

# Characterization of States of Infinite Boson Systems

## II. On the Existence of the Conditional Reduced Density Matrix

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Received February 10, 1990; in revised form October 1, 1990

**Abstract.** In the present paper we deal with the problem of existence and uniqueness of the conditional reduced density matrix (c.r.d.m.) corresponding to a locally normal state of a boson system. The c.r.d.m. was introduced in [3] (Part I of the present series of papers). In order to characterize the class of states possessing a c.r.d.m. we will introduce the family of conditional states of a locally normal state, and we will discuss the relation between the conditional states, the c.r.d.m. and the conditional distribution of the position distribution of the state.

### 1. Introduction

In [2, 3] we introduced the position distribution  $Q_\omega$  and the conditional reduced density matrix  $k_\omega$  (c.r.d.m.) of a locally normal state  $\omega$  of a boson system. It was shown that  $Q_\omega$  and  $k_\omega$  determine the whole state. In the present paper we will characterize a class of states which possess a c.r.d.m. For that reason we first will introduce the notion of conditional states  $\omega_A^\varphi$  of a state  $\omega$  that describe the behaviour of the system inside a bounded region  $A$  having fixed a configuration  $\varphi$  outside this area. It is shown that the position distribution of the conditional state  $\omega_A^\varphi$  is just the conditional distribution  $Q_\omega(\cdot|_A, \mathfrak{M})(\varphi)$  of the position distribution  $Q_\omega$ .

Further, we will see that the c.r.d.m. exists if for each  $A \in \mathfrak{B}$  the family  $(\omega_A^\varphi)$  of conditional states exists and if  $Q_\omega$  is  $\Sigma'_\nu$ -point process. Moreover, we will prove that the c.r.d.m. is a.e.-uniquely determined.

We use the notations and notions given in Part I [3]. We refer to this part by adding I, e.g. I.2.1 means Sect. 2.1 in [3].

As in the previous papers we consider exclusively locally normal states of bosons without spin. The phase space  $G$  is assumed to be Polish endowed with a locally finite diffuse measure  $\nu$ , and the local algebras consist of all bounded linear operators on the Fock space over the bounded regions of the Fock space  $G$ .

**2. The Results**

The idea to describe the infinite system by its behaviour in bounded areas led in quantum statistical mechanics to the introductions of the notion of quasilocal algebras. If one restricts measurements to a bounded region one “forgets” all information about the behaviour outside this set. In analogy to the concept of conditional distributions in probability theory (especially in the classical theory of Gibbs measures) we want to introduce now the conditional states  $\omega_A^\varphi$  of a locally normal state  $\omega$  that describe the behaviour of the system in  $A \in \mathfrak{B}$  having fixed a configuration  $\varphi \in M_{A^c}$  (outside of  $A$ ). For basic notations used below cf I.2–I.7.

First, we need a measurability condition for families of states. With respect to further considerations (in Sect. 3) the definition will be slightly more general than needed in this section.

*2.1. Definition.* Let  $\tilde{\mathcal{A}}$  be a  $*$ -subalgebra of  $\mathcal{L}(\mathcal{M})$  and  $\mathfrak{M}$  a  $\sigma$ -subalgebra of  $\mathfrak{M}$ . A family  $(\xi_\varphi^\varphi)_{\varphi \in M}$  of positive linear functionals on  $\tilde{\mathcal{A}}$  is called  $\mathfrak{M}$ -measurable if for all  $A \in \tilde{\mathcal{A}}, A \geq 0$  the mapping  $\varphi \mapsto \xi_\varphi^\varphi(A)$  from  $M$  into  $[0, \infty)$  is a  $\mathfrak{M}$ -measurable function.

*2.2. Definition.* Let  $Q$  be a point process, and let  $(\xi_1^\varphi)_{\varphi \in M}$  and  $(\xi_2^\varphi)_{\varphi \in M}$  be two  $\mathfrak{M}$ -measurable families of positive linear functionals on  $\tilde{\mathcal{A}}$ . We say that  $(\xi_1^\varphi)_{\varphi \in M} = (\xi_2^\varphi)_{\varphi \in M}$   $Q$ -a.s. if for all  $A \in \tilde{\mathcal{A}} \xi_1^\varphi(A) = \xi_2^\varphi(A)$  for  $Q$ -a.a.  $\varphi$ .

Now, for arbitrary  $A \in \mathfrak{B}$  we set

$${}_A\mathfrak{M}^\perp := \bigcup_{\substack{A' \in \mathfrak{B} \\ A \cap A' = \emptyset}} {}_{A'}\mathfrak{M}, \quad {}_A\mathfrak{M} := \bigcup_{A \in \mathfrak{B}} {}_A\mathfrak{M}. \tag{2.1}$$

Observe that

$${}_A\mathfrak{M}^\perp = {}_{A^c}\mathfrak{M} \cap {}_A\mathfrak{M} \quad (\neq {}_{A^c}\mathfrak{M}).$$

*2.3. Definition.* Let  $\omega$  be a locally normal state on  $\mathcal{A}$ , and let  $A \in \mathfrak{B}$ . A  ${}_A\mathfrak{M}$ -measurable family  $({}_A\omega^\varphi)_{\varphi \in M}$  of states on  ${}_A\mathcal{A}$  is called the *family of conditional states of  $\omega$  on  $A$*  if for all  $A \in {}_A\mathcal{A}$  and  $Y \in {}_A\mathfrak{M}^\perp$

$$\omega(AO_Y) = \int_Y Q_\omega(d\varphi) {}_A\omega^\varphi(A). \tag{2.2}$$

The left side of (2.2) is always well-defined, and we have the following useful relation:

**2.4. Lemma.** Let  $A, A' \in \mathfrak{B}, A \cap A' = \emptyset, A \in {}_A\mathcal{A}, Y \in {}_{A'}\mathfrak{M}$ . Then  $AO_Y \in {}_{A \cup A'}\mathcal{A}$ , and we have

$$AO_Y = S(Y \cap M_{A^c}, O_{M_A} AO_{M_A}). \tag{2.3}$$

*2.5. Remark.*  $AO_Y$  is a combination of the local observable  $A$  (from  ${}_A\mathcal{A}$ ) with a position measurement outside  $A$  ( $Y \in {}_{A'}\mathfrak{M}, A' \cap A = \emptyset$ ). So (2.2) allows an interpretation of  ${}_A\omega^\varphi$  as the conditional state in  $A$  having fixed the configuration  $\varphi$  outside.

