

131. On a Degenerate Oblique Derivative Problem with Interior Boundary Conditions

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1. **Introduction.** In this note we shall give the unique solvability theorem for a degenerate oblique derivative problem with a *complex* parameter, by introducing an extra boundary condition and adding an error term to the original boundary condition. The background is some work of Egorov and Kondrat'ev [4] and Sjöstrand [6]. In the non-degenerate case such theorem was obtained by Agranovič and Višić [2]. As an application of this theorem, we shall state some results on the angular distribution of eigenvalues and the completeness of eigenfunctions of a degenerate oblique derivative problem having an extra boundary condition. In the non-degenerate case such results were obtained by Agmon [1].

Let Ω be a bounded domain in \mathbb{R}^n ($n \geq 3$) with boundary Γ of class C^∞ . $\bar{\Omega} = \Omega \cup \Gamma$ is a C^∞ -manifold with boundary. Let a, b and c be real valued C^∞ -functions on Γ , \mathbf{n} the unit exterior normal to Γ and α a real C^∞ -vector field on Γ . We shall consider the following oblique derivative problem: For given functions f and ϕ defined in Ω and on Γ respectively, find a function u in Ω such that

$$(*) \quad \begin{cases} (\lambda + \Delta)u = f & \text{in } \Omega, \\ \mathcal{B}u \equiv a \frac{\partial u}{\partial \mathbf{n}} + \alpha u + (b + ic)u|_{\Gamma} = \phi & \text{on } \Gamma. \end{cases}$$

Here $\lambda = re^{i\theta}$ with $r \geq 0$ and $0 < \theta < 2\pi$ and $\Delta = \partial^2/\partial x_1^2 + \partial^2/\partial x_2^2 + \dots + \partial^2/\partial x_n^2$.

If $a(x) \neq 0$ on Γ , then the problem (*) is *coercive* and the unique solvability theorem was obtained by Agranovič and Višić [2].

If $a(x)$ vanishes at some points of Γ , then the problem (*) is *non-coercive*. Egorov and Kondrat'ev [4] studied the problem (*) under the following assumptions (A) and (B):

(A) The set $\Gamma_0 = \{x \in \Gamma; a(x) = 0\}$ is an $(n-2)$ -dimensional *regular* submanifold of Γ .

(B) The vector field α is *transversal* to Γ_0 .

In the case that $a(x)$ changes signs on Γ , they proved the non-existence and non-regularity theorem for the problem (*) and, by introducing an extra boundary condition and adding an error term to the original boundary condition $\mathcal{B}u = \phi$, they succeeded in getting a problem for which they could obtain the existence and regularity theorem,

though the unique solvability theorem is not obtained. On the other hand, in the case that $a(x)$ does not change signs on Γ , i.e., in the case that $a(x) \geq 0$ on Γ , the unique solvability theorem for the problem (*) was obtained by Taira [7].

2. Results. In this note, in addition to the assumptions (A) and (B), we introduce the following assumption (C):

(C) On every connected component Γ_0^i of Γ_0 ($i=1, 2, \dots, N$), we have

$$a = \alpha(a) = \dots = \alpha^{k_i-1}(a) = 0 \quad \text{and} \quad \alpha^{k_i}(a) \neq 0$$

for some positive integer k_i .

We divide the set $\{1, 2, \dots, N\} = I^0 \cup I^+ \cup I^-$ where

$$\begin{cases} i \in I^0 & \text{if and only if } k_i \text{ is even;} \\ i \in I^+ & \text{if and only if } k_i \text{ is odd and } \alpha^{k_i}(a) > 0 \text{ on } \Gamma_0^i; \\ i \in I^- & \text{if and only if } k_i \text{ is odd and } \alpha^{k_i}(a) < 0 \text{ on } \Gamma_0^i, \end{cases}$$

and we put

$$\Gamma_0^0 = \bigcup_{i \in I^0} \Gamma_0^i; \quad \Gamma_0^+ = \bigcup_{i \in I^+} \Gamma_0^i; \quad \Gamma_0^- = \bigcup_{i \in I^-} \Gamma_0^i,$$

hence $\Gamma_0 = \Gamma_0^0 \cup \Gamma_0^+ \cup \Gamma_0^-$. Further we put

$$k^0 = \max_{i \in I^0} k_i; \quad k^+ = \max_{i \in I^+} k_i; \quad k^- = \max_{i \in I^-} k_i,$$

and

$$\delta^0 = 1/(k^0 + 1); \quad \delta^+ = 1/(k^+ + 1); \quad \delta^- = 1/(k^- + 1); \quad \delta = \min(\delta^0, \delta^+, \delta^-).$$

