Existence and Regularity Results for Harmonic Maps with Potential

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1. Introduction.

Let (M, g) and (N, h) be Riemannian m- and n- manifolds, G a smooth function on N. For a bounded domain $\Omega \subset M$ and a map $u: M \to N$ we define the energy functional with the potential G on Ω :

(1.1)
$$E_G(u;\Omega) = \int_{\Omega} [e(u) - G(u)] d\mu,$$

where e(u) and $d\mu$ are the standard energy density and the volume element on M. Using local coordinate systems (x^1, \dots, x^m) and (u^1, \dots, u^n) on M and N respectively, we can write

(1.2)
$$E_G(u;\Omega) = \int_{\Omega} \left[\frac{1}{2} g^{\alpha\beta}(x) h_{ij}(u) D_{\alpha} u^i D_{\beta} u^j - G(u(x)) \right] \sqrt{g} dx,$$

where $(g^{\alpha\beta}(x)) = (g_{\alpha\beta}(x))^{-1}$, $g = \det(g_{\alpha\beta}(x))$ and $D_{\alpha} = \partial/\partial x^{\alpha}$. The Euler-Lagrange equation of E_G is given as

$$\tau(u) + \nabla G = 0,$$

where $\tau(u)$ denotes the tension field of u. In local

$$(\tau(u))^i = \frac{1}{\sqrt{g}} D_{\alpha} \{ \sqrt{g} g^{\alpha\beta} D_{\beta} u^i \} + g^{\alpha\beta} \Gamma^i_{jk} D_{\alpha} u^j D_{\beta} u^k .$$

A solution $u: \Omega \to N$ of (1.3) is called to be a harmonic map with potential G.

The equations of type (1.3) appear also in some physical contexts. Let $\Omega \subset \mathbb{R}^m$, $N = S^2 = \{(x, y, z) \in \mathbb{R}^3; x^2 + y^2 + z^2 = 1\}$ and $G(u) = (u, H) = u^1 H^1 + \dots + u^n H^n$ for some constant vector $H \in \mathbb{R}^3$, then the equation (1.3) becomes

(1.4)
$$\Delta u + u|Du|^2 - (H, u)u + H = 0$$

which is called as the static Landau-Lifshitz equation (see [1], [2], [3], [12] and [13]). Here and in the sequel (,) and | | denote the standard Euclidean inner products and norms respectively. In [2], [12] and [13], Dirichlet problems for the equation (1.4)

(1.5)
$$\begin{cases} \Delta u + u |Du|^2 - (H, u)u + H = 0 \\ u = f \quad \text{on} \quad \partial \Omega \end{cases}$$

are considered.

When $\Omega = B^3$, Hong [12] showed the existence of a smooth solution to the Dirichlet problem (1.5), assuming that an extension u_0 of the boundary value f to B^3 satisfies

$$\int_{B^3} \frac{1}{2} \left(|Du_0|^2 + |H| \cdot \left| u_0 - \frac{H}{|H|} \right|^2 \right) dx < \varepsilon$$

for a sufficiently small $\varepsilon > 0$.

More recently, Chen [2] showed the existence of a smooth solution to (1.5) for $H = \lambda q$ and $f \in C^{\infty}(\partial\Omega, S_q^2)$, where λ is a positive constant, q a point in S^2 and S_q^2 the open hemisphere with the north pole q. He also showed the uniqueness of the small solutions i.e. if u_1 and u_2 are solutions of the Dirichlet problem with $u_1(\Omega)$, $u_2(\Omega) \subset S_q^2$ then $u_1 = u_2$.

On the other hand, when $\Omega = B^2$, Hong-Lemaire [13] showed that if f is neither constant H/|H| nor constant -H/|H| then there are at least two different smooth solution to the Dirichlet problem (1.5). Moreover, they showed also that under a certain condition there are at least three different solutions to (1.5).

In this paper, more general cases are treated. We will prove existence of a minimizer of E_G in a suitable class of Sobolev maps with the Dirichlet boundary condition

$$(1.6) u = f on \partial \Omega,$$

by the direct method of calculus of variations, assuming some conditions on G, f and N. We will prove also boundedness and regularity of the minimizer and get existence results for harmonic maps with potential.

