

Totally Real Submanifolds in a 6-Sphere

SHARIEF DESHMUKH

1. Introduction

On a 6-dimensional unit sphere S^6 , one can construct an almost complex structure using the properties of the Cayley division algebra; we refer to [3] for this construction. Further, it is known that this almost complex structure on S^6 is not integrable and that it is a nearly Kaehler structure on S^6 . Regarding submanifolds of S^6 , it is known that S^6 has no 4-dimensional complex submanifolds [4]. However, S^6 has 3-dimensional totally real submanifolds, which are minimal and orientable [3]. For a compact 3-dimensional totally real submanifold M of S^6 , in [2] it is shown that if the sectional curvatures k of M satisfy $1/16 < k \leq 1$, then $k = 1$, that is, M is totally geodesic. However, there are 3-dimensional compact totally real submanifolds of S^6 some of whose sectional curvatures are greater than 1 (cf. [1, p. 436]).

The object of the present paper is to prove the following.

THEOREM. *Let M be a compact 3-dimensional totally real submanifold of S^6 . If k_0 is the infimum of the sectional curvatures of M , then either $4k_0 \leq 1$ or M is totally geodesic.*

2. Totally Real Submanifolds of S^6

Let J be the almost complex structure defined on S^6 by the properties of the Cayley division algebra, and let g be the standard metric of constant curvature 1 on S^6 . Then we have

$$(2.1) \quad g(JX, JY) = g(X, Y), \quad (\bar{\nabla}_X J)(X) = 0, \quad X, Y \in \chi(S^6),$$

where $\bar{\nabla}$ is the Riemannian connection on S^6 with respect to g and $\chi(S^6)$ is the Lie algebra of vector fields on S^6 .

Define a tensor field G of the type $(1, 2)$ on S^6 by $G(X, Y) = (\bar{\nabla}_X J)(Y)$, $X, Y \in \chi(S^6)$. This tensor field has the following properties:

Received December 7, 1989. Revision received December 17, 1990.

Financially supported by research grant no. (Math/1409/05), Research Center, College of Science, King Saud University.

Michigan Math. J. 38 (1991).

$$(2.2) \quad G(X, Y) + G(Y, X) = 0;$$

$$(2.3) \quad G(X, JY) + JG(X, Y) = 0;$$

$$(2.4) \quad (\bar{\nabla}_X G)(Y, Z) = g(Y, JZ)X + g(X, Z)JY - g(X, Y)JZ, \\ X, Y, Z \in \chi(S^6).$$

A 3-dimensional submanifold M of S^6 is called a *totally real* submanifold of S^6 if $JTM = T^\perp M$, where TM is the tangent bundle and $T^\perp M$ is the normal bundle of M . In [3] Ejiri proved that a 3-dimensional totally real submanifold M of S^6 is orientable and minimal, and that $G(X, Y)$ is orthogonal to M for $X, Y \in \chi(M)$, where $\chi(M)$ is the Lie algebra of vector fields on M . We denote by ∇ and ∇^\perp the Riemannian connection on M and the connection in the normal bundle $T^\perp M$ induced by the connection $\bar{\nabla}$. The formulae of Gauss and Weingarten are given by

$$(2.5) \quad \bar{\nabla}_X Y = \nabla_X Y + h(X, Y)$$

and

$$(2.6) \quad \bar{\nabla}_X \xi = -A_\xi X + \nabla_X^\perp \xi,$$

where X and Y are vector fields on M and ξ is a normal vector field on M . The second fundamental form h is related to A_ξ by

$$(2.7) \quad g(h(X, Y), \xi) = g(A_\xi X, Y),$$

$$(2.8) \quad A_{JX} Y = -Jh(X, Y),$$

and

$$(2.9) \quad g(h(X, Y), JZ) = g(h(Y, Z), JX).$$

If we denote the curvature tensors of ∇ and ∇^\perp by R and R^\perp , respectively, then the equation of Codazzi gives

$$(2.10) \quad (\bar{\nabla}h)(X, Y, Z) = (\bar{\nabla}h)(Y, Z, X),$$

and the equations (2.4), (2.8), and (2.9) give

$$(2.11) \quad g(R^\perp(X, Y)JZ, JW) = g(R(X, Y)Z, W) + g(Z, X)g(Y, W) \\ - g(Z, Y)g(X, W),$$

where $X, Y, Z, W \in \chi(M)$ and $\bar{\nabla}h$ is defined by

$$(\bar{\nabla}h)(X, Y, Z) = \nabla_X^\perp h(Y, Z) - h(\nabla_X Y, Z) - h(Y, \nabla_X Z).$$

