

On the Interval Maps Associated to the α -mediant Convergents

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1. Introduction

For an irrational number $x \in (0, 1)$, if a non-zero rational number $\frac{p}{q}$, $(p, q) = 1$, satisfies $\left| x - \frac{p}{q} \right| < \frac{1}{2q^2}$, then it is the n th regular principal convergent $\frac{p_n}{q_n}$ for some $n \geq 1$. Here, the n th regular principal convergents are defined by the regular continued fraction expansion of x :

$$x = \frac{1}{|a_1|} + \frac{1}{|a_2|} + \frac{1}{|a_3|} + \cdots .$$

We put

$$\begin{cases} p_{-1} = p_{-1}(x) = 1, & p_0 = p_0(x) = 0 \\ q_{-1} = q_{-1}(x) = 0, & q_0 = q_0(x) = 1 \end{cases}$$

and

$$\begin{cases} p_n = p_n(x) = a_n \cdot p_{n-1} + p_{n-2} \\ q_n = q_n(x) = a_n \cdot q_{n-1} + q_{n-2} \end{cases} \quad \text{for } n \geq 1 .$$

Then it is well-known that

$$\frac{p_n}{q_n} = \frac{1}{|a_1|} + \frac{1}{|a_2|} + \cdots + \frac{1}{|a_n|} \quad \text{for } n \geq 1 .$$

If $x \in [k, k + 1)$ for an integer k , we define its n th regular principal convergent by $\frac{p_n(x-k)}{q_n(x-k)} + k = \frac{p_n(x-k) + k \cdot q_n(x-k)}{q_n(x-k)}$.

For some $x \in (0, 1)$, there exists $\frac{p}{q}$ with $(p, q) = 1$ and $\left|x - \frac{p}{q}\right| < \frac{1}{q^2}$, which is not the n th regular principal convergent for any $n \geq 0$. However, we can find such a fraction $\frac{p}{q}$ in the set $\left\{\frac{p_n - p_{n-1}}{q_n - q_{n-1}}, \frac{p_n + p_{n-1}}{q_n + q_{n-1}} : n \geq 1\right\}$. This leads us to the notion of the regular mediant convergents of level n , $\frac{u_{n,t}}{v_{n,t}}$, which is defined by

$$\begin{cases} u_{n,t} = t \cdot p_n + p_{n-1} & \text{for } 1 \leq t < a_{n+1}, n \geq 0. \\ v_{n,t} = t \cdot q_n + q_{n-1} \end{cases}$$

The regular principal and the regular mediant convergents are obtained by the following maps T and F of $[0, 1]$, which are called the Gauss map and the Farey map, respectively, see [2]:

$$T(x) = \begin{cases} \frac{1}{x} - \left[\frac{1}{x}\right] & \text{if } x \in (0, 1] \\ 0 & \text{if } x = 0 \end{cases} \quad (1.1)$$

and

$$F(x) = \begin{cases} \frac{x}{1-x} & \text{if } x \in \left[0, \frac{1}{2}\right) \\ \frac{1-x}{x} & \text{if } x \in \left[\frac{1}{2}, 1\right], \end{cases}$$

where $[y] = n$ if $y \in [n, n+1)$. We get the coefficients of the regular continued fraction expansion of $x \in [0, 1]$ by

$$a_n = a_n(x) = [(T^{n-1}(x))^{-1}], \quad n \geq 1.$$

We refer to Sh. Ito [3] on the relation between F and the regular mediant convergents. In this paper, we generalize the notion of the mediant convergents to the continued fraction expansion introduced by H. Nakada [5], which are called the α -continued fraction expansion. The α -continued fraction expansion is a generalization of the regular continued fraction expansion and is induced by the following map T_α of $\mathbf{I}_\alpha = [\alpha - 1, \alpha]$ for $\frac{1}{2} \leq \alpha \leq 1$:

$$T_\alpha(x) = \begin{cases} \left| \frac{1}{x} \right| - \left[\left| \frac{1}{x} \right| \right]_\alpha & \text{if } x \in \mathbf{I}_\alpha \setminus \{0\} \\ 0 & \text{if } x = 0, \end{cases}$$

where $[y]_\alpha = n$ if $y \in [n - 1 + \alpha, n + \alpha)$. We note that T_1 is the Gauss map. For $n \geq 1$, put

$$\varepsilon_{\alpha,n} = \varepsilon_{\alpha,n}(x) = \text{sgn } T_\alpha^{n-1}(x),$$

$$c_{\alpha,n} = c_{\alpha,n}(x) = \left[\left| \frac{1}{T_{\alpha}^{n-1}(x)} \right| \right]_{\alpha} \quad (\text{or } = \infty \quad \text{if } T_{\alpha}^{n-1}(x) = 0).$$

Then we have the α -continued fraction expansion of $x \in \mathbf{I}_{\alpha}$:

$$x = \frac{\varepsilon_{\alpha,1}}{c_{\alpha,1}} + \frac{\varepsilon_{\alpha,2}}{c_{\alpha,2}} + \frac{\varepsilon_{\alpha,3}}{c_{\alpha,3}} + \cdots, \quad c_{\alpha,n} \geq 1.$$

Next for $n \geq 1$, we define the n th α -principal convergents $\frac{p_{\alpha,n}}{q_{\alpha,n}}$ by

$$\begin{cases} p_{\alpha,-1} = 1, & p_{\alpha,0} = 0 \\ q_{\alpha,-1} = 0, & q_{\alpha,0} = 1 \end{cases} \quad \text{and} \quad \begin{cases} p_{\alpha,n} = c_{\alpha,n} \cdot p_{\alpha,n-1} + \varepsilon_{\alpha,n} \cdot p_{\alpha,n-2} \\ q_{\alpha,n} = c_{\alpha,n} \cdot q_{\alpha,n-1} + \varepsilon_{\alpha,n} \cdot q_{\alpha,n-2}. \end{cases}$$

We note that the $\{q_{\alpha,n}\}$ is strictly increasing, see [5]. Also we define the α -mediant convergents of level $n \geq 0$, $\left\{ \frac{u_{\alpha,n,t}}{v_{\alpha,n,t}} : 1 \leq t < c_{\alpha,n+1} \right\}$, by

$$\begin{cases} u_{\alpha,n,t} = t \cdot p_{\alpha,n} + \varepsilon_{\alpha,n+1} \cdot p_{\alpha,n-1} \\ v_{\alpha,n,t} = t \cdot q_{\alpha,n} + \varepsilon_{\alpha,n+1} \cdot q_{\alpha,n-1} \end{cases} \quad \text{for } 1 \leq t < c_{\alpha,n+1}. \quad (1.2)$$

In §2, we define a new map G_{α} for each α , $\frac{1}{2} \leq \alpha \leq 1$ and show how G_{α} induces the sequence of the α -principal and the α -mediant convergents. We call G_{α} the α -Farey map of the first type. We note that G_{α} is the same as F in the above if $\alpha = 1$. Our idea for getting the mediant convergents is slightly different from the one in [3]. In §3, we give some estimates on the error term of the convergence of $\frac{u_{\alpha,n,t}}{v_{\alpha,n,t}}$ to $x \in \mathbf{I}_{\alpha}$. The first assertion is its upper estimate:

$$\left| x - \frac{u_{\alpha,n,t}}{v_{\alpha,n,t}} \right| < \frac{1}{q_{\alpha,n} \cdot q_{\alpha,n-1}}.$$

This shows that $\frac{u_{\alpha,n,t}}{v_{\alpha,n,t}}$ converges to x . The second assertion is

$$\limsup_{\substack{1 \leq t < c_{\alpha,n+1} \\ n \rightarrow \infty}} v_{\alpha,n,t}^2 \left| x - \frac{u_{\alpha,n,t}}{v_{\alpha,n,t}} \right| = \infty \quad (\text{a.e.}),$$

though

$$\liminf_{\substack{1 \leq t < c_{\alpha,n+1} \\ n \rightarrow \infty}} v_{\alpha,n,t}^2 \left| x - \frac{u_{\alpha,n,t}}{v_{\alpha,n,t}} \right| < 2 \quad \text{if } c_{\alpha,n} \geq 2 \quad \text{occur infinitely often.}$$

