

## RECURRENCE OF STATIONARY SEQUENCES<sup>1</sup>

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Let  $\{X_n\}_{-\infty}^{+\infty}$  be a stationary sequence of random variables, with common distribution  $\pi(dx)$ . If the initial value  $X_0$  is repeated with probability one (e.g. when  $\pi(dx)$  is discrete), then the "shifted" sequence  $\{X_{n+N}\}_{-\infty}^{\infty}$  is also stationary where  $N = N(\omega)$  is the first  $n > 0$  for which  $X_n(\omega) = X_0(\omega)$ . Surprisingly, this may even occur when  $\pi(dx)$  is continuous and  $\{X_n\}$  is ergodic (although not when  $\{X_n\}$  is  $\phi$ -mixing). For Markov sequences, we also give other conditions which prohibit the a.s. recurrence of  $X_0$ .

For recurrent sequences, we show that when  $X_0$  is "conditionally discrete," the invariant  $\sigma$ -field for the  $\{X_{n+N}\}$  process coincides (up to null sets) with  $X_0 \vee \mathcal{A}$ , the  $\sigma$ -field generated by  $X_0$  and the invariant sets for  $\{X_n\}$ . Finally, we find an expression for  $E(N | X_0 \vee \mathcal{A})$  which reduces to Kac's recurrence formula when  $X_0$  is an indicator function.

**0. Introduction.** Suppose  $\{X_n\}$ ,  $n \in \mathbb{Z}$  (the integers), is a stationary random sequence, and let  $N$  be the first time  $n \geq 1$  that  $X_n = X_0$  or  $N = \infty$  if there is no such  $n$ . If the sequence is independent and identically distributed (i.i.d.), then it is easy to see that the finiteness of  $N$  is completely determined by the common distribution  $\pi$  as follows: if  $X_0 = x$  is an atom of  $\pi$ , then  $N < \infty$ ; otherwise  $N = \infty$  (all with the exception of a set of probability zero).

The purpose of this paper is to discuss the return time  $N$  for an arbitrary stationary sequence; specifically we allow  $\pi$  to be continuous. We begin with some more precise definitions. Let  $X$  be a random variable on a probability space  $(\Omega, \mathcal{F}, P)$ , and  $T: \Omega \rightarrow \Omega$  an automorphism, i.e. a bijective, bimeasurable, measure-preserving transformation. Our primary interest is in real-valued random variables, but we will allow  $X$  to take its values in a measurable state space  $(E, \mathcal{E})$ , with  $\mathcal{E}$  separable (see Example 1 below). The distribution of  $X$  is denoted by  $\pi: \pi(\Gamma) = P(X \in \Gamma)$ ,  $\Gamma \in \mathcal{E}$ . Now, for  $n \in \mathbb{Z}$ , let  $X_n = X \circ T^n$  ( $T^0 = \text{identity}$ ), noting that every stationary sequence may be realized in this manner. The return time  $N$  is defined by

$$(1) \quad N(\omega) = \min \{n \geq 1 : X_n(\omega) = X_0(\omega)\}$$

with the usual convention that  $N(\omega) = \infty$  if the set in (1) is empty. The transformation  $T^N: \Omega \rightarrow \Omega$  is defined as  $T^N(\omega) = T^{N(\omega)}(\omega)$  when  $N(\omega) < \infty$ ,  $T^N(\omega) = \omega$  otherwise. It follows from Neveu [6] (also see [3]) that, when  $N < \infty$  a.s.,  $T^N$  preserves  $P$ -measure. We note that the discreteness of  $\pi$  is sufficient to yield  $N < \infty$  a.s., by the ergodic theorem, but it is not necessary.

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Similar questions for (dependent) stationary sequences with  $\pi$  discrete were first studied by Kac [4] and by Ryll-Nardzewski [9] (for point processes) whereas Breiman [1] considers the first time the sequence returns to a Borel set  $B$  of positive  $\pi$ -measure given that it started in  $B$ —this amounts to taking the sequence  $I_B(X_n)$ .

When  $N < \infty$  a.s. and  $T$  is ergodic, it is known [3] that

$$(2) \quad E(N|X) = 1/\pi(\{X\}) .$$

An immediate consequence is that  $\pi$  is discrete iff  $E(N|X) < \infty$  a.s.; another is Kac’s formula for the mean return time to a set of positive measure. Next, since  $T^N$  preserves measure, one may study its ergodic structure. Because  $X$  itself is a  $T^N$ -invariant function,  $T^N$  is never ergodic, except in the trivial case when  $X$  is constant. Indeed, when  $X$ (or  $\pi$ ) is discrete, and  $T$  is ergodic, the  $T^N$ -invariant  $\sigma$ -field in  $\Omega$ , denoted  $\mathcal{A}_N$ , coincides (up to null sets) with  $\sigma(X)$ , the  $\sigma$ -field generated by  $X$ .

