

## MINIMIZATION ALGORITHMS AND RANDOM WALK ON THE $d$ -CUBE<sup>1</sup>

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Consider the number of steps needed by algorithms to locate the minimum of functions defined on the  $d$ -cube, where the functions are known to have no local minima except the global minimum. Regard this as a game: one player chooses a function, trying to make the number of steps needed large, while the other player chooses an algorithm, trying to make this number small. It is proved that the value of this game is approximately of order  $2^{d/2}$  steps as  $d \rightarrow \infty$ . The key idea is that the hitting times of the random walk provide a random function for which no algorithm can locate the minimum within  $2^{d(1/2-\epsilon)}$  steps.

**1. Introduction.** An important practical problem is to find algorithms to locate the minimum of functions on  $R^d$ . As an abstraction of the “dimensionality” part of this problem, Tovey (1981) studied algorithms to locate the minimum of functions defined on the vertices of the unit cube in  $d$  dimensions (the  $d$ -cube). Let  $I = \{i, j, k, \dots\}$  be the vertices of the  $d$ -cube. Let  $\mathcal{F}$  be the set of functions  $f: I \rightarrow R$  taking distinct values. For brevity, say “evaluate  $i$ ” for “evaluate the value of  $f$  at vertex  $i$ .” An *algorithm*  $\mathbf{a}$  is a rule specifying which vertex to evaluate next, depending on the vertices already evaluated. Mathematically, an algorithm can be described as a collection  $(j_1; a_n, n \geq 1)$  where  $j_1$  is an initial vertex and  $a_n$  a function  $I^n \times R^n \rightarrow I$ . When the algorithm is applied to  $f$ , it evaluates the series  $j_1, j_2, \dots$  of vertices, where

$$j_{n+1} = a_n(j_1, \dots, j_n, f(j_1), \dots, f(j_n)),$$

and terminates at vertex  $j_N$ , for some  $N = N(f, \mathbf{a})$ . Since we are concerned with minimization algorithms, we require

$$(1.1) \quad f(j_N) = \min_I f = f_{(1)}, \quad \text{for each } f,$$

where  $f_{(1)}, f_{(2)}, \dots, f_{(2^d)}$  is the increasing ordering of  $\{f(i): i \in I\}$ . We are interested in algorithms which make small the number  $N(f, \mathbf{a})$  of vertices which have to be evaluated (the *number of steps*). If no restrictions are placed on  $f$ , then to ensure (1.1), an algorithm must evaluate every vertex, so  $N(f, \mathbf{a})$  cannot be smaller than  $2^d$ . But if we restrict  $f$  to some subclass  $\mathcal{F}_0$  of  $\mathcal{F}$ , it may be possible to do better. Following Tovey (1981) we shall consider the class  $\mathcal{F}_0$  of *local-global* functions. That is, functions  $f$  such that for each vertex  $j$ ,

either  $f(j) = \min_I f$ ,  
or there exists a neighbor  $k$  of  $j$  such that  $f(k) < f(j)$ .

For this class there is an obvious algorithm, the *optimal-adjacency* algorithm  $\mathbf{a}^*$  which can be summarised as follows.

1. Let  $j$  be the initial vertex  $j_1$ .
2. Evaluate the neighbors  $k_1, \dots, k_d$  of  $j$ . If  $f(j) < \min f(k_n)$ , terminate. Otherwise proceed to 3.
3. Let  $k$  be the neighbor for which  $f(k) = \min f(k_n)$ . Set  $j = k$  and go to 2.

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For future reference note

$$(1.2) \quad \text{if } f(j_1) = f_{(m)} \text{ then } N(f, \mathbf{a}^*) \leq md + 1.$$

How good is this algorithm? Tovey (1981) observed that the worst case is very bad:

$$\sup_{\mathcal{F}_0} N(f, \mathbf{a}^*) / 2^{d(1-\epsilon)} \rightarrow \infty \text{ as } d \rightarrow \infty; \quad \epsilon > 0.$$

But his simulations with several specific distributions  $\mu$  on  $\mathcal{F}_0$  suggest that  $E_\mu N(f, \mathbf{a}^*)$  is of order  $d^2$  for these specific distributions, so that in practice this algorithm seems good.

Our purpose is to present a theoretical result, adopting the viewpoint of game theory. Imagine one player choosing  $f$  at random from some distribution  $\mu$  on  $\mathcal{F}_0$ , and another player choosing  $\mathbf{a}$  at random from some distribution  $\nu$  on the set  $\mathcal{A}$  of algorithms. The first player seeks to maximize  $N(f, \mathbf{a})$ , the second to minimize it. Now  $\mathcal{F}$  and  $\mathcal{A}$  are essentially finite, because only the ordering  $(f_{(n)})$  matters, so the fundamental theorem of game theory asserts that the game has a value

$$v = \sup_\mu \inf_\nu E_{\mu, \nu} N(f, \mathbf{a}) = \inf_\nu \sup_\mu E_{\mu, \nu} N(f, \mathbf{a}).$$

We shall prove that  $v$  is roughly of order  $2^{d/2}$ . Precisely

THEOREM 1.3.  $\frac{\log(v)}{d \log(2)} \rightarrow \frac{1}{2} \text{ as } d \rightarrow \infty.$

Informally, one might say that locating the minimum of a local-global function requires exponential rather than polynomial time. Such problems are studied in computational complexity theory, but the techniques used there do not seem to give explicit results like Theorem 1.3.

The proof of the upper bound is very easy. It suffices to exhibit a random algorithm (distribution  $\nu$ , say, on  $\mathcal{A}$ ) such that

$$(1.4) \quad E_\nu N(f, \mathbf{a}) \leq Cd2^{d/2}, \quad f \in \mathcal{F}_0,$$

where  $C$  is a constant not depending on  $f, d$ . Set  $M = \lceil 2^{d/2} \rceil$  and consider the following random algorithm.

