

## NONPARAMETRIC ESTIMATION OF OPTIMAL PERFORMANCE CRITERIA IN QUALITY ENGINEERING

BY R. J. CARROLL AND PETER HALL

*Texas A & M University and Australian National University*

Box and Leon, Shoemaker and Kackar have discussed the problem of closeness to target in quality engineering. If the mean response  $f(x, z)$  depends on  $(x, z)$ , the variance function is a PERMIA if it is  $g(z)$ , i.e., depends only on  $z$ . The goal is to find  $(x_0, z_0)$  which minimizes variance while achieving a target mean value. We pose and answer the question: For given smoothness assumptions about  $f$  and  $g$ , how accurately can we estimate  $x_0$  and  $z_0$ ? As part of the investigation, we also find optimal rates of convergence for estimating  $f$ ,  $g$  and their derivatives.

**1. Introduction.** We investigate estimation of optimal policies in what Box (1988) calls the problem of "closeness to target" in quality engineering; see also Leon, Shoemaker and Kackar (1988) and Taguchi and Wu (1985). System variability is governed by a control factor  $z$ , so that observations have variance function  $g(z)$ . System mean is governed not only by the control factor  $z$  but also by a signal factor  $x$ , so that observations have mean function  $f(x, z)$ . In the terminology of Leon, Shoemaker and Kackar (1988), the variance function  $g(z)$  is a PERMIA. As in Box (1988), the goal is to find the control setting  $z_0$  which minimizes  $g$  and to find the signal setting  $x_0$  for which  $f(x_0, z_0) = \tau_0$ , where  $\tau_0$  is a prespecified target value.

For example, consider a production line producing extruded plastic parts, whose mean length should equal  $\tau_0$ . Actual mean length  $f(x, z)$  is influenced by the length  $x$  into which the hot parts are cut and by the temperature  $z$  (or any quantity, such as viscosity, which is a monotone function of temperature) of the parts when they are cut. We would like to choose the pair  $(x, z)$  such that mean length equals  $\tau_0$  and variance of length is minimized. Assuming that variance of length depends only on temperature, we choose  $z = z_0$  to minimize the variance  $g(z)$  and then select  $x = x_0$  to solve  $f(x, z_0) = \tau_0$ . We assume that  $g$  has a unique minimum and that  $f(\cdot, z)$  has a unique minimum for each fixed  $z$ .

In practice,  $f$  and  $g$  would usually be unknown, and so we sample a variety of signal factors and control factors to produce estimators  $\hat{f}$  and  $\hat{g}$  of  $f$  and  $g$ , respectively. Choose  $\hat{z}_0$  to minimize  $\hat{g}$ , and given  $\hat{z}_0$ , choose  $\hat{x}_0$  so that  $\hat{f}(\hat{x}_0, \hat{z}_0) = \tau_0$ . Interest in this paper focuses on the case where  $f$  and  $g$  cannot be specified parametrically. We pose and answer the question: For given smoothness assumptions about  $f$  and  $g$ , how accurately can we estimate  $x_0$  and  $z_0$ ?

Practical interest usually does centre on estimation of  $x_0$  and  $z_0$ , because the production line will be operated for an indefinite (or at least, unspecified) period

---

Received September 1987; revised November 1988.

AMS 1980 subject classifications. Primary 62G05; secondary 62G20.

Key words and phrases. Nonparametric regression, performance measure, PERMIA, quality control, Taguchi's method, variance function estimation.

of time with specific settings of these parameters. Nevertheless one can envisage alternative prescriptions for optimality. For example, if we were to focus on the loss associated with a given choice  $(\hat{x}, \hat{z})$ , we might wish to choose them to minimize

$$E\{f(\hat{x}, \hat{z}) - \tau_0\}^2 \quad \text{or} \quad E|f(\hat{x}, \hat{z}) - \tau_0| \quad \text{or} \quad P\{|f(\hat{x}, \hat{z}) - \tau_0| > c\}.$$

Some insight into the problem may be obtained by simple Taylor expansion, as follows. Assume  $f$  and  $g$  have one and two continuous derivatives, respectively. Then it is reasonable to suppose  $\hat{f}$  and  $\hat{g}$  to satisfy those smoothness conditions. Since  $g'(z_0) = \hat{g}'(\hat{z}_0) = 0$ , then

$$0 = \hat{g}'(\hat{z}_0) = \hat{g}'(z_0) + (\hat{z}_0 - z_0)\hat{g}''(\hat{z}_0^\dagger) = \hat{g}'(z_0) - g'(z_0) + (\hat{z}_0 - z_0)\hat{g}''(\hat{z}_0^\dagger),$$

where  $\hat{z}_0^\dagger$  lies between  $z_0$  and  $\hat{z}_0$ . Therefore,

$$(1.1) \quad \hat{z}_0 - z_0 = -\{\hat{g}'(z_0) - g'(z_0)\} / \hat{g}''(\hat{z}_0^\dagger).$$

Likewise, since  $f(x_0, z_0) = \hat{f}(\hat{x}_0, \hat{z}_0) = \tau_0$ , then

$$\begin{aligned} \tau_0 &= \hat{f}(\hat{x}_0, \hat{z}_0) = \hat{f}(x_0, \hat{z}_0) + (\hat{x}_0 - x_0)\hat{f}^{(1,0)}(\hat{x}_0^*, \hat{z}_0) \\ &= \tau_0 + \hat{f}(x_0, z_0) - f(x_0, z_0) + (\hat{z}_0 - z_0)\hat{f}^{(0,1)}(x_0, \hat{z}_0^*) \\ &\quad + (\hat{x}_0 - x_0)\hat{f}^{(1,0)}(\hat{x}_0^*, \hat{z}_0), \end{aligned}$$

where  $\hat{x}_0^*$  lies between  $x_0$  and  $\hat{x}_0$ , and  $\hat{z}_0^*$  lies between  $z_0$  and  $\hat{z}_0$ . Therefore,

$$(1.2) \quad \begin{aligned} \hat{x}_0 - x_0 &= -\{\hat{f}(x_0, z_0) - f(x_0, z_0)\} / \hat{f}^{(1,0)}(\hat{x}_0^*, \hat{z}_0) \\ &\quad - (\hat{z}_0 - z_0)\hat{f}^{(0,1)}(x_0, \hat{z}_0^*) / \hat{f}^{(1,0)}(\hat{x}_0^*, \hat{z}_0). \end{aligned}$$

From equations (1.1) and (1.2) we conclude that (i) if  $g^{(2)}(z_0)$  is nonzero, then  $z_0$  can be estimated with the same accuracy as  $g^{(1)}(z_0)$ , and (ii) if  $f^{(1,0)}(x_0, z_0)$ ,  $f^{(0,1)}(x_0, z_0)$  and  $g^{(2)}(z_0)$  are nonzero, then  $x_0$  can be estimated with the worst of the accuracies with which  $f(x_0, z_0)$  and  $g^{(1)}(z_0)$  can be estimated. In the pathological event that one or other of these functions should be zero, higher-order Taylor expansions must be investigated.

Thus, estimation of  $x_0$  and  $z_0$  reduces to estimation of  $f$ ,  $g$  and derivatives of those functions. Inference about the mean  $f$  is a classic nonparametric regression problem, but not so inference about the variance  $g$ . There, interest centres on the effect which not knowing  $f$  has on our ability to estimate  $g$ . The problem of variance function estimation in the presence of an unknown  $f$  would be one of semiparametric inference if we had a parametric model for  $f$ .

We now discuss convergence rates obtainable from (1.1) and (1.2). Suppose  $f$  has  $\nu_1$  derivatives and  $g$  has  $\nu_2$  derivatives. We allow  $\nu_1$  and  $\nu_2$  to be arbitrary positive numbers, since fractional derivatives may be expressed in terms of Lipschitz conditions. (See the second paragraph of Section 2 for definitions.) The argument leading to (1.1) and (1.2) requires at least one derivative of  $f$  and two derivatives of  $g$ , and so we assume here that  $\nu_1 > 1$  and  $\nu_2 > 2$ . In Sections 2 and 4 we shall use (1.1) and (1.2) to show that kernel-type estimators achieve

convergence rates

$$(1.3) \quad |\hat{x}_0 - x_0| = O_p\{\max(N^{-\nu/2(\nu_1+1)}, N^{-(\nu_2-1)/(2\nu_2+1)}),\}$$

$$(1.4) \quad |\hat{z}_0 - z_0| = O_p(N^{-(\nu_2-1)/(2\nu_2+1)}),$$

where  $N$  denotes the number of pairs of signal factors and control factors in our sample. The first contribution to the right-hand side of (1.3) is due to the possible effect of not knowing  $f$ . When  $\nu_1 > 1$  and  $\nu_2 > 2$ , not knowing  $f$  has no effect on the accuracy with which we can estimate  $z_0$ , but does influence the accuracy with which we can estimate  $x_0$ . Of course,  $x_0$  is defined in terms of  $f$ , and so this fact occasions no surprise. A necessary and sufficient condition for the right-hand side of (1.3) to equal  $O_p(N^{-(\nu_2-1)/(2\nu_2+1)})$ , and so for there to be no penalty in not knowing  $f$ , is  $\nu_1 \geq (2/3)(\nu_2 - 1)$ .

That there should be some sort of "smoothness threshold" at which not knowing  $f$  begins to worsen performance, is not altogether surprising. If  $f$  is sufficiently smooth, then by working with high-order differences of data points, the influence of  $f$  on variance estimates can be rendered negligible. However, it seems difficult to give a simple, cogent argument describing why the threshold takes the value which it does.

We shall prove in Section 3 that the rates of convergence described by (1.3) and (1.4) are optimal, in the sense that under the stated smoothness assumptions, no nonparametric estimator can achieve faster rates.

Result (1.2), which leads to rates of convergence for estimates of  $z_0$ , requires only  $\nu_2 > 2$  and  $\nu_1 > 0$ . We shall show that in this general circumstance, the best achievable rate of convergence of any estimator of  $z_0$  is

$$(1.5) \quad |\hat{z}_0 - z_0| = O_p\{\max(N^{-(\nu_2-1)/(2\nu_2+1)}, N^{-\nu_1(\nu_2-1)/\{(\nu_1+1)\nu_2\}})\}.$$

For small  $\nu_1$ , this rate is inferior to that described by (1.4) unless  $\nu_1(\nu_2 - 1)/\{(\nu_1 + 1)\nu_2\} \geq (\nu_2 - 1)/(2\nu_2 + 1)$ ; that is, unless  $\nu_1 \geq \nu_2/(\nu_2 + 1)$ . Of course, the latter inequality is always satisfied when  $\nu_1 > 1$ , and in that case (1.4) and (1.5) are identical.

In some respects the problem of estimating  $z_0$  is a little like that of estimating the mode of a density function. See Parzen (1962), Eddy (1980) and Müller (1984) for an account of the latter problem. However, aside from the common feature that the turning point of a nonparametrically determined function is sought in both cases, there are several important dissimilarities. Not least of these is the way in which the variance estimator is defined, in terms of squared residuals which themselves involve a nonparametric curve estimator. There does not seem to be any hope of simplifying our argument by appealing to results on mode estimation.

Most of our attention will be devoted to the case of an experiment of fixed design, defined by model (2.1) in Section 2. Fixed design is more realistic than random design in most control contexts and is amenable to complete asymptotic analysis. Section 4 will outline analogous results in the random design case. Some of this work has a counterpart in heteroscedastic, nonparametric regression and will be discussed elsewhere in that context.

