

An Existence Theorem of Solutions for Degenerate Semilinear Elliptic Equations

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Abstract

In this paper we study existence of solutions to a class of semilinear degenerate elliptic equations in Weighted Sobolev spaces.

1 Introduction

In this paper we prove the existence of a solution in $H_0(\Omega)$ (see definition in section 2) for the semilinear Dirichlet problem

$$(P) \begin{cases} Lu(x) - \mu u(x)g_1(x) + h(u(x))g_2(x) = f(x), & \text{in } \Omega \\ u(x) = 0, & \text{in } \partial\Omega \end{cases}$$

where L is an elliptic operator in divergence form

$$Lu(x) = - \sum_{i,j=1}^n D_j(a_{ij}(x)D_i u(x)), \quad \text{with } D_j = \frac{\partial}{\partial x_j} \quad (1.1)$$

where the coefficients a_{ij} are measurable, real-valued functions whose coefficient matrix $\mathcal{A} = (a_{ij})$ is symmetric and satisfies the degenerate ellipticity condition

$$|\xi|^2 \omega(x) \leq \sum_{i,j=1}^n a_{ij}(x) \xi_i \xi_j \leq |\xi|^2 v(x), \quad (1.2)$$

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for all $\xi \in \mathbb{R}^n$ and almost everywhere $x \in \Omega$, $\Omega \subset \mathbb{R}^n$ is bounded and open, ω and v are weight functions (locally integrable, nonnegative functions on \mathbb{R}^n) and $\mu \in \mathbb{R}$.

The following will be proved in section 3.

THEOREM 1. Suppose that: (H1) The function $h : \mathbb{R} \rightarrow \mathbb{R}$ is continuous and bounded ($|h(t)| \leq M$, for all $t \in \mathbb{R}$); (H2) $(v, \omega) \in A_2$; (H3) $g_1/v \in L^\infty(\Omega)$, $g_2/\omega \in L^2(\Omega, \omega)$ and $f/\omega \in L^2(\Omega, \omega)$; (H4) $\mu > 0$ is not an eigenvalue of the linearized problem

$$(LP) \begin{cases} Lu(x) - \mu u(x)g_1(x) = 0, & \text{in } \Omega \\ u(x) = 0, & \text{in } \partial\Omega. \end{cases}$$

Then the problem (P) has a solution $u \in H_0(\Omega)$.

Simple example. Let $\Omega = \{(x, y) \in \mathbb{R}^2 : x^2 + y^2 < 1\}$. By theorem 1, with $h(t) = te^{-t^2}$, $f(x, y) = e^{-(x^2+y^2)}$, $g_1(x, y) = (x^2 + y^2)^{-1/3} \cos(xy)$, $g_2(x, y) = (x^2 + y^2)^{-1/2} \sin(xy)$, $\omega(x, y) = (x^2 + y^2)^{-1/2}$ and $v(x, y) = (x^2 + y^2)^{-1/3}$ the problem

$$\begin{cases} Lu(x, y) - \mu u(x, y)g_1(x, y) + h(u(x, y))g_2(x, y) = f(x, y), & \text{in } \Omega \\ u(x, y) = 0, & \text{in } \partial\Omega \end{cases}$$

where

$$Lu(x, y) = -\frac{\partial}{\partial x} \left((x^2 + y^2)^{-1/2} \frac{\partial u}{\partial x} \right) - \frac{\partial}{\partial y} \left((x^2 + y^2)^{-1/3} \frac{\partial u}{\partial y} \right),$$

has solution $u \in H_0(\Omega)$ if $\mu > 0$ is not an eigenvalue of the linearized problem (LP).

2 Definitions and basic results

Let ω be a locally integrable nonnegative function in \mathbb{R}^n and assume that $0 < \omega < \infty$ almost everywhere. We say that ω belongs to a Muckenhoupt class A_p , $1 < p < \infty$, or that ω is an A_p -weight, if there is a constant $C_1 = C_{p, \omega}$ such that

$$\left(\frac{1}{|B|} \int_B \omega(x) dx \right) \left(\frac{1}{|B|} \int_B \omega^{1/(1-p)}(x) dx \right)^{p-1} \leq C_1$$

