# J. DIFFERENTIAL GEOMETRY 83 (2009) 273-288

# ISOTROPIC JACOBI FIELDS ON COMPACT 3-SYMMETRIC SPACES

JOSÉ CARMELO GONZÁLEZ-DÁVILA

#### Abstract

We prove that a compact Riemannian 3-symmetric space is globally symmetric if every Jacobi field along a geodesic vanishing at two points is the restriction to that geodesic of a Killing field induced by the isotropy action or, in particular, if the isotropy action is variationally complete.

#### 1. Introduction

A Jacobi field V on a homogeneous Riemannian manifold (M, g)which is the restriction of a Killing vector field along a geodesic is called *isotropic* [10]. It means that V is the restriction of an infinitesimal motion of elements in the Lie algebra of the isometry group I(M, g)of (M, g). Moreover, if V vanishes at a point o of the geodesic then it is obtained as restriction of an infinitesimal K-motion, being K the isotropy subgroup of I(M, g) at  $o \in M$ . This particular situation was what originally motivated the term "isotropic" (see [2] and [3]).

The Jacobi equation on a symmetric space has simple solutions and one can directly show that all Jacobi field vanishing at two points is isotropic (see for example [4]). In the case of a naturally reductive space, the adapted canonical connection has the same geodesics and the Jacobi equation can be also written as a differential equation with constant coefficients (equation (2.7)). Using this fact, I. Chavel in [2] (see also [3]) proved that all simply connected normal Riemannian homogeneous space (M = G/K, g) of rank one with the property that all Jacobi fields vanishing at two points are G-isotropic, i.e. restrictions of infinitesimal G-motions along geodesics, are homeomorphic to a rank one symmetric space. Afterwards, W. Ziller in [10] proposed to examine conjectures like:

A naturally reductive space with the property that all Jacobi fields vanishing at two points are isotropic is locally symmetric.

Research supported by a grant from MEC (Spain), project MTM2007-65852. Received 07/12/2005.

In this paper, we consider a Riemannian 3-symmetric space  $(M = G/K, \sigma, <, >)$ , where G is a compact connected Lie group acting effectively and the inner product <, > determines an adapted naturally reductive metric on M, or equivalently, the canonical almost complex structure J is nearly Kählerian [5]. Then, we find geodesics on non-symmetric spaces  $(M = G/K, \sigma, <, >)$  admitting Jacobi fields vanishing at two points which are not G-isotropic. It allows us to prove the following theorem:

**Theorem 1.1.** A compact Riemannian 3-symmetric space  $(M = G/K, \sigma, <, >)$  with the property that all Jacobi fields vanishing at two points are G-isotropic is a symmetric space.

When  $(M = G/K, \sigma, <, >)$  is moreover simply connected, irreducible and not isometric to a symmetric space, G coincides with the identity component  $I_o(M,g)$  of I(M,g) [8, Theorem 3.6]. Then, we have

**Corollary 1.2.** A compact irreducible simply connected Riemannian 3-symmetric space is a symmetric space if and only if all Jacobi field vanishing at two points is isotropic.

R. Bott and H. Samelson introduced in [1] the notion of variationally complete action and they obtained that the isotropy action, i.e. the action of an isotropy subgroup K as subgroup of G, on a symmetric space of compact type is variationally complete (for the definition of variationally complete action, see section 2). Using Lemma 2.1, we can conclude

**Corollary 1.3.** If the isotropy action of K on a compact Riemannian 3-symmetric space  $(M = G/K, \sigma, <, >)$  is variationally complete then it is a symmetric space.

# 2. Variational completeness. Isotropic Jacobi fields

Let (M, g) be a connected homogeneous Riemannian manifold. Then (M, g) can be expressed as coset space G/K, where G is a Lie group, which is supposed to be connected, acting transitively and effectively on M, K is the isotropy subgroup of G at some point  $o \in M$  and g is a G-invariant Riemannian metric. Moreover, we can assume that G/K is a reductive homogeneous space, i.e., there is an Ad(K)-invariant subspace  $\mathfrak{m}$  of the Lie algebra  $\mathfrak{g}$  of G such that  $\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{k}, \mathfrak{k}$  being the Lie algebra of K. (M = G/K, g) is said to be naturally reductive, or more precisely G-naturally reductive, if there exists a reductive decomposition  $\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{k}$  satisfying

(2.1)  $< [X,Y]_{\mathfrak{m}}, Z > + < [X,Z]_{\mathfrak{m}}, Y > = 0$ 

for all  $X, Y, Z \in \mathfrak{m}$ , where  $[X, Y]_{\mathfrak{m}}$  denotes the  $\mathfrak{m}$ -component of [X, Y]and  $\langle \rangle$  is the metric induced by g on  $\mathfrak{m}$ , or equivalently,  $[X, \cdot]_{\mathfrak{m}} : \mathfrak{m} \to$ 

 $\mathfrak{m}$  is skew-symmetric for all  $X \in \mathfrak{m}$ . When there exists a bi-invariant metric on  $\mathfrak{g}$  whose restriction to  $\mathfrak{m} = \mathfrak{k}^{\perp}$  is the metric  $\langle , \rangle$ , the (naturally reductive) space (M = G/K, g) is called *normal homogeneous*. Then, for all  $X, Y, Z \in \mathfrak{g}$ , we have

(2.2) 
$$< [X,Y], Z > + < [X,Z], Y > = 0.$$

For each  $X \in \mathfrak{g}$ , the mapping  $\psi : \mathbb{R} \times M \to M$ ,  $(t, p) \in \mathbb{R} \times M \mapsto \psi_t(p) = (\exp tX)p$  is a one-parameter group of isometries and consequently,  $\psi$  induces a Killing vector field  $X^*$  given by

(2.3) 
$$X_p^* = \frac{d}{dt}_{|t=0}(\exp tX)p, \quad p \in M.$$

 $X^*$  is called the fundamental vector field or the infinitesimal G-motion corresponding to X on M. If  $G = I_o(M, g)$ , then all (complete) Killing vector field on M is a fundamental vector field  $X^*$ , for some  $X \in \mathfrak{g}$ .

For any  $a \in G$ , we have

$$(a\exp tX)a^{-1} = \exp(tAd_aX).$$

This implies

(2.4) 
$$(Ad_a X)^*_{ap} = a_{*p} X^*_p,$$

where  $a_{*p}$  denotes the differential map of a at  $p \in M$ .

The K-orbit  $O_p(K) = \{kp \mid k \in K\}$ , for each  $p \in M$ , is a regular submanifold of M and, from (2.3), its tangent space  $T_pO_p(K)$  at p is given by

$$T_p O_p(K) = \{ A_p^* \mid A \in \mathfrak{k} \}.$$

A geodesic  $\gamma = \gamma(t)$  of (M = G/K, g) is called *K*-transversal if for each  $t \in \mathbb{R}$  the tangent vector  $\gamma'(t)$  is orthogonal to the *K*-orbit  $O_{\gamma(t)}(K)$  at  $\gamma(t)$ . Since a geodesic which is orthogonal to a Killing vector field at one of its points it is orthogonal to it at all of points, this condition is equivalent to require only the existence of a  $t_o \in \mathbb{R}$  such that  $\gamma'(t_o)$  is orthogonal to  $O_{\gamma(t_o)}(K)$  at  $\gamma(t_o)$ . A Jacobi field *V* along  $\gamma$  is said to be *K*-transversal if it is derived from a geodesic variation  $\phi$ of  $\gamma$  in which all geodesic  $t \to \phi(t, s_o)$  is *K*-transversal. Any restriction of a Killing field to a *K*-transversal geodesic induced by the isotropy action is *K*-transversal [1, Proposition 6.6].

