# Weak expectations in $C^{*}$-dynamical systems 

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(Received April 20, 1987)

## 1. Introduction.

Attempts to extend a factorial state $\varphi$ on a $C^{*}$-algebra $B$ to a factorial state on a larger $C^{*}$-algebra $A$ mainly centred around searches for solutions of a tensor product problem, or equivalently for weak expectations for the GNS representation $\pi_{\varphi}$, that is, linear contractions $P$ of $A$ into $\pi_{\varphi}(B)^{\prime \prime}$ such that $\left.P\right|_{B}=\pi_{\varphi}$ (see [1] and the references cited therein). The eventual solutions of the problem [7,9] were variants of this method.

In the case when there is an action $\alpha$ of an amenable group $G$ on $A$ leaving $B$ invariant, an analogous problem is to consider an $\alpha$-invariant state $\varphi$ of $B$ which is centrally ergodic in the sense that

$$
\boldsymbol{\pi}_{\varphi}(B)^{\prime \prime} \cap \boldsymbol{\pi}_{\varphi}(B)^{\prime} \cap u_{\varphi}(G)^{\prime}=\boldsymbol{C} \cdot 1
$$

where $\left(\pi_{\varphi}, u_{\varphi}\right)$ is the associated covariant representation of ( $B, G, \alpha$ ), and to try to find an extension to a centrally ergodic state of $A$. It was shown in [3] that this can be done by the method of [1] if $B$ is (semi)nuclear, but the von Neumann algebra theory developed in [7,9] is not sufficient to provide a general solution. A corollary of a successful solution is that if $A$ is separable and $G$-central (and $B$ is nuclear), then $B$ is also $G$-central.

The purpose of this paper is to clarify the covariant situation. Firstly, in Section 2, we consider the problem lifted to the $C^{*}$-crossed products. Thus the existence of a weak expectation $\hat{Q}$ for the representation $\pi_{\varphi} \times u_{\varphi}$ of $A \times{ }_{\alpha} G$ (with respect to the subalgebra $B \times{ }_{\alpha} G$ ) is seen to be equivalent to the existence of a (covariant) completely positive contraction $Q$ of $A$ into $\left(\pi_{\varphi}(B) \cup u_{\varphi}(G)\right)^{\prime \prime}$ such that $\left.Q\right|_{B}=\pi_{\varphi}$. Under these circumstances, one may apply the results of [1] to the crossed products. Secondly, in Section 3, it is observed that, if $A$ is $G$-central, then $\hat{Q}$ and $Q$ always exist. Thus the question of $G$-centrality of $B$ is reduced to the problem of arranging that $Q$ maps $A$ into $\pi_{\varphi}(B)^{\prime \prime}$.

For the theory of crossed products, the reader is referred to [8, Chapter 7]; for the basic theory of invariant states, to [4, 4.3].

## 2. Covariant weak expectations.

Let ( $A, G, \alpha$ ) be a $C^{*}$-dynamical system, and $B$ be an $\alpha$-invariant $C^{*}$-subalgebra of $A$. Let $(\mathscr{H}, \pi, u)$ be a covariant representation of $(B, G, \alpha)$ and $\mathscr{M}=(\pi(B) \cup u(G))^{\prime \prime}$. A covariant weak expectation for $(\mathscr{H}, \pi, u)$ is a completely positive linear contraction $Q: A \rightarrow \mathscr{M}$ such that $\left.Q\right|_{B}=\pi$ and $Q\left(\alpha_{t}(a)\right)=u_{t} Q(a) u_{i}^{*}$ $(a \in A, t \in G)$.

We may also consider the $C^{*}$-crossed product $A \times{ }_{\alpha} G$, which is the completion of $L^{1}(G ; A)$ in a suitable norm, and the $C^{*}$-subalgebra $B_{G}$ of $A \times{ }_{\alpha} G$ generated by $L^{1}(G ; B)$. A weak expectation for $(\mathscr{H}, \pi \times u)$ is a linear contraction $\hat{Q}: A \times{ }_{\alpha} G \rightarrow \mathcal{M}$ such that $\hat{Q}(y)=(\pi \times u)(y)\left(y \in L^{1}(G ; B)\right)$. Note that this definition is not quite covered by the definition of weak expectations in [1], since there is no reason, a priori, why it is automatically possible to embed $B \times{ }_{\alpha} G$ in $A \times{ }_{\alpha} G$, or to factor $\pi \times u$ through $B_{G}$. (In general, $B_{G}$ is a quotient of $B \times{ }_{\alpha} G$; the algebras coincide if $G$ is amenable.)