In view of formula (2), the question was raised in [3] of whether it was even possible to have  $T$  ergodic,  $N$  a.s. finite, and  $\pi$  continuous. We begin Section 1 with some examples answering this affirmatively, and then show that for processes satisfying certain mixing conditions, and for various types of Markov processes, it is impossible to have  $N$  a.s. finite and  $\pi$  continuous. Section 2 contains some generalizations of the results discussed above. Specifically, equation (2) is extended to the case in which  $T$  need not be ergodic nor  $\pi$  discrete. Finally, we discuss the structure of  $\mathcal{A}_N$  with no restriction on  $T$ ; for stationary Markov processes, there are no further requirements on  $X$  either, but in general we must still assume that  $X$  is “conditionally discrete” as explained below.

**1. Recurrence, mixing, and the Markov case.** First, we give two examples which show the possibility of having  $T$  ergodic,  $N < \infty$  a.s., and  $\pi$  continuous. If the ergodicity requirement is dropped, it is trivial to construct examples, e.g., using a rational rotation on the circle; on the other hand, if the  $\sigma$ -field  $\mathcal{E}$  in the state space is not separable, one may easily give pathological examples satisfying all three conditions. (We would like to thank John Walsh for the remark on separability and for a conversation concerning Theorem 5(b) below.) The state space in our example will be the unit circle with its usual Borel  $\sigma$ -field. Notice that (2) necessitates  $E(N|X) = \infty$  a.s.

EXAMPLE 1. Let  $X_0$  be uniformly distributed on the unit circle, and  $\theta$  be a number such that  $\theta/2\pi$  is irrational. Next let  $\{Y_n\}$  be an i.i.d. sequence with  $P\{Y_n = +\theta\} = P\{Y_n = -\theta\} = \frac{1}{2}$ , and  $S_n = Y_1 + Y_2 + \dots + Y_n$  ( $S_0 \equiv 0$ ) the corresponding random walk. Now define  $X_n = X_0 e^{iS_n}$  for  $n \geq 0$ . This is a stationary Markov process having transition function  $P(e^{ix}, \Gamma) = \frac{1}{2}I_\Gamma(e^{i(x+\theta)}) + \frac{1}{2}I_\Gamma(e^{i(x-\theta)})$ , where  $\Gamma$  is a circular Borel set. Using the customary function space representation, one may construct an automorphism  $T$  as described in Section 0, but we shall not pursue this point. Clearly  $\pi$  is continuous and, because the

random walk  $S_n$  is recurrent,  $N$  is a.s. finite. We defer the proof of ergodicity for the moment—see below.

EXAMPLE 2. Let  $\Omega = \{0, 1, 2\}^{\mathbb{N}}$ , where  $\mathbb{N} = \{1, 2, 3, \dots\}$  and let  $P$  be the product measure on  $\Omega$ , each coordinate measure being uniform over  $\{0, 1, 2\}$ . Let  $\Omega_0 \subseteq \Omega$  be the set of sequences which contain infinitely many zeros, ones and twos; clearly  $P(\Omega_0) = 1$ . Define  $T$  on  $\Omega_0$  as follows:

$$T(\omega_1, \omega_2, \dots, \omega_k, \omega_{k+1}, \dots) = (0, 0, \dots, 0, \omega_k + 1, \omega_{k+1}, \dots),$$

where  $k$  is the first integer for which  $\omega_k \neq 2$ . The transformation  $T$  (called the “adding machine” and well-known to ergodic theorists) is measure-preserving and ergodic.

Finally, let  $X(\omega) = \sum_{k=1}^{\infty} \delta(0, \omega_k)2^{-k}$ , where  $\delta$  is the Kronecker symbol. This clearly has a continuous distribution and one checks that  $N < \infty$  on  $\Omega_0$ .

(We learned of this example through an associate editor of this *Annals*.)

We will now show that, in various situations, it is impossible to have  $N$  a.s. finite and  $\pi$  continuous. Recall that a stationary sequence  $\{X_n\}$  is  $\phi$ -mixing if, for  $A \in \mathcal{F}_n$  and  $B \in \mathcal{F}'_{n+k}$ ,

$$|P(B \cap A) - P(A)P(B)| \leq \phi(k)P(A)$$

where  $\phi(k) \rightarrow 0$  as  $k \rightarrow \infty$ ; here  $\mathcal{F}_n$  is the  $\sigma$ -field generated by all  $X_m, m \leq n$ , and  $\mathcal{F}'_{n+k}$  is that generated by all  $X_m, m \geq n + k + 1$ .

