

On the existence of transversal homoclinic points of some real analytic plane transformation

By

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0. Introduction

In this paper we shall consider the following real analytic plane transformation f :

$$\begin{aligned}f(x, y) &= (y + \zeta(x), x), \\f^{-1}(x, y) &= (y, x - \zeta(y)),\end{aligned}$$

where ζ is a real analytic function belonging to X which will be define in Section 5 below. X is not vacant. For example $\zeta(x) = cx(1-x)$ ($c > 0$) is in X .

The differential of f is

$$df_{(x,y)} = \begin{pmatrix} \zeta'(x) & 1 \\ 1 & 0 \end{pmatrix}$$

(x_0, y_0) is a fixed point if and only if $x_0 = y_0$ and $\zeta(x_0) = 0$. Also, it is hyperbolic if and only if $\zeta'(x_0) \neq 0$.

By the parallel transformation along the line $x = y$, its form is invariant ($\zeta(x)$ tends to $\zeta(x-a)$).

We assume $0 = (0, 0)$ to be a hyperbolic fixed point. The eigenvalue λ of df_0 satisfies following equation:

$$\lambda^2 - \zeta'(0)\lambda - 1 = 0.$$

Let s be the reflection with respect to the line $x + y = 1$:

$$s(x, y) = (1 - y, 1 - x).$$

Conjugating f by s , we get

$$sfs^{-1} = (y, x - \zeta(1 - y)).$$

The identity $sfs^{-1} = f^{-1}$ holds if and only if ζ satisfies the following functional equation:

$$\zeta(1-x) = \zeta(x).$$

Under this symmetricity, we consider the heteroclinic point $g(t_0^+)$ (resp. $g(t_0^-)$) on the line $x+y=1$ between unstable (resp. stable) manifold g through $(0, 0)$ and stable (resp. unstable) manifold $s \cdot g$ through $(1, 1)$. (See S. Ushiki [2].)

In the case $\zeta(x) = cx(1-x)$, we shall show that each of two heteroclinic points $g(t_0^+)$ and $g(t_0^-)$ is transversal, if $|c| > 2\sqrt{2}$. Two transversal heteroclinic points imply transversal homoclinic points. The heteroclinic point $g(t_0^+)$ is always transversal except for isolated values of $c \neq 0$.

Remark. This transformation f is obtained by central difference scheme of the following ordinary differential equation:

$$\frac{dx}{dt} = \zeta(x).$$

1. Stable (unstable) manifold theorem

Next is a definition of stable and unstable manifold (See S. Smale [3], C. L. Siegel [5] and S. Ushiki [2]).

Definition 1-1. There exists a real analytic embedding $g = (\alpha, \beta)$ from line to plane such that

$$g(0) = 0,$$

$$g(\lambda t) = f(g(t)),$$

where λ is an eigenvalue of df_0 . And g is uniquely determined by $\alpha'(0)$. We say that g is stable (resp. unstable) if $|\lambda| < 1$ (resp. $|\lambda| > 1$).

The pair (α, β) satisfies the following equations:

$$\alpha(0) = 0,$$

$$\alpha(\lambda t) - \alpha(t/\lambda) = \zeta(\alpha(t)),$$

$$\beta(t) = \alpha(t/\lambda).$$

Let expand α and ζ into the power series:

$$\alpha(t) = \sum_{n=1}^{\infty} \alpha_n t^n,$$

$$\zeta(x) = \sum_{n=1}^{\infty} \zeta_n x^n.$$

Combining the previous relations and comparing the coefficients of t , we obtain

$$(\lambda^2 - \zeta_1 \lambda - 1)\alpha_1 = 0.$$

Looking at the coefficient of t^n ($n \geq 2$), we get

$$\alpha_n = \frac{\lambda}{\lambda^{2n} - \xi_1 \lambda^n - 1} \sum_{2 \leq m \leq n} \xi_m \left(\sum_{i_1 + \dots + i_m = n} \alpha_{i_1} \dots \alpha_{i_m} \right).$$

It is clear that α_n is uniquely determined by $\alpha_1, \dots, \alpha_{n-1}$.