Proposition 1. There is a bijective correspondence between covariant weak expectations $Q: A \rightarrow \mathscr{M}$ for $(\mathscr{H}, \pi, u)$ and weak expectations $\hat{Q}: A \times{ }_{\alpha} G \rightarrow \mathcal{M}$ for ( $\mathcal{H}, \pi \times u$ ).

Proof. Suppose that $Q: A \rightarrow \mathcal{M}$ is a covariant weak expectation for $(\mathscr{R}, \pi, u)$. Define $\hat{Q}: L^{1}(G ; A) \rightarrow \mathcal{M}$ by

$$
\hat{Q}(x)=\int_{G} Q(x(t)) u_{t} d t
$$

Then

$$
\begin{aligned}
\hat{Q}\left(x^{*}\right) & =\int_{G} \Delta(t)^{-1} Q\left(\alpha_{t}\left(x\left(t^{-1}\right)^{*}\right)\right) u_{t} d t \\
& =\int_{G} \Delta(t)^{-1} u_{t} Q\left(x\left(t^{-1}\right)\right)^{*} d t \\
& =\int_{G} u_{t}^{*} Q(x(t))^{*} d t \\
& =\hat{Q}(x)^{*} .
\end{aligned}
$$

For $y$ in $L^{1}(G ; B)$,

$$
\hat{Q}(y)=\int_{G} Q(y(t)) u_{t} d t=\int_{G} \pi(y(t)) u_{t} d t=(\pi \times u)(y) .
$$

Let $\xi$ be a unit vector in $\mathscr{H}$. Consider the map $\Psi: G \rightarrow A^{*}$ defined by

$$
\Psi(t)(a)=\left\langle Q(a) u_{t} \xi, \xi\right\rangle
$$

For $t_{i}$ in $G$ and $a_{i}$ in $A$,

$$
\sum_{i, j=1}^{n} \Psi\left(t_{i}^{-1} t_{j}\right)\left(\alpha_{t_{i}^{-1}}\left(a_{i}^{*} a_{j}\right)\right)=\sum_{i, j=1}^{n}\left\langle u_{t_{i}}^{*} Q\left(a_{i}^{*} a_{j}\right) u_{t_{i}} u_{\hat{t}_{i}}^{*} u_{t_{j}} \xi, \xi\right\rangle \geqq 0
$$

by [10, IV.3.4]. Thus $\Psi$ is positive-definite. Also $\Psi(e)(a)=\langle Q(a) \xi, \xi\rangle$, so $\Psi(e)$ is a state of $A$. By [8, 7.6.8], there is a state $\omega_{\xi}$ of $A \times{ }_{\alpha} G$ such that

$$
\Psi(t)(a)=\omega_{\xi}\left(a \lambda_{t}\right)
$$

where the same symbols are used to denote the canonical extension of $\omega_{\Sigma}$ to the multiplier algebra $M\left(A \times{ }_{\alpha} G\right), A$ is embedded in $M\left(A \times{ }_{\alpha} G\right)$, and $\lambda$ is the unitary representation of $G$ in $M\left(A \times{ }_{\alpha} G\right)$. For $x=x^{*}$ in $L^{1}(G ; A)$,

$$
\omega_{\xi}(x)=\int_{G} \omega_{\xi}\left(x(t) \lambda_{t}\right) d t=\int_{G}\left\langle Q(x(t)) u_{t} \xi, \xi\right\rangle d t=\langle\hat{Q}(x) \xi, \xi\rangle .
$$

