

Characteristic function of Cayley projective plane as a harmonic manifold

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Abstract. Any locally rank one Riemannian symmetric space is a harmonic manifold. We give the characteristic function of a Cayley projective plane as a harmonic manifold. The aim of this work is to show the explicit form of the characteristic function of the Cayley projective plane.

Key words: Cayley projective plane, harmonic manifold, characteristic function.

1. Introduction

Let $M = (M, g)$ be an m -dimensional Riemannian manifold and $\theta_p(q) = \sqrt{\det(g_{ij}(q))}$ (resp. $\Theta_p(q) = r_p(q)^{m-1}\theta_p(q)$) be the volume density function (resp. the density function of the geodesic sphere $S(p, r_p(q))$) in a normal coordinate neighborhood $U_p(x^1, \dots, x^m)$ centered at $p \in M$, where $r_p(q) = d(p, q)$ is the geodesic distance from p to q in U_p .

Definition 1 A Riemannian manifold $M = (M, g)$ is said to be locally harmonic if the volume density function θ_p is a radial function (correspondingly, the density function Θ_p of the geodesic sphere $S(p, r_p(q))$ is also a radial function).

In the sequel, we call a locally harmonic manifold briefly a harmonic manifold. Let $M = (M, g)$ be a harmonic manifold. Then, it is shown that the density function Θ_p does not depend on the choice of p . A rank one symmetric space is a harmonic manifold. There are several equivalent definitions for harmonic manifolds ([1, pp. 156]). One of them is as follows:

Theorem 2 A Riemannian manifold $M = (M, g)$ is a harmonic manifold if and only if the equality

$$\Delta\Omega = f_p(\Omega_p) \quad \left(\Omega_p = \frac{1}{2}r_p^2 \right)$$

holds for a certain smooth function f_p on $[0, \varepsilon(p))$, where $\varepsilon(p)$ is the injectivity radius at $p \in M$.

We note that the function f_p in Theorem 2 does not depend on the choice of $p \in M$ ([1, Proposition 6.16]) then the function $f = f_p$ ($p \in M$) is called the characteristic function of a harmonic manifold $M = (M, g)$. The characteristic function plays an important role in the geometry of harmonic manifolds and its applications [4], [6], [7], [9]. The characteristic functions of rank one symmetric spaces have been obtained except for Cayley projective plane $\mathbb{C}P^2$ and its non-compact dual $\mathbb{C}H^2$ (Cayley hyperbolic plane) [6], [7], [9]. So it seems natural to determine the characteristic functions for Cayley projective plane $\mathbb{C}P^2$ and Cayley hyperbolic plane $\mathbb{C}H^2$ in order to complete the table of the characteristic functions of rank one symmetric spaces. In this article, we shall prove the following theorems 3 and 4.

Theorem 3 *Let $\mathbb{C}P^2$ be a Cayley projective plane. Then, the characteristic function as a harmonic manifold is given by*

$$f(\Omega) = 1 + \sqrt{\frac{\Omega}{2}} \left\{ 15 \cot \sqrt{\frac{\Omega}{2}} - 7 \tan \sqrt{\frac{\Omega}{2}} \right\}. \quad (1.1)$$

Theorem 4 *Let $\mathbb{C}H^2$ be a Cayley hyperbolic plane. Then, the characteristic function as a harmonic manifold is given by*

$$*f(\Omega) = 1 + \sqrt{\frac{\Omega}{2}} \left\{ 15 \coth \sqrt{\frac{\Omega}{2}} + 7 \tanh \sqrt{\frac{\Omega}{2}} \right\}. \quad (1.2)$$

Our arguments in this paper are much indebted to the article by R. Brown and A. Gray [2] and I. Yokota [10]. We aimed our paper to be self-contained as much as possible. The authors thank to the referee for the kind suggestions.

