# IDEAL KAEHLERIAN SLANT SUBMANIFOLDS IN COMPLEX SPACE FORMS 

ION MIHAI


#### Abstract

Roughly speaking, an ideal immersion of a Riemannian manifold into a space form is an isometric immersion which produces the least possible amount of tension from the ambient space at each point of the submanifold. Recently, Chen studied Lagrangian submanifolds in complex space forms which are ideal. He proved that such submanifolds are minimal. He also classified ideal Lagrangian submanifolds in complex space forms.

In the present paper, we investigate ideal Kaehlerian slant submanifolds in a complex space form. We prove that such submanifolds are minimal. We also obtain obstructions to ideal slant immersions in complex hyperbolic space.


1. Chen invariants and Chen inequalities. It is well known that Riemannian invariants play the most fundamental role in Riemannian geometry. Riemannian invariants provide the intrinsic characteristics of Riemannian manifolds which affect the behavior in general of the Riemannian manifold.

Let $M$ be an $n$-dimensional Riemannian manifold. We denote by $K(\pi)$ the sectional curvature of $M$ associated with a plane section $\pi \subset T_{p} M, p \in M$. For any orthonormal basis $\left\{e_{1}, \ldots, e_{n}\right\}$ of the tangent space $T_{p} M$, the scalar curvature $\tau$ at $p$ is defined by

$$
\begin{equation*}
\tau(p)=\sum_{i<j} K\left(e_{i} \wedge e_{j}\right) \tag{1.1}
\end{equation*}
$$

Let $L$ be a subspace of $T_{p} M$ of dimension $r \geq 2$ and $\left\{e_{1}, \ldots, e_{r}\right\}$ an orthonormal basis of $L$. The scalar curvature $\tau(L)$ of the $r$-plane

[^0]section $L$ is defined by
\[

$$
\begin{equation*}
\tau(L)=\sum_{\alpha<\beta} K\left(e_{\alpha} \wedge e_{\beta}\right), \quad 1 \leq \alpha, \beta \leq r \tag{1.2}
\end{equation*}
$$

\]

For an integer $k \geq 0$, we denote by $\mathcal{S}(n, k)$ the finite set consisting of unordered $k$-tuples $\left(n_{1}, \ldots, n_{k}\right)$ of integers $\geq 2$ satisfying $n_{1}<n$ and $n_{1}+\cdots+n_{k} \leq n$. Then $\mathcal{S}(n)$ is the union $\cup_{k \geq 0} \mathcal{S}(n, k)$.

Chen introduced in $[\mathbf{3}, \mathbf{4}]$ a new type of curvature invariant $\delta\left(n_{1}, \ldots\right.$, $n_{k}$ ) known as Chen invariants, defined as follows.

$$
\begin{equation*}
\delta\left(n_{1}, \ldots, n_{k}\right)=\tau-\inf \left\{\tau\left(L_{1}\right)+\cdots+\tau\left(L_{k}\right)\right\} \tag{1.3}
\end{equation*}
$$

where, at each point $p \in M, L_{1}, \ldots, L_{k}$ run over all $k$ mutually orthogonal subspaces of $T_{p} M$ such that $\operatorname{dim} L_{j}=n_{j}, j=1, \ldots, k$.

He proved in [4] an optimal relationship between the Chen invariants $\delta\left(n_{1}, \ldots, n_{k}\right)$ and the squared mean curvature $\|H\|^{2}$, which we call the Chen inequality, for an arbitrary submanifold in a real space form.

Chen also pointed out in [4] that the same result holds for totally real submanifolds in complex space forms.

Let $\widetilde{M}(4 c)$ be an $m$-dimensional complex space form with constant holomorphic sectional curvature $4 c$. We denote by $J$ the complex structure of $\widetilde{M}(4 c)$. The curvature tensor $\widetilde{R}$ of $\widetilde{M}(4 c)$ is given by [13]:

$$
\begin{align*}
\widetilde{R}(X, Y) Z= & c(g(Y, Z) X-g(X, Z) Y  \tag{1.4}\\
& +g(J Y, Z) J X-g(J X, Z) J Y-2 g(J X, Y) J Z)
\end{align*}
$$

for any tangent vector fields $X, Y, Z$ to $\widetilde{M}(4 c)$.
An $n$-dimensional submanifold $M$ of $\widetilde{M}(4 c)$ is said to be a slant submanifold $[\mathbf{1}]$ if, for any $p \in M$ and any nonzero vector $X \in T_{p} M$, the angle between $J X$ and the tangent space $T_{p} M$ is constant which is denoted by $\theta$. Moreover, if $M$ is neither complex, $\theta=0$, nor totally real, $\theta=\pi / 2$, then $M$ is called a proper slant submanifold.

