

UMBILICAL SURFACES OF PRODUCTS OF SPACE FORMS

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Abstract. We give a complete classification of umbilical surfaces of arbitrary codimension of a product $\mathbb{Q}_{k_1}^{n_1} \times \mathbb{Q}_{k_2}^{n_2}$ of space forms whose curvatures satisfy $k_1 + k_2 \neq 0$.

1. Introduction. A submanifold of a Riemannian manifold is *umbilical* if it is equally curved in all tangent directions. More precisely, an isometric immersion $f: M^m \rightarrow \tilde{M}^n$ between Riemannian manifolds is umbilical if there exists a normal vector field H along f such that its second fundamental form $\alpha_f \in \text{Hom}(TM \times TM, N_f M)$ with values in the normal bundle satisfies

$$\alpha_f(X, Y) = \langle X, Y \rangle H \text{ for all } X, Y \in \mathfrak{X}(M).$$

The classification of umbilical submanifolds of space forms is very well known. For a general symmetric space N , it was shown by Nikolayevsky (see Theorem 1 of [6]) that any umbilical submanifold of N is an umbilical submanifold of a product of space forms totally geodesically embedded in N . This makes the classification of umbilical submanifolds of a product of space forms an important problem. For submanifolds of dimension $m \geq 3$ of a product $\mathbb{Q}_{k_1}^{n_1} \times \mathbb{Q}_{k_2}^{n_2}$ of space forms whose curvatures satisfy $k_1 + k_2 \neq 0$, the problem was reduced in [3] to the classification of m -dimensional umbilical submanifolds with codimension two of $\mathbb{S}^n \times \mathbb{R}$ and $\mathbb{H}^n \times \mathbb{R}$, where \mathbb{S}^n and \mathbb{H}^n stand for the sphere and hyperbolic space, respectively. The case of $\mathbb{S}^n \times \mathbb{R}$ (respectively, $\mathbb{H}^n \times \mathbb{R}$) was carried out in [4] (respectively, [5]), extending previous results in [7] and [8] (respectively, [1]) for hypersurfaces.

In this paper we extend the results of [3] to the surface case. In this case, the argument in one of the steps of the proof for the higher dimensional case (see Lemma 8.2 of [3]) does not apply, and requires more elaborate work. This is carried out in Lemma 4 below, which shows that the difficulty is due to the existence of new interesting families of examples in the surface case. Indeed, our main result (see Theorem 5 below) states that, in addition to the examples that appear already in higher dimensions, there are precisely two distinct two-parameter families of complete embedded flat umbilical surfaces that lie substantially in $\mathbb{H}_k^3 \times \mathbb{R}^2$ and $\mathbb{H}_{k_1}^3 \times \mathbb{H}_{k_2}^3$, respectively. These are discussed in Section 3.

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2. Preliminaries. Let $f: M \rightarrow \mathbb{Q}_{k_1}^{n_1} \times \mathbb{Q}_{k_2}^{n_2}$ be an isometric immersion of a Riemannian manifold. We always assume that M is connected. Denote by \mathcal{R} and \mathcal{R}^\perp the curvature tensors of the tangent and normal bundles TM and N_fM , respectively, by $\alpha = \alpha_f \in \Gamma(T^*M \otimes T^*M \otimes N_fM)$ the second fundamental form of f and by $A_\eta = A_\eta^f$ its shape operator in the normal direction η , given by

$$\langle A_\eta X, Y \rangle = \langle \alpha(X, Y), \eta \rangle$$

for all $X, Y \in \mathfrak{X}(M)$. Set

$L = L^f := \pi_2 \circ f_* \in \Gamma(T^*M \otimes T\mathbb{Q}_{k_2}^{n_2})$ and $K = K^f := \pi_2|_{N_fM} \in \Gamma((N_fM)^* \otimes T\mathbb{Q}_{k_2}^{n_2})$, where $\pi_i: \mathbb{Q}_{k_1}^{n_1} \times \mathbb{Q}_{k_2}^{n_2} \rightarrow \mathbb{Q}_{k_i}^{n_i}$ denotes the canonical projection, $1 \leq i \leq 2$, and by abuse of notation also its derivative, which we regard as a section of $T^*(\mathbb{Q}_{k_1}^{n_1} \times \mathbb{Q}_{k_2}^{n_2}) \otimes T\mathbb{Q}_{k_i}^{n_i}$.

2.1. The fundamental equations. The tensors $R \in \Gamma(T^*M \otimes TM)$, $S \in \Gamma(T^*M \otimes N_fM)$ and $T \in \Gamma((N_fM)^* \otimes N_fM)$ given by

$$(1) \quad R = L^t L, \quad S = K^t L \quad \text{and} \quad T = K^t K,$$

or equivalently, by

$$L = f_* R + S \quad \text{and} \quad K = f_* S^t + T,$$

were introduced in [2] (see also [3]), where they were shown to satisfy the algebraic relations

$$(2) \quad S^t S = R(I - R), \quad TS = S(I - R) \quad \text{and} \quad SS^t = T(I - T),$$

as well as the differential equations

$$(3) \quad (\nabla_X R)Y = A_{SY}X + S^t \alpha(X, Y),$$

$$(4) \quad (\nabla_X S)Y = T\alpha(X, Y) - \alpha(X, RY)$$

and

$$(5) \quad (\nabla_X T)\xi = -SA_\xi X - \alpha(X, S^t \xi)$$

for all $X, Y \in \mathfrak{X}(M)$ and all $\xi \in \Gamma(N_fM)$. In particular, from the first and third equations of (1) and (2), respectively, it follows that R and T are nonnegative operators whose eigenvalues lie in $[0, 1]$.

The Gauss, Codazzi and Ricci equations of f are, respectively,

$$(6) \quad \mathcal{R}(X, Y)Z = (k_1(X \wedge Y - X \wedge RY - RX \wedge Y) + \kappa RX \wedge RY)Z + A_{\alpha(Y, Z)}X - A_{\alpha(X, Z)}Y,$$

$$(7) \quad (\nabla_X^\perp \alpha)(Y, Z) - (\nabla_Y^\perp \alpha)(X, Z) = \langle k_1 X - \kappa RX, Z \rangle SY - \langle k_1 Y - \kappa RY, Z \rangle SX$$

and

$$(8) \quad \mathcal{R}^\perp(X, Y)\eta = \alpha(X, A_\eta Y) - \alpha(A_\eta X, Y) + \kappa(SX \wedge SY)\eta,$$

where $\kappa = k_1 + k_2$.

2.2. The flat underlying space. In order to study isometric immersions $f: M \rightarrow \mathbb{Q}_{k_1}^{n_1} \times \mathbb{Q}_{k_2}^{n_2}$, it is useful to consider their compositions $F = h \circ f$ with the canonical isometric embedding

$$h: \mathbb{Q}_{k_1}^{n_1} \times \mathbb{Q}_{k_2}^{n_2} \rightarrow \mathbb{R}_{\sigma(k_1)}^{N_1} \times \mathbb{R}_{\sigma(k_2)}^{N_2} = \mathbb{R}_{\mu}^{N_1+N_2}.$$

Here, for $k \in \mathbb{R}$ we set $\sigma(k) = 1$ if $k < 0$ and $\sigma(k) = 0$ otherwise, and as a subscript of an Euclidean space it means the index of the corresponding flat metric. Also, we denote $\mu = \sigma(k_1) + \sigma(k_2)$, $N_i = n_i + 1$ if $k_i \neq 0$ and $N_i = n_i$ otherwise, in which case $\mathbb{Q}_{k_i}^{n_i}$ stands for \mathbb{R}^{n_i} .

