

# Propagation of singularities for a system of semilinear wave equations with null condition

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**Abstract.** We study the propagation of singularities for a system of semilinear wave equations satisfying the null condition in one space dimension. We show that if a solution  $(u, v)$  to the system is in  $H_{loc}^s(\Omega) \cap H_{ml}^r(0, x_0, \tau_0, \xi_0)$ , then  $(u, v) \in H_{ml}^r(\Gamma)$  as long as  $3/2 < s < r < 2s - 1$ , where  $\Omega \subset \mathbb{R}^2$  is an open set and  $\Gamma$  is a null bicharacteristic of  $\square$  passing through  $(0, x_0, \tau_0, \xi_0)$ .

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## §1. Introduction

In this paper, we consider the propagation of singularities of solutions to the following system of semilinear wave equations with the null condition in one space dimension,

$$(1.1) \quad \begin{cases} \square u = h_1(u, v)Q_0(u, u) + h_2(u, v)Q_0(u, v) + h_3(u, v)Q_0(v, v) + h_4(u, v)Q_1(u, v), \\ \square v = h_5(u, v)Q_0(u, u) + h_6(u, v)Q_0(u, v) + h_7(u, v)Q_0(v, v) + h_8(u, v)Q_1(u, v), \\ u(0, x) = u_0(x), \quad \partial_t u(0, x) = u_1(x), \\ v(0, x) = v_0(x), \quad \partial_t v(0, x) = v_1(x), \end{cases}$$

where  $(t, x) \in \mathbb{R}^2$ ,  $u(t, x)$ ,  $v(t, x)$ ,  $u_0(x)$ ,  $u_1(x)$ ,  $v_0(x)$  and  $v_1(x)$  are real valued functions,  $h_j(u, v)$  are polynomials of  $u$  and  $v$  for  $j = 1, 2, \dots, 8$  and  $Q_0, Q_1$  are the null forms

$$(1.2) \quad Q_0(f, g) = (\partial_t f)(\partial_t g) - (\partial_x f)(\partial_x g)$$

and

$$(1.3) \quad Q_1(f, g) = (\partial_t f)(\partial_x g) - (\partial_x f)(\partial_t g).$$

We assume that  $3/2 < s \leq 2$ , initial data  $u_0$  and  $v_0$  are in  $H^s(\mathbb{R})$  and  $u_1$  and  $v_1$  are in  $H^{s-1}(\mathbb{R})$ .

*Notation.*  $\langle \xi \rangle$  and  $\langle \tau, \xi \rangle$  denote  $(1 + |\xi|^2)^{1/2}$  and  $(1 + |\tau|^2 + |\xi|^2)^{1/2}$  respectively. If  $\Omega \subset \mathbb{R}^n$  is open,  $H_{loc}^s(\Omega)$  is the standard Sobolev space of distributions  $u$  such that  $\langle \xi \rangle^s \widehat{\phi u} \in L^2(\mathbb{R}^n)$  for all  $\phi \in C_0^\infty(\Omega)$ . Let  $(x_0, \xi_0) \in \Omega \times (\mathbb{R}_\xi^n \setminus \{0\})$ . We say that  $u$  is in microlocally  $H^r$  at  $(x_0, \xi_0)$  and write  $u \in H_{ml}^r(x_0, \xi_0)$  if there exists a  $\phi \in C_0^\infty(\mathbb{R}^n)$  with  $\phi(x_0) = 1$  and a conic neighborhood  $K$  of  $\xi_0$  in  $\mathbb{R}^n \setminus \{0\}$  such that  $\langle \xi \rangle^r \chi_K(\xi) |\widehat{\phi u}(\xi)| \in L^2(\mathbb{R}^n)$ , where  $\chi_K$  is the characteristic function of  $K$ . If  $\Gamma$  is a closed conic set in  $\Omega \times (\mathbb{R}_\xi^n \setminus \{0\})$ , we say that  $u \in H_{ml}^r(\Gamma)$  if  $u \in H_{ml}^r(x, \xi)$  for all  $(x, \xi) \in \Gamma$ . Let  $p(x, \xi)$  is a characteristic polynomial of differential operator  $P$  of order  $m$  and homogeneous of degree  $m$  in  $\xi$ . For a point  $(x_0, \xi_0)$  with  $p(x_0, \xi_0) = 0$ , the null bicharacteristic through  $(x_0, \xi_0)$  is the curve defined by  $\frac{dx}{ds} = \frac{\partial p}{\partial \xi}$ ,  $\frac{d\xi}{ds} = -\frac{\partial p}{\partial x}$  with  $x(0) = x_0$ ,  $\xi(0) = \xi_0$ . Throughout this paper,  $C_s$  serves as a generalized positive constant depending only on  $s$  if the precise value of which is not needed.

In the case of the linear wave equation  $\square u = 0$ , Hörmander [9] has shown that the wave front set of  $u$  propagates along the null bicharacteristic for  $\square$ . Generally, in the case of nonlinear wave equations, such a result cannot be obtained. However, it is known that if we consider the microlocal Sobolev regularity and assume the suitable range of the Sobolev exponent, then a phenomenon similar to the linear case is observed. In [20], Rauch first analyzed such result for the solutions to  $\square u = f(u)$  where  $f$  is a polynomial of  $u$ . Let  $f \in C^\infty$ ,  $\Omega \subset \mathbb{R}^n$  be an open set,  $u \in H_{loc}^s(\Omega) \cap H_{ml}^r(t_0, x_0, \tau_0, \xi_0)$  be a solution to

$$(1.4) \quad \square u = f(u, Du)$$

and  $(t_0, x_0, \tau_0, \xi_0)$  is a point in the null bicharacteristic  $\Gamma \subset \Omega \times \mathbb{R}^n$  of  $\square$ . Bony [7] and Beals-Reed [6] have shown that  $u$  is in  $H_{ml}^r$  at all points of  $\Gamma$  as long as for  $n/2 + 1 < s \leq r < 2s - 1 - n/2$  by the different way, respectively. For a second order strictly hyperbolic differential operator  $p_2(x, D)$ , Beals [5] has shown that solutions  $u \in H_{loc}^s(\Omega) \cap H_{ml}^r(x_0, \xi_0)$  to  $p_2(x, D)u = f(u, Du)$  is in  $H_{ml}^r$  at all points of a null bicharacteristic of  $p_2$  starting from  $(x_0, \xi_0)$  as long as for  $n/2 + 1 < s \leq r < 3s - n - 2$  by using a simple commutator lemma, Rauch's lemma and the standard calculus of pseudo differential operators. The technique used in Beals [5] plays an important role in this paper. In [18], Linqi Liu has shown that the same result holds in the case of  $n/2 + 1 < s \leq$

$r < 3s - n - 1$  for  $\square u = f(u, Du)$  by using a particular kind of weighted Sobolev spaces. In the case of a system, H. Michael [19] has shown that for  $U = (u_1, \dots, u_m) \in H_{loc}^s(\Omega) \cap H_{ml}^r(x_0, \xi_0)$  which are solutions to  $p_2(x, D)U = G(U)$  ( $G \in C^\infty$ ),  $U$  is in  $H_{ml}^r$  at all points of the null bicharacteristic of  $\Gamma$  as long as for  $n/2 < s \leq r < 3s - n + 1$ . On the other hand, if  $r$  is sufficiently large, new singularities are observed (refer to [3], [4], [21] and [22]). We are interested in the threshold of  $r$  and  $s$ . Although numerous attempts have been made to study these analysis, the threshold of  $r$  has not been determined exactly. In [11] and [12], we consider the case which nonlinearity satisfying the null condition. The null condition is defined by Klainerman [14]. Klainerman introduced the null condition as a sufficient condition for a global existence of smooth solutions to  $\square u = F(u, u', u'')$ , which is defined as follows.

**Definition 1.1.** (Klainerman [14]) *Let  $F(u, v_1, \dots, v_n)$  a real valued function, smoothly defined in a neighborhood of the origin in  $\mathbb{R} \times \mathbb{R}^n$ . We say that  $F(u, Du)$  (where  $Du$  denote the first partial derivatives of  $u$ ) satisfies the null condition if, for any  $u, v$  and any vector  $X = (X_1, \dots, X_n)$  such that  $X_1^2 - \sum_{i=2}^n X_i^2 = 0$ , the following identity holds;*

$$(1.5) \quad \sum_{i,j=1}^n \frac{\partial^2 F}{\partial v_i \partial v_j} X_i X_j = 0.$$

The attempt to lead the global and local existence theorem has been studied by a lot of people who have improved the null condition (refer to [1], [2], [8], [10], [13], [16], [17] and [23]). The null condition of semilinear wave equation which we consider are restricted to (1.1). In [12], we improved a lower bound of the threshold of  $s$  and  $r$  in the case that the nonlinear term satisfies the null condition. We have shown that if  $n/2 < s \leq r < 3s - n$  then  $u$  is in  $H_{ml}^r$  at all points of a null bicharacteristic of  $\square$ . The key of the proof is to make the Cole-Hopf type transformation to  $u$ . This transformation makes nonlinearity of (1.4) change to a polynomial of first degree with respect to  $Du$ . Then, we can apply the result of Beals [5] directly. This feature is obtained when nonlinearity satisfies the null condition.

The result of this paper is an extension of [12] to the system (1.1) and we show that the same result is true for a time local solution  $(u, v)$  of the system (1.1) as long as  $3/2 < s \leq r < 2s - 1$ . In the case of the system (1.1), the Cole-Hopf type transformation doesn't work. To avoid this problem, we estimate the microlocal regularity of the solution in the function space used by Klainerman and Machedon [15]. Firstly, we construct a time local solution of the initial value problem (1.1) in the function space associated to  $\square$  introduce in [15]. Secondly, we prove a propagation of a singularities to the constructed solution in the above function space by using the idea of Beals [5].