(3) THEOREM. *If  $\{X_n\}$  is  $\phi$ -mixing and  $X_0$  has a continuous distribution, then  $P\{N < \infty\} < 1$ .*

PROOF. One can check that there is no loss of generality in assuming  $X_0$  is uniformly distributed on  $[0, 1]$ . Let

$$A_k = \{X_n = X_0 \text{ for some } n, n_k < n \leq n_{k+1}\},$$

where the sequence  $n_k$  is chosen so that  $\sum \phi(n_k) < \infty$ . If  $P(N < \infty) = 1$ , it follows (from the fact that  $T^N$  preserves measure) that  $P(A_k \text{ i.o.}) = 1$  (“i.o.” means “infinitely often”).

Let  $\Gamma_i = [(i - 1)/m, i/m)$ ,  $1 \leq i \leq m$ . We have, for  $m$  fixed,

$$\begin{aligned} P(A_k) &\leq \sum_{j=1}^m P\{X_0 \in \Gamma_j, X_n \in \Gamma_j \text{ for some } n, n_k < n \leq n_{k+1}\} \\ &\leq \sum_{j=1}^m [P\{X_0 \in \Gamma_j\}P\{X_n \in \Gamma_j \text{ for some } n, n_k < n \leq n_{k+1}\} \\ &\quad + \phi(n_k)P\{X_0 \in \Gamma_j\}] \\ &\leq \frac{1}{m} \sum_{j=1}^m \frac{n_{k+1} - n_k}{m} + \phi(n_k) = \frac{n_{k+1} - n_k}{m} + \phi(n_k). \end{aligned}$$

Letting  $m \rightarrow \infty$ , we find  $P(A_k) \leq \phi(n_k)$ , hence (Borel–Cantelli)  $P(A_k \text{ i.o.}) = 0$ , which contradicts  $P(N < \infty) = 1$ .  $\square$

In light of (3) it is interesting that the process of Example 1 satisfies the following mixing condition:

$$(4) \quad \sup_{A \in \mathcal{F}'_n, B \in \mathcal{F}} |P(A \cap B) - P(A)P(B)| \rightarrow 0 \quad \text{as } n \rightarrow \infty.$$

It is shown in [7] that (4) is equivalent to the triviality of  $\mathcal{F}$ , the tail  $\sigma$ -field of the process, i.e.  $P(A) = 0$  or  $1$  for every  $A \in \mathcal{F}$ , and so implies ergodicity. We will prove that  $\mathcal{F}$  is trivial in the appendix to Section 1.

If  $\{X_n\}$  is an i.i.d. sequence with a continuous common distribution, the return time  $N$  is a.s. infinite. In contrast, a  $\phi$ -mixing sequence may have  $N < \infty$  on a set of probability arbitrarily close to 1. For example, let  $0 < \alpha < 1$ , and let  $\mu$  be a continuous distribution on  $[0, 1]$ . Define a transition function of  $[0, 1]$  by  $P(x, \Gamma) = \alpha I_\Gamma(x) + (1 - \alpha)\mu(\Gamma)$ . The measure  $\mu$  is invariant for this transition function, and one may verify that the corresponding stationary Markov process  $\{X_n\}$  is  $\phi$ -mixing, with  $\phi(k) = \alpha^k$ , and  $P\{N < \infty\} = P\{N = 1\} = \alpha$ .

Suppose now that  $\{X_n\}$  is a stationary Markov process with state space  $(E, \mathcal{E})$ . We denote the transition function by  $P(x, \Gamma)$ ,  $x \in E$ ,  $\Gamma \in \mathcal{E}$ , and the initial (stationary) distribution by  $\pi$ . Our terminology for Markov process follows [7].

(5) THEOREM. *Under any of the conditions below, if  $P_\pi(N < \infty) = 1$ , then  $\pi$  is purely discrete:*

- (a) *the Harris recurrence condition;*
- (b) *the state space is indecomposable;*
- (c) *the process is  $\pi$ -nonsingular [7];*
- (d)  *$|P^n(x, \Gamma) - \pi(\Gamma)| \leq a_n$ , where  $\sum a_n < \infty$ .*

PROOF. (a) First note that  $P_\pi(N < \infty) = 1$  implies  $P_\pi(X_n = X_0 \text{ i.o.}) = 1$  which implies  $P_x\{X_n = x \text{ i.o.}\} = 1$  for  $\pi$ -a.e.  $x$ . Fix such an  $x$ , and define  $f(y) = P_y\{X_n = x \text{ i.o.}\}$ . This function is harmonic, hence ([7], page 22) constant by Harris recurrence. Since  $f(x) = 1$ , we have  $f(y) \equiv 1$ , and so conclude  $P_\pi\{X_n = x \text{ i.o.}\} = 1$  for  $\pi$ -a.e.  $x$ . But then  $\infty = \sum_{n=1}^\infty P_\pi\{X_n = x\} = \sum_1^\infty \pi(\{x\})$  for such  $x$ , and so  $\pi(\{x\}) > 0$  for  $\pi$ -a.e.  $x$ , i.e.  $\pi$  is purely discrete.

