## 44. A Screw Line in Hilbert Space and its Application to the Probability Theory<sup>\*</sup>.

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§1. A. Kolmogoroff has investigated the spectralization of the screw line in Hilbert space in his paper "Kurven in Hilbertschen Raum, die gegenüber einer einparametrigen Gruppen von Bewegung invariant sind"<sup>1</sup>, where he has promised to give the complete proofs in another paper. In this note I will show his results, although the proofs may run in the same way as his own. And I will apply the results to the theory of two-dimensional brownian motions.

§ 2. Under a congruent transformation in a Hilbert space we understand an isometric mapping from  $\mathfrak{H}$  to  $\mathfrak{H}$  itself. On account of the Mazur-Ulam's theorem<sup>2)</sup> any congruent transformation K is expressible in the form :

$$K_{z} = a + U_{z}$$

where a is a fixed element in  $\mathfrak{H}$  and U is a unitary operator.

Following after Kolmogoroff, we call a curve g(t) in  $\mathfrak{H}$  as a screw line (induced by a  $\|\|$ -continuous one-parameter group  $\{K_t\}$  of congruent transformations), if we have  $g(t) = K_t g(0)$  for any t. We have clearly  $g(t+s) = K_{t+s}g(0) = K_s K_t g(0) = K_s g(t)$ . We define the moment function  $B_t(t, \tau, \sigma)$  of any curve g(t) by

(2.2) 
$$B_{\mathfrak{x}}(t, \tau, \sigma) = \left(\mathfrak{x}(t+\tau) - \mathfrak{x}(t), \mathfrak{x}(t+\sigma) - \mathfrak{x}(t)\right).$$

Theorem 1. A necessary and sufficient condition that g(t) should be a screw line is that  $B_x(t, \tau, \sigma)$  is independent of t and continuous in  $\tau$  and  $\sigma$ .

*Proof.* The *necessity* is clear by the identity :

$$B_{\rm x}(t, \tau, \sigma) = (K_{\rm r} {\rm x}(0) - {\rm x}(0), K_{\sigma} {\rm x}(0) - {\rm x}(0)).$$

Sufficiency. The following proof is essentially due to Mr. K. Yosida. Suppose that  $B_{\varepsilon}(t,\tau,\sigma) = B(\tau,\sigma)$ , where  $B(\tau,\sigma)$  is continuous in  $\tau$  and  $\sigma$ . Let  $\mathfrak{H}_1$  be the linear manifold determined by the set  $\mathfrak{g}(t) - \mathfrak{g}(s)$ ,  $-\infty < s, t < \infty$ , and  $\mathfrak{H}_2$  be  $\mathfrak{H} \odot \overline{\mathfrak{H}_1}$ . Since we have

(2.3) 
$$\left\| \sum_{i} a_{i} \left( \mathfrak{x}(t_{i}+\tau) - \mathfrak{x}(s_{i}+\tau) \right) \right\|^{2} \\ = \sum_{ij} a_{i} \bar{a}_{j} B(t_{i}-s_{i},t_{j}-s_{j}) = \left\| \sum_{i} a_{i} \left( \mathfrak{x}(t_{i}) - \mathfrak{x}(s_{i}) \right) \right\|^{2},$$

the following isometric mapping  $V_{\tau}$  can be well defined in  $\mathfrak{H}_1$ :

<sup>\*</sup> The cost of this research has been defrayed from the Scientific Expenditure of the Department of Education.

<sup>1)</sup> C. R. (Doklady), 1940, vol. 26, 1. Cf. also Neumann and Schoenberg: Fourier integral and metric geometry, Trans. Amer. Math. Soc. vol. 50, 2, 1941.

<sup>2)</sup> Cf. S. Banach: Theorie des opérations linéaires, p. 166.

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(2.4) 
$$\sum_{i} a_i(\mathfrak{g}(t_i) - \mathfrak{g}(s_i)) \rightarrow \sum_{i} a_i(\mathfrak{g}(t_i + \tau) - \mathfrak{g}(s_i + \tau)).$$

Since we have  $V_{\tau}^{-1} = V_{-\tau}$  by the definition, we can extend  $V_{\tau}$  and define a unitary operator in  $\overline{\mathfrak{H}}_{1}$ , say  $V_{\tau}$  again.