In order to state the main results precisely, we define several function spaces. We put

$$(1.6) \quad X^s = \left\{ f \in H_{loc}^s(\mathbb{R}^2) \left| \begin{array}{l} \forall a(t) \in C_0^\infty(\mathbb{R}) \text{ such that } a(t)f \in H^s(\mathbb{R}^2), \\ f|_{t=0} \in H^s(\mathbb{R}), \partial_t f|_{t=0} \in H^{s-1}(\mathbb{R}), \\ \|\square f\|_{X_1^{s-1}} < \infty \end{array} \right. \right\}$$

with norm

$$(1.7) \quad \|f\|_{X^s} = \|f|_{t=0}\|_{H^s} + \|\partial_t f|_{t=0}\|_{H^{s-1}} + \|\square f\|_{X_1^{s-1}}$$

and  $\|F\|_{X_1^s} = \|\langle D_x \rangle^s F\|_{L_{t,x}^2}$ .

**Proposition 1.2.** *Let  $3/2 < s \leq 2$ . Then for any  $u_0, v_0 \in H^s$  and  $u_1, v_1 \in H^{s-1}$ , there exists a positive constant  $T$  and a unique time local solution  $(u, v)$  of the initial value problem (1.1) satisfying*

$$(1.8) \quad (u, v) \in \{X^s \cap L^\infty([-T, T]; H_x^s)\} \times \{X^s \cap L^\infty([-T, T]; H_x^s)\}.$$

Our main result is the following.

**Theorem 1.3.** *Let  $3/2 < s \leq 2$  and  $(u, v) \in \{X^s \cap L^\infty([-T, T]; H_x^s)\} \times \{X^s \cap L^\infty([-T, T]; H_x^s)\}$  be a time local solution constructed in Proposition 1.2. If  $\Gamma \subset \mathbb{R}_{t,x}^2 \times (\mathbb{R}_{\tau,\xi}^2 \setminus \{0\})$  denotes a null bicharacteristic of  $\square$  and  $(u, v) \in H_{ml}^r(0, x_0, \tau_0, \xi_0) \times H_{ml}^r(0, x_0, \tau_0, \xi_0)$  for a point  $(0, x_0, \tau_0, \xi_0)$  on  $\Gamma$ , then  $(u, v) \in H_{ml}^r(\Gamma) \times H_{ml}^r(\Gamma)$  for  $|t| < T$  as long as  $r < 2s - 1$ .*

**Remark 1.4.** *For the case of  $s > 2$ , the same result holds but this case is treated in Beals [5]. So we do not treat this case.*

**Remark 1.5.** *Simple calculation shows that the null bicharacteristic of  $\square$  through the point  $(0, x_0, \tau_0, \xi_0) \in \mathbb{R}_{t,x}^2 \times (\mathbb{R}_{\tau,\xi}^2 \setminus \{0\})$  with  $\tau_0 = \pm|\xi_0|$  is the straight line  $\Gamma = \{(t, x, \tau_0, \xi_0) \mid x = x_0 - (\xi_0/\tau_0)t\}$ .*

In section 2, we prepare the null form estimate which is necessary for proving the existence of a time local solution. In section 3, we prove the existence of a time local solution. In section 4, we prove a propagation of a singularity theorem.

### §2. Estimate for the Null form

In this section, we give the estimates for the  $X_1^{s-1}$  norm of the null forms. From the definition (1.2) and (1.3) of the null forms, we can rewrite

$$(2.1) \quad Q_0(u, v) = \frac{1}{2} \{(\partial_t + \partial_x)u \cdot (\partial_t - \partial_x)v + (\partial_t - \partial_x)u \cdot (\partial_t + \partial_x)v\}$$

and

$$(2.2) \quad Q_1(u, v) = \frac{1}{2}\{(\partial_t - \partial_x)u \cdot (\partial_t + \partial_x)v - (\partial_t + \partial_x)u \cdot (\partial_t - \partial_x)v\}.$$

Let  $a(t) \in C_0^\infty(\mathbb{R})$  such that  $a(t) = 1$  for  $|t| \leq 1/2$ ,  $a(t) = 0$  for  $|t| \geq 1$  and  $0 \leq a(t) \leq 1$  and put  $a_T(t) = a(t/T)$  for  $T > 0$ . The following lemma is prepared in order to prove Proposition 2.2.

**Lemma 2.1.** *Let  $f, g \in H^{s-1}(\mathbb{R})$  for  $3/2 < s \leq 2$ . Then*

$$(2.3) \quad \|a_T(t)f(x+t)g(x-t)\|_{X_1^{s-1}} \leq C\sqrt{T} \|f\|_{H^{s-1}} \|g\|_{H^{s-1}},$$

where  $C$  is a constant depending on  $s$  and  $a(t)$ .

*Proof.* Since  $s - 1 > 1/2$ ,  $fg \in H^{s-1}(\mathbb{R})$ . Hence we have

$$\begin{aligned} \|a_T(t)f(x+t)g(x-t)\|_{X_1^{s-1}} &\leq \left\| a_T(t) \left\| \langle D_x \rangle^{s-1} (f(x+t)g(x-t)) \right\|_{L_x^2} \right\|_{L_t^2} \\ &\leq C_s \|a_T(t)\|_{L_t^2} \|f\|_{H^{s-1}} \|g\|_{H^{s-1}} \\ &\leq C_s \sqrt{T} \|a\|_{L^2} \|f\|_{H^{s-1}} \|g\|_{H^{s-1}}. \end{aligned}$$

Putting  $C = C_s \|a\|_{L^2}$ , we have the conclusion. ■

**Proposition 2.2.** *Let  $(u, v) \in X^s \times X^s$  for  $3/2 < s \leq 2$ . Then we have*

$$(2.4) \quad \|a_T(t)Q(u, v)\|_{X_1^{s-1}} \leq CT' \|u\|_{X^s} \|v\|_{X^s},$$

where  $Q(u, v)$  stands either  $Q_0(u, v)$  or  $Q_1(u, v)$ ,  $T' = \max\{T^{3/2}, T, T^{1/2}\}$  and  $C$  is a constant depending on  $s$  and  $a(t)$ .

*Proof.* We prove only the case of  $Q_0(u, u)$ , since the other cases can be proved similarly. We put  $u(0, x) = u_0(x)$ ,  $\partial_t u(0, x) = u_1(x)$  and  $f_0(t, x) = \frac{1}{2}\{u_0(x+t) + u_0(x-t)\} + \frac{1}{2} \int_{x-t}^{x+t} u_1(y) dy$ . By the density argument, we have

$$a_T(t)(\partial_t \pm \partial_x)u = a_T(t)(\partial_t \pm \partial_x)f_0 + 2a_T(t) \int_0^t \square u(\alpha, x \pm t \mp \alpha) d\alpha$$

holds in  $L_{loc}^2(\mathbb{R}, H_x^{s-1}(\mathbb{R}))$ . Putting  $f_{0,\pm} = (\partial_t \pm \partial_x)f_0$ ,  $u_\pm = (\partial_t \pm \partial_x)u$  and  $\tilde{u}_\pm = 2 \int_0^t \square u(\alpha, x \pm t \mp \alpha) d\alpha$ , we have

$$\begin{aligned} &\|a_T Q_0(u, u)\|_{X_1^{s-1}} \\ &\leq \|a_T \tilde{u}_+ \tilde{u}_-\|_{X_1^{s-1}} + \|a_T \tilde{u}_+ f_{0,-}\|_{X_1^{s-1}} + \|a_T \tilde{u}_- f_{0,+}\|_{X_1^{s-1}} + \|a_T f_{0,+} f_{0,-}\|_{X_1^{s-1}}. \end{aligned}$$

We only show that

$$(2.5) \quad \|a_T \tilde{u}_+ \tilde{u}_-\|_{X_1^{s-1}} \leq C_s T^{3/2} \|a\|_{L^2} \|\square u\|_{X_1^{s-1}}^2$$

since the other terms can be estimated similarly. By Lemma 2.1 and the Schwarz inequality, we obtain

$$(2.6) \quad \begin{aligned} & \|a_T(t) \tilde{u}_+ \tilde{u}_-\|_{X_1^{s-1}} \\ & \leq C_s \int_0^T \int_0^T \|a_T(t) \langle D_x \rangle^{s-1} \{\square u(\alpha, x+t-\alpha) \square u(\beta, x-t+\beta)\}\|_{L_{t,x}^2} d\alpha d\beta \\ & \leq C_s \int_0^T \int_0^T \sqrt{T} \|a\|_{L^2} \|\square u(\alpha, \cdot)\|_{H^{s-1}} \|\square u(\beta, \cdot)\|_{H^{s-1}} d\alpha d\beta \\ & \leq C_s T^{3/2} \|a\|_{L^2} \|\square u\|_{X_1^{s-1}}^2. \end{aligned}$$

Similarly, we obtain

$$(2.7) \quad \|a_T(t) f_{0,+} f_{0,-}\|_{X_1^{s-1}} \leq C_s T^{1/2} \|a\|_{L^2} (\|u_0\|_{H^s} + \|u_1\|_{H^{s-1}})^2,$$

$$(2.8) \quad \|a_T(t) \tilde{u}_+ f_{0,-}\|_{X_1^{s-1}} \leq C_s T \|a\|_{L^2} (\|u_0\|_{H^s} + \|u_1\|_{H^{s-1}}) \|\square u\|_{X_1^{s-1}}$$

and

$$(2.9) \quad \|a_T(t) \tilde{u}_- f_{0,+}\|_{X_1^{s-1}} \leq C_s T \|a\|_{L^2} (\|u_0\|_{H^s} + \|u_1\|_{H^{s-1}}) \|\square u\|_{X_1^{s-1}}.$$

