^{n+1} h_j \max(|U_{j-1}|^2, |U_j|^2) \leq 2(\mathbf{U}, H^{-1} \mathbf{U})$
- (vi) $\sum_{j=1}^{n+1} h_j \max(|U_{j-1}|, |U_j|) \leq 2\sqrt{b-a} \sqrt{(\mathbf{U}, H^{-1} \mathbf{U})}$

Proof. For examples, we have

$$\begin{aligned}
 \sum_{j=1}^{n+1} h_j |U_j - U_{j-1}|^2 &\leq 2 \sum_{j=1}^{n+1} h_j (U_j^2 + U_{j-1}^2) = 4(\mathbf{U}, H^{-1} \mathbf{U}), \\
 \sum_{j=1}^{n+1} h_j |U_j - U_{j-1}| &\leq \sqrt{\sum_{j=1}^{n+1} (\sqrt{h_j})^2 \sum_{J=1}^{n+1} (\sqrt{h_j})^2 |U_j - U_{j-1}|^2} \\
 &\leq \sqrt{(b-a) \cdot 4(\mathbf{U}, H^{-1} \mathbf{U})} \\
 &= 2\sqrt{b-a} \sqrt{(\mathbf{U}, H^{-1} \mathbf{U})}, \quad \text{etc.} \quad \square
 \end{aligned}$$

LEMMA 3.3. $\int_a^b |\widehat{U}(x)| dx \leq (1 + \sqrt{2})\sqrt{b-a} \sqrt{(\mathbf{U}, H^{-1} \mathbf{U})}$.

Proof. We have from Lemma 3.2

$$\begin{aligned}
 \int_a^b |\widehat{U}(x)| dx &= \sum_{i=1}^{n+1} \int_{x_{i-1}}^{x_i} |\widehat{U}(x)| dx \\
 &\leq \sum_{i=1}^{n+1} \int_{x_{i-1}}^{x_i} \left\{ \frac{|U_i - U_{i-1}|}{h_i} (x - x_{i-1}) + |U_{i-1}| \right\} dx
 \end{aligned}$$

$$\begin{aligned} &\leq \sum_{i=1}^{n+1} \left(\frac{|U_i - U_{i-1}|}{2} + |U_{i-1}| \right) h_i \\ &\leq (1 + \sqrt{2})\sqrt{b-a}\sqrt{(U, H^{-1}U)}. \end{aligned} \quad \square$$

Since the Green function $G(x, \xi)$ belongs to C^2 class in the regions $\Omega_1 = \{(x, \xi) \mid a \leq x \leq \xi \leq b\}$ and $\Omega_2 = \{(x, \xi) \mid a \leq \xi \leq x \leq b\}$, there exists a constant $M > 0$ such that

$$\left| \frac{\partial^k G(x, \xi)}{\partial x^k} \right| \leq M \quad (0 \leq k \leq 2)$$

in Ω_1 or Ω_2 .

LEMMA 3.4. *Let $(U, H^{-1}U) = 1$. Then*

$$\sum_{j=0}^{n+1} G(x_i, x_j)\omega_j U_j = \int_a^b G(x_i, \xi)\widehat{U}(\xi) d\xi + \varepsilon_i, \quad 0 \leq i \leq n+1,$$

where

$$|\varepsilon_i| \leq \varepsilon \equiv \frac{Mh}{6}(2+h)\sqrt{b-a} = O(h).$$

Proof. Let $\widehat{U}(x)$ be as defined in Lemma 3.1 and put

$$\varphi_i(\xi) = G(x_i, \xi)\widehat{U}(\xi).$$

Then

$$\begin{aligned} \int_a^b G(x_i, \xi)\widehat{U}(\xi) d\xi &= \sum_{j=1}^{n+1} \int_{x_{j-1}}^{x_j} G(x_i, \xi)\widehat{U}(\xi) d\xi \\ &= \sum_{j=1}^{n+1} \left[\frac{h_j}{2} \{ \varphi_i(x_{j-1}) + \varphi_i(x_j) \} - \frac{h_j^3}{12} \varphi_i''(\xi_j) \right] \\ &\hspace{25em} (x_{j-1} \leq \xi_j \leq x_j) \\ &= \sum_{j=0}^{n+1} \omega_j \varphi_i(x_j) - \varepsilon_i, \end{aligned}$$

where $\varepsilon_i = (1/12) \sum_{j=1}^{n+1} h_j^3 \varphi_i''(\xi_j)$.