for all balls B in \mathbb{R}^n , where $|\cdot|$ denotes the n -dimensional Lebesgue measure in \mathbb{R}^n . If $1 < q \leq p$ then $A_q \subset A_p$ (see [HKM] or [GR] for more information about A_p -weights). As an example of A_p -weights, if $x \in \mathbb{R}^n$, the function $\omega(x) = |x|^\alpha$ is A_p if and only if $-n < \alpha < n(p-1)$. Let $\Omega \subset \mathbb{R}^n$ be a bounded open set. We shall denote by $L^p(\Omega, \omega)$ ($1 \leq p < \infty$) the Banach space of all measurable functions, f , defined in Ω for which

$$\|f\|_{L^p(\Omega, \omega)} = \left(\int_\Omega |f(x)|^p \omega(x) dx \right)^{1/p} < \infty.$$

For $p \geq 1$ and k a nonnegative integer, the Weighted Sobolev spaces $W^{k,p}(\Omega, \omega)$ is defined by

$$W^{k,p}(\Omega, \omega) = \{u \in L^p(\Omega, \omega) : D^\alpha u \in L^p(\Omega, \omega), \quad 1 \leq |\alpha| \leq k\}$$

with norm

$$\|u\|_{W^{k,p}(\Omega,\omega)} = \left(\int_{\Omega} |u(x)|^p \omega(x) dx + \sum_{1 \leq |\alpha| \leq k} \int_{\Omega} |D^{\alpha}u(x)|^p \omega(x) dx \right)^{1/p}. \quad (2.1)$$

If $\omega \in A_p$ then $W^{k,p}(\Omega, \omega)$ is a closure of $C^{\infty}(\overline{\Omega})$ with respect to the norm (2.1) (see proposition 3.5 in [CS]). The space $W_0^{k,p}(\Omega, \omega)$ is the closure of $C_0^{\infty}(\Omega)$ with respect to the norm

$$\|u\|_{W_0^{k,p}(\Omega,\omega)} = \left(\sum_{1 \leq |\alpha| \leq k} \int_{\Omega} |D^{\alpha}u(x)|^p \omega(x) dx \right)^{1/p}.$$

When $k = 1$ and $p = 2$ the spaces $W^{1,2}(\Omega, \omega)$ and $W_0^{1,2}(\Omega, \omega)$ are Hilbert spaces. The space $H(\Omega)$ is defined to be the completion of $C^{\infty}(\overline{\Omega})$ with respect to the norm

$$\|u\|_{H(\Omega)} = \left(\int_{\Omega} u^2 v dx + \int_{\Omega} \langle \mathcal{A} \nabla u, \nabla u \rangle dx \right)^{1/2}$$

where $\mathcal{A} = (a_{ij})$ is the coefficient matrix of operator L defined in (1.1), $\langle \cdot, \cdot \rangle$ denotes the usual inner product in \mathbb{R}^n and the symbol ∇ indicates the gradient. The space $H_0(\Omega)$ is defined to be the completion of $C_0^{\infty}(\Omega)$ with respect to the norm

$$\|u\|_{H_0(\Omega)} = \left(\int_{\Omega} \langle \mathcal{A} \nabla u, \nabla u \rangle dx \right)^{1/2}.$$

We say that the pair (v, ω) of nonnegative locally integrable functions v and ω satisfies the condition A_p , $1 < p < \infty$, and we write $(v, \omega) \in A_p$, if there is a constant $C_2 = C_{p,v,\omega}$ such that

$$\left(\frac{1}{|B|} \int_B v(x) dx \right) \left(\frac{1}{|B|} \int_B \omega^{1/(1-p)}(x) dx \right)^{p-1} \leq C_2,$$

for all balls B in \mathbb{R}^n .

Remark 2. If $(v, \omega) \in A_p$ and $\omega \leq v$ then $v \in A_p$ and $\omega \in A_p$. In this cases, for $p = 2$ and using condition (1.2) we obtain

$$\int_{\Omega} |\nabla u|^2 \omega dx \leq \int_{\Omega} \langle \mathcal{A} \nabla u, \nabla u \rangle dx \leq \int_{\Omega} |\nabla u|^2 v dx.$$

Therefore $W_0^{1,2}(\Omega, v) \subset H_0(\Omega) \subset W_0^{1,2}(\Omega, \omega)$. ■

We make the following basic assumption on the weights ω and v .