We denote by $h$ and $A$ the second fundamental form and the shape operator, respectively, of $M$ in $\widetilde{M}(4 c)$.
The equations of Gauss and Codazzi are given respectively by

$$
\begin{align*}
\widetilde{R}(X, Y, Z, W)= & R(X, Y, Z, W)-g(h(X, Z), h(Y, W))  \tag{1.5}\\
& +g(h(X, W), h(Y, Z))
\end{align*}
$$

$$
\begin{equation*}
\left(\nabla_{X} h\right)(Y, Z)=\left(\nabla_{Y} h\right)(X, Z) \tag{1.6}
\end{equation*}
$$

where $X, Y, Z, W$ are tangent vector fields to $M$, and $\nabla h$ is defined by

$$
\left(\nabla_{X} h\right)(Y, Z)=\nabla_{X}^{\perp} h(Y, Z)-h\left(\nabla_{X} Y, Z\right)-h\left(Y, \nabla_{X} Z\right)
$$

For any vector field $X$ tangent to $M$, we put $J X=P X+F X$, where $P X$ and $F X$ are the tangential and normal components of $J X$. Thus, $P$ is an endomorphism of the tangent bundle $T M$.
We obtained inequalities satisfied by some Chen invariants $\delta^{\prime}\left(n_{1}, \ldots, n_{k}\right)$ for slant submanifolds in a complex space form in [11].

We consider the Riemannian invariant

$$
\delta^{\prime}\left(n_{1}, \ldots, n_{k}\right)=\tau-\inf \left\{\tau\left(L_{1}\right)+\cdots+\tau\left(L_{k}\right)\right\}
$$

where, at each point $p \in M, L_{1}, \ldots, L_{k}$ run over all $k$ mutually orthogonal subspaces of $T_{p} M$ invariant by the endomorphism $P$, such that $\operatorname{dim} L_{j}=n_{j}, j=1, \ldots, k$. We set

$$
\begin{aligned}
b\left(n_{1}, \ldots, n_{k}\right) & =\frac{n^{2}\left(n+k-1-\sum_{j=1}^{k} n_{j}\right)}{2\left(n+k-\sum_{j=1}^{k} n_{j}\right)} \\
d\left(n_{1}, \ldots, n_{k}\right) & =\frac{1}{2}\left[n(n-1)-\sum_{j=1}^{k} n_{j}\left(n_{j}-1\right)\right]
\end{aligned}
$$

Theorem 1.1. Let $M$ be an $n$-dimensional $\theta$-slant submanifold of an m-dimensional complex space form $\widetilde{M}(4 c)$. Then, for any $\left(n_{1}, \ldots, n_{k}\right) \in \mathcal{S}(n)$, we have

$$
\begin{align*}
\delta^{\prime}\left(n_{1}, \ldots, n_{k}\right) \leq & b\left(n_{1}, \ldots, n_{k}\right)\|H\|^{2}+d\left(n_{1}, \ldots, n_{k}\right) c \\
& +\frac{3}{2}\left(n-\sum_{j=1}^{k} n_{j}\right) c \cos ^{2} \theta \tag{1.7}
\end{align*}
$$

Moreover, the equality holds at a point $p \in M$ if and only if there exists a tangent basis $\left\{e_{1}, \ldots, e_{n}\right\} \subset T_{p} M$ and a normal basis
$\left\{e_{n+1}, \ldots, e_{2 m}\right\} \subset T_{p}^{\perp} M$ such that, for any vector $\xi$ normal to $M$ at $p$, the shape operator $A_{\xi}$ takes the following form

$$
A_{\xi}=\left(\begin{array}{cccc}
A_{1}^{\xi} & \cdots & 0 &  \tag{1.8}\\
\vdots & \ddots & \vdots & 0 \\
0 & \cdots & A_{k}^{\xi} & \\
& 0 & & \mu_{\xi} I
\end{array}\right)
$$

where $I$ is an identity matrix and $A_{j}^{\xi}$ is a symmetric $n_{j} \times n_{j}$ submatrix satisfying

$$
\begin{equation*}
\operatorname{tr}\left(A_{1}^{\xi}\right)=\cdots=\operatorname{tr}\left(A_{k}^{\xi}\right)=\mu_{\xi} \tag{1.9}
\end{equation*}
$$