If $x_{j-1} < \xi < x_j$, then

$$\varphi''(\xi) = \frac{\partial^2 G(x_i, \xi)}{\partial \xi^2} \widehat{U}(\xi) + 2 \frac{\partial G(x_i, \xi)}{\partial \xi} \widehat{U}'(\xi)$$

and

$$\begin{aligned} |\varphi''(\xi)| &\leq M|\widehat{U}(\xi)| + 2M \frac{|U_j - U_{j-1}|}{h_j} \\ &\leq M \max(|U_{j-1}|, |U_j|) + 2M \frac{|U_j - U_{j-1}|}{h_j}. \end{aligned}$$

Hence we have

$$\frac{h_j^3}{12} |\varphi''(\xi_j)| \leq \frac{M}{12} h_j^3 \max(|U_{j-1}|, |U_j|) + \frac{M}{6} h_j^2 |U_j - U_{j-1}|$$

and, by Lemma 3.2,

$$\begin{aligned} |\varepsilon_i| &\leq \frac{1}{12} \sum_{j=1}^{n+1} h_j^3 |\varphi''(\xi_j)| \\ &\leq \frac{M}{12} \sum_{j=1}^{n+1} h_j^3 \max(|U_{j-1}|, |U_j|) + \frac{1}{6} \sum_{j=1}^{n+1} h_j^2 |U_j - U_{j-1}| \\ &\leq \frac{Mh^2}{12} \sum_{j=1}^{n+1} h_j \max(|U_{j-1}|, |U_j|) + \frac{Mh}{6} \sum_{j=1}^{n+1} h_j |U_j - U_{j-1}| \\ &\leq \frac{Mh^2}{6} \sqrt{b-a} \sqrt{(\mathbf{U}, H^{-1}\mathbf{U})} + \frac{Mh}{6} 2\sqrt{b-a} \sqrt{(\mathbf{U}, H^{-1}\mathbf{U})} \\ &= \frac{Mh}{6} (h+2) \sqrt{b-a} \sqrt{(\mathbf{U}, H^{-1}\mathbf{U})} \\ &= \frac{Mh}{6} (h+2) \sqrt{b-a} = \varepsilon. \end{aligned} \quad \square$$

LEMMA 3.5. Let $(\mathbf{U}, H^{-1}\mathbf{U}) = 1$. Then

$$\begin{aligned} &\int_a^b \int_a^b G(x, \xi) \widehat{U}(\xi) d\xi \widehat{U}(x) dx \\ &= \sum_{i=0}^{n+1} \sum_{j=0}^{n+1} G(x_i, x_j) (\omega_i U_i) (\omega_j U_j) + O(h). \end{aligned}$$

Proof. Let

$$\psi(x) = \int_a^b G(x, \xi) \widehat{U}(\xi) d\xi \widehat{U}(x).$$

Then

$$\begin{aligned} &\int_a^b \int_a^b G(x, \xi) \widehat{U}(\xi) d\xi \widehat{U}(x) dx \\ &= \sum_{i=1}^{n+1} \int_{x_{i-1}}^{x_i} \psi(x) dx \\ &= \sum_{i=1}^{n+1} \left\{ \frac{h_i}{2} [\psi(x_{i-1}) + \psi(x_i)] - \frac{h_i^3}{12} \psi''(\eta_i) \right\}, \quad x_{i-1} < \eta_i < x_i. \end{aligned} \tag{3.1}$$