It is easy to check the convergency of α when ξ is convergent.

Local existence of g implies global existence of g , because of the functional equation. It is trivial that g is embedding.

Remark 1. If $\lambda > 0$, we have a majorant function:

$$\bar{\alpha}(t) = \frac{t}{1-rt} \text{ and}$$

$$\bar{\xi}(x) = \frac{x}{1-r(\lambda-1)x} - \frac{1}{\lambda} \frac{x}{1-r(1/\lambda-1)x},$$

where r is sufficiently large.

(Since $\bar{\alpha}$ is a linear fractional function, $\bar{\xi}$ exists.)

Remark 2. In the case $\xi(x) = cx(1-x)$, we can show that the function $\alpha(t)$ ($t < 0, \lambda > 0$) is monotone by using induction on α_n .

2. Function α .

λ and α have been defined in Section 1.

Theorem 2-1. Let I be an interval including 0 on which ξ is monotone and convex (resp. concave). If $\lambda > 1$, then α is monotone and convex (resp. concave) on $\lambda \cdot J$ and if $0 < \lambda < 1$, then α is monotone concave (resp. convex) on $\frac{1}{\lambda} J$ where J is the connected component of 0 in $\alpha^{-1}(I)$. If λ is negative, then α is monotone on K where K is some connected interval including 0 such that I does not contain $\alpha(K)$.

Remark. In this paper, we say that v is monotone (resp. convex, concave) if v is strictly monotone (resp. convex, concave), namely $v''(x) \neq 0$ (resp. $v''(x) > 0, v''(x) < 0$) on some interval.

Proof. We can derive the next equation from the functional equation of α in the proof of theorem 1-1,

$$\lambda \alpha'(\lambda t) - \frac{1}{\lambda} \alpha'(t/\lambda) = \alpha'(t) \xi'(\alpha(t)).$$

If $\lambda > 1$, then $\xi'(x) > 0$ on I . From the above functional equation, $\alpha'(t/\lambda) \geq 0$ and $\alpha'(t) \geq 0$ imply $\alpha'(\lambda t) \geq 0$. Then α is monotone on λJ .

We can prove the monotonicity of α in the cases $0 < \lambda < 1, -1 < \lambda < 0$ and $\lambda < -1$ by using similar methods.

From the functional equation of α' , we obtain

$$\lambda^2 \alpha''(\lambda t) - \frac{1}{\lambda^2} \alpha''(t/\lambda) = \alpha''(t) \xi'(\alpha(t)) + (\alpha'(t))^2 \xi''(\alpha(t)).$$

Let $t=0$ and $\xi'(0)=\lambda - \frac{1}{\lambda}$, then

$$\{(\lambda - 1/2)^2 - (1/\lambda - 1/2)^2\}\alpha''(0) = (\alpha'(0))^2\xi''(0).$$

If $\lambda > 1$, then $\xi'(x) > 0$ on I and $\alpha''(0)$ has the same sign with $\xi''(0)$. From the above functional equation of α'' , we conclude that $\alpha''(t/\lambda) \geq 0$, $\alpha''(t) \geq 0$ and $\xi''(x) \geq 0$ imply $\alpha''(\lambda t) \geq 0$. Then $\alpha''(t) \geq 0$ on λJ . We can prove the same things in the case $0 < \lambda < 1$ by the same way.

3. Zero of γ

From now on, we suppose that $\alpha'(0) = 1$.

We define a function γ follows:

$$\gamma(t) = \alpha(t) + \beta(t) - 1 = \alpha(t) + \alpha(t/\lambda) - 1.$$

Remark 1. α , β and γ are dependent on ξ and on sign of λ .

Theorem 3-1. *We assume λ to be positive. If $\xi(x)$ is positive on $(0, 1)$, then $\gamma(t)$ has a zero on $(0, \infty)$.*

Remark 2. Considering f^{-1} instead of f , we can obtain another sufficient condition.

Proof. See [2]. Consider the region:

$$\{(x, y) | x > 0, y > 0 \text{ and } x + y < 1\},$$

and the function $x + y$ with respect of f , then $g(t > 0)$ intersects the line $x + y = 1$.

