

Satake compactification and the great Picard theorem

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§1. Introduction.

Let Δ be the unit disk $\{z \in \mathbb{C}; |z| < 1\}$ in the complex plane and Δ^* the punctured disk $\{z \in \mathbb{C}; 0 < |z| < 1\}$. Let $P_1(\mathbb{C})$ be the 1-dimensional complex projective space, $P_1(\mathbb{C}) = \mathbb{C} \cup \{\infty\}$. Delete three points, say, $0, 1, \infty$, from $P_1(\mathbb{C})$. The great Picard theorem says that every holomorphic mapping $f: \Delta^* \rightarrow P_1(\mathbb{C}) - \{0, 1, \infty\}$ can be extended to a holomorphic mapping $f: \Delta \rightarrow P_1(\mathbb{C})$.

We consider a generalization of the great Picard theorem. Given a complex space M , let d_M be the intrinsic pseudo-distance introduced in [3]. We say that M is hyperbolic if d_M is a distance on M . For example, $P_1(\mathbb{C}) - \{0, 1, \infty\}$ is hyperbolic. Consider the following question.

“Let Y be a complex space and M a complex hyperbolic subspace of Y such that its closure \bar{M} is compact. Does every holomorphic mapping $f: \Delta^* \rightarrow M$ extend to a holomorphic mapping $f: \Delta \rightarrow Y$?”

The answer is, in general, negative as shown by Kiernan [2] (see also [4, Ch. VI, §1]). On the other hand, we have the following result, [4].

THEOREM 1. *Let Y be a complex space and M a complex subspace of Y satisfying the following conditions:*

- (1) M is hyperbolic;
- (2) the closure \bar{M} of M is compact;
- (3) Given a point p on the boundary $\partial M = \bar{M} - M$ and a neighborhood \mathcal{U} of p , there exists a smaller neighborhood \mathcal{V} of p in Y such that

$$d_M(M \cap (Y - \mathcal{U}), M \cap \mathcal{V}) > 0.$$

Let X be a complex manifold and A a locally closed complex submanifold of X . Then every holomorphic mapping $X - A \rightarrow M$ extends to a holomorphic mapping $X \rightarrow Y$.

It has been shown in [4; Ch. VI, §6] that if $Y = P_2(\mathbb{C})$ and $M = P_2(\mathbb{C}) - Q$, where Q is a complete quadrilateral, then the three conditions of Theorem 1 are satisfied. Hence, every holomorphic mapping of $X - A$ into $P_2(\mathbb{C}) - Q$ extends to a holomorphic mapping of X into $P_2(\mathbb{C})$. This may be considered

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as a generalized great Picard theorem.

The purpose of this paper is to give another example of $M \subset Y$ satisfying the three conditions of Theorem 1.

THEOREM 2. *Let D be a symmetric bounded domain in C^N and Γ an arithmetically defined discrete subgroup of the largest connected group G of holomorphic automorphisms of D . Let Y be the Satake compactification of $M = D/\Gamma$. Then M and Y satisfy the three conditions of Theorem 1, provided that Γ acts freely on D .*

We shall make comments in Remark 1 below on the technical assumption that Γ acts freely on D .

From Theorems 1 and 2, we obtain immediately the following

COROLLARY. *Let M and Y be as in Theorem 2. Let X be a complex manifold and A a locally closed complex submanifold of X . Then every holomorphic mapping $X - A \rightarrow M$ extends to a holomorphic mapping $X \rightarrow Y$.*

REMARK 1. In order to include into our consideration the case where the action of Γ is not free, we have to use a modified intrinsic pseudo-distance d'_M on a V -manifold M . Let D be a complex manifold and Γ a properly discontinuous group of holomorphic automorphisms of D . Put $M = D/\Gamma$. Then M is a V -manifold in the sense of Satake. Since M is a complex space, we have an intrinsic pseudo-distance d_M . In the definition of d_M , use only those holomorphic mappings f from the disk Δ in M which can be lifted to holomorphic mappings \tilde{f} from Δ to D . Then we obtain a modified intrinsic pseudo-distance d'_M . This pseudo-distance may be defined also by

$$(*) \quad d'_M(p, q) = d_D(\eta^{-1}(p), \eta^{-1}(q)) \quad p, q \in M,$$

where $\eta: D \rightarrow D/\Gamma = M$ is the projection. For details, see [4; Ch. VII, § 6]. Of course, if Γ acts freely on D , then $d_M = d'_M$. Then Theorem 1 can be modified as follows:

THEOREM 1'. *Let $M = D/\Gamma$ be a complex subspace of a complex space Y . Assume*

- (1') *the pseudo-distance d'_M is a distance;*
- (2) *the closure \bar{M} of M is compact;*
- (3') *Given a point $p \in \partial M$ and a neighborhood \mathcal{U} of p in Y , there exists a smaller neighborhood \mathcal{V} of p in Y such that*

$$d'_M(M \cap (Y - \mathcal{U}), M \cap \mathcal{V}) > 0.$$

Let X be a complex manifold and A a locally closed complex submanifold of X . Then every locally liftable holomorphic mapping $X - A \rightarrow M$ extends to a holomorphic mapping $X \rightarrow Y$.

A holomorphic mapping $f: X - A \rightarrow M$ is said to be *locally liftable* if, for each point x of $X - A$, there exist a neighborhood N_x and a holomorphic

mapping $f_x: N_x \rightarrow D$ such that $\eta \circ f_x = f$ on N_x .

Theorem 2 can be modified as follows:

THEOREM 2'. *Let $D, \Gamma, M = D/\Gamma$ and Y be as in Theorem 2 (but without the condition that Γ acts freely on D). Then M and Y satisfy the three conditions of Theorem 1'.*

Accordingly, Corollary can be also modified. In the proof of Theorem 2 or Theorem 2', we have only to verify the condition (3) or (3'). The remaining conditions are trivially satisfied. In the proof of Theorem 2', the equality (*) above will be used as the definition of the distance d'_M . Actually, the proof will be written in terms of d_D . Although it may be possible to prove Theorem 2' using the distance defined by an invariant hermitian metric of D , the intrinsic distance d_D allows us to prove our main proposition (Proposition 2.5) even for non-homogeneous Siegel domains.

REMARK 2. In connection with Theorem 1, we mention the following result of Kwack [5], (see also [4]).

Let M be a hyperbolic complex space, X a complex manifold and A a locally closed complex subspace of X . Then every holomorphic mapping $X - A \rightarrow M$ extends to a holomorphic mapping $X \rightarrow M$ if one of the following conditions is satisfied:

- (1) M is compact;
- (2) M is complete with respect to d_M and $\text{codim } A \geq 2$.

She proved this result in her attempt to prove Corollary above.

REMARK 3. We have been informed that Corollary has been proved recently by A. Borel by a different method. During the spring quarter of 1970, W. Schmid presented his own proof of Corollary for the case where D is a generalized upper-halfplane of Siegel in his seminar in Berkeley.

REMARK 4. For the compactification of D/Γ , we have used the method of Pyatetzki-Shapiro [6]. One can easily check that this is equivalent to that of [1] (See W.L. Baily, Fourier-Jacobi Series, Proc. Symp. Pure Math., Vol. IX, Amer. Math. Soc., 1966).

§ 2. Siegel domains of the third kind and cylindrical subsets [6] [7] [9].

Let V be an n -dimensional real vector space. A convex cone Ω in V is an open convex subset such that

- i) if $y \in \Omega$ and $t > 0$, then $ty \in \Omega$;
- ii) Ω contains no straight line.

The open subset T_Ω of $V_c = V + iV$ defined by

$$T_\Omega = \{x + iy \in V_c; y \in \Omega\}$$

is called the *tube domain* associated to Ω . It is well known that the tube domain T_Ω is analytically equivalent to a bounded domain. The domain T_Ω

is also called the Siegel domain of the first kind associated to Ω .

An Ω -hermitian form on an m -dimensional complex vector space W is a mapping $H: W \times W \rightarrow V_{\mathbb{C}}$ such that

- i) $H(\alpha u + \beta v, w) = \alpha H(u, w) + \beta H(v, w)$ for $u, v, w \in W, \alpha, \beta \in \mathbb{C}$;
- ii) $H(u, v) = \overline{H(v, u)}$ for $u, v \in W$,

where $\overline{H(v, u)}$ is the natural complex conjugate of $H(u, v)$ in $V_{\mathbb{C}}$;

- iii) $H(u, u) \in \bar{\Omega}$ for $u \in W$,

where $\bar{\Omega}$ denotes the topological closure of Ω ;

- iv) $H(u, u) = 0$ only if $u = 0$.