By (2.6), (2.7), (2.8) and (2.9), we have the conclusion.  $\blacksquare$

### §3. Existence of solutions

Let

$$X_\rho^s = \{f \in X^s \mid \|f|_{t=0}\|_{H^s} + \|\partial_t f|_{t=0}\|_{H^{s-1}} \leq \rho/8, \|\square f\|_{X_1^{s-1}} \leq \rho\}$$

and

$$Y_{\rho,T}^s = \{f \in L^\infty([-T, T]; H_x^s) \mid \|f\|_{Y_T^s} \leq \rho\}$$

with  $\|f\|_{Y_T^s} = \|f\|_{L^\infty([-T, T]; H_x^s)}$ . We define a mapping  $M$  formally as follows

$$(3.1) \quad M(u, v) = \begin{pmatrix} M_1(u, v) \\ M_2(u, v) \end{pmatrix} = \begin{pmatrix} f_0 + \int_0^t U(t-\alpha) a_T(\alpha) A(u, v; \alpha, x) d\alpha \\ g_0 + \int_0^t U(t-\alpha) a_T(\alpha) B(u, v; \alpha, x) d\alpha \end{pmatrix},$$

where  $U$  is the evolution operator for  $\square$  defined by  $U(t)\psi(x) = \int_{x-t}^{x+t} \psi(y)dy$ ,  $f_0(t, x) = \frac{1}{2}\{u_0(x+t)+u_0(x-t)\} + \frac{1}{2} \int_{x-t}^{x+t} u_1(y)dy$ ,  $g_0(t, x) = \frac{1}{2}\{v_0(x+t)+v_0(x-t)\} + \frac{1}{2} \int_{x-t}^{x+t} v_1(y)dy$  with  $u(0, x) = u_0(x)$ ,  $\partial_t u(0, x) = u_1(x)$ ,  $v(0, x) = v_0(x)$  and  $\partial_t v(0, x) = v_1(x)$ ,  $a_T(t)$  is a function defined in section 2,

$$A(u, v; t, x) = h_1(u, v)Q_0(u, u) + h_2(u, v)Q_0(u, v) + h_3(u, v)Q_0(v, v) + h_4(u, v)Q_1(u, v)$$

and

$$B(u, v; t, x) = h_5(u, v)Q_0(u, u) + h_6(u, v)Q_0(u, v) + h_7(u, v)Q_0(v, v) + h_8(u, v)Q_1(u, v).$$

We show that the mapping  $M$  is a contraction mapping on  $(X_\rho^s \cap Y_{\rho,T}^s) \times (X_\rho^s \cap Y_{\rho,T}^s)$  for sufficiently small  $T > 0$ . To prove this, we use the following lemma.

**Lemma 3.1.** *Let  $(u, v) \in (X_\rho^s \cap Y_{\rho,T}^s) \times (X_\rho^s \cap Y_{\rho,T}^s)$  for  $3/2 < s \leq 2$ . Then we have*

$$(3.2) \quad \|\square M_\ell(u, v)\|_{X_1^{s-1}} \leq CT' \sum_{0 \leq j+k \leq n} \|u\|_{Y_T^s}^j \|v\|_{Y_T^s}^k (\|u\|_{X^s} + \|v\|_{X^s})^2,$$

where  $M_\ell$  ( $\ell = 1, 2$ ) is the mapping defined in (3.1),  $T' = \max\{T^{3/2}, T, T^{1/2}\}$ ,  $C$  is a constant depending on  $s$ ,  $a(t)$  and  $h_i$  and  $n$  is the maximum of orders of  $h_i$  ( $i = 1, 2, \dots, 8$ ).

*Proof.* From the definition (3.1) of the mapping  $M$  and the triangle inequality, we have

$$\begin{aligned} \|\square M_1(u, v)\|_{X_1^{s-1}} &= \|a_T(t)A(u, v; t, x)\|_{X_1^{s-1}} \\ &\leq \|a_T(t)h_1(u, v)Q_0(u, u)\|_{X_1^{s-1}} + \|a_T(t)h_2(u, v)Q_0(u, v)\|_{X_1^{s-1}} \\ &\quad + \|a_T(t)h_3(u, v)Q_0(v, v)\|_{X_1^{s-1}} + \|a_T(t)h_4(u, v)Q_1(u, v)\|_{X_1^{s-1}}. \end{aligned}$$

We put  $h_i(u, v) = \sum_{0 \leq j+k \leq n_i} c_{j,k}^{(i)} u^j v^k$ . By Proposition 2.2 and the assumption  $s - 1 > 1/2$ , we have

$$\begin{aligned} &\|a_T(t)h_1(u, v)Q_0(u, u)\|_{X_1^{s-1}} \\ &\leq C_s \left\| \|h_1(u, v)\|_{H_x^{s-1}} \|a_T(t)Q_0(u, u)\|_{H_x^{s-1}} \right\|_{L_{[-T, T]}^2} \\ &\leq C_s \left\| \|h_1(u, v)\|_{H_x^{s-1}} \right\|_{L_{[-T, T]}^\infty} \|a_T(t)Q_0(u, u)\|_{X_1^{s-1}} \\ &\leq C_1 T' \sum_{0 \leq j+k \leq n_1} \|u\|_{Y_T^s}^j \|v\|_{Y_T^s}^k \|u\|_{X^s}^2, \end{aligned}$$

where  $C_1$  is a constant depending on  $s$ ,  $a(t)$  and  $h_1$ . Similarly, we have

$$\|a_T(t)h_2(u, v)Q_0(u, v)\|_{X_1^{s-1}} \leq C_2 T' \sum_{0 \leq j+k \leq n_2} \|u\|_{Y_T^s}^j \|v\|_{Y_T^s}^k \|u\|_{X^s} \|v\|_{X^s},$$

$$\|a_T(t)h_3(u, v)Q_0(v, v)\|_{X_1^{s-1}} \leq C_3 T' \sum_{0 \leq j+k \leq n_3} \|u\|_{Y_T^s}^j \|v\|_{Y_T^s}^k \|v\|_{X^s}^2$$

and

$$\|a_T(t)h_4(u, v)Q_1(u, v)\|_{X_1^{s-1}} \leq C_4 T' \sum_{0 \leq j+k \leq n_4} \|u\|_{Y_T^s}^j \|v\|_{Y_T^s}^k \|u\|_{X^s} \|v\|_{X^s},$$

where  $C_i$  are constants depending on  $s$ ,  $a(t)$  and  $h_i$  ( $i = 2, 3, 4$ ). If we put  $n = \max_{1 \leq i \leq 4} n_i$  and  $C = \max_{1 \leq i \leq 4} C_i$ , then we obtain

$$\|\square M_1(u, v)\|_{X_1^{s-1}} \leq C T' \sum_{0 \leq j+k \leq n} \|u\|_{Y_T^s}^j \|v\|_{Y_T^s}^k (\|u\|_{X^s} + \|v\|_{X^s})^2.$$

Similarly, we obtain

$$\|\square M_2(u, v)\|_{X_1^{s-1}} \leq C T' \sum_{0 \leq j+k \leq n} \|u\|_{Y_T^s}^j \|v\|_{Y_T^s}^k (\|u\|_{X^s} + \|v\|_{X^s})^2.$$

■

**Lemma 3.2.** *Under the same assumptions in Lemma 3.1, we have*

$$(3.3) \quad \begin{aligned} & \|M_1(u, v)\|_{Y_T^s} \\ & \leq C T' \sum_{0 \leq j+k \leq n} \|u\|_{Y_T^s}^j \|v\|_{Y_T^s}^k (\|u\|_{X^s} + \|v\|_{X^s})^2 + \|u_0\|_{H^s} + 2 \|u_1\|_{H^{s-1}} \end{aligned}$$

and

$$(3.4) \quad \begin{aligned} & \|M_2(u, v)\|_{Y_T^s} \\ & \leq C T' \sum_{0 \leq j+k \leq n} \|u\|_{Y_T^s}^j \|v\|_{Y_T^s}^k (\|u\|_{X^s} + \|v\|_{X^s})^2 + \|v_0\|_{H^s} + 2 \|v_1\|_{H^{s-1}}, \end{aligned}$$

where  $C$  are constants depending on  $s$ ,  $a(t)$  and  $h_i$  ( $i = 1, 2, \dots, 8$ ).



*Proof.* From the definition (3.1) of the mapping  $M$  and the triangle inequality, we have

$$\begin{aligned} \|M_1(u, v)\|_{Y_T^s} &= \left\| f_0 + \int_0^t U(t - \alpha) a_T(\alpha) A(u, v; \alpha, x) d\alpha \right\|_{L^\infty([-T, T]; H_x^s)} \\ &\leq \|f_0\|_{L^\infty([-T, T]; H_x^s)} + C_s \left( \left\| \int_0^t U(t - \alpha) a_T(\alpha) A(u, v; \alpha, x) d\alpha \right\|_{L^\infty([-T, T]; L_x^2)} \right. \\ &\quad \left. + \left\| |D_x|^s \int_0^t U(t - \alpha) a_T(\alpha) A(u, v; \alpha, x) d\alpha \right\|_{L^\infty([-T, T]; L_x^2)} \right). \end{aligned}$$

By change of variables and the Schwarz inequality, we obtain

$$\begin{aligned} &\left\| \int_0^t U(t - \alpha) a_T(\alpha) A(u, v; \alpha, x) d\alpha \right\|_{L^\infty([-T, T]; L_x^2)} \\ &\leq \left\| \int_0^T \left\| \int_{x-(t-\alpha)}^{x+t-\alpha} a_T(\alpha) A(u, v; \alpha, y) dy \right\|_{L_x^2} d\alpha \right\|_{L^\infty[-T, T]} \\ &\leq \left\| \int_0^T \int_{-(t-\alpha)}^{t-\alpha} \|a_T(\alpha) A(u, v; \alpha, x + y)\|_{L_x^2} dy d\alpha \right\|_{L^\infty[-T, T]} \\ &\leq \left\| 2 \sup_{\alpha \in [0, T]} |t - \alpha| \int_0^T \|a_T(\alpha) A(u, v; \alpha, x)\|_{L_x^2} d\alpha \right\|_{L^\infty[-T, T]} \\ &\leq 2 \left\| \sup_{\alpha \in [0, T]} |t - \alpha| \sqrt{T} \|a_T(t) A(u, v; t, x)\|_{X_1^{s-1}} \right\|_{L^\infty[-T, T]} \\ &\leq 4T^{3/2} \|a_T(t) A(u, v; t, x)\|_{X_1^{s-1}} \end{aligned}$$

and

$$\begin{aligned} &\left\| |D_x|^s \int_0^t U(t - \alpha) a_T(\alpha) A(u, v; \alpha, x) d\alpha \right\|_{L^\infty([-T, T]; L_x^2)} \\ &\leq \left\| \left\| \int_0^t |D_x|^{s-1} a_T(\alpha) (A(u, v; \alpha, x+t-\alpha) - A(u, v; \alpha, x-t+\alpha)) d\alpha \right\|_{L_x^2} \right\|_{L^\infty[-T, T]} \\ &\leq \left\| 2 \int_0^T \left\| |D_x|^{s-1} a_T(\alpha) A(u, v; \alpha, x) \right\|_{L_x^2} d\alpha \right\|_{L^\infty[-T, T]} \\ &\leq 2\sqrt{T} \|a_T(t) A(u, v; t, x)\|_{X_1^{s-1}}. \end{aligned}$$