A slant submanifold $M$ of a complex space form $\widetilde{M}(4 c)$ is called ideal if it satisfies the equality case of the inequality (1.7) identically for some $\left(n_{1}, \ldots, n_{k}\right) \in \mathcal{S}(n)$.
2. Minimality of ideal submanifolds. In the following sections, we will investigate $n$-dimensional Kaehlerian slant ideal submanifolds in an $n$-dimensional complex space form $\widetilde{M}(4 c)$.

We recall a proper slant submanifold is Kaehlerian slant if the endomorphism $P$ is parallel with respect to the Riemannian connection $\nabla$. It is known in [1] that this condition is equivalent to

$$
\begin{equation*}
A_{F X} Y=A_{F Y} X, \quad \forall X, Y \in \Gamma(T M) \tag{2.1}
\end{equation*}
$$

First, we will prove that such submanifolds are minimal.

Theorem 2.1. Let $M$ be an $n$-dimensional Kaehlerian slant submanifold of an n-dimensional complex space form $\widetilde{M}(4 c)$. If $M$ is an ideal submanifold, then it is minimal.

Proof. Let $M$ be a Kaehlerian slant submanifold of a complex space form $\widetilde{M}(4 c)$ with $\operatorname{dim} M=n$ and $\operatorname{dim} \widetilde{M}(c)=n$, and let $p \in M$.

We distinguish two cases:
(a) $g(h(u, v), F w)=0$, for all $u, v, w \in T_{p} M$.

Obviously, it follows that $H(p)=0$.
(b) $g(h(u, u), F u) \neq 0$, for some $u \in T_{p} M$.

We will construct an orthonormal basis $\left\{\varepsilon_{1}, \ldots, \varepsilon_{n}\right\}$ of $T_{p} M$ such that

$$
\begin{equation*}
A_{F \varepsilon_{1}} \varepsilon_{i}=\lambda_{i} \varepsilon_{i}, \quad i=1, \ldots, n \tag{2.2}
\end{equation*}
$$

where $\lambda_{1}, \ldots, \lambda_{n}$ satisfy $\lambda_{1} \geq 2 \lambda_{j}, j=2, \ldots, n$.
We define a function $f_{p}$ by

$$
f_{p}: T_{p}^{1} M \longrightarrow \mathbf{R} ; \quad u \longmapsto f_{p}(u)=g(h(u, u), F u),
$$

where $T_{p}^{1} M$ is the unit hypersphere of $T_{p} M$ consisting of all unit vectors in $T_{p} M$. Since $T_{p}^{1} M$ is a compact set, there exists a vector $v$ in $T_{p}^{1} M$ such that $f_{p}$ attains an absolute maximum at $v$. We denote $\lambda_{1}=f_{p}(v)>0$. It is easily seen that $A_{F v} v=\lambda_{1} v$. We put $\varepsilon_{1}=v$ and choose $\varepsilon_{2}, \ldots, \varepsilon_{n}$ so that $\left\{\varepsilon_{1}, \ldots, \varepsilon_{n}\right\}$ is an orthonormal basis of $T_{p} M$ and each $\varepsilon_{i}$ is an eigenvector of $A_{F \varepsilon_{1}}$ with eigenvalue $\lambda_{i}$.

Since $f_{p}$ attains an absolute maximum at $\varepsilon_{1}$, the function $f_{i}, i \in$ $\{2, \ldots, n\}$, defined by $f_{i}(t)=f_{p}\left((\cos t) \varepsilon_{1}+(\sin t) \varepsilon_{i}\right)$ has a relative maximum at $t=0$. So, by a straightforward computation, we get

$$
0 \geq f_{i}^{\prime \prime}(0)=-3 \lambda_{1}+6 \lambda_{i}
$$

i.e., $\lambda_{1} \geq 2 \lambda_{i}$, for all $i \geq 2$.

Since $\lambda_{1}>0$, we find $\lambda_{1}>\lambda_{i}$, for $i \geq 2$. In particular, this implies that the eigenspace of $A_{F \varepsilon_{1}}$ corresponding to the eigenvalue $\lambda_{1}$ is 1dimensional.