In some applications, our model (2.1) applies only after a data transformation of the response variable. Our discussion still applies for the closeness-to-target problem, by using approximations suggested by Box (1987) [see his equation (15)].

There has recently been work done on variance estimation in nonparametric regression, although unrelated to the problem of variance function minimization. It includes Gasser, Sroka and Jenner (1986), Buckley, Eagleson and Silverman (1988) and Hall and Carroll (1989).

**2. Fixed design case.** In the fixed design case our model is

$$(2.1) \quad Y_{ij} = f(i/n, j/n) + g(j/n)^{1/2} \varepsilon_{ij}, \quad 1 \leq i, j \leq n,$$

where the  $\varepsilon_{ij}$ 's are independent with zero means, unit variances and uniformly bounded fourth moments. We observe the data set  $\{Y_{ij}, 1 \leq i, j \leq n\}$ , and wish to estimate  $f, g$  and their derivatives. Note that there are  $N \equiv n^2$  observations, not  $n$ ; this is important when comparing our results with those in classical nonparametric regression problems.

Let  $\nu > 0$ , and write  $\langle \nu \rangle$  for the largest integer strictly less than  $\nu$ . A univariate function  $g$  is said to be  $\nu$ -smooth if it has  $\langle \nu \rangle$  bounded derivatives and if  $g^{(\langle \nu \rangle)}$  satisfies a Lipschitz condition of order  $\nu - \langle \nu \rangle$ :

$$|g^{(\langle \nu \rangle)}(x) - g^{(\langle \nu \rangle)}(y)| \leq C|x - y|^{\nu - \langle \nu \rangle}$$

for all  $x, y \in (0, 1)$ . A bivariate function  $f$  is said to be  $\nu$ -smooth if  $f^{(i, j)}(x, y)$  exists and is bounded for all  $i \geq 0, j \geq 0$  satisfying  $i + j \leq \langle \nu \rangle$  and if

$$|f^{(i, j)}(u, v) - f^{(i, j)}(x, y)| \leq C(|u - x|^{\nu - \langle \nu \rangle} + |v - y|^{\nu - \langle \nu \rangle})$$

for all  $u, v, x, y \in (0, 1)$  and all  $i \geq 0, j \geq 0$  satisfying  $i + j = \langle \nu \rangle$ . We assume that in model (2.1), the bivariate mean function  $f$  is  $\nu_1$ -smooth and the univariate variance function  $g$  is  $\nu_2$ -smooth.

Our estimates of  $f$  and  $g$  are based on fixed-design analogues of kernel sequences which may be defined as follows. Given  $0 < h_1, h_2 < 1$  and nonnegative integers  $r, s$  and  $t$ , let  $\{a_k(h_1), -\infty < k < \infty\}$ ,  $\{b_k(h_1), -\infty < k < \infty\}$  and  $\{c_k(h_2), -\infty < k < \infty\}$  be sequences of constants satisfying

$$(2.2) \quad \begin{aligned} |a_k| &\leq Ch_1^{r+1}, & |b_k| &\leq Ch_1^{s+1}, & |c_k| &\leq Ch_2^{t+1}, \\ a_k = b_k = 0 & \text{ if } |k| > Ch_1^{-1}, & c_k = 0 & \text{ if } |k| > Ch_2^{-1}, \\ \sum_k k^i a_k &= \begin{cases} r! & \text{if } i = r, \\ 0 & \text{if } 0 \leq i \leq \langle \nu_1 \rangle \text{ and } i \neq r, \end{cases} \\ \sum_k k^i b_k &= \begin{cases} s! & \text{if } i = s, \\ 0 & \text{if } 0 \leq i \leq \langle \nu_1 \rangle \text{ and } i \neq s, \end{cases} \\ \sum_k k^i c_k &= \begin{cases} t! & \text{if } i = t, \\ 0 & \text{if } 0 \leq i \leq \langle \nu_2 \rangle \text{ and } i \neq t. \end{cases} \end{aligned}$$

The constant  $C$  does not depend on  $h_1$  or  $h_2$ .

To construct  $\{a_k\}$ , for example, let  $K$  be a compactly supported, real-valued,  $r$ -times continuously differentiable function satisfying  $\int u^i K(u) du = 1$  if  $i = 0$  and  $= 0$  if  $1 \leq i \leq \langle \nu_1 \rangle$ . Put  $L(u) \equiv (-1)^r K^{(r)}(u)$ . Then  $\int u^i L(u) du = r!$  if  $i = r$  and  $= 0$  if  $0 \leq i \leq \langle \nu_1 \rangle$  and  $i \neq r$ . A slight adjustment of  $L$ , taking account of errors in series approximations to integrals and giving the function  $L_1$ , say, ensures that  $a_k \equiv h_1^{r+1} L_1(h_1 k)$  has the desired properties.

Our estimator of  $f^{(r,s)}$  is

$$(2.3) \quad \hat{f}^{(r,s)}(i/n, j/n) \equiv n^{r+s} \sum_k \sum_l a_k b_l Y_{i+k, j+l},$$

where  $Y_{ij}$  is defined to be zero if one or other of  $i, j$  is less than 1 or greater than  $n$ . Basic properties of  $\hat{f}^{(r,s)}$  are described by the following theorem.

**THEOREM 2.1.** *Assume  $f$  is  $\nu_1$ -smooth,  $\nu_1 \geq r + s$ ,  $g$  is bounded,  $\sup E(\epsilon_{ij}^2) < \infty$  and  $h_1 = h_1(n)$  satisfies  $h_1 \rightarrow 0$  and  $nh_1 \rightarrow \infty$ . Then, for each  $0 < \delta < \frac{1}{2}$ ,*

$$(2.4) \quad \sup_{\delta n < i, j < (1-\delta)n} |E\hat{f}^{(r,s)}(i/n, j/n) - f^{(r,s)}(i/n, j/n)| = O\{(nh_1)^{-(\nu_1-r-s)}\},$$

$$(2.5) \quad \sup_{1 \leq i, j \leq n} \text{var}\{\hat{f}^{(r,s)}(i/n, j/n)\} = O\{(nh_1)^{2(r+s)} h_1^2\}.$$

**REMARK 2.1.** Given any  $(x, y) \in (0, 1)^2$ , we may define  $\hat{f}^{(r,s)}(x, y)$  by linear interpolation among the four vertices of the integer square containing  $(x, y)$ . It is easily shown that analogues of (2.4) and (2.5) hold for this ‘‘more general’’ estimator:

$$\sup_{\delta < x, z < 1-\delta} |E\hat{f}^{(r,s)}(x, z) - f^{(r,s)}(x, z)| = O\{(nh_1)^{-(\nu_1-r-s)}\},$$

$$\sup_{0 < x, z < 1} \text{var}\{\hat{f}^{(r,s)}(x, z)\} = O\{(nh_1)^{2(r+s)} h_1^2\}.$$

**REMARK 2.2.** It follows from Theorem 2.1 that the mean squared error of  $\hat{f}^{(r,s)}$  is

$$(2.6) \quad \begin{aligned} E\{\hat{f}^{(r,s)}(i/n, j/n) - f^{(r,s)}(i/n, j/n)\}^2 \\ = O\{(nh_1)^{-2(\nu_1-r-s)} + (nh_1)^{2(r+s)} h_1^2\}, \end{aligned}$$

uniformly in  $\delta n \leq i, j \leq (1 - \delta)n$ . The order of magnitude of the right-hand side is minimized at  $O(n^{-2(\nu_1-r-s)/(\nu_1+1)}) = O(N^{-(\nu_1-r-s)/(\nu_1+1)})$  by taking  $h_1 = n^{-\nu_1/(\nu_1+1)}$ . By modifying techniques of Stone (1980) we may show that the rate  $O(N^{-(\nu_1-r-s)/(\nu_1+1)})$  is optimal in a minimax sense, where the maximum is over the class of  $\nu_1$ -smooth functions having a given constant  $C$  in the Lipschitz condition and in bounds on derivatives.

If we knew  $f$ , we could form the ‘‘true’’ residuals  $r_{ij} \equiv Y_{ij} - f(i/n, j/n) = g(j/n)^{1/2} \epsilon_{ij}$  and construct an estimator  $\tilde{g}^{(t)}$  of  $g^{(t)}$  as follows:

$$(2.7) \quad \tilde{g}^{(t)}(j/n) \equiv n^{t-1} \sum_{i=1}^n \sum_k c_k r_{i, j+k}^2.$$

Here  $r_{ij}$  is defined to be zero if  $j < 1$  or  $j > n$ , and  $\{c_k\}$  is as in (2.2). An argument similar to that employed to prove Theorem 2.1 may be used to establish:

**THEOREM 2.2.** *Assume  $g$  is  $\nu_2$ -smooth,  $\nu_2 > t$ ,  $E(\varepsilon_{ij}^4)$  is uniformly bounded and  $h_2 = h_2(n)$  satisfies  $h_2 \rightarrow 0$  and  $nh_2 \rightarrow \infty$ . Then for each  $0 < \delta < \frac{1}{2}$ ,*

$$\sup_{\delta n < j < (1-\delta)n} |E\tilde{g}^{(t)}(j/n) - g^{(t)}(j/n)| = O\{(nh_2)^{-(\nu_2-t)}\}$$

$$\sup_{1 \leq j \leq n} \text{var}\{\tilde{g}^{(t)}(j/n)\} = O\{(nh_2)^{2t-1}h_2^2\}.$$

**REMARK 2.3.** It follows from Theorem 2.2 that the mean squared error of  $\tilde{g}^{(t)}$  satisfies

$$(2.8) \quad E\{\tilde{g}^{(t)}(j/n) - g^{(t)}(j/n)\}^2 = O\{(nh_2)^{-2(\nu_2-t)} + (nh_2)^{2t-1}h_2^2\}.$$

The right-hand side here is minimized by taking  $h_2 = n^{-(2\nu_2-1)/(2\nu_2+1)}$ , giving a mean square error of  $O(n^{-4(\nu_2-t)/(2\nu_2+1)}) = O(N^{-2(\nu_2-t)/(2\nu_2+1)})$ . Again, this rate is optimal if  $f$  is known. However, we pay a penalty for not knowing  $f$ , as Theorem 2.3 shows.

Replace the true residual  $r_{ij}$  by its estimate  $\hat{r}_{ij} \equiv Y_{ij} - \hat{f}(i/n, j/n)$ , giving rise to the following practical estimator of  $g^{(t)}$ :

$$(2.9) \quad \hat{g}^{(t)}(j/n) \equiv n^{t-1} \sum_{i=1}^n \sum_k c_k \hat{r}_{i,j+k}^2.$$

**THEOREM 2.3.** *Assume  $f$  is  $\nu_1$ -smooth,  $g$  is  $\nu_2$ -smooth,  $\nu_2 > t$ ,  $E(\varepsilon_{ij}^4)$  is uniformly bounded and  $h_i = h_i(n)$  satisfies  $h_i \rightarrow 0$  and  $nh_i \rightarrow \infty$  for  $i = 1, 2$ . Then for each  $0 < \delta < \frac{1}{2}$ ,*

$$(2.10) \quad \sup_{\delta n < j < (1-\delta)n} E\{\hat{g}^{(t)}(j/n) - g^{(t)}(j/n)\}^2 = O\left[\{(nh_2)^{-2(\nu_2-t)} + (nh_2)^{2t-1}h_2^2\} + (nh_2)^{2t}\{(nh_1)^{-2\nu_1} + h_1^2\}^2\right].$$

**REMARK 2.4.** The order of the mean squared error of  $\hat{g}^{(t)}$  is that of the mean squared error of  $\tilde{g}^{(t)}$ , plus  $(nh_2)^{2t}$  times the square of the mean squared error of  $\hat{f}$ ; compare (2.8) and (2.10), noting result (2.6) for  $r = s = 0$ . The additional term represents the penalty in not knowing  $f$  when estimating  $g^{(t)}$ .

