IRREDUCIBLE VECTOR-VALUED MODULAR FORMS OF DIMENSION LESS THAN SIX

CHRISTOPHER MARKS

ABSTRACT. An algebraic classification is given for spaces of holomorphic vector-valued modular forms of arbitrary real weight and multiplier system, associated to irreducible, *T*-unitarizable representations of the full modular group, of dimension less than six. For representations of dimension less than four, it is shown that the associated space of vector-valued modular forms is a cyclic module over a certain skew polynomial ring of differential operators. For dimensions four and five, a complete list of possible Hilbert–Poincaré series is given, using the fact that the space of vector-valued modular forms is a free module over the ring of classical modular forms for the full modular group. A mild restriction is then placed on the class of representation considered in these dimensions, and this again yields an explicit determination of the associated Hilbert–Poincaré series.

1. Introduction

The general theory of vector-valued modular forms is now well-established in the literature, largely due to the efforts of Knopp/Mason [7], [8], [9], [13], [14] and Bantay/Gannon [1], [2], [3], [4]. The present paper builds upon the foundation of the Knopp/Mason theory, and is in some sense a direct generalization, to higher dimension, of the main results of [14]. Specifically, we generalize Theorem 5.5, loc. cit., which gives an algebraic classification of \mathbb{Z} -graded spaces of holomorphic vector-valued modular forms associated to two-dimensional irreducible, *T*-unitarizable representations of $\Gamma = SL_2(\mathbb{Z})$. This is accomplished in [14] by establishing that each such space is a cyclic module over a certain skew polynomial ring \mathcal{R} of differential operators (2.27), and a free module of rank two over the ring $\mathcal{M} = \mathbb{C}[E_4, E_6]$ of holomorphic,

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integral weight modular forms for Γ . This classification (and in particular the computation of the minimal weight associated to the space) is made possible by exploiting the theory of *modular differential equations*, as introduced in [13], together with Theorem 3.1 of [14], which classifies indecomposable, T-semi-simple representations $\rho \colon \Gamma \to GL_2(\mathbb{C})$, according to the eigenvalues of $\rho(T)$; here $T = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$.

More recently, it has been shown [12, Thm 1], [9, Thm 3.13] that this free \mathcal{M} -module structure is realized in arbitrary dimension, for an even broader class of representation than was treated in [14]. Consequently, giving an algebraic classification of spaces of vector-valued modular forms in arbitrary dimension is equivalent to determining the weights of the free generators for the \mathcal{M} -module structure of the given spaces, including the all-important minimal weight. Furthermore, Theorem 3 of [12] gives an equivalence between the cyclicity of an \mathcal{R} -module of vector-valued modular forms, and the existence of a certain monic modular differential equation. This is significant because cyclic \mathcal{R} -modules exhibit the simplest \mathcal{M} -module structure possible and, even more importantly, the minimal weight can be determined explicitly in these cases.

Because of these advances, it is quite natural to try and generalize the techniques used in [14] to arbitrary dimension (in fact, the main results of this paper were established *before* [12] was written (cf. [11]) and formed the initial evidence which led to Theorems 1 and 3 in [12]). What one requires for this task is a higher dimension analogue of Theorem 3.1 of [14], that is, one needs to classify indecomposable, T-unitarizable representations of Γ in arbitrary dimension. Unfortunately, very little is known about the representation theory of Γ , even in the irreducible setting. A notable exception is [16], which classifies irreducible representations of the braid group B_3 , of dimension less than six. As is well known, $PSL_2(\mathbb{Z}) = \Gamma/\{\pm I\}$ is isomorphic to the quotient of B_3 by its (infinite cyclic) center, and the Main theorem of [16], when translated into the modular setting (Theorem 5.6 below), serves as the desired generalization of [14, Thm 3.1]. This result is, to our knowledge, the strongest such generalization that exists in the literature and, furthermore (as can be seen in the Appendix below), dimension five is in any event a natural boundary for the applicability of the techniques used here and in [14]. It should be noted that [16] does not address the classification of indecomposable representations of Γ , and this creates an obstruction to using the techniques of [14] (see comments following Theorem 5.6 below). For this reason, we define in Section 5 a slightly restricted class of irreducible representations of Γ , for which the theory of modular differential equations may be applied with impunity; cf. Definition 5.7 below.

The layout of the paper is quite simple. In Section 2, we define the relevant terms and review the theory of vector-valued modular forms and modular differential equations. We then proceed in subsequent sections with the algebraic classifications, on a dimension-by-dimension basis. Section 3 contains a quick and easy proof of [14, Thm 5.5], made possible by the results of [12], and requiring no knowledge of the representation theory of Γ , nor of the theory of modular differential equations. The dimension three setting is handled in a completely analogous way, and this is the content of Section 4; in particular (Theorem 4.1 below), we prove there that every irreducible, T-unitarizable $\rho: \Gamma \to GL_3(\mathbb{C})$ yields a space of holomorphic vector-valued modular forms which is cyclic as \mathcal{R} -module. In Sections 5 and 6, we first use the Free Module theorem [12, Thm 1] to determine the possible Hilbert–Poincaré series for \mathcal{M} -modules of vector-valued modular forms of dimension four and five, respectively, and then by restricting slightly to the *T*-determined representations (cf. Definition 5.7 below), we are able to give an explicit classification in these dimensions as well. Finally, we include the Appendix, containing what we find to be an interesting example from the theory of modular differential equations; among other things, this example gives another indication of the impossibility of generalizing the results of [16] to dimension greater than five.

2. Preliminaries

Let $\rho: \Gamma \to GL_d(\mathbb{C})$ denote a *d*-dimensional representation of $\Gamma = SL_2(\mathbb{Z})$, $k \in \mathbb{R}$ an arbitrary real number, and v a multiplier system in weight k (see Section 2.1 below). A function

(2.1)
$$F(z) = \begin{pmatrix} f_1(z) \\ \vdots \\ f_d(z) \end{pmatrix}$$

from the complex upper half-plane \mathbb{H} to \mathbb{C}^d is a holomorphic vector-valued modular form of weight k (for the pair (ρ, v)) if the following conditions are satisfied:

(1) Each component function $f_j : \mathbb{H} \to \mathbb{C}$ is holomorphic in \mathbb{H} , and is of moderate growth at infinity, i.e. there is an integer $N \ge 0$ such that $|f(x+iy)| < y^N$ holds for any fixed x and $y \gg 0$.

(2) For each
$$\gamma \in \Gamma$$
, $F|_k^{\upsilon} \gamma = \rho(\gamma) F$

Here $|_k^{\upsilon}$ denotes the standard "slash" action of Γ on the space \mathcal{H} of holomorphic functions $f: \mathbb{H} \to \mathbb{C}$, where for $\gamma = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \Gamma$, $z \in \mathbb{H}$ we have

(2.2)
$$f|_k^{\upsilon}\gamma(z) = \upsilon^{-1}(\gamma)(cz+d)^{-k}f\left(\frac{az+b}{cz+d}\right).$$

We write $\mathcal{H}(k,\rho,\upsilon)$ for the \mathbb{C} -linear space of weight k vector-valued modular forms for (ρ,υ) . If $\rho(-I)$ is a scalar matrix, then the space $\mathcal{H}(\rho,\upsilon)$ of holomorphic vector-valued modular forms for (ρ, v) is \mathbb{Z} -graded as

(2.3)
$$\mathcal{H}(\rho, \upsilon) = \bigoplus_{k \ge 0} \mathcal{H}(k_0 + 2k, \rho, \upsilon),$$

for some minimal weight k_0 which is congruent (mod \mathbb{Z}) to the cusp parameter of v (see Section 2.1 below), and satisfies the inequality $k_0 \geq 1 - d$ (see Corollary 2.9 below). Note that if $\rho(-I)$ is *not* a scalar matrix, then ρ necessarily decomposes into a direct sum $\rho_+ \oplus \rho_-$ of sub-representations such that $\rho_{\pm}(-I) = \pm I$ (cf. comments following Lemma 2.3 in [8]), so the assumption is merely one of convenience.

For $U \in GL_d(\mathbb{C})$, denote by ρ_U the representation $\rho_U(\gamma) = U\rho(\gamma)U^{-1}$. As usual, we say that ρ and $\rho' : \Gamma \to GL_d(\mathbb{C})$ are *equivalent*, and write $\rho \sim \rho'$, if $\rho' = \rho_U$ for some U. It is clear that in this case there is a graded isomorphism of \mathbb{C} -linear spaces

(2.4)
$$\mathcal{H}(\rho, \upsilon) \cong \mathcal{H}(\rho', \upsilon),$$
$$F \in \mathcal{H}(k, \rho, \upsilon) \quad \leftrightarrow \quad UF \in \mathcal{H}(k, \rho', \upsilon).$$

This isomorphism allows us to focus, within a given equivalence class, on representations with particularly nice properties. Along these lines, note that we consider in this paper only those ρ which are *T*-unitarizable, meaning that $\rho(T)$, $T = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$, is similar to a unitary matrix. By the above isomorphism we may, and henceforth shall, assume that

(2.5)
$$\rho(T) = \operatorname{diag}\{\mathbf{e}(r_1), \dots, \mathbf{e}(r_d)\}, \quad 0 \le r_j < 1.$$

(Here and throughout, we write the exponential of a real number r as $\mathbf{e}(r) := e^{2\pi i r}$.) Assuming this form for $\rho(T)$ ensures that the components of any $F \in \mathcal{H}(\rho, v)$ have q-expansions familiar from the classical theory of modular forms. In other words, slashing F with the T matrix and using the assumption of moderate growth shows that each component of F has the form

(2.6)
$$f_j(z) = q^{\lambda_j} \sum_{n \ge 0} a_j(n) q^n,$$

where $q = e^{2\pi i z}$, for each j we have

(2.7)
$$0 \le \lambda_j \equiv r_j + \frac{m}{12} \pmod{\mathbb{Z}},$$

and *m* denotes the cusp parameter of v (Section 2.1 below). We define an *admissible set* for (ρ, v) to be any real numbers $\{\lambda_1, \ldots, \lambda_d\}$ which satisfy (2.7). Thus, the set of leading exponents of the components of any nonzero $F \in \mathcal{H}(\rho, v)$ will, by definition, form an admissible set for (ρ, v) (but not conversely, that is, we are not claiming that *every* admissible set appears as the set of leading exponents of some F). Among all admissible sets, there is a unique one which additionally satisfies $\lambda_j < 1$ for each j; we will refer to this as the *minimal admissible set* for (ρ, v) . If $\{\lambda_1, \ldots, \lambda_d\}$ is the minimal

admissible set for (ρ, v) , then every nonzero vector $F \in \mathcal{H}(\rho, v)$ will have the form

(2.8)
$$\begin{pmatrix} q^{\lambda_1+n_1} \sum_{n \ge 0} a_1(n)q^n \\ \vdots \\ q^{\lambda_d+n_d} \sum_{n \ge 0} a_d(n)q^n \end{pmatrix},$$

where $a_j(0) \neq 0$ for each j, and the n_j are nonnegative integers.

We write $\mathcal{M} = \bigoplus_{k\geq 0} \mathcal{M}_{2k}$ for the graded ring of integral weight, holomorphic modular forms for Γ , that is, for each $k\geq 0$ we have $\mathcal{M}_{2k} = \mathcal{H}(2k, \mathbf{1}, \mathbf{1})$, where **1** denotes the trivial one-dimensional representation/multiplier system, which satisfies $\mathbf{1}(\gamma) = 1$ for each $\gamma \in \Gamma$. As is well known, $\mathcal{M} = \mathbb{C}[E_4, E_6]$ is also a graded polynomial algebra, where for each even integer $k \geq 2$ we write

$$E_k(q) = 1 - \frac{2k}{B_k} \sum_{k \ge 1} \sigma_{k-1}(n) q^n$$

for the normalized Eisenstein series in weight k; here B_k denotes the kth Bernoulli number and $\sigma_k(n) = \sum_{0 < d \mid n} d^k$. Componentwise multiplication makes $\mathcal{H}(\rho, v)$ a graded left \mathcal{M} -module, and it is clear that the isomorphism (2.4) is one of graded \mathcal{M} -modules as well as vector spaces. Regarding this structure, one of the most important results we use in this paper [12, Thm 1] is the following theorem.

