

CONVEXITY PROPERTIES OF GENERALIZED MEAN VALUE FUNCTIONS¹

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Consider the following generalized mean value functions: (1) the unit weight or simple sample form, $\phi(t) = \left(\frac{x_1^t + x_2^t + \cdots + x_n^t}{n}\right)^{\frac{1}{t}}$, in which the x_i are positive real numbers not all equal each to each, and in which t may take any real value; (2) the weighted sample form, $\omega(t) = \left(\frac{c_1x_1^t + c_2x_2^t + \cdots + c_nx_n^t}{c_1 + c_2 + \cdots + c_n}\right)^{\frac{1}{t}}$, in which the c_i are positive numbers not all equal each to each, and in which the x_i and t are restricted as in $\phi(t)$; (3) the integral form, $\theta(t) = \left[\int_{x=0}^1 x^t dx\right]^{\frac{1}{t}}$, where $\int_{x=0}^1 x^t dx$ exists for every real value of t ; and (4) the generalized integral form $\Phi(t) = \left[\int_{x=0}^{\infty} x^t d\psi(x)\right]^{\frac{1}{t}}$, where $\psi(x)$ is a non-decreasing function integrable in the Riemann-Stieltjes sense such that $\psi(\infty) - \psi(0) = 1$, and such that $\int_{x=0}^{\infty} x^t d\psi(x)$ exists for every real value of t . The facts that all of these functions are monotonic increasing and that both $\phi(t)$ and $\omega(t)$ have two horizontal asymptotes have been previously demonstrated.² Although the existence of $\phi(t)$ and $\omega(t)$ has been known since 1840, there appears to have been no attempt made to investigate the behavior of the second derivatives of them.³

When the x_i are price relatives, production relatives, or similar data, $\phi(t)$ and $\omega(t)$ yield common types of index numbers by direct substitution of integral values of t . For any values of t such that $0 < t_1 < t_2 < \infty$, the type bias of $\phi(t_2)$ will be greater than the type bias of $\phi(t_1)$. Similarly, for any values of t such that $-\infty < t_1 < t_2 < 0$, the type bias of $\phi(t_1)$ will be greater than the type bias of $\phi(t_2)$. The second derivatives of $\phi(t)$ and $\omega(t)$ indicate whether

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² G. H. Hardy, J. E. Littlewood, and G. Pólya, *Inequalities* (Cambridge University Press, London, 1934), pp. 12-15; and Nilan Norris, "Inequalities among Averages," *Annals of Mathematical Statistics*, Vol. VI, No. 1, March, 1935, pp. 27-29.

³ Jules Biènaymé, *Société Philomatique de Paris*, Extraits des procès-verbaux des séances pendant l'année 1840 (Imprimerie D'A. René et Cie., Paris, 1841), Séance du 13 juin 1840 p. 68.

type bias is changing at an increasing or a decreasing rate as between the unlimited number of averages available for use. Considerable interest attaches to $\omega(t)$, the weighted sample form of function.

Let $\omega(t)$ be made arbitrary for the case of $n = 2$, with $x_1 = 1$, and $x_2 = e^{-\lambda}$, where λ is any real number. Also let $c_1 = \alpha$, and $c_2 = \beta$, where $\alpha + \beta = 1$. Then $\omega(t) = [\alpha + \beta e^{-\lambda t}]^{\frac{1}{t}}$. Now for all values of t ,

$$\alpha + \beta e^{-\lambda t} = 1 - \frac{\beta\lambda}{1} t + \frac{\beta\lambda^2}{2} t^2 - \frac{\beta\lambda^3}{6} t^3 + \dots$$

For $|t|$ sufficiently small, it follows that

$$\log(\alpha + \beta e^{-\lambda t}) = -\beta\lambda t + \frac{1}{2}\beta\lambda^2(1 - \beta)t^2 + \beta\lambda^3\left[-\frac{1}{6} + \frac{\beta}{2} - \frac{\beta^2}{3}\right]t^3 + \dots,$$

so that for $t \neq 0$

$$\frac{1}{t} \log(\alpha + \beta e^{-\lambda t}) = -\beta\lambda + \frac{1}{2}\beta\lambda^2(1 - \beta)t + \beta\lambda^3\left[-\frac{1}{6} + \frac{\beta}{2} - \frac{\beta^2}{3}\right]t^2 + \dots$$

Therefore $\omega(t) = \exp.\left[\frac{1}{t} \log(\alpha + \beta e^{-\lambda t})\right]$

$$= e^{-\beta\lambda} \left[1 + \frac{1}{2}\beta\lambda^2(1 - \beta)t + \beta\lambda^3\left\{-\frac{1}{6} + \frac{\beta}{2} - \frac{\beta^2}{3} + \frac{1}{8}\beta(1 - \beta)^2\lambda\right\}t^2 + \dots\right].$$