**2.6. Proposition.** Let  $\omega$  be a locally normal state,  $A \in \mathfrak{B}$  and assume the family  $({}_A\omega^\varphi)_{\varphi \in M}$  of conditional states exists. Then we have the following:

- (i)  $({}_A\omega^\varphi)_{\varphi \in M}$  is  $Q_\omega$ -a.s. uniquely determined.
- (ii) For  $Q_\omega$ -a.a.  $\varphi$   ${}_A\omega^\varphi$  is a normal state on  ${}_A\mathcal{A}$ .

We thus have that not only the local states  ${}_A\omega$  given by

$${}_A\omega(A) = \omega(A) \quad (A \in \mathcal{A}_A)$$

are normal ones (by definition) but also the conditional states provided they exist. Observe that by

$$\omega_A^\varphi(A) := {}_A\omega^\varphi(J_A A) \quad (A \in \mathcal{A}_A) \tag{2.4}$$

we may define an (equivalent) family of normal states on  $\mathcal{A}_A$ , and (2.2) could be written also in the form

$$\omega(O_Y J_A A) = \int_Y Q_\omega(d\varphi) \omega_A^\varphi(A). \tag{2.5}$$

In [2] we proved that the position distribution of a locally normal state is locally a  $\Sigma'_v$ -point process. If the conditional states exist still more is true.

**2.7. Proposition.** *Let  $\omega$  be a locally normal state on  $\mathcal{A}$  such that for all  $A \in \mathfrak{B}$  the family  $({}_A\omega^\varphi)_{\varphi \in M}$  of conditional states exists. Then  $Q_\omega$  is a  $\Sigma'_v$ -point process.*

The proof of the above statement is based on the observation that the position distribution of the conditional state  ${}_A\omega^\varphi$  is just the conditional distribution of the position distribution of  $\omega$ . Indeed, we have the following connection.

**2.8. Proposition.** *Let  $\omega$  be a locally normal state on  $\mathcal{A}$  such that for a set  $A \in \mathfrak{B}$  the family  $({}_A\omega^\varphi)_{\varphi \in M}$  of conditional states exists. Then for  $Q_\omega$ -a.a.  $\varphi$  we have*

$${}_A\omega^\varphi(O_Y) = Q_\omega(Y | {}_A c \mathfrak{M})(\varphi) \quad (Y \in {}_A \mathfrak{M}). \tag{2.6}$$

In Part I of this series we always assumed that  $Q_\omega$  is a  $\Sigma'_v$ -point process. There are some hints for the conjecture that all conditional states exist if  $Q_\omega$  is of the type  $\Sigma'_v$ . However, this could be shown only for normal states.

**2.9. Proposition.** *Let  $\omega$  be a normal state on  $\mathcal{L}(\mathcal{M})$  such that  $Q_\omega$  is a  $\Sigma'_v$ -point process. Then for all  $A \in \mathfrak{B}$  the family  $({}_A\omega^\varphi)_{\varphi \in M}$  of conditional states of  $\omega$  on  $A$  exists.*

In I we introduce the c.r.d.m. and showed that it is a useful tool for the characterization and for the description of the state. States possessing all conditional states are just the states having a c.r.d.m.

**2.10. Theorem.** *Let  $\omega$  be a locally normal state on  $\mathcal{A}$  such that  $Q_\omega$  is a  $\Sigma'_v$ -point process. Then the c.r.d.m. of  $\omega$  exists if and only if for all  $A \in \mathfrak{B}$  the family  $({}_A\omega^\varphi)_{\varphi \in M}$  of conditional states exists.*

In Theorem I.7.3 we gave sufficient conditions on a point process  $Q$  and a function  $k$  ensuring the existence of a (unique) locally normal state  $\omega$  with position distribution  $Q$  and c.r.d.m.  $k$ . From Theorem 2.10 we thus obtain that for the state constructed from  $Q$  and  $k$  all conditional states exist, and we have the following relation:

**2.11. Proposition.** *Let  $\omega$  be a locally normal state on  $\mathcal{A}$  such that  $Q_\omega$  is a  $\Sigma'_v$ -point process and the c.r.d.m.  $k$  exists. Then for all  $A \in \mathfrak{B}$  and  $Q_\omega$ -a.a.  $\varphi$*

$${}_A\omega^\varphi(J_A A) = \frac{1}{\eta_{Q_\omega}^{\varphi, A^c}(M_A)} \text{Tr}(K_A^{\varphi, A^c} A) \quad (A \in \mathcal{A}_A), \tag{2.7}$$

where  $K_A^{\varphi, A^c}$  is the positive trace-class operator with kernel  $k(\cdot, \cdot, \varphi_{A^c})$ .

From the proofs of the above statements we get also that the c.r.d.m. is a.e.-uniquely determined (for normal states this was shown already in I – cf. Theorem I.6.4).

**2.12. Proposition.** *Let  $\omega$  be a locally normal state on  $\mathcal{A}$  such that the position distribution  $Q_\omega$  is a  $\Sigma'_v$ -point process, and let  $k_1, k_2$  be two c.r.d.m. of  $\omega$ . Then for  $F \times F \times Q_\omega$ -a.a.  $(\varphi_1, \varphi_2, \varphi)$  we have  $k_1(\varphi_1, \varphi_2, \varphi) = k_2(\varphi_1, \varphi_2, \varphi)$ .*

It seems to be obvious that a locally normal state is a normal one if (and only if)  $Q_\omega$  is a finite point process. However, based on the above result we can show it only for states possessing a c.r.d.m.

**2.13. Proposition.** *Let  $\omega$  be a locally normal state such that  $Q_\omega$  is a  $\Sigma'_v$ -point process and the c.r.d.m. exists. Then  $\omega$  is a normal state if and only if  $Q_\omega$  is a finite point process.*

Summarizing, we can give the following characterization:

**2.14. Proposition.** *Let  $\omega_1, \omega_2$  be locally normal states such that  $Q_{\omega_1}$  and  $Q_{\omega_2}$  are  $\Sigma'_v$ -point processes and the c.r.d.m.  $k_{\omega_1}, k_{\omega_2}$  exist. The following statements are equivalent:*

- (i)  $\omega_1 = \omega_2$ ,
- (ii)  $Q_{\omega_1} = Q_{\omega_2}$  and  $k_{\omega_1} = k_{\omega_2}$  a.e.

