

# The Parabolic Infinite-Laplace Equation in Carnot Groups

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ABSTRACT. By employing a Carnot parabolic maximum principle we show the existence and uniqueness of viscosity solutions to a class of equations modeled on the parabolic infinite Laplace equation in Carnot groups. We show the stability of solutions within the class and examine the limit as  $t$  goes to infinity.

## 1. Motivation

In Carnot groups, the following theorem has been established.

THEOREM 1.1 [3; 14; 5]. *Let  $\Omega$  be a bounded domain in a Carnot group, and let  $v : \partial\Omega \rightarrow \mathbb{R}$  be a continuous function. Then the Dirichlet problem*

$$\begin{cases} \Delta_\infty u = 0 & \text{in } \Omega, \\ u = v & \text{on } \partial\Omega \end{cases}$$

*has a unique viscosity solution  $u_\infty$ .*

Our goal is to prove a parabolic version of Theorem 1.1 for a class of equations (defined in the next section), namely:

CONJECTURE 1.2. Let  $\Omega$  be a bounded domain in a Carnot group, and let  $T > 0$ . Let  $\psi \in C(\overline{\Omega})$  and  $g \in C(\Omega \times [0, T])$ . Then the Cauchy–Dirichlet problem

$$\begin{cases} u_t - \Delta_\infty^h u = 0 & \text{in } \Omega \times (0, T), \\ u(x, 0) = \psi(x) & \text{on } \overline{\Omega}, \\ u(x, t) = g(x, t) & \text{on } \partial\Omega \times (0, T) \end{cases} \quad (1.1)$$

has a unique viscosity solution  $u$ .

In Sections 2 and 3, we review key properties of Carnot groups and parabolic viscosity solutions. In Section 4, we prove the uniqueness, and Section 5 covers the existence.

## 2. Calculus on Carnot Groups

We begin by denoting an arbitrary Carnot group in  $\mathbb{R}^N$  by  $G$  and its corresponding Lie algebra by  $\mathfrak{g}$ . Recall that  $\mathfrak{g}$  is nilpotent and stratified, resulting in the

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decomposition

$$g = V_1 \oplus V_2 \oplus \cdots \oplus V_l$$

for appropriate vector spaces that satisfy the Lie bracket relation  $[V_1, V_j] = V_{1+j}$ . The Lie algebra  $g$  is associated with the group  $G$  via the exponential map  $\exp : g \rightarrow G$ . Since this map is a diffeomorphism, we can choose a basis for  $g$  so that it is the identity map. Denote this basis by

$$X_1, X_2, \dots, X_{n_1}, Y_1, Y_2, \dots, Y_{n_2}, Z_1, Z_2, \dots, Z_{n_3},$$

so that

$$\begin{aligned} V_1 &= \text{span}\{X_1, X_2, \dots, X_{n_1}\}, \\ V_2 &= \text{span}\{Y_1, Y_2, \dots, Y_{n_2}\}, \\ V_3 \oplus V_4 \oplus \cdots \oplus V_l &= \text{span}\{Z_1, Z_2, \dots, Z_{n_3}\}. \end{aligned}$$

We endow  $g$  with an inner product  $\langle \cdot, \cdot \rangle$  and related norm  $\| \cdot \|$  so that this basis is orthonormal. Clearly, the Riemannian dimension of  $g$  (and so  $G$ ) is  $N = n_1 + n_2 + n_3$ . However, we will also consider the homogeneous dimension of  $G$ , denoted  $\mathcal{Q}$ , which is given by

$$\mathcal{Q} = \sum_{i=1}^l i \cdot \dim V_i.$$

Before proceeding with the calculus, we recall the group and metric space properties. Since the exponential map is the identity, the group law is the Campbell–Hausdorff formula (see, e.g., [7]). For our purposes, this formula is given by

$$p \cdot q = p + q + \frac{1}{2}[p, q] + R(p, q), \tag{2.1}$$

where  $R(p, q)$  are terms of order 3 or higher. The identity element of  $G$  will be denoted by 0 and called the origin. There is also a natural metric on  $G$ , which is the Carnot–Carathéodory distance, defined for the points  $p$  and  $q$  as follows:

$$d_C(p, q) = \inf_{\Gamma} \int_0^1 \|\gamma'(t)\| dt,$$

where  $\Gamma$  is the set of all curves  $\gamma$  such that  $\gamma(0) = p$ ,  $\gamma(1) = q$ , and  $\gamma'(t) \in V_1$ . By Chow’s theorem (see, e.g., [2]) any two points can be connected by such a curve, which means that  $d_C(p, q)$  is an honest metric. Define the Carnot–Carathéodory ball of radius  $r$  centered at a point  $p_0$  by

$$B(p_0, r) = \{p \in G : d_C(p, p_0) < r\}.$$

In addition to the Carnot–Carathéodory metric, there is a smooth (off the origin) gauge. This gauge is defined for a point  $p = (\zeta_1, \zeta_2, \dots, \zeta_l)$  with  $\zeta_i \in V_i$  by

$$\mathcal{N}(p) = \left( \sum_{i=1}^l \|\zeta_i\|^{2l/i} \right)^{1/(2l)} \tag{2.2}$$

and induces the metric  $d_{\mathcal{N}}$  that is bi-Lipschitz equivalent to the Carnot–Carathéodory metric and is given by

$$d_{\mathcal{N}}(p, q) = \mathcal{N}(p^{-1} \cdot q).$$

We define the gauge ball of radius  $r$  centered at a point  $p_0$  by

$$B_{\mathcal{N}}(p_0, r) = \{p \in G : d_{\mathcal{N}}(p, p_0) < r\}.$$

In this environment, a smooth function  $u : G \rightarrow \mathbb{R}$  has the horizontal derivative given by

$$\nabla_0 u = (X_1 u, X_2 u, \dots, X_{n_1} u)$$

and the symmetrized horizontal second derivative matrix, denoted by  $(D^2 u)^*$ , with entries

$$((D^2 u)^*)_{ij} = \frac{1}{2}(X_i X_j u + X_j X_i u)$$

for  $i, j = 1, 2, \dots, n_1$ . We also consider the semihorizontal derivative given by

$$\nabla_1 u = (X_1 u, X_2 u, \dots, X_{n_1} u, Y_1 u, Y_2 u, \dots, Y_{n_2} u).$$

Using these derivatives, we define the  $h$ -homogeneous infinite Laplace operator for  $h \geq 1$  by

$$\Delta_{\infty}^h f = \|\nabla_0 f\|^{h-3} \sum_{i,j=1}^{n_1} X_i f X_j f X_i X_j f = \|\nabla_0 f\|^{h-3} \langle (D^2 f)^* \nabla_0 f, \nabla_0 f \rangle.$$

Given  $T > 0$  and a function  $u : G \times [0, T] \rightarrow \mathbb{R}$ , we may define the analogous subparabolic infinite Laplace operator by

$$u_t - \Delta_{\infty}^h u,$$

and we consider the corresponding equation

$$u_t - \Delta_{\infty}^h u = 0. \tag{2.3}$$

We note that when  $h \geq 3$ , this operator is continuous. When  $h = 3$ , we have the subparabolic infinite Laplace equation analogous to the infinite Laplace operator in [5]. The Euclidean analog for  $h = 1$  has been explored in [12], and the Euclidean analog for  $1 < h < 3$  in [13].

We recall that for any open set  $\mathcal{O} \subset G$ , the function  $f$  is in the horizontal Sobolev space  $W^{1,p}(\mathcal{O})$  if  $f$  and  $X_i f$  are in  $L^p(\mathcal{O})$  for  $i = 1, 2, \dots, n_1$ . Replacing  $L^p(\mathcal{O})$  by  $L^p_{\text{loc}}(\mathcal{O})$ , the space  $W^{1,p}_{\text{loc}}(\mathcal{O})$  is defined similarly. The space  $W^1_{\text{loc}}(\mathcal{O})$  is the closure in  $W^{1,p}(\mathcal{O})$  of smooth functions with compact support. In addition, we recall that a function  $u : G \rightarrow \mathbb{R}$  is  $C^2_{\text{sub}}$  if  $\nabla_1 u$  and  $X_i X_j u$  are continuous for all  $i, j = 1, 2, \dots, n_1$ . Note that  $C^2_{\text{sub}}$  is not equivalent to (Euclidean)  $C^2$ . For spaces involving time, the space  $C(t_1, t_2; X)$  consists of all continuous functions  $u : [t_1, t_2] \rightarrow X$  with  $\max_{t_1 \leq t \leq t_2} \|u(\cdot, t)\|_X < \infty$ . A similar definition holds for  $L^p(t_1, t_2; X)$ .

Given an open box  $\mathcal{O} = (a_1, b_1) \times (a_2, b_2) \times \dots \times (a_N, b_N)$ , we define the parabolic space  $\mathcal{O}_{t_1, t_2}$  to be  $\mathcal{O} \times [t_1, t_2]$ . Its parabolic boundary is given by  $\partial_{\text{par}} \mathcal{O}_{t_1, t_2} = (\overline{\mathcal{O}} \times \{t_1\}) \cup (\partial \mathcal{O} \times (t_1, t_2))$ .

