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# An invariance principle for one-dimensional random walks in degenerate dynamical random environments* 

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#### Abstract

We study random walks on the integers driven by a sample of time-dependent nearestneighbor conductances that are bounded but are permitted to vanish over time intervals of positive Lebesgue-length. Assuming only ergodicity of the conductance law under space-time shifts and a moment assumption on the time to accumulate a unit conductance over a given edge, we prove that the walk scales, under a diffusive scaling of space and time, to a non-degenerate Brownian motion for a.e. realization of the environment. The conclusion particularly applies to random walks on one-dimensional dynamical percolation subject to fairly general stationary edge-flip dynamics.


Keywords: random walks among dynamical random conductances; quenched invariance principle; dynamical percolation; stochastic homogenization.
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## 1 Definitions and main results

This note is concerned with large-scale behavior of a particular class of one-dimensional nearest-neighbor random walks in dynamical random environments. Each of our random walks is technically a continuous-time Markov chain on $\mathbb{Z}$ with time-varying generator $L_{t}$ at time $t$ that acts on $f: \mathbb{Z} \rightarrow \mathbb{R}$ as

$$
\begin{equation*}
L_{t} f(x):=\sum_{z= \pm 1} a_{t}(x, x+z)[f(x+z)-f(x)] \tag{1.1}
\end{equation*}
$$

where $a_{t}(x, x+z)$ is a non-negative number interpreted as the instantaneous jump rate from $x$ to $x+z$ at time $t$. The key restriction we impose is that this jump rate is symmetric,

$$
\begin{equation*}
a_{t}(x, x+z)=a_{t}(x+z, x), \quad x \in \mathbb{Z}, z= \pm 1, \tag{1.2}
\end{equation*}
$$

[^0]and so $a_{t}(e)$ is just a function of the undirected edge $e$. No jump across edge $e$ can occur at time $t$ when $a_{t}(e)$ vanishes.

In order to construct the Markov chain precisely we need to make some regularity assumptions on the environment. Writing $E(\mathbb{Z})$ for the set of undirected edges of $\mathbb{Z}$, let $\Omega:=[0, \infty)^{\mathbb{R} \times E(\mathbb{Z})}$ denote the set of all environments and $\mathcal{F}:=\bigotimes_{\mathbb{R} \times E(\mathbb{Z})} \mathcal{B}([0, \infty))$ for the product $\sigma$-algebra on $\Omega$. For each $t \in \mathbb{R}$ and $x \in \mathbb{Z}$, let $\tau_{t, x}: \Omega \rightarrow \Omega$ be the canonical space-time shift acting on $a \in \Omega$ as

$$
\begin{equation*}
\left(\tau_{t, x} a\right)_{s}(y, y+z)=a_{t+s}(y+x, y+x+z), \quad s \in \mathbb{R}, x \in \mathbb{Z}, z= \pm 1 \tag{1.3}
\end{equation*}
$$

We will assume throughout that a probability measure $\mathbb{P}$ on $(\Omega, \mathcal{F})$ is given, with expectation denoted as $\mathbb{E}$, such that the following holds:
Assumption 1.1. For each edge $e \in E(\mathbb{Z})$, the map $t \rightarrow a_{t}(e)$ is Borel measurable and locally Lebesgue integrable. The law $\mathbb{P}$ is invariant and ergodic with respect to the family of space-time shifts $\left\{\tau_{t, x}: t \in \mathbb{R}, x \in \mathbb{Z}\right\}$.

Under Assumption 1.1, a $\mathbb{Z}$-valued Markov chain with generator (1.1) can be constructed for all environments in a measurable set $\Omega_{0}$ of full $\mathbb{P}$-measure. (See [6] for an outline of that construction with non-explosivity being its main concern.) Let $X=\left\{X_{t}: t \geq 0\right\}$ denote the càdlàg trajectory of the chain and write $P_{a}^{x}$ to denote the law of $X$ in environment $a \in \Omega_{0}$ subject to the initial condition $P_{a}^{x}\left(X_{0}=x\right)=1$. The aim of the present note is to give sufficient conditions under which the walk behaves "usually" at large space-time scales. We formalize this as:
Definition 1.2. We say that a Quenched Invariance Principle holds if there exists a constant $\sigma^{2} \in(0, \infty)$ such that for any $t_{0}>0$ and $\mathbb{P}$-a.e. environment $a$, the law of

$$
\begin{equation*}
t \mapsto \frac{1}{\sqrt{n}} X_{n t}, \quad 0 \leq t \leq t_{0} \tag{1.4}
\end{equation*}
$$

induced by $P_{a}^{0}$ on the Skorohod space $D\left[0, t_{0}\right]$ of càdlàg paths converges, as $n \rightarrow \infty$, to the law of Brownian motion $\left\{B_{t}: t \in\left[0, t_{0}\right]\right\}$ with $E B_{t}=0$ and $E B_{t}^{2}=\sigma^{2} t$.

We note that, for one-dimensional walks subject to Assumption 1.1, a Quenched Invariance Principle was proved earlier by Deuschel and Slowik [9] assuming the finiteness of the $p$-th positive and the $q$-th negative moments of $a_{t}(e)$ subject to $p, q \geq 1$ and $\frac{1}{p-1}\left(1+\frac{1}{q}\right)<1$. The latter inequality stems from the method of proof, which is based on elliptic regularity techniques. In [6], the first author discovered a different proof that works solely under the first-moment conditions

$$
\begin{equation*}
\mathbb{E}\left[a_{t}(e)\right]<\infty \quad \text { and } \quad \mathbb{E}\left[a_{t}(e)^{-1}\right]<\infty \tag{1.5}
\end{equation*}
$$

These were also shown to be necessary for the result to hold in general.
Unfortunately, under Assumption 1.1, the negative moment condition in (1.5) makes it impossible for $t \mapsto a_{t}(e)$ to vanish on a set of positive Lebesgue measure. This excludes natural examples of prime interest. We mend this partially in:
Theorem 1.3. In addition to Assumption 1.1, suppose that
(1) $a_{t}(e) \in[0,1]$ for all $t \in \mathbb{R}$ and $e \in \mathbb{E}(\mathbb{Z})$,
(2) the quantity

$$
\begin{equation*}
T:=\inf \left\{t \geq 0: \int_{0}^{t} a_{s}(0,1) \mathrm{d} s \geq 1\right\} \tag{1.6}
\end{equation*}
$$

obeys

$$
\begin{equation*}
\exists \varepsilon>0: \quad \mathbb{E}\left(T^{3+\varepsilon}\right)<\infty \tag{1.7}
\end{equation*}
$$

Then a Quenched Invariance Principle holds.