By a similar calculation for  $f_0 = \frac{1}{2}\{u_0(x+t) + u_0(x-t)\} + \frac{1}{2} \int_{x-t}^{x+t} u_1(y) dy$ , we obtain

$$\|f_0\|_{L^\infty([-T, T]; H_x^s)} \leq \|u_0\|_{H^s} + 2 \|u_1\|_{H^{s-1}} + 2T \|u_1\|_{H^{s-1}}.$$

By Lemma 3.1, we have (3.3). Similarly, we obtain (3.4). ■

**Lemma 3.3.** *Let  $(u, v), (\tilde{u}, \tilde{v}) \in (X_\rho^s \cap Y_{\rho,T}^s) \times (X_\rho^s \cap Y_{\rho,T}^s)$  for  $3/2 < s \leq 2$ ,  $h(u, v)$  is a polynomial of degree  $n$  with respect to  $u$  and  $v$ . Then we have*

$$(3.5) \quad \begin{aligned} & \|a_T(t)\{h(u, v)Q(u, v) - h(\tilde{u}, \tilde{v})Q(\tilde{u}, \tilde{v})\}\|_{X_1^{s-1}} \\ & \leq CT' \left\{ \left( K(u, \tilde{u}, v) \|u - \tilde{u}\|_{Y_T^s} + K(v, \tilde{v}, \tilde{u}) \|v - \tilde{v}\|_{Y_T^s} \right) \|u\|_{X^s} \|v\|_{X^s} \right. \\ & \quad \left. + h(\|\tilde{u}\|_{Y_T^s}, \|\tilde{v}\|_{Y_T^s}) (\|u - \tilde{u}\|_{X^s} \|v\|_{X^s} + \|\tilde{u}\|_{X^s} \|v - \tilde{v}\|_{X^s}) \right\} \end{aligned}$$

and

$$(3.6) \quad \begin{aligned} & \left\| \int_0^t U(t - \alpha) a_T(\alpha) \{h(u, v)Q(u, v) - h(\tilde{u}, \tilde{v})Q(\tilde{u}, \tilde{v})\} d\alpha \right\|_{Y_T^s} \\ & \leq CT' \left\{ \left( K(u, \tilde{u}, v) \|u - \tilde{u}\|_{Y_T^s} + K(v, \tilde{v}, \tilde{u}) \|v - \tilde{v}\|_{Y_T^s} \right) \|u\|_{X^s} \|v\|_{X^s} \right. \\ & \quad \left. + h(\|\tilde{u}\|_{Y_T^s}, \|\tilde{v}\|_{Y_T^s}) (\|u - \tilde{u}\|_{X^s} \|v\|_{X^s} + \|\tilde{u}\|_{X^s} \|v - \tilde{v}\|_{X^s}) \right\} \end{aligned}$$

where

$$K(p, q, r) = \sum_{1 \leq i+j \leq n} \|r\|_{Y_T^s}^i (\|p\|_{Y_T^s}^{j-1} + \|p\|_{Y_T^s}^{j-2} \|q\|_{Y_T^s} + \|p\|_{Y_T^s}^{j-3} \|q\|_{Y_T^s}^2 + \cdots + \|q\|_{Y_T^s}^{j-1}),$$

$T' = \max\{T^{3/2}, T, T^{1/2}\}$ ,  $Q(u, v)$  stands either  $Q_0(u, v)$  or  $Q_1(u, v)$  and  $C$  is a constant depending on  $s$  and  $h$ .

*Proof.* Since  $3/2 < s \leq 2$ , we have

$$(3.7) \quad \begin{aligned} & \|a_T(t)\{h(u, v)Q(u, v) - h(\tilde{u}, \tilde{v})Q(\tilde{u}, \tilde{v})\}\|_{X_1^{s-1}} \\ & \leq C(\|h(u, v) - h(\tilde{u}, \tilde{v})\|_{Y_T^s} \|a_T(t)Q(u, v)\|_{X_1^{s-1}} \\ & \quad + \|h(\tilde{u}, \tilde{v})\|_{Y_T^s} \|a_T(t)\{Q(u, v) - Q(\tilde{u}, \tilde{v})\}\|_{X_1^{s-1}}). \end{aligned}$$

Putting  $h(u, v) = \sum_{0 \leq i+j \leq n} c_{i,j} u^i v^j$ , we have

$$\begin{aligned}
 (3.8) \quad & \|h(u, v) - h(\tilde{u}, \tilde{v})\|_{Y_T^s} \\
 & \leq \|h(u, v) - h(\tilde{u}, v)\|_{Y_T^s} + \|h(\tilde{u}, v) - h(\tilde{u}, \tilde{v})\|_{Y_T^s} \\
 & \leq \left\| (u - \tilde{u}) \sum_{1 \leq i+j \leq n} c_{i,j} v^j (u^{i-1} + \dots + \tilde{u}^{i-1}) \right\|_{Y_T^s} \\
 & \quad + \left\| (v - \tilde{v}) \sum_{1 \leq i+j \leq n} c_{i,j} \tilde{u}^i (v^{j-1} + \dots + \tilde{v}^{j-1}) \right\|_{Y_T^s} \\
 & \leq C \max_{1 \leq i+j \leq n} |c_{i,j}| \left( K(u, \tilde{u}, v) \|u - \tilde{u}\|_{Y_T^s} + K(v, \tilde{v}, \tilde{u}) \|v - \tilde{v}\|_{Y_T^s} \right).
 \end{aligned}$$

By Proposition 2.2, we have

$$\begin{aligned}
 (3.9) \quad & \|a_T(t)\{Q(u, v) - Q(\tilde{u}, \tilde{v})\}\|_{X_1^{s-1}} \\
 & \leq \|a_T(t)Q(u - \tilde{u}, v)\|_{X_1^{s-1}} + \|a_T(t)Q(\tilde{u}, v - \tilde{v})\|_{X_1^{s-1}} \\
 & \leq CT' (\|u - \tilde{u}\|_{X^s} \|v\|_{X^s} + \|\tilde{u}\|_{X^s} \|v - \tilde{v}\|_{X^s}).
 \end{aligned}$$

Therefore the conclusion is obtained combining (3.7), (3.8) and (3.9). Similarly we can prove (3.6).  $\blacksquare$

**Proof of Proposition 1.2.** We show that the nonlinear map  $M$  defined in (3.1) is a contraction mapping from  $(X_\rho^s \cap Y_{\rho,T}^s) \times (X_\rho^s \cap Y_{\rho,T}^s)$  to itself for sufficiently small  $T > 0$ . That is, for any  $(u, v), (\tilde{u}, \tilde{v}) \in (X_\rho^s \cap Y_{\rho,T}^s) \times (X_\rho^s \cap Y_{\rho,T}^s)$ , we show that

$$(3.10) \quad (M_1(u, v), M_2(u, v)) \in (X_\rho^s \cap Y_{\rho,T}^s) \times (X_\rho^s \cap Y_{\rho,T}^s)$$

and

$$\begin{aligned}
 (3.11) \quad & \|M(u, v) - M(\tilde{u}, \tilde{v})\|_{X^s} + \|M(u, v) - M(\tilde{u}, \tilde{v})\|_{Y_T^s} \\
 & \leq \frac{1}{2} \|(u, v) - (\tilde{u}, \tilde{v})\|_{X^s} + \frac{1}{2} \|(u, v) - (\tilde{u}, \tilde{v})\|_{Y_T^s}.
 \end{aligned}$$

The contraction mapping principle yields from (3.10) and (3.11) that there is a fixed point of  $(X_\rho^s \cap Y_{\rho,T}^s) \times (X_\rho^s \cap Y_{\rho,T}^s)$ . This gives the solution of (1.1).

It is obvious that  $M_1(u, v)|_{t=0} = u_0(x)$  and  $\partial_t M_1(u, v)|_{t=0} = u_1(x)$ . So we have that  $\|M_1(u, v)|_{t=0}\|_{H^s} + \|\partial_t M_1(u, v)|_{t=0}\|_{H^{s-1}} \leq \rho/8$  for  $(u, v) \in (X_\rho^s \cap Y_{\rho,T}^s) \times (X_\rho^s \cap Y_{\rho,T}^s)$ . By Lemma 3.1 and Lemma 3.2, we have

$$\|\square M_1(u, v)\|_{X_1^{s-1}} \leq CT' \sum_{0 \leq j+k \leq n} \rho^{j+k+2}$$

and

$$\|M_1(u, v)\|_{Y_T^s} \leq CT' \sum_{0 \leq j+k \leq n} \rho^{j+k+2} + \frac{3\rho}{8}.$$

If we take sufficiently small  $T > 0$ , we obtain  $M_1(u, v) \in X_\rho^s \cap Y_{\rho, T}^s$ . Similarly, we obtain  $M_2(u, v) \in X_\rho^s \cap Y_{\rho, T}^s$ . Hence we have (3.10).

Similarly, we can prove (3.11) for sufficiently small  $T > 0$  by Lemma 3.1, Lemma 3.2 and Lemma 3.3. ■

### §4. Propagation of Singularities

Let  $\varphi(x)$  be a  $C_0^\infty$  function satisfying  $\varphi \equiv 1$  near  $x_0$  and  $\chi(\tau, \xi)$  be smooth, homogeneous of degree 0 in  $|(\tau, \xi)| > \epsilon$  for some  $\epsilon > 0$ , with conic support,  $\chi \equiv 1$  on conic neighborhood of  $(\tau_0, \xi_0)$ . We consider the operator  $P$  with its symbol  $p(t, x, \tau, \xi) = \varphi(x + (\xi/\tau)t)\chi(\tau, \xi)$ , which is defined by

$$(4.1) \quad Pf = \int_{\mathbb{R}^2} p(t, x, \tau, \xi) \hat{f}(\tau, \xi) e^{i(t\tau + x\xi)} d\tau d\xi.$$

Simple calculation yields that the symbol of the commutator  $[\square, P] = \square P - P \square$  is  $(\xi^2/\tau^2 - 1)\varphi''(x + (\xi/\tau)t)\chi$ , which is a symbol of pseudo differential operator of order 0.