This means that we can not give any estimates after the normalization by the square of the denominator. For the asymptotic behavior of the values

$$v_{\alpha,n,t}^2 \left| x - \frac{u_{\alpha,n,t}}{v_{\alpha,n,t}} \right|, \quad (1.3)$$

we give a 2-dimensional map \widehat{G}_α which we call the “natural extension” of G_α in §4. By this map, we can discuss the distribution of (1.3) for almost every x by using the ratio ergodic theorem. In §5, we describe a relation between the α -mediant convergents and the regular mediant convergents. Actually, we show that the set of the α -principal and the α -mediant convergents coincides with the set of the regular’s. K. Dajani and C. Kraaikamp [1] showed that Lehner fractions induce the set of the regular principal and the regular mediant convergents. They also showed that this set includes all principal convergents arising from S -expansions, see [4] for the definition of S -expansions. In this sense, they called this set “the mother of all semi-regular continued fractions”. Our claim is that we can construct the “mother” from any α -continued fractions, $\frac{1}{2} \leq \alpha \leq 1$, by producing the α -mediant convergents. Incidentally, it is easy to see that

$$\frac{u_{\alpha,n,1}}{v_{\alpha,n,1}} = \frac{u_{\alpha,n-1,c_{\alpha,n-1}}}{v_{\alpha,n-1,c_{\alpha,n-1}}} \quad \text{if } \varepsilon_{\alpha,n+1} = -1.$$

This means that one rational number appears twice when $\varepsilon_{\alpha,n+1} = -1$ in the approximating sequence. In the final part of this paper, we give a new map F_α , $\frac{1}{2} \leq \alpha \leq 1$, the α -Farey map of the second type, which also induces the α -principal and the α -mediant convergents without $\frac{u_{\alpha,n-1,c_{\alpha,n-1}}}{v_{\alpha,n-1,c_{\alpha,n-1}}}$ if $\varepsilon_{\alpha,n+1} = -1$.

2. The α -Farey maps and the α -mediant convergents

For a real number α , $\frac{1}{2} \leq \alpha \leq 1$, we put $\mathbf{J}_\alpha = \left[\alpha - 1, \frac{1}{\alpha} \right]$. Define a map G_α of \mathbf{J}_α by

$$G_\alpha(x) = \begin{cases} -\frac{x}{1+x} & \text{if } x \in [\alpha - 1, 0) := \mathbf{J}_{\alpha,1} \\ \frac{x}{1-x} & \text{if } x \in \left[0, \frac{1}{1+\alpha} \right] := \mathbf{J}_{\alpha,2} \\ \frac{1-x}{x} & \text{if } x \in \left(\frac{1}{1+\alpha}, \frac{1}{\alpha} \right] := \mathbf{J}_{\alpha,3}. \end{cases}$$

We note that G_1 is the Farey map for the regular continued fractions. In this sense, G_α is a generalization of the Farey map. We call this map the α -Farey map of the first type, because we give a map which will be called the α -Farey map of the second type in the final part of this paper.

In order to get the α -principal and the α -mediant convergents of $x \in \mathbf{J}_\alpha$ by the iterations of G_α , it is convenient to use the following matrices:

$$V_- = \begin{pmatrix} -1 & 0 \\ 1 & 1 \end{pmatrix}, \quad V_+ = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}, \quad U = \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}.$$

Since

$$\frac{ax+b}{cx+d} = \frac{u}{v} \quad \text{with} \quad \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} xz \\ z \end{pmatrix}$$

for any real numbers x and $z \neq 0$, we denote

$$A(x) = \frac{ax+b}{cx+d} \quad \text{and} \quad A(-\infty) = A(\infty) = \frac{a}{c} \quad \text{for} \quad A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}.$$

Hence, we can write

$$G_\alpha(x) = \begin{cases} V_-^{-1}(x) & \text{if } x \in \mathbf{J}_{\alpha,1} \\ V_+^{-1}(x) & \text{if } x \in \mathbf{J}_{\alpha,2} \\ U^{-1}(x) & \text{if } x \in \mathbf{J}_{\alpha,3}. \end{cases}$$

Next, we put

$$M_n(x) := \begin{cases} V_- & \text{if } (G_\alpha)^{n-1}(x) \in \mathbf{J}_{\alpha,1} \\ V_+ & \text{if } (G_\alpha)^{n-1}(x) \in \mathbf{J}_{\alpha,2} \\ U & \text{if } (G_\alpha)^{n-1}(x) \in \mathbf{J}_{\alpha,3}. \end{cases}$$

Then, we get a sequence of matrices

$$M_1(x), \quad M_2(x), \quad \dots$$

from the iterations of G_α for each $x \in \mathbf{J}_\alpha$. Here, all matrices M_n 's are of determinants ± 1 . To investigate relationship between T_α and G_α , we need the following lemmas.

LEMMA 1.

$$(i) \quad \begin{pmatrix} 0 & 1 \\ 1 & t \end{pmatrix} = \underbrace{\begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix} \cdots \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}}_{t-1} \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix} = \underbrace{V_+ \cdots V_+}_{t-1} U \quad \text{for } t \geq 1.$$

$$(ii) \quad \begin{pmatrix} 0 & -1 \\ 1 & t \end{pmatrix} = \begin{pmatrix} -1 & 0 \\ 1 & 1 \end{pmatrix} \underbrace{\begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix} \cdots \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}}_{t-2} \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix} = V_- \underbrace{V_+ \cdots V_+}_{t-2} U \\ \text{for } t \geq 2.$$

LEMMA 2. Suppose that $x \in \mathbf{J}_\alpha$. If $x \in \left[-\frac{1}{j-1+\alpha}, -\frac{1}{j+\alpha} \right) \cup \left(\frac{1}{j+\alpha}, \frac{1}{j-1+\alpha} \right]$, then $G_\alpha(x) \in \left(\frac{1}{j-1+\alpha}, \frac{1}{j-2+\alpha} \right]$ for $j \geq 2$.

We put

$$k_0(x) := 0 \quad \text{and} \quad k_n(x) := \min\{k > k_{n-1}(x) : (G_\alpha)^{k-1}(x) \in \mathbf{J}_{\alpha,3}\}, \quad n \geq 1.$$

Next proposition shows that T_α is obtained as a jump transformation in the sense of F. Schweiger, see [9].

PROPOSITION 1.

$$(G_\alpha)^{k_1(x)}(x) = T_\alpha(x) \quad \text{for} \quad x \in \mathbf{I}_\alpha = [\alpha - 1, \alpha].$$

PROOF. If $x \in \left(\frac{1}{j+\alpha}, \frac{1}{j-1+\alpha}\right] \cap \mathbf{I}_\alpha$, then by Lemma 2, we see

$$M_1(x)M_2(x) \cdots M_{k_1(x)}(x) = \underbrace{V_+ \cdots V_+}_{j-1} U \quad \text{for} \quad j \geq 1. \quad (2.1)$$

Hence, from Lemma 1, we have

$$(G_\alpha)^{k_1(x)}(x) = U^{-1} \underbrace{V_+^{-1} \cdots V_+^{-1}}_{j-1}(x) = \begin{pmatrix} -j & 1 \\ 1 & 0 \end{pmatrix} (x) = \frac{-jx+1}{x} = T_\alpha(x). \quad (2.2)$$

If $x \in \left[-\frac{1}{j-1+\alpha}, -\frac{1}{j+\alpha}\right) \cap \mathbf{I}_\alpha$, then by Lemma 2 again, we see

$$M_1(x)M_2(x) \cdots M_{k_1(x)}(x) = V_- \underbrace{V_+ \cdots V_+}_{j-2} U \quad \text{for} \quad j \geq 2. \quad (2.3)$$

Thus, we also have

$$(G_\alpha)^{k_1(x)}(x) = U^{-1} \underbrace{V_+^{-1} \cdots V_+^{-1}}_{j-2} V_-^{-1}(x) = \begin{pmatrix} j & 1 \\ -1 & 0 \end{pmatrix} (x) = T_\alpha(x). \quad (2.4)$$

□

For any two numbers x and $x' \in \mathbf{I}_\alpha$, their α -continued fraction expansions are different from each other since the expansions converge to x and x' , respectively. Thus we have the following.