THEOREM 2.1. Suppose $\rho : \Gamma \to GL_d(\mathbb{C})$ is *T*-unitarizable, such that $\rho(-I)$ is a scalar matrix, and let v be any multiplier system for Γ . Then $\mathcal{H}(\rho, v)$ is a free \mathcal{M} -module of rank d.

Theorem 2.1 implies that the data needed to describe the \mathcal{M} -module structure of the graded space (2.3) boils down to the minimal weight k_0 , together with d distinguished nonnegative integers k_1, \ldots, k_d , which give the weights $k_0 + 2k_1, \ldots, k_0 + 2k_d$ of the free generators for $\mathcal{H}(\rho, v)$. Because the generators of \mathcal{M} as graded polynomial algebra are of weights four and six, each space $\mathcal{H}(\rho, v)$ has a *Hilbert-Poincaré series* (cf. [5]) of the form

(2.9)
$$\Psi(\rho, \upsilon)(t) = \sum_{k \ge 0} \dim \mathcal{H}(k_0 + 2k, \rho, \upsilon) t^{k_0 + 2k}$$
$$= \frac{t^{k_0} (t^{2k_1} + \dots + t^{2k_d})}{(1 - t^4)(1 - t^6)}.$$

Ideally, one would like to be able to determine explicitly the Hilbert–Poincaré series of $\mathcal{H}(\rho, \upsilon)$ for a representation $\rho : \Gamma \to GL_d(\mathbb{C})$ of arbitrary dimension d, in terms of some invariants attached to the equivalence class of ρ . It seems that the crucial step in solving this problem is the determination of the minimal weight k_0 . For example, it follows from the bounds developed in the proof of [12, Thm 1] that if ρ is irreducible of dimension d and $\mathcal{H}(\rho, \upsilon)$ has minimal weight k_0 , then the weights of the *d* free generators of $\mathcal{H}(\rho, v)$ as \mathcal{M} -module must lie in the interval $[k_0, k_0 + 2(d-1)]$; in particular, there are only a finite number of possible Hilbert–Poincaré series which could describe $\mathcal{H}(\rho, v)$.

Unfortunately, it is not known how to determine the minimal weight of a graded space (2.3) for arbitrary ρ . In fact, it is not even known whether the minimal weight of $\mathcal{H}(\rho, \upsilon)$ has a universal upper bound as a function of dim ρ , although it seems likely that this is true (and in particular, when ρ is unitary this universal bound does exist, a fact which is implicit in the proof of the Main Theorem of [7]). Note, however, that in situations where one is able to exploit the existence of a vector-valued modular form arising from the solution space of a monic modular differential equation (Section 2.2 below), and in particular in the case that $\mathcal{H}(\rho, \upsilon)$ is a cyclic \mathcal{R} -module (cf. Theorem 2.11 below), the minimal weight *can* be determined explicitly; this provides a strong motivation for elucidating the general theory of such equations.

2.1. Multiplier systems for Γ . See [15, Ch 3] for a discussion of multiplier systems of arbitrary real weight. Note that (unlike [15]) we do *not* assume that our multiplier systems are defined on $PSL_2(\mathbb{Z})$, thus we obtain twelve multiplier systems for each weight, instead of the six described in loc. cit.

Let $\mathbb{S}^1 = \{z \in \mathbb{C} \mid |z| = 1\}$ denote the unit circle. A multiplier system in weight $k \in \mathbb{R}$ is a function $v : \Gamma \to \mathbb{S}^1$ which makes the map (2.2) a right action of Γ on \mathcal{H} . The ratio of any two multiplier systems of weight k is a homomorphism, and in fact the group $\operatorname{Hom}(\Gamma, \mathbb{C}^{\times})$ acts transitively on the set $\operatorname{Mult}(k)$ of multiplier systems in weight k. As is well known, the commutator quotient of Γ is cyclic of order 12, thus $\operatorname{Hom}(\Gamma, \mathbb{C}^{\times}) = \langle \chi \rangle$ is cyclic of order 12 as well, with generator χ satisfying

(2.10)
$$\chi(T) = \mathbf{e}\left(\frac{1}{12}\right), \qquad \chi(S) = \mathbf{e}\left(-\frac{1}{4}\right),$$

where $S = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$. So we have, for example,

$$\operatorname{Mult}(k) = \{ v_k \chi^N \mid 0 \le N \le 11 \},\$$

where v_k is the multiplier system which makes η^{2k} a modular form of weight k; here

(2.11)
$$\eta(q) = q^{\frac{1}{24}} \prod_{n \ge 1} \left(1 - q^n \right)$$

denotes Dedekind's eta function. We have $\operatorname{Mult}(k) = \operatorname{Mult}(l)$ if and only if $k \equiv l \pmod{\mathbb{Z}}$, and in particular, if $k \in \mathbb{Z}$ then $v_k = \chi^k$ is a character of Γ , so that $\operatorname{Mult}(k) = \operatorname{Hom}(\Gamma, \mathbb{C}^{\times})$ in this case. For a given multiplier system v, we define the *cusp parameter* of v to be the unique real number $0 \leq m < 12$ such that $v(T) = \mathbf{e}(\frac{m}{12})$; note that this differs from the definition given in [15] by a factor of 12.

We mention here that in Theorem 2.1 above and in the remainder of this section, we state results in terms of arbitrary real weight and multiplier system, whereas the reference given usually will contain a statement and proof in the integral weight, trivial multiplier system setting. In all cases, an analysis of the proof shows that the appearance of a nontrivial multiplier system is either inconsequential (as in the statement and proof of Theorem 2.1), or that one may make some trivial modifications to the original proof in order to obtain what is being claimed; most of these proofs are written down explicitly in the present author's doctoral dissertation [11], thus we will say nothing further regarding these modifications.

2.2. Modular differential equations and the modular Wronskian. Recall (e.g., [10, Ch 10]) the modular derivative in weight $k \in \mathbb{R}$,

$$D_k = \frac{1}{2\pi i} \frac{d}{dz} - \frac{k}{12} E_2 = q \frac{d}{dq} - \frac{k}{12} E_2.$$

 D_k acts (componentwise) as a weight two operator on spaces of vector-valued modular forms, so that

$$F \in \mathcal{H}(k,\rho,\upsilon) \mapsto D_k F \in \mathcal{H}(k+2,\rho,\upsilon)$$

for any (ρ, v) . This defines a weight two operator $D : \mathcal{H}(\rho, v) \to \mathcal{H}(\rho, v)$, which acts as D_k on $\mathcal{H}(k, \rho, v)$, and is graded with respect to the \mathcal{M} -module structure of $\mathcal{H}(\rho, v)$, that is,

$$(f,F) \in \mathcal{M}_k \times \mathcal{H}(l,\rho,\upsilon) \mapsto D(fF) = FD_kf + fD_lF \in \mathcal{H}(k+l+2,\rho,\upsilon)$$

For each $n \ge 1$, we write D_k^n for the composition

$$D_k^n = D_{k+2(n-1)} \circ \cdots \circ D_{k+2} \circ D_k.$$

An dth order monic modular differential equation (MMDE) in weight $k \in \mathbb{R}$ is an ordinary differential equation in the disk |q| < 1, of the form

(2.12)
$$L[f] = D_k^d f + M_4 D_k^{d-2} f + \dots + M_{2(d-1)} D_k f + M_{2d} f = 0,$$

with $M_j \in \mathcal{M}_j$ for each j. When rewritten in terms of $\frac{d}{dq}$, one obtains from (2.12) an ODE

(2.13)
$$q^{d}f^{(d)}(q) + q^{d-1}g_{d-1}(q)f^{(d-1)}(q) + \dots + g_{0}(q)f = 0,$$

where $f^{(n)} = \frac{d^n f}{dq^n}$ and g_j is holomorphic in |q| < 1 for each j (in fact, each $g_j \in \mathbb{C}[E_2, E_4, E_6]$, the ring of quasi-modular forms for Γ). Thus, an MMDE has, at worst, q = 0 as regular singular point, and no other singularities. The theory (cf. [6]) of such equations, due to Fuchs and Frobenius, tells us that if the *indicial roots* of (2.13) are nonnegative real numbers $\lambda_1, \ldots, \lambda_d$, pairwise incongruent (mod \mathbb{Z}), then the *d*-dimensional solution space V of (2.12) has a basis, which in this context is called a *fundamental system of solutions* of (2.12), consisting of functions of the form (2.6). It is clear that V defines a subspace of \mathcal{H} , consisting of moderate growth functions. Furthermore, it is

proven in [13, Thm 4.1] that V, when viewed in this way, is invariant under the $|_{k}^{v}$ action of Γ on \mathcal{H} , for any multiplier v in weight k. Thus, MMDEs provide a rich source of vector-valued modular forms, as we record in the following theorem.

THEOREM 2.2 (Mason). Suppose that the MMDE (2.12) has real, nonnegative indicial roots $\lambda_1, \ldots, \lambda_d$, which are pairwise incongruent (mod Z). Then there is a vector

$$F(z) = \begin{pmatrix} q^{\lambda_1} + \sum_{n \ge 1} a_1(n) q^{\lambda_1 + n} \\ \vdots \\ q^{\lambda_d} + \sum_{n \ge 1} a_d(n) q^{\lambda_d + n} \end{pmatrix},$$

whose components form a basis of the solution space V of (2.12), with the following property: given any multiplier system v in weight k, there is a representation $\rho: \Gamma \to GL_d(\mathbb{C})$, arising from the $|_k^v$ action of Γ on V, such that $F \in \mathcal{H}(k, \rho, v)$.

Note that if m denotes the cusp parameter of v, then any such ρ will satisfy (2.5), where for each j the relation (2.7) holds; in fact $v(T)\rho(T)$ is the monodromy matrix for (2.12) at the regular singular point q = 0, relative to the ordered basis $\{f_1, \ldots, f_d\}$ of V.

We define an *n*th order *Eisenstein operator* (of weight $k \in \mathbb{R}$) to be an expression of the form

(2.14)
$$L = D_k^n + \alpha_4 E_4 D_k^{n-2} + \dots + \alpha_{2n} E_{2n},$$

where $\alpha_j \in \mathbb{C}$ for each j. We have the

LEMMA 2.3. Let $n \ge 1$, and suppose L[f] = 0 is an MMDE with L the Eisenstein operator (2.14). Then the weight k and the α_j are uniquely determined by the indicial roots of the equation.