2. Preliminaries

In this section, we prepare a brief review on algebraic background which plays a basic role in the geometry of Cayley projective plane $\mathbb{C}P^2$. Let \mathfrak{C} be the Cayley division normed algebra with the multiplicative unity 1 and positive definite bilinear form $\langle \cdot, \cdot \rangle$ where associated norm $\| \cdot \|$ satisfies $\| ab \| = \| a \| \cdot \| b \|$ for $a, b \in \mathfrak{C}$. Every element $a \in \mathfrak{C}$ is written as $a = \alpha + a_0$,

where α is a real number and $\langle a_0, 1 \rangle = 0$, where a_0 is said to be purely imaginary. We denote by \bar{a} the conjugate of $a = \alpha + a_0$ defined by $\bar{a} = \alpha - a_0$. we may easily check that $a\bar{a} = \bar{a}a = \langle a, a \rangle = 1 = \|a\|^2$ holds for any $a \in \mathfrak{C}$ and further, by linearizing the equality $a\bar{a} = \langle a, a \rangle 1$, we have

$$a\bar{b} + b\bar{a} = \bar{a}b + \bar{b}a = 2\langle a, b \rangle 1 \tag{2.1}$$

for any $a, b \in \mathfrak{C}$. A canonical basis of \mathfrak{C} is defined as a basis of the form $\{1, e_1, \dots, e_7\}$ for which $\langle e_i, e_j \rangle = \delta_{ij}$, $e_i^2 = -1$, $e_i e_j + e_j e_i = 0$ ($1 \leq i \neq j \leq 7$) satisfying the following multiplicative operations given by the following figure:

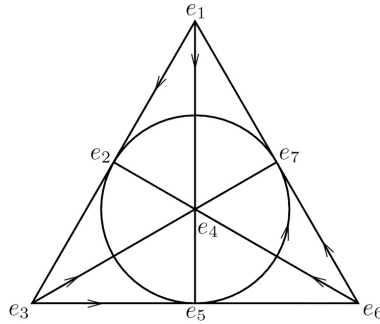


Figure 1.

We denote by \mathbf{D}_4 the Lie algebra consisting of linear maps $A : \mathfrak{C} \rightarrow \mathfrak{C}$ such that $\langle Aa, b \rangle = -\langle a, Ab \rangle$ for $a, b \in \mathfrak{C}$. It is well-known that \mathbf{D}_4 is the compact simple Lie algebra over real number \mathbb{R} with an outer automorphism $Aut(\mathbf{D}_4)/Inn(\mathbf{D}_4)$ of order 3. $Aut(\mathbf{D}_4)/Inn(\mathbf{D}_4)$ is isomorphic to the symmetric group on 3 letters \mathfrak{S}_3 . Namely, there exist $\kappa, \lambda \in Aut(\mathbf{D}_4)$ which generate $Aut(\mathbf{D}_4)/Inn(\mathbf{D}_4)$ and satisfy the relations $\lambda^3 = 1, \kappa^2 = 1, \kappa\lambda\kappa = \lambda^2$. Here, we may choose κ and λ as follows. Let $\{e_i\} = \{e_0 = 1, e_1, \dots, e_7\}$ be a canonical orthonormal basis of $\mathfrak{C} = (\mathfrak{C}, \langle \cdot, \cdot \rangle)$ and \mathbf{D}_4 be the real Lie algebra of skew-symmetric endomorphisms of $\mathfrak{C} = (\mathfrak{C}, \langle \cdot, \cdot \rangle)$. Now, we define $G_{ij} \in \mathbf{D}_4$ and $F_{ij} \in \mathbf{D}_4$ ($i \neq j, i, j = 0, 1, \dots, 7$) be the linear endomorphisms of \mathfrak{C} defined respectively by

$$G_{ij}e_j = e_i, \quad G_{ij}e_i = -e_j, \quad G_{ij}e_k = 0 \quad (k \neq i, j) \tag{2.2}$$

and

$$F_{ij}e_i = \frac{1}{2}e_i e_j, \quad F_{ij}e_j = -\frac{1}{2}e_i e_j \quad (i \geq 1, 0 \leq j \leq 7), \quad (2.3)$$

and

$$F_{ij}a = \frac{1}{2}e_j(e_i a) \quad (i \neq 0, j \neq 0, i \neq j)$$

for any $a \in \mathfrak{C}$. Then, we may easily check that $\{G_{ij}\}$ (resp. $\{F_{ij}\}$) ($i < j$) is a basis of \mathbf{D}_4 . We here define linear endomorphisms κ , π and λ on \mathbf{D}_4 respectively by

$$\begin{aligned} \kappa(G_{ij}) &= G_{ij} \quad (i, j \geq 1), & \kappa(G_{0i}) &= -G_{0i} \quad (i \geq 1), \\ \pi(G_{ij}) &= F_{ij} \quad (i \neq j) & \text{and} \quad \lambda &= \pi\kappa. \end{aligned} \quad (2.4)$$