For each $s \in \mathbf{R}$, we denote the Sobolev spaces on $\Omega, \Gamma, \Gamma_0^+$ and Γ_0^- of order s by $H^s(\Omega), H^s(\Gamma), H^s(\Gamma_0^+)$ and $H^s(\Gamma_0^-)$ and their norms by $\| \cdot \|_{H^s(\Omega)}, \| \cdot \|_{H^s(\Gamma)}, \| \cdot \|_{H^s(\Gamma_0^+)}$ and $\| \cdot \|_{H^s(\Gamma_0^-)}$ respectively.

Now we can state the main result:

Theorem. Let $\lambda = re^{i\theta}$ with $r \geq 0$ and $0 < \theta < 2\pi$ and let s be any integer ≥ 2 . Assume that the conditions (A), (B) and (C) hold. Then we can find the properly supported continuous linear operators $R^+ : H^\sigma(\Gamma) \rightarrow H^{\sigma-1/2}(\Gamma_0^+)$ and $R^- : H^\sigma(\Gamma_0^-) \rightarrow H^{\sigma-1/2}(\Gamma)$ for all $\sigma \in \mathbf{R}$ such that if $|\lambda| = r \geq r_1(\theta)$ for some constant $r_1(\theta) > 0$ depending only on θ and s then for any $(f, \phi, u^+) \in H^{s-2}(\Omega) \oplus H^{s-3/2}(\Gamma) \oplus H^{s-3/2+\delta-\delta^+/2}(\Gamma_0^+)$ the problem

$$\begin{cases} (\lambda + \Delta)u = f & \text{in } \Omega, \\ \mathcal{B}u + R^- w^- \equiv \left(a \frac{\partial u}{\partial \mathbf{n}} + \alpha u + (b + ic)u \right) \Big|_{\Gamma} + R^- w^- = \phi & \text{on } \Gamma, \\ R^+(u|_{\Gamma}) = u^+ & \text{on } \Gamma_0^+ \end{cases}$$

has a unique solution $(u, w^-) \in H^{s-1+\delta}(\Omega) \oplus H^{s-3/2+\delta-1/2}(\Gamma_0^-)$ and that the a priori estimate

$$\begin{aligned} & \|u\|_{H^{s-1+\delta}(\Omega)}^2 + |\lambda|^{s-1+\delta} \|u\|_{L^2(\Omega)}^2 + \|w^-\|_{H^{s-3/2+\delta-1/2}(\Gamma_0^-)}^2 \\ & + |\lambda|^{s-3/2+\delta-1/2} \|w^-\|_{L^2(\Gamma_0^-)}^2 \leq C_1(\theta) (\|f\|_{H^{s-2}(\Omega)}^2 + |\lambda|^{s-2} \|f\|_{L^2(\Omega)}^2 \\ & + \|\phi\|_{H^{s-3/2}(\Gamma)}^2 + \lambda^{s-3/2} \|\phi\|_{L^2(\Gamma)}^2 + \|u^+\|_{H^{s-3/2+\delta-\delta^+/2}(\Gamma_0^+)}^2 \\ & + |\lambda|^{s-3/2+\delta-\delta^+/2} \|u^+\|_{L^2(\Gamma_0^+)}^2) \end{aligned}$$

holds for some constant $C_1(\theta) > 0$ depending only on θ and s .

Remark 1. In the case that $\Gamma_0 = \Gamma_0^0$, the condition (C) can be weak-

ened (see [7], the condition (C)).