If $x_{i-1} < x < x_i$, then

$$\begin{aligned} \psi''(x) &= \left(\int_a^b \frac{\partial^2 G(x, \xi)}{\partial x^2} \widehat{U}(\xi) d\xi - \frac{\widehat{U}(x)}{p(x)} \right) \widehat{U}(x) \\ &\quad + 2 \int_a^b \frac{\partial G(x, \xi)}{\partial x} \widehat{U}(\xi) d\xi \cdot \widehat{U}'(x), \end{aligned}$$

and

$$\begin{aligned} |\psi''(x)| &\leq \left(M \int_a^b |\widehat{U}(\xi)| d\xi + \frac{1}{p_*} \max(|U_{i-1}|, |U_i|) \right) \max(|U_{i-1}|, |U_i|) \\ &\quad + 2M \int_a^b |\widehat{U}(\xi)| d\xi \cdot \frac{|U_i - U_{i-1}|}{h_i}. \end{aligned}$$

Therefore,

$$\begin{aligned} &\frac{1}{12} \sum_{i=1}^{n+1} h_i^3 |\varphi''(\eta_i)| \\ &\leq \left(\frac{M}{12} \int_a^b |\widehat{U}(\xi)| d\xi \right) \sum_{i=1}^{n+1} h_i^3 \max(|U_{i-1}|, |U_i|) \\ &\quad + \frac{1}{12p_*} \sum_{i=1}^{n+1} h_i^3 \max(|U_{i-1}|^2, |U_i|^2) \\ &\quad + \frac{M}{6} \int_a^b |\widehat{U}(\xi)| d\xi \sum_{i=1}^{n+1} h_i^2 |U_i - U_{i-1}| \\ &\leq \frac{M}{6} \sqrt{b-a} h^2 \int_a^b |\widehat{U}(\xi)| d\xi + \frac{h^2}{6p_*} \\ &\quad + \frac{Mh}{3} \sqrt{b-a} \int_a^b |\widehat{U}(\xi)| d\xi \\ &\leq \frac{M}{6} (1 + \sqrt{2})(b-a)h^2 + \frac{h^2}{6p_*} + \frac{M}{3} (1 + \sqrt{2})(b-a)h \\ &= \tilde{\varepsilon} \quad (\text{say}). \end{aligned} \tag{3.2}$$

By Lemma 3.4, we have

$$\psi(x_i) = \left(\sum_{j=0}^{n+1} G(x_i, x_j) \omega_j U_j - \varepsilon_i \right) U_i.$$

We obtain from (3.1) that

$$\int_a^b \int_a^b G(x, \xi) \widehat{U}(\xi) d\xi \widehat{U}(x) dx$$

$$\begin{aligned}
 &= \sum_{i=1}^{n+1} \frac{h_i}{2} [\psi(x_{i-1}) + \psi(x_i)] - \frac{1}{12} \sum_{i=1}^{n+1} h_i^3 \psi''(\eta_i) \\
 &= \sum_{i=0}^{n+1} \psi(x_i) \omega_i - \frac{1}{12} \sum_{i=1}^{n+1} h_i^3 \psi''(\eta_i) \\
 &= \sum_{i=0}^{n+1} \left(\sum_{j=0}^{n+1} G(x_i, x_j) \omega_j U_j - \varepsilon_i \right) U_i \omega_i - \frac{1}{12} \sum_{i=1}^{n+1} h_i^3 \psi''(\eta_i) \\
 &= \sum_{i=0}^{n+1} \sum_{j=0}^{n+1} G(x_i, x_j) (\omega_j U_j) (\omega_i U_i) + \sigma,
 \end{aligned}$$

where

$$\sigma = - \sum_{i=0}^{n+1} \varepsilon_i (U_i \omega_i) - \frac{1}{12} \sum_{i=1}^{n+1} h_i^3 \psi''(\eta_i).$$

We thus obtain from Lemma 3.4 and (3.2)

$$\begin{aligned}
 |\sigma| &\leq \sum_{i=0}^{n+1} |\varepsilon_i| \cdot |U_i| \omega_i + \tilde{\varepsilon} \\
 &\leq \varepsilon \sum_{i=0}^{n+1} \omega_i |U_i| + \tilde{\varepsilon} \\
 &= \varepsilon \sum_{i=1}^{n+1} \frac{h_i}{2} (|U_i| + |U_{i-1}|) + \tilde{\varepsilon} \\
 &\leq \varepsilon \sqrt{b-a} (\mathbf{U}^{-1}, H^{-1} \mathbf{U}) + \tilde{\varepsilon} \\
 &= \varepsilon \sqrt{b-a} + \tilde{\varepsilon} \\
 &= O(h) \sqrt{b-a} + O(h) = O(h). \quad \square
 \end{aligned}$$