1. Pick  $M$  vertices  $J_1, \dots, J_M$  at random (uniformly, independently) from  $I$ . Let  $J$  be a vertex for which  $f(J) = \min f(J_n)$ .
2. Follow the optimal-adjacency algorithm from  $J$ .

Fix  $f \in \mathcal{F}_0$ . For  $m \geq 1$ ,

$$(1.5) \quad \begin{aligned} P_\nu(N(f, \mathbf{a}) > M + md + 1) &\leq P(f(J) > f_{(m)}) \text{ by (1.2)} \\ &= P(f(J_n) > f_{(m)}, 1 \leq n \leq M) \\ &= (1 - m2^{-d})^M. \end{aligned}$$

Now

$$E_\nu N(f, \mathbf{a}) = \sum_{n \geq 0} P(N(f, \mathbf{a}) > n) \leq M + 1 + d \sum_{m \geq 0} (1 - m2^{-d})^M \text{ by (1.5)}$$

and calculus gives (1.4).

The proof of the lower bound involves the random walk, whose basic properties are developed in Section 2. The reader may wish first to glance at Section 3, which outlines how the random walk is used to obtain the lower bound.

**2. The random walk.** Each vertex  $i$  of the  $d$ -cube can be represented as a  $d$ -tuple  $(i_1, \dots, i_d)$  of 0's and 1's. Let  $|i - j| = \sum |i_r - j_r|$ , so vertices  $i, j$  are *neighbors* if  $|i - j| = 1$ . Let  $\pi$  be the uniform distribution on  $I$ ;  $\pi(i) \equiv 2^{-d}$ . By the *random walk*  $(X_t)_{t \geq 0}$  on  $I$  we

mean the the continuous-time Markov chain with  $Q$ -matrix

$$Q(i, j) = 1/d; \quad |i - j| = 1$$

$$= 0; \quad \text{other } i \neq j.$$

Thus  $X$  holds at vertex  $i$  for an exponential (mean 1) time, then jumps to a neighboring vertex selected uniformly from the  $d$  neighbors of  $i$ . Unless otherwise specified, take the initial distribution  $X_0$  to be uniform on  $I$ . Write  $P_i(\cdot), E_i(\cdot)$  for probability, expectation given  $X_0 = i$ . Write  $p_{i,j}(t) = P_i(X_t = j)$ .

The process  $(X_t)$  may be written coordinatewise as  $(X_t^1, \dots, X_t^d)$ . It is easy to verify that the coordinate processes  $(X_t^i)$  are independent Markov chains on  $\{0, 1\}$  with  $Q$ -matrix  $Q(0, 1) = Q(1, 0) = 1/d$ . It is therefore elementary to obtain the formula

$$(2.1) \quad p_{i,j}(t) = 2^{-d}(1 + e^{-2t/d})^{d-m}(1 - e^{-2t/d})^m, \quad \text{where } m = |i - j|.$$

The simplicity of this formula is the reason for using the continuous time random walk instead of the discrete time version. Note that the uniform distribution  $\pi$  is the stationary distribution, and  $p_{i,j}(t) \rightarrow 2^{-d} = \pi(j)$  as  $t \rightarrow \infty$ .

Let  $H_i$  be the first *hitting* time of vertex  $i$ :

$$H_i = \inf\{t \geq 0: X_t = i\}.$$

Let  $H_i^+$  be the first *entry* time of  $i$ :

$$H_i^+ = \min\{t > 0: X_t = i, X_{t-} \neq i\}.$$

So  $H_i^+ = H_i$  unless  $X_0 = i$ . Let  $L_i$  be the first *exit* time from  $i$ :

$$L_i = \inf\{t > H_i: X_t \neq i\}.$$

For a non-empty subset  $A$  of  $I$  let

$$H_A = \min_A H_i; \quad H_A^+ = \min_A H_i^+; \quad L_A = \min_A L_i.$$

Note that  $L_A$  is the first time  $X$  exits some vertex of  $A$ , *not* the first time  $X$  exits  $A$ .

Fix  $t > 0$ . Call two processes  $(Y_u)_{0 \leq u \leq t}, (Z_u)_{0 \leq u \leq t}$  *time-reversals* of each other if  $(Y_u)$  has the same distribution as  $(Z_{t-u})$ . It is not hard to verify that the following pairs are time-reversals of each other. Throughout,  $(X_u)$  is the random walk.

$$(2.2) \quad \begin{aligned} (a) & (X_u) \text{ with } X_0 \text{ uniform, conditioned on } X_t = i; \\ (b) & (X_u) \text{ with } X_0 = i. \end{aligned}$$

$$(2.3) \quad \begin{aligned} (a) & (X_u) \text{ with } X_0 \text{ uniform, conditioned on } L_i = t; \\ (b) & (X_u) \text{ with } X_0 = i, \text{ conditioned on } H_i^+ > t. \end{aligned}$$

$$(2.4) \quad \begin{aligned} (a) & (X_u) \text{ with } X_0 \text{ uniform, conditioned on } L_A = t, X(L_A-) = i; \\ (b) & (X_u) \text{ with } X_0 = i, \text{ conditioned on } H_A^+ > t. \end{aligned}$$

Think of the event " $L_A = t, X(L_A-) = i$ " as meaning " $X$  hits  $A$  at vertex  $i$ , and first exits  $i$  at time  $t$ ." Of course events like this have probability zero: strictly, our assertions should be formulated in terms of regular conditional distributions.

We shall need estimates for the transition probabilities  $p_{i,j}(t)$  and the distribution of  $H_i$ . The lemmas below are sufficient for our needs (Lemma 2.8 could alternatively be derived by transform techniques, which give an explicit though complicated expression for the distribution of  $H_i$ ).