Now, let us prepare some notations and terminology. For a Riemannian manifold N, $\kappa_N(p;\pi)$ denotes the sectional curvature at $p \in N$ with respect to a plane section $\pi \subset T_pN$. Let $q_0 \in N$ be a fixed point and $I(q_0)$ the injectivity radius of N centered at q_0 . For $p \in B_{I(q_0)}(q_0)$, let $\sigma(q_0, p)(t)$ be the geodesic curve such that $\sigma(q_0, p)(0) = q_0$ and $\sigma(q_0, p)(1) = p$. When π contains $\sigma'(q_0, p)(1)$, let us call $\kappa_N(p;\pi)$ a radial curvature at p with respect to q_0 . We denote as $K_{rad}(p;q_0)$ the maximum of radial curvatures of N at p with respect to q_0 , namely

$$K_{\rm rad}(p;q_0)=\max\{\kappa_N(p;\pi)|\pi\ni\sigma'(q_0,p)(1)\}.$$

Throughout this paper we consider the following condition $C(q_0, R_0)$ on the radial curvatures of N.

 $C(q_0, R_0)$: Let q_0 be a fixed point of N and R_0 a positive number which is smaller than the injectivity radius $I(q_0)$ of N centered at q_0 . There exists a nonnegative function

 $\rho:[0,R_0)\to [0,\infty)$ which satisfies the following conditions:

$$\lim_{t \to 0} \frac{\rho(t)}{t} = 1,$$

(1.8)
$$\rho(t) > 0$$
, $\rho'(t) > 0$ for all $t \in (0, R_0)$,

(1.9)
$$K_{\text{rad}}(p; q_0) \leq -\frac{\rho''}{\rho}(\text{dist}(q_0, p)) \text{ for all } p \in B_{R_0}(q_0).$$

Under this condition, \exp_{q_0} gives a normal coordinate system centered at q_0 on B_{R_0} . Moreover, with respect to this normal coordinate system we get an estimate on the nonlinear term of $\tau(u)$ which corresponds to the one-sided condition of Giaquinta-Giusti [6]. (See Lemma 2.1.)

EXAMPLES 1. An upper hemisphere S_+^n satisfies $C(q_0, R_0)$ with q_0 ="the north pole", $R_0 = \pi/2$ and $\rho(t) = \sin t$.

2. A simply connected complete manifold N with nonpositive sectional curvatures satisfies $C(q_0, R_0)$ with arbitrarily fixed $q_0 \in N$, $R_0 = \infty$ and $\rho(t) = t$.

In section 2, we will show the existence of minimizers of E_G and their L^{∞} -bounds (Theorem 2.2). These lead us to the existence of weak solutions of (1.3).

In section 3, the regularity of the weak solutions whose existence is guaranteed in section 2 will be shown (Theorems 3.2 and 3.3). Thus we will achieve at the existence theorem of harmonic maps with potential (Theorem 3.4).

2. Existence and global boundedness of a minimizer.

First of all we prepare an auxiliary geometric lemma.

LEMMA 2.1 (Revised version of [15, Lemma 1.1]). Let N be a Riemannian n-manifold which satisfies $C(q_0, R_0)$, (u^1, \dots, u^n) a normal coordinate system centered at q_0 and $h_{ij}(u)$ the metric tensor with respect to the normal coordinate system. Then we have the following estimates:

(2.1)
$$h_{ij}(u)(X^{i}X^{j} + u^{k}\Gamma_{kl}^{i}(u)X^{j}X^{l}) \ge |\zeta|^{2} + t\frac{\rho'(t)}{\rho(t)}h_{ij}(y)\xi^{i}\xi^{j},$$

(2.2)
$$h_{ij}(u)X^{i}X^{j} \geq |\zeta|^{2} + \frac{\rho^{2}(t)}{t^{2}}|\xi|^{2},$$

for all $u, X \in \mathbb{R}^n$, where $t = |u|, \zeta = t^{-2}(X, u)u$ and $\xi = X - \zeta$.

PROOF. We can proceed as in the proof of [15, Lemma 1.1] or [16, Lemma 2.1], noticing that the assumptions only on the radial curvatures like $C(q_0, R_0)$ are sufficient to apply Rauch's comparison theorem.

REMARK. The estimate (2.1) corresponds to the one-sided condition of Giaquinta-Giusti [6] (see the proof of Theorem 3.3).