In order to prove Theorem 1.3, we multiply the operator  $P$  to the both sides of the equations (1.1) and use the energy estimates. We prepare several lemmas to prove the main theorem. The following well-known result will be used frequently.

**Lemma 4.1.** *(Rauch and Reed [21]) Suppose that  $G(\xi, \eta)$  may be decomposed into finitely many pieces, i.e.,  $G = \sum_i G_i(\xi, \eta)$ , each of which satisfies either*

$$(4.2) \quad \sup_\xi \int |G_i|^2 d\eta < \infty \quad \text{or} \quad \sup_\eta \int |G_i|^2 d\xi < \infty.$$

*If  $f, g \in L^2$  and  $h(\xi) = \int G(\xi, \eta) f(\xi - \eta) g(\eta) d\eta$ , then we have  $\|h\|_{L^2} \leq C \|f\|_{L^2} \|g\|_{L^2}$ .*

**Lemma 4.2.** *Let  $P$  be the operator defined in (4.1). Suppose that  $f, g, h \in H^s$ ,  $\square f, \square g \in H^{s-1}$  and  $3/2 < s \leq 2$ . Then, for any  $0 \leq \epsilon < s - 1$ , we have*

$$[P, h(t, x)(\partial_t + \partial_x)f(\partial_t - \partial_x)](\partial_t \pm \partial_x)g \in H^{s-2+\epsilon}$$

and

$$[P, h(t, x)(\partial_t - \partial_x)f(\partial_t + \partial_x)](\partial_t \pm \partial_x)g \in H^{s-2+\epsilon}.$$

**Remark 4.3.** To estimate for  $K$  defined in the following proof, the inequality

$$(4.3) \quad \int_{\mathbb{R}} \frac{1}{(1 + |x - \alpha|)^r (1 + |x - \beta|)^r} dx \leq \frac{C}{(1 + |\alpha - \beta|)^r} \quad \text{for } r > 1$$

is used frequently.

*Proof.* Assume that  $p$  depends only on  $\tau$  and  $\xi$  (the general case requires some obvious modifications). Let  $f_{\pm} = (\partial_t \pm \partial_x)f$  and  $g_{\pm} = (\partial_t \pm \partial_x)g$ . For simplicity, we put  $\eta = (\tau, \xi)$ ,  $\eta' = (\tau', \xi')$ . Then

$$\begin{aligned} & \mathcal{F}_{t,x} [[P, (hf_-)(\partial_t + \partial_x)]g_+] \\ &= ip(\eta) \int \widehat{hf_-}(\eta') \{(\tau - \tau') + (\xi - \xi')\} \widehat{g_+}(\eta - \eta') d\eta' \\ & \quad - i \int \widehat{hf_-}(\eta') \{(\tau - \tau') + (\xi - \xi')\} p(\eta - \eta') \widehat{g_+}(\eta - \eta') d\eta' \\ &= i \int \widehat{hf_-}(\eta') \{p(\eta) - p(\eta - \eta')\} \{(\tau - \tau') + (\xi - \xi')\} \widehat{g_+}(\eta - \eta') d\eta'. \end{aligned}$$

Write  $\theta_1(\eta) = \{\langle \eta \rangle^{s-1} (1 + |\tau + \xi|)\} \widehat{hf_-}(\eta)$  and  $\theta_2(\eta) = \{\langle \eta \rangle^{s-1} (1 + |\tau - \xi|)\} \widehat{g_+}(\eta)$ , then simple calculation yields that  $\theta_1, \theta_2 \in L^2$ . Thus

$$\langle \eta \rangle^{s-2+\epsilon} \mathcal{F}_{t,x} [[P, (hf_-)(\partial_t + \partial_x)]g_+] = \int K(\eta, \eta') \theta_1(\eta') \theta_2(\eta - \eta') d\eta',$$

where

$$|K(\eta, \eta')| = \frac{\langle \eta \rangle^{s-2+\epsilon} |p(\eta) - p(\eta - \eta')| \cdot |(\tau - \tau') + (\xi - \xi')|}{\langle \eta' \rangle^{s-1} \langle \eta - \eta' \rangle^{s-1} (1 + |\tau' + \xi'|) (1 + |(\tau - \tau') - (\xi - \xi')|)}.$$

By Lemma 4.1, it suffices to divide  $K$  into finitely many pieces  $K_i$  such that

$$(4.4) \quad \sup_{\eta'} \int |K_i|^2 d\eta < \infty \quad \text{or} \quad \sup_{\eta} \int |K_i|^2 d\eta' < \infty.$$

(i) For  $|\eta'| \geq |\eta|/2$ ,  $|\eta - \eta'| \geq |\eta|/2$  and  $\frac{|\tau - \tau' + \xi - \xi'|}{2} \leq |\tau' + \xi'|$ ,

$$|K| \leq \frac{C}{\langle \eta \rangle^{s-\epsilon} (1 + |(\tau - \tau') - (\xi - \xi')|)}.$$

(ii) For  $|\eta'| \geq |\eta|/2$ ,  $|\eta - \eta'| \geq |\eta|/2$  and  $\frac{|\tau - \tau' + \xi - \xi'|}{2} \leq |\tau + \xi|$ ,

$$|K| \leq \frac{C}{\langle \eta' \rangle^{s-1-\epsilon} (1 + |\tau' + \xi'|) (1 + |(\tau - \tau') - (\xi - \xi')|)}.$$

(iii) For  $|\eta'| \geq |\eta|/2$ ,  $|\eta - \eta'| \leq |\eta|/2$  and  $\frac{|\tau - \tau' + \xi - \xi'|}{2} \leq |(\tau - \tau') - (\xi - \xi')|$ ,

$$|K| \leq \frac{C}{\langle \eta - \eta' \rangle^{s-\epsilon} (1 + |\tau' + \xi'|)}.$$

(iv) For  $|\eta'| \geq |\eta|/2$ ,  $|\eta - \eta'| \leq |\eta|/2$  and  $\frac{|\tau - \tau' + \xi - \xi'|}{2} \leq 2|\xi - \xi'|$ ,

$$|K| \leq \frac{C}{\langle \eta - \eta' \rangle^{s-1-\epsilon} (1 + |\tau' + \xi'|) (1 + |(\tau - \tau') - (\xi - \xi')|)}.$$

(v) For  $|\eta'| < |\eta|/2$  and  $\frac{|\tau - \tau' + \xi - \xi'|}{2} \leq |\tau' + \xi'|$ , thus  $|p(\eta) - p(\eta - \eta')| \leq C\langle \eta' \rangle / \langle \eta \rangle$ ,

$$|K| \leq \frac{C}{\langle \eta' \rangle^{s-\epsilon} (1 + |(\tau - \tau') - (\xi - \xi')|)}.$$

(vi) For  $|\eta'| < |\eta|/2$  and  $\frac{|\tau - \tau' + \xi - \xi'|}{2} \leq |\tau + \xi|$ , thus  $|p(\eta) - p(\eta - \eta')| \leq C\langle \eta' \rangle / \langle \eta \rangle$ ,

$$|K| \leq \frac{C}{\langle \eta' \rangle^{s-1-\epsilon} (1 + |\tau' + \xi'|) (1 + |(\tau - \tau') - (\xi - \xi')|)}.$$

Therefore, in all the cases, (4.4) holds since  $\epsilon < s - 1$ . Here, we used Hölder's inequality and (4.3) in the case of (ii), (iv) and (vi). It is similar in the case of  $[P, (hf_-)(\partial_t + \partial_x)]g_-$ ,  $[P, (hf_+)(\partial_t - \partial_x)]g_+$  and  $[P, (hf_+)(\partial_t - \partial_x)]g_-$ . ■

**Proposition 4.4.** *Let  $3/2 < s \leq 2$ . Suppose that  $(u, v)$  is a solution of the initial value problem (1.1) in  $(X_\rho^s \cap Y_{\rho,T}^s) \times (X_\rho^s \cap Y_{\rho,T}^s)$  for some  $T > 0$  with  $u_0(x), v_0(x) \in H^s$  and  $u_1(x), v_1(x) \in H^{s-1}$ . Then  $a_T(t)Q(u, v) \in H^{s-1}(\mathbb{R}^2)$ , where  $Q(u, v)$  stands either  $Q_0(u, v)$  or  $Q_1(u, v)$ .*

*Proof.* Because of the fact that

$$\|a_T(t)Q_0(u, v)\|_{H^{s-1}} \leq \|a_T(t)Q_0(u, v)\|_{X_1^{s-1}} + \|\langle D_x \rangle^{s-2} \langle D_t \rangle a_T(t)Q_0(u, v)\|_{L_{t,x}^2}$$

and the fact that  $\|a_T(t)Q_0(u, v)\|_{X_1^{s-1}} < \infty$  from Proposition 2.2, it suffices to show that

$$\|\langle D_x \rangle^{s-2} \langle D_t \rangle a_T(t)Q_0(u, v)\|_{L_{t,x}^2} < \infty.$$

For the solution  $u$  and  $v$  of (1.1), we write  $u = f_0 + \tilde{u}$  and  $v = g_0 + \tilde{v}$ , where

$$\begin{aligned} f_0(t, x) &= \frac{1}{2}\{u_0(x+t) + u_0(x-t)\} + \frac{1}{2} \int_{x-t}^{x+t} u_1(y)dy, \\ g_0(t, x) &= \frac{1}{2}\{v_0(x+t) + v_0(x-t)\} + \frac{1}{2} \int_{x-t}^{x+t} v_1(y)dy, \\ \tilde{u} &= \int_0^t U(t-\alpha)a_T(\alpha)A(u, v; \alpha, x)d\alpha \end{aligned}$$

and

$$\tilde{v} = \int_0^t U(t-\beta)a_T(\beta)B(u, v; \beta, x)d\beta.$$

Then we have  $Q_0(u, v) = Q_0(f_0, g_0) + Q_0(f_0, \tilde{v}) + Q_0(g_0, \tilde{u}) + Q_0(\tilde{u}, \tilde{v})$ . We show that only

$$(4.5) \quad \|\langle D_x \rangle^{s-2} \langle D_t \rangle a_T(t) Q_0(\tilde{u}, \tilde{v})\|_{L^2_{t,x}} < \infty,$$

since the other terms can be estimated similarly. From Leibniz rule and the triangle inequality, we have

$$\begin{aligned} &\|\langle D_x \rangle^{s-2} \langle D_t \rangle a_T(t) Q_0(\tilde{u}, \tilde{v})\|_{L^2_{t,x}} \\ &\leq \|a_T(t) Q_0(\tilde{u}, \tilde{v})\|_{X_1^{s-1}} + \|\langle D_x \rangle^{s-2} (D_t a_T(t)) Q_0(\tilde{u}, \tilde{v})\|_{L^2_{t,x}} \\ &\quad + \|\langle D_x \rangle^{s-2} a_T(t) (D_t Q_0(\tilde{u}, \tilde{v}))\|_{L^2_{t,x}}. \end{aligned}$$