**REMARK 2.5.** The value of  $h_1$  which minimizes the order of the second term on the right-hand side of (2.10) is  $h_1 = h_1^* \equiv n^{-\nu_1/(\nu_1+1)}$ . Using this value of  $h_1$ , we find that

$$(2.11) \quad E\{\hat{g}^{(t)}(j/n) - g^{(t)}(j/n)\}^2 = O\left[\{(nh_2)^{-2(\nu_2-t)} + (nh_2)^{2t-1}h_2^2\} + (nh_2)^{2t}n^{-4\nu_1/(\nu_1+1)}\right].$$

The value of  $h_2$  which minimizes the order of  $A(h_2) \equiv (nh_2)^{-2(\nu_2-t)} + (nh_2)^{2t-1}h_2^2$  is  $h_2 = h_2^* \equiv n^{-(2\nu_2-1)/(2\nu_2+1)}$  and  $A(h_2^*) = 2n^{-4(\nu_2-t)/(2\nu_2+1)}$ . Furthermore,  $(nh_2^*)^{2t}n^{-4\nu_1/(\nu_1+1)} \leq A(h_2^*)$  if and only if

$$(2.12) \quad \nu_1 \geq \nu_2/(\nu_2 + 1).$$

Therefore, when (2.12) is true, the term involving  $h_1$  on the right-hand side of (2.10) does not influence the convergence rate of the optimally constructed version of  $\hat{g}^{(t)}$ , and for  $h_1 = h_1^*$  and  $h_2 = h_2^*$ ,

$$E\{\hat{g}^{(t)}(j/n) - g^{(t)}(j/n)\}^2 = O(n^{-4(\nu_2-t)/(2\nu_2+1)}).$$

This is the same as the best rate of convergence of  $\tilde{g}^{(t)}$ ; see Remark 2.3.

REMARK 2.6. If (2.12) fails, then there is a cost to estimating  $f$ . An optimal balance among terms on the right-hand side of (2.11) is achieved by making  $(nh_2)^{-2(\nu_2-t)}$  the same size as  $(nh_2)^{2t}n^{-4\nu_1/(\nu_1+1)}$ . This is, take  $h_2 = h_2^{**} \equiv n^{\{2\nu_1 - \nu_2(\nu_1+1)\}/\{(\nu_1+1)\nu_2\}}$ , in which case

$$E\{\hat{g}^{(t)}(j/n) - g^{(t)}(j/n)\}^2 = O(n^{-4\nu_1(\nu_2-t)/\{(\nu_1+1)\nu_2\}}).$$

REMARK 2.7. Note that  $h_2^{**}$  [the optimal version of  $h_2$  when (2.12) fails] is different from  $h_2^*$  [the optimal  $h_2$  when (2.12) holds]. Also, none of  $h_1^*$ ,  $h_2^*$  and  $h_2^{**}$  depends on  $t$ .

REMARK 2.8. We may summarize the main points made during Remarks 2.5 and 2.6 by stating that if  $\hat{g}^{(t)}$  is constructed using  $h_1 = h_1^*$  and  $h_2 = h_2^*$  [if (2.12) holds] or  $h_2 = h_2^{**}$  [if (2.12) fails], then

$$(2.13) \quad E\{\hat{g}^{(t)}(j/n) - g^{(t)}(j/n)\}^2 = O\{\max(n^{-4(\nu_2-t)/(2\nu_2+1)}, n^{-4\nu_1(\nu_2-t)/\{(\nu_1+1)\nu_2\}})\}.$$

The term involving only  $\nu_2$  dominates the right-hand side here if (2.12) holds, while the other term dominates if (2.12) fails. We shall show in Section 3 that the rate of convergence described by (2.13) is optimal in a minimax sense.

To solve the first part of our control problem, we need to estimate that value  $z_0$  which minimizes  $g$ . If  $g$  has a continuous derivative, then this amounts to estimating the solution  $z_0$  of the equation  $g^{(1)}(z) = 0$ . A potential estimator  $\hat{g}^{(1)}(z)$  of  $g^{(1)}(z)$  may be obtained by interpolating among values of  $\hat{g}^{(1)}(j/n)$ , defined at (2.9). However, this approach results in a very rough estimator, without even a single continuous derivative. There are several ways of deriving a smoother estimator. One is to derive  $\hat{g}^{(2)}(z)$  by linearly interpolating among values of  $\hat{g}^{(2)}(j/n)$ , and then estimate  $g^{(1)}$  by integrating  $\hat{g}^{(2)}$ . This we do below.

Define  $\hat{g}^{(1)}(j/n)$  and  $\hat{g}^{(2)}(j/n)$  as at (2.9), construct  $\hat{g}^{(2)}(z)$  by linearly interpolating among points  $\hat{g}^{(2)}(j/n)$  and, for an arbitrary  $j_0$  satisfying  $j_0 \sim n\alpha$

for some  $0 < \alpha < 1$ , put

$$\bar{g}^{(1)}(z) \equiv \hat{g}^{(1)}(j_0/n) + \int_{j_0/n}^z \hat{g}^{(2)}(u) du, \quad 0 < z < 1.$$

This will be our estimator of  $g^{(1)}(z)$ . It is continuously differentiable, with derivative  $(\bar{g}^{(1)})'(z) = \hat{g}^{(2)}(z)$ , and is a quadratic interpolation of an estimator “like”  $\hat{g}^{(1)}$ . It shares the mean squared error properties of  $\hat{g}^{(1)}$ , as follows.

**THEOREM 2.4.** *Assume the conditions of Theorem 2.3, with  $t = 1$ . Then for each  $0 < \delta < \frac{1}{2}$ ,*

$$(2.14) \quad \sup_{\delta < z < 1-\delta} E\{\bar{g}^{(1)}(z) - g^{(1)}(z)\}^2 = O\left[\{(nh_2)^{-2(\nu_2-1)} + nh_2^3\} + (nh_2)^2\{(nh_1)^{-2\nu_1} + h_1^2\}^2\right].$$

**REMARK 2.9.** Note that the right-hand sides of (2.10) (for  $t = 1$ ) and (2.14) are identical.

**REMARK 2.10.** The conditions in Theorem 2.4 do not require the existence of a second derivative of  $g$ , even though  $\hat{g}^{(2)}$  is used in the construction of  $\bar{g}^{(1)}$ . We need only assume  $\nu_2 > 1$ ; of course,  $\hat{g}^{(2)}$  is well-defined without any smoothness assumptions, being given by formula (2.9).

We are now in a position to solve the first part of our control problem. Let  $\hat{z}_0$  be any solution of the equation  $\bar{g}^{(1)}(\hat{z}_0) = 0$ , and  $z_0$  be the unique solution of  $g^{(1)}(z_0) = 0$ . Then

$$(2.15) \quad 0 = \bar{g}^{(1)}(\hat{z}_0) = \bar{g}(z_0) + (\hat{z}_0 - z_0)\hat{g}^{(2)}\{z_0 + \hat{\theta}(\hat{z}_0 - z_0)\},$$

where  $0 \leq \hat{\theta} \leq 1$ . Assume  $g$  is  $\nu_2$ -smooth for some  $\nu_2 > 2$ . Then  $g^{(2)}$  is well-defined and continuous. Suppose that for an integer  $l \geq 1$ ,  $4l$ th moments of the errors  $\varepsilon_{ij}$  are uniformly bounded. Then the argument leading to Theorem 2.3 may be generalized to prove that for each  $0 < \delta < \frac{1}{2}$ ,

$$\sup_{\delta n < j < (1-\delta)n} E\{\hat{g}^{(2)}(j/n) - g^{(2)}(j/n)\}^{2l} = O\{B_2(h_1, h_2)^l\},$$

where  $B_t(h_1, h_2) \equiv \{(nh_2)^{-2(\nu_2-t)} + (nh_2)^{2t-1}h_2^2\} + (nh_2)^{2t}\{(nh_1)^{-2\nu_1} + h_1^2\}^2$ . Choose  $h_1, h_2$  to minimize the order of  $B_1(h_1, h_2)$ , as described in Remark 2.8. Then  $B_2(h_1, h_2) = O(n^{-b})$ , where  $b \equiv \min[4(\nu_2 - 2)/(2\nu_2 + 1), 4\nu_1(\nu_2 - 2)/\{(\nu_1 + 1)\nu_2\}] > 0$ . If  $l > 1/b$ , then for each  $\eta > 0$  and each  $0 < \delta < \frac{1}{2}$ , we have by Markov’s inequality,

$$P\left\{\sup_{\delta n < j < (1-\delta)n} |\hat{g}^{(2)}(j/n) - g^{(2)}(j/n)| > \eta\right\} = O(n^{1-bl}) = o(1),$$



so that

$$(2.16) \quad \sup_{\delta < z < 1 - \delta} |\hat{g}^{(2)}(z) - g^{(2)}(z)| = o_p(1).$$

Therefore, by (2.15), assuming that  $g^{(2)}(z_0) \neq 0$ ,

$$\hat{z}_0 - z_0 = -\{1 + o_p(1)\} \{ \bar{g}^{(1)}(z_0) - g^{(1)}(z_0) \} / g^{(2)}(z_0).$$

We conclude that  $\hat{z}_0$  converges to  $z_0$  at the same rate as  $\bar{g}^{(1)}(z_0)$  converges to  $g^{(1)}(z_0)$ ; that is,

$$(2.17) \quad |\hat{z}_0 - z_0| = O_p\{ \max(n^{-2(\nu_2-1)/(2\nu_2+1)}, n^{-2\nu_1(\nu_2-1)/\{( \nu_1+1)\nu_2\}}) \}.$$

This is result (1.5), announced in Section 1, and implies (1.4) when  $\nu_1 > 1$ .

The second part of our control problem consists of estimating the value  $x_0$  which satisfies  $f(x_0, z_0) = \tau_0$ . An estimator of  $f$  is  $\hat{f} = \hat{f}^{(0,0)}$ , defined in (2.3) with  $r = s = 0$ . However, as in the case of our estimator of  $g^{(1)}$ , this suffers from being "too rough." Therefore we compute  $\hat{f}^{(0,1)}$ ,  $\hat{f}^{(1,0)}$  and  $\hat{f}^{(1,1)}$  by linearly interpolating among values defined in (2.3), and then derive an estimator  $\bar{f}$  of  $f$  by integration, as follows. Let  $i_0, j_0$  satisfy  $i_0 \sim n\alpha, j_0 \sim n\beta$ , where  $0 < \alpha, \beta < 1$ , and put

$$(2.18) \quad \begin{aligned} \bar{f}(x, z) \equiv & \hat{f}(i_0/n, j_0/n) + \int_{i_0/n}^x \hat{f}^{(1,0)}(u, j_0/n) du + \int_{j_0/n}^z \hat{f}^{(0,1)}(i_0/n, v) dv \\ & + \int_{i_0/n}^x du \int_{j_0/n}^z \hat{f}^{(1,1)}(u, v) dv, \quad 0 < x, z < 1. \end{aligned}$$

This will be our estimator of  $f(x, z)$ . It is continuously differentiable in both variables, satisfying

$$(\partial/\partial x)\bar{f}(x, z) = \hat{f}^{(1,0)}(x, j_0/n) + \int_{j_0/n}^z \hat{f}^{(1,1)}(x, v) dv$$

and an analogous expression for  $(\partial/\partial z)\bar{f}(x, z)$ . It shares the mean squared error properties of  $\hat{f}^{(0,0)}$ , as follows.