In the following we assume that the target manifold N satisfies the condition $C(q_0, R_0)$ and always use a normal coordinate (u^1, \dots, u^n) centered at q_0 on $B_{R_0}(q_0)$. For some positive constant $R < R_0$ and a boundary data $f \in H^{1,2} \cap L^{\infty}(\Omega, \mathbb{R}^n)$ with $||f||_{L^{\infty}(\Omega)} < R$ we seek a minimizer of E_G in the class

$$(2.3) X_{f,R} := \{ v \in H^{1,2}(\Omega, \mathbb{R}^n); v - f \in H_0^{1,2}(\Omega, \mathbb{R}^n), \|v\|_{L^{\infty}(\Omega)} \le R \}.$$

and show that the minimizer u satisfies the equation (1.3) weakly. (In order to see that minimizer u in the class $X_{f,R}$, we must show the strict inequality $||u||_{L^{\infty}} < R$.)

To find a minimizer, we consider the following condition on G:

$$|G(u)| \le b_0 + b_1 |u|^{\gamma} \quad \text{for some} \quad \gamma \in [0, 2^*).$$

Moreover, in order to show the boundedness of |u| we put the following conditions on $\partial G/\partial s(s = |u|)$:

(2.5)
$$\left| \frac{\partial G}{\partial s}(u) \right| \le b_2 + b_3 |u|^{\gamma - 1} \quad \text{for some} \quad \gamma \in \left[0, \frac{4}{m - 2} \right) .$$

Here, b_0 , b_1 , b_2 and b_3 are positive constants.

Now, we can state our results on the existence of minimizers of E_G in the class $X_{f,R}$ (Theorem 2.2) and L^{∞} -estimate of them (Theorem 2.3).

THEOREM 2.2. Let (M, g) be a smooth Riemannian m-manifold, and Ω a bounded domain of M with the smooth boundary $\partial \Omega$. Let (N, h) be a smooth Riemannian n-manifold which satisfies the condition $C(q_0, R_0)$ for some $q_0 \in N$ and $R_0 \in (0, +\infty]$. Assume that G satisfies (2.4). Then for any $R < R_0$ and $f \in H^{1,2} \cap L^{\infty}(\Omega, \mathbb{R}^n)$ with $||f||_{L^{\infty}(\Omega)} < R$ there exists a minimizer of E_G in the class $X_{f,R}$.

PROOF. Let $\{v_k\}$ be a minimizing sequence of E_G in the class $X_{f,R}$. Since the condition (2.4) implies that

(2.6)
$$E_G(v; \Omega) \ge c_0(g, h) \int_{\Omega} |Dv|^2 dx - c_1(b_0, b_1, \gamma, R, \Omega)$$

for every $v \in X_{f,R}$, we see that the sequence $\{v_k\}$ is equibounded in $H^{1,2}$. Therefore, taking subsequence if necessary, we see that

$$(2.7) v_k \rightharpoonup u \text{weakly in} H^{1,2},$$

(2.8)
$$v_k \to u$$
 strongly in L^{γ} for $\gamma \in [1, 2^*)$

for some $u \in \{v \in H^{1,2} \cap L^{\gamma}(\Omega, \mathbb{R}^n); v - f \in H^{1,2}\}$. Here, we used the Kondrachov compactness theorem also. From (2.7) and (2.8), we see easily that

$$\liminf_{k\to\infty} E_G(v_k;\Omega) \geq E_G(u;\Omega).$$

On the other hand, L^{γ} -strong convergence implies the almost everywhere convergence, therefore the limit map u belongs to the class $X_{f,R}$. Thus, u minimizes E_G in the class $X_{f,R}$.

THEOREM 2.3 Let (M, g), (N, h), Ω and f be as in Theorem 2.2. Suppose that $2 \le m \le 4$ and that G satisfies (2.4) and (2.5). If we have

$$(2.9) b_0, b_1, b_2, b_3, E_G(f), ||f||_{L^{\infty}(\Omega)} < r_0$$

for a sufficiently small constant $r_0 > 0$, then a minimizer u in the class $X_{f,R}$ satisfies $||u||_{L^{\infty}(\Omega)} < R$ for some $R < R_0$ and solves (1.3) weakly. Here, r_0 depends only on g, h, m, Ω and R_0 .

When we can take $R_0 = +\infty$, the smallness condition (2.9) is not necessary.