An important family of examples covered by Theorem 1.3, but not the conclusions of $[9,6]$, are random walks on dynamical percolation. Here $a_{t}(e)$ takes values in $\{0,1\}$, with value 1 representing the edge being "ON" and 0 for the edge being "OFF." The processes $\left\{t \mapsto a_{t}(e)\right\}_{e \in \mathbb{E}(\mathbb{Z})}$ are i.i.d. copies of a given stationary process on $\{0,1\}$ which we assume to have càdlàg (and thus piecewise-constant) sample paths and take both values a.s. To make a connection to percolation we note that, at each given time $t \in \mathbb{R}$, the configuration of the " ON " edges is Bernoulli with probability $p:=\mathbb{E} a_{0}(0,1)$.

While the nature of the individual edge dynamics can be quite arbitrary, the assumptions permit a representation via a sequence of pairs of strictly positive random variables

$$
\begin{equation*}
\left\{\left(T_{i}^{\mathrm{ofF}}, T_{i}^{\mathrm{oN}}\right)\right\}_{i \in \mathbb{Z}} \tag{1.8}
\end{equation*}
$$

to be called "OFF" and "ON"-times, that stand for the lengths of successive time intervals on which $t \mapsto a_{t}(e)$ equals 0 and 1, respectively. Explicitly, writing $\left\{\tau_{i}\right\}_{i \in \mathbb{Z}}$ for the successive times when $t \mapsto a_{t}(e)$ switches from 1 to 0 and $\left\{\tau_{i}^{\prime}\right\}_{i \in \mathbb{Z}}$ for the times it switches from 0 to 1 , indexed so that $\tau_{i}<\tau_{i}^{\prime}<\tau_{i+1}$ for each $i \in \mathbb{Z}$ and $\tau_{0} \leq 0<\tau_{1}$, these are defined as $T_{i}^{\text {OFF }}:=\tau_{i}^{\prime}-\tau_{i}$ and $T_{i}^{\text {ON }}:=\tau_{i+1}-\tau_{i}^{\prime}$.

The sequence (1.8) in turn determines the trajectory $t \mapsto a_{t}(e)$ except for the placement of the "initial" jump time $\tau_{0}$. For this we note that, as $t \mapsto a_{t}(e)$ is stationary, the random variable $U:=-\tau_{0} /\left(\tau_{1}-\tau_{0}\right)$ is uniform on $[0,1]$ and independent of the family (1.8). (See the proof of Lemma 4.2 for a justification.) Starting from (1.8) and an independent uniform $U$, we thus set $\tau_{0}:=-\left(T_{0}^{\text {ofF }}+T_{0}^{\text {oN }}\right) U$ and define the other $\tau_{i}$ and $\tau_{i}^{\prime}$ by adding/subtracting appropriate terms from (1.8).

A minor complication of the representation via (1.8) is that the law of the interarrival times $\left\{\left(T_{i}^{\text {off }}, T_{i}^{\text {oN }}\right)\right\}_{i \in \mathbb{Z}}$ is not stationary under the law $\mathbb{P}$, but rather under the de-sizebiased measure $\widetilde{\mathbb{P}}$ defined for $A \in \sigma\left(\left\{a_{t}(e): t \in \mathbb{R}\right\}\right)$ by

$$
\begin{equation*}
\widetilde{\mathbb{P}}(A):=\frac{\mathbb{E}\left(\left(T_{0}^{\mathrm{ofF}}+T_{0}^{\mathrm{oN}}\right)^{-1} 1_{A}\right)}{\mathbb{E}\left(\left(T_{0}^{\mathrm{OFF}}+T_{0}^{\mathrm{oN}}\right)^{-1}\right)} \tag{1.9}
\end{equation*}
$$

where, as before, $\mathbb{E}$ is expectation with respect to $\mathbb{P}$. This in particular requires that the expectation in the denominator is finite. See, again, the proof of Lemma 4.2.

The main advantage of the representation based on (1.8) and (1.9) is that it makes it easier to describe specific examples. For instance, $\left\{\left(T_{i}^{\text {off }}, T_{i}^{\text {oN }}\right)\right\}_{i \in \mathbb{Z}}$ could be i.i.d. under $\widetilde{\mathbb{P}}$ which makes $t \mapsto a_{t}(e)$ a stationary renewal process modulo 2 under $\mathbb{P}$. This is exactly the setting that many earlier studies (e.g., by Peres, Stauffer and Steif [16], Peres, Sousi and Steif [17, 18] or Hermon and Sousi [12]) have focused on. Another possibility is to draw $\left\{\left(T_{i}^{\text {off }}, T_{i}^{\text {ON }}\right)\right\}_{i \in \mathbb{Z}}$ from a stationary Markovian law on $(0, \infty) \times(0, \infty)$ although even this is still unnecessarily restrictive for our purposes. Our result on dynamical percolation is cast as follows:
Theorem 1.4. Consider the random walk on dynamical percolation as specified above: The conductance processes $\left\{t \mapsto a_{t}(e)\right\}_{e \in E(\mathbb{Z})}$ are i.i.d. taking values in $\{0,1\}$ with the associate sequence $\left\{\left(T_{i}^{\text {off }}, T_{i}^{\text {oN }}\right)\right\}_{i \in \mathbb{Z}}$ of interarrival times stationary under $\widetilde{\mathbb{P}}$. Assume, in addition to $T_{1}^{\text {off }}, T_{1}^{\text {oN }}$ being positive and finite, that

$$
\begin{equation*}
\exists p>4 \exists s>4 \frac{1-1 / p}{1-4 / p}: \quad \widetilde{\mathbb{E}}\left(\left(T_{1}^{\mathrm{OFF}}+T_{1}^{\mathrm{oN}}\right)^{p}\right)<\infty \quad \text { and } \quad \widetilde{\mathbb{E}}\left(\left(T_{1}^{\mathrm{ON}}\right)^{-s}\right)<\infty \tag{1.10}
\end{equation*}
$$

where $\widetilde{\mathbb{E}}$ is expectation with respect to $\widetilde{\mathbb{P}}$. Then a Quenched Invariance Principle holds.
The restriction to (at least) four moments of the "OFF" and "ON" times comes from the restriction in Theorem 1.3. That being said, some moment condition is definitely needed to ensure convergence to a non-degenerate Brownian motion. Indeed, as we
show in Lemma 4.4, when $T_{i}^{\text {ON }}:=1$ for all $i \in \mathbb{Z}$ and $\left\{T_{i}^{\text {off }}\right\}_{i \in \mathbb{Z}}$ are i.i.d. under $\widetilde{\mathbb{P}}$ with $\widetilde{\mathbb{E}}\left(\left(T_{1}^{\text {off }}\right)^{1 / 2}\right)=\infty$, the random walk behaves subdiffusively. (Note that this translates to divergence of the $3 / 2$-th moment of $T$ from (1.6) under $\mathbb{P}$.) We do not know what moments of the "ON/OFF"-times are critical for existence of such singular examples and/or the validity of a Quenched Invariance Principle. In any case, we do not believe that our conditions (1.7) and (1.10) are optimal; cf Remark 3.8.

