

## ON THE FINITE-TIME BLOW-UP OF A NON-LOCAL PARABOLIC EQUATION DESCRIBING CHEMOTAXIS

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**Abstract.** The non-local parabolic equation

$$v_t = \Delta v + \frac{\lambda e^v}{\int_{\Omega} e^v} \quad \text{in } \Omega \times (0, T)$$

associated with Dirichlet boundary and initial conditions is considered here. This equation is a simplified version of the full chemotaxis system. Let  $\lambda^*$  be such that the corresponding steady-state problem has no solutions for  $\lambda > \lambda^*$ , then it is expected that blow-up should occur in this case. In fact, for  $\lambda > \lambda^*$  and any bounded domain  $\Omega \subset \mathbf{R}^2$  it is proven, using Trudinger-Moser's inequality, that  $\int_{\Omega} e^{v(x,t)} dx \rightarrow \infty$  as  $t \rightarrow T_{max} \leq \infty$ . Moreover, in this case, some properties of the blow-up set are provided. For the two-dimensional radially symmetric problem, i.e. when  $\Omega = B(0, 1)$ , where it is known that  $\lambda^* = 8\pi$ , we prove that  $v$  blows up in finite time  $T^* < \infty$  for  $\lambda > 8\pi$  and this blow-up occurs only at the origin  $r = 0$  (single-point blow-up, mass concentration at the origin).

### 1. INTRODUCTION

The full system of chemotaxis is composed of parabolic equations concerning  $u = u(x, t)$  and  $v = v(x, t)$ , which stand for the particle density and the field distribution, respectively [12, 13, 28]. A typical case,

$$\begin{aligned} \varepsilon u_t &= \nabla \cdot (\nabla u - u \nabla v) \\ \tau v_t &= \Delta v + u - \frac{1}{|\Omega|} \int_{\Omega} u \quad \text{in } \Omega \times (0, T) \\ \frac{\partial u}{\partial \nu} - u \frac{\partial v}{\partial \nu} &= \frac{\partial v}{\partial \nu} = 0 \quad \text{on } \partial \Omega \times (0, T) \end{aligned}$$

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$$\begin{aligned} \int_{\Omega} v(x, t) dx &= 0 \quad \text{for } t \in (0, T) \\ u|_{t=0} = u_0(x) \geq 0, \quad v|_{t=0} = v_0(x) &\quad \text{in } \Omega, \end{aligned} \tag{1.1}$$

is called the Keller-Segel system, where  $\Omega \subset \mathbf{R}^n$  is a bounded domain with smooth boundary  $\partial\Omega$ ,  $\nu$  is the outward unit normal vector, and  $\varepsilon, \tau$  are positive constants [15]. It is associated with the Lagrange function,

$$L(u, v) = \int_{\Omega} u(\log u - 1) + \frac{1}{2} \|\nabla v\|_2^2 - \langle v, u \rangle$$

provided with the constraint  $\int_{\Omega} v = 0$ , and is formulated by the model (B) - model (A) equations [29] :

$$\begin{aligned} \varepsilon u_t &= \nabla \cdot u \nabla L_u(u, v) \\ \tau v_t &= -L_v(u, v) \quad \text{in } \Omega \times (0, T) \\ u \frac{\partial}{\partial \nu} L_u(u, v) &= \frac{\partial v}{\partial \nu} = 0 \quad \text{on } \partial\Omega \times (0, T). \end{aligned}$$

Here and henceforth,  $\langle \cdot, \cdot \rangle$  denotes the  $L^2$ -inner product.

Since  $u = u(x, t) \geq 0$ , follows from the maximum principle, this formulation results in

$$\|u(\cdot, t)\|_1 = \|u_0\|_1 = \lambda, \quad \frac{d}{dt} L(u(\cdot, t), v(\cdot, t)) \leq 0,$$

and consequently, the stationary state is described by

$$\begin{aligned} \log u - v &= \text{constant} \quad \text{in } \Omega \\ -\Delta v &= u - \frac{1}{|\Omega|} \int_{\Omega} u \quad \text{in } \Omega, \quad \frac{\partial v}{\partial \nu} = 0 \quad \text{on } \partial\Omega, \quad \int_{\Omega} v = 0. \end{aligned} \tag{1.2}$$

The first relation of (1.2) implies

$$u = \frac{\lambda e^v}{\int_{\Omega} e^v}, \tag{1.3}$$

where  $\lambda = \|u\|_1$ , and henceforth, we shall write  $v = (-\Delta_{JL})^{-1}u$  for the second equation of (1.2). Thus, in the stationary state of (1.1), it holds that

$$\log u - (-\Delta_{JL})^{-1}u = \text{constant}, \quad u \geq 0 \quad \text{in } \Omega, \quad \|u\|_1 = \lambda \tag{1.4}$$

and

$$-\Delta v = \lambda \left( \frac{e^v}{\int_{\Omega} e^v} - \frac{1}{|\Omega|} \right) \quad \text{in } \Omega, \quad \frac{\partial v}{\partial \nu} = 0 \quad \text{on } \partial\Omega, \quad \int_{\Omega} v = 0. \tag{1.5}$$