The Weighted Sobolev Inequality (WSI). Let Ω be a bounded open set in \mathbb{R}^n . There is an index $q = 2\sigma$, $\sigma > 1$, such that for every ball B and every $f \in \text{Lip}_0(B)$ (i.e., $f \in \text{Lip}(B)$ and whose support is contained in the interior of B),

$$\left(\frac{1}{v(B)} \int_B |f|^q v dx \right)^{1/q} \leq C R_B \left(\frac{1}{\omega(B)} \int_B |\nabla f|^2 \omega dx \right)^{1/2}$$

with the constant C independent of f and B , R_B is the radius of B , $v(B) = \int_B v(x)dx$ and $\omega(B) = \int_B \omega(x)dx$. Thus, we can write

$$\|f\|_{L^q(B,v)} \leq C_S \|\nabla f\|_{L^2(B,\omega)}$$

where C_S is called the Sobolev constant and

$$C_S = \frac{C[v(B)]^{1/q}R_B}{[\omega(B)]^{1/2}}.$$

For instance, the WSI holds if ω and v are as in Theorem 4.8, chapter X of [T] or if ω and v are as in Theorem 1.5 of [CW]. ■

Lemma 3. If $\omega \in A_2$ then $W_0^{1,2}(\Omega, \omega) \hookrightarrow L_2(\Omega, \omega)$ is compact and

$$\|u\|_{L_2(\Omega,\omega)} \leq C_2 \|u\|_{W_0^{1,2}(\Omega,\omega)}.$$

Proof. The proof of this lemma follows the lines of theorem 4.6 in [FS]. ■

Remark 4. Let $q = 2\sigma$, $\sigma > 1$ be as in (WSI). We have that: (i) If $u \in L^q(\Omega, v)$ then $u \in L^2(\Omega, v)$ and $\|u\|_{L^2(\Omega,v)} \leq [v(\Omega)]^{1/2\sigma'} \|u\|_{L^q(\Omega,v)}$. (ii) If $u \in H_0(\Omega)$ then

$$\int_{\Omega} |\nabla u|^2 \omega dx \leq \int_{\Omega} \langle \mathcal{A} \nabla u, \nabla u \rangle dx < \infty.$$

Using (WSI) we obtain

$$\|u\|_{L^q(\Omega,v)} \leq C_S \left(\int_B |\nabla u|^2 \omega dx \right)^{1/2},$$

that is, $u \in L^q(\Omega, v)$. Hence, using (i), we get $u \in L^2(\Omega, v)$. Therefore $H_0(\Omega) \subset L^2(\Omega, v)$ and

$$\|u\|_{L^2(\Omega,v)} \leq C_S [v(\Omega)]^{1/2\sigma'} \|u\|_{H_0(\Omega)}.$$

Definition 5. We say that an element $u \in H_0(\Omega)$ is a (weak) solution of problem (P) if

$$\int_{\Omega} \left(a_{ij}(x) D_i u(x) D_j \varphi(x) - \mu u(x) g_1(x) \varphi(x) \right) dx + \int_{\Omega} h(u(x)) g_2(x) \varphi(x) dx = \int_{\Omega} f(x) \varphi(x) dx$$

for every $\varphi \in H_0(\Omega)$.

3 Proof of theorem 1

The basic idea is to reduce (P) to an operator equation $Bu + Nu = T$ and apply the following theorem.

Theorem A. Let $B, N : X \rightarrow X^*$ be forms on the real separable reflexive Banach space X . Assume:

- (a) The operator $B : X \rightarrow X^*$ is linear and continuous;
- (b) The operator $N : X \rightarrow X^*$ is demicontinuous and bounded;
- (c) $B + N$ is asymptotically linear;
- (d) For each $T \in X^*$ and each $t \in [0, 1]$ the operator $A_t(u) = Bu + t(Nu - T)$ satisfies condition (S) in X .

If $Bu = 0$ implies $u = 0$, then for each $T \in X^*$ the operator equation $Bu + Nu = T$ has a solution in X .

Proof. See [H] or theorem 29.C in [EZ]. ■

Remark 6. Let X be a real separable reflexive Banach space.