LEMMA 2.5. (a) For  $\epsilon < 1$  and  $t \geq (d/2)\log(2d/\epsilon)$ ,  $|p_{i,j}(t) - 2^{-d}| \leq \epsilon 2^{-d}$ .

(b)  $\int_0^d p_{i,i}(t) dt \rightarrow 1$  as  $d \rightarrow \infty$ .

(c)  $\int_0^{2^{d/2}} p_{i,i}(t) dt \rightarrow 1$  as  $d \rightarrow \infty$ .

(d)  $P_i(X_t = i \text{ for some } L_i < t \leq 2^{d/2}) \rightarrow 0$  as  $d \rightarrow \infty$ .

PROOF. Assertion (a) is a straightforward consequence of (2.1). The integral in (b) may be written as

$$\int_0^\infty \left\{ \frac{1 + e^{-2t/d}}{2} \right\}^d 1_{(t \leq d)} dt.$$

The integrand converges pointwise to  $e^{-t}$  and is dominated by  $e^{-at}$ , where  $a > 0$  is chosen so that  $e^{ax} + e^{(a-2)x} \leq 2$  on  $0 \leq x \leq 1$ . Use the dominated convergence theorem. For (c),

$$\int_d^{2^{d/2}} p_{i,i}(t) dt \leq 2^{d/2} \sup_{t \geq d} p_{i,i}(t) = 2^{d/2} \left\{ \frac{1 + e^{-2}}{2} \right\}^d \rightarrow 0.$$

Assertion (d) follows easily from (c) and the fact that each sojourn at  $i$  has expected duration 1.

Define

$$(2.6) \quad t_1 = \frac{d}{2} \log(2d2^d).$$

Roughly,  $t_1$  is of order  $d^2$ . By (2.5)(a),

$$(2.7) \quad |p_{i,j}(u) - 2^{-d}| \leq 2^{-2d}, \quad u \geq t_1.$$

So conditional on  $X_0$ , the distribution of  $X$  at any time  $u \geq t_1$  is almost uniform; informally, events separated by time  $t_1$  or more are almost independent.

Let time ( $t \leq t_0$ ;  $X_t = j$ ) be the random variable measuring the duration of time before  $t_0$  for which  $X$  is at  $j$ .

LEMMA 2.8. *There exist constants  $\varepsilon_1(d), \varepsilon_2(d) \rightarrow 0$  as  $d \rightarrow \infty$  such that*

(a)  $P(H_i \leq u) \geq u2^{-d}(1 - \varepsilon_1(d)), u \leq 2^{d/2}$ .

(b)  $P(H_i \leq u) \leq u2^{-d}(1 + \varepsilon_2(d)), u \geq t_1$ .

PROOF. (a) By considering the first hit on  $i$ ,

$$E_\pi \text{ time}(t \leq u; X_t = i) \leq P_\pi(H_i \leq u) \cdot E_i \text{ time}(t \leq u; X_t = i) = P_\pi(H_i \leq u) \cdot \int_0^u p_{i,i}(t) dt.$$

By symmetry,  $E_\pi \text{ time}(t \leq u; X_t = i)$  does not depend on  $i$ , so must equal  $u2^{-d}$ . Apply (2.5)(c).

(b) Again by considering the first hit on  $i$ ,

$$E_\pi \text{ time}(t \leq u + d; X_t = i) \geq P_\pi(H_i \leq u) \cdot E_i \text{ time}(t \leq d; X_t = i) = P_\pi(H_i \leq u) \cdot \int_0^d p_{i,i}(t) dt.$$

Again  $E \text{ time}(t \leq u + d; X_t = i) = (u + d)2^{-d}$  by symmetry. Rearrange, and apply (2.5)(b) and (2.6).

**3. The random walk and the lower bound for  $v$ .** As in Section 2,  $(X_t)$  is the random walk with uniform initial distribution. The collection  $(H_i)$  of first hitting times may be regarded as a random function  $H: I \rightarrow [0, \infty)$ . For each  $\omega$  and each  $j \in I$ :

either  $H_j(\omega) = 0$  (that is,  $X_0(\omega) = j$ );

or  $X_{H_j(\omega)-}$  is a neighboring vertex ( $k$ , say) of  $j$ , and  $H_k(\omega) < H_j(\omega)$ .

Thus each  $H(\omega)$  is a local-global function. For technical reasons it is convenient to use the first exit times  $(L_i)$  instead of the first hitting times. Again, we may regard the collection  $(L_i)$  as a random local-global function  $L$ . Of course  $L$  attains its minimum at the vertex  $X_0$ . We shall prove that no algorithm can locate this minimum in much less than  $2^{d/2}$  steps.

Precisely:

$$(3.1) \quad \frac{\inf_{\mathbf{a}} EN(L, \mathbf{a})}{2^{d(1/2-\epsilon)}} \rightarrow \infty \quad \text{as } d \rightarrow \infty; \quad \epsilon > 0,$$

and this will establish the lower bound in Theorem 1.3.

The details of the argument are rather intricate; here are the underlying ideas. First we argue that there is no loss of generality in assuming that the first vertex  $j_1$  evaluated has  $L_{j_1} \approx 2^{d/2}$ . Now suppose the algorithm has evaluated  $L$  at vertices  $j_1, \dots, j_n$ . Let  $A = \{j_1, \dots, j_n\}$  and let  $i_0$  be the element of  $A$  for which  $L_{i_0} = \min L_{j_i}$ . The algorithm selects some vertex  $j$  to evaluate next: suppose we can prove that for any  $j$

$$(*) \quad P(L_j < L_{i_0} - t_1) \text{ is at most order } 2^{-d/2}$$

where  $t_1$  was defined at (2.6). Since  $\min L$  is almost zero, (\*) and induction show that  $N(L, \mathbf{a})$  is likely to be at least  $2^{d/2}/t_1$ , giving the result. Why does (\*) hold? By time reversal, the probability in (\*) is at most

$$(**) \quad P_{i_0}(X \text{ visits } j \text{ during } [t_1, 2^{d/2}] | X \text{ does not re-enter } A).$$

Without the conditioning, this probability would indeed be of order  $2^{-d/2}$ , by Lemma 2.8(b). To handle the conditioning, we need regularity properties of  $A$  to ensure that the conditioning does not affect much the behavior of  $X$  after time  $t_1$ ; and then we need to ensure that these regularity properties are carried forward in the induction. This makes the proof technically complicated.

