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Continuous Linear Transformations of n-Convex Functions

1. Introduction. In a recent paper [1] Bojanic and Roulier obtained a result on the uniform approximation of n-convex functions by n-convex splines and, as an application, proved necessary and sufficient conditions that a continuous linear operator transforms every continuous, n-convex function into an r-convex function.

Their proof is based on the fact that the Bernstein polynomials of a continuous, n-convex function  $F$  (which converges uniformly to  $F$ ) are themselves n-convex.

In this paper we express the result of Bojanic and Roulier in a slightly different notation and terminology and then we take a similar approach, after obtaining various decompositions of an n-convex function, to obtain new sufficient conditions that a continuous linear operator transform every continuous n-convex function into an r-convex function.

2. n-convex functions and n-convex splines. Let  $F(x)$  be defined on  $[a,b]$ . The  $n^{\text{th}}$  divided difference of  $F$  is defined by

$$V_n(F; x_k) \equiv \sum_{k=0}^n F(x_k) / w_n'(x_k),$$

where

$$a \leq x_0 < x_1 < \dots < x_{n-1} < x_n \leq b$$

and

$$w_n(x) = (x-x_0)(x-x_1)\dots(x-x_n).$$

Definition 2.1. If  $V_n(F; x_k) \geq 0$  for all choices of  $(n+1)$  distinct points  $x_0, x_1, \dots, x_n$  in  $[a, b]$ , then  $F$  is said to be  $n$ -convex on  $[a, b]$ .

The set of all continuous,  $n$ -convex functions on  $[a, b]$  will be denoted by  $K_n[a, b]$ , and the set of all functions on  $[a, b]$ , by  $L[a, b]$ .

It is easy to see that all polynomials of degree  $(n-1)$  and those polynomials of degree  $n$  with positive leading coefficient are  $n$ -convex.

Some important properties of  $n$ -convex functions are contained in the following theorem.

Theorem 2.1. If  $F$  is  $n$ -convex on  $[a, b]$ , then

(a)  $F^r(x)$  exists and is continuous,  $1 \leq r \leq n-2$ ,

$x \in (a, b)$ ;

(b)  $F^{(n-1)}(x)$  exists except possibly on a countable set in  $(a, b)$  and is increasing;

(c) If  $x \in [\alpha, \beta] \subset (a, b)$ ,  $F(x)$  is the  $(n-1)^{\text{th}}$  integral of  $F^{(n-1)}(x)$ , i.e.

$$F(x) = \frac{1}{(n-2)!} \int_{\alpha}^x (x-t)^{n-2} F^{(n-1)}(t) dt + \sum_{k=0}^{n-2} F^{(k)}(\alpha) \frac{(x-\alpha)^k}{k!} .$$

Proof: This follows from Theorem 7 and Corollary 8 of [2] (where the results are erroneously stated to hold on the closed interval  $[a,b]$ .)

However, the Bernstein polynomials provide n-convex uniform approximants to a continuous n-convex function which satisfy (a), (b), and (c) on the closed interval  $[a,b]$ . As we shall see, even more is true.

Definition 2.2. If  $a < c_1 < c_2 < \dots < c_m < b$ , and if  $x_+^n$  denotes the function

$$x_+^n = \begin{cases} x^n & \text{if } x \geq 0 \\ 0 & \text{if } x < 0, \end{cases}$$

then a spline function of degree  $n$ ,  $n \geq 1$ , with knots  $c_1, c_2, \dots, c_m$  is defined to be any function of the form

$$g(x) = \sum_{r=0}^n \alpha_r x^r + \sum_{j=1}^m \beta_j (x-c_j)_+^n .$$

Theorem 2.2. [3] A spline function of degree  $n$  is any  $n^{\text{th}}$  order indefinite integral of a step function.

It is easy to show that if the step function of Theorem 2.2 is increasing, then the spline function of degree  $n$  is  $(n+1)$  convex.