Since Proposition 2.2 shows that

$$\|a_T(t) Q_0(\tilde{u}, \tilde{v})\|_{X_1^{s-1}} < \infty \quad \text{and} \quad \|\langle D_x \rangle^{s-2} (D_t a_T(t)) Q_0(\tilde{u}, \tilde{v})\|_{L^2_{t,x}} < \infty,$$

we only show

$$\|\langle D_x \rangle^{s-2} a_T(t) (D_t Q_0(\tilde{u}, \tilde{v}))\|_{L^2_{t,x}} < \infty.$$

For simplicity, we write  $A(u, v; \alpha, x) = A(\alpha, x)$ ,  $B(u, v; \alpha, x) = B(\alpha, x)$ . From (2.1), we have

$$\begin{aligned} Q_0(\tilde{u}, \tilde{v}) &= 2 \int_0^t \int_0^t a_T(\alpha) a_T(\beta) \{A(\alpha, x+t-\alpha) B(\beta, x-t+\beta) \\ &\quad + A(\alpha, x-t+\alpha) B(\beta, x+t-\beta)\} d\alpha d\beta \end{aligned}$$

and

$$\begin{aligned} \partial_t Q_0(\tilde{u}, \tilde{v}) &= 2 \int_0^t \int_0^t a_T(\alpha) a_T(\beta) \partial_t \{A(\alpha, x+t-\alpha) B(\beta, x-t+\beta) \\ &\quad + A(\alpha, x-t+\alpha) B(\beta, x+t-\beta)\} d\alpha d\beta \\ &\quad + 2a_T(t) (B(t, x) \partial_t \tilde{u} + A(t, x) \partial_t \tilde{v}). \end{aligned}$$

It follows that

$$\begin{aligned}
& \left\| \langle D_x \rangle^{s-2} a_T(t) \int_0^t \int_0^t a_T(\alpha) a_T(\beta) \partial_t \{A(\alpha, x+t-\alpha) B(\beta, x-t+\beta)\} d\alpha d\beta \right\|_{L_{t,x}^2} \\
& \leq \int_0^T \int_0^T a_T(\alpha) a_T(\beta) \left\| \langle D_x \rangle^{s-2} a_T(t) \partial_t A(\alpha, x+t-\alpha) B(\beta, x-t+\beta) \right\|_{L_{t,x}^2} d\alpha d\beta \\
& \leq \int_0^T \int_0^T a_T(\alpha) a_T(\beta) \left\| \langle D_x \rangle^{s-2} \partial_t \{a_T(t) A(\alpha, x+t-\alpha) B(\beta, x-t+\beta)\} \right\|_{L_{t,x}^2} d\alpha d\beta \\
& + \int_0^T \int_0^T a_T(\alpha) a_T(\beta) \left\| \langle D_x \rangle^{s-2} (\partial_t a_T(t)) A(\alpha, x+t-\alpha) B(\beta, x-t+\beta) \right\|_{L_{t,x}^2} d\alpha d\beta \\
& \equiv I_1 + I_2.
\end{aligned}$$

Applying Lemma 4.1 as in the proof of Lemma 4.2, we have

$$I_1 \leq C_1 \int_0^T \int_0^T \|A(\alpha, \cdot)\|_{H^{s-1}} \|B(\alpha, \cdot)\|_{H^{s-1}} d\alpha d\beta \leq C \|A\|_{X_1^{s-1}} \|B\|_{X_1^{s-1}}$$

and

$$I_2 \leq C_2 \int_0^T \int_0^T \|A(\alpha, \cdot)\|_{H^{s-1}} \|B(\alpha, \cdot)\|_{H^{s-1}} d\alpha d\beta \leq C \|A\|_{X_1^{s-1}} \|B\|_{X_1^{s-1}},$$

where  $C_1$  and  $C_2$  are constants depending on  $s$  and  $a_T$ . Since

$$\partial_t \tilde{u} = \int_0^t a_T(\alpha) \{A(\alpha, x+t-\alpha) + A(\alpha, x-t+\alpha)\} d\alpha$$

and

$$\partial_t \tilde{v} = \int_0^t a_T(\beta) \{B(\beta, x+t-\beta) + B(\beta, x-t+\beta)\} d\beta,$$

the same calculation as the above yields

$$\left\| \langle D_x \rangle^{s-2} a_T(t) \partial_t \tilde{u} B(t, x) \right\|_{L_{t,x}^2} \leq C \|A\|_{X_1^{s-1}} \|B\|_{Y_T^s}$$

and

$$\left\| \langle D_x \rangle^{s-2} a_T(t) \partial_t \tilde{v} A(t, x) \right\|_{L_{t,x}^2} \leq C \|B\|_{X_1^{s-1}} \|A\|_{Y_T^s}.$$

Therefore the proof is completed. ■

**Lemma 4.5.** *Let  $3/2 < s \leq 2$ . Suppose that  $P$  is the operator defined in (4.1) and  $(u, v)$  is a solution of the initial value problem (1.1) in  $(X_\rho^s \cap Y_{\rho,T}^s) \times (X_\rho^s \cap$*



$Y_{\rho,T}^s$ ) for some  $T > 0$ . If  $0 < \delta < T$  and  $0 \leq \epsilon < s - 1$ , then, for  $|t| < T - \delta$ , we have

$$\begin{aligned}
 (4.6) \quad & \left\| a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{s-2+\epsilon} (P(\partial_t \pm \partial_x)h(u,v)Q(u,v)) (t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2} \\
 & \leq C_1(\|u\|_{X^s}, \|v\|_{X^s}, \|u\|_{Y_T^s}, \|v\|_{Y_T^s}) \left\| a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{s-1+\epsilon} P u_\pm(t - \tilde{t}, x) \right\|_{L_{\tilde{t},x}^2} \\
 & \quad + C_2(\|u\|_{X^s}, \|v\|_{X^s}, \|u\|_{Y_T^s}, \|v\|_{Y_T^s}) \left\| a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{s-1+\epsilon} P v_\pm(t - \tilde{t}, x) \right\|_{L_{\tilde{t},x}^2} \\
 & \quad + C_3(\|u\|_{X^s}, \|v\|_{X^s}, \|u\|_{Y_T^s}, \|v\|_{Y_T^s}),
 \end{aligned}$$

where  $u_\pm = (\partial_t \pm \partial_x)u$ ,  $v_\pm = (\partial_t \pm \partial_x)v$ ,  $C_i(\|u\|_{X^s}, \|v\|_{X^s}, \|u\|_{Y_T^s}, \|v\|_{Y_T^s})$  ( $i = 1, 2, 3$ ) are constants depending on  $\|u\|_{X^s}$ ,  $\|v\|_{X^s}$ ,  $\|u\|_{Y_T^s}$  and  $\|v\|_{Y_T^s}$  and  $Q(u, v)$  stands either  $Q_0(u, v)$  or  $Q_1(u, v)$ .

*Proof.* It is enough to consider only the case  $Q(u, v) = Q_0(u, v)$ . Let  $b(\tilde{t}) \in C_0^\infty$  with  $\text{supp } b \subset \{|\tilde{t}| < T\}$  and  $b \equiv 1$  for  $|\tilde{t}| \leq \delta + \delta'$ , where  $\delta'$  is a positive constant satisfying  $|t| < \delta' < T - \delta$ . Then

$$\begin{aligned}
 (4.7) \quad & \left\| a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{s-2+\epsilon} (P(\partial_t \pm \partial_x)h(u,v)Q_0(u,v)) (t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2} \\
 & = \left\| b(t - \tilde{t}) a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{s-2+\epsilon} (P(\partial_t \pm \partial_x)h(u,v)Q_0(u,v)) (t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2} \\
 & \leq \left\| b(t - \tilde{t}) a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{s-2+\epsilon} (Ph_1 u_\pm Q_0(u,v)) (t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2} \\
 & \quad + \left\| b(t - \tilde{t}) a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{s-2+\epsilon} (Ph_2 v_\pm Q_0(u,v))(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2} \\
 & \quad + \left\| b(t - \tilde{t}) a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{s-2+\epsilon} (PhQ(u, v_\pm))(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2} \\
 & \quad + \left\| b(t - \tilde{t}) a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{s-2+\epsilon} (PhQ(u_\pm, v))(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2}
 \end{aligned}$$

as long as  $|t| < \delta'$ , where  $h_j$  ( $j = 1, 2$ ) are partial derivatives of  $h$ . Here, we have with  $[A, B] = AB - BA$ ,

$$\begin{aligned}
 (4.8) \quad & b(t - \tilde{t}) a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{s-2+\epsilon} (Ph_1 u_\pm Q_0(u,v))(t - \tilde{t}) \\
 & = [b(t - \tilde{t}) a_\delta(\tilde{t}), \Lambda_{\tilde{t},x}^{s-2+\epsilon}] (Ph_1 u_\pm Q_0(u,v))(t - \tilde{t}) \\
 & \quad + \Lambda_{\tilde{t},x}^{s-2+\epsilon} a_\delta(\tilde{t}) [b(t - \tilde{t}), P] (h_1 Q_0(u,v) u_\pm)(t - \tilde{t}) \\
 & \quad + \Lambda_{\tilde{t},x}^{s-2+\epsilon} a_\delta(\tilde{t}) [P, (bh_1 Q_0(u,v))(t - \tilde{t})] u_\pm(t - \tilde{t}) \\
 & \quad + \Lambda_{\tilde{t},x}^{s-2+\epsilon} a_\delta(\tilde{t}) (h_1 b Q_0(u,v))(t - \tilde{t}) (P u_\pm)(t - \tilde{t}).
 \end{aligned}$$