Thus

$$
|\langle\hat{Q}(x) \xi, \xi\rangle| \leqq\|x\|_{A \times_{\alpha} G} .
$$

Since $\hat{Q}(x)^{*}=\hat{Q}\left(x^{*}\right)=\hat{Q}(x),\|\hat{Q}(x)\| \leqq\|x\|_{A \times_{\alpha} G}$. Hence $\hat{Q}$ extends by continuity to a bounded self-adjoint linear map, also denoted by $\hat{Q}$, of $A \times{ }_{\alpha} G$ into $\mathscr{M}$ which is a contraction on the self-adjoint part. Then $\hat{Q}$ extends to an ultraweakly continuous linear map, also denoted by $\hat{Q}$, of $\left(A \times{ }_{\alpha} G\right)^{* *}$ into $\mathscr{M}$ which is a contraction between the self-adjoint parts. Furthermore, $\pi \times u=\hat{Q} \circ \Phi$ where $\Phi: B \times{ }_{\alpha} G \rightarrow B_{G}$ is the canonical *-homomorphism, so this identity remains valid for the ultraweakly continuous extensions. Since $\pi \times u$ is non-degenerate, $\hat{Q}(\hat{e})=I_{\mathscr{G}}$, where $\hat{e}$ is the identity of $B_{G}{ }^{* *}$, so $\hat{e}$ is a projection in $\left(A \times_{\alpha} G\right)^{* *}$. Now, if $\hat{1}$ is the identity of $\left(A \times{ }_{\alpha} G\right)^{* *}$,

$$
\left\|I_{\mathscr{H}} \pm \hat{Q}(\hat{1}-\hat{e})\right\|=\|Q(\hat{e} \pm(\hat{1}-\hat{e}))\| \leqq\|\hat{e} \pm(\hat{1}-\hat{e})\|=1
$$

Hence $\hat{Q}(\hat{1}-\hat{e})=0$ so $\hat{Q}(\hat{1})=I_{\mathscr{G}}$. For $x$ in $\left(A \times{ }_{\alpha} G\right)^{* *}$ with $0 \leqq x \leqq \hat{1}$,

$$
\left\|I_{\mathscr{G}}-\hat{Q}(x)\right\| \leqq\|\hat{1}-x\| \leqq 1 .
$$

Since $\hat{Q}(x)$ is self-adjoint, $\hat{Q}(x) \geqq 0$. Thus $\hat{Q}$ is positive. Since $\hat{Q}(\hat{1})=I_{\mathscr{R}}, \hat{Q}$ is a contraction on $\left(A \times{ }_{\alpha} G\right)^{* *}$ and hence on $A \times{ }_{\alpha} G$ [4, 3.2.6].

Let $\left(f_{i}\right)$ be an approximate unit for $L^{1}(G)$. For $a$ in $A$, put $\left(a \otimes f_{i}\right)(t)=$ $f_{i}(t) a$, so $a \otimes f_{i} \in L^{1}(G ; A)$ and $a \otimes f_{i} \rightarrow a$ ultraweakly in $\left(A \times{ }_{\alpha} G\right)^{* *}$. Then

$$
Q(a)=\lim \left(\int_{G} f_{i}(t) u_{t} d t\right) Q(a)=\lim \hat{Q}\left(a \otimes f_{i}\right)=\hat{Q}(a),
$$

the limits being in the ultraweak topology.
Conversely, let $\hat{Q}: A \times{ }_{\alpha} G \rightarrow \mathscr{M}$ be a weak expectation for ( $\mathscr{A}, \pi \times u$ ). Then $\hat{Q}$ extends to an ultraweakly continuous mapping, also denoted by $\hat{Q}$, of $\left(A \times{ }_{\alpha} G\right)^{* *}$ into $\mathscr{M}$. Furthermore, the kernel of $\Phi$ is contained in the kernel of $\pi \times u$, so there is a representation $\rho$ of $B_{G}$ such that $\pi \times u=\rho \circ \Phi$ and $\hat{Q}$ is a weak expectation for $\rho$ in the sense of [1]. By [1,2.1], $\hat{Q}$ is completely positive, and satisfies the module property:

$$
\hat{Q}\left(y_{1} x y_{2}\right)=\rho\left(y_{1}\right) \hat{Q}(x) \rho\left(y_{2}\right) \quad\left(y_{1}, y_{2} \in B_{G}{ }^{* *} ; \quad x \in\left(A \times{ }_{\alpha} G\right)^{* *}\right) .
$$