We assume that $M$ is ideal. Then it satisfies

$$
\begin{align*}
\delta^{\prime}\left(n_{1}, \ldots, n_{k}\right)= & b\left(n_{1}, \ldots, n_{k}\right)\|H\|^{2}+d\left(n_{1}, \ldots, n_{k}\right) c \\
& +\frac{3}{2}\left(n-\sum_{j=1}^{k} n_{j}\right) c \cos ^{2} \theta \tag{2.3}
\end{align*}
$$

identically for some $k$-tuple $\left(n_{1}, \ldots, n_{k}\right) \in \mathcal{S}(n)$.

Thus, according to Theorem 1.1, there is an orthonormal basis $\left\{e_{1}, \ldots, e_{n}\right\}$ of $T_{p} M$ at each $p \in M$ such that, for any normal vector $\xi$ at $p$, the shape operator $A_{\xi}$ with respect to $\left\{e_{1}, \ldots, e_{n}\right\}$ takes the form (1.8).

With respect to the orthonormal basis $\left\{e_{1}, \ldots, e_{n}\right\}$ chosen above, we put

$$
\begin{align*}
& L_{i}=\operatorname{Span}\left\{e_{\alpha} \mid \alpha \in I_{i}\right\},  \tag{2.4}\\
& \operatorname{tr}_{L_{i}} h=\sum_{\alpha \in I_{i}} h\left(e_{\alpha}, e_{\alpha}\right), \tag{2.5}
\end{align*}
$$

where $I_{i}=\left\{n_{1}+\cdots+n_{i-1}+1, \ldots, n_{1}+\cdots+n_{i}\right\}, i=1, \ldots, k$, and

$$
L_{k+1}=\operatorname{Span}\left\{e_{n_{1}+\cdots+n_{k}+1}, \ldots, e_{n}\right\}
$$

Obviously, we have $T_{p} M=L_{1} \oplus \cdots \oplus L_{k+1}$. We will show that $\varepsilon_{1}$ lies in one of $L_{1}, \ldots, L_{k}$. Let

$$
\begin{equation*}
\varepsilon_{1}=v_{1}+\cdots+v_{k}+v_{k+1} \tag{2.6}
\end{equation*}
$$

with $v_{1} \in L_{1}, \ldots, v_{k+1} \in L_{k+1}$. Then, we have

$$
\begin{equation*}
\lambda_{1} \varepsilon_{1}=A_{\phi \varepsilon_{1}} \varepsilon_{1}=A_{F \varepsilon_{1}} v_{1}+\cdots+A_{F \varepsilon_{1}} v_{k}+A_{F \varepsilon_{1}} v_{k+1} \tag{2.7}
\end{equation*}
$$

From (1.8) we have $A_{F \varepsilon_{1}} v_{i} \in L_{i}$. Thus, (2.6) and (2.7) imply

$$
A_{F \varepsilon_{1}} v_{1}=\lambda_{1} v_{1}, \ldots, A_{F \varepsilon_{1}} v_{k+1}=\lambda_{1} v_{k+1}
$$

Since the eigenspace of $A_{F \varepsilon_{1}}$ corresponding to the eigenvalue $\lambda_{1}$ is 1 -dimensional, the above equation implies that exactly one of $v_{1}, \ldots, v_{k+1}$ does not vanish. If we suppose that $\varepsilon_{1}=v_{k+1}$, then $n_{1}+\cdots+n_{k}=n-1$, because the multiplicity of $\lambda_{1}$ is 1 . In this case, $\varepsilon_{1}= \pm e_{n}$. Therefore, we get

$$
\pm A_{F \varepsilon_{i}} e_{n}=A_{F \varepsilon_{i}} \varepsilon_{1}=A_{F \varepsilon_{1}} \varepsilon_{i}=\lambda_{i} \varepsilon_{i} \perp e_{n}= \pm \varepsilon_{1}
$$

for $i=2, \ldots, n$. Thus, we obtain $\lambda_{2}=\cdots=\lambda_{n}=0$ by applying (1.8). Hence, by (1.9), one has $\lambda_{1}=0$, which is a contradiction. Consequently, $\varepsilon_{1}$ must belong to one of $L_{1}, \ldots, L_{k}$.

Without loss of generality, we may now assume $\varepsilon_{1}=e_{1}$. Moreover, since $A_{F e_{1}}$ takes the form (1.8), we may also assume $\varepsilon_{2}=e_{2}, \ldots, \varepsilon_{n}=$ $e_{n}$.