Then, we see that κ and λ satisfy the required relations and further, the following identity

$$(\lambda(A)a)b + a(\lambda^2(A)b) = \kappa(A)(ab) \quad (2.5)$$

holds for any $A \in \mathbf{D}_4$ and any $a, b \in \mathfrak{C}$ [10]. The identity (2.5) is called the principle of triality of \mathbf{D}_4 .

Now, for $a, b, c \in \mathfrak{C}$, we define $T(a, b)$, $G(a, b)$, $D(a, b) \in \mathbf{D}_4$ as follows:

$$\begin{aligned} T(a, b)c &= 4\langle a, c \rangle b - 4\langle b, c \rangle a, \\ G(a, b)c &= \bar{a}(bc) - \bar{b}(ac), \\ D(a, b)c &= (cb)\bar{a} - (ca)\bar{b}. \end{aligned} \quad (2.6)$$

Then, they satisfy

$$\begin{aligned} \lambda(T(a, b)) &= -G(a, b), & \lambda^2(T(a, b)) &= -D(a, b), \\ \kappa(T(a, b)) &= T(\bar{a}, \bar{b}), & \kappa(G(a, b)) &= D(\bar{a}, \bar{b}), \end{aligned} \quad (2.7)$$

and further

$$\begin{aligned} \langle T(a, b)c, d \rangle &= 4(\langle a, c \rangle \langle b, d \rangle - \langle a, d \rangle \langle b, c \rangle) \\ \langle G(a, b)c, d \rangle &= \langle ad, bc \rangle - \langle ac, bd \rangle, \\ \langle D(a, b)c, d \rangle &= \langle da, cb \rangle - \langle ca, db \rangle \end{aligned} \quad (2.8)$$

for any $a, b, c, d \in \mathfrak{C}$.

We denote by \mathbf{B}_4 the real Lie algebra consisting of 9×9 skew-symmetric matrices. Now we shall define a 16-dimensional representation of the Lie algebra \mathbf{B}_4 on the real vector space $V = V_2 = \mathfrak{C} \oplus \mathfrak{C}$. First, we regard each $X \in \mathbf{B}_4$ as a 9×9 skew-symmetric matrix and the last column vector as an element $a \in \mathfrak{C}$. Further, considering the ordinary inclusion of \mathbf{D}_4 in \mathbf{B}_4 we may write as follows:

$$X = A + M_a, \tag{2.9}$$

where $A \in \mathbf{D}_4$ and $M_a = \begin{pmatrix} 0 & 2a \\ -2a & 0 \end{pmatrix}$. Now, we define an action of \mathbf{B}_4 on V by

$$A(b, c) = (\lambda(A)b, \lambda^2(A)c) \tag{2.10}$$

for $A \in \mathbf{D}_4$ and

$$M_a(b, c) = (a\bar{c}, -\bar{b}a) \tag{2.11}$$

for $(b, c) \in \mathfrak{C} \oplus \mathfrak{C}$. Then, we may check that the above action of \mathbf{B}_4 on $\mathfrak{C} \oplus \mathfrak{C}$ defines a representation of the real Lie algebra \mathbf{B}_4 on $\mathfrak{C} \oplus \mathfrak{C}$ ([2, pp. 46]). The vector space $V = \mathfrak{C} \oplus \mathfrak{C}$ has a positive definite symmetric bilinear form \langle , \rangle given by $\langle (a, c), (b, d) \rangle = \langle a, b \rangle + \langle c, d \rangle$ for $a, b, c, d \in \mathfrak{C}$. Then each element of \mathbf{B}_4 is skew-symmetric with respect to the bilinear form \langle , \rangle .