It follows that $\omega''(0) = 2\beta\lambda^3 e^{-\beta\lambda} \left[-\frac{1}{6} + \frac{\beta}{2} - \frac{\beta^2}{3} + \frac{1}{8}\beta(1 - \beta)^2\lambda\right]$. It is clear that $\omega(0)$ is the weighted geometric mean, and that $\phi(0)$ is the unit weight or simple sample form of geometric mean. As a means of demonstrating the range of values which $\omega''(0)$ may take it is helpful to rewrite the expression for $\omega''(0)$ as follows:

$$\omega''(0) = \frac{1}{4}\beta^2(1 - \beta)^2\lambda^3 \left[\lambda - \frac{4}{3} \frac{1 - 2\beta}{\beta(1 - \beta)}\right] e^{-\beta\lambda} \equiv f(\lambda, \beta).$$

This consideration makes it possible to distinguish three cases of $y = f(\lambda, \beta)$ for fixed β , namely, $0 < \beta < \frac{1}{2}$; $\beta = \frac{1}{2}$; and $\frac{1}{2} < \beta < 1$. In all three cases $f(\lambda, \beta)$ has an absolute minimum $\mu(\beta) \leq 0$, and $\mu(\frac{1}{2}) = 0$. The corresponding values of λ satisfies the quadratic equation $\lambda^2 - \frac{4}{3} \frac{4 - 5\beta}{\beta(1 - \beta)} \lambda + \frac{4 - 8\beta}{\beta^2(1 - \beta)} = 0$.

It is clear that by taking β near enough to 0, one can make $\mu(\beta)$ as large negative as is desired. Also, by choosing λ properly, one can make $\omega''(0)$ take any value between $\mu(\beta)$ and ∞ . For example, when $\alpha = \beta = \frac{1}{2}$, λ may be selected so as to make $\omega''(0)$ any arbitrarily chosen non-negative number. For then $\omega''(0) = \frac{\lambda^4}{64} e^{-\frac{\lambda}{2}}$, and as λ increases from $-\infty$ to 0, $\omega''(0)$ decreases from ∞ to 0. If $\lambda = 0$, $\omega''(0) = 0$. If $\lambda > 0$, as λ increases from 0 to 8, $\omega''(0)$ increases to

$64e^{-4}$, and as λ increases beyond 8, $\omega''(0)$ decreases, approaching 0 as λ increases indefinitely. It is evident that the case of $\alpha = \beta = \frac{1}{2}$, with $\lambda = -\log 2$, $x_1 = 1$, and $x_2 = e^{-\lambda}$, is one in which $\omega(t)$ becomes the unit weight or simple sample type of generalized mean value function, namely, $\phi(t) = \left(\frac{1^t + 2^t}{2}\right)^{\frac{1}{t}}$. Reference to the first expression above noted for $\omega''(0)$ will make clear that $\phi''(0) = \frac{(\log 2)^4}{64} \sqrt{2}$ in this special case.

Analysis of $\Phi(t)$, the generalized integral form of generalized mean value function, makes it possible to characterize populations of a very general character, as well as samples. But in the case of $\Phi(t)$ it is even more difficult to generalize as to convexity properties. For example, let

$$\Phi(t) = \left[\int_{u=-\infty}^{\infty} e^{-ut} dE(u) \right]^{\frac{1}{t}},$$

where

$$E(u) = \frac{1}{\sqrt{\pi}} \int_{v=-\infty}^u e^{-v^2} dv.$$

This expression is obviously of the required generalized integral type. Now

$$[\Phi(t)]^t = \frac{1}{\sqrt{\pi}} \int_{u=-\infty}^{\infty} e^{-ut-u^2} du = \frac{1}{\sqrt{\pi}} e^{\frac{t^2}{4}} \int_{u=-\infty}^{\infty} e^{-\left(u+\frac{t}{2}\right)^2} du = e^{\frac{t^2}{4}}.$$

Therefore $\Phi(t) = e^{\frac{t}{4}}$, and $\Phi''(t) = \frac{e^{\frac{t}{4}}}{16} > 0$ for all t . That is, in this particular case, $\Phi(t)$ has only one horizontal asymptote.

The foregoing examples indicate that the following conclusions may be drawn as to the diverse convexity attributes of the various means as functions of t : (1) The unit weight form, $\phi(t)$, and the weighted sample form, $\omega(t)$, must always have a point of inflection, since both of them not only increase with t , but are doubly asymptotic (have two horizontal asymptotes). (2) Points of inflection for $\phi(t)$ and $\omega(t)$ do not necessarily occur at $t = 0$. (3) The generalized integral form, $\Phi(t)$, need not always have a point of inflection. That is, the second derivatives of certain forms of $\Phi(t)$ do not change their sign, since such forms are concave upward.