**THEOREM 2.5.** *Assume the condition of Theorem 2.1, with  $r = s = 0$ . Then for each  $0 < \delta < \frac{1}{2}$ ,*

$$(2.19) \quad \sup_{\delta < z < 1 - \delta} E\{ \bar{f}(x, z) - f(x, z) \}^2 = O\{ (nh_1)^{-2\nu_1} + h_1^2 \}.$$

**REMARK 2.11.** Note that the right-hand sides of (2.14) (for  $r = s = 0$ ) and (2.19) are identical.

**REMARK 2.12.** Theorem 2.5 does not require the existence of any derivative of  $f$ , even though numerical values of  $\hat{f}^{(0,1)}$ ,  $\hat{f}^{(1,0)}$  and  $\hat{f}^{(1,1)}$  are used in the construction of  $\bar{f}$ .

We are now in a position to solve the second part of our control problem. Suppose  $f$  is  $\nu_1$ -smooth, where  $\nu_1 > 1$ . Then  $f^{(0,1)}$  and  $f^{(1,0)}$  are well-defined and continuous. Assume  $f^{(0,1)}(x_0, z_0) \neq 0 \neq f^{(1,0)}(x_0, z_0)$ . Define  $\bar{f}$  as at (2.18) and write  $\bar{f}^{(i,j)}(x, z)$  for  $(\partial/\partial x)^i(\partial/\partial z)^j \bar{f}(x, z)$ . Choose  $h_1 = n^{-\nu_1/(\nu_1+1)}$  to minimize the order of  $(nh_1)^{-2\nu_1} + h_1^2$ . Then by (2.19),

$$(2.20) \quad |\bar{f}(x_0, z_0) - f(x_0, z_0)| = O_p(n^{-\nu_1/(\nu_1+1)}).$$

Suppose that for an integer  $l \geq 1$ ,  $2l$ th moments of the errors  $\varepsilon_{ij}$  are uniformly bounded. The argument leading to (2.16) may be modified to show that if  $l$  is sufficiently large, then for each  $0 < \delta < \frac{1}{2}$ ,

$$(2.21) \quad \sup_{\delta < x, z < 1-\delta} |\bar{f}^{(i,j)}(x, z) - f^{(i,j)}(x, z)| = o_p(1)$$

for  $(i, j) = (0, 1)$  or  $(1, 0)$ . Using the Taylor expansion which produced (1.2) we may now deduce that

$$\begin{aligned} \hat{x}_0 - x_0 = & -\{1 + o_p(1)\} \{ \bar{f}(x_0, z_0) - f(x_0, z_0) \} / f^{(1,0)}(x_0, z_0) \\ & - \{1 + o_p(1)\} (\hat{z}_0 - z_0) f^{(0,1)}(x_0, z_0) / f^{(1,0)}(x_0, z_0). \end{aligned}$$

We conclude that the rate of convergence of  $\hat{x}_0$  to  $x_0$  is the worst of the rates of convergence of  $\bar{f}(x_0, z_0)$  to  $f(x_0, z_0)$  and of  $\hat{z}_0$  to  $z_0$ . By (2.17) and (2.20), this is

$$\begin{aligned} |\hat{x}_0 - x_0| = & O_p\{ \max(n^{-\nu_1/(\nu_1+1)}, n^{-2(\nu_2-1)/(2\nu_2+1)}, n^{-2\nu_1(\nu_2-1)/((\nu_1+1)\nu_2)}) \} \\ = & O_p\{ \max(n^{-\nu_1/(\nu_1+1)}, n^{-2(\nu_2-1)/(2\nu_2+1)}) \}, \end{aligned}$$

the second identity following from the fact that  $\nu_1 > 1$ . This is result (1.3), announced in Section 1.

**PROOF OF THEOREM 2.1.** We begin with a lemma.

**LEMMA.** *Let  $m \geq 0$ . Suppose the bivariate function  $f$  has continuous derivatives  $f^{(i,j)}$ , for  $i \geq 0, j \geq 0$  and  $i + j \leq m$ , on the square  $[0, 1]^2$ . There exist numbers  $\theta_{i_1}, \theta_{i_2}$  satisfying  $0 \leq \theta_{ij} \leq 1$ , such that*

$$\begin{aligned} f(u_1 + \delta_1, u_2 + \delta_2) = & \sum_{0 \leq i+j \leq m-1} (\delta_1^i \delta_2^j / i! j!) f^{(i,j)}(u_1, u_2) \\ & + \sum_{i+j=m} (\delta_1^i \delta_2^j / i! j!) f^{(i,j)}(u_1 + \theta_{i_1} \delta_1, u_2 + \theta_{i_2} \delta_2) \end{aligned}$$

whenever  $u_1, u_2, u_1 + \delta_1, u_2 + \delta_2 \in [0, 1]$ .

To prove the lemma, write  $f(u_1 + \delta_1, u_2 + \delta_2) = \{f(u_1 + \delta_1, u_2 + \delta_2) - f(u_1, u_2 + \delta_2)\} + f(u_1, u_2 + \delta_2)$ , and repeatedly apply the univariate version of Taylor's theorem with remainder.

To prove (2.4), put  $m \equiv \langle \nu_1 \rangle$  and apply the lemma, obtaining for integer  $\alpha$  and  $\beta$ ,

$$\begin{aligned} & E \left\{ \hat{f}^{(r,s)} \left( \frac{\alpha}{n}, \frac{\beta}{n} \right) - f^{(r,s)} \left( \frac{\alpha}{n}, \frac{\beta}{n} \right) \right\} \\ &= n^{r+s} \sum_k \sum_l a_k b_l \sum_{i+j=m} \frac{(k/n)^i (l/n)^j}{i! j!} \\ &\quad \times \left\{ f^{(i,j)} \left( \frac{\alpha + \theta_{i1} k}{n}, \frac{\beta + \theta_{i2} l}{n} \right) - f^{(i,j)} \left( \frac{\alpha}{n}, \frac{\beta}{n} \right) \right\} \\ &= O \left( n^{r+s} \sum_k \sum_l \sum_{i+j=m} \left| \left( \frac{k}{n} \right)^i \left( \frac{l}{n} \right)^j a_k b_l \left( \left| \frac{k}{n} \right|^{\nu_1 - m} + \left| \frac{l}{n} \right|^{\nu_1 - m} \right) \right| \right) \\ &= O \{ (nh_1)^{r+s-\nu_1} \}. \end{aligned}$$

To prove (2.5), observe that

$$\text{var} \left\{ \hat{f}^{(r,s)} \left( \frac{i}{n}, \frac{j}{n} \right) \right\} = O \{ n^{2(r+s)} (\sum a_k^2) (\sum b_k^2) \} = O \{ (nh_1)^{2(r+s)} h_1^2 \}. \quad \square$$

**PROOF OF THEOREM 2.3.** Take  $r = s = 0$ , in which case we may assume  $a_l = b_l$ , and our estimator of  $f$  is

$$\hat{f}(i/n, j/n) = \sum_{l_1} \sum_{l_2} a_{l_1} a_{l_2} Y_{i+l_1, j+l_2}.$$

Put

$$\Delta_{ij} \equiv \sum_{l_1} \sum_{l_2} a_{l_1} a_{l_2} g \{ (j + l_2)/n \}^{1/2} \varepsilon_{i+l_1, j+l_2}$$

and

$$B_{ij} \equiv \sum_{l_1} \sum_{l_2} a_{l_1} a_{l_2} f \{ (i + l_1)/n, (j + l_2)/n \} - f(i/n, j/n).$$

In this notation,  $\hat{r}_{ij} = r_{ij} - \Delta_{ij} - B_{ij}$ , so that  $n^{1-t} \hat{g}^{(t)}(j/n) = n^{1-t} \tilde{g}^{(t)}(j/n) - 2A_j + B_j$ , where

$$A_j \equiv \sum_{i=1}^n \sum_k (\Delta_{i, j+k} + B_{i, j+k}) r_{i, j+k} c_k, \quad B_j \equiv \sum_{i=1}^n \sum_k (\Delta_{i, j+k} + B_{i, j+k})^2 c_k.$$

Therefore, in view of (2.8), it suffices to prove that

$$\begin{aligned} (2.22) \quad & E(A_j^2) = O \left[ (nh_2^t)^2 \{ (nh_1)^{-2\nu_1} + h_1^2 \}^2 + h_2^{2(t+1)} \right], \\ & E(B_j^2) = O \left[ (nh_2^t)^2 \{ (nh_1)^{-2\nu_1} + h_1^2 \}^2 \right]. \end{aligned}$$

Since  $A_j \equiv \sum_i \sum_k (\Delta_{i, j+k} + B_{i, j+k}) \mathcal{G}\{(j+k)/n\}^{1/2} \varepsilon_{i, j+k} c_k$ , then

$$(2.23) \quad \begin{aligned} \frac{1}{2} E(A_j^2) &\leq E \left[ \sum_i \sum_k \Delta_{i, j+k} \varepsilon_{i, j+k} \mathcal{G}\{(j+k)/n\}^{1/2} c_k \right]^2 \\ &\quad + E \left[ \sum_i \sum_k \varepsilon_{i, j+k} B_{i, j+k} \mathcal{G}\{(j+k)/n\}^{1/2} c_k \right]^2. \end{aligned}$$

Now,

$$\begin{aligned} &E(\Delta_{i_1, j+k_1} \varepsilon_{i_1, j+k_1} \Delta_{i_2, j+k_2} \varepsilon_{i_2, j+k_2}) \\ &= \sum_{l_1, \dots, l_4} \dots \sum_{l_4} a_{l_1, \dots, l_4} \left[ \prod_{\alpha=1}^4 \mathcal{G}\{(j+l_\alpha)/n\} \right]^{1/2} \\ &\quad \times E(\varepsilon_{i_1+l_1, j+k_1+l_2} \varepsilon_{i_1, j+k_1} \varepsilon_{i_2+l_3, j+k_2+l_4} \varepsilon_{i_2, j+k_2}) \\ &= O\{h_1^4 + h_1^2 I(i_1 = i_2, k_1 = k_2)\}. \end{aligned}$$

Hence, the first term on the right-hand side of (2.23) equals

$$\begin{aligned} &O \left[ \sum_{i_1, i_2, k_1, k_2} \dots \sum \{h_1^4 + h_1^2 I(i_1 = i_2, k_1 = k_2)\} h_2^{2(t+1)} I(|k_1|, |k_2| \leq Ch_2^{-1}) \right] \\ &= O\{(nh_2^t)^2 h_1^4 + nh_1^2 h_2^{2t+1}\} = O\{(nh_2^t)^2 h_1^4 + h_2^{2(t+1)}\}. \end{aligned}$$