 $V_{\tau}V_{\sigma} = V_{\tau+\sigma}$  is clear. The continuity of  $V_{\tau}$  (with respect to  $\tau$ ) follows from that of  $B(\tau, \sigma)$ .

Let  $I_2$  be the identical operator in  $\mathfrak{H}_2$ . Then  $V_r \oplus I_2$  will be a unitary operator in  $\mathfrak{H} = \mathfrak{H}_1 \oplus \mathfrak{H}_2$ , say  $U_r$ . Thus we have a continuous one-parameter group  $\{U_r\}$  of unitary operators.

We put  $a_{\tau} = \mathfrak{x}(\tau) - U_r \mathfrak{x}(0)$  and define  $K_r$  by  $K_r \mathfrak{x} = a_r + U_r \mathfrak{x}$ . By simple calculations we obtain  $K_t K_s = K_{t+s}$ . Therefore  $\mathfrak{x}(t)$  is a screw line induced by the group  $\{K_t\}$ .

§3. A canonical form of a screw line.

Theorem 2 (A. Kolmogoroff). A necessary and sufficient condition that g(t) should be a screw line is that it is expressible in the form:

(3.1) 
$$g(t) - g(0) = \int_{-\infty}^{\infty} \frac{e^{i\lambda t} - 1}{i\lambda} \varphi(d\lambda) ,$$

where  $\Phi$  satisfies

(3.2) orthogonality:  $E \cap E' = 0$  implies  $(\varphi(E), \varphi(E')) = 0$ , and

(3.3) 
$$\int_{|\lambda| \leq 1} \| \varphi(d\lambda) \|^2 + \int_{|\lambda| > 1} \frac{\| \varphi(d\lambda) \|^2}{\lambda^2} < \infty.$$

*Proof.* Sufficiency. We will calculate the moment function  $B_{i}(t, \tau, \sigma)$ .

$$B_{\mathfrak{x}}(t,\tau,\sigma) = \left(\mathfrak{x}(t+\tau) - \mathfrak{x}(t), \mathfrak{x}(t+\sigma) - \mathfrak{x}(t)\right)$$
$$= \int_{-\infty}^{\infty} \frac{e^{i\lambda(t+\tau)} - e^{i\lambda t}}{i\lambda} \cdot \frac{e^{-i\lambda(t+\tau)} - e^{-i\lambda t}}{-i\lambda} \| \varphi(d\lambda) \|^{2}$$
$$= \int_{-\infty}^{\infty} \frac{e^{i\lambda\tau} - 1}{i\lambda} \cdot \frac{e^{-i\lambda\sigma} - 1}{-i\lambda} \| \varphi(d\lambda) \|^{2}$$

By Theorem 1 we can see that g(t) is a screw line.

*Necessity.* Let  $\{K_t\}$  be the group that induces g(t). Put  $K_t g = a_t + U_t g$ . Then  $\{U_t\}$  is a continuous one-parameter group of unitary operators. By the Stone's theorem we have

(3.4) 
$$U_t = \int_{-\infty}^{\infty} e^{i\lambda t} E(d\lambda) \, .$$

Now we have

$$\begin{split} \mathfrak{x}\Big(\frac{k}{n}\Big) - \mathfrak{x}(0) &= \sum_{\nu=1}^{k} \left(\mathfrak{x}\Big(\frac{\nu}{n}\Big) - \mathfrak{x}\Big(\frac{\nu-1}{n}\Big)\Big) \\ &= \sum_{\nu=1}^{k} U_{\frac{\nu-1}{n}}\Big(\mathfrak{x}\Big(\frac{1}{n}\Big) - \mathfrak{x}(0)\Big) \\ &= \int_{-\infty}^{\infty} \Big(\sum_{\nu=1}^{k} e^{i\lambda\frac{\nu-1}{n}}\Big) E(d\lambda)\Big(\mathfrak{x}\Big(\frac{1}{n}\Big) - \mathfrak{x}(0)\Big) \quad (by \ (3.4)\Big) \\ (^{*}) &= \int_{-\infty}^{\infty} \frac{e^{i\lambda\frac{k}{n}} - 1}{e^{i\frac{\lambda}{n}} - 1} E(d\lambda)\Big(\mathfrak{x}\Big(\frac{1}{n}\Big) - \mathfrak{x}(0)\Big) \,. \end{split}$$