The open subset $D(H, \Omega)$ of $V_{\mathbb{C}} \times W$ defined by

$$D(H, \Omega) = \{(x + iy, w) \in V_{\mathbb{C}} \times W; y - H(w, w) \in \Omega\}$$

is called the Siegel domain of the second kind associated to H and Ω . It is also analytically equivalent to a bounded domain. The domain $D(H, \Omega)$ always has analytic automorphisms of the following type:

$$(1) \quad \begin{cases} z \mapsto z + a + 2iH(w, b) + iH(b, b) \\ w \mapsto w + b, \end{cases}$$

where $a \in V$ and $b \in W$.

In order to define the Siegel domains of the third kind following [7], we consider the set \mathcal{K} of all complex antilinear mappings $p: W \rightarrow W$ such that

- i) $H(pu, v) = H(pv, u)$ for $u, v \in W$;
- ii) $H(u, u) - H(pu, pu) \in \bar{\Omega}$ for $u \in W$;
- iii) $H(u, u) \neq H(pu, pu)$ if $u \neq 0$.

The totality of complex antilinear mappings $p: W \rightarrow W$ satisfying only (i) forms a complex vector space in which \mathcal{K} is a bounded domain. We need the following lemma.

LEMMA 2.1. *If $p \in \mathcal{K}$, then $I + p$ is a real linear isomorphism of W onto itself, where I denotes the identity transformation of W .*

PROOF. Suppose $(I + p)w = 0$. Then $H(pw, pw) = H(-w, -w) = H(w, w)$. From (iii) above, we obtain $w = 0$. QED.

For $p \in \mathcal{K}$, we define $L_p: W \times W \rightarrow V_{\mathbb{C}}$ by

$$L_p(u, v) = H(u, (I + p)^{-1}v) \quad \text{for } u, v \in W.$$

Now, let \mathcal{D} be a bounded domain in a complex vector space U and φ an analytic mapping from \mathcal{D} into \mathcal{K} . We define a domain $D(H, \Omega, \mathcal{D}, \varphi)$ of $U \times V_{\mathbb{C}} \times W$ by

$$D(H, \Omega, \mathcal{D}, \varphi) = \{(t, z, w) \in U \times V_{\mathbb{C}} \times W; t \in \mathcal{D}, \text{Im}(z) - \text{Re}(L_{\varphi(t)}(w, w)) \in \Omega\}.$$

This domain is called the Siegel domain of the third kind associated to H, Ω, \mathcal{D} , and φ . This domain admits automorphisms of the following type:

$$(2) \quad \begin{cases} t \mapsto t \\ z \mapsto z + a + 2iH(w, b) + iH((I + \varphi(t))b, b) \\ w \mapsto w + b + \varphi(t)b, \end{cases}$$

where $a \in V$, $b \in W$.

LEMMA 2.2. $\operatorname{Re}(L_p(w, w)) \in \bar{\Omega}$ for $p \in \mathcal{K}$ and $w \in W$.

PROOF. Put $c = I + p$. From the definition of L_p , we have

$$L_p(cv, cv) = H(cv, v) \quad \text{for } v \in W.$$

Hence,

$$\begin{aligned} & 2 \operatorname{Re}(L_p(cv, cv)) - H(cv, cv) \\ &= 2 \operatorname{Re}(H(cv, v)) - \{H(v, v) + H(pv, pv) + H(v, pv) + H(pv, v)\} \\ &= 2H(v, v) + 2 \operatorname{Re}(H(pv, v)) - \{H(v, v) + H(pv, pv) + 2 \operatorname{Re}(H(pv, v))\} \\ &= H(v, v) - H(pv, pv) \in \bar{\Omega} \quad (\text{from the definition of } \mathcal{K}). \end{aligned}$$

Since c is surjective by Lemma 2.1, we obtain

$$2 \operatorname{Re}(L_p(w, w)) - H(w, w) \in \bar{\Omega} \quad \text{for } w \in W.$$

Since $H(w, w) \in \bar{\Omega}$ by the definition of H and since $\bar{\Omega}$ is convex, we obtain

$$\operatorname{Re}(L_p(w, w)) = \frac{1}{2} \{H(w, w) + (2 \operatorname{Re}(L_p(w, w)) - H(w, w))\} \in \bar{\Omega}. \quad \text{QED.}$$

For $r \in \Omega$, we define a subdomain D_r of $D = D(H, \Omega, \mathcal{D}, \varphi)$ by

$$D_r = \{(t, z, w) \in D; \operatorname{Im}(z) - \operatorname{Re}(L_{\varphi(t)}(w, w)) - r \in \Omega\}.$$

More generally, for an open set \mathcal{O} in \mathcal{D} , the set

$$D_r(\mathcal{O}) = \{(t, z, w) \in D_r; t \in \mathcal{O}\}$$

is called a *cylindrical set* with base \mathcal{O} . In particular, $D_r = D_r(\mathcal{D})$.

