# Hyperinvariant subspaces for contractions of class $\boldsymbol{C}_{\text {. }}$ 

By Mitsuru Uchiyama

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## 1. Introduction

Let $T$ be a bounded operator on a separable Hilbert space $\mathfrak{G}$. A subspace $\mathfrak{L}$ of $\mathfrak{E}$ is said to be hyperinvariant for $T$ if $\mathbb{Z}$ is invariant for every operator that commutes with $T$. In [2] the hyperinvariant subspaces for a unilateral shift were determined, and those for an isometry in [1]. Recall that $T$ is said to be of class $C_{.0}$ if $T$ is a contraction (i.e., $\|T\| \leqq 1$ ) and $T^{* n} \longrightarrow 0$ (strongly) as $n \longrightarrow \infty$. Hence a unilateral shift is of class $C_{.0}$. Let $T$ be of class $C_{0}$. Then it necessarily follows that

$$
\delta_{*} \equiv \operatorname{dim}\left(1-T T^{*}\right) \mathfrak{E} \geqq \operatorname{dim}\left(1-T^{*} T\right) \mathfrak{S} \equiv \delta
$$

(see [6]). In the case of $\delta_{*}=\boldsymbol{\delta}<\infty$, in an earlier paper [8] we established a canonical isomorphism between the lattice of hyperinvariant subspaces for $T$ and that for the Jordan model of $T$. In this paper we extend this result to the case of $\delta<\delta_{*}<\infty$. For an operator $T$ of this class we shall present complete description of the hyperinvariant subspaces $9 \ell$ with the property that every subspace of $\mathfrak{N}$ hyperinvariant for $T$ is hyperinvariant for the restricted operator $T \mid \mathfrak{R}$. The author wishes to express his gratitude to Prof. T. Ando for his constant encouragement.

## 2. Preliminaries

Let $\theta$ be an $n \times m(\infty>n \geqq m)$ matrix over $H^{\infty}$ on the unit circle. Such a matrix $\theta$ is called inner if $\theta(z)$ is isometry a. e. on the unit circle. For such an inner function $\theta$ a Hilbert space $\mathscr{S}(\theta)$ and an operator $S(\theta)$ are defined by

$$
\begin{equation*}
\mathfrak{S}(\theta)=H_{n}^{2} \ominus \theta H_{m}^{2} \quad \text { and } \quad S(\theta) h=P_{\theta}(S h) \quad \text { for } h \text { in } \mathscr{S}(\theta), \tag{1}
\end{equation*}
$$

where $H_{n}^{2}$ is the Hardy space of $n$-dimensional (column) vector valued functions, $P_{\theta}$ is the projection from $H_{n}^{2}$ onto $\mathfrak{K}(\theta)$, and $S$ is the simple unilateral shift, that is, $(S h)(z)=z h(z)$. A contraction $T$ of class $C_{\cdot 0}$ with $\delta_{*}=n$ and $\delta=m$ is unitarily equivalent to an $S(\theta)$ of this type [7]. Thus in the sequel we may discuss $S(\theta)$ in place of $T$.

For a completely non unitary contraction $T$, it is possible to define
$\phi(T)$ for every function $\phi$ in $H^{\infty}$. In particular, for $S(\theta)$ given above $\phi(S$ $(\theta))$ can be equivalently defined by the following:

$$
\phi(S(\theta)) h=P_{\theta} \phi h \quad \text { for } h \text { in } \quad \mathscr{S}(\theta) \quad \text { (see [5], [7]) } .
$$

If there is a function $\phi$ such that $\phi(T)=0$, then $T$ is said to be of class $C_{0}$. $T$ of class $C_{\cdot}$ with $\delta \leqq \delta_{*}<\infty$ is of class $C_{0}$ if and only if $\delta=\delta_{*}$ [7].

Suppose $T_{1}$ is a bounded operator on $\mathfrak{S}_{1}$ and $T_{2}$ a bounded operator on $\mathfrak{S}_{2}$. If there exists a complete injective family $\left\{X_{\alpha}\right\}$ from $\mathfrak{K}_{1}$ to $\mathfrak{S}_{2}$ (i. e., for each $\alpha, X_{\alpha}$ is an one to one bounded operator from $\mathfrak{S}_{1}$ to $\mathfrak{S}_{2}$ and $\left.\vee X_{\alpha} \mathfrak{S}_{1}=\mathfrak{S}_{2}\right)$ such that for each $\alpha X_{\alpha} T_{1}=T_{2} X_{\alpha}$, then we write $T_{1}{ }^{\text {ci }}\left\langle T_{2}\right.$. If $T_{1}{ }^{\mathrm{ci}} \prec T_{2}$ and $T_{2}{ }^{\mathrm{ci}} \prec T_{1}$, then $T_{1}$ and $T_{2}$ are said to be completely injectionsimilar, and denote by $T_{1} \stackrel{\text { ci }}{\sim} T_{2}$ [6].

An $n \times m(n \geqq m)$ normal inner matrix $N^{\prime}$ over $H^{\infty}$ is, by definition, of the form :

$$
N^{\prime}=\left.\left[\begin{array}{cccc}
\phi_{1} & 0 & \cdots & 0  \tag{2}\\
0 & \psi_{2} & \cdots & 0 \\
\vdots & \ddots & \vdots \\
0 & 0 & \ddots & \psi_{m} \\
\hline 0 & 0 & \cdots & 0 \\
0 & 0 & \cdots & 0
\end{array}\right]\right|_{n-m}
$$

where, for each $i, \phi_{i}$ is a scalar inner function and a divisor of its succesor. Then

$$
S\left(N^{\prime}\right)=S\left(\psi_{1}\right) \oplus \cdots \oplus S\left(\psi_{m}\right) \oplus \underbrace{S \cdots \oplus S}_{n-m}
$$

is called a Jordan operator.
Let $\theta$ be an $n \times m(\infty>n \geqq m)$ inner matrix over $H^{\infty}$ and $N$ a corresponding normal matrix, i. e., $N$ is the $n \times m$ normal inner matrix of the form (2), where $\psi_{1}, \psi_{2} \cdots, \psi_{m}$ are the "invariant factors" of $\theta$, that is,

$$
\phi_{k}=\frac{d_{k}}{d_{k-1}} \quad \text { for } \quad k=1,2, \cdots, m
$$

where $d_{0}=1$ and $d_{k}$ is the largest common inner divisor of all the minors of order $k$. In this case, Nordgren [4] has shown that there exist pairs of matrices $\Delta_{i}, \Lambda_{i}$ and $\Delta_{i}^{\prime}, \Lambda_{i}^{\prime}(i=1,2)$ satisfying

$$
\begin{equation*}
\Delta_{i} \theta=N \Lambda_{i} \tag{3}
\end{equation*}
$$

$$
\begin{equation*}
\theta \Lambda_{i}^{\prime}=\Delta_{i}^{\prime} N, \tag{3}
\end{equation*}
$$

$$
\begin{equation*}
\left(\operatorname{det} \Lambda_{i}\right)\left(\operatorname{det} \Lambda_{i}^{\prime}\right) \wedge d_{m}=1 \tag{4}
\end{equation*}
$$

$$
\begin{align*}
& \left(\operatorname{det} \Delta_{1}\right)\left(\operatorname{det} \Delta_{1}^{\prime}\right) \wedge\left(\operatorname{det} \Delta_{2}\right)\left(\operatorname{det} \Lambda_{2}^{\prime}\right)=1  \tag{5}\\
& \left(\operatorname{det} \Lambda_{1}\right)\left(\operatorname{det} \Lambda_{1}^{\prime}\right) \wedge\left(\operatorname{det} \Lambda_{2}\right)\left(\operatorname{det} \Lambda_{2}^{\prime}\right)=1 \tag{5}
\end{align*}
$$

where $x \wedge y$ denotes the largest common inner divisor of scalar function $x$ and $y$ in $H^{\infty}$. Setting

$$
\begin{align*}
& X_{i}=P_{N} \Delta_{i} \mid H(\theta) \quad \text { and }  \tag{6}\\
& Y_{i}=P_{\theta} \Delta_{i}^{\prime} \mid H(N) \quad \text { for } \quad i=1,2 \tag{6}
\end{align*}
$$