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Put 
$$\varphi_n(\alpha,\beta) = \int_{\alpha}^{\beta} \frac{i\lambda}{e^{i\frac{\lambda}{n}} - 1} E(d\lambda) \left( x\left(\frac{1}{n}\right) - y(0) \right).$$

Then we have

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$$\begin{split} \varphi_{1}(a,\beta) &= \int_{a}^{\beta} \frac{i\lambda}{e^{i\lambda} - 1} E(d\lambda) \left( g(1) - g(0) \right) \\ &= \int_{a}^{\beta} \frac{i\lambda}{e^{i\lambda} - 1} E(d\lambda) \left( \int_{-\infty}^{\infty} \frac{e^{i\sigma} - 1}{e^{i\frac{\sigma}{n}} - 1} E(d\sigma) \left( g\left(\frac{1}{n}\right) - g(0) \right) \right) \quad (by \ (^{*})) \\ &= \int_{a}^{\beta} \frac{i\lambda}{e^{i\frac{\lambda}{n}} - 1} E(d\lambda) \left( g\left(\frac{1}{n}\right) - g(0) \right) \qquad (by \ the \ orthogonality) \\ &= \varphi_{n}(a,\beta) \,. \end{split}$$

Thus we see that  $\varphi_n(\alpha, \beta)$  is independent of n, say  $\varphi(\alpha, \beta)$ . Then we obtain

(3.5) 
$$g\left(\frac{k}{n}\right) - g(0) = \int_{-\infty}^{\infty} \frac{e^{i\lambda \frac{k}{n}} - 1}{i\lambda} \varphi(d\lambda) .$$

The orthogonality of  $\mathcal{P}$  follows at once from that of  $E(d\lambda)$ . Next we have

$$\int_{-1}^{1} \| \mathscr{O}(d\lambda) \|^{2} = \int_{-1}^{1} \left| \frac{i\lambda}{e^{i\lambda} - 1} \right|^{2} \left\| E(d\lambda) \left( \mathfrak{x}(1) - \mathfrak{x}(0) \right) \right\|^{2}$$
$$\leq \left( \frac{\pi}{2} \right)^{2} \left\| E(-1, 1) \left( \mathfrak{x}(1) - \mathfrak{x}(0) \right) \right\|^{2} < \infty$$

We have only to prove  $\int_{|\lambda| \ge 1} \frac{\| \varphi(d\lambda) \|^2}{\lambda^2} < \infty$ . By the orthogonality of  $\varphi$  we have,

$$B\left(\frac{k}{n},\frac{k}{n}\right) = \left(\mathfrak{x}\left(\frac{k}{n}\right) - \mathfrak{x}(0), \mathfrak{x}\left(\frac{k}{n}\right) - \mathfrak{x}(0)\right)$$
$$\geq \left\|\int_{1 \le |\lambda| < A} \frac{e^{i\lambda \frac{k}{n}} - 1}{i\lambda} \varphi(d\lambda)\right\|^{2} \quad (1 < A < \infty)$$
$$= \int_{1 \le |\lambda| < A} \left|\frac{e^{i\lambda \frac{k}{n}} - 1}{i\lambda}\right|^{2} \|\varphi(d\lambda)\|^{2}.$$

On account of the continuity of  $B(\tau, \tau) \left(\equiv \left(\mathfrak{g}(\tau) - \mathfrak{g}(0), \mathfrak{g}(\tau) - \mathfrak{g}(0)\right)\right)$ , we have  $B(\tau, \tau) \geq \int_{1 \leq |\lambda| < A} \left|\frac{e^{i\lambda\tau} - 1}{i\lambda}\right|^2 \|\mathscr{O}(d\lambda)\|^2$ , and so  $\int_0^1 B(\tau, \tau) d\tau \geq \frac{1}{4}$  $\int_{1 \leq |\lambda| < A} \frac{\|\mathscr{O}(d\lambda)\|^2}{\lambda^2}$ .  $\left(\because \int_0^1 |e^{i\lambda\tau} - 1|^2 d\tau = 2\left(1 - \frac{\sin\lambda}{\lambda}\right) \geq \frac{1}{4}$  for  $|\lambda| \geq 1$ . Let  $\lambda$  tend to  $\infty$ . Then we have  $\int_{1 \leq |\lambda|} \frac{\|\mathscr{O}(d\lambda)\|^2}{\lambda^2} \leq 4 \int_0^1 B(\tau, \tau) d\tau < \infty$ .