There is a duality in these problems describing stationary states, in fact (1.4) and (1.5) are equivalent to the variational problems

$$\delta\mathcal{F}(u) = 0, \quad u \geq 0, \quad \|u\|_1 = \lambda$$

and

$$\delta\mathcal{J}_\lambda(v) = 0, \quad \int_\Omega v = 0,$$

using free energy and field functionals,

$$\begin{aligned} \mathcal{F}(u) &= L|_{v=(-\Delta_{JL})^{-1}u} = \int_\Omega u(\log u - 1) - \frac{1}{2} \langle (-\Delta_{JL}^{-1}u, u) \rangle \\ \mathcal{J}_\lambda(v) &= L|_{u=\frac{\lambda e^v}{\int_\Omega e^v}} = \frac{1}{2} \|\nabla v\|_2^2 - \lambda \log \left( \int_\Omega e^v \right) + \lambda(\log \lambda - 1), \end{aligned}$$

respectively. See [29] for more details and background of this structure.

Since (1.5) with  $n = 2$  is provided with the quantized blow-up mechanism [20, 3, 16], a similar property to (1.1) has been suspected [4]. Actually, Herrero-Velázquez, [11], constructed a family of radially symmetric solutions satisfying

$$u(x, t) \rightarrow 8\pi\delta_0 + f(x)$$

in  $\mathcal{M}(\overline{\Omega})$  as  $t \uparrow T < +\infty$ , where  $\Omega = B(0, 1) = \{x \in \mathbf{R}^2 : |x| < 1\}$  and  $0 \leq f = f(x) \in L^1(\Omega) \cap C(\overline{\Omega} \setminus \{0\})$ .

The reduced case  $(\varepsilon, \tau) = (1, 0)$  of (1.6) is called the simplified system. For this problem, the above profile has a generalization, and if  $u = u(x, t)$  is a blow-up solution in finite time to

$$\begin{aligned} u_t &= \nabla \cdot (\nabla u - u\nabla v) \\ -\Delta v &= u - \frac{1}{|\Omega|} \int_\Omega u \quad \text{in } \Omega \times (0, T) \\ \frac{\partial u}{\partial \nu} - u \frac{\partial v}{\partial \nu} &= \frac{\partial v}{\partial \nu} = 0 \quad \text{on } \partial\Omega \times (0, T) \\ \int_\Omega v(x, t) dx &= 0 \quad \text{for } t \in (0, T) \\ u|_{t=0} &= u_0(x) > 0 \quad \text{in } \Omega \end{aligned} \tag{1.6}$$

with  $n = 2$ , then it develops delta-function singularities with the coefficients quantized by  $8\pi$  or  $4\pi$  inside  $\Omega$  and on  $\partial\Omega$ , respectively [23, 25, 28]. This system (1.6) is also a typical form of the Smoluchowski equation [6], one of the fundamental equations of material transport subject to the second law of thermodynamics, and is put into the mean field hierarchy, see [29].

This paper studies the case  $n = 2$  only. The above described quantized blow-up mechanism is regarded as a localization of the threshold of the total mass for the existence of the solution globally in time. For instance, Nagai [17] treated radially symmetric solutions to (1.6) and showed that  $T = +\infty$  holds if  $\lambda < 8\pi$ , while  $T < +\infty$  occurs if  $\lambda > 8\pi$  and  $u_0$  is sufficiently concentrated at the origin. Here and henceforth,  $T = T_{\max} \in (0, +\infty]$  denotes the existence time of the solution. See [19, 2, 7, 18, 24] for this threshold phenomenon in the non-radially symmetric case.

The proof of  $T = +\infty$  in this system is based on the Trudinger-Moser inequality, and is valid even in (1.1). There seems to be, however, no criterion of  $T < +\infty$  valid in (1.1) up to now. To this connection, Wolansky [31] introduced the limiting system of  $(\varepsilon, \tau) = (0, 1)$  as

$$\begin{aligned} \varepsilon u_t &= \nabla \cdot (\nabla u - u \nabla v) \\ \tau v_t &= \Delta v + u \quad \text{in } \Omega \times (0, T) \\ \frac{\partial u}{\partial \nu} - u \frac{\partial v}{\partial \nu} &= v = 0 \quad \text{on } \partial\Omega \times (0, T) \end{aligned} \quad (1.7)$$

and showed the formation of collapse of radially symmetric solutions. Since in this case the first equation is transformed to (1.3), the original system is reduced to the non-local problem

$$v_t = \Delta v + \frac{\lambda e^v}{\int_{\Omega} e^v} \quad \text{in } \Omega \times (0, T), \quad v = 0 \quad \text{on } \partial\Omega \times (0, T). \quad (1.8)$$

Then, his result is the following.

**Theorem 1** ([31]). *If  $\Omega = B(0, 1) = \{x \in \mathbf{R}^2 : |x| < 1\}$ ,  $v_0 = v_0(|x|)$  is smooth, and  $\lambda \geq 8\pi$ , then*

$$\frac{e^v}{\int_{\Omega} e^v} \rightharpoonup \delta_0(dx) \quad (1.9)$$

as  $t \uparrow T$  in (1.8).

Although the case  $T = +\infty$  is also included in the above theorem, we can actually show the following.