The specific example of random walk on dynamical percolation irregardless, the main thrust of our result is that it requires no assumptions (beyond stationarity and ergodicity under space-time shifts) on how the conductances evolve. This takes our approach significantly beyond earlier works (e.g., by Bérard [3], Rassoul-Agha and Seppälainen [19], Bandyopadhyay and Zeitouni [2], Boldrighini, Minlos and Pellegrinotti [8], Dolgopyat, Keller and Liverani [10], Redig and Völlering [20]) that require more explicit assumptions. A limitation of our approach compared to these studies is its restriction to time-continuous variable-speed random walks with uniformly bounded jump rates. (The standard time-change argument that allows us to represent the constant-speed walk by its variable-speed counterpart applies only for static environments.)

## 2 Main steps and technical claims

We proceed to discuss the main steps of the proof articulating the key technical statements to be established. The actual proofs come in Section 3.

### 2.1 Overall picture

There are two strategies we could follow in the proof of Theorem 1.3. One would be based on elliptic regularity techniques developed earlier by Andres, Chiarini, Deuschel and Slowik [1] in $d \geq 2$ and by Deuschel and Slowik [9] in $d=1$ for models satisfying, on top of Assumption 1.1, suitable positive and negative moment conditions on the conductances. Besides a rather disqualifying restriction to (a.s.) strictly positive conductances, a disadvantage of this approach is its significant complexity caused by its reliance on advanced techniques such as functional inequalities and Moser iteration.

The complexity notwithstanding, an important feature of the proofs in [1] and [9] is that the negative-moment condition is used only lightly - mainly, to convert unadorned norms of important quantities to norms weighted by the conductances. In dimensions $d \geq 2$, this was observed and fruitfully utilized by the first author and P.-F. Rodriguez [7] to prove a Quenched Invariance Principle for models with bounded conductances assuming that the quantity in (1.6) obeys

$$
\begin{equation*}
\exists \varepsilon>0: \quad \mathbb{E}\left(T^{4 d+\varepsilon}\right)<\infty . \tag{2.1}
\end{equation*}
$$

While a similar (albeit still very technical) proof is expected to work for random walks with degenerate conductances in $d=1$, details of this have not been completed due to a different behavior of the Sobolev inequality in spatial dimension one.

Another strategy we could follow would rely on the aforementioned work of the first author [6]. An inspection of the proofs of [6] reveals that also here the negative moment condition is used only sporadically; namely, only in [6, Lemma 4.2], dealing with the construction of an auxiliary random walk that the whole proof is based on, and in [6, Theorem 5.5] that constructs and proves the relevant properties of so called parabolic coordinates. We will follow this route and show that a slightly weaker form of Lemma 4.2 remains true, still sufficient to serve our purposes, and so does Theorem 5.5 provided we replace the negative-moment condition by assumptions (1-2) of Theorem 1.3. Our proof thus turns out to be a blend of the two approaches, relying mainly on [6] but drawing on some key observations from [7].

### 2.2 Main steps

In order to bring the reader into the picture, let us recount the main steps of the proof in [6]. The overall structure adheres to that of the proofs of invariance principles by the corrector method; see Biskup [5] or Kumagai [13] for recent reviews. The proof thus starts with the construction of a parabolic coordinate which is a random map $\psi: \mathbb{R} \times \mathbb{Z} \rightarrow \mathbb{R}$ of which we require the following:
(1) $t \mapsto \psi(t, x)$ is continuous for each $x \in \mathbb{Z}$ and $t, x \mapsto \psi(t, x)$ is a weak solution to

$$
\begin{equation*}
\frac{\partial}{\partial t} \psi(t, x)+L_{t} \psi(t, x)=0, \quad t \in \mathbb{R}, x \in \mathbb{Z} \tag{2.2}
\end{equation*}
$$

with the "initial" data

$$
\begin{equation*}
\psi(0,0)=0 \tag{2.3}
\end{equation*}
$$

Here $L_{t}$ acts only on the second coordinate.
(2) For each $t, s \in \mathbb{R}$ and each $x, y \in \mathbb{Z}$, the cocycle condition holds

$$
\begin{equation*}
\psi(t+s, x+y)-\psi(t, x)=\psi(s, y) \circ \tau_{t, x} \tag{2.4}
\end{equation*}
$$

(3) $\psi(\cdot, x)$ is, for each $x \in \mathbb{Z}$, a jointly measurable function of time (i.e., the first variable) and the random environment and we have

$$
\begin{equation*}
\psi(t, x) \in L^{1}(\mathbb{P}) \quad \text { and } \quad \mathbb{E} \psi(t, x)=x, \quad t \in \mathbb{R}, x \in \mathbb{Z} \tag{2.5}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathbb{E}\left(a_{0}(0,1) \psi(0,1)^{2}\right)<\infty \tag{2.6}
\end{equation*}
$$

(4) The spatial gradients of $\psi(t, \cdot)$ are a.s. positive,

$$
\begin{equation*}
\psi(t, x+1)-\psi(t, x)>0, \quad t \in \mathbb{R}, x \in \mathbb{Z} . \tag{2.7}
\end{equation*}
$$

Thinking of the map $x \mapsto \psi(t, x)$ as a different embedding of $\mathbb{Z}$ into $\mathbb{R}$, the above properties ensure that, in the new embedding, the random walk $t \mapsto \psi\left(t, X_{t}\right)$ is an $L^{2}$-martingale (under $P_{a}^{0}$ ). See [6, Fig. 2] for an illustration.

Relying on the point of view of the particle enabled by Assumption 1.1 and the Markov property of $X$, we now check the conditions of the Functional Central Limit Theorem (see, e.g., Helland [11, Theorem 5.1(a)]) for the process $t \mapsto \psi\left(t, X_{t}\right)$, which thus tends in law, under a diffusive scaling of space and time, to Brownian motion with variance

$$
\begin{equation*}
\sigma^{2}:=2 \mathbb{E}\left(a_{0}(0,1) \psi(0,1)^{2}\right) \tag{2.8}
\end{equation*}
$$

The proof of [6, Theorem 1.2] contains all relevant (and explicit) details that apply to the present setting more or less verbatim.