Finally, recall that if  $G$  is a Carnot group with homogeneous dimension  $\mathcal{Q}$ , then  $G \times \mathbb{R}$  is again a Carnot group of homogeneous dimension  $\mathcal{Q} + 1$ , where we have added an extra vector field  $\frac{\partial}{\partial t}$  to the first layer of the grading. This allows us to give meaning to notations such as  $W^{1,2}(\mathcal{O}_{t_1,t_2})$  and  $\mathcal{C}_{\text{sub}}^2(\mathcal{O}_{t_1,t_2})$ , where we consider  $\nabla_0 u$  to be  $(X_1 u, X_2 u, \dots, X_{n_1} u, \frac{\partial u}{\partial t})$ .

### 3. Parabolic Jets and Viscosity Solutions

#### 3.1. Parabolic Jets

In this subsection, we recall the definitions of the parabolic jets, as given in [6], but included here for completeness. We define the parabolic superjet of  $u(p, t)$  at the point  $(p_0, t_0) \in \mathcal{O}_{t_1,t_2}$ , denoted  $P^{2,+}u(p_0, t_0)$ , by using triples  $(a, \eta, X) \in \mathbb{R} \times V_1 \oplus V_2 \times S^{n_1}$  so that  $(a, \eta, X) \in P^{2,+}u(p_0, t_0)$  if

$$u(p, t) \leq u(p_0, t_0) + a(t - t_0) + \langle \eta, \widehat{p_0^{-1} \cdot p} \rangle + \frac{1}{2} \langle X \overline{p_0^{-1} \cdot p}, \overline{p_0^{-1} \cdot p} \rangle + o(|t - t_0| + |p_0^{-1} \cdot p|^2) \quad \text{as } (p, t) \rightarrow (p_0, t_0).$$

We recall that  $S^k$  is the set of  $k \times k$  symmetric matrices and  $n_i = \dim V_i$ . We define  $\overline{p_0^{-1} \cdot p}$  as the first  $n_1$  coordinates of  $p_0^{-1} \cdot p$  and  $\widehat{p_0^{-1} \cdot p}$  as the first  $n_1 + n_2$  coordinates of  $p_0^{-1} \cdot p$ . This definition is an extension of the superjet definition for subparabolic equations in the Heisenberg group [4]. We define the subjet  $P^{2,-}u(p_0, t_0)$  by

$$P^{2,-}u(p_0, t_0) = -P^{2,+}(-u)(p_0, t_0).$$

We define the set-theoretic closure of the superjet, denoted  $\overline{P}^{2,+}u(p_0, t_0)$ , by requiring  $(a, \eta, X) \in \overline{P}^{2,+}u(p_0, t_0)$  exactly when there is a sequence  $(a_n, p_n, t_n, u(p_n, t_n), \eta_n, X_n) \rightarrow (a, p_0, t_0, u(p_0, t_0), \eta, X)$  with the triple  $(a_n, \eta_n, X_n) \in P^{2,+}u(p_n, t_n)$ . A similar definition holds for the closure of the subjet.

We may also define jets using appropriate test functions. Given a function  $u : \mathcal{O}_{t_1,t_2} \rightarrow \mathbb{R}$ , we consider the set  $\mathcal{A}u(p_0, t_0)$  given by

$$\mathcal{A}u(p_0, t_0) = \{ \phi \in \mathcal{C}_{\text{sub}}^2(\mathcal{O}_{t_1,t_2}) : u(p, t) - \phi(p, t) \leq u(p_0, t_0) - \phi(p_0, t_0) = 0 \forall (p, t) \in \mathcal{O}_{t_1,t_2} \},$$

consisting of all test functions that touch  $u$  from above at  $(p_0, t_0)$ . We define the set of all test functions that touch from below, denoted  $\mathcal{B}u(p_0, t_0)$ , similarly.

The following lemma relates the test functions to jets. The proof is identical to that of Lemma 3.1 in [4] but uses the (smooth) gauge  $\mathcal{N}(p)$  instead of Euclidean distance.

LEMMA 3.1.

$$P^{2,+}u(p_0, t_0) = \{ (\phi_t(p_0, t_0), \nabla \phi(p_0, t_0), (D^2 \phi(p_0, t_0))^*) : \phi \in \mathcal{A}u(p_0, t_0) \}.$$

### 3.2. Jet Twisting

We recall that the set  $V_1 = \text{span}\{X_1, X_2, \dots, X_{n_1}\}$ , and notationally, we will always denote  $n_1$  by  $n$ . The vectors  $X_i$  at the point  $p \in G$  can be written as

$$X_i(p) = \sum_{j=1}^N a_{ij}(p) \frac{\partial}{\partial x_j},$$

forming the  $n \times N$  matrix  $\mathbb{A}$  with smooth entries  $\mathbb{A}_{ij} = a_{ij}(p)$ . By linear independence of the  $X_i$ ,  $\mathbb{A}$  has rank  $n$ . Similarly,

$$Y_i(p) = \sum_{j=1}^N b_{ij}(p) \frac{\partial}{\partial x_j},$$

forming the  $n_2 \times N$  matrix  $\mathbb{B}$  with smooth entries  $\mathbb{B}_{ij} = b_{ij}$ . The matrix  $\mathbb{B}$  has rank  $n_2$ . The following lemma differs from [5, Cor. 3.2] only in that there is now a parabolic term. This term, however, does not need to be twisted. The proof is then identical since only the space terms need twisting.

LEMMA 3.2. Let  $(a, \eta, X) \in \overline{P}_{\text{eucl}}^{2,+}u(p, t)$ . (Recall that  $(\eta, X) \in \mathbb{R}^N \times S^N$ .) Then

$$(a, \mathbb{A} \cdot \eta \oplus \mathbb{B} \cdot \eta, \mathbb{A}X\mathbb{A}^T + \mathbb{M}) \in \overline{P}^{2,+}u(p, t).$$

Here the entries of the (symmetric) matrix  $\mathbb{M}$  are given by

$$\mathbb{M}_{ij} = \begin{cases} \sum_{k=1}^N \sum_{l=1}^N (a_{il}(p) \frac{\partial}{\partial x_l} a_{jk}(p) + a_{jl}(p) \frac{\partial a_{ik}}{\partial x_l}(p)) \eta_k, & i \neq j, \\ \sum_{k=1}^N \sum_{l=1}^N a_{il}(p) \frac{\partial a_{ik}}{\partial x_l}(p) \eta_k, & i = j. \end{cases}$$

### 3.3. Viscosity Solutions

We consider parabolic equations of the form

$$u_t + F(t, p, u, \nabla_1 u, (D^2 u)^*) = 0 \tag{3.1}$$

for continuous and proper  $F : [0, T] \times G \times \mathbb{R} \times g \times S^n \rightarrow \mathbb{R}$  [8]. We recall that  $S^n$  is the set of  $n \times n$  symmetric matrices (where  $\dim V_1 = n$ ) and the derivatives  $\nabla_1 u$  and  $(D^2 u)^*$  are taken in the space variable  $p$ . We then use the jets to define subsolutions and supersolutions to Equation (3.1) in the usual way.

DEFINITION 1. Let  $(p_0, t_0) \in \mathcal{O}_{t_1, t_2}$  be as before. The upper semicontinuous function  $u$  is a *parabolic viscosity subsolution* in  $\mathcal{O}_{t_1, t_2}$  if for all  $(p_0, t_0) \in \mathcal{O}_{t_1, t_2}$ , we have that  $(a, \eta, X) \in \overline{P}^{2,+}u(p_0, t_0)$  produces

$$a + F(t_0, p_0, u(p_0, t_0), \eta, X) \leq 0.$$

A lower semicontinuous function  $u$  is a *parabolic viscosity supersolution* in  $\mathcal{O}_{t_1, t_2}$  if for all  $(p_0, t_0) \in \mathcal{O}_{t_1, t_2}$ , we have that  $(b, \nu, Y) \in \overline{P}^{2,-}u(p_0, t_0)$  produces

$$b + F(t_0, p_0, u(p_0, t_0), \nu, Y) \geq 0.$$

A continuous function  $u$  is a *parabolic viscosity solution* in  $\mathcal{O}_{t_1, t_2}$  if it is both a parabolic viscosity subsolution and parabolic viscosity supersolution.

REMARK 3.3. In the special case where  $F(t, p, u, \nabla_1 u, (D^2 u)^*) = F_\infty^h(\nabla_0 u, (D^2 u)^*) = -\Delta_\infty^h u$  for  $h \geq 3$ , we use the terms “parabolic viscosity  $h$ -infinite supersolution”, and so on.

In the case where  $1 \leq h < 3$ , the definition above is insufficient due to the singularity occurring when the horizontal gradient vanishes. Therefore, following [12] and [13], we define viscosity solutions to Equation (2.3) when  $1 \leq h < 3$  as follows.