Theorem 3. The measure  $\varphi$  in the preceding theorem is expressible by  $\chi(t)$  as follows:

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(3.6) 
$$\varphi(\alpha,\beta) = \lim_{a\to\infty} \frac{1}{2\pi} \lim_{n\to\infty} \sum_{k=1}^n \left( \int_a^\beta e^{-i\mu\delta_k} d\mu \right) \left( \mathfrak{x}(\gamma_k) - \mathfrak{x}(\gamma_{k-1}) \right) ,$$

 $\gamma_k = c\left(-1 + \frac{2k}{n}\right), \ \delta_k = c\left(-1 + \frac{2k-1}{n}\right), \ for \ any \ continuity \ points \ a, \ \beta$ of  $\varphi$ .

For the proof we shall mention some preliminary lemmas concerning the  $\mathscr{Q}$ -integrability; we say that a complex-valued function  $f(\lambda)$  is  $\mathscr{Q}$ -integrable, if we have

(3.7) 
$$\int_{-\infty}^{\infty} |f(\lambda)|^2 \| \varphi(d\lambda) \|^2 < \infty$$

Lemma 1. Assume that  $|f_n(\lambda)|$  be bounded from above by a  $\varphi$ integrable function  $f(\lambda)$  and that  $\lim_{n\to\infty} f_n(\lambda) = f_0(\lambda)$ . Then we have

(3.8) 
$$\lim_{n\to\infty}\int_{-\infty}^{\infty}f_n(\lambda)\varphi(d\lambda) = \int_{-\infty}^{\infty}f_0(\lambda)\varphi(d\lambda) .$$

By Lemma 1 and by (3.3) we obtain

Lemma 2. If there exist two positive numbers A, M such that we have  $|f(\lambda)| < M$  for  $|\lambda| < A$  and that  $|f(\lambda)| < \frac{A}{|\lambda|}$  otherwise, then  $f(\lambda)$  is  $\varphi$ -integrable.

The proof of Theorem 3. We put

(3.9) 
$$S_n(c) = \sum_{k=1}^n \left( \int_a^\beta e^{-i\mu\delta_k} d\mu \right) \left( \mathfrak{g}(\gamma_k) - \mathfrak{g}(\gamma_{k-1}) \right),$$

and

(3.10) 
$$F_n(\lambda,\mu) = \sum_{k=1}^n e^{-i\mu\delta_k} \cdot \frac{e^{i\lambda\tau_k} - e^{i\lambda\tau_{k-1}}}{i\lambda}$$

Then we have

(3.11) 
$$S_n(c) = \int_{-\infty}^{\infty} \int_a^{\beta} F_n(d\mu) \varphi(d\lambda) \, .$$

By simple calculations we obtain

(3.12) 
$$F_n(\lambda,\mu) = \sum_{k=1}^n e^{i(\lambda-\mu)\delta_k} \frac{e^{i\frac{c}{n}\lambda} - e^{-i\frac{c}{n}\lambda}}{i\lambda} = \frac{2\sin(\lambda-\mu)c\sin\frac{\lambda c}{n}}{\lambda\sin\frac{\lambda-\mu}{n}c},$$

and

(3.13) 
$$i\lambda F_n(\lambda,\mu) = \sum_{k=1}^n e^{i\lambda\gamma_k} (e^{-i\mu\delta_k} - e^{-i\mu\delta_{k+1}}) + e^{i(\lambda\gamma_n - \mu\delta_{n+1})} - e^{i(\lambda\gamma_0 - \mu\delta_1)}, \qquad \delta_{n+1} = c\left(1 + \frac{1}{n}\right).$$

For any  $\lambda \neq 0$  and for any *n* we have, by (3.13),

$$\left|\int_{a}^{\beta} F_{n}(\lambda,\mu)d\mu\right| \leq \frac{1}{\lambda}\int_{a}^{\beta} \left(\sum_{k=1}^{n} |\mu|(\delta_{k+1}-\delta_{k})+2\right)d\mu = \frac{1}{\lambda}\int_{a}^{\beta} 2(|\mu|c+1)d\mu.$$