Let $\tilde{\pi}_i: \mathbb{R}_{\mu}^{N_1+N_2} \rightarrow \mathbb{R}_{\sigma(k_i)}^{N_i}$, $1 \leq i \leq 2$, denote the canonical projection. Then, the normal space of h at each point $z \in \mathbb{Q}_{k_1}^{n_1} \times \mathbb{Q}_{k_2}^{n_2}$ is spanned by $k_1\tilde{\pi}_1(h(z))$ and $k_2\tilde{\pi}_2(h(z))$, and its second fundamental form is given by

$$(9) \quad \alpha_h(X, Y) = -k_1\langle \pi_1 X, Y \rangle \tilde{\pi}_1 \circ h - k_2\langle \pi_2 X, Y \rangle \tilde{\pi}_2 \circ h.$$

Therefore, if $k_i \neq 0$, $1 \leq i \leq 2$, then, setting $r_i = |k_i|^{-1/2}$, the unit vector field $v_i = v_i^F = \frac{1}{r_i}\tilde{\pi}_i \circ F$ is normal to F and we have

$$\tilde{\nabla}_X v_1 = \frac{1}{r_1}\tilde{\pi}_1 F_* X = \frac{1}{r_1}(F_* X - h_* L X) = \frac{1}{r_1}(F_*(I - R)X - h_* S X)$$

and

$$\tilde{\nabla}_X v_2 = \frac{1}{r_2}\tilde{\pi}_2 F_* X = \frac{1}{r_2}h_* L X = \frac{1}{r_2}(F_* R X + h_* S X),$$

where $\tilde{\nabla}$ stands for the derivative in $\mathbb{R}_{\mu}^{N_1+N_2}$. Hence

$$(10) \quad {}^F \nabla_X^\perp v_1 = -\frac{1}{r_1}h_* S X, \quad A_{v_1}^F = -\frac{1}{r_1}(I - R),$$

$$(11) \quad {}^F \nabla_X^\perp v_2 = \frac{1}{r_2}h_* S X \quad \text{and} \quad A_{v_2}^F = -\frac{1}{r_2}R.$$

2.3. Reduction of codimension. An isometric immersion $f: M^m \rightarrow \mathbb{Q}_{k_1}^{n_1} \times \mathbb{Q}_{k_2}^{n_2}$ is said to *reduce codimension on the left* by ℓ if there exists a totally geodesic inclusion $j_1: \mathbb{Q}_{k_1}^{m_1} \rightarrow \mathbb{Q}_{k_1}^{n_1}$, with $n_1 - m_1 = \ell$, and an isometric immersion $\tilde{f}: M^m \rightarrow \mathbb{Q}_{k_1}^{m_1} \times \mathbb{Q}_{k_2}^{n_2}$ such that $f = (j_1 \times id) \circ \tilde{f}$. Similarly one defines what it means by f reducing codimension *on the right*.

We will need the following result from [3] on reduction of codimension. In the statement, U and V stand for $\ker T$ and $\ker(I - T)$, respectively. Notice that the third equation in (2) implies that $S(TM)^\perp$ splits orthogonally as $S(TM)^\perp = U \oplus V$, with $U = (I - T)(S(TM)^\perp)$ and $V = T(S(TM)^\perp)$. Also, given an isometric immersion $f: M \rightarrow \tilde{M}$ between Riemannian manifolds, its *first normal space* at $x \in M$ is the subspace $N_1(x)$ of $N_f M(x)$ spanned by the image of its second fundamental form at x .

PROPOSITION 1. *Let $f: M^m \rightarrow \mathbb{Q}_{k_1}^{n_1} \times \mathbb{Q}_{k_2}^{n_2}$ be an isometric immersion. If $U \cap N_1^\perp$ (respectively, $V \cap N_1^\perp$) is a vector subbundle of $N_f M$ with rank ℓ satisfying $\nabla^\perp(U \cap N_1^\perp) \subset N_1^\perp$ (respectively, $\nabla^\perp(V \cap N_1^\perp) \subset N_1^\perp$), then f reduces codimension on the left (respectively, on the right) by ℓ .*

2.4. Frenet formulae for space-like curves in \mathbb{R}_1^4 . We briefly recall the definition of the Frenet curvatures and the Frenet frame of a unit-speed space-like curve $\gamma: I \rightarrow \mathbb{R}_1^4$ in the four dimensional Lorentz space, as well as the corresponding Frenet formulae, which will be needed in the sequel.

Thus, we assume that $t(s) = \gamma'(s)$ satisfies $\langle t(s), t(s) \rangle = 1$ for all $s \in I$. Assume first that $\langle \gamma''(s), \gamma''(s) \rangle \neq 0$ for all $s \in I$. Define $\hat{k}_1(s) = \|\gamma''(s)\| = |\langle \gamma''(s), \gamma''(s) \rangle|^{1/2}$ and $n_1(s) = \gamma''(s)/\hat{k}_1(s)$ for all $s \in I$. Denote $\epsilon_1 = \langle n_1, n_1 \rangle$. Suppose that $v(s) = n'_1(s) + \epsilon_1 \hat{k}_1(s)t(s)$ satisfies $\langle v(s), v(s) \rangle \neq 0$ for all $s \in I$. Define $\hat{k}_2(s) = \|v(s)\|$ and $n_2(s) = v(s)/\hat{k}_2(s)$. Let $n_3(s)$ be chosen so that $\{t(s), n_1(s), n_2(s), n_3(s)\}$ is a positively-oriented orthonormal basis of \mathbb{R}_1^4 and set $\epsilon_3 = \langle n_3, n_3 \rangle$. Then the following Frenet formulae hold, where \hat{k}_3 is defined by the third equation:

$$\begin{cases} t' = \hat{k}_1 n_1, \\ n'_1 = -\epsilon_1 \hat{k}_1 t + \hat{k}_2 n_2, \\ n'_2 = \epsilon_3 \hat{k}_2 n_1 + \hat{k}_3 n_3, \\ n'_3 = \epsilon_1 \hat{k}_3 n_2. \end{cases}$$

Lesser known are the formulae in the case in which $\gamma''(s)$ is a nonzero light-like vector everywhere, i.e., $\tilde{n}_1(s) = \gamma''(s)$ satisfies $\langle \tilde{n}_1(s), \tilde{n}_1(s) \rangle = 0$ for all $s \in I$. We carry them out in more detail below.

First notice that $\langle t, \tilde{n}_1 \rangle = 0$. Here, and in the next computations, we drop the “s” for simplicity of notation and understand that all equalities hold for all $s \in I$. Thus,

$$\langle \tilde{n}'_1, t \rangle = -\langle t', \tilde{n}_1 \rangle = -\langle \tilde{n}_1, \tilde{n}_1 \rangle = 0.$$

Moreover, $\langle \tilde{n}'_1, \tilde{n}_1 \rangle = 0$, hence \tilde{n}'_1 is space-like. Define $\tilde{k}_1 = \|\tilde{n}'_1\|$ and \tilde{n}_2 by $\tilde{n}'_1 = \tilde{k}_1 \tilde{n}_2$. Now let $\tilde{n}_3 \in \{t, \tilde{n}_2\}^\perp$ be the unique vector such that

$$\langle \tilde{n}_3, \tilde{n}_3 \rangle = 0 \quad \text{and} \quad \langle \tilde{n}_1, \tilde{n}_3 \rangle = 1,$$

that is, $\{\tilde{n}_1, \tilde{n}_3\}$ is a pseudo-orthonormal basis of the time-like plane $\{t, \tilde{n}_2\}^\perp$. Since

$$\langle \tilde{n}'_2, t \rangle = -\langle \tilde{n}_2, t' \rangle = -\langle \tilde{n}_2, \tilde{n}_1 \rangle = 0$$

and

$$\langle \tilde{n}'_2, \tilde{n}_1 \rangle = -\langle \tilde{n}_2, \tilde{n}'_1 \rangle = -\tilde{k}_1,$$

we have

$$\tilde{n}'_2 = \langle \tilde{n}'_2, \tilde{n}_1 \rangle \tilde{n}_3 + \langle \tilde{n}'_2, \tilde{n}_3 \rangle \tilde{n}_1 = -\tilde{k}_1 \tilde{n}_3 - \tilde{k}_2 \tilde{n}_1,$$

where

$$\tilde{k}_2 = \langle \tilde{n}'_3, \tilde{n}_2 \rangle.$$

Finally, since

$$0 = \langle \tilde{n}'_3, t \rangle = \langle \tilde{n}'_3, \tilde{n}_1 \rangle = \langle \tilde{n}'_3, \tilde{n}_3 \rangle,$$

we have

$$\tilde{n}'_3 = \langle \tilde{n}'_3, \tilde{n}_2 \rangle \tilde{n}_2 = \tilde{k}_2 \tilde{n}_2.$$

In summary, for a unit-speed space-like curve $\gamma: I \rightarrow \mathbb{R}^4_1$ with light-like curvature vector γ'' , one can define two Frenet curvatures \tilde{k}_1 and \tilde{k}_2 and a pseudo-orthonormal Frenet frame $\{t, \tilde{n}_1, \tilde{n}_2, \tilde{n}_3\}$ with respect to which the Frenet formulae are

$$\begin{cases} t' = \tilde{n}_1, \\ \tilde{n}'_1 = \tilde{k}_1 \tilde{n}_2, \\ \tilde{n}'_2 = -\tilde{k}_2 \tilde{n}_1 - \tilde{k}_1 \tilde{n}_3, \\ \tilde{n}'_3 = \tilde{k}_2 \tilde{n}_2. \end{cases}$$

In both cases, a unit-speed space-like curve $\gamma: I \rightarrow \mathbb{R}^4_1$ is completely determined by its Frenet curvatures, up to an isometry of \mathbb{R}^4_1 .