COROLLARY 1.

$$(M_1(x), M_2(x), \dots) \neq (M_1(x'), M_2(x'), \dots) \quad \text{whenever} \quad x \neq x' \in \mathbf{J}_\alpha.$$

PROOF. Suppose that $x \neq x' \in \mathbf{J}_\alpha$. If $k_1(x) \neq k_1(x')$ or $M_i(x) \neq M_i(x')$ for some $1 \leq i \leq k_1(x)$, then the assertion is clear. So we assume that $k_1(x) = k_1(x')$ and $M_i(x) = M_i(x')$ for $1 \leq i \leq k_1(x)$. Then Lemma 2 implies that

$$x \text{ and } x' \in \left[-\frac{1}{k_1(x)-1+\alpha}, -\frac{1}{k_1(x)+\alpha}\right) \cup \left(\frac{1}{k_1(x)+\alpha}, \frac{1}{k_1(x)-1+\alpha}\right]$$

and

$$G_\alpha^{k_1(x)}(x) \neq G_\alpha^{k_1(x)}(x').$$

since $G_\alpha^{k_1(x)}$ is a one-to-one map on $\left[-\frac{1}{k_1(x) - 1 + \alpha}, -\frac{1}{k_1(x) + \alpha} \right) \cup \left(\frac{1}{k_1(x) + \alpha}, \frac{1}{k_1(x) - 1 + \alpha} \right]$. Then we get sequences

$$M_{k_1(x)+1}(x), M_{k_1(x)+2}(x), \dots$$

and

$$M_{k_1(x)+1}(x'), M_{k_1(x)+2}(x'), \dots$$

Here we note that

$$G_\alpha^{k_1(x)}(x) \in \mathbf{I}_\alpha \quad \text{and} \quad G_\alpha^{k_1(x)}(x') = G_\alpha^{k_1(x')}(x') \in \mathbf{I}_\alpha.$$

By (2.1), (2.2), (2.3) and (2.4), the above sequences correspond to the α -continued fraction expansions of $G_\alpha^{k_1(x)}(x)$ and $G_\alpha^{k_1(x)}(x')$, which are not the same. \square

Finally we have the following theorem, which connects the map G_α to the α -mediant convergents explicitly.

THEOREM 1. *For $x \in \mathbf{I}_\alpha$, we have*

(i) *If $l = k_n(x)$, $n \geq 1$,*

$$M_1(x)M_2(x) \cdots M_l(x) = \begin{pmatrix} p_{\alpha,n-1} & p_{\alpha,n} \\ q_{\alpha,n-1} & q_{\alpha,n} \end{pmatrix} \quad (2.5)$$

(ii) *If $l = k_n(x) + t$, $1 \leq t < c_{\alpha,n+1}$, $n \geq 0$,*

$$M_1(x)M_2(x) \cdots M_l(x) = \begin{pmatrix} u_{\alpha,n,t} & p_{\alpha,n} \\ v_{\alpha,n,t} & q_{\alpha,n} \end{pmatrix} \quad (2.6)$$

PROOF. First, we show (2.5) by induction on n .

[I] $n = 1$

From (2.1), (2.2), (2.3) and (2.4), we have

$$M_1(x)M_2(x) \cdots M_{k_1(x)}(x) = \begin{pmatrix} 0 & \varepsilon_{\alpha,1} \\ 1 & c_{\alpha,1} \end{pmatrix} = \begin{pmatrix} p_{\alpha,0} & p_{\alpha,1} \\ q_{\alpha,0} & q_{\alpha,1} \end{pmatrix}.$$

[II] Suppose we have

$$M_1(x)M_2(x) \cdots M_{k_m(x)}(x) = \begin{pmatrix} p_{\alpha,m-1} & p_{\alpha,m} \\ q_{\alpha,m-1} & q_{\alpha,m} \end{pmatrix}$$

and

$$(G_\alpha)^{k_m(x)}(x) = T_\alpha^m(x) =: y.$$

Then, we see

$$M_{k_m(x)+1}(x)M_{k_m(x)+2}(x) \cdots M_{k_{m+1}(x)}(x) = M_1(y)M_2(y) \cdots M_{k_1(y)}(y)$$

since $k_1(y) = k_{m+1}(x) - k_m(x)$. Thus,

$$M_{k_m(x)+1}(x) \cdots M_{k_{m+1}(x)}(x) = \begin{pmatrix} 0 & \varepsilon_{\alpha,1}(y) \\ 1 & c_{\alpha,1}(y) \end{pmatrix} = \begin{pmatrix} 0 & \varepsilon_{\alpha,m+1}(x) \\ 1 & c_{\alpha,m+1}(x) \end{pmatrix}.$$

Hence, we have

$$M_1(x)M_2(x) \cdots M_{k_{m+1}(x)}(x) = \begin{pmatrix} p_{\alpha,m-1} & p_{\alpha,m} \\ q_{\alpha,m-1} & q_{\alpha,m} \end{pmatrix} \begin{pmatrix} 0 & \varepsilon_{\alpha,m+1} \\ 1 & c_{\alpha,m+1} \end{pmatrix} = \begin{pmatrix} p_{\alpha,m} & p_{\alpha,m+1} \\ q_{\alpha,m} & q_{\alpha,m+1} \end{pmatrix}.$$

Moreover, we see that

$$(G_\alpha)^{k_{m+1}(x)}(x) = (G_\alpha)^{k_{m+1}(x)-k_m(x)}((G_\alpha)^{k_m(x)}(x)) = T_\alpha(T_\alpha^m(x)) = T_\alpha^{m+1}(x).$$

Consequently, we have

$$M_1(x)M_2(x) \cdots M_{k_n(x)}(x) = \begin{pmatrix} p_{\alpha,n-1} & p_{\alpha,n} \\ q_{\alpha,n-1} & q_{\alpha,n} \end{pmatrix} \quad \text{for any } n \geq 1. \quad (2.7)$$

Next, we prove (2.6). If $(G_\alpha)^{k_n(x)}(x) = T_\alpha^n(x) > 0$, then $\varepsilon_{\alpha,n+1}(x) = 1$, otherwise $\varepsilon_{\alpha,n+1}(x) = -1$. So by (2.7), we see that

$$\begin{aligned} M_1(x)M_2(x) \cdots M_{k_n(x)+t}(x) &= \begin{pmatrix} p_{\alpha,n-1} & p_{\alpha,n} \\ q_{\alpha,n-1} & q_{\alpha,n} \end{pmatrix} \begin{pmatrix} \varepsilon_{\alpha,n+1} & 0 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}^{t-1} \\ &= \begin{pmatrix} p_{\alpha,n-1} & p_{\alpha,n} \\ q_{\alpha,n-1} & q_{\alpha,n} \end{pmatrix} \begin{pmatrix} \varepsilon_{\alpha,n+1} & 0 \\ t & 1 \end{pmatrix} \\ &= \begin{pmatrix} u_{\alpha,n,t} & p_{\alpha,n} \\ v_{\alpha,n,t} & q_{\alpha,n} \end{pmatrix} \end{aligned}$$

for $1 \leq t < c_{\alpha,n+1}$. □

The following is a direct consequence of Theorem 1.