Proof. First of all, note that a simple inductive argument shows that the operator D_k^n can be written in the form

(2.15)
$$D_k^n = q^n \frac{d^n}{dq^n} + q^{n-1} f_{n,n-1}(q) \frac{d^{n-1}}{dq^{n-1}} + \dots + f_{n,0}(q),$$

where the $f_{n,j}$ are holomorphic in |q| < 1 and, furthermore,

(2.16)
$$f_{n,n-1}(0) = \frac{n(5(n-1)-k)}{12}.$$

If we rewrite the given MMDE in the form (2.13) (replacing d with n) then we have, in the notation of (2.15),

(2.17)
$$g_{n-j} = \begin{cases} f_{n,n-1}, & j = 1, \\ f_{n,n-2} + \alpha_4 E_4, & j = 2, \\ f_{n,n-j} + \alpha_{2j} E_{2j} + \sum_{i=2}^{j-1} \alpha_{2i} E_{2i} f_{n-i,n-j}, & j \ge 3. \end{cases}$$

Let r_1, \ldots, r_n denote the indicial roots of the MMDE. The corresponding indicial polynomial factors as

(2.18)
$$\prod_{j=1}^{n} (r-r_j) = \sum_{j=0}^{n} (-1)^j e_j r^{n-j},$$

where e_j denotes the *j*th elementary symmetric polynomial in r_1, \ldots, r_n . On the other hand, if for each $i \in \{0, 1, \ldots, n-1\}$ we define integers a_j^i such that

$$\prod_{j=0}^{i} (r-j) = \sum_{j=1}^{i+1} a_j^i r^j,$$

then we may write the indicial equation as

(2.19)
$$r^{n} + A_{n-1}r^{n-1} + \dots + A_{1}r + A_{0} = 0,$$

where we set $A_0 = g_0(0)$, and for $1 \le j \le n-1$ we define

(2.20)
$$A_{n-j} = a_{n-j}^{n-1} + \sum_{i=2}^{j+1} a_{n-j}^{n-i} g_{n-i+1}(0).$$

Equating coefficients in (2.18) and (2.19), we obtain for each j the identity

(2.21)
$$(-1)^j e_j = A_{n-j}.$$

Taking j = 1 in (2.21) yields

$$-(r_1 + \dots + r_n) = a_{n-1}^{n-1} + a_{n-1}^{n-2}g_{n-1}(0),$$

and combining this with (2.17) and (2.16) (and noting that $a_i^{i-1} = 1$ for any $i \ge 0$) produces the formula

$$k = \frac{12}{n} \left(a_{n-1}^{n-1} + \sum_{j=1}^{n} r_j \right) + 5(n-1),$$

thus the weight k of the MMDE is determined uniquely by the r_j (note that this also follows from Theorem 2.8 below). For j = 2, (2.21) and (2.17) (recall also that $E_4(0) = 1$ by definition) yield

$$e_2 = a_{n-2}^{n-1} + a_{n-2}^{n-2} f_{n,n-1}(0) + f_{n,n-2}(0) + \alpha_4,$$

so by (2.16) we have α_4 as a function of k and the indicial roots; since we have just shown that k itself is a function of the r_j , we see that α_4 is as well. For arbitrary $j \geq 3$, (2.17) and (2.21) show that α_{2j} is a function of the indicial roots and $k, \alpha_4, \ldots, \alpha_{2(j-1)}$. If we assume inductively that k and α_{2i} , $2 \leq i \leq j-1$ are determined uniquely by the indicial roots of the MMDE, then we find that α_{2j} is as well.

COROLLARY 2.4. Let $n \leq 5$. For each set $\{\lambda_1, \ldots, \lambda_n\}$ of complex numbers, there is a unique nth order MMDE with indicial roots $\lambda_1, \ldots, \lambda_n$.

Proof. This follows directly from the previous lemma and the fact that \mathcal{M}_{2j} is spanned by E_{2j} for j = 2, 3, 4, 5, so that every MMDE of order less than 6 is of the form L[f] = 0, with L an Eisenstein operator.

As is well known, the solution space of the first-order MMDE $D_k f = 0$ is spanned by η^{2k} , and this immediately implies the following lemma.

LEMMA 2.5. Assume that dim $\rho \geq 2$, and that $F \in \mathcal{H}(\rho, \upsilon)$ has linearly independent components. Then $DF \neq 0$.

Thus, we have the useful corollary.

COROLLARY 2.6. If ρ is irreducible, dim $\rho \geq 2$, then for each multiplier system v, D is an injective operator on $\mathcal{H}(\rho, v)$.

We will also make use of the lemma below.

LEMMA 2.7. Suppose $F = (f_1, \ldots, f_d)^t \in \mathcal{H}(k, \rho, v)$ has linearly independent components. Then for each $n \leq d$, the set $\{F, D_k F, \ldots, D_k^{n-1}F\}$ is independent over \mathcal{M} ; in particular, this set spans a rank n free submodule

$$\bigoplus_{j=0}^{n-1} \mathcal{M}D_k^j F$$

of $\mathcal{H}(\rho, \upsilon)$.

Proof. Suppose there is a relation

(2.22)
$$M_{n-1}D_k^{n-1}F + M_{n-2}D_k^{n-2}F + \dots + M_1D_kF + M_0F = 0$$

with $M_j \in \mathcal{M}$ for each j. Rewriting (2.22) in terms of $\frac{d}{dq}$ yields an ordinary differential equation L[f] = 0 of order at most n - 1, for which each of the d linearly independent components of F is a solution. By the Fuchsian theory of ODEs in the complex domain, this is impossible unless L is identically 0, and one sees easily that this forces $M_j = 0$ for each j.

The modular Wronskian, defined in [13, Sec 3], plays a key role in the techniques we use in the current paper. We gather here various results (Thms 3.7, 4.3 loc. cit.) in the following theorem.

THEOREM 2.8 (Mason). Assume $F \in \mathcal{H}(k, \rho, v)$ is of the form (2.8), and has linearly independent components; set $\lambda = \sum \lambda_j$, $n = \sum n_j$. Then the modular Wronskian of F has the form

$$W(F) = \eta^{24(\lambda+n)} g \in \mathcal{H}(d(d+k-1), \det \rho, v^d),$$

for some nonzero modular form $g \in \mathcal{M}_{d(d+k-1)-12\lambda}$ which is not a cusp form. In particular, the weight k of F satisfies the inequality

(2.23)
$$k \ge \frac{12(\lambda+n)}{d} + 1 - d,$$

and equality holds in (2.23) if, and only if, the components of F span the solution space of an MMDE (2.12) in weight k.

Since the exponents $\lambda_j + n_j$ in (2.8) are nonnegative, we obtain from (2.23) a universal lower bound on the minimal weight k_0 in (2.3).

COROLLARY 2.9. Assume ρ is irreducible with $\rho(T)$ given by (2.5), let v be an arbitrary multiplier system, and let $\{\lambda_1, \ldots, \lambda_d\}$ be the minimal admissible set for (ρ, v) , with $\lambda = \sum \lambda_j$. Then the minimal weight k_0 in (2.3) satisfies the inequality

$$(2.24) k_0 \ge \frac{12\lambda}{d} + 1 - d.$$

One also obtains from the modular Wronskian the important observation that the representations "of MMDE type"—that is, those representations arising from the slash action of Γ on the solution space of an MMDE—are always indecomposable.

LEMMA 2.10. Suppose $\rho: \Gamma \to GL_d(\mathbb{C})$ is *T*-unitarizable, $v \in Mult(k)$, and $\mathcal{H}(\rho, v)$ contains a vector

(2.25)
$$F = \begin{pmatrix} f_1 \\ \vdots \\ f_d \end{pmatrix} = \begin{pmatrix} q^{\lambda_1} + \sum_{n \ge 1} a_1(n)q^n \\ \vdots \\ q^{\lambda_d} + \sum_{n \ge 1} a_d(n)q^n \end{pmatrix}$$

whose components form a fundamental system of solutions of an MMDE in weight k. Then ρ is indecomposable.

Proof. Suppose ρ decomposes into a direct sum $\rho = \rho_1 \oplus \rho_2$. We may assume, up to equivalence of representation, that the $|_k^{\upsilon}$ -invariant subspaces corresponding to ρ_1 and ρ_2 are spanned by $\{f_1, \ldots, f_{d_1}\}, \{f_{d_1+1}, \ldots, f_d\}$ respectively, for some $1 \leq d_1 \leq d$. Set dim $\rho_2 = d_2 = d - d_1$, and $\Lambda_1 = \lambda_1 + \cdots + \lambda_{d_1}$, $\Lambda_2 = \lambda_{d_1+1} + \cdots + \lambda_d$. By Theorem 2.8, we have

(2.26)
$$d(k+d-1) = 12(\Lambda_1 + \Lambda_2).$$

On the other hand, if we define $F_1 = (f_1, \ldots, f_{d_1})^t$, $F_2 = (f_{d_1+1}, \ldots, f_d)^t$, then $F_1 \in \mathcal{H}(k, \rho_1, \upsilon)$, $F_2 \in \mathcal{H}(k, \rho_2, \upsilon)$, and Theorem 2.8 yields the inequalities

$$d_1(k+d_1-1) \ge 12\Lambda_1,$$

 $d_2(k+d_2-1) \ge 12\Lambda_2.$

Adding these inequalities and using (2.26) yields the inequality

$$2d_1d_2 \le 0,$$

so that $d_1 = d, d_2 = 0$.

Finally, we recall [14, Sec 2] the skew polynomial ring

(2.27)
$$\mathcal{R} = \left\{ f_0 + f_1 d + \dots + f_n d^n \mid f_j \in \mathcal{M}, n \ge 0 \right\}$$

of differential operators, which combines the actions of \mathcal{M} and the modular derivative on $\mathcal{H}(\rho, v)$. Addition is defined in \mathcal{R} as though it were the polynomial ring $\mathcal{M}[d]$, and multiplication is performed via the identity

$$df = fd + Df,$$

where D denotes the modular derivative. Each space $\mathcal{H}(\rho, v)$ of vector-valued modular forms is a \mathbb{Z} -graded left \mathcal{R} -module in the obvious way, and again we point out that the isomorphism (2.4) is one of graded \mathcal{R} -modules as well as vector spaces. Regarding this structure, we record here another key result from [12], which will be used frequently in subsequent sections.

THEOREM 2.11. Suppose $\rho: \Gamma \to GL_d(\mathbb{C})$ satisfies (2.5), $\rho(-I)$ is a scalar matrix, and let v be any multiplier system for Γ . Let $\{\lambda_1, \ldots, \lambda_d\}$ denote the minimal admissible set for (ρ, v) , put $\lambda = \sum_{j=1}^d \lambda_j$, and write $\mathcal{H}(\rho, v)$ as in (2.3). Then the following hold:

- If H(ρ, v) = RF₀ is cyclic as R-module, then F₀ has the form (2.25), and the f_j form a fundamental system of solutions of a dth-order MMDE of weight k₀ = ^{12λ}/_d + 1 − d. The indicial roots of the MMDE are λ₁,...,λ_d, and they are distinct.
- (2) Conversely, suppose that the λ_j are distinct. Then there is a dth-order MMDE in weight $k_0 = \frac{12\lambda}{d} + 1 d$, such that

$$\mathcal{H}(\rho',\upsilon) = \bigoplus_{k\geq 0} \mathcal{H}(k_0 + 2k, \rho', \upsilon) = \mathcal{R}F$$

is cyclic as \mathcal{R} -module; here F is as in (2.25), the f_j span the solution space V of the MMDE, and ρ' denotes the representation of Γ arising from the $|_{k_0}^{\upsilon}$ -action of Γ on V, relative to the ordered basis $\{f_1, \ldots, f_d\}$. Consequently, $\rho'(T) = \rho(T)$, and ρ' is indecomposable by Lemma 2.10, so in particular $\rho'(-I)$ is a scalar matrix.

This completes the necessary review of the basic theory of vector-valued modular forms and modular differential equations. We now proceed to the classification of spaces $\mathcal{H}(\rho, \upsilon)$ for irreducible ρ of dimension $d \leq 5$. As a warm-up, we derive here the well-known results from the classical (i.e., one-dimensional) setting, using the vector-valued methods.

Fix an integer $0 \le N \le 11$ and a character $\chi^N : \Gamma \to \mathbb{C}^*$, with χ as in (2.10), and let v be a multiplier system for Γ , with cusp parameter m. Then $\chi^N(T) = \mathbf{e}(\frac{N}{12})$, and the minimal admissible set for (χ^N, v) is $\{\lambda_1\}$, where λ_1 satisfies the congruence (2.7), with $r_1 = \frac{N}{12}$. Viewing λ_1 as an indicial root, we obtain by Corollary 2.4 a unique first order MMDE $D_{k_0}f = 0$, where by

Theorem 2.8 we have $k_0 = \frac{\lambda_1}{12}$. The solution space V of the MMDE is spanned by a function

$$f_1(z) = q^{\lambda_1} + \sum_{n \ge 1} a(n) q^{\lambda_1 + n} \in \mathcal{H}(k_0, \rho, \upsilon),$$

where $\rho: \Gamma \to \mathbb{C}^*$ is the representation afforded us by Theorem 2.2, which arises from the $|_{k_0}^v$ action of Γ on V, relative to the basis $\langle f_1 \rangle$ of V. In fact $f_1 = \eta^{2k_0}$, as is well known, and from Theorem 2.11 we obtain a cyclic \mathcal{R} -module

$$\mathcal{H}(\rho, \upsilon) = \bigoplus_{k \ge 0} \mathcal{H}(k_0 + 2k, \rho, \upsilon) = \mathcal{R}\eta^{2k_0},$$

which in the one-dimensional setting is equivalent to saying that $\mathcal{H}(\rho, v)$ is a free \mathcal{M} -module of rank one, with generator η^{2k_0} ; this is the content of Theorem 2.1, as it pertains to the present setting. Note that by definition we have $\eta^{2k_0}|_{k_0}^v T = \rho(T)\eta^{2k_0}$, so from (2.7) we conclude that $\rho(T) = \mathbf{e}(\frac{N}{12})$. Recalling that a character of Γ is completely determined by its value at the matrix T, this shows that $\rho = \chi^N$, so we have classified our space $\mathcal{H}(\chi^N, v)$.