3. Flat umbilical surfaces in $\mathbb{H}^3_k \times \mathbb{R}^2$ and $\mathbb{H}^3_{k_1} \times \mathbb{H}^3_{k_2}$. We present below two families of complete flat properly embedded umbilical surfaces, the first one in $\mathbb{H}^3_k \times \mathbb{R}^2$ and the second in $\mathbb{H}^3_{k_1} \times \mathbb{H}^3_{k_2}$, each of which depending on two parameters.

EXAMPLE 2. Let $F: \mathbb{R}^2 \rightarrow \mathbb{R}^6_1 = \mathbb{R}^4_1 \times \mathbb{R}^2$, where \mathbb{R}^4_1 has signature $(-, +, +, +)$, be given by

$$(12) \quad F(s, t) = \left(a_1 \cosh \frac{s}{c}, a_1 \sinh \frac{s}{c}, a_2 \cos \frac{t}{c}, a_2 \sin \frac{t}{c}, b_1 \frac{s}{c}, b_2 \frac{t}{c} \right),$$

with

$$(13) \quad a_1^2 - a_2^2 = r^2 \quad \text{and} \quad a_1^2 + b_1^2 = c^2 = a_2^2 + b_2^2.$$

Then $F(\mathbb{R}^2) \subset \mathbb{H}^3_k \times \mathbb{R}^2$, where $k = -1/r^2$, by the first relation in (13). If $\{e_1, \dots, e_6\}$ is the orthonormal basis of \mathbb{R}^6_1 with respect to which F is given by (12), then the subspaces V_1 and V_2 of \mathbb{L}^6 spanned by $\{e_1, e_2, e_5\}$ and $\{e_3, e_4, e_6\}$ can be identified with \mathbb{R}^3_1 and \mathbb{R}^3 , respectively, and

$$F = \gamma_1 \times \gamma_2: \mathbb{R} \times \mathbb{R} = \mathbb{R}^2 \rightarrow V_1 \times V_2 = \mathbb{R}^3_1 \times \mathbb{R}^3 = \mathbb{R}^6_1,$$

where γ_1 and γ_2 are the helices in \mathbb{R}^3_1 and \mathbb{R}^3 , respectively, parameterized by

$$\gamma_1(s) = \left(a_1 \cosh \frac{s}{c}, a_1 \sinh \frac{s}{c}, b_1 \frac{s}{c} \right)$$

and

$$\gamma_2(t) = \left(a_2 \cos \frac{t}{c}, a_2 \sin \frac{t}{c}, b_2 \frac{t}{c} \right).$$

By the relations on the right in (13), both γ_1 and γ_2 are unit-speed curves, hence F is an isometric immersion. Since $F(\mathbb{R}^2) \subset \mathbb{H}^3_k \times \mathbb{R}^2$, there exists an isometric immersion $f: \mathbb{R}^2 \rightarrow$

$\mathbb{H}_k^3 \times \mathbb{R}^2$ such that $F = h \circ f$, where $h: \mathbb{H}_k^3 \times \mathbb{R}^2 \rightarrow \mathbb{R}_1^6$ denotes the inclusion. It is easily checked that the second fundamental form of f satisfies

$$\alpha_f \left(\frac{\partial}{\partial s}, \frac{\partial}{\partial t} \right) = 0$$

and

$$\alpha_f \left(\frac{\partial}{\partial s}, \frac{\partial}{\partial s} \right) = H(s, t) = \alpha_f \left(\frac{\partial}{\partial t}, \frac{\partial}{\partial t} \right),$$

where

$$h_*H(s, t) = \frac{ka_1a_2}{c^2} \left(a_2 \cosh \frac{s}{c}, a_2 \sinh \frac{s}{c}, a_1 \cos \frac{t}{c}, a_1 \sin \frac{t}{c}, 0, 0 \right).$$

Hence f is umbilical with mean curvature vector field H .

In view of (13), one can write

$$a_1^2 = r^2 \frac{(1 - \lambda_1)}{\lambda_2 - \lambda_1}, \quad a_2^2 = r^2 \frac{(1 - \lambda_2)}{\lambda_2 - \lambda_1}, \quad b_1^2 = r^2 \frac{\lambda_1}{\lambda_2 - \lambda_1}, \quad b_2^2 = r^2 \frac{\lambda_2}{\lambda_2 - \lambda_1}, \quad c^2 = \frac{r^2}{\lambda_2 - \lambda_1},$$

with $0 < \lambda_1 < \lambda_2 < 1$. Then, one can check that the curvature vector γ_i'' of γ_i , $1 \leq i \leq 2$, satisfies

$$(14) \quad \langle \gamma_i'', \gamma_j'' \rangle = k(\lambda_j - \lambda_i)(1 - \lambda_i), \quad 1 \leq i \neq j \leq 2,$$

and that the second Frenet curvature (torsion) of γ_i satisfies

$$(15) \quad \tau_i^2 = -k\lambda_i|\lambda_j - \lambda_i|, \quad 1 \leq i \neq j \leq 2.$$

EXAMPLE 3. Let $\mathbb{R}_2^8 = \mathbb{R}_1^4 \times \mathbb{R}_1^4$ denote Euclidean space of dimension 8 endowed with an inner product of signature $(-, +, +, +, -, +, +, +)$, and let $F: \mathbb{R}^2 \rightarrow \mathbb{R}_2^8$ be given by

$$(16) \quad F(s, t) = \left(a_1 \cosh \frac{s}{c}, a_1 \sinh \frac{s}{c}, a_2 \cos \frac{t}{c}, a_2 \sin \frac{t}{c}, a_3 \cosh \frac{t}{d}, a_3 \sinh \frac{t}{d}, a_4 \cos \frac{s}{d}, a_4 \sin \frac{s}{d} \right),$$

with

$$(17) \quad a_1^2 - a_2^2 = r_1^2, \quad a_3^2 - a_4^2 = r_2^2 \quad \text{and} \quad \frac{a_1^2}{c^2} + \frac{a_4^2}{d^2} = 1 = \frac{a_2^2}{c^2} + \frac{a_3^2}{d^2}.$$

The first pair of relations in (17) implies that $F(\mathbb{R}^2) \subset \mathbb{H}_{k_1}^3 \times \mathbb{H}_{k_2}^3 \subset \mathbb{R}_1^4 \times \mathbb{R}_1^4$, with $k_i = -1/r_i^2$ for $1 \leq i \leq 2$. If $\{e_1, \dots, e_4, f_1, \dots, f_4\}$ is the orthonormal basis of \mathbb{R}_2^8 with respect to which F is given by (16), then the subspaces V_1 and V_2 of \mathbb{R}_2^8 spanned by $\{e_1, e_2, f_3, f_4\}$ and $\{f_1, f_2, e_3, e_4\}$ can also be identified with \mathbb{R}_1^4 , and

$$F = \gamma_1 \times \gamma_2: \mathbb{R} \times \mathbb{R} = \mathbb{R}^2 \rightarrow V_1 \times V_2,$$

where γ_1 and γ_2 are the curves parameterized by

$$\gamma_1(s) = \left(a_1 \cosh \frac{s}{c}, a_1 \sinh \frac{s}{c}, a_4 \cos \frac{s}{d}, a_4 \sin \frac{s}{d} \right)$$

and

$$\gamma_2(t) = \left(a_3 \cosh \frac{t}{d}, a_3 \sinh \frac{t}{d}, a_2 \cos \frac{t}{c}, a_2 \sin \frac{t}{c} \right).$$