### 3. Proofs

#### 3.1. Proof of Lemma 2.4

Observe that  $A \in {}_A\mathcal{A} \subseteq {}_{A \cup A'}\mathcal{A}$ ,  $Y \in {}_A\mathfrak{M} \subseteq {}_{A \cup A'}\mathfrak{M}$ . Thus  $AO_Y \in {}_{A \cup A'}\mathcal{A}$ . For all  $\Psi \in \mathcal{M}$ ,  $\varphi \in M$  we get

$$\begin{aligned} & S(Y \cap M_{A^c}, O_{M_A} A O_{M_A}) \Psi(\varphi) \\ &= \sum_{\hat{\phi} \subseteq \varphi} \chi_{Y \cap M_{A^c}}(\hat{\phi}) \chi_{M_A}(\varphi - \hat{\phi}) (A O_{M_A} \Psi_{\hat{\phi}})(\varphi - \hat{\phi}) \\ &= \sum_{\hat{\phi} \subseteq \varphi_A} \chi_{Y \cap M_{A^c}}(\hat{\phi} + \varphi_{A^c}) (A O_{M_A} \Psi_{\hat{\phi} + \varphi_{A^c}})(\varphi_A - \hat{\phi}) \\ &= \chi_{Y \cap M_{A^c}}(\varphi_{A^c}) (A O_{M_A} \Psi_{\varphi_{A^c}})(\varphi_A) = \chi_Y(\varphi) (A O_{M_A} \Psi_{\varphi_{A^c}})(\varphi_A) \\ &= O_Y A \Psi(\varphi). \quad \square \end{aligned} \tag{3.1}$$

#### 3.2. Proof of Proposition 2.6

1°. We fix an  $A \in {}_A\mathcal{A}$ ,  $A \geq 0$ . Suppose there are given two versions  $(\omega_j^\varphi)_{\varphi \in M}$ ,  $j = 1, 2$  of conditional states of  $\omega$  on  $\mathcal{A}_A$ .

We thus get for all  $Y \in {}_A\mathfrak{M}^\perp$

$$\int_Y Q_\omega(d\varphi) \omega_1^\varphi(A) = \int_Y Q_\omega(d\varphi) \omega_2^\varphi(A). \tag{3.2}$$

Since  ${}_A\mathfrak{M}^\perp \subseteq {}_{A^c}\mathfrak{M}$  and for each  $Y \in {}_{A^c}\mathfrak{M}$  there exists an increasing sequence  $(Y_n) \subseteq {}_A\mathfrak{M}^\perp$  with  $\lim_{n \rightarrow \infty} Y_n = Y$  (3.2) holds for all  $Y \in {}_{A^c}\mathfrak{M}$ .

The mapping  $\varphi \mapsto \omega_j^\varphi(A)$  was assumed to be  ${}_{A^c}\mathfrak{M}$ -measurable. This implies  $\omega_1^\varphi(A) = \omega_2^\varphi(A)$  for  $Q_\omega$ -a.a.  $\varphi$ . Since each operator from  ${}_A\mathcal{A}$  may be expressed in a unique way as a sum  $A_1 - A_2 + iA_3 - iA_4$  of four positive operators from  ${}_A\mathcal{A}$  we

get for all  $A \in \mathcal{A}$   $\omega_1^\varphi(A) = \omega_2^\varphi(A)$  for  $Q_\omega$ -a.a.  $\varphi$ . This proves assertion (i) of Proposition 2.6.

2°.  ${}_A\omega^\varphi$  is a normal state on  $\mathcal{A}$  if and only if  $\omega_A^\varphi$  defined by (2.4) is a normal state on  $\mathcal{A}_A$ . It is known that a state on  $\mathcal{A}_A$  is normal if it achieves its norm already on compact operators from  $\mathcal{A}_A$  (cf. [1, Theorem 2.6.14]), i.e. we have to prove that for  $Q_\omega$ -a.a.  $\varphi$

$$\sup\{\|\omega_A^\varphi(A)\|: A \in \mathcal{A}_A, A \text{ compact}, \|A\| = 1\} = 1. \tag{3.3}$$

Consequently, it suffices to show that there exists a sequence  $(A_n)_{n \geq 0}$  of compact operators from  $\mathcal{A}_A$  with  $\|A_n\| = 1$  such that for  $Q_\omega$ -a.a.  $\varphi$   $\lim_{n \rightarrow \infty} \omega_A^\varphi(A_n) = 1$ .

Let  $(\Psi_n)_{n \geq 0}$  be an orthonormal base in  $\mathcal{M}_A$  and denote by  $A_n$  the (finite rank) projector onto the span of  $\{\Psi_0, \dots, \Psi_n\}$ ,  $n \geq 0$ . We have  $\|A_n\| = 1$ ,  $0 \leq A_n \leq A_{n+1} \leq O_{\mathcal{M}_A}$  for all  $n \geq 0$ . Thus the limit  $\lim_{n \rightarrow \infty} \omega_A^\varphi(A_n)$  exists for all  $\varphi$  and we have

$$0 \leq \lim_{n \rightarrow \infty} \omega_A^\varphi(A_n) \leq 1. \tag{3.4}$$

$(A_n)_{n \geq 0}$  converges to  $O_{\mathcal{M}_A}$  in the  $\sigma$ -weak topology on  $\mathcal{A}_A$ . So  $((J_A A_n)O_Y)_{n \geq 0}$  converges  $\sigma$ -weakly in  $\mathcal{L}(\mathcal{M})$  to  $O_Y$  for all  $Y \in \mathfrak{M}$ . Since the local states are continuous in the  $\sigma$ -weak topology we get for each  $Y \in {}_A\mathfrak{M}^\perp$ ,

$$\lim_{n \rightarrow \infty} \omega((J_A A_n)O_Y) = \omega(O_Y) = Q_\omega(Y). \tag{3.5}$$

Using Lebesgue's dominated convergence theorem which can be applied because of (3.4) we obtain for all  $Y \in {}_A\mathfrak{M}^\perp$

$$\begin{aligned} Q_\omega(Y) &= \lim_{n \rightarrow \infty} \int_Y Q_\omega(d\varphi) {}_A\omega^\varphi(J_A A_n) = \lim_{n \rightarrow \infty} \int_Y Q_\omega(d\varphi) \omega_A^\varphi(A_n) \\ &= \int_Y Q_\omega(d\varphi) \lim_{n \rightarrow \infty} \omega_A^\varphi(A_n) = \int_Y Q_\omega(d\varphi) \cdot 1. \end{aligned}$$