(b) As in (a),  $P_x\{X_n = x \text{ i.o.}\} = 1$   $\pi$ -a.e. For any such  $x$ ,  $P_y\{X_n = x \text{ for some } n \geq 1\} > 0$  for every  $y \in E$  by ([7], page 36), and so  $P_\pi\{X_n = x \text{ i.o.}\} > 0$ . One now shows  $\pi(\{x\}) > 0$  as in the proof of (a).

(c) Fix  $x$  and let  $f(y)$  be as in the proof of (a), so  $f(x) = 1$ . By nonsingularity there is an  $n$  such that  $P^n(x, dy)$  is not purely singular. Since  $f(x) = P^n f(x) = 1$ , it follows that  $f(y) > 0$  on a set of positive  $\pi$ -measure, whence  $P_\pi\{X_n = x \text{ i.o.}\} > 0$ . The proof is now completed as above. Notice that we only need the nonsingularity condition to hold for *almost every*  $x$  (cf. [7], page 42).

(d) Let  $\Delta$  be the complement of the set of atoms of  $\pi$ . Then

$$\begin{aligned} P_\pi(X_n = X_0, X_0 \in \Delta) &= \int_\Delta P_x\{X_n = x\}\pi(dx) \\ &= \int_\Delta P^n(x, \{x\})\pi(dx) \\ &= \int_\Delta (\pi(\{x\}) + a_n)\pi(dx) \leq a_n. \end{aligned}$$

By Borel-Cantelli,  $P_\pi\{X_n = X_0 \text{ i.o.}, X_0 \in \Delta\} = 0$ ; if  $P_\pi\{N < \infty\} = 1$ , we must have  $P_\pi\{X_0 \in \Delta\} = \pi(\Delta) = 0$ .  $\square$

From (5) it follows that the Markov process in Example 1 cannot satisfy

Harris recurrence, indecomposability, or the exponential convergence condition. One verifies the first two of these directly by considering the orbits  $\{e^{i(x+k\theta)} : k \in \mathbb{Z}\}$ . The last is more difficult in view of the mixing condition (4).

*Appendix.* Let  $\{X_n\}$ ,  $n \geq 0$ , be a Markov process with state space  $(E, \mathcal{E})$ , initial distribution  $\pi$ , and transition function  $P(x, \Gamma)$ . The usual operator on bounded,  $\mathcal{E}$ -measurable functions  $f$  is given by

$$Pf(x) = \int P(x, dy)f(y).$$

A sequence of functions  $g_n$  is called *space-time harmonic* if  $Pg_{n+1} = g_n$  for every  $n$ . An easy adaptation of an argument in [7] proves: a necessary and sufficient condition for the tail  $\sigma$ -field  $\mathcal{F}$  to be trivial relative to  $P_\pi$  is that every uniformly bounded space-time harmonic sequence  $g_n(x)$  be constant  $\pi$ -a.e., i.e. for some constant  $c$ ,  $g_n(x) = c$  for every  $n$  and  $\pi$ -a.e.  $x$ .

Suppose  $g_n(e^{ix})$  is a uniformly bounded space-time harmonic sequence for the process  $\{X_n\}$  of Example 1; the defining relation becomes

$$(6) \quad g_n(e^{ix}) = \frac{1}{2}[g_{n+1}(e^{i(x+\theta)}) + g_{n+1}(e^{i(x-\theta)})].$$

Write  $c_m^n$  for the  $m$ th Fourier coefficient of  $g_n$ . Expanding (6) in Fourier series and equating coefficients (all of which is easily justified) we find  $c_m^n = c_m^{n+1} \cos(m\theta)$  or  $c_m^n = c_m^1 / (\cos(m\theta))^{n-1}$ , where  $c_m = c_m^1$ . Note, since  $\theta/2\pi$  is irrational,  $0 < |\cos(m\theta)| < 1$ , for all  $m \neq 0$ . Thus, if  $c_m \neq 0$ , we have  $|c_m^n| \rightarrow \infty$  ( $n \rightarrow \infty$ ).

Now  $g_n$  is real-valued, so  $c_{-m}^n = c_m^n$ . Let  $M > 0$  be the first integer for which  $c_m \neq 0$ , if one exists. The  $M$ th partial sum of the Fourier series for  $g_n$  is then  $c_0 + 2c_M \cos(Mx) / (\cos(M\theta))^{n-1}$ , and the Cesaro average of the first  $M + 1$  partial sums equals  $c_0 + 2c_M \cos(Mx) / (M + 1)(\cos(M\theta))^{n-1}$ . It is well known that if a function is bounded in modulus by a constant, each of the corresponding Cesaro averages is bounded by the *same* constant. This is clearly impossible in the present situation unless  $c_m = 0$  for every  $m \neq 0$ , i.e.  $g_n(x) = c_0$  for every  $n$  and  $\pi$ -a.e.  $x$ .