DEFINITION 2. Let  $\mathcal{O}_{t_1, t_2}$  be as before. A lower semicontinuous function  $v : \mathcal{O}_{t_1, t_2} \rightarrow \mathbb{R}$  is a *parabolic viscosity  $h$ -infinite supersolution* of  $u_t - \Delta_\infty^h u = 0$  if whenever  $(p_0, t_0) \in \mathcal{O}_{t_1, t_2}$  and  $\phi \in \mathcal{B}u(p_0, t_0)$ , we have

$$\left\{ \begin{array}{ll} \phi_t(p_0, t_0) - \Delta_\infty^h \phi(p_0, t_0) \geq 0 & \text{when } \nabla_0 \phi(p_0, t_0) \neq 0, \\ \phi_t(p_0, t_0) - \min_{\|\eta\|=1} \langle (D^2 \phi)^*(p_0, t_0) \eta, \eta \rangle \geq 0 & \text{when } \nabla_0 \phi(p_0, t_0) = 0 \text{ and} \\ & h = 1, \\ \phi_t(p_0, t_0) \geq 0 & \text{when } \nabla_0 \phi(p_0, t_0) = 0 \text{ and} \\ & 1 < h < 3. \end{array} \right.$$

An upper semicontinuous function  $u : \mathcal{O}_{t_1, t_2} \rightarrow \mathbb{R}$  is a *parabolic viscosity  $h$ -infinite subsolution* of  $u_t - \Delta_\infty^h u = 0$  if whenever  $(p_0, t_0) \in \mathcal{O}_{t_1, t_2}$  and  $\phi \in \mathcal{A}u(p_0, t_0)$ , we have

$$\left\{ \begin{array}{ll} \phi_t(p_0, t_0) - \Delta_\infty^h \phi(p_0, t_0) \leq 0 & \text{when } \nabla_0 \phi(p_0, t_0) \neq 0, \\ \phi_t(p_0, t_0) - \max_{\|\eta\|=1} \langle (D^2 \phi)^*(p_0, t_0) \eta, \eta \rangle \leq 0 & \text{when } \nabla_0 \phi(p_0, t_0) = 0 \text{ and} \\ & h = 1, \\ \phi_t(p_0, t_0) \leq 0 & \text{when } \nabla_0 \phi(p_0, t_0) = 0 \text{ and} \\ & 1 < h < 3. \end{array} \right.$$

A continuous function is a *parabolic viscosity  $h$ -infinite solution* if it is both a parabolic viscosity  $h$ -infinite subsolution and parabolic viscosity  $h$ -infinite supersolution.

REMARK 3.4. When  $1 < h < 3$ , we can actually consider the continuous operator

$$\begin{aligned} & F_\infty^h(\nabla_0 u, (D^2 u)^*) \\ &= \begin{cases} -\|\nabla_0 u\|^{h-3} \langle (D^2 u)^* \nabla_0 u, \nabla_0 u \rangle = -\Delta_\infty^h u, & \nabla_0 u \neq 0, \\ 0, & \nabla_0 u = 0. \end{cases} \end{aligned} \tag{3.2}$$

Definitions 1 and 2 would then agree (cf. [13]).

We also wish to define what [11] refers to as parabolic viscosity solutions. We first need to consider the set

$$\mathcal{A}^- u(p_0, t_0) = \{ \phi \in \mathcal{C}^2(\mathcal{O}_{t_1, t_2}) : u(p, t) - \phi(p, t) \leq u(p_0, t_0) - \phi(p_0, t_0) = 0 \text{ for } p \neq p_0, t < t_0 \},$$

consisting of all functions that touch from above only when  $t < t_0$ . Note that this set is larger than  $\mathcal{A}u$  and corresponds physically to the past alone playing a role in determining the present. We define  $\mathcal{B}^-u(p_0, t_0)$  similarly. We then have the following definition.

**DEFINITION 3.** An upper semicontinuous function  $u$  on  $\mathcal{O}_{t_1, t_2}$  is a *past parabolic viscosity subsolution* in  $\mathcal{O}_{t_1, t_2}$  if  $\phi \in \mathcal{A}^-u(p_0, t_0)$  produces

$$\phi_t(p_0, t_0) + F(t_0, p_0, u(p_0, t_0), \nabla_1\phi(p_0, t_0), (D^2\phi(p_0, t_0))^*) \leq 0.$$

An lower semicontinuous function  $u$  on  $\mathcal{O}_{t_1, t_2}$  is a *past parabolic viscosity supersolution* in  $\mathcal{O}_{t_1, t_2}$  if  $\phi \in \mathcal{B}^-u(p_0, t_0)$  produces

$$\phi_t(p_0, t_0) + F(t_0, p_0, u(p_0, t_0), \nabla_1\phi(p_0, t_0), (D^2\phi(p_0, t_0))^*) \geq 0.$$

A continuous function is a *past parabolic viscosity solution* if it is both a past parabolic viscosity supersolution and subsolution.

We have the following proposition whose proof is obvious. The analogous theorem and its converse for the Euclidean case can be found in [11]. We will address the converse in the Carnot group case in the next section.

**PROPOSITION 3.5.** *Past parabolic viscosity sub(super)solutions are parabolic viscosity sub(super)solutions. In particular, past parabolic viscosity  $h$ -infinite sub(super)solutions are parabolic viscosity  $h$ -infinite sub(super)solutions for  $h \geq 1$ .*

### 3.4. The Carnot Parabolic Maximum Principle

In this subsection, we recall the Carnot parabolic maximum principle and key corollaries, as proved in [6].

**LEMMA 3.6** (Carnot parabolic maximum principle). *Let  $u$  be a viscosity subsolution to Equation (3.1), and  $v$  be a viscosity supersolution to Equation (3.1) in the bounded parabolic set  $\Omega \times (0, T)$  where  $\Omega$  is a (bounded) domain, and let  $\tau$  be a positive real parameter. Let  $\phi(p, q, t) = \varphi(p \cdot q^{-1}, t)$  be a  $C^2$  function in the space variables  $p$  and  $q$ , and a  $C^1$  function in  $t$ . Suppose that the local maximum*

$$M_\tau \equiv \max_{\overline{\Omega} \times \overline{\Omega} \times [0, T]} \{u(p, t) - v(q, t) - \tau\phi(p, q, t)\} \tag{3.3}$$

*occurs at the interior point  $(p_\tau, q_\tau, t_\tau)$  of the parabolic set  $\Omega \times \Omega \times (0, T)$ . Define the  $n \times n$  matrix  $W$  by*

$$W_{ij} = X_i(p)X_j(q)\phi(p_\tau, q_\tau, t_\tau).$$

*Let the  $2n \times 2n$  matrix  $\mathfrak{W}$  be given by*

$$\mathfrak{W} = \begin{pmatrix} 0 & \frac{1}{2}(W - W^T) \\ \frac{1}{2}(W^T - W) & 0 \end{pmatrix}, \tag{3.4}$$

and let the matrix  $\mathcal{W} \in S^{2N}$  be given by

$$\mathcal{W} = \begin{pmatrix} D_{pp}^2 \phi(p_\tau, q_\tau, t_\tau) & D_{pq}^2 \phi(p_\tau, q_\tau, t_\tau) \\ D_{qp}^2 \phi(p_\tau, q_\tau, t_\tau) & D_{qq}^2 \phi(p_\tau, q_\tau, t_\tau) \end{pmatrix}. \tag{3.5}$$

Suppose that

$$\lim_{\tau \rightarrow \infty} \tau \phi(p_\tau, q_\tau, t_\tau) = 0.$$

Then for each  $\tau > 0$ , there exists real numbers  $a_1$  and  $a_2$ , symmetric matrices  $\mathcal{X}_\tau$  and  $\mathcal{Y}_\tau$ , and a vector  $\Upsilon_\tau \in V_1 \oplus V_2$ , namely  $\Upsilon_\tau = \nabla_1(p)\phi(p_\tau, q_\tau, t_\tau)$ , such that the following hold:

- A)  $(a_1, \tau \Upsilon_\tau, \mathcal{X}_\tau) \in \overline{P}^{2,+} u(p_\tau, t_\tau)$  and  $(a_2, \tau \Upsilon_\tau, \mathcal{Y}_\tau) \in \overline{P}^{2,-} v(q_\tau, t_\tau)$ .
- B)  $a_1 - a_2 = \phi_t(p_\tau, q_\tau, t_\tau)$ .
- C) For any vectors  $\xi, \epsilon \in V_1$ , we have

$$\begin{aligned} \langle \mathcal{X}_\tau \xi, \xi \rangle - \langle \mathcal{Y}_\tau \epsilon, \epsilon \rangle &\leq \tau \langle (D_p^2 \phi)^*(p_\tau, q_\tau, t_\tau)(\xi - \epsilon), (\xi - \epsilon) \rangle \\ &\quad + \tau \langle \mathfrak{W}(\xi \oplus \epsilon), (\xi \oplus \epsilon) \rangle \\ &\quad + \tau \|\mathcal{W}\|^2 \|\mathbb{A}(\hat{p})^T \xi \oplus \mathbb{A}(\hat{q})^T \epsilon\|^2. \end{aligned} \tag{3.6}$$

In particular,

$$\langle \mathcal{X}_\tau \xi, \xi \rangle - \langle \mathcal{Y}_\tau \xi, \xi \rangle \lesssim \tau \|\mathcal{W}\|^2 \|\xi\|^2. \tag{3.7}$$

**COROLLARY 3.7.** Let  $\phi(p, q, t) = \phi(p, q) = \varphi(p \cdot q^{-1})$  be a nonnegative function independent of  $t$ . Suppose that  $\phi(p, q) = 0$  exactly when  $p = q$ . Then

$$\lim_{\tau \rightarrow \infty} \tau \phi(p_\tau, q_\tau) = 0.$$

In particular, if

$$\phi(p, q, t) = \frac{1}{m} \sum_{i=1}^N ((p \cdot q^{-1})_i)^m \tag{3.8}$$

for some **even** integer  $m \geq 4$  where  $(p \cdot q^{-1})_i$  is the  $i$ th component of the Carnot group multiplication group law, then for the vector  $\Upsilon_\tau$  and matrices  $\mathcal{X}_\tau, \mathcal{Y}_\tau$  from the lemma, we have:

- A)  $(a_1, \tau \Upsilon_\tau, \mathcal{X}_\tau) \in \overline{P}^{2,+} u(p_\tau, t_\tau)$  and  $(a_1, \tau \Upsilon_\tau, \mathcal{Y}_\tau) \in \overline{P}^{2,-} v(q_\tau, t_\tau)$ .
- B) The vector  $\Upsilon_\tau$  satisfies

$$\|\Upsilon_\tau\| \sim \phi(p_\tau, q_\tau)^{(m-1)/m}.$$

- C) For any fixed vector  $\xi \in V_1$ , we have

$$\langle \mathcal{X}_\tau \xi, \xi \rangle - \langle \mathcal{Y}_\tau \xi, \xi \rangle \lesssim \tau \|\mathcal{W}\|^2 \|\xi\|^2 \lesssim \tau (\phi(p_\tau, q_\tau))^{(2m-4)/m} \|\xi\|^2. \tag{3.9}$$

### 4. Uniqueness of Viscosity Solutions

We wish to formulate a comparison principle for the following problem.