Since  $({}_A\omega^\varphi)_{\varphi \in \mathfrak{M}}$  was assumed to be  ${}_A\mathfrak{M}$ -measurable we finally get that for  $Q_\omega$ -a.a.  $\varphi$   $\lim_{n \rightarrow \infty} \omega_A^\varphi(A_n) = 1$ . Thus, for  $Q_\omega$ -a.a.  $\varphi$   $\omega_A^\varphi$  is a normal state on  $\mathcal{A}_A$ , i.e.  ${}_A\omega^\varphi$  is a normal one on  $\mathcal{A}$ .  $\square$

### 3.3. Proof of Proposition 2.8

For all  $Y_1 \in {}_A\mathfrak{M}$ ,  $Y_2 \in {}_A\mathfrak{M}^\perp$  we get from the definition of the conditional state

$$\omega(O_{Y_1}O_{Y_2}) = \int_{Y_2} Q_\omega(d\varphi) {}_A\omega^\varphi(O_{Y_1}). \tag{3.6}$$

On the other side, from  $O_{Y_1}O_{Y_2} = O_{Y_1 \cap Y_2}$  we conclude

$$\omega(O_{Y_1}O_{Y_2}) = \omega(O_{Y_1 \cap Y_2}) = Q_\omega(Y_1 \cap Y_2). \tag{3.7}$$

(3.6) and (3.7) lead to the relation

$$\int_{Y_2} Q_\omega(d\varphi) \chi_{Y_1}(\varphi) = \int_{Y_2} Q_\omega(d\varphi) {}_A\omega^\varphi(O_{Y_1}) \quad (Y_1 \in {}_A\mathfrak{M}, Y_2 \in {}_A\mathfrak{M}^\perp). \tag{3.8}$$

As in the first part of the proof of Proposition 2.6 one can see that the equality in (3.8) holds for all  $Y_2 \in {}_A\mathfrak{M}$ . Since  $\varphi \mapsto {}_A\omega^\varphi(O_{Y_1})$  is  ${}_A\mathfrak{M}$ -measurable we get that for all  $Y \in {}_A\mathfrak{M}$

$${}_A\omega^\varphi(O_Y) = Q_\omega(Y|{}_A\mathfrak{M})(\varphi) \quad (Q_\omega\text{-a.a. } \varphi). \quad \square \tag{3.9}$$

3.4. Proof of Proposition 2.7

We fix a set  $A \in \mathfrak{B}$ . From Proposition 2.6 we know that for  $Q_\omega$ -a.a.  $\varphi$   $\omega_A^\varphi$  [defined by (2.4)] is a normal state on  $\mathcal{A}_A$ . This implies that the position distribution of  $\omega_A^\varphi$  (which we will denote by  $Q_A^\varphi$ ) is a finite  $\Sigma_A^c$ -point process concentrated on  $M_A$  (cf. [2, Proposition 3.1]). The  $A^c$ - $\mathfrak{M}$ -measurability of  $(\omega_A^\varphi)_{\varphi \in M}$  causes that for  $Q_\omega$ -a.a.  $\varphi$   $Q_A^\varphi = Q_{A^c}^\varphi$ .

From [6, Theorem 2.13] we conclude that for all  $\varphi \in M_{A^c}$  there exists a measurable function  $g_{A,\varphi}: M \rightarrow \mathbb{R}$  such that

$$Q_A^\varphi(Y) = \int_Y F_A(d\hat{\phi}) g_{A,\varphi}(\hat{\phi}) \quad (Y \in \mathfrak{M}_A). \tag{3.10}$$

From Proposition 2.8 and (3.10) we finally get that for all  $A \in \mathfrak{B}$ ,  $Y \in A^c \mathfrak{M}$  and  $Q_\omega$ -a.a.  $\varphi$ ,

$$\begin{aligned} Q_\omega(Y|_{A^c \mathfrak{M}})(\varphi) &= \omega_A^\varphi(O_Y) = \omega_A^\varphi(O_{v_{A^c} Y}) = Q_A^\varphi(v_A Y) \\ &= \int_{v_A Y} F_A(d\hat{\phi}) g_{A,\varphi_{A^c}}(\hat{\phi}). \end{aligned} \tag{3.11}$$

Condition (3.11) is necessary and sufficient for  $Q_\omega$  to be a  $\Sigma_A^c$ -point process [5, Theorem 2.11].  $\square$

3.5. Proof of Proposition 2.9

There exists an orthonormal sequence  $(\Psi^n)_{n \geq 0}$  from  $\mathcal{M}$  and a sequence  $(\alpha_n)_{n \geq 0}$ ,  $\alpha_n \geq 0$ ,  $\sum_{n=0}^\infty \alpha_n = 1$  such that

$$\omega(A) = \text{Tr}(\varrho A) \quad (A \in \mathcal{L}(\mathcal{M})),$$

where  $\varrho$  is a density matrix given by

$$\varrho = \sum_{n=0}^\infty \alpha_n (\Psi^n, \cdot) \Psi^n, \tag{3.12}$$

and  $Q_\omega$  can be written in the form

$$Q_\omega(Y) = \int_Y F(d\varphi) D(\varphi) \quad (Y \in \mathfrak{M})$$

with

$$D(\varphi) = \sum_{n=0}^\infty \alpha_n |\Psi^n(\varphi)|^2 \quad (\varphi \in M). \tag{3.13}$$

One easily shows that (if  $Q_\omega$  is of the type  $\Sigma_A^c$ ) the density  $D(\varphi)$  has the property that

$$D(\varphi + \hat{\phi}) > 0 \text{ implies } D(\varphi) > 0 \quad (F \times F\text{-a.a. } (\varphi, \hat{\phi})) \tag{3.14}$$

and the conditional intensity measure  $\eta_{Q_\omega}^\varphi$  of  $Q_\omega$  is given by

$$\eta_{Q_\omega}^\varphi(Y) = \int_Y F(d\hat{\phi}) \frac{D(\varphi + \hat{\phi})}{D(\varphi)}. \tag{3.15}$$

For all  $A \in \mathfrak{B}$  and all  $\varphi \in M$  we set

$${}_A\omega^\varphi(A) = \frac{1}{\eta_{Q_\omega}^{\varphi, A^c}(M_A)D(\varphi_{A^c})} \sum_{n=0}^\infty \alpha_n(\Psi_{\varphi_{A^c}}^n, O_{M_A} A O_{M_A} \Psi_{\varphi_{A^c}}^n) \quad (A \in {}_A\mathcal{A}). \quad (3.16)$$

The right side of (3.16) is well-defined because for each  $\Psi \in \mathcal{M}$ ,  $\chi_{M_A} \Psi_{\varphi_{A^c}} \in \mathcal{M}_A$  (Lemma I.2.7) and

$$\begin{aligned} \sum_{n=0}^\infty (\Psi_{\varphi_{A^c}}^n, O_{M_A} \mathbf{1} O_{M_A} \Psi_{\varphi_{A^c}}^n) &= \int_{M_A} F(d\hat{\phi}) D(\hat{\phi} + \varphi_{A^c}) \\ &= \eta_{Q_\omega}^{\varphi, A^c}(M_A) D(\varphi_{A^c}). \end{aligned} \quad (3.17)$$

Since for  $Q_\omega$ -a.a.  $\varphi$   $0 < \eta_{Q_\omega}^{\varphi, A^c}(M_A) < \infty$  from (3.16) and (3.17) we get that  $({}_A\omega^\varphi)_{\varphi \in M}$  is a  ${}_A\mathcal{M}$ -measurable family of states.