**2. Structure of the  $\sigma$ -field  $\mathcal{A}_N$ .** In this section, we extend equation (2) and also indicate the structure of  $\mathcal{A}_N$ , the  $\sigma$ -field in  $\mathcal{F}$  which is invariant under  $T^N$ . (These topics turn out to be closely related). In addition to the assumptions of Section 0, we now take  $N < \infty$  a.s.

Let  $\mathcal{G}$  be a sub  $\sigma$ -field of  $\mathcal{F}$  and recall that a regular conditional probability (r.c.p.) given  $\mathcal{G}$  is a Markov kernel  $Q(\omega, A)$  which is a version of  $P(A | \mathcal{G})$ , i.e.  $Q(\cdot, A)$  is  $\mathcal{G}$ -measurable for each  $A \in \mathcal{F}$ ,  $Q(\omega, \cdot)$  is a probability measure on  $\mathcal{F}$  for each  $\omega \in \Omega$ , and  $\int_{\mathcal{G}} Q(\omega, A)P(d\omega) = P(AG)$  for each  $A \in \mathcal{F}$ ,  $G \in \mathcal{G}$ . Since we will need the existence of r.c.p.'s for various sub  $\sigma$ -fields, we now impose the requirements that  $\mathcal{F}$  be *separable* (i.e. generated by a countable subfamily) and that there is a compact subfamily  $C$  of  $\mathcal{F}$  relative to which  $P$  has the "inner approximation property"

$$(7) \quad P(A) = \sup \{P(B) : A \supset B \in C\}, \quad A \in \mathcal{F}.$$

This implies the existence of an r.c.p. for any sub  $\sigma$ -field  $\mathcal{G}$  of  $\mathcal{F}$ , as is fully explained in [5]; we will make no other use of (7).

Next we must lay the groundwork for the ergodic decomposition of  $T$  which will be used in reducing all problems to the ergodic case. An atom of a  $\sigma$ -field  $\mathcal{G}$  is defined as an equivalence class for the relation  $\omega \sim \omega'$  on  $\Omega$  determined by  $I_A(\omega) = I_A(\omega')$  for every  $A \in \mathcal{G}$ . It is well known that (i) every  $\mathcal{G}$ -measurable function is constant on the atoms of  $\mathcal{G}$ , and (ii) if  $\mathcal{G}$  is separable, then its atoms are  $\mathcal{G}$ -measurable.

(8) LEMMA. Let  $Q(\omega, A)$  be an r.c.p. given a separable sub  $\sigma$ -field  $\mathcal{G}$  of  $\mathcal{F}$ . Then:

- (a) for almost every  $\omega \in \Omega$ ,  $Q(\omega, A) = I_A(\omega)$  for all  $A \in \mathcal{G}$ ;
- (b) if  $f$  is a  $\mathcal{G}$ -measurable function, then, for almost every  $\omega \in \Omega$ ,  $f$  is equal to the constant  $f(\omega) Q(\omega, \cdot)$ -a.s.

PROOF. (a) Let  $\mathcal{H}$  be a countable field which generates  $\mathcal{G}$ . Then there exists a  $P$ -null set  $N$  such that  $Q(\omega, H) = I_H(\omega)$  for every  $H \in \mathcal{H}$ ,  $\omega \notin N$ ; this relation extends immediately to  $\mathcal{G}$  since two measures agreeing on  $\mathcal{H}$  must also agree on  $\mathcal{G}$ .

(b) Immediate, since  $Q(\omega, \cdot)$  is concentrated on that atom of  $\mathcal{G}$  which contains  $\omega$  (by (a)), for almost every  $\omega$ .  $\square$

Now we may discuss the ergodic decomposition of  $T$ . Proofs may be found in [8]. We write  $\mathcal{A}$  for the  $\sigma$ -field in  $\mathcal{F}$  of sets  $A$  which are strictly invariant under  $T: T^{-1}A = A$ . Finally,  $\bar{\mathcal{F}}$  will denote the  $P$ -completion of  $\mathcal{F}$  while  $\bar{\mathcal{A}}$  is the augmentation of  $\mathcal{A}$  in  $\bar{\mathcal{F}}$ , i.e.  $\bar{\mathcal{A}}$  is the  $\sigma$ -field generated by  $\mathcal{A}$  and  $P$ -null sets in  $\bar{\mathcal{F}}$  (similar notation will be used for other sub  $\sigma$ -fields of  $\mathcal{F}$ ).