$\left\{X_{1}, X_{2}\right\}$ and $\left\{Y_{1}, Y_{2}\right\}$ are complete injective families satisfying the following relations:

$$
\begin{align*}
& X_{i} S(\theta)=S(N) X_{i} \quad \text { and }  \tag{7}\\
& S(\theta) Y_{i}=Y_{i} S(N) \quad \text { for } \quad i=1,2 \tag{8}
\end{align*}
$$

This implies $S(\theta) \stackrel{\text { ci }}{\sim} S(N)$ (cf. [6]).
To every subspace $\mathbb{Z}$ of $\mathfrak{G}(\theta)$, invariant for $S(\theta)$, there corresponds an unique factorization $\theta=\theta_{2} \theta_{1}$ of $\theta$ such that $\theta_{1}$ is an $k \times m$ inner matrix and $\theta_{2}$ is an $n \times k$ inner matrix ( $n \geqq k \geqq m$ ) satisfying

$$
\mathfrak{Z}=\theta_{2}\left\{H_{k}^{2} \Theta \theta_{1} H_{m}^{2}\right\}=\theta_{2} H_{k}^{2} \Theta \theta H_{m}^{2}
$$

In this case $S(\theta) \mid \mathfrak{R}$ and $P_{\mathcal{B}^{\perp}} S(\theta) \mid \mathfrak{R}^{\perp}$ are unitarily equivalent to $S\left(\theta_{1}\right)$ and $S\left(\theta_{2}\right)$, respectively. For this discussion see [7].

Let $M$ be an $m \times m$ normal inner matrix over $H^{\infty}$. Then, in [8], we showed that, in order that a factorization $M=M_{2} M_{1}$ corresponds to a subspace hyperinvariant for $S(M)$, it is necessary and sufficient that both $M_{1}$ and $M_{2}$ are $m \times m$ normal inner matrices.

## 3. Jordan operator

Let $N=\left[\begin{array}{c}M \\ 0\end{array}\right]$ be an $n \times m$ normal inner matrix over $H^{\infty}$, that is, $M$ is an $m \times m$ normal inner matrix over $H^{\infty}$. Then $S(N)$ on $\mathfrak{S}(N)$ are identified with

$$
S(M) \oplus S_{n-m} \quad \text { on } \quad \mathfrak{S}(M) \oplus H_{n-m}^{2}
$$

where $\left(S_{n-m} h\right)(z)=z h(z)$ for $h$ in $H_{n-m}^{2}$.
Let $\mathfrak{N}$ be a hyperinvariant subspace for $S(N)$. Then it is clear that $\mathfrak{R}$ is decomposed to the direct sum,

$$
\mathfrak{R}=\mathfrak{N}_{1} \oplus \mathfrak{R}_{2},
$$

where $\mathfrak{R}_{1}$ is a subspace of $\mathfrak{G}(M)$, hyperinvariant for $S(M)$, and $\mathfrak{R}_{2}$ is a subspace of $H_{n-m}^{2}$, hyperinvariant for $S_{n-m}$. In this case we have the fol-
lowing lemma.
Lemma 1. For $\mathfrak{R}_{1}$ and $\mathfrak{N}_{2}$ which are hyperinvariant for $S(M)$ and $S_{n-m}$, respectively, in order that the direct sum $\mathfrak{N}=\mathfrak{N}_{1} \oplus \mathfrak{R}_{2}$ is hyperinvariant for $S(N)$, it is necessary and sufficient that $\mathfrak{R}_{2}=\{0\}$ or there exists an inner function $\phi$ such that $\mathfrak{R}_{2}=\phi H_{n-m}^{2}$ and $\mathfrak{R}_{1} \supseteq \phi(S(M)) \mathfrak{g}(M)$.

Proof. An operator $X=\left[\begin{array}{ll}Y_{11} & Y_{12} \\ Y_{21} & Y_{22}\end{array}\right]$ commutes with $S(N)$, if and only if $Y_{i j}$ satisfy the following conditions:

$$
\begin{aligned}
& Y_{11} S(M)=S(M) Y_{11}, \quad Y_{12} S_{n-m}=S(M) Y_{12} \\
& Y_{21} S(M)=S_{n-m} Y_{21} \quad \text { and } \quad Y_{22} S_{n-m}=S_{n-m} Y_{22}
\end{aligned}
$$

Since $S(M)^{n} \longrightarrow 0$ as $n \longrightarrow \infty$ and $S_{n-m}$ is isometry, we have $Y_{21}=0$. Thus if $\mathfrak{R}_{2}=\{0\}$, then it follows that $X \mathfrak{N} \subseteq \mathfrak{N}$ for every $X$ commuting $S(N)$. By the lifting theorem (cf. [5], [7]), a bounded operator $Y_{12}$ from $H_{n-m}^{2}$ to $H(M)$ intertwines $S_{n-m}$ and $S(M)$, if and only if there is an $m \times(n-m)$ matrix $\Omega$ over $H^{\infty}$ such that $Y_{12}=P_{M} \Omega$. Thus, if $\mathfrak{R}_{2}=\phi H_{n-m}^{2}$ and $\mathfrak{R}_{1} \supseteqq \phi$ $(S(M)) \mathfrak{S}(M)$ for some inner function $\phi$, then we have

$$
\begin{aligned}
X \mathfrak{N} & =\left(Y_{11} \mathfrak{R}_{1}+Y_{12} \phi H_{n-m}^{2}\right) \oplus Y_{22} \phi H_{n-m}^{2} \\
& \subseteq\left(\mathfrak{N}_{1}+P_{M} \Omega \phi H_{n-m}^{2}\right) \oplus \phi H_{n-m}^{2} \\
& \subseteq\left(\mathfrak{N}_{1}+P_{M} \phi H_{m}^{2}\right) \oplus \phi H_{n-m}^{2} \\
& =\left(\mathfrak{R}_{1}+\phi(S(M)) \mathfrak{S}(M)\right) \oplus \phi H_{n-m}^{2} \\
& \subseteq \mathfrak{N}_{1} \oplus \phi H_{n-m}^{2}=\mathfrak{R}
\end{aligned}
$$

for every $X$ commuting with $S(N)$.
Conversely suppose $\mathfrak{n}=\mathfrak{N}_{1} \oplus \mathfrak{N}_{2}$ is hyperinvariant for $S(N)$, and $\mathfrak{R}_{2} \neq\{0\}$. Then by [2] there exists an inner function $\phi$ such that $\mathfrak{R}_{2}=\phi H_{n-m}^{2}$. Let $\Omega_{i}(i=1,2, \cdots, m)$ be the $m \times(n-m)$ matrix such that the $(j, k)$-th entry of $\Omega_{i}$ is 1 for $(j, k)=(i, 1)$ and 0 for $(j, k) \neq(i, 1)$. Setting

$$
X_{i}=\left[\begin{array}{cc}
0 & Y_{i} \\
0 & 0
\end{array}\right] \quad \text { and } \quad Y_{i}=P_{M} \Omega_{i},
$$

each $X_{i}$ commutes with $S(N)$, hence we have $\mathfrak{N}_{1} \supseteq \sum_{i=1}^{n} Y_{i} \phi H_{n-m}^{2}=P_{M} \phi H_{m}^{2}=$ $\phi(S(M)) \mathfrak{S}(M)$. This completes the proof.