While $\sigma^{2}<\infty$ by (2.6) and $\sigma^{2}>0$ is checked via (2.7), the next, and usually the hardest, technical problem is to show that the "deformation" $\psi\left(t, X_{t}\right)-X_{t}$ of the randomwalk path caused by the change of embedding of $\mathbb{Z}$ is asymptotically irrelevant under the diffusive scaling of the process. As usual, it suffices to show this for the embedding itself which amounts to proving that the parabolic corrector,

$$
\begin{equation*}
\chi(t, x):=\psi(t, x)-x \tag{2.9}
\end{equation*}
$$

obeys

$$
\begin{equation*}
\max _{\substack{x \in \mathbb{Z} \\|x| \leq \sqrt{n}}} \sup _{\substack{t \in \mathbb{R} \\ 0 \leq t \leq n}} \frac{|\chi(t, x)|}{\sqrt{n}} \underset{n \rightarrow \infty}{\longrightarrow} 0, \quad \text { P-a.s. } \tag{2.10}
\end{equation*}
$$

Indeed, the aforementioned Functional CLT gives $\max _{0 \leq t \leq n}\left|\psi\left(t, X_{t}\right)\right|=O(\sqrt{n}) \mathbb{P}$-a.s. and (2.10) then shows $\max _{0 \leq t \leq n}\left|\chi\left(t, X_{t}\right)\right|=o(\sqrt{n}) \mathbb{P}$-a.s. as desired. (Here and henceforth, $O(r)$ denotes a quantity bounded by a constant times $r$ while $o(r)$ is a quantity that upon division by $r$ vanishes as $r \rightarrow \infty$.)

The proof of Theorem 1.3 is thus reduced to two technical steps: a construction of the parabolic coordinate $\psi$ satisfying (1-4) above and a proof of the sublinear/subdiffusive bound (2.10). In the approach of references [1, 9, 7], this is exactly where elliptic regularity techniques are employed to their full extent. The approach of [6] instead relies on the observation that, thanks to the one-dimensional nature of the problem, the spatial gradient of the parabolic coordinate

$$
\begin{equation*}
g(t, x):=\psi(t, x+1)-\psi(t, x) \tag{2.11}
\end{equation*}
$$

obeys the PDE

$$
\begin{equation*}
-\frac{\partial}{\partial t} g(t, x)=\mathcal{L}_{t}^{+} g(t, x) \tag{2.12}
\end{equation*}
$$

where the operator on the right-hand side acts on the spatial variable as

$$
\begin{equation*}
\mathcal{L}_{t}^{+} f(x):=b_{t}(x+1) f(x+1)+b_{t}(x-1) f(x-1)-2 b_{t}(x) f(x) \tag{2.13}
\end{equation*}
$$

with

$$
\begin{equation*}
b_{t}(x):=a_{t}(x, x+1) \tag{2.14}
\end{equation*}
$$

henceforth abbreviating the conductance of edge $(x, x+1)$.
As our use of adjoint notation suggests, $\mathcal{L}_{t}^{+}$is the adjoint in $\ell^{2}(\mathbb{Z})$ of an operator $\mathcal{L}_{t}$ that acts on $f: \mathbb{Z} \rightarrow \mathbb{R}$ as

$$
\begin{equation*}
\mathcal{L}_{t} f(x):=b_{t}(x)[f(x+1)+f(x-1)-2 f(x)] . \tag{2.15}
\end{equation*}
$$

A key point is that $\mathcal{L}_{t}$ is the generator of a continuous time simple symmetric random walk $Y$ time-changed so that the jump rate at $x$ at time $t$ is $2 b_{t}(x)$, which is a much simpler process than $X$ to analyze. As it turns out, the process $Y$ supplies all the needed tools for the proof of a Quenched Invariance Principle for the walk $X$.

### 2.3 Statements to be proved

We will now describe what needs to be done in order to extend the proofs of [6] to that of Theorem 1.3. The first item of business is a formal construction of the random walk $Y$. Note that this walk moves on the set of edges of $\mathbb{Z}$ so we will refer to it as a dual random walk. The negative sign on the left of (2.12) necessitates that $Y$ be run in negative time direction. The following generalizes [6, Lemma 4.2] to the situation when $t \mapsto b_{t}(x)$ is allowed to vanish over sets of positive Lebesgue measure:
Lemma 2.1. Suppose that $t \rightarrow b_{-t}(x)$ is Borel-measurable and locally integrable on $(0, \infty)$ and, in addition, for all $x \in \mathbb{Z}$,

$$
\begin{equation*}
\int_{0}^{\infty} b_{-t}(x) \mathrm{d} t=\infty \tag{2.16}
\end{equation*}
$$

Given $x \in \mathbb{Z}$, let $P^{x}$ be the measure under which $Z$ is a discrete-time simple symmetric random walk on $\mathbb{Z}$ started from $x$ and $N$ is an independent rate-1 Poisson point process. Then, for all $x \in \mathbb{Z}$, there is a non-decreasing continuous function $A:[0, \infty) \rightarrow[0, \infty)$ satisfying

$$
\begin{equation*}
A(t)=\int_{0}^{t} 2 b_{-s}\left(Z_{N(A(s))}\right) \mathrm{d} s, \quad t \geq 0 \tag{2.17}
\end{equation*}
$$

such that $P^{x}(A(t)<\infty)=1$ for each $t \geq 0$ and $x \in \mathbb{Z}$. Moreover, the process

$$
\begin{equation*}
Y_{t}:=Z_{N(A(t))}, \quad t \geq 0 \tag{2.18}
\end{equation*}
$$

is a continuous-time Markov chain on $\mathbb{Z}$ with generator $\mathcal{L}_{t}$ in (2.15).
We note that (1.7) along with stationarity implies that, $\mathbb{P}-$ a.s., at any time and position, the time it takes to accumulate one unit of conductance is finite. Hence, the P-a.s. validity of (2.16) follows. Lemma 2.1 then shows that the dual random walk $Y$ is well defined (as a time change of the constant-speed simple symmetric random walk) for $\mathbb{P}$-a.e. sample of the random environment.

As it turns out, the construction of the parabolic coordinate for $X$ is equivalent to the construction of an invariant measure $\mathbb{Q}$ for the environment as seen by the walk $Y$. In [6], such an invariant measure is extracted by constructing its Radon-Nikodym derivative with respect to $\mathbb{P}$, and thus proving that $\mathbb{Q} \ll \mathbb{P}$. For us this comes in:
Theorem 2.2. Under the conditions of Theorem 1.3, there exists $\varphi \in L^{1}(\mathbb{P})$ that satisfies
(1) $\mathbb{P}(\varphi>0)=1$ and $\mathbb{E} \varphi=1$,
(2) $\mathbb{E}\left(b_{0}(0) \varphi^{2}\right) \leq \mathbb{E} b_{0}(0)$,
(3) the map $t \rightarrow \varphi \circ \tau_{t, x}$ is continuous and weakly differentiable such that

$$
\begin{equation*}
\frac{\partial}{\partial t} \varphi \circ \tau_{t, x}+\mathcal{L}_{t}^{+} \varphi \circ \tau_{t, x}=0 \tag{2.19}
\end{equation*}
$$

holds for all $t \in \mathbb{R}$ and $x \in \mathbb{Z}$.
In particular, $\mathbb{Q}$ defined for $A \in \mathcal{F}$ by $\mathbb{Q}(A):=\mathbb{E}\left(\varphi 1_{A}\right)$ is a probability measure on $(\Omega, \mathcal{F})$ that is stationary and ergodic for the chain $t \mapsto \tau_{-t, Y_{t}}(a)$.