Theorem 3-2. *We assume λ to be negative. If $\xi(x)$ is positive on $(0, 1)$ and $\xi(x)$ is negative on $(-\infty, 0)$ and $\xi'(x) < 1$ on $[1, \infty)$, then $\gamma(t)$ has zero's on $(-\infty, 0)$ and on $(0, \infty)$.*

Proof. First consider the region:

$$\{(x, y) | x < 0 \text{ and } 0 < y < 1\}$$

and the functions x and y with respect to f^{-2} :

$$f^{-2} = (x - \xi(y), y - \xi(x - \xi(y))).$$

Then $g(t < 0)$ intersects the line $y = 1$. Next consider the region:

$$\{(x, y) | x + y - \xi(y) < 1 \text{ and } y > 1\}$$

and the functions x and y with respect to f^{-2} . Then $g(t < 0)$ intersects the curve $x + y - \xi(y) = 1$. This curve is the image of the line $x + y = 1$ by f . So $g(t > 0)$ intersects the line $x + y = 1$.

We can show that $g(t < 0)$ intersects the line $x + y = 1$ in the same way.

Remark. Let t_0 be a zero of γ . If ξ satisfies the functional equation $\xi(x) = \xi(1-x)$, then $g(t_0)$ is a heteroclinic point between $(0, 0)$ and $(1, 1)$.

4. The value $\delta(t_0^+)$ and $\delta(t_0^-)$.

Let t_0^+ (resp. t_0^-) be the minimum (resp. maximum) zero of γ on $(0, \infty)$ (resp. $-\infty, 0)$). This is well defined because $\gamma(0) = -1$.

We introduce a function δ as follows:

$$\delta(t) = \frac{\beta'(t)}{\alpha'(t)} = \frac{1}{\lambda} \frac{\alpha'(t/\lambda)}{\alpha'(t)},$$

where δ means the inclination of stable (resp. unstable) curve at point $g(t)$. From the functional equation of α' , δ satisfies

$$\frac{1}{\delta(\lambda t)} - \delta(t) = \xi'(\alpha(t)).$$

Theorem 4-1. We assume λ to be positive. If ξ is a concave monotone increasing function on $I = [0, 1/2)$ and there exists a point (d, e) such that

$$d + e + \xi(d) = 1,$$

$$e = \frac{1}{\lambda} d,$$

$$0 < d < \frac{1}{2} \quad \text{and}$$

$$\frac{1}{\lambda} + \xi'(d) > 1,$$

then $1/\lambda < \delta(t_0^+) < 1$.

Remark. Point (d, e) is unique if exists.

Proof. From theorem 2-1 and $\alpha'(0) = 1$, α is a concave monotone increasing function on $\lambda \cdot J$.

$$\delta(t) = \frac{1}{\lambda} \frac{\alpha'(t/\lambda)}{\alpha'(t)} > \frac{1}{\lambda} \quad \text{on } \lambda \cdot J.$$

Integrating this inequality, we can show that $g(\lambda \cdot J)$ lies above the line $y = \frac{1}{\lambda} x$. $g(J)$ intersects the curve $x + y + \xi(x) = 1$ because $d < 1/2$ and $-1 - \xi'(x) < 0$ on I . And this intersection is really $g(t_0^+/\lambda)$ because α is monotone on J . t_0^+ is on $\lambda \cdot J$.

$$\delta(t_0^+) > \frac{1}{\lambda}.$$

ξ is concave on I and $\alpha(t_0^+/\lambda) < d < 1/2$.

$$\delta(t_0^+/\lambda) + \xi'(\alpha(t_0^+/\lambda)) > \frac{1}{\lambda} + \xi'(d) > 1.$$

From the functional equation of δ , we get

$$\delta(t_0^+) = \frac{1}{\delta(t_0^+/\lambda) + \xi'(\alpha(t_0^+/\lambda))} < 1.$$

Theorem 4-2. We assume λ to be negative. If ξ is concave monotone increasing function on $I = (-\infty, 1/2)$ and there exists a point (d, e) such that

$$d + e + \xi(d) = 1,$$

$$d + e - \xi(e) = 1,$$

$$0 < d < 1/2 \quad \text{and}$$

$$e < 0,$$

then $\delta(t_0^-) < 1/\lambda < 1$.

