

## A generalization of F. Schur's theorem

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The following theorem, due to F. Schur, is well-known:

THEOREM A. *Let  $M$  be a Riemannian manifold with  $\dim M \geq 3$ . If the sectional curvature  $K$  of  $M$  is constant at each point of  $M$ , then  $K$  is actually constant on  $M$ .*

There are several other theorems of this type; we mention a few of them.

THEOREM B. *Let  $M$  be an Einstein manifold, that is, assume the Ricci curvature of  $M$  is a scalar multiple  $\lambda$  of the metric tensor of  $M$ . If  $\dim M \geq 3$ , then  $\lambda$  is constant.*

THEOREM C (Thorpe [2]). *Let  $M$  be a Riemannian manifold with  $\dim M \geq 2p+1$ . If the  $2p$ th sectional curvature  $\gamma_{2p}$  is constant at each point of  $M$ , then  $\gamma_{2p}$  is constant on  $M$ .*

THEOREM D. *Let  $M$  be a Kähler manifold with  $\dim M \geq 4$ . If the holomorphic sectional curvature  $K_h$  is pointwise constant, then it is actually constant.*

THEOREM E (M. Berger, unpublished). *Let  $M$  be a Riemannian manifold with metric tensor  $g_{ij}$  and Riemann curvature tensor  $R_{ijkl}$ . Suppose*

$$\sum_{i,j,k} R_{ijks} R^{ijk t} = \lambda g_{st}.$$

*If  $\dim M \geq 5$ , then  $\lambda$  is constant.*

In this paper we prove a result (theorem 2) which includes theorems A, B, C, and D as special cases. Although theorem E is not a consequence of theorem 2, it almost is, in the sense that it would be if a slightly different contraction were used.

We shall use the notation of [1]. Recall that a *double form* of type  $(p, q)$  is a function  $\omega: \mathfrak{X}(M)^{p+q} \rightarrow \mathcal{F}(M)$  which is skew-symmetric in the first  $p$  variables and also in the last  $q$  variables. Here, as usual,  $\mathfrak{X}(M)$  denotes the Lie algebra of vector fields on the  $C^\infty$  manifold  $M$  and  $\mathcal{F}(M)$  the ring of  $C^\infty$  real valued functions on  $M$ . We write  $\omega(X_1, \dots, X_p)(Y_1, \dots, Y_q)$  for the value of  $\omega$  on  $X_1, \dots, X_p, Y_1, \dots, Y_q$ . If  $p=q$  and

$$\omega(X_1, \dots, X_p)(Y_1, \dots, Y_p) = \omega(Y_1, \dots, Y_p)(X_1, \dots, X_p)$$

for

$$X_1, \dots, X_p, Y_1, \dots, Y_p \in \mathfrak{X}(M),$$

the double form  $\omega$  is said to be *symmetric*.

Now assume that  $M$  has a Riemannian metric  $g$ , and let  $\nabla$  be the corresponding connection. Then if  $\omega$  is a double form of type  $(p, p)$ , so is  $\nabla_X(\omega)$  for  $X \in \mathfrak{X}(M)$  (see [1]). Furthermore a double form  $D\omega$  of type  $(p+1, q)$  is defined by

$$(D\omega)(X_1, \dots, X_{p+1}) = \sum_{j=1}^{p+1} (-1)^{j+1} \nabla_{X_j}(\omega)(X_1, \dots, \hat{X}_j, \dots, X_{p+1}).$$

Here  $D$  is an analog of the exterior derivative  $d$ ; however, unlike  $d$ ,  $D$  is not independent of  $\nabla$ .

It will also be necessary to define the notion of the *contraction operator*  $C$  on double forms. If  $\omega$  is a double form of type  $(p, q)$ , then  $C\omega$  is the double form of type  $(p-1, q-1)$  defined by

$$(C\omega)(X_1, \dots, X_{p-1})(Y_1, \dots, Y_{q-1}) = \sum_{i=1}^n \omega(X_1, \dots, X_{p-1}, E_i)(Y_1, \dots, Y_{q-1}, E_i)$$

where  $n = \dim M$  and  $\{E_1, \dots, E_n\}$  is any orthonormal frame field defined on an open subset of  $M$ . Then  $C^r$ ,  $r = 0, 1, 2, \dots$  are defined inductively. We shall agree that if  $p = 0$  or  $q = 0$ , then  $C\omega = 0$ .