COROLLARY 2. *We have*

$$(M_1(x)M_2(x) \cdots M_l(x))(\infty) = \begin{cases} \frac{p_{\alpha,n-1}}{q_{\alpha,n-1}} & \text{if } l = k_n(x), n \geq 1 \\ \frac{u_{\alpha,n,t}}{v_{\alpha,n,t}} & \text{if } l = k_n(x) + t, \\ & 1 \leq t < c_{\alpha,n+1}, n \geq 0. \end{cases}$$

REMARK. In [3], the regular mediant convergents were obtained as

$$(M_1(x)M_2(x) \cdots M_{l-1}(x))(1).$$

3. The convergence of the approximation

In this section, we discuss the convergence of the α -mediant convergents to x . We put

$$x_l = (G_\alpha)^l(x) \quad \text{for } l \geq 0.$$

From the definitions of G_α and M_n in §2, we see that

$$x = (M_1(x)M_2(x) \cdots M_l(x))(x_l). \quad (3.1)$$

First, we show the fundamental formulas concerning the error of the α -principal and the α -mediant convergents to x .

PROPOSITION 2.

(i) If $l = k_n(x)$, $n \geq 1$,

$$q_{\alpha, n-1}^2 \left| x - \frac{p_{\alpha, n-1}}{q_{\alpha, n-1}} \right| = \frac{1}{\left| x_l - \left(-\frac{q_{\alpha, n}}{q_{\alpha, n-1}} \right) \right|}.$$

(ii) If $l = k_n(x) + t$, $1 \leq t < c_{\alpha, n+1}$, $n \geq 0$,

$$v_{\alpha, n, t}^2 \left| x - \frac{u_{\alpha, n, t}}{v_{\alpha, n, t}} \right| = \frac{1}{\left| x_l - \left(-\frac{q_{\alpha, n}}{v_{\alpha, n, t}} \right) \right|}.$$

REMARK. We note that

$$(M_1(x)M_2(x) \cdots M_l(x))^{-1}(\infty) = \begin{cases} -\frac{q_{\alpha, n}}{q_{\alpha, n-1}} & \text{if } l = k_n(x), n \geq 1 \\ -\frac{q_{\alpha, n}}{v_{\alpha, n, t}} & \text{if } l = k_n(x) + t, \\ & 1 \leq t < c_{\alpha, n+1}, n \geq 0, \end{cases}$$

see Theorem 1.

PROOF. (i) If $l = k_n(x)$, $n \geq 1$, from (3.1) and (2.5), we see that

$$q_{\alpha, n-1}^2 \left| x - \frac{p_{\alpha, n-1}}{q_{\alpha, n-1}} \right| = q_{\alpha, n-1}^2 \left| \frac{p_{\alpha, n-1}x_l + p_{\alpha, n}}{q_{\alpha, n-1}x_l + q_{\alpha, n}} - \frac{p_{\alpha, n-1}}{q_{\alpha, n-1}} \right| = \frac{1}{\left| x_l - \left(-\frac{q_{\alpha, n}}{q_{\alpha, n-1}} \right) \right|}.$$

(ii) From (3.1) and (2.6), we conclude the assertion by the same calculation. \square

From this proposition, it is possible to show that the sequence of the α -mediant convergents certainly converges to x . However, this convergence also follows from Theorem 2 below. To prove it, we need the following lemma.

LEMMA 3. For $n \geq 0$, we have

- (i) $v_{\alpha, n, 1} > q_{\alpha, n-1}$,
- (ii) $v_{\alpha, n, t} > (t-1)q_{\alpha, n}$ for $2 \leq t < c_{\alpha, n+1}$.

PROOF. If $t \geq 2$, then

$$v_{\alpha,n,t} = t \cdot q_{\alpha,n} \pm q_{\alpha,n-1} > (t-1)q_{\alpha,n},$$

since $q_{\alpha,n}$ is strictly increasing.

Suppose that $t = 1$. If $\varepsilon_{\alpha,n+1} = -1$, then either $\varepsilon_{\alpha,n} = -1$ and $c_{\alpha,n} \geq 3$ or $\varepsilon_{\alpha,n} = 1$ and $c_{\alpha,n} \geq 2$ holds, see H. Nakada [5], p. 403. In the first case, we have

$$v_{\alpha,n,t} = q_{\alpha,n} - q_{\alpha,n-1} \geq 3q_{\alpha,n-1} - q_{\alpha,n-2} - q_{\alpha,n-1} > q_{\alpha,n-1}.$$

In the latter case,

$$v_{\alpha,n,t} = q_{\alpha,n} - q_{\alpha,n-1} \geq 2q_{\alpha,n-1} + q_{\alpha,n-2} - q_{\alpha,n-1} > q_{\alpha,n-1}.$$

This completes the proof of this lemma. \square

From Proposition 2 (ii) and Lemma 3, we have the following theorem which implies the convergence of $\frac{u_{\alpha,n,t}}{v_{\alpha,n,t}}$ to x .

THEOREM 2. For $n \geq 0$ and $1 \leq t < c_{\alpha,n+1}$, we have

$$\left| x - \frac{u_{\alpha,n,t}}{v_{\alpha,n,t}} \right| < \frac{1}{q_{\alpha,n} \cdot q_{\alpha,n-1}}.$$

PROOF. If $l \neq k_n(x)$, we see $x_l > 0$. From Proposition 2 (ii), we see

$$\begin{aligned} \left| x - \frac{u_{\alpha,n,t}}{v_{\alpha,n,t}} \right| &= \frac{1}{v_{\alpha,n,t}^2} \frac{1}{\left| x_l - \left(-\frac{q_{\alpha,n}}{v_{\alpha,n,t}} \right) \right|} \\ &= \frac{1}{v_{\alpha,n,t}} \left| \frac{1}{v_{\alpha,n,t} x_l + q_{\alpha,n}} \right| \\ &= \frac{1}{v_{\alpha,n,t}} \left| \frac{1}{(t \cdot q_{\alpha,n} + \varepsilon_{\alpha,n+1} \cdot q_{\alpha,n-1}) x_l + q_{\alpha,n}} \right| \\ &< \frac{1}{v_{\alpha,n,t}} \cdot \frac{1}{q_{\alpha,n}}. \end{aligned}$$

Then from Lemma 3, we have the assertion of the theorem. \square

The above theorem shows that $\left| x - \frac{u_{\alpha,n,t}}{v_{\alpha,n,t}} \right|$ is bounded by $\frac{1}{q_{\alpha,n-1}^2}$. However, next theorem

shows that $v_{\alpha,n,t}^2 \left| x - \frac{u_{\alpha,n,t}}{v_{\alpha,n,t}} \right|$ is not bounded by any absolute constant.

THEOREM 3. We have the following:

$$(i) \quad \limsup_{\substack{1 \leq t < c_{\alpha,n+1} \\ n \rightarrow \infty}} v_{\alpha,n,t}^2 \left| x - \frac{u_{\alpha,n,t}}{v_{\alpha,n,t}} \right| = \infty \quad (a.e. x),$$

(ii) $\liminf_{\substack{1 \leq t < c_{\alpha, n+1} \\ n \rightarrow \infty}} v_{\alpha, n, t}^2 \left| x - \frac{u_{\alpha, n, t}}{v_{\alpha, n, t}} \right| < 2$ if $c_{\alpha, n+1} \geq 2$ occur infinitely often.