LEMMA 3.6. *For sufficiently small h , the matrix $HA - \eta I$ is an M -matrix, hence nonsingular.*

Proof. Since A is an irreducibly diagonally dominant L -matrix and symmetric, A is a positive definite M -matrix. Then, for any $\mathbf{U}, \mathbf{V} \in \mathbb{R}^{n+2}$, we have

$$\begin{aligned}
 (\mathbf{U}, \mathbf{V})^2 &= \left(\sqrt{A} \mathbf{U}, \sqrt{A}^{-1} \mathbf{V} \right)^2 \\
 &\leq (\sqrt{A} \mathbf{U}, \sqrt{A} \mathbf{U}) \left(\sqrt{A}^{-1} \mathbf{V}, \sqrt{A}^{-1} \mathbf{V} \right) \\
 &= (A \mathbf{U}, \mathbf{U}) (A^{-1} \mathbf{V}, \mathbf{V}). \tag{3.3}
 \end{aligned}$$

Let $\mathbf{W} \in \mathbb{R}^{n+2}$ and $\mathbf{W} \neq \mathbf{0}$. Then $c = (\mathbf{W}, H^{-1} \mathbf{W}) > 0$. We put $\mathbf{U} = (1/\sqrt{c}) \mathbf{W}$. Then we have $(\mathbf{U}, H^{-1} \mathbf{U}) = 1$.

We then have from (3.3), Lemma 3.1 and Lemma 3.5

$$\begin{aligned}
 ((A - \eta H^{-1})\mathbf{U}, \mathbf{U}) &= (A\mathbf{U}, \mathbf{U}) - \eta(\mathbf{U}, H^{-1}\mathbf{U}) \\
 &\geq \frac{(\mathbf{U}, H^{-1}\mathbf{U})^2}{(A^{-1}H^{-1}\mathbf{U}, H^{-1}\mathbf{U})} - \eta(\mathbf{U}, H^{-1}\mathbf{U}) \\
 &\hspace{20em} (\text{Put } \mathbf{V} = H^{-1}\mathbf{U} \text{ in (3.3)}) \\
 &= \left[\frac{(\mathbf{U}, H^{-1}\mathbf{U})}{\sum_{i=0}^{n+1} \sum_{j=0}^{n+1} G(x_i, x_j)(\omega_i U_i)(\omega_j U_j)} - \eta \right] (\mathbf{U}, H^{-1}\mathbf{U}) \\
 &\geq \frac{\|\widehat{U}\|^2}{\int_a^b \int_a^b G(x, \xi) \widehat{U}(\xi) d\xi \widehat{U}(x) dx + O(h)} - \eta \\
 &\geq \frac{\|\widehat{U}\|^2}{(1/\lambda_1)\|\widehat{U}\|^2 + O(h)} - \eta \\
 &= (\lambda_1 - \eta) + \frac{O(h)}{\|\widehat{U}\|^2}.
 \end{aligned}$$

By Lemma 3.1, we have $\|\widehat{U}\| = O(1)$ and

$$\lambda_1 - \eta + \frac{O(h)}{\|\widehat{U}\|^2} > 0$$

for sufficiently small $h > 0$ and $((A - \eta H^{-1})\mathbf{W}, \mathbf{W}) > 0$ for any $\mathbf{W} \neq \mathbf{0}$. Consequently the symmetric matrix $B = A - \eta H^{-1}$ is then positive definite and eigenvalues are all positive. Since B is a Z -matrix, this means that B as well as $HB = HA - \eta I$ is an M -matrix (cf. [7]). \square

We are now in a position to prove the following:

THEOREM 3.1. *Under the assumption of Theorem 2.1, the discretized system (1.8) has a unique solution if h is sufficiently small.*

Proof. We again assume $\alpha = \beta = 0$, without loss of generality.