Corollary. *Assume that the conditions (A), (B) and (C) hold with $\Gamma_0^- = \phi$. Let us introduce the linear unbounded operator \mathfrak{A} in the Hilbert space $L^2(\Omega)$ as follows:*

a) *The domain of \mathfrak{A} is $\mathcal{D}(\mathfrak{A}) = \{u \in H^{1+\delta}(\Omega); \Delta u \in L^2(\Omega), \mathcal{B}u \equiv a(\partial u / \partial \mathbf{n}) + \alpha u + (b + ic)u|_r = 0 \text{ and } R^+(u|_r) = 0\}$. ($\delta = \min(\delta^0, \delta^+)$.)*

b) *For $u \in \mathcal{D}(\mathfrak{A})$, $\mathfrak{A}u = -\Delta u$.*

Then the operator \mathfrak{A} is closed and has the following properties:

1) *The spectrum of \mathfrak{A} is discrete and the eigenvalues of \mathfrak{A} have finite multiplicities.*

2) *For any $\varepsilon > 0$ there is a constant $r_2(\varepsilon) > 0$ depending only on ε such that the resolvent set of \mathfrak{A} comprises the set $\{\lambda = re^{i\theta}; r \geq r_2(\varepsilon), \varepsilon \leq \theta \leq 2\pi - \varepsilon\}$ and that there the resolvent $(\lambda I - \mathfrak{A})^{-1}$ satisfies the estimate*

$$\|(\lambda I - \mathfrak{A})^{-1}\| \leq \frac{C_2(\varepsilon)}{|\lambda|^{(1+\delta)/2}}$$

for some constant $C_2(\varepsilon) > 0$ depending only on ε . In particular, there are only a finite number of eigenvalues outside any angle: $|\arg \lambda| < \varepsilon$, $\varepsilon > 0$.

3) *The positive axis is a direction of condensation of eigenvalues.*

4) *The generalized eigenfunctions are complete in $L^2(\Omega)$; they are also complete in $\mathcal{D}(\mathfrak{A})$ in the $\|\cdot\|_{H^{1+\delta}(\Omega)}$ -norm.*

Remark 2. Combining the result 2) with Theorema 1–1 of [3], we obtain that the operator- \mathfrak{A} generates an exponential distribution semi-group $U(t)$ which is holomorphic in any sector: $\{z = t + is; z \neq 0, |\arg z| < \zeta\}$, $0 < \zeta < \pi/2$. Further, arguing as in the proof of Theorem 3.4 in Chap. 1 of [5], it follows that in this sector the estimate $\|U(z)\| \leq Me^{\omega t} t^{(\delta-1)/2}$ holds for some positive constants M and ω depending only on ζ (cf. [3], Theorema 2–1). Since $0 < \delta < 1$, the semi-group $U(t)$ is unbounded near $t=0$. But, by using Theorem 3.3 and Theorem 6.8 in Chap. 1 of [5], we can apply Corollary to a mixed problem for the heat equation and obtain the existence and uniqueness theorem.

3. Idea of Proofs. The proof of Theorem is similar to that of Theorem of [7]. First we reduce the problem (*) to the study of a first order pseudodifferential equation $T(\lambda)\varphi = \psi$ on the boundary Γ by means of the Dirichlet problems. Next, by introducing an extra boundary condition $R^+ : \mathcal{D}'(\Gamma) \rightarrow \mathcal{D}'(\Gamma_0^+)$ and adding an error term $R^- : \mathcal{D}'(\Gamma_0^-) \rightarrow \mathcal{D}'(\Gamma)$ to the equation $T(\lambda)\varphi = \psi$, we get a problem

$$\tau(\lambda) \begin{pmatrix} \varphi \\ w^- \end{pmatrix} \equiv \begin{pmatrix} T(\lambda) & R^- \\ R^+ & 0 \end{pmatrix} \begin{pmatrix} \varphi \\ w^- \end{pmatrix} = \begin{pmatrix} \psi \\ u^+ \end{pmatrix},$$

for which we have the existence and regularity theorem. This is the essential step in the proof and proved exactly as in Theorem 1 of [6] (cf. [6], Remark 4.19). Further, using a method of Agmon and Nirenberg as in [7], we show that for $|\lambda|$ sufficiently large the mapping $\tau(\lambda)$ is

one to one and onto. Finally we combine these results to get Theorem. The proof of Corollary is the same as that of Corollary of [7].

The details will be given elsewhere.

References

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