We shall need the following result.

**THEOREM 1.** *Let  $A$  be a double form of type  $(p, q)$  such that  $DA = 0$ . Then*

$$(1) \quad (DC^r A)(U, X_1, \dots, X_{p-r})(Y_1, \dots, Y_{q-r}) \\ = (-1)^{p-r} \sum_{i=1}^n \nabla_{E_i}(C^{r-1} A)(U, X_1, \dots, X_{p-r})(Y_1, \dots, Y_{q-r}, E_i)$$

for  $U, X_1, \dots, X_{p-r}, Y_1, \dots, Y_{q-r} \in \mathfrak{X}(M)$ , where  $\{E_1, \dots, E_n\}$  is a local orthonormal frame field on  $M$ .

**PROOF.** We induct on  $r$ . The assumption  $DA = 0$  implies that (1) is true for  $r = 0$ . Next suppose that (1) is true for general  $r$ . Then

$$0 = (CDC^r A)(U, X_1, \dots, X_{p-r-1})(Y_1, \dots, Y_{q-r-1}) \\ + (-1)^{p-r} \sum_{i=1}^n \nabla_{E_i}(C^r A)(U, X_1, \dots, X_{p-r-1})(Y_1, \dots, Y_{q-r-1}, E_i) \\ = (DC^{r+1} A)(U, X_1, \dots, X_{p-r-1})(Y_1, \dots, Y_{q-r-1}) \\ + (-1)^{p-r}(r+1) \sum_{i=1}^n \nabla_{E_i}(C^r A)(U, X_1, \dots, X_{p-r-1})(Y_1, \dots, Y_{q-r-1}, E_i).$$

Hence (1) is true for  $r+1$ . This completes the proof.

If  $\omega$  is a double form of type  $(p, q)$ , then  $\omega'$  is a double form of type  $(p+1, q-1)$  defined by

$$\omega'(X_1, \dots, X_{p+1})(Y_2, \dots, Y_q) = \sum_{j=1}^{p+1} (-1)^{j+1} \omega(X_1, \dots, \hat{X}_j, \dots, X_{p+1})(X_j, Y_2, \dots, Y_q)$$

for  $X_1, \dots, X_{p+1}, Y_2, \dots, Y_q \in \mathfrak{X}(M)$ . We define a *Riemannian double form* (as in [1]) to be a symmetric double form such that  $D\omega = \omega' = 0$ .

The best known examples of Riemannian double forms are the metric tensor  $g$  (type (1, 1)) and the Riemannian curvature tensor  $R$  (type (2, 2)). (The Bianchi identities state that  $R' = DR = 0$ .) In [1] the notion of exterior products of double forms is defined. In particular  $g^p = g \wedge \dots \wedge g$  and  $R^p = R \wedge \dots \wedge R$  (each  $p$  times) are double forms of types  $(p, p)$  and  $(2p, 2p)$  respectively.

We are now ready to prove our main result.

**THEOREM 2.** *Let  $A$  and  $B$  be Riemannian double forms of types  $(p, p)$  and  $(r, r)$  respectively and assume that (a)  $B$  is parallel (that is  $\nabla_X B = 0$  for all  $X \in \mathfrak{X}(M)$ ), (b)  $C^{r-1}B = \alpha g$  for some  $\alpha \in \mathfrak{F}(M)$ , not identically 0, (c)  $p < n = \dim M$ , (d) there exist  $\lambda \in \mathfrak{F}(M)$  and an integer  $q$  such that for all  $X_1, \dots, X_{p-q} \in \mathfrak{X}(M)$  we have*

$$(C^q A)(X_1, \dots, X_{p-q})(X_1, \dots, X_{p-q}) = \lambda(C^{r-p+q} B)(X_1, \dots, X_{p-q})(X_1, \dots, X_{p-q}).$$

Then  $\lambda$  is constant on  $M$ .