PROOF. Suppose $c_{\alpha, n+1} > 4M$ for any sufficiently large M . Let $l = k_n(x) + t$, $t = \left\lfloor \frac{c_{\alpha, n+1}}{2} \right\rfloor$. Since $(G_\alpha)^{k_n(x)}(x) = T_\alpha^n(x)$ and $\left\lfloor \left| \frac{1}{T_\alpha^n(x)} \right| \right\rfloor_\alpha = c_{\alpha, n+1}$, we see that

$$\frac{1}{c_{\alpha, n+1} + \alpha} < |(G_\alpha)^{k_n(x)}(x)| \leq \frac{1}{c_{\alpha, n+1} - 1 + \alpha}.$$

Hence, from Lemma 2,

$$\frac{1}{c_{\alpha, n+1} - \left\lfloor \frac{c_{\alpha, n+1}}{2} \right\rfloor + \alpha} < x_l \leq \frac{1}{c_{\alpha, n+1} - 1 - \left\lfloor \frac{c_{\alpha, n+1}}{2} \right\rfloor + \alpha}.$$

Thus we have

$$x_l < \frac{2}{c_{\alpha, n+1} - 4}. \quad (3.2)$$

By Lemma 3 (ii), we have

$$\left(\frac{c_{\alpha, n+1}}{2} - 2 \right) q_{\alpha, n} < \left(\left\lfloor \frac{c_{\alpha, n+1}}{2} \right\rfloor - 1 \right) q_{\alpha, n} < v_{\alpha, n, t}$$

and so

$$\frac{q_{\alpha, n}}{v_{\alpha, n, t}} < \frac{2}{c_{\alpha, n+1} - 4}. \quad (3.3)$$

From Proposition 2 (ii), (3.2) and (3.3), we have

$$v_{\alpha, n, t}^2 \left| x - \frac{u_{\alpha, n, t}}{v_{\alpha, n, t}} \right| \geq \frac{1}{\left| \frac{2}{c_{\alpha, n+1} - 4} + \frac{2}{c_{\alpha, n+1} - 4} \right|} = \frac{|c_{\alpha, n+1} - 4|}{4} > M - 1.$$

By the ergodicity of T_α , there exist infinitely many such n 's for almost every x . On the other hand, if we choose $t = 1$ with any $n \geq 0$ such that $c_{\alpha, n+1} \geq 2$, we have

$$v_{\alpha, n, 1}^2 \left| x - \frac{u_{\alpha, n, 1}}{v_{\alpha, n, 1}} \right| = \frac{1}{\left| x_l - \left(-\frac{q_{\alpha, n}}{v_{\alpha, n, 1}} \right) \right|} = \frac{1}{\left| x_l + \frac{q_{\alpha, n}}{q_{\alpha, n} \pm q_{\alpha, n-1}} \right|} < \frac{q_{\alpha, n} \pm q_{\alpha, n-1}}{q_{\alpha, n}} < 2,$$

since $x_l > 0$ and $q_{\alpha, n} > q_{\alpha, n-1}$. This completes the proof of the theorem. \square

Recall $x_l = (M_1(x)M_2(x) \cdots M_l(x))^{-1}(x)$. From the remark after Proposition 2, we see that the explicit value of $q_{\alpha, n}^2 \left| x - \frac{p_{\alpha, n}}{q_{\alpha, n}} \right|$ or $v_{\alpha, n, t}^2 \left| x - \frac{u_{\alpha, n, t}}{v_{\alpha, n, t}} \right|$ is determined by the images of

x and ∞ by $(M_1(x)M_2(x) \cdots M_l(x))^{-1}$. This leads us to the notion of the natural extension of G_α , which is defined in next section.

4. Natural extension of G_α

In this section, we discuss the distribution of $v_{\alpha,n,t}^2 \left| x - \frac{u_{\alpha,n,t}}{v_{\alpha,n,t}} \right|$ using a 2-dimensional map \widehat{G}_α , which is called the natural extension of G_α .

We define the map \widehat{G}_α of $\widehat{\mathbf{J}}_\alpha$ as follows:

$$\widehat{\mathbf{J}}_\alpha = \begin{cases} \left[\alpha - 1, \frac{1-2\alpha}{\alpha} \right) \times \left[-\infty, -\frac{\sqrt{5}+3}{2} \right] \cup \left[\frac{1-2\alpha}{\alpha}, 0 \right) \times [-\infty, -2] \cup [0, \alpha) \\ \times [-\infty, 0] \cup \left[\alpha, \frac{1-\alpha}{\alpha} \right) \times \left[-\frac{\sqrt{5}+1}{2}, 0 \right] \cup \left[\frac{1-\alpha}{\alpha}, \frac{\alpha}{1-\alpha} \right) \times [-1, 0] \\ \cup \left[\frac{\alpha}{1-\alpha}, \frac{1}{\alpha} \right) \times \left[-\frac{\sqrt{5}-1}{2}, 0 \right] & \text{if } \frac{1}{2} \leq \alpha \leq \frac{\sqrt{5}-1}{2} \\ [\alpha - 1, 0) \times [-\infty, -2] \cup [0, \alpha) \times [-\infty, 0] \cup \left[\alpha, \frac{1}{\alpha} \right) \times [-1, 0] & \text{if } \frac{\sqrt{5}-1}{2} \leq \alpha \leq 1 \end{cases}$$

and

$$\widehat{G}_\alpha(x, y) = \begin{cases} \left(-\frac{x}{1+x}, -\frac{y}{1+y} \right) & \text{if } x \in \mathbf{J}_{\alpha,1} \\ \left(\frac{x}{1-x}, \frac{y}{1-y} \right) & \text{if } x \in \mathbf{J}_{\alpha,2} \\ \left(\frac{1-x}{x}, \frac{1-y}{y} \right) & \text{if } x \in \mathbf{J}_{\alpha,3}. \end{cases}$$

From Proposition 2 (ii), we see that the deviation of the α -mediant convergent $\frac{u_{\alpha,n,t}}{v_{\alpha,n,t}}$ from x normalized by $v_{\alpha,n,t}^2$ is equal to $\left| \frac{1}{x_l - y_l} \right|$ with $(x_l, y_l) = \widehat{G}_\alpha^l(x, \infty)$, $l = \sum_{i=1}^n k_i(x) + t$ for $x \in \mathbf{J}_\alpha$, $1 \leq t < c_{\alpha,n+1}$. A number of properties associated to the approximation by α -mediant convergents are obtained by dynamical behaviors of this map. One of the important applications which are obtained from the construction of \widehat{G}_α is the derivation of the density function of the absolutely continuous invariant measure for G_α . In the rest of this section, the most of proofs can be completed by routine calculation, and therefore, we will only sketch the ideas involved.

PROPOSITION 3. \widehat{G}_α is a one-to-one onto map of $\widehat{\mathbf{J}}_\alpha$ modulo a set of Lebesgue measure 0.

PROOF. We put

$$\widehat{\mathbf{J}}_{\alpha,i} = \{(x, y) \in \widehat{\mathbf{J}}_\alpha : x \in \mathbf{J}_{\alpha,i}\}, \quad i = 1, 2, 3$$

and

$$\widehat{\mathbf{K}}_{\alpha,i} = \widehat{G}_\alpha \widehat{\mathbf{J}}_{\alpha,i}, \quad i = 1, 2, 3.$$

It is easy to see the following:

case (i) $\frac{1}{2} \leq \alpha \leq \frac{\sqrt{5}-1}{2}$

$$\widehat{\mathbf{K}}_{\alpha,1} = \left[0, \frac{2\alpha-1}{1-\alpha}\right] \times [-2, -1] \cup \left[\frac{2\alpha-1}{1-\alpha}, \frac{1-\alpha}{\alpha}\right] \times \left[-\frac{\sqrt{5}+1}{2}, -1\right],$$

$$\widehat{\mathbf{K}}_{\alpha,2} = \left[0, \frac{\alpha}{1-\alpha}\right] \times [-1, 0] \cup \left[\frac{\alpha}{1-\alpha}, \frac{1}{\alpha}\right] \times \left[-\frac{\sqrt{5}-1}{2}, 0\right],$$

$$\begin{aligned} \widehat{\mathbf{K}}_{\alpha,3} &= \left[\alpha-1, \frac{1-2\alpha}{\alpha}\right] \times \left[-\infty, -\frac{\sqrt{5}+3}{2}\right] \cup \left[\frac{1-2\alpha}{\alpha}, \frac{2\alpha-1}{1-\alpha}\right] \times [-\infty, -2] \\ &\quad \cup \left[\frac{2\alpha-1}{1-\alpha}, \alpha\right] \times \left[-\infty, -\frac{\sqrt{5}+1}{2}\right]. \end{aligned}$$

case (ii) $\frac{\sqrt{5}-1}{2} \leq \alpha \leq 1$

$$\widehat{\mathbf{K}}_{\alpha,1} = \left[0, \frac{1-\alpha}{\alpha}\right] \times [-2, -1],$$

$$\widehat{\mathbf{K}}_{\alpha,2} = \left[0, \frac{1}{\alpha}\right] \times [-1, 0],$$

$$\widehat{\mathbf{K}}_{\alpha,3} = \left[\alpha-1, \frac{1-\alpha}{\alpha}\right] \times [-\infty, -2] \cup \left[\frac{1-\alpha}{\alpha}, \alpha\right] \times [-\infty, -1].$$