- (i) The operator $N : X \rightarrow X^*$ is said to be demicontinuous if

$$u_n \rightarrow u \text{ implies } Nu_n \rightarrow Nu, \text{ as } n \rightarrow \infty.$$

- (ii) The operator N is strongly continuous if

$$u_n \rightarrow u \text{ implies } Nu_n \rightarrow Nu, \text{ as } n \rightarrow \infty.$$

- (iii) $B + N : X \rightarrow X^*$ is asymptotically linear if B is linear and

$$\frac{\|Nu\|}{\|u\|} \rightarrow 0 \text{ as } \|u\| \rightarrow \infty.$$

- (iv) The operator $B : X \rightarrow X^*$ satisfies condition (S) if

$$u_n \rightarrow u \text{ and } \lim_{n \rightarrow \infty} (Bu_n - Bu | u_n - u) = 0 \text{ implies } u_n \rightarrow u,$$

where $(f|x)$ denotes the value of linear functional f at the point x . ■

Step 1. We define the operators $B_1, B_2 : H_0(\Omega) \times H_0(\Omega) \rightarrow \mathbb{R}$ through

$$B_1(u, \varphi) = \int_{\Omega} a_{ij}(x) D_i u(x) D_j \varphi(x) dx - \mu \int_{\Omega} u(x) \varphi(x) g_1(x) dx,$$

$$B_2(u, \varphi) = \int_{\Omega} h(u(x)) g_2(x) \varphi(x) dx,$$

and $T : H_0(\Omega) \rightarrow \mathbb{R}$ through

$$T(\varphi) = \int_{\Omega} f(x) \varphi(x) dx.$$

We have that $u \in H_0(\Omega)$ solves problem (P) if

$$B_1(u, \varphi) + B_2(u, \varphi) = T(\varphi), \text{ for all } \varphi \in H_0(\Omega).$$

Using Hölder inequality, condition (H3) and remark 4(ii) we get

$$\begin{aligned}
|B_1(u, \varphi)| &\leq \int_{\Omega} | \langle \mathcal{A}\nabla u, \nabla \varphi \rangle | dx + |\mu| \int_{\Omega} |u| |\varphi| |g_1| dx \\
&\leq \int_{\Omega} \langle \mathcal{A}\nabla u, \nabla u \rangle^{1/2} \langle \mathcal{A}\nabla \varphi, \nabla \varphi \rangle^{1/2} dx + |\mu| \int_{\Omega} |u| |\varphi| \left| \frac{g_1}{v} \right| v dx \\
&\leq \left(\int_{\Omega} \langle \mathcal{A}\nabla u, \nabla u \rangle dx \right)^{1/2} \left(\int_{\Omega} \langle \mathcal{A}\nabla \varphi, \nabla \varphi \rangle dx \right)^{1/2} + \\
&\quad + |\mu| \|g_1/v\|_{L^\infty(\Omega)} \int_{\Omega} |u| |\varphi| v dx \\
&\leq \|u\|_{H_0(\Omega)} \|\varphi\|_{H_0(\Omega)} + |\mu| \|g_1/v\|_{L^\infty(\Omega)} \|u\|_{L^2(\Omega, v)} \|\varphi\|_{L^2(\Omega, v)} \\
&\leq \left(1 + C|\mu| \|g_1/v\|_{L^\infty(\Omega)} \right) \|u\|_{H_0(\Omega)} \|\varphi\|_{H_0(\Omega)} \\
&= \mathbf{C} \|u\|_{H_0(\Omega)} \|\varphi\|_{H_0(\Omega)}.
\end{aligned}$$

By conditions (H1) and (H3), Lemma 3 and remark 2, we obtain

$$\begin{aligned}
|B_2(u, \varphi)| &\leq \int_{\Omega} |h(u)| |\varphi| |g_2| dx \\
&\leq M \int_{\Omega} \left| \frac{g_2}{\omega} \right| |\varphi| \omega dx \\
&\leq M \|g_2/\omega\|_{L^2(\Omega, \omega)} \|\varphi\|_{L^2(\Omega, \omega)} \\
&\leq M \|g_2/\omega\|_{L^2(\Omega, \omega)} C_2 \|\varphi\|_{W_0^{1,2}(\Omega, \omega)} \\
&\leq C_2 M \|g_2/\omega\|_{L^2(\Omega, \omega)} \|\varphi\|_{H_0(\Omega)}. \tag{3.1}
\end{aligned}$$