ThEOREM 1. In order that a factorization $N=N_{2} N_{1}$ of $N$ into the product of an $n \times k$ inner matrix $N_{2}$ and an $k \times m$ inner matrix $N_{1}(n \geqq k$ $\geqq m$ ) corresponds to a hyperinvariant subspace $\mathfrak{N}$ for $S(N)$, it is necessary and sufficient that $N_{1}$ and $N_{2}$ are normal matrices satisfying (i) or (ii):
(i) $k=m$,
(ii) $k=n$ and $N_{2}$ has the form $\left[\begin{array}{c:c}M_{2} & 0 \\ \hdashline 0 & \phi 1_{n-m}\end{array}\right]$

Proof. First, assume that $k=m$, and both $N_{1}$ and $N_{2}$ are normal inner matrices. Then, setting $N_{2}=\left[\begin{array}{c}M_{2}^{\prime} \\ 0\end{array}\right]$, it follows that $N_{2}\left\{H_{m}^{2} \ominus N_{1} H_{m}^{2}\right\}=M_{2}^{\prime}\left\{H_{m}^{2}\right.$ $\left.\Theta N_{1} H_{m}^{2}\right\}$ is hyperinvariant for $S(M)$ (see [8]]. Therefore, by Lemma 1, it is hyperinvariant for $S(N)$. Next, assume that $N_{1}$ and $N_{2}$ are normal matrices satisfying (ii). Set $N_{1}=\left[\begin{array}{c}M_{1} \\ 0\end{array}\right]$. Then we have

$$
\mathfrak{R}=N_{2}\left\{H_{n}^{2} \ominus N_{1} H_{m}^{2}\right\}=M_{2}\left\{H_{m}^{2} \ominus M_{1} H_{m}^{2}\right\} \oplus \phi H_{n-m}^{2} .
$$

Normality of $M_{1}$ and $M_{2}$ implies that $M_{2}\left\{H_{m}^{2} \ominus M_{1} H_{m}^{2}\right\}$ is hyperinvariant for $S(M)$. On the other hand, normality of $N_{2}$ implies $M_{2} H_{m}^{2} \supseteq \phi H_{m}^{2}$, and hence we have

$$
M_{2} H_{m}^{2} \ominus M H_{m}^{2} \supseteq \phi(S(M) \mathfrak{S}(M) .
$$

Thus from Lemma 1 we deduce that $\mathfrak{R}$ is hyperinvariant for $S(N)$.
Conversely, first, assume that $\mathfrak{R}=\mathfrak{M}_{1} \oplus\{0\}$ is hyperinvariant for $S(N)$, and $N=N_{2} N_{1}$ is the factorization corresponding to $\mathfrak{R}$. Since $S(N) \mid \mathfrak{\Re}=$ $S(M) \mid \Re_{1}$ is of class $C_{0}, S\left(N_{1}\right)$ is of class $C_{0}$ (cf. 2). This implies that $N_{1}$ is an $m \times m$ inner matrix, that is, $k=m$. Setting $N_{2}=\left[\begin{array}{c}M_{2} \\ \Gamma\end{array}\right]$, where $M_{2}$ is an $m \times m$ matrix and $\Gamma$ an $(n-m) \times m$ matrix, we have

$$
M=M_{2} N_{1}, \mathfrak{R}_{1}=M_{2}\left\{H_{m}^{2} \ominus N_{1} H_{m}^{2}\right\} \quad \text { and } \quad \Gamma H_{m}^{2}=\{0\} .
$$

Since $\Gamma=0$ and $N_{2}$ is inner, it follows that $M_{2}$ is inner. Thus the hyperinvariance of $\mathfrak{\Re}_{1}$ corresponding to $M=M_{2} N_{1}$ implies that $M_{2}$ and $N_{1}$ are $m$ $\times m$ normal inner matrices. Next assume that $\mathfrak{R}=\mathfrak{R}_{1} \oplus \phi H_{n-m}^{2}$ and $\mathfrak{R}_{1} \supseteq$ $\phi(S(M)) \mathfrak{S}(M)$. Clearly we have

$$
P_{s \perp} S(N)\left|\mathfrak{R}^{\perp}=P_{\Re_{1}^{1}} S(M)\right| \mathfrak{R}_{1}^{\perp} \oplus S\left(\phi 1_{n-m}\right),
$$

where $\mathfrak{\Re}_{1}^{\perp}$ denotes the orthogonal complement of $\mathfrak{R}_{1}$ in $\mathfrak{g}(M)$. Since the right-hand operator is of class $C_{0}$ (page 129 of [7]), $S\left(N_{2}\right)$ is of class $C_{0}$. This implies that $N_{2}$ is an $n \times n$ matrix; i. e., $k=n$. To the hyperinvariant subspace $\Re_{1}$ for $S(M)$ there corresponds a factorization $M=M_{2} M_{1}$, where $M_{1}$ and $M_{2}$ are $m \times m$ normal inner matrices. Thus setting $N_{2}^{\prime}=\left[\begin{array}{cc}M_{2} & 0 \\ 0 & \phi 1_{n-m}\end{array}\right]$ and $N_{1}^{\prime}=\left[\begin{array}{c}M_{1} \\ 0\end{array}\right]$, it is clear that $N=N_{2}^{\prime} N_{1}^{\prime}$ and $\mathfrak{R}=N_{2}^{\prime}\left\{H_{n}^{2} \ominus N_{1}^{\prime} H_{m}^{2}\right\}$. From
the uniqueness of the factorization of $N$ into product of two inner matrices corresponding to (hyper) invariant subspace $\mathfrak{N}$, only this factorization $N=N_{2}^{\prime} N_{1}^{\prime}$ corresponds to $\mathfrak{R}$, that is, $N_{2}=N_{2}^{\prime}$ and $N_{1}=N_{1}^{\prime}$. Since

$$
M_{2}\left\{H_{m}^{2} \ominus M_{1} H_{m}^{2}\right\}=\mathfrak{R}_{1} \supseteqq \phi(S(M)) \mathfrak{R}(M)=P_{M} \phi H_{m}^{2}
$$

we have $M_{2} H_{m}^{2} \supseteqq \phi H_{m}^{2}$; this implies that every entry of $M_{2}$ is a divisor of $\phi$. Therefore $N_{2}$ is an $n \times n$ normal inner matrix. Hence $N_{1}$ and $N_{2}$ are normal inner matrices satisfying (ii).