(i) **UNIQUENESS.** Let $\mathbf{U}, \mathbf{V} \in \mathbb{R}^{n+2}$ be two solutions of (1.8) and put $\mathbf{W} = \mathbf{U} - \mathbf{V} = (W_0, W_1, \dots, W_{n+1})^t$. Then \mathbf{W} satisfies the system of $(n + 2)$ equations

$$(HA + D)\mathbf{W} = \mathbf{0},$$

where

$$D = \text{diag}(d_0, d_1, \dots, d_{n+1}), \tag{3.4}$$

with

$$d_i = \int_0^1 f_u(x_i, V_i + \theta(U_i - V_i)) d\theta, \quad 0 \leq i \leq n + 1.$$

By Lemma 3.6, we have for sufficiently small h

$$((A + H^{-1}D)\mathbf{U}, \mathbf{U}) \geq ((A - \eta H^{-1})\mathbf{U}, \mathbf{U}) > 0 \quad \forall \mathbf{U} (\neq \mathbf{0}) \in \mathbb{R}^{n+2},$$

and $HA + D$ is nonsingular. We thus obtain $\mathbf{W} = \mathbf{0}$, which means the uniqueness of the solution.

(ii) EXISTENCE. We write (1.8) as

$$HA\mathbf{U} + Z\mathbf{U} = -\tilde{\mathbf{f}}(\mathbf{0}),$$

where

$$Z = Z(\mathbf{U}) = \text{diag}(\zeta_0, \zeta_1, \dots, \zeta_{n+1}) \tag{3.5}$$

with

$$\zeta_i = \int_0^1 f_u(x_i, \theta U_i) d\theta, \quad 0 \leq i \leq n + 1,$$

and

$$\begin{aligned} \tilde{\mathbf{f}}(\mathbf{0}) &= (f(x_0, 0), f(x_1, 0), \dots, f(x_{n+1}, 0))^t \\ &= (f_0(x_0), f_0(x_1), \dots, f_0(x_{n+1}))^t \end{aligned}$$

with $f_0(x) = f(x, 0)$.

Since $Z \geq -\eta I$ (I is the $(n+2) \times (n+2)$ identity), given $\mathbf{U} \in \mathbb{R}^{n+2}$, the system of linear equations

$$(HA + Z)\mathbf{W} = -\tilde{\mathbf{f}}(\mathbf{0})$$

has a unique solution

$$\begin{aligned} \mathbf{W} &= -(HA + Z)^{-1}\tilde{\mathbf{f}}(\mathbf{0}) \\ &= -(A + H^{-1}Z)^{-1}H^{-1}\tilde{\mathbf{f}}(\mathbf{0}), \end{aligned} \tag{3.6}$$

where $A + H^{-1}Z$ is again a symmetric M -matrix. Let $\varphi \in C^2[a, b]$ be the unique solution of the problem

$$-\frac{d}{dx} \left(p(x) \frac{du}{dx} \right) - \eta u = 2, \quad u \in \mathcal{D},$$

whose existence is guaranteed by Theorem 2.1. Let

$$\boldsymbol{\tau} = (HA - \eta I)\boldsymbol{\varphi} - 2\mathbf{e},$$

where

$$\boldsymbol{\varphi} = (\varphi(x_0), \varphi(x_1), \dots, \varphi(x_{n+1}))^t \quad \text{and} \quad \mathbf{e} = (1, 1, \dots, 1)^t \in \mathbb{R}^{n+2}.$$

Then a simple computation based upon the usual Taylor expansion for $p(x) \in C^1[a, b]$ and $\varphi(x) \in C^2[a, b]$ yields

$$\|\tau\|_\infty = o(1) \rightarrow 0$$

as $h \rightarrow 0$, where we apply the midpoint rule to estimate the integrals $a_i = \int_{x_{i-1}}^{x_i} (dt/p(t))$, $1 \leq i \leq n+1$ and employ the fact that p' and φ'' are uniformly continuous in the interval $[a, b]$. Hence, for sufficiently small h ,

$$(HA - \eta I)\varphi = 2e + \tau \geq e$$

or

$$(HA - \eta I)^{-1}e \leq \varphi. \quad (3.7)$$

We denote by $|\mathbf{W}|$ the vector $(|W_0|, |W_1|, \dots, |W_{n+1}|)^t$.