**PROBLEM 4.1.** Let  $h \geq 1$ . Let  $\Omega$  be a bounded domain, and let  $\Omega_T = \Omega \times [0, T)$ . Let  $\psi \in C(\overline{\Omega})$  and  $g \in C(\overline{\Omega_T})$ . We consider the following boundary and initial value problem:

$$\begin{cases} u_t + F_\infty^h(\nabla_0 u, (D^2 u)^*) = 0 & \text{in } \Omega \times (0, T), & \text{(E)} \\ u(p, t) = g(p, t), & p \in \partial\Omega, t \in [0, T), & \text{(BC)} \\ u(p, 0) = \psi(p), & p \in \overline{\Omega}. & \text{(IC)} \end{cases} \quad (4.1)$$

We also adopt the definition that a subsolution  $u(p, t)$  to Problem 4.1 is a viscosity subsolution to (E),  $u(p, t) \leq g(p, t)$  on  $\partial\Omega$  with  $0 \leq t < T$ , and  $u(p, 0) \leq \psi(p)$  on  $\overline{\Omega}$ . Supersolutions and solutions are defined in an analogous matter.

Because our solution  $u$  will be continuous, we offer the following remark.

**REMARK 4.2.** The functions  $\psi$  and  $g$  may be replaced by one function  $g \in C(\overline{\Omega_T})$ . This combines conditions (E) and (BC) into one condition

$$u(p, t) = g(p, t), \quad (p, t) \in \partial_{\text{par}}\Omega_T. \quad \text{(IBC)} \quad (4.2)$$

**THEOREM 4.3.** Let  $\Omega$  be a bounded domain in  $G$ , and let  $h \geq 1$ . If  $u$  is a parabolic viscosity subsolution and  $v$  a parabolic viscosity supersolution to Problem 4.1, then  $u \leq v$  on  $\Omega_T \equiv \Omega \times [0, T)$ .

*Proof.* Our proof follows that of [8, Thm. 8.2], and so we discuss only the main parts.

For  $\varepsilon > 0$ , we substitute  $\tilde{u} = u - \frac{\varepsilon}{T-t}$  for  $u$  and prove the theorem for

$$u_t + F_\infty^h(\nabla_0 u, (D^2 u)^*) \leq -\frac{\varepsilon}{T^2} < 0, \quad (4.3)$$

$$\lim_{t \uparrow T} u(p, t) = -\infty \quad \text{uniformly on } \overline{\Omega}, \quad (4.4)$$

and take limits to obtain the desired result. Assume that the maximum occurs at  $(p_0, t_0) \in \Omega \times (0, T)$  with

$$u(p_0, t_0) - v(p_0, t_0) = \delta > 0.$$

*Case 1:  $h > 1$ .*

Let  $H \geq h + 3$  be an even number. As in Equation (3.8), we let

$$\phi(p, q) = \frac{1}{H} \sum_{i=1}^N ((p \cdot q^{-1})_i)^H$$

where  $(p \cdot q^{-1})_i$  is the  $i$ th component of the Carnot group multiplication group law. Let

$$M_\tau = u(p_\tau, t_\tau) - v(q_\tau, t_\tau) - \tau\phi(p_\tau, q_\tau)$$

with  $(p_\tau, q_\tau, t_\tau)$  the maximum point in  $\overline{\Omega} \times \overline{\Omega} \times [0, T)$  of  $u(p, t) - v(q, t) - \tau\phi(p, q)$ .

If  $t_\tau = 0$ , then we have

$$0 < \delta \leq M_\tau \leq \sup_{\overline{\Omega} \times \overline{\Omega}} (\psi(p) - \psi(q) - \tau\phi(p, q)),$$

leading to a contradiction for large  $\tau$ . We therefore conclude that  $t_\tau > 0$  for large  $\tau$ . Since  $u \leq v$  on  $\partial\Omega \times [0, T)$  by Equation (BC) of Problem 4.1, we conclude that for large  $\tau$ , we have that  $(p_\tau, q_\tau, t_\tau)$  is an interior point, that is,  $(p_\tau, q_\tau, t_\tau) \in \Omega \times \Omega \times (0, T)$ . Using Corollary 3.7, Property A, we obtain

$$(a, \tau\Upsilon(p_\tau, q_\tau), \mathcal{X}_\tau) \in \overline{P}^{2,+} u(p_\tau, t_\tau)$$

and  $(a, \tau\Upsilon(p_\tau, q_\tau), \mathcal{Y}_\tau) \in \overline{P}^{2,-} v(q_\tau, t_\tau),$

satisfying the equations

$$a + F_\infty^h(\tau\Upsilon(p_\tau, q_\tau), \mathcal{X}_\tau) \leq -\frac{\varepsilon}{T^2}$$

and  $a + F_\infty^h(\tau\Upsilon(p_\tau, q_\tau), \mathcal{Y}_\tau) \geq 0.$

If there is a subsequence  $\{p_\tau, q_\tau\}_{\tau>0}$  such that  $p_\tau \neq q_\tau$ , we subtract, and using Corollary 3.7, we have

$$0 < \frac{\varepsilon}{T^2}$$

$$\leq (\tau\Upsilon(p_\tau, q_\tau))^{h-3} \tau^2 (\langle \mathcal{X}_\tau \Upsilon(p_\tau, q_\tau), \Upsilon(p_\tau, q_\tau) \rangle - \langle \mathcal{Y}_\tau \Upsilon(p_\tau, q_\tau), \Upsilon(p_\tau, q_\tau) \rangle)$$

$$\lesssim \tau^h (\varphi(p_\tau, q_\tau))^{(H-1)/H} (\varphi(p_\tau, q_\tau))^{h-3} (\varphi(p_\tau, q_\tau))^{(2H-4)/H} (\varphi(p_\tau, q_\tau))^{(2H-2)/H} \tag{4.5}$$

$$= \tau^h (\varphi(p_\tau, q_\tau))^{(Hh+H-h-3)/H} = (\tau\varphi(p_\tau, q_\tau))^h \varphi(p_\tau, q_\tau)^{(H-h-3)/H}. \tag{4.6}$$

Because  $H > h + 3$ , we arrive at a contradiction as  $\tau \rightarrow \infty$ .

If we have  $p_\tau = q_\tau$ , then we arrive at a contradiction since

$$F_\infty^h(\tau\Upsilon(p_\tau, q_\tau), \mathcal{X}_\tau) = F_\infty^h(\tau\Upsilon(p_\tau, q_\tau), \mathcal{Y}_\tau) = 0.$$

Case 2:  $h = 1$ .

We follow the proof of Theorem 3.1 in [12]. Let

$$\varphi(p, q, t, s) = \frac{1}{4} \sum_{i=1}^N ((p \cdot q^{-1})_i)^4 + \frac{1}{2} (t - s)^2,$$

and let  $(p_\tau, q_\tau, t_\tau, s_\tau)$  be the maximum of

$$u(p, t) - v(q, s) - \tau\phi(p, q, t, s).$$

Again, for large  $\tau$ , this point is an interior point. If we have a sequence where  $p_\tau \neq q_\tau$ , then Lemma 3.2 yields

$$(\tau(t_\tau - s_\tau), \tau\Upsilon(p_\tau, q_\tau), \mathcal{X}_\tau) \in \overline{P}^{2,+} u(p_\tau, t_\tau)$$

and  $(\tau(t_\tau - s_\tau), \tau\Upsilon(p_\tau, q_\tau), \mathcal{Y}_\tau) \in \overline{P}^{2,-} v(q_\tau, s_\tau),$

satisfying the equations

$$\begin{aligned} \tau(t_\tau - s_\tau) + F_\infty^h(\tau\Upsilon(p_\tau, q_\tau), \mathcal{X}_\tau) &\leq -\frac{\varepsilon}{T^2} \\ \text{and } \tau(t_\tau - s_\tau) + F_\infty^h(\tau\Upsilon(p_\tau, q_\tau), \mathcal{Y}_\tau) &\geq 0. \end{aligned}$$

As in the first case, we subtract to obtain

$$\begin{aligned} 0 &< \frac{\varepsilon}{T^2} \\ &\leq (\tau\Upsilon(p_\tau, q_\tau))^{-2}\tau^2(\langle \mathcal{X}_\tau\Upsilon(p_\tau, q_\tau), \Upsilon(p_\tau, q_\tau) \rangle - \langle \mathcal{Y}_\tau\Upsilon(p_\tau, q_\tau), \Upsilon(p_\tau, q_\tau) \rangle) \\ &\lesssim \varphi(p_\tau, q_\tau)^{-3/2}(\tau\varphi(p_\tau, q_\tau)\varphi(p_\tau, q_\tau)^{3/2}) = \tau\varphi(p_\tau, q_\tau). \end{aligned}$$

We arrive at a contradiction as  $\tau \rightarrow \infty$ .