4. We now start the formal argument for (3.1). In this section we show how (3.1) can be reduced to Lemmas 4.17 and 4.19, which are assertions about the behavior of the random walk, not involving any algorithm.

Let  $0 < \epsilon < 1/4$  be fixed throughout. We make two conventions. First, each assertion will hold “for  $d$  sufficiently large,” that is for  $d$  larger than some  $d_0(\epsilon)$  depending only on  $\epsilon$  and the assertion. Second, subsets  $A$  of  $I$  are assumed to satisfy

$$(4.1) \quad 1 \leq \#A \leq 2^{d(1/2-2\epsilon)}.$$

Recall definition (2.6) of  $t_1$ . By (2.7)

$$(4.2) \quad p_{i,j}(u) \leq 2^{-d}(1 + 2^{-d}); \quad u \geq t_1.$$

Also, by (2.6),

$$(4.3) \quad t_1(1 + \#A) \leq 2^{d(1/2-\epsilon)}.$$

(Here we use the conventions:  $A$  satisfies (4.1), and (4.3) holds for  $d$  sufficiently large.)

**DEFINITION 4.4.** Let  $A \subset I, i \in A, t > 0$ . Say  $(i, A, t)$  is *regular* if

- (a)  $2^{d/2} \geq t \geq 2^{d(1/2-\epsilon)} - t_1\#A$
- (b)  $s(i, A, u) \leq 2 \cdot 2^{-d}$ , where

$$(4.5) \quad u = t - 2^{d(1/2-\epsilon)} + t_1(1 + \#A)$$

and where  $s$  is a certain function to be specified later (5.1).

Note that if (a) holds, then by (4.3)

$$(4.6) \quad t_1 \leq u \leq t.$$

**DEFINITION 4.7.** Let  $A \subset I$  and let  $f$  be a local-global function on  $I$ . Say  $(f, A)$  is *good* if  $(i, A, f(i))$  is regular, where  $i \in A$  is the vertex for which

$$(4.8) \quad f(i) = \min_A f.$$

Let  $\mathbf{a}$  be an algorithm as in Section 1. When  $\mathbf{a}$  is applied to the random local-global

function  $L$ , it evaluates a sequence of vertices  $J_1, J_2, \dots$  of the form

$$(4.9) \quad J_1 = j_1, \quad J_{n+1} = a_n(J_1, \dots, J_n, L_{J_1}, \dots, L_{J_n});$$

the algorithm terminates after  $N = N(L, \mathbf{a})$  steps, and  $J_{N(L, \mathbf{a})} = X_0$ . For notational convenience, set  $J_n = J_N, n \geq N$ . We shall prove

$$(4.10) \quad EN(L, \mathbf{a}) \geq \frac{1}{2} 2^{d(1/2-2\epsilon)}(1 - o(1)) \quad \text{as } d \rightarrow \infty,$$

which establishes (3.1).

LEMMA 4.11. *Let  $J_1$  be a random vertex, dependent on the random walk  $(X_t)$ . If (4.10) holds for algorithms  $\hat{\mathbf{a}}$  with initial vertex  $J_1$ , then it holds for all  $\mathbf{a}$  with deterministic initial vertex.*

PROOF. Given any algorithm  $\mathbf{a}$ , we can define an algorithm  $\hat{\mathbf{a}}$  which has random initial vertex  $J_1$  but then ignores the information given by  $J_1, L_{J_1}$ , and proceeds as  $\mathbf{a}$ . Then  $N(L, \hat{\mathbf{a}}) = N(L, \mathbf{a}) + 1$ .

In other words, in proving the lower bound (4.10) we may specify the initial vertex  $J_1$  any way we choose. We shall take  $J_1$  to be the vertex visited immediately before the vertex occupied by  $X_t$  at time  $2^{d(1/2-\epsilon)}$ ,

$$(4.12) \quad J_1 = X(H_{J_0-}), \quad \text{where } J_0 = X(2^{d(1/2-\epsilon)}).$$

The algorithm then evaluates  $J_2, J_3, \dots$  of the form (4.9). Let  $A_n^*$  be the random set  $\{J_1, \dots, J_n\}$ . We shall prove

$$(4.13) \quad P((L, A_1^*) \text{ is good}) \rightarrow 1 \quad \text{as } d \rightarrow \infty;$$

$$(4.14) \quad P((L, A_{n+1}^*) \text{ is not good} \mid (L, A_n^*) \text{ is good}) \leq 6 \cdot 2^{-d/2}$$

(this is a formalisation of the idea of (\*), Section 3). Let us show how to deduce (4.10) from these assertions. Set  $n_0 = \lceil 2^{d(1/2-2\epsilon)} \rceil$ . By (4.14)

$$(4.15) \quad \begin{aligned} P((L, A_{n_0}^*) \text{ is good}) &\geq (1 - 6 \cdot 2^{-d/2})^{n_0} P((L, A_1^*) \text{ is good}) \\ &\rightarrow 1 \quad \text{as } d \rightarrow \infty \quad \text{by (4.13)}. \end{aligned}$$