The link between the above Radon-Nikodym derivative and the parabolic coordinate is supplied by the observation that the PDEs (2.12) for $t, x \mapsto g(t, x)$ and (2.19) for $t, x \mapsto \varphi \circ \tau_{t, x}$ are identical. Setting $g(t, x):=\varphi \circ \tau_{t, x}$ would give us access to the gradient of $\psi$. The parabolic coordinate $\psi$ is extracted from this via

$$
\begin{equation*}
\psi(t, x):=\chi(t, 0) \circ \tau_{0, x}+\sum_{k=0}^{x-1} \varphi \circ \tau_{0, k} \tag{2.20}
\end{equation*}
$$

where

$$
\begin{equation*}
\chi(t, 0):=-\int_{0}^{t}\left(b_{s}(0) \varphi \circ \tau_{s, 0}-b_{s}(-1) \varphi \circ \tau_{s,-1}\right) \mathrm{d} s \tag{2.21}
\end{equation*}
$$

Here the (Lebesgue) integral converges absolutely under expectation, and thus $\mathbb{P}$-a.s., by Tonelli's Theorem along with $\varphi \in L^{1}(\mathbb{P})$ and $b_{t}(x) \in[0,1]$ as implied by the assumptions of Theorem 1.3. Standard interpretations of the integral in (2.21) and the sum in (2.20) are to be used for negative $t$ and $x$.

It is straightforward to check (see the proof of [6, Theorem 3.2]) that $\psi$ from (2.20) obeys conditions (1-4) listed earlier. (In particular, (2.4) makes (2.9) and (2.21) consistent.) It then remains to prove the bound (2.10) for the corrector. In light of the cocycle conditions (2.4), for this suffices to prove separately sublinearity in space

$$
\begin{equation*}
\lim _{n \rightarrow \pm \infty} \frac{|\chi(0, n)|}{n}=0, \quad \mathbb{P} \text {-a.s. } \tag{2.22}
\end{equation*}
$$

and subdiffusivity in time

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \frac{|\chi(t, 0)|}{\sqrt{t}}=0, \quad \text { P-a.s. } \tag{2.23}
\end{equation*}
$$

Indeed, the "good grid" argument (originally designed in Berger and Biskup [4] for random walk on static percolation) used in [6] then builds this into (2.10).

As to the above almost sure limits, the one in (2.22) is proved by following the argument from [6, Lemma 7.1] with the moment conditions supplied by Theorem 2.2(1). (In particular, no path interpolation as used in Berger and Biskup [4] are needed, nor is the conversion of the first moment of $\chi$ to the weighted second moment from Biskup [5].) The proof of (2.23), which comes as [6, Proposition 7.2], is considerably longer as it involves a different representation of $\chi(0, t)$ and the use of a Quenched Central Limit Theorem for the walk $Y$ (which needs the invariant measure $\mathbb{Q}$ and its equivalence with $\mathbb{P}$, as implied by Theorem $2.2(1)$ ). But, as an inspection of these proofs reveals, the negative moment condition is not used throughout and some proofs (e.g., that of [6, Lemma 8.1]) become even simpler for bounded conductances.

The bottom line is that the proof of Theorem 1.3 is reduced to those of Lemma 2.1 and Theorem 2.2. These proofs, which we will address in the next section, are the main technical contributions of the present note.

## 3 Actual proofs

We now move to the proofs of the technical claims from Section 2, starting with the construction of the dual random walk $Y$ on which the rest of the argument is based. We assume the conditions of Theorem 1.3 throughout this section.

### 3.1 The dual random walk

Our overall goal is to construct the continuous-time random walk $Y$ from (2.18). As is standard in the theory of continuous-time Markov chains (cf., e.g., Liggett [14]), we first construct the associated transition probabilities. For this we define a family of non-negative kernels $\mathrm{K}_{n}(s, x ; t, y)$ indexed by integers $n \geq 0$ and depending on reals $-\infty<t \leq s<\infty$ and vertices $x, y \in \mathbb{Z}$ inductively via

$$
\begin{align*}
& \mathrm{K}_{n+1}(s, x ; t, y):=\mathrm{e}^{-\int_{t}^{s} 2 b_{u}(x) \mathrm{d} u} \delta_{x, y} \\
&+\int_{t}^{s} \mathrm{e}^{-\int_{r}^{s} 2 b_{u}(x) \mathrm{d} u} b_{r}(x)\left(\sum_{z= \pm 1} \mathrm{~K}_{n}(r, x+z ; t, y)\right) \mathrm{d} r \tag{3.1}
\end{align*}
$$

with the initial value $\mathrm{K}_{0}(s, x ; t, y):=0$. Note that time runs in the opposite direction of how the conductances are parametrized.

The definition (3.1) readily yields that $n \mapsto \mathrm{~K}_{n}(s, x ; t, y)$ is non-decreasing and nonnegative with $\sum_{y \in \mathbb{Z}} \mathrm{~K}_{n}(s, x ; t, y) \leq 1$. The limit

$$
\begin{equation*}
\mathrm{K}(s, x ; t, y):=\lim _{n \rightarrow \infty} \mathrm{~K}_{n}(s, x ; t, y) \tag{3.2}
\end{equation*}
$$

thus exists, is non-negative and obeys $\sum_{y \in \mathbb{Z}} \mathrm{~K}(s, x ; t, y) \leq 1$ thanks to the Monotone Convergence Theorem. With all these objects being random variables on the probability space $(\Omega, \mathcal{F}, \mathbb{P})$, we also have

$$
\begin{equation*}
\mathrm{K}(s, x ; t, y) \circ \tau_{u, z}=\mathrm{K}(s+u, x+z ; t+u, y+z) \tag{3.3}
\end{equation*}
$$

for all $s \geq t$, all $u \in \mathbb{R}$ and all $x, y, z \in \mathbb{Z}$. The main difficulty is to show that K is stochastic which, as usual, is achieved by constructing the continuous time Markov chain as a time-change of a discrete-time chain. This is what is done in:

Proof of Lemma 2.1. As in the proof of [6, Lemma 4.2], instead of $A$ we construct its inverse. Unfortunately, due to $s \mapsto b_{-s}(x)$ potentially vanishing over sets of positive

Lebesgue measure, this inverse is no longer continuous which complicates its use. We thus proceed by a perturbation argument.

