

**THREE-DIMENSIONAL THERMO-VISCO-ELASTICITY
WITH THE EINSTEIN–DEBYE $(\theta^3 + \theta)$ -LAW
FOR THE SPECIFIC HEAT.
GLOBAL REGULAR SOLVABILITY**

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*We dedicate the paper to Professor Marek Burnat
for his personal warmth and devotion to mathematics*

ABSTRACT. A three-dimensional thermo-visco-elastic system for the Kelvin–Voigt type material at small strain is considered. The system involves the constant heat conductivity and the specific heat satisfying the Einstein–Debye $(\theta^3 + \theta)$ -law. Such a nonlinear law, relevant at relatively low temperatures, represents the main novelty of the paper. The existence of global regular solutions is proved without the small data assumption. The crucial part of the proof is the strictly positive lower bound on the absolute temperature θ . The problem remains open in the case of the Debye θ^3 -law. The existence of local in time solutions is proved by the Banach successive approximations method. The global *a priori* estimates are derived with the help of the theory of anisotropic Sobolev spaces with a mixed norm. Such estimates allow to extend the local solution step by step in time.

1. Introduction

The aim. In this paper we study the three-dimensional (3-D) thermo-visco-elastic system at small strains with the constant heat conductivity $k > 0$, and the specific heat (heat capacity) $c(\theta)$ satisfying the Einstein–Debye $(\theta^3 + \theta)$ -law,

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$c(\theta) = c_v^1\theta^3 + c_v^2\theta$, where $\theta > 0$ is the absolute temperature and c_v^1, c_v^2 positive constants. The system describes homogeneous, isotropic, linearly responding materials in the Kelvin–Voigt rheology at relatively low temperatures $\theta \ll \theta_D$, below the Debye temperature θ_D . According to the Debye theory the specific heat c depends on θ/θ_D with θ_D as the scaling factor for different materials (known for most materials, see e.g. the monograph by Kittel [16]).

The present paper continues our previous studies [23], [24], where we addressed the global regular solvability of thermo-visco-elastic systems with the specific heat of the forms $c(\theta) = c_v\theta$, $c_v = \text{const} > 0$ in [23], and $c(\theta) = c_v\theta^\sigma$, $\sigma \in (1/2, 1]$ in [24]. Such forms of $c(\theta)$ are relevant at very low temperatures below the range where the Debye law $c(\theta) = c_v\theta^3$ is appropriate.

The Einstein–Debye ($\theta^3 + \theta$)-law combining the Einstein θ -law and the Debye θ^3 -law is typical for metals at low temperatures at which the electron contribution becomes significant.

Prior to discussing mathematical motivations and pointing out the associated technical difficulties for this type of problems, let us add few physical comments (for more details see Section 2).

Specific heat has a weak temperature dependence at high temperatures $\theta \gg \theta_D$ above the Debye temperature θ_D , but decreases down to zero as θ approaches 0. The constant value of the specific heat of many solids is usually referred to as *Dulong–Petit law*. In 1819 Dulong and Petit [26] found experimentally that for many solids at room temperature specific heat is constant.

At this point it is important to emphasize that the global solvability of 3-D thermo-visco-elastic system with constant heat conductivity k and the constant specific heat c is, in spite of great effort through many decades, still remains open in dimensions $n \geq 2$. In dimension $n = 1$ it was established already at the beginning of ninetieth of the last century by Slemrod [31], Dafermos [6], and Dafermos and Hsiao [7]. For detailed references concerning solvability of thermo-visco-elastic systems we refer to Roubíček [27]–[29], authors’ papers [23], [24], and the recent review paper by Zvyagin and Orlov [35]. All known results on multi-dimensional thermo-visco-elasticity deal with a modified energy equation. Modifications involve either the nonconstant specific heat or the nonconstant heat conductivity. In view of the Einstein and the Debye theories it seems natural to consider thermo-visco-elastic systems with the nonlinear temperature-dependent specific heat. Our primary mathematical goal in this paper was to admit the Debye θ^3 -law, $c(\theta) = c_v\theta^3$. To our best knowledge such problem has not been so far addressed in the mathematical literature. Unfortunately, in the case of the θ^3 -law we have been faced with a serious mathematical obstacle to prove strictly positive lower bound for the absolute temperature. We have managed to prove this after adding a linear (possibly small) term $c_v^2\theta$, $c_v^2 = \text{const} > 0$. In other

words, we have assumed the Einstein–Debye $(\theta^3 + \theta)$ -law, $c(\theta) = c_v^1\theta^3 + c_v^2\theta$. Having proved the strict positivity of θ the existence of global regular solutions to the thermo-visco-elastic system can be concluded by using similar arguments as in [24]. These arguments, based on the idea of successive improvement of energy estimates by the application of the theory of anisotropic Sobolev spaces with a mixed norm, indicate that the main role plays just the term $c_v^1\theta^3$. Therefore, all considerations could be repeated provided the lower bound for θ is established.

Finally, let us remark that apart from the mathematical issues the system under consideration may be of some practical interest in the cryogenic engineering problems where one needs to understand and characterize the behavior of various materials on the basis of the mathematical model and recorded materials properties.

Thermo-visco-elastic system. The system under consideration has the following form

$$(1.1) \quad \mathbf{u}_{tt} - \nabla \cdot [\mathbf{A}_1 \boldsymbol{\varepsilon}_t + \mathbf{A}_2(\boldsymbol{\varepsilon} - \theta \boldsymbol{\alpha})] = \mathbf{b} \quad \text{in } \Omega^T := \Omega \times (0, T),$$

$$(1.2) \quad (c_v^1\theta^3 + c_v^2\theta)\theta_t - k\Delta\theta = -\theta(\mathbf{A}_2\boldsymbol{\alpha}) \cdot \boldsymbol{\varepsilon}_t + (\mathbf{A}_1\boldsymbol{\varepsilon}_t) \cdot \boldsymbol{\varepsilon}_t + g \quad \text{in } \Omega^T,$$

where

$$\boldsymbol{\varepsilon} \equiv \boldsymbol{\varepsilon}(\mathbf{u}) = \frac{1}{2}(\nabla\mathbf{u} + (\nabla\mathbf{u})^T), \quad \boldsymbol{\varepsilon}_t \equiv \boldsymbol{\varepsilon}(\mathbf{u}_t) = \frac{1}{2}(\nabla\mathbf{u}_t + (\nabla\mathbf{u}_t)^T),$$

and c_v^1, c_v^2, k are the positive constants.

Here $\Omega \subset \mathbb{R}^3$ is a bounded domain occupied by a body in a fixed reference configuration, and $(0, T)$ is the time interval. The system is completed by appropriate boundary and initial conditions. We assume

$$(1.3) \quad \mathbf{u} = \mathbf{0}, \quad \mathbf{n} \cdot \nabla\theta = 0 \quad \text{on } S^T := S \times (0, T),$$

$$(1.4) \quad \mathbf{u}|_{t=0} = \mathbf{u}_0, \quad \mathbf{u}_t|_{t=0} = \mathbf{u}_1, \quad \theta|_{t=0} = \theta_0 \quad \text{in } \Omega,$$

where S is the boundary of Ω and \mathbf{n} is the unit outward normal to S .

The field $\mathbf{u}: \Omega^T \rightarrow \mathbb{R}^3$ is the displacement, $\theta: \Omega^T \rightarrow \mathbb{R}_+ = (0, \infty)$ is the absolute temperature, the second order tensors $\boldsymbol{\varepsilon} = (\varepsilon_{ij})_{i,j=1,2,3}$ and $\boldsymbol{\varepsilon}_t = ((\varepsilon_t)_{ij})_{i,j=1,2,3}$ denote, respectively, the fields of the linearized strain and the strain rate.

Equation (1.1) is the linear momentum balance with the stress tensor given by a linear thermo-visco-elastic law of the Kelvin–Voigt type (cf. [10, Chapter 5.4])

$$\mathbf{S} = \mathbf{A}_1\boldsymbol{\varepsilon}_t + \mathbf{A}_2(\boldsymbol{\varepsilon} - \theta\boldsymbol{\alpha}).$$

The fourth order tensors

$$\mathbf{A}_1 = ((A_1)_{ijkl})_{i,j,k,l=1,2,3} \quad \text{and} \quad \mathbf{A}_2 = ((A_2)_{ijkl})_{i,j,k,l=1,2,3}$$

are, respectively, the linear viscosity and the elasticity tensors, defined by

$$(1.5) \quad \boldsymbol{\varepsilon} \mapsto \mathbf{A}_m \boldsymbol{\varepsilon} = \lambda_m \operatorname{tr} \boldsymbol{\varepsilon} \mathbf{I} + 2\mu_m \boldsymbol{\varepsilon}, \quad m = 1, 2,$$

where λ_1, μ_1 are the viscosity constants and λ_2, μ_2 are the Lamé constants, both λ_1, μ_1 and λ_2, μ_2 with the values within the elasticity range

$$(1.6) \quad \mu_m > 0, \quad 3\lambda_m + 2\mu_m > 0, \quad m = 1, 2,$$

$\mathbf{I} = (\delta_{ij})_{i,j=1,2,3}$ is the identity tensor, and $\operatorname{tr} \boldsymbol{\varepsilon}$ denotes the trace of $\boldsymbol{\varepsilon}$.

The second order symmetric tensor $\boldsymbol{\alpha} = (\alpha_{ij})_{i,j=1,2,3}$ with constant entries α_{ij} represents the thermal expansion. The vector field $\mathbf{b}: \Omega^T \rightarrow \mathbb{R}^3$ is the external body force.

Equation (1.2) is the energy balance in which the linear Fourier law for the heat flux $\mathbf{q} = -k\nabla\theta$ with the constant heat conductivity $k > 0$, and the Einstein–Debye law for the specific heat, $c(\theta) = c_v^1\theta^3 + c_v^2\theta$, with constant $c_v^1, c_v^2 > 0$, have been adopted.

The first two nonlinear terms on the right-hand side of (1.2) represent heat sources created by the deformation of the material due to thermal expansion and by the viscosity. The field $g: \Omega^T \rightarrow \mathbb{R}$ is the external heat source. The boundary conditions in (1.3) mean that the body is fixed at the boundary S and is there thermally isolated. The initial conditions (1.4) prescribe displacement, velocity and temperature at $t = 0$.

We remark that since our main goal is to focus on the existence of global regular solutions we have assumed the simplest homogeneous boundary conditions (1.3). However, with some additional technical complications, other types of nonhomogeneous boundary conditions can be considered as well.

The system (1.1)–(1.2) can be derived by various arguments of thermodynamics, see e.g. [13], [21], [27], [3]. In Section 2 we summarize its thermodynamic basis. As a main point we put emphasis on the Debye and the Einstein–Debye laws of the specific heat.

Above and hereafter the summation convention over the repeated indices is used. Vectors (tensors of the first order), tensors of the second order (referred to simply as tensors), and tensors of higher order are denoted by bold letters. A dot designates the scalar product, irrespective of the space in question, e.g. for $\mathbf{u} = (u_i)_{i=1,2,3}$, $\mathbf{v} = (v_i)_{i=1,2,3}$, $\mathbf{S} = (S_{ij})_{i,j=1,2,3}$, $\mathbf{R} = (R_{ij})_{i,j=1,2,3}$, $\mathbf{A} = (A_{ijkl})_{i,j,k,l=1,2,3}$, $\boldsymbol{\varepsilon} = (\varepsilon_{ij})_{i,j=1,2,3}$, we have

$$\begin{aligned} \mathbf{u} \cdot \mathbf{v} &= u_i v_i, & \mathbf{S} \cdot \mathbf{R} &= S_{ij} R_{ij}, & \mathbf{S} \mathbf{u} &= (S_{ij} u_j)_{i=1,2,3}, \\ \mathbf{A} \boldsymbol{\varepsilon} &= (A_{ijkl} \varepsilon_{kl})_{i,j=1,2,3}, & (\mathbf{A} \boldsymbol{\varepsilon}) \cdot \boldsymbol{\varepsilon} &= A_{ijkl} \varepsilon_{kl} \varepsilon_{ij}, \end{aligned}$$

where the summation convention is used.

The term *field* means a function of a material point $\mathbf{x} \in \mathbb{R}^3$ and time t . For the reader's convenience we use the notation \mathbf{u}_t (instead of $\dot{\mathbf{u}}$) for the material

time derivative of the field \mathbf{u} (with respect to t holding \mathbf{x} fixed). The operators ∇ and $\nabla \cdot$ denote the material gradient and the divergence (with respect to \mathbf{x} holding t fixed). For the divergence we use the convention of the contraction over the last index, e.g.,

$$\nabla \cdot (\mathbf{A}\boldsymbol{\varepsilon}) = \left(\frac{\partial}{\partial x_j} (A_{ijkl} \varepsilon_{kl}) \right)_{i=1,2,3}.$$

We write

$$f_{,i} = \frac{\partial f}{\partial x_i}, \quad i = 1, 2, 3, \quad f_t = \frac{\partial f}{\partial t}, \quad \boldsymbol{\varepsilon} = (\varepsilon_{ij})_{i,j=1,2,3},$$

$$F_{,\boldsymbol{\varepsilon}}(\boldsymbol{\varepsilon}, \theta) = \left(\frac{\partial F(\boldsymbol{\varepsilon}, \theta)}{\partial \varepsilon_{ij}} \right)_{i,j=1,2,3}, \quad F_{,\theta}(\boldsymbol{\varepsilon}, \theta) = \frac{\partial F(\boldsymbol{\varepsilon}, \theta)}{\partial \theta},$$

where the space and the time derivatives are material.

For simplicity, whenever there is no danger of confusion, we omit arguments $(\boldsymbol{\varepsilon}, \theta)$ of the function $f(\boldsymbol{\varepsilon}, \theta)$. The specification of tensor indices is omitted as well. For vector $\mathbf{b} = (b_i)_{i=1,2,3}$ and tensor $\mathbf{B} = (B_{ij})_{i,j=1,2,3}$ we denote

$$|\mathbf{b}| = (b_i b_i)^{1/2}, \quad |\mathbf{B}| = (B_{ij} B_{ij})^{1/2}.$$

Linear elasticity and viscosity operators. For the further analysis it is convenient to formulate problem (1.1)–(1.4) in terms of the linear viscosity and elasticity operators, \mathbf{Q}_1 and \mathbf{Q}_2 , defined by

$$(1.7) \quad \mathbf{u} \mapsto \mathbf{Q}_m \mathbf{u} = \nabla \cdot (\mathbf{A}_m \boldsymbol{\varepsilon}(\mathbf{u})) = \mu_m \Delta \mathbf{u} + (\lambda_m + \mu_m) \nabla (\nabla \cdot \mathbf{u}), \quad m = 1, 2,$$

with the domains $D(\mathbf{Q}_m) = \mathbf{H}^2(\Omega) \cap \mathbf{H}_0^1(\Omega)$.

For the notational simplicity we introduce also the second order symmetric tensor $\mathbf{B} = (B_{ij})$ defined by

$$(1.8) \quad \mathbf{B} := -\mathbf{A}_2 \boldsymbol{\alpha} = -((A_2)_{ijkl} \alpha_{kl}).$$

Then system (1.1)–(1.2) takes the form

$$(1.9) \quad \begin{aligned} \mathbf{u}_{tt} - \mathbf{Q}_1 \mathbf{u}_t &= \mathbf{Q}_2 \mathbf{u} + \nabla \cdot (\theta \mathbf{B}) + \mathbf{b} && \text{in } \Omega^T, \\ (c_v^1 \theta^3 + c_v^2 \theta) \theta_t - k \Delta \theta &= \theta \mathbf{B} \cdot \boldsymbol{\varepsilon}_t + (\mathbf{A}_1 \boldsymbol{\varepsilon}_t) \cdot \boldsymbol{\varepsilon}_t + g && \text{in } \Omega^T, \end{aligned}$$

with the boundary and initial conditions (1.3), (1.4).