Moreover, we also have

$$\begin{aligned}
|T(\varphi)| &\leq \int_{\Omega} |f| |\varphi| dx \\
&= \int_{\Omega} \left(\frac{|f|}{\omega} \right) |\varphi| \omega dx \\
&\leq \|f/\omega\|_{L^2(\Omega, \omega)} \|\varphi\|_{L^2(\Omega, \omega)} \\
&\leq C_2 \|f/\omega\|_{L^2(\Omega, \omega)} \|\varphi\|_{W_0^{1,2}(\Omega, \omega)} \\
&\leq C_2 \|f/\omega\|_{L^2(\Omega, \omega)} \|\varphi\|_{H_0(\Omega)}.
\end{aligned}$$

Step 2. Since $H_0(\Omega)$ is a real Hilbert space with inner product

$$a_0(u, \varphi) = \int_{\Omega} \langle \mathcal{A}\nabla u, \nabla \varphi \rangle dx$$

using the Identification Principle (theorem 21.18 in [EZ]) we set $H_0(\Omega) = [H_0(\Omega)]^*$ and $a_0(u, \varphi) = (u|\varphi)$ (if $f \in X^*$ and $u \in X$, then $(f|u) = f(u)$).

We define the operators $B, N : H_0(\Omega) \longrightarrow H_0(\Omega)$ through

$$\begin{aligned}
(Bu|\varphi) &= B_1(u, \varphi); \\
(Nu|\varphi) &= B_2(u, \varphi), \forall u, \varphi \in H_0(\Omega).
\end{aligned}$$

Since $T \in [H_0(\Omega)]^*$, the problem (P) is equivalent to the operator equation

$$Bu + Nu = T, \quad u \in H_0(\Omega).$$

Step 3: Using that $H_0(\Omega) \hookrightarrow L_2(\Omega, v)$ is compact (see Lemma 3 and remark 4(ii)), we have that $B_1(\cdot, \cdot)$ is a regular Gårding form. In fact: since $\mu > 0$ and by condition (1.2) we obtain

$$\begin{aligned} B_1(u, u) &= \int_{\Omega} a_{ij} D_i u D_j u dx - \mu \int_{\Omega} u^2 g_1 dx \\ &= \int_{\Omega} \langle \mathcal{A} \nabla u, \nabla u \rangle dx - \mu \int_{\Omega} u^2 \left(\frac{g_1}{v} \right) v dx \\ &\geq \int_{\Omega} \langle \mathcal{A} \nabla u, \nabla u \rangle dx - \mu \|g_1/v\|_{L^\infty(\Omega)} \int_{\Omega} u^2 v dx \\ &= \|u\|_{H_0(\Omega)}^2 - \mu \|g_1/v\|_{L^\infty(\Omega)} \|u\|_{L_2(\Omega, v)}^2. \end{aligned}$$

Hence, there exist a decomposition of the form $B = T_1 + T_2$, where T_1 and T_2 are bilinear and bounded, $T_1(\cdot, \cdot)$ is strongly positive and $T_2(\cdot, \cdot)$ is compact (see lemma 22.38 in [EZ]). Thus, B is Fredholm of index zero (see definition 8.13 and theorem 21.F in [EZ]) and B satisfies condition (S) (see proposition 27.12, [EZ]).

Step 4: By (3.1) we get

$$\begin{aligned} |(Nu, \varphi)| &= |B_2(u, \varphi)| \\ &\leq C_2 M \|g_2/\omega\|_{L^\infty(\Omega)} \|\varphi\|_{H_0(\Omega)}. \end{aligned}$$

Hence, $\|Nu\| \leq C$, for all $u \in H_0(\Omega)$. Therefore,

$$\frac{\|Nu\|}{\|u\|} \longrightarrow 0, \quad \text{as } \|u\|_{H_0(\Omega)} \longrightarrow \infty,$$

that is, $B + N$ is asymptotically linear and the operator N is strongly continuous (see corollary 26.14 in [EZ]).

Step 5. For each $t \in [0, 1]$, the operator $A_t(u) = Bu + t(Nu - T)$ is a strongly continuous perturbation of the operator B . Thus, the operator A_t also satisfies condition (S) (see proposition 27.12, [EZ]).

If μ is not an eigenvalue of the linearized problem (LP), $Bu = 0$ implies $u = 0$. Therefore, by theorem A, the operator equation $Bu + Nu = T$ has a solution $u \in H_0(\Omega)$ and u is solution for the problem (P). ■

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