Abusing our earlier notation, let $\tau_{0}:=0<\tau_{1}<\ldots$ denote the successive arrivals of a rate- 1 (right-continuous) Poisson process $N$ and let $Z$ be the sample path of an independent discrete-time simple symmetric random walk on $\mathbb{Z}$. Given $\delta>0$, and restricting to the full-measure event $\bigcap_{n \geq 0}\left\{\tau_{n}<\infty\right\}$, set $W_{\delta}(0):=0$ and, for each $n \geq 0$ and $t \in\left(\tau_{n}, \tau_{n+1}\right]$, let $W_{\delta}(t)$ be the unique number such that

$$
\begin{equation*}
\int_{W_{\delta}\left(\tau_{n}\right)}^{W_{\delta}(t)}\left[\delta+2 b_{-s}\left(Z_{n}\right)\right] \mathrm{d} s=t-\tau_{n} \tag{3.4}
\end{equation*}
$$

The assumptions ensure that $W_{\delta}(t)$ is finite for each $t \geq 0$ with $t \mapsto W_{\delta}(t)$ continuous and strictly increasing with the lower bound $W_{\delta}(t)-W_{\delta}(s) \geq(2+\delta)^{-1}(t-s)$ whenever $t \geq s \geq 0$. In particular, $\lim _{t \rightarrow \infty} W_{\delta}(t)=\infty$.

It follows that $W_{\delta}$ admits a unique continuous and strictly increasing inverse $A_{\delta}$ mapping $[0, \infty)$ onto itself. Thanks to the strict monotonicity, the defining relation (3.4) shows that $A_{\delta}(s) \in\left[\tau_{n}, \tau_{n+1}\right)$ is equivalent to $s \in\left[W_{\delta}\left(\tau_{n}\right), W_{\delta}\left(\tau_{n+1}\right)\right)$ and, since this forces $N\left(A_{\delta}(s)\right)=n$ for all $s \in\left[W_{\delta}\left(\tau_{n}\right), W_{\delta}\left(\tau_{n+1}\right)\right)$, we may rewrite (3.4) into

$$
\begin{equation*}
\int_{W_{\delta}\left(\tau_{n}\right)}^{t}\left[\delta+2 b_{-s}\left(Z_{N\left(A_{\delta}(s)\right)}\right)\right] \mathrm{d} s=A_{\delta}(t)-\tau_{n}, \quad t \in\left[W_{\delta}\left(\tau_{n}\right), W_{\delta}\left(\tau_{n+1}\right)\right] \tag{3.5}
\end{equation*}
$$

Here continuity of both sides in $t$ was used to include $t=W_{\delta}\left(\tau_{n+1}\right)$.
We now take $\delta \downarrow 0$ to extract the desired function $A$. To that end we first note that a telescoping argument applied to (3.5) gives

$$
\begin{equation*}
\int_{0}^{t}\left[\delta+2 b_{-s}\left(Z_{N\left(A_{\delta}(s)\right)}\right)\right] \mathrm{d} s=A_{\delta}(t) \tag{3.6}
\end{equation*}
$$

for all $t \geq 0$, where we used that $A_{\delta}(0)=0$. A similar argument applied to (3.4) shows that $\delta \mapsto W_{\delta}(t)$ is non-increasing and so $\delta \mapsto A_{\delta}(t)$ is non-decreasing. In light of the Lipschitz bound $0 \leq A_{\delta}(t)-A_{\delta}(s) \leq(2+\delta)(t-s)$ for $t \geq s \geq 0$, the limit

$$
\begin{equation*}
A(t):=\lim _{\delta \downarrow 0} A_{\delta}(t) \tag{3.7}
\end{equation*}
$$

exists and defines a continuous real-valued non-decreasing function $t \mapsto A(t)$ satisfying $A(0)=0$. The upward monotonicity of $\delta \mapsto A_{\delta}(s)$ in conjunction with the right-continuity of $N$ gives $b_{-s}\left(Z_{N\left(A_{\delta}(s)\right)}\right) \rightarrow b_{-s}\left(Z_{N(A(s))}\right)$ as $\delta \downarrow 0$, for each $s \geq 0$. Taking $\delta \downarrow 0$ in (3.6) with the help of the Bounded Convergence Theorem then proves (2.17).

Define $Y$ from the processes $N, Z$ and $A$ by the formula (2.18). Recall that $P^{x}$ is the law of these objects such that $P^{x}\left(Z_{0}=x\right)=1$. The identity (3.1) then inductively shows that, for all $t \geq 0$,

$$
\begin{equation*}
\mathrm{K}_{n}(0, x ;-t, y)=P^{x}\left(Y_{t}=y, N(A(t))<n\right), \quad n \geq 0 \tag{3.8}
\end{equation*}
$$

As $P^{x}(N(A(t))<\infty)=1$ due to $P^{x}(A(t)<\infty)=1$, taking $n \rightarrow \infty$ gives

$$
\begin{equation*}
\mathrm{K}(0, x ;-t, y)=P^{x}\left(Y_{t}=y\right) . \tag{3.9}
\end{equation*}
$$

In particular, K is stochastic and, taking $n \rightarrow \infty$ in (3.1) using the Monotone Convergence Theorem, $Y$ is a Markov chain with generator $\mathcal{L}_{t}$.

### 3.2 Proof of Theorem 2.2

Having constructed the random walk $Y$, we now move to the construction of the Radon-Nikodym derivative $\varphi$ of the invariant measure on environments as seen from $Y$. As in [6], we will extract $\varphi$ as an $\varepsilon \downarrow 0$ limit of the quantity

$$
\begin{equation*}
\varphi_{\varepsilon}:=\varepsilon \int_{0}^{\infty} \mathrm{e}^{-\varepsilon t}\left(\sum_{y \in \mathbb{Z}} \mathrm{~K}(t, y ; 0,0)\right) \mathrm{d} t \tag{3.10}
\end{equation*}
$$

We first pull some observations from [6]:
Lemma 3.1. For each $\varepsilon>0$,

$$
\begin{equation*}
\mathbb{E}\left(\varphi_{\varepsilon}\right)=1 \tag{3.11}
\end{equation*}
$$

and, in particular, $\varphi_{\varepsilon}$ is finite $\mathbb{P}$-a.s. Moreover, abbreviating

$$
\begin{equation*}
\varphi_{\varepsilon}(t, x):=\varphi_{\varepsilon} \circ \tau_{t, x} \tag{3.12}
\end{equation*}
$$

the function $t \mapsto \varphi_{\varepsilon}(t, x)$ is continuous and weakly differentiable with

$$
\begin{equation*}
\frac{\partial}{\partial t} \varphi_{\varepsilon}(t, x)=\varepsilon\left(\varphi_{\varepsilon}(t, x)-1\right)-\mathcal{L}_{t}^{+} \varphi_{\varepsilon}(t, x) \tag{3.13}
\end{equation*}
$$

Proof. Formula (3.11) is obtained by invoking stationarity of $\mathbb{P}$ along with (3.3) and the Monotone Convergence Theorem to rewrite the sum in (3.10) under expectation into $\sum_{y \in \mathbb{Z}} \mathrm{~K}(0,0 ;-t, y)=1$. Formula (3.13) is a limit version of [6, formula 5.20] whose derivation applies verbatim.