In view of the second pair of relations in (17), both γ_1 and γ_2 are unit-speed curves, hence F is an isometric immersion. Since $F(\mathbb{R}^2) \subset \mathbb{H}_{k_1}^3 \times \mathbb{H}_{k_2}^3$, there exists an isometric immersion $f: \mathbb{R}^2 \rightarrow \mathbb{H}_{k_1}^3 \times \mathbb{H}_{k_2}^3$ such that $F = h \circ f$, where $h: \mathbb{H}_{k_1}^3 \times \mathbb{H}_{k_2}^3 \rightarrow \mathbb{R}_2^8$ denotes the inclusion. One can easily check that the second fundamental form of f satisfies

$$\alpha_f \left(\frac{\partial}{\partial s}, \frac{\partial}{\partial t} \right) = 0$$

and

$$\alpha_f \left(\frac{\partial}{\partial s}, \frac{\partial}{\partial s} \right) = H(s, t) = \alpha_f \left(\frac{\partial}{\partial t}, \frac{\partial}{\partial t} \right)$$

where

$$h_*H(s, t) = \frac{k_1 a_1 a_2}{c^2} \left(a_2 \cosh \frac{s}{c}, a_2 \sinh \frac{s}{c}, a_1 \cos \frac{t}{c}, a_1 \sin \frac{t}{c}, 0, 0, 0, 0 \right) + \frac{k_2 a_3 a_4}{d^2} \left(0, 0, 0, 0, a_4 \cosh \frac{t}{d}, a_4 \sinh \frac{t}{d}, a_3 \cos \frac{s}{d}, a_3 \sin \frac{s}{d} \right).$$

It follows that f is umbilical with mean curvature vector field H .

By the conditions in (17), one can write

$$a_1^2 = r_1^2 \frac{(1 - \lambda_1)}{\lambda_2 - \lambda_1}, \quad a_2^2 = r_1^2 \frac{(1 - \lambda_2)}{\lambda_2 - \lambda_1}, \quad a_3^2 = r_2^2 \frac{\lambda_2}{\lambda_2 - \lambda_1}, \quad a_4^2 = r_2^2 \frac{\lambda_1}{\lambda_2 - \lambda_1},$$

$$c^2 = \frac{r_1^2}{\lambda_2 - \lambda_1} \quad \text{and} \quad d^2 = \frac{r_2^2}{\lambda_2 - \lambda_1},$$

with $0 < \lambda_1 < \lambda_2 < 1$. Then, the curvature vector γ_i'' of the curve γ_i , $1 \leq i \leq 2$, satisfies

$$(18) \quad \langle \gamma_i'', \gamma_j'' \rangle = (\lambda_i - \lambda_j)(\kappa \lambda_i - k_1), \quad 1 \leq i \neq j \leq 2, \quad \kappa = k_1 + k_2.$$

If $\kappa \lambda_i - k_1 \neq 0$, one can check that γ_i , $1 \leq i \leq 2$, has constant Frenet curvatures \hat{k}_ℓ^i , $1 \leq \ell \leq 3$, given by

$$(19) \quad (\hat{k}_1^i)^2 = |(\lambda_i - \lambda_j)(\kappa \lambda_i - k_1)|,$$

$$(20) \quad (\hat{k}_2^i)^2 = \frac{\kappa^2 |\lambda_i - \lambda_j| \lambda_i (1 - \lambda_i)}{|\kappa \lambda_i - k_1|}$$

and

$$(21) \quad (\hat{k}_3^i)^2 = \frac{k_1 k_2 |\lambda_i - \lambda_j|}{|\kappa \lambda_i - k_1|}, \quad 1 \leq j \neq i \leq 2.$$

If $\kappa \lambda_i - k_1 = 0$, that is, the curvature vector of γ_i is light-like, then one can check that γ_i has constant Frenet curvatures \tilde{k}_1^i and \tilde{k}_2^i , $1 \leq i \leq 2$ (see Subsection 2.4), given by

$$(22) \quad (\tilde{k}_1^i)^2 = \frac{k_1 k_2 (\kappa \lambda_j - k_1)^2}{\kappa^2}, \quad 1 \leq j \neq i \leq 2,$$

and

$$(23) \quad (\tilde{k}_2^i)^2 = \frac{(k_1 - k_2)^2}{4k_1 k_2}, \quad 1 \leq i \leq 2.$$

It is also easily checked that the isometric immersions in both of the preceding examples have the frame of coordinate vector fields $\{\frac{\partial}{\partial s}, \frac{\partial}{\partial t}\}$ as a frame of principal directions for the associated tensor R , with corresponding eigenvalues λ_1 and λ_2 , respectively. Moreover, they are clearly injective and proper, hence embeddings. Therefore, all surfaces in both families are properly embedded and isometric to the plane.

4. The main step. Umbilical submanifolds of $\mathbb{Q}_{k_1}^{n_1} \times \mathbb{Q}_{k_2}^{n_2}$ were studied in [3] according to the possible structures of the tensor S . When $\ker S = \{0\}$, it was shown that R must be a constant multiple of the identity tensor whenever the dimension of the submanifold is at least three (see [3], Lemma 8.2), which corresponds to case (i) in the statement of Lemma 4 below. We now show that in the surface case the only exceptions are the surfaces of the two families in the preceding section.

LEMMA 4. *Let $f : M^2 \rightarrow \mathbb{Q}_{k_1}^{n_1} \times \mathbb{Q}_{k_2}^{n_2}$, $k_1 + k_2 \neq 0$, be an umbilical isometric immersion. Assume that $\ker S = \{0\}$ at some point $x \in M^2$. Then one of the following holds:*

- (i) *there exist umbilical isometric immersions $f_i : M^2 \rightarrow \mathbb{Q}_{\tilde{k}_i}^{n_i}$, $1 \leq i \leq 2$, with $\tilde{k}_1 = k_1 \cos^2 \theta$ and $\tilde{k}_2 = k_2 \sin^2 \theta$ for some $\theta \in (0, \pi/2)$, such that $f = (\cos \theta f_1, \sin \theta f_2)$;*
- (ii) *after interchanging the factors, if necessary, we have $k_2 = 0$, $n_1 \geq 3$, $n_2 \geq 2$ and $f = j \circ \tilde{f}$, where $j : \mathbb{Q}_{k_1}^3 \times \mathbb{R}^2 \rightarrow \mathbb{Q}_{k_1}^{n_1} \times \mathbb{R}^{n_2}$ and $\tilde{f} : M^2 \rightarrow \mathbb{Q}_{k_1}^3 \times \mathbb{R}^2$ are isometric immersions such that j is totally geodesic and $\tilde{f}(M^2)$ is an open subset of a surface as in Example 2;*
- (iii) *$k_i < 0$ and $n_i \geq 3$, $1 \leq i \leq 2$, and $f = j \circ \tilde{f}$, where $j : \mathbb{Q}_{k_1}^3 \times \mathbb{Q}_{k_2}^3 \rightarrow \mathbb{Q}_{k_1}^{n_1} \times \mathbb{Q}_{k_2}^{n_2}$ and $\tilde{f} : M^2 \rightarrow \mathbb{Q}_{k_1}^3 \times \mathbb{Q}_{k_2}^3$ are isometric immersions such that j is totally geodesic and $\tilde{f}(M^2)$ is an open subset of a surface as in Example 3.*

PROOF. Let λ_1 and λ_2 be the eigenvalues of R . If $\lambda_1 = \lambda_2$ on M then f is as in (i) by Proposition 5.2 of [3]. Now assume that $\lambda_1 \neq \lambda_2$ at x and let $\mathcal{U} \subset \mathcal{M}$ be the maximal connected open neighborhood of x where $\ker S = \{0\}$ and $\lambda_1 \neq \lambda_2$. In particular, λ_1 and λ_2 are differentiable on \mathcal{U} .