PROOF. Let u be a minimizer of E_G in the class $X_{f,R}$, then u satisfies

(2.10)
$$0 = \frac{d}{dt} \Big|_{t=0} E_G(u + t\varphi; \Omega)$$

$$= \int_{\Omega} \left[g^{\alpha\beta} h_{ij} D_{\alpha} u^i \{ D_{\beta} \varphi^j + \Gamma^j_{kl} D_{\beta} u^l \varphi^k \} - \varphi^i \frac{\partial G}{\partial u^i} \right] \sqrt{g} dx$$

for all $\varphi \in H_0^{1,2}(\Omega, \mathbb{R}^n)$ with

(2.11)
$$u + t\varphi \in X_{f,R}$$
 for all t with $|t| < \varepsilon$ for some $\varepsilon > 0$.

Because of the restriction (2.11), we can not say that (2.10) holds for every test function $\varphi \in C_0^{\infty}(\Omega, \mathbb{R}^n)$. Therefore, we can not call u a weak solution yet.

Now, let us show the estimate

$$(2.12) ||u||_{L^{\infty}(\Omega)} < R,$$

which enables us to call u as a weak solution.

For any nonnegative function $\eta \in C_0^1(\Omega)$, if we take $\varepsilon > 0$ sufficiently small, $u + (-\varepsilon)\eta u$ belongs to the class $X_{f,R}$. Therefore we can take $\varphi = -\varepsilon \eta u$ in (2.10) and get

(2.13)
$$0 = \int_{\Omega} \left[g^{\alpha\beta}(x) h_{ij}(u) \{ D_{\alpha} u^{i} D_{\beta} u^{j} + u^{k} \Gamma_{lk}^{j} D_{\alpha} u^{i} D_{\beta} u^{l} \} \eta + g^{\alpha\beta}(x) h_{ij}(u) D_{\alpha} u^{i} u^{j} D_{\beta} \eta - u^{i} \frac{\partial G}{\partial u^{i}} \eta \right] d\mu.$$

Since we are using a normal coordinate on N, (2.13) implies that

(2.14)
$$\int_{\Omega} g^{\alpha\beta}(x)h_{ij}(u)\{D_{\alpha}u^{i}D_{\beta}u^{j} + u^{k}\Gamma_{lk}^{j}D_{\alpha}u^{i}D_{\beta}u^{l}\}\eta d\mu$$
$$= -\int_{\Omega} \left\{ \frac{1}{2}g^{\alpha\beta}(x)D_{\alpha}|u|^{2}D_{\beta}\eta - u^{i}\frac{\partial G}{\partial u^{i}}\eta \right\} d\mu.$$

On the other hand, from (2.1) of Lemma 2.1, we have

$$(2.15) g^{\alpha\beta}(x)h_{ij}(u)\{D_{\alpha}u^{i}D_{\beta}u^{j}+u^{k}\Gamma_{lk}^{j}D_{\alpha}u^{i}D_{\beta}u^{l}\}\geq \delta|Du|^{2}$$

for

$$\delta = \min\{1, \inf_{0 \le t \le R} t \rho'(t)/\rho(t)\} > 0.$$

Thus, under the condition $C(q_0, R_0)$, we get for all $\eta \in C_0^1(\Omega)$ with $\eta \ge 0$ that

(2.16)
$$0 \ge \int_{\Omega} \left\{ \frac{1}{2} g^{\alpha\beta}(x) D_{\alpha} |u|^2 D_{\beta} \eta - |u| \frac{\partial G}{\partial s} \eta \right\} d\mu,$$

where $s = |u| = \text{dist}(q_0, u(x))$. Since u belongs to the class $X_{f,R}$, u is essentially bounded and therefore $D|u|^2$ is in the class L^2 , namely $|u|^2 \in H^{1,2}$.

Let $w = |u|^2 - |f|^2$, then from (2.16), w satisfies

(2.17)
$$\int_{\Omega} \left\{ g^{\alpha\beta}(x) D_{\alpha} w D_{\beta} \eta - g^{\alpha\beta}(x) D_{\alpha} |f|^2 D_{\beta} \eta + |u| \frac{\partial G}{\partial s} \eta \right\} d\mu \le 0$$

for any $\eta \in C_0^1(\Omega)$ with $\eta \ge 0$. Assume that $|u|\partial G/\partial s \in L^q(\Omega)$ for some q > m/2, then using [9, Theorem 8.15] we get

(2.18)
$$\sup_{\Omega} |w| \leq c_2(m, g, \Omega) \left(\|u\|_{L^4} + \|f\|_{L^{2_q}} + \|u| \frac{\partial G}{\partial s} \|_{L^q} \right).$$