It will be seen in what follows that this same method may, to some extent, be utilized in any dimension less than six.

3. Dimension two

This has been worked out in the trivial multiplier system case in [14]. Here we extend the results to arbitrary real weight, and provide a streamlined (indeed, nearly trivial) proof, made possible by Theorems 2.1 and 2.11.

THEOREM 3.1. Let $\rho : \Gamma \to GL_2(\mathbb{C})$ be irreducible with $\rho(T)$ as in (2.5), fix a multiplier system v, and let $\{\lambda_1, \lambda_2\}$ be the minimal admissible set of (ρ, v) . Then

$$\mathcal{H}(\rho,\upsilon) = \bigoplus_{k \ge 0} \mathcal{H}(k_0 + 2k, \rho, \upsilon) = \mathcal{R}F_0$$

is cyclic as \mathcal{R} -module, with $k_0 = 6(\lambda_1 + \lambda_2) - 1$, and the components of F_0 form a fundamental system of solutions of a second order MMDE in weight k_0 .

Proof. Write $\mathcal{H}(\rho, v)$ as in (2.3). It is clear that the number of weight k_0 generators of $\mathcal{H}(\rho, v)$ (as \mathcal{M} -module) is exactly dim $\mathcal{H}(k_0, \rho, v)$. Similarly, since $\mathcal{M}_2 = \{0\}$, the number of weight $k_0 + 2$ generators is dim $\mathcal{H}(k_0 + 2, \rho, v)$. But if we fix any nonzero $F_0 \in \mathcal{H}(k_0, \rho, v)$, then by Corollary 2.6 we know that $DF_0 \in \mathcal{H}(k_0 + 2, \rho, v)$ is nonzero, so by Theorem 2.1, we conclude that $\mathcal{H}(k_0, \rho, v) = \langle F_0 \rangle$ and $\mathcal{H}(k_0 + 2, \rho, v) = \langle DF_0 \rangle$ are 1-dimensional, and $\mathcal{H}(\rho, v) = \mathcal{M}F_0 \oplus \mathcal{M}DF_0$ as \mathcal{M} -module. In particular, $\mathcal{H}(\rho, v) = \mathcal{R}F_0$ is cyclic as \mathcal{R} -module, and part 1 of Theorem 2.11 finishes the proof.

COROLLARY 3.2. The Hilbert–Poincaré series of $\mathcal{H}(\rho, v)$ is

$$\Psi(\rho,\upsilon)(t) = \frac{t^{k_0}(1+t^2)}{(1-t^4)(1-t^6)},$$

thus for each $k \geq 0$ we have (using the well-known dimension formula for \mathcal{M}_k)

$$\dim \mathcal{H}(k_0 + 2k, \rho, \upsilon) = \left[\frac{k}{3}\right] + 1.$$

We now give an alternate proof of Theorem 3.1, along the same lines as the method used to classify spaces for one-dimensional representations at the end of the last section. This is roughly the method used in the original proof found in [14], and its successful application relies on the following theorem, [14, Thm 3.1]:

THEOREM 3.3 (Mason). Suppose $\rho : \Gamma \to GL_2(\mathbb{C})$ is indecomposable, with $\rho(T) = \text{diag}\{x_1, x_2\}$ for some $x_j \in \mathbb{C}$. Then the following are equivalent:

- (1) ρ is irreducible.
- (2) The ratio x_1/x_2 is not a primitive sixth root of 1.
- (3) The eigenvalues {x₁, x₂} of ρ(T) define a unique equivalence class of 2dimensional indecomposable representations of Γ.

Assume once again the hypotheses of Theorem 3.1. By Corollary 2.4, there is a unique second order MMDE

$$D_{k_0}^2 f + \alpha_4 E_4 f = 0$$

whose set of indicial roots is exactly $\{\lambda_1, \lambda_2\}$, the minimal admissible set of (ρ, v) . By part two of Theorem 2.11, we have $k_0 = 6(\lambda_1 + \lambda_2) - 1$, and there is a cyclic \mathcal{R} -module

$$\mathcal{H}(\rho',\upsilon) = \mathcal{R}F_0 = \bigoplus_{k\geq 0} \mathcal{H}(k_0 + 2k, \rho', \upsilon),$$

where $\rho': \Gamma \to GL_2(\mathbb{C})$ is a representation arising from the $|_{k_0}^{v}$ action of Γ on the solution space V of the MMDE, and the generator

$$F_0 = \begin{pmatrix} q^{\lambda_1} + \cdots \\ q^{\lambda_2} + \cdots \end{pmatrix} \in \mathcal{H}(k_0, \rho', \upsilon)$$

has components which span V. We have $\rho'(T) = \rho(T)$ and Theorem 2.11 (really Lemma 2.10) says that ρ' is indecomposable. Applying Theorem 3.3, we see that ρ and ρ' are equivalent irreducible representations, so the isomorphism (2.4) establishes Theorem 3.1.

4. Dimension three

This is completely analogous to dimension two, and we will prove quite easily

THEOREM 4.1. Let $\rho: \Gamma \to GL_3(\mathbb{C})$ be an irreducible representation with $\rho(T)$ as in (2.5), fix a multiplier system v, and write $\{\lambda_1, \lambda_2, \lambda_3\}$ for the minimal admissible set of (ρ, v) . Then

$$\mathcal{H}(\rho,\upsilon) = \bigoplus_{k\geq 0} \mathcal{H}(k_0 + 2k, \rho, \upsilon) = \mathcal{R}F_0$$

is cyclic as \mathcal{R} -module, with $k_0 = 4(\lambda_1 + \lambda_2 + \lambda_3) - 2$, and the components of F_0 form a fundamental system of solutions of a third order MMDE in weight k_0 .

Proof. Write $\mathcal{H}(\rho, \upsilon)$ as the graded sum (2.3). It follows immediately from Corollary 2.6 that dim $\mathcal{H}(k_0, \rho, \upsilon) = 1$, since otherwise there would be two generators F, G of weight k_0 and two DF, DG of weight $k_0 + 2$, in violation of Theorem 2.1. Fix any nonzero F_0 of minimal weight, and write $\mathcal{H}(k_0, \rho, \upsilon) =$ $\langle F_0 \rangle$. Again by Corollary 2.6, we may take DF_0 as a second generator of $\mathcal{H}(\rho, \upsilon)$. Suppose there is another generator of weight $k_0 + 2$, say G. Then by Theorem 2.1 we have

$$\mathcal{H}(\rho, v) = \mathcal{M}F_0 \oplus \mathcal{M}DF_0 \oplus \mathcal{M}G.$$

But then $D^2F_0 \in \mathcal{H}(k_0 + 4, \rho, v)$ must satisfy a relation $D^2F_0 = M_4F_0$, with $M_4 \in \mathcal{M}_4$. This is impossible by Lemma 2.7, so we must have $\mathcal{H}(k_0 + 2, \rho, v) = \langle DF_0 \rangle$, and D^2F_0 can be taken as the third generator of $\mathcal{H}(\rho, v)$. Therefore $\mathcal{H}(\rho, v) = \mathcal{R}F_0$ is cyclic as \mathcal{R} -module, and the rest of the theorem follows from part 1 of Theorem 2.11.

COROLLARY 4.2. The Hilbert–Poincaré series of $\mathcal{H}(\rho, v)$ is

$$\Psi(\rho, \upsilon)(t) = \frac{t^{k_0}(1+t^2+t^4)}{(1-t^4)(1-t^6)},$$

so that

$$\dim \mathcal{H}(k_0 + 2k, \rho, \upsilon) = \left[\frac{k}{2}\right] + 1$$

for all $k \geq 0$.

5. Dimension four

We first record a technical result which we will need in this section.

LEMMA 5.1. Let $\rho : \Gamma \to GL_4(\mathbb{C})$ be irreducible with $\rho(T)$ as in (2.5), and set $r = \sum r_j$. Then $3r \in \mathbb{Z}$. Proof. Because ρ is irreducible, we know that $\rho(S^2) = \rho(-I) = \pm I_4$, so the eigenvalues of $\rho(S)$ are $\pm 1, \pm i$, respectively. Note that in either case both eigenvalues occur, since ρ is irreducible and, as is well known, S and T generate Γ . Define $R = TS^{-1} = \begin{pmatrix} -1 & 1 \\ -1 & 0 \end{pmatrix}$. Then $R^3 = I$ and R, S generate Γ as well. If $\rho(S)$ has a three-dimensional eigenspace U, then the nonzero subspace $U \cap \rho(R)U \cap \rho(R^2)U$ is invariant under both $\rho(R)$ and $\rho(S)$, and this violates the irreducibility of ρ . Therefore, the eigenvalues of $\rho(S)$ are either $\{1, 1, -1, -1\}$ or $\{i, i, -i, -i\}$, and either way we have $\det \rho(S) = 1$. This implies

$$e(3r) = \det \rho(T^3) = \det \rho(RS)^3 = 1,$$

so 3r is an integer.

Continuing with the assumptions of the lemma, fix a multiplier system v, and write the minimal admissible set of (ρ, v) as $\{\lambda_1, \lambda_2, \lambda_3, \lambda_4\}$. From the relations (2.7) and Lemma 5.1, we find that $3\lambda \equiv m \pmod{\mathbb{Z}}$, so the minimal weight k_0 in (2.3) must be of the form $3\lambda + N$ for some integer N. Furthermore, if one takes a nonzero vector F of minimal weight, then the identity $F|_{3\lambda+N}^v S^2 = \rho(S^2)F$ implies the relation

(5.1)
$$\rho(S^2) = \nu(S^2)^{-1} (-1)^{3\lambda + N} I_4.$$

In particular, if $\mathcal{H}(\rho, v)$ is cyclic as \mathcal{R} -module, then by Theorem 2.11 we know $k_0 = 3\lambda - 3$, so (5.1) holds exactly when N is odd; this provides a necessary, though perhaps not sufficient, criterion for $\mathcal{H}(\rho, v)$ to be cyclic as \mathcal{R} -module. Regardless, it turns out that the lowest weight space for $\mathcal{H}(\rho, v)$ will be one-dimensional, as we now prove the following.

LEMMA 5.2. Let F be an arbitrary nonzero vector in $\mathcal{H}(k_0, \rho, v)$, written as in (2.8). Then $n_j = 0$ for j = 1, 2, 3, 4.

Proof. Suppose otherwise, so that $n_i \ge 1$ for some fixed $i \in \{1, 2, 3, 4\}$, and consider the subspace

$$V = \langle E_{10}F, E_8DF, E_6D^2F, E_4D^3F \rangle \le \mathcal{H}(k_0 + 10, \rho, v)$$

By Lemma 2.7 we have dim V = 4, and it is clear that any nonzero $G \in V$, written in the form (2.8), will again satisfy $n_i \ge 1$. For each $j \in \{1, 2, 3, 4\} - \{i\}$, let $\phi_j : V \to \mathbb{C}$ denote the linear functional which takes such a G to $\phi_j(G) = a_j(0)$, the first Fourier coefficient of the *j*th component of G. Then dim ker $\phi_j \ge 3$ for each *j*, so that

$$\bigcap_{j \neq i} \ker \phi_j \neq \{0\}.$$

This is equivalent to saying there is a nonzero $G \in V$ which satisfies $n_j \ge 1$ for j = 1, 2, 3, 4, when written in the form (2.8). In other words, recalling the

$$\Box$$

weight 12 cusp form

$$\Delta(q) = \eta^{24}(q) = q \prod_{n \ge 1} (1 - q^n)^{24} \in \mathcal{M}_{12},$$

we have that $\frac{G}{\Delta}$ is a nonzero vector in $\mathcal{H}(k_0 - 2, \rho, v)$. But this cannot be, since k_0 is by definition the minimal weight for $\mathcal{H}(\rho, v)$, and this contradiction finishes the proof.