Assumptions and their implications. Throughout we shall assume that

- (A1) $\Omega \subset \mathbb{R}^3$ is a bounded domain with the boundary S of class at least C^2 ; $T > 0$ is an arbitrary finite number;
- (A2) $\boldsymbol{\alpha} = (\alpha_{ij})_{i,j=1,2,3}$ is a second order symmetric tensor with constant entries α_{ij} ;
- (A3) The fourth order tensors \mathbf{A}_1 and \mathbf{A}_2 are defined by (1.5) with the coefficients $\mu_m, \lambda_m, m = 1, 2$, satisfying (1.6).

We list the implications of assumption (A3) which are used in the further analysis. The conditions (1.5), (1.6) ensure the symmetry of tensors \mathbf{A}_m

$$(1.10) \quad (\mathbf{A}_m)_{ijkl} = (\mathbf{A}_m)_{jikl} = (\mathbf{A}_m)_{klij}, \quad m = 1, 2,$$

and their coercivity and boundedness

$$(1.11) \quad a_{m*}|\boldsymbol{\varepsilon}|^2 \leq (\mathbf{A}_m \boldsymbol{\varepsilon}) \cdot \boldsymbol{\varepsilon} \leq a_m^*|\boldsymbol{\varepsilon}|^2, \quad m = 1, 2,$$

where $a_{m*} = \min\{3\lambda_m + 2\mu_m, 2\mu_m\}$ and $a_m^* = \max\{3\lambda_m + 2\mu_m, 2\mu_m\}$. Moreover, (1.6) ensures the following properties of operators \mathbf{Q}_m , $m = 1, 2$:

- \mathbf{Q}_m are strongly elliptic (property holding true under weaker assumption $\mu_m > 0$, $\lambda_m + 2\mu_m > 0$, (see [25, Section 7])) and satisfy the estimate (see [20, Lemma 3.2]):

$$(1.12) \quad c_m \|\mathbf{u}\|_{\mathbf{H}^2(\Omega)} \leq \|\mathbf{Q}_m \mathbf{u}\|_{L_2(\Omega)} \quad \text{for } \mathbf{u} \in D(\mathbf{Q}_m), \quad m = 1, 2,$$

with the positive constants c_m depending on Ω . Since clearly,

$$\|\mathbf{Q}_m \mathbf{u}\|_{L_2(\Omega)} \leq \bar{c}_m \|\mathbf{u}\|_{\mathbf{H}^2(\Omega)}, \quad \bar{c}_m > 0,$$

it follows that the norms $\|\mathbf{Q}_m \mathbf{u}\|_{L_2(\Omega)}$ and $\|\mathbf{u}\|_{\mathbf{H}^2(\Omega)}$ are equivalent on $D(\mathbf{Q}_m)$.

- The operators \mathbf{Q}_m are self-adjoint on $D(\mathbf{Q}_m)$:

$$(1.13) \quad (\mathbf{Q}_m \mathbf{u}, \mathbf{v})_{L_2(\Omega)} = -\mu_m (\nabla \mathbf{u}, \nabla \mathbf{v})_{L_2(\Omega)} \\ - (\lambda_m + \mu_m) (\nabla \cdot \mathbf{u}, \nabla \cdot \mathbf{v})_{L_2(\Omega)} = (\mathbf{u}, \mathbf{Q}_m \mathbf{v})_{L_2(\Omega)}$$

for $\mathbf{u}, \mathbf{v} \in D(\mathbf{Q}_m)$.

- The operators \mathbf{Q}_m are positive on $D(\mathbf{Q}_m)$:

$$(1.14) \quad (-\mathbf{Q}_m \mathbf{u}, \mathbf{u})_{L_2(\Omega)} = \mu_m \|\nabla \mathbf{u}\|_{L_2(\Omega)}^2 + (\lambda_m + \mu_m) \|\nabla \cdot \mathbf{u}\|_{L_2(\Omega)}^2 \geq 0$$

for $\mathbf{u} \in D(\mathbf{Q}_m)$. Hence, there exist the fractional powers $\mathbf{Q}_m^{1/2}$ with the domains $D(\mathbf{Q}_m^{1/2}) = \mathbf{H}_0^1(\Omega)$, satisfying

$$(1.15) \quad (\mathbf{Q}_m^{1/2} \mathbf{u}, \mathbf{Q}_m^{1/2} \mathbf{v})_{L_2(\Omega)} = (-\mathbf{Q}_m \mathbf{u}, \mathbf{v})_{L_2(\Omega)} = (\mathbf{u}, -\mathbf{Q}_m \mathbf{v})_{L_2(\Omega)}$$

for $\mathbf{u}, \mathbf{v} \in D(\mathbf{Q}_m)$.

Let us also notice that by (1.11) and the Korn inequality

$$(1.16) \quad d^{1/2} \|\mathbf{u}\|_{\mathbf{H}^1(\Omega)} \leq \|\boldsymbol{\varepsilon}(\mathbf{u})\|_{L_2(\Omega)} \quad \text{for } \mathbf{u} \in \mathbf{H}_0^1(\Omega), \quad d > 0,$$

it follows that

$$(1.17) \quad \|\mathbf{Q}_m^{1/2} \mathbf{u}\|_{L_2(\Omega)}^2 = \mu_m \|\nabla \mathbf{u}\|_{L_2(\Omega)}^2 + (\lambda_m + \mu_m) \|\nabla \cdot \mathbf{u}\|_{L_2(\Omega)}^2 \\ = (\mathbf{A}_m \boldsymbol{\varepsilon}(\mathbf{u}), \boldsymbol{\varepsilon}(\mathbf{u}))_{L_2(\Omega)} \geq a_{m*} \|\boldsymbol{\varepsilon}(\mathbf{u})\|_{L_2(\Omega)}^2 \geq a_{m*} d \|\mathbf{u}\|_{\mathbf{H}^1(\Omega)}^2.$$

Thus, the norms $\|\mathbf{Q}_m^{1/2} \mathbf{u}\|_{L_2(\Omega)}$ and $\|\mathbf{u}\|_{\mathbf{H}^1(\Omega)}$ are equivalent on $D(\mathbf{Q}_m^{1/2})$.

Main result. This result is analogous to that proved in [24].

THEOREM 1.1 (Existence). *Let assumptions (A1)–(A3) formulated above be satisfied, and*

$$\begin{aligned} \mathbf{b} &\in \mathbf{L}_{10^+}(\Omega^T) \cap \mathbf{L}_{5,12}(\Omega^T), & \mathbf{u}_0 &\in \mathbf{W}_{5^+}^2(\Omega), \\ \mathbf{u}_1 &\in \mathbf{B}_{5^+,5^+}^{2-2/5^+}(\Omega), \quad g \in L_{5^+}(0, T; L_\infty(\Omega)), & g &\geq 0, \\ \theta_0 &\in H^1(\Omega) \cap B_{5^+,5^+}^{2-2/5^+}(\Omega) \cap L_\infty(\Omega), & \theta_0 &\geq \underline{\theta} > 0, \end{aligned}$$

where $\underline{\theta}$ is a constant. Then there exists a global solution to problem (1.1)–(1.4) such that

$$\mathbf{u}_t \in \mathbf{W}_{5^+}^{2,1}(\Omega^T) \quad \text{and} \quad \theta \in W_{5^+}^{2,1}(\Omega^T),$$

where 5^+ is a number larger than 5 but close to 5. The spaces used above are defined in Section 3. Moreover,

$$\theta(t) \geq \underline{\theta} \exp(-at) \equiv \theta_*(t) \quad \text{for } t \leq T,$$

where a is a positive constant given by $a = |\mathbf{B}| / (2a_{1*} \min \{c_v^1, c_v^2\})$.

Plan of the paper. In Section 2 we present the thermodynamic basis of system (1.1)–(1.2). In Section 3 we define spaces used in this paper, in particular the anisotropic Sobolev spaces with a mixed norm. We recall the corresponding imbeddings and interpolations as well as the trace and the inverse trace theorems for the Sobolev–Slobodetskii spaces with a mixed norm. Moreover, we present auxiliary results on the solvability of linear parabolic initial-boundary value problems in such spaces. Section 4 is devoted to the proof of a global positive infimum of temperature. In Section 5, applying the Banach method of successive approximations, we state the local existence of solutions such that $\mathbf{u}_t \in \mathbf{W}_{5^+}^{2,1}(\Omega^t)$ and $\theta \in W_{5^+}^{2,1}(\Omega^t)$, where $t > 0$ is sufficiently small. In the proof we can use exactly the same arguments as in [24, Section 5]. In Section 6 we derive *a priori* global estimates such that $\mathbf{u}_t \in \mathbf{W}_{5^+}^{2,1}(\Omega^t)$ and $\theta \in W_{5^+}^{2,1}(\Omega^t)$ where $t > 0$ is arbitrary finite. In this case the derivation is much shorter than in [24].

Combining the results of sections 5 and 6 in section 7 we conclude the global existence of solutions.

2. Thermodynamic basis

We recall (see [23], [24]) the thermodynamic basis of the thermo-visco-elastic system (1.1)–(1.2) with the special emphasis put onto the Debye θ^3 -law and the Einstein–Debye ($\theta^3 + \theta$)-law of the specific heat.

The system (1.1)–(1.2) represents the local forms of the balance laws for the linear momentum and the internal energy in a referential description, with the referential mass density assumed constant, normalized to unity, $\varrho_0 = 1$:

$$(2.1) \quad \mathbf{u}_{tt} - \nabla \cdot \mathbf{S} = \mathbf{b}, \quad e_t + \nabla \cdot \mathbf{q} - \mathbf{S} \cdot \boldsymbol{\varepsilon}_t = g.$$

Here \mathbf{S} is the stress tensor, \mathbf{q} is the referential heat flux, and e is the specific internal energy.

The system is governed by two thermodynamic potentials. The first one is the specific free energy $f = \widehat{f}(\boldsymbol{\varepsilon}, \theta)$ which by a thermodynamic requirement is strictly concave with respect to $\theta > 0$ for all $\boldsymbol{\varepsilon}$. The second one is the dissipation potential $\mathcal{D} = \widehat{\mathcal{D}}(\boldsymbol{\varepsilon}_t, \nabla\theta; \boldsymbol{\varepsilon}, \theta)$, which by a thermodynamic requirement is nonnegative, convex in $(\boldsymbol{\varepsilon}_t, \nabla\theta)$ – variables and such that $\mathcal{D}(\mathbf{0}, \mathbf{0}; \boldsymbol{\varepsilon}, \theta) = 0$ for all $(\boldsymbol{\varepsilon}, \theta)$. In [14] and [3] \mathcal{D} is referred to as the pseudopotential of dissipation.

The only difference of the present paper in comparison with [23], [24] is the form of the thermal part $f_*(\theta)$ of the free energy

$$(2.2) \quad f(\boldsymbol{\varepsilon}, \theta) = f_*(\theta) + W(\boldsymbol{\varepsilon}, \theta),$$

where

$$(2.3) \quad f_*(\theta) = -\frac{c_v^1}{12}\theta^4 - \frac{c_v^2}{2}\theta^2, \quad c_v^1, c_v^2 = \text{const} > 0.$$

The second term in (2.2) represents the elastic energy

$$(2.4) \quad W(\boldsymbol{\varepsilon}, \theta) = \frac{1}{2}\boldsymbol{\varepsilon} \cdot (\mathbf{A}_2\boldsymbol{\varepsilon}) - \theta\boldsymbol{\varepsilon} \cdot (\mathbf{A}_2\boldsymbol{\alpha}).$$

In [23] it has been assumed that

$$(2.5) \quad f_*(\theta) = -\frac{c_v}{2}\theta^2, \quad c_v = \text{const} > 0,$$

whereas in [24]

$$(2.6) \quad f_*(\theta) = -\frac{c_v}{\sigma(\sigma+1)}\theta^{\sigma+1}$$

with $c_v = \text{const} > 0$ and $1/2 < \sigma \leq 1$.

The paper [24] provides an essential improvement of the theoretical results from [23].

The thermal energy (2.3) is associated with the Einstein–Debye law of the specific heat. The case $c_v^2 = 0$ corresponds to the Debye law. Both cases are relevant at low temperature range; see comments below.

In view of thermodynamic relations

$$(2.7) \quad \begin{aligned} \eta &= -f_{,\theta} = \eta_*(\theta) + \boldsymbol{\varepsilon} \cdot (\mathbf{A}_2\boldsymbol{\alpha}), \\ e &= f + \theta\eta = e_*(\theta) + \frac{1}{2}\boldsymbol{\varepsilon} \cdot (\mathbf{A}_2\boldsymbol{\varepsilon}), \\ c &= e_{,\theta} = c_*, \end{aligned}$$

in case of (2.3) we have

$$(2.8) \quad \begin{aligned} \eta_*(\theta) &= \frac{c_v^1}{3} \theta^3 + c_v^2 \theta, \\ e_*(\theta) &= f_*(\theta) + \theta \eta_*(\theta) = \frac{c_v^1}{4} \theta^4 + \frac{c_v^2}{2} \theta^2, \\ c_*(\theta) &= e_{*,\theta} = c_v^1 \theta^3 + c_v^2 \theta. \end{aligned}$$

According to (2.1)₂ and (2.7)₃ this gives rise to the term $(c_v^1 \theta^3 + c_v^2 \theta) \theta_t$ in temperature equation (1.2).

Remarks on the theories of specific heat. There exists extensive literature in solid state physics on the theories of specific heat (see, e.g., [2], [5], [16], [19], [30], [12]). It seems to be of interest to compile some basic facts on the four well-known models of the specific heat:

- the classical *Dulong–Petit model* (1819) [26];
- the quantum mechanical *Einstein model* (1907) [11];
- the *Debye model* (1912) [8] expanding the Einstein model;
- the *Einstein–Debye model* for metals at low temperatures.

In the Dulong–Petit model the specific heat is constant. It is known to show poor agreement with the experiment except at high temperatures. The Einstein model yields good agreement with the experiment at very high and very low temperatures, but not in between. The Debye theory provides a more accurate model. The thermal energy expression from the Debye theory of the specific heat is of the form (in our notation)

$$(2.9) \quad e_*(\theta) = \bar{c} \frac{\theta^4}{\theta_D^3} \int_0^{\theta_D/\theta} \frac{x^3}{\exp x - 1} dx,$$

where θ_D is the *Debye temperature* and \bar{c} a positive physical constant. Thus, the Debye specific heat is the function of the ratio $\xi = \theta/\theta_D$, given by

$$(2.10) \quad c_*(\theta) = e_{*,\theta} = \bar{c} D \left(\frac{\theta}{\theta_D} \right),$$

where

$$(2.11) \quad D(\xi) = 4\xi^3 \int_0^{1/\xi} \frac{1}{\exp x - 1} dx - \frac{1}{\xi(\exp 1/\xi - 1)}$$

is known as the *Debye specific heat function*. Even though the integral in (2.9) and (2.11) cannot be evaluated in closed form, the low and high temperature limits can be assessed.

For the high temperature case where $\theta \gg \theta_D$, the value of x is very small throughout the range of integral. This justifies using the approximation to the

exponential by the exponential series $\exp(x) \cong 1 + x$. This reduces the energy expression (2.9) to (see, e.g. [30, Chapter 7])

$$(2.12) \quad e_*(\theta) = \bar{c} \frac{\theta^4}{\theta_D^3} \int_0^{\theta_D/\theta} x^2 dx = \frac{\bar{c}}{3} \frac{\theta^4}{\theta_D^3} \left(\frac{\theta_D}{\theta} \right)^3 = \frac{\bar{c}}{3} \theta.$$

Hence, in this case

$$(2.13) \quad c_*(\theta) = e_{*,\theta} = \frac{\bar{c}}{3},$$

which yields the constant Dulong–Petit specific heat.

