## A REMARK ON SIMPLE PATH FIELDS IN POLYHEDRA OF CHARACTERISTIC ZERO

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1. Introduction. A path field $\varphi$ on a space $X$ is a map $\varphi: X \rightarrow X^{I}$ such that $\varphi(x)(0)=x, x \in X$, and if $\varphi(x)(t)=x$ for $t>0$ then $\varphi(x)$ is the constant path. $\varphi$ is non-singular if $\varphi(x)$ is never the constant path. A non-singular path field $\varphi$ is simple if $\varphi(x)$ is a simple are for each $x$. Differentiable manifolds of (Euler) characteristic zero admit simple path fields while topological manifolds of characteristic zero are known to admit non-singular path fields [1]. The existence of simple path fields in the topological category is an open question. The purpose of this note is to observe that in the case of triangulated manifolds of characteristic zero it is easy to find a simple path field. In fact, every polyhedron $K$ satisfying the so-called Wecken condition of characteristic zero admits a simple path field $\varphi$ such that the track of $\varphi(x)$ is a broken line segment.
2. Preliminaries. Let $K$ denote a finite polyhedron. We will not distinguish in the notation between $K$ as a simplicial complex and $K$ as the underlying space. If $x$ is a point of $K$, then $\sigma(x)$ is the unique (open) simplex of $K$ which contains $x$. Furthermore, if $\Delta$ represents the diagonal in $K \times K$, there is a special neighborhood of $\Delta$ given by

$$
\begin{equation*}
\eta(\Delta)=\{(x, y): \boldsymbol{\sigma}(x) \text { and } \boldsymbol{\sigma}(y) \text { have a common vertex }\} . \tag{1}
\end{equation*}
$$

Each point $x \in K$ also has a special neighborhood defined by

$$
\begin{equation*}
V(x)=\{y:(x, y) \in \eta(\Delta)\} \tag{2}
\end{equation*}
$$

Following R. F. Brown [2], we call a map $f: K \rightarrow K$ a proximity map if $f(x) \in V(x)$ for all $x \in K$.

If $a, b$ are points of $K$ in the same closed simplex, then $[a, b]$ will denote the segment from $a$ to $b$. The following lemma is a somewhat stronger version of a lemma contained in [2] and [3]. The proof is the same except for additional observations.

Lemma 2.1. There exists a map $\alpha: \eta(\Delta) \rightarrow K^{I}$ such that
(1) $\boldsymbol{\alpha}(x, y)$ is a path from $x$ to $y$,
(2) $\boldsymbol{\alpha}(x, x)$ is the constant path at $x$,
(3) the track of $\alpha(x, y)$ has the form

$$
\begin{aligned}
& {[x, z] \cup[z, y]} \\
& \text { where } z=z(x, y),
\end{aligned}
$$

(4) $\boldsymbol{\alpha}(y, x)$ is the reverse of $\boldsymbol{\alpha}(x, y)$, i.e.,

$$
\alpha(y, x)(t)=\boldsymbol{\alpha}(x, y)(1-t), \text { and }
$$

(5) if $x \neq y, \alpha(x, y)$ is a simple path.

Proof. Following [2] and [3] we assume $K$ is realized in some Euclidean space and each $x \in K$ is provided with coordinates, i.e.,

$$
\begin{equation*}
x=\Sigma \lambda_{j} v_{j}, \lambda_{j} \geqq 0, \Sigma \lambda_{j}=1 \tag{3}
\end{equation*}
$$

where $v_{1}, \cdots, v_{n}$ are the vertices of $K$. If $y=\Sigma \mu_{j} v_{j}$, set

$$
\begin{equation*}
\beta=\beta(x, y)=\Sigma\left(\lambda_{j} \mu_{j}\right)^{1 / 2} \tag{4}
\end{equation*}
$$

and

$$
\begin{equation*}
z=z(x, y)=(1 / \beta) \Sigma\left(\lambda_{j} \mu_{j}\right)^{1 / 2} v_{j} \tag{5}
\end{equation*}
$$

A simple argument shows that

$$
\begin{equation*}
[x, z] \cap[z, y]=z,(x, y) \in \eta(\Delta) \tag{6}
\end{equation*}
$$