**Theorem 2.** *In the previous theorem, it holds that  $T < +\infty$  if  $\lambda > 8\pi$ .*

This means that the formation of collapse with dis-quantized mass occurs in finite time in the limiting case  $\varepsilon = 0$ , in contrast with the other limiting case  $\tau = 0$ , in (1.7).

Theorem 2 is the main result of this work and is, according to our knowledge, the only finite-time blow-up result associated to problem (1.8).

In the case of the non-local problem

$$v_t = \Delta v + \frac{\lambda e^v}{\left(\int_{\Omega} e^v\right)^p} \quad \text{in } \Omega \times (0, T), \quad v = 0 \quad \text{on } \partial\Omega \times (0, T)$$

with  $0 < p < 1$ , which models shear-banding phenomena, more results regarding blow-up are known. In this case the problem defines a gradient-like semiflow with its Lyapunov functional given by

$$\mathcal{J}_{\lambda}(v) = \frac{1}{2} \|\nabla v\|_2^2 + \frac{\lambda}{p-1} \left(\int_{\Omega} e^v\right)^{1-p}$$

and blow-up can be proven using energy methods either in the case where  $E = \emptyset$  ( $E$ : the set of the steady states) or for large enough initial data, see [1, 33]. For a nonlinearity that is positive, increasing, convex and growing superlinearly to infinity (different from the exponential) when the above problem doesn't admit a Lyapunov functional some blow-up results have been also proven. For this purpose Kaplan's method could be applied, see [14]. For problem (1.8) the methods in [1, 14, 33] cannot be applied. It seems that the exponent  $p = 1$  is a kind of critical one, see also Section 4, and in this case we probably need more delicate arguments to prove blow-up.

This paper is composed of four sections. In the next section we present some preliminary results, and in Section 3 we give a proof of Theorem 2. Section 4 is devoted to concluding remarks.

## 2. PRELIMINARIES

If  $\Omega \subset \mathbf{R}^2$  is a bounded domain with smooth boundary  $\partial\Omega$ , then the functional

$$\mathcal{J}_{\lambda}(v) = \frac{1}{2} \|\nabla v\|_2^2 - \lambda \log \left(\int_{\Omega} e^v\right) + \lambda(\log \lambda - 1)$$

is  $C^2$  in  $v \in H_0^1(\Omega)$ , and we obtain the Trudinger-Moser inequality indicated by

$$\inf_{v \in H_0^1(\Omega)} \mathcal{J}_{8\pi}(v) > -\infty. \quad (2.1)$$

Equation (1.8) is the gradient flow of this functional,

$$v_t = -\delta \mathcal{J}_{\lambda}(v) \quad \text{in } X = H_0^1(\Omega),$$

and hence it holds that

$$\frac{d}{dt} \mathcal{J}_{\lambda}(v(\cdot, t)) = -\|v_t(\cdot, t)\|_2^2. \quad (2.2)$$

The mapping

$$v \in X \mapsto \frac{e^v}{\int_{\Omega} e^v} \in X$$

is Lipschitz continuous on each bounded set of  $X$ , and therefore (1.8) is well posed in  $X$ ; i.e., given an initial value  $v_0 \in X$ , we obtain a unique semi-group solution  $v = v(\cdot, t) \in X$  locally in time, and henceforth the maximal time of its existence is denoted by  $T = T_{\max} \in (0, +\infty]$ , which is estimated from below by  $\|\nabla v_0\|_2$ . Then, from (2.1) and the parabolic regularity we obtain

$$T = +\infty \quad \text{and} \quad \sup_{t \geq 0} \|v(\cdot, t)\|_{\infty} < +\infty, \quad (2.3)$$

in the case of  $\lambda < 8\pi$ , and also

$$\lim_{t \uparrow T} \|v(\cdot, t)\|_{\infty} = +\infty, \quad (2.4)$$

if  $T < +\infty$ . In the latter case we can define

$$\mathcal{S} = \{x_0 \in \overline{\Omega} : \exists x_k \rightarrow x_0, \exists t_k \uparrow T, \text{ s.t. } v(x_k, t_k) \rightarrow +\infty\} \neq \emptyset,$$

called the blow-up set.  $\mathcal{S}$  can be also defined in the case where (2.4) is fulfilled for  $T = \infty$ . We obtain

$$v(\cdot, t) \geq \inf_{\Omega} v_0$$

by the comparison principle, and henceforth,  $v_0 \geq 0$  is assumed without loss of generality.

The parabolic Brezis-Merle inequality [9, 32], on the other hand, is concerned with the linear parabolic equation

$$v_t = \Delta v + f(x, t) \quad \text{in } \Omega \times (0, T), \quad v|_{\partial\Omega} = 0, \quad v|_{t=0} = 0,$$

where  $\Omega$  is again a two-dimensional bounded domain with smooth boundary  $\partial\Omega$ . Its global form ensures that any  $\delta > 0$  admits  $p > 1$  and  $C > 0$  such that

$$\sup_{t \in (0, T)} \|f(\cdot, t)\|_1 < 4\pi - \delta \quad \Rightarrow \quad \sup_{t \in (0, T)} \left\| e^{v(\cdot, t)} \right\|_p \leq C.$$

This induces the local version, i.e., given subdomains  $\omega$  and  $\hat{\omega}$  with  $\omega \subset\subset \hat{\omega} \subset\subset \Omega$  and  $\delta > 0$ , we obtain  $p > 1$  and  $C > 0$  both determined by  $\sup_{t \in (0, T)} \|f(\cdot, t)\|_1$  such that

$$\sup_{t \in (0, T)} \|f(\cdot, t)\|_{L^1(\hat{\omega})} < 4\pi - \delta \quad \Rightarrow \quad \sup_{t \in (0, T)} \left\| e^{v(\cdot, t)} \right\|_{L^p(\omega)} \leq C.$$

Regarding now the location of blow-up points in the case of a convex set we have the following.