For low temperatures where $\theta \ll \theta_D$, the exponential in the denominator becomes very large before reaching the limit, implying that the integrand in (2.9) is very small near the upper limit. This makes it plausible to approximate the integral by increasing the limit to infinity to make use of the standard integral

$$\int_0^\infty \frac{x^3}{\exp x - 1} dx = \frac{\pi^4}{15}.$$

Then the energy becomes

$$(2.14) \quad e_*(\theta) = \frac{\bar{c}\pi^4}{15} \frac{\theta^4}{\theta_D^3},$$

so that the corresponding specific heat is

$$(2.15) \quad c_*(\theta) = e_{*,\theta} = c_1 \left(\frac{\theta}{\theta_D} \right)^3, \quad \text{where } c_1 = \frac{4\pi^4}{15} \bar{c}.$$

This yields the *Debye θ^3 -law* for the specific heat (see e.g. [2, Section 4.3]).

This θ^3 -form of the specific heat at low temperatures is known to agree with experiment for nonmetals. For metals the electronic specific heat becomes significant at low temperatures and results in the additional linear term in θ

$$(2.16) \quad c_*(\theta) = c_1 \left(\frac{\theta}{\theta_D} \right)^3 + c_2\theta, \quad c_2 = \text{const} > 0.$$

Such form of the specific heat is referred to as the *Einstein–Debye specific heat*. The θ^3 term arises from the lattice vibrations, and the linear term from the electrons conduction. The Einstein contribution $c_2\theta$ becomes dominating at very low temperatures.

The dissipation potential. For system (1.1)–(1.2) it has exactly the same form as in [23], [24]

$$(2.17) \quad \mathcal{D} = \frac{1}{2\theta} \boldsymbol{\varepsilon}_t \cdot (\mathbf{A}_1 \boldsymbol{\varepsilon}_t) + \frac{k}{2} \theta^2 \left| \nabla \frac{1}{\theta} \right|^2,$$

where \mathbf{A}_1 is the fourth order viscosity tensor given by (1.5), and $k > 0$ is the constant heat conductivity.

In particular, the free energy (2.2) and the dissipation potential (2.17) lead to the same formulas for the stress tensor \mathbf{S} and the heat flux \mathbf{q} . Moreover, the Clausius-Duhem inequality is satisfied

$$(2.18) \quad \eta_t + \nabla \cdot \frac{\mathbf{q}}{\theta} = \sigma + \frac{g}{\theta} \geq \frac{g}{\theta},$$

where

$$(2.19) \quad \sigma := \frac{\partial \mathcal{D}}{\partial \nabla(1/\theta)} \cdot \nabla \frac{1}{\theta} + \frac{\partial \mathcal{D}}{\partial \varepsilon_t} \cdot \varepsilon_t = k\theta^2 \left| \nabla \frac{1}{\theta} \right|^2 + \frac{1}{\theta} (\mathbf{A}_1 \varepsilon_t) \cdot \varepsilon_t \geq 0$$

is the specific entropy production. This inequality together with the positive lower bound for temperature constitute the basis of energy estimates in the existence proof, see Sections 4–6.

3. Notation and auxiliary results

For readers convenience this section recalls basic facts from [24, Section 3] and adds new ones.

Notation. Let $\Omega \subset \mathbb{R}^n$, $n \geq 1$, be a domain in \mathbb{R}^n with boundary S . Let $\Omega^T = \Omega \times (0, T)$, $S^T = S \times (0, T)$ with $T > 0$ finite. By $W_p^k(\Omega)$, $k \in \mathbb{N} \cup \{0\} \equiv \mathbb{N}_0$, $p \in [1, \infty)$, we denote the Sobolev space with the finite norm

$$\|u\|_{W_p^k(\Omega)} = \left(\sum_{|\alpha| \leq k} \int_{\Omega} |D_x^\alpha u|^p dx \right)^{1/p},$$

where $\alpha = (\alpha_1, \dots, \alpha_n)$ is a multi-index, $\alpha_i \in \mathbb{N}_0$, $|\alpha| = \alpha_1 + \dots + \alpha_n$, $D_x^\alpha = \partial_{x_1}^{\alpha_1} \dots \partial_{x_n}^{\alpha_n}$. Let $H^k(\Omega) = W_2^k(\Omega)$.

Next, we introduce the anisotropic Lebesgue spaces $L_{p,p_0}(\Omega^T) = L_{p_0}(0, T; L_p(\Omega))$, $p, p_0 \in [1, \infty]$, with the finite norm

$$\|u\|_{L_{p,p_0}(\Omega^T)} = \left(\int_0^T \|u(t)\|_{L_p(\Omega)}^{p_0} dt \right)^{1/p_0}.$$

Moreover, $W_{p,p_0}^{k,k/2}(\Omega^T)$, $k, k/2 \in \mathbb{N}_0$, $p, p_0 \in [1, \infty]$ are Sobolev spaces with a mixed norm, which are the completion of $C^\infty(\Omega^T)$ -functions under the finite norm

$$\|u\|_{W_{p,p_0}^{k,k/2}(\Omega^T)} = \left(\int_0^T \left(\sum_{|\alpha|+2a \leq k} \int_{\Omega} |D_x^\alpha \partial_t^a u|^p dx \right)^{p_0/p} dt \right)^{1/p_0}.$$

By $W_{p,p_0}^{s,s/2}(\Omega^T)$, $s \in \mathbb{R}_+$, $p, p_0 \in [1, \infty]$, we denote the Sobolev–Slobodetskiĭ space with the finite norm

$$\begin{aligned} \|u\|_{W_{p,p_0}^{s,s/2}(\Omega^T)} &= \sum_{|\alpha|+2a \leq [s]} \|D_x^\alpha \partial_t^a u\|_{L_{p,p_0}(\Omega^T)} \\ &+ \left[\int_0^T \left(\int_{\Omega} \int_{\Omega} \sum_{|\alpha|+2a=[s]} \frac{|D_x^\alpha \partial_t^a u(x, t) - D_{x'}^\alpha \partial_t^a u(x', t)|^p}{|x - x'|^{n+p(s-[s])}} dx dx' \right)^{p_0/p} dt \right]^{1/p_0} \end{aligned}$$

$$+ \left[\int_0^T \int_0^T \left(\int_{\Omega} \sum_{|\alpha|+2a=[s]} \frac{|D_x^\alpha \partial_t^a u(x, t) - D_x^\alpha \partial_{t'}^a u(x, t')|^p}{|t - t'|^{1+p(s/2-[s/2])}} dx \right)^{p_0/p} dt dt' \right]^{1/p_0},$$

where $a \in \mathbb{N}_0$ and $[s]$ is the integer part of s . For s odd the one before last term in the above norm vanishes whereas for s even the two last terms vanish.

We use also the notation $L_p(\Omega^T) = L_{p,p}(\Omega^T)$, $W_p^{s,s/2}(\Omega^T) = W_{p,p}^{s,s/2}(\Omega^T)$, and so on.

By $B_{p,p_0}^l(\Omega)$, $l \in \mathbb{R}_+$, $p, p_0 \in [1, \infty)$ we denote the Besov space of functions making the following norm finite

$$\|u\|_{B_{p,p_0}^l(\Omega)} = \|u\|_{L_p(\Omega)} + \left(\sum_{i=1}^n \int_0^\infty \frac{\|\Delta_i^m(h, \Omega) \partial_{x_i}^k u\|_{L_p(\Omega)}^{p_0}}{h^{1+(l-k)p_0}} dh \right)^{1/p_0},$$

where $k \in \mathbb{N}_0$, $m \in \mathbb{N}$, $m > l - k > 0$, $\Delta_i^j(h, \Omega)u$, $j \in \mathbb{N}$, $h \in \mathbb{R}_+$, is the finite difference of the order j of the function $u(x)$ with respect to x_i , with $\Delta_i^1(h, \Omega)u = \Delta_i(h, \Omega)u = u(x_1, \dots, x_{i-1}, x_i + h, x_{i+1}, \dots, x_n) - u(x_1, \dots, x_n)$, $\Delta_i^j(h, \Omega)u = \Delta_i(h, \Omega)\Delta_i^{j-1}(h, \Omega)u$ and $\Delta_i^j(h, \Omega)u = 0$ for $x_i + jh \notin \Omega$.

From Golovkin [15] it is known that the norms of the Besov space $B_{p,p_0}^l(\Omega)$ are equivalent for different m and k satisfying the condition $m > l - k > 0$.

By $C^{\alpha, \alpha/2}(\Omega^T)$, $\alpha \in (0, 1)$, we denote the anisotropic Hölder space of functions making the following norm finite

$$\|u\|_{C^{\alpha, \alpha/2}(\Omega^T)} = \sup_{\Omega^T} |u(x, t)| + \sup_{x', x'', t} \frac{|u(x', t) - u(x'', t)|}{|x' - x''|^\alpha} + \sup_{x, t', t''} \frac{|u(x, t') - u(x, t'')|}{|t' - t''|^{\alpha/2}}.$$

By δ we denote a small positive number, and by c a generic positive constant which changes its value from formula to formula and depends at most on the imbedding constants, constants of the considered problem, and the regularity of the boundary.

By $\varphi = \varphi(\sigma_1, \dots, \sigma_k)$, $k \in \mathbb{N}$, we denote a generic function which is a positive increasing function of its arguments $\sigma_1, \dots, \sigma_k$, and may change its form from formula to formula.

Boldface \mathbf{L} , \mathbf{W} , \mathbf{B} are used for the corresponding spaces of vector and tensor valued functions.

Auxiliary results. We use the following interpolation lemma

LEMMA 3.1. (see [1, Chapter 4, Section 18]) *Let $u \in W_{p,p_0}^{s,s/2}(\Omega^T)$, $s \in \mathbb{R}_+$, $p, p_0 \in [1, \infty]$, $\Omega \subset \mathbb{R}^3$. Let $\sigma \in \mathbb{R}_+ \cup \{0\}$, and*

$$\varkappa = \frac{3}{p} + \frac{2}{p_0} - \frac{3}{q} - \frac{2}{q_0} + |\alpha| + 2a + \sigma < s.$$

Then $D_x^\alpha \partial_t^\alpha u \in W_{q,q_0}^{\sigma,\sigma/2}(\Omega^T)$, $q \geq p$, $q_0 \geq p_0$, and there exists $\varepsilon \in (0, 1)$ such that

$$\|D_x^\alpha \partial_t^\alpha u\|_{W_{q,q_0}^{\sigma,\sigma/2}(\Omega^T)} \leq \varepsilon^{s-\varkappa} \|u\|_{W_{p,p_0}^{s,s/2}(\Omega^T)} + c\varepsilon^{-\varkappa} \|u\|_{L_{p,p_0}(\Omega^T)}.$$

As a special case of Lemma 3.1 we need

LEMMA 3.2. (see [1, Chapter 4, Section 18]) Let $u \in W_p^s(\Omega)$, $s \in \mathbb{R}_+$, $p \in [1, \infty]$, $\Omega \subset \mathbb{R}^3$. Let $\sigma \in \mathbb{R}_+ \cup \{0\}$, and

$$\varkappa = \frac{3}{p} - \frac{3}{q} + |\alpha| + \sigma < s.$$

Then $D_x^\alpha u \in W_q^\sigma(\Omega)$, $q \geq p$, and there exists $\varepsilon \in (0, 1)$ such that

$$\|D_x^\alpha u\|_{W_q^\sigma(\Omega)} \leq \varepsilon^{s-\varkappa} \|u\|_{W_p^s(\Omega)} + c\varepsilon^{-\varkappa} \|u\|_{L_p(\Omega)}.$$

LEMMA 3.3 (Imbedding between Besov spaces [1, Chapter 3, Section 18]). Let $u \in B_{r_1, r_2}^{\sigma-2/r_2}(\Omega)$. Then $u \in B_{r'_1, r'_2}^{\sigma'-2/r'_2}(\Omega)$, $\Omega \subset \mathbb{R}^3$, if

$$\frac{3}{r_1} + \frac{2}{r_2} - \frac{3}{r'_1} - \frac{2}{r'_2} + \sigma' \leq \sigma,$$

where $r'_i \geq r_i$, $i = 1, 2$, and $\sigma \geq \sigma'$.

Let us consider the problem

$$(3.1) \quad \begin{aligned} \mathbf{u}_t - \mathbf{Q}\mathbf{u} &= \mathbf{f} && \text{in } \Omega^T, \\ \mathbf{u} &= \mathbf{0} && \text{on } S^T, \\ \mathbf{u}|_{t=0} &= \mathbf{u}_0 && \text{in } \Omega, \end{aligned}$$

where $\Omega \subset \mathbb{R}^3$ and

$$\mathbf{Q}\mathbf{u} = \mu\Delta\mathbf{u} + \nu\nabla(\nabla \cdot \mathbf{u})$$

with $\mu > 0$, $\nu > 0$. Let us notice that \mathbf{Q} replaces \mathbf{Q}_1 , so $\mu = \mu_1$, $\nu = \lambda_1 + \mu_1$. Hence assumption (1.6) implies that $\mu > 0$ and $\nu > 0$.

LEMMA 3.4 (Parabolic system in $\mathbf{W}_{p,p_0}^{2,1}(\Omega^T)$ [17], [22], [33], [32]).

(a) Assume that $\mathbf{f} \in \mathbf{L}_{p,p_0}(\Omega^T)$, $\mathbf{u}_0 \in \mathbf{B}_{p,p_0}^{2-2/p_0}(\Omega)$, $p, p_0 \in (1, \infty)$, and $S \in C^2$. If $2 - 2/p_0 - 1/p > 0$ the compatibility condition $\mathbf{u}_0|_S = \mathbf{0}$ is assumed. Then there exists a unique solution to problem (3.1) such that $\mathbf{u} \in \mathbf{W}_{p,p_0}^{2,1}(\Omega^T)$ and

$$(3.2) \quad \|\mathbf{u}\|_{\mathbf{W}_{p,p_0}^{2,1}(\Omega^T)} \leq c(\|\mathbf{f}\|_{\mathbf{L}_{p,p_0}(\Omega^T)} + \|\mathbf{u}_0\|_{\mathbf{B}_{p,p_0}^{2-2/p_0}(\Omega)})$$

with constant c depending on Ω , S , p , p_0 .

(b) Assume that $\mathbf{f} = \nabla \cdot \mathbf{g} + \mathbf{b}$, $\mathbf{g} = (g_{ij})$, $\mathbf{b} = (b_i)$, $\mathbf{g}, \mathbf{b} \in \mathbf{L}_{p,p_0}(\Omega^T)$, and $\mathbf{u}_0 \in \mathbf{B}_{p,p_0}^{1-2/p_0}(\Omega)$. Assume the compatibility condition

$$\mathbf{u}_0|_S = \mathbf{0} \quad \text{if } 1 - 2/p_0 - 1/p > 0.$$

Then there exists a unique solution to (3.1) such that $\mathbf{u} \in \mathbf{W}_{p,p_0}^{1,1/2}(\Omega^T)$ and

$$(3.3) \quad \|\mathbf{u}\|_{\mathbf{W}_{p,p_0}^{1,1/2}(\Omega^T)} \leq c(\|\mathbf{g}\|_{L_{p,p_0}(\Omega^T)} + \|\mathbf{b}\|_{L_{p,p_0}(\Omega^T)} + \|\mathbf{u}_0\|_{\mathbf{B}_{p,p_0}^{1-2/p_0}(\Omega)})$$

with a constant c depending on Ω , S , p , p_0 .