The action of K on M = G/K, as subgroup of G, is said to be variationally complete [1] if every K-transversal Jacobi field V along a (transversal) geodesic  $\gamma$  with  $V(t_0) = 0$ , for some  $t_0 \in \mathbb{R}$ , and for which there exists  $t_1 \neq t_0$  such that  $V(t_1)$  is tangent to the K-orbit of  $\gamma(t_1)$  is G-isotropic.

Let  $K_p = \{a \in G \mid a(p) = p\}$  be the isotropy subgroup at a point  $p \in M$ . In particular,  $K_o = K$ , where o denotes the origin of G/K.

Let  $a \in G$  such that p = a(o). The elements of  $K_p$  are obtained by conjugation of elements of K by a, i.e.,

$$K_n = aKa^{-1}$$

and hence, the Lie algebra  $\mathfrak{k}_p$  of  $K_p$  is given by

(2.5) 
$$\mathfrak{k}_p = A d_a \mathfrak{k}.$$

From (2.4), a geodesic  $\gamma$  on (M, g) is K-transversal if and only if  $a \circ \gamma$  is  $K_p$ -transversal and V is a K-transversal (resp. G-isotropic) Jacobi field along  $\gamma$  if and only if  $a_*V$  is  $K_p$ -transversal (resp. G-isotropic) along  $a \circ \gamma$ . Hence, taking into account that any Jacobi field V along a geodesic  $\gamma$  starting at a point  $p \in M$  with V(0) = 0 is always  $K_p$ -transversal, we directly obtain

**Lemma 2.1.** If the isotropy action of K on M = G/K is variationally complete, then:

- (i) the action of the isotropy subgroup  $K_p$  at p, for all  $p \in M$ , is variationally complete;
- (ii) all Jacobi field vanishing at two points is G-isotropic.

Next, let  $\tilde{T}$  denote the torsion tensor and  $\tilde{R}$  the curvature tensor of the *canonical connection*  $\tilde{\nabla}$  of (M, g) adapted to the reductive decomposition  $\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{k}$  [7, I, p.110]. Because  $\tilde{\nabla}$  is a *G*-invariant affine connection, these tensors (under the canonical identification of  $\mathfrak{m}$  with the tangent space  $T_oM$  of the origin o) are given by

(2.6) 
$$\tilde{T}_o(X,Y) = -[X,Y]_{\mathfrak{m}} , \quad \tilde{R}_o(X,Y) = \operatorname{ad}_{[X,Y]_{\mathfrak{k}}}$$

for  $X, Y \in \mathfrak{m}$ , where  $[X, Y]_{\mathfrak{k}}$  denotes the  $\mathfrak{k}$ -component of [X, Y].

On naturally reductive spaces,  $\nabla$  and  $\tilde{\nabla}$  have the same geodesics and, consequently, the same Jacobi fields (see [10]). Such geodesics are orbits of one-parameter subgroups of G of type  $\exp tu$  where  $u \in \mathfrak{m}$ . Then, taking into account that  $\tilde{\nabla}\tilde{T} = \tilde{\nabla}\tilde{R} = 0$  and the parallel translation with respect to  $\tilde{\nabla}$  of tangent vectors at the origin o along  $\gamma(t) = (\exp tu)o$ ,  $u \in \mathfrak{m}, ||u|| = 1$ , coincides with the differential of  $\exp tu \in G$  acting on M, it follows that the Jacobi equation can be expressed as the differential equation

(2.7) 
$$X'' - \tilde{T}_u X' + \tilde{R}_u X = 0$$

in the vector space  $\mathfrak{m}$ , where  $\tilde{T}_u X = \tilde{T}(u, X) = -[u, X]_{\mathfrak{m}}$  and  $\tilde{R}_u X = \tilde{R}(u, X)u = [[u, X]_{\mathfrak{k}}, u]$ . The operator  $\tilde{T}_u$  is skew-symmetric with respect to  $\langle , \rangle, \tilde{R}_u$  is self-adjoint and they satisfy [4]

$$(2.8) R_u = \tilde{R}_u - \frac{1}{4}\tilde{T}_u^2.$$

A Jacobi field V along  $\gamma(t) = (\exp tu)o$  with V(0) = 0 is G-isotropic if and only if there exists an  $A \in \mathfrak{k}$  such that (see [4])

(2.9) 
$$V'(0) = [A, u].$$

Then,  $V = A^* \circ \gamma$ .

We shall need the following characterization for G-isotropic Jacobi fields on normal homogeneous spaces (M = G/K, g).

**Lemma 2.2.** A Jacobi field V along  $\gamma(t) = (\exp tu)o$  on a normal homogeneous space (M = G/K, g) with V(0) = 0 is G-isotropic if and only if  $V'(0) \in (\text{Ker } \tilde{R}_u)^{\perp}$ .

*Proof.* From (2.9), we have to show that

(2.10) 
$$(\operatorname{Ker} \dot{R}_u)^{\perp} \cap \mathfrak{m} = [u, \mathfrak{k}]$$

For each  $v \in \mathfrak{m}$ , using (2.2), we get

$$<\tilde{R}_uv,v>=<[[u,v]_{\mathfrak{k}},u],v>=<[u,v]_{\mathfrak{k}},[u,v]_{\mathfrak{k}}>.$$

Hence,  $v \in \text{Ker } R_u$  if and only if  $[u, v]_{\mathfrak{k}} = 0$ . But,

$$[u,v]_{\mathfrak{k}} = 0 \Leftrightarrow 0 = <[u,v]_{\mathfrak{k}}, \mathfrak{k} > = - <[u,\mathfrak{k}], v > \Leftrightarrow v \in [u,\mathfrak{k}]^{\perp}$$

Then, we obtain (2.10) and it gives the result.

q.e.d.

Next, we give conditions to obtain Jacobi fields along  $\gamma$  vanishing at two points which are or not G-isotropic.

**Proposition 2.3.** Let u, v be orthonormal vectors in  $\mathfrak{m}$  such that  $[[u, v], u] = \lambda v$ , for some  $\lambda > 0$ . We have:

(i) If  $[u, v]_{\mathfrak{m}} = 0$ , then the vector fields V(t) along  $\gamma(t) = (\exp tu)o$  given by

$$V(t) = (\exp tu)_{*o} \left(A \sin \sqrt{\lambda} tv\right),$$

for A constant, are G-isotropic Jacobi fields with  $V(\frac{p\pi}{\sqrt{\lambda}}) = 0$ , for all  $p \in \mathbb{Z}$ .