(9) THEOREM. There exists a separable  $\sigma$ -field  $\mathcal{A}' \subseteq \mathcal{A}$  such that

- (a)  $\bar{\mathcal{A}}' = \bar{\mathcal{A}}$ ;
- (b)  $Q(\omega, A) = I_A(\omega)$  for all  $A \in \mathcal{A}'$ , and  $P$ -a.e.  $\omega \in \Omega$ , where  $Q$  is an r.c.p. given  $\mathcal{A}'$ ;
- (c) If  $\mathcal{C}$  is any separable sub  $\sigma$ -field of  $\mathcal{A}$  satisfying (a) and (b), and  $Q'$  an r.c.p. given  $\mathcal{C}$ , then, except for  $\omega$  on a  $P$ -null set
  - (i)  $Q'(\omega, \cdot)$  is preserved by  $T$
  - (ii)  $Q'(\omega, \cdot)$  is ergodic relative to  $T$ , i.e.  $Q'(\omega, A) = 0$  or  $1$  for every  $A \in \mathcal{A}$ .

Notice that  $Q, Q'$  above are also r.c.p.'s given  $\mathcal{A}$ .

Let now  $X$  be a random variable on  $(\Omega, \bar{\mathcal{F}}, P)$ , and assume the return time  $N$  is a.s. finite. Without loss of generality we may take  $Q(\omega, \cdot)$  to be ergodic for every  $\omega \in \Omega$  where  $Q$  is as in (9). In what follows, we write  $F(\omega, dx)$  for the conditional distribution of  $X$  given  $\mathcal{A}'$ , i.e.  $F(\omega, dx) = Q(\omega, \{X \in dx\})$ , and  $X \vee \mathcal{A}$  for the  $\sigma$ -field generated by  $X$  and  $\mathcal{A}$ .

(10) THEOREM.  $E(N|X \vee \mathcal{A})(\omega) = 1/F(\omega, \{X(\omega)\})$ .

PROOF. When  $T$  is ergodic ( $\mathcal{A}$  trivial), this result is Lemma (22) of [3], which we apply to the system  $(\Omega, \mathcal{F}, Q(\omega', \cdot), T)$  for a fixed  $\omega' \in \Omega$ , obtaining for  $Q(\omega', \cdot)$ -a.e.  $\omega$ ,

$$E_{\omega'}(N|X)(\omega) = 1/F(\omega', \{X(\omega)\}) .$$

Here and below  $E_{\omega'}$  indicates integration by the measure  $Q(\omega', \cdot)$ . We will show that, for  $\omega'$  outside a  $P$ -null set,

- 1°  $F(\omega', \{X(\omega)\}) = F(\omega, \{X(\omega)\}) \quad Q(\omega', \cdot)$ -a.s.
- 2°  $E_{\omega'}(N|X)(\omega) = E(N|X \vee \mathcal{A}')(\omega) \quad Q(\omega', \cdot)$ -a.s.,

and these together provide the result.

For every  $x$ ,  $F(\omega', \{x\})$  is an  $\mathcal{A}'$ -measurable function of  $\omega'$ , hence  $F(\omega', \{x\}) = F(\omega, \{x\})$  for every  $\omega \in A(\omega')$ , where  $A(\omega')$  denotes the atom of  $\mathcal{A}'$  which contains  $\omega'$ . Hence  $F(\omega', \{X(\omega)\}) = F(\omega, \{X(\omega)\})$  for every  $\omega \in A(\omega')$ , and, since  $Q(\omega', A(\omega')) = 1$ , we have 1°.

To prove 2°, it suffices to show that each member has the same  $E_{\omega'}$ -integral over sets of the form  $\{X \in \Gamma\} \cap A$ , where  $\Gamma \in \mathcal{E}$  and  $A \in \mathcal{A}'$ . The left member gives

$$\int_{\{X \in \Gamma\} \cap A} E_{\omega'}(N|X)(\omega) Q(\omega', d\omega) = I_A(\omega') E_{\omega'}(N|I_{\Gamma}(X)) ,$$

while, on the right, we find  $I_A(\omega') E_{\omega'}(I_{\Gamma}(X) E(N|X \vee \mathcal{A}'))$ . Now, to see that these are equal for almost all  $\omega'$ , we note that both are  $\mathcal{A}'$ -measurable and have the same expectation for every  $A \in \mathcal{A}'$ .  $\square$

REMARK. As for  $EN$  itself, it can be shown that for discrete  $X$ ,  $EN = \sum_{x \in \mathbb{R}} P(B_x) \leq \infty$  where  $B_x = \bigcup_{n \in \mathbb{Z}} \{X_n = x\}$ . Call  $X$  "conditionally discrete" if  $F(\omega, dx)$  is a discrete distribution for almost every  $\omega \in \Omega$ . For such  $X$ , it follows at once from the invariance of the  $B_x$ 's that

$$EN = E(\sum_{x \in \mathbb{R}} I_{B_x}(\omega)) ,$$

the mean cardinality of the "range"  $\{X_n(\omega)\}$ . (Or take expectations of both sides of (10).) Of course, the order of integration cannot, in general, be reversed. In the ergodic case,  $EN$  is just the number of atoms of  $P(X \in dx)$ .