LEMMA 2.3. *The cylindrical set $D_r(\mathcal{O})$ is invariant under the transformations of the type (2).*

PROOF. If $(t, z, w) \rightarrow (t', z', w')$ is a transformation of the type (2), then

$$(2) \quad \begin{cases} t' = t \\ z' = z + a + 2iH(w, b) + iH((I + \varphi(t))b, b) \\ w' = w + b + \varphi(t)b. \end{cases}$$

It suffices therefore to prove that D_r is invariant by a transformation of the type (2). We have

$$\begin{aligned} & \operatorname{Im}(z') - \operatorname{Re}(L_{\varphi(t)}(w', w')) - r \\ &= \operatorname{Im}(z) + 2 \operatorname{Re}(H(w, b)) + \operatorname{Re}(H((I + \varphi(t))b, b)) - r \end{aligned}$$

$$\begin{aligned}
 & -\operatorname{Re} \{H(w+(1+\varphi(t))b, (I+\varphi(t))^{-1}(w+(I+\varphi(t))b))\} - r \\
 = & \operatorname{Im}(z) + 2 \operatorname{Re}(H(w, b)) + \operatorname{Re}(H((I+\varphi(t))b, b)) \\
 & - \operatorname{Re} \{H(w+(I+\varphi(t))b, b+(I+\varphi(t))^{-1}w)\} - r \\
 = & \operatorname{Im}(z) + 2 \operatorname{Re}(H(w, b)) + \operatorname{Re}(H((I+\varphi(t))b, b)) \\
 & - \operatorname{Re} \{H(w, b) + H(w, (I+\varphi(t))^{-1}w) \\
 & + H((I+\varphi(t))b, b) + H((I+\varphi(t))b, (I+\varphi(t))^{-1}w)\} - r \\
 = & \operatorname{Im}(z) - \operatorname{Re}(L_{\varphi(t)}(w, w)) - r \\
 & + \operatorname{Re} \{H(w, b) - H((I+\varphi(t))b, (I+\varphi(t))^{-1}w)\}.
 \end{aligned}$$

It suffices therefore to prove

$$\operatorname{Re} \{H(w, b) - H((I+\varphi(t))b, (I+\varphi(t))^{-1}w)\} = 0.$$

We have, for $e \in W$,

$$\begin{aligned}
 H((I+\varphi(t))b, e) &= H(b, e) + H(\varphi(t)b, e) \\
 &= H(b, e) + H(\varphi(t)e, b) \quad (\text{definition of } \mathcal{K}, \text{ (i)}) \\
 &= H(b, e) + \overline{H(b, \varphi(t)e)} \quad (H: \text{hermitian}).
 \end{aligned}$$

Hence,

$$\begin{aligned}
 \operatorname{Re}(H((I+\varphi(t))b, e)) &= \operatorname{Re}(H(b, e)) + \operatorname{Re}(\overline{H(b, \varphi(t)e)}) \\
 &= \operatorname{Re}(H(b, e)) + \operatorname{Re}(H(b, \varphi(t)e)) \\
 &= \operatorname{Re}(H(b, (I+\varphi(t))e)).
 \end{aligned}$$

If we set $e = (I+\varphi(t))^{-1}w$ in the equality above, then

$$\operatorname{Re}(H((I+\varphi(t))b, (I+\varphi(t))^{-1}w)) = \operatorname{Re}(H(b, w)) = \operatorname{Re}(H(w, b)),$$

thus proving the desired equality.

QED.

The following lemma is evident.

LEMMA 2.4.

$$D_r(\mathcal{O}) \supset D_{tr}(\mathcal{O}) \quad \text{if } t > 1.$$

We state the main proposition of this section.