Since  $|B_{i,j}| = O\{(nh_1)^{-\nu_1}\}$ , then the second term on the right-hand side of (2.23) equals

$$\begin{aligned} E(\varepsilon_{11}^2) \sum_i \sum_k B_{i, j+k}^2 \mathcal{G}\{(j+k)/n\} c_k^2 &= O\{(nh_1)^{-2\nu_1} nh_2^{2t+1}\} \\ &= O\{(nh_2^t)^2 (nh_1)^{-4\nu_1} + h_2^{2(t+1)}\}. \end{aligned}$$

Combining estimates from (2.23) down we get the first part of (2.22). The second part follows from the fact that  $|c_k| \leq Ch_2^{t+1} I(|k| \leq Ch_2^{-1})$ ,  $E(\Delta_{ij}^4) = O(h_1^4)$  and  $|B_{i,j}| = O\{(nh_1)^{-\nu_1}\}$ .  $\square$

**PROOF OF THEOREM 2.4.** If  $j/n \leq u \leq (j+1)/n$ , then

$$\hat{g}^{(2)}(n) = (nu - j) \hat{g}^{(2)}\{(j+1)/n\} + (j+1 - nu) \hat{g}^{(2)}(j/n),$$

whence

$$\int_{j/n}^{(j+1)/n} \hat{g}^{(2)}(u) du = (2n)^{-1} [\hat{g}^{(2)}(j/n) + \hat{g}^{(2)}\{(j+1)/n\}].$$

Therefore, if  $j/n \leq z \leq (j+1)/n$  and  $j \geq j_0 + 2$ ,

$$\begin{aligned} \bar{g}^{(1)}(z) &= \hat{g}^{(1)}(j_0/n) + n^{-1} \sum_{i=j_0+1}^{j-1} \hat{g}^{(2)}(i/n) + T_1 + T_2 \\ &= \hat{g}^{(1)}(j_0/n) + \hat{g}^{*(1)}\{(j-1)/n\} - \hat{g}^{*(1)}(j_0/n) + T_1 + T_2, \end{aligned}$$

where

$$\hat{g}^{*(1)}(j/n) = \sum_{i=1}^n \sum_k d_k \hat{r}_{i,j+k}^2, \quad d_k \equiv \sum_{l=0}^{\infty} c_{k+l},$$

$$T_1 \equiv \int_{j/n}^z \hat{g}^{(2)}(u) du, \quad T_2 \equiv (2n)^{-1} \{ \hat{g}^{(2)}(j_0/n) + \hat{g}^{(2)}(j/n) \}.$$

If  $\{c_k\}$  satisfies condition (2.2) with  $t = 2$ , then  $\{d_k\}$  satisfies the same condition (stated there for  $\{c_k\}$ ) with  $t = 1$ . Therefore, Theorem 2.4 will follow from Theorem 2.3 if we prove that, for  $i = 1$  and 2,

$$(2.24) \quad E(T_i^2) = O \left[ (nh_2)^{-2(\nu_2-1)} + nh_2^3 + (nh_2)^2 \{ (nh_1)^{-2\nu_1} + h_1^2 \}^2 \right].$$

(The case of  $j$  values with  $j \leq j_0 + 1$  may be treated similarly. Note that we may not, and do not, assume existence of  $g^{(2)}$ .)

Observe that

$$E(T_1^2) \leq n^{-2} \sup_{j/n \leq u \leq (j+1)/n} E\{ \hat{g}^{(2)}(u)^2 \} \leq 2n^{-2} \max_{l=j, j+1} E\{ \hat{g}^{(2)}(l/n)^2 \}.$$

Let  $A_j, B_j$  be as in the Proof of Theorem 2.3, this time with  $t = 2$ . Then  $\hat{g}^{(2)}(l/n) = \tilde{g}^{(2)}(l/n) + n(B_l - 2A_l)$  and (as shown during our proof of Theorem 2.3)  $E(A_l^2) + E(B_l^2) = O[(nh_2^2)^2 \{ (nh_1)^{-2\nu_1} + h_1^2 \}^2 + h_2^6]$ . Also,

$$n^{-2} E\{ \hat{g}^{(2)}(l/n)^2 \} \leq 16 \left[ n^{-2} E\{ \tilde{g}^{(2)}(l/n)^2 \} + E(A_l^2) + E(B_l^2) \right],$$

and, since  $\tilde{g}^{(2)}(l/n) = n \sum_i \sum_k c_k g\{(l+k)/n\} \varepsilon_{i,l+k}^2$ , then

$$\begin{aligned} E\{ \tilde{g}^{(2)}(l/n)^2 \} &= \text{var}\{ \tilde{g}^{(2)}(l/n) \} + \{ E\tilde{g}^{(2)}(l/n) \}^2 \\ &= O \left[ n^3 \sum_k c_k^2 + \left| n^2 \sum_k c_k g\{(l+k)/n\} \right|^2 \right] \\ &= O \{ n^3 h_2^5 + (nh_2)^{2(2-\nu_2)} \}. \end{aligned}$$

Combining all these estimates we conclude that, for  $i = 1$  and 2,

$$E(T_i^2) = O \left[ nh_2^5 + (nh_2)^{-2(\nu_2-1)} h_2^2 + (nh_2^2)^2 \{ (nh_1)^{-2\nu_1} + h_1^2 \}^2 \right],$$

from which follows (2.24).  $\square$

**3. Optimal rates of convergence.** In this section we show that the convergence rates derived in Section 2 for kernel-type estimators cannot be improved upon by other estimators. Our optimality results will be in the form of “worst possible” rates computed over function classes. It is a trivial matter to obtain the same rates for our kernel-type estimators by extending arguments in Section 2. In the next paragraph we define the function classes and state the extended results.

Given positive numbers  $\nu_1, \nu_2$  and  $B$ , let  $\mathcal{C}_1 = \mathcal{C}_1(\nu_1, B)$  be the class of bivariate functions  $f$  on  $[0, 1]^2$  for which  $\sup |f^{(i,j)}| \leq B$  whenever  $i \geq 0, j \geq 0$

and  $i + j \leq \langle \nu_1 \rangle$ , and

$$|f^{(i,j)}(u, v) - f^{(i,j)}(x, y)| \leq B(|u - x|^{\nu_1 - \langle \nu_1 \rangle} + |v - y|^{\nu_1 - \langle \nu_1 \rangle})$$

whenever  $u, v, x, y \in [0, 1]$ ,  $i \geq 0$ ,  $j \geq 0$  and  $i + j = \langle \nu_1 \rangle$ . Let  $\mathcal{C}_2 = \mathcal{C}_2(\nu_2, B)$  be the class of nonnegative univariate functions  $g$  on  $[0, 1]$  for which  $\sup|g^{(i)}| \leq B$  whenever  $0 \leq i \leq \langle \nu_2 \rangle$  and

$$|g^{(\langle \nu_2 \rangle)}(x) - g^{(\langle \nu_2 \rangle)}(y)| \leq B|x - y|^{\nu_2 - \langle \nu_2 \rangle}$$

whenever  $x, y \in [0, 1]$ . Let  $\mathcal{C}_3 = \mathcal{C}_3(B)$  be the class of nonnegative univariate functions  $g$  on  $[0, 1]$  such that  $\sup g \leq B$ . Take  $\hat{f}^{(r,s)}$ ,  $\tilde{g}^{(t)}$  and  $\hat{g}^{(t)}$  to be the estimators defined at (2.3), (2.7) and (2.9), respectively, calculated by linear interpolation at points which are not integer multiples of  $n^{-1}$ . (See Remark 2.1.) Assume that  $\nu_1 > r + s$  and  $\nu_2 > t$ . For appropriate choices of the smoothing parameters  $h_1$  and  $h_2$ , and for each  $0 < \delta < \frac{1}{2}$ , there exist positive constants  $C_1$ ,  $C_2$  and  $C_3$  depending on  $\nu_1$ ,  $\nu_2$  and  $B$  such that

$$\begin{aligned} \sup_{f \in \mathcal{C}_1, g \in \mathcal{C}_3} \sup_{\delta < x, z < 1 - \delta} E_{f,g} \{ \hat{f}^{(r,s)}(x, z) - f^{(r,s)}(x, z) \}^2 &\leq C_1 n^{-2(\nu_1 - r - s)/(\nu_1 + 1)}, \\ \sup_{g \in \mathcal{C}_2} \sup_{\delta < z < 1 - \delta} E_g \{ \tilde{g}^{(t)}(z) - g^{(t)}(z) \}^2 &\leq C_2 n^{-4(\nu_2 - t)/(2\nu_2 + 1)}, \\ \sup_{f \in \mathcal{C}_1, g \in \mathcal{C}_2} \sup_{\delta < z < 1 - \delta} E_{f,g} \{ \hat{g}^{(t)}(z) - g^{(t)}(z) \}^2 &\leq C_3 \max(n^{-4(\nu_2 - t)/(2\nu_2 + 1)}, n^{-4\nu_1(\nu_2 - t)/\{(\nu_1 + 1)\nu_2\}}). \end{aligned}$$

These results, but without the suprema over  $f$  and  $g$ , were obtained in Remarks 2.2, 2.3 and 2.8 respectively. The methods of proof, smoothing parameters and convergence rates are exactly the same in the present uniform context.

In this section we show that, for *any* nonparametric estimators  $\hat{f}^{(r,s)}$ ,  $\tilde{g}^{(t)}$  and  $\hat{g}^{(t)}$  (not just for our kernel estimators), the above inequalities may be reversed. Let  $\hat{f}^{(r,s)}$  and  $\hat{g}^{(t)}$  be nonparametric estimators of  $f^{(r,s)}$  and  $g^{(t)}$ , respectively, based on model (2.1), and let  $\tilde{g}^{(t)}$  be a nonparametric estimator of  $g^{(t)}$ , based on the true residuals  $r_{ij} \equiv g(j/n)^{1/2} \varepsilon_{ij}$ ,  $1 \leq i, j \leq n$ . Assume that the errors  $\varepsilon_{ij}$  are independent and identically distributed as normal  $N(0, 1)$  and that  $\nu_1 > r + s$  and  $\nu_2 > t$ . We claim that for any fixed  $(x_0, z_0) \in (0, 1)^2$  and arbitrary nonparametric estimators  $\hat{f}^{(r,s)}$ ,  $\tilde{g}^{(t)}$  and  $\hat{g}^{(t)}$ , there exist positive constants  $D_1$ ,  $D_2$  and  $D_3$  such that, for large  $n$ ,

$$(3.1) \quad \sup_{f \in \mathcal{C}_1, g \in \mathcal{C}_3} E_{f,g} \{ \hat{f}^{(r,s)}(x_0, z_0) - f^{(r,s)}(x_0, z_0) \}^2 \geq D_1 n^{-2(\nu_1 - r - s)/(\nu_1 + 1)},$$

$$(3.2) \quad \sup_{g \in \mathcal{C}_2} E_g \{ \tilde{g}^{(t)}(z_0) - g^{(t)}(z_0) \}^2 \geq D_2 n^{-4(\nu_2 - t)/(2\nu_2 + 1)},$$

$$(3.3) \quad \begin{aligned} \sup_{f \in \mathcal{C}_1, g \in \mathcal{C}_2} E_{f,g} \{ \hat{g}^{(t)}(z_0) - g^{(t)}(z_0) \}^2 \\ \geq D_3 \max(n^{-4(\nu_2 - t)/(2\nu_2 + 1)}, n^{-4\nu_1(\nu_2 - t)/\{(\nu_1 + 1)\nu_2\}}). \end{aligned}$$

Results (3.1) and (3.2) may be viewed as lower bounds to convergence rates for estimation of mean functions in nonparametric regression with uniformly bounded variances. In the case of (3.2), the regression is replicated  $n$  times at each design point. Both results may be derived by modifying arguments of Stone (1980), who treats lower bounds in nonreplicated regression. Result (3.3) is more difficult to obtain and is proved in detail later in this section.