## 4. Lattice isomorphism

Let $\theta$ be an $n \times m$ inner matrix and $N$ be the corresponding normal inner matrix. Set

$$
\begin{equation*}
\alpha(\mathfrak{Z})=\underset{Z}{\bigvee}\{Z \mathfrak{R}: Z S(\theta)=S(N) Z\} \tag{9}
\end{equation*}
$$

and

$$
\begin{equation*}
\beta(\mathfrak{R})=\underset{W}{\vee}\{W \mathfrak{N}: W S(N)=S(\theta) W\} \tag{10}
\end{equation*}
$$

for each subspace $\mathfrak{Z}$ and $\mathfrak{N}$ hyperinvariant for $S(\theta)$ and $S(N)$, respectively, where $\vee \mathfrak{R}_{i}$ denotes the minimum subspace including all $\mathfrak{R}_{i}$. Since $S(\theta) \stackrel{\text { ci }}{\sim}$ $S(N)$, it is clear that $\alpha(\mathbb{R})$ is the non trivial hyperinvarinat subspace for $S(N)$, if $\mathfrak{R}$ is non trivial.

Lemma 2. If $\theta=\theta_{2} \theta_{1}$ is the factorization corresponding to a non trivial hyperinvariant subspace $\mathfrak{Z}$ for $S(\theta)$, then $\theta_{1}$ is an $m \times m$ inner matrix, or $\theta_{2}$ is an $n \times n$ inner matrix.

Proof. Let $S(\theta)=\left[\begin{array}{cc}T_{1} & * \\ 0 & T_{2}\end{array}\right]$ and $S(N)=\left[\begin{array}{cc}S_{1} & * \\ 0 & S_{2}\end{array}\right]$ be the triangulations corresponding to $\mathfrak{K}(\theta)=\Omega \oplus \mathbb{Z}^{\perp}$ and $\mathfrak{K}(N)=\alpha(\mathfrak{R}) \oplus \alpha(\mathfrak{Z})^{\perp}$, respectively. Theorem 1 implies that $S_{1}$ or $S_{2}$ is of class $C_{0}$. First, suppose $u\left(S_{1}\right)=0$ for some $u$ in $H^{\infty}$. For the bounded operator $X_{1}$ given by (6) and every $f$ in $\mathcal{S}$, in virtue of (3), it follows that

$$
\begin{aligned}
X_{1} u\left(T_{1}\right) f & =X_{1} u(S(\theta)) f=P_{N} \Delta_{1} P_{\theta} u f=P_{N} \Delta_{1} u f \\
& =P_{N} u \Delta_{1} f=u(S(N)) X_{1} f=0
\end{aligned}
$$

Since $X_{1}$ is an injection, we have $u\left(T_{1}\right) f=0$, which implies that $T_{1}$ is of class $C_{0}$, that is, $\theta_{1}$ is an $m \times m$ inner matrix. Next suppose $S_{2}$ is of class $C_{0}$, hence so is $S_{2}^{*}$. For $Y_{i}$ given by (6) and every $Z$ such that $Z S(\theta)=$ $S(N) Z$, in virtue of (8), $Y_{i} Z$ commutes with $S(\theta)$; this implies $Y_{i} Z \mathbb{G} \subseteq \mathbb{Z}$ and hence $Y_{i} \alpha(\mathfrak{R}) \subseteq \mathbb{R}$. Thus we have $Y_{i}^{*} \mathbb{R}^{\perp} \subseteq \alpha(\mathbb{Z})^{\perp}$. From this and (8), for each
$h$ in $\mathbb{R}^{\perp}$, it follows that

$$
Y_{i}^{*} T_{2}^{*} h=S_{2}^{*} Y_{i}^{*} h \quad \text { for } \quad i=1,2 .
$$

From this we can deduce that

$$
Y_{i}^{*} u\left(T_{2}^{*}\right) h=u\left(S_{2}^{*}\right) Y_{i}^{*} h \text { for every } u \text { in } H^{\infty},
$$

(see [7] chap 3). Since $Y_{1} \mathfrak{G}(N) \vee Y_{2} \mathfrak{G}(N)=\mathfrak{G}(\theta)$, we have $u\left(T_{2}^{*}\right)=0$ for $u$ satisfying $u\left(S_{2}^{*}\right)=0$. Therefore $\theta_{2}$ is an $n \times n$ inner matrix. This completes the proof.

The following theorem implies that the mapping $\alpha: \Omega \longrightarrow \alpha(\Omega)$ is isomorphism from the lattice of hyperinvariant subspaces for $S(\theta)$ onto that for $S(N)$, and its inverse is given by $\beta: \mathfrak{R} \longrightarrow \beta(\mathfrak{Y})$.

Theorem 2. For $X_{i}$ and $Y_{i}(i=1,2)$ given by (6) and (6)',

$$
\begin{aligned}
& \alpha(\mathfrak{R})=X_{1} \mathfrak{R} \vee X_{2} \mathfrak{R}, \quad \text { and } \quad \beta \cdot \alpha(\mathfrak{R})=\mathfrak{R}, \\
& \beta(\mathfrak{R})=Y_{1} \mathfrak{P} \vee Y_{2} \mathfrak{M} \text { and } \quad \alpha \cdot \beta(\mathfrak{R})=\mathfrak{R},
\end{aligned}
$$

where $\mathfrak{Z}$ and $\mathfrak{R}$ are arbitrary hyperinvariant subspaces for $S(\theta)$ and $S(N)$, respectively.

Proof. Let $\theta=\theta_{2} \theta_{1}$ and $N=N_{2} N_{1}$ be the factorizations of $\theta$ and $N$ corresponding to $\mathbb{Z}$ and $\alpha(\Omega)$, respectively. Then the proof of Lemma 2 implies that both $\theta_{1}$ and $N_{1}$ are $k \times m$ matrices and both $\theta_{2}$ and $N_{2}$ are $n \times$ $k$ matrices, where $k=n$ or $k=m$. Since $X_{i} \mathfrak{R} \subseteq \alpha(\mathfrak{Z})$ and $Y_{i} \alpha(\mathfrak{Z}) \subseteq \mathfrak{R}$, it clearly follows that

$$
\Delta_{i} \theta_{2} H_{k}^{2} \subseteq N_{2} H_{k}^{2} \quad \text { and } \quad \Delta_{i}^{\prime} N_{2} H_{k}^{2} \subseteq \theta_{2} H_{k}^{2},
$$

which guarantee the existence of $k \times k$ matirces $A_{i}$ and $B_{i}$ over $H^{\infty}$ satisfying

$$
\begin{equation*}
\Delta_{i} \theta_{2}=N_{2} A_{i} \quad \text { and } \quad \Delta_{i}^{\prime} N_{2}=\theta_{2} B_{i} . \tag{13}
\end{equation*}
$$

This and (3) implies that

$$
\begin{equation*}
A_{i} \theta_{1}=N_{1} \Lambda_{i} \quad \text { and } \quad B_{i} N_{1}=\theta_{1} \Lambda_{i}^{\prime} . \tag{13}
\end{equation*}
$$

By (13) we have

$$
\begin{equation*}
\Delta_{i}^{\prime} \Delta_{i} \theta_{2}=\theta_{2} B_{i} A_{i}, \tag{14}
\end{equation*}
$$

and by (13)'

$$
\begin{equation*}
B_{i} A_{i} \theta_{1}=\theta_{1} \Lambda_{i}^{\prime} \Lambda_{i} . \tag{1}
\end{equation*}
$$