Fix an orthonormal frame $\{X_1, X_2\}$ of eigenvectors of R , with X_i associated to λ_i , and define $\xi_i := SX_i$ for $i = 1, 2$. Thus, from (2) we have

$$(24) \quad \langle \xi_i, \xi_j \rangle = \langle S^t SX_i, X_j \rangle = \delta_{ij} \lambda_i (1 - \lambda_i)$$

and

$$(25) \quad T \xi_i = T S X_i = (1 - \lambda_i) \xi_i$$

for $i, j = 1, 2$. We can write equations (6)–(8) in the frames $\{X_1, X_2\}$ and $\{\xi_1, \xi_2\}$, in terms of the Gaussian curvature K of M^2 and the mean curvature vector H of f , as

$$(26) \quad K = k_1(1 - \lambda_1)(1 - \lambda_2) + k_2 \lambda_1 \lambda_2 + |H|^2,$$

$$(27) \quad \nabla_{X_i}^\perp H = (\kappa \lambda_j - k_1) \xi_i, \quad 1 \leq i \neq j \leq 2,$$

and

$$(28) \quad \mathcal{R}^\perp(X_1, X_2) = \kappa(\xi_1 \wedge \xi_2),$$

whereas equations (3)–(5) become

$$(29) \quad (\nabla_{X_i} R) X_j = \langle \xi_j, H \rangle X_i + \delta_{ij} S^t H,$$

$$(30) \quad (\nabla_{X_i} S) X_j = \delta_{ij} (T - \lambda_j I) H$$

and

$$(31) \quad (\nabla_{X_i} T) \xi = -\langle \xi, H \rangle \xi_i - \langle \xi, \xi_i \rangle H$$

for $i, j = 1, 2$ and all $\xi \in \Gamma(N_f M^2)$. Define the Christoffel symbols Γ_{11}^2 and Γ_{22}^1 by

$$(32) \quad \nabla_{X_1} X_1 = \Gamma_{11}^2 X_2 \quad \text{and} \quad \nabla_{X_2} X_2 = \Gamma_{22}^1 X_1.$$

Substituting

$$\begin{aligned} (\nabla_{X_i} R) X_j &= \nabla_{X_i} R X_j - R \nabla_{X_i} X_j \\ &= X_i(\lambda_j) X_j + (\lambda_j I - R) \nabla_{X_i} X_j \end{aligned}$$

into (29) yields

$$(33) \quad X_i(\lambda_j) = \delta_{ij} 2 \langle \xi_i, H \rangle$$

and

$$(34) \quad \langle \xi_i, H \rangle = (\lambda_j - \lambda_i) \Gamma_{jj}^i, \quad 1 \leq i \neq j \leq 2.$$

On the other hand, from (30) we get

$$(35) \quad \nabla_{X_i}^\perp \xi_j = -\Gamma_{ii}^j \xi_i, \quad 1 \leq i \neq j \leq 2.$$

Using (27), (32), (33) and (35) we obtain

$$\begin{aligned} \mathcal{R}^\perp(X_1, X_2) H &= \nabla_{X_1}^\perp \nabla_{X_2}^\perp H - \nabla_{X_2}^\perp \nabla_{X_1}^\perp H - \nabla_{[X_1, X_2]}^\perp H \\ &= \nabla_{X_1}^\perp (\kappa \lambda_1 - k_1) \xi_2 - \nabla_{X_2}^\perp (\kappa \lambda_2 - k_1) \xi_1 + (\kappa \lambda_2 - k_1) \Gamma_{11}^2 \xi_1 \\ &\quad - (\kappa \lambda_1 - k_1) \Gamma_{22}^1 \xi_2 \\ &= \kappa X_1(\lambda_1) \xi_2 + (\kappa \lambda_1 - k_1) \nabla_{X_1}^\perp \xi_2 - \kappa X_2(\lambda_2) \xi_1 - (\kappa \lambda_2 - k_1) \nabla_{X_2}^\perp \xi_1 \\ &\quad + (\kappa \lambda_2 - k_1) \Gamma_{11}^2 \xi_1 - (\kappa \lambda_1 - k_1) \Gamma_{22}^1 \xi_2 \\ &= 2\kappa \langle \xi_1, H \rangle \xi_2 - (\kappa \lambda_1 - k_1) \Gamma_{11}^2 \xi_1 - 2\kappa \langle \xi_2, H \rangle \xi_1 + (\kappa \lambda_2 - k_1) \Gamma_{22}^1 \xi_2 \\ &\quad + (\kappa \lambda_2 - k_1) \Gamma_{11}^2 \xi_1 - (\kappa \lambda_1 - k_1) \Gamma_{22}^1 \xi_2 \\ &= -\kappa (2 \langle \xi_2, H \rangle + (\lambda_1 - \lambda_2) \Gamma_{11}^2) \xi_1 + \kappa (2 \langle \xi_1, H \rangle + (\lambda_2 - \lambda_1) \Gamma_{22}^1) \xi_2. \end{aligned}$$

In view of (34), the above equation becomes

$$\mathcal{R}^\perp(X_1, X_2) H = -3\kappa (\langle \xi_2, H \rangle \xi_1 - \langle \xi_1, H \rangle \xi_2).$$

Comparing the preceding equation with

$$\mathcal{R}^\perp(X_1, X_2)H = \kappa(\langle \xi_2, H \rangle \xi_1 - \langle \xi_1, H \rangle \xi_2),$$

which follows from (28), and using that $\kappa \neq 0$, we get $\langle \xi_1, H \rangle = 0 = \langle \xi_2, H \rangle$, i.e.,

$$(36) \quad H \in \Gamma(S(TM)^\perp).$$

In particular, we obtain from (33) that λ_1 and λ_2 assume constant values in $(0, 1)$ everywhere on \mathcal{U} . If \mathcal{U} were a proper subset of M^2 , then λ_1 and λ_2 would assume the same values on the boundary of \mathcal{U} , hence $\lambda_i(1 - \lambda_i) \neq 0$ on an open connected neighborhood of $\bar{\mathcal{U}}$, $1 \leq i \leq 2$, contradicting the maximality of \mathcal{U} as an open connected neighborhood of x where $\ker S = \{0\}$ and $\lambda_1 \neq \lambda_2$. It follows that $\mathcal{U} = M^2$.

We obtain from (34) and (36) that $\Gamma_{11}^2 = 0 = \Gamma_{22}^1$. In particular, we have $K = 0$ everywhere, and then (26) gives

$$(37) \quad |H|^2 = -k_1(1 - \lambda_1)(1 - \lambda_2) - k_2\lambda_1\lambda_2.$$

Set $\xi = H$ in (31). By using (25), (27) and (37), we obtain

$$(38) \quad \nabla_{X_i}^\perp TH = k_2\lambda_j\xi_i, \quad 1 \leq i \neq j \leq 2,$$

and similarly

$$(39) \quad \nabla_{X_i}^\perp (I - T)H = -(1 - \lambda_j)k_1\xi_i, \quad 1 \leq i \neq j \leq 2.$$

In particular, bearing in mind (36) and the fact that T leaves $S(TM)$ invariant, as follows from the second equation in (2), we obtain that both TH and $(I - T)H$ have constant length on M^2 , hence either $TH = 0$, $TH = H$ or both TH and $(I - T)H$ are nonzero everywhere. Therefore $L_1 = U \cap \{H\}^\perp = U \cap N_1^\perp$ and $L_2 = V \cap \{H\}^\perp = V \cap N_1^\perp$ have constant dimensions on M^2 , which are, accordingly, $(\text{rank } U - 1, \text{rank } V)$, $(\text{rank } U, \text{rank } V - 1)$ or $(\text{rank } U - 1, \text{rank } V - 1)$. Moreover, equations (27) and (36) imply that $\nabla_{T^*M}^\perp L_i \subset \{H\}^\perp$ for $i = 1, 2$. Hence, the assumptions of Proposition 1 are satisfied, and we conclude that there are three corresponding possibilities for the pairs (n_1, n_2) of *substantial* values of n_1 and n_2 : $(3, 2)$, $(2, 3)$ and $(3, 3)$.

We first consider the case $(n_1, n_2) = (3, 2)$. This is the case in which $TH = 0$, and hence $k_2 = 0$ by (38). Thus we have $k_1 < 0$ from (37), and we may assume that f takes values in $\mathbb{H}_k^3 \times \mathbb{R}^2$, with $k = k_1 < 0$.