Then we have from (3.6)

$$\begin{aligned} |\mathbf{W}| &\leq (A + H^{-1}Z)^{-1}H^{-1}|\tilde{\mathbf{f}}(\mathbf{0})| \\ &\leq (A - \eta H^{-1})^{-1}H^{-1}\|\tilde{\mathbf{f}}(\mathbf{0})\|_\infty e \\ &= \|\tilde{\mathbf{f}}(\mathbf{0})\|_\infty (HA - \eta I)^{-1}e \\ &\leq \|\tilde{\mathbf{f}}(\mathbf{0})\|_\infty \varphi \end{aligned}$$

and

$$\|\mathbf{W}\|_\infty \leq \|\tilde{\mathbf{f}}(\mathbf{0})\|_\infty \|\varphi\|_\infty \leq \|f_0\|_{[a,b]} \|\varphi\|_{[a,b]} = C \quad (\text{say}), \quad (3.8)$$

since we have assumed $\alpha = \beta = 0$ and $\tilde{\mathbf{f}}(\mathbf{0}) = (f_0(x_0), f_0(x_1), \dots, f_0(x_{n+1}))^t$. Hence we put

$$S = \{\mathbf{U} \in \mathbb{R}^{n+2} \mid \|\mathbf{U}\|_\infty \leq C\}$$

and define a map $T: S \rightarrow S$ by $T\mathbf{U} = \mathbf{W}$, $\mathbf{U} \in S$. Then T is continuous. In fact, we have for $\mathbf{U}, \hat{\mathbf{U}} \in S$

$$\begin{aligned} T\mathbf{U} - T\hat{\mathbf{U}} &= -\{(HA + Z)^{-1} - (HA + \hat{Z})^{-1}\}\tilde{\mathbf{f}}(\mathbf{0}) \\ &= (HA + \hat{Z})^{-1}(Z - \hat{Z})(HA + Z)^{-1}\tilde{\mathbf{f}}(\mathbf{0}), \end{aligned} \quad (3.9)$$

where $Z = Z(\mathbf{U})$ and $\hat{Z} = Z(\hat{\mathbf{U}})$. It now follows from (3.8) and (3.9) that

$$\|T\mathbf{U} - T\hat{\mathbf{U}}\|_\infty \leq \|Z - \hat{Z}\|_\infty \|\varphi\|_{[a,b]} C \rightarrow 0$$

as $\|\mathbf{U} - \hat{\mathbf{U}}\|_\infty \rightarrow 0$, since $\|Z - \hat{Z}\|_\infty \rightarrow 0$ as $\|\mathbf{U} - \hat{\mathbf{U}}\|_\infty \rightarrow 0$ because of the uniform continuity of $f_u(x, u)$ in $[a, b] \times [-C, C]$.

Consequently, we conclude, by Brouwer's theorem, that T has a fixed point \mathbf{U} in S , which is a solution of (1.8). \square

4. Error Estimates

We still keep the assumption $\alpha_1\beta_1 \neq 0$ without loss of generality.

Let $u = u(x)$ be the solution of the continuous problem (1.1)–(1.6) and $\mathbf{u} = (u(x_0), u(x_1), \dots, u(x_{n+1}))^t$. We put

$$\boldsymbol{\tau} = HA\mathbf{u} + \tilde{\mathbf{f}}(\mathbf{u}) = (\tau_0, \tau_1, \dots, \tau_{n+1})^t.$$