PROPOSITION 2.5. *Let $D = D(H, \Omega, \mathfrak{D}, \varphi)$ be a Siegel domain of the third kind. Then*

$$d_D(a, b) \geq \log t \quad \text{for } a \in D - D_r, b \in D_{tr}, t > 1, r \in \Omega,$$

where d_D denotes the intrinsic distance of D explained in § 1.

We prove the proposition in several steps.

LEMMA 2.6. *Let $V = \mathbf{R}$, $\Omega = \{a \in \mathbf{R}; a > 0\}$ and $D = T_{\Omega} = \{z \in \mathbf{C}; \operatorname{Im}(z) > 0\}$.*

Then

$$d_D(a, b) \geq \log t \quad \text{for } a \in D - D_r, b \in D_{tr}, t > 1, r \in \Omega.$$

PROOF. The intrinsic distance d_D is identical in this case with the distance defined by the Bergman metric $(dx^2+dy^2)/y^2$. Hence,

$$d_D(a, b) \geq d_D(\operatorname{Im}(a), \operatorname{Im}(b)) \geq d_D(ir, itr) = d_D(i, it) = \log t. \quad \text{QED.}$$

LEMMA 2.7. Let $V = \mathbf{R}^n$, $\Omega = \{(y^1, \dots, y^n) \in \mathbf{R}^n; y^1 > 0, \dots, y^n > 0\}$ and $D = T_\Omega = \{(z^1, \dots, z^n) \in \mathbf{C}^n; \operatorname{Im}(z^1) > 0, \dots, \operatorname{Im}(z^n) > 0\}$. Then

$$d_D(a, b) \geq \log t \quad \text{for } a \in D - D_r, b \in D_{tr}, t > 1, r \in \Omega.$$

PROOF. Let $a = (a^1, \dots, a^n)$, $b = (b^1, \dots, b^n)$ and $r = (r^1, \dots, r^n)$. Then

$$\operatorname{Im}(a^j) \leq r^j \quad \text{for some } j, 1 \leq j \leq n,$$

$$\operatorname{Im}(b^i) > tr^i \quad \text{for all } i, 1 \leq i \leq n.$$

We can write $D = D_1 \times \dots \times D_1$, where D_1 is the domain defined by $D_1 = \{z \in \mathbf{C}; \operatorname{Im}(z) > 0\}$. Let $p_j: D \rightarrow D_1$ be the projection to the j -th factor. Since p_j is holomorphic and hence distance-decreasing, we have

$$d_D(a, b) \geq d_{D_1}(p_j a, p_j b) = d_{D_1}(a^j, b^j).$$

Applying Lemma 2.6 to the domain D_1 , we obtain

$$d_{D_1}(a^j, b^j) \geq \log t.$$

Hence,

$$d_D(a, b) \geq \log t. \quad \text{QED.}$$

LEMMA 2.8. Let Ω be a convex cone in an n -dimensional real vector space V . Let $D = T_\Omega = \{z \in V_{\mathbf{C}}; \operatorname{Im}(z) \in \Omega\}$. Then

$$d_D(a, b) \geq \log t \quad \text{for } a \in D - D_r, b \in D_{tr}, t > 1, r \in \Omega.$$

PROOF. Put $y = \operatorname{Im}(a)$. Consider the line $y + sr$, $(-\infty < s < \infty)$; this is a line through y and parallel to the vector r . We shall show that this line meets the boundary $\partial\Omega$ of Ω exactly at one point, say, y_0 . Since this line contains a point of Ω , e. g., $y \in \Omega$ and since the convex cone Ω cannot contain a whole straight line, this line meets the boundary $\partial\Omega$. If y_0 is any point where this line meets $\partial\Omega$, we may write $y_0 = y + s_0 r$. If $\varepsilon > 0$, then

$$y + (s_0 + \varepsilon)r = y_0 + \varepsilon r = (1 + \varepsilon) \left(\frac{1}{1 + \varepsilon} y_0 + \frac{\varepsilon}{1 + \varepsilon} r \right).$$

Since $y_0 \in \bar{\Omega}$, $r \in \Omega$ and Ω is convex, it follows that $\frac{1}{1 + \varepsilon} y_0 + \frac{\varepsilon}{1 + \varepsilon} r$ is in Ω . Since Ω is a cone, $(1 + \varepsilon) \left(\frac{1}{1 + \varepsilon} y_0 + \frac{\varepsilon}{1 + \varepsilon} r \right)$ is in Ω . This shows that the half-line $\{y + sr; s > s_0\}$ is completely contained in Ω . Hence, y_0 is the unique intersection point.