**Lemma 3.** *If  $T < +\infty$  and  $\Omega$  is convex, then  $\mathcal{S} \subset \Omega$ .*

**Proof.** Let  $v = v(x, t)$  be a solution to (1.8) with  $v|_{t=0} = v_0(x)$ . Having assumed  $v_0 \geq 0$ , we obtain  $v = v(x, t) \geq 0$ , and then

$$\sup_{t \in [0, T]} \|v(\cdot, t)\|_p < +\infty \tag{2.5}$$

follows for any  $p \geq 1$  from the global parabolic Brezis-Merle inequality.

This  $v$  is a solution to

$$v_t = \Delta v + \sigma(t)e^v \quad \text{in } \Omega \times (0, T), \quad v|_{\partial\Omega} = 0, \quad v|_{t=0} = v_0(x)$$

for  $\sigma(t) = \frac{\lambda}{\int_{\Omega} e^{v(\cdot, t)}}$  and the method of the moving plane, [8], is applicable.

Using (2.5), we can apply the argument of [5], and consequently, there is an open set  $\hat{\omega}$  containing  $\partial\Omega$  and a constant  $C > 0$  such that

$$\sup_{t \in [0, T]} \|v(\cdot, t)\|_{L^\infty(\Omega \cap \hat{\omega})} \leq C,$$

and therefore,  $\mathcal{S} \subset \Omega$ . □

**Remark 2.1.** Due to a uniform  $L^1$ -estimate of the solution of (1.8) the result of the above lemma can be extended to higher dimensions  $n \geq 2$ . In fact, multiplying the equation of (1.8) by the eigenfunction  $\phi_1(x) > 0$  corresponding to the principal eigenvalue  $\lambda_1$  of  $-\Delta_D$  and integrating over  $\Omega$  we obtain

$$\frac{d}{dt} \int_{\Omega} v(x, t) \phi_1(x) dx \leq -\lambda_1 \int_{\Omega} v(x, t) \phi_1(x) dx + \lambda M, \quad 0 < t < T,$$

for  $M = \max_{\bar{\Omega}} \phi_1(x) > 0$ , which implies

$$\int_{\Omega} v(x, t) \phi_1(x) dx \leq C := C(v_0, \lambda_1, \lambda, M) \quad \text{for any } 0 < t < T. \tag{2.6}$$

Since  $\Omega$  is convex, using the method of moving planes, [8], we can find  $\bar{\Omega}_0 \subset \Omega$  such that

$$\int_{\Omega} v(x, t) dx \leq \frac{k+1}{m} \int_{\Omega_0} v(x, t) \phi_1(x) dx \leq \frac{k+1}{m} \int_{\Omega} v(x, t) \phi_1(x) dx < C_1, \tag{2.7}$$

by (2.6) for any  $0 < t < T$  and  $m = \min_{\bar{\Omega}_0} \phi_1(x) > 0$ . Using now estimate (2.7), which for  $N = 2$  comes out from the parabolic version of the Brezis-Merle inequality, along with the ideas existing in [5] we derive the desired result. If  $v = v(x, t)$  is radially symmetric and decreasing in  $r = |x|$ , and if (2.4) holds, then  $\mathcal{S} = \{0\}$  by the same reasoning. We also note that in the

case of  $T_{\max} = +\infty$ , any radially symmetric solution becomes decreasing in  $r = |x|$  eventually, see [21].

The stationary problem to (1.8) is described by

$$-\Delta v_* = \frac{\lambda e^{v_*}}{\int_{\Omega} e^{v_*}} \quad \text{in } \Omega, \quad v_* = 0 \quad \text{on } \partial\Omega. \quad (2.8)$$

Let  $E = \{v_* : \text{solution to (2.8)}\}$  then we have the following lemma due to Wolansky, see Theorem 8 in [31]. Since we use the local well-posedness in time of (1.8) in  $X = H_0^1(\Omega)$  and the Trudinger-Moser inequality, the proof is valid only to  $n = 1, 2$ . However, here a simpler proof is provided.

**Lemma 4.** *If  $E = \emptyset$ , then it holds that*

$$\lim_{t \uparrow T} \int_{\Omega} e^{v(\cdot, t)} = +\infty \quad (2.9)$$

and  $\mathcal{S} \neq \emptyset$ , where the case  $T = +\infty$  is also included.

**Proof.** We follow the argument of [31]. First, if  $\mathcal{S} = \emptyset$ , then

$$\sup_{t \in [0, T)} \|v(\cdot, t)\|_{\infty} < +\infty.$$

This implies  $T = +\infty$  and  $E \neq \emptyset$  by a standard argument using Lyapunov functions [10], a contradiction.