Thus, if $k=n$, then $\operatorname{det} A_{i}$ is a divisor of $\left(\operatorname{det} \Delta_{i}\right)\left(\operatorname{det} \Delta_{i}^{\prime}\right)$, and if $k=m$ then $\operatorname{det} A_{i}$ is a divisor of $\left(\operatorname{det} \Lambda_{i}\right)\left(\operatorname{det} \Lambda_{i}^{\prime}\right)$. To prove the first relation of (11), suppose that

$$
f \in \alpha(\mathbb{R}) \ominus\left\{X_{1} \mathfrak{Z} \vee X_{2} \mathbb{Z}\right\}
$$

Then $f$ is orthogonal to $\Delta_{1} \theta_{2} H_{k}^{2} \vee \Delta_{2} \theta_{2} H_{k}^{2}$. On the other hand $f \in \alpha(\mathbb{Z})$ implies the existence of $g$ belonging to $H_{k}^{2} \ominus N_{1} H_{m}^{2}$ such that $f=N_{2} g$. Thus for every $h$ in $H_{k}^{2}$, we have for $i=1,2$

$$
\begin{equation*}
0=\left(f, \Delta_{i} \theta_{2} h\right)=\left(N_{2} g, N_{2} A_{i} h\right)=\left(g, A_{i} h\right) . \tag{15}
\end{equation*}
$$

If $k=n$, then, by (5) and Beurling's theorem

$$
A_{i} H_{n}^{2} \supseteq\left(\operatorname{det} A_{i}\right) H_{m}^{2} \supseteq\left(\operatorname{det} \Delta_{i}\right)\left(\operatorname{det} \Delta_{i}^{\prime}\right) H_{n}^{2}
$$

induce $A_{1} H_{n}^{2} \vee A_{2} H_{n}^{2}=H_{n}^{2}$ and hence $g=0$. If $k=m$, then it follows that from (13) and (4) det $N_{1}$ is a divisor of $d_{m}$, and that $A_{i} H_{m}^{2} \supseteq\left(\operatorname{det} \Lambda_{i}\right)$ (det $\left.\Lambda_{i}^{\prime}\right) H_{m}^{2}$; this implies, by (4), $N_{1} H_{m}^{2} \vee A_{i} H_{m}^{2}=H_{m}^{2}$. Consequently we have $g=$ 0 . Thus we showed that if $k=n$, then $\alpha(\mathfrak{R})=X_{1} \mathbb{R} \vee X_{2} \mathbb{R}$, and if $k=m$, then $\alpha(\mathfrak{R})=\overline{X_{1} \mathfrak{R}}=\overline{X_{2} \mathbb{Z}}$. The rest is proved in a similar way. Thus we can conclude the proof.

Corollary 1. Let $\theta$ be an $n \times m(n>m)$ inner matrix over $H^{\infty}$. Then for any non constant scalar inner function $\phi, \overline{\phi(S(\theta)) \mathfrak{S}(\theta)}$ is a non trivial hyperinvariant subspace for $S(\theta)$.

Proof. Since $\left\{X_{1}, X_{2}\right\}$ is a complete injective family, it is clear that

$$
\overline{\alpha(\phi(S(\theta)) \mathfrak{S}(\theta))}=\overline{\phi(S(N)) \mathfrak{K}(N)}
$$

The following relation:

$$
\mathfrak{S}(M) \oplus \phi H_{n-m}^{2} \supseteqq \phi(S(N)) \mathscr{N}(N) \supseteqq\{0\} \oplus \phi H_{n-m}^{2}
$$

implies that $\overline{\phi(S(N)) \mathfrak{K}(N)}$ is trivial and hence so $\overline{\phi(S(\theta)) \mathfrak{K}(\theta)}$ is by Theorem 2.

Corollary 2. $K \phi(S(\theta))=\{h \in \mathfrak{S}(\theta): \phi(S(\theta)) h=0\}$ is a non trivial $h y$ perinvariant subspace for $S(\theta)$ if and only if $\phi \wedge d_{m} \neq 1$.

Proof. It is clear that $K \phi(S(\theta))$ is hyperinvariant for $S(\theta)$ and

$$
\alpha(K \phi(S(\theta)))=K \phi(S(N))=K \phi(S(M)) \oplus\{0\}
$$

Since, by the definition, we have $d_{m}=\operatorname{det} M$, we must show that

$$
K \phi(S(M))=\{0\} \quad \text { if and only if } \quad \phi \wedge(\operatorname{det} M)=1
$$

But this results have already been proved in [3].

## 5. Restricted operators

For an arbitrary subspace $\mathfrak{Z}$ of $\mathfrak{K}(\theta)$ we define the subspace $\alpha^{\prime}(\mathfrak{Z})$ of
$\mathfrak{S}(N)$ by

$$
\begin{equation*}
\alpha^{\prime}(\mathfrak{Z})=X_{1} \mathfrak{Z} \vee X_{2} \mathfrak{Z} \tag{15}
\end{equation*}
$$

Similarly define the subspace $\beta^{\prime}(\mathfrak{N})$ of $\mathfrak{F}(\theta)$ by

$$
\begin{equation*}
\beta^{\prime}(\mathfrak{R})=Y_{1} \mathfrak{N} \vee Y_{2} \mathfrak{N} \quad \text { for a subspace } \mathfrak{N} \text { of } \mathfrak{S}(N) \tag{16}
\end{equation*}
$$

Then by Theorem $2 \alpha^{\prime}(\mathfrak{Z})=\alpha(\mathfrak{R})$ if $\mathfrak{R}$ is hyperinvariant for $S(\theta)$.
THEOREM 3. Let $\mathbb{R}$ be a hyperinvariant subspace for $S(\theta)$. If $\mathbb{Z}^{\prime}$ is a subspace of $\mathfrak{R}$, hyperinvariant for $S(\theta) \mid \mathbb{Z}$, then $\alpha^{\prime}\left(\mathfrak{R}^{\prime}\right)$ is a subspace of $\alpha^{\prime}(\mathfrak{Z})$, hyperinvariant for $S(N) \mid \alpha^{\prime}(\mathfrak{Z})$ and $\beta^{\prime}\left(\alpha^{\prime}\left(\mathfrak{Z}^{\prime}\right)\right)=\mathfrak{Z}^{\prime}$.

Proof. Let $\theta=\theta_{2} \theta_{1}$ and $N=N_{2} N_{1}$ be the factorization of $\theta$ and $N$ corresponding to $\mathfrak{R}$ and $\alpha^{\prime}(\mathbb{R})=\alpha(\mathbb{Z})$, respectively.

$$
\mathfrak{Z}=\theta_{2}\left\{H_{k}^{2} \Theta \theta_{1} H_{m}^{2}\right\}
$$

implies that $\theta_{2} \mid \mathfrak{S}\left(\theta_{1}\right)$ is unitary from $\mathfrak{S}\left(\theta_{1}\right)$ onto $\mathfrak{L}$. Hence, in virtue of

$$
(S(\theta) \mid \mathfrak{Z})\left(\theta_{2} \mid \mathfrak{S}\left(\theta_{1}\right)\right)=\left(\theta_{2} \mid \mathfrak{S}\left(\theta_{1}\right)\right)\left(S\left(\theta_{1}\right)\right)
$$

it follows that $\left(\theta_{2} \mid \mathfrak{S}\left(\theta_{1}\right)\right)^{-1} \mathbb{Z}^{\prime}$ is hyperinvariant for $S\left(\theta_{1}\right)$. Now for $A_{i}$ and $B_{i}$ given by (13), from (14) or $(14)^{\prime} .\left(\operatorname{det} A_{i}\right)\left(\operatorname{det} B_{i}\right)$ is a divisor of $\left(\operatorname{det} \Delta_{i}\right)$ $\left(\operatorname{det} \Delta_{i}^{\prime}\right)$ or $\left(\operatorname{det} \Lambda_{i}\right)\left(\operatorname{det} \Lambda_{i}^{\prime}\right)$. Thus by (5) or $(5)^{\prime}$ we have

$$
\begin{equation*}
\left(\operatorname{det} A_{1}\right)\left(\operatorname{det} B_{1}\right) \wedge\left(\operatorname{det} A_{2}\right)\left(\operatorname{det} B_{2}\right)=1 \tag{17}
\end{equation*}
$$