We claim that there exists a basis e_1, \dots, e_n of V such that the open convex cone $\Omega_n = \{\sum y^i e_i \in V; y^1 > 0, \dots, y^n > 0\}$ contains Ω and $y_0 \in \partial\Omega_n$. In

order to prove our claim, we use the following well known fact on the dual cone. Let V^* be the dual space of V and define the dual cone Ω^* of Ω by

$$\Omega^* = \{y^* \in V^*; \langle y^*, y \rangle > 0 \text{ for all nonzero } y \in \bar{\Omega}\}.$$

Then $\Omega^{**} = \Omega$. In particular, Ω^* is an open convex cone in V^* . It is easy to see that there exists a nonzero element e_1^* in the closure of Ω^* such that $\langle e_1^*, y_0 \rangle = 0$. Choose e_2^*, \dots, e_n^* in Ω^* so that e_1^*, \dots, e_n^* is a basis for V^* ; this is possible because Ω^* is an open cone. Then the dual basis e_1, \dots, e_n for V possesses the desired property.

Put $D_n = T_{\Omega_n} = \{z \in V_c; \text{Im}(z) \in \Omega_n\}$. Since $D_{tr} = \{z \in D; \text{Im}(z) - tr \in \Omega\}$ and $D_{n,tr} = \{z \in D_n; \text{Im}(z) - tr \in \Omega_n\}$, we have $D_{tr} \subset D_{n,tr}$. Hence $b \in D_{tr}$ implies $b \in D_{n,tr}$. We shall now show that $a \in D_n - D_{n,r}$. Since $y = \text{Im}(a)$ and $a \notin D_r$, it follows that $y - r \notin \Omega$. Since $y + sr$ is in Ω if and only if $s > s_0$ as we saw above, we may conclude that $-1 \leq s_0$. Since the line $y + sr$, $(-\infty < s < \infty)$, meets $\partial\Omega_n$ also exactly at one point $y_0 = y + s_0r$, we see that $y + sr$ is in Ω_n if and only if $s > s_0$. Hence, $y - r$ is not in Ω_n . This shows that $a \notin D_{n,r}$.

Since the injection $h : D \rightarrow D_n$ is holomorphic and hence distance-decreasing, we have

$$d_D(a, b) \geq d_{D_n}(ha, hb) = d_{D_n}(a, b).$$

Applying Lemma 2.7 to the domain D_n , we have

$$d_{D_n}(a, b) \geq \log t.$$

Hence,

$$d_D(a, b) \geq \log t. \qquad \text{QED.}$$

PROOF OF PROPOSITION 2.5. Let $D = D(H, \Omega, \mathcal{D}, \varphi)$, $a \in D - D_r$ and $b \in D_{tr}$ with $t > 1$. Put $a = (\check{t}, \check{z}, \check{w}) \in U \times V_c \times W$. Since $I + \varphi(\check{t})$ is a real automorphism of W by Lemma 2.1, the Siegel domain D of the third kind admits an automorphism of the type (2) which sends $a = (\check{t}, \check{z}, \check{w})$ into $(\check{t}, \check{z}, 0)$. Since such an automorphism of D leaves the distance d_D invariant and, by Lemma 2.3, leaves the domains D_r and D_{tr} invariant, we may assume without loss of generality that $a = (\check{t}, \check{z}, 0)$.

Let $\rho : U \times V_c \times W \rightarrow V_c$ be the natural projection. We claim that ρ maps D into $D' = T_{\Omega} = \{z \in V_c; \text{Im}(z) \in \Omega\}$. In fact, if (t, z, w) is in D so that $\text{Im}(z) - \text{Re}(L_{\varphi(t)}(w, w)) \in \Omega$, then $\text{Im}(z) \in \Omega$ because $\text{Re}(L_{\varphi(t)}(w, w))$ is in $\bar{\Omega}$ by Lemma 2.2. Hence, z is in D' , proving our claim. In particular, $\rho(a)$ is in D' . Since $a = (\check{t}, \check{z}, 0)$ is not in D_r , it follows that $\text{Im}(\check{z}) - r$ is not in Ω . Hence $\check{z} = \rho(a)$ is not in D'_r , thus proving $\rho(a) \in D' - D'_r$. From Lemma 2.2 it follows easily that $b \in D_{tr}$ implies $\rho(b) \in D'_{tr}$. Since ρ is holomorphic and hence distance-decreasing, we have

$$d_D(a, b) \geq d_{D'}(\rho(a), \rho(b)).$$

Applying Lemma 2.8 to the domain D' , we have

$$d_{D'}(\rho(a), \rho(b)) \geq \log t.$$

Hence,

$$d_D(a, b) \geq \log t. \quad \text{QED.}$$

§ 3. Boundary components of symmetric bounded domains [1], [6], [7], [8], [9].