Next, if

$$\liminf_{t \uparrow T} \int_{\Omega} e^{v(\cdot, t)} < +\infty,$$

then we obtain

$$\lim_{t \uparrow T} \mathcal{J}_{\lambda}(v(\cdot, t)) \geq \limsup_{t \uparrow T} \left\{ -\lambda \log \left( \int_{\Omega} e^{v(\cdot, t)} \right) \right\} + \lambda(\log \lambda - 1) > -\infty \quad (2.10)$$

and

$$\begin{aligned} & \frac{1}{2} \liminf_{t \uparrow T} \|\nabla v(\cdot, t)\|_2^2 \\ & \leq \mathcal{J}_{\lambda}(v_0) + \lambda \liminf_{t \uparrow T} \log \left( \int_{\Omega} e^{v(\cdot, t)} \right) - \lambda(\log \lambda + 1) < +\infty. \end{aligned}$$

The latter relation guarantees  $T = +\infty$  because of the well posedness in  $X = H_0^1(\Omega)$  of (1.8). Furthermore, there are  $\delta \in (0, 1)$ ,  $t_k \uparrow +\infty$ , and  $C > 0$  such that  $t_{k+1} > t_k + 1$  and

$$\sup_{t \in (t_k, t_k + \delta)} \|\nabla v(\cdot, t)\|_2 \leq C.$$



This implies

$$\sum_{k=1}^{\infty} \int_{t_k}^{t_k+\delta} \|v_t(\cdot, t)\|_2^2 dt \leq \int_0^{\infty} \|v_t(\cdot, t)\|_2^2 dt < +\infty$$

by (2.10) and (2.2), and therefore,

$$\lim_{k \rightarrow \infty} \int_{t_k}^{t_k+\delta} \|v_t(\cdot, t)\|_2^2 dt = 0.$$

Then, we obtain  $t'_k \in (t_k, t_k + \delta)$  satisfying  $\|v_t(\cdot, t'_k)\|_2 \rightarrow 0$ . Since  $\|\nabla v(\cdot, t'_k)\|_2 \leq C$ , we obtain a subsequence, denoted by the same symbol, such that  $v(\cdot, t'_k) \rightharpoonup w$  weakly in  $X$ . This implies  $e^{v(\cdot, t'_k)} \rightarrow e^w$  strongly in  $L^p(\Omega)$ ,  $p \geq 1$  by the Trudinger-Moser inequality, and then  $w \in E$  follows, a contradiction.  $\square$

Now, we show the following:

**Proof of Theorem 1.** Let  $\Omega = B(0, 1)$ ,  $v_0 = v_0(|x|) \geq 0$ , and  $\lambda \geq 8\pi$ . We obtain  $E = \emptyset$  in this case, and therefore,  $\mathcal{S} \neq \emptyset$  and (2.9) follows. Since  $v = v(|x|, t)$ , any  $x_0 \in \Omega \setminus \{0\}$  admits  $0 < r \ll 1$  such that

$$\sup_{t \in (0, T)} \left\| \frac{\lambda e^{v(\cdot, t)}}{\int_{\Omega} e^{v(\cdot, t)}} \right\|_{L^1(B(x_0, 2r))} < 4\pi.$$

Then, the local parabolic Brezis-Merle inequality to (1.8) guarantees

$$\sup_{t \in (0, T)} \left\| e^{v(\cdot, t)} \right\|_{L^p(B(x_0, r))} < +\infty$$

with  $p > 1$ , and therefore, it holds that

$$\sup_{t \in (0, T)} \left\| \frac{\lambda e^{v(\cdot, t)}}{\int_{\Omega} e^{v(\cdot, t)}} \right\|_{L^p(B(x_0, r))} < +\infty$$

since  $v \geq 0$ . This implies

$$\sup_{t \in (0, T)} \|v(\cdot, t)\|_{W^{2,p}(B(x_0, r/2))} < +\infty$$

from the local parabolic regularity, and hence  $x_0 \notin \mathcal{S}$  by Sobolev's imbedding theorem. Thus, it holds that  $\mathcal{S} = \{0\}$  and (1.9) follows.  $\square$

## 3. PROOF OF THE MAIN RESULT

This section is devoted to the proof of Theorem 2. Thus,  $v = v(|x|, t)$  denotes a solution to (1.8) for  $\Omega = B(0, 1)$  and  $\lambda > 8\pi$ , and we define  $u$  by (1.3). Then, we have  $\nabla u = u\nabla v$  and therefore,

$$-\int_{\Omega} u\nabla \cdot \psi \, dx = \int_{\Omega} u\psi \cdot \nabla v \, dx \quad (3.1)$$

for any  $\psi \in C^1(\overline{\Omega})^2$ . Since

$$v_t = \Delta v + u \quad \text{in } \Omega, \quad v|_{\partial\Omega} = 0 \quad (3.2)$$

holds, by (1.8), we have

$$v = (-\Delta_D)^{-1}u - (-\Delta_D)^{-1}v_t,$$

where  $w = (-\Delta_D)^{-1}u$  denotes the solution of the problem

$$-\Delta w = u \quad \text{in } \Omega, \quad w = 0 \quad \text{on } \partial\Omega.$$