If  $p_\tau = q_\tau$ , then  $v(q, s) - \beta^v(q, s)$  has a local minimum at  $(q_\tau, s_\tau)$  where

$$\beta^v(q, s) = -\frac{\tau}{4} \sum_{i=1}^N ((p_\tau \cdot q^{-1})_i)^4 - \frac{\tau}{2}(t_\tau - s_\tau)^2.$$

We then have

$$0 < \varepsilon(T - s_\tau)^{-2} \leq \beta_s^v(q_\tau, s_\tau) - \min_{\|\eta\|=1} \langle (D^2\beta^v)^*(q_\tau, s_\tau)\eta, \eta \rangle.$$

Similarly,  $u(p, t) - \beta^u(p, t)$  has a local maximum at  $(p_\tau, t_\tau)$  where

$$\beta^u(p, t) = \frac{\tau}{4} \sum_{i=1}^N ((p \cdot q_\tau^{-1})_i)^4 + \frac{\tau}{2}(t - s_\tau)^2.$$

We then have

$$0 \geq \beta_t^u(p_\tau, t_\tau) - \max_{\|\eta\|=1} \langle (D^2\beta^u)^*(p_\tau, t_\tau)\eta, \eta \rangle,$$

and subtraction gives us

$$\begin{aligned} 0 &< \varepsilon(T - s_\tau)^{-2} \\ &\leq \max_{\|\eta\|=1} \langle (D^2\beta^u)^*(p_\tau, t_\tau)\eta, \eta \rangle - \min_{\|\eta\|=1} \langle (D^2\beta^v)^*(q_\tau, s_\tau)\eta, \eta \rangle \\ &\quad + \beta_s^v(q_\tau, s_\tau) - \beta_t^u(p_\tau, t_\tau) \\ &= \tau \max_{\|\eta\|=1} \langle (D_{pp}^2\varphi(p \cdot q_\tau^{-1}))^*(p_\tau, t_\tau)\eta, \eta \rangle \\ &\quad - \tau \min_{\|\eta\|=1} \langle (D_{qq}^2\varphi(p_\tau \cdot q^{-1}))^*(q_\tau, s_\tau)\eta, \eta \rangle \\ &\quad + \tau(t_\tau - s_\tau) - \tau(t_\tau - s_\tau) \\ &= 0. \end{aligned}$$

Here, the last equality comes from the fact that  $p_\tau = q_\tau$  and from the definition of  $\varphi(p \cdot q^{-1})$ . □

The comparison principle has the following consequences concerning properties of solutions.

**COROLLARY 4.4.** *Let  $h \geq 1$ . The past parabolic viscosity  $h$ -infinite solutions are exactly the parabolic viscosity  $h$ -infinite solutions.*

*Proof.* By Proposition 3.5 past parabolic viscosity  $h$ -infinite sub(super)solutions are parabolic viscosity  $h$ -infinite sub(super)solutions. To prove the converse, we will follow the proof of the subsolution case found in [11], highlighting the main details. Assume that  $u$  is not a past parabolic viscosity  $h$ -infinite subsolution. Let  $\phi \in \mathcal{A}^-u(p_0, t_0)$  have the property that

$$\phi_t(p_0, t_0) - \Delta_\infty^h \phi(p_0, t_0) \geq \epsilon > 0$$

for a small parameter  $\epsilon$ . We may assume that  $p_0$  is the origin. Let  $r > 0$  and define  $S_r = B_{\mathcal{N}}(r) \times (t_0 - r, t_0)$ , and let  $\partial S_r$  be its parabolic boundary. Then the function

$$\tilde{\phi}_r(p, t) = \phi(p, t) + (t_0 - t)^{8l!} - r^{8l!} + (\mathcal{N}(p))^{8l!}$$

is a classical supersolution for sufficiently small  $r$ . We then observe that  $u \leq \tilde{\phi}_r$  on  $\partial S_r$  but  $u(0, t_0) > \tilde{\phi}(0, t_0)$ . Thus, the comparison principle, Theorem 4.3, does not hold. Thus,  $u$  is not a parabolic viscosity  $h$ -infinite subsolution. The supersolution case is identical and omitted.  $\square$

The following corollary has a proof similar to that of [12, Lemma 3.2].

**COROLLARY 4.5.** *Let  $u : \Omega_T \rightarrow \mathbb{R}$  be upper semicontinuous. Let  $\phi \in \mathcal{A}u(p_0, t_0)$ . If*

$$\begin{cases} \phi_t(p_0, t_0) - \Delta_\infty^1 \phi(p_0, t_0) \leq 0 & \text{when } \nabla_0 \phi(p_0, t_0) \neq 0, \\ \phi_t(p_0, t_0) \leq 0 & \text{when } \nabla_0 \phi(p_0, t_0) = 0, \\ & (D^2 \phi)^*(p_0, t_0) = 0, \end{cases} \quad (4.7)$$

*then  $u$  is a viscosity subsolution to (E) of Problem 4.1.*

We also have the following function estimates with respect to boundary data.

**COROLLARY 4.6.** *Let  $h \geq 1$ . Let  $g_1, g_2 \in C(\overline{\Omega_T})$  and  $u_1, u_2$  be parabolic viscosity solutions to Equation (4.1) with boundary data  $g_1$  and  $g_2$ , respectively. Then*

$$\sup_{(p,t) \in \Omega_T} |u_1(p, t) - u_2(p, t)| \leq \sup_{(p,t) \in \partial_{\text{par}} \Omega_T} |g_1(p, t) - g_2(p, t)|.$$

*Proof.* The function  $u^+(p, t) = u_2(p, t) + \sup_{(p,t) \in \partial_{\text{par}} \Omega_T} |g_1(p, t) - g_2(p, t)|$  is a parabolic viscosity supersolution with boundary data  $g_1$ , and the function  $u^-(p, t) = u_2(p, t) - \sup_{(p,t) \in \partial_{\text{par}} \Omega_T} |g_1(p, t) - g_2(p, t)|$  is a parabolic viscosity subsolution with boundary data  $g_1$ . Moreover,  $u^- \leq u_1 \leq u^+$  on  $\partial_{\text{par}} \Omega_T$ , and by Theorem 4.3  $u^- \leq u_1 \leq u^+$  in  $\Omega_T$ .  $\square$

**COROLLARY 4.7.** *Let  $h \geq 1$ . Let  $g \in C(\overline{\Omega_T})$ . Then every parabolic viscosity solution to Problem 4.1 satisfies*

$$\sup_{(p,t) \in \Omega_T} |u(p, t)| \leq \sup_{(p,t) \in \partial_{\text{par}} \Omega_T} |g(p, t)|.$$

*Proof.* The proof is similar to the previous corollary but using the functions  $u^\pm(p, t) = \pm \sup_{(p,t) \in \partial_{\text{par}} \Omega_T} |g(p, t)|$  instead.  $\square$

### 5. Existence of Viscosity Solutions

#### 5.1. Parabolic Viscosity Infinite Solutions: The Continuity Case

As before, we will focus on the equations of the form (3.1) for continuous and proper  $F : [0, T] \times G \times \mathbb{R} \times g \times S^{n_1} \rightarrow \mathbb{R}$  that possess a comparison principle such as Theorem 4.3 or [6, Thm. 3.6]. We will use Perron’s method combined with the Carnot parabolic maximum principle to yield the desired existence theorem. In particular, the following proofs are similar to those found in [10, Chap. 2] except that the Euclidean derivatives have been replaced with horizontal derivatives and the Euclidean norms have been replaced with the gauge norm.

LEMMA 5.1. *Let  $\mathcal{L}$  be a collection of parabolic viscosity supersolutions to (3.1), and let  $u(p, t) = \inf\{v(p, t) : v \in \mathcal{L}\}$ . If  $u$  is finite in a dense subset of  $\Omega_T = \Omega \times [0, T]$ , then  $u$  is a parabolic viscosity supersolution to (3.1).*

*Proof.* First, note that  $u$  is lower semicontinuous since every  $v \in \mathcal{L}$  is. Let  $(p_0, t_0) \in \Omega_T$  and  $\phi \in \mathcal{A}u(p_0, t_0)$ . Now let

$$\psi(p, t) = \phi(p, t) - (d_{\mathcal{N}}(p_0, p))^{2l_1} - |t - t_0|^2$$

and notice that  $\psi \in \mathcal{A}u(p_0, t_0)$ . Then

$$\begin{aligned} (u - \psi)(p, t) - (d_{\mathcal{N}}(p_0, p))^{2l_1} - |t - t_0|^2 &= (u - \phi)(p, t) \\ &\geq (u - \phi)(p_0, t_0) \\ &= (u - \psi)(p_0, t_0) \\ &= 0 \end{aligned}$$

yields

$$(u - \psi)(p, t) \geq (d_{\mathcal{N}}(p_0, p))^{2l_1} + |t - t_0|^2. \tag{5.1}$$