(ii) If  $[u, v] \in \mathfrak{m} \setminus \{0\}$ , then the vector fields V(t) along  $\gamma(t) = (\exp tu)o$  given by

$$V(t) = (\exp tu)_{*o} \Big( \Big( A \sin \sqrt{\lambda}t + B(1 - \cos \sqrt{\lambda}t) \Big) v \\ + \Big( -A(1 - \cos \sqrt{\lambda}t) + B \sin \sqrt{\lambda}t \Big) w \Big),$$

for A, B constants with  $w = \frac{1}{\sqrt{\lambda}}[u, v]$ , are Jacobi fields such that  $V(\frac{2p\pi}{\sqrt{\lambda}}) = 0$ , for all  $p \in \mathbb{Z}$ , which are not G-isotropic.

*Proof.* (i) From (2.6) we get  $\tilde{T}_u v = 0$  and  $\tilde{R}_u v = \lambda v$ . Then it is easy to see that  $X(t) = A \sin \sqrt{\lambda} t v$  is a solution of (2.7) with X(0) = 0. Because  $\tilde{R}_u$  is self-adjoint,  $v \in (\text{Ker } \tilde{R}_u)^{\perp}$  and from Lemma 2.2,  $V(t) = (\exp t u)_{*o} X(t)$  is G-isotropic.

(ii) Here, we obtain

$$\tilde{T}_u v = -\sqrt{\lambda}w, \quad \tilde{T}_u w = \sqrt{\lambda}v, \quad \tilde{R}_u v = \tilde{R}_u w = 0$$

and, from (2.2),  $||[u, v]|| = \sqrt{\lambda}$ . Then the solutions  $X(t) = X^1(t)v + X^2(t)w$  of (2.7) satisfy

$$\begin{cases} Y^{1'}(t) - \sqrt{\lambda}Y^2(t) = 0, \\ Y^{2'}(t) + \sqrt{\lambda}Y^1(t) = 0, \end{cases}$$

where  $Y^{i}(t) = X^{i'}(t)$ , i = 1, 2. Hence X(t) with X(0) = 0 is given by  $X(t) = \left(A \sin \sqrt{\lambda}t + B(1 - \cos \sqrt{\lambda}t)\right)v + \left(-A(1 - \cos \sqrt{\lambda}t) + B \sin \sqrt{\lambda}t\right)w$ , for A, B constants. Hence,  $V(t) = (\exp tu)_{*o}X(t)$  are Jacobi fields along  $\gamma$  verifying  $V(0) = V(\frac{2p\pi}{\sqrt{\lambda}}) = 0$  and V'(0) = X'(0). Because  $X'(0) \in \mathbb{R}\{v, w\}$  and  $[u, v]_{\mathfrak{k}} = [u, w]_{\mathfrak{k}} = 0$ , we have  $\tilde{R}_{u}V'(0) = 0$  and Lemma 2.2

implies that these Jacobi fields V are not G-isotropic. q.e.d.

#### 3. Compact irreducible Riemannian 3-symmetric spaces

We recall that a connected Riemannian manifold (M, g) is called a 3symmetric space [5] if it admits a family of isometries  $\{\theta_p\}_{p \in M}$  of (M, g)satisfying

- (i)  $\theta_p^3 = I$ ,
- (ii) p is an isolated fixed point of  $\theta_p$ ,
- (iii) the tensor field  $\Theta$  defined by  $\Theta = (\theta_p)_{*p}$  is of class  $C^{\infty}$ ,
- (iv)  $\theta_{p*} \circ J = J \circ \theta_{p*}$ ,

where J is the canonical almost complex structure associated with the family  $\{\theta_p\}_{p\in M}$  given by  $J = \frac{1}{\sqrt{3}}(2\Theta + I)$ . Riemannian 3-symmetric spaces are characterized by a triple  $(G/K, \sigma, <, >)$  satisfying the following conditions:

- (1) G is a connected Lie group and  $\sigma$  is an automorphism of G of order 3,
- (2) K is a closed subgroup of G such that  $G_o^{\sigma} \subseteq K \subseteq G^{\sigma}$ , where  $G^{\sigma} = \{x \in G \mid \sigma(x) = x\}$  and  $G_o^{\sigma}$  denotes its identity component,
- (3) <, > is an Ad(K)- and  $\sigma$ -invariant inner product on the vector space  $\mathfrak{m} = (\mathfrak{m}^+ \oplus \mathfrak{m}^-) \cap \mathfrak{g}$ , where  $\mathfrak{m}^+$  and  $\mathfrak{m}^-$  are the eigenspaces of  $\sigma$  on the complexification  $\mathfrak{g}_{\mathbb{C}}$  of  $\mathfrak{g}$  corresponding to the eigenvalues  $\varepsilon$  and  $\varepsilon^2$ , respectively, where  $\varepsilon = e^{2\pi\sqrt{-1/3}}$ .

Here and in the sequel,  $\sigma$  and its differential  $\sigma_*$  on  $\mathfrak{g}$  and on  $\mathfrak{g}_{\mathbb{C}}$  are denoted by the same letter  $\sigma$ .

The inner product  $\langle , \rangle$  induces a *G*-invariant Riemannian metric gon M = G/K and (G/K, g) becomes into a Riemannian 3-symmetric space. Then, it is a reductive homogeneous space with reductive decomposition  $\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{k}$ , where the algebra of Lie  $\mathfrak{k}$  of K is  $\mathfrak{g}^{\sigma} = \{X \in \mathfrak{g} \mid \sigma X = X\}$ . Moreover, the canonical almost structure J on G/K is Ginvariant, (M = G/K, g, J) is quasi-Kählerian and it is nearly Kählerian if and only if (G/K, g) is a naturally reductive homogeneous space with adapted reductive decomposition  $\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{k}$ . In this case g is said to be an *adapted naturally reductive metric* for M.

We shall need some general results of complex simple Lie algebras. See [6] for more details. Let  $\mathfrak{g}_{\mathbb{C}}$  be a simple Lie algebra over  $\mathbb{C}$  and  $\mathfrak{h}_{\mathbb{C}}$ a Cartan subalgebra of  $\mathfrak{g}_{\mathbb{C}}$ . Let  $\Delta$  denote the set of non-zero roots of  $\mathfrak{g}_{\mathbb{C}}$  with respect to  $\mathfrak{h}_{\mathbb{C}}$  and  $\Pi = \{\alpha_1, \ldots, \alpha_l\}$  a system of simple roots or a basis of  $\Delta$ . Because the restriction of the Killing form B of  $\mathfrak{g}_{\mathbb{C}}$  to  $\mathfrak{h}_{\mathbb{C}} \times \mathfrak{h}_{\mathbb{C}}$  is nondegenerate, there exists a unique element  $H_{\alpha} \in \mathfrak{h}_{\mathbb{C}}$  such that

$$B(H, H_{\alpha}) = \alpha(H)$$

for all  $H \in \mathfrak{h}_{\mathbb{C}}$ . Moreover, we have  $\mathfrak{h}_{\mathbb{C}} = \sum_{\alpha \in \Delta} \mathbb{C}H_{\alpha}$  and B is strictly positive definite on  $\mathfrak{h}_{I\!R} = \sum_{\alpha \in \Delta} I\!R H_{\alpha}$ . Put  $\langle \alpha, \beta \rangle = B(H_{\alpha}, H_{\beta})$ . We choose root vectors  $\{E_{\alpha}\}_{\alpha \in \Delta}$ , such that for all  $\alpha, \beta \in \Delta$ , we have