Let D be a symmetric bounded domain in C^N in the so-called Harish-Chandra realization. Let \bar{D} be the topological closure of D and put $\partial D = \bar{D} - D$. A subset \mathcal{F} of ∂D is called a *boundary component* of D if (i) \mathcal{F} is an analytic subset of C^N and (ii) \mathcal{F} is minimal with respect to the property that any analytic arc contained in ∂D and having a point in common with \mathcal{F} must be entirely contained in \mathcal{F} . Then each boundary component \mathcal{F} is again a bounded symmetric domain. And if \mathcal{F}' is another boundary component of D and if $\mathcal{F}' \subset \partial \mathcal{F}$, then \mathcal{F}' is a boundary component of \mathcal{F} also. For each boundary component \mathcal{F} of D , there exists a Siegel domain of the third kind $D(H, \Omega, \mathcal{F}, \varphi)$ which is biholomorphic to D . In the following, we fix such a realization $D(H, \Omega, \mathcal{F}, \varphi)$ once and for all for each D and \mathcal{F} .

Let G be the identity component of the group of automorphisms of D . Then each element of G extends to an automorphism of a neighborhood of \bar{D} . Let Γ be a discrete subgroup of G defined arithmetically. We consider only those boundary components \mathcal{F} which are called the rational boundary components with respect to Γ . Let B denote the union of all rational boundary components of D and set

$$D^* = D \cup B.$$

The action of Γ on D extends to D^* in a natural manner. With a topology described below, $D^*/\Gamma = (D/\Gamma) \cup (B/\Gamma)$ is the so-called Satake compactification of D/Γ . Let $\eta: D^* \rightarrow D^*/\Gamma$ denote the natural projection. For each point of D/Γ , a basis of its neighborhood system is given by its neighborhood system in D/Γ with the usual quotient topology. For a point p in B/Γ , we construct a basis of its neighborhood system as follows. Assume $p \in \eta(\mathcal{F})$ and let $\tilde{p} \in \mathcal{F}$ be a point such that $\eta(\tilde{p}) = p$. Consider the family of all rational boundary components \mathcal{E} of D such that $\mathcal{F} \subset \partial \mathcal{E}$. It is known that there are only a finite number of Γ -equivalence classes in this family. Let $\mathcal{F}_1, \dots, \mathcal{F}_m$ be a system of representatives for these Γ -equivalence classes. Thus the family $\{\gamma(\mathcal{F}_i); \gamma \in \Gamma \text{ and } i=1, \dots, m\}$ exhausts the rational boundary components \mathcal{E} of D such that $\mathcal{F} \subset \partial \mathcal{E}$. Let \mathcal{O} be an open neighborhood of \tilde{p} in \mathcal{F} . Considering D as a Siegel domain $D(H, \Omega, \mathcal{F}, \varphi)$ of the third kind, we consider a cylindrical

set $D_r(\mathcal{O})$ in D (as defined in §2), where r is an element of the open convex cone Ω . Each \mathcal{F}_i is also a Siegel domain $\mathcal{F}_i = D(H_i, \Omega_i, \mathcal{F}, \varphi_i)$ of the third kind. We choose a cylindrical set $\mathcal{F}_{i,r_i}(\mathcal{O})$ in \mathcal{F}_i , where $r_i \in \Omega_i$. Put

$$\tilde{\mathcal{U}} = \mathcal{O} \cup D_r(\mathcal{O}) \cup \mathcal{F}_{1,r_1}(\mathcal{O}) \cup \dots \cup \mathcal{F}_{m,r_m}(\mathcal{O})$$

and

$$\mathcal{U} = \eta(\tilde{\mathcal{U}}).$$

We take the family of \mathcal{U} with varying $\mathcal{O}, r, r_1, \dots, r_m$ as a basis for the open neighborhood system for \tilde{p} .