Let us consider the problem

$$(3.4) \quad \begin{aligned} \alpha(x,t)\theta_t - \Delta\theta &= f && \text{in } \Omega^T, \\ \mathbf{n} \cdot \nabla\theta &= 0 && \text{on } S^T, \\ \theta|_{t=0} &= \theta_0 && \text{in } \Omega. \end{aligned}$$

LEMMA 3.5 (see [18, Chapter 4], [24], [32]). Assume that $f \in L_{p,p_0}(\Omega^T)$, $\theta_0 \in B_{p,p_0}^{2-2/p_0}(\Omega)$, $p, p_0 \in (1, \infty)$, $\Omega \in \mathbb{R}^n$, $S \in C^2$. Assume that $0 < \alpha_0 \leq \alpha \leq \alpha_* < \infty$, where α_0 and α_* are constants, $\alpha \in C^{\delta, \delta/2}(\Omega^T)$, $\alpha_t \in L_{3/2\mu, 1/(1-\mu)}(\Omega^T)$, $\mu \in (0, 1)$. Then there exists a solution to problem (3.4) such that $\theta \in W_{p,p_0}^{2,1}(\Omega^T)$ and the following estimate holds

$$(3.5) \quad \|\theta\|_{W_{p,p_0}^{2,1}(\Omega^T)} \leq \varphi(1/\alpha_0, \alpha_*, \|\alpha\|_{C^{\delta, \delta/2}(\Omega^T)}, \|\alpha_t\|_{L_{3/2\mu, 1/(1-\mu)}(\Omega^T)}) \cdot (\|f\|_{L_{p,p_0}(\Omega^T)} + \|\theta_0\|_{B_{p,p_0}^{2-2/p_0}(\Omega)}).$$

REMARK 3.6. The above result is a special case of the more general theorem due to Denk, Hieber, and Prüss [9, Theorem 2.3].

REMARK 3.7. The constant c in (3.2), (3.3) and the function φ in (3.5) do not depend on T . For T small the proof of these facts is evident. For T large it can be deduced by applying the arguments of the proof of Theorem 3.1.1 in [34, Chapter 3].

4. Lower bound for temperature

The existence of the lower positive bound on temperature ensures not only the thermodynamic correctness of the model but is also of basic importance for the proof of global estimates of the solutions. To show such property we use the ideas of the proof of Lemma 4.1 [23].

LEMMA 4.1. Assume that equation (1.2), boundary condition (1.3)₂ and initial condition (1.4)₃ hold, $g \geq 0$, $\theta_0 \geq \underline{\theta} > 0$, where $\underline{\theta}$ is a constant, as well as k , c_v^1 , c_v^2 are positive constants. Assume that the coercivity and boundedness condition (1.11) hold for viscosity tensor \mathbf{A}_1 . Then there exists a positive constant

$$a \equiv \frac{|\mathbf{B}|}{2a_{1*} \min\{c_v^1, c_v^2\}},$$

where $\mathbf{B} = -\mathbf{A}_2\boldsymbol{\alpha}$, and a_{1*} is defined in (1.11), such that

$$(4.1) \quad \theta(t) \geq \underline{\theta} \exp(-at) \equiv \theta_*(t) \quad \text{for } t \in [0, T].$$

PROOF. For $m \in \mathbb{R}_+$ we define the truncation $\theta_m = \max\{\theta, 1/m\}$ and $\Omega_m(t) = \{x \in \Omega : \theta(x, t) > 1/m\}$. Multiplying (1.2) by $-\theta_m^{-\varrho}$ with $\varrho > 4$ (admissible test function) and integrating over $\Omega_m(t)$ gives

$$(4.2) \quad - \left[c_v^1 \int_{\Omega_m(t)} \theta^3 \theta_t \theta_m^{-\varrho} dx + c_v^2 \int_{\Omega_m(t)} \theta \theta_t \theta_m^{-\varrho} dx \right] + k \int_{\Omega_m(t)} \theta_m^{-\varrho} \Delta \theta dx \\ + \int_{\Omega_m(t)} (\mathbf{A}_1 \boldsymbol{\varepsilon}_t) \cdot \boldsymbol{\varepsilon}_t \theta_m^{-\varrho} dx + \int_{\Omega_m(t)} g \theta_m^{-\varrho} dx = \int_{\Omega_m(t)} \theta \theta_m^{-\varrho} (\mathbf{A}_2 \boldsymbol{\alpha}) \cdot \boldsymbol{\varepsilon}_t dx.$$

Now we examine the terms on the left-hand side of (4.2). The first term is equal to

$$(4.3) \quad - \left[c_v^1 \int_{\Omega_m(t)} \theta_m^3 \theta_{m,t} \theta_m^{-\varrho} dx + c_v^2 \int_{\Omega_m(t)} \theta_m \theta_{m,t} \theta_m^{-\varrho} dx \right] \\ = \frac{c_v^1}{\varrho - 4} \int_{\Omega} \partial_t \theta_m^{4-\varrho} dx + \frac{c_v^2}{\varrho - 2} \int_{\Omega} \partial_t \theta_m^{2-\varrho} dx \\ = \frac{c_v^1}{\varrho - 4} \frac{d}{dt} \int_{\Omega} \theta_m^{4-\varrho} dx + \frac{c_v^2}{\varrho - 2} \frac{d}{dt} \int_{\Omega} \theta_m^{2-\varrho} dx,$$

because $\partial_t \theta_m^{4-\varrho} = \partial_t \theta_m^{2-\varrho} = 0$ for $x \in \Omega \setminus \Omega_m(t) = \{x \in \Omega : \theta_m(x, t) = 1/m\}$.

The second term equals

$$(4.4) \quad k \int_{\Omega_m(t)} \theta_m^{-\varrho} \Delta \theta_m dx = k \int_{\Omega} \theta_m^{-\varrho} \Delta \theta_m dx = \frac{4k\varrho}{(\varrho - 1)^2} \int_{\Omega} \left| \nabla \left(\frac{1}{\theta_m^{(\varrho-1)/2}} \right) \right|^2 dx,$$

since $\nabla \theta_m = \nabla \theta$ for $x \in \Omega_m(t)$ and $\nabla \theta_m = \mathbf{0}$ for $x \in \Omega \setminus \Omega_m(t)$. On account of (1.11) the third term is bounded from below by

$$(4.5) \quad a_{1*} \int_{\Omega_m(t)} \frac{|\boldsymbol{\varepsilon}_t|^2}{\theta_m^{\varrho}} dx.$$

The fourth term is nonnegative because $g \geq 0$.

In view of the boundedness of tensors \mathbf{A}_2 and $\boldsymbol{\alpha}$ the integral on the right-hand side of (4.2) is estimated by the Cauchy inequality

$$(4.6) \quad \int_{\Omega_m(t)} \frac{\theta}{\theta_m^{\varrho}} (\mathbf{A}_2 \boldsymbol{\alpha}) \cdot \boldsymbol{\varepsilon}_t dx = \int_{\Omega_m(t)} \frac{\theta_m}{\theta_m^{\varrho/2}} (\mathbf{A}_2 \boldsymbol{\alpha}) \cdot \frac{\boldsymbol{\varepsilon}_t}{\theta_m^{\varrho/2}} dx \\ \leq \frac{\delta}{2} \int_{\Omega_m(t)} \frac{|\boldsymbol{\varepsilon}_t|^2}{\theta_m^{\varrho}} dx + \frac{|\mathbf{B}|}{2\delta} \int_{\Omega_m(t)} \theta_m^{2-\varrho} dx,$$

$\mathbf{B} = -\mathbf{A}_2 \boldsymbol{\alpha}$. Setting $\delta = a_{1*}$ and incorporating (4.3)–(4.7) into (4.2) we arrive at

$$(4.7) \quad \frac{c_v^1}{\varrho - 4} \frac{d}{dt} \int_{\Omega} \frac{dx}{\theta_m^{\varrho-4}} + \frac{c_v^2}{\varrho - 2} \frac{d}{dt} \int_{\Omega} \frac{dx}{\theta_m^{\varrho-2}} + \frac{4k\varrho}{(\varrho - 1)^2} \int_{\Omega} \left| \nabla \left(\frac{1}{\theta_m^{(\varrho-1)/2}} \right) \right|^2 dx \\ + \frac{a_{1*}}{2} \int_{\Omega_m(t)} \frac{|\boldsymbol{\varepsilon}_t|^2}{\theta_m^{\varrho}} dx \leq \frac{|\mathbf{B}|}{2a_{1*}} \int_{\Omega_m(t)} \theta_m^{2-\varrho} dx \leq \frac{|\mathbf{B}|}{2a_{1*}} \int_{\Omega} \frac{dx}{\theta_m^{\varrho-2}},$$

where in the last inequality we taken into account that $\theta_m > 0$ in Ω .

Let us introduce the positive quantities

$$(4.8) \quad X_1(t) = \left(\int_{\Omega} \frac{dx}{\theta_m^{\varrho-4}} \right)^{1/(\varrho-4)}, \quad X_2(t) = \left(\int_{\Omega} \frac{dx}{\theta_m^{\varrho-2}} \right)^{1/(\varrho-2)}.$$

By (4.8) we infer from (4.7) the inequality

$$(4.9) \quad \frac{c_v^1}{\varrho-4} \frac{d}{dt} X_1^{\varrho-4}(t) + \frac{c_v^2}{\varrho-2} \frac{d}{dt} X_2^{\varrho-2}(t) \leq \frac{|\mathbf{B}|}{2a_{1*}} X_2^{\varrho-2}(t).$$

Let us set now

$$(4.10) \quad Y(\varrho, t) = \frac{c_v^1}{\varrho-4} X_1^{\varrho-4}(t) + \frac{c_v^2}{\varrho-2} X_2^{\varrho-2}(t).$$

Then (4.9) yields

$$(4.11) \quad \frac{d}{dt} Y(\varrho, t) \leq a(\varrho-2)Y(\varrho, t),$$

where $a \equiv |\mathbf{B}|/(2a_{1*} \min\{c_v^1, c_v^2\})$. Integrating (4.11) with respect to time from 0 to t leads to

$$(4.12) \quad Y(\varrho, t) \leq \exp[a(\varrho-2)t]Y(\varrho, 0).$$

Hence, using the form of $Y(\varrho, t)$, we get

$$(4.13) \quad X_2(t) \leq \exp(at) \cdot \left[\left(\frac{c_v^1}{c_v^2} \right)^{1/(\varrho-2)} \left(\frac{\varrho-2}{\varrho-4} \right)^{1/(\varrho-2)} \cdot X_1^{(\varrho-4)/(\varrho-2)}(0) + X_2(0) \right],$$

or equivalently,

$$(4.14) \quad \|\theta_m^{-1}(t)\|_{L_{\varrho-2}(\Omega)} \leq \exp(at) \cdot \left[\left(\frac{c_v^1}{c_v^2} \right)^{1/(\varrho-2)} \left(\frac{\varrho-2}{\varrho-4} \right)^{1/(\varrho-2)} \|\theta_m^{-1}(0)\|_{L_{\varrho-4}(\Omega)}^{(\varrho-4)/(\varrho-2)} + \|\theta_m^{-1}(0)\|_{L_{\varrho-2}(\Omega)} \right].$$

Letting $\varrho \rightarrow \infty$, (4.14) implies the bound

$$(4.15) \quad \theta_m(t) \geq \theta_m(0) \exp(-at) \quad \text{for } t \in [0, T].$$

Further, letting $m \rightarrow \infty$ and noting that for sufficiently large m , $\theta_m(0) = \max\{\theta_0, 1/m\} \geq \underline{\theta} > 0$, we conclude the bound (4.1). \square

5. Local existence

To prove the local existence of solutions we use the following Banach successive approximation method:

$$(5.1) \quad \mathbf{u}_{(n+1),tt} - \nabla \cdot (\mathbf{A}_1 \boldsymbol{\varepsilon}(\mathbf{u}_{(n+1),t})) = \nabla \cdot [\mathbf{A}_2 \boldsymbol{\varepsilon}(\mathbf{u}_{(n)}) + \mathbf{B}\theta_{(n)}] + \mathbf{b} \quad \text{in } \Omega^T,$$

$$(5.2) \quad [c_v^1 \theta_{(n)}^3 + c_v^2 \theta_{(n)}] \theta_{(n+1),t} - k \Delta \theta_{(n+1)} = \theta_{(n)} \mathbf{B} \cdot \boldsymbol{\varepsilon}(\mathbf{u}_{(n),t}) + \mathbf{A}_1 \boldsymbol{\varepsilon}(\mathbf{u}_{(n),t}) \cdot \boldsymbol{\varepsilon}(\mathbf{u}_{(n),t}) + g \quad \text{in } \Omega^T,$$

$$(5.3) \quad \mathbf{u}_{(n+1)} = \mathbf{0}, \quad \mathbf{n} \cdot \nabla \theta_{(n+1)} = 0 \quad \text{on } S^T,$$

$$(5.4) \quad \mathbf{u}_{(n+1)}|_{t=0} = \mathbf{u}_0, \quad \mathbf{u}_{(n+1),t} = \mathbf{u}_1, \quad \theta_{(n+1)}|_{t=0} = \theta_0 \quad \text{in } \Omega,$$

where $\mathbf{u}_{(n)}, \theta_{(n)}, n \in \mathbb{N} \cup \{0\}$ are treated as given.

Moreover, the zero approximations $(\mathbf{u}_{(0)}, \theta_{(0)})$ are constructed by an extension of the initial data in such a way that

$$(5.5) \quad \mathbf{u}_{(0)}|_{t=0} = \mathbf{u}_0, \quad \mathbf{u}_{(0),t}|_{t=0} = \mathbf{u}_1, \quad \theta_{(0)}|_{t=0} = \theta_0 \quad \text{in } \Omega,$$

$$(5.6) \quad \mathbf{u}_{(0)} = \mathbf{0}, \quad \mathbf{n} \cdot \nabla \theta_{(0)} = 0 \quad \text{on } S^T.$$

We note that problem (5.1)–(5.6) and that analysed in [24, Section 5] differ only by the presence of the additional term $c_v^1 \theta_{(n)}^3$ in (5.2) which has the same properties as $c_v^2 \theta_{(n)}$. For this reason in order to prove the uniform boundedness of the sequence $\{\mathbf{u}_{(n)}, \theta_{(n)}\}$ we can use exactly the same arguments as in Lemma 5.1 [24].