We now state the two theorems of Bojanic and Roulier mentioned earlier and prove a third in the spirit of the first.

Theorem 2.3. (Theorem 1, [1]). Every  $F \in K_n[a, b]$ ,  $n \geq 2$  can be approximated uniformly on  $[a, b]$  by spline functions of the form

$$\begin{aligned} \psi_{m, N}(F, x) = & \sum_{k=0}^{n-1} \binom{n}{k} \left( \Delta_{\frac{b-a}{m}}^k F(a) \right) (x-a)^k / (b-a)^k \\ & + \frac{C(F, m)}{N} \sum_{k=1}^{N-1} (x-c_k)_+^{n-1} / (b-a)^{n-1} \end{aligned}$$

where  $C(F, m) = \binom{m}{n-1} \sum_{k=0}^{m-n} \Delta_{\frac{b-a}{m}}^n F\left(a+k\left(\frac{b-a}{m}\right)\right) \geq 0$ ,  $m \geq n$ ,  $N \geq 2$ ,

$c_k \in (a, b)$ ,  $k = 1, 2, \dots, N-1$ , and

$$\Delta_h^k F(x) = \sum_{r=0}^k (-1)^{k-r} \binom{k}{r} F(x+rh).$$

Theorem 2.4. (Theorem 2. [1]). Let  $T: C[a, b] \rightarrow L[a, b]$  be a continuous linear operator. In order that for every  $F \in K_n[a, b]$ ,  $n \geq 2$ , we have  $T(F) \in K_r[a, b]$ ,  $r \geq 0$ , it is necessary and sufficient that

- (i)  $V_r(T(P); x_k) = 0$  for every polynomial  $P$  of degree  $\leq n-1$  and every set of  $r+1$  points  $x_0 < x_1 < \dots < x_r$  in  $[a, b]$ ;

(ii)  $T\left((t-c)_+^{n-1}\right) \in K_r[a,b]$  for every  $c \in (a,b)$ .

Theorem 2.5. If  $F \in K_n[a,b]$ , then given  $\epsilon > 0$  there exists  $G \in K_n[a,b]$  such that

(a)  $G^{(n)}(x)$  exists in  $[a,b]$ ;

$$(b) \quad G(x) = \sum_{k=0}^{n-2} G^{(k)}(a) \frac{(x-a)^k}{k!} + \int_a^x \dots \int_a^{x_1} G^{(n-1)}(t) dt dx_1 \dots dx_{n-2}$$

where  $G^{(n-1)}$  is increasing on  $[a,b]$ ;

(c)  $|G(x) - F(x)| < \epsilon$ , for  $x \in [a,b]$ .

Proof: There is no loss in generality in assuming  $[a,b] = [0,1]$ . Let  $G(x)$  be the Bernstein polynomial of  $F$  of degree  $m \geq n$ :

$$G(x) = \sum_{k=0}^m \binom{m}{k} F\left(\frac{k}{m}\right) x^k (1-x)^{m-k},$$

where  $m$  is so large that  $|G(x) - F(x)| < \epsilon$  for  $x \in [0,1]$ . It is shown in [4] that since  $F \in K_n[0,1]$ ,  $G^{(n)}(x) \geq 0$ , for  $x \in [0,1]$  and (b) follows.

The class of functions  $G \in K_n[a,b]$  which satisfy (a) and (b) of Theorem 2.5 will be denoted by  $\bar{K}_n[a,b]$ .

3. The uniform approximation of continuous n-convex functions by n-convex splines. It is easily shown that if a function  $f(x)$  is continuous and monotonic on  $[0,1]$ , then it can be uniformly approximated on  $[0,1]$  by step functions of the form

$$f_N(x) = f(0) + \left( \frac{f(1)-f(0)}{N} \right) \sum_{k=1}^{N-1} (x-c_k)_+^0,$$

where  $N \geq 2$ ,  $0 < c_1 < c_2 < \dots < c_{N-1} < b$ , and

$$(x-c)_+^0 = \begin{cases} 0 & \text{if } x < c \\ 1 & \text{if } x \geq c. \end{cases}$$

We now state and prove the theorem on the approximation of n-convex functions by n-convex splines.