On the set where  $(L, A_{n_0}^*)$  is good, (4.4) (a) implies

$$\begin{aligned} L_{A_{n_0}^*} &\geq 2^{d(1/2-\epsilon)} - t_1 n_0 \\ &\geq \frac{1}{2} \cdot 2^{d(1/2-\epsilon)}, \quad \text{for } d \text{ sufficiently large.} \end{aligned}$$

On the set where  $N(L, \mathbf{a}) \leq n_0$ , we have  $L_{A_{n_0}^*} = L_{X_0}$ , and so  $X_t = X_0$  on  $0 \leq t < L_{A_{n_0}^*}$ . So

$$(4.16) \quad \begin{aligned} P((L, A_{n_0}^*) \text{ is good}, N(L, \mathbf{a}) \leq n_0) &\leq P(X_t = X_0 \quad \text{on } 0 \leq t < \frac{1}{2} \cdot 2^{d(1/2-\epsilon)}) \\ &\rightarrow 0 \quad \text{as } d \rightarrow \infty. \end{aligned}$$

Now (4.15) and (4.16) imply  $P(N(L, \mathbf{a}) \geq n_0) \rightarrow 1$  as  $d \rightarrow \infty$ , which establishes (4.10).

We have now reduced the proof of Theorem 1.3 to the proof of (4.13) and (4.14). Next, we translate these assertions into assertions about the random walk. For (4.13) this is straightforward from Definitions 4.7 and 4.4; it suffices to prove

LEMMA 4.17.

- (a)  $P(2^{d/2} \geq L_{J_1} \geq 2^{d(1/2-\epsilon)} - t_1) \rightarrow 1$  as  $d \rightarrow \infty$ ;
- (b)  $s(j, \{j\}, u) \leq 2 \cdot 2^{-d}$  for  $j \in I; t_1 \leq u \leq 2^{d/2}$ .

We shall prove this in Section 5. Translating (4.14) requires more effort. For  $i \in A$  define

$$(4.18) \quad \tilde{P}(\cdot \mid i, A, t) = P(\cdot \mid X(L_A-) = i, L_A = t).$$

In Section 6 we shall prove

LEMMA 4.19. *Suppose  $(i, A, t)$  is regular,  $j \notin A$ . Then*

- (a)  $\tilde{P}((i, A \cup \{j\}, t) \text{ is not regular}, L_j \geq L_A | i, A, t) \leq 2 \cdot 2^{-d/2}$
- (b)  $\tilde{P}((j, A \cup \{j\}, L_j) \text{ is not regular}, L_j < L_A | i, A, t) \leq 4 \cdot 2^{-d/2}$ .

These remain true for  $j \in A$ , since then  $L_j \geq L_A$  and  $(i, A \cup \{j\}, t) = (i, A, t)$  is regular.

The rest of this section is devoted to proving (4.14) from Lemma 4.19. We need the technical lemma below. For  $A \subset I$  define the post- $L_A$ - $\sigma$ -field  $\mathcal{L}_A = \sigma(L_A; X(L_A-); X_u, u \geq L_A)$ . Plainly

$$(4.20) \quad L_j \in \mathcal{L}_A, \quad X_{L_j} \in \mathcal{L}_A; \quad j \in A$$

$$(4.21) \quad \mathcal{L}_B \subset \mathcal{L}_A, \quad B \subset A.$$

LEMMA 4.22.  $\{A_n^* = A, J_{n+1} = j\} \in \mathcal{L}_A, n \geq 1$ .

PROOF. We shall prove that for any  $n \geq 1, A = \{j_1, \dots, j_n\}, t_1, \dots, t_n,$

$$(4.23) \quad \{A_n^* = A; J_1 = j_1, \dots, J_n = j_n; L_{j_1} \geq t_1, \dots, L_{j_n} \geq t_n\} \in \mathcal{L}_A.$$

This is true for  $n = 1$ , since  $\{A_1^* = \{j_1\}, J_1 = j_1, L_{j_1} \geq t\} = \{t \leq L_{j_1} < 2^{d(1/2-\epsilon)}; X(u) = X(L_{j_1}) \text{ for } L_{j_1} \leq u \leq 2^{d(1/2-\epsilon)}\} \in \mathcal{L}_{j_1}$ . Suppose inductively that (4.23) holds for  $n$ . Then by (4.9),

$$(4.24) \quad \{A_n^* = A; J_1 = j_1, \dots, J_{n+1} = j_{n+1}; L_{j_1} \geq t_1, \dots, L_{j_n} \geq t_n\} \in L_A \subset L_{A \cup \{j_{n+1}\}}.$$

Since  $\{L_{j_{n+1}} \geq t_{n+1}\} \in L_{A \cup \{j_{n+1}\}}$  by (4.20) and (4.21), and since  $A_{n+1}^* = A_n^* \cup \{J_{n+1}\}$ , we see that (4.23) holds for  $n + 1$ . So by induction (4.23) is true for all  $n$ ; so (4.24) is true for all  $n$ , and the lemma follows.

Now let  $\mathcal{F}_A$  be the strict pre- $L_A$   $\sigma$ -field  $\sigma(X_u: u < L_A)$ . By a variant of the strong Markov property,

$$(4.25) \quad \begin{aligned} P(B | \mathcal{L}_A) &= P(B | X(L_A-), L_A); \quad B \in \mathcal{F}_A \\ &= \tilde{P}(B | X(L_A-), A, L_A) \quad \text{in notation of (4.18)}. \end{aligned}$$

We can now prove (4.14). By definition 4.7,  $(L, A \cup \{j\})$  is good if

- either  $L_j \geq L_A$  and  $(i, A \cup \{j\}, t)$  is regular
- or  $L_j < L_A$  and  $(j, A \cup \{j\}, L_j)$  is regular.