Thus, the right-hand side of (3.1) is equal to

$$\begin{aligned} \int_{\Omega} u\psi \cdot \nabla v \, dx &= \int_{\Omega} u\psi \cdot \nabla \{(-\Delta_D)^{-1}u - (-\Delta_D)^{-1}v_t\} \, dx \\ &= \frac{1}{2} \int \int_{\Omega \times \Omega} \rho(x, x')u(x, t)u(x', t)dx dx' - \int_{\Omega} u\psi \cdot \nabla(-\Delta_D)^{-1}v_t \, dx \end{aligned}$$

for

$$\rho(x, x') = \psi(x) \cdot \nabla_x G(x, x') + \psi(x') \cdot \nabla_{x'} G(x, x'),$$

where  $G = G(x, x')$  is the Green's function of  $-\Delta_D$  satisfying  $G(x', x) = G(x, x')$  and

$$G(x, x') = \frac{1}{2\pi} \log \frac{1}{|x - x'|} + K(x, x') \quad (3.3)$$

with  $K \in C_{loc}^{2+\theta}(\overline{\Omega} \times \Omega \cup \Omega \times \overline{\Omega})$  for  $0 < \theta < 1$  ([28]).

Here, we take  $\psi(x) = x\varphi(|x|)$  for  $\varphi = \varphi(|x|) \in C_0^\infty(\Omega)$  satisfying  $0 \leq \varphi \leq 1$  and  $\varphi = 1$  near  $x = 0$ . Then,  $\nabla \cdot \psi|_{x=0} = 2$  and therefore,

$$\int_{\Omega} u\nabla \cdot \psi \, dx = 2\lambda + o(1) \quad (3.4)$$

holds as  $t \uparrow T$  by (1.9). The relation (3.3), on the other hand, guarantees

$$\rho(x, x') = -\frac{1}{2\pi} + L(x, x')$$

with  $L = L(x, x') \in C(\overline{\Omega} \times \overline{\Omega})$  satisfying  $L(0, 0) = 0$ , and therefore,

$$\frac{1}{2} \int \int_{\Omega \times \Omega} \rho(x, x') u(x, t) u(x', t) dx dx' = -\frac{\lambda^2}{4\pi} + o(1)$$

as  $t \uparrow T$ . Thus, we obtain

$$-\int_{\Omega} u(\psi \cdot \nabla)(-\Delta_D)^{-1} v_t dx = \frac{\lambda^2}{4\pi} - 2\lambda + o(1) \tag{3.5}$$

as  $t \uparrow T$  by (3.1) and (3.4).

The relation  $V = (-\Delta_D)^{-1} v_t$  implies  $(rV_r)_r = -rv_t$ , and hence

$$rV_r(r, t) = -\int_0^r sv_t(s, t) ds$$

for  $r = |x|$ . This implies

$$\begin{aligned} (\psi \cdot \nabla)(-\Delta_D)^{-1} v_t &= \varphi(r) r \partial_r (-\Delta_D)^{-1} v_t = -\varphi(r) \int_0^r sv_t(s, t) ds \\ &= -\frac{\varphi(r)}{2\pi} \int_{B(0,r)} v_t(s, t) dx, \end{aligned}$$

and therefore,

$$-\int_{\Omega} u(\psi \cdot \nabla)(-\Delta_D)^{-1} v_t dx \leq \frac{\lambda}{2\pi} \sup_r \varphi(r) \int_{B(0,r)} v_t dx \leq \frac{\lambda}{2\pi} \|v_t\|_1$$

since  $u \geq 0$  and  $\|u\|_1 = \lambda$ .

It holds that

$$\liminf_{t \uparrow T} \|v_t(\cdot, t)\|_1 \geq \frac{\lambda}{2} - 4\pi > 0 \tag{3.6}$$

by (3.5) and  $\lambda > 8\pi$ , and hence

$$\|v_t(\cdot, t)\|_2 \geq \delta \tag{3.7}$$

with  $\delta > 0$  independent of  $t \geq 1$ , in case of  $T = +\infty$ .

Let  $0 < \mu_1 < \mu_2 \leq \dots$  be the eigenvalues of  $-\Delta_D$  with corresponding  $L^2$ -normalized eigenfunctions  $\varphi_j = \varphi_j(x)$ ,  $j = 1, 2, \dots$ ; i.e.,

$$-\Delta \varphi_j = \mu_j \varphi_j \text{ in } \Omega, \quad \varphi_j = 0 \text{ on } \partial\Omega, \quad \|\varphi_j\|_2 = 1.$$