Identifying $A$ with its image in $M\left(A \times{ }_{\alpha} G\right)$, put $Q=\left.\hat{Q}\right|_{A}$. Then $Q$ is a completely positive contraction of $A$ into $\mathscr{M}$,

$$
\begin{gathered}
Q(b)=\hat{Q}(b)=\rho(b)=\pi(b) \quad(b \in B) \\
Q\left(\alpha_{t}(a)\right)=\hat{Q}\left(\lambda_{t} a \lambda_{t}^{*}\right)=\rho\left(\lambda_{t}\right) \hat{Q}(a) \rho\left(\lambda_{t}^{*}\right)=u_{t} Q(a) u_{t}^{*} \quad(a \in A) .
\end{gathered}
$$

Thus $Q$ is a covariant weak expectation.
For $x$ in $L^{1}(G ; A), x=\int_{G} x(t) \lambda_{t} d t$, the integral being ultraweakly convergent in $\left(A \times{ }_{\alpha} G\right)^{* *}$. Hence

$$
\hat{Q}(x)=\int_{G} \hat{Q}\left(x(t) \lambda_{t}\right) d t=\int_{G} \hat{Q}(x(t)) \rho\left(\lambda_{t}\right) d t=\int_{G} Q(x(t)) u_{t} d t .
$$

This establishes the bijective correspondence.
Remarks. 1. From the proof of Proposition 1, we see that a covariant weak expectation $Q$ satisfies the module property

$$
Q\left(b_{1} a b_{2}\right)=\pi\left(b_{1}\right) Q(a) \pi\left(b_{2}\right) \quad\left(a \in A ; b_{1}, b_{2} \in B\right) .
$$

This may also be deduced from Stinespring's theorem for any completely positive mapping $Q: A \rightarrow \mathcal{M}$ such that $\left.Q\right|_{B}=\pi$.
2. There is a standard argument to show that any linear contraction $Q: A \rightarrow \mathcal{M}$, such that $\left.Q\right|_{B}=\pi$, is positive. Moreover, $Q$ is completely positive if it satisfies any one of the following additional properties:
(i) $Q$ is a complete contraction,
(ii) $Q$ maps $A$ into $\pi(B)^{\prime \prime}[1,2.1]$,
(iii) $Q$ is covariant, and for $t_{i}$ in $G$ and $a_{i}$ in $A$,

$$
\sum_{i, j=1}^{n} u_{t_{i}}^{*} Q\left(a_{i}^{*} a_{j}\right) u_{t_{j}} \geqq 0
$$

(see the proof of Proposition 1).
However, in general, $Q$ may not be completely positive, even if it is covariant. For example, let $A$ be the $C^{*}$-algebra $M_{2}$ of $2 \times 2$ complex matrices, $B$ be the subalgebra of diagonal matrices, $G=\{0,1\}, \alpha_{1}=\operatorname{Ad}\left[\begin{array}{ll}0 & 1 \\ 1 & 0\end{array}\right], \pi$ be the identity representation of $B$ on $C^{2}, u_{1}=\left[\begin{array}{ll}0 & 1 \\ 1 & 0\end{array}\right]$, and $Q$ be the transpose map.
3. A covariant weak expectation $Q$ may fail to map $A$ into $\pi(B)^{\prime \prime}$. For example, let $A=M_{2} \otimes M_{2}, \quad B=M_{2} \otimes I_{2}, \quad G=U(2), \quad \alpha_{t}=\operatorname{Ad}(t \otimes \bar{t}), \quad \mathscr{H}=\boldsymbol{C}^{2} \otimes \boldsymbol{C}^{2}$, $\pi\left(b \otimes I_{2}\right)=b \otimes I_{2}\left(b \in M_{2}\right), u_{t}=t \otimes \bar{t}$. Then $(\mathscr{H}, \pi, u)$ is a covariant representation of $(B, G, \alpha)$ with $u(G)$-invariant cyclic vector $(1 / \sqrt{2})((1,0) \otimes(1,0)+(0,1) \otimes(0,1))$, and $\pi(B)^{\prime \prime}=\pi(B)=M_{2} \otimes I_{2}, \mathcal{M}=M_{2} \otimes M_{2}$. The identity representation $Q=\pi_{0}$ of $A$ is a covariant weak expectation, mapping $A$ onto $\mathscr{M}$. Here $Q=\pi_{0} \times u$.
4. Suppose that $G$ is amenable, and let $m$ be an invariant mean on $L^{\infty}(G)$. Suppose that there is a completely positive contraction $P: A \rightarrow \mathscr{M}$ such that $\left.P\right|_{B}=\pi$. Then there is a covariant weak expectation $Q: A \rightarrow \mathscr{M}$ given by

$$
\langle Q(a) \xi, \eta\rangle=m\left(t \rightarrow\left\langle u_{t}^{*} P\left(\alpha_{t}(a)\right) u_{t} \xi, \eta\right\rangle\right) \quad(\xi, \eta \in \mathscr{A}) .
$$