We have

LEMMA 5.1 (Boundedness of the approximation). *Let*

$$X_0(t) = \|\mathbf{u}_{(0),t}\|_{\mathbf{W}_{p,p_0}^{2,1}(\Omega^t)} + \|\theta_{(0)}\|_{W_{q,q_0}^{2,1}(\Omega^t)},$$

where $\mathbf{u}_{(0)}, \theta_{(0)}$ are introduced by (5.5), be finite. Let $\theta_0 \geq \underline{\theta} > 0$. Further, let

$$D(t) = \|\mathbf{u}_0\|_{\mathbf{W}_p^2(\Omega)} + \|\mathbf{u}_1\|_{\mathbf{B}_{p,p_0}^{2-2/p_0}(\Omega)} + \|\theta_0\|_{B_{q,q_0}^{2-2/q_0}(\Omega)} + \|\mathbf{b}\|_{\mathbf{L}_{p,p_0}(\Omega^t)} + \|g\|_{L_{q,q_0}(\Omega^t)}$$

be finite, and

$$3/p + 2/p_0 < 1, \quad 3/q + 2/q_0 < 1 + 3/p + 2/p_0.$$

Assume that there exists a constant A and time t sufficiently small such that

$$X_0(t) \leq A, \quad \varphi(t^\alpha A, D(t)) \leq A,$$

where $\alpha > 0$ and the nonlinear function φ appears in the proof of Lemma 5.1 [24, (5.22)], and $ct^{\delta/2} A \leq \underline{\theta}$, $\delta > 0$. Then

$$(5.7) \quad X_n(t) = \|\mathbf{u}_{(n),t}\|_{\mathbf{W}_{p,p_0}^{2,1}(\Omega^t)} + \|\theta_{(n)}\|_{W_{q,q_0}^{2,1}(\Omega^t)} \leq A \quad \text{for any } n \in \mathbb{N}.$$

To show the convergence of the sequences $\{\mathbf{u}_{(n)}, \theta_{(n)}\}$ we introduce the differences

$$(5.8) \quad \mathbf{U}_n(t) = \mathbf{u}_{(n)}(t) - \mathbf{u}_{(n-1)}(t), \quad \vartheta_n(t) = \theta_{(n)}(t) - \theta_{(n-1)}(t),$$

$n \in \mathbb{N}$, which are solutions to the problem

$$(5.9) \quad \begin{aligned} \mathbf{U}_{n+1,tt} - \nabla \cdot (\mathbf{A}_1 \boldsymbol{\varepsilon}(\mathbf{U}_{n+1,t})) &= \nabla \cdot [\mathbf{A}_2 \boldsymbol{\varepsilon}(\mathbf{U}_n) + \mathbf{B} \vartheta_n] && \text{in } \Omega^T, \\ \mathbf{U}_{n+1} &= \mathbf{0} && \text{on } S^T, \\ \mathbf{U}_{n+1}|_{t=0} &= \mathbf{0}, \quad \mathbf{U}_{n+1,t}|_{t=0} = \mathbf{0} && \text{in } \Omega, \end{aligned}$$

and

$$\begin{aligned}
& (c_v^1 \theta_{(n)}^3 + c_v^2 \theta_{(n)}) \vartheta_{n+1,t} - k \Delta \vartheta_{n+1} = -c_v^1 (\theta_{(n)}^3 - \theta_{(n-1)}^3) \theta_{(n),t} \\
& \quad - c_v^2 \vartheta_n \theta_{(n),t} + \vartheta_n \mathbf{B} \cdot \boldsymbol{\varepsilon}(\mathbf{u}_{(n),t}) + \theta_{(n-1)} \mathbf{B} \cdot \boldsymbol{\varepsilon}(\mathbf{U}_{(n),t}) \\
(5.10) \quad & + \mathbf{A}_1 \boldsymbol{\varepsilon}(\mathbf{U}_{n,t}) \cdot \boldsymbol{\varepsilon}(\mathbf{u}_{(n),t}) + \mathbf{A}_1 \boldsymbol{\varepsilon}(\mathbf{u}_{(n-1),t}) \cdot \boldsymbol{\varepsilon}(\mathbf{U}_{n,t}) \quad \text{in } \Omega^T, \\
& \mathbf{n} \cdot \nabla \vartheta_{n+1} = 0 \quad \text{on } S^T, \\
& \vartheta_{n+1}|_{t=0} = 0 \quad \text{in } \Omega.
\end{aligned}$$

Let

$$(5.11) \quad Y_n(t) = \|\mathbf{U}_{n,t}\|_{\mathbf{W}_{p',p'_0}^{2,1}(\Omega^t)} + \|\vartheta_n\|_{W_{q',q'_0}^{2,1}(\Omega^t)}.$$

As for the uniform boundedness, we can repeat the arguments of the corresponding proof of the convergence of approximation of [24, Lemma 5.3]. This lemma required (see [24, (5.30)]) several technical restrictions on the indices $p, p_0, q, q_0, p', p'_0, q', q'_0$ of the involved Sobolev spaces with a mixed norm $\mathbf{W}_{p,p_0}^{2,1}(\Omega^t)$, $W_{q,q_0}^{2,1}(\Omega^t)$, $\mathbf{W}_{p',p'_0}^{2,1}(\Omega^t)$, $W_{q',q'_0}^{2,1}(\Omega^t)$. As noted in [24, Corollary 5.5] these restrictions and the restrictions of Lemma 5.1 can be satisfied for the following special choice:

$$(5.12) \quad p = p_0 = 5^+, \quad q = q_0 = 5^+, \quad p' = p'_0 = 5, \quad q' = q'_0 = 5,$$

where 5^+ is any number larger than 5 possibly close to 5. Then we have

LEMMA 5.2 (Convergence of the approximation). *Let the assumptions of Lemma 5.1 be satisfied and (5.12) holds. Then there exists a positive constant $d = d(A)$ and $a > 0$ such that*

$$(5.13) \quad Y_{n+1}(t) \leq dt^a Y_n(t).$$

From Lemmas 5.1 and 5.2 it follows that

THEOREM 5.3 (Local existence). *Let the assumptions of Lemmas 5.1 and (5.2) hold. Then there exists a local solution to problem (1.1)–(1.4) such that $\mathbf{u}_t \in \mathbf{W}_{5^+}^{2,1}(\Omega^{\tilde{T}})$, $\theta \in W_{5^+}^{2,1}(\Omega^{\tilde{T}})$, where \tilde{T} is sufficiently small.*

6. Global estimates

In this section we prove some global estimates on an arbitrary finite time interval $(0, T)$ for a regular local solution. All estimates use the regularity of local solutions. By Lemma 4.1 we know that there exists the lower positive bound on the temperature

$$(6.1) \quad \theta(t) \geq \theta_* := \theta_*(T) > 0 \quad \text{for } t \leq T.$$

Throughout we assume that assumptions (A1)–(A3) of Theorem 1.1 hold.

LEMMA 6.1 (Energy estimates). *Assume that*

$$\begin{aligned} \mathbf{u}_0 &\in \mathbf{H}^1(\Omega), \quad \mathbf{u}_1 \in \mathbf{L}_2(\Omega), \quad \theta_0 \in L_4(\Omega), \\ \mathbf{b} &\in \mathbf{L}_2(\Omega^t), \quad g \in L_1(\Omega^t), \quad g \geq 0, \quad t \leq T. \end{aligned}$$

Then solutions to problem (1.1)–(1.4) satisfy the estimate

$$(6.2) \quad \begin{aligned} \|\mathbf{u}(t)\|_{\mathbf{H}^1(\Omega)}^2 + \|\mathbf{u}_t(t)\|_{\mathbf{L}_2(\Omega)}^2 + \|\theta(t)\|_{L_4(\Omega)}^4 &\leq c(t)(\|\mathbf{u}_0\|_{\mathbf{H}^1(\Omega)}^2 \\ &+ \|\mathbf{u}_1\|_{\mathbf{L}_2(\Omega)}^2 + \|\theta_0\|_{L_4(\Omega)}^4 + \|\mathbf{b}\|_{\mathbf{L}_2(\Omega^t)}^2 + \|g\|_{L_1(\Omega^t)}) \equiv c_1(t), \end{aligned}$$

where $c(t)$ is an increasing positive function.

PROOF. Multiplying (1.1) by \mathbf{u}_t and integrating over Ω yields

$$(6.3) \quad \begin{aligned} \frac{1}{2} \frac{d}{dt} \|\mathbf{u}_t\|_{\mathbf{L}_2(\Omega)}^2 + \int_{\Omega} (\mathbf{A}_1 \boldsymbol{\varepsilon}_t) \cdot \boldsymbol{\varepsilon}_t \, dx \\ - \int_{\Omega} [\nabla \cdot (\mathbf{A}_2 \boldsymbol{\varepsilon})] \cdot \mathbf{u}_t \, dx + \int_{\Omega} \theta \mathbf{B} \cdot \boldsymbol{\varepsilon}_t \, dx = \int_{\Omega} \mathbf{b} \cdot \mathbf{u}_t \, dx, \end{aligned}$$

where we recall (see (1.8)) that $\mathbf{B} := -\mathbf{A}_2 \boldsymbol{\alpha}$. Integrating (1.2) over Ω implies

$$(6.4) \quad \frac{c_v^1}{4} \frac{d}{dt} \int_{\Omega} \theta^4 \, dx + \frac{c_v^2}{2} \frac{d}{dt} \int_{\Omega} \theta^2 \, dx = \int_{\Omega} \theta \mathbf{B} \cdot \boldsymbol{\varepsilon}_t \, dx + \int_{\Omega} (\mathbf{A}_1 \boldsymbol{\varepsilon}_t) \cdot \boldsymbol{\varepsilon}_t \, dx + \int_{\Omega} g \, dx.$$

From the properties of the operator \mathbf{A}_2 (see (1.5)) we have

$$(6.5) \quad \begin{aligned} - \int_{\Omega} [\nabla \cdot (\mathbf{A}_2 \boldsymbol{\varepsilon})] \cdot \mathbf{u}_t \, dx &= - \int_{\Omega} [\mu_2 \Delta \mathbf{u} \cdot \mathbf{u}_t + (\lambda_2 + \mu_2) \nabla(\nabla \cdot \mathbf{u}) \cdot \mathbf{u}_t] \, dx \\ &= \frac{1}{2} \frac{d}{dt} [\mu_2 \|\nabla \mathbf{u}\|_{\mathbf{L}_2(\Omega)}^2 + (\lambda_2 + \mu_2) \|\nabla \cdot \mathbf{u}\|_{L_2(\Omega)}^2], \end{aligned}$$

where the boundary condition (1.3)₁ was used. Applying (6.5) in (6.3) gives

$$(6.6) \quad \begin{aligned} \frac{1}{2} \frac{d}{dt} [\|\mathbf{u}_t\|_{\mathbf{L}_2(\Omega)}^2 + \mu_2 \|\nabla \mathbf{u}\|_{\mathbf{L}_2(\Omega)}^2 + (\lambda_2 + \mu_2) \|\nabla \cdot \mathbf{u}\|_{L_2(\Omega)}^2] \\ + \int_{\Omega} (\mathbf{A}_1 \boldsymbol{\varepsilon}_t) \cdot \boldsymbol{\varepsilon}_t \, dx + \int_{\Omega} \theta \mathbf{B} \cdot \boldsymbol{\varepsilon}_t \, dx = \int_{\Omega} \mathbf{b} \cdot \mathbf{u}_t \, dx. \end{aligned}$$

By adding (6.4) and (6.6) we have

$$(6.7) \quad \begin{aligned} \frac{d}{dt} \left[\frac{c_v^1}{4} \|\theta\|_{L_4(\Omega)}^4 + \frac{c_v^2}{2} \|\theta\|_{L_2(\Omega)}^2 + \frac{1}{2} \|\mathbf{u}_t\|_{\mathbf{L}_2(\Omega)}^2 + \mu_2 \|\nabla \mathbf{u}\|_{\mathbf{L}_2(\Omega)}^2 \right. \\ \left. + (\lambda_2 + \mu_2) \|\nabla \cdot \mathbf{u}\|_{L_2(\Omega)}^2 \right] = \int_{\Omega} \mathbf{b} \cdot \mathbf{u}_t \, dx + \int_{\Omega} g \, dx. \end{aligned}$$

Integrating (6.7) with respect to time, using the lower bound (1.17) for the sum of the last two terms in the squared parenthesis, and eventually applying the Gronwall inequality we get (6.2) which concludes the proof. \square

To derive “stronger” estimates for \mathbf{u} and θ we apply the regularity theory of parabolic systems in Sobolev spaces with a mixed norm, stated in Lemmas 3.4 and 3.5. Let us first consider the viscoelasticity system (1.1), (1.3)₁, (1.4)_{1,2}, expressed in the form

$$(6.8) \quad \begin{aligned} \mathbf{u}_{tt} - \mathbf{Q}_1 \mathbf{u}_t &= \nabla \cdot (\mathbf{A}_2 \boldsymbol{\varepsilon} + \theta \mathbf{B}) + \mathbf{b} && \text{in } \Omega^T, \\ \mathbf{u}_t &= \mathbf{0} && \text{on } S^T, \\ \mathbf{u}_t|_{t=0} &= \mathbf{u}_1, \quad \mathbf{u}|_{t=0} = \mathbf{u}_0 && \text{in } \Omega, \end{aligned}$$

where \mathbf{B} is defined by (1.8).

We have

LEMMA 6.2. *Assume that*

$$\begin{aligned} \theta &\in L_{p,r}(\Omega^t), \quad \mathbf{b} \in \mathbf{L}_{p,r}(\Omega^t), \\ \mathbf{u}_0 &\in \mathbf{W}_p^1(\Omega), \quad \mathbf{u}_1 \in \mathbf{B}_{p,r}^{1-2/r}(\Omega), \quad p, r \in (1, \infty), \quad t \leq T. \end{aligned}$$

Then for solutions to problem (1.1)–(1.4) the following inequality holds

$$(6.9) \quad \begin{aligned} \|\boldsymbol{\varepsilon}_{t'}\|_{\mathbf{L}_{p,r}(\Omega^t)} &\leq c(t) (\|\theta\|_{L_{p,r}(\Omega^t)} + \|\mathbf{b}\|_{\mathbf{L}_{p,r}(\Omega^t)} + \|\mathbf{u}_0\|_{\mathbf{W}_p^1(\Omega)} + \|\mathbf{u}_1\|_{\mathbf{B}_{p,r}^{1-2/r}(\Omega)}) \\ &\equiv c_2(t, p, r) + c(t) \|\theta\|_{L_{p,r}(\Omega^t)}. \end{aligned}$$

PROOF. Applying Lemma 3.4 (b) to problem (6.8), using the boundedness of tensors \mathbf{A}_2, \mathbf{B} we have

$$\begin{aligned} \|\boldsymbol{\varepsilon}_{t'}\|_{\mathbf{L}_{p,r}(\Omega^t)} &\leq c \|\mathbf{u}_{t'}\|_{\mathbf{W}_{p,r}^{1,1/2}(\Omega^t)} \\ &\leq c (\|\boldsymbol{\varepsilon}\|_{\mathbf{L}_{p,r}(\Omega^t)} + \|\theta\|_{L_{p,r}(\Omega^t)} + \|\mathbf{b}\|_{\mathbf{L}_{p,r}(\Omega^t)} + \|\mathbf{u}_1\|_{\mathbf{B}_{p,r}^{1-2/r}(\Omega)}). \end{aligned}$$

Using the Gronwall lemma to the latter inequality we conclude (6.9). \square

Now, using (6.2) in (6.9) implies the estimate

$$(6.10) \quad \|\boldsymbol{\varepsilon}_{t'}\|_{\mathbf{L}_{4,r}(\Omega^t)} \leq c(t) c_1^{1/4}(t) + c_2(t, 4, r) \equiv c_3(t, r), \quad r \in (1, \infty).$$

We have also the following

LEMMA 6.3. *Let $\nabla\theta \in \mathbf{L}_{p,r}(\Omega^t)$, $\mathbf{b} \in \mathbf{L}_{p,r}(\Omega^t)$, $\mathbf{u}_1 \in \mathbf{B}_{p,r}^{2-2/r}(\Omega)$, $\mathbf{u}_0 \in \mathbf{W}_p^2(\Omega)$, $p, r \in (1, \infty)$, $t \leq T$. Then for solutions to problem (1.1)–(1.4) the following inequality holds*

$$(6.11) \quad \begin{aligned} \|\boldsymbol{\varepsilon}_{t'}\|_{\mathbf{W}_{p,r}^{1,1/2}(\Omega^t)} &\leq c \|\mathbf{u}_{t'}\|_{\mathbf{W}_{p,r}^{2,1}(\Omega^t)} \\ &\leq c(t) (\|\nabla\theta\|_{\mathbf{L}_{p,r}(\Omega^t)} + \|\mathbf{b}\|_{\mathbf{L}_{p,r}(\Omega^t)} + \|\mathbf{u}_0\|_{\mathbf{W}_p^2(\Omega)} + \|\mathbf{u}_1\|_{\mathbf{B}_{p,r}^{2-2/r}(\Omega)}) \\ &\equiv c(t) \|\nabla\theta\|_{\mathbf{L}_{p,r}(\Omega^t)} + c_4(t, p, r). \end{aligned}$$

PROOF. Applying Lemma 3.4 (a) to problem (6.8) and the boundedness of \mathbf{A}_2, \mathbf{B} yields

$$\|\boldsymbol{\varepsilon}_{t'}\|_{\mathbf{W}_{p,r}^{1,1/2}(\Omega^t)} \leq c(\|\nabla \boldsymbol{\varepsilon}\|_{\mathbf{L}_{p,r}(\Omega^t)} + \|\nabla \theta\|_{\mathbf{L}_{p,r}(\Omega^t)} + \|\mathbf{b}\|_{\mathbf{L}_{p,r}(\Omega^t)} + \|\mathbf{u}_1\|_{\mathbf{B}_{p,r}^{2-2/r}(\Omega)}).$$

Hence, by the Gronwall lemma, (6.11) follows. \square

On account of (6.10) we obtain “better” estimates on θ .