COROLLARY 5.3. dim $\mathcal{H}(k_0, \rho, \upsilon) = 1$.

Proof. Suppose there are two linearly independent vectors F, G in $\mathcal{H}(k_0, \rho, v)$. Since F and G each satisfy the conclusion of Lemma 5.2, it is clear that some linear combination of these vectors will produce a nonzero vector in $\mathcal{H}(k_0, \rho, v)$ which violates the conclusion of the lemma.

With these results in hand, we are now able to show that there is only one possible non-cyclic structure for $\mathcal{H}(\rho, v)$:

LEMMA 5.4. If $\mathcal{H}(\rho, \upsilon)$ is not cyclic as \mathcal{R} -module, then it has the Hilbert– Poincaré series

(5.2)
$$\Psi(\rho, \upsilon)(t) = \frac{t^{k_0}(1+2t^2+t^4)}{(1-t^4)(1-t^6)},$$

with corresponding dimension formula

$$\dim \mathcal{H}(k_0 + 2k, \rho, \upsilon) = \left[\frac{2k+1}{3}\right] + 1,$$

for all $k \ge 0$. The minimal weight k_0 is congruent (mod \mathbb{Z}) to the cusp parameter of v, and satisfies the inequality (2.24).

Proof. Corollary 5.3 implies that $\mathcal{H}(k_0, \rho, v)$ contributes exactly one generator to the \mathcal{M} -module structure of $\mathcal{H}(\rho, v)$, say F, and we know that $DF \in \mathcal{H}(k_0 + 2, \rho, v)$ can be taken as a second generator. If $\mathcal{H}(\rho, v)$ is not cyclic as \mathcal{R} -module, and if there is not a second generator of weight $k_0 + 2$, then there must be two of weight $k_0 + 4$. But this would imply a relation $D^3F = \alpha_1 E_6 F + \alpha_2 DF$, in violation of Lemma 2.7. Thus the Hilbert–Poincaré series indicated is the correct one.

Thus, there are exactly two possible \mathcal{M} -module structures in the fourdimensional irreducible setting. Unfortunately, in the most general case we are not able to say definitively which of the two structures obtains, given the input (ρ, v) ; neither are we able to determine explicitly the minimal weight k_0 . We can say the following.

COROLLARY 5.5. Suppose that (5.1) holds for N even. Then the Hilbert– Poincaré series of $\mathcal{H}(\rho, v)$ is given by (5.2), and $k_0 = 3\lambda + N$ for some even $N \geq -2$. *Proof.* By the comments following (5.1), it is clear that the Hilbert–Poincaré series is the non-cyclic one, and the inequality $N \ge -2$ follows from (2.24). \Box

In the case where (5.1) holds for N odd, one would like to say that $\mathcal{H}(\rho, v)$ is a cyclic \mathcal{R} -module, but again, this is not known in complete generality. Nonetheless, in the vast majority of cases, we are able to determine quite explicitly what occurs. To see this, we will employ the method given in the alternative proof of Theorem 3.1 above, together with the following results concerning the representation theory of Γ , due to Tuba and Wenzl (cf. [16], corollary in Section 2, Main Theorem 2.9, and subsequent corollary).

THEOREM 5.6 (Tuba/Wenzl). Let $\rho : \Gamma \to GL_d(\mathbb{C})$ be an irreducible representation of dimension $d \leq 5$. Then the following hold:

- (1) The minimal and characteristic polynomials of $\rho(T)$ coincide.
- (2) If $d \neq 4$, then the eigenvalues of $\rho(T)$ define a unique equivalence class of irreducible representations.
- (3) If d = 4, there are at most two equivalence classes of irreducible representations defined by the eigenvalues of ρ(T).

The above theorem provides a higher-dimensional generalization of Theorem 3.3, with the significant *caveat* that it says nothing about indecomposable representations which might be lurking about, with the same eigenvalues at T as the given irreducible representation ρ ; note that an important consequence of Theorem 3.3 is that this does *not* happen in dimension two. To our knowledge, there is currently no classification theory for indecomposable representations of Γ , in any dimension, apart from Theorem 3.3. Thus it is not known to what extent this phenomenon occurs in dimensions 3, 4, 5,i.e. how often an indecomposable-but-not-irreducible representation ρ' occurs such that $\rho'(T) = \rho(T)$ for some irreducible ρ ; see, however, the Appendix below for an explicit example which shows that this phenomenon definitely *does* occur in every dimension greater than five. In any event, this concept presents an obstruction to the use of the MMDE theory for the classification of spaces of four- or five-dimensional vector-valued modular forms: one may, as in the two-dimensional setting, construct MMDEs which produce representations ρ' such that $\rho'(T) = \rho(T)$, where ρ is the given irreducible representation, but Lemma 2.10 tells us only that ρ' is indecomposable, so in the most general context Theorem 5.6 might not apply. In order to overcome this deficiency in our method, we must restrict to those irreducible representations which have no "shadow" indecomposables. To this end, we make the following.

DEFINITION 5.7. Let $d \geq 1$. An irreducible representation $\rho : \Gamma \to GL_d(\mathbb{C})$ is *T*-determined if the following condition holds:

If $\rho': \Gamma \to GL_d(\mathbb{C})$ is indecomposable and $\rho'(T)$ has the same eigenvalues as $\rho(T)$, then ρ' is irreducible.

In fact, this is a very mild restriction. For example, given an arbitrary representation ρ , if no proper sub-product of the eigenvalues of $\rho(T)$ is a 12th root of 1 then ρ is *T*-determined; this follows from the fact that det ρ is a character χ^N of Γ , with χ as in (2.10). Also, Theorem 3.3 implies that every irreducible $\rho: \Gamma \to GL_2(\mathbb{C})$ with $\rho(T)$ semi-simple is *T*-determined. And for unitary representations, of course, the notions of indecomposable and irreducible coincide. In any event, for the *T*-determined representations we are able to give a completely explicit classification in dimension four:

THEOREM 5.8. Let $\rho: \Gamma \to GL_4(\mathbb{C})$ be a *T*-determined representation with $\rho(T)$ as in (2.5), fix a multiplier system v for Γ , let $\{\lambda_1, \ldots, \lambda_4\}$ be the minimal admissible set for (ρ, v) , and set $\lambda = \sum \lambda_j$. Then exactly one of the following holds:

- The relation (5.1) holds for N odd, and H(ρ, υ) is cyclic as R-module, with minimal weight 3λ - 3.
- (2) The relation (5.1) holds for N even, and $\mathcal{H}(\rho, \upsilon)$ has the Hilbert–Poincaré series (5.2), with minimal weight $3\lambda 2$.

Proof. Note first that, since $\rho(T)$ is diagonal, part one of Theorem 5.6 and the relations (2.7) imply that the λ_j are distinct. As in the alternate proof of Theorem 3.1, one views the λ_j as the indicial roots of a unique (by Corollary 2.4) MMDE of order 4. By part two of Theorem 2.11, we obtain a cyclic \mathcal{R} -module

$$\mathcal{H}(\rho_0, \upsilon) = \mathcal{R}F_0 = \bigoplus_{k \ge 0} \mathcal{H}(3\lambda - 3 + 2k, \rho_0, \upsilon),$$

for some representation ρ_0 which satisfies $\rho_0(T) = \rho(T)$; note that (5.1) is satisfied by ρ_0 for N odd. On the other hand, we may take as indicial roots the set $\{\lambda_1 + 1, \lambda_2, \lambda_3, \lambda_4\}$, and obtain a fourth order MMDE in weight $3(\lambda + 1) - 3 = 3\lambda$. From Theorem 2.2, we obtain a nonzero vector

(5.3)
$$F_1 = \begin{pmatrix} q^{\lambda_1+1} + \cdots \\ q^{\lambda_2} + \cdots \\ q^{\lambda_3} + \cdots \\ q^{\lambda_4} + \cdots \end{pmatrix} \in \mathcal{H}(3\lambda, \rho_1, v),$$

whose components span the solution space of this second MMDE. Note that this second representation ρ_1 —arising from the $|_{3\lambda}^v$ action of Γ on the solution space of the MMDE—satisfies (5.1) for N even. The isomorphism (2.4) then shows that ρ_0 and ρ_1 are inequivalent representations, each of which is indecomposable thanks to Lemma 2.10. Furthermore, we have $\rho_0(T) = \rho_1(T) =$ $\rho(T)$. Since ρ is T-determined, this forces ρ_0 and ρ_1 to be irreducible. By part two of Theorem 5.6, we find that ρ is equivalent to exactly one of the ρ_j , thus $\mathcal{H}(\rho, v)$ is isomorphic to $\mathcal{H}(\rho_j, v)$ for j = 0 or 1; this can be determined explicitly, of course, by examining the relation (5.1). We have already seen that if (5.1) holds for N odd, then ρ is equivalent to ρ_0 , and part one of the theorem obtains.

On the other hand, suppose (5.1) holds for N even, so that ρ is equivalent to ρ_1 . Then we already know that $\mathcal{H}(\rho, v)$ has the Hilbert–Poincaré series (5.2), so to finish the proof we need only determine the minimal weight for this module. By (2.4), it suffices to do this for $\mathcal{H}(\rho_1, v)$. We know there is a nonzero vector in $\mathcal{H}(3\lambda, \rho_1, v)$, so by (2.3) and Corollary 2.9, the minimal weight is either 3λ or $3\lambda - 2$. But (5.3) and Lemma 5.2 make it clear that 3λ cannot be the minimal weight, so it must be $3\lambda - 2$.

6. Dimension five

In this section, we again apply Theorem 2.1, etc., to determine the possible Hilbert–Poincaré series for spaces of vector-valued modular forms associated to five-dimensional irreducible representations of Γ , and then restrict to the *T*-determined setting in order to obtain the most explicit results possible via our methods.

Assume for the remainder of this section that $\rho : \Gamma \to GL_5(\mathbb{C})$ is irreducible with $\rho(T)$ as in (2.5), fix a multiplier system v with cusp parameter m, and write $\{\lambda_1, \ldots, \lambda_5\}$ for the minimal admissible set of (ρ, v) . If we write each λ_j in the form

$$\lambda_j = r_j + \frac{m}{12} + l_j, \quad l_j \in \{-1, 0\}$$

and set $\lambda = \sum \lambda_j$, $r = \sum r_j$, $l = \sum l_j$, then we have

$$\frac{12\lambda}{5} - 4 = \frac{12}{5} \left(r + \frac{5m}{12} + l \right) - 4$$
$$= m + \frac{12(r+l)}{5} - 4,$$

so that

$$\frac{12\lambda}{5} - 4 \equiv m \pmod{\mathbb{Z}} \quad \Leftrightarrow \quad 12(r+l) \equiv 0 \pmod{5}.$$

This shows in particular (via Theorem 2.11) that if $\mathcal{H}(\rho, v)$ is cyclic as \mathcal{R} -module, then necessarily

$$\frac{12(r+l)}{5} \in \mathbb{Z}.$$

Certainly this does not hold in general, and instead represents a very special case. Note that $12r \in \mathbb{Z}$, since det ρ is a character of Γ , and (5, 12) = 1, so in fact there is a unique $N \in \{0, 1, 2, 3, 4\}$ such that

(6.1)
$$12(r+l+N) \equiv 0 \pmod{5}.$$

Thus the minimal weight for $\mathcal{H}(\rho, v)$, whatever it turns out to be, will necessarily be of the form

(6.2)
$$\frac{12(\lambda+N)}{5} - 4 + n,$$

for some $n \ge -\frac{12N}{5}$ (this follows from Corollary 2.9), and N = n = 0 exactly when $\mathcal{H}(\rho, v)$ is cyclic as \mathcal{R} -module.