Next we turn attention to estimation of  $z_0$ , the unique element of  $[0, 1]$  such that  $\inf g = g(z_0)$ . The rate of convergence for our kernel-based estimator was described by (2.17). To extend this to a rate uniform over a function class, we must define a new function class, as follows. Fix  $\nu_2 > 2$ ,  $0 < \delta < \frac{1}{2}$  and  $0 < c < \frac{1}{2}B$ . Write  $\mathcal{D}_2 = \mathcal{D}_2(\nu_2, \delta, B, c)$  for the class of nonnegative functions  $g$  which are in  $\mathcal{C}_2(\nu_2, B)$  and which satisfy  $\frac{1}{2}c \leq g^{(2)}(z) \leq 2c$  for  $z \in [0, 1]$ ,  $g^{(1)}(z_0) = 0$  for some  $z_0 \in [\delta, 1 - \delta]$ . It follows that each  $g \in \mathcal{D}_2$  is strictly convex, with minimum attained at its unique turning point  $z_0$ . Fix  $\nu_1 > 0$  and let  $\mathcal{C}_1 = \mathcal{C}_1(\nu_1, B)$  be the function class defined earlier. Then if  $\hat{z}_0$  is our kernel-based estimator of  $z_0$ , and if  $\{a_n\}$  is a positive sequence with  $a_n \rightarrow \infty$ ,

$$(3.4) \quad \sup_{f \in \mathcal{C}_1, g \in \mathcal{D}_2} P_{f, g} \{ |\hat{z}_0 - z_0| > a_n \max(n^{-2(\nu_1-1)/(2\nu_2+1)}, n^{-2\nu_1(\nu_2-1)/((\nu_1+1)\nu_2)}) \} \rightarrow 0$$

as  $n \rightarrow \infty$ . (Here  $\nu_1 > 0$  and  $\nu_2 > 2$ .) This is a version of (2.17) uniformly over function classes and is proved in the same manner as (2.17). To state a converse result, let  $\hat{z}_0$  be any nonparametric estimator of  $z_0$  and  $\{a_n\}$  be any positive sequence. We claim that if (3.4) holds, then  $a_n \rightarrow \infty$ . An outline of the proof of this fact will be given later in this section.

Similar results for estimation of  $x_0$  require a new class  $\mathcal{D}_1$  of mean functions  $f$ . Fix  $d \in (0, \frac{1}{2}B)$ ,  $\nu_1 > 1$  and  $\tau_0$ , and let  $\mathcal{D}_1 = \mathcal{D}_1(\nu_1, \delta, \tau_0, B, d)$  be the class of functions  $f$  which are in  $\mathcal{C}_2(\nu_2, B)$ , which satisfy  $\frac{1}{2}d \leq |f^{(0,1)}(x, z)|, |f^{(1,0)}(x, z)| \leq 2d$  for  $(x, z) \in [0, 1]^2$ , and which are such that for each  $z \in [\delta, 1 - \delta]$  the equation  $f(x, z) = \tau_0$  has a unique solution  $x(z)$ . Then if  $\hat{x}_0$  is our kernel-based estimator of  $x_0 = x(z_0)$ , and if  $\{a_n\}$  is a positive sequence with  $a_n \rightarrow \infty$ ,

$$(3.5) \quad \sup_{f \in \mathcal{D}_1, g \in \mathcal{D}_2} P_{f, g} \{ |\hat{x}_0 - x_0| > a_n \max(n^{-\nu_1/(\nu_1+1)}, n^{-2(\nu_2-1)/(2\nu_2+1)}) \} \rightarrow 0$$

as  $n \rightarrow \infty$ . (Here  $\nu_1 > 1$  and  $\nu_2 > 2$ .) Conversely, if  $\hat{x}_0$  is any nonparametric estimator of  $x_0$ , if  $\{a_n\}$  is a positive sequence and if (3.5) holds, then  $a_n \rightarrow \infty$ .

We conclude this section with a detailed proof of (3.3), and sketches of proofs of the rates of convergence described by (3.4) and (3.5).

**PROOF OF (3.3).** It is notationally simpler to assume a regular design on the square  $[-1, 1]^2$  instead of on  $[0, 1]^2$  and to take  $x_0 = 0$ . There is no loss of generality in confining attention to this situation, and so we suppose instead of model (2.1) that  $Y_{i,j} = f(i/n, j/n) + g(j/n)^{1/2}\epsilon_{i,j}$ ,  $-n \leq i, j \leq n$ , where the  $\epsilon_{i,j}$ 's are i.i.d.  $N(0, 1)$ . Define the function classes  $\mathcal{C}_1$  and  $\mathcal{C}_2$  on  $[-1, 1]$  instead of on  $[0, 1]$ .

In the case  $\nu_1 \geq \nu_2/(\nu_2 + 1)$ , we must prove that for large  $n$ ,

$$\sup_{f \in \mathcal{C}_1, g \in \mathcal{C}_2} E_{f, g} \{ \hat{g}^{(t)}(x_0) - g^{(t)}(x_0) \}^2 \geq Cn^{-4(\nu_2 - t)/(2\nu_2 + 1)}.$$

This inequality follows from

$$(3.6) \quad \sup_{f=0, g \in \mathcal{C}_2} E_{f, g} \{ \hat{g}^{(t)}(x_0) - g^{(t)}(x_0) \}^2 \geq Cn^{-4(\nu_2 - t)/(2\nu_2 + 1)},$$

which is true for all  $\nu_2 > t$ . To prove (3.6), note that when  $f \equiv 0$  our model entails  $Y_{ij}^2 = g(j/n) + \eta_{ij}$ , where  $\eta_{ij} \equiv g(j/n)(\epsilon_{ij}^2 - 1)$ . This is a replicated regression model, having mean function  $g$  and residuals with uniformly bounded variance. Techniques of Stone (1980), giving lower bounds to convergence rates for nonreplicated regression models, are easily modified to produce (3.6).

When  $\nu_1 < \nu_2/(\nu_2 + 1)$ , we must show that for large  $n$ ,

$$(3.7) \quad \sup_{f \in \mathcal{C}_1, g \in \mathcal{C}_2} E_{f, g} \{ \hat{g}^{(t)}(x_0) - g^{(t)}(x_0) \}^2 \geq Cn^{-4\nu_1(\nu_2 - t)/\{(\nu_1 + 1)\nu_2\}}.$$

Our first proof of this inequality is valid for

$$(3.8) \quad \nu_1 < \nu_2/(\nu_2 + 1), \quad \nu_2 > \max(t, 1), \quad t = 0, 1, \dots$$

The only case of interest not covered by these conditions is

$$(3.9) \quad \nu_1 < \nu_2/(\nu_2 + 1), \quad 0 < \nu_2 \leq 1, \quad t = 0,$$

and we shall treat this separately at the end of our main proof.

Assume condition (3.8). Let  $\psi_1, \psi_2$  be real-valued functions having at least  $\langle \nu_2 \rangle + 2$  bounded derivatives on  $(-\infty, \infty)$ , such that  $\psi_1$  vanishes outside  $[0, 1]$ ,  $\psi_2$  vanishes outside  $[-1, 1]$ ,  $\psi_1(\frac{1}{2}) \neq 0$ ,  $\psi_2^{(t)}(0) \neq 0$  and  $\sup |\psi_j^{(i)}| \leq \frac{1}{2}B$  for  $0 \leq i \leq \langle \nu_2 \rangle + 2$  and  $j = 1, 2$ . Fix  $c > 0$  and put  $m_1 \equiv [cn^{\nu_1/(\nu_1 + 1)}]$ ,  $m \equiv [n^{1 - (2\nu_1)/\{(\nu_1 + 1)\nu_2\}}/m_1]$  (where  $[x]$  denotes the integer part of  $x$ ),  $m_2 \equiv m_1 m$  and  $\delta_i \equiv m_i/n$  for  $i = 1, 2$ . Let  $m_0$  be an integer such that  $m_0 m_1 \leq n$  and  $m_0 \sim n/m_1$ . Since we are assuming  $\nu_2 > 1$ , then  $\nu_2/(\nu_2 + 1) < \frac{1}{2}\nu_2$ , and so the hypothesis  $\nu_1 < \nu_2/(\nu_2 + 1)$  entails  $\nu_1 < \frac{1}{2}\nu_2$ . This implies  $m \rightarrow \infty$  as  $n \rightarrow \infty$ . Let  $\{I_{ij}, -m_0 \leq i \leq m_0 - 1 \text{ and } -m \leq j \leq m - 1\}$  be a sequence of  $\pm 1$ 's, put  $A(x, y) \equiv \delta_1^{\nu_1} \psi_1(x/\delta_1) \psi_1(y/\delta_2)$ , and define  $f = f(\cdot | \{I_{ij}\})$  by

$$f(x, y) = I_{ij} A(x - n^{-1}m_1 i, y - n^{-1}m_1 j) \quad \text{if } (x, y) \in \mathcal{I}_{ij},$$

$$f(x, y) = 0 \quad \text{if } (x, y) \notin \bigcup_{ij} \mathcal{I}_{ij},$$

where  $\mathcal{I}_{ij} \equiv [n^{-1}m_1 i, n^{-1}m_1(i + 1)) \times [n^{-1}m_1 j, n^{-1}m_1(j + 1))$  for  $-m_0 \leq i \leq m_0 - 1$  and  $-m \leq j \leq m - 1$ , and where  $\bigcup_{ij}$  denotes the union over these values of  $i, j$ . Write  $\mathcal{F}$  for the class of all such  $f$ s. Let  $G(x) \equiv \delta_1^{2\nu_1} \psi_2(x/\delta_2)$ ,  $g_0 \equiv 1$ ,  $g_1 \equiv (1 - G)^{-1}$  and  $\mathcal{G} \equiv \{g_0, g_1\}$ . For large  $n$ ,  $\mathcal{F} \subseteq \mathcal{C}_1$  and  $\mathcal{G} \subseteq \mathcal{C}_2$ , provided  $B > 1$ . (The latter restriction may be removed at the cost of notational complexity.)

Let  $\hat{g}^{(t)}(0)$  be any nonparametric estimator of  $g^{(t)}(0)$ . It suffices to show that

$$\liminf_{n \rightarrow \infty} n^{4\nu_1(\nu_2 - t)/\{(\nu_1 + 1)\nu_2\}} \sup_{f \in \mathcal{F}, g \in \mathcal{G}} E_{f, g} \{ \hat{g}^{(t)}(0) - g^{(t)}(0) \}^2 > 0.$$



This result will follow if we prove that

$$(3.10) \quad \liminf_{n \rightarrow \infty} n^{4\nu_1(\nu_2 - t)/((\nu_1 + 1)\nu_2)} \sup_{g \in \mathcal{G}} E_g^* \{ \hat{g}^{(t)}(0) - g^{(t)}(0) \}^2 > 0,$$

where  $E_g^*$  denotes expectation under the model

$$Y_{ij} = f(i/n, j/n | \{I_{\alpha\beta}\}) + g(j/n)^{1/2} \varepsilon_{ij}, \quad -n \leq i, j \leq n,$$

in which the  $I_{\alpha\beta}$ 's are independent symmetric  $\pm 1$  variables [independent of the  $\varepsilon_{ij}$ 's, which are i.i.d.  $N(0, 1)$ ].