Then we see

- \widehat{G}_α maps $\widehat{\mathbf{J}}_{\alpha,i}$ to $\widehat{\mathbf{K}}_{\alpha,i}$ one-to-one and onto fashion,
- $\bigcup_{i=1}^3 \widehat{\mathbf{K}}_{\alpha,i} = \widehat{\mathbf{J}}_\alpha$,
- the interiors of $\widehat{\mathbf{K}}_{\alpha,i}$, $i = 1, 2, 3$, are disjoint from each other.

Hence, we have the assertion of this proposition. \square

PROPOSITION 4. The measure $\widehat{\mu}_\alpha$ given by the density function $\widehat{h}_\alpha(x, y) = \frac{1}{(x-y)^2}$ is an invariant measure for \widehat{G}_α .

PROOF. It is easy to check that

$$\widehat{h}_\alpha(\widehat{G}_\alpha(x, y)) \cdot |\det(D\widehat{G}_\alpha(x, y))| \cdot \widehat{h}_\alpha^{-1}(x, y) = 1 \quad (\text{a.e.}),$$

which implies the assertion of this proposition, where $\det(D\widehat{G}_\alpha(x, y))$ denotes the determinant of the Jacobian matrix $D\widehat{G}_\alpha(x, y)$. \square

REMARK.

$$\iint_{\widehat{\mathbf{J}}_\alpha} \widehat{h}_\alpha(x, y) dx dy = \infty.$$

THEOREM 4. *The dynamical system $(\widehat{\mathbf{J}}_\alpha, \widehat{G}_\alpha, \widehat{\mu}_\alpha)$ is ergodic.*

PROOF. We put

$$\widehat{\mathbf{I}}_\alpha = \begin{cases} \left[\alpha - 1, \frac{1-2\alpha}{\alpha} \right) \times \left[-\infty, -\frac{\sqrt{5}+3}{2} \right] \cup \left[\frac{1-2\alpha}{\alpha}, \frac{2\alpha-1}{1-\alpha} \right) \times \left[-\infty, -2 \right] \\ \cup \left[\frac{2\alpha-1}{1-\alpha}, \alpha \right] \times \left[-\infty, -\frac{\sqrt{5}+1}{2} \right] & \text{if } \frac{1}{2} \leq \alpha \leq \frac{\sqrt{5}-1}{2}, \\ \left[\alpha - 1, \frac{1-\alpha}{\alpha} \right) \times [-\infty, -2] \cup \left[\frac{1-\alpha}{\alpha}, \alpha \right] \times [-\infty, -1] & \text{if } \frac{\sqrt{5}-1}{2} \leq \alpha \leq 1. \end{cases}$$

It is not so hard to see that $\widehat{\mathbf{I}}_\alpha$ is invariant under the map $(x, y) \mapsto \widehat{G}_\alpha^{k_1(x)}(x, y)$ and this map is the induced transformation $(\widehat{G}_\alpha)_{\widehat{\mathbf{I}}_\alpha}$ of \widehat{G}_α . It is also possible to show that $(\widehat{G}_\alpha)_{\widehat{\mathbf{I}}_\alpha}^{k_1(\cdot)}$ is isomorphic to the map \widehat{T}_α of H. Nakada [5], via the isomorphism $(x, w) \mapsto (x, -\frac{1}{w})$. Since \widehat{T}_α is ergodic, so are $(\widehat{G}_\alpha)_{\widehat{\mathbf{I}}_\alpha}$ and $\widehat{G}_\alpha^{k_1(x)}(x, y) \in \widehat{\mathbf{I}}_\alpha$ for any $(x, y) \in \widehat{\mathbf{J}}_\alpha$. Then we have the ergodicity of \widehat{G}_α from the ergodicity of $(\widehat{G}_\alpha)_{\widehat{\mathbf{I}}_\alpha}$. \square

REMARK. For the notion of the induced transformation and its ergodicity, we refer to K. Petersen [8].

We put

$$h_\alpha(x) = \int_{\{y:(x,y) \in \widehat{\mathbf{J}}_\alpha\}} \widehat{h}_\alpha(x, y) dy.$$

Then, we have the following corollaries:

COROLLARY 3. *The measure μ_α , which is defined by $d\mu_\alpha(x) = h_\alpha(x)dx$, is infinite and G_α -invariant.*

COROLLARY 4. *The dynamical system $(\mathbf{J}_\alpha, G_\alpha, \mu_\alpha)$ is ergodic.*

Next proposition shows that a number of “ $\widehat{\mu}_\alpha$ -a.e. (x, y) ” properties induce “ μ_α -a.e. x ”.

PROPOSITION 5. For any $(x, z) \in \widehat{\mathbf{J}}_\alpha$, we put $(x_l, z_l) = \widehat{G}_\alpha^l(x, z)$. Then we see

$$\lim_{l \rightarrow \infty} |z_l - y_l| = 0,$$

where $(x_l, y_l) = \widehat{G}_\alpha^l(x, \infty)$.

PROOF. For $(x, z) \in \widehat{\mathbf{I}}_\alpha$, it is possible to show that

$$\lim_{n \rightarrow \infty} |z_{k_n(x)} - y_{k_n(x)}| = 0.$$

Then the rest of the proof is easy. □

By this proposition and the ratio ergodic theorem, we can get some metric properties of the α -mediant convergents, which were given by Sh. Ito for the regular case, see [3]. However we do not discuss them in detail. For basic facts on ergodic theory, we refer to K. Petersen [8].

For example, we can get the following:

Put

$$\frac{\eta_l}{\xi_l} := (M_1(x)M_2(x) \cdots M_l(x))(\infty).$$

Then, for almost every $x \in \mathbf{I}_\alpha$, we have

$$\frac{\#\left\{n : 1 \leq n \leq N, \xi_l^2 \left| x - \frac{\eta_l}{\xi_l} \right| < t\right\}}{\#\left\{n : 1 \leq n \leq N, \xi_l^2 \left| x - \frac{\eta_l}{\xi_l} \right| < t'\right\}} = \frac{t}{t'} \quad \text{for any } 0 < t, t' \leq c_\alpha,$$

where

$$c_\alpha = \begin{cases} \frac{\alpha}{\frac{\sqrt{5}-1}{2} - \alpha + 1} & \text{if } \frac{1}{2} \leq \alpha \leq \alpha^* \\ 1 - \alpha & \text{if } \alpha^* < \alpha \leq \frac{\sqrt{5}-1}{2} \\ \frac{\alpha}{1 + \alpha} & \text{if } \frac{\sqrt{5}-1}{2} < \alpha < 1 \\ 1 & \text{if } \alpha = 1 \end{cases}$$

and α^* is the unique positive root of $\alpha^2 + \sqrt{5}\alpha - \frac{\sqrt{5}-1}{2} = 0$.