Since  $u$  is lower semicontinuous, there exists a sequence  $\{(p_k, t_k)\}$  with  $t_k < t_0$  converging to  $(p_0, t_0)$  as  $k \rightarrow \infty$  such that

$$(u - \psi)(p_k, t_k) \rightarrow (u - \psi)(p_0, t_0) = 0.$$

Since  $u(p, t) = \inf\{v(p, t) : v \in \mathcal{L}\}$ , there exists a sequence  $\{v_k\} \subset \mathcal{L}$  such that  $v_k(p_k, t_k) < u(p_k, t_k) + 1/k$  for  $k = 1, 2, \dots$ . Since  $v_k \geq u$ , Equation (5.1) gives us

$$(v_k - \psi)(p, t) \geq (u - \psi)(p, t) \geq (d_{\mathcal{N}}(p_0, p))^{2l_1} + |t - t_0|^2. \tag{5.2}$$

Let  $B \subset \Omega$  denote a compact neighborhood of  $(p_0, t_0)$ . Since  $v_k - \psi$  is lower semicontinuous, it attains a minimum in  $B$  at a point  $(q_k, s_k) \in B$ . Then by (5.1) and (5.2) we have

$$\begin{aligned} (u - \psi)(p_k, t_k) + 1/k &> (v_k - \psi)(p_k, t_k) \geq (v_k - \psi)(q_k, s_k) \\ &\geq (d_{\mathcal{N}}(p_0, q_k))^{2l_1} + |s_k - t_0|^2 \geq 0 \end{aligned}$$

for sufficiently large  $k$  such that  $(p_k, t_k) \in B$ . By the squeeze theorem,  $(q_k, s_k) \rightarrow (p_0, t_0)$  as  $k \rightarrow \infty$ . Let  $\eta = \psi - (d_{\mathcal{N}}(q_k, p))^{2l} - |s_k - t|^2$ . Then  $\eta \in \mathcal{A}v_k(q_k, s_k)$ , and we have that

$$\eta_t(q_k, s_k) + F(s_k, q_k, v_k(q_k, s_k), \nabla_1 \eta(q_k, s_k), (D^2 \eta(q_k, s_k))^*) \geq 0.$$

This implies

$$\psi_t(q_k, s_k) + F(s_k, q_k, v_k(q_k, s_k), \nabla_1 \psi(q_k, s_k), (D^2 \psi(s_k, s_k))^*) \geq 0.$$

Letting  $k \rightarrow \infty$  yields

$$\phi_t(p_0, t_0) + F(t_0, p_0, u(p_0, t_0) \nabla_1 \phi(p_0, t_0), (D^2 \phi(p_0, t_0))^*) \geq 0$$

and that  $u$  is a parabolic viscosity supersolution, as desired. □

A similar argument yields the following:

**LEMMA 5.2.** *Let  $\mathcal{L}$  be a collection of parabolic viscosity subsolutions to (3.1), and let  $u(p, t) = \sup\{v(p, t) : v \in \mathcal{L}\}$ . If  $u$  is finite in a dense subset of  $\Omega_T$ , then  $u$  is a parabolic viscosity subsolution to (3.1).*

For the following lemmas, we need to recall the following definition.

**DEFINITION 4.** The *upper and lower semicontinuous envelopes* of a function  $u$  are given by

$$u^*(p, t) := \limsup_{r \downarrow 0} \{u(q, s) : |q^{-1}p|_g + |s - t| \leq r\}$$

and

$$u_*(p, t) := \liminf_{r \downarrow 0} \{u(q, s) : |q^{-1}p|_g + |s - t| \leq r\},$$

respectively.

**LEMMA 5.3.** *Let  $h$  be a parabolic viscosity supersolution to (3.1) in  $\Omega_T$ . Let  $\mathcal{S}$  be the collection of all parabolic viscosity subsolutions  $v$  of (3.1) satisfying  $v \leq h$ . If for  $\hat{v} \in \mathcal{S}$ ,  $\hat{v}_*$  is not a parabolic viscosity supersolution of (3.1), then there are a function  $w \in \mathcal{S}$  and a point  $(p_0, t_0)$  such that  $\hat{v}(p_0, t_0) < w(p_0, t_0)$ .*

*Proof.* Let  $\hat{v} \in \mathcal{S}$  such that  $\hat{v}_*$  is not a parabolic viscosity supersolution of (3.1). Then there exist  $(\hat{p}, \hat{t}) \in \Omega_T$  and  $\phi \in \mathcal{A}\hat{v}_*(\hat{p}, \hat{t})$  such that

$$\phi_t(p, t) + F(t, p, \hat{v}_*(p, t), \nabla_1 \phi(p, t), (D^2 \phi(p, t))^*) > 0. \tag{5.3}$$

Let

$$\psi(p, t) = \phi(p, t) - (d_{\mathcal{N}}(\hat{p}, p))^{2l} - |t - \hat{t}|^2$$

and notice that  $\psi \in \mathcal{A}\hat{v}_*(\hat{p}, \hat{t})$ . As in Lemma 5.1,

$$(\hat{v}_* - \psi)(p, t) \geq (d_{\mathcal{N}}(\hat{p}, p))^{2l} + |t - \hat{t}|^2. \tag{5.4}$$

Let  $B$  denote a compact neighborhood of  $(\hat{p}, \hat{t})$ , and let

$$B_{k\epsilon} = B \cap \{(p, t) : (d_{\mathcal{N}}(\hat{p}, p))^{2l} \leq k\epsilon \text{ and } |t - \hat{t}|^2 \leq k\epsilon\}.$$

Since  $\hat{v} \in \mathcal{S}$ , we have that  $\hat{v} \leq h$ , and thus  $\psi(\hat{p}, \hat{t}) = \hat{v}_*(\hat{p}, \hat{t}) \leq \hat{v}(\hat{p}, \hat{t}) \leq h(\hat{p}, \hat{t})$ . However, if  $\psi(\hat{p}, \hat{t}) = h(\hat{p}, \hat{t})$ , then  $\psi \in \mathcal{A}h(\hat{p}, \hat{t})$ , and inequality (5.3) would be contradictory. Thus,

$$\psi(\hat{p}, \hat{t}) < h(\hat{p}, \hat{t}).$$

Since  $\psi$  is continuous and  $h$  is lower semicontinuous, there exists  $\epsilon > 0$  such that

$$\psi(p, t) + 4\epsilon \leq h(p, t)$$

for  $(p, t) \in B_{2\epsilon}$ . Notice that  $\psi + 4\epsilon$  is a subsolution of (3.1) on the interior of  $B_{2\epsilon}$ . Further, by (5.4)

$$\hat{v}(p, t) \geq \hat{v}_*(p, t) \geq \psi(p, t) + 4\epsilon \quad \text{for } (p, t) \in B_{2\epsilon} \setminus B_\epsilon. \tag{5.5}$$

We now define  $\omega$  by

$$\omega = \begin{cases} \max\{\psi(p, t) + 4\epsilon, \hat{v}(p, t)\}, & (p, t) \in B_\epsilon, \\ \hat{v}(p, t), & (p, t) \in \Omega_T \setminus B_\epsilon. \end{cases}$$

But by (5.5)

$$\omega(p, t) = \max\{\psi(p, t) + 4\epsilon, \hat{v}(p, t)\} \quad \text{for } (p, t) \in B_{2\epsilon},$$

not just for  $(p, t) \in B_\epsilon$ . Then by Lemma 5.2,  $\omega$  is a subsolution in the interior of  $B_{2\epsilon}$  and thus a subsolution in  $\Omega_T$ . Therefore,  $\omega \in \mathcal{S}$ . Since

$$0 = (\hat{v}_* - \psi)(\hat{p}, \hat{t}) = \liminf_{r \downarrow 0} \{(\hat{v} - \psi)(p, t) : (p, t) \in B_r\},$$

there is a point  $(p_0, t_0) \in B_\epsilon$  that satisfies

$$\hat{v}(p_0, t_0) - \psi(p_0, t_0) < 4\epsilon,$$

which yields

$$\hat{v}(p_0, t_0) < \psi(p_0, t_0) + 4\epsilon = \omega(p_0, t_0).$$

Thus, we have constructed  $\omega \in \mathcal{S}$  that satisfies  $\hat{v}(p_0, t_0) < \omega(p_0, t_0)$ . □

We then have the following existence theorem concerning parabolic viscosity solutions.

**THEOREM 5.4.** *Let  $f$  be a parabolic viscosity subsolution to (3.1), and  $g$  be a parabolic viscosity supersolution to (3.1) satisfying  $f \leq g$  on  $\Omega_T$  and  $f_* = g^*$  on  $\partial_{\text{par}}\mathcal{O}_{0,T}$ . Then there is a parabolic viscosity solution  $u$  to (3.1) satisfying  $u \in C(\overline{\Omega_T})$ . Explicitly, there exists a unique parabolic viscosity infinite solution to Problem 4.1 when  $h > 1$ .*

*Proof.* Let

$$S = \{v : v \text{ is a parabolic viscosity subsolution to (3.1) in } \Omega_T \text{ with } v \leq g \text{ in } \Omega_T\}$$

and

$$u(p, t) = \sup\{v(p, t) : v \in S\}.$$

Since  $f \leq g$ , the set  $S$  is nonempty. Notice that  $f \leq u \leq g$  by construction. By Lemma 5.2,  $u$  is a parabolic viscosity subsolution. Suppose  $u_*$  is not a parabolic viscosity supersolution. Then by Lemma 5.3 there exist a function  $w \in S$  and

a point  $(p_0, t_0) \in \Omega_T$  such that  $u(p_0, t_0) < w(p_0, t_0)$ . But this contradicts the definition of  $u$  at  $(p_0, t_0)$ . Thus,  $u_*$  is a parabolic viscosity supersolution. By our assumptions on  $f$  and  $g$  on  $\partial_{\text{par}}\mathcal{O}_{0,T}$ ,

$$u = u^* \leq g^* = f_* \leq u_*$$

on  $\partial_{\text{par}}\mathcal{O}_{0,T}$ . Then by the (assumed) comparison principle,  $u \leq u_*$  on  $\Omega_T$ . Thus, we have that  $u$  is a parabolic viscosity solution such that  $u \in C(\overline{\mathcal{O}_T})$ .  $\square$

### 5.2. The $h = 1$ Case

We begin by recalling the definition of upper and lower relaxed limits of a function [8; 10].