Using equations (2.4) and (2.10), by a straightforward computation we obtain

$$(2.12) \quad g((\bar{\nabla}h)(X, Y, Z), JW) - g((\bar{\nabla}h)(X, Y, W), JZ) \\ = g(h(Y, W), G(X, Z)) - g(h(Y, Z), G(X, W)).$$

We also define $\bar{\nabla}^2 h$ by

$$(\bar{\nabla}^2 h)(X, Y, Z, W) = \nabla_X^\perp (\bar{\nabla}h)(Y, Z, W) - (\bar{\nabla}h)(\nabla_X Y, Z, W) \\ - (\bar{\nabla}h)(Y, \nabla_X Z, W) - (\bar{\nabla}h)(Y, Z, \nabla_X W).$$

Then $\bar{\nabla}^2 h$ satisfies the following equation:

$$(2.13) \quad (\bar{\nabla}^2 h)(X, Y, Z, W) = (\bar{\nabla}^2 h)(Y, X, Z, W) + R^\perp(X, Y)h(Z, W) - h(R(X, Y)Z, W) - h(Z, R(X, Y)W).$$

For a unit vector $v \in TM$, we can choose an orthonormal basis $\{e_1, e_2, e_3\}$, with $e_3 = v$, such that $G(e_1, e_2) = Je_3$, $G(e_2, e_3) = Je_1$, and $G(e_3, e_1) = Je_2$ (cf. [3]). Then, using minimality of M and (2.12), we have

$$(2.14) \quad \begin{aligned} & \sum_{i=1}^3 g(G(e_i, v), (\bar{\nabla} h)(e_i, v, v)) \\ &= g(-Je_2, (\bar{\nabla} h)(e_1, v, v)) + g(Je_1, (\bar{\nabla} h)(e_2, v, v)) \\ &= g((\bar{\nabla} h)(v, v, e_2), Je_1) - g((\bar{\nabla} h)(v, v, e_1), Je_2) \\ &= -g(h(v, e_1), e_1) - g(h(v, e_2), e_2) \\ &= -g(h(e_1, e_1) + h(e_2, e_2), Jv) \\ &= g(h(v, v), Jv). \end{aligned}$$

3. Proof of the Theorem

Let UM be the unit tangent bundle of M and let UM_p be the fiber over $p \in M$. Define a smooth function $f: UM \rightarrow R$ by $f(v) = g(h(v, v), Jv)$. Since UM is compact, f attains a maximum at a unit vector v tangent to M at a point p . For any $u \in UM_p$, let $\alpha(t) = (\gamma(t), v(t))$, $t \in (-\delta, \delta)$ be a smooth curve in UM such that $\gamma(t)$ is the unique geodesic in M with $\gamma(0) = p$ and $\gamma'(0) = u$; let $v(t)$ be the parallel vector field along γ with $v(0) = v$. Then we have

$$\begin{aligned} 0 = df_v(u) &= \left(\frac{d}{dt} \right)_{t=0} g(h(v(t), v(t)), Jv(t)) \\ &= g((\bar{\nabla} h)(u, v, v), Jv) + g(h(v, v), G(u, v)) \end{aligned}$$

and

$$(3.1) \quad \begin{aligned} 0 \geq d_v^2 f(u, u) &= g((\bar{\nabla}^2 h)(u, u, v, v), Jv) \\ &+ 2g((\bar{\nabla} h)(u, v, v), G(u, v)) + g(h(v, v), (\bar{\nabla}_u G)(u, v)), \end{aligned}$$

where we have used the fact that $\nabla_X Y = \bar{\nabla}_X Y - h(X, Y)$ and that $G(h(X, Y), Z)$ is tangent to M for X, Y, Z tangent to M . Now, using (2.4), (2.9), (2.10), (2.11), and (2.13), we have

$$(3.2) \quad \begin{aligned} d^2 f_v(u, u) &= g((\bar{\nabla}^2 h)(v, v, u, u), Jv) + 2R(u, v; v, Jh(u, v)) \\ &+ R(u, v; u, Jh(v, v)) + g(h(u, u), Jv) \\ &- g(u, v)g(h(u, v), Jv) + 2g((\bar{\nabla} h)(u, v, v), G(u, v)) \\ &+ g(u, v)g(h(v, v), Ju) - g(h(v, v), Jv). \end{aligned}$$