If (3.10) fails, choose a sequence  $\{n_k\}$  such that the left-hand side of (3.10) converges to zero as  $n \rightarrow \infty$  through  $\{n_k\}$ . Since

$$|g_0^{(t)}(0) - g_1^{(t)}(0)| \sim \delta_1^{2\nu_1} \delta_2^{-t} |\psi_2^{(t)}(0)| \sim \text{const. } n^{-2\nu_1(\nu_2 - t)/((\nu_1 + 1)\nu_2)},$$

then the decision rule  $\hat{D}$  given by  $\hat{D} = 0$  if  $|\hat{g}^{(t)}(0) - g_0^{(t)}(0)| \leq |g^{(t)}(0) - g_1^{(t)}(0)|$ ,  $\hat{D} = 1$  otherwise, provides asymptotically perfect discrimination between  $g_0^{(t)}(0)$  and  $g_1^{(t)}(0)$  as  $n \rightarrow \infty$  through  $\{n_k\}$ , in the sense that

$$P_{g_0}^*(\hat{D} = 1) + P_{g_1}^*(\hat{D} = 0) \rightarrow 0.$$

We shall complete our proof by showing that this is impossible, even for the likelihood ratio (LR) rule. It suffices to show that if the true  $g$  is  $g_0$  then the chance that the LR rule picks  $g_1$  is bounded away from zero as  $n \rightarrow \infty$ . We may confine attention to the LR rule based on  $\{Y_{ij}, |i| \leq m_0 m_1 \text{ and } |j| \leq m m_1\}$ . (Note that  $m_0 m_1 \sim n$  and that  $g_0(x) = g_1(x)$  for  $|x| > m m_1/n$ . Therefore,  $Y_{ij}$  with  $|j| > m m_1$  provides no information for discriminating between  $g_0$  and  $g_1$ .)

Let  $a, b, \alpha, \beta$  be integers satisfying  $-m_0 \leq a \leq m_0 - 1, -m \leq \alpha \leq m - 1, 1 \leq b, \beta \leq m_1$ . If  $i = a m_1 + b$  and  $j = \alpha m_1 + \beta$ , write  $Y_{ab\alpha\beta}$  and  $\varepsilon_{ab\alpha\beta}$  for  $Y_{ij}$  and  $\varepsilon_{ij}$ , respectively. For fixed  $a, \alpha$ , the likelihood of  $\{Y_{ab\alpha\beta}, 1 \leq b, \beta \leq m_1\}$  is proportional to

$$\begin{aligned} & \left( \exp \left[ -\frac{1}{2} \sum_b \sum_\beta \frac{\{Y_{ab\alpha\beta} + A(b/n, \beta/n)\}^2}{g_0\{(\alpha m_1 + \beta)/n\}} \right] \right. \\ & \left. + \exp \left[ -\frac{1}{2} \sum_b \sum_\beta \frac{\{Y_{ab\alpha\beta} + A(b/n, \beta/n)\}^2}{g_1\{(\alpha m_1 + \beta)/n\}} \right] \right) \left[ \prod_{\beta=1}^{m_1} g \left( \frac{(\alpha m_1 + \beta)}{n} \right) \right]^{-m_1/2} \end{aligned}$$

The chance that the LR rule wrongly picks  $g_1$ , equals the probability that

$$\begin{aligned} & \exp \left[ -\frac{1}{2} \sum_a \sum_b \sum_\alpha \sum_\beta \frac{\varepsilon_{ab\alpha\beta}^2}{g_1\{(\alpha m_1 + \beta)/n\}} \right] \left\{ \prod_{j=1}^n g_1 \left( \frac{j}{n} \right) \right\}^{-n/2} \\ & \times \prod_a \prod_\alpha \left( 1 + \exp \left[ -2 \sum_b \sum_\beta \frac{\{A(b/n, \beta/n)^2 + A(b/n, \beta/n) \varepsilon_{ab\alpha\beta}\}}{g_1\{(\alpha m_1 + \beta)/n\}} \right] \right) \\ & \geq \exp \left( -\frac{1}{2} \sum_a \sum_b \sum_\alpha \sum_\beta \varepsilon_{ab\alpha\beta}^2 \right) \prod_a \prod_\alpha \left( 1 + \exp \left[ -2 \sum_b \sum_\beta \left\{ A \left( \frac{b}{n}, \frac{\beta}{n} \right)^2 \right. \right. \right. \\ & \left. \left. \left. + A \left( \frac{b}{n}, \frac{\beta}{n} \right) \varepsilon_{ab\alpha\beta} \right\} \right] \right). \end{aligned}$$

(Here we have used symmetry of the Normal distribution, which implies that  $\epsilon_{ab\alpha\beta}$  and  $I_{\alpha\beta}\epsilon_{ab\alpha\beta}$  have the same distribution.) Equivalently, since  $G = 1 - g_1^{-1}$ , it equals the chance that

$$\begin{aligned} & \exp\left(n \sum_{j=1}^n \left[ G\left(\frac{j}{n}\right) + \log\left(1 - G\left(\frac{j}{n}\right)\right) \right] + \sum_a \sum_b \sum_{\alpha} \sum_{\beta} (\epsilon_{ab\alpha\beta}^2 - 1) G\left(\frac{\alpha m_1 + \beta}{n}\right)\right) \\ & \times \prod_a \prod_{\alpha} \left\{ \left( 1 + \exp\left[-2 \sum_b \sum_{\beta} \left\{ A\left(\frac{b}{n}, \frac{\beta}{n}\right)^2 + A\left(\frac{b}{n}, \frac{\beta}{n}\right) \epsilon_{ab\alpha\beta} \right\} \right. \right. \right. \\ & \qquad \qquad \qquad \left. \left. \left. \times \left( 1 - G\left(\frac{\alpha m_1 + \beta}{n}\right) \right) \right] \right) \right\}^2 \\ & \times \left( 1 + \exp\left[-2 \sum_b \sum_{\beta} \left\{ A\left(\frac{b}{n}, \frac{\beta}{n}\right)^2 + A\left(\frac{b}{n}, \frac{\beta}{n}\right) \epsilon_{ab\alpha\beta} \right\} \right] \right)^{-2} \geq 1. \end{aligned}$$

Denote the left-hand side of this inequality by  $B$  and put

$$\begin{aligned} d_1 & \equiv \sum_b \sum_{\beta} A\left(\frac{b}{n}, \frac{\beta}{n}\right)^2 \sim c^{2(\nu_1+1)} \left( \int \psi_1^2 \right)^2 \equiv d, \\ N_{\alpha\alpha} & \equiv d_1^{-1/2} \sum_b \sum_{\beta} A\left(\frac{b}{n}, \frac{\beta}{n}\right) \epsilon_{ab\alpha\beta} \stackrel{\mathcal{D}}{=} N(0, 1). \end{aligned}$$

Noting that  $\delta_1 \sim m_0^{-1} \sim cn^{-1/(\nu_1+1)}$  and  $\delta_2 \sim n^{-2\nu_1/((\nu_1+1)\nu_2)}$ , we see that

$$\begin{aligned} \log B & = -\{1 + o(1)\} \frac{1}{2} n \sum_{j=1}^n G\left(\frac{j}{n}\right)^2 + O_p \left[ \left\{ n \sum_{j=1}^n G\left(\frac{j}{n}\right)^2 \right\}^{1/2} \right] \\ & + \{1 + o_p(1)\} 4 \sum_a \sum_{\alpha} \exp\{-2(d_1 + d_1^{1/2} N_{\alpha\alpha})\} \\ & \times [1 + \exp\{-2(d_1 + d_1^{1/2} N_{\alpha\alpha})\}]^{-1} (d_1 + d_1^{1/2} N_{\alpha\alpha}) G\left(\frac{\alpha m_1}{n}\right) \\ & = -\{1 + o_p(1)\} \frac{1}{2} n^2 \delta_1^{4\nu_1} \delta_2 \int \psi_2^2 + \{1 + o_p(1)\} 8m_0 \delta_1^{2\nu_1-1} \delta_2 s \\ & = n^{(\nu_2 - \nu_1(\nu_2+1))/((\nu_1+1)\nu_2)} \left\{ 8c^{2\nu_1-2} s - \frac{1}{2} c^{4\nu_1} \int \psi_2^2 + o_p(1) \right\}, \end{aligned}$$

where  $s \equiv (\int \psi_2) E([\exp\{2(d + d^{1/2}N)\} + 1]^{-1} (d + d^{1/2}N))$ ,  $N \stackrel{\mathcal{D}}{=} N(0, 1)$  and  $c$  is chosen so that the expectation is nonzero. Choose  $\psi_2$  to be either nonnegative or nonpositive, the sign being selected so that  $s > 0$ , and choose  $|\psi_2|$  so small that  $8c^{2\nu_1-2}s - \frac{1}{2}c^{4\nu_1}\int\psi_2^2 > 0$ . Then  $B \rightarrow +\infty$  in probability, implying that the chance that the LR rule picks  $g_1$  when  $g_0$  is the true variance function converges to one as  $n \rightarrow \infty$ . This completes our proof in the presence of condition (3.8).

The proof when (3.9) holds is simpler. Adopt the same notation as before, except that  $m$  is redefined as  $m_0$  ( $\sim n/m_1$ ),  $\psi_2 \equiv 1$ , and  $m_2$  and  $\delta_2$  are no longer needed. Pursue the same argument.  $\square$

We next sketch a proof of the fact that if (3.4) holds for a nonparametric estimator  $\hat{z}_0$  of  $z_0$ , then  $a_n \rightarrow \infty$ . We treat only the case  $\nu_1 < \nu_2/(\nu_2 + 1)$ , which is the context of the major part of our proof of (3.3). The case  $\nu_1 \geq \nu_2/(\nu_2 + 1)$  is similar. Our argument is almost identical to that employed to derive (3.3).

Assume that estimation takes place on  $[-1, 1]^2$ . Use the same class of  $f$ 's but change  $g_0, g_1$  from  $1, (1 - G)^{-1}$  respectively to  $H, H + G$ , respectively, where  $G$  is as before and  $H$  is a positive, strictly convex function with unique minimum interior to  $[-1, 1]$ . For definiteness we shall take  $H(z) \equiv (1 + z^2)B_0$ , where our selection of the positive constant  $B_0$  depends on the value of  $B$ . Let  $z_{00}$  ( $= 0$ ) and  $z_{01}$  be the values which minimize  $g_0$  and  $g_1$ , respectively. Now,

$$g_1'(z) = 2B_0z + \delta_1^{2\nu_1}\delta_2^{-1}\psi_2'(z/\delta_2),$$

which equals zero when  $z = z_{01}$ . Thus, by appropriate choice of  $\psi_2$  we may ensure that  $z_{00}$  and  $z_{01}$  are distant apart an amount which is asymptotic to  $\text{const.}\delta_1^{2\nu_1}\delta_2^{-1}$ . The argument given during our proof of (3.3) shows that it is impossible to discriminate between  $z_{00}$  and  $z_{01}$ , and so it is also impossible to discriminate between  $z_0$  and  $z_{01}$ . Therefore no nonparametric estimator of  $z_0$  can converge to  $z_0$  more rapidly than  $\delta_1^{2\nu_1}\delta_2^{-1}$ , and the latter is asymptotic to a constant multiple of

$$n^{-2\nu_1(\nu_2-1)/\{(\nu_1+1)\nu_2\}} = \max(n^{-2(\nu_2-1)/(2\nu_2+1)}, n^{-2\nu_1(\nu_2-1)/\{(\nu_1+1)\nu_2\}}),$$

the above identity holding since  $\nu_1 < \nu_2/(\nu_2 + 1)$ . It follows that if (3.4) holds, then  $a_n \rightarrow \infty$ .