DEFINITION 5. For  $\varepsilon > 0$ , consider the function  $\mathfrak{h}_\varepsilon : \mathcal{O}_T \subset G \rightarrow \mathbb{R}$ . The upper relaxed limit  $\overline{\mathfrak{h}}(p, t)$  and the lower relaxed limit  $\underline{\mathfrak{h}}(p, t)$  are given by

$$\begin{aligned} \overline{\mathfrak{h}}(p, t) &= \limsup_{\hat{p} \rightarrow p, \hat{t} \rightarrow t, \varepsilon \rightarrow 0} \mathfrak{h}_\varepsilon(\hat{p}, \hat{t}) \\ &= \lim_{\varepsilon \rightarrow 0} \sup_{0 < \delta < \varepsilon} \{\mathfrak{h}_\delta(\hat{p}, \hat{t}) : \mathcal{O}_T \cap B_\varepsilon(\hat{p}, \hat{t})\} \\ \text{and } \underline{\mathfrak{h}}(p, t) &= \liminf_{\hat{p} \rightarrow p, \hat{t} \rightarrow t, \varepsilon \rightarrow 0} \mathfrak{h}_\varepsilon(\hat{p}, \hat{t}) \\ &= \lim_{\varepsilon \rightarrow 0} \inf_{0 < \delta < \varepsilon} \{\mathfrak{h}_\delta(\hat{p}, \hat{t}) : \mathcal{O}_T \cap B_\varepsilon(\hat{p}, \hat{t})\}. \end{aligned}$$

Taking the relaxed limits as  $h \rightarrow 1^+$  of the operator  $F_\infty^h(\nabla_0 u, (D^2 u)^*)$  in Equation (3.2), we have via the continuity of the operator

$$\begin{aligned} \overline{F}_\infty^1(\nabla_0 u, (D^2 u)^*) &= \underline{F}_\infty^1(\nabla_0 u, (D^2 u)^*) \\ &= \begin{cases} -\|\nabla_0 u\|^{-2} \langle (D^2 u)^* \nabla_0 u, \nabla_0 u \rangle, & \nabla_0 u \neq 0, \\ 0, & \nabla_0 u = 0. \end{cases} \end{aligned}$$

We give this operator the label  $\mathcal{F}(\nabla_0 u, (D^2 u)^*)$ . Consider the relaxed limits  $\overline{u}(p, t)$  and  $\underline{u}(p, t)$  of the sequence of unique (continuous) viscosity solutions to Problem 4.1  $\{u_h(p, t)\}$  as  $h \rightarrow 1^+$ . By [10, Thm. 2.2.1] we have that  $\overline{u}(p, t)$  is a viscosity subsolution and  $\underline{u}(p, t)$  is a viscosity supersolution to

$$u_t + \mathcal{F}(\nabla_0 u, (D^2 u)^*) = 0.$$

We have the following comparison principle, whose proof is similar to that of Theorem 4.3 in the case  $h = 1$  and is omitted.

LEMMA 5.5. Let  $\Omega$  be a bounded domain in  $G$ . If  $u$  is a parabolic viscosity subsolution and  $v$  a parabolic viscosity supersolution to

$$u_t + \mathcal{F}(\nabla_0 u, (D^2 u)^*) = 0,$$

then  $u \leq v$  on  $\Omega_T \equiv \Omega \times [0, T)$ .

COROLLARY 5.6.  $\overline{u}(p, t) = \underline{u}(p, t)$ .

*Proof.* By construction,  $\underline{u}(p, t) \leq \bar{u}(p, t)$ . By the lemma,  $\underline{u}(p, t) \geq \bar{u}(p, t)$ .  $\square$

REMARK 5.7. Using the corollary, we will call this common relaxed limit  $u^1(p, t)$ . By [10, Chap. 2] and [8, Sect. 6], it is continuous, and the sequence  $\{u_h(p, t)\}$  converges locally uniformly to  $u^1(p, t)$  as  $h \rightarrow 1^+$ .

We then have the following theorem.

THEOREM 5.8. *There exists a unique parabolic viscosity infinite solution to Problem 4.1 when  $h = 1$ .*

*Proof.* Let  $\{u_h(p, t)\}$  and  $u^1(p, t)$  be as before. Let  $\{h_j\}$  be a subsequence with  $h_j \rightarrow 1^+$  where  $u_{h_j}(p, t) \rightarrow u^1(p, t)$  uniformly. We may assume that  $h_j < 3$ .

Let  $\phi \in \mathcal{A}u_1(p_0, t_0)$ . Using the uniform convergence, there is a sequence  $\{p_j, t_j\} \rightarrow (p_0, t_0)$  such that  $\phi \in \mathcal{A}u_{h_j}(p_j, t_j)$ . If  $\nabla_0\phi(p_0, t_0) \neq 0$ , then we have  $\nabla_0\phi(p_j, t_j) \neq 0$  for sufficiently large  $j$ . We then have

$$\phi_t(p_j, t_j) - \Delta_\infty^{h_j}\phi(p_j, t_j) \leq 0,$$

and letting  $j \rightarrow \infty$  yields

$$\phi_t(p_0, t_0) - \Delta_\infty^1\phi(p_0, t_0) \leq 0.$$

Suppose  $\nabla_0\phi(p_0, t_0) = 0$ . By Corollary 4.5 we may assume that  $(D^2\phi)^*(p_0, t_0) = 0$ . Passing to a subsequence if needed, we have  $\nabla_0\phi(p_j, t_j) \neq 0$ . Then

$$\phi_t(p_j, t_j) - \max_{\|\eta\|=1} \langle (D^2\phi)^*(p_j, t_j)\eta, \eta \rangle \leq \phi_t(p_j, t_j) - \Delta_\infty^{h_j}\phi(p_j, t_j) \leq 0.$$

Letting  $j \rightarrow \infty$  yields

$$\phi_t(p_0, t_0) = \phi_t(p_j, t_j) - \max_{\|\eta\|=1} \langle (D^2\phi)^*(p_0, t_0)\eta, \eta \rangle \leq 0.$$

In the case  $\nabla_0\phi(p_j, t_j) = 0$ , since  $h_j < 3$ , we have  $\phi_t(p_j, t_j) \leq 0$ , and letting  $j \rightarrow \infty$  yields  $\phi_t(p_0, t_0) \leq 0$ . We conclude that  $u_1$  is a parabolic viscosity  $h$ -infinite subsolution. Similarly,  $u_1$  is a parabolic viscosity  $h$ -infinite supersolution.  $\square$

### 6. The Limit as $t \rightarrow \infty$

We now focus our attention on the asymptotic limits of the parabolic viscosity  $h$ -infinite solutions. We wish to show that for  $1 \leq h$ , we have that the (unique) viscosity solution to  $u_t - \Delta_\infty^h u = 0$  approaches the viscosity solution of  $-\Delta_\infty^h u = 0$  as  $t \rightarrow \infty$ . Our goal is the following theorem.

THEOREM 6.1. *Let  $h > 1$ , and let  $u \in C(\bar{\Omega} \times [0, \infty))$  be a viscosity solution of*

$$\begin{cases} u_t - \Delta_\infty^h u = 0 & \text{in } \Omega \times (0, \infty), \\ u(p, t) = g(p) & \text{on } \partial_{\text{par}}(\Omega \times (0, \infty)) \end{cases} \tag{6.1}$$

with  $g : \bar{\Omega} \rightarrow \mathbb{R}$  continuous and assuming that  $\partial\Omega$  satisfies the property of positive geometric density (see [11, p. 2,909]). Then  $u(p, t) \rightarrow U(p)$  uniformly in  $\Omega$

as  $t \rightarrow \infty$  where  $U(p)$  is the unique viscosity solution of  $-\Delta_\infty^h U = 0$  with the Dirichlet boundary condition  $\lim_{q \rightarrow p} U(q) = g(p)$  for all  $p \in \partial\Omega$ .

We first must establish the uniqueness of viscosity solutions to the limit equation. Note that for future reference, we include the case  $h = 1$ .