Now, let us estimate the right hand side of (2.18). Since we are assuming (2.4), the minimality of u implies that

$$\int_{\Omega} e(u)d\mu \leq \int_{\Omega} G(u)d\mu + E_{G}(f)$$

$$\leq E_{G}(f) + b_{0}\text{vol.}(\Omega) + b_{1} \int_{\Omega} |u|^{\gamma} d\mu$$

$$\leq E_{G}(f) + b_{0}\text{vol.}(\Omega) + b_{1} \int_{\Omega} \left\{ \varepsilon |u|^{2^{*}} + \varepsilon^{-\frac{\gamma}{2^{*}-\gamma}} \right\} d\mu$$

$$\leq c_{3}(E_{G}(f), \Omega, g, \varepsilon, \gamma, b_{0}, b_{1}) + \varepsilon c_{4}(\Omega, g, h, b_{1}) \int_{\Omega} e(u) d\mu.$$

Here, we used Young's inequality and the Sobolev inequality. By choosing $\varepsilon > 0$ sufficiently small, we get the following a-priori estimate:

(2.19)
$$\int_{\Omega} |Du|^2 dx \le c_5(g, h, \gamma, b_0, b_1, \Omega, E_G(f)).$$

Using the Sobolev inequality and the assumption that $2 \le m \le 4$, from (2.19) we get

$$||u||_{L^4} \le c_6(\Omega, m)||u||_{L^{2^*}} \le c_6 K_0(g, h, \gamma, b_0, b_1, \Omega, E_G(f)).$$

for some positive constants c_6 and K_0 . Here, it is nothing to see that K_0 satisfies

(2.21)
$$\lim_{b_0,b_1,E_G(f)\to 0} K_0(g,h,\gamma,b_0,b_1,\Omega,E_G(f)) = 0.$$

On the other hand, using the condition (2.5), we see that

$$\||u|\frac{\partial G}{\partial s}\|_{L^q} \le c_7(b_2, b_3, q, \Omega)\|u\|_{L^{2^*}}$$
 for $q = \min\{2^*, 2^*/\gamma\} > m/2$.

Thus, if $2 \le m \le 4$ and (2.5) holds, we obtain from (2.18)

(2.22)
$$\sup_{\Omega} |u|^2 \le c_4 \{c_6(1+c_7)K_0 + ||f||_{L^{2q}}\} + \sup_{\Omega} |f|^2.$$

Now, from (2.21) and (2.22), we can see that if b_0 , b_1 , b_2 , b_3 , $E_G(f)$ and $||f||_{L^{\infty}(\Omega)}$ are sufficiently small we have (2.12).

When we can take $R_0 = +\infty$, for any given b_0, b_1, b_2, b_3 and f we can choose R sufficiently large so that R is greater than the right hand side of (2.22).

3. Regularity of minimizers.

In this section we show the $C^{0,\alpha}$ -regularity of a minimizer u under the condition (2.5). When the boundedness of a minimizer u of E_G is given, we can easily see that the results of [6] and [14] are valid for our case. More precisely we have the following theorems:

THEOREM 3.1. Let M, N, Ω and f be as in Theorem 2.2 and G a smooth function defined on N. Assume that u minimize E_G in the class $X_{f,R}$ and that $\|u\|_{L^{\infty}(\Omega)} < R$. Then there exists an open set $\Omega_0 \subset \Omega$ such that $u \in C^{0,\alpha}(\Omega_0, \mathbb{R}^n)$ for every $\alpha \in (0, 1)$. Moreover,

(3.1)
$$\Omega \setminus \Omega_0 = \left\{ x_0 \in \Omega; \liminf_{r \to 0} r^{2-n} \int_{B_r(x_0)} |Du|^2 dx > \varepsilon_0 \right\}$$

where ε_0 is a positive constant independent of u. Finally

$$\mathcal{H}^{n-q}(\Omega \backslash \Omega_0) = 0$$

for some q > 2, \mathcal{H}^{n-q} denoting (n-q)-dimensional Hausdorff measure.