Since  $[b(t-\tilde{t})a_\delta(\tilde{t}), \Lambda_{\tilde{t},x}^{s-2+\epsilon}]$  and  $[b, P]$  are of order  $s-3+\epsilon$  and  $-1$  respectively and  $fgh \in H^{3s-5-\nu}$  for  $f, g, h \in H^{s-1}(\mathbb{R}^2)$  and any  $\nu > 0$ , thus for the first and second terms of the right hand side of (4.8), we have

$$\left\| [b(t-\tilde{t})a_\delta(\tilde{t}), \Lambda_{\tilde{t},x}^{s-2+\epsilon}](Ph_1u_\pm Q_0(u, v))(t-\tilde{t}) \right\|_{L_{\tilde{t},x}^2} < \infty$$

and

$$\left\| \Lambda_{\tilde{t},x}^{s-2+\epsilon} a_\delta(\tilde{t}) ([b(t-\tilde{t}), P]h_1Q_0(u, v)u_\pm)(t-\tilde{t}) \right\|_{L_{\tilde{t},x}^2} < \infty.$$

In the same way, as the proof of Lemma 4.2, for the third term of the right hand side of (4.8) we have

$$\left\| \Lambda_{\tilde{t},x}^{s-2+\epsilon} a_\delta(\tilde{t}) ([P, (bh_1Q_0(u, v))(t-\tilde{t})]u_\pm)(t-\tilde{t}) \right\|_{L_{\tilde{t},x}^2} < \infty.$$

Now, we estimate the fourth term of (4.8). For simplicity, we put  $\eta = (\tilde{\tau}, \xi)$  and  $\eta' = (\tilde{\tau}', \xi')$ . Then

$$\begin{aligned} \langle \eta \rangle^{s-2+\epsilon} \mathcal{F}_{\tilde{t},x} [ (h_1bQ_0(u, v))(t-\tilde{t})a_\delta(\tilde{t})Pu_\pm(t-\tilde{t}) ] (\eta) \\ = \int K_1(\eta, \eta') \theta_t^{(1)}(\eta') \theta_t^{(2)}(\eta - \eta') d\eta', \end{aligned}$$

where  $\theta_t^{(1)}(\eta) = \langle \eta \rangle^{s-1} \mathcal{F}_{\tilde{t},x} [h_1bQ_0(u, v)(t-\tilde{t})]$ ,  $\theta_t^{(2)}(\eta) = \langle \eta \rangle^{s-1+\epsilon} \mathcal{F}_{\tilde{t},x} [a_\delta(\tilde{t})Pu_\pm(t-\tilde{t})]$  and  $|K_1(\eta, \eta')| = \frac{\langle \eta \rangle^{s-2+\epsilon}}{\langle \eta' \rangle^{s-1} \langle \eta - \eta' \rangle^{s-1+\epsilon}}$ . By Lemma 4.1, we have

$$\begin{aligned} & \left\| \Lambda_{\tilde{t},x}^{s-2+\epsilon} (h_1bQ_0(u, v))(t-\tilde{t})a_\delta(\tilde{t})(Pu_\pm)(t-\tilde{t}) \right\|_{L_{\tilde{t},x}^2} \\ & \leq C \|\theta_t^{(1)}\|_{L_{\tilde{t},x}^2} \|\theta_t^{(2)}\|_{L_{\tilde{t},x}^2} \\ & \leq C' \|h_1bQ_0(u, v)\|_{H^{s-1}} \\ & \quad \times \left( \left\| a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{s-1+\epsilon} Pu_\pm(t-\tilde{t}) \right\|_{L_{\tilde{t},x}^2} + \left\| [\Lambda_{\tilde{t},x}^{s-1+\epsilon}, a_\delta(\tilde{t})] Pu_\pm(t-\tilde{t}) \right\|_{L_{\tilde{t},x}^2} \right) \end{aligned}$$

as long as  $0 \leq \epsilon < s-1$ . Thus we obtain

$$\begin{aligned} (4.9) \quad & \left\| b(t-\tilde{t})a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{s-2+\epsilon} (Ph_1u_\pm Q_0(u, v))(t-\tilde{t}) \right\|_{L_{\tilde{t},x}^2} \\ & \leq C'_1 (\|u\|_{X^s}, \|v\|_{X^s}, \|u\|_{Y_T^s}, \|v\|_{Y_T^s}) \left\| a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{s-1+\epsilon} Pu_\pm(t-\tilde{t}) \right\|_{L_{\tilde{t},x}^2} \\ & \quad + C'_2 (\|u\|_{X^s}, \|v\|_{X^s}, \|u\|_{Y_T^s}, \|v\|_{Y_T^s}). \end{aligned}$$

Since  $Q_0(u, v_\pm) = 1/2\{u_+(\partial_t - \partial_x)v_\pm + u_-(\partial_t + \partial_x)v_\pm\}$ , we have

$$(4.10) \quad 2 \left\| b(t - \tilde{t})a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{s-2+\epsilon}(PhQ(u, v_\pm))(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2} \\ \leq \left\| b(t - \tilde{t})a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{s-2+\epsilon}(Phu_+(\partial_t - \partial_x)v_\pm)(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2} \\ + \left\| b(t - \tilde{t})a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{s-2+\epsilon}(Phu_-(\partial_t + \partial_x)v_\pm)(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2}.$$

In the same way as the estimates of (4.8), we have

$$(4.11) \quad b(t - \tilde{t})a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{s-2+\epsilon}(Phu_+(\partial_t - \partial_x)v_\pm)(t - \tilde{t}) \\ = [b(t - \tilde{t})a_\delta(\tilde{t}), \Lambda_{\tilde{t},x}^{s-2+\epsilon}](Phu_+(\partial_t - \partial_x)v_\pm)(t - \tilde{t}) \\ + \Lambda_{\tilde{t},x}^{s-2+\epsilon}a_\delta(\tilde{t})([b(t - \tilde{t}), P]hu_+(\partial_t - \partial_x)v_\pm)(t - \tilde{t}) \\ + \Lambda_{\tilde{t},x}^{s-2+\epsilon}a_\delta(\tilde{t})[P, b(t - \tilde{t})]hu_+(\partial_t - \partial_x)v_\pm \\ - \Lambda_{\tilde{t},x}^{s-2+\epsilon}(bhu_+)(t - \tilde{t})[a_\delta(\tilde{t}), \partial_{\tilde{t}} + \partial_x](Pv_\pm)(t - \tilde{t}) \\ - \Lambda_{\tilde{t},x}^{s-2+\epsilon}(bu_+h)(t - \tilde{t})(\partial_{\tilde{t}} + \partial_x)a_\delta(\tilde{t})(Pv_\pm)(t - \tilde{t})$$

and first, second and fourth terms of the right hand side of (4.11) are in  $L_{\tilde{t},x}^2$ . By Lemma 4.2, third term is in  $L_{\tilde{t},x}^2$ . Now, we estimate the fifth term of (4.11). Putting  $\theta_t^{(3)}(\eta) = \langle \eta \rangle^{s-1}(1 + |\tilde{\tau} - \xi|)\mathcal{F}_{\tilde{t},x}[(bhu_+)(t - \tilde{t})]$ ,  $\theta_t^{(4)}(\eta) = \langle \eta \rangle^{s-1+\epsilon}\mathcal{F}_{\tilde{t},x}[a_\delta(\tilde{t})Pv_\pm(t - \tilde{t})]$  and

$$|K_2(\eta, \eta')| = \frac{\langle \eta \rangle^{s-2+\epsilon}|\tilde{\tau}' + \xi'|}{\langle \eta' \rangle^{s-1}\langle \eta - \eta' \rangle^{s-1+\epsilon}(1 + |(\tilde{\tau} - \tilde{\tau}') - (\xi - \xi')|)},$$

we have

$$\langle \eta \rangle^{s-2+\epsilon}\mathcal{F}_{\tilde{t},x}[(bu_+h)(t - \tilde{t})(\partial_{\tilde{t}} + \partial_x)a_\delta(\tilde{t})(Pv_\pm)(t - \tilde{t})](\eta) \\ = \int K_2(\eta, \eta')\theta_t^{(3)}(\eta')\theta_t^{(4)}(\eta - \eta')d\eta'.$$

By Lemma 4.1, we have

$$\left\| \Lambda_{\tilde{t},x}^{s-2+\epsilon}(bu_+h)(t - \tilde{t})(\partial_{\tilde{t}} + \partial_x)a_\delta(\tilde{t})(Pv_\pm)(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2} \\ \leq C\|\theta_t^{(3)}\|_{L_{\tilde{t},x}^2}\|\theta_t^{(4)}\|_{L_{\tilde{t},x}^2} \\ \leq C\|h\|_{H^s}(\|u_\pm\|_{H^{s-1}} + \|\partial_{\tilde{t}}b u_+\|_{H^{s-1}} + \|b(t)\square u\|_{H^{s-1}}) \\ \times \left( \left\| a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{s-2+\epsilon}Pv_\pm(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2} + \left\| [\Lambda_{\tilde{t},x}^{s-2+\epsilon}, a_\delta(\tilde{t})]Pv_\pm(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2} \right).$$

Therefore we obtain

$$\begin{aligned}
 (4.12) \quad & \left\| b(t - \tilde{t}) a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{s-2+\epsilon} (Phu_+(\partial_t - \partial_x)v_\pm)(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2} \\
 & \leq C'_3 (\|u\|_{X^s}, \|v\|_{X^s}, \|u\|_{Y_T^s}, \|v\|_{Y_T^s}) \left\| a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{s-2+\epsilon} P v_\pm(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2} \\
 & \quad + C'_4 (\|u\|_{X^s}, \|v\|_{X^s}, \|u\|_{Y_T^s}, \|v\|_{Y_T^s}).
 \end{aligned}$$

By (4.9) and (4.12), we have the conclusion. ■

Now, we prove the main theorem.

