

33. Existence Theorems on Difference-Differential Equations

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As an application of a fixed point theorem due to Tychonov, the author [2] has obtained a theorem concerning the existence of solutions of difference-differential equations defined on a finite interval of t such that

$$x'(t) = f(t, x(t), x(t-1))$$

under the initial conditions $x(t-1) = \varphi(t)$ ($0 \leq t < 1$) and $x(0) = x_0$, where $\varphi(t)$ is a given continuous function. In [2], he imposed on $f(t, x, y)$ only the condition of continuity of $f(t, x, y)$ in (t, x, y) . For the practical problems defined on an infinite interval of t , the function $f(t, x, y)$ has so restricted a form that in the sequel we shall consider the equations, in which the function f has some stronger restrictions than those in [2].

The purpose of this paper is to obtain some results concerning the existence, stability, and boundedness of solutions of difference-differential equations by making use of Tychonov's fixed point theorem.

Recently, as an application of Tychonov's theorem, Stokes [1] has discussed the same problems as above for nonlinear differential equations. His method can also be applied for difference-differential equations.

We first prove the following

THEOREM 1. *Let $F(t, x, y)$ be continuous and nonnegative in (t, x, y) and nondecreasing in x and y for fixed t in the region R defined by $0 \leq t < \infty$ and $0 \leq x \leq f(t)$, $0 \leq y \leq f(t)$ ¹⁾ where*

(i) $f(t)$ is continuous in the interval I : $0 \leq t < \infty$ and $f(0) = \alpha$ (≥ 0);

(ii) $f(t)$ satisfies a difference-differential inequality

$$f'(t) \geq F(t, f(t), f(t-1))$$

under the condition $f(t-1) = |\varphi(t)|$ ($0 \leq t < 1$) for a given continuous function $\varphi(t)$, which has the limit $\lim_{t \rightarrow 1-0} \varphi(t)$.

Then, if we define a transformation T such that

$$Tf(t) = \alpha + \int_0^t F(s, f(s), f(s-1)) ds,$$

1) As usual, $F(t, x, y)$ may be continuously extended to the whole region $|x| < \infty$, $|y| < \infty$. (Cf. [2].)

T has at least a fixed point, that is, there exists a solution of

$$(1) \quad x'(t) = F(t, x(t), x(t-1))$$

on I with the initial conditions $x(t-1) = \varphi(t)$ ($0 \leq t < 1$) and $x(0) = \alpha$.

PROOF. It follows from (ii) that

$$\begin{aligned} Tf(t) - f(t) &= \alpha + \int_0^t F(s, f(s), f(s-1)) ds - \left(\int_0^t f'(s) ds + \alpha \right) \\ &= \int_0^t (F(s, f(s), f(s-1)) - f'(s)) ds \leq 0. \end{aligned}$$

Hence, we have $Tf(t) \leq f(t)$. On account of the properties imposed on F , we inductively obtain the monotonicity

$$T^{n+1}f(t) \leq T^n f(t) \quad (n=0, 1, 2, \dots)$$

on I . Since $F \geq 0$ and $\alpha \geq 0$, it follows that $\{T^n f(t)\}_{n=0}^\infty$ is monotone decreasing and bounded below by 0. Furthermore, since it is proved that every $T^n f(t)$ is equicontinuous, we obtain that $\lim_{n \rightarrow \infty} T^n f(t)$ converges uniformly in the interval I and the limit is a fixed point, which is a solution of the equation

$$x(t) = \alpha + \int_0^t F(s, x(s), x(s-1)) ds.$$

This is equivalent to (1) with the initial conditions $x(t-1) = \varphi(t)$ ($0 \leq t < 1$) and $x(0) = \alpha$.

Now, using the above result, we shall prove the following

THEOREM 2. *In the equation*

$$(2) \quad x'(t) = f(t, x(t), x(t-1))$$

with the initial conditions $x(t-1) = \varphi(t)$ ($0 \leq t < 1$) and $x(0) = x_0$, we suppose that the following conditions are satisfied:

(i) $f(t, x, y)$ is continuous in (t, x, y) for the region $R: 0 \leq t < \infty, |x| < \infty, |y| < \infty$;

(ii) $|f(t, x, y)| \leq F(t, |x|, |y|)$ in R , where the function F is defined as in Theorem 1;

(iii) there is a function $f(t)$ as in Theorem 1.