3. The curvature tensor of the Cayley projective plane

Let $\mathfrak{CP}^2 = (F_4/spin(9), g)$ be Cayley projective plane equipped with a Riemannian metric g defined by a bi-invariant Riemannian metric on the compact Lie group F_4 . Then, it is well known that \mathfrak{CP}^2 is a compact rank one symmetric space and further the holonomy group is isomorphic to $Spin(9)$ ([2, Examples]). It is easily checked that the corresponding Cartan decomposition is given by

$$\mathbf{F}_4 = \mathbf{B}_4 \oplus \mathfrak{m}, \tag{3.1}$$

where $\mathfrak{m} = \{(a, b) \in \mathfrak{C} \times \mathfrak{C}\} \cong \mathfrak{C} \oplus \mathfrak{C}$, which can be identified with the tangent space $T_o(\mathfrak{CP}^2)$ at the origin $o = Spin(9)$. Further, we may also see that the linear isotropy representation of the isotropy group $Spin(9)$ on $\mathfrak{m} \cong \mathfrak{C} \oplus \mathfrak{C}$ is

equivalent to the representation of the group $\text{Spin}(9)$ on $V = \mathfrak{C} \oplus \mathfrak{C}$ defined by (2.10) and (2.11) in §2. From the above observation identifying the tangent space $(T_o(\mathbb{C}\mathbb{P}^2), g_o)$ with $(\mathfrak{C} \oplus \mathfrak{C}, \langle \cdot, \cdot \rangle)$, we see that the curvature tensor R of the Cayley projective plane $\mathbb{C}\mathbb{P}^2$ at the origin o is given algebraically by the following formula:

$$R((a, b) \wedge (c, d)) = \frac{1}{4} \{D(a, c) + G(b, d) + M_{ad-cb}\} \tag{3.2}$$

for $a, b, c, d \in \mathfrak{C}$ and a positive real number μ ([2, Example 4, pp. 52]). Here, we assume that the curvature tensor R is defined by

$$R(X, Y) = [\nabla_X, \nabla_Y] - \nabla_{[X, Y]} \tag{3.3}$$

for any smooth vector fields X, Y on $\mathbb{C}\mathbb{P}^2$ where ∇ denotes the Levi-Civita connection of the Riemannian metric g . Now, we shall rewrite (3.2) to the more explicit form. From (3.2) with (3.3), taking account of (2.6)~(2.8), we have

$$\begin{aligned} R((a, b), (c, d))(u, v) &= \frac{1}{4} \{D(a, c)(u, v) + G(b, d)(u, v) + M_{ad-cb}(u, v)\} \end{aligned} \tag{3.4}$$

for $a, b, c, d, u, v \in \mathfrak{C}$. Here, from (2.6)~(2.8), (2.10) and (2.11), we get

$$\begin{aligned} D(a, c)(u, v) &= (\lambda(D(a, c))u, \lambda^2(D(a, c))v) \\ &= (-T(a, c)u, G(a, c)v) \\ &= (-4\langle a, u \rangle c + 4\langle c, u \rangle a, \bar{a}(cv) - \bar{c}(av)), \end{aligned} \tag{3.5}$$

$$\begin{aligned} G(b, d)(u, v) &= (\lambda(G(b, d))u, \lambda^2(G(b, d))v) \\ &= (-\lambda^2(T(b, d))u, -T(b, d)v) \\ &= (D(b, d)u, -T(b, d)v) \\ &= ((ud)\bar{b} - (ub)\bar{d}, -4\langle b, v \rangle d + 4\langle d, v \rangle b), \end{aligned} \tag{3.6}$$

$$M_{ad-cb}(u, v) = ((ad - cb)\bar{v}, -\bar{u}(ad - cb)). \tag{3.7}$$

Thus, from (3.4), taking account of (3.5)~(3.7), we have

$$\begin{aligned}
 R((a, b), (c, d))(u, v) &= \frac{1}{4}(-4\langle a, u \rangle c + 4\langle c, u \rangle a + (ud)\bar{b} - (ub)\bar{d} + (ad - cb)\bar{v}, \\
 &\quad -4\langle b, v \rangle d + 4\langle d, v \rangle b + \bar{a}(cv) - \bar{c}(av) - \bar{u}(ad - cb)) \quad (3.8)
 \end{aligned}$$