5. Some properties of the α -mediant convergents

The aim of this section is to describe relations between the α -mediant convergents and the regular mediant convergents. At first, we give a coding method which translates the α -continued fraction expansion of x to the regular continued fraction expansion of x (if $0 \leq$

$x \leq \alpha$) or $1 + x$ (if $\alpha - 1 \leq x < 0$).

We suppose that

$$x = \frac{\varepsilon_{\alpha,1}}{c_{\alpha,1}} + \frac{\varepsilon_{\alpha,2}}{c_{\alpha,2}} + \frac{\varepsilon_{\alpha,3}}{c_{\alpha,3}} + \cdots \quad \text{for } x \in \mathbf{I}_\alpha$$

and

$$x = \frac{1}{a_1} + \frac{1}{a_2} + \frac{1}{a_3} + \cdots \quad \text{if } 0 \leq x \leq \alpha$$

or

$$1 + x = \frac{1}{a_1} + \frac{1}{a_2} + \frac{1}{a_3} + \cdots \quad \text{if } \alpha - 1 \leq x < 0.$$

We put $l_n = l_n(x) := \#\{1 \leq k \leq n : \varepsilon_{\alpha,k}(x) = -1\}$. Note that $l_1 = 1$ and $a_1 = 1$ if $x < 0$ (equivalently $\varepsilon_{\alpha,1} = -1$).

LEMMA 4.

- (i) $a_{n+l_n} = c_{\alpha,n}$ and $l_{n+1} = l_n$ if $(\varepsilon_{\alpha,n}, \varepsilon_{\alpha,n+1}) = (1, 1)$
- (ii) $a_{n+l_n} = c_{\alpha,n} - 1$, $a_{n+l_n+1} = 1$ and $l_{n+1} = l_n + 1$ if $(\varepsilon_{\alpha,n}, \varepsilon_{\alpha,n+1}) = (1, -1)$
- (iii) $a_{n+l_n} = c_{\alpha,n} - 1$ and $l_{n+1} = l_n$ if $(\varepsilon_{\alpha,n}, \varepsilon_{\alpha,n+1}) = (-1, 1)$
- (iv) $a_{n+l_n} = c_{\alpha,n} - 2$, $a_{n+l_n+1} = 1$ and $l_{n+1} = l_n + 1$ if $(\varepsilon_{\alpha,n}, \varepsilon_{\alpha,n+1}) = (-1, -1)$

PROOF. The assertions follow from a discussion in §3, [6]. \square

This lemma implies that we can determine a_1, \dots, a_{n+l_n} when $(\varepsilon_{\alpha,1}, c_{\alpha,1}), \dots, (\varepsilon_{\alpha,n}, c_{\alpha,n})$ are given and, moreover, $a_{n+l_n+1} = 1$ if $\varepsilon_{\alpha,n+1} = -1$. Now we see that the following repetition of a rational number occurs in the sequence of the α -mediant convergents and such a rational number is a regular principal convergent.

PROPOSITION 6. *Suppose that $x \in \mathbf{I}_\alpha$ and $\varepsilon_{\alpha,n+1}(x) = -1$, then we have*

$$\frac{u_{\alpha,n,1}(x)}{v_{\alpha,n,1}(x)} = \frac{u_{\alpha,n-1,c_{\alpha,n-1}}(x)}{v_{\alpha,n-1,c_{\alpha,n-1}}(x)} = \frac{p_{n+l_n}(x)}{q_{n+l_n}(x)}.$$

PROOF. We note that if $c_{\alpha,n} = 1$, then $\varepsilon_{\alpha,n+1} = 1$. In other words, $\varepsilon_{\alpha,n+1} = -1$ implies $c_{\alpha,n} \geq 2$. From the definition (1.2), we see

$$\begin{aligned} \frac{u_{\alpha,n,1}}{v_{\alpha,n,1}} &= \frac{1 \cdot p_{\alpha,n} - p_{\alpha,n-1}}{1 \cdot q_{\alpha,n} - q_{\alpha,n-1}} \\ &= \frac{c_{\alpha,n} p_{\alpha,n-1} + \varepsilon_{\alpha,n} p_{\alpha,n-2} - p_{\alpha,n-1}}{c_{\alpha,n} q_{\alpha,n-1} + \varepsilon_{\alpha,n} q_{\alpha,n-2} - q_{\alpha,n-1}} \\ &= \frac{(c_{\alpha,n} - 1) p_{\alpha,n-1} + \varepsilon_{\alpha,n} p_{\alpha,n-2}}{(c_{\alpha,n} - 1) q_{\alpha,n-1} + \varepsilon_{\alpha,n} q_{\alpha,n-2}} \end{aligned}$$

$$= \frac{u_{\alpha,n-1,c_{\alpha,n-1}}}{v_{\alpha,n-1,c_{\alpha,n-1}}}.$$

Hence, we have the first equality of the assertion.

Next, we consider the second equality. We only show it in the case of $0 \leq x \leq \alpha$. For $\alpha - 1 \leq x < 0$, the proof is essentially the same since $\frac{p_n(1+x)}{q_n(1+x)} = \frac{p_n(x)}{q_n(x)} + 1$. By using Lemma 4, we have

$$\frac{p_{\alpha,n}}{q_{\alpha,n}} = \begin{cases} \frac{p_{n+l_n}}{q_{n+l_n}} & \text{if } \varepsilon_{\alpha,n+1} = 1 \\ \frac{p_{n+l_n+1}}{q_{n+l_n+1}} & \text{if } \varepsilon_{\alpha,n+1} = -1. \end{cases} \quad (5.1)$$

In particular, if $\varepsilon_{\alpha,n+1} = -1$, then $a_{n+l_n+1} = 1$ and

$$\begin{cases} p_{n+l_n+1} = p_{n+l_n} + p_{n+l_n-1} \\ q_{n+l_n+1} = q_{n+l_n} + q_{n+l_n-1}. \end{cases} \quad (5.2)$$

On the other hand, by (5.1),

$$\frac{p_{\alpha,n-1}}{q_{\alpha,n-1}} = \frac{p_{n-1+l_n}}{q_{n-1+l_n}}, \quad (5.3)$$

since $l_n = l_{n-1}$ if $\varepsilon_{\alpha,n} = 1$ and $l_n = l_{n-1} + 1$ if $\varepsilon_{\alpha,n} = -1$, respectively. Hence, from (5.1), (5.3) and (5.2), we have

$$\frac{u_{\alpha,n,1}}{v_{\alpha,n,1}} = \frac{p_{\alpha,n} - p_{\alpha,n-1}}{q_{\alpha,n} - q_{\alpha,n-1}} = \frac{p_{n+l_n+1} - p_{n+l_n-1}}{q_{n+l_n+1} - q_{n+l_n-1}} = \frac{p_{n+l_n}}{q_{n+l_n}}.$$

□

Next theorem explains how the α -mediant convergents of level n correspond to the regular mediant and the regular principal convergents.