Then we have from (1.8)

$$HA(\mathbf{u} - \mathbf{U}) + \tilde{\mathbf{f}}(\mathbf{u}) - \tilde{\mathbf{f}}(\mathbf{U}) = \boldsymbol{\tau}$$

or

$$(HA + \tilde{D})(\mathbf{u} - \mathbf{U}) = \boldsymbol{\tau} \tag{4.1}$$

where $\tilde{D} = \text{diag}(\tilde{d}_0, \tilde{d}_1, \dots, \tilde{d}_{n+1})^t$ with $\tilde{d}_i = \int_0^1 f_u(x_i, U_i + \theta(u_i - U_i)) d\theta$. As is shown in the end of the proof of Lemma 3.6, $HA - \eta I$ is an M -matrix and

$$HA + \tilde{D} \geq HA - \eta I.$$

Hence, $HA + \tilde{D}$ is an M -matrix and

$$0 < (HA + \tilde{D})^{-1} \leq (HA - \eta I)^{-1} \tag{4.2}$$

since $HA + \tilde{D}$ is an irreducible Z -matrix and $(HA + \tilde{D})^{-1}$ is a positive matrix ([7]).

It now follows from (4.1) and (4.2) that

$$\mathbf{u} - \mathbf{U} = (HA + \tilde{D})^{-1} \boldsymbol{\tau}. \tag{4.3}$$

As is easily seen, we have

$$\|\boldsymbol{\tau}\|_\infty = \begin{cases} o(1) & (\text{if } u \in C^2[a, b]) \\ O(h) & (\text{if } u \in C^{2,1}[a, b], p \in C^{1,1}[a, b]) \end{cases}$$

and

$$\begin{aligned} |\mathbf{u} - \mathbf{U}| &\leq (HA + \tilde{D})^{-1} |\boldsymbol{\tau}| \leq \|\boldsymbol{\tau}\|_\infty (HA + \tilde{D})^{-1} \mathbf{e} \\ &\leq \|\boldsymbol{\tau}\|_\infty (HA - \eta)^{-1} \mathbf{e} \leq \|\boldsymbol{\tau}\|_\infty \boldsymbol{\varphi} \quad \text{by (3.7).} \end{aligned}$$

Hence

$$\|\mathbf{u} - \mathbf{U}\|_\infty = \begin{cases} o(1) & (u \in C^2[a, b]) \\ O(h) & (u \in C^{2,1}[a, b]). \end{cases} \tag{4.4}$$

Furthermore, if $p \in C^{2,1}[a, b]$ and $u \in C^{3,1}[a, b]$, then it can be shown (see [8] pp. 52–56) that

$$\tau_i = \begin{cases} O(h_1) & (i = 0) \\ \frac{2}{h_i + h_{i+1}} (s_{i+(1/2)} h_{i+1}^2 - s_{i-(1/2)} h_i^2) u'_i - (h_{i+1} - h_i) \kappa_i + O(h^2) & (1 \leq i \leq n) \\ O(h_{n+1}) & (i = n+1) \end{cases}$$

where

$$s(x) = \frac{1}{24} \left(\frac{1}{p} \right)'' p^2, \tag{4.5}$$

$$\kappa(x) = \frac{1}{12} \{ 3p''(x)u'(x) + 6p'(x)u''(x) + 4p(x)u'''(x) \}, \tag{4.6}$$

$$s_{i+(1/2)} = s \left(x_i + \frac{1}{2} h_{i+1} \right),$$

$$s_{i-(1/2)} = s \left(x_i - \frac{1}{2} h_i \right)$$

and

$$\kappa_i = \kappa(x_i).$$

We have from (4.3)

$$\begin{aligned} \mathbf{u} - \mathbf{U} &= (HA + \tilde{D})^{-1} \boldsymbol{\tau} \\ &= \left[(HA)^{-1} - (HA + \tilde{D})^{-1} \tilde{D} (HA)^{-1} \right] \boldsymbol{\tau} \\ &= A^{-1} H^{-1} \boldsymbol{\tau} - (HA + \tilde{D})^{-1} \tilde{D} (A^{-1} H^{-1} \boldsymbol{\tau}) \end{aligned}$$

and

$$\begin{aligned} |\mathbf{u} - \mathbf{U}| &\leq |A^{-1} H^{-1} \boldsymbol{\tau}| + (HA + \tilde{D})^{-1} |\tilde{D}| |A^{-1} H^{-1} \boldsymbol{\tau}| \\ &\leq |A^{-1} H^{-1} \boldsymbol{\tau}| + (HA - \eta I)^{-1} |\tilde{D}| |A^{-1} H^{-1} \boldsymbol{\tau}|. \end{aligned} \tag{4.7}$$