Then, we obtain

$$\mu_j \sim j \quad \text{and} \quad \|\varphi_j\|_{\infty} \leq Cj^{1/4} \tag{3.8}$$

as  $j \rightarrow \infty$ , see [26]. If  $T = +\infty$ , there is  $t_k \rightarrow +\infty$  such that

$$v(\cdot, t_k) \rightharpoonup \exists v_* \text{ weakly in } L^2(\Omega) \text{ as } k \rightarrow \infty \tag{3.9}$$

by (2.5) with  $p = 2$ . Then, it follows that

$$g_j(t + t_k) = e^{-\mu_j t} g_j(t_k) + \int_0^t e^{-(t-s)\mu_j} \langle u(\cdot, s + t_k), \varphi_j \rangle ds$$

for  $g_j(t) = \langle v(\cdot, t), \varphi_j \rangle$  by

$$\dot{g}_j = -\mu_j g_j + \langle u, \varphi_j \rangle,$$

and therefore,

$$|\langle v(\cdot, t + t_k), \varphi_j \rangle| \leq e^{-\mu_j t} \|v(\cdot, t_k)\|_2 + \lambda \|\varphi_j\|_\infty \mu_j^{-1}.$$

Due to (2.5) and (3.8), the above relation implies

$$|\langle v(\cdot, t + t_k), \varphi_j \rangle| \leq A_j$$

for  $t \geq 1$  and  $k = 1, 2, \dots$  where  $A_j = C(e^{-\alpha j} + \lambda j^{-\frac{3}{4}}) > 0$  for  $j \gg 1$ ,  $\alpha > 0$ , and  $C > 0$ , satisfying  $\sum_{j=1}^{\infty} A_j^2 < +\infty$ . Now taking into account (1.9) and (3.9) we derive

$$\begin{aligned} \langle v(\cdot, t + t_k), \varphi_j \rangle &= g_j(t + t_k) \\ &\rightarrow e^{-\mu_j t} \langle v_*, \varphi_j \rangle + \int_0^t e^{-(t-s)\mu_j} \lambda \varphi_j(0) ds \\ &= e^{-\mu_j t} \langle v_*, \varphi_j \rangle + \frac{\lambda \varphi_j(0)}{\mu_j} (1 - e^{-\mu_j t}) \end{aligned}$$

as  $k \rightarrow \infty$  uniformly in  $t \geq 1$  for each  $j$ , and therefore,

$$v(\cdot, t + t_k) \rightarrow V(\cdot, t) \quad \text{as } k \rightarrow \infty$$

in  $L^2(\Omega)$  uniformly in  $t \geq 1$ , where

$$V(\cdot, t) = \sum_{j=1}^{\infty} \left\{ e^{-\mu_j t} \langle v_*, \varphi_j \rangle + \frac{\lambda \varphi_j(0)}{\mu_j} (1 - e^{-\mu_j t}) \right\} \varphi_j$$

converging in  $L^2(\Omega)$ . Similarly,

$$v_t(\cdot, t + t_k) \rightarrow W(\cdot, t) \quad \text{as } k \rightarrow \infty$$

in  $L^2(\Omega)$  uniformly in  $t \geq 1$ , where

$$W(\cdot, t) = \sum_{j=1}^{\infty} e^{-\mu_j t} \{-\mu_j \langle v_*, \varphi_j \rangle + \lambda \varphi_j(0)\} \varphi_j = V_t.$$

Hence we derive  $\|W(\cdot, t)\|_2^2 \geq \delta^2$  by (3.7). On the other hand, we obtain

$$\|W(\cdot, t)\|_2^2 = \sum_{j=1}^{\infty} e^{-2\mu_j t} |-\mu_j \langle v_*, \varphi_j \rangle + \lambda \varphi_j(0)|^2 \rightarrow 0$$

as  $t \rightarrow +\infty$ , a contradiction. □

#### 4. CONCLUDING REMARKS

This section is devoted to several remarks. First, the Green's function to  $-\Delta_D$  for  $\Omega = B(0, 1)$  is given explicitly by

$$G(x, x') = -\frac{1}{4\pi} \log \left| \frac{z - z'}{1 - \bar{z}z'} \right|^2,$$

where  $z$  and  $z'$  are complex numbers corresponding to  $x$  and  $x'$ , respectively. This implies

$$x \cdot \nabla_x G(x, x') + x' \cdot \nabla_{x'} G(x, x') = -\frac{1}{2\pi} \cdot \frac{1 - |\zeta|^2}{|1 - \zeta|^2}$$

for  $\zeta = \bar{z}z'$ . We can see that this function does not belong to  $L^\infty(\Omega \times \Omega)$  in contrast with the corresponding function derived from the Green's function to  $-\Delta_{JL}$  ([28]). There is a similar difficulty in (1.7), and the control of the boundary blow-up points has not been completed even in the case of  $(\varepsilon, \tau) = (1, 0)$ .

Next, if  $0 < \lambda < 8\pi$ , the stationary problem (2.8) admits a unique solution [27, 30]. Since (2.3) holds in this range of  $\lambda$ , the solution  $v = v(x, t)$  to (1.8) converges uniformly to this steady solution. What is expected in the case that  $\lambda = 8\pi$ ,  $\Omega = B(0, 1)$ , and  $v_0 = v_0(|x|)$  is that an infinite-time blow-up occurs for the solution  $v$ ; i.e.,  $T = +\infty$  and  $v(x, t) \rightarrow 4 \log \frac{1}{|x|}$  locally uniformly in  $x \in \bar{\Omega} \setminus \{0\}$  as  $t \uparrow +\infty$ .