Then, there exists a solution of (2) with the initial conditions $x(t-1) = \varphi(t)$ ($0 \leq t < 1$) and $x(0) = x_0$, where $|x_0| \leq \alpha$.

PROOF. Let A be a set of all functions $x(t)$ continuous on I such that $|x(t)| \leq f(t)$, where $x(t-1) = \varphi(t)$ ($0 \leq t < 1$).

In order to apply a fixed point theorem, we define a transformation T such that

$$Tx(t) = x_0 + \int_0^t f(s, x(s), x(s-1)) ds$$

for any function in A . Then, it follows from the properties mentioned above that

$$\begin{aligned}
|Tx(t)| &\leq |x_0| + \int_0^t |f(s, x(s), x(s-1))| ds \\
&\leq |x_0| + \int_0^t F(s, |x(s)|, |x(s-1)|) ds \\
&\leq \alpha + \int_0^t F(s, f(s), f(s-1)) ds.
\end{aligned}$$

Now, it follows from (iii) that there exists a function $f(t)$ such that

$$F(t, f(t), f(t-1)) \leq f'(t)$$

on I with the conditions $f(t-1) = |\varphi(t)|$ ($0 \leq t < 1$) and $f(0) = \alpha$, which shows us that the inequality $|Tx(t)| \leq f(t)$ ($t \in I$) remains valid. This implies $TA \subset A$.

Since it is well known that A is closed, convex, and bounded in the topology suitably chosen, it follows that there exists at least a fixed point in A , which yields an integral equation

$$x(t) = x_0 + \int_0^t f(s, x(s), x(s-1)) ds.$$

This is equivalent to (2) with the conditions $x(t-1) = \varphi(t)$ ($0 \leq t < 1$) and $x(0) = x_0$, which proves the theorem.

COROLLARY 1. *In the equation $f'(t) = F(t, f(t), f(t-1))$, where F is defined as in Theorem 1, suppose that there exists a solution defined on I under the initial conditions $f(t-1) = |\varphi(t)|$ ($0 \leq t < 1$) and $f(0) = \alpha$ (≥ 0).*

Then, there exists a solution of (2) on I under the conditions $x(t-1) = \varphi(t)$ ($0 \leq t < 1$) and $x(0) = x_0$, where $|x_0| \leq \alpha$.

COROLLARY 2. *Let the inequality $|f(t, x, y)| \leq \lambda(t)(M(|x|) + M(|y|))$ be satisfied, where λ and M are piecewise continuous, nonnegative, M is nondecreasing, $M(0) = 0$, and the integral*

$$\int_{r_0}^r \frac{d\rho}{M(\rho)}$$

is divergent as $r \rightarrow \infty$ for any $r_0 (\geq 0)$.

Then, there exists a solution of (2) on I under the conditions $x(t-1) = 0$ ($0 \leq t < 1$) and $x(0) = x_0$, where $|x_0| \leq r_0$.

As is observed in the proof of Theorem 2, if a solution of (1) is stable (bounded), there exists a stable (bounded) solution of (2).²⁾ Hence, we obtain the following

THEOREM 3. *Under the assumptions in Theorem 2, if $f(t)$ is stable (bounded), there exists a stable (bounded) solution of (2).*

COROLLARY 3. *Under the assumptions in Theorem 2, if there is a stable (bounded) solution of $f'(t) = F(t, f(t), f(t-1))$ with the conditions $f(t-1) = |\varphi(t)|$ ($0 \leq t < 1$) and $f(0) = \alpha$, then there exists a stable*

2) Although there are many types of stability and boundedness, any type of $x(t)$ corresponds to that of $f(t)$.

(bounded) solution of (2) with the conditions $x(t-1)=\varphi(t)$ ($0 \leq t < 1$) and $x(0)=x_0$, where $|x_0| \leq \alpha$.

COROLLARY 4. Suppose that the inequality $|f(t, x, y)| \leq \lambda(t)(M(|x|) + M(|y|))$ is satisfied on R , where λ and M are piecewise continuous, nonnegative, M is nondecreasing, $M(0)=0$, and the integral

$$\int_0^{\infty} \lambda(t) dt$$

is convergent, but the integral

$$\int_{r_0}^r \frac{d\rho}{M(\rho)}$$

diverges as $r \rightarrow \infty$ for any r_0 (≥ 0).

Then, there exists a bounded solution of (2) on I with the conditions $x(t-1)=0$ ($0 \leq t < 1$) and $x(0)=x_0$, where $|x_0| \leq r_0$.