(3.1) 
$$\begin{cases} [E_{\alpha}, E_{-\alpha}] = H_{\alpha}, & [H, E_{\alpha}] = \alpha(H)E_{\alpha} \text{ for } H \in \mathfrak{h}_{\mathbb{C}}; \\ [E_{\alpha}, E_{\beta}] = 0 & \text{if } \alpha + \beta \neq 0 \text{ and } \alpha + \beta \notin \Delta; \\ [E_{\alpha}, E_{\beta}] = N_{\alpha,\beta}E_{\alpha+\beta} & \text{if } \alpha + \beta \in \Delta, \end{cases}$$

where the constants  $N_{\alpha,\beta}$  satisfy

(3.2) 
$$N_{\alpha,\beta} = -N_{-\alpha,-\beta}, \quad N_{\alpha,\beta} = -N_{\beta,\alpha}$$

and, if  $\alpha, \beta, \gamma \in \Delta$  and  $\alpha + \beta + \gamma = 0$ , then

$$(3.3) N_{\alpha,\beta} = N_{\beta,\gamma} = N_{\gamma,\alpha}$$

Moreover, given an  $\alpha$ -series  $\beta + n\alpha$   $(p \le n \le q)$  containing  $\beta$ , then

(3.4) 
$$(N_{\alpha,\beta})^2 = \frac{q(1-p)}{2} < \alpha, \alpha > .$$

For this choice,  $E_{\alpha}$  and  $E_{\beta}$  are orthogonal under B if  $\alpha + \beta \neq 0$ ,  $B(E_{\alpha}, E_{-\alpha}) = 1$  and we have the orthogonal direct sum

$$\mathfrak{g}_{\mathbb{C}} = \mathfrak{h}_{\mathbb{C}} + \sum_{\alpha \in \Delta} \mathbb{C} E_{\alpha}.$$

Denote by  $\Delta^+$  the set of positive roots of  $\Delta$  with respect to some lexicographic order in  $\Pi$ . Then the  $\mathbb{R}$ -linear subspace  $\mathfrak{g}$  of  $\mathfrak{g}_{\mathbb{C}}$  given by

$$\mathfrak{g} = \mathfrak{h} + \sum_{\alpha \in \Delta^+} (I\!\!R \, U_\alpha + I\!\!R \, V_\alpha)$$

Type	σ	$m_i$	$\Pi(H)$
Ι	$Ad_{\exp{\frac{2\pi\sqrt{-1}}{3}H_i}}$	1	$\{\alpha_k \in \Pi \mid k \neq i\}$
II	$Ad_{\exp 2\pi\sqrt{-1}\frac{(H_i+H_j)}{3}}$	$m_i = m_j = 1$	$\{\alpha_k \in \Pi \mid k \neq i, \ k \neq j\}$
III	$Ad_{\exp{\frac{4\pi\sqrt{-1}}{3}H_i}}$	2	$\{\alpha_k \in \Pi \mid k \neq i\}$
IV	$Ad_{\exp 2\pi\sqrt{-1}H_i}$	3	$\{\alpha_k \in \Pi \mid k \neq i\} \cup \{-\mu\}$

#### Table I

is a compact real form of  $\mathfrak{g}_{\mathbb{C}}$ , where  $\mathfrak{h} = \sum_{\alpha \in \Delta} I\!\!R \sqrt{-1} H_{\alpha}$  and  $U_{\alpha} = E_{\alpha} - E_{-\alpha}$  and  $V_{\alpha} = \sqrt{-1}(E_{\alpha} + E_{-\alpha})$ . Here, we get

$$(3.5) \quad [U_{\alpha}, \sqrt{-1}H_{\beta}] = -\langle \alpha, \beta \rangle V_{\alpha}, \qquad [V_{\alpha}, \sqrt{-1}H_{\beta}] = \langle \alpha, \beta \rangle U_{\alpha}.$$

Next, we shall describe automorphisms of order 3 on the compact Lie algebra  $\mathfrak{g}$  (or on  $\mathfrak{g}_{\mathbb{C}}$ ) which do not preserve any proper ideals. First, suppose that  $\sigma$  is an *inner* automorphism.

# (A) $\sigma$ is an inner automorphism

Because  $\mathfrak{g}$  decomposes into a direct sum of an abelian ideal and simple ideals, we can assume that  $\mathfrak{g}$  is simple. Let  $\mu = \sum_{i=1}^{l} m_i \alpha_i$  be the maximal root of  $\Delta$  and consider  $H_i \in \mathfrak{h}_{\mathbb{C}}$ ,  $i = 1, \ldots, l$ , defined by

$$\alpha_j(H_i) = \frac{1}{m_i} \delta_{ij}, \quad i, j = 1, \dots, l.$$

Following [9, Theorem 3.3], each inner automorphism of order 3 on  $\mathfrak{g}_{\mathbb{C}}$  is conjugate in the inner automorphism group of  $\mathfrak{g}_{\mathbb{C}}$  to some  $\sigma = Ad_{\exp 2\pi\sqrt{-1}H}$ , where  $H = \frac{1}{3}m_iH_i$  with  $1 \le m_i \le 3$  or  $H = \frac{1}{3}(H_i + H_j)$  with  $m_i = m_j = 1$ . Then there are four types of  $\sigma = Ad_{\exp 2\pi\sqrt{-1}H}$  with corresponding simple root systems  $\Pi(H)$  for  $\mathfrak{g}_{\mathbb{C}}^{\sigma}$  given in Table I. Denote by  $\Delta^+(H)$  the positive root system generated by  $\Pi(H)$ . Then, we have  $\mathfrak{h} \subset \mathfrak{k} = \mathfrak{g}^{\sigma}$  and

$$\mathfrak{k} = \mathfrak{h} + \sum_{\alpha \in \Delta^+(H)} (\operatorname{I\!R} U_\alpha + \operatorname{I\!R} V_\alpha).$$

Because  $B(U_{\alpha}, U_{\beta}) = B(V_{\alpha}, V_{\beta}) = -2\delta_{\alpha\beta}$  and  $B(U_{\alpha}, V_{\beta}) = 0$ , it follows that  $\{U_{\alpha}, V_{\alpha} \mid \alpha \in \Delta^{+} \smallsetminus \Delta^{+}(H)\}$  becomes into an orthonormal basis for  $(\mathfrak{m}, <, >= -\frac{1}{2}B_{|\mathfrak{m}})$ .