Proof. From the functional equation of δ :

$$\delta(t) = \frac{1}{\frac{1}{\delta(\lambda^2 t)} - \xi'(\alpha(\lambda t))} - \xi'(\alpha(t)),$$

$\delta(0) = 1/\lambda < \delta(\lambda^2 t) < 0$ implies $1/\lambda < \delta(t) < 0$ on L where L is an interval in K and $\alpha(L) = (0, 1/2)$. Because $I = (-\infty, 1/2)$ $\alpha(K)$ contains $(0, 1/2)$. Inequality $1/\lambda < \delta(t)$ holds in some neighbourhood of origin because $\xi'(0) < 0$.

Consider the following region:

$$\{(x, y) \mid x + y + \xi(x) < 1, x + y - \xi(y) < 1, x > 0 \text{ and } y < 0\}.$$

$g(L)$ intersects the curve $x + y - \xi(y) = 1$ because $d < 1/2$. And this intersection is really $g(\lambda t_0^-)$ because α is monotone on L . So,

$$\delta(t_0^-) = \frac{1}{\delta(\lambda t_0^-)} - \xi'(\alpha(t_0^-)) < \frac{1}{\delta(0)} - \xi'(0) = \frac{1}{\lambda}.$$

Remark. Let t_0 be a zero of γ such that $|\delta(t_0)| \neq 1$. If ξ satisfies the functional equation $\xi(x) = \xi(1-x)$, then $f(t_0)$ is a transversal heteroclinic point.

Example. In the case $\xi(x) = cx(1-x)$, f has a transversal homoclinic point if $|c| > 2\sqrt{2}$. (Check the sufficient conditions of Theorem 4-1 and 4-2.)

5. Shift of ξ_0

Let X be the set of all real analytic functions ξ that satisfy the following four conditions:

$$\xi(x) = \xi(1-x),$$

$$\xi(0) = 0$$

$$\xi'(x) > 0 \quad \text{on } (-\infty, 1/2) \quad \text{and}$$

$$\xi''(x) < 0 \quad \text{on} \quad (-\infty, 1/2).$$

We introduce a shift ξ for a given function ξ_0 in X by the following way.

$$\xi(u, x) = u\xi_0(x) \quad (u > 0).$$

In this section the letter u express a positive number. For any u , $\xi(u, x)$ belongs to X because X is a cone.

We consider the following parameterized plane transformation:

$$f(u, x, y) = (y + \xi(u, x), x).$$

f has a heteroclinic point for any u (See Section 3), and f has a transversal heteroclinic point for large u (See Section 4).

We can recognize α , β , γ and δ as a real analytic function of t and u (See Section 1). And we can also recognize $t_0(t_0^+, t_0^-)$ as a real analytic variety defined by γ (subvariety of t_0) in t - u plane.

Conjecture. f has a transversal heteroclinic point except for isolated value of u .

If there exists a union of irreducible components of t_0 such that projection from it to u line is surjective and if δ is not constant on each of them, then the conjecture is true because of the theorem of identity.

Moreover, if $\delta \neq -1$ everywhere and $\delta \neq 1$ on it, then it is irreducible and the conjecture is true.

Example. In the case $\xi = ux(1-x)$ ($\lambda > 0$), the conjecture is true. Projection from t_0^+ to u line is surjective (Theorem 3-1). $\delta \neq -1$ on t_0^+ everywhere. Under the same aspect with theorem 4-1, we only have to check that there exists a point (d, e) such that

$$d + e + \xi(d) = 1,$$

$$e = \frac{1}{\lambda} d \quad \text{and}$$

$$0 < d < \frac{1}{2}$$

for any u . This is an absolute inequality. And $\delta \neq 1$ on t_0^+ (Theorem 4-1).

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$$f(x, y) = (y + cx(1-x), x),$$

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