In particular, if there is an injective von Neumann algebra $\boldsymbol{N}$ such that $\pi(B)^{\prime \prime}$ $\cong N \subseteq \mathscr{M}$, then there is a weak expectation $\hat{Q}: A \times{ }_{\alpha} G \rightarrow \mathcal{M}$. If $B$ is nuclear, one may take $\Omega=\pi(B)^{\prime \prime}$ or $\Omega=\mathscr{M}$ since $B \times{ }_{\alpha} G$ is nuclear [5]. If $B$ is seminuclear [6], there is a weak expectation $P: A \rightarrow \pi(B)^{\prime \prime}$ and hence a covariant weak expectation $Q: A \rightarrow \mathcal{M}$.

Recall that there is an affine homeomorphism between $\alpha$-invariant states $\varphi$ of $B$ and states $\tilde{\varphi}$ of $B \times{ }_{\alpha} G$ with $\tilde{\varphi}\left(\lambda_{t}\right)=1$ for all $t$ in $G$, given by

$$
\tilde{\varphi}(y)=\int_{G} \varphi(y(t)) d t \quad\left(y \in L^{1}(G ; B)\right)
$$

(see, for example, $[2,4.1])$. The GNS representation of $\tilde{\varphi}$ is $\left(\mathscr{H}_{\varphi}, \pi_{\varphi} \times u_{\varphi}\right)$.
Theorem 2. Let $\varphi$ be an $\alpha$-invariant state of $B$ with associated covariant representation $\left(\mathscr{H}_{\varphi}, \pi_{\varphi}, u_{\varphi}\right)$ of $(B, G, \alpha)$, and let $\mathscr{M}_{\varphi}$ be the von Neumann algebra generated by $\pi_{\varphi}(B) \cup u_{\varphi}(G)$. There are bijective correspondences between:
(i) $(\alpha \otimes 1)$-invariant states $\omega$ of $A \otimes_{\max } \mathscr{H}_{\varphi}^{\prime}$ such that

$$
\begin{equation*}
\omega(b \otimes d)=\left\langle\pi_{\varphi}(b) d \xi_{\varphi}, \xi_{\varphi}\right\rangle \quad\left(b \in B, d \in \mathscr{M}_{\varphi}^{\prime}\right), \tag{*}
\end{equation*}
$$

(ii) covariant weak expectations $Q: A \rightarrow \mathscr{M}_{\varphi}$ for $\left(\mathscr{H}_{\varphi}, \pi_{\varphi}, u_{\varphi}\right)$,
(iii) $\alpha$-invariant states $\psi$ of $A$ such that $\left.\psi\right|_{B}=\varphi$ and $E_{\psi} \pi_{\varphi}(A) E_{\psi} \subseteq \mathscr{M}_{\varphi}$, where $E_{\psi}$ is the projection of $\mathscr{I}_{\varphi}$ onto $\mathscr{H}_{\varphi}$,
(iv) weak expectations $\hat{Q}: A \times{ }_{\alpha} G \rightarrow \mathscr{M}_{\varphi}$ for $\left(\mathscr{H}_{\varphi}, \pi_{\varphi} \times u_{\varphi}\right)$,
(v) states $\tilde{\omega}$ of $\left(A \times{ }_{\alpha} G\right) \otimes_{\max } \mathscr{H}_{\varphi}^{\prime}$ such that

$$
\begin{equation*}
\tilde{\omega}(x \otimes d)=\int_{G}\left\langle\pi_{\varphi}(x(t)) d \xi_{\varphi}, \xi_{\varphi}\right\rangle d t \quad\left(x \in L^{1}(G ; B)\right), \tag{**}
\end{equation*}
$$