# (B) $\sigma$ is an outer automorphism

Let  $\sigma$  be an outer automorphism of order 3 on a compact Lie algebra  $\mathfrak{g}$  such that there is no proper  $\sigma$ -invariant ideal in  $\mathfrak{g}$ . Then  $\mathfrak{g}$  must be

semisimple [9, Theorem 5.10]. First, suppose that  $\mathfrak{g}$  is simple. Then the complexification  $\mathfrak{g}_{\mathbb{C}}$  of  $\mathfrak{g}$  is of type



and the complex Lie algebra  $\mathfrak{g}^{\sigma}_{\mathbb{C}}$ , the set of fixed points of  $\sigma$  on  $\mathfrak{g}_{\mathbb{C}}$ , is either of type  $\mathfrak{g}_2$ , where a Weyl basis is given by [9, Theorem 5.5]

$$\{ H_{\alpha_2}, H_{\alpha_1} + H_{\alpha_3} + H_{\alpha_4}; E_{\pm \alpha_2}, E_{\pm (\alpha_1 + \alpha_2 + \alpha_3 + \alpha_4)}, E_{\pm (\alpha_1 + 2\alpha_2 + \alpha_3 + \alpha_4)}, \\ E_{\pm \alpha_1} + E_{\pm \alpha_3} + E_{\pm \alpha_4}, E_{\pm (\alpha_1 + \alpha_2)} + E_{\pm (\alpha_2 + \alpha_3)} + E_{\pm (\alpha_2 + \alpha_4)}, \\ E_{\pm (\alpha_1 + \alpha_2 + \alpha_3)} + E_{\pm (\alpha_2 + \alpha_3 + \alpha_4)} + E_{\pm (\alpha_1 + \alpha_2 + \alpha_4)} \},$$

or of type  $\mathfrak{a}_2$ , being a Weyl basis  $\{H_{\beta_1}, H_{\beta_2}; F_{\pm\beta_1}, F_{\pm\beta_2}, F_{\pm(\beta_1+\beta_2)}\}$ , where

Finally, if  $\mathfrak{g}$  is semisimple but not simple then  $\mathfrak{g} = \mathfrak{L} \oplus \mathfrak{L} \oplus \mathfrak{L}$  with  $\mathfrak{L}$  simple and  $\mathfrak{k} = \mathfrak{g}^{\sigma}$  is  $\mathfrak{L}$  embedded diagonally.

## 4. Proof of Theorem 1.1

This will require some previous propositions and lemmas. We start considering, as in above section, Riemannian 3-symmetric spaces  $(M = G/K, \sigma, <, >)$  where G is a compact connected Lie group acting effectively, the automorphism  $\sigma$  on the Lie algebra  $\mathfrak{g}$  of G does not preserve any proper ideals and <, > determines a *naturally reductive* Riemannian metric adapted to  $\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{k}$ . According with [5], the inner product <, > is then the restriction to  $\mathfrak{m}$  of a bi-invariant product on  $\mathfrak{g}$ . Because  $\mathfrak{g}$  is semisimple, we take  $<, >= -\frac{1}{2}B_{|\mathfrak{m}}$ , where B denotes the Killing form of  $\mathfrak{g}$ . Then, we have

**Lemma 4.1.**  $(M = G/K, \sigma, <, >)$  is a normal homogeneous space.

*Proof.* We only have to prove that  $\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{k}$  is orthogonal with respect to B. Let  $B_{\mathfrak{g}_{\mathbb{C}}}$  be the Killing form of  $\mathfrak{g}_{\mathbb{C}}$ . Because  $B_{\mathfrak{g}_{\mathbb{C}}}$  is invariant under automorphisms, we get that the subspaces  $\mathfrak{g}_{\mathbb{C}}^{\sigma}$ ,  $\mathfrak{m}^+$  and  $\mathfrak{m}^-$  are

orthogonal in  $(\mathfrak{g}_{\mathbb{C}}, B_{\mathfrak{g}_{\mathbb{C}}})$ . Then the result follows taking into account that  $B_{\mathfrak{g}_{\mathbb{C}}}(X, Y) = B(X, Y)$ , for all  $X, Y \in \mathfrak{g}$ . q.e.d.

In the following, we look for geodesics on  $(M = G/K, \sigma, <, >)$  with non-G-isotropic Jacobi fields vanishing at two points.

#### (A) $\sigma$ is an inner automorphism

**Lemma 4.2.** If  $\sigma$  is of Type I then  $(M = G/K, \sigma, <, >)$  is one of the following irreducible Hermitian symmetric spaces of compact type:

$$\begin{split} SU(n)/(S(U(r) \times U(n-r))), & SO(n)/(SO(n-2) \times SO(2)), \\ Sp(n)/U(n), & SO(2n)/U(n), \\ E_6/(SO(10) \times SO(2)), & E_7/(E_6 \times SO(2)). \end{split}$$

*Proof.* (i) Put  $H = \frac{1}{3}H_i$ , for some  $i \in \{1, \ldots, l\}$  with  $m_i = 1$ . Then each  $\alpha \in \Delta^+ \setminus \Delta^+(H)$  may be written as

$$\alpha = \sum_{j=1}^{l} n_j \alpha_j,$$

where  $n_j \in \mathbb{Z}, n_j \geq 0$ , and  $n_i = 1$ . It implies that  $\alpha + \beta \notin \Delta$  and  $\alpha - \beta \notin \Delta \setminus \Delta(H)$ , for all  $\alpha, \beta \in \Delta^+ \setminus \Delta^+(H)$ . Hence, using (3.1) and (3.2), we get that  $[U_{\alpha}, U_{\beta}]$  and  $[V_{\alpha}, V_{\beta}]$  are collinear with  $U_{\alpha-\beta}$  and  $[U_{\alpha}, V_{\beta}]$  with  $V_{\alpha-\beta}$ . Then,  $[\mathfrak{m}, \mathfrak{m}] \subset \mathfrak{k}$  and consequently (M = G/K, g) must be locally symmetric. Because rank  $G = \operatorname{rank} K$  and the center of G is trivial, it follows from [9, Theorem 6.4] that it is moreover globally symmetric. For the list of these spaces, we use [9, Theorem 3.3].

q.e.d.

**Remark 4.3.** Notice that on above compact symmetric spaces M = G/K, the action of G is almost effective but not necessarily effective.

As a consequence of the following results, we will prove that a compact irreducible Riemannian 3-symmetric space  $(M = G/K, \sigma, <, >)$  is a Hermitian symmetric space if and only if  $\sigma$  is an inner automorphism of Type I.

**Proposition 4.4.** Let  $\alpha, \beta \in \Delta \setminus \Delta(H)$  such that  $\alpha - \beta \neq 0, \alpha - \beta \notin \Delta$ and  $2\alpha + \beta \neq 0, 2\alpha + \beta \notin \Delta$ . We have:

- (i) If  $\alpha + \beta \in \Delta(H)$  then  $\gamma(t) = (\exp tU_{\alpha})o$  on  $(M = G/K, \sigma, <, >)$ admits G-isotropic Jacobi fields V with  $V(\frac{\sqrt{2}p\pi}{||\alpha||}) = 0, p \in \mathbb{Z}.$
- (ii) If  $\alpha + \beta \in \Delta \setminus \Delta(H)$  then  $\gamma(t) = (\exp tU_{\alpha}) \overset{\text{"""}}{o} on (M = G/K, \sigma, < , >)$  admits Jacobi fields V with  $V(\frac{2\sqrt{2}p\pi}{\|\alpha\|}) = 0, p \in \mathbb{Z}$ , which are not G-isotropic.

*Proof.* Since  $\alpha + \beta \in \Delta$ , we get from (3.1) and (3.2)

$$[U_{\alpha}, U_{\beta}] = N_{\alpha,\beta} U_{\alpha+\beta}.$$

Then, taking into account that the  $\alpha$ -series containing  $\beta$  is  $\{\beta, \beta + \alpha\}$ , (3.3) and (3.4) imply

$$[[U_{\alpha}, U_{\beta}], U_{\alpha}] = N_{\alpha,\beta} N_{-(\alpha+\beta),\alpha} U_{\beta} = (N_{\alpha,\beta})^2 U_{\beta} = \frac{\langle \alpha, \alpha \rangle}{2} U_{\beta}.$$

Hence, taking  $u = U_{\alpha}$ ,  $v = U_{\beta}$  and  $\lambda = \frac{\langle \alpha, \alpha \rangle}{2}$  in Proposition 2.3, we obtain the result. q.e.d.