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If 
$$|\lambda| > \max\{|\alpha|, |\beta|\}$$
 and  $n > \frac{4Ac}{\pi}$ , then we have  $\left|\frac{\lambda-\mu}{n}c\right|$   
 $\leq \frac{2Ac}{n} < \frac{\pi}{2}$  for  $\alpha \leq \mu \leq \beta$ , and so  
 $\left|\int_{a}^{\beta} F_{n}(\lambda, \mu) d\mu\right| \leq \int_{a}^{\beta} 2\frac{|\sin(\lambda-\mu)c|}{\frac{2}{\pi}|\frac{\lambda-\mu}{n}c|} \cdot \frac{\left|\frac{\lambda}{n}c\right|}{|\lambda|} d\mu = \pi \int_{a}^{\beta} \frac{|\sin(\lambda-\mu)c|}{|\lambda-\mu|} d\mu$   
 $\leq \pi c(\beta-\alpha).$ 

Making use of Lemma 1 and 2 we obtain, by (3.11),

$$S_{\infty} = \int_{-\infty}^{\infty} \left( \lim_{n \to \infty} \int_{a}^{\beta} F(\lambda, \mu) d\mu \right) \Phi(d\lambda)$$
  
=  $\int_{-\infty}^{\infty} \int_{a}^{\beta} \lim_{n \to \infty} F_{n}(\lambda, \mu) d\mu \Phi(d\lambda)$  ( $\therefore$   $|F_{n}(0, \mu)| \leq 2c$ ,  $|F_{n}(\lambda, \mu)|$ )  
 $\leq 2(|\mu||c+1)$  for  $\lambda \neq 0$ )  
=  $2 \int_{-\infty}^{\infty} \int_{a}^{\beta} \frac{\sin(\lambda - \mu)c}{\lambda - \mu} d\mu \Phi(d\lambda)$  (by (3.12))  
( $\dagger$ ) =  $2 \int_{a}^{\beta} \int_{a}^{c(\beta - \lambda)} \frac{\sin \theta}{\theta} d\theta \Phi(d\lambda)$ .

In order to obtain  $S \equiv \lim_{e \to \infty} S_{\infty}(e)$  we shall first estimate  $\int_{c(a-\lambda)}^{c(\beta-\lambda)} \frac{\sin \theta}{\theta} d\theta$  in two ways:

$$\left|\int_{c(\alpha-\lambda)}^{c(\beta-\lambda)}\frac{\sin\theta}{\theta}d\theta\right| \leq \int_{-\pi}^{\pi}\frac{\sin\theta}{\theta}d\theta,$$

and

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$$\left|\int_{c(a-\lambda)}^{c(\beta-\lambda)} \frac{\sin \theta}{\theta} d\theta\right| \leq \frac{c(\beta-a)}{c\min(|a-\lambda|, |\beta-\lambda|)} \leq \frac{2(\beta-a)}{|\lambda|}$$

for  $|\lambda| > 2 \max \{ |\alpha|, |\beta| \}$ .

Therefore, making use of Lemma 1 and 2 again, we obtain, from (†),  $S=2\int_{-\infty}^{\infty} \lim_{\alpha \to \infty} \int_{\sigma(\alpha-\lambda)}^{\sigma(\beta-\lambda)} \frac{\sin \theta}{\theta} d\theta \varphi(d\lambda)$ , if  $\alpha$  and  $\beta$  are both continuity points of  $\varphi$ .

§4. A canonical form of a screw function. A complex-valued function  $B(\tau, \sigma)$ ,  $-\infty < \tau$ ,  $\sigma < \infty$  is called a screw function, if there exists a screw line  $\mathfrak{x}$  such that  $B_{\mathfrak{x}}(t, \tau, \sigma) = B(\tau, \sigma)$ .