(vi) states $\tilde{\psi}$ of $A \times{ }_{\alpha} G$ such that $\tilde{\psi} \circ \Phi=\tilde{\varphi}$ and $E_{\tilde{\psi} \pi_{\tilde{\psi}}\left(A \times{ }_{\alpha} G\right) E_{\tilde{\psi}} \subseteq \mathscr{M}_{\varphi} \text {, where }}$ $\Phi$ is the $*$-homomorphism of $B \times{ }_{\alpha} G$ onto $B_{G^{\prime}}$ and $E_{\tilde{\psi}}$ is the projection of $\mathscr{H}_{\tilde{\psi}}$ onto $\left[\pi_{\tilde{\psi}}(B) \xi_{\tilde{\psi}}\right]$.

Proof. The proof of [1,2.3] shows that there is a correspondence between states $\omega$ of $A \otimes_{\max } \mathcal{M}_{\varphi}^{\prime}$ satisfying (*) and completely positive contractions $Q: A \rightarrow \mathscr{M}_{\varphi}$ such that $\left.Q\right|_{B}=\pi_{\varphi}$, given by

$$
\omega(a \otimes d)=\left\langle Q(a) d \xi_{\varphi}, \xi_{\varphi}\right\rangle \quad\left(a \in A, d \in \mathscr{M}_{\varphi}^{\prime}\right) .
$$

(The proof in [1] did not use the assumption that the $C^{*}$-subalgebra $D$ is ultraweakly dense in $\pi_{\varphi}(B)^{\prime}$ except to show that $Q(A) \cong \pi_{\varphi}(B)^{\prime}\left(=D^{\prime \prime}\right)$. Now
taking $D=D^{\prime \prime}=\mathscr{M}_{\varphi}^{\prime}$, the same proof gives the present result.) Furthermore, $Q$ is covariant

$$
\begin{aligned}
& \Longleftrightarrow\left\langle Q\left(\alpha_{t}(a)\right) \pi_{\varphi}\left(b_{1}\right) d \xi_{\varphi}, \pi_{\varphi}\left(b_{2}\right) \xi_{\varphi}\right\rangle=\left\langle u_{\varphi}(t) Q(a) u_{\varphi}(t) * \pi_{\varphi}\left(b_{1}\right) d \xi_{\varphi}, \pi_{\varphi}\left(b_{2}\right) \xi_{\varphi}\right\rangle \\
&\left(a \in A ; b_{1}, b_{2} \in B ; t \in G ; d \in \mathscr{M}_{\varphi}^{\prime}\right) \\
& \Longleftrightarrow\left\langle Q\left(b_{2}^{*} \alpha_{t}(a) b_{1}\right) d \xi_{\varphi}, \xi_{\varphi}\right\rangle=\left\langle Q\left(\alpha_{t-1}\left(b_{2}^{*}\right) a \alpha_{t-1}\left(b_{1}\right)\right) u_{\varphi}(t)^{*} d u_{\varphi}(t) \xi_{\varphi}, \xi_{\varphi}\right\rangle \\
& \quad\left(a \in A ; b_{1}, b_{2} \in B ; t \in G ; d \in \mathscr{M}_{\varphi}^{\prime}\right) \\
& \Longleftrightarrow \omega\left(b_{2}^{*} \alpha_{t}(a) b_{1} \otimes d\right)=\omega\left(\alpha_{t-1}\left(b_{2}^{*}\right) a \alpha_{t-1}\left(b_{1}\right) \otimes d\right) \\
& \quad\left(a \in A ; b_{1}, b_{2} \in B ; t \in G ; d \in \mathscr{M}_{\varphi}^{\prime}\right) \\
& \Longleftrightarrow \omega\left(\alpha_{t}(a) \otimes d\right)=\omega(a \otimes d) \quad\left(a \in A ; t \in G ; d \in \mathscr{M}_{\varphi}^{\prime}\right) \\
& \Longleftrightarrow \omega \text { is }(\alpha \otimes 1) \text {-invariant. }
\end{aligned}
$$

This establishes the correspondence between (i) and (ii).
It was also shown in [1,2.3] that the restriction map of the state space of $A \otimes_{\max } \mathscr{M}_{\varphi}^{\prime}$ into the state space of $A$ gives an affine homeomorphism between states $\omega$ satisfying (*) and states $\psi$ of $A$ with $\left.\psi\right|_{B}=\varphi$ and $E_{\psi} \pi_{\psi}(A) E_{\psi} \cong \mathscr{M}_{\varphi}$. Clearly, if $\omega$ is $(\alpha \otimes 1)$-invariant, $\psi$ is $\alpha$-invariant. On the other hand, if $\psi$ is $\alpha$-invariant, then it follows, for example by the uniqueness of $\omega$, that $\omega$ is ( $\alpha \otimes 1$ )-invariant. This establishes the correspondence between (i) and (iii).