It is easy to show that for $X_{i}^{\prime}=P_{N_{1}} A_{i} \mid \mathfrak{S}\left(\theta_{1}\right)$,

$$
X_{1}^{\prime}\left(\theta_{2} \mid \mathfrak{K}\left(\theta_{1}\right)\right)^{-1} \mathfrak{Z}^{\prime} \vee X_{2}^{\prime}\left(\theta_{2} \mid \mathfrak{H}\left(\theta_{1}\right)\right)^{-1} \mathfrak{Z}^{\prime}
$$

is hyperinvariant for $S\left(N_{1}\right)$, by making use of (13)', (4) and (17), as we have shown Theorem 2 by making use of (3), (4), (5) and (6). Since $N_{2} \mid \mathfrak{H}$ $\left(N_{1}\right)$ is unitary from $\mathfrak{S}\left(N_{1}\right)$ onto $\alpha^{\prime}(\mathfrak{Z})=\alpha(\mathfrak{Z})$,

$$
(S(N) \mid \alpha(\mathfrak{Z}))\left(N_{2} \mid \mathfrak{G}\left(N_{1}\right)\right)=\left(N_{2} \mid \mathfrak{S}\left(N_{1}\right)\right) S\left(N_{1}\right)
$$

implies that

$$
\begin{aligned}
& N_{2}\left(X_{1}^{\prime}\left(\theta_{2} \mid \mathfrak{S}\left(\theta_{1}\right)\right)^{-1} \mathbb{Z}^{\prime} \vee X_{2}^{\prime}\left(\theta_{2} \mid \mathfrak{K}\left(\theta_{1}\right)\right)^{-1} \mathbb{Z}^{\prime}\right) \\
& =N_{2}\left(P_{N_{1}} A_{1}\left(\theta_{2} \mid \mathfrak{G}\left(\theta_{1}\right)\right)^{-1} \mathfrak{Q}^{\prime} \vee P_{N_{1}} A_{2}\left(\theta_{2} \mid \mathfrak{L}\left(\theta_{1}\right)\right)^{-1} \mathfrak{Z}^{\prime}\right) \\
& =P_{N} N_{2} A_{1}\left(\theta_{2} \mid \mathfrak{K}\left(\theta_{1}\right)\right)^{-1} \mathfrak{Z}^{\prime} \vee P_{N} N_{2} A_{2}\left(\theta_{2} \mid \mathfrak{G}\left(\theta_{1}\right)\right)^{-1} \mathfrak{Z}^{\prime} \\
& =P_{N} \Delta_{1} \theta_{2}\left(\theta_{2} \mid \mathfrak{K}\left(\theta_{1}\right)\right)^{-1} \mathbb{R}^{\prime} \vee P_{N} \Delta_{2} \theta_{2}\left(\theta_{2} \mid \mathfrak{S}\left(\theta_{1}\right)\right)^{-1} \mathbb{R}^{\prime} \\
& =P_{N} \Delta_{1} \mathfrak{B}^{\prime} \vee P_{N} \Delta_{2} \mathfrak{L}^{\prime}=X_{1} \mathfrak{Z}^{\prime} \vee X_{2} \mathfrak{Z}^{\prime}=\alpha^{\prime}\left(\mathfrak{Z}^{\prime}\right)
\end{aligned}
$$

is hyperinvariant for $S(N) \mid \alpha^{\prime}(\mathfrak{Z}) . \quad \beta^{\prime}\left(\alpha^{\prime}\left(\mathfrak{Z}^{\prime}\right)\right)=\mathfrak{Z}^{\prime}$ is proved by the same way
as Theorem 2. Thus we complete the proof.
The same argument as the proof of Theorem 3 yields.
Theorem 3'. Let $\mathfrak{R}$ be a hyperinvariant subspace for $S(N)$. If $\mathfrak{M}^{Y}$ is a subspace of $\mathfrak{R}$, hyperinvariant for $S(N) \mid \mathfrak{R}$, then $\beta^{\prime}(\mathfrak{Y})$ is a subspace of $\beta^{\prime}(\mathfrak{\Re})$, hyperinvariant for $S(\theta) \mid \beta^{\prime}(\mathfrak{R})$, and $\alpha^{\prime}\left(\beta^{\prime}(\mathfrak{Y})\right)=\mathfrak{\Re}^{\prime}$.

Theorem 4. Let $\mathfrak{\&}$ be a subspace hyperinvariant for $S(\theta)$. Then $\mathfrak{Z}^{\prime}$ is a subspace of $\mathfrak{S}(\theta)$, hyperinvariant for $S(\theta)$, if it is a subspace of $\mathfrak{R}$, hyperinvariant for $S(\theta) \mid$.

Proof. Set $\alpha^{\prime}\left(\mathfrak{Z}^{\prime}\right)=\mathfrak{M}^{\prime}$ and $\alpha^{\prime}(\mathfrak{Z})=\alpha(\mathfrak{Z})=\mathfrak{R}$. Theorem 3 implies that $\mathfrak{Y}$ is hyperinvariant for $S(N) \mid \mathfrak{R}$. Let $N=N_{2} N_{1}$ be the factorization of $N$ corresponding to $\mathfrak{M}$. Then $\left(N_{2} \mid \mathfrak{G}\left(N_{1}\right)\right)^{-1} \mathfrak{Y}$ is a subspace of $\mathfrak{g}\left(N_{1}\right)$, hyperinvariant for $S\left(N_{1}\right)$. Since $N_{1}$ is a $k \times m(k=n$ or $k=m)$ normal inner matrix over $H^{\infty}$, by Theorem 1 there is an $l \times m$ normal inner matrix $N_{1}^{\prime}$ and an $k \times l$ normal inner matrix $N_{2}^{\prime}$ such that

$$
N_{1}=N_{2}^{\prime} N_{1}^{\prime} \quad \text { and } \quad\left(N_{2} \mid \mathfrak{S}\left(N_{1}\right)\right)^{-1} \mathfrak{M ^ { \prime }}=N_{2}^{\prime}\left\{H_{l}^{2} \ominus N_{1}^{\prime} H_{m}^{2}\right\},
$$

where $n \geqq k \geqq l \geqq m$, and $l=m$ or $l=n$. It is easy to show that $N_{2} N_{2}^{\prime}$ and $N_{1}^{\prime}$ satisfy the condition (i) or the condition (ii) of Theorem 1; this implies that

$$
\mathfrak{Y}^{\prime}=N_{2} N_{2}^{\prime}\left\{H_{\rho}^{2} \ominus N_{1}^{\prime} H_{m}^{2}\right\}
$$

is hyperinvariant for $S(N)$. Thus

$$
\beta\left(\mathfrak{M}^{\prime}\right)=\beta^{\prime}\left(\mathfrak{Y}^{\prime}\right)=\beta^{\prime}\left(\alpha^{\prime}\left(\mathfrak{Z}^{\prime}\right)\right)=\mathfrak{Z}^{\prime}
$$

is hyperinvariant for $S(\theta)$. Thus we conclude the proof.
Now, we determine a particular hyperinvariant subspace $\AA_{*}$ for $S(\theta)$ by the following relation:

$$
\mathfrak{R}_{*}=\left\{h \in \mathfrak{G}(\theta): S(\theta)^{n} h \longrightarrow 0 \text { as } n \longrightarrow \infty\right\} \text { ([7] P. 73). }
$$