In the limiting case  $\varepsilon = 0$  system (1.1) is described by

$$\begin{aligned} v_t &= \Delta v + \lambda \left( \frac{e^v}{\int_{\Omega} e^v} - \frac{1}{|\Omega|} \right) \quad \text{in } \Omega \times (0, T) \\ \frac{\partial v}{\partial \nu} &= 0 \quad \text{on } \partial\Omega \times (0, T) \end{aligned} \tag{4.1}$$

with the smooth initial value  $v_0 = v_0(x)$  satisfying  $\int_{\Omega} v_0 \, dx = 0$ . In the case that either  $0 < \lambda < 4\pi$  or  $0 < \lambda < 8\pi$ ,  $\Omega = B(0, 1)$ , and  $v_0 = v_0(|x|)$ , we obtain (2.3) similarly to the full system, see [19, 2, 7]. In contrast to (2.8) the stationary problem (1.5) to (4.1) has the trivial solution  $v = 0$  for any  $\lambda$ . Furthermore, multiple existence of the stationary (non-radially symmetric)

solutions arises even when  $0 < \lambda < 4\pi$  and  $\Omega = B(0, 1)$  ([22, 28]). On the other hand, it is proven that either  $T = +\infty$  or (1.9) with  $T < +\infty$  holds in (4.1), similarly to Theorem 2, for  $\Omega = B(0, 1)$ ,  $v_0 = v_0(|x|)$  smooth, and  $\lambda > 8\pi$ .

If the former case occurs, then the  $\omega$ -limit set contains a (radially symmetric) stationary solution, while there is a bifurcation of non-constant radially symmetric stationary solutions at  $\lambda = \lambda_* > 8\pi$ . Then, we can suspect that any  $\lambda > 8\pi$  admits a radially symmetric stationary solution (possibly the trivial one  $v = 0$ ), stable in the space of radially symmetric functions. Therefore, the possibility of (1.9) holding with  $T < +\infty$  is left open in (4.1) even for  $\lambda > 8\pi$ ,  $\Omega = B(0, 1)$  and  $v_0 = v_0(|x|)$ , in contrast to Theorem 2.

A simple blow-up criterion is obtained for the semilinear parabolic equation

$$v_t = \Delta v + |v|^{q-1} v \quad \text{in } \Omega \times (0, T), \quad v = 0 \quad \text{on } \partial\Omega \times (0, T)$$

with  $1 < q < \infty$ . In fact, this equation admits the properties

$$\begin{aligned} \frac{d}{dt} J(v(\cdot, t)) &\leq 0 \\ \frac{1}{4} \frac{d}{dt} \|v(\cdot, t)\|_2^2 &= -J(v(\cdot, t)) + \left(\frac{1}{2} - \frac{1}{q+1}\right) \|v(\cdot, t)\|_{q+1}^{q+1} \end{aligned}$$

for

$$J(v) = \frac{1}{2} \|\nabla v\|_2^2 - \frac{1}{q+1} \|v\|_{q+1}^{q+1}.$$

Using the above, we can infer  $T < +\infty$  by  $J(v_0) \leq 0$ . The same argument is valid with

$$v_t = \Delta v + \frac{\lambda e^v}{\left(\int_{\Omega} e^v\right)^p} \quad \text{in } \Omega \times (0, T), \quad v = 0 \quad \text{on } \partial\Omega \times (0, T)$$

with  $0 < p < 1$  ([1]), but this is not the case with (1.8).

In fact, (1.8) is written in the form (3.2) with  $u = \frac{\lambda e^v}{\int_{\Omega} e^v}$  satisfying  $\|u\|_1 = \lambda$ . Setting  $\mathcal{J}_\lambda(v) = L(u, v)$ , where

$$\begin{aligned} \mathcal{J}_\lambda(v) &= \frac{1}{2} \|\nabla v\|_2^2 - \lambda \log \left( \int_{\Omega} e^v \right) + \lambda(\log \lambda - 1) \\ L(u, v) &= \int_{\Omega} u(\log u - 1) + \frac{1}{2} \|\nabla v\|_2^2 - \langle v, u \rangle, \end{aligned}$$

it then holds that

$$\frac{1}{4} \frac{d}{dt} \|v\|_2^2 = -L(u, v) + \int_{\Omega} u(\log u - 1) - \frac{1}{2} uv \, dx = -\mathcal{J}_\lambda(v) + K(u, v)$$

with

$$\begin{aligned} K(u, v) &= \int_{\Omega} u(\log u - 1) - \frac{1}{2}uv \, dx \\ &\geq K \Big|_{u = \frac{\lambda e^{v/2}}{\int_{\Omega} e^{v/2}}} = -\lambda \log \int_{\Omega} e^{v/2} + \lambda(\log \lambda - 1); \end{aligned}$$

i.e.,

$$\frac{1}{4} \frac{d}{dt} \|v(\cdot, t)\|_2^2 \geq -\mathcal{J}_{\lambda}(v(\cdot, t)) - \lambda \log \left( \int_{\Omega} e^{v(\cdot, t)/2} \right) + \lambda(\log \lambda - 1).$$

In spite of

$$\frac{d}{dt} \mathcal{J}_{\lambda}(v(\cdot, t)) \leq 0,$$

the above inequality is not sufficient to guarantee  $T < +\infty$  because of the negativity of the second term of the right-hand side.

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