Set $F = h \circ f$, where $h: \mathbb{H}_k^3 \times \mathbb{R}^2 \rightarrow \mathbb{R}_1^6$ denotes the inclusion. By (9), the second fundamental form of F is given by

$$\alpha_F(X, Y) = \langle X, Y \rangle h_*H + \frac{1}{r} \langle (I - R)X, Y \rangle \nu,$$

where $r = (-k)^{-1/2}$ and $\nu = \frac{1}{r} \tilde{\pi}_1 \circ F$. Therefore

$$(40) \quad \alpha_F(X_i, X_j) = \delta_{ij} \left(h_*H + \frac{1}{r} (1 - \lambda_i) \nu \right) := \delta_{ij} Z_i = \tilde{\nabla}_{X_j} F_*X_i, \quad 1 \leq i, j \leq 2.$$

Notice that

$$\langle Z_1, Z_2 \rangle = |H|^2 + k(1 - \lambda_1)(1 - \lambda_2) = 0$$

by (37), and that

$$(41) \quad \langle Z_i, Z_i \rangle = k(\lambda_j - \lambda_i)(1 - \lambda_i), \quad 1 \leq i \neq j \leq 2.$$

Moreover, since

$$\tilde{\pi}_2(h_*H) = h_*\pi_2H = h_*(f_*S^tH + TH) = 0,$$

it follows that

$$\tilde{\pi}_2Z_i = 0, \quad 1 \leq i \leq 2.$$

Using (27), we have

$$\begin{aligned} \tilde{\nabla}_{X_i}h_*H &= h_*\hat{\nabla}_{X_i}H + \alpha_h(f_*X_i, H) \\ &= -F_*A_H^fX_i + h_*\nabla_{X_i}^\perp H + \frac{1}{r}\langle \pi_1f_*X_i, H \rangle \nu \\ &= -|H|^2F_*X_i - k(1 - \lambda_j)h_*\xi_i + \frac{1}{r}\langle f_*(I - R)X_i - SX_i, H \rangle \nu \\ &= k(1 - \lambda_j)((1 - \lambda_i)F_*X_i - h_*\xi_i), \quad 1 \leq i \neq j \leq 2. \end{aligned}$$

On the other hand, by (10) we have

$$\tilde{\nabla}_{X_i}\nu = \frac{1}{r}(F_*(I - R)X_i - h_*SX_i) = \frac{1}{r}((1 - \lambda_i)F_*X_i - h_*\xi_i).$$

Therefore

$$(42) \quad \tilde{\nabla}_{X_i}Z_j = 0, \quad \text{if } i \neq j,$$

and

$$(43) \quad \tilde{\nabla}_{X_i}Z_i = k(\lambda_i - \lambda_j)((1 - \lambda_i)F_*X_i - h_*\xi_i), \quad 1 \leq i \neq j \leq 2.$$

Also, using that

$$\nabla_{X_i}^\perp \xi_i = -\frac{1}{|H|^2}\langle \nabla_{X_i}H, \xi_i \rangle H = -\lambda_i H,$$

as follows from (24), (27) and (37), we obtain that

$$\begin{aligned} \tilde{\nabla}_{X_i}h_*\xi_j &= h_*\hat{\nabla}_{X_i}\xi_j + \alpha_h(f_*X_i, \xi_j) \\ &= -F_*A_{\xi_j}^fX_i + h_*\nabla_{X_i}^\perp \xi_j + \frac{1}{r}\langle \pi_1f_*X_i, \xi_j \rangle \nu \\ (44) \quad &= -\delta_{ij}\lambda_i Z_i, \quad 1 \leq i, j \leq 2. \end{aligned}$$

It follows from (40), (42), (43) and (44) that the subspaces $V_i = \text{span}\{F_*X_i, Z_i, h_*\xi_i\}$, $1 \leq i \leq 2$, are constant. Moreover, they are orthogonal to each other, hence \mathbb{R}_1^6 splits orthogonally as $\mathbb{R}_1^6 = V_1 \oplus V_2$.

Since $\Gamma_{11}^2 = \Gamma_{22}^1 = 0$, for each $x \in M^2$ there exists an isometry $\psi: W = I_1 \times I_2 \rightarrow U_x$ of a product of open intervals $I_j \subset \mathbb{R}$, $1 \leq j \leq 2$, onto an open neighborhood of x , such that $\psi_*\frac{\partial}{\partial s} = X_1$ and $\psi_*\frac{\partial}{\partial t} = X_2$, where s and t are the standard coordinates on I_1 and I_2 , respectively. Write $g = F \circ \psi$. In terms of the coordinates (s, t) , the fact that $\alpha_F(X_1, X_2) = 0$ translates into

$$\frac{\partial^2 g}{\partial s \partial t} = 0,$$

which implies that there exist smooth curves $\gamma_1 : I_1 \rightarrow V_1$ and $\gamma_2 : I_2 \rightarrow V_2$ such that $g = \gamma_1 \times \gamma_2$. By (40), (43) and (44), each γ_i is a helix in V_i with curvature vector $\gamma_i'' = Z_i$ and binormal vector $h_*(\xi_i/|\xi_i|)$, $1 \leq i \leq 2$. It follows from (41) that (14) holds for γ_i , whereas (41) and (44) imply that the second Frenet curvature of γ_i satisfies (15), i.e.,

$$\tau_i^2 = \frac{\lambda_i^2 |\langle Z_i, Z_i \rangle|}{\langle \xi_i, \xi_i \rangle} = -k\lambda_i |\lambda_j - \lambda_i|, \quad 1 \leq i \neq j \leq 2.$$

Therefore, the helices γ_1 and γ_2 are precisely, up to congruence, those given in Example 2. Moreover, since the curvature vector Z_i along γ_i spans a two-dimensional subspace of V_i orthogonal to the axis of γ_i and $\tilde{\pi}_2 Z_i = Z_i$, $1 \leq i \leq 2$, it follows that the subspace \mathbb{R}^2 in the orthogonal decomposition $\mathbb{R}^6 = \mathbb{R}^4 \oplus \mathbb{R}^2$ adapted to $\mathbb{H}_k^3 \times \mathbb{R}^2$ is spanned by the axes of γ_1 and γ_2 . We conclude that g is (the restriction to W of) an isometric immersion as in Example 2.

We have shown that, for each $x \in M^2$, there exists an open neighborhood U_x of x such that $f(U_x)$ is contained in a surface as in Example 2 in a totally geodesic $\mathbb{Q}_{k_1}^3 \times \mathbb{R}^2 \subset \mathbb{Q}_{k_1}^{n_1} \times \mathbb{R}^{n_2}$. A standard connectedness argument now shows that f is as in the statement.

The case $(n_1, n_2) = (2, 3)$ is entirely similar and leads to the same conclusion with the factors interchanged. Let us consider the case $(n_1, n_2) = (3, 3)$, so we may now assume that f takes values in $\mathbb{Q}_{k_1}^3 \times \mathbb{Q}_{k_2}^3$. Here both TH and $(I - T)H$ are nonzero everywhere, and we can choose unit vector fields $\xi_3 \in \ker T$, $\xi_4 \in \ker(I - T)$ and write $H = \rho_3 \xi_3 + \rho_4 \xi_4$, where $\rho_k = \langle \xi_k, H \rangle \neq 0$ for $k = 3, 4$. Applying (31) to $\xi = \xi_k$, with $k = 3, 4$, we get

$$T \nabla_{X_i}^\perp \xi_3 = \rho_3 \xi_i \quad \text{and} \quad (I - T) \nabla_{X_i}^\perp \xi_4 = -\rho_4 \xi_i$$

for $i = 1, 2$. Therefore, for $i = 1, 2$ we obtain

$$(45) \quad \nabla_{X_i}^\perp \xi_3 = \frac{\rho_3}{1 - \lambda_i} \xi_i \quad \text{and} \quad \nabla_{X_i}^\perp \xi_4 = -\frac{\rho_4}{\lambda_i} \xi_i.$$

Using (24), the preceding equations yield

$$(46) \quad \nabla_{X_i}^\perp \xi_i = -\lambda_i \rho_3 \xi_3 + (1 - \lambda_i) \rho_4 \xi_4, \quad 1 \leq i \leq 2.$$

On the other hand, we have

$$(47) \quad (I - T)H = \rho_3 \xi_3 \quad \text{and} \quad TH = \rho_4 \xi_4.$$

Thus, combining (38), (39) and (47) we get

$$(48) \quad \rho_3^2 = -k_1(1 - \lambda_1)(1 - \lambda_2) \quad \text{and} \quad \rho_4^2 = -k_2 \lambda_1 \lambda_2.$$

In particular, we must have $k_1, k_2 < 0$, so f takes values in $\mathbb{H}_{k_1}^3 \times \mathbb{H}_{k_2}^3$.