Assuming that $K$ is simplicially imbedded in some Euclidean space with the usual metric $d$, define

$$
\ell(w)= \begin{cases}d(x, w), & w \in[x, z]  \tag{7}\\ d(x, z)+d(z, w), w \in[z, y]\end{cases}
$$

and parametrize $[x, z] \cup[z, y]$ with a map

$$
\begin{equation*}
\alpha(x, y): I \rightarrow K,(x, y) \in \eta(\Delta) \tag{8}
\end{equation*}
$$

characterized by

$$
\begin{equation*}
\ell(\boldsymbol{\alpha}(x, y)(t))=t \ell(\boldsymbol{\alpha}(x, y)(1)) ; \tag{9}
\end{equation*}
$$

then

$$
\begin{equation*}
\alpha: \eta(\Delta) \rightarrow K^{I} \tag{10}
\end{equation*}
$$

is the required map. The fact that $\alpha(x, y)$ is a simple path when $x \neq y$ is an immediate consequence of (6). The symmetry (4) is proved as
follows. Let $\ell$ denote the length function (7) along $[x, z] \cup[z, y]$ and $\ell^{\prime}$ the length function along $[y, z] \cup[z, x]$. Then, $\alpha(x, y)(t)$ and $\alpha(y, x)(1-t)$ are characterized by

$$
\begin{gather*}
\ell(\alpha(x, y)(t))=t \ell(\boldsymbol{\alpha}(x, y)(1))=t \ell(y)  \tag{11}\\
\ell^{\prime}\left(\alpha(y, x)(1-t)=(1-t) \ell^{\prime}(\alpha(y, x)(1))=(1-t) \ell^{\prime}(x)\right. \tag{12}
\end{gather*}
$$

where $\ell(y)=\ell^{\prime}(x)$. Since

$$
\begin{equation*}
\ell(\boldsymbol{\alpha}(x, y)(t))+\ell^{\prime}(\boldsymbol{\alpha}(x, y)(t))=\ell^{\prime}(x)=\ell(y) \tag{13}
\end{equation*}
$$

we have

$$
\begin{equation*}
\ell^{\prime}(\boldsymbol{\alpha}(x, y)(t))=\ell^{\prime}(x)-t \ell^{\prime}(x)=(1-t) \ell^{\prime}(x) \tag{14}
\end{equation*}
$$

and, finally,

$$
\begin{equation*}
\boldsymbol{\alpha}(x, y)(t)=\boldsymbol{\alpha}(y, x)(1-t), 0 \leqq t \leqq 1 \tag{15}
\end{equation*}
$$

3. The Observation. First we recall that a polyhedron $K$ satisfied the Wecken conditions if every maximal simplex has dimension $\geqq 2$ and given maximal simplices $\boldsymbol{\sigma}$ and $\boldsymbol{\tau}$ there is a sequence of maximal simplices $\sigma_{1}, \cdots, \sigma_{k}$ such that $\sigma_{1}=\sigma, \quad \sigma_{k}=\tau \quad$ and $\sigma_{i} \cap \sigma_{i+1}$ has dimension $\geqq 1, i=1, \cdots, k-1$.

The following theorem is implicit in [2] or [3]. It is only necessary to observe that at each stage of the proof, one always obtains proximity maps.

Theorem 3.1. Let $K$ denote a polyhedron which satisfies the Wecken condition. Then, there exists a proximity map $f: K \rightarrow K$ which has no fixed points if $\chi(K)=0$ and exactly one fixed point if $\chi(K) \neq 0$.

Observation 3.2. Let $K$ denote a polyhedron which satisfies the Wecken condition. Then, if $K$ has characteristic $\chi(K)=0, K$ admits a simple path field $\varphi: K \rightarrow K^{I}$ such that the track of $\varphi(x)$ is a broken segment for every $x \in K$. [If $\chi(K) \neq 0, \varphi(x)$ is simple for all but one point.]

Proof. Let $f$ denote the map in Theorem 3.1 and let $\varphi(x)=$ $\alpha(x, f(x))$, for $x \in K$, where $\alpha$ is as in Lemma 2.1.

## Bibliography

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