

A problem on the existence of an Einstein metric

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This note is to present a variational problem, to which the problem of the existence of an Einstein metric is reduced. The latter has called certain geometers' attention from various points of view; for instance, if an Einstein metric is proved to exist on a compact simply connected 3-manifold then the Poincaré conjecture for the 3-sphere is answered affirmatively (see e. g. [1]). The variational problem arises from the characterization of Einstein metrics in the following theorem.

THEOREM. *Let M be an n -dimensional compact orientable manifold with a fixed volume element Ω (or an $SL(n, \mathbf{R})$ -structure P). And let \mathcal{G} be the family of all Riemannian metrics with Ω on M (or all $SO(n)$ -structures contained in P). Then a Riemannian metric g_0 in \mathcal{G} is Einstein if and only if the function $I = I(g) = \int_M R\Omega$ on \mathcal{G} attains a critical value at g_0 , where R is the scalar curvature of g .*

Before the proof some comments will be adequate. An $SL(n, \mathbf{R})$ -structure is essentially unique on M [2]. I attains its critical value at g_0 by definition if one has $D(I(g(t))) = g_0$ at $t=0$, $D = d/dt$, for any differentiable one-parameter family $\{g(t)\}$ with $g(0) = g_0$ of Riemannian metrics in \mathcal{G} . The theorem is trivial when $n=2$, since I is then a constant by the Gauss-Bonnet formula.

Now the proof is given by a straightforward tensor calculus. We put $a = Dg(t)$. Such an $a = (a_{ij})$ is characterized as a symmetric covariant tensor field of degree 2 whose "trace" $a_a^a = g^{ij}a_{ij}$ vanishes identically due to the assumption on the volume element. It is easy to obtain $DR_{ij} = \nabla_a D\left\{ \begin{smallmatrix} a \\ i \ j \end{smallmatrix} \right\}$ by noting $D\left\{ \begin{smallmatrix} a \\ a \ j \end{smallmatrix} \right\} = 0$, so that we have $DI(g) = D\int_M R\Omega = \int_M (DR)\Omega = \int_M (g^{ab}DR_{ab} + R_{ab}Dg^{ab})\Omega = \int_M (\nabla_a g^{bc}D\left\{ \begin{smallmatrix} a \\ b \ c \end{smallmatrix} \right\} - R_{ab}g^{ab})\Omega = -\int_M R_{ab}a^{ab}\Omega$, since the second integrand in the third integral is the divergence of the vector field $(v^i) = (g^{bc}D\left\{ \begin{smallmatrix} i \\ b \ c \end{smallmatrix} \right\})$. Thus $DI(g)$ vanishes if and only if $R_{ab}a^{ab}$ vanishes everywhere on M . This occurs when and only when (R_{ab}) is a scalar multiple of g . The theorem is proved.

It should be noted that in the variation above the volume element is left fixed, which is a condition which was not posed by Hilbert (Nachr. Ges. Wiss. Göttingen, p. 395, 1915) and Einstein in deriving the Einstein field equation (see A. H. Taub, *Conversation laws and variational principles in general relativity*, Lecture I, Santa Barbara, 1962).

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Bibliography

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- [2] J. Moser, *On the volume elements on a manifold*, Trans. Amer. Math. Soc., 120 (1965), 286-294.