Thus by Lemma 4.19,

$$(4.26) \quad \tilde{P}((L, A \cup \{j\}) \text{ is not good} | i, A, t) \leq 6 \cdot 2^{-d/2} \quad \text{if } (i, A, t) \text{ regular.}$$

Now

$$\begin{aligned} \{(L, A \cup \{j\}) \text{ is not good}\} &\in \sigma(L_{A \cup \{j\}}, X(L_{A \cup \{j\}}-)) \quad \text{by definition} \\ &\subset \mathcal{F}_{A \cup \{j\}} \subset \mathcal{F}_A. \end{aligned}$$

So by (4.25) and (4.26)

$$P((L, A \cup \{j\}) \text{ is not good} | \mathcal{L}_A) \leq 6 \cdot 2^{-d/2} \quad \text{on } \{(X(L_A-), A, L_A) \text{ is regular}\}.$$

Applying Lemma 4.22,

$$\begin{aligned} P((L, A_{n+1}^*) \text{ is not good} | \mathcal{L}_A) &= P((L, A \cup \{j\}) \text{ is not good} | \mathcal{L}_A) \quad \text{on } \{A_n^* = A, J_{n+1} = j\} \\ &\leq 6 \cdot 2^{-d/2} \quad \text{on } \{A_n^* = A, (X(L_A-), A, L_A) \text{ is regular}\}. \end{aligned}$$

But this last set is  $\{A_n^* = A, (L, A_n^*) \text{ is good}\}$ , and (4.14) follows.

5. Here is the definition of the function  $s$  appearing in the definition (4.4) of “regular”.

DEFINITION 5.1. For  $A \subset I, i \in A, u \geq 0$  define

$$s(i, A, u) = \max_{j \in I} P_i(X_u = j | H_A^+ > u).$$

PROOF OF LEMMA 4.17. (a)  $L_{J_1} \leq 2^{d/2}$  by definition. Set  $t_0 = 2^{d(1/2-\epsilon)}$ .

$$\begin{aligned} P(L_{J_1} < t_0 - t_1) &= P(L_{J_1} < t_0 - t_1 | X(t_0) = k) \quad \text{by symmetry} \\ &= P_k(X_u = X(L_k) \text{ for some } t_1 \leq u \leq t_0) \quad \text{by time-reversal (2.2).} \end{aligned}$$

By conditioning on  $(L_k, X(L_k))$ , this is at most

$$P_k(L_k > \frac{1}{2}t_1) + P_j(X_u = j \text{ for some } \frac{1}{2}t_1 \leq u \leq t_0).$$

As  $d \rightarrow \infty$ , the first term tends to zero since  $P_k(L_k \geq u) = e^{-u}$ , and the second term tends to zero by Lemma 2.5(d).

(b) Let  $t_1 \leq u \leq 2^{d/2}$ . Then

$$\begin{aligned} P_j(X_u = k | H_j^+ > u) &\leq P_j(X_u = k) / P_j(H_j^+ > u) \\ &\leq 2^{-d}(1 + 2^{-d}) / P_j(H_j^+ > 2^{d/2}) \text{ by (4.2)} \\ &\leq 2 \cdot 2^{-d} \quad \text{for } d \text{ sufficiently large,} \end{aligned}$$

because  $P_j(H_j^+ > 2^{d/s}) \rightarrow 1$  as  $d \rightarrow \infty$  by Lemma 2.5(d). So  $s(j, \{j\}, u) \leq 2 \cdot 2^{-d}$  for sufficiently large  $d$ .

6. It remains to prove Lemma 4.19. The key idea is that the time-reversal (2.4) can be written, in the notation (4.18), as

$$(6.1) \quad \tilde{P}((X_u)_{0 \leq u \leq t} \in \cdot | i, A, t) = P_i((X_{t-u})_{0 \leq u \leq t} \in \cdot | H_A^+ > t).$$

Thus the assertions of Lemma 4.19 can be translated into assertions about the behavior of the random walk started at  $i \in A$  and conditional on  $\{H_A^+ > t\}$ . We start with a sequence of lemmas concerning this conditioned random walk.

LEMMA 6.2.  $P_i((X_{t+u})_{t \geq 0} \in \cdot | H_A^+ > u) \leq 2^d s(i, A, u) \cdot P_\pi((X_t)_{t \geq 0} \in \cdot)$ .

PROOF.

$$\begin{aligned} P_i((X_{t+u}) \in \cdot | H_A^+ > u) &= \sum_k P_i(X_u = k | H_A^+ > u) \cdot P_k((X_t) \in \cdot) \\ &\leq 2^d \max_k P_i(X_u = k | H_A^+ > u) \sum_k 2^{-d} P_k((X_t) \in \cdot) \\ &= 2^d s(i, A, u) P_\pi((X_t) \in \cdot). \end{aligned}$$

LEMMA 6.3. If  $u \leq 2^{d/2}$  and  $s(i, A, u) \leq 2 \cdot 2^{-d}$  then

$$P_i(H_A^+ > 2^{d/2} | H_A^+ > u) \geq 1 - 2^{-\epsilon d}.$$

PROOF.

$$\begin{aligned} P_i(H_A^+ \leq 2^{d/2} | H_A^+ > u) &\leq 2P_\pi(H_A^+ \leq 2^{d/2} - u) \quad \text{by Lemma 6.2} \\ &\leq 2P_\pi(H_A \leq 2^{d/2}) \\ &\leq 2\#AP_\pi(H_j \leq 2^{d/2}) \quad \text{by symmetry} \\ &\leq 2\#A2^{-d/2}(1 + \epsilon_2(d)) \quad \text{by Lemma 2.8(b)} \\ &\leq 2^{-\epsilon d} \quad \text{for } d \text{ sufficiently large, by (4.1).} \end{aligned}$$



The first lemma below is elementary; the second is an immediate consequence of (4.2).