**Proof of Theorem 1.3.** Since  $(\partial_t + \partial_x)$  or  $(\partial_t - \partial_x)$  is elliptic near  $\Gamma$ , it suffices to show that  $(\partial_t \pm \partial_x)u, (\partial_t \pm \partial_x)v \in H_{ml}^{r-1}(\Gamma)$  for  $|t| < T$ . Let  $u_\pm = (\partial_t \pm \partial_x)u$  and  $v_\pm = (\partial_t \pm \partial_x)v$ . Multiplying  $(\partial_t \pm \partial_x)$  to the both sides of (1.1), we have

$$(4.13) \quad \square u_\pm = (\partial_t \pm \partial_x)A(u, v),$$

where

$$\begin{aligned}
 (4.14) \quad & A(u, v) \\
 & = h_1(u, v)Q_0(u, u) + h_2(u, v)Q_0(u, v) + h_3(u, v)Q_0(v, v) + h_4(u, v)Q_1(u, v).
 \end{aligned}$$

Applying the operator  $P$  defined in (4.1) to the both sides of (4.13), We have

$$\begin{aligned}
 (4.15) \quad & \square P u_\pm = [\square, P]u_\pm + P \square u_\pm \\
 & = [\square, P]u_\pm + P(\partial_t \pm \partial_x)A(u, v).
 \end{aligned}$$

Let

$$\begin{aligned}
 E(t; u, v) \equiv & \left\| a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{r-2} \partial_{\tilde{t}} P u_\pm(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2}^2 + \left\| a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{r-2} \partial_x P u_\pm(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2}^2 \\
 & + \left\| a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{r-2} P u_\pm(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2}^2 + \left\| a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{r-2} \partial_{\tilde{t}} P v_\pm(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2}^2 \\
 & + \left\| a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{r-2} \partial_x P v_\pm(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2}^2 + \left\| a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{r-2} P v_\pm(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2}^2,
 \end{aligned}$$

where  $\Lambda = \langle D \rangle$  and  $0 < \delta < T$ . Let  $\varphi \in C_0^\infty(\mathbb{R})$ ,  $\int \varphi(x) dx = 1$ ,  $\varphi_\omega(x) = \frac{1}{\omega} \varphi(\frac{x}{\omega})$  and put  $u_0^\omega = \varphi_\omega * u_0$ ,  $u_1^\omega = \varphi_\omega * u_1$ ,  $v_0^\omega = \varphi_\omega * v_0$  and  $v_1^\omega = \varphi_\omega * v_1$ . Let  $(u_\omega, v_\omega)$  be a smooth solution of  $u_\omega = f_0^\omega(t, x) + \int_0^t U(t - \alpha) a_T(\alpha) (\varphi_\omega * A(u_\omega, v_\omega)) d\alpha$ ,  $v_\omega = g_0^\omega(t, x) + \int_0^t U(t - \alpha) a_T(\alpha) (\varphi_\omega * B(u_\omega, v_\omega)) d\alpha$  where  $f_0^\omega(t, x) = \frac{1}{2} \{u_0^\omega(x + t) + u_0^\omega(x - t)\} + \frac{1}{2} \int_{x-t}^{x+t} u_1^\omega(y) dy$ ,  $g_0^\omega(t, x) = \frac{1}{2} \{v_0^\omega(x +$

$t) + v_0^\omega(x-t)\} + \frac{1}{2} \int_{x-t}^{x+t} v_1^\omega(y)dy$ . Using the same technique as in the proof of Lemma 3.2 and Lemma 3.3, we have

$$\|u - u_\omega\|_{X^s} \rightarrow 0, \quad \|u - u_\omega\|_{Y_T^s} \rightarrow 0 \quad \text{as } \omega \rightarrow 0.$$

Hence  $\|u_\omega\|_{X^s} \leq C\|u\|_{X^s}$  and  $\|u_\omega\|_{X^s} \leq C\|v\|_{X^s}$  for  $0 < \forall \omega \leq 1$ . Similarly, we have  $\|v_\omega\|_{X^s} \leq C\|u\|_{X^s}$  and  $\|v_\omega\|_{X^s} \leq C\|v\|_{X^s}$ . By the calculus of pseudo differential operators and the Schwarz inequality, we have

$$\begin{aligned} & \frac{1}{2} \frac{dE(t; u_\omega, v_\omega)}{dt} \\ &= -\operatorname{Re}\langle a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}\square Pu_{\omega,\pm}(t-\tilde{t}), a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}\partial_{\tilde{t}}(Pu_{\omega,\pm}(t-\tilde{t})) \rangle \\ & \quad + \operatorname{Re}\langle a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}\partial_{\tilde{t}}(Pu_{\omega,\pm}(t-\tilde{t})), a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}Pu_{\omega,\pm}(t-\tilde{t}) \rangle \\ & \quad - \operatorname{Re}\langle a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}\square Pv_{\omega,\pm}(t-\tilde{t}), a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}\partial_{\tilde{t}}(Pv_{\omega,\pm}(t-\tilde{t})) \rangle \\ & \quad + \operatorname{Re}\langle a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}\partial_{\tilde{t}}(Pv_{\omega,\pm}(t-\tilde{t})), a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}Pv_{\omega,\pm}(t-\tilde{t}) \rangle \\ & \leq \left\| a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}\square Pu_{\omega,\pm}(t-\tilde{t}) \right\|_{L_{\tilde{t},x}^2} \cdot \left\| a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}\partial_{\tilde{t}}(Pu_{\omega,\pm}(t-\tilde{t})) \right\|_{L_{\tilde{t},x}^2} \\ & \quad + \left\| a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}\partial_{\tilde{t}}(Pu_{\omega,\pm}(t-\tilde{t})) \right\|_{L_{\tilde{t},x}^2} \cdot \left\| a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}Pu_{\omega,\pm}(t-\tilde{t}) \right\|_{L_{\tilde{t},x}^2} \\ & \quad + \left\| a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}\square Pv_{\omega,\pm}(t-\tilde{t}) \right\|_{L_{\tilde{t},x}^2} \cdot \left\| a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}\partial_{\tilde{t}}(Pv_{\omega,\pm}(t-\tilde{t})) \right\|_{L_{\tilde{t},x}^2} \\ & \quad + \left\| a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}\partial_{\tilde{t}}(Pv_{\omega,\pm}(t-\tilde{t})) \right\|_{L_{\tilde{t},x}^2} \cdot \left\| a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}Pv_{\omega,\pm}(t-\tilde{t}) \right\|_{L_{\tilde{t},x}^2} \\ & \leq \frac{1}{2} \left\| a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}\square Pu_{\omega,\pm}(t-\tilde{t}) \right\|_{L_{\tilde{t},x}^2}^2 + \frac{1}{2} \left\| a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}\square Pv_{\omega,\pm}(t-\tilde{t}) \right\|_{L_{\tilde{t},x}^2}^2 \\ & \quad + 3E(t; u_\omega, v_\omega), \end{aligned}$$

where  $u_{\omega,\pm} = (\partial_t \pm \partial_x)u_\omega$ ,  $v_{\omega,\pm} = (\partial_t \pm \partial_x)v_\omega$ . By (4.15) we have

$$\begin{aligned} & \left\| a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}\square Pu_{\omega,\pm}(t-\tilde{t}) \right\|_{L_{\tilde{t},x}^2}^2 \\ & \leq \left\| a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}[\square, P]u_{\omega,\pm}(t-\tilde{t}) \right\|_{L_{\tilde{t},x}^2}^2 \\ & \quad + \left\| a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}P(\partial_t \pm \partial_x)A(u_\omega, v_\omega)(t-\tilde{t}) \right\|_{L_{\tilde{t},x}^2}^2. \end{aligned}$$

Since  $r < 2s - 1$  and  $[\square, P]$  is of order 0,

$$\left\| a_\delta(\tilde{t})\Lambda_{\tilde{t},x}^{r-2}[\square, P]u_{\omega,\pm}(t-\tilde{t}) \right\|_{L_{\tilde{t},x}^2}^2 < \infty.$$

By (4.14), Lemma 4.5 and the triangle inequality, we have

(4.16)

$$\begin{aligned} & \left\| a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{r-2} P(\partial_t \pm \partial_x) A(u_\omega, v_\omega)(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2}^2 \\ & \leq \left( C_1 \left\| a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{r-1} P u_{\omega,\pm}(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2} + C_2 \left\| a_\delta(\tilde{t}) \Lambda_{\tilde{t},x}^{r-1} P v_{\omega,\pm}(t - \tilde{t}) \right\|_{L_{\tilde{t},x}^2} + C_3 \right)^2 \\ & \leq C_4 E(t; u_\omega, v_\omega) + C_5 \end{aligned}$$

for  $\delta < T$ ,  $|t| < T - \delta$  and  $r < 2s - 1$ , where  $C_i$  ( $i = 1, 2, 3, 4, 5$ ) are positive constants depending on  $\|u\|_{X^s}$ ,  $\|v\|_{X^s}$ ,  $\|u\|_{Y_T^s}$  and  $\|v\|_{Y_T^s}$ . Therefore we obtain

$$\frac{dE(t; u_\omega, v_\omega)}{dt} \leq C'_1 E(t; u_\omega, v_\omega) + C'_2.$$

By Gronwall's inequality, we have

$$E(t, u_\omega, v_\omega) \leq e^{C'_1 t} \left\{ E(0, u_\omega, v_\omega) + \frac{C'_2}{C'_1} (1 - e^{-C'_1 t}) \right\}.$$

Taking the limit of the above inequality as  $\omega \rightarrow 0$ , we have

$$E(t; u, v) \leq e^{C'_1 t} \left\{ E(0, u, v) + \frac{C'_2}{C'_1} (1 - e^{-C'_1 t}) \right\} < \infty$$

since  $E(0; u, v) < \infty$ . Hence  $Pu_\pm \in H^{r-1}$  for  $|t| < T - \delta$ . If we take sufficiently small  $\delta > 0$ , then we have  $Pu_\pm \in H^{r-1}$  for  $|t| < T$  and  $r < 2s - 1$ . Hence we have  $u_\pm \in H_{ml}^{r-1}(\Gamma)$  for  $|t| < T$ . Similarly, we have  $v_\pm \in H_{ml}^{r-1}(\Gamma)$  for  $|t| < T$ . Therefore we have  $(u, v) \in H_{ml}^r(\Gamma) \times H_{ml}^r(\Gamma)$  for  $|t| < T$  and  $r < 2s - 1$ . ■

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