We will see below that in some sense, the possible Hilbert–Poincaré series for $\mathcal{H}(\rho, v)$ correspond to the values of N in the discussion above. The following result starts us down this path, by determining explicitly these possibilities:

THEOREM 6.1. Write $\mathcal{H}(\rho, \upsilon)$ as the graded \mathcal{M} -module (2.3). Then there are five possibilities for the associated Hilbert–Poincaré series, namely

(6.3)
$$\Psi(\rho, \upsilon)(t) = \frac{t^{k_0} P_N(t)}{(1 - t^4)(1 - t^6)},$$

where $k_0 \geq \frac{12\lambda}{5} - 4$ and

$$P_{0}(t) = 1 + t^{2} + t^{4} + t^{6} + t^{8},$$

$$P_{1}(t) = 2 + 2t^{2} + t^{4},$$

$$P_{2}(t) = 1 + t^{2} + 2t^{4} + t^{6},$$

$$P_{3}(t) = 1 + 2t^{2} + t^{4} + t^{6},$$

$$P_{4}(t) = 1 + 2t^{2} + 2t^{4}.$$

Proof. The bound claimed for the minimal weight k_0 is just that provided by the modular Wronskian (2.24).

Obviously the N = 0 case occurs exactly when $\mathcal{H}(\rho, v)$ is cyclic as \mathcal{R} module, so assume for the remainder of the proof that this is *not* the case. Then at least one of the spaces $\mathcal{H}(k_0 + 2k, \rho, v), 0 \le k \le 4$, contains more than one generator for the \mathcal{M} -module structure of $\mathcal{H}(\rho, v)$. On the other hand, it is clear from Theorem 2.1 and Corollary 2.6 that dim $\mathcal{H}(k_0, \rho, v) < 3$, since assuming otherwise would produce at least six generators in the $k_0, k_0 + 2$ spaces alone.

Suppose for the moment that $\mathcal{H}(k_0, \rho, \upsilon)$ is two-dimensional. By taking an appropriate linear combination of vectors, it is clear that we may produce an $1 \leq i \leq 5$ and a nonzero $F \in \mathcal{H}(k_0, \rho, \upsilon)$ which, when written in the notation (2.8), satisfies $n_i \geq 1$. Then every vector in the subspace

$$V = \langle E_4 D^4 F, E_6 D^3 F, E_8 D^2 F, E_{10} DF, E_{12} F \rangle \leq \mathcal{H}(k_0 + 12, \rho, v)$$

satisfies $n_i \geq 1$ as well, when written as in (2.8). We again argue via linear functionals, as in Lemma 5.2, and (noting that dim V = 5 by Lemma 2.7) obtain a nonzero vector $G \in \mathcal{H}(k_0, \rho, v)$ such that $\Delta G \in V$. Lemma 2.7 and the fact that $\Delta G \in V$ make it clear that G is not a scalar multiple of F, so we have $\mathcal{H}(k_0, \rho, v) = \langle F, G \rangle$. By Corollary 2.6, we know that $\mathcal{H}(k_0 + 2, \rho, v)$ is at least two-dimensional, as it contains the subspace $\langle DF, DG \rangle$; thus four of the five generators predicted by Theorem 2.1 are already accounted for. Note that the fifth generator is found in $\mathcal{H}(k_0 + 2, \rho, v)$ if and only if dim $\mathcal{H}(k_0 + 2, \rho, v) = 3$, and in this case we would know from Corollary 2.6 that dim $\mathcal{H}(k_0 + 4, \rho, v) \geq 3$. But this arrangement would also imply that $\mathcal{H}(k_0 + 4, \rho, v) = \langle E_4F, E_4G \rangle$ is two-dimensional, since $\mathcal{M}_2 = \{0\}$ and there would be no additional generators in $\mathcal{H}(k_0 + 4, \rho, v)$. This contradiction shows that $\mathcal{H}(k_0 + 2, \rho, v) = \langle DF, DG \rangle$ is in fact two-dimensional.

We claim that D^2F may be taken as the fifth generator for the \mathcal{M} -module structure of $\mathcal{H}(\rho, v)$. To prove this, it suffices to establish that $D^2F \notin \langle E_4F, E_4G \rangle$, but this is clear from the fact that $\Delta G \in V$, that is, assuming a relation

$$D^2F = \alpha_1 E_4 F + \alpha_2 E_4 G$$

for some $\alpha_1, \alpha_2 \in \mathbb{C}$ and multiplying by Δ would produce a relation which violates the conclusion of Lemma 2.7. Consequently, $\mathcal{H}(\rho, v)$ has the Hilbert–Poincaré series (6.3), with N = 1, and in all the remaining cases we should, and will now, assume that $\mathcal{H}(k_0, \rho, v)$ is one-dimensional:

Suppose that $\dim \mathcal{H}(k_0 + 2, \rho, v) = 1$ as well, and fix any nonzero F in $\mathcal{H}(k_0, \rho, v)$. Then we infer from the hypotheses and Corollary 2.6 that

$$\mathcal{H}(k_0,\rho,\upsilon) = \langle F \rangle, \qquad \mathcal{H}(k_0+2,\rho,\upsilon) = \langle DF \rangle.$$

We may also take $D^2 F \in \mathcal{H}(k_0 + 4, \rho, v)$ as a third generator, by Lemma 2.7. Note that, since $\mathcal{H}(\rho, v)$ is not cyclic as \mathcal{R} -module, either $\mathcal{H}(k_0 + 4, \rho, v)$ or $\mathcal{H}(k_0 + 6, \rho, v)$ contains more than one generator. In particular, if

$$\mathcal{H}(k_0+4,\rho,\upsilon) = \left\langle E_4 F, D^2 F \right\rangle$$

is two-dimensional then there must be a vector G such that

$$\mathcal{H}(k_0+6,\rho,\upsilon) = \left\langle D^3F, E_4DF, E_6F, G \right\rangle$$

is four-dimensional, and D^3F, G can be taken as the fourth and fifth generators of $\mathcal{H}(\rho, v)$. This would mean $\mathcal{H}(k_0 + 8, \rho, v) = \langle E_8F, E_6DF, E_4D^2F \rangle$ is three-dimensional, yet (by Corollary 2.6) contains the four-dimensional subspace $D\mathcal{H}(k_0 + 6, \rho, v)$, contradiction. Thus dim $\mathcal{H}(k_0 + 4, \rho, v) \geq 3$, which implies (again by Corollary 2.6) that dim $\mathcal{H}(k_0 + 6, \rho, v) \geq 3$. Since the three known generators F, DF, D^2F only produce the two-dimensional subspace $\langle E_6F, E_4DF \rangle \leq \mathcal{H}(k_0 + 6, \rho, v)$, it is clear in this case that the Hilbert–Poincaré series for $\mathcal{H}(\rho, v)$ is (6.3) with N = 2.

Finally, suppose that dim $\mathcal{H}(k_0, \rho, \upsilon) = 1$, dim $\mathcal{H}(k_0 + 2, \rho, \upsilon) = 2$. By the hypotheses and Corollary 2.6, there are generators F, G such that $\mathcal{H}(k_0, \rho, \upsilon) = \langle F \rangle$, $\mathcal{H}(k_0 + 2, \rho, \upsilon) = \langle DF, G \rangle$. Lemma 2.7, together with the fact that $\mathcal{M}_2 = \{0\}$, makes it clear that D^2F can be taken as a fourth generator. If DG is not contained in the subspace $\langle E_4F, D^2F \rangle \leq \mathcal{H}(k_0 + 4, \rho, \upsilon)$, then the five generators are F, G, DF, D^2F, DG and we have the N = 4 case of the theorem. Otherwise, there is a relation

$$(6.4) DG = \alpha_1 D^2 F + \alpha_2 E_4 F$$

for some $\alpha_j \in \mathbb{C}$, and to show that the N = 3 case obtains, it suffices to show that the set $\{F, G, DF, D^2F, D^3F\}$ is independent over \mathcal{M} .

Assume there is a homogeneous relation in weight $k_0 + 2k$, say

(6.5)
$$QG = M_{2k}F + M_{2(k-1)}DF + M_{2(k-2)}D^2F + M_{2(k-3)}D^3F,$$

where $Q \in \mathcal{M}_{2(k-1)}$, and $M_j \in \mathcal{M}_j$ for each j. If $Q \neq 0$, then dividing by Q and taking the modular derivative in (6.5) yields, after utilizing (6.4), a relation

$$0 = \frac{M_{2(k-3)}}{Q} D^4 F + \left[\frac{M_{2(k-2)}}{Q} + D\left(\frac{M_{2(k-3)}}{Q}\right)\right] D^3 F + \left[\frac{M_{2(k-1)}}{Q} + D\left(\frac{M_{2(k-2)}}{Q}\right) - \alpha_1\right] D^2 F + \left[\frac{M_{2k}}{Q} + D\left(\frac{M_{2(k-1)}}{Q}\right)\right] DF + \left[D\left(\frac{M_{2k}}{Q}\right) - \alpha_2 E_4\right] F.$$

Noting that Lemma 2.7 obviously still holds when the coefficient functions lie in the fraction field of \mathcal{M} , we conclude that each of the coefficients in the above equation is identically zero. It is then apparent that all the M_j must be zero, so that no relation like (6.5) exists with a nonzero Q. But again by Lemma 2.7, if Q = 0 in (6.5) then all the M_j are zero as well. This concludes the proof of the theorem.

As with the analogous statements in the previous section, the above theorem serves as an existence result only, since we face in dimension five the same obstruction discussed after the statement of Theorem 5.6: the existence of indecomposable representations which are *not* irreducible, yet have the same eigenvalues at T as some irreducible representation. As in dimension four, in these cases we cannot say definitively which Hilbert–Poincaré series obtains in Theorem 6.1, nor can we determine explicitly the minimal weight. However, if we again fall back into the *T*-determined setting (cf. Definition 5.7), everything is quite explicit, as we now show. We begin with an important lemma.

LEMMA 6.2. Retaining the hypotheses and notations from the beginning of this section, make the additional assumption that ρ is T-determined, let $N \in \{0, 1, 2, 3, 4\}$ be the unique integer such that (6.1) holds, and set

$$k_N = \frac{12(\lambda + N)}{5} - 4.$$

Then the following statements hold:

(1) For each set $\{N_1, \ldots, N_5\}$ of nonnegative integers such that $\sum N_j = N$, there is a unique fifth order MMDE with indicial roots $\lambda_j + N_j$, of weight k_N , and a vector-valued modular form

(6.6)
$$F_{(N_1,\ldots,N_5)}(z) = \begin{pmatrix} q^{\lambda_1+N_1} + \cdots \\ \vdots \\ q^{\lambda_5+N_5} + \cdots \end{pmatrix} \in \mathcal{H}(k_N,\rho',\upsilon)$$

whose components span the solution space of the MMDE. The representation ρ' (which depends on the N_j) is equivalent to ρ , and we have

$$\mathcal{H}(\rho',\upsilon) = \bigoplus_{k \ge n_N} \mathcal{H}(k_N + 2k, \rho', \upsilon),$$

where the integer n_N satisfies the inequality $n_N \ge -\frac{6N}{5}$. (2) For each integer $k \ge -\frac{6N}{5}$, we have

$$\dim \mathcal{H}(k_N + 2k, \rho', \upsilon) \leq \begin{cases} \left[\frac{5k}{6}\right] + N, & k \equiv 5 \pmod{6}, \\ \left[\frac{5k}{6}\right] + N + 1, & k \not\equiv 5 \pmod{6}. \end{cases}$$

Proof. Given any appropriate set of N_j , the existence and uniqueness of the MMDE follows from Corollary 2.4. Note that part one of Theorem 5.6, the assumption that $\rho(T)$ is diagonal, and the relations (2.7) imply that the indicial roots $\lambda_j + N_j$ are incongruent (mod \mathbb{Z}), thus by Theorem 2.2 we obtain the vector $F_{(N_1,\ldots,N_5)}$ and representation ρ' . Noting that $\rho'(T) = \rho(T)$, we find from Lemma 2.10 and the assumption that ρ is *T*-determined that ρ' and ρ are equivalent. The fact that the minimal weight of $\mathcal{H}(\rho', v)$ is congruent (mod \mathbb{Z}) to k_N follows from the discussion at the beginning of this section, and the inequality on n_N follows from the bound (2.24). This establishes part one of the lemma.