Finally, for all  $A \in \mathfrak{B}$ ,  $A \in {}_A\mathcal{A}$ , and  $Y \in {}_A\mathfrak{M}^\perp$  we get using Lemma I.2.5 and the fact that  $Y \in {}_A\mathcal{M}$ ,

$$\begin{aligned} &\int_Y Q_\omega(d\varphi) {}_A\omega^\varphi(A) \\ &= \int_{Y \cap {}_A\mathcal{M}^c} Q_\omega(d\varphi) \eta_{Q_\omega}^{\varphi, A^c}(M_A) {}_A\omega^\varphi(A) \\ &= \int_{Y \cap {}_A\mathcal{M}^c} F(d\varphi) \eta_{Q_\omega}^{\varphi, A^c}(M_A) D(\varphi) {}_A\omega^\varphi(A) \\ &= \int_{Y \cap {}_A\mathcal{M}^c} F(d\varphi) \sum_{n=0}^\infty \alpha_n(\Psi_\varphi^n, O_{M_A} A O_{M_A} \Psi_\varphi^n) \\ &= \int_{M_{A^c}} F(d\varphi) \int_{M_A} F(d\varphi_1) \chi_Y(\varphi) \sum_{n=0}^\infty \alpha_n(\overline{\Psi_\varphi^n(\varphi_1)} O_{M_A} A O_{M_A} \Psi_\varphi^n(\varphi_1)) \\ &= \int F(d\varphi) \chi_Y(\varphi_{A^c}) \sum_{n=0}^\infty \alpha_n(\overline{\Psi_{\varphi_{A^c}}^n(\varphi_A)} O_{M_A} A O_{M_A} \Psi_{\varphi_{A^c}}^n(\varphi_A)) \\ &= \int F(d\varphi) \chi_Y(\varphi) \sum_{n=0}^\infty \alpha_n(\overline{\Psi^n(\varphi)} A \Psi^n(\varphi)) = \sum_{n=0}^\infty \alpha_n(\Psi^n, O_Y A \Psi^n) \\ &= \omega(AO_Y). \quad \square \end{aligned}$$

### 3.6. Proof of Theorem 2.10

1°. We first assume that for each  $A \in \mathfrak{B}$  the family  $({}_A\omega^\varphi)_{\varphi \in M}$  of conditional states exists. From Proposition 2.6 we have that for all  $A \in \mathfrak{B}$  and  $Q_\omega$ -a.a.  $\varphi$   ${}_A\omega^\varphi$  is a normal state on  ${}_A\mathcal{A}$ . Thus  $\omega_A^\varphi$  defined by (2.4) is a normal state on  $\mathcal{A}_A$ . Now, we fix a set  $A \in \mathfrak{B}$ . Without loss of generality we may assume that  $\omega_A^\varphi$  is a normal state for all  $\varphi \in M$ . Since  $({}_A\omega^\varphi)_{\varphi \in M}$  is assumed to be  ${}_A\mathcal{M}$ -measurable we have, of course,  $\omega_A^\varphi = \omega_A^{\varphi_{A^c}}$  for all  $\varphi \in M$ . Denote by  $Q_A^\varphi$  the position distribution of  $\omega_A^\varphi$ .  $Q_A^\varphi$  is a finite  $\Sigma'_v$ -point process on  $[M_A, \mathfrak{M}_A]$  [2, Proposition 3.1]. We will show that  $Q_A^\varphi$  is even a  $\Sigma'_v$ -point process. Indeed, from Proposition 2.8 and Lemma I.5.3(iii) we obtain for all  $Y \in \mathfrak{M}_A$  and all  $\varphi \in M$ ,

$$\begin{aligned} Q_A^\varphi(Y) &= \omega_A^\varphi(O_Y) = {}_A\omega^\varphi(v_A^{-1} Y) = Q_\omega(v_A^{-1} Y \mid {}_A\mathcal{M})(\varphi) \\ &= (\eta_{Q_\omega}^{\varphi, A^c}(M_A))^{-1} \eta_{Q_\omega}^{\varphi, A^c}(Y) \\ &= (\eta_{Q_\omega}^{\varphi, A^c}(M_A))^{-1} \int_Y F_A(d\hat{\phi}) \kappa(\hat{\phi}, \varphi_{A^c}), \end{aligned} \quad (3.18)$$

where  $\kappa$  is a version of  $dC_{Q_\omega}^{(\infty)}/d(F \times Q_\omega)$ .

For all  $A' \in \mathfrak{B} \cap \mathcal{A}$ ,  $Y \in \mathfrak{M}_A$ , and  $\varphi \in M$  we get

$$\begin{aligned}
 C_{Q_A}^{(1)}(A' \times Y) &= \int Q_A^{\omega}(d\hat{\varphi}) \int_{A'} \hat{\varphi}(dx) \chi_Y(\hat{\varphi} - \delta_x) \\
 &= (\eta_{Q_{\omega}^{A^c}}^{\varphi}(M_A))^{-1} \sum_{n=1}^{\infty} \frac{1}{n!} \int_{A^n} v^n(d\underline{x}^n) \kappa(\delta_{\underline{x}^n}, \varphi_{A^c}) \\
 &\quad \times \sum_{j=1}^n \chi_{A'}(x_j) \chi_Y(\delta_{\underline{x}^n} - \delta_{x_j}) \\
 &= (\eta_{Q_{\omega}^{A^c}}^{\varphi}(M_A))^{-1} \sum_{n=1}^{\infty} \frac{1}{(n-1)!} \int_{A^{n-1}} v^{n-1}(d\underline{x}^{n-1}) \\
 &\quad \times \int_{A'} v(dx) \chi_Y(\delta_{\underline{x}^{n-1}}) \kappa(\delta_{\underline{x}^{n-1}} + \delta_x, \varphi_{A^c}) \\
 &= (\eta_{Q_{\omega}^{A^c}}^{\varphi}(M_A))^{-1} \int_Y F_A(d\hat{\varphi}) \int_{A'} v(dx) \kappa(\hat{\varphi} + \delta_x, \varphi_{A^c}). \tag{3.19}
 \end{aligned}$$