Set $F = h \circ f$, where $h : \mathbb{H}_{k_1}^3 \times \mathbb{H}_{k_2}^3 \rightarrow \mathbb{R}_1^4 \times \mathbb{R}_1^4 = \mathbb{R}_2^8$ denotes the inclusion. By (9), the second fundamental form of F is given by

$$\alpha_F(X, Y) = \langle X, Y \rangle h_* H + \frac{1}{r_1} \langle (I - R)X, Y \rangle v_1 + \frac{1}{r_2} \langle RX, Y \rangle v_2,$$

where $r_i = (-k_i)^{-1/2}$ and $v_i = \frac{1}{r_i} \tilde{\pi}_i \circ F$, $1 \leq i \leq 2$. Therefore

$$(49) \quad \alpha_F(X_i, X_j) = \delta_{ij} \left(h_* H + \frac{1}{r_1} (1 - \lambda_i) v_1 + \frac{1}{r_2} \lambda_i v_2 \right) := \delta_{ij} Z_i = \tilde{\nabla}_{X_j} F_* X_i, \quad 1 \leq i \leq 2.$$

Notice that

$$\langle Z_i, Z_j \rangle = |H|^2 + k_1(1 - \lambda_i)(1 - \lambda_j) + k_2\lambda_i\lambda_j, \quad 1 \leq i, j \leq 2.$$

It follows from (37) that

$$\langle Z_1, Z_2 \rangle = 0$$

and

$$(50) \quad \langle Z_i, Z_i \rangle = (\lambda_i - \lambda_j)(\kappa\lambda_i - k_1), \quad 1 \leq i \neq j \leq 2.$$

Using (27), we obtain

$$\begin{aligned} \tilde{\nabla}_{X_i} h_* H &= h_* \hat{\nabla}_{X_i} H + \alpha_h(f_* X_i, H) \\ &= -F_* A_H^f X_i + h_* \nabla_{X_i}^\perp H \\ &= -|H|^2 F_* X_i + (\kappa\lambda_j - k_1) h_* \xi_i. \end{aligned}$$

On the other hand, by (10) and (11) we have

$$\tilde{\nabla}_{X_i} v_1 = \frac{1}{r_1} (F_* (I - R) X_i - h_* S X_i) = \frac{1}{r_1} ((1 - \lambda_i) F_* X_i - h_* \xi_i)$$

and

$$\tilde{\nabla}_{X_i} v_2 = \frac{1}{r_2} (F_* R X_i + h_* S X_i) = \frac{1}{r_2} (\lambda_i F_* X_i + h_* \xi_i).$$

Using (37), it follows that

$$\tilde{\nabla}_{X_i} Z_j = 0, \quad \text{if } i \neq j,$$

whereas

$$(51) \quad \tilde{\nabla}_{X_i} Z_i = -\langle Z_i, Z_i \rangle F_* X_i + \kappa(\lambda_j - \lambda_i) h_* \xi_i, \quad 1 \leq i \neq j \leq 2.$$

Also,

$$\begin{aligned} \tilde{\nabla}_{X_i} h_* \xi_j &= h_* \hat{\nabla}_{X_i} \xi_j + \alpha_h(f_* X_i, \xi_j) \\ &= -F_* A_{\xi_j}^f X_i + h_* \nabla_{X_i}^\perp \xi_j + \frac{1}{r_1} \langle \pi_1 f_* X_i, \xi_j \rangle v_1 + \frac{1}{r_2} \langle \pi_2 f_* X_i, \xi_j \rangle v_2 \\ (52) \quad &= \delta_{ij} \left(-\lambda_i Z_i + \rho_4 h_* \xi_4 + \frac{\lambda_i}{r_2} v_2 \right), \end{aligned}$$

where we have used (46).

If $\kappa\lambda_i - k_1 \neq 0$, that is, $\langle Z_i, Z_i \rangle \neq 0$, define

$$W_i = \tilde{\nabla}_{X_i} h_* \xi_i - \frac{\langle \tilde{\nabla}_{X_i} h_* \xi_i, Z_i \rangle}{\langle Z_i, Z_i \rangle} Z_i = \frac{-k_2\lambda_i}{\kappa\lambda_i - k_1} Z_i + \rho_4 h_* \xi_4 + \frac{\lambda_i}{r_2} v_2, \quad 1 \leq i \leq 2.$$

Then the vectors $F_* X_i, Z_i, h_* \xi_i$ and W_i are pairwise orthogonal and the subspaces $V_i = \text{span}\{F_* X_i, Z_i, h_* \xi_i, W_i\}, 1 \leq i \leq 2$, are orthogonal to each other. Using the second equations in (48) and (45), we obtain that $\tilde{\nabla}_{X_i} W_j = 0$ and

$$(53) \quad \tilde{\nabla}_{X_i} W_i = \frac{k_1 k_2 (\lambda_i - \lambda_j)}{\kappa\lambda_i - k_1} h_* \xi_i, \quad 1 \leq i \neq j \leq 2.$$

It follows that the subspaces V_1 and V_2 are constant, and that \mathbb{R}_2^8 also splits orthogonally as $\mathbb{R}_2^8 = V_1 \oplus V_2$.

If $\kappa\lambda_i - k_1 = 0$, define

$$\zeta_i = \frac{\kappa}{2k_1k_2(\kappa\lambda_j - k_1)}(-2\kappa\tilde{\nabla}_{X_i}h_*\xi_i + (k_2 - k_1)Z_i), \quad 1 \leq i \neq j \leq 2.$$

Then $\langle \zeta_i, \zeta_i \rangle = 0$, $\langle \zeta_i, Z_i \rangle = 1$ and $\zeta_i \in \text{span}\{F_*X_i, h_*\xi_i\}^\perp$. Moreover, the subspaces $V_i = \text{span}\{F_*X_i, Z_i, h_*\xi_i, \zeta_i\}$, $1 \leq i \leq 2$, are orthogonal to each other. Furthermore, since

$$(54) \quad \tilde{\nabla}_{X_i}\zeta_i = \frac{k_1^2 - k_2^2}{2k_1k_2}h_*\xi_i,$$

it follows that V_1 and V_2 are constant and that \mathbb{R}_2^8 also splits orthogonally as $\mathbb{R}_2^8 = V_1 \oplus V_2$.

Since $\Gamma_{11}^2 = \Gamma_{22}^1 = 0$, for each $x \in M^2$ there exists an isometry $\psi: W = I_1 \times I_2 \rightarrow U_x$ of a product of open intervals $I_j \subset \mathbb{R}$, $1 \leq j \leq 2$, onto a neighborhood of x , such that $\psi_*\frac{\partial}{\partial s} = X_1$ and $\psi_*\frac{\partial}{\partial t} = X_2$, where s and t are the standard coordinates on I_1 and I_2 , respectively. Write $g = F \circ \psi$. In terms of the coordinates (s, t) , the fact that $\alpha_F(X_1, X_2) = 0$ translates into

$$\frac{\partial^2 g}{\partial s \partial t} = 0,$$

which implies that there exist smooth curves $\gamma_1: I_1 \rightarrow V_1$ and $\gamma_2: I_2 \rightarrow V_2$ such that $g = \gamma_1 \times \gamma_2$.

If $\kappa\lambda_i - k_1 \neq 0$, it follows from (49), (51), (52) and (53) that γ_i is a unit-speed space like curve in V_i with constant Frenet curvatures \hat{k}_ℓ^i , $1 \leq \ell \leq 3$, and Frenet frame $\{F_*X_i, \hat{Z}_i, h_*\hat{\xi}_i, \hat{W}_i\}$, where \hat{Z}_i , $\hat{\xi}_i$ and \hat{W}_i denote the unit vectors in the direction of Z_i , ξ_i and W_i , respectively. Moreover, by (49) and (50) we have

$$(\hat{k}_1^i)^2 = |\langle Z_i, Z_i \rangle| = |(\lambda_i - \lambda_j)(\kappa\lambda_i - k_1)|,$$

whereas from (43) and (53) we obtain, respectively, that

$$(\hat{k}_2^i)^2 = \frac{\kappa^2(\lambda_j - \lambda_i)^2 \langle \xi_i, \xi_i \rangle}{|\langle Z_i, Z_i \rangle|} = \frac{\kappa^2|\lambda_j - \lambda_i|\lambda_i(1 - \lambda_i)}{|\kappa\lambda_i - k_1|}$$

and

$$(\hat{k}_3^i)^2 = \frac{k_1^2k_2^2(\lambda_i - \lambda_j)^2 \langle \xi_i, \xi_i \rangle}{(\kappa\lambda_i - k_1)^2 |\langle W_i, W_i \rangle|} = \frac{k_1k_2|\lambda_i - \lambda_j|}{|\kappa\lambda_i - k_1|}, \quad 1 \leq j \neq i \leq 2.$$