As for part two, suppose that $k \ge -\frac{6N}{5}$, and assume there is a nonzero vector F in $\mathcal{H}(k_N + 2k, \rho', \upsilon)$ of the form (2.8). By Theorem 2.8, the modular Wronskian of F is of the form $W(F) = \eta^{24(\lambda+n)}g$, where $n = \sum n_j$, and the weight of the non-cusp form g is

$$wt(g) = 5(k_N + 2k + 4) - 12(\lambda + n)$$

= $5\left(\frac{12(\lambda + N)}{5} - 4 + 2k + 4\right) - 12(\lambda + n)$
= $12(N - n) + 10k.$

In particular, g is nonzero, so we know that $wt(g) \ge 0, \ne 2$, as $\mathcal{M}_k = \{0\}$ if k < 0, = 2. We clearly have

$$wt(g) \equiv 2 \pmod{12} \iff k \equiv 5 \pmod{6},$$

and this gives the inequalities

(6.7)
$$n \leq \begin{cases} \left[\frac{5k}{6}\right] + N - 1, & k \equiv 5 \pmod{6}, \\ \left[\frac{5k}{6}\right] + N, & k \not\equiv 5 \pmod{6}. \end{cases}$$

Now one may argue using linear functionals, as in the proof of Lemma 5.2, and conclude that the $\mathcal{H}(k_N + 2k, \rho', v)$ will always contain a vector of the form (2.8), such that the inequality

$$n \ge \dim \mathcal{H}(k_N + 2k, \rho', \upsilon) - 1$$

obtains. Combining this fact with (6.7) completes the proof of the lemma. \Box

Using this lemma, we may now establish the following theorem.

THEOREM 6.3. Assume the hypotheses and conclusions of Lemma 6.2. Then the Hilbert–Poincaré series of $\mathcal{H}(\rho, \upsilon)$ is of the form

(6.8)
$$\Psi(\rho,\upsilon)(t) = \Psi_N(t) = \frac{t^{k_N + n_N} P_N(t)}{(1 - t^4)(1 - t^6)},$$

with P_N as in the statement of Theorem 6.1, and n_N given by

$$n_N = 0, 0, -2, -3, -4$$
 for $N = 0, 1, 2, 3, 4$

respectively.

Proof. Thanks to Lemma 6.2 and the isomorphism (2.4), it suffices to determine the Hilbert–Poincaré series for $\mathcal{H}(\rho', \upsilon)$, where ρ' is any representation arising from the $|_{k_N}^{\upsilon}$ action of Γ on the solution space of any MMDE with indicial roots $\lambda_j + N_j$ satisfying $\sum N_j = N$. We now proceed on a case-by-case basis, depending on N:

N = 0. By Theorem 2.11, $\mathcal{H}(\rho', v)$ is cyclic as \mathcal{R} -module, thus the Hilbert–Poincaré series is of the form (6.8) with N = 0, $n_0 = 0$, as claimed.

N = 1. Choose the integers N_j as $N_1 = 1$, $N_j = 0$ for $2 \le j \le 5$. Let $F_1 = F_{(1,0,0,0,0)} \in \mathcal{H}(k_1,\rho',\upsilon)$ denote the vector (6.6), and note that Lemma 6.2 implies that k_1 is the minimal weight space for $\mathcal{H}(\rho',\upsilon)$, since $-1 \equiv 5 \pmod{6}$. We claim that the minimal weight space $\mathcal{H}(k_1,\rho',\upsilon)$ is two-dimensional. To verify this claim, we use the linear functional argument from Lemma 5.2 together with Lemma 2.7, and produce a vector

$$(6.9) \qquad \overline{G} = \beta_1 E_4 D^4 F_1 + \beta_2 E_6 D^3 F_1 + \beta_3 E_8 D^2 F_1 + \beta_4 E_{10} DF_1 + \beta_5 E_{12} F_1$$

in $\mathcal{H}(k_1 + 12, \rho, v)$ such that $G = \frac{G}{\Delta}$ is a nonzero vector in $\mathcal{H}(k_1, \rho', v)$. If there is a relation $\alpha_1 F_1 + \alpha_2 G = 0$, then multiplying by Δ and substituting with (6.9) yields

(6.10)
$$0 = \alpha_2 \beta_1 E_4 D^4 F_1 + \alpha_2 \beta_2 E_6 D^3 F_1 + \alpha_2 \beta_3 E_8 D^2 F_1 + \alpha_2 \beta_4 E_{10} DF_1 + [\alpha_1 \Delta + \alpha_2 \beta_5 E_{12}] F_1.$$

By Lemma 2.7, each coefficient function in (6.10) must be zero. In particular, we have $\alpha_1 \Delta = -\alpha_2 \beta_5 E_{12}$. Comparing *q*-expansions forces $\alpha_1 = 0$, which means $\alpha_2 G = 0$, i.e. $\alpha_2 = 0$. Therefore F and G are linearly independent, so by part two of Lemma 6.2 (with (N,k) = (1,0)), we conclude that $\mathcal{H}(k_1,\rho',\upsilon) = \langle F_1,G \rangle$ is two-dimensional. Theorem 6.1 then makes it clear that the Hilbert–Poincaré series for $\mathcal{H}(\rho',\upsilon)$ must be of the form (6.8) with $N = 1, n_1 = 0$.

N = 2. Set $F_2 = F_{(1,1,0,0,0)} \in \mathcal{H}(k_2, \rho', \upsilon)$ in (6.6). As in the N = 1 case just treated, we use F_2 to produce a nonzero vector

$$G' \in \langle D^4 F_2, E_4 D^2 F_2, E_6 D F_2, E_8 F_2 \rangle \leq \mathcal{H}(k_2 + 8, \rho', v)$$

such that $G = \frac{G'}{\Delta}$ is a nonzero vector in $\mathcal{H}(k_2 - 4, \rho', v)$. Part one of Lemma 6.2 implies that the minimal weight of $\mathcal{H}(\rho', v)$ is in fact $k_2 - 4$, and part two with (k, N) = (-2, 2) shows that $\mathcal{H}(k_2 - 4, \rho', v) = \langle G \rangle$ is one-dimensional. Similarly, part two of the lemma with (k, N) = (-1, 2) and Corollary 2.6 show that $\mathcal{H}(k_2 - 2, \rho', v) = \langle DG \rangle$ is one-dimensional. Since we know from Theorem 2.11 that $\mathcal{H}(\rho', v)$ is not cyclic, this information is enough to conclude, via Theorem 6.1, that the Hilbert–Poincaré series of $\mathcal{H}(\rho, v)$ is given by (6.8) with $N = 2, n_2 = -2$, as claimed.

N = 3. We shall be more particular in this case about our choice of indicial roots, singling out a $j_1 \in \{1, \ldots, 5\}$ such that $\lambda_{j_1} \neq k_3 - 6$; this is certainly possible, since the diagonal nature of $\rho(T)$ and part one of Theorem 5.6 imply that the λ_j are distinct. Having made this selection, we then choose distinct $j_2, j_3, j_4, j_5 \in \{1, \ldots, 5\} - \{j_1\}$, and set $N_{j_1} = N_{j_2} = 0$, $N_{j_3} = N_{j_4} = N_{j_5} = 1$. Using these integers, we then proceed as usual, and set $F_3 = F_{(N_1,\ldots,N_5)} \in \mathcal{H}(k_3, \rho', v)$ in (6.6). We find, using the linear functional argument, a vector

$$G \in \langle D^3F_3, E_4DF_3, E_6F_3 \rangle \leq \mathcal{H}(k_3 + 6, \rho', v)$$

such that $G_1 = \frac{G}{\Delta}$ is a nonzero vector in $\mathcal{H}(k_3 - 6, \rho', \upsilon)$. Part one of Lemma 6.2 shows that $k_3 - 6$ is the minimal weight for $\mathcal{H}(\rho', \upsilon)$, and part two with (k, N) = (-3, 3) shows that $\mathcal{H}(k_3 - 6, \rho', \upsilon) = \langle G_1 \rangle$ is one-dimensional. A second application of this reasoning produces a vector

$$H \in \langle D^4 F_3, E_4 D^2 F_3, E_6 D F_3, E_8 F_3 \rangle \le \mathcal{H}(k_3 + 8, \rho', v)$$

such that $G_2 = \frac{H}{\Delta} \in \mathcal{H}(k_3 - 4, \rho', v)$ has the form (2.8) with $n_{j_1} \geq 1$. Now, setting (k, N) = (-2, 3) in part two of Lemma 6.2 informs us that $\mathcal{H}(k_3 - 4, \rho', v)$ is at most two-dimensional, and we claim that in fact $\mathcal{H}(k_3 - 4, \rho', v) = \langle DG_1, G_2 \rangle$ is exactly two-dimensional. To see this, we must show that no relation $DG_1 = \alpha G_2$ exists, with $\alpha \in \mathbb{C}$. Writing G_1 in the form (2.8) and examining the modular Wronskian $W(G_1)$, we find from the bound (2.23) that $n_j = 0$ for $1 \leq j \leq 5$ in (2.8). Furthermore, because of the way we chose j_1 , it follows directly from the definition of the modular derivative that when we write DG_1 in the form (2.8), we again have $n_{j_1} = 0$. On the other hand, by definition we know that G_2 , when written as (2.8), satisfies $n_{j_1} \geq 1$. Therefore $DG_1 \neq \alpha G_2$ for any $\alpha \in \mathbb{C}$, and our claim about $\mathcal{H}(k_3 - 4, \rho', v)$ is verified. Part two of Lemma 6.2 with (k, N) = (-1, 3) and Lemma 2.7 show that $\mathcal{H}(k_3 - 2, \rho', \upsilon) = \langle D^2 G_1, E_4 G_1 \rangle$ is two-dimensional, and this is enough information to establish that $\mathcal{H}(\rho', \upsilon)$ has the Hilbert–Poincaré series (6.8) with N = 3, $n_3 = -3$, as claimed.

N=4. Set $F_4=F_{(1,1,1,1,0)}\in\mathcal{H}(k_4,\rho',\upsilon)$ in (6.6). We find, as usual, a vector

$$G \in \langle D^2 F_4, E_4 F_4 \rangle \leq \mathcal{H}(k_4 + 4, \rho', \upsilon)$$

such that $G_1 = \frac{G}{\Delta}$ is a nonzero vector in $\mathcal{H}(k_4 - 8, \rho', \upsilon)$. Part one of Lemma 6.2 implies that $k_4 - 8$ is the minimal weight for $\mathcal{H}(\rho', \upsilon)$, and part two with (k, N) = (-4, 4) shows that $\mathcal{H}(k_4 - 8, \rho', \upsilon) = \langle G_1 \rangle$ is one-dimensional. Similar to the N = 3 case above, let us fix an $i_1 \in \{1, \ldots, 5\}$ such that $\lambda_{i_1} \neq \frac{k_4 - 8}{12}$. Using this i_1 to define the appropriate linear functionals, we may locate a vector

$$H \in \left\langle D^3 F_4, E_4 D F_4, E_6 F_4 \right\rangle \le \mathcal{H} \left(k_4 + 6, \rho', \upsilon \right)$$

such that $G_2 = \frac{H}{\Delta}$ is a nonzero vector in $\mathcal{H}(k_4 - 6, \rho', v)$ which, when written in the form (2.8), has the property that $n_{i_1} \geq 1$. Once again, it then follows directly from the definition of the modular derivative that DG_1 and G_2 are linearly independent, and part two of Lemma 6.2 implies (using (k, N) =(-3, 4)) that $\mathcal{H}(k_3 - 6, \rho', v) = \langle DG_1, G_2 \rangle$ is two-dimensional. We iterate this logic one last time, defining an $i_2 \in \{1, \ldots, 5\} - \{i_1\}$ such that $\lambda_{i_2} \neq \frac{k_4 - 6}{12}$, and using this i_2 we define the appropriate linear functionals to produce a vector

$$\widetilde{G} \in \left\langle D^4 F_4, E_4 D^2 F_4, E_6 D F_4, E_8 F_4 \right\rangle \le \mathcal{H} \left(k_4 + 8, \rho', \upsilon \right)$$

such that $G_3 = \frac{G}{\Delta}$ is a nonzero vector in $\mathcal{H}(k_4 - 4, \rho', \upsilon)$, with the property that, when written in the form (2.8), we have $n_j \geq 1$ for $j = i_1, i_2$. Using (k, N) = (-2, 4) in part two of Lemma 6.2 shows that $\mathcal{H}(k_4 - 4, \rho', \upsilon)$ is at most three-dimensional, and we claim that this bound is realized, that is,

$$\mathcal{H}(k_4 - 4, \rho', \upsilon) = \langle E_4 G_1, DG_2, G_3 \rangle$$

To verify this, assume there is a relation

(6.11)
$$\alpha_1 E_4 G_1 + \alpha_2 D G_2 + \alpha_3 G_3 = 0$$

for some $\alpha_j \in \mathbb{C}$. Now, it follows directly from the definition of G_1 and the bound obtained from Theorem 2.8 that when G_1 is written in the form (2.8), we have $n_j = 0$ for $1 \le j \le 5$. Similarly, when G_2 is written in this form we have $n_{i_1} = 1$ and $n_j = 0$ otherwise, and for G_3 we find that $n_{i_1} = n_{i_2} = 1$ and $n_j = 0$ otherwise. From this information, one sees that the *j*th component of the left-hand side of (6.11) is of the form