Next, we put

$$\alpha_{ij} = \alpha_i + \dots + \alpha_j \quad (1 \le i \le j \le l), \quad \tilde{\mu} = \sum_{j=1}^l (m_j - 1)\alpha_j.$$

It is easy to see by a case-by-case check the following.

Lemma 4.5. We have:

(a)  $\alpha_{ij} \in \Delta$  except if (i, j) = (l - 1, l) in



or 
$$(i, j) = (1, 2), (1, 3)$$
 and  $(2, 3)$  in

$$\mathfrak{e}_6, \mathfrak{e}_7, \mathfrak{e}_8: \cdots \circ - \overset{\circ}{-} \overset{\circ}{\alpha_4} - \overset{\circ}{-} \overset{\circ}{\alpha_3} - \overset{\circ}{-} \overset{\circ}{\alpha_1}$$

(b)  $\tilde{\mu} \in \Delta$  for  $\mathfrak{g}_{\mathbb{C}} \neq \mathfrak{a}_l$ . In  $\mathfrak{a}_l$ ,  $\tilde{\mu}$  is zero.

Then, we can conclude

**Proposition 4.6.** Let  $(M = G/K, \sigma, <, >)$  be a Riemannian 3symmetric space where G is a compact simple Lie group acting effectively on M and  $\sigma$  is an inner automorphism on the Lie algebra  $\mathfrak{g}$  of G. If all Jacobi field vanishing at two points is G-isotropic then (M, g) is a symmetric space.

*Proof.* From Lemma 4.2, we only need to show that there exist  $\alpha, \beta \in \Delta \setminus \Delta(H)$  satisfying the hypothesis of Proposition 4.4 (ii) for  $\sigma$  of Type II, III and IV.

If  $\sigma$  is of Type II then  $m_i = m_j = 1$   $(H = \frac{1}{3}(H_i + H_j))$ , for some  $i, j \in \{1, \ldots, l\}, i < j$ . So, the complex simple Lie algebra  $\mathfrak{g}_{\mathbb{C}}$  is  $\mathfrak{a}_l$   $(l \geq 2), \mathfrak{d}_l$   $(l \geq 4)$  or  $\mathfrak{e}_6$ . Take

$$\alpha = \alpha_{1l}, \quad \beta = -\alpha_{(i+1)l},$$

Then  $\alpha + \beta = \alpha_{1i}$ . Because  $i \neq l-2$  for  $\mathfrak{g}_{\mathbb{C}}$  of type  $\mathfrak{d}_l$  and (i, j) = (1, 6) for



it follows from Lemma 4.5 that  $\alpha, \beta$  and  $\alpha + \beta$  belongs to  $\Delta \setminus \Delta(H)$ . Moreover, taking into account that  $m_i = m_j = 1$ , we easily see that  $\alpha - \beta$  and  $2\alpha + \beta$  are not roots.

If  $\sigma$  is of Type III then  $m_i = 2$   $(H = \frac{2}{3}H_i)$ , for some  $i = 1, \ldots, l$ . It implies that  $\mathfrak{g}_{\mathbb{C}}$  is one of the following:  $\mathfrak{b}_l$ ,  $(l \ge 2)$ ,  $\mathfrak{c}_l$ ,  $(l \ge 2)$ ,  $\mathfrak{d}_l$ ,  $(l \ge 4)$ ,  $\mathfrak{g}_2$ ,  $\mathfrak{f}_4$ ,  $\mathfrak{e}_6$ ,  $\mathfrak{e}_7$  and  $\mathfrak{e}_8$ . Here, we put

$$\alpha = \mu, \qquad \beta = -\tilde{\mu}.$$

Then  $\alpha + \beta = \alpha_{1l}$  and from Lemma 4.5,  $\beta$  and  $\alpha + \beta$  are non-zero roots of  $\mathfrak{g}_{\mathbb{C}}$ . Moreover,  $\alpha, \beta, \alpha + \beta$  belong to  $\Delta \smallsetminus \Delta(H)$ . Because  $\mu$  is the maximal root, we have that  $\alpha - \beta$  and  $2\alpha + \beta$  are not roots.

Finally, we consider  $\sigma$  of Type IV. Then,  $m_i = 3$ , for some  $i = 1, \ldots, l$ , and  $\mathfrak{g}_{\mathbb{C}}$  is one of the exceptional Lie algebras  $\mathfrak{g}_2$ ,  $\mathfrak{f}_4$ ,  $\mathfrak{e}_6$ ,  $\mathfrak{e}_7$  or  $\mathfrak{e}_8$ . Except for  $\mathfrak{g}_2$ , in each one of these algebras we can find, using again Lemma 4.5,  $\alpha$  and  $\beta$  satisfying Proposition 4.4 (ii). Concretely, for the case  $\mathfrak{f}_4: \begin{array}{c} 2\\ \alpha_1 \end{array} \xrightarrow{\alpha_2} \xrightarrow{\alpha_2} \begin{array}{c} 4\\ \alpha_3 \end{array} \xrightarrow{\alpha_2} \begin{array}{c} 2\\ \alpha_4 \end{array}$ , we take  $\alpha = \alpha_1 + 2\alpha_2 + 4\alpha_3 + 2\alpha_4$ and  $\beta = -(\alpha_1 + \alpha_2 + 2\alpha_3 + 2\alpha_4)$ . In  $\mathfrak{e}_6$ , we can choose  $\alpha = \tilde{\mu}$  and  $\beta = -\alpha_{24}$ . In



we take  $\alpha = \tilde{\mu}$  and  $\beta = -\alpha_{35}$  and,  $\alpha = \tilde{\mu} - \alpha_4 = \alpha_1 + 2\alpha_2 + 3\alpha_3 + 4\alpha_4 + 4\alpha_5 + 3\alpha_6 + 2\alpha_7 + \alpha_8$  and  $\beta = -\alpha_{27}$ , in



The corresponding Riemannian 3-symmetric space for  $\mathfrak{g}_{\mathbb{C}} = \mathfrak{g}_2$ :  $\overset{3}{\overset{\circ}{\alpha_1}} \equiv \overset{2}{\overset{\circ}{\alpha_2}}$  is the sphere  $S^6 = G_2/SU(3)$  equipped with the usual metric of constant curvature. q.e.d.

**Remark 4.7.** There exist geodesics on  $(M = G/K, \sigma, <, >)$  with isotropically conjugate points and admitting Jacobi fields vanishing at these points which are not isotropic. This is the case of the geodesic  $\gamma(t) = (\exp tU_{\alpha})o$  in M = G/K, where  $\mathfrak{g}_{\mathbb{C}} = \mathfrak{a}_l$  (l > 2) and  $\alpha = \alpha_{1l}$ . From the proof of above Proposition,  $\gamma$  admits Jacobi fields vanishing at the origin and at  $p = \gamma(\frac{2\sqrt{2}\pi}{\|\alpha\|})$  which are not *G*-isotropic and, taking  $\beta = -\alpha_{1j}, j < l$ , it follows from Proposition 4.4 (i) that *o* and *p* are moreover *G*-isotropically conjugate points.