LEMMA 6.4. For events  $G, H, \hat{H}$  with  $H \subset \hat{H}$  and  $P(H) > 0$ ,

$$P(G|H) \leq P(G|\hat{H})/P(H|\hat{H}).$$

LEMMA 6.5.  $P_i(X_{u+t_1} = j | X_r, r \leq u) \leq 2^{-d}(1 + 2^{-d})$ .

LEMMA 6.6. If  $s(i, A, u) \leq 2 \cdot 2^{-d/2}$  then  $s(i, A, u + t_1) \leq 2 \cdot 2^{-d}$ .

PROOF.

$$\begin{aligned} P_\pi(H_A \leq t_1) &\leq \#AP_\pi(H_j \leq t_1) \\ (6.7) \quad &\leq \#A2^{-d}t_1(1 + \varepsilon_2(d)) \quad \text{by Lemma 2.8(b)} \\ &\leq 2^{-d(1/2+\varepsilon)}(1 + \varepsilon_2(d)) \quad \text{by (4.3)}. \end{aligned}$$

$$\begin{aligned} (6.8) \quad P_i(H_A^+ \leq u + t_1 | H_A^+ > u) &\leq 2^d \cdot 2^{-d/2} P_\pi(H_A \leq t_1) \quad \text{by Lemma 6.2} \\ &\rightarrow 0 \quad \text{as } d \rightarrow \infty \quad \text{by (6.7)}. \end{aligned}$$

And by Lemma 6.5,

$$(6.9) \quad P_i(X_{u+t_1} = j | H_A^+ > u) \leq 2^{-d}(1 + 2^{-d}).$$

Finally,

$$\begin{aligned} P_i(X_{u+t_1} = j | H_A^+ > u + t_1) &\leq \frac{P_i(X_{u+t_1} = j | H_A^+ > u)}{P_i(H_A^+ > u + t_1 | H_A^+ > u)} \quad \text{by Lemma 6.4} \\ &\leq 2 \cdot 2^{-d} \quad \text{for } d \text{ sufficiently large, by (6.8) and (6.9)}. \end{aligned}$$

LEMMA 6.10. If  $s(i, A, u) \leq 2 \cdot 2^{-d}$  and  $P_i(H_j^+ > u | H_A^+ > u) \geq 2^{-d/2}$  then  $s(i, A \cup \{j\}, u + t_1) \leq 2 \cdot 2^{-d}$ .

PROOF. By Lemma 6.4,

$$\begin{aligned} P_i(X_u = k | H_{A \cup \{j\}}^+ > u) &\leq \frac{P_i(X_u = k | H_A^+ > u)}{P_i(H_{A \cup \{j\}}^+ > u | H_A^+ > u)} \\ &\leq \frac{s(i, A, u)}{P_i(H_j^+ > u | H_A^+ > u)} \\ &\leq 2 \cdot 2^{-d/2} \quad \text{by hypothesis.} \end{aligned}$$

So  $s(i, A \cup \{j\}, u) \leq 2 \cdot 2^{-d/2}$ . Apply Lemma 6.6.

PROOF OF LEMMA 4.19(a). By hypothesis  $(i, A, t)$  is regular, in particular

$$(6.11) \quad s(i, A, u) \leq 2 \cdot 2^{-d},$$

for  $u$  as at (4.5). Now  $(i, A \cup \{j\}, t)$  satisfies condition (a) of Definition 4.4 because  $(i, A, t)$  satisfies that condition, so to prove regularity it suffices to verify condition (b):  $s(i, A \cup \{j\}, u + t_1) \leq 2 \cdot 2^{-d}$ . Thus it suffices to prove

$$\begin{aligned} \text{either (i)} \quad &s(i, A \cup \{j\}, u + t_1) \leq 2 \cdot 2^{-d} \\ \text{or (ii)} \quad &\tilde{P}(L_j > L_A | i, A, t) \leq 2 \cdot 2^{-d/2}. \end{aligned}$$

First suppose

$$(6.12) \quad P_i(H_j^+ > u | H_A^+ > u) \geq 2^{-d/2}.$$

Then by (6.11) we can apply Lemma 6.10 and deduce that (i) holds. Now suppose (6.12)

fails. Then

$$\begin{aligned}
 \tilde{P}(L_j > L_A | i, A, t) &= P_i(H_j^+ > t | H_A^+ > t) \quad \text{by (6.1)} \\
 &\leq P_i(H_j^+ > u | H_A^+ > t) \quad \text{since } u \leq t \text{ by (4.6)} \\
 &\leq \frac{P_i(H_j^+ > u | H_A^+ > u)}{P_i(H_A^+ > t | H_A^+ > u)} \quad \text{by Lemma 6.4} \\
 &\leq 2^{-d/2} / P_i(H_A^+ > 2^{d/2} | H_A^+ > u) \\
 &\quad \text{since (6.12) fails, and } t \leq 2^{d/2} \text{ because } (i, A, t) \text{ is regular,} \\
 &\leq 2^{-d/2} / (1 - 2^{-\varepsilon d}) \quad \text{by Lemma 6.3.}
 \end{aligned}$$

So (ii) holds for  $d$  sufficiently large.

One more lemma is needed before we can prove part (b) of Lemma 4.19.

LEMMA 6.13. *Suppose  $s(i, A, u) \leq 2 \cdot 2^{-d}$ . Let  $j \notin A$ . Define*

$$\begin{aligned}
 V &= \sup\{t \leq u: X_t = j, X_{t-} \neq j\} \\
 &= 0 \quad \text{if no such } t \text{ exists.}
 \end{aligned}$$

Then  $P_i(V > 0, s(j, A \cup \{j\}, u + t_1 - V) > 2 \cdot 2^{-d} | H_A^+ > u) \leq \frac{1}{2} \cdot 2^{-d/2}$ .