Since $\|\mathbf{U} - \mathbf{u}\|_\infty \rightarrow 0$ as $h \rightarrow 0$ by (4.4), $\|\mathbf{u}\|_\infty \leq \|u\|_{[a,b]} \leq \delta_0$ (cf. the proof of Theorem 2.1) and, for any $\theta \in [0, 1]$,

$$\begin{aligned} \|\mathbf{U} + \theta(\mathbf{u} - \mathbf{U})\|_\infty &= \|\mathbf{u} + (1 - \theta)(\mathbf{U} - \mathbf{u})\|_\infty \\ &\leq \|\mathbf{u}\|_\infty + (1 - \theta)\|\mathbf{U} - \mathbf{u}\|_\infty \\ &\leq \|\mathbf{u}\|_\infty + \|\mathbf{U} - \mathbf{u}\|_\infty, \end{aligned}$$

we may assume that $\|\mathbf{U} + \theta(\mathbf{u} - \mathbf{U})\|_\infty \leq 2\delta_0 \ \forall \theta \in [0, 1]$.

Then

$$|\tilde{d}_i| \leq \widehat{K} = \max_{[a,b] \times [-2\delta_0, 2\delta_0]} |f_u(x, u)| < +\infty \quad \forall i.$$

Therefore we obtain from (4.7) and (3.7)

$$\begin{aligned} \|\mathbf{u} - \mathbf{U}\|_\infty &\leq \|A^{-1}H^{-1}\boldsymbol{\tau}\|_\infty + \widehat{K}\|A^{-1}H^{-1}\boldsymbol{\tau}\|_\infty\|\boldsymbol{\varphi}\|_\infty \\ &\leq (1 + \widehat{K}\|\boldsymbol{\varphi}\|_{[a,b]})\|A^{-1}H^{-1}\boldsymbol{\tau}\|_\infty. \end{aligned} \tag{4.8}$$

If $p \in C^{2,1}[a, b]$ and $u \in C^{3,1}[a, b]$, then we have

$$(A^{-1}H^{-1}\boldsymbol{\tau})_i = \sum_{j=0}^{n+1} G(x_i, x_j)\omega_j\tau_j$$

and we can show

$$\|A^{-1}H^{-1}\boldsymbol{\tau}\|_\infty = O(h^2)$$

by noting that the functions $s(x)$ and $\kappa(x)$ defined by (4.5) and (4.6) are Lipschitz continuous in $[a, b]$ (cf. [8]). Hence, from (4.8) we have $\|\mathbf{u} - \mathbf{U}\|_\infty = O(h^2)$.

Summarizing we have the following result.

THEOREM 4.1. *Under the assumption (2.5), we have*

$$\|\mathbf{u} - \mathbf{U}\|_\infty = \begin{cases} o(1) & (u \in C^2[a, b], p \in C^1[a, b]) \\ O(h) & (u \in C^{2,1}[a, b], p \in C^{1,1}[a, b]) \\ O(h^2) & (u \in C^{3,1}[a, b], p \in C^{2,1}[a, b]). \end{cases}$$

5. Remark

In (1.8), if we replace the integral $\int_{x_{i-1}}^{x_i} (dt/p(t))$ by the mid point formula $h_i/p(x_{i-(1/2)})$ ($x_{i-(1/2)} = (1/2)(x_i+x_{i-1})$) for each i , then the usual finite difference formula arises. We can also derive Theorems 3.1 and 4.1 in this case.

Acknowledgements. The authors are grateful to the referees for their helpful comments, by which this paper has been improved. Among others, constructions of upper and lower solutions described in Remark 2.1 are due to one of the referees.

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