Since  $Q_{\omega}$  is a  $\Sigma'_v$ -point process we have

$$\kappa(\varphi_1 + \varphi_2, \varphi) = \kappa(\varphi_1, \varphi) \kappa(\varphi_2, \varphi + \varphi_1) \quad (F \times F \times Q_{\omega} \text{ -a.a. } (\varphi_1, \varphi_2, \varphi))$$

(cf. [4, Chap. 9] or also (6.10) in I). Thus we may continue (3.19)

$$\begin{aligned}
 C_{Q_A}^{(1)}(A' \times Y) &= (\eta_{Q_{\omega}^{A^c}}^{\varphi}(M_A))^{-1} \int_Y F_A(d\hat{\varphi}) \kappa(\hat{\varphi}, \varphi_{A^c}) \\
 &\quad \times \int_{A'} v(dx) \kappa(\delta_x, \hat{\varphi} + \varphi_{A^c}) \\
 &= \int_Y Q_A^{\omega}(d\hat{\varphi}) \int_{A'} v(dx) \kappa(\delta_x, \hat{\varphi} + \varphi_{A^c}).
 \end{aligned}$$

This proves that  $C_{Q_A}^{(1)} \ll v \times Q_A^{\omega}$  and

$$\frac{dC_{Q_A}^{(1)}}{d(v \times Q_A^{\omega})}(x, \hat{\varphi}) = \frac{dC_{Q_{\omega}}^{(1)}}{d(v \times Q_{\omega})}(x, \hat{\varphi} + \varphi_{A^c}) \quad (x \in A, \hat{\varphi} \in M_A). \tag{3.20}$$

From (3.20) we easily get that for all  $A \in \mathfrak{B}$ ,  $\varphi \in M$ ,

$$\frac{dC_{Q_A}^{(\omega)}}{d(F_A \times Q_A^{\omega})}(\varphi_1, \varphi_2) = \frac{d\eta_{Q_A}^{\varphi_2, \varphi}}{dF_A}(\varphi_1) = \kappa(\varphi_1, \varphi + \varphi_{A^c}) \quad (\varphi_1, \varphi_2 \in M_A). \tag{3.21}$$

2°. Above we thus have shown that for all  $A \in \mathfrak{B}$  and all  $\varphi \in M$   $\omega_A^{\varphi}$  is a normal  $\Sigma'_v$ -state on  $\mathcal{A}_A$ . Applying Theorem I.6.4 we obtain that there exists the (a.e. uniquely determined) c.r.d.m.  $k_A^{\varphi}$  of  $\omega_A^{\varphi}$  having the following properties:

For all  $Y \in \mathfrak{M}_A$  and integral operators  $A \in \mathcal{A}_A$  such that  $S_A(Y, A) \in \mathcal{A}_A$  we have

$$\omega_A^{\varphi}(S_A(Y, A)) = \int_Y Q_A^{\omega}(d\varphi_1) \int F_A(d\varphi_2) k_A^{\varphi} * k_A^{\varphi}(\varphi_2, \varphi_1) \tag{3.22}$$

and for  $F_A \times Q_A^{\omega}$ -a.a.  $(\varphi_1, \varphi_2)$ ,

$$k_A^{\varphi}(\varphi_1, \varphi_1, \varphi_2) = \kappa(\varphi_1, \varphi_2 + \varphi_{A^c}). \tag{3.23}$$

Now, for all  $A \in \mathfrak{B}$  we put

$$k_A(\varphi_1, \varphi_2, \varphi) = k_A^{\varphi, A^c}(\varphi_1, \varphi_2, \varphi) \quad (\varphi_1, \varphi_2 \in M_A, \varphi \in M). \tag{3.24}$$

We will show now that for all  $A, A' \in \mathfrak{B}$   $A \subseteq A'$  one has

$$k_A(\varphi_1, \varphi_2, \varphi) = k_{A'}(\varphi_1, \varphi_2, \varphi) \quad (F_A \times F_{A'} \times Q_{\omega} \text{ -a.a. } (\varphi_1, \varphi_2, \varphi)).$$

We fix  $A, A' \in \mathfrak{B}$ ,  $A \subseteq A'$ . Let  $Y_1 \in {}_A\mathfrak{M}^f$ ,  $Y_2 \in {}_{A' \setminus A}\mathfrak{M}^f$ ,  $Y_3 \in {}_{A'}\mathfrak{M}^\perp$ . Then  $Y_1 \cap Y_2 \in {}_{A'}\mathfrak{M}^f$ , and for all integral operators  $A \in \mathcal{A}_A^f$  ( $\subseteq \mathcal{A}_{A'}^f$ ) we have  $S(Y_1 \cap Y_2, A) \in {}_{A'}\mathcal{A}$  (Proposition I.3.4) and consequently we get using (3.22),

$$\begin{aligned}
 &\omega(S(Y_1 \cap Y_2, A)O_{Y_3}) \\
 &= \int_{Y_3} Q_\omega(d\varphi) \omega_A^{\varphi}(S_{A'}(v_{A'}(Y_1 \cap Y_2), A)) \\
 &= \int_{Y_3} Q_\omega(d\varphi) \int_{v_{A'}(Y_1 \cap Y_2)} Q_A^{\varphi}(d\varphi_1) \int F_{A'}(d\varphi_2) k_A * k_A^{\varphi}(\varphi_2, \varphi_1) \\
 &= \int_{Y_3} Q_\omega(d\varphi) \int_{v_{A'}(Y_1 \cap Y_2)} F_{A'}(d\varphi_1) \kappa(\varphi_1, \varphi_{A'^c}) \frac{1}{\eta_{Q_\omega}^{\varphi(A')^c}(M_{A'})} \\
 &\quad \times \int F_A(d\varphi_2) k_A * k_A^{\varphi}(\varphi_2, \varphi_1) \\
 &= \int_{v_{A'} \circ Y_3} Q_\omega(d\varphi) \int_{v_{A'}(Y_1 \cap Y_2)} F_{A'}(d\varphi_1) \kappa(\varphi_1, \varphi) \\
 &\quad \times \int F_A(d\varphi_2) k_A * k_A^{\varphi}(\varphi_2, \varphi_1) \\
 &= \int_{Y_1 \cap Y_2 \cap Y_3} Q_\omega(d\varphi) \int F_A(d\varphi_2) k_A * k_A^{\varphi(A')^c}(\varphi_2, \varphi_{A'}) \\
 &= \int_{Y_1 \cap Y_2 \cap Y_3} Q_\omega(d\varphi) \int F_A(d\varphi_2) k_A * k_A(\varphi_2, \varphi). \tag{3.26}
 \end{aligned}$$