We now describe the  $\sigma$ -field  $\mathcal{A}_N$  of sets  $A \in \mathcal{F}$  such that  $(T^N)^{-1}A = A$ .

(11) THEOREM. For any random variable  $X$ , the following are equivalent:

- (a)  $\overline{\mathcal{A}_N} = \overline{\sigma(X)}$ ;
- (b)  $(P_x, T^N)$  is ergodic for  $\pi$ -a.e.  $x$ .

If, in addition,  $X$  is discrete, then (a) and (b) are equivalent to each of

- (c)  $\mathcal{A} \subseteq \overline{\sigma(X)}$ ;
- (d)  $(P(\cdot|B), T)$  is ergodic for all  $x$  for which  $P(X = x) > 0$ .

PROOF. To prove (a)  $\Rightarrow$  (b), apply Theorem (9c) to the system  $(\Omega, \mathcal{F}, P, T^N)$ . Suppose (b) holds for  $A \in \mathcal{A}_N$ ; let  $\Gamma = \{x: P_x(A) = 1\}$ , noting that  $P_x(A) = 0$

for  $x \notin \Gamma$ , except for a  $\pi$ -null set. We then have, for  $B \in \mathcal{F}$ ,

$$P(A \cap B) = \int P_x(A \cap B)\pi(dx) = \int_{\Gamma} P_x(B)\pi(dx) = P(B, x \in \Gamma),$$

and hence  $A = (X \in \Gamma)$  a.s., i.e. the symmetric difference has measure zero.

Now suppose that  $X$  is discrete. We will show that (c)  $\Rightarrow$  (d) and (d)  $\Rightarrow$  (b); since (a)  $\Rightarrow$  (c) is trivial, we will then be done. (c)  $\Rightarrow$  (d). Choose  $A \in \mathcal{A}$  and  $x$  such that  $P(X = x) > 0$ . Since  $\mathcal{A} \subseteq \overline{\sigma(X)}$ , there exists a  $\Gamma$  such that  $A = (X \in \Gamma)$  a.s. Now, if  $x \in \Gamma$ ,  $B_x \subseteq \bigcup_n (X_n \in \Gamma) = (X \in \Gamma)$  a.s.; if  $x \notin \Gamma$ ,  $B_x \subseteq \bigcup_n (X_n \in \Gamma^c) = (\bigcap_n (X_n \in \Gamma))^c = (X \in \Gamma^c)$  a.s. In either case,  $P(A|B_x) = I_{\Gamma}(x)$  and (d) is proven. (d)  $\Rightarrow$  (b). First, for any  $\mathcal{F}$ -measurable  $Z \geq 0$ , if  $P(X = x) > 0$ ,

$$(*) \quad E(Z|B_x) = \frac{1}{E_x N} E_x \sum_{k=0}^{n-1} Z \circ T^k.$$

To see this, write  $E(Z; B_x) = \sum_{n=0}^{\infty} E(Z; X_{-n} = x, X_{-n+i} \neq x, i = 1, \dots, n)$  and apply  $T^n$  in the  $n$ th term. The rest of the proof can be done along the lines suggested by Ryll-Nardzewski for the ‘‘point process’’ case (i.e.  $X = I_{\Gamma}$ ), that is, using (\*) and the characterization of ergodic measures as extreme points. We omit the details, although some care must be taken since, in the point process case,  $B_0 = B_1 = \Omega$  and the  $B_x$ ’s play no role.

(12) THEOREM. *If  $X$  is conditionally discrete, then  $\overline{\mathcal{A}}_N = \overline{X \vee \mathcal{A}}$ .*

NOTE. We will give an example below in which the conclusion of (12) holds, but with  $X$  not conditionally discrete, and also one with  $X$  conditionally discrete but not discrete. A general proof of (12) without any condition on  $X$  still eludes us; the following shows that it would suffice to prove (12) for ergodic systems.

PROOF. In the ergodic case ‘‘conditionally discrete’’ is just ‘‘discrete,’’ so use Theorem 11, (c)  $\Rightarrow$  (a). In general, for  $X$  conditionally discrete apply the result in the ergodic case to each system  $(\Omega, \mathcal{F}, Q(\omega', \cdot), T)$ : if  $Y$  is  $\mathcal{A}_N$ -measurable, it will be measurable in the  $Q(\omega', \cdot)$ -completion of  $\sigma(X)$  for each  $\omega'$ , i.e.,  $Y = E_{\omega'}(Y|X)$ ,  $Q(\omega', \cdot)$ -a.s. Putting  $Y$  in place of  $N$  in 2° in the proof of (10), we conclude  $Y = E(Y|X \vee \mathcal{A}')$   $Q(\omega', \cdot)$ -a.s., and this for a.e.  $\omega'$ . So  $Y$  is  $\overline{X \vee \mathcal{A}'}$ -measurable. Since  $X \vee \mathcal{A} \subseteq \mathcal{A}_N$ , the proof is concluded.