THEOREM 5. *Suppose that $x \in \mathbb{I}_\alpha$. The set of the α -mediant convergents of level n coincides with the following:*

- (i) *the set of the regular mediant convergents of level $n+l_n(x)+1$ and the $(n+l_n(x))$ th regular principal convergents if $(\varepsilon_{\alpha,n+1}, \varepsilon_{\alpha,n+2}) = (-1, 1)$*
- (ii) *the set of the regular mediant convergents of level $n+l_n(x)+1$, the $(n+l_n(x)-1)$ th regular principal convergents and the $(n+l_n(x)+2)$ th regular principal convergents if $(\varepsilon_{\alpha,n+1}, \varepsilon_{\alpha,n+2}) = (-1, -1)$*
- (iii) *the set of the regular mediant convergents of level $n+l_n(x)$ if $(\varepsilon_{\alpha,n+1}, \varepsilon_{\alpha,n+2}) = (1, 1)$*
- (iv) *the set of the regular mediant convergents of level $n+l_n(x)$ and the $(n+l_n(x)+1)$ th regular principal convergents if $(\varepsilon_{\alpha,n+1}, \varepsilon_{\alpha,n+2}) = (1, -1)$*

PROOF. (i) We assume $x \geq 0$. If $\varepsilon_{\alpha, n+1} = -1$ and $\varepsilon_{\alpha, n+2} = 1$, then from (5.1), (5.3) and (5.2), we have

$$\begin{aligned} u_{\alpha, n, t} &= t \cdot p_{\alpha, n} - p_{\alpha, n-1} \\ &= t \cdot p_{n+l_n+1} - p_{n+l_n-1} \\ &= t(p_{n+l_n} + p_{n+l_n-1}) - p_{n+l_n-1} \\ &= u_{n+l_n+1, t-1} \end{aligned}$$

and

$$v_{\alpha, n, t} = v_{n+l_n+1, t-1}$$

for $2 \leq t < c_{\alpha, n+1} = a_{n+l_n+2} + 1$. In the case $x < 0$, we use $\frac{p_m(1+x)}{q_m(1+x)} = \frac{p_m(x)}{q_m(x)} + 1$ and get the same conclusion. Thus

$$\frac{u_{\alpha, n, t}}{v_{\alpha, n, t}} = \frac{u_{n+l_n+1, t-1}}{v_{n+l_n+1, t-1}} \quad \text{for } 2 \leq t < a_{n+l_n+2} + 1.$$

For $t = 1$, by Proposition 6,

$$\frac{u_{\alpha, n, 1}}{v_{\alpha, n, 1}} = \frac{p_{n+l_n}}{q_{n+l_n}}.$$

Consequently, we have

$$\left\{ \frac{u_{\alpha, n, t}}{v_{\alpha, n, t}} : 1 \leq t < c_{\alpha, n+1} \right\} = \left\{ \frac{p_{n+l_n}}{q_{n+l_n}} \right\} \cup \left\{ \frac{u_{n+l_n+1, t-1}}{v_{n+l_n+1, t-1}} : 2 \leq t < a_{n+l_n+2} + 1 \right\}.$$

This completes the proof of the assertion (i). (ii), (iii) and (iv) follow in the same way. \square

As a corollary of Theorem 5, we claim that the set of the α -principal and the α -mediant convergents coincides with the set of the regular principal and the regular mediant convergents.

COROLLARY 5. For any α , $\frac{1}{2} \leq \alpha < 1$ and $x \in \mathbf{I}_\alpha$,

$$\begin{aligned} \left\{ \frac{p_{\alpha, n}(x)}{q_{\alpha, n}(x)} : n \geq 1 \right\} \cup \left\{ \frac{u_{\alpha, n, t}(x)}{v_{\alpha, n, t}(x)} : 1 \leq t < c_{\alpha, n+1}, n \geq 0 \right\} \\ = \left\{ \frac{p_n(x)}{q_n(x)} : n \geq 1 \right\} \cup \left\{ \frac{u_{n, t}(x)}{v_{n, t}(x)} : 1 \leq t < a_{n+1}, n \geq 0 \right\}. \end{aligned}$$

PROOF. The only regular principal convergents which are not α -principal convergents are $\frac{p_{n+l_n}}{q_{n+l_n}}$ with $\varepsilon_{\alpha, n+1} = -1$. However, these are α -mediant convergents, see Proposition 6. Since $a_{n+l_n+1} = 1$, there is no regular mediant convergent of level $n + l_n$ when $\varepsilon_{\alpha, n+1} = -1$.

Other mediant convergents are α -mediant convergents because of Theorem 5. Indeed, the α -mediant convergents of level n include the regular mediant convergents of level $n + l_n + 1$ if $\varepsilon_{\alpha,n+1} = -1$. In this case, $l_{n+1} = l_n + 1$. Then the next mediant convergent level is $(n + 1) + l_{n+1}$. The same holds for the case $\varepsilon_{\alpha,n+1} = 1$ (then $l_{n+1} = l_n$). This completes the proof of this corollary. \square

Finally we construct a map F_α which we call the α -Farey map of the second type. By this map F_α , we can also get the sequence of the α -mediant convergents without $\frac{u_{\alpha,n-1,c_{\alpha,n-1}}}{v_{\alpha,n-1,c_{\alpha,n-1}}}$ associated to $\varepsilon_{\alpha,n+1} = -1$, that is, without the repetition which was stated in Proposition 6.

We put $\mathcal{J}_\alpha = [\alpha - 1, 1]$ for $\frac{1}{2} \leq \alpha \leq 1$ and define a new map F_α of \mathcal{J}_α by

$$F_\alpha(x) = \begin{cases} V_-^{-1}(x) = -\frac{x}{1+x} & \text{if } x \in [\alpha - 1, 0) =: \mathcal{J}_{\alpha,1} \\ V_+^{-1}(x) = \frac{x}{1-x} & \text{if } x \in \left[0, \frac{1}{2}\right) =: \mathcal{J}_{\alpha,2} \\ (V_+U)^{-1}(x) = \frac{1-2x}{x} & \text{if } x \in \left[\frac{1}{2}, \frac{1}{1+\alpha}\right] =: \mathcal{J}_{\alpha,3} \\ U^{-1}(x) = \frac{1-x}{x} & \text{if } x \in \left(\frac{1}{1+\alpha}, 1\right] =: \mathcal{J}_{\alpha,4}. \end{cases}$$

Similarly as in §2, we put

$$\mathcal{M}_n(x) := \begin{cases} V_- & \text{if } (F_\alpha)^{n-1}(x) \in \mathcal{J}_{\alpha,1} \\ V_+ & \text{if } (F_\alpha)^{n-1}(x) \in \mathcal{J}_{\alpha,2} \\ V_+U & \text{if } (F_\alpha)^{n-1}(x) \in \mathcal{J}_{\alpha,3} \\ U & \text{if } (F_\alpha)^{n-1}(x) \in \mathcal{J}_{\alpha,4} \end{cases}$$

and

$$\begin{cases} k_0^*(x) := 0, \\ k_n^*(x) := \min\{k > k_{n-1}(x) : (F_\alpha)^{k-1}(x) \in \mathcal{J}_{\alpha,3} \cup \mathcal{J}_{\alpha,4}\}, \quad n \geq 1. \end{cases}$$

This means that we abbreviate V_+UV_- to $(V_+U)V_-$ and get a new sequence $\mathcal{M}_1(x), \mathcal{M}_2(x), \dots$ from $M_1(x), M_2(x), \dots$. Then it is easy to see the following.

THEOREM 6. For $x \in \mathbf{I}_\alpha$,

$$\mathcal{M}_1(x)\mathcal{M}_2(x) \cdots \mathcal{M}_l(x)$$

$$= \begin{cases} \begin{pmatrix} p_{\alpha,n-1} & p_{\alpha,n} \\ q_{\alpha,n-1} & q_{\alpha,n} \end{pmatrix} & \text{if } l = k_n^*(x), n \geq 1 \\ \begin{pmatrix} u_{\alpha,n,t} & p_{\alpha,n} \\ v_{\alpha,n,t} & q_{\alpha,n} \end{pmatrix} & \text{if } l = k_n^*(x) + t, n \geq 0 \\ & \text{with } \begin{cases} 1 \leq t < c_{\alpha,n+1} & \text{if } \varepsilon_{\alpha,n+1} = 1 \\ 1 \leq t < c_{\alpha,n+1} - 1 & \text{if } \varepsilon_{\alpha,n+1} = -1. \end{cases} \end{cases}$$

Thus we see that $\frac{u_{\alpha,n-1,c_{\alpha,n-1}}}{v_{\alpha,n-1,c_{\alpha,n-1}}}$ is removed whenever $\varepsilon_{\alpha,n+1} = -1$ by this abbreviation.

The author will discuss the α -Farey map of the second type from the ergodic theoretic point of view in [7].

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