The correspondence between (ii) and (iv) is immediate from Proposition 1, while the correspondences between (iv), (v) and (vi) again follow from [1]. One merely has to observe that the condition ( $* *$ ) is equivalent to the requirement that

$$
\widetilde{\omega}(x \otimes d)=\left\langle\left(\pi_{\varphi} \times u_{\varphi}\right)(x) d \xi_{\varphi}, \xi_{\varphi}\right\rangle,
$$

and that if $\tilde{\omega}$ exists, then $\tilde{\omega}(y \otimes 1)=\tilde{\varphi}(y)\left(y \in L^{1}(G ; B)\right)$, so $\tilde{\varphi}$ factors through $B_{G}, \pi_{\varphi} \times u_{\varphi}$ induces a representation $\rho_{\varphi}$ of $B_{G}$ and the weak expectations $\hat{Q}$ for $\left(\mathscr{H}_{\varphi}, \pi_{\varphi} \times u_{\varphi}\right)$ correspond to the weak expectations for the representation ( $\mathscr{H}_{\varphi}, \rho_{\varphi}$ ) of the $C^{*}$-subalgebra $B_{G}$.

Remarks. 1. The correspondences of Theorem 2 are all affine homeomorphisms in the weak* and point-ultraweak topologies. The correspondence between (iii) and (vi) is the canonical correspondence between $\alpha$-invariant states $\psi$ of $A$ and states $\tilde{\psi}$ of $A \times{ }_{\alpha} G$ with $\tilde{\psi}\left(\lambda_{t}\right)=1(t \in G)$.
2. This is an opportunity to correct an error of detail in the proof of Theorem 1 of [3]. Instead of working with $A \otimes_{\max } \pi_{\varphi}(B)^{\prime}$, one should consider $A \otimes_{\max } D$, where $D$ is an ultraweakly dense $C^{*}$-subalgebra of $\pi_{\varphi}(B)^{\prime}$ and the action $\operatorname{Ad} u_{\varphi}$ of $G$ leaves $D$ invariant and is strongly continuous on $D$. This
ensures that one can apply an invariant mean to a measurable (even, continuous) function to obtain a $G$-invariant extension of $\tilde{\varphi}$ to $A \otimes_{\max } D$.

## 3. $G$-centrality.

Recall that an $\alpha$-invariant state $\psi$ of $A$ is said to be $G$-abelian if, for each $a, b$ in $A$ and $u_{\psi}$-invariant vector $\eta$ in $\mathscr{H}_{\psi}$,

$$
\inf \left|\left\langle\pi_{\psi}\left(a^{\prime} b-b a^{\prime}\right) \eta, \eta\right\rangle\right|=0
$$

where the infimum is taken over all $a^{\prime}$ in the convex hull of $\left\{\alpha_{t}(a): t \in G\right\}$. Moreover, $A$ is said to be $G$-abelian if every $\alpha$-invariant state $\psi$ is $G$-abelian; equivalently, for each $\psi, \mathscr{M}_{\psi}^{\prime}\left(=\pi_{\psi}(A)^{\prime} \cap u_{\psi}(G)^{\prime}\right)$ is abelian; equivalently, the $\alpha$ invariant states of $A$ form a Choquet simplex [4, 4.3.11].

Proposition 3. Suppose that $G$ is amenable, and $A$ is $G$-abelian. For each $\alpha$-invariant state $\varphi$ of $B$, there is a covariant weak expectation for $\left(\mathscr{H}_{\varphi}, \pi_{\varphi}, u_{\varphi}\right)$.