If $\kappa\lambda_i - k_1 = 0$, it follows from (49), (51), (52) and (54) that γ_i is a unit-speed space like curve in V_i with light-like curvature vector, constant Frenet curvatures \tilde{k}_ℓ^i , $1 \leq \ell \leq 2$, and Frenet frame $\{F_*X_i, Z_i, h_*\hat{\xi}_i, \zeta_i\}$, where $\hat{\xi}_i$ is the unit vector in the direction of ξ_i . Moreover, from (51) we obtain that

$$(\tilde{k}_1^i)^2 = \frac{k_1k_2(\kappa\lambda_j - k_1)^2}{\kappa^2},$$

whereas from (54) it follows that

$$(\tilde{k}_2^i)^2 = \langle \xi_i, \xi_i \rangle \frac{(k_1^2 - k_2^2)^2}{4k_1^2k_2^2} = \frac{(k_1 - k_2)^2}{4k_1k_2}.$$

Comparing with (19), (20) and (21) in the first case, and with (22) and (23) in the second, we see that γ_1 and γ_2 are precisely, up to congruence, the curves given in Example 3.

Now observe that

$$\tilde{\pi}_2 F_* \xi_i = h_* \pi_2 f_* \xi_i = h_*(f_* \xi_i + SX_i) = \lambda_i F_* X_i + h_* \xi_i,$$

whereas

$$\tilde{\pi}_2 h_* \xi_i = h_* \pi_2 \xi_i = h_*(f_* S^t \xi_i + T \xi_i) = (1 - \lambda_i)(\lambda_i F_* X_i + h_* \xi_i),$$

where we have used that

$$S^t \xi_i = S^t SX_i = R(I - R)X_i = \lambda_i(1 - \lambda_i)X_i$$

and

$$T \xi_i = TSX_i = S(I - R)X_i = (1 - \lambda_i)SX_i = (1 - \lambda_i)\xi_i.$$

On the other hand,

$$\tilde{\pi}_2 Z_i = h_* \pi_2 H + \frac{\lambda_i}{r_2} \pi_2 \nu_2 = \rho_4 h_* \xi_4 + \frac{\lambda_i}{r_2} \nu_2.$$

Since

$$\tilde{\pi}_2 h_* \xi_4 = h_* \pi_2 \xi_4 = h_*(f_* S^t \xi_4 + T \xi_4) = h_* \xi_4,$$

we obtain that

$$\tilde{\pi}_2 \left(\rho_4 h_* \xi_4 + \frac{\lambda_i}{r_2} \nu_2 \right) = \rho_4 h_* \xi_4 + \frac{\lambda_i}{r_2} \nu_2.$$

If $\langle Z_i, Z_i \rangle \neq 0$, it follows that $\tilde{\pi}_2 W_i$ and $\tilde{\pi}_2 Z_i$ are colinear. Similarly, $\tilde{\pi}_2 \zeta_i$ and $\tilde{\pi}_2 Z_i$ are colinear if $\langle Z_i, Z_i \rangle = 0$. It follows that $\tilde{\pi}_2(V_i)$ is spanned by

$$\lambda_i F_* X_i + h_* \xi_i \quad \text{and} \quad \rho_4 h_* \xi_4 + \frac{\lambda_i}{r_2} \nu_2.$$

Therefore, the subspaces $\tilde{\pi}_2(V_1)$ and $\tilde{\pi}_2(V_2)$ (and hence also $\tilde{\pi}_1(V_1)$ and $\tilde{\pi}_1(V_2)$) are mutually orthogonal, thus the first (respectively, second) factor \mathbb{R}_1^4 in the decomposition $\mathbb{R}_1^4 \times \mathbb{R}_1^4$ adapted to the product $\mathbb{H}_{k_1}^3 \times \mathbb{H}_{k_2}^3$ splits orthogonally as $\mathbb{R}_1^4 = \tilde{\pi}_1(V_1) \oplus \tilde{\pi}_1(V_2)$ (respectively, $\mathbb{R}_1^4 = \tilde{\pi}_2(V_1) \oplus \tilde{\pi}_2(V_2)$). We conclude that g is (the restriction to W of) an isometric immersion as in Example 3, and the conclusion follows as in the preceding case. \square

5. The main result. We are now in a position to state and prove our main result.

THEOREM 5. *Let $f: M^2 \rightarrow \mathbb{Q}_{k_1}^{n_1} \times \mathbb{Q}_{k_2}^{n_2}$, $k_1 + k_2 \neq 0$, be an umbilical non totally geodesic isometric immersion. Then one of the following possibilities holds:*

- (i) *f is an umbilical isometric immersion into a slice of $\mathbb{Q}_{k_1}^{n_1} \times \mathbb{Q}_{k_2}^{n_2}$;*
- (ii) *there exist umbilical isometric immersions $f_i: M^2 \rightarrow \mathbb{Q}_{k_i}^{n_i}$, $1 \leq i \leq 2$, with $\tilde{k}_1 = k_1 \cos^2 \theta$ and $\tilde{k}_2 = k_2 \sin^2 \theta$ for some $\theta \in (0, \pi/2)$, such that $f = (\cos \theta f_1, \sin \theta f_2)$;*

- (iii) after interchanging the factors, if necessary, we have $k_2 = 0$, $n_1 \geq 3$, $n_2 \geq 2$ and $f = j \circ \tilde{f}$, where $j: \mathbb{Q}_{k_1}^3 \times \mathbb{R}^2 \rightarrow \mathbb{Q}_{k_1}^{n_1} \times \mathbb{R}^{n_2}$ and $\tilde{f}: M^2 \rightarrow \mathbb{Q}_{k_1}^3 \times \mathbb{R}^2$ are isometric immersions such that j is totally geodesic and $\tilde{f}(M^2)$ is an open subset of a surface as in Example 2;
- (iv) $k_i < 0$ and $n_i \geq 3$, $1 \leq i \leq 2$, and $f = j \circ \tilde{f}$, where $j: \mathbb{Q}_{k_1}^3 \times \mathbb{Q}_{k_2}^3 \rightarrow \mathbb{Q}_{k_1}^{n_1} \times \mathbb{Q}_{k_2}^{n_2}$ and $\tilde{f}: M^2 \rightarrow \mathbb{Q}_{k_1}^3 \times \mathbb{Q}_{k_2}^3$ are isometric immersions such that j is totally geodesic and $\tilde{f}(M^2)$ is an open subset of a surface as in Example 3;
- (v) after possibly reordering the factors, we have $k_1 > 0$ (respectively, $k_1 \leq 0$) and $f \circ \tilde{\Pi} = j \circ \Pi \circ \tilde{f}$ (respectively, $f = j \circ \Pi \circ \tilde{f}$), where $\tilde{\Pi}: \tilde{M}^2 \rightarrow M^2$ is the universal covering of M^2 , $\tilde{f}: \tilde{M}^2 \rightarrow \mathbb{R} \times \mathbb{Q}_{k_2}^{2+\delta}$ (respectively, $\tilde{f}: M^2 \rightarrow \mathbb{R} \times \mathbb{Q}_{k_2}^{2+\delta}$) is an umbilical isometric immersion with $\delta \in \{0, 1\}$, $j: \mathbb{Q}_{k_1}^1 \times \mathbb{Q}_{k_2}^{2+\delta} \rightarrow \mathbb{Q}_{k_1}^{n_1} \times \mathbb{Q}_{k_2}^{n_2}$ is totally geodesic and $\Pi: \mathbb{R} \times \mathbb{Q}_{k_2}^{2+\delta} \rightarrow \mathbb{Q}_{k_1}^1 \times \mathbb{Q}_{k_2}^{2+\delta}$ is a locally isometric covering map (respectively, isometry).

PROOF. If S vanishes everywhere on M^2 , then f is as in (i) by Lemma 8.1 in [3]. If $\ker S = \{0\}$ at some point $x \in M^2$, then f is as in (ii), (iii) or (iv) by Lemma 4. Then, we are left with the case in which there is an open subset $\mathcal{U} \subset M^2$ where $\ker S$ has rank one. In this case, the argument in the proof of Theorem 1.4 of [3] applies and shows that f is as in (v). \square

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