**THEOREM 6.2.** *Let  $1 \leq h < \infty$ , and let  $\Omega$  be a bounded domain. Let  $u$  be a viscosity subsolution to  $\Delta_\infty^h u = 0$ , and let  $v$  be a viscosity supersolution to  $-\Delta_\infty^h u = 0$ . Then,*

$$\sup_{p \in \overline{\Omega}} (u(p) - v(p)) = \sup_{p \in \partial\Omega} (u(p) - v(p)).$$

*Proof.* Let  $u$  be a viscosity subsolution to  $-\Delta_\infty^h u = 0$ . Then choose  $\phi \in \mathcal{C}_{\text{sub}}^2(\Omega)$  such that  $0 = \phi(p_0) - u(p_0) < \phi(p) - u(p)$  for  $p \in \Omega$ ,  $p \neq p_0$ . If  $\|\nabla_0 \phi(p_0)\| = 0$ , then  $-\langle (D^2 \phi)^*(p_0) \nabla_0 \phi(p_0), \nabla_0 \phi(p_0) \rangle = 0 \leq 0$ . If  $\|\nabla_0 \phi(p_0)\| \neq 0$ , we then have

$$-\Delta_\infty^h \phi(p_0) = -\|\nabla_0 \phi(p_0)\|^{h-3} \langle (D^2 \phi)^*(p_0) \nabla_0 \phi(p_0), \nabla_0 \phi(p_0) \rangle \leq 0.$$

Dividing, we have  $-\langle (D^2 \phi)^*(p_0) \nabla_0 \phi(p_0), \nabla_0 \phi(p_0) \rangle \leq 0$ . In either case,  $u$  is a viscosity subsolution to  $-\Delta_\infty^3 u = 0$ . Similarly,  $v$  is a viscosity supersolution to  $-\Delta_\infty^3 u = 0$ . The theorem follows from the corresponding result for  $-\Delta_\infty^3 u = 0$  in [5; 3; 14].  $\square$

We state some obvious corollaries.

**COROLLARY 6.3.** *Let  $1 \leq h < \infty$ , and let  $g : \partial\Omega \rightarrow \mathbb{R}$  be continuous. Then there is exactly one solution to*

$$\begin{cases} -\Delta_\infty^h u = 0 & \text{in } \Omega, \\ u = g & \text{on } \partial\Omega. \end{cases}$$

**COROLLARY 6.4.** *Let  $1 \leq h < \infty$ , and let  $g : \partial\Omega \rightarrow \mathbb{R}$  be continuous. The unique viscosity solution to*

$$\begin{cases} -\Delta_\infty^h u = 0 & \text{in } \Omega, \\ u = g & \text{on } \partial\Omega \end{cases}$$

*is the unique viscosity solution to*

$$\begin{cases} -\Delta_\infty^3 u = 0 & \text{in } \Omega, \\ u = g & \text{on } \partial\Omega. \end{cases}$$

Our method of proof for Theorem 6.1 follows that of [11, Thm. 2], the core of which hinges on the construction of a parabolic test function from an elliptic one. In order to construct such a parabolic test function, we need to examine the homogeneity of Equation (6.1). A quick calculation shows that for a fixed  $h > 1$ ,  $k^{1/(h-1)} u(x, kt)$  is a  $\mathcal{C}_{\text{sub}}^2$  solution to Equation (6.1) if  $u(x, t)$  is a  $\mathcal{C}_{\text{sub}}^2$  solution. A routine calculation then shows that parabolic viscosity  $h$ -infinite solutions share

this homogeneity. We use this property in the following lemma, the proof of which can be found in [9, p. 170]. (Also, cf. [6, Lemma 6.2] and [11].)

LEMMA 6.5. *Let  $u$  be as in Theorem 6.1, and  $h > 1$ . Then for every  $(x, t) \in \Omega \times (0, \infty)$  and for  $0 < \mathcal{T} < t$ , we have*

$$|u(x, t - \mathcal{T}) - u(x, t)| \leq \frac{2\|g\|_{\infty, \Omega}}{h - 1} \left(1 - \frac{\mathcal{T}}{t}\right)^{h/(1-h)} \frac{\mathcal{T}}{t}.$$

*Proof of Theorem 6.1.* Fix  $h > 1$ . Let  $u$  be a viscosity solution of (6.1). The results of [9, Chap. III] imply that the family  $\{u(\cdot, t) : t \in (0, \infty)\}$  is equicontinuous. Since it is uniformly bounded due to the boundedness of  $g$ , Arzelà–Ascoli’s theorem yields that there exists a sequence  $t_j \rightarrow \infty$  such that  $u(\cdot, t_j)$  converge uniformly in  $\overline{\Omega}$  to a function  $U \in C(\overline{\Omega})$  for which  $U(p) = g(p)$  for all  $p \in \partial\Omega$ . By Corollary 6.3 it suffices to show that  $U$  is a viscosity subsolution to  $-\Delta_{\infty}^h U = 0$  on  $\Omega$ . With that in mind, let  $p_0 \in \Omega$  and choose  $\phi \in C_{\text{sub}}^2(\Omega)$  such that  $0 = \phi(p_0) - U(p_0) < \phi(p) - U(p)$  for  $p \in \Omega$ ,  $p \neq p_0$ . Using the uniform convergence, we can find a sequence  $p_j \rightarrow p_0$  such that  $u(\cdot, t_j) - \phi$  has a local maximum at  $p_j$ . Now define

$$\phi_j(p, t) = \phi(p) + C \left(\frac{t}{t_j}\right)^{h/(1-h)} \frac{t_j - t}{t_j},$$

where  $C = 2\|g\|_{\infty, \Omega}/(h - 1)$ . Note that  $\phi_j(p, t) \in C_{\text{sub}}^2(\Omega \times (0, \infty))$ . Then using Lemma 6.5, we have

$$\begin{aligned} u(p_j, t_j) - \phi_j(p_j, t_j) &= u(p_j, t_j) - \phi(p_j) \geq u(p, t_j) - \phi(p) \\ &\geq u(p, t) - \phi(p) - C \left(\frac{t}{t_j}\right)^{h/(1-h)} \frac{t_j - t}{t_j} \\ &= u(p, t) - \phi_j(p, t) \end{aligned}$$

for any  $p \in \Omega$  and  $0 < t < t_j$ . Thus, we have that  $\phi_j$  is an admissible test function at  $(p_j, t_j)$  on  $\Omega \times [0, T]$ . Therefore,

$$(\phi_j)_t(p_j, t_j) - \Delta_{\infty}^h \phi_j(p_j, t_j) \leq 0.$$

This yields

$$-\Delta_{\infty}^h \phi(p_j) \leq \frac{C}{t_j}.$$

The theorem follows by letting  $j \rightarrow \infty$ . □

Combining the results of the previous sections, we have the following theorem.

THEOREM 6.6. *Let  $\Omega$  be a bounded domain where  $\partial\Omega$  satisfies the property of positive geometric density. Let  $h \geq 1$ , and let  $g : \overline{\Omega} \rightarrow \mathbb{R}$  be continuous. Let  $u^{h,t}$  be the unique viscosity solution to*

$$\begin{cases} u_t^{h,t} - \Delta_{\infty}^h u^{h,t} = 0 & \text{in } \Omega \times (0, \infty), \\ u^{h,t}(p, t) = g(p) & \text{on } \partial_{\text{par}}(\Omega \times (0, \infty)), \end{cases}$$

and let  $u^{h,\infty}$  be the unique viscosity solution to

$$\begin{cases} -\Delta_\infty^h u^{h,\infty} = 0 & \text{in } \Omega, \\ u^{h,\infty} = g & \text{on } \partial\Omega \end{cases}$$

with the Dirichlet boundary condition  $\lim_{q \rightarrow p} u^{h,\infty}(q) = g(p)$  for all  $p \in \partial\Omega$ . Then

$$\lim_{\substack{h \rightarrow 1^+ \\ t \rightarrow \infty}} u^{h,t} = \lim_{h \rightarrow 1^+} \lim_{t \rightarrow \infty} u^{h,t} = \lim_{t \rightarrow \infty} \lim_{h \rightarrow 1^+} u^{h,t} = u^{1,\infty}.$$

That is, the following diagram commutes:

$$\begin{array}{ccc} u_t^{h,t} - \Delta_\infty^h u^{h,t} = 0 & \xrightarrow{h \rightarrow 1^+} & u_t^{1,t} - \Delta_\infty^1 u^{1,t} = 0 \\ \downarrow t \rightarrow \infty & & \downarrow t \rightarrow \infty \\ -\Delta_\infty^h u^{h,\infty} = 0 & \xrightarrow{h \rightarrow 1^+} & -\Delta_\infty^1 u^{1,\infty} = 0 \end{array}$$

*Proof.* By Theorem 6.1,

$$\lim_{t \rightarrow \infty} u^{h,t} = u^{h,\infty}, \tag{6.2}$$

and the convergence is uniform. By Corollary 6.4,

$$\lim_{h \rightarrow 1^+} u^{h,\infty} = u^{1,\infty},$$

and this convergence is clearly uniform. We thus have the iterated limit

$$\lim_{h \rightarrow 1^+} \lim_{t \rightarrow \infty} u^{h,t} = u^{1,\infty}$$

with both limits converging uniformly. By Remark 5.7 we have

$$\lim_{h \rightarrow 1^+} u^{h,t} = u^{1,t},$$

and this convergence is locally uniform. By the proof of Theorem 6.1 we have

$$\lim_{t \rightarrow \infty} u^{1,t} = f \tag{6.3}$$

for some function  $f$ , and the convergence is uniform. We then have

$$\lim_{t \rightarrow \infty} \lim_{h \rightarrow 1^+} u^{h,t} = f$$

with the inner limit locally uniform and the outer limit uniform. By the results of iterated limits in [1, Sect. 19] we then have that the full (double) limit exists. In addition, the full limit and both iterated limits equal. That is,  $f = u^{1,\infty}$  and

$$\lim_{\substack{h \rightarrow 1^+ \\ t \rightarrow \infty}} u^{h,t} = \lim_{h \rightarrow 1^+} \lim_{t \rightarrow \infty} u^{h,t} = \lim_{t \rightarrow \infty} \lim_{h \rightarrow 1^+} u^{h,t} = u^{1,\infty}. \quad \square$$

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