The function f restricted to the fiber UM_p attains a maximum at v . Thus, if $\beta(t)$, $t \in (-\delta, \delta)$, is a curve in UM_p with $\beta(0) = v$, $\|\beta'(t)\| = 1$, and $\beta'(0) = u$, then realising UM_p as S^2 and using (2.9) we obtain

$$(3.3) \quad \begin{aligned} 0 &= d(f|_{UM_p})_v(u) = \left(\frac{d}{dt}\right)_{t=0} g(h(\beta(t), \beta(t)), J\beta(t)) \\ &= 3g(h(v, v), Ju) \end{aligned}$$

and

$$(3.4) \quad \begin{aligned} 0 &\geq d^2(f|_{UM_p})(u, u) = 6g(h(\beta'(0), v), J\beta'(0)) + 3g(h(v, v), J\beta''(0)) \\ &= 6g(h(u, v), Ju) - 3g(h(v, v), Jv). \end{aligned}$$

Since (3.3) is true for any unit vector u orthogonal to v , we have $h(v, v) = f(v)Jv$ and thus, in light of (2.9), we see that v is an eigenvector of A_{Jv} corresponding to the eigenvalue $f(v)$. Now we can choose an orthonormal basis $\{u_1, u_2, u_3\}$ of T_pM (the tangent space of M at p) which diagonalizes A_{Jv} such that $u_3 = v$. If $A_{Jv}u_i = \rho_i u_i$, $i = 1, 2$, then using $h(v, v) = f(v)Jv$ and $h(u_i, v) = \rho_i Ju_i$ in (3.4) yields

$$(3.5) \quad f(v) - 2\rho_i \geq 0, \quad i = 1, 2.$$

Now, adding the equations (3.2) over basis vectors $\{u_1, u_2, v\}$ and using (2.9), (2.14), and (3.1) as well as minimality, we obtain

$$(3.6) \quad 0 \geq \sum_{i=1}^3 d^2 f_v(u_i, u_i) = \sum_{i=1}^2 K(v, u_i)(f(v) - 2\rho_i) - f(v),$$

where $K(v, u_i)$ is the sectional curvature of the plane section spanned by $\{v, u_i\}$. If k_0 is the infimum of the sectional curvatures of M , then using (3.5) together with $\rho_1 + \rho_2 = -f(v)$ in (3.6) yields $(4k_0 - 1)f(v) \leq 0$. Also, since $f(v)$ is the maximum value of the cubic function f , we have $f(v) \geq 0$ (this also follows from (3.5) and the minimality).

Thus we get that either $4k_0 \leq 1$ or $f(v) = 0$. In case $f(v) = 0$, as $f(v)$ is the maximum value of f , we get $f(u) \leq 0$ for all $u \in UM$, and this together with the formula $f(-u) = -f(u)$ gives $f(u) = 0$, $u \in UM$. Using the standard polarization formula

$$\begin{aligned} 6g(h(u_1, u_2), Ju_3) &= f(u_1 + u_2 + u_3) - f(u_2 + u_3) - f(u_1 + u_3) \\ &\quad - f(u_1 + u_2) + f(u_1) + f(u_2) + f(u_3), \end{aligned}$$

which is valid for any symmetric cubic form, we obtain $g(h(u, v), Jw) = 0$, $u, v, w \in UM$, that is, M is totally geodesic.

ACKNOWLEDGMENTS. The author wishes to thank the referee for many helpful suggestions, and Professor M. Abdullah Al-Rashed for his kind help.

References

1. F. Dillen, L. Verstraelen, and L. Vrancken, *On problems of U. Simon concerning minimal submanifolds of the nearly Kaehler 6-sphere*, Bull. Amer. Math. Soc. (N.S.) 19 (1988), 433–438.

2. F. Dillen, B. Opozda, L. Verstraelen, and L. Vrancken, *On totally real 3-dimensional submanifolds of the nearly Kaehler 6-sphere*, Proc. Amer. Math. Soc. **99** (1987), 741–749.
3. N. Ejiri, *Totally real submanifolds in a 6-sphere*, Proc. Amer. Math. Soc. **83** (1981), 759–763.
4. A. Gray, *Almost complex submanifolds of the six sphere*, Proc. Amer. Math. Soc. **20** (1969), 277–279.

Department of Mathematics
College of Science
King Saud University
Riyadh 11451
Saudi Arabia