PROOF. It is enough to proceed as the proof of [6, Theorem 5.1], adding $\int G(u)dx$ to their quadratic functional. We will get

$$\int_{B\rho} (1+|Du|^2) dx$$

$$\leq c_8 \left[\left(\frac{\rho}{r} \right)^m + \omega \left(r^2 + c_9 r^{2-m} \int_{B_r} |Du|^2 dx \right)^{1-2/q} \right] \int_{B_{2r}} |Du|^2 dx + c_{10} r^m,$$

instead of [6, (5.11)]. Now, the assertion follows from the above estimate using "a useful lemma" on [5, p. 44].

THEOREM 3.2. Let M, N, Ω, G, f and u be as in Theorem 3.1. Assume that the boundary data f is in the class $H^{1,s}(\Omega, N)$ for some s > m. Then u is Hölder continuous in a neighborhood of $\partial \Omega$.

PROOF. Let x_0 be an arbitrary point on $\partial \Omega$ and choose a local coordinate system so that $x_0 = 0$. As in [14], let us consider the blown-up functions

$$u_{(\nu)}(x) = u(x/\nu), \quad g_{(\nu)}^{\alpha\beta}(x) = g^{\alpha\beta}(x/\nu), \quad (\nu = 1, 2, 3, ...).$$

Then $u_{(\nu)}$ minimizes the functional

$$\int \left[\frac{1}{2}g_{(\nu)}^{\alpha\beta}(x)h_{ij}(v)D_{\alpha}v^{i}D_{\beta}v^{j}-\frac{1}{v^{2}}G(v(x))\right]\sqrt{g_{(\nu)}}dx\,,$$

and converges to a minimizer v of the functional

$$\int \left[\frac{1}{2}g^{\alpha\beta}(0)h_{ij}(v)D_{\alpha}v^{i}D_{\beta}v^{j}\right]\sqrt{g}dx.$$

Namely, the potential term disappears in the blowing-up process. Thus, we can proceed as in [14] and get the assertion.

Now, we prove the following regularity theorem for minimizers of E_G .

THEOREM 3.3. Suppose that all assumptions in Theorem 3.2 are satisfied. Let u be a minimizer of E_G in the class $X_{f,R}$ which satisfies $\|u\|_{L^{\infty}(\Omega)} < R$. Then u is Hölder continuous on $\bar{\Omega}$.

PROOF. By virtue of Theorems 3.1 and 3.2, it is enough to show that for every $\varepsilon_0 > 0$ and $x \in \Omega$ there exists a positive constant $\rho > 0$ such that

(3.2)
$$\rho^{2-n} \int_{B_{\rho}(x)} |Du|^2 dx \le \varepsilon_0.$$

To show (3.2) we can proceed similarly as in [6] by remarking that the estimate (2.15) plays the role of the one-sided condition of [6].

Let $x \in \Omega$ be an arbitrarily fixed point and r a positive constant such that $B_{2r}(x) \subset\subset \Omega$. Choosing $\eta \geq 0$ in (2.14) so that spt $\eta \subset B_{2r}(x)$ and using (2.15) we get

(3.3)
$$\delta \int_{B_{2r}(x)} |Du|^2 \eta d\mu \leq -\int_{B_{2r}(x)} \left\{ \frac{1}{2} g^{\alpha\beta}(x) D_{\alpha} |u|^2 D_{\beta} \eta - |u| \frac{\partial G}{\partial s} \right\} d\mu.$$

Since we are assuming that $||u||_{L^{\infty}} < R$, we have

$$\left| |u| \frac{\partial G}{\partial s} \right| \le K$$

for some positive constant K which depends only g, h, G and f. Let $M(r) = \sup_{B_r(x)} |u|$ and $z = M^2(2r) - |u|^2$. Then from (3.3) and (3.4) we get

$$(3.5) 0 \leq \int_{B_{\sigma}(x)} (g^{\alpha\beta}(x)D_{\alpha}zD_{\beta}\eta + K)d\mu.$$

Thus, z is a nonnegative supersolution of a uniformly elliptic equation and therefore, using the weak Harnack inequality (see [9, Theorem 8.18]), we obtain

(3.6)
$$r^{-m} \int_{B_{2r}(x)} |z| dx \le c_{11}(g, m, K) \left(\inf_{B_r(x)} z + r^2 \right) .$$

Let $w \in C^2(B_{2r}(x)) \cup C(B_{2\bar{r}}(x))$ be a solution of the Dirichlet problem

$$\begin{cases} D_{\beta} \{ \sqrt{g} g^{\alpha\beta}(x) D_{\alpha} w \} = -\frac{1}{r^2} & \text{in } B_{2r}(x) , \\ w = 0 & \text{on } \partial B_{2r}(x) . \end{cases}$$