for $a, b, c, d, u, v \in \mathfrak{C}$ ([3, (1.7), pp. 269]). Now, let $\{e_0 = 1, e_1, e_2, e_3, e_4, e_5, e_6, e_7\}$ be a canonical basis of \mathfrak{C} and we set

$$\begin{aligned}
 y_0 &= (1, 0), & y_1 &= (e_1, 0), & y_2 &= (e_2, 0), & y_3 &= (e_3, 0), \\
 y_4 &= (e_4, 0), & y_5 &= (e_5, 0), & y_6 &= (e_6, 0), & y_7 &= (e_7, 0), \\
 y_{\bar{0}} &= (0, 1), & y_{\bar{1}} &= (0, e_1), & y_{\bar{2}} &= (0, e_2), & y_{\bar{3}} &= (0, e_3), \\
 y_{\bar{4}} &= (0, e_4), & y_{\bar{5}} &= (0, e_5), & y_{\bar{6}} &= (0, e_6), & y_{\bar{7}} &= (0, e_7).
 \end{aligned} \quad (3.9)$$

Then, $\{y_0, y_1, \dots, y_7, y_{\bar{0}}, \dots, y_{\bar{7}}\}$ is regarded as an orthonormal basis of $(T_0(\mathbb{C}P^2), g_0)$ and hence, from the formula (3.8), taking account of (3.9) and Figure 1, we have

$$\begin{aligned}
 R(y_i, y_j)y_i &= -y_j, & (i \neq j) \\
 R(y_i, y_{\bar{j}})y_i &= -\frac{1}{4}y_{\bar{j}}
 \end{aligned} \quad (3.10)$$

and further,

$$R(y_i, y_j)y_k = 0, \quad (k \neq i, j) \quad (3.11)$$

$$R(y_{\bar{i}}, y_j)y_{\bar{i}} = -\frac{1}{4}y_j, \quad (3.12)$$

$$R(y_{\bar{i}}, y_{\bar{j}})y_{\bar{i}} = -y_{\bar{j}}, \quad (3.13)$$

$$R(y_{\bar{i}}, y_{\bar{j}})y_{\bar{k}} = 0 \quad (k \neq i, j) \quad (3.14)$$

for $0 \leq i, j, k \leq 7$.

4. Proofs of Theorems 3 and 4

First, let $\{e_0 = 1, e_1, \dots, e_7\}$ be a canonical basis of \mathfrak{C} and $\{y_0, y_1, \dots, y_7, y_{\bar{0}}, y_{\bar{1}}, \dots, y_{\bar{7}}\}$ be the basis of the real vector space $T_o(\mathbb{C}P^2)$ of the Cayley projective plane $\mathbb{C}P^2 = (F_4/\text{Spin}(9), g)$ at the origin $o = \text{Spin}(9)$

can be identified with $V = \mathfrak{C} \oplus \mathfrak{C}$ with the canonical positive definite symmetric bilinear form $\langle \cdot, \cdot \rangle$ defined in Section 2. Then, it follows that $\{y_0, y_1, \dots, y_7, y_{\bar{0}}, y_{\bar{1}}, \dots, y_{\bar{7}}\}$ is an orthonormal basis of $(V, \langle \cdot, \cdot \rangle)$. We now identify $(T_o(\mathbb{C}\mathbb{P}^2), g_o)$ with the vector space $(V, \langle \cdot, \cdot \rangle)$ by the above identification.