Theorem 3.1. If  $F \in K_n[a,b]$ , then  $F$  can be uniformly approximated by n-convex spline functions of the form

$$G_N(x) = \sum_{k=0}^{n-1} \left( \frac{\alpha_k (x-a)^k}{k!} \right) + \left( \frac{C}{N} \right) \sum_{j=1}^{N-1} (x-c_j)_+^{n-1}, \quad (3.1)$$

where  $C > 0$ ,  $N \geq 2$ , and  $a < c_1 < c_2 < \dots < c_{N-1} < b$ .

(Note: This has the same form as the corresponding decomposition in [1] without the constants precisely determined.)

Proof: (For  $[a,b] = [0,1]$ ). The first step will be to approximate  $F$  by  $G \in \bar{K}_n[0,1]$ . Thus, writing  $g(t) = G^{(n-1)}(t)$  we have by Theorem 2.5

$$G(x) = \sum_{k=0}^{n-2} G^{(k)}(0) \frac{x^k}{k!} + \int_0^x \dots \int_0^{x_1} g(t) dt dx_1 \dots dx_{n-2},$$

where  $g(t)$  is continuous and increasing. Now let

$$g_N(x) = g(0) + \left( \frac{g(1)-g(0)}{N} \right) \sum_{k=1}^{N-1} (x-c_k)_+^0$$

be an approximating spline to the continuous, increasing function  $g(t)$ . Then define  $G_N$  by

$$G_N(x) = \sum_{k=0}^{n-2} \frac{G^{(k)}(0)x^k}{k!} + \int_0^x \dots \int_0^{x_1} g_N(t) dt dx_1 \dots dx_{n-2} .$$

Then  $G_N(x)$  is a convex spline which after integration becomes

$$G_N(x) = \sum_{k=0}^{n-1} \frac{G^{(k)}(0)x^k}{k!} + \left( \frac{g(1)-g(0)}{N} \right) \sum_{j=1}^{N-1} (x-c_j)_+^{n-1} ,$$

which is the decomposition required in (3.1).

Furthermore, it is clear that given  $F \in K_n[a,b]$  and  $\epsilon > 0$  we may choose  $G_N(x)$  so that

$$\begin{aligned} |F(x) - G_N(x)| &\leq |F(x) - G(x)| + |G(x) - G_N(x)| \\ &< \epsilon + \frac{\epsilon x^{n-1}}{(n-1)!} < 2\epsilon . \end{aligned}$$

The proof of Theorem 2.4 follows as in [1].

#### 4. Sufficient Conditions for Convexity Preserving Linear Operators.

We first obtain a decomposition of  $G \in \bar{K}_n[a,b]$  which is interesting by itself.

Theorem 4.1. If  $G \in \bar{K}_n[a,b]$ , then for  $x \in [a,b]$

$$G(x) = H(x) + \sum_{k=0}^{n-1} G^{(k)}(a) \frac{(x-a)^k}{k!}, \quad (4.1)$$

where  $H(x)$  is increasing and  $H(x) \in \bar{K}_r[a,b]$  for each  
fixed  $r$ ,  $2 \leq r \leq n$ .

Proof: Let  $H$  be defined by

$$H(x) \equiv G(x) - \sum_{k=0}^{n-1} G^{(k)}(a) \frac{(x-a)^k}{k!}.$$

Then  $H(x)$  is  $n$ -convex and  $H^{(k)}(a) = 0$ ,  $k = 0, 1, 2, \dots, n-1$ , and  $H^{(n-1)}(x)$  is increasing. We have then for  $x \in [a,b]$ ,  $(H^{(n-2)}(x))' = H^{(n-1)}(x) \geq H^{(n-1)}(a) = 0$ , and it follows that  $H^{(n-2)}(x)$  is increasing on  $[a,b]$  and  $H(x) \in \bar{K}_{n-1}[a,b]$ .