LEMMA 6.4. *Let (6.10) for $r = 2$ holds true and the assumptions of Lemma 6.1 be satisfied. Let $\theta_0 \in L_5(\Omega)$ and $g \in L_{5/4,1}(\Omega^t)$. Then the following inequality holds*

$$(6.12) \quad \|\theta(t)\|_{L_5(\Omega)}^5 + \|\theta(t)\|_{L_3(\Omega)}^3 + \|\nabla \theta\|_{L_2(\Omega^t)}^2 \leq [c_1^{1/2}(t)c_3(t, 2) + c_1^{1/4}(t)c_3^2(t, 2) + \|g\|_{L_{5/4,1}(\Omega^t)}^{5/4} + \|\theta_0\|_{L_5(\Omega)}^5] \equiv c_5(t).$$

PROOF. Multiplying (1.2) by θ , integrating with respect to time and using (1.3)₂, (1.4)₃ gives

$$(6.13) \quad \int_{\Omega} \theta^5 dx + \int_{\Omega} \theta^3 dx + \int_{\Omega^t} |\nabla \theta|^2 dx dt' \leq c \int_{\Omega^t} \theta^2 |\boldsymbol{\varepsilon}_{t'}| dx dt' + c \int_{\Omega^t} \theta |\boldsymbol{\varepsilon}_{t'}|^2 dx dt' + c \int_{\Omega^t} g \theta dx dt' + c \int_{\Omega} \theta_0^5 dx + c \int_{\Omega} \theta_0^3 dx.$$

The first term on the right-hand side of (6.13) is bounded by

$$\begin{aligned} \int_0^t dt' \int_{\Omega} \theta^2 |\boldsymbol{\varepsilon}_{t'}| dx &\leq \int_0^t \|\theta\|_{L_4(\Omega)}^2 \|\boldsymbol{\varepsilon}_{t'}\|_{L_2(\Omega)} dt' \\ &\leq c_1^{1/2}(t) \int_0^t \|\boldsymbol{\varepsilon}_{t'}\|_{L_2(\Omega)} dt' \leq c_1^{1/2}(t) t^{1/2} c_3(t, 2), \end{aligned}$$

and the second one by

$$\int_0^t dt' \int_{\Omega} \theta |\boldsymbol{\varepsilon}_{t'}|^2 dx \leq \int_0^t \|\theta\|_{L_4(\Omega)} \|\boldsymbol{\varepsilon}_{t'}\|_{L_{8/3}(\Omega)}^2 dt' \leq c_1^{1/4}(t) c_3^2(t, 2).$$

The third term is bounded by

$$\begin{aligned} \int_0^t \|\theta\|_{L_5(\Omega)} \|g\|_{L_{5/4}(\Omega)} dt' &\leq \sup_t \|\theta\|_{L_5(\Omega)} \|g\|_{L_{5/4,1}(\Omega^t)} \\ &\leq \delta \sup_t \|\theta\|_{L_5(\Omega)}^5 + \frac{c}{\delta} \|g\|_{L_{5/4,1}(\Omega^t)}^{5/4}, \end{aligned}$$

for $\delta > 0$. Applying the above inequalities in (6.13) we conclude (6.12). This completes the proof. \square

Let us note that from (6.9) and (6.12) it follows that

$$(6.14) \quad \|\boldsymbol{\varepsilon}_{t'}\|_{\mathbf{L}_{5,r}(\Omega^t)} \leq c_2(t, 5, r) + c(t) c_5^{1/5}(t) \equiv c_6(t, r), \quad r \in (1, \infty).$$

We continue with further estimates for θ .

LEMMA 6.5. *Let the assumptions of Lemma 6.4 be satisfied, and the estimate (6.14) holds. Moreover, assume that $\theta_0 \in L_{15}(\Omega)$, $g \in L_{36/25,12}(\Omega^t)$, $t \leq T$. Then*

$$(6.15) \quad \begin{aligned} & \|\theta(t)\|_{L_{15}(\Omega)}^{15} + \int_0^t \|\theta\|_{L_{36}(\Omega)}^{12} dt' + \int_{\Omega^t} |\nabla \theta^6|^2 dt' \\ & \leq c(c_6^5(t, 12) + c_6^{24}(t, 12) + c(12, t) \\ & \quad + \|g\|_{L_{36/25,12}(\Omega^t)}^{12} + \|\theta_0\|_{L_{15}(\Omega)}^{15}) \equiv c_7(t). \end{aligned}$$

PROOF. Multiplying (1.2) by $\theta^{\alpha-1}$, where $\alpha > 1$, integrating the result over Ω , taking into account the boundedness of tensors \mathbf{B} , \mathbf{A}_1 and the boundary condition (1.3)₂, we obtain

$$(6.16) \quad \begin{aligned} & \frac{c_v^1}{\alpha+3} \frac{d}{dt} \int_{\Omega} \theta^{\alpha+3} dx + \frac{c_v^2}{\alpha+1} \frac{d}{dt} \int_{\Omega} \theta^{\alpha+1} dx + \frac{4k(\alpha-1)}{\alpha^2} \int_{\Omega} |\nabla \theta^{\alpha/2}|^2 dx \\ & \leq c \int_{\Omega} \theta^{\alpha} |\varepsilon_t| dx + c \int_{\Omega} \theta^{\alpha-1} |\varepsilon_t|^2 dx + \int_{\Omega} g \theta^{\alpha-1} dx. \end{aligned}$$

Integration of (6.16) with respect to time gives

$$(6.17) \quad \begin{aligned} & \frac{1}{\alpha+3} \int_{\Omega} \theta^{\alpha+3} dx + \frac{1}{\alpha+1} \int_{\Omega} \theta^{\alpha+1} dx + \frac{4(\alpha-1)}{\alpha^2} \int_{\Omega^t} |\nabla \theta^{\alpha/2}|^2 dx dt' \\ & \leq c \int_{\Omega^t} \theta^{\alpha} |\varepsilon_{t'}| dx dt' + c \int_{\Omega^t} \theta^{\alpha-1} |\varepsilon_{t'}|^2 dx dt' + \int_{\Omega^t} g \theta^{\alpha-1} dx dt' \\ & \quad + \frac{c}{\alpha+3} \|\theta_0\|_{L_{\alpha+3}(\Omega)}^{\alpha+3} + \frac{c}{\alpha+1} \|\theta_0\|_{L_{\alpha+1}(\Omega)}^{\alpha+1}. \end{aligned}$$

Prior to deal with the terms on the right-hand side of (6.17) we first estimate from below the third term on the left-hand side by applying a Sobolev imbedding. Setting $u = \theta^{\alpha/2}$ this term takes the form

$$\frac{4(\alpha-1)}{\alpha^2} \int_0^t \int_{\Omega} |\nabla u|^2 dx dt'.$$

Now we add to the both sides of (6.17) the term

$$\frac{2(\alpha-1)}{\alpha^2} \int_0^t \int_{\Omega} u^2 dx dt'.$$

Then we have

$$(6.18) \quad \begin{aligned} & \frac{2(\alpha-1)}{\alpha^2} \int_0^t \int_{\Omega} (|\nabla u|^2 + u^2) dx dt' \geq \frac{2c(\alpha-1)}{\alpha^2} \int_0^t \|u\|_{L_6(\Omega)}^2 dt' \\ & = \frac{2c(\alpha-1)}{\alpha^2} \int_0^t \|\theta\|_{L_{3\alpha}(\Omega)}^{\alpha} dt'. \end{aligned}$$

The additional term on the right-hand side of (6.17) equals

$$\frac{2(\alpha-1)}{\alpha^2} \int_0^t \int_{\Omega} |\theta^{\alpha/2}|^2 dx dt' = \frac{2(\alpha-1)}{\alpha^2} \int_0^t \int_{\Omega} \theta^{\alpha} dx dt',$$

so, by applying the Hölder and the Young inequalities, it is bounded by

$$\delta_1 \sup_t \int_{\Omega} \theta^{\alpha+3} dx + c(1/\delta_1, \alpha, t), \quad \delta_1 > 0.$$

Consequently, employing (6.18) in (6.17) gives

$$(6.19) \quad \begin{aligned} & \frac{1}{\alpha+3} \|\theta\|_{L_{\alpha+3}(\Omega)}^{\alpha+3} + \frac{1}{\alpha+1} \|\theta\|_{L_{\alpha+1}(\Omega)}^{\alpha+1} \\ & + \frac{2c(\alpha-1)}{\alpha^2} \int_0^t \|\theta\|_{L_{3\alpha}(\Omega)}^{\alpha} dt' + \frac{2(\alpha-1)}{\alpha^2} \int_{\Omega^t} |\nabla \theta^{\alpha/2}|^2 dx dt' \\ & \leq c \int_0^t \|\theta\|_{L_{\alpha\lambda_1}(\Omega)}^{\alpha} \|\varepsilon_{t'}\|_{L_{\lambda_2}(\Omega)} dt' + c \int_0^t \|\theta\|_{L_{(\alpha-1)\mu_1}(\Omega)}^{\alpha-1} \|\varepsilon_{t'}\|_{L_{2\mu_2}(\Omega)}^2 dt' \\ & + c \int_0^t \|g\|_{L_{\nu_1}(\Omega)} \|\theta\|_{L_{(\alpha-1)\nu_2}(\Omega)}^{\alpha-1} dt' \\ & + \frac{c}{\alpha+3} \|\theta_0\|_{L_{\alpha+3}(\Omega)}^{\alpha+3} + \frac{c}{\alpha+1} \|\theta_0\|_{L_{\alpha+1}(\Omega)}^{\alpha+1} + c(\alpha, t), \end{aligned}$$

where $1/\lambda_1 + 1/\lambda_2 = 1$, $1/\mu_1 + 1/\mu_2 = 1$, $1/\nu_1 + 1/\nu_2 = 1$.

On account of (6.14) we can assume that $\lambda_2 = 5$, so $\lambda_1 = 5/4$. Setting $5\alpha/4 = \alpha + 3$, we get $\alpha = 12$. Then the first term on the right-hand side of (6.19) is bounded by

$$\delta_2 \int_0^t \|\theta\|_{L_{\alpha+3}(\Omega)}^{\alpha+3} dt' + \frac{c}{\delta_2} c_6^{(\alpha+3)/3}(t, 12), \quad \delta_2 > 0.$$

In the second term on the right-hand side of (6.19) we assume that $\mu_2 = 5/2$, $\mu_1 = 5/3$ and $(\alpha-1)\mu_1 \leq 3\alpha$, so $5(\alpha-1)/3 \leq 3\alpha$. We note that the latter inequality is satisfied for any $\alpha > 1$. Hence, the second term is bounded by

$$\delta_3 \int_0^t \|\theta\|_{L_{3\alpha}(\Omega)}^{\alpha} dt' + \frac{c}{\delta_3} \int_0^t \|\varepsilon_{t'}\|_{L_5(\Omega)}^{2\alpha} dt' \leq \delta_3 \int_0^t \|\theta\|_{L_{3\alpha}(\Omega)}^{\alpha} dt' + \frac{c}{\delta_3} c_6^{2\alpha}(t, 12),$$

where (6.14) is used.

In the third term on the right-hand side of (6.19) we assume that $\nu_2 = 3\alpha/(\alpha-1)$ so $\nu_1 = 3\alpha/(2\alpha+1)$. Then this term is bounded by

$$\delta_4 \int_0^t \|\theta\|_{L_{3\alpha}(\Omega)}^{\alpha} dt' + \frac{c}{\delta_4} \int_0^t \|g\|_{L_{3\alpha/(2\alpha+1)}(\Omega)}^{\alpha} dt', \quad \delta_4 > 0.$$

From the above considerations it follows that we can take $\alpha = 12$. Employing the obtained estimates in (6.19), choosing δ_k , $k = 1, \dots, 4$, appropriately, in particular assuming that $\delta_2, \delta_3, \delta_4$ are sufficiently small, we arrive at (6.15). This concludes the proof. \square

Let us note that using (6.15) in (6.9) yields

$$(6.20) \quad \|\varepsilon_{t'}\|_{L_{15,r}(\Omega^t)} \leq c_2(t, 15, r) + c(t)c_7^{1/15}(t) \equiv c_8(t, r), \quad r \in (1, \infty).$$

We proceed now to prove that $\theta \in L_\infty(0, t; L_\alpha(\Omega))$ for any finite α . For this purpose we repeat and improve appropriately the arguments of the proof of Lemma 6.5.

LEMMA 6.6. *Let (6.15) and (6.20) with $r = \alpha \in (1, \infty)$ hold. Moreover, assume that*

$$\theta_0 \in L_{\alpha+3}(\Omega) \quad \text{and} \quad g \in L_{3\alpha/(2\alpha+1), \alpha}(\Omega^t), \quad t \leq T.$$

Then, for $\alpha < \infty$,

$$(6.21) \quad \begin{aligned} & \frac{1}{\alpha+3} \|\theta(t)\|_{L_{\alpha+3}(\Omega)}^{\alpha+3} + \frac{1}{\alpha+1} \|\theta(t)\|_{L_{\alpha+1}(\Omega)}^{\alpha+1} \\ & \quad + \frac{4k(\alpha-1)}{\alpha^2} \int_{\Omega^t} |\nabla \theta^{\alpha/2}|^2 dx dt' \\ & \leq c(c_7(t), c_8(t, \alpha)) + c \|g\|_{L_{3\alpha/(2\alpha+1), \alpha}(\Omega^t)}^\alpha \\ & \quad + \frac{c}{\alpha+3} \|\theta_0\|_{L_{\alpha+3}(\Omega)}^{\alpha+3} \equiv c_9(t, \alpha). \end{aligned}$$

PROOF. Let us turn to the inequality (6.17) from the proof of Lemma 6.5. We proceed now as follows. The first term on the right-hand side of (6.17) we express in the form

$$\int_0^t \int_{\Omega} \theta^{\alpha-1} \theta |\varepsilon_{t'}| dx dt'.$$

On account of (6.15) and (6.20) it is estimated by

$$\begin{aligned} & \int_0^t \|\theta\|_{L_{15(\alpha-1)/13}(\Omega)}^{\alpha-1} \|\theta\|_{L_{15}(\Omega)} \|\varepsilon_{t'}\|_{L_{15}(\Omega)} dt' \\ & \leq c_7^{1/15}(t) \int_0^t \|\theta\|_{L_{15(\alpha-1)/13}(\Omega)}^{\alpha-1} \|\varepsilon_{t'}\|_{L_{15}(\Omega)} dt' \\ & \leq \delta_1 \int_0^t \|\theta\|_{L_{3\alpha}(\Omega)}^\alpha dt' + c(1/\delta_1, c_7^{1/15}(t)) \int_0^t \|\varepsilon_{t'}\|_{L_{15}(\Omega)}^\alpha dt' \\ & \leq \delta_1 \int_0^t \|\theta\|_{L_{3\alpha}(\Omega)}^\alpha dt' + c(1/\delta_1, c_7^{1/15}(t), c_8^\alpha(t, \alpha)), \end{aligned}$$

for $\delta_1 > 0$, where we used the relation $15(\alpha-1)/13 \leq 3\alpha$, holding true for any finite α . Similarly, the second term on the right-hand side of (6.17) is bounded by

$$(6.22) \quad \begin{aligned} & \int_0^t \|\theta\|_{L_{15(\alpha-1)/13}(\Omega)}^{\alpha-1} \|\varepsilon_{t'}\|_{L_{15}(\Omega)}^2 dt' \\ & \leq \delta_2 \int_0^t \|\theta\|_{L_{3\alpha}(\Omega)}^\alpha dt' + c(1/\delta_2) \int_0^t \|\varepsilon_{t'}\|_{L_{15}(\Omega)}^{2\alpha} dt' \\ & \leq \delta_2 \int_0^t \|\theta\|_{L_{3\alpha}(\Omega)}^\alpha dt' + c(1/\delta_2) c_8^{2\alpha}(t, \alpha). \end{aligned}$$

for $\delta_2 > 0$. Finally, the third term on the right-hand side of (6.17) is bounded by

$$\int_0^t \|\theta\|_{L_{3\alpha}(\Omega)}^{\alpha-1} \|g\|_{L_{3\alpha/(2\alpha+1)}(\Omega)} dt' \leq \delta_3 \int_0^t \|\theta\|_{L_{3\alpha}(\Omega)}^\alpha dt' + \frac{1}{\delta_3} \int_0^t \|g\|_{L_{3\alpha/(2\alpha+1)}(\Omega)}^\alpha dt',$$

for $\delta_3 > 0$. Employing the above estimates in (6.17), and setting δ_k sufficiently small, we arrive at (6.21). \square

Let us note that from (6.21) it follows in particular that

$$(6.23) \quad \|\theta\|_{L_\infty(0,t;L_\alpha(\Omega))} \leq [(\alpha+3)c_9(t,\alpha)]^{1/(\alpha+3)} \equiv c_{10}(t,\alpha) \quad \text{for any } \alpha < \infty.$$

We obtain now an estimate on θ_t .