Now, we denote by $\gamma = \gamma(s)$ the normal geodesic in $(\mathbb{C}\mathbb{P}^2, g)$ through the origin $o = \gamma(0)$ with the initial direction $\gamma'(0) = y_0$. Further, we set $y_0(s) = \gamma'(s)$ and assume that the vector fields, $y_1(s), \dots, y_7(s), y_{\bar{0}}(s), \dots, y_{\bar{7}}(s)$ are parallel along γ satisfying

$$y_i(0) = y_i \quad (1 \leq i \leq 7) \quad \text{and} \quad y_{\bar{k}}(0) = y_{\bar{k}} \quad (0 \leq k \leq 7). \quad (4.1)$$

Then, we can check that $\{y_0(s), y_1(s), \dots, y_7(s), y_{\bar{0}}(s), y_{\bar{1}}(s), \dots, y_{\bar{7}}(s)\}$ is an orthonormal frame field along γ . Now, let $Y_i(s)$ ($1 \leq i \leq 7$) and $Y_{\bar{k}}(s)$ ($0 \leq k \leq 7$) be the Jacobi vector fields along γ satisfying the following conditions

$$\begin{aligned} Y_i(0) = 0, Y_{\bar{k}}(0) = 0 \quad \text{and} \\ Y'_i(0) = (\nabla_{\gamma'} Y_i)(0) = y_i, \quad Y'_{\bar{k}}(0) = (\nabla_{\gamma'} Y_{\bar{k}})(0) = y_{\bar{k}}, \end{aligned} \quad (4.2)$$

for $1 \leq i \leq 7, 0 \leq k \leq 7$. Then, we set as follows along γ :

$$\begin{aligned} Y_i(s) &= \sum_{j=1}^7 a_{ji}(s) y_j(s) + \sum_{l=0}^7 a_{\bar{l}i} y_{\bar{l}}(s), \\ Y_{\bar{k}}(s) &= \sum_{j=1}^7 a_{j\bar{k}}(s) y_j(s) + \sum_{l=0}^7 a_{\bar{l}\bar{k}}(s) y_{\bar{l}}(s), \end{aligned} \quad (4.3)$$

for $1 \leq i \leq 7, 0 \leq k \leq 7$ and

$$\begin{aligned} R(\gamma'(s), y_i(s))\gamma'(s) &= \sum_{j=1}^7 K_{ij}(s) y_j(s) + \sum_{l=0}^7 K_{\bar{l}i}(s) y_{\bar{l}}(s), \\ R(\gamma'(s), y_{\bar{k}}(s))\gamma'(s) &= \sum_{j=1}^7 K_{\bar{k}j}(s) y_j(s) + \sum_{l=0}^7 K_{\bar{k}\bar{l}}(s) y_{\bar{l}}(s), \end{aligned} \quad (4.4)$$

for $1 \leq i \leq 7, 0 \leq k \leq 7$. Then, since $\nabla R = 0$ and the vector fields

$y_i(s), y_{\bar{k}}(s)$ ($1 \leq i \leq 7, 0 \leq k \leq 7$) are parallel along γ , we easily see that $K_{ij}(s)$ ($= K_{ji}(s)$), $K_{i\bar{k}}(s)$ ($= K_{\bar{k}i}(s)$), $K_{\bar{k}l}(s)$ ($= K_{l\bar{k}}(s)$) are all constant along γ . Thus, from (4.4) taking account of (3.10), we have

$$\begin{aligned} K_{ij}(s) &= K_{ji}(s) = -\delta_{ij}, \\ K_{i\bar{k}}(s) &= K_{\bar{k}i}(s) = 0, \\ K_{\bar{k}l}(s) &= K_{l\bar{k}} = -\frac{1}{4}\delta_{kl}, \end{aligned} \tag{4.5}$$

for $1 \leq i, j \leq 7, 0 \leq k, l \leq 7$. Since $Y_i(s), Y_{\bar{k}}(s)$ ($1 \leq i \leq 7, 0 \leq k \leq 7$) are Jacobi vector fields along the geodesic, from (4.3), taking account of (4.4) with (4.5), we have the following system of differential equations along γ :

$$\begin{aligned} a''_{ij} + a_{ij} &= 0, \\ a''_{i\bar{k}} &= 0, \quad a''_{\bar{l}i} = 0, \\ a''_{\bar{k}l} + \frac{1}{4}a_{\bar{k}l} &= 0. \end{aligned} \tag{4.6}$$

Solving (4.6) under the initial conditions (4.2), we have

$$\begin{aligned} a_{ij}(s) &= \delta_{ij} \sin s, \\ a_{i\bar{k}}(s) &= a_{\bar{k}i}(s) = 0, \\ a_{\bar{k}l}(s) &= 2\delta_{kl} \sin \frac{1}{2}s, \end{aligned} \tag{4.7}$$

for $1 \leq i, j \leq 7, 0 \leq k, l \leq 7$.