As for a perturbed equation

$$(3) \quad x'(t) = A(t)x(t) + B(t)x(t-1) + f(t, x(t), x(t-1)),$$

we consider as usual the matrix equation

$$(4) \quad \mathbf{X}'(t) = A(t)\mathbf{X}(t) + B(t)\mathbf{X}(t-1)$$

under the initial conditions $\mathbf{X}(t-1)=\mathbf{0}$ ($0 \leq t < 1$) and $\mathbf{X}(0)=E$, where $\mathbf{0}$ is a zero matrix and E the unit matrix.

Let $R(t)$ be a nonsingular solution of (4) under the same initial conditions as above. Then, it is easily seen that $x(t)=R(t)x_0$ is a solution of a vector equation

$$x'(t) = A(t)x(t) + B(t)x(t-1)$$

with the conditions $x(t-1)=0$ ($0 \leq t < 1$) and $x(0)=x_0$.

Let $K(t, s)$ be a matrix solution of the equations

$$\frac{\partial}{\partial t} K(t, s) = A(t)K(t, s) + B(t)K(t-1, s) \quad (0 \leq s < t-1),$$

$$\frac{\partial}{\partial t} K(t, s) = A(t)K(t, s) \quad (0 < t-1 < s < t, 0 \leq s < t < 1),$$

$$K(t, t) = 1,$$

$$K(t, s) = 0 \quad (-1 \leq t < 0).$$

Then, it is observed that

$$x(t) = R(t)x_0 + \int_0^t K(t, s)w(s) ds$$

is a solution of

$$x'(t) = A(t)x(t) + B(t)x(t-1) + w(t)$$

with the conditions $x(t-1)=0$ ($0 \leq t < 1$) and $x(0)=x_0$.

If we define a transformation T such that

$$Tx(t) = R(t)x_0 + \int_0^t K(t, s)f(s, x(s), x(s-1)) ds,$$

we obtain, by means of the same methods as before, the following

THEOREM 4. *In the equation (3), we suppose that the following conditions are satisfied:*

- (i) $R(t)$ and $K(t, s)$ are bounded, that is, $|R(t)| \leq C$, $|K(t, s)| \leq C$;
- (ii) $|f(t, x, y)| \leq F(t, |x|, |y|)$, where F is defined as in Theorem 2;
- (iii) there exists a solution $f(t)$ such that

$$f'(t) \geq CF(t, f(t), f(t-1))$$

with the conditions $f(t-1) = 0$ ($0 \leq t < 1$) and $f(0) = \alpha$ (≥ 0).

Then, there exists a solution of (3) with the conditions $x(t-1) = 0$ ($0 \leq t < 1$) and $x(0) = x_0$, where $C|x_0| \leq \alpha$.

COROLLARY 5. *In the equation $f'(t) = CF(t, f(t), f(t-1))$, suppose that for any constant α (≥ 0) there exists a solution with $f(t-1) = 0$ ($0 \leq t < 1$) and $f(0) = \alpha$.*

Then, there exists a solution of (3) with $x(t-1) = 0$ ($0 \leq t < 1$) and $x(0) = x_0$, where $C|x_0| \leq \alpha$.

COROLLARY 6. *If $f(t)$ in Theorem 3 is stable (bounded), the solution of (3) is also stable (bounded).*

COROLLARY 7. *If $|f(t, x, y)| \leq \lambda(t)(M(|x|) + M(|y|))$, where λ and M are defined as in Corollary 2, there exists a solution of (3) on I with the conditions $x(t-1) = 0$ ($0 \leq t < 1$) and $x(0) = x_0$, where $|x_0| \leq r_0$.*

COROLLARY 8. *If $|f(t, x, y)| \leq \lambda(t)(M(|x|) + M(|y|))$ in (3), where λ and M are defined as in Corollary 4, there exists a bounded solution of (3) on I with the conditions $x(t-1) = 0$ ($0 \leq t < 1$) and $x(0) = x_0$, where $|x_0| \leq r_0$.*

References

- [1] Stokes, A.: The applications of a fixed point theorem to a variety of non-linear stability problems, Contributions to the Theory of Nonlinear Oscillations. V, Ann. Math. Studies, **45**, 173-184 (1960).
- [2] Sugiyama, S.: On the existence and uniqueness theorems of difference-differential equations, Kōdai Math. Sem. Rep., **12**, 179-190 (1960).