LEMMA 6.7. *Let the assumptions of the previous lemmas be satisfied, in particular the lower bound (6.1) holds, $\theta_0 \in H^1(\Omega)$ and $g \in L_2(\Omega^t)$, $g \geq 0$, $t \leq T$. Then*

$$(6.24) \quad \|\theta_t\|_{L_2(\Omega^t)}^2 + \|\theta\|_{L_\infty(0,t;H^1(\Omega))}^2 \leq c(1/\theta_*) (c_{10}^2(t,4)c_8^2(t,4) + c_8^4(t,4)) \\ + c(1/\theta_*) \|g\|_{L_2(\Omega^t)}^2 + c\|\theta_0\|_{H^1(\Omega)}^2 \equiv c_{11}^2(t).$$

PROOF. Multiplying (1.2) by θ_t , integrating over Ω^t , $t \leq T$, using boundary condition (1.3)₂, the boundedness of tensors \mathbf{A}_1 , $\mathbf{B} = -\mathbf{A}_2\boldsymbol{\alpha}$, and the global lower bound (6.1) for θ , we get

$$(6.25) \quad \|\theta_t\|_{L_2(\Omega^t)}^2 + \frac{k}{2} \|\nabla\theta(t)\|_{L_2(\Omega)}^2 \leq \frac{c}{\theta_*^3} \left[\int_{\Omega^t} \theta |\boldsymbol{\varepsilon}_t| |\theta_t| dx dt' \right. \\ \left. + \int_{\Omega^t} |\boldsymbol{\varepsilon}_t|^2 |\theta_t| dx dt' + \int_{\Omega^t} |g| |\theta_t| dx dt' \right] + \frac{k}{2} \|\theta_0\|_{H^1(\Omega)}^2.$$

Therefore, by the Young inequality, we have

$$(6.26) \quad \|\theta_t\|_{L_2(\Omega^t)}^2 + \frac{k}{2} \|\nabla\theta(t)\|_{L_2(\Omega)}^2 \leq \frac{c}{\theta_*^6} \left[\int_{\Omega^t} \theta^2 |\boldsymbol{\varepsilon}_t|^2 dx dt' \right. \\ \left. + \int_{\Omega^t} |\boldsymbol{\varepsilon}_t|^4 dx dt' + \int_{\Omega^t} |g|^2 dx dt' \right] + \frac{k}{2} \|\theta_0\|_{H^1(\Omega)}^2.$$

Hence, on account of estimates (6.20) and (6.23) we conclude (6.24). \square

We shall apply now the elliptic regularity result. In view of estimate (6.24) we express (1.2), (1.3)₂ in the form of the following elliptic problem

$$(6.27) \quad \begin{aligned} k\Delta\theta &= (c_v^1\theta^3 + c_v^2\theta)\theta_t - \theta\mathbf{B} \cdot \boldsymbol{\varepsilon}_t - (\mathbf{A}_1\boldsymbol{\varepsilon}_t) \cdot \boldsymbol{\varepsilon}_t - g & \text{in } \Omega, t \leq T, \\ \mathbf{n} \cdot \nabla\theta &= 0 & \text{on } S, t \leq T. \end{aligned}$$

We have

LEMMA 6.8. *Assume that estimates (6.20), (6.23), (6.24), and the lower bound (6.1) for θ hold. Then for problem (6.27) the following estimate is satisfied*

$$(6.28) \quad \|\theta\|_{L_2(0,t;W_\rho^2(\Omega))} \leq c_{10}^3 \left(t, \frac{6\rho}{2-\rho} \right) c_{11}(t) \\ + c_{10}(t, 4) c_8(t, 2) + c_8^2(t, 4) + c\|g\|_{L_2(\Omega^t)} \equiv c_{12}(t, \rho)$$

for $\rho < 2^-$, where 2^- stands for a number less than but very close to 2.

PROOF. We estimate the terms on the right-hand side of (6.27)₁. First, by the Hölder inequality, using (6.23) and (6.24) we have

$$\left(\int_0^t \int_\Omega (|\theta^3 \theta_{t'}|^e dx)^{2/e} dt' \right)^{1/2} \leq \left(\int_0^t \|\theta\|_{L_{6e/(2-\rho)}(\Omega)}^6 \|\theta_{t'}\|_{L_2(\Omega)}^2 dt' \right)^{1/2} \\ \leq \sup_t \|\theta\|_{L_{6e/(2-\rho)}(\Omega)}^3 \|\theta_{t'}\|_{L_2(\Omega^t)} \leq c_{10}^3 \left(t, \frac{6\rho}{2-\rho} \right) c_{11}(t),$$

where $\rho < 2$ but is very close to 2. Similarly,

$$\left(\int_0^t \int_\Omega (|\theta \theta_{t'}|^e dx)^{2/e} dt' \right)^{1/2} \leq \left(\int_0^t \|\theta\|_{L_{2e/(2-\rho)}(\Omega)}^2 \|\theta_{t'}\|_{L_2(\Omega)}^2 dt' \right)^{1/2} \\ \leq \sup_t \|\theta\|_{L_{2e/(2-\rho)}(\Omega)} \|\theta_{t'}\|_{L_2(\Omega^t)} \leq c_{10} \left(t, \frac{2\rho}{2-\rho} \right) c_{11}(t) \leq c_{10} \left(t, \frac{6\rho}{2-\rho} \right) c_{11}(t).$$

Finally, using the boundedness of tensors \mathbf{B} , \mathbf{A}_1 , and applying (6.20), (6.23) yield

$$\left(\int_0^t \int_\Omega |\theta \mathbf{B} \cdot \varepsilon_{t'}|^2 dx dt' \right)^{1/2} \\ \leq c \sup_t \|\theta\|_{L_4(\Omega)} \left(\int_0^t \|\varepsilon_{t'}\|_{L_4(\Omega)}^2 dt' \right)^{1/2} \leq c_{10}(t, 4) c_8(t, 2),$$

and

$$\left(\int_0^t \int_\Omega |(\mathbf{A}_1 \varepsilon_{t'}) \cdot \varepsilon_{t'}|^2 dx dt' \right)^{1/2} \\ \leq c \left(\int_0^t \|\varepsilon_{t'}\|_{L_4(\Omega)}^4 dt' \right)^{1/2} = c \|\varepsilon_{t'}\|_{L_4(\Omega^t)}^2 \leq c_8^2(t, 4).$$

On account of the above estimates we conclude (6.28) and thereby complete the proof. \square

From (6.24) and (6.28) it follows that

$$(6.29) \quad \|\theta\|_{W_{\rho,2}^{2,1}(\Omega^t)} \leq c_{11}(t) + c_{12}(t, \rho) \equiv c_{13}(t, \rho) \quad \text{for } \rho < 2^-.$$

Hence, by the imbedding (see Lemma 3.1) it follows that $\nabla\theta \in \mathbf{L}_{5\varrho/3}(\Omega^t)$, $\varrho < 2^-$. Consequently, due to (6.11),

$$(6.30) \quad \|\boldsymbol{\varepsilon}_{t'}\|_{\mathbf{W}_{5\varrho/3}^{1,1/2}(\Omega^t)} \leq c(t)(c_{13}(t, \varrho) + c_4(t, 5\varrho/3, 5\varrho/3)) \equiv c_{14}(t, \varrho), \quad \varrho < 2^-.$$

Further, by the imbedding, we have the estimates

$$(6.31) \quad \|\boldsymbol{\varepsilon}_{t'}\|_{\mathbf{L}_q(\Omega^t)} \leq cc_{14}(t, \varrho) \quad \text{for } q < 10, \varrho < 2^-,$$

and

$$(6.32) \quad \|\boldsymbol{\varepsilon}_{t'}\|_{L_2(0,t;L_\infty(\Omega))} \leq cc_{14}(t, \varrho),$$

which holds for $3/2 < \varrho < 2^-$. The latter estimate plays the key role in getting $L_\infty(\Omega^T)$ -norm bound for θ .

LEMMA 6.9 ($L_\infty(\Omega^T)$ -norm bound on θ). *Assume that $\theta_0 \in L_\infty(\Omega)$, $g \in L_1(0, t; L_\infty(\Omega))$, $g \geq 0$, $t \leq T$, and estimate (6.32) holds. Then*

$$(6.33) \quad \|\theta\|_{L_\infty(\Omega^t)} \leq \varphi(c_{14}(t, 2^-), \|\theta_0\|_{L_\infty(\Omega)}, \|g\|_{L_1(0,t;L_\infty(\Omega))}) \equiv c_{15}(t).$$

PROOF. Multiplying (1.2) by θ^r , $r > 1$, integrating over Ω , and using (6.32), we get

$$(6.34) \quad \begin{aligned} c_v^1 \|\theta\|_{L_{r+4}(\Omega)}^{r+3} \frac{d}{dt} \|\theta\|_{L_{r+4}(\Omega)} + c_v^2 \|\theta\|_{L_{r+2}(\Omega)}^{r+1} \frac{d}{dt} \|\theta\|_{L_{r+2}(\Omega)} \\ + \frac{4kr}{(r+1)^2} \int_{\Omega} |\nabla\theta^{(r+2)/2}|^2 dx \\ \leq c[\|\boldsymbol{\varepsilon}_t\|_{L_\infty(\Omega)} \|\theta\|_{L_{r+1}(\Omega)}^{r+1} \\ + \|\boldsymbol{\varepsilon}_t\|_{L_\infty(\Omega)}^2 \|\theta\|_{L_r(\Omega)}^r + \|g\|_{L_\infty(\Omega)} \|\theta\|_{L_r(\Omega)}^r]. \end{aligned}$$

Taking into account that $\theta \geq \theta_* > 0$ we deduce from (6.34) that

$$(6.35) \quad \begin{aligned} c_v^1 \|\theta\|_{L_{r+4}(\Omega)}^{r+3} \frac{d}{dt} \|\theta\|_{L_{r+4}(\Omega)} + c_v^2 \|\theta\|_{L_{r+2}(\Omega)}^{r+1} \frac{d}{dt} \|\theta\|_{L_{r+2}(\Omega)} \\ \leq c(1/\theta_*)[\|\boldsymbol{\varepsilon}_t\|_{L_\infty(\Omega)} + \|\boldsymbol{\varepsilon}_t\|_{L_\infty(\Omega)}^2 + \|g\|_{L_\infty(\Omega)}] \|\theta\|_{L_{r+4}(\Omega)}^{r+4} \\ \equiv \alpha(t) \|\theta\|_{L_{r+4}(\Omega)}^{r+4}. \end{aligned}$$

Expressing (6.35) in the form

$$\begin{aligned} \frac{d}{dt} \left[\frac{c_v^1}{r+4} \|\theta\|_{L_{r+4}(\Omega)}^{r+4} + \frac{c_v^2}{r+2} \|\theta\|_{L_{r+2}(\Omega)}^{r+2} \right] \\ \leq \frac{\alpha(t)}{c_v^1} (r+4) \left[\frac{c_v^1}{r+4} \|\theta\|_{L_{r+4}(\Omega)}^{r+4} + \frac{c_v^2}{r+2} \|\theta\|_{L_{r+2}(\Omega)}^{r+2} \right], \end{aligned}$$

and introducing the notation

$$Y(t) = \frac{c_v^1}{r+4} \|\theta(t)\|_{L_{r+4}(\Omega)}^{r+4} + \frac{c_v^2}{r+2} \|\theta(t)\|_{L_{r+2}(\Omega)}^{r+2},$$

we have

$$(6.36) \quad \frac{d}{dt} Y(t) \leq \frac{\alpha(t)(r+4)}{c_v^1} Y(t).$$

Integrating (6.36) with respect to time yields

$$Y(t) \leq Y(0) \exp\left(\frac{r+4}{c_v^1} \int_0^t \alpha(t') dt'\right), \quad t \leq T.$$

From the above inequality we get

$$\frac{c_v^1}{r+4} \|\theta(t)\|_{L_{r+4}(\Omega)}^{r+4} \leq Y(0) \exp\left(\frac{r+4}{c_v^1} \int_0^t \alpha(t') dt'\right).$$

Hence,

$$(6.37) \quad \begin{aligned} \|\theta(t)\|_{L_{r+4}(\Omega)} &\leq \left(\frac{r+4}{c_v^1} Y(0)\right)^{1/(r+4)} \exp\left(\frac{1}{c_v^1} \int_0^t \alpha(t') dt'\right) \\ &\leq \left(\|\theta_0\|_{L_{r+4}(\Omega)} + \frac{c_v^2}{c_v^1} \left(\frac{r+4}{r+2}\right) \|\theta_0\|_{L_{r+2}(\Omega)}^{(r+2)/(r+4)}\right) \exp\left(\frac{1}{c_v^1} \int_0^t \alpha(t') dt'\right). \end{aligned}$$

Now, letting $r \rightarrow \infty$ in (6.37) we conclude (6.33). \square

To prove the Hölder continuity of θ we follow exactly the arguments from [24, Lemma 6.14 and Corollary 6.15] related to thermo-visco-elasticity with the specific heat $c = c_v \theta^\sigma$, $\sigma \in (1/2, 1]$. Consequently, we have

LEMMA 6.10 (Hölder continuity of θ). *Assume that $\theta(t) \geq \theta_* > 0$ for $t \leq T$. Let $M = \|\theta\|_{L_\infty(\Omega^t)} \leq c_{15}(T)$ (see (6.33)), $\|\theta_0\|_{L_\infty(\Omega)} < k$, and $M - k < \delta$ for some sufficiently small $\delta > 0$. Let $g \in L_\lambda(\Omega^t)$, $\varepsilon_{t'} \in \mathbf{L}_{2\lambda}(\Omega^t)$, where $\lambda = 1/(1 - 2(1 + \varkappa)/r)$, $2/r + 3/q = 3/2$, q, r are positive numbers, and $\varkappa > 0$. Then*

$$(6.38) \quad \theta \in C^{\beta, \beta/2}(\Omega^t), \quad \beta \in (0, 1), \quad t \leq T,$$

where β depends on θ_* , M , δ , \varkappa , r .