In other words, we may choose the eigenvectors $\varepsilon_{2}, \ldots, \varepsilon_{n}$ of $A_{F e_{1}}$ to be compatible with the decomposition arisen from (1.8). Therefore, by applying (1.8) and (2.1), we have

$$
\begin{equation*}
g\left(h\left(X_{i}, Y_{i}\right), F X_{j}\right)=g\left(h\left(X_{i}, X_{j}\right), F Y_{i}\right)=0 \tag{2.8}
\end{equation*}
$$

for vectors $X_{i}, Y_{i} \in L_{i}, X_{j} \in L_{j}, 1 \leq i \neq j \leq k$.
If $n_{1}+\cdots+n_{k}=n$, then $k \geq 2$ by the definition of $\mathcal{S}(n)$. In this case, (1.8), (1.9) and (2.8) imply that the second fundamental form of $M$ satisfies

$$
\begin{gather*}
h\left(L_{i}, L_{i}\right) \subset F\left(L_{i}\right), \quad h\left(L_{i}, L_{j}\right)=0  \tag{2.9}\\
\operatorname{tr}_{L_{i}} h=0, \quad i, j=1, \ldots, k \tag{2.10}
\end{gather*}
$$

If $n_{1}+\cdots+n_{k}<n$, then (1.8) implies that, for any $t \in\left\{n_{1}+\cdots+\right.$ $\left.n_{k}+1, \ldots, n\right\}$ and any $j \neq t$, we have

$$
\begin{equation*}
g\left(A_{F e_{t}} e_{i}, e_{j}\right)=g\left(A_{F e_{i}} e_{t}, e_{j}\right)=0 \tag{2.11}
\end{equation*}
$$

By using (2.11) and (1.9) with $\xi=F e_{t}$, we also obtain $g\left(A_{F e_{t}} e_{t}, e_{t}\right)=$ 0 . Hence, $A_{F e_{t}}=0$ for each $t \in\left\{n_{1}+\cdots+n_{k}+1, \ldots, n\right\}$. Thus, we obtain (2.9), (2.10) and

$$
\begin{equation*}
h\left(X, e_{n_{1}+\cdots+n_{k}+1}\right)=\cdots=h\left(X, e_{n}\right)=0, \quad \forall X \in T_{p} M \tag{2.12}
\end{equation*}
$$

Therefore, in both cases, $H(p)=0$.
3. Obstructions to ideal slant immersions. In this section we will prove the nonexistenceness of $n$-dimensional ideal Kaehlerian slant submanifolds in an $n$-dimensional complex hyperbolic space with full first normal bundle.

First, we state the following.

Proposition 3.1. Every minimal slant submanifold of a hyperbolic complex space form is irreducible.

Proof. Assume that $M$ is an $n$-dimensional reducible slant submanifold of an $m$-dimensional complex space form $\widetilde{M}(4 c)$, with $c<0$. Then, locally, $M$ is the Riemannian product of some Riemannian manifolds, say $M=N_{1} \times \cdots \times N_{s}, s \geq 2$. If $\operatorname{dim} N_{1}=a$, then we can choose an orthonormal basis $\left\{e_{1}, \ldots, e_{n}\right\}$ such that $e_{1}, \ldots, e_{a}$ are tangent to $N_{1}$ and $e_{a+1}, \ldots, e_{n}$ are tangent to $N_{2} \times \cdots \times N_{s}$. Since $M$ is minimal, the Gauss equation yields

$$
\begin{aligned}
0 & =\sum_{i=1}^{a} \sum_{j=a+1}^{n} R\left(e_{i}, e_{j}, e_{i}, e_{j}\right) \\
& =a(n-a)\left(1+3 \cos ^{2} \theta\right) c-\left\|\sum_{i=1}^{a} h\left(e_{i}, e_{i}\right)\right\|^{2}-\sum_{i=1}^{a} \sum_{j=a+1}^{n}\left\|h\left(e_{i}, e_{j}\right)\right\|^{2}
\end{aligned}
$$

which is impossible.