Now, we define 15×15 -matrix $A(s)$ by

$$A(s) = \begin{pmatrix} a_{ij}(s) & a_{i\bar{l}}(s) \\ a_{\bar{k}j}(s) & a_{\bar{k}l}(s) \end{pmatrix} \tag{4.8}$$

for $1 \leq i, j \leq 7, 0 \leq k, l \leq 7$. Then, it is well-known that the following equality

$$\Theta_o(\gamma(s)) = s^{15}\theta_o(\gamma(s)) = \det A(s) \tag{4.9}$$

holds along the geodesic γ . From (4.8) with (4.7), we have

$$\begin{aligned} \det A(s) &= (\sin s)^7 \left(2 \sin \frac{1}{2} s \right)^8 \\ &= 16^2 (\sin s)^7 \left(\sin \frac{1}{2} s \right)^8. \end{aligned} \quad (4.10)$$

Thus, from (4.9) and (4.10), we have

$$\Theta_o(\gamma(s)) = 16^2 (\sin s)^7 \left(\sin \frac{1}{2} s \right)^8. \quad (4.11)$$

Here, since the Cayley projective plane $\mathbb{C}P^2 = (F_4/\text{Spin}(9), g)$ is a harmonic manifold, the volume density function θ_o (and hence, the function Θ_o) is a radial function on a normal neighborhood U_o centered at the origin o . Thus, Θ_o is determined by its value along the geodesic γ . Thus, from (4.11), we easily see the function Θ_o is given by

$$\begin{aligned} \Theta_o(q) &= \det A(s) \\ &= 16^2 (\sin s)^7 \left(\sin \frac{1}{2} s \right)^8, \end{aligned} \quad (4.12)$$

where $q = \gamma(s) \in U_o - \{o\}$ ([3, pp. 269]).

Now, let $\phi(s)$ be a smooth function of s ($0 < s < \epsilon$, $\epsilon > 0$), and consider the function $f(q)$ on U_o defined by $f(q) = \phi(s)$, $s = d(0, q)$, $q \in U_o$. Then, the following equality holds as in [5] with the sign difference:

$$\Delta f = \phi''(s) + \frac{(\Theta_o(\gamma(s)))'}{\Theta_o(\gamma(s))} \phi'(s), \quad q = \gamma(s), \quad (4.13)$$

where Δ denotes the Laplace-Beltrami operator of $\mathbb{C}P^2 = (F_4/\text{Spin}(9), g)$. Here, from (4.12), we get

$$\begin{aligned} &\frac{(\Theta_o(\gamma(s)))'}{\Theta_o(\gamma(s))} \\ &= \frac{7(\sin s)^6 (\sin((1/2)s))^8 \cos s + 4(\sin s)^7 (\sin((1/2)s))^7 \cos(1/2)s}{(\sin s)^7 (\sin((1/2)s))^8} \\ &= 7 \cot s + 4 \cot \frac{1}{2} s \end{aligned}$$

$$= \frac{15}{2} \cot \frac{1}{2}s - \frac{7}{2} \tan \frac{1}{2}s. \tag{4.14}$$

We here consider the special case where $\phi(s) = (1/2)s^2$ ($s > 0$). Then, from (4.13) and (4.14), by direct calculation, we see that

$$\Delta\Omega = 1 + \sqrt{\frac{\Omega}{2}} \left\{ 15 \cot \sqrt{\frac{\Omega}{2}} - 7 \tan \sqrt{\frac{\Omega}{2}} \right\} \tag{4.15}$$

holds on $U_o - \{o\}$. This completes the proof of Theorem 3.