Then, from $\alpha\left(\mathfrak{Z}_{*}\right) \subseteq \mathfrak{G}(M)$ and $\beta(\mathfrak{G}(M)) \subseteq \mathfrak{R}^{*}$, it follows that $\alpha\left(\mathfrak{R}_{*}\right)=\mathfrak{G}(M)$.
Theorem 5. Let \& be a subspace hyperinvariant for $S(\theta)$. In order that if $\mathfrak{R}^{\prime}$ is a subspace of $\mathfrak{R}$, hyperinvariant for $S(\theta)$, then $\mathfrak{Z}^{\prime}$ is hyperinvariant for $S(\theta) \mid \mathfrak{R}$, it is necessary and sufficient that there is a function $\phi$ in $H^{\infty}$ such that

$$
\mathfrak{Z}=\overline{\phi(S(\theta)) \mathfrak{K}(\theta)} \text { or } \quad \mathfrak{Z}=\overline{\phi(S(\theta)) \mathfrak{K}(\theta) \cap \mathfrak{Z}_{*} .}
$$

Proof. Sufficiency. Case $a$ : suppose $\mathcal{R}=\bar{\phi}(S(\theta)) \mathfrak{g}(\theta)$ and hence $\alpha(\mathfrak{Z})=\overline{\phi(S(N))} \mathfrak{\mathcal { E } ( N )}$. Let $N=N_{2} N_{1}$ be the factorization corresponding to $\alpha(\mathfrak{Z})$. Then $N_{2}=\operatorname{diag}\left(\phi_{1}, \cdots, \phi_{m}, \phi, \cdots, \phi\right)$, where $\phi_{i}=\phi \wedge \phi_{i}$ for $i=1,2, \cdots, m$. Set $\phi=\phi_{i} u_{i}$ and $\psi_{i}=\phi_{i} v_{i}$ for $i=1,2, \cdots, m$. Then it follows that for $i=$
$1,2, \cdots, m-1$,

$$
\phi_{i+1}=\phi \wedge \phi_{i+1}=\phi_{i} u_{i} \wedge \phi_{i} v_{i} \frac{\psi_{i+1}}{\psi_{i}}=\phi_{i}\left(u_{i} \wedge v_{i} \frac{\phi_{i+1}}{\phi_{i}}\right)
$$

Since $u_{i} \wedge v_{i}=1$, this implies that

$$
\begin{equation*}
\frac{\phi_{i+1}}{\phi_{i}} \wedge v_{i}=1 \tag{18}
\end{equation*}
$$

Let $\mathfrak{Z}^{\prime}$ be a subspace of $\mathfrak{Z}$, hyperinvariant for $S(\theta)$. Then there is the factorization $N_{1}=N_{2}^{\prime} N_{1}^{\prime}$, where $N_{1}^{\prime}$ is a $k \times m$ inner matrix and $N_{2}^{\prime}$ is an $n \times k$ inner matrix, such that $\alpha\left(\mathbb{Z}^{\prime}\right)=N_{2} N_{2}^{\prime}\left\{H_{k}^{2} \Theta N_{1}^{\prime} H_{n}^{2}\right\}$ (see [7] P. 291). The hyperinvariance of $\alpha\left(\mathbb{Z}^{\prime}\right)$ implies that $N_{2} N_{2}^{\prime}$ and $N_{1}^{\prime}$ are normal inner matrices satisfying (i) or (ii) of Theorem 1. First, assume (i). Then $N_{1}^{\prime}$ is an $m \times m$ normal inner matrix and hence $N_{2}^{\prime}$ is an $n \times m$ inner matrix. From the normalities of $N_{2} N_{2}^{\prime}$ and $N_{2}$, we can deduce that $N_{2}^{\prime}$ has the form $\left[\begin{array}{c}M^{\prime} \\ 0\end{array}\right]$, where $M^{\prime}=\operatorname{diag}\left(t_{1}, t_{2}, \cdots, t_{m}\right)$. Since $\phi_{i} t_{i}$ is a divisor of $\phi_{i}$, it follows that $t_{i}$ is a divisor of $v_{i}$ and, by (18), $\frac{\phi_{i+1}}{\phi_{i}} \wedge t_{i}=1$. Then normality of $N_{2} N_{2}^{\prime}$ implies that there is an inner function $w_{i}$ such that $w_{i}=\frac{\phi_{i+1} t_{i+1}}{\phi_{i} t_{i}}$. From $t_{i} w_{i}=\frac{\phi_{i+1}}{\phi_{i}}$ $t_{i+1}$, it follows that $t_{i}$ is a divisor of $t_{i+1}$. Thus $N_{2}^{\prime}$ is normal. Hence $N_{2}^{-1}$ $\alpha\left(\mathbb{Z}^{\prime}\right)=N_{2}^{\prime}\left\{H_{m}^{2} \ominus N_{1}^{\prime} H_{m}^{2}\right\}$ is hyperinvariant for $S\left(N_{1}\right)$. Therefore $\alpha\left(\mathbb{Z}^{\prime}\right)$ is hyperinvariant for $S(N) \mid \alpha(\mathfrak{Z})$. Consequently $\beta^{\prime}\left(\alpha\left(\mathfrak{Z}^{\prime}\right)\right)=\beta\left(\alpha\left(\mathfrak{Z}^{\prime}\right)\right)=\mathfrak{Z}^{\prime}$ is hyperinvariant for $S(\theta) \mid \mathcal{R}$. Next assume that $N_{2} N_{2}^{\prime}$ and $N_{1}^{\prime}$ satisfy (ii). Then we have $N_{2}^{\prime}=\operatorname{diag}\left(t_{1}, \cdots, t_{m}, t, \cdots, t\right)$, for inner functions $t_{1}, t_{2}, \cdots, t_{m}$ and $t$. It is proved as above that $t_{i}$ is a divisor of $t_{i+1}$ for $i=1,2, \cdots, m-1$. Since $\phi_{m}$ $t_{m}$ is a divisor of $\phi t, t_{m}$ is a divisor of $u_{m} t$. On the other hand since $t_{m}$ is a divisor of $v_{m}$ and $v_{m} \wedge u_{m}=1, t_{m}$ is a divisor of $t$. Thus it follows that $N_{2}^{\prime}$ is normal. Consequently in the same way as above we can deduce that $\mathfrak{Z}^{\prime}$ is hyperinvariant for $S(\theta) \mid \mathfrak{Z}$.