To prove the global existence of solutions to problem (1.1)–(1.4) we need the existence of local solutions and a global estimate in the norms in which the local existence is proved. More precisely, we are going to obtain a global estimate for $\mathbf{u}_t \in \mathbf{W}_{5^+}^{2,1}(\Omega^t)$ and $\theta \in W_{5^+}^{2,1}(\Omega^t)$.

LEMMA 6.11 (Global *a priori* estimates compatible with estimates for local solution). *Assume that $\mathbf{b} \in \mathbf{L}_{15,\infty}(\Omega^t)$, $\mathbf{u}_0 \in \mathbf{W}_{5^+}^2(\Omega)$, $\mathbf{u}_1 \in \mathbf{B}_{5^+,5^+}^{2-2/5^+}(\Omega)$, $g \in L_{5^+}(0, t; L_\infty(\Omega))$, $g \geq 0$, $\theta_0 \in H^1(\Omega) \cap B_{5^+,5^+}^{2-2/5^+}(\Omega) \cap L_\infty(\Omega)$. Then solutions to problem (1.1)–(1.4) satisfy the estimates*

$$(6.39) \quad \|\mathbf{u}_t\|_{\mathbf{W}_{5^+}^{2,1}(\Omega^t)} \leq \varphi(t, 1/\theta_*, d(t)),$$

$$(6.40) \quad \|\theta\|_{W_{5^+}^{2,1}(\Omega^t)} \leq \varphi(t, 1/\theta_*, d(t)),$$

where, for $t \leq T$,

$$\begin{aligned} d(t) = & \|\mathbf{b}\|_{L_{15,\infty}(\Omega^t)} + \|\mathbf{u}_0\|_{W_{5^+}^2(\Omega)} + \|\mathbf{u}_1\|_{\mathbf{B}_{5^+,5^+}^{2-2/5^+}(\Omega)} \\ & + \|g\|_{L_{5^+}(0,t;L_\infty(\Omega))} + \|\theta_0\|_{H^1(\Omega) \cap \mathbf{B}_{5^+,5^+}^{2-2/5^+}(\Omega) \cap L_\infty(\Omega)}. \end{aligned}$$

PROOF. In Section 5 we proved the existence of local solutions such that $\mathbf{u}_t \in \mathbf{W}_{5^+}^{2,1}(\Omega^t)$, $\theta \in W_{5^+}^{2,1}(\Omega^t)$ for t sufficiently small. Then $\boldsymbol{\varepsilon}_t \in \mathbf{W}_{5^+}^{1,1/2}(\Omega^t)$. To prove the global existence we need a global estimate for solutions to problem (1.1)–(1.4) in these classes. For this purpose let us recall estimates from Lemmas 6.1–6.10. From (6.2) we have

$$\begin{aligned} (6.41) \quad & \|\mathbf{u}(t)\|_{H^1(\Omega)} + \|\mathbf{u}_t(t)\|_{L_2(\Omega)}^2 + \|\theta(t)\|_{L_4(\Omega)}^4 \\ & \leq c(t) (\|\mathbf{u}_0\|_{H^1(\Omega)}^2 + \|\mathbf{u}_1\|_{L_2(\Omega)}^2 + \|\theta_0\|_{L_4(\Omega)}^4 + \|\mathbf{b}\|_{L_2(\Omega^t)}^2 + \|g\|_{L_1(\Omega^t)}). \end{aligned}$$

Let $\theta \in L_{p,r}(\Omega^t)$. Then (6.9) yields

$$(6.42) \quad \|\boldsymbol{\varepsilon}_t\|_{L_{p,r}(\Omega^t)} \leq c(t) (\|\theta\|_{L_{p,r}(\Omega^t)} + \|\mathbf{b}\|_{L_{p,r}(\Omega^t)} + \|\mathbf{u}_0\|_{\mathbf{W}_p^1(\Omega)} + \|\mathbf{u}_1\|_{\mathbf{B}_{p,r}^{1-2/r}(\Omega)}).$$

Estimate (6.41) implies that $\theta \in L_{4,r}(\Omega^t)$, $r \in (1, \infty)$. Then (6.42) implies that

$$\begin{aligned} (6.43) \quad & \|\boldsymbol{\varepsilon}_t\|_{L_{4,r}(\Omega^t)} \\ & \leq \varphi_1 (\|\mathbf{u}_0\|_{\mathbf{W}_4^1(\Omega)}, \|\mathbf{u}_1\|_{\mathbf{B}_{4,r}^{1-2/r}(\Omega)}, \|\mathbf{b}\|_{L_{4,r}(\Omega^t)}, \|\theta_0\|_{L_4(\Omega)}, \|g\|_{L_1(\Omega^t)}), \end{aligned}$$

where φ_1 is an increasing positive function. Later on we shall always denote by φ_k , $k \in \mathbb{N}$, an increasing positive function of its arguments.

Let $\nabla\theta \in L_{p,r}(\Omega^t)$. Then from (6.11) it follows that

$$\begin{aligned} (6.44) \quad & \|\boldsymbol{\varepsilon}_t\|_{\mathbf{W}_{p,r}^{1,1/2}(\Omega^t)} \leq c \|\mathbf{u}_t\|_{\mathbf{W}_{p,r}^{2,1}(\Omega^t)} \\ & \leq c(t) (\|\nabla\theta\|_{L_{p,r}(\Omega^t)} + \|\mathbf{b}\|_{L_{p,r}(\Omega^t)} + \|\mathbf{u}_0\|_{\mathbf{W}_p^2(\Omega)} + \|\mathbf{u}_1\|_{\mathbf{B}_{p,r}^{2-2/r}(\Omega)}), \end{aligned}$$

where $p, r \in (1, \infty)$ and will be chosen appropriately later on. From Lemma 6.4 and (6.41), (6.43) we get

$$\begin{aligned} (6.45) \quad & \|\theta(t)\|_{L_5(\Omega)} + \|\nabla\theta\|_{L_2(\Omega)} \\ & \leq \varphi_2 (\|\mathbf{u}_0\|_{\mathbf{W}_4^1(\Omega)}, \|\mathbf{u}_1\|_{L_4(\Omega)}, \|\mathbf{b}\|_{L_{4,2}(\Omega^t)}, \|g\|_{L_{5/4,1}(\Omega^t)}, \|\theta_0\|_{L_5(\Omega)}). \end{aligned}$$

Using (6.45) in (6.42) yields

$$\begin{aligned} (6.46) \quad & \|\boldsymbol{\varepsilon}_t\|_{L_{5,r}(\Omega^t)} \\ & \leq \varphi_3 (\|\mathbf{u}_0\|_{\mathbf{W}_5^1(\Omega)}, \|\mathbf{u}_1\|_{\mathbf{B}_{5,r}^{1-2/r}(\Omega)}, \|\mathbf{b}\|_{L_{5,r}(\Omega^t)}, \|g\|_{L_{5/4,1}(\Omega^t)}, \|\theta_0\|_{L_5(\Omega)}), \end{aligned}$$

for $r \geq 2$. Further, applying (6.5) with $r = 24$, Lemma 6.5 provides the estimate

$$\begin{aligned} (6.47) \quad & \|\theta(t)\|_{L_{15}(\Omega)} + \|\theta\|_{L_{36,12}(\Omega^t)} \\ & \leq \varphi_4 (\|\mathbf{u}_0\|_{\mathbf{W}_5^1(\Omega)}, \|\mathbf{u}_1\|_{\mathbf{B}_{5,24}^{1-2/24}(\Omega)}, \|\mathbf{b}\|_{L_{5,24}(\Omega^t)}, \|g\|_{L_{36/25,12}(\Omega^t)}, \|\theta_0\|_{L_{15}(\Omega)}). \end{aligned}$$

Employing (6.47) in (6.42) we have

$$(6.48) \quad \|\varepsilon_t\|_{L_{15,r}(\Omega^t)} \leq \varphi_5 \left(\|\mathbf{u}_0\|_{W_{15}^1(\Omega)}, \|\mathbf{u}_1\|_{B_{15,r}^{1-2/24}(\Omega)}, \right. \\ \left. \|\mathbf{b}\|_{L_{15,r}(\Omega^t) \cap L_{5,24}(\Omega^t)}, \|g\|_{L_{36/25,12}(\Omega^t)}, \|\theta_0\|_{L_{15}(\Omega)} \right).$$

Now we use Lemma 6.6. The estimate (6.21) holds true provided $\varepsilon_t \in L_{15,2\alpha}(\Omega^t)$ with $\alpha \geq 12$ (see (6.15)). Then (6.21) takes the form

$$(6.49) \quad \|\theta(t)\|_{L_{\alpha+3}(\Omega)} + \|\nabla \theta^{\alpha/2}\|_{L_2(\Omega^t)}^{2/\alpha} \leq \varphi_6 \left(\|\mathbf{u}_0\|_{W_{15}^1(\Omega)}, \|\mathbf{u}_1\|_{B_{15,2\alpha}^{1-2/2\alpha}(\Omega)}, \right. \\ \left. \|\mathbf{b}\|_{L_{15,2\alpha}(\Omega^t)}, \|g\|_{L_{3\alpha/(2\alpha+1),\alpha}(\Omega^t)}, \|\theta_0\|_{L_{\alpha+3}(\Omega)} \right).$$

Continuing, Lemma 6.7 yields

$$(6.50) \quad \|\theta_t\|_{L_2(\Omega^t)} + \|\theta\|_{L_\infty(0,t;H^1(\Omega))} \leq \varphi_7 \left(1/\theta_*, \|\mathbf{u}_0\|_{W_{15}^1(\Omega)}, \right. \\ \left. \|\mathbf{u}_1\|_{B_{15,2\alpha}^{1-2/2\alpha}(\Omega)}, \|\mathbf{b}\|_{L_{15,2\alpha}(\Omega^t)}, \|g\|_{L_{2,\alpha}(\Omega^t)}, \|\theta_0\|_{L_{\alpha+3}(\Omega) \cap H^1(\Omega)} \right).$$

In the next step we use Lemma 6.8. It implies that

$$(6.51) \quad \|\theta\|_{L_2(0,t;W_\varrho^2(\Omega))} \leq \varphi_7, \quad \varrho < 2,$$

where φ_7 is defined by (6.50) with α arbitrary large. Hence, (6.50) and (6.51) imply

$$(6.52) \quad \|\theta\|_{W_{\varrho,2}^{2,1}(\Omega^t)} \leq \varphi_7$$

with α arbitrary large (see (6.50)) and $\varrho < 2$. Hence, by the imbedding from Lemma 3.1 it follows that $\nabla \theta \in L_{5\varrho/3}(\Omega^t)$, $\varrho < 2$. Consequently, due to (6.44),

$$(6.53) \quad \|\varepsilon_t\|_{W_{5\varrho/3}^{1,1/2}(\Omega^t)} \leq c(\varphi_7 + \|\mathbf{u}_0\|_{W_{5\varrho/3}^2(\Omega)} + \|\mathbf{u}_1\|_{B_{5\varrho/3,5\varrho/3}^{2-2/(5\varrho/3)}(\Omega)}) \\ \equiv \varphi_8(1/\theta_*, \|\mathbf{u}_0\|_{W_{15}^1(\Omega) \cap W_{5\varrho/3}^2(\Omega)}, \|\mathbf{u}_1\|_{B_{15,2\alpha}^{1-2/2\alpha}(\Omega) \cap B_{5\varrho/3,5\varrho/3}^{2-2/(5\varrho/3)}(\Omega)}, \\ \|\mathbf{b}\|_{L_{15,2\alpha}(\Omega^t)}, \|g\|_{L_{2,\alpha}(\Omega^t)}, \|\theta_0\|_{L_{\alpha+3}(\Omega) \cap H^1(\Omega)}),$$

where $\varrho < 2$ and $\alpha = 6\varrho/(2 - \varrho)$. Further, Lemma 6.9 yields the estimate

$$(6.54) \quad \|\theta\|_{L_\infty(\Omega^t)} \leq c(\varphi_8 + \|g\|_{L_1(0,t;L_\infty(\Omega))} + \|\theta_0\|_{L_\infty(\Omega)}),$$

where the following imbeddings were used

$$(6.55) \quad \|\varepsilon_t\|_{L_q(\Omega^t)} + \|\varepsilon_t\|_{L_2(0,t;L_\infty(\Omega))} \leq c\|\varepsilon_t\|_{W_{5\varrho/3}^{1,1/2}(\Omega^t)}$$

for $3/2 < \varrho < 2$, where $q < 5/(3/\varrho - 1)$.

Finally, Lemma 6.10 implies that $\theta \in C^{\beta,\beta/2}(\Omega^t)$, $\beta \in (0, 1)$ for $g \in L_\lambda(\Omega^t)$, $\varepsilon_t \in L_{2\lambda}(\Omega^t)$, $\lambda = 1/(1 - 2(1 + \varkappa)/r)$, $2/r + 3/q = 3/2$, $\varkappa > 0$. Hence, we can choose $\lambda = 2$. Moreover, $\theta_0 \in C^\beta(\Omega)$.

Since θ is the Hölder continuous we can apply the theory of parabolic equations described by Lemmas 3.4 and 3.5. However, looking for $\mathbf{u} \in W_{5^+}^{2,1}(\Omega^t)$ we need that $\nabla \theta \in L_{5^+}(\Omega^t)$. Because, up to now, we have not proved such estimate

for θ we consider problem (1.2), (1.3)₂, (1.4)₃ for θ . By (6.48) it follows that $\varepsilon_t \in \mathbf{L}_{15,2\alpha}(\Omega^t)$, $\alpha \geq 12$ and $\theta \in L_\infty(\Omega^t)$. In result we have

$$(6.56) \quad \|\theta\|_{W_{5^+}^{2,1}(\Omega^t)} \leq \varphi_9(\|\theta\|_{L_\infty(\Omega^t)}, \|\varepsilon_t\|_{\mathbf{L}_{2\sigma}(\Omega^t)}, \|g\|_{L_\sigma(\Omega^t)}, \|\theta_0\|_{W_{\sigma}^{-2/\sigma}(\Omega)}),$$

for $\sigma = 5^+$. Hence, by the imbedding,

$$\|\nabla\theta\|_{\mathbf{L}_\delta(\Omega^t)} \leq c\|\theta\|_{W_{5^+}^{2,1}(\Omega^t)} \quad \text{for any } \delta > 1.$$

Then problem (1.1), (1.3)_{1,2}, (1.4)_{1,2} implies

$$(6.57) \quad \|\mathbf{u}_t\|_{\mathbf{W}_{5^+}^{2,1}(\Omega^t)} \leq c(\|\nabla\theta\|_{\mathbf{L}_{5^+}(\Omega^t)}, \|\mathbf{b}\|_{\mathbf{L}_{5^+}(\Omega^t)}, \|\mathbf{u}_1\|_{\mathbf{W}_{5^+}^{2-2/5^+}(\Omega)}, \|uu_0\|_{\mathbf{W}_{5^+}^2(\Omega)}).$$

therefore (6.56) and (6.57) imply (6.39), (6.40), respectively. \square

7. Global existence

PROOF OF THEOREM 1.1. Theorem 5.3 provides the local existence of solutions to problem (1.1)–(1.4) such that $\mathbf{u}_t \in \mathbf{W}_{5^+}^{2,1}(\Omega^t)$ and $\theta \in W_{5^+}^{2,1}(\Omega^t)$, where t is sufficiently small. By virtue of Lemma 6.11 we have global *a priori* estimates for problem (1.1)–(1.4) such that $\mathbf{u}_t \in \mathbf{W}_{5^+}^{2,1}(\Omega^t)$ and $\theta \in W_{5^+}^{2,1}(\Omega^t)$ for any t finite. These estimates are compatible with the estimates for local solutions on the time interval of the local existence. This implies a possibility of extension of the local solution for any finite time. \square

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