PROOF. Let

$$\begin{aligned}
 \Omega_0 &= \{H_A^+ > u + t_1\} \cap \{X_t \neq j, u \leq t \leq u + t_1\} \\
 \Omega_1 &= \{P_i(\Omega_0^c | V, H_A^+ > u) < \frac{1}{3}\}.
 \end{aligned}$$

Then

$$\begin{aligned}
 P(\Omega_1^c | H_A^+ > u) &\leq 3P(\Omega_0^c | H_A^+ > u) \\
 &\leq 3 \cdot 2 \cdot P_\pi(H_{A \cup \{j\}} \leq t_1) && \text{by Lemma 6.2} \\
 (6.14) \quad &\leq 6 \#(A \cup \{j\}) P_\pi(H_i \leq t_1) && \text{by symmetry} \\
 &\leq 6(1 + \#A) t_1 2^{-d} (1 + \varepsilon_2(d)) && \text{by Lemma 2.8(b)} \\
 &\leq \frac{1}{2} \cdot 2^{-d/2} \quad \text{for } d \text{ sufficiently large, by (4.3).}
 \end{aligned}$$

Next, since  $\Omega_0 \subset \{H_A^+ > u\}$  the continuous analog of Lemma 6.4 gives

$$\begin{aligned}
 P_i(X(u + t_1) = k | V, \Omega_0) &\leq \frac{P_i(X(u + t_1) = k | V, H_A^+ > u)}{P_i(\Omega_0 | V, H_A^+ > u)} \\
 (6.15) \quad &\leq \frac{1}{2} P_i(X(u + t_1) = k | V, H_A^+ > u) \quad \text{on } \Omega_1 \\
 &\leq \frac{1}{2} \cdot 2^{-d} (1 + 2^{-d}) \quad \text{on } \Omega_1, \text{ by Lemma 6.5} \\
 &\leq 2 \cdot 2^{-d} \quad \text{on } \Omega_1, \text{ for } d \text{ sufficiently large.}
 \end{aligned}$$

Now fix  $0 < v \leq u$ . By definition of  $V$ ,  $\Omega_0$  and the Markov property at  $v$ ,

$$(6.16) \quad P_i(X(u + t_1) = k | V = v, \Omega_0) = P_j(X(u + t_1 - v) = k | H_{A \cup \{j\}}^+ > u + t_1 - v).$$

So

$$\begin{aligned}
 s(j, A \cup \{j\}, u + t_1 - v) &= \max_k P_j(X(u + t_1 - v) = k | H_{A \cup \{j\}}^+ > u + t_1 - v) \\
 &= \max P_i(X(u + t_1) = k | V = v, \Omega_0) \quad \text{by (6.16).}
 \end{aligned}$$

So

$$s(j, A \cup \{j\}, u + t_1 - V) = \max P_i(X(u + t_1) = k | V, \Omega_0) \text{ on } \{V > 0\}$$

$$\leq 2 \cdot 2^{-d} \text{ on } \Omega_1 \cap \{V > 0\} \text{ by (6.15),}$$

and now the lemma follows from (6.14).

PROOF OF LEMMA 4.19(b). By hypothesis  $(i, A, t)$  is regular. Let  $u$  be as at (4.5). In order that  $(j, A \cup \{j\}, L_j)$  satisfy condition (a) of (4.4) we need  $L_j \geq t - u$ . In order to satisfy (b) we need  $s(j, A \cup \{j\}, \hat{u}) \leq 2 \cdot 2^{-d}$ , for  $\hat{u} = u + t_1 + L_j - t$ . So it suffices to prove

$$(6.17) \quad \tilde{P}(L_j < t - u | i, A, t) \leq 3 \cdot 2^{-d/2}$$

$$(6.18) \quad \tilde{P}(S(j, A \cup \{j\}, u + t_1 + L_j - t) > 2 \cdot 2^{-d}, t - u \leq L_j < t | i, A, t) \leq 2^{-d/2}.$$

Say “ $X$  enters  $j$  during  $[u, t]$ ” if there exists  $r \in [u, t]$  such that  $X_r = j, X_{r-} \neq j$ . To estimate (6.17),

$$\begin{aligned} \tilde{P}(L_j < t - u | i, A, t) &= P_i(X \text{ enters } j \text{ during } [u, t] | H_A^+ > t) \text{ by time-reversal (6.1)} \\ &\leq \frac{P_i(X \text{ enters } j \text{ during } [u, t] | H_A^+ > u)}{P_i(H_A^+ > t | H_A^+ > u)} \text{ by Lemma 6.4} \\ &\leq \frac{2P_\pi(H_j^+ \leq t - u)}{1 - 2^{-ed}} \text{ by Lemmas 6.2 and 6.3, since } t \leq 2^{d/2}, \\ &\leq 2 \cdot 2^{-d/2}(1 + \varepsilon_2(d))/(1 - 2^{-ed}) \text{ by Lemma 2.8(b),} \end{aligned}$$

and so (6.17) holds for sufficiently large  $d$ .

To prove (6.18), time-reversal (6.1) shows that the probability in (6.18) equals

$$P_i(s(j, A \cup \{j\}, u + t_1 - V) > 2 \cdot 2^{-d}, V > 0, X \text{ does not enter } j \text{ during } [u, t] | H_A^+ > t).$$

Since  $u \leq t \leq 2^{d/2}$ , Lemmas 6.13 and 6.4 show this quantity is at most

$$\frac{1}{2} \cdot 2^{-d/2} / P_i(H_A^+ > t | H_A^+ > u).$$

Now

$$\begin{aligned} P_i(H_A^+ > t | H_A^+ > u) &\geq P_i(H_A^+ > 2^{d/2} | H_A^+ \geq u) \\ &\geq 1 - 2^{-ed} \text{ by Lemma 6.3} \end{aligned}$$

and this establishes (6.18).

### REFERENCE

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