(6.12)
$$(\alpha_1 a_j(0)q^{\lambda_j} + \cdots) + \left(\alpha_2 b_j(0) \left(\lambda_j + \delta_{j,i_1} - \frac{k_4 - 6}{12} \right) q^{\lambda_j + \delta_{j,i_1}} + \cdots \right) + (\alpha_3 c_j(0)q^{\lambda_j + n_j} + \cdots),$$

where $a_j(0)q^{\lambda_j}$, $b_j(0)q^{\lambda_j+\delta_{j,i_1}}$, $c_j(0)q^{\lambda_j+n_j}$ denote the leading terms of G_1 , DG_2 , G_3 , respectively, and n_j is as stated above for G_3 . Setting $j = i_1$ in (6.12), we find that $\alpha_1 = 0$, since $a_{i_1}(0) \neq 0$ and the second and third expansions in (6.12) have no $q^{\lambda_{i_1}}$ term. Similarly, the $j = i_2$ version of (6.12) shows that $\alpha_2 = 0$, since we now know that $\alpha_1 = 0$, the second expansion in (6.12) has leading term $q^{\lambda_{i_2}}$, and the third has leading term $q^{\lambda_{i_2}+1}$. But then $\alpha_3 = 0$ also, and this proves that $\mathcal{H}(k_4 - 4, \rho', v)$ is three-dimensional. We now have have enough information to see that $\{G_1, DG_1, G_2, DG_2, G_3\}$ forms a set of free generators for $\mathcal{H}(\rho', v)$ as \mathcal{M} -module, so that the Hilbert–Poincaré series for $\mathcal{H}(\rho', v)$ is of the form (6.8), with $N = 4, n_4 = -4$.

Although we omit them here in favor of concision, we note that explicit \mathcal{M} bases have been computed for the N = 1, 2, 3 cases of Theorem 6.3, and may be found in [11, Secs 4.5.2-4.5.4]. Similarly, one may find in loc. cit. explicit formulas for the dimensions of the various spaces $\mathcal{H}(k, \rho, \upsilon)$; of course this information may be also be obtained directly from the given Hilbert–Poincaré series and the classical formula for the dimension of \mathcal{M}_k .

Appendix: Cusp forms and modular differential equations

One way of seeing why Definition 5.7 is not frivolous in arbitrary dimension is to examine the effect of cusp forms on the MMDE theory reviewed in Section 2.2. For concreteness, we focus on dimension six. Because $\mathcal{M}_{12} = \mathbb{C}E_{12} \oplus \mathbb{C}\Delta$, one observes that the arbitrary MMDE of order six is of the form $(L + c\Delta)[f] = 0$, where L is a sixth order Eisenstein operator (2.14), and c an arbitrary complex number. Now, Lemma 2.3 states that for any set Λ of six complex numbers, there is a unique Eisenstein operator L_{Λ} , such that the MMDE $L_{\Lambda}[f] = 0$ has the indicial roots Λ . Recall (cf. [6]) that if this MMDE is written in the form (2.13), the indicial polynomial (whose roots are the indicial roots of (2.13)) is determined by the constant terms of the holomorphic functions $g_j(q)$. But for any $c \in \mathbb{C}$, $c\Delta$ has constant term 0. Thus we find that for each set Λ , every operator in the family $\{L_{\Lambda} + c\Delta \mid c \in \mathbb{C}\}$ has Λ as its set of indicial roots. Using this fact, it is easy to construct irreducible representations of dimension six which are *not* T-determined:

For example, let $\Lambda = \{r_1, \ldots, r_5\}$ be any set of distinct real numbers satisfying $0 < r_j < 1$ for each j, such that no proper sub-sum of the r_j is of the form $\frac{x}{12}, x \in \mathbb{Z}$, and such that $r = \sum r_j = \frac{5}{2}$. (For example, one may choose $\Lambda = \{\frac{2}{22}, \frac{5}{22}, \frac{8}{22}, \frac{19}{22}, \frac{21}{22}\}$.) Using these r_j as indicial roots, one obtains by Corollary 2.4 a unique Eisenstein operator in weight (by Theorem 2.8) $\frac{12r}{5} - 4 = 2$, of the form

$$L_{\Lambda} = D_2^5 + \alpha_4 E_4 D_2^3 + \dots + \alpha_{10} E_{10}.$$

For each $c \in \mathbb{C}$, consider the operator

$$L_c = L_{\Lambda} D_0 + c\Delta = D_0^6 + \alpha_4 E_4 D_0^4 + \dots + \alpha_{10} E_{10} D_0 + c\Delta_4$$

and the associated representation $\rho_c: \Gamma \to GL_6(\mathbb{C})$, arising from the $|_0$ action of Γ on the solution space V_c of the MMDE $L_c[f] = 0$, as afforded us by Theorem 2.2. Recalling that the solution space of $D_k f = 0$ is spanned by η^{2k} , one sees immediately that any constant function will be a solution of $L_0[f] = 0$, thus the solution space V_0 contains a one-dimensional subspace $\mathcal{M}_0 = \mathbb{C}$ of functions which are invariant under $|_0$. In particular, the representation ρ_0 is indecomposable (by Lemma 2.10) but *not* irreducible.

As mentioned above, the indicial roots of $L_c[f] = 0$ will be the same for any $c \in \mathbb{C}$, and it is clear that the indicial roots of $L_0[f] = 0$ are $\{0, r_1, \ldots, r_5\}$: The solutions of $L_0[f] = 0$ are exactly the functions $\{f \mid L_{\Lambda}[D_0 f] = 0\}$, and if $f = q^{\lambda} + \cdots$, then $D_0 f = q \frac{df}{dq} = \lambda q^{\lambda} + \cdots$, so either $\lambda = 0$ or the solution f satisfying $L_0[f] = 0$ has the same leading exponent as the solution $g = D_0 f$ satisfying $L_{\Lambda}[g] = 0$. In particular, for any $c \in \mathbb{C}$ we have, say, $\rho_c(T) =$ diag $\{1, \mathbf{e}(r_1), \ldots, \mathbf{e}(r_5)\}$.

We claim that ρ_c is irreducible for any $c \in \mathbb{C}^*$. To see this, observe that for any c, the set $\{0, r_1, \ldots, r_5\}$ of indicial roots of L_c has the same sub-sum property as Λ , with the obvious exceptions $0 = \frac{0}{12}$ and $\sum r_j = \frac{5}{2}$. But any proper invariant subspace of a solution space V_c must correspond to some proper sub-sum of indicial roots of the form $\frac{x}{12}$, since this subspace defines a sub-representation of Γ . Thus for any $c \in \mathbb{C}$, the only possibilities are that the proper invariant subspace of V_c is one-dimensional, and corresponds to the single indicial root 0, or that it is five dimensional, and corresponds to the sub-sum $\frac{5}{2} = \sum r_j$. In the former case, the invariant subspace V must again consist of holomorphic modular forms of weight 0 (since it must be invariant under $|_0$ and is one-dimensional), so that $V = \mathcal{M}_0 = \mathbb{C}$ again consists of the constant functions. But clearly a constant function solves $L_c[f] = 0$ exactly when c = 0 (since these functions already satisfy $L_{\Lambda} D_0[f] = 0$), thus the former case is impossible. In the latter case, the invariant subspace V yields a subrepresentation $\rho: \Gamma \to GL_5(\mathbb{C})$ which is evidently irreducible, and has the property that $\rho(T)$ and $\rho_{\Lambda}(T)$ have the same eigenvalues, where ρ_{Λ} denotes any representation associated to the MMDE $L_{\Lambda}[f] = 0$. Thus $\rho \sim \rho_{\Lambda}$, by Theorem 5.6. But $\mathcal{H}(\rho_{\Lambda}, \mathbf{1})$ is a cyclic \mathcal{R} -module with minimal weight 2, by Theorem 2.11, whereas there is a nonzero vector $F \in \mathcal{H}(0, \rho, \mathbf{1})$, whose components form a basis of the invariant subspace V. This is a contradiction, in light of the isomorphism (2.4). Thus the latter case is also ruled out, and our claim is verified, that is, ρ_c is irreducible for each $c \in \mathbb{C}^*$.

Along the same line of reasoning, there is one more important aspect of this example which must be mentioned. By Theorem 2.11, each space $\mathcal{H}(\rho_c, \mathbf{1})$ is a cyclic \mathcal{R} -module $\mathcal{R}F_c$, where the minimal weight vector $F_c \in \mathcal{H}(0, \rho_c, \mathbf{1})$ has components which span the solution space V_c of the MMDE $L_c[f] = 0$. In particular, each space $\mathcal{H}(0, \rho_c, \mathbf{1}) = \langle F_c \rangle$ is one-dimensional. Using this fact, it is easy to see that ρ_{c_1} is equivalent to ρ_{c_2} if, and only if, $c_1 = c_2$. This follows

directly from the isomorphism (2.4): If $\rho_{c_1} \sim \rho_{c_2}$, then there is a $U \in GL_6(\mathbb{C})$ such that $UF_{c_1} = \alpha F_{c_2}$ for some $\alpha \in \mathbb{C}$, and this implies that every component of F_{c_2} is a solution of $L_{c_1}[f] = 0$ and vice-versa. Clearly this happens if, and only if, $c_1 = c_2$.

Finally, we point out that this example obviously generalizes to any dimension/order greater than 5, since there will always be cusp forms available to be utilized in this same manner. Indeed, it is hoped that a deep understanding of this type of example may eventually lead to some sort of progress in solving the general problem of classifying irreducible (or, even better, indecomposable) representations of Γ in arbitrary dimension.

We summarize the above discussion by recording the following.

PROPOSITION A.1. In each dimension $d \ge 6$, there exists a one parameter family of inequivalent indecomposable, *T*-unitarizable representations

$$\{\rho_c: \Gamma \to GL_d(\mathbb{C}) \mid c \in \mathbb{C}\}$$

with the following properties:

(1) For every $c_1, c_2 \in \mathbb{C}$, $\rho_{c_1}(T) = \rho_{c_2}(T)$.

(2) ρ_c is irreducible if, and only if, $c \in \mathbb{C}^*$.

This proposition gives an indication of just how spectacularly the results of [16] fail to be true in dimension greater than five; see also Remark 2.11.3, loc. cit.

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Christopher Marks, Department of Mathematical and Statistical Sciences, University of Alberta, Canada

E-mail address: chris.marks@ualberta.ca