Recall that the first normal space $\operatorname{Im} h_{p}$ and the relative null space Ker $h_{p}$ of a submanifold $M$ at a point $p \in M$ are the vector spaces defined respectively by

$$
\begin{aligned}
\operatorname{Im} h_{p} & =\operatorname{sp}\left\{h(X, Y) \mid X, Y \in T_{p} M\right\} \\
\operatorname{Ker} h_{p} & =\left\{Z \in T_{p} M \mid h(X, Z)=0, \forall X \in T_{p} M\right\}
\end{aligned}
$$

It is easily seen that the first normal space $\operatorname{Im} h_{p}$ and the relative null space $\operatorname{Ker} h_{p}$ of a Kaehlerian slant submanifold $M$ in a complex space form $\widetilde{M}(4 c)$ are related by $\left(\operatorname{Im} h_{p}\right)^{\perp}=F\left(\operatorname{Ker} h_{p}\right)$.

For an ideal $n$-dimensional Kaehlerian slant submanifold $M$ in an $n$ dimensional complex space form $\widetilde{M}(4 c)$ satisfying (2.3), we denote by $\mathcal{D}_{i}$ the distribution generated by $L_{i}$, where $L_{i}$ is defined by (2.4).

The following lemma implies the integrability and the minimality of the distributions $\mathcal{D}_{1}, \ldots, \mathcal{D}_{k}$.

Lemma 3.2. Let $M$ be an $n$-dimensional ideal Kaehlerian slant submanifold of an $n$-dimensional complex space form $\widetilde{M}(4 c)$ satisfying the equality (2.3) identically. If the first normal bundle of $M$ is full, then

$$
\begin{equation*}
n_{1}+\cdots+n_{k}=n \tag{3.1}
\end{equation*}
$$

$$
\begin{gather*}
h\left(\mathcal{D}_{i}, \mathcal{D}_{i}\right)=F\left(\mathcal{D}_{i}\right), \quad h\left(\mathcal{D}_{i}, \mathcal{D}_{j}\right)=\{0\}, \quad 1 \leq i \neq j \leq k  \tag{3.2}\\
\nabla_{Y_{j}} X_{i} \in \mathcal{D}_{i} \oplus \mathcal{D}_{j}, \quad 1 \leq i \neq j \leq k \tag{3.3}
\end{gather*}
$$

for vector fields $X_{i}$ in $\mathcal{D}_{i}$ and $Y_{j}$ in $\mathcal{D}_{j}$, respectively. Moreover, $\mathcal{D}_{1}, \ldots, \mathcal{D}_{k}$ are completely integrable distributions and the leaves of $\mathcal{D}_{1}, \ldots, \mathcal{D}_{k}$ are totally geodesic submanifolds in $M$ and minimal submanifolds in $\widetilde{M}(4 c)$, respectively.

This lemma follows from the equation of Codazzi like Lemmas 4 and 11 in [5] for ideal Lagrangian submanifolds in complex space forms. For an elegant simple proof of Lemma 11, see also [6]. So, we omit the proof of Lemma 3.2.

Using the above results, we will obtain a nonexistence theorem for certain ideal slant submanifolds.

Theorem 3.3. There do not exist n-dimensional ideal Kaehlerian slant submanifolds in an n-dimensional complex hyperbolic space whose first normal bundle is full.

Proof. We assume $M$ is an $n$-dimensional ideal Kaehlerian slant submanifold in an $n$-dimensional complex hyperbolic space $H^{n}$. Then it satisfies the equality (2.3) for some $k$-tuple $\left(n_{1}, \ldots, n_{k}\right) \in \mathcal{S}(n)$. If the first normal bundle is full, then $n_{1}+\cdots+n_{k}=n$ and $k \geq 2$. Hence, the tangent bundle $T M$ of $M$ is the direct sum $\mathcal{D}_{1} \oplus \cdots \oplus$ $\mathcal{D}_{k}$. According to Lemma 3.2, each $\mathcal{D}_{i}$ is an integrable distribution with totally geodesic leaves. Moreover, by the form (1.8) of the shape operators of an ideal submanifold, any sum $\mathcal{D}_{j_{1}} \oplus \cdots \oplus \mathcal{D}_{j_{s}}$, $s \in\{2, \ldots, k\}$ is also an integrable distribution with totally geodesic leaves. Therefore, de Rham's decomposition theorem implies that $M$ is locally the Riemannian product of $k$ Riemannian manifolds $M_{1}, \ldots, M_{k}$ of dimensions $n_{1}, \ldots, n_{k}$, respectively, where $M_{i}$ is an integral submanifold of $\mathcal{D}_{i}$. Thus, $M$ is a reducible Riemannian manifold. By applying Theorem 2.1, we know that the submanifold $M$ is minimal. Hence, by using Proposition 3.1, we obtain the desired result.