Case $b$ : suppose $\mathfrak{Z}=\overline{\phi(S(\theta)) \mathfrak{S}(\theta)} \cap \mathfrak{Z}_{*}$. Then by Corollary 1 and $\alpha\left(\mathfrak{Z}_{*}\right)$ $=\mathfrak{F}(M)$ we have

$$
\alpha(\mathfrak{Z})=\overline{\phi(S(N)) \mathfrak{S}(N)} \cap \mathfrak{K}(M)=\overline{\phi(S(M)) \mathfrak{K}(M)},
$$

because $\alpha$ is a lattice isomorphism. Let $N=N_{2} N_{1}$ be the factorization corresponding to $\alpha(\mathbb{Z})$. Then it follows that

$$
N_{2}=\left[\begin{array}{c}
M_{2} \\
0
\end{array}\right] \quad \text { with } \quad M_{2}=\operatorname{diag}\left(\phi_{1}, \phi_{2}, \cdots, \phi_{m}\right),
$$

where $\phi_{i}=\phi \wedge \psi_{i}$ for $i=1,2, \cdots, m$. Let $\mathfrak{L}^{\prime}$ be a subspace of $\mathbb{R}$, hyperinvariant for $S(\theta)$, and $N_{1}=N_{2}^{\prime} N_{1}^{\prime}$ be the factorization of $N_{1}$ such that $N=$
$\left(N_{2} N_{2}^{\prime}\right) N_{1}^{\prime}$ is the factorization of $N$ corresponding to $\alpha^{\prime}\left(\mathbb{Z}^{\prime}\right)=\alpha\left(\mathbb{Z}^{\prime}\right)$. The hyperinvariance of $\alpha\left(\mathfrak{L}^{\prime}\right)$ for $S(N)$ implies that $N_{2} N_{2}^{\prime}$ and $N_{1}^{\prime}$ are normal inner matrices satidfying (i). In the same way as Case $a$ it follows that $N_{2}^{\prime}$ is an $m \times m$ normal inner matrix. Therefore it is simple to show that $\mathfrak{Z}^{\prime}$ is hyperinvariant for $S(\theta) \mid \mathbb{R}$.

Necessity. Let $\mathbb{Z}$ be the hyperinvariant subspace for $S(\theta)$ such that $\mathfrak{Z}^{\prime}$ is hyperinvariant for $S(\theta) \mid \mathcal{Z}$, if $\mathfrak{Z}^{\prime}$ is a subspace of $\mathfrak{R}$, hyperinvariant for $S(\theta)$. Then, for every subspace $\mathfrak{N}^{\prime}$ of $\alpha(\mathfrak{R})$ such that $\mathfrak{K}^{\prime}$ is hyperinvariant for $S(N)$, it follows from Theorem 3 that $\beta\left(\mathfrak{N}^{\prime}\right)=\beta^{\prime}\left(\Re^{\prime}\right)$ is hyperinvariant for $S(\theta) \mid \mathfrak{Q}$. Hence, by Theorem 3, $\mathfrak{K}^{\prime}=\alpha^{\prime}\left(\beta^{\prime}\left(\mathfrak{K}^{\prime}\right)\right)$ is hyperinvariant for $S$ $(N) \mid \alpha(\mathbb{Z})$. Let $N=N_{2} N_{1}$ be the factorization corresponding to $\alpha(\mathbb{Z})$. Then $N_{2}$ and $N_{1}$ are normal inner matrices.

Case $a^{\prime}$ : assume that $N_{1}$ and $N_{2}$ have the form :
$N_{1}=\operatorname{diag}\left(\xi_{1}, \xi_{2}, \cdots, \xi_{m}\right) \quad$ and
$N_{2}=\left[\begin{array}{c}M_{2} \\ 0\end{array}\right] \quad$ with $\quad M_{2}=\operatorname{diag}\left(\eta_{1}, \eta_{2}, \cdots, \eta_{m}\right)$.
Then it follows that $\eta_{i}$ and $\xi_{i}$ satisfy (18), that is $\frac{\eta_{i+1}}{\eta_{i}}$ and $\xi_{i}$ are relatively prime. In fact, if it were not true, then we have

$$
\omega \equiv \frac{\eta_{i+1}}{\eta_{i}} \wedge \frac{\xi_{j}}{\xi_{j-1}} \neq 1 \quad \text { for some } \quad j: 1 \leqq j \leqq i, \xi_{0}=1
$$

Set

$$
\begin{aligned}
& M_{2}^{\prime}=\operatorname{diag}\left(\eta_{1}, \cdots, \eta_{j-1}, \eta_{j} \omega, \eta_{j+1} \omega, \cdots, \eta_{i} \omega, \eta_{i+1}, \cdots, \eta_{m}\right) \\
& N_{1}^{\prime}=\operatorname{dag}\left(\xi_{1}, \cdots, \xi_{j-1}, \frac{\xi_{j}}{\omega}, \frac{\xi_{j+1}}{\omega}, \cdots, \frac{\xi_{i}}{\omega}, \xi_{i+1}, \cdots, \xi_{m}\right)
\end{aligned}
$$

and $N_{2}^{\prime}=\left[\begin{array}{c}M_{2}^{\prime} \\ 0\end{array}\right]$. It is clear that $\mathfrak{Y}^{\prime} \equiv N_{2}^{\prime}\left\{H_{m}^{2} \ominus N_{1}^{\prime} H_{m}^{2}\right\}$ is a subspace of $\alpha(\mathbb{Z})$. Since $N_{1}^{\prime}$ and $N_{2}^{\prime}$ are normal inner matrices, by Lemma 1 is hyperinvariant for $S(N)$. However,

$$
\left(N_{2} \mid \mathfrak{S}\left(N_{1}\right)\right)^{-1} N_{2}^{\prime} \mathfrak{S}\left(N_{1}^{\prime}\right)=\operatorname{diag}(1, \cdots, 1, \omega, \cdots, \omega, 1, \cdots 1) \mathfrak{K}\left(N_{1}^{\prime}\right)
$$

implies that $\mathfrak{R}^{\prime}$ is not hyperinvariant for $S(N) \mid \alpha(\mathbb{R})$. Thus we have $\frac{\eta_{i+1}}{\eta_{i}}<$ $\xi_{i}=1$. Since $\xi_{i}$ is a divisor of $\xi_{i+1}$, it follows that

$$
\eta_{m} \wedge \psi_{i}=\eta_{m} \wedge\left(\eta_{i} \xi_{i}\right)=\eta_{i}\left(\frac{\eta_{m}}{\eta_{i}} \wedge \xi_{i}\right)=\eta_{i}
$$

Thus we have

$$
\alpha(\mathfrak{Z})=\overline{\eta_{m}(S(M)) \mathfrak{G}(M)}=\overline{\eta_{m}(S(N)) \mathfrak{S}(N)} \cap \mathfrak{S}(M) .
$$

Consequently $\mathfrak{Z}=\overline{\eta_{m}(S(\theta)) \mathscr{S}(\theta)} \cap \mathfrak{Z}_{*}$.

Case $b^{\prime}$ : assume that $N_{1}$ and $N_{2}$ are normal inner matrices satisfying (ii). In this case, we can show

$$
\mathfrak{Z}=\overline{\phi(S(\theta)) \mathfrak{g}(\theta)} \text { for some } \phi \text { in } H^{\infty}
$$

in the same way as Case $a^{\prime}$. Thus we complete the proof of Theorem 5,

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M. Uchiyama

Division of Applied Mathematics
Research Institute of Applied Electricity Hokkaido University

Sapporo, Japan
M. Uchiyama

The Department of Education Fukuoka University of Education Fukuoka, Japan