**PROOF.** Since  $B$  is parallel, so is  $C^{r-1}B$ , and thus  $\alpha$  is a nonzero constant. Furthermore  $n\alpha = C^r B$ . According to [1] condition (d) is equivalent to  $C^q A = \lambda C^{r-p+q} B$ . Hence for  $U \in \mathfrak{X}(M)$  we have

$$\begin{aligned} 0 &= (DC^p A - D(\lambda C^r B))(U) \\ &= p \sum_{i=1}^n \nabla_{E_i} (\lambda C^{r-1} B)(U)(E_i) - (U\lambda)C^r B \\ &= p \sum_{i=1}^n (E_i \lambda)(C^{r-1} B)(U)(E_i) - (U\lambda)C^r B \\ &= (p-n)\alpha(U\lambda). \end{aligned}$$

Since  $U$  is arbitrary, it follows that  $\lambda$  is constant.

The following is an important special case of theorem 2.

**THEOREM 3.** *Let  $A$  be a Riemannian double form of type  $(p, p)$  with  $p < n = \dim M$ , and assume that for some  $q \leq p-1$  and  $\lambda \in \mathfrak{F}(M)$  we have*

$$(C^q A)(X_1, \dots, X_{p-q})(X_1, \dots, X_{p-q}) = \lambda g^{p-q}(X_1, \dots, X_{p-q})(X_1, \dots, X_{p-q}),$$

for all  $X_1, \dots, X_{p-q} \in \mathfrak{X}(M)$ . Then  $\lambda$  is constant on  $M$ .

**PROOF.** In theorem 2 we take  $B = g^{p-q}$ . We have the general formula

$$C^s g^t = \frac{t!(n-t+s)!}{(t-s)!(n-t)!} g^{t-s}$$

for all integers  $s$  and  $t$  with  $0 \leq s \leq t$ . Thus condition (b) of theorem 2 is satisfied. Furthermore  $g^t$  is parallel for all  $t$  (see [1]) and so condition (a) of theorem (2) holds. We conclude that  $\lambda$  must be constant.

We obtain theorems A and B from theorem 3 by taking  $A = R$  and  $q = 0$

and 1, respectively. Theorem C is also obtained from theorem 3, using  $A = R^p$ ,  $q = 0$ .

Furthermore we have the following generalization of theorems A, B and C.

THEOREM 4. *Suppose  $p < n$ ,  $q < 2p - 1$ , and*

$$C^q R^p(X_1, \dots, X_{2p-q})(X_1, \dots, X_{2p-q}) = \lambda g^{2p-q}(X_1, \dots, X_{2p-q})(X_1, \dots, X_{2p-q})$$

for all  $X_1, \dots, X_{2p-q} \in \mathfrak{X}(M)$ . Then  $\lambda$  is constant.

However, to prove theorem D we must use theorem 2 with  $A = R$ ,  $q = 0$ , and  $B$  defined by

$$\begin{aligned} B(W, X)(Y, Z) &= g(W, Y)g(X, Z) - g(W, Z)g(X, Y) \\ &\quad + g(JW, Y)g(JX, Z) - g(JW, Z)g(JX, Y) \\ &\quad + 2g(JW, X)g(JY, Z) \end{aligned}$$

for  $W, X, Y, Z \in \mathfrak{X}(M)$ , where  $J$  denotes the almost complex structure of the Kähler manifold  $M$ . It seems plausible that an analog of theorem D holds for  $2p$ th holomorphic sectional curvature; however, the author has been unable to prove this.

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### References

- [ 1 ] A. Gray, Some relations between curvature and characteristic classes (to appear).
- [ 2 ] J. Thorpe, Sectional curvatures and characteristic classes, *Ann. of Math.*, **80** (1964), 429-443.