On the other hand, there do exist $n$-dimensional ideal Kaehlerian slant submanifolds in the complex Euclidean space $\mathbf{C}^{n}$ with full first normal bundle. In fact, we have the following.

Theorem 3.4. Let $M$ be an n-dimensional Kaehlerian slant submanifold in $\mathbf{C}^{n}$ with full first normal bundle. Then $M$ is ideal if and only if, locally, $M$ is the Riemannian product of some minimal Kaehlerian slant submanifolds $M_{j}, j=1, \ldots, k$, with full first normal bundle.

Proof. Let $x: M \rightarrow \mathbf{C}^{n} \cong \mathbf{R}^{2 n}$ be an ideal Kaehlerian slant immersion with full first normal bundle. Moore's lemma [10] implies that $x$ is a product immersion, say

$$
x=x_{1} \times \cdots \times x_{k}: M_{1} \times \cdots \times M_{k} \rightarrow \mathbf{R}^{N_{1}} \times \cdots \times \mathbf{R}^{N_{k}}=\mathbf{R}^{2 n}
$$

where each $x_{j}: M_{j} \rightarrow \mathbf{R}^{N_{j}}$ is an isometric immersion and $\operatorname{dim} M_{j}=n_{j}$.
By the first equation (3.2), we have $h\left(\mathcal{D}_{j}, \mathcal{D}_{j}\right)=F\left(\mathcal{D}_{j}\right)$, for each $j \in\{1, \ldots, k\}$. Then each $\mathbf{R}^{N_{j}}$ must contain a $2 n_{j}$-dimensional subspace $\mathbf{R}^{2 n_{j}}$ of $\mathbf{R}^{2 n}$. Therefore, we have $N_{j}=2 n_{j}$, for $j=1, \ldots, k$. It follows by Lemma 3.2 that the first normal bundle of each $M_{j}$ is full. Moreover, each $M_{j}$ is a minimal submanifold. Consequently, the ideal submanifold $M$ is, locally, the Riemannian product of some minimal Kaehlerian slant submanifolds.

The converse statement is clear.

We state a theorem of characterization of ideal Kaehlerian slant submanifolds in the complex Euclidean space.

Theorem 3.5. Let $M$ be an $n$-dimensional Kaehlerian slant submanifold of the complex Euclidean space $\mathbf{C}^{n}$ such that $\operatorname{Im} h_{p} \neq T_{p}^{\perp} M$, at each point $p \in M$. Then $M$ is ideal if and only if $M$ is a ruled minimal submanifold.

Proof. Let $M$ be an $n$-dimensional ideal Kaehlerian slant submanifold in $\mathbf{C}^{n}$. Then, by Theorem 2.1, $M$ is a minimal submanifold.

Let $U_{l}$ denote the interior of the subset consisting of points in $M$ such that the relative null space at $p$ has dimension $l$. Since $\operatorname{Im} h_{p} \neq T_{p}^{\perp} M$,
at each point $p \in M$, it follows that $U_{l} \neq \varnothing$, for some integer $1 \leq l \leq n$. By applying Codazzi equation, it is easily seen that $\operatorname{Ker} h$ is integrable on $U_{l}$ and each leaf of $\left.(\operatorname{Ker} h)\right|_{U_{l}}$ is an $l$-dimensional totally geodesic submanifold of $\mathbf{C}^{n}$. Thus, $M$ contains a geodesic of $\mathbf{C}^{n}$ through each point $p \in U_{l}$. Since $M$ is the union of the closure of all $U_{l}$, we conclude by continuity that $M$ contains a geodesic of the ambient space through each point in $M$. Therefore, $M$ is a ruled minimal submanifold.

The converse statement is obvious.

Note added in proof. After the acceptance for publication of this article, we discovered a very recent paper of I. Salavessa [12]. By combining Proposition 1.2 of [12] and Theorem 2.1 of this article, we have the following nonexistence result.

Theorem 3.6. There do not exist n-dimensional ideal Kaehlerian slant submanifolds in the complex projective space $P^{n}(\mathbf{C})$.

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University of Bucharest, Str. Academiei 14, 70109 Bucharest, Romania E-mail address: imihai@fmi.unibuc.ro


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