Lemma 3.2. For each $\varepsilon>0$, we have

$$
\begin{equation*}
\mathbb{E}\left(b_{0}(0) \varphi_{\varepsilon}^{2}\right) \leq \mathbb{E} b_{0}(0) \tag{3.14}
\end{equation*}
$$

Proof. This is a restatement of [6, Proposition 5.1] whose proof applies without changes in our case as well.

The argument of [6] proceeds by taking a weak limit of $\varphi_{\varepsilon}$ as $\varepsilon \downarrow 0$ and using (3.14) to show that "no mass is lost" in (3.11) in this process. In [6], this step required the negative moment condition which would restrict us to $b_{0}(0)>0 \mathrm{P}$-a.s. Once this does not apply, even the subsequent use of (3.14) becomes problematic as the inequality can at best give control of the weak limit on the set where $b_{0}(0)>0$.

In order to overcome these issues, we invoke an idea from Biskup and Rodriguez [7] that is itself drawn from Mourrat and Otto [15]. In these works, the argument proceeds by finding a version of (3.14) in which $b_{t}(x)$ is replaced by the time-averaged quantity of the form

$$
\begin{equation*}
c_{t}(x):=\int_{t}^{\infty} k_{s-t} b_{s}(x) \mathrm{d} s \tag{3.15}
\end{equation*}
$$

where $t \mapsto k_{t}$ is a suitable positive function on $(0, \infty)$ with sufficient decay at infinity. Note that $c_{t}(x)$ is positive as soon as $s \mapsto b_{s}(x)$ is positive on a set of positive Lebesgue measure, which for us occurs P-a.s. thanks to (1.7).

As it turns out, the most useful choice is to take $t \mapsto k_{t}$ with a power-law decay and so we henceforth set

$$
\begin{equation*}
k_{t}:=(1+t)^{-\alpha} \tag{3.16}
\end{equation*}
$$

for some $\alpha>0$ to be determined momentarily. The reason for this is seen from:
Lemma 3.3. Recall the quantity $T$ from (1.6) and let $\alpha>0$. Then for $c_{0}(0)$ defined using the kernel (3.16),

$$
\begin{equation*}
\mathbb{E}\left(T^{\alpha}\right)<\infty \quad \Rightarrow \quad \mathbb{E}\left(c_{0}(0)^{-1}\right)<\infty \tag{3.17}
\end{equation*}
$$

Proof. We have

$$
\begin{equation*}
c_{0}(0)=\int_{0}^{\infty} k_{t} b_{t}(0) \mathrm{d} t \geq \int_{0}^{T} k_{t} b_{t}(0) \mathrm{d} t \geq \frac{1}{(1+T)^{\alpha}} \int_{0}^{T} b_{t}(0) \mathrm{d} t=\frac{1}{(1+T)^{\alpha}} \tag{3.18}
\end{equation*}
$$

which yields $c_{0}(0)^{-1} \leq(1+T)^{\alpha}$. The claim follows.
The restriction on the moment of $T$ now comes via:
Proposition 3.4. For any $\alpha>3$ and for $c_{0}(0)$ defined using the kernel (3.16),

$$
\begin{equation*}
\sup _{0<\varepsilon<1} \mathbb{E}\left(c_{0}(0) \varphi_{\varepsilon}^{2}\right)<\infty \tag{3.19}
\end{equation*}
$$

Before giving the proof of Proposition 3.4, which comes in Section 3.3, we give:
Proof of Theorem 2.2 from Proposition 3.4. Suppose the moment condition (1.7) holds with some $\varepsilon>0$ and let $\alpha:=3+\varepsilon$. Writing $L^{0}(\mathbb{P})$ for the set of measurable $f: \Omega \rightarrow \mathbb{R}$ modulo changes on $\mathbb{P}$-null sets, consider the Hilbert space

$$
\begin{equation*}
\mathcal{H}:=\left\{f \in L^{0}(\mathbb{P}): \mathbb{E}\left(c_{0}(0)^{-1} f^{2}\right)<\infty\right\} \tag{3.20}
\end{equation*}
$$

endowed with the inner product $\langle f, g\rangle_{\mathcal{H}}:=\mathbb{E}\left(c_{0}(0)^{-1} f g\right)$. Using $C$ to denote the supremum in (3.19), for any $f \in L^{\infty}(\mathbb{P})$ and $\varepsilon \in(0,1)$ the Cauchy-Schwarz inequality shows

$$
\begin{equation*}
\mathbb{E}\left(\varphi_{\varepsilon} f\right) \leq C^{1 / 2}\left[\mathbb{E}\left(c_{0}(0)^{-1} f^{2}\right)\right]^{1 / 2} \tag{3.21}
\end{equation*}
$$

It follows that

$$
\begin{equation*}
\phi_{\varepsilon}(f):=\mathbb{E}\left(\varphi_{\varepsilon} f\right) \tag{3.22}
\end{equation*}
$$

defines a continuous linear functional on $\mathcal{H}$ with the operator norm bounded by $C^{1 / 2}$ uniformly in $\varepsilon \in(0,1)$. As $\mathcal{H}$ is separable, and the unit ball in $\mathcal{H}^{\star}$ thus weakly compact, the Cantor diagonal argument yields a sequence $\varepsilon_{n} \downarrow 0$ and $\phi \in \mathcal{H}^{\star}$ such that $\phi_{\varepsilon_{n}}(f) \rightarrow \phi(f)$ for all $f \in \mathcal{H}$. The Riesz lemma then shows that $\phi$ takes the form $\phi(f)=\mathbb{E}\left[c_{0}(0)^{-1} h f\right]$ for some $h \in \mathcal{H}$. We define $\varphi:=c_{0}(0)^{-1} h$.

Lemma 3.3 along with the moment condition (1.7) implies that the space $L^{\infty}(\mathbb{P})$ of bounded measurable functions obeys

$$
\begin{equation*}
L^{\infty}(\mathbb{P}) \subset \mathcal{H} \tag{3.23}
\end{equation*}
$$

In particular, $1 \in \mathcal{H}$. The identity $\phi_{\varepsilon}(1)=\mathbb{E}\left(\varphi_{\varepsilon}\right)=1$ then survives the limit and so we get $\mathbb{E}(\varphi)=1$, proving the second half of (1). For the inequality in (2), we first note that the bound $\mathbb{E}\left[b_{0}(0)\left(\varphi_{\varepsilon}-f\right)^{2}\right] \geq 0$ shows that, for any $f \in L^{\infty}(\mathbb{P})$,

$$
\begin{equation*}
2 \mathbb{E}\left(b_{0}(0) f \varphi_{\varepsilon}\right)-\mathbb{E}\left(b_{0}(0) f^{2}\right) \leq \mathbb{E}\left[b_{0}(0) \varphi_{\varepsilon}^{2}\right] \leq \mathbb{E}\left[b_{0}(0)\right], \tag{3.24}
\end{equation*}
$$

where the last inequality is taken from Lemma 3.2. Since $b_{0}(0) \in[0,1]$ implies $b_{0}(0) f \in$ $L^{\infty}(\mathbb{P})$ for $f \in L^{\infty}(\mathbb{P})$, the first term on the left of (3.24) converges to $2 \mathbb{E}\left(b_{0}(0) f \varphi\right)$ along the sequence $\left\{\varepsilon_{n}\right\}_{n \geq 1}$ that was used to define $\varphi$. Combining this with

$$
\begin{equation*}
\mathbb{E}\left[b_{0}(0) \varphi^{2}\right]=\sup _{f \in L^{\infty}(\mathbb{P})}\left[2 \mathbb{E}\left(b_{0}(0) f \varphi\right)-\mathbb{E}\left(b_{0}(0) f^{2}\right)\right] \tag{3.25}
\end{equation*}
$$

which, as is checked by a suitable truncation, holds regardless whether the left-hand side is finite or infinite, then yields the inequality in (2).