Next, we shall give an outline of the proof of Theorem 4. Let ${}^*\mathfrak{CP}^2 = ({}^*\mathfrak{CP}^2, {}^*g)$ be the non-compact dual of the Cayley projective plane $\mathfrak{CP}^2 = (F_4/\text{Spin}(9), g)$. Then, we see that ${}^*\mathfrak{CP}^2$ is isometric to the Cayley hyperbolic plane $\mathfrak{CH}^2 = (F_{4(-20)}/\text{Spin}(9), {}^*g)$ and the corresponding Cartan decomposition of the Lie algebra $\mathbf{F}_{4(-20)}$ of the Lie group $F_{4(-20)}$ is given by

$$\mathbf{F}_{4(-20)} = \mathbf{D}_4 \oplus \sqrt{-1}\mathfrak{m} \tag{4.16}$$

in the complexification $\mathbf{F}_{4(-20)}$ of the Lie algebra \mathbf{F}_4 . Thus, taking account of (4.16), we easily check that the curvature tensor of \mathfrak{CH}^2 is only sign difference of curvature tensor R of \mathfrak{CP}^2 algebraically. Thus, by suitably modifying the arguments for the case of the Cayley projective plane suitably, we have Theorem 4.

5. Characteristic functions of rank one symmetric spaces

Summing up the results in [6], [7], [9] and ours of the present paper, we have the following list of the characteristic functions for the rank one symmetric spaces.

We here denote by $S^m(1)$, $H^m(-1)$, $\mathbb{C}P^n(1)$, $\mathbb{C}H^n(-1)$, $\mathbb{H}P^n(1)$, $\mathbb{H}H^n(-1)$, $\mathfrak{CP}^2(1)$, $\mathfrak{CH}^2(-1)$ the m -dimensional sphere of constant sectional curvature 1, m -dimensional hyperbolic space of constant sectional curvature -1 , $2n$ -dimensional complex projective space of constant holomorphic sectional curvature 1, $2n$ -dimensional complex hyperbolic space of constant holomorphic sectional curvature -1 , $4n$ -dimensional quaternion projective space of constant Q -sectional curvature 1, $4n$ -dimensional quaternion hyperbolic space of constant Q -sectional curvature -1 , Cayley projective plane and Cayley hyperbolic plane, respectively.

Space	Characteristic function
$S^m(1)$	$f(\Omega) = 1 + (m - 1)\sqrt{2\Omega} \cot(\sqrt{2\Omega})$
$H^m(-1)$	$f(\Omega) = 1 + (m - 1)\sqrt{2\Omega} \coth(\sqrt{2\Omega})$
$\mathbb{C}P^n(1)$	$f(\Omega) = 1 + \sqrt{\frac{\Omega}{2}} \left\{ (2n - 1) \cot\left(\sqrt{\frac{\Omega}{2}}\right) - \tan\left(\sqrt{\frac{\Omega}{2}}\right) \right\}$
$\mathbb{C}H^n(-1)$	$f(\Omega) = 1 + \sqrt{\frac{\Omega}{2}} \left\{ (2n - 1) \coth\left(\sqrt{\frac{\Omega}{2}}\right) + \tanh\left(\sqrt{\frac{\Omega}{2}}\right) \right\}$
$\mathbb{H}P^n(1)$	$f(\Omega) = 1 + \sqrt{\frac{\Omega}{2}} \left\{ (4n - 1) \cot\left(\sqrt{\frac{\Omega}{2}}\right) - 3 \tan\left(\sqrt{\frac{\Omega}{2}}\right) \right\}$
$\mathbb{H}H^n(-1)$	$f(\Omega) = 1 + \sqrt{\frac{\Omega}{2}} \left\{ (4n - 1) \coth\left(\sqrt{\frac{\Omega}{2}}\right) + 3 \tanh\left(\sqrt{\frac{\Omega}{2}}\right) \right\}$
$\mathfrak{C}P^2(1)$	$f(\Omega) = 1 + \sqrt{\frac{\Omega}{2}} \left\{ 15 \cot\left(\sqrt{\frac{\Omega}{2}}\right) - 7 \tan\left(\sqrt{\frac{\Omega}{2}}\right) \right\}$
$\mathfrak{C}H^2(-1)$	$f(\Omega) = 1 + \sqrt{\frac{\Omega}{2}} \left\{ 15 \coth\left(\sqrt{\frac{\Omega}{2}}\right) + 7 \tanh\left(\sqrt{\frac{\Omega}{2}}\right) \right\}$

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