Repeating the same process on  $H^{(n-2)}(x)$  we obtain  $(H^{(n-3)}(x))' = H^{(n-2)}(x) \geq H^{(n-2)}(a) = 0$  and so  $H^{(n-3)}(x)$  is increasing and  $H(x) \in K_{n-2}[a,b]$ . Continuing in this way



we obtain after  $(n-1)$  steps that  $H'(x) \geq 0$  and  $H(x)$  is increasing on  $[a,b]$ .

Theorem 4.2. If  $F \in K_n[a,b]$ , then  $F$  can be uniformly approximated by splines of the form

$$G_{N_s}(x) = \sum_{k=0}^{n-1} \frac{\alpha_k (x-a)^k}{k!} + \left( \frac{C_s}{N_s} \right) \sum_{j=1}^{N_s-1} (x-c_j)_+^{s-1}, \quad (4.2)$$

for each  $1 \leq s \leq n-1$ , where  $C_s > 0$  and  $N_s > 0$  are constants (depending on  $s$ ), and

$$a < c_1 < c_2 < \dots < c_{N_s-1} < b.$$

Proof: (For fixed  $s$  and  $[a,b] = [0,1]$ ). As before we first approximate  $F$  by  $G \in \bar{K}_n[0,1]$ . Then, utilizing the decomposition in (4.1) and writing  $g(t) = H^{(s-1)}(t)$  (noting that  $H^{(k)}(0) = 0$ ,  $1 \leq k \leq n-1$ ) we next obtain

$$\begin{aligned} H(x) &= \int_0^x \dots \int_0^{x_1} g(t) dt dx_1 \dots dx_{s-2} \\ &= \left( \frac{C_s}{N_s} \right) \sum_{j=1}^{N_s-1} (x-c_j)_+^{s-1}, \end{aligned}$$

as in the proof of Theorem 3.1, and (4.2) follows.

We now state and prove our result on continuous linear transformations of  $n$ -convex functions.

Theorem 4.3. Let  $T: C[a,b] \rightarrow L[a,b]$  be a continuous linear operator. In order that for every  $F \in K_n[a,b]$ ,  $n \geq 2$ , we have  $T(F) \in K_r[a,b]$ ,  $r \geq 0$ , it is sufficient that

- (i)  $V_r(T(P); x_k) = 0$  for every polynomial  $P$  of degree  $\leq n-1$  and every set of  $r+1$  points  $x_0 < x_1 < \dots < x_r$  in  $[a,b]$ ;
- (ii)  $T((t-c)_+^{s-1}) \in K_r[a,b]$  for some fixed  $s$ ,  $2 \leq s \leq n$ , and every  $c \in (a,b)$ .

Proof: (For fixed  $s$ ). Let  $f \in K_n[a,b]$  and let  $G_{N_s}(x)$  be a spline function of the form (4.2). Since  $C_s > 0$  and  $N_s > 0$ , and  $T$  is linear, conditions (i) and (ii) imply that  $V_r(T(G_{N_s}); x_k) \geq 0$  for every set of  $r+1$  points  $x_0 < x_1 < \dots < x_r$  in  $[a,b]$ . Since  $T$  is continuous and  $G_{N_s}$  approximates  $F$  uniformly it follows that

$$V_r(T(F); x_k) \geq 0$$

and so  $T(F) \in K_r[a,b]$ .

Notes: (a) The theorem as stated does not hold for  $s = 1$  since  $(t-c)_+^0$  is not continuous.

(b) Condition (ii), for  $s < n$ , is not a necessary condition since  $(t-c)_+^{s-1}$  need not be  $n$ -convex.

## References

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