Then, w is bounded from above by a positive constant α_1 in $B_{2r}(x)$ (see for example [9, Theorem 3.7]). On the other hand, since the right hand side of the above equation is negative, w is a positive supersolution of the equation $D_{\beta}\{\sqrt{g}g^{\alpha\beta}(x)D_{\alpha}w\}=0$, and therefore by the weak Harnack inequality we have that $w \geq \alpha_2$ in $B_r(x)$ for some positive constant α_2 . Here, α_1 and α_2 does not depend on r. Indeed, if w_1 is a solution of the above Dirichlet problem for r=1, then $w(x)=w_1(tx)$ solves the Dirichlet problem for r=t.

Now, w is in the class $H_0^{1,2}(B_{2r}(x))$ clearly and satisfies the following weak from of the equation

$$(3.7) \qquad \int_{B_{2r}(x)} g^{\alpha\beta}(x) D_{\beta} w D_{\alpha} \varphi \sqrt{g} dx = r^{-2} \int_{B_{2r}(x)} \varphi dx \quad \text{for all} \quad \varphi \in H_0^{1,2}(B_{2r}(x)).$$

Let $\varphi = wz$ in (3.7), then we have

$$\frac{1}{2} \int_{B_{2r}(x)} g^{\alpha\beta} D_{\beta} w^2 D_{\alpha} z d\mu + \int_{B_{2r}(x)} g^{\alpha\beta} D_{\beta} w D_{\alpha} w z d\mu = r^{-2} \int_{B_{2r}(x)} w z dx,$$

and therefore

(3.8)
$$\frac{1}{2} \int_{B_{2r}(x)} g^{\alpha\beta} D_{\beta} w^2 D_{\alpha} z dx \le \alpha_1 r^{-2} \int_{B_{2r}(x)} z dx.$$

Since w^2 is in the class $H_0^{1,2}$ also, we can take $\eta = w^2$ in (3.3). Taking $\eta = w^2$ in (3.3) and using (3.6) and (3.8), we get

(3.9)
$$\delta\alpha_{2}^{2} \int_{B_{r}(x)} |Du|^{2} d\mu \leq \frac{1}{2} \int_{B_{2r}(x)} g^{\alpha\beta} D_{\alpha} z D_{\beta} \eta d\mu + \int_{B_{2r}(x)} K w^{2} d\mu$$
$$\leq \alpha_{1} r^{-2} \int_{B_{2r}(x)} z dx + K \alpha_{1}^{2} (2r)^{m}$$
$$\leq \alpha_{1} c_{12} r^{m-2} \inf_{B_{r}(x)} z + c_{13} r^{m}.$$

Thus we obtain

$$(3.10) r^{2-m} \int_{B_r(x)} |Du|^2 dx \le c_{14} \left\{ \inf_{B_r(x)} z + r^2 \right\} \le c_{14} \{ M^2(2r) - M^2(r) + r^2 \}.$$

On the other hand u is bounded and therefore

$$\sum_{k=0}^{+\infty} [M^2(2^{1-k}r) - M^2(2^kr)] \le M^2(2r) \le \sup_{\Omega} |u|^2.$$

Thus (3.10) implies (3.2) with $\rho = 2^{-k}r$ for some k.

Now, combining Theorems 2.2, 3.3 and the standard Schauder estimates, we get the following existence theorem.

THEOREM 3.4. Let M, N and Ω be as in Theorem 2.2 and r_0 as in Theorem 2.3. Suppose that a smooth function G(u) satisfies (2.4) and (2.5) with $b_i < r_0$ (i = 0, 1, 2, 3) and that the boundary data f is in the class $H^{1,s} \cap L^{\infty}(\Omega, \mathbb{R}^n)$ for some s > m and satisfies $E_G(f)$, $||f||_{L^{\infty}(\Omega)} < r_0$. Then there exists a minimizer u of E_G in the class $X_{f,R}$ for some $R < R_0$. Moreover, the minimizer u is in the class $C^{2,\alpha}(\Omega, B_R) \cap C^{0,\alpha}(\bar{\Omega}, B_R)$ and a harmonic map with potential G.

If we can take $R_0 = \infty$, the smallness conditions on b_i (i = 0, 1, 2, 3), $E_G(f)$ and on $||f||_{L^{\infty}(\Omega)}$ are not necessary.

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