(B)  $\sigma$  is an outer automorphism

**Proposition 4.8.** Let  $(M = G/K, \sigma, <, >)$  be a Riemannian 3symmetric space where G is a compact Lie group acting effectively on M and  $\sigma$  is an outer automorphism on the Lie algebra  $\mathfrak{g}$  of G such that there is no proper  $\sigma$ -invariant ideal in  $\mathfrak{g}$ . Then there exist Jacobi fields vanishing at two points which are not G-isotropic.

*Proof.* Suppose that  $\mathfrak{g}$  is simple. If  $\mathfrak{g}_{\mathbb{C}}^{\sigma}$  is of type  $\mathfrak{g}_2$ , then the corresponding real form  $\mathfrak{k} = \mathfrak{g}^{\sigma}$  is generated by

$$\{ \sqrt{-1}H_{\alpha_2}, \sqrt{-1}(H_{\alpha_1} + H_{\alpha_3} + H_{\alpha_4}); U_{\alpha_2}, V_{\alpha_2}, \\ U_{(\alpha_1 + \alpha_2 + \alpha_3 + \alpha_4)}, V_{(\alpha_1 + \alpha_2 + \alpha_3 + \alpha_4)}, \\ U_{(\alpha_1 + 2\alpha_2 + \alpha_3 + \alpha_4)}, V_{(\alpha_1 + 2\alpha_2 + \alpha_3 + \alpha_4)}, U_{\alpha_1} + U_{\alpha_3} + U_{\alpha_4}, V_{\alpha_1} + V_{\alpha_3} + V_{\alpha_4}, \\ U_{(\alpha_1 + \alpha_2)} + U_{(\alpha_2 + \alpha_3)} + U_{(\alpha_2 + \alpha_4)}, V_{(\alpha_1 + \alpha_2)} + V_{(\alpha_2 + \alpha_3)} + V_{(\alpha_2 + \alpha_4)}, \\ U_{(\alpha_1 + \alpha_2 + \alpha_3)} + U_{(\alpha_2 + \alpha_3 + \alpha_4)} + U_{(\alpha_1 + \alpha_2 + \alpha_4)}, \\ V_{(\alpha_1 + \alpha_2 + \alpha_3)} + V_{(\alpha_2 + \alpha_3 + \alpha_4)} + V_{(\alpha_1 + \alpha_2 + \alpha_4)} \}.$$

Since the set  $\Delta^+$  of the positive roots of  $\mathfrak{d}_4$  is given by

$$\begin{aligned} \Delta^+ &= & \left\{ \alpha_i \; (1 \le i \le 4), \alpha_1 + \alpha_2, \alpha_2 + \alpha_3, \alpha_2 + \alpha_4, \alpha_1 + \alpha_2 + \alpha_3, \\ &\alpha_1 + \alpha_2 + \alpha_4, \alpha_2 + \alpha_3 + \alpha_4, \alpha_1 + \alpha_2 + \alpha_3 + \alpha_4, \\ &\mu = \alpha_1 + 2\alpha_2 + \alpha_3 + \alpha_4 \right\} \end{aligned}$$

and the simple roots  $\alpha_1, \ldots, \alpha_4$  satisfy

(4.1) 
$$<\alpha_i, \alpha_i>=\frac{1}{6}, <\alpha_1, \alpha_2>=<\alpha_2, \alpha_3>=<\alpha_2, \alpha_4>=-\frac{1}{12},$$

where  $1 \leq i \leq 4$ , and the other inner products are zero, we obtain the following basis for  $\mathfrak{m} = (\mathfrak{g}^{\sigma})^{\perp}$  in  $\mathfrak{g}$ :

$$\{ \sqrt{-1}(H_{\alpha_1} - H_{\alpha_3}), \sqrt{-1}(H_{\alpha_1} + H_{\alpha_3} - 2H_{\alpha_4}); U_{\alpha_1} - U_{\alpha_3}, V_{\alpha_1} - V_{\alpha_3}, U_{\alpha_1} + U_{\alpha_3} - 2U_{\alpha_4}, V_{\alpha_1} + V_{\alpha_3} - 2V_{\alpha_4}, U_{(\alpha_1+\alpha_2)} - U_{(\alpha_2+\alpha_3)}, V_{(\alpha_1+\alpha_2)} - V_{(\alpha_2+\alpha_3)}, U_{(\alpha_1+\alpha_2)} + U_{(\alpha_2+\alpha_3)} - 2U_{(\alpha_2+\alpha_4)}, V_{(\alpha_1+\alpha_2)} + V_{(\alpha_2+\alpha_3)} - 2V_{(\alpha_2+\alpha_4)}, U_{(\alpha_1+\alpha_2+\alpha_3)} - U_{(\alpha_2+\alpha_3+\alpha_4)}, V_{(\alpha_1+\alpha_2+\alpha_3)} - V_{(\alpha_2+\alpha_3+\alpha_4)} - V_{(\alpha_1+\alpha_2+\alpha_4)}, U_{(\alpha_1+\alpha_2+\alpha_3)} + U_{(\alpha_2+\alpha_3+\alpha_4)} - 2U_{(\alpha_1+\alpha_2+\alpha_4)}, V_{(\alpha_1+\alpha_2+\alpha_3)} + V_{(\alpha_2+\alpha_3+\alpha_4)} - 2V_{(\alpha_1+\alpha_2+\alpha_4)} \}.$$

We put,

$$u = \frac{1}{\sqrt{6}} (U_{\alpha_1} + U_{\alpha_3} - 2U_{\alpha_4}), \quad v = \sqrt{-6} (H_{\alpha_1} - H_{\alpha_3}).$$

Then, u and v are orthonormal vectors in  $\mathfrak{m}$  and using (3.1), (3.5) and (4.1), we obtain

$$[u,v] = -\frac{1}{6}(V_{\alpha_1} - V_{\alpha_3}), \quad [[u,v],v] = \frac{1}{18}v.$$

Hence, Lemma 4.1 and Proposition 2.3 (ii) imply that  $\gamma(t) = (\exp tu)o$ admits Jacobi fields vanishing at the origin and at  $\gamma(6\sqrt{2}p\pi), p \in \mathbb{Z}$ , which are not G-isotropic.