Theorem 4 (A. Kolmogoroff). A necessary and sufficient condition that  $B(\tau, \sigma)$  should be a screw function is that  $B(\tau, \sigma)$  is expressible in the form :

(4.1) 
$$B(\tau, \sigma) = \int_{-\infty}^{\infty} \frac{e^{i\lambda\tau} - 1}{i\lambda} \frac{e^{-i\lambda\sigma} - 1}{-i\lambda} F(d\lambda),$$

where  $\int_{|\lambda|<1} F(d\lambda) + \int_{|\lambda|\geq 1} \frac{F(d\lambda)}{\lambda^2} < \infty$ 

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Proof. The necessity is evident by Theorem 3.

Sufficiency. We define the functions  $\xi_{\tau}$  depending on a real parameter  $\tau$  as follows:  $\xi_{\tau}(t)=0$   $(t \neq \tau)$ ,  $\xi_{\tau}(\tau)=1$ . Let  $\mathfrak{F}^*$  be the system of all linear forms of  $\xi_{\tau}$ 's with complex coefficients. We introduce an inner product (f, g) into  $\mathfrak{F}^*$  by

$$\left(\sum_{\mu} c_{\mu}(\xi_{\tau_{\mu}}-\xi_{0}), \sum_{\nu} d_{\nu}(\xi_{\sigma_{\mu}}-\xi_{0})\right) = \sum_{\mu,\nu} c_{\mu} \bar{d}_{\nu} B(\tau_{\mu},\sigma_{\nu});$$

(f, g) is evidently linear (conjugate linear) with respect to f(g), and we have further

$$\left(\sum_{\mu}c_{\mu}(\xi_{\tau_{\mu}}-\xi_{0}),\sum_{\mu}c_{\mu}(\xi_{\tau_{\mu}}-\xi_{0})\right)=\int_{-\infty}^{\infty}\left|\sum_{\mu}\frac{e^{i\lambda\tau_{\mu}}-1}{i\lambda}c_{\mu}\right|^{2}F(d\lambda)\geq0.$$

Let  $\mathfrak{N}^*$  denote the set of all f's such that (f, f) = 0. Then  $\mathfrak{H} = \overline{\mathfrak{H}^*/\mathfrak{N}^*}$  may be considered as a Hilbert space. Let  $\mathfrak{g}(t)$  denote the element of  $\mathfrak{H}$  corresponding to  $\xi_t$ . Then we have

$$\begin{split} B_{\mathfrak{x}}(t,\tau,\sigma) &= \left(\mathfrak{x}(t+\tau) - \mathfrak{x}(t), \, \mathfrak{x}(t+\sigma) - \mathfrak{x}(t)\right) \\ &= \left(\xi_{t+\tau} - \xi_t, \, \xi_{t+\sigma} - \xi_t\right) \\ &= B(t+\tau, \, t+\tau) - B(t+\tau, \, t) - B(t, \, t+\sigma) + B(t, \, t) \\ &= \int_{-\infty}^{\infty} \frac{e^{i\lambda\tau} - 1}{i\lambda} \cdot \frac{e^{-i\lambda\sigma} - 1}{-i\lambda} F(d\lambda) = B(\tau, \, \sigma) \,. \end{split}$$

Therefore g(t) is a screw line by Theorem 1, and so  $B(\tau, \sigma)$  is a screw function.

Theorem 5. The measure F in the preceding theorem is expressible in the form :

(4.2) 
$$F(\alpha,\beta) = \lim_{n \to \infty} \left(\frac{1}{2\pi}\right)^2 \lim_{n \to \infty} \sum_{k,h=1}^n \left(\int_a^\beta e^{-i\mu(\delta_k - \delta_k)} d\mu\right) \left(B(\gamma_k,\gamma_h) - B(\gamma_k,\gamma_{h-1}) - B(\gamma_{k-1},\gamma_h) + B(\gamma_{k-1},\gamma_{h-1})\right),$$

 $r_k = c\left(-1 + \frac{2k}{n}\right), \ \delta_k = c\left(-1 + \frac{2k-1}{n}\right)$  for any continuity points  $\alpha, \beta$  of F.

The proof can be achieved in the same way as in Theorem 4 and so will be omitted.