A proof of the fact that (3.5) entails  $a_n \rightarrow \infty$  is similar. It uses the same  $g_0$  ( $= H$ ) and  $g_1$  ( $= H + G$ ) as above, but has the class of  $f$ 's changed from  $\mathcal{F}$  to  $\mathcal{F}' \equiv \{F + f; f \in \mathcal{F}\}$ , where  $F$  is an appropriate bivariate function which is strictly monotone in both variables. For example, if  $\tau_0 = 2$  and  $z_0$  is close to zero, then we may take  $F(x, z) \equiv (x + 1)^2 + (z + 1)^2$ .

**4. Random design case.** Although the fixed design case is the more important, analogues of our results may be obtained if  $(x_i, z_i), 1 \leq i \leq N$ , are random variables distributed within the square  $[0, 1]^2$  according to density  $d$ , rather than points on a lattice. In the present section we briefly discuss the random design case. The reader is referred to Prakasa Rao (1983), Section 4.2 for details of nonparametric regression estimation.

Assume that  $N$  observations  $(x_i, Y_i, z_i)$  are generated by the model

$$Y_i = f(x_i, z_i) + g(z_i)^{1/2}\epsilon_i, \quad 1 \leq i \leq N,$$

where  $f$  is  $\nu_1$ -smooth,  $g$  is  $\nu_2$ -smooth, the density  $d$  of the pairs  $(x_i, z_i)$  is

$\max(\nu_1, \nu_2)$ -smooth and, conditional on the  $(x_i, z_i)$ 's, the  $\varepsilon_i$ 's are independent with zero mean and uniformly bounded second moments. A kernel estimator of  $d$  is

$$(4.1) \quad \hat{d}(x, z) \equiv (Nh_1^2)^{-1} \sum_{j=1}^N K_1\{(x_j - x)/h_1, (z_j - z)/h_1\},$$

where  $K_1$  is a compactly supported bivariate function as in Theorem 3.1 of Stute (1984) and such that  $\int x^i z^j K_1(x, z) dx dz = 1$  if  $i = j = 0$  and  $= 0$  if  $1 \leq i + j \leq \langle \nu_1 \rangle$ . A kernel estimator of  $f$  is

$$(4.2) \quad \begin{aligned} \hat{f}(x, z) &\equiv \hat{s}(x, z)/\hat{d}(x, z), \\ \hat{s}(x, z) &= (Nh_1^2)^{-1} \sum_{j=1}^N Y_j K_1\{(x_j - x)/h_1, (z_j - z)/h_1\}. \end{aligned}$$

Let  $\hat{d}_i(x, z)$  and  $\hat{s}_i(x, z)$  be as in (4.1) and (4.2), but with the sums taken only over  $j \neq i$ , and let  $\hat{f}_i(x, z) \equiv \hat{s}_i(x, z)/\hat{d}_i(x, z)$ ,  $r_i \equiv Y_i - f(x_i, z_i)$  (not observable) and  $\hat{r}_i \equiv Y_i - \hat{f}_i(x_i, z_i)$ . Fix  $0 < \delta < \frac{1}{2}$ . Analogues of  $\tilde{g}$  and  $\hat{g}$  are

$$(4.3) \quad \begin{aligned} \tilde{g}(z) &\equiv \sum_{j=1}^N r_j^2 I(\delta < x_j < 1 - \delta) K_2\{(z_j - z)/h_2\} \\ &\quad \Bigg/ \sum_{j=1}^N I(\delta < x_j < 1 - \delta) K_2\{(z_j - z)/h_2\}, \\ \hat{g}(z) &\equiv \sum_{j=1}^N \hat{r}_j^2 I(\delta < x_j < 1 - \delta) K_2\{(z_j - z)/h_2\} \\ &\quad \Bigg/ \sum_{j=1}^N I(\delta < x_j < 1 - \delta) K_2\{(z_j - z)/h_2\}, \end{aligned}$$

respectively, where  $K_2$  is a univariate function satisfying  $\int z^i K_2(z) dz = 1$  for  $i = 0$  and  $= 0$  for  $1 \leq i \leq \langle \nu_2 \rangle$ .

Take  $h_1 = N^{-1/(2\nu_1+2)}$  and write  $a_N = N^{-\nu_1/(\nu_1+1)}$ . By moment calculations applied to  $\hat{s}^{(r,s)}$  and  $\hat{d}^{(r,s)}$  for  $0 \leq r + s \leq \nu_1$ , using (4.2) we find that for  $\delta \leq x$ ,  $z \leq 1 - \delta$ ,

$$(4.4) \quad \{ \hat{f}^{(r,s)}(x, z) - f^{(r,s)}(x, z) \}^2 = O_p\{N^{-(\nu_1-r-s)/(\nu_1+1)}\}.$$

By Theorem 3.1 of Stute (1984),

$$\sup\{|\hat{d}_i(x, z) - d(x, z)| : 1 \leq i \leq N, \delta \leq x, z \leq 1 - \delta\} = O_p\{(a_N \log N)^{1/2}\}.$$

Assuming that  $d$  is bounded away from zero on  $[0, 1]^2$ , one can show that, uniformly in  $\delta < x, z < 1 - \delta$ ,

$$(4.5) \quad \begin{aligned} \hat{f}_i - f &= (\hat{s}_i - f\hat{d}_i)/d - (\hat{s}_i - f\hat{d}_i)(\hat{d}_i - d)/d^2 \\ &\quad + (\hat{s}_i - f\hat{d}_i)(\hat{d}_i - d)^2/(d^2\hat{d}_i) + O_p(a_N \log N). \end{aligned}$$

Let  $h_2 \rightarrow 0$  such that  $Nh_2 \rightarrow \infty$ . By moment calculations applied to each term in  $\tilde{g}^{(t)}$ , it follows that, for  $0 \leq t \leq \langle \nu_2 \rangle$ ,  $\delta \leq z \leq 1 - \delta$ ,

$$(4.6) \quad \{\tilde{g}^{(t)}(z) - g^{(t)}(z)\}^2 = O_p\left\{(Nh_2^{2t+1})^{-1} + h_2^{2(\nu_2-t)}\right\}.$$

Using (4.5), detailed calculations yield

$$(4.7) \quad \{\hat{g}^{(t)}(z) - g^{(t)}(z)\}^2 = O_p\left\{(Nh_2^{2t+1})^{-1} + h_2^{2(\nu_2-t)} + h_2^{-2t}N^{-2\nu_1/(\nu_1+1)}\right\}.$$

Equations (4.4), (4.6) and (4.7) are analogues of (2.6), (2.8) and (2.11), respectively.

We may also derive analogues of (1.3), (1.4) and (1.5), by following essentially the arguments given in Section 1. It is necessary to show that

$$\sup_{\delta < z < 1-\delta} |\hat{g}^{(2)}(z) - g^{(2)}(z)| \rightarrow 0, \quad \sup_{\delta < x, z < 1-\delta} |\hat{f}^{(i,j)}(x, z) - f^{(i,j)}(x, z)| \rightarrow 0$$

in probability, where  $(i, j) = (0, 1)$  or  $(1, 0)$ . The trick is to decompose  $\hat{g}^{(2)}$  and  $\hat{f}^{(i,j)}$  into a series of terms, each of which is a ratio of two consistent function estimators. Assuming sufficiently many moments of the errors  $\varepsilon_i$  and Hölder continuity of derivatives of  $K_1$  and  $K_2$ , uniform consistency of these function estimators may be proved by using the "continuity argument"; see, for example, Stone [(1984), foot of page 1292] and Hall (1985). The technique is intricate and laborious, but conceptually straightforward. It gives the same rates of convergence exhibited in (1.3), (1.4) and (1.5), under the same conditions on  $f$  and  $g$ . Arguments similar to those in Section 3 may be employed to show that these rates are optimal.

**Acknowledgments.** The work of R. J. Carroll occurred during a visit to the Australian National University and was supported by the Air Force Office of Scientific Research. The paper has benefited from suggestions by a referee and an Associate Editor.

## REFERENCES

- BOX, G. E. P. (1988). Signal to noise ratios, performance criteria and transformation (with discussion). *Technometrics* **30** 1-40.
- BUCKLEY, M. J., EAGLESON, G. K. and SILVERMAN, B. W. (1988). The estimation of residual variance in nonparametric regression. *Biometrika* **75** 189-199.
- EDDY, W. F. (1980). Optimum kernel estimators of the mode. *Ann. Statist.* **8** 870-882.
- GASSER, T., SROKA, L. and JENNER, C. (1986). Residual variance and residual pattern in nonlinear regression. *Biometrika* **73** 625-633.
- HALL, P. (1985). Asymptotic theory of minimum integrated square error for multivariate density estimation. In *Multivariate Analysis-VI* (P. R. Krishnaiah, ed.) 289-309. Academic, New York.
- HALL, P. and CARROLL, R. J. (1989). Variance function estimation in regression: The effect of estimating the mean. *J. Roy. Statist. Soc. Ser. B* **51** 3-14.
- LEON, R. V., SHOEMAKER, A. C. and KACKAR, R. N. (1988). Performance measures independent of adjustment: An explanation and extension of Taguchi's signal to noise ratios (with discussion). *Technometrics* **30** 253-285.

- MÜLLER, H.-G. (1984). Smooth optimum kernel estimators of densities, regression curves and modes. *Ann. Statist.* **12** 766–774.
- PARZEN, E. (1962). On estimation of a probability density and mode. *Ann. Math. Statist.* **35** 1065–1076.
- PRAKASA RAO, B. L. S. (1983). *Nonparametric Functional Estimation*. Academic, New York.
- STONE, C. J. (1980). Optimal rates of convergence for nonparametric estimators. *Ann. Statist.* **8** 1348–1360.
- STONE, C. J. (1984). An asymptotically optimal window selection rule for kernel density estimates. *Ann. Statist.* **12** 1285–1297.
- STUTE, W. (1984). The oscillation behavior of empirical processes: The multivariate case. *Ann. Probab.* **12** 361–379.
- TAGUCHI, G. and WU, Y. (1985). *Introduction to Off-Line Quality Control*. Central Japan Quality Control Association, Tokyo.

DEPARTMENT OF STATISTICS  
TEXAS A & M UNIVERSITY  
COLLEGE STATION, TEXAS 77853

DEPARTMENT OF STATISTICS  
AUSTRALIAN NATIONAL UNIVERSITY  
CANBERRA, ACT 2601  
AUSTRALIA