LEMMA 3.1. *Let $D_r(\mathcal{O})$ be a cylindrical set in D with a base \mathcal{O} in a boundary component \mathcal{F} . Let \mathcal{O}' be an open set in \mathcal{F} such that $\bar{\mathcal{O}}' \subset \mathcal{O}$ and let $D_{tr}(\mathcal{O}')$ be a cylindrical set in D with a base \mathcal{O}' , where $t > 1$. Then*

$$d_D(a, b) \geq \text{Min} \{ \log t, d_{\mathcal{F}}(\mathcal{F} - \mathcal{O}, \mathcal{O}') \} \quad \text{for } a \in D - D_r(\mathcal{O}), b \in D_{tr}(\mathcal{O}').$$

PROOF. Let $\theta: D = D(H, \Omega, \mathcal{F}, \varphi) \rightarrow \mathcal{F}$ be the natural projection. If $\theta(a) \in \mathcal{O}$, then $a \in D - D_r$ and Proposition 2.5 implies $d_D(a, b) \geq \log t$. Suppose $\theta(a) \notin \mathcal{O}$. Since θ is holomorphic and hence distance-decreasing, we have

$$d_D(a, b) \geq d_{\mathcal{F}}(\theta a, \theta b) \geq d_{\mathcal{F}}(\mathcal{F} - \mathcal{O}, \mathcal{O}'). \quad \text{QED.}$$

PROOF OF THEOREM 2'. Let p be a point of B/Γ and \mathcal{U} a neighborhood of p in $D^*/\Gamma = (D/\Gamma) \cup (B/\Gamma)$. We have to prove that there is a smaller neighborhood \mathcal{CV} of p in D^*/Γ such that $\bar{\mathcal{C}}\mathcal{V} \subset \mathcal{U}$ and

$$d_D(a, b) \geq \delta \quad \text{if } a, b \in D, \eta(a) \notin \mathcal{U} \text{ and } \eta(b) \in \mathcal{CV},$$

where δ is a positive number which depends only on \mathcal{U} and \mathcal{CV} but not on a, b . We choose $\tilde{p} \in \mathcal{F}$ such that $\eta(\tilde{p}) = p$.

Without loss of generality, we may assume that $\mathcal{U} = \eta(\tilde{\mathcal{U}})$, where $\tilde{\mathcal{U}}$ is of the form

$$\tilde{\mathcal{U}} = \mathcal{O} \cup D_r(\mathcal{O}) \cup \mathcal{F}_{1,r_1}(\mathcal{O}) \cup \dots \cup \mathcal{F}_{m,r_m}(\mathcal{O}),$$

where \mathcal{O} is an open neighborhood of $\tilde{p} \in \mathcal{F}$, (see the definition of the topology in D^*/Γ above). Let \mathcal{O}' be a smaller neighborhood of \tilde{p} in \mathcal{F} such that $\bar{\mathcal{O}}' \subset \mathcal{O}$ and let $t > 1$. Put

$$\tilde{\mathcal{C}}\mathcal{V} = \mathcal{O}' \cup D_{tr}(\mathcal{O}') \cup \mathcal{F}_{1,tr_1}(\mathcal{O}') \cup \dots \cup \mathcal{F}_{m,tr_m}(\mathcal{O}')$$

and

$$\mathcal{CV} = \eta(\tilde{\mathcal{C}}\mathcal{V}).$$

Let $a, b \in D, \eta(a) \notin \mathcal{U}$ and $\eta(b) \in \mathcal{CV}$. Since b is equivalent to a point in $\tilde{\mathcal{C}}\mathcal{V}$ under the group Γ and since d_D is invariant by Γ , we may assume that $b \in \tilde{\mathcal{C}}\mathcal{V}$. Clearly, $a \notin \tilde{\mathcal{U}}$. Since $a \in D$ and $a \notin \tilde{\mathcal{U}}$, we have $a \in D - D_r(\mathcal{O})$. Since $b \in D$ and $b \in \tilde{\mathcal{C}}\mathcal{V}$, we have $b \in D_{tr}(\mathcal{O}')$. By Lemma 3.1,

$$d_D(a, b) \geq \delta,$$

where

$$\delta = \text{Min} \{ \log t, d_{\mathcal{F}}(\mathcal{F} - \mathcal{O}, \mathcal{O}') \} . \quad \text{QED.}$$

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