On the other side, it is easy to check that

$$S(Y_1 \cap Y_2, A) = S(Y_1, A)O_{Y_2}.$$

Consequently, we get  $(S(Y_1, A) \in {}_{A'}\mathcal{A}$ ,  $O_{Y_1 \cap Y_3} \in {}_{A'}\mathfrak{M}^\perp$ )

$$\begin{aligned}
 \omega(S(Y_1 \cap Y_2, A)O_{Y_3}) &= \omega(S(Y_1, A)O_{Y_1 \cap Y_3}) \\
 &= \int_{Y_1 \cap Y_3} Q_\omega(d\varphi) \omega_A^{\varphi}(S_{A'}(v_A Y_1, A)) \\
 &= \int_{Y_1 \cap Y_3} Q_\omega(d\varphi) \int_{Y_2} Q_A^{\varphi}(d\varphi_1) \int F_A(d\varphi_2) k_A * k_A^{\varphi}(\varphi_2, \varphi_1) \\
 &= \int_{Y_1 \cap Y_2 \cap Y_3} Q_\omega(d\varphi) \int F_A(d\varphi_2) k_A * k_A^{\varphi(A')^c}(\varphi_2, \varphi_A) \\
 &= \int_{Y_1 \cap Y_2 \cap Y_3} Q_\omega(d\varphi) \int F_A(d\varphi_2) k_A * k_A(\varphi_2, \varphi). \tag{3.27}
 \end{aligned}$$

Since  ${}_A\mathfrak{M}^f \cap {}_{A' \setminus A}\mathfrak{M}^f \cap {}_{A'}\mathfrak{M}^\perp$  generate  $\mathfrak{M}$  and the integral operators from  $\mathcal{A}_A$  are dense in this space we conclude from (3.26) and (3.27) the relation (3.25). Now, we choose an increasing sequence  $(A_n)_{n \geq 0}$ ,  $A_n \in \mathfrak{B}$  such that  $\lim_{n \rightarrow \infty} A_n = G$ . For all  $\varphi_1, \varphi_2 \in M^f$  there exists an  $n_0 \in \mathbb{N}$  such that for all  $n \geq n_0$   $\varphi_1, \varphi_2 \in M_{A_n}$ . Thus, from (3.25) we get that

$$k_\omega(\varphi_1, \varphi_2, \varphi) = \lim_{n \rightarrow \infty} k_{A_n}(\varphi_1, \varphi_2, \varphi) \tag{3.28}$$

exists for  $F \times F \times Q_\omega$ -a.a.  $(\varphi_1, \varphi_2, \varphi)$ , and defines a measurable function from  $M^f \times M^f \times M$  into  $\mathbb{C}$ . Setting  $k_\omega(\varphi_1, \varphi_2, \varphi) = 0$  for  $\varphi_1 \in M \setminus M^f$  or  $\varphi_2 \in M \setminus M^f$  we obtain a well-defined measurable function from  $M^3$  into  $\mathbb{C}$ .

3°. We show that  $k_\omega$  is the c.r.d.m. of  $\omega$ , i.e. we must show that  $k_\omega$  has the properties given in Definition I.7.1.

From (3.28), (3.23), (3.24), and (3.25) we obtain for all  $A \in \mathfrak{B}$  and  $F_A \times Q_\omega$ -a.a.  $(\varphi_1, \varphi)$ ,

$$\begin{aligned} k_\omega(\varphi_1, \varphi_1, \varphi_{A^c}) &= k_A(\varphi_1, \varphi_1, \varphi_{A^c}) = k_A^{\varphi_{A^c}}(\varphi_1, \varphi_1, \mathbf{0}) \\ &= \kappa(\varphi_1, \varphi_{A^c}) = \frac{d\eta_{Q_\omega}^{\varphi_{A^c}}}{dF}(\varphi_1) \end{aligned}$$

what proves (i).

For  $A \in \mathfrak{B}$  and  $\varphi \in M$  we set

$$K_A^\varphi \Psi(\varphi_1) = \int F_A(d\varphi_2) k_\omega(\varphi_1, \varphi_2, \varphi_{A^c}) \Psi(\varphi_2) \quad (\Psi \in \mathcal{M}_A, \varphi_1 \in M_A). \quad (3.29)$$

Since for  $A \in \mathcal{A}_A$   $A = S_A(\{\mathbf{0}\}, A)$  we get from (3.22),

$$\begin{aligned} \omega_A^\varphi(A) &= Q_A^\varphi(\{\mathbf{0}\}) \int F_A(d\varphi_1) k_A * k_A^\varphi(\varphi_1, \mathbf{0}) \\ &= Q_A^\varphi(\{\mathbf{0}\}) \int F_A(d\varphi_1) k_A * k_\omega(\varphi_1, \varphi_{A^c}) \\ &= Q_A^\varphi(\{\mathbf{0}\}) \text{Tr}_A(K_A^\varphi A). \end{aligned} \quad (3.30)$$

Since  $\omega_A^\varphi$  is a normal state  $K_A^\varphi$  is a positive trace-class operator on  $\mathcal{M}_A$ .