(13) COROLLARY. *If  $E(N) < \infty$ ,  $\overline{\mathcal{A}}_N = \overline{X \vee \mathcal{A}}$ .*

In fact, from the proof of (10) it is clear that if only the conditional expectation of  $N$  given  $X$  is finite,  $X$  is conditionally discrete, so that (12) applies.

REMARKS. (a) It can be shown that  $X \vee \mathcal{A}$  and  $\mathcal{A}_N$  have the same atoms whenever ‘‘points’’  $\{\omega\}$  are in  $\mathcal{F}$ . If, for example,  $(\Omega, \mathcal{F})$  were a Blackwell space and these  $\sigma$ -fields were separable, one could then conclude they were equal, but  $\mathcal{A}$  and  $\mathcal{A}_N$  are typically not separable.

(b) Theorem (11) allows us to prove that  $\overline{\mathcal{A}}_N = \overline{\sigma(X)}$  for any stationary



Markov process with  $N < \infty$  a.s., in particular the process in Example 1. To see this, fix an  $x$  such that  $P_x(X_n = x \text{ i.o.}) = 1$ . Writing  $\tau_k^x$  for the  $k$ th return to  $x$  (so  $\tau_k^x = (T^N)^k P_x$ -a.s.), it is well known (see, e.g. [1], page 140) that the random ( $\mathbb{R}^\infty$ -valued) vectors  $Z_k = (X_{\tau_k^x}, \dots, X_{\tau_{k+1}^x-1})$ ,  $k \geq 1$ , are i.i.d. under  $P_x$ . However, a moment's reflection shows that any  $T^N$ -invariant random variable (for the process) is measurable over the tail  $\sigma$ -field of the  $\{Z_k\}$  process, and hence constant  $P_x$ -a.s. Note that  $\overline{\mathcal{A}_N} = \overline{\sigma(X)}$  is equivalent to  $\overline{X \vee \mathcal{A}} = \overline{\mathcal{A}_N}$  since we always have  $\mathcal{A} \subseteq \overline{\sigma(X)}$ —see [2], page 460.

EXAMPLE 3. We can “code” an integer-valued stationary sequence into one with the same recurrence structure but with a continuous initial distribution. For example, given independent, stationary sequences  $\{Z_n\}$  and  $\{Y_n\}$ , the former  $\mathbb{Z}$ -valued and the latter with  $P(Y_1 \in dx)$  continuous, consider the “coded” stationary sequence  $\{Y_{Z_n(\omega)}(\omega)\}$ , which repeats its initial value a.s. and has the same initial distribution as  $Y_0$ .

To pursue such examples, it will be convenient to take  $\Omega = \prod_{-\infty}^{\infty} (\mathbb{R} \times \mathbb{Z})$  with the usual product  $\sigma$ -field. For  $\omega = (\dots, n_{-1}; y_0, n_0, y_1, n_1, \dots) \in \Omega$ , define  $Z(\omega) = n_0$ ,  $Y_n(\omega) = y_n$ , and  $X(\omega) = y_{n_0}$ ; moreover, define a bijective, bimeasurable transformation  $T: \Omega \rightarrow \Omega$  by  $T(\omega) = (\dots, n_0; y_0, n_1, y_1, n_2, \dots)$ . In this way,  $X \circ T^n = Y_{Z \circ T^n}$  for all  $n$  and  $N \equiv \min(n \geq 1: X \circ T^n = X) \leq \min(n \geq 1: Z \circ T^n = Z)$ . For the probability  $P$ , we choose any one preserved by  $T$  and for which each of the  $Y_n$ 's is independent of  $Z$  and has a continuous law. In particular,  $X$  then has a continuous law. (For instance, choose  $P = \prod_{-\infty}^{\infty} (\mu \times \nu)$  where  $\mu, \nu$  are probabilities on  $\mathbb{R}, \mathbb{Z}$  respectively and  $\mu$  is continuous.)

Now clearly  $N < \infty$  a.s. and notice that  $X$ , though not discrete, is “conditionally discrete.” Indeed,  $F(\omega, B) \equiv \sum_{n \in \mathbb{Z}} P(Z = n | \mathcal{A})(\omega) I_B(Y_n(\omega))$  is clearly a probability measure on  $\mathcal{B}$  for each  $\omega$ ,  $\mathcal{A}$ -measurable (since the  $Y_n$ 's are) for each  $B \in \mathcal{B}$  and for any  $A \in \mathcal{A}$ ,  $B \in \mathcal{B}$ :  $E(F(\omega, B); A) = \sum_{n \in \mathbb{Z}} P(Z = n, Y_n \in B, A) = P(X \in B, A)$ . Thus  $\overline{X \vee \mathcal{A}} = \overline{\mathcal{A}_N}$ . Such systems, of course, are never ergodic due to the invariance of the  $Y_n$ 's.

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