Next, we suppose that  $\mathfrak{g}^{\sigma}_{\mathbb{C}}$  is of type  $\mathfrak{a}_2$ . Then, a basis for  $\mathfrak{k} = \mathfrak{g}^{\sigma}$  is given by

$$\left\{\sqrt{-1}H_{\beta_1}, \sqrt{-1}H_{\beta_2}; \tilde{U}_{\beta_1}, \tilde{V}_{\beta_1}, \tilde{U}_{\beta_2}, \tilde{V}_{\beta_2}, \tilde{U}_{\beta_1+\beta_2}, \tilde{V}_{\beta_1+\beta_2}\right\},\$$

where

$$\begin{split} \tilde{U}_{\beta_{i}} &= F_{\beta_{i}} - F_{-\beta_{i}}, \\ \tilde{U}_{\beta_{1}+\beta_{2}} &= F_{\beta_{1}+\beta_{2}} - F_{-(\beta_{1}+\beta_{2})}, \\ \tilde{V}_{\beta_{1}+\beta_{2}} &= \sqrt{-1} \left( F_{\beta_{1}+\beta_{2}} + F_{-(\beta_{1}+\beta_{2})} \right) \\ \text{Put}, \end{split}$$

Ρ

$$u = \sqrt{-6}(H_{\alpha_1} - H_{\alpha_3}), \quad v = \frac{1}{\sqrt{2}}(U_{\alpha_1} - U_{\alpha_3}).$$

Then, using (3.1) and (4.1), we can check that  $u, v \in \mathfrak{m}$  and they are orthonormal. Moreover, we get

$$[u,v] = \frac{\sqrt{3}}{6}(V_{\alpha_1} + V_{\alpha_3}), \quad [[u,v],u] = \frac{1}{6}v$$

and  $V_{\alpha_1} + V_{\alpha_3} \in \mathfrak{m}$ . Hence, u, v satisfy the hypothesis of Proposition 2.3 (ii).

Finally, suppose that  $\mathfrak{g}$  is semisimple but not simple, then  $\mathfrak{g} = \mathfrak{L} \oplus \mathfrak{L} \oplus \mathfrak{L}$  with  $\mathfrak{L}$  simple and  $\mathfrak{k} = \mathfrak{g}^{\sigma}$  is  $\mathfrak{L}$  embedded diagonally. Let  $\alpha$  be a root of  $\mathfrak{L}_{\mathbb{C}}$ . Take in  $\mathfrak{g}$ ,

$$u = \frac{1}{\sqrt{6}}(U_{\alpha}, U_{\alpha}, -2U_{\alpha}), \qquad v = \frac{\sqrt{-1}}{\|\alpha\|}(H_{\alpha}, -H_{\alpha}, 0).$$

Then u, v are orthogonal to  $\mathfrak{k}$  and, from (3.1) and (3.5),

$$[u, v] = -\frac{\|\alpha\|}{\sqrt{6}}(V_{\alpha}, -V_{\alpha}, 0), \quad [[u, v], u] = \frac{\langle \alpha, \alpha \rangle}{3}v$$

and, consequently they again satisfy the hypothesis of Proposition 2.3 (ii). q.e.d.

The proof of Theorem 1.1 is now easy. Following [9, Theorem 6.4], compact 3-symmetric spaces  $(M = G/K, \sigma, <, >)$  are given by

$$M = (M_0 \times M_1 \times \cdots \times M_r) / \Gamma = \{ (G_0 \times G_1 \times \cdots \times G_r) / \Gamma \} / K,$$

where

- (i) M<sub>0</sub> is a complex Euclidean space, G<sub>0</sub> is its translation group and K<sub>0</sub> = {I} ⊂ G<sub>0</sub>;
- (ii)  $M_i = G_i/K_i$ ,  $1 \le i \le r$ , is a simply connected 3-symmetric space,  $G_i$  is a compact connected Lie group acting effectively and  $\sigma_i = \sigma_{|\mathfrak{g}_i|}$  does not preserve any proper ideals;
- (iii)  $\Gamma$  is any discrete subgroup of  $G_0 \times Z_1 \times \cdots \times Z_r$ , being  $Z_i$  the center of  $G_i$  and  $\Gamma \cap G_0$  a lattice in  $G_0$ ;
- (iv) K is the image of  $(K_0 \times K_1 \times \cdots \times K_r)$  in  $(G_0 \times G_1 \times \cdots \times G_r)/\Gamma$ .

Hence, the subspace  $\mathfrak{m} = \mathfrak{k}^{\perp}$  of  $\mathfrak{g}$  can be expressed as

$$\mathfrak{m}=\mathfrak{g}_0\oplus\mathfrak{m}_1\oplus\cdots\oplus\mathfrak{m}_r,$$

where  $\mathfrak{m}_i = \mathfrak{k}_i^{\perp}$  on  $(\mathfrak{g}_i, B_i)$ ,  $i = 1, \ldots, r$ . Then  $(\exp tu)o$  with  $u \in \mathfrak{m}_i$  is geodesic on (M = G/K, g) and we can again apply Propositions 4.6 and 4.8 to obtain that (M = G/K, g) must be locally symmetric. In this case, rank  $G_i = \operatorname{rank} K_i$  and  $Z_i$  is trivial, for  $i = 1, \ldots, r$ , which implies that (M = G/K, g) is moreover symmetric. Concretely, (M, g) is given by

$$M = T \times M_1 \times \cdots \times M_r,$$

where  $(T, g_0)$  is a complex flat torus and  $(M_i, g_i)$ , is one of the irreducible symmetric spaces given in Lemma 4.2 and the metric g on M is the product metric  $g = g_0 + g_1 + \cdots + g_r$ .

#### J.C. GONZÁLEZ-DÁVILA

#### References

- R. Bott & H. Samelson, Applications of the theory of Morse to symmetric spaces, Amer. J. of Math. 80 (1958), 964–1029, MR 0105694, Zbl 0101.39702, Correction in: Amer. J. of Math. 83 (1961), 207–208, MR 0170351.
- I. Chavel, Isotropic Jacobi fields, and Jacobi's equations on Riemannian homogeneous spaces, Comment. Math. Helv. 42 (1967), 237–248, MR 0221426, Zbl 0166.17501.
- [3] I. Chavel, On normal Riemannian homogeneous spaces of rank 1, Bull. Amer. Math. Soc. 73 (1967), 477–481, MR 0220209, Zbl 0153.23102.
- [4] J.C. González-Dávila & R.O. Salazar, Isotropic Jacobi fields on naturally reductive spaces, Publ. Math. Debrecen 66 (2005), 41–61, MR 2128684, Zbl 1075.53046.
- [5] A. Gray, Riemannian manifolds with geodesic symmetries of order 3, J. Differential Geom. 7 (1972), 343–369, MR 0331281, Zbl 0275.53026.
- [6] S. Helgason, Differential geometry, Lie groups, and symmetric spaces, Academic Press, New York, 1978, MR 0514561, Zbl 0451.53038.
- [7] S. Kobayashi & K. Nomizu, Foundations of differential geometry, I, II, Interscience Publishers, New York, 1963, MR 0152974, Zbl 0119.37502; 1969, MR 0238225, Zbl 0175.48504.
- [8] K. Tojo, Kähler C-spaces and k-symmetric spaces, Osaka J. Math., 34 (1997), 803–820, MR 1618665, Zbl 0899.53042.
- J.A. Wolf & A. Gray, Homogeneous spaces defined by Lie group automorphisms, I, II, J. Differential Geom. 2 (1968), 77–159, MR 0236328, MR 0236329;
  Zbl 0169.24103, Zbl 0182.24702.
- [10] W. Ziller, The Jacobi equation on naturally reductive compact Riemannian homogeneous spaces, Comment. Math. Helv. 52 (1977), 573–590, MR 0474145, Zbl 0368.53033.

Departamento de Matemática Fundamental Sección de Geometría y Topología Universidad de La Laguna La Laguna, Spain *E-mail address*: jcgonza@ull.es