Finally, we have to show that  $k_\omega$  fulfills (I.7.1). For all  $A \in \mathfrak{B}$ ,  $Y \in {}_A\mathfrak{M}$  and all integral operators  $A \in \mathcal{A}_A$  such that  $S(Y, A) \in {}_A\mathcal{A}$  we get (using (3.22) and the fact that  $M \in {}_A\mathfrak{M}^\perp$ )

$$\begin{aligned} \omega(S(Y, A)) &= \omega(S(Y, A)O_M) = \int Q_\omega(d\varphi) \omega_A^\varphi(S_A(v_A Y, A)) \\ &= \int_{M_{A^c}} Q_\omega(d\varphi) \eta_{Q_\omega}^\varphi(M_A) \int_{v_A Y} Q_A^\varphi(d\varphi_1) \int F_A(d\varphi_2) k_A * k_A^\varphi(\varphi_2, \varphi_1) \\ &= \int_Y Q_\omega(d\varphi) \int F_A(d\varphi_1) k_A * k_A^{\varphi_{A^c}}(\varphi_2, \varphi_1) \\ &= \int Q_\omega(d\varphi) \int F_A(d\varphi_1) k_A * k_\omega(\varphi_2, \varphi). \end{aligned}$$

4°. We still have to show the converse, and we assume now that the locally normal state  $\omega$  possesses a c.r.d.m. Then we use (3.29) and (3.30) to define a family  $(\omega_A^\varphi)_{\varphi \in M}$  of positive linear functionals on  $\mathcal{A}_A$ , i.e. we put

$$Q_A^\varphi(Y) = Q_\omega(v_A^{-1} Y|_{A^c} \mathfrak{M})(\varphi) \quad (Y \in \mathfrak{M}_A, \varphi \in M)$$

and

$$\omega_A^\varphi(A) = Q_A^\varphi(\{\mathbf{0}\}) \text{Tr}(K_A^\varphi A) \quad (A \in \mathcal{A}_A), \quad (3.31)$$

where  $K_A^\varphi$  is defined by (3.29).

Since  $\kappa(\mathbf{0}, \varphi) = 1$  and

$$Q_A^\varphi(Y) = (\eta_{Q_\omega}^{\varphi_{A^c}}(M_A))^{-1} \int_Y F(d\hat{\varphi}) \kappa(\hat{\varphi}, \varphi) \quad (3.32)$$

we get

$$Q_A^\varphi(\{\mathbf{0}\}) = (\eta_{Q_\omega}^{\varphi_{A^c}}(M_A))^{-1}. \quad (3.33)$$

Further, it is easy to see that

$$\omega_A^\varphi(O_{M_A}) = Q_A^\varphi(\{\mathbf{0}\}) \text{Tr}(K_A^\varphi O_{M_A}) = Q_A^\varphi(\{\mathbf{0}\}) \eta_{Q_\omega}^{\varphi_{A^c}}(M_A) = 1.$$

Thus,  $(\omega_A^\varphi)_{\varphi \in M}$  is a  ${}_A\mathfrak{M}$ -measurable family of normal states on  $\mathcal{A}_A$ , and by

$${}_A\omega^\varphi(A) = \omega_A^\varphi(O_{M_A} A O_{M_A}) \quad (A \in {}_A\mathcal{A}, \varphi \in M),$$

there is defined a  $_{A^c}\mathfrak{M}$ -measurable family of normal states on  $_{A^c}\mathcal{A}$ . We finally have to show that these states are just the conditional states of  $\omega$ . Let  $A \in \mathcal{A}_A, Y \in \mathcal{A}'\mathfrak{M}, A \cap A' = \emptyset, A, A' \in \mathfrak{B}$ . From Lemma 2.4 we know that  $J_A A O_Y \in \mathcal{A} \cap \mathcal{A}'$  and  $J_A A O_Y = S(Y \cap M_{A^c}, A)$ . Consequently, if  $A$  is an integral operator we get from the definition of the c.r.d.m.,

$$\begin{aligned} &\omega(J_A A O_Y) \\ &= \omega(S(Y \cap M_{A^c}, A)) \\ &= \int_{Y \cap M_{A^c}} Q_\omega(d\varphi) \int F_{A \cup A'}(d\varphi_1) \int F_{A \cup A'}(d\varphi_2) k_A(\varphi_1, \varphi_2) k_\omega(\varphi_2, \varphi_1, \varphi) \\ &= \int_{Y \cap M_{A^c}} Q_\omega(d\varphi) \int F_A(d\varphi_1) \int F_A(d\varphi_2) k_A(\varphi_1, \varphi_2) k_\omega(\varphi_2, \varphi_1, \varphi) \\ &= \int_{Y \cap M_{A^c}} Q_\omega(d\varphi) \text{Tr}(K_A^\varphi A) = \int_{Y \cap M_{A^c}} Q_\omega(d\varphi) \eta_{Q_\omega}^\varphi(M_A) Q_A^\varphi(\{\emptyset\}) \text{Tr}(K_A^\varphi A) \\ &= \int_Y Q_\omega(d\varphi) Q_{A^c}^\varphi(\{\emptyset\}) \text{Tr}(K_{A^c}^\varphi A) = \int_Y Q_\omega(d\varphi) \omega_A^\varphi(A) \\ &= \int_Y Q_\omega(d\varphi) \omega^\varphi(J_A A). \quad \square \end{aligned}$$

3.7. Proof of Proposition 2.11

The proof follows immediately from the proof of Theorem 2.10 [from (3.31), (3.33), and (2.4)].  $\square$

3.8. Proof of Proposition 2.12

Let  $k_1, k_2$  be two c.r.d.m. of  $\omega$ . As in the proof of Theorem 2.10 [(3.26), (3.27)] one easily shows that

$$k_1(\varphi_1, \varphi_2, \varphi) = k_2(\varphi_1, \varphi_2, \varphi) \quad (F_A \times F_A \times Q_\omega - a.a. (\varphi_1, \varphi_2, \varphi)).$$

Since  $F$  is concentrated on  $M^f = \bigcup_{A \in \mathfrak{B}} M_A$  this implies immediately that the c.r.d.m. is a.e. uniquely determined.  $\square$

3.9. Proof of Proposition 2.13

If  $\omega$  is normal it follows from Proposition I.6.1 that  $Q_\omega$  is a finite point process. Now, let  $Q_\omega$  be a finite  $\Sigma'_v$ -point process. It is easy to see that the c.r.d.m.  $k_\omega$  of  $\omega$  fulfills the assumptions of Theorem I.6.8. Consequently, there exists a normal  $\Sigma'_v$ -state  $\tilde{\omega}$  such that  $Q_{\tilde{\omega}} = Q_\omega$  and  $k_{\tilde{\omega}} = k_\omega$  a.e. Since a normal state is also a locally normal one we conclude from Proposition 2.12 that  $\tilde{\omega} = \omega$  [more precisely,  $\omega$  may be extended in a unique way to a normal state on  $\mathcal{L}(\mathcal{M})$ ].  $\square$

3.10. Proof of Proposition 2.14

The implication (i)  $\Rightarrow$  (ii) is a consequence of Proposition 2.12 and of the uniqueness of the position distribution [2, Theorem 3.3]. The implication (ii)  $\Rightarrow$  (i) follows from Remark I.7.5, 5 $^\circ$ .

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Communicated by Ya. G. Sinai