§5. The two-dimensional brownian motion as a screw line on  $L^2(\Omega, P)$ . A system of complex-valued random variables  $x_a(\omega)$ ,  $\omega \in (\Omega, P)$ ,  $\alpha \in A$ , is called normal, if any random variable of the form:  $\sum c_i x_{a_i}(\omega)$ ,  $c_i$ 's being any complex numbers, is subjected to the normal law in the complex plane, i, e. to the law of the form:  $\frac{1}{\pi}e^{-\frac{\xi^2+\gamma^2}{a^2}}d\xi d\gamma$ . In any normal system the orthogonality in  $L^2(\Omega, P)$  implies the (stochastic) independence. A stochastic process  $x(t, \omega)$ ,  $S \leq t \leq T$ , is called normal, if the system  $\{x(t, \omega)\}$  is normal. Under a (two-dimensional) brownian motion in the time-interval  $(S, T), -\infty \leq S, T \leq \infty$ , we understand

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a normal, differential<sup>3)</sup>, and temporally homogeneous (complex-valued) process.

A screw line  $x(t, \omega)$ ,  $-\infty < t < \infty$ , in the Hilbert space  $L^2(\Omega, P)$ is called normal, if it is a normal process. The moment function  $B(\tau, \sigma)$  of any normal screw line is real-valued and so is determined by  $B(\tau, \tau)$  as follows:  $B(\tau, \sigma) = \frac{1}{2} (B(\tau + \sigma, \tau + \sigma) - B(\tau, \tau) - B(\sigma, \sigma)).$ 

Theorem 6. Let  $x(t, \omega)$  be a normal screw line in  $L^2(\mathcal{Q}, P)$ . A necessary and sufficient condition that it should be a brownian motion is that  $B(\tau, \tau) = a^2 |\tau|$ , a being a positive constant, i.e. that  $B(\tau, \sigma) = \frac{a^2}{2}(|\tau+\sigma|-|\tau|-|\sigma|)$ .

The proof is brief and so will be omitted.

Usually we obtain a mathematical scheme of brownian motions by introducing a convenient probability distribution into a functional space<sup>4</sup>. But the above theorem gives another method of constructing the scheme.

Let C be the complex plane, and G be the probability distribution on C such that  $G(E) = \iint_E \frac{1}{\pi} e^{-(\xi^2 + \eta^2)} d\xi d\eta$ . We consider the product measure space  $(C, G)^{\aleph_0}$ , say  $(\mathcal{Q}, P)$ . We denote by  $a_n(\omega)$  the *n*-th coordinate of  $\omega$ ,  $n=0, 1, 2, \ldots$  Now we define  $x(t, \omega)$ ,  $0 \leq t \leq 2\pi$ , by

$$x(t, \omega) = ta_0(\omega) + \sum_{n \neq 0} \frac{a_n(\omega)e^{int}}{in}$$

Since  $a_n$ , n=0, 1, 2, ..., are independent and normally distributed, the system  $\{a_n\}$  is normal and so  $x(t, \omega)$  is a normal process. On account of the identities :

$$x(t,\omega) - \lambda(0,\omega) = \sum_{n} a_{n} \frac{e^{int}}{in}, \qquad ||a_{0}||^{2} + \sum_{n \neq 0} \frac{||a_{n}||^{2}}{n^{2}} = 1 + \frac{\pi^{2}}{3} < \infty ,$$

we see by Theorem 2 that  $x(t, \omega)$  is a screw line, whose moment function  $B(t, \sigma)$  is determined by  $B(\tau, \tau) = \sum_{n} \left| \frac{e^{int} - 1}{in} \right|^{2} ||a_{n}||^{2} = 2\pi t$  for  $0 \leq t \leq 2\pi$ . By Theorem 6  $x(t, \omega)$ ,  $0 \leq t \leq 2\pi$ , is a brownian motion. This is the scheme obtained by N. Wiener<sup>5</sup>.

By this method we cannot construct a brownian motion on an infinite time-interval; in this point the former is more advantageous, while the latter may be more convenient on account of its concreteness.

I wish to express my gratitude for the kindness with which Mr. K. Yosida has encouraged and directed me through the course of this investigation.

<sup>3)</sup> Cf. J. L. Doob: Stochastic processes depending on a continuous parameter, Trans. Amer. Math. Soc. vol. 42.

<sup>4)</sup> Cf. J. L. Doob. loc. cit. (3).

<sup>5)</sup> R.E.A.C. Paley and N. Wiener: Fourier transforms in the complex domain, Chap. 9. Random functions, Amer. Math. Soc. Coll. Publ. 19, 1984.