Proof. The first step is to note that $B$ is $G$-abelian. This is well known, but for completeness we give the proof. We have to show that for each $\alpha$ invariant $\varphi$, and $a, b$ in $B$,

$$
\begin{equation*}
\inf \left|\varphi\left(a^{\prime} b-b a^{\prime}\right)\right|=0 \tag{*}
\end{equation*}
$$

Since $G$ is amenable, there is an $\alpha$-invariant state $\psi$ of $A$ extending $\varphi$, and then (*) follows from the $G$-abelianness of $\psi$.

Now $\mathscr{M}_{\varphi}^{\prime}\left(=\pi_{\varphi}(A)^{\prime} \cap u_{\varphi}(G)^{\prime}\right)$ is abelian, so $\mathscr{M}_{\varphi}$ is of type I, hence injective, and the existence of a weak expectation $\hat{Q}: A \times{ }_{\alpha} G \rightarrow \mathscr{M}_{\varphi}$ follows, since $B_{G} \cong B \times{ }_{\alpha} G$.

Recall also that an $\alpha$-invariant state $\psi$ of $A$ is said to be $G$-central if, for each $a, b$ in $A$ and $u_{\psi}$-invariant vector $\eta$ in $\mathscr{H}_{\varphi}$, and $x$ in $\pi_{\varphi}(A)^{\prime}$,

$$
\inf \left|\left\langle\pi_{\varphi}\left(a^{\prime} b-b a^{\prime}\right) x \eta, \eta\right\rangle\right|=0
$$

where the infimum is taken over all $a^{\prime}$ in the convex hull of $\left\{\alpha_{t}(a): t \in G\right\}$. Moreover, $A$ is said to be $G$-central if every $\alpha$-invariant state $\psi$ is $G$-central ; equivalently, $A$ is $G$-central if $\pi_{\psi}(A)^{\prime} \cap u_{\varphi}(G)^{\prime} \subseteq \pi_{\psi}(A)^{\prime \prime}$ for each $\psi$; equivalently, the $\alpha$-invariant states of $A$ form a Choquet simplex whose boundary measures are subcentral [4, 4.3.14].

In [3], attention was given to the question whether $B$ is $G$-central, assuming that $A$ is $G$-central and $G$ is amenable. In separable cases, it is enough to show that every centrally ergodic state $\varphi$ of $B$ is compressible in $A$ (that is, there is a weak expectation $P: A \rightarrow \pi_{\varphi}(B)^{\prime \prime}$ for $\left.\pi_{\varphi}\right)$. Proposition 3 shows that there exist covariant expectations $Q: A \rightarrow \mathscr{M}_{\varphi}$, but in general there is no reason to suppose that $\varphi$ is compressible.

One non-amenable instance when the existence of $Q$ implies the existence of $P$ is described in the following result.

Proposition 4. Let $G$ be the unitary group of the $C^{*}$-algebra $\tilde{B}$ spanned by $B$ and a unit of $A$ (adjointed to $A$ if necessary), and let $\alpha$ be the inner action of $G$ on $A$. Let $\varphi$ be a trace ( $\alpha$-invariant state) of $B$. Any covariant weak expectation $Q: A \rightarrow \mathcal{M}_{\varphi}$ maps $A$ into $\pi_{\varphi}(B)^{\prime \prime}$. Conversely, any weak expectation $P: A \rightarrow \pi_{\varphi}(B)^{\prime \prime}$ is convariant.

Proof. It is possible to prove the first statement directly, but we give an alternative proof using the correspondences developed above. Let $\psi$ be the $\alpha$ invariant state of $A$ corresponding to $Q$ given by Theorem 2. The $\alpha$-invariance means that $\psi$ is $B$-central ( $\psi(a b)=\psi(b a)$ for $a$ in $A, b$ in $B$ ), and by [1,3.1] $\psi$ corresponds to a weak expectation $P: A \rightarrow \pi_{\varphi}(B)^{\prime \prime}$. Since the correspondences are the same and one-one, $P=Q$.

Conversely, the covariance of $P$ follows from the identity :

$$
P\left(\alpha_{v}(a)\right)=P\left(v a v^{*}\right)=\pi_{\varphi}(v) P(a) \pi_{\varphi}\left(v^{*}\right)=u_{\varphi}(v) P(a) u_{\varphi}(v)^{*}
$$

for $a$ in $A$, unitary $v$ in $\tilde{B}$.
Various examples where $\varphi$ is a trace were given in [1, Section 4].

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