The proof of the needed regularity of $t \mapsto \varphi \circ \tau_{t, x}$ - or, more precisely, the existence of a continuous, weakly-differentiable version - so that the PDE (2.19) holds is identical to that in [6] and we omit it here. It remains to prove the P-a.s. positivity of $\varphi$. First
note that $\varphi$ is nonnegative. This is because $\mathbb{E}\left(1_{\{\varphi<0\}} \varphi_{\varepsilon_{n}}\right)$ tends to $\mathbb{E}\left(1_{\{\varphi<0\}} \varphi\right)$ in the limit and $\varphi_{\varepsilon_{n}} \geq 0$ then shows $\mathbb{E}\left(1_{\{\varphi<0\}} \varphi\right) \geq 0$ forcing $\mathbb{P}(\varphi<0)=0$. Next we observe that, for each $t \geq 0$ we have

$$
\begin{equation*}
\varphi=\sum_{x \in \mathbb{Z}} \varphi \circ \tau_{t, x} \mathrm{~K}(t, x ; 0,0) \tag{3.26}
\end{equation*}
$$

on a set of full $\mathbb{P}$-measure, which is proved using the same argument as in [6, Theorem 5.5]. As $\mathrm{K}(t, 0 ; 0,0)>0$, assuming $\varphi=0$ in (3.26) forces $\varphi \circ \tau_{t, 0}=0 \mathbb{P}$-a.s. for each $t \geq 0$. Using shift invariance and continuity, we conclude

$$
\begin{equation*}
\{\varphi=0\} \stackrel{\mathbb{P} \text {-a.s. }}{=}\left\{\forall t \in \mathbb{R}: \varphi \circ \tau_{t, 0}=0\right\} \tag{3.27}
\end{equation*}
$$

But for each $x \in \mathbb{Z}$ and $\mathbb{P}$-a.e. realization of the random environment, $\mathrm{K}(t, x ; 0,0)>0$ once $t \geq 0$ is large enough and so, invoking (3.26) and shift invariance again we get

$$
\begin{equation*}
\{\varphi=0\} \stackrel{\mathbb{P} \text {-a.s. }}{=}\left\{\forall t \in \mathbb{R} \forall x \in \mathbb{Z}: \varphi \circ \tau_{t, x}=0\right\} . \tag{3.28}
\end{equation*}
$$

The event on the right is shift invariant and so, in light of ergodicity of $\mathbb{P}$ from Assumption 1.1, it is a zero-one event under $\mathbb{P}$. The case of full measure is ruled out by $\mathbb{E} \varphi=1$ thus proving $\mathbb{P}(\varphi=0)=0$.

### 3.3 Boundedness of weighted Dirichlet energy

The last remaining item needed to complete the proof of Theorem 1.3 is the proof of the uniform bound (3.19). We again need a couple lemmas that are drawn from, or otherwise available in [6]. Define

$$
\begin{equation*}
\chi_{\varepsilon}:=\int_{0}^{\infty} \mathrm{e}^{-\varepsilon t}\left[b_{t}(0) \varphi_{\varepsilon}(t, 0)-b_{t}(-1) \varphi_{\varepsilon}(t,-1)\right] \mathrm{d} t \tag{3.29}
\end{equation*}
$$

where the integral of each of the two terms in the square bracket is finite under expectation with respect to $\mathbb{P}$, and thus $\mathbb{P}$-a.s., by the fact that $0 \leq b_{t}(0) \varphi_{\varepsilon}(t, 0) \leq \varphi_{\varepsilon}(t, 0)$ thanks to (1.6) and $\varphi_{\varepsilon}(t, 0) \in L^{1}(\mathbb{P})$ thanks to (3.11). We start with:
Lemma 3.5. For each $\varepsilon>0$,

$$
\begin{equation*}
\left\|\chi_{\varepsilon}\right\|_{L^{2}(\mathbb{P})} \leq \frac{2}{\varepsilon} \tag{3.30}
\end{equation*}
$$

Proof. Minkowski's inequality yields

$$
\begin{align*}
\left\|\chi_{\varepsilon}\right\|_{L^{2}(\mathbb{P})} & \leq \int \mathrm{e}^{-\varepsilon t}\left\|b_{t}(0) \varphi_{\varepsilon}(t, 0)-b_{t}(-1) \varphi_{\varepsilon}(t,-1)\right\|_{L^{2}(\mathbb{P})} \mathrm{d} t \\
& \leq 2 \int \mathrm{e}^{-\varepsilon t}\left\|b_{t}(0) \varphi_{\varepsilon}(t, 0)\right\|_{L^{2}(\mathbb{P})} \mathrm{d} t \leq 2 \int \mathrm{e}^{-\varepsilon t}\left\|b_{t}(0)^{1 / 2} \varphi_{\varepsilon}(t, 0)\right\|_{L^{2}(\mathbb{P})} \mathrm{d} t \tag{3.31}
\end{align*}
$$

where we used $b_{t}(0) \leq 1$ in the last inequality. Lemma 3.2 along with $\mathbb{E} b_{0}(0) \leq 1$ bounds the last $L^{2}$-norm by one.

The motivation for introducing $\chi_{\varepsilon}$ in [6] is that its spatial gradients (under environment shifts) are those of centered $\varphi_{\varepsilon}$, which (in light of $\varphi$ being the gradient of the parabolic coordinate) makes $\chi_{\varepsilon}$ an approximate corrector. Indeed, we have:
Lemma 3.6. For each $\varepsilon>0$,

$$
\begin{equation*}
\chi_{\varepsilon} \circ \tau_{0,1}-\chi_{\varepsilon}=\varphi_{\varepsilon}-1 \tag{3.32}
\end{equation*}
$$

Proof. [6, Lemma 5.2] proves a truncated version of this equation; namely,

$$
\begin{equation*}
\chi_{\varepsilon, n} \circ \tau_{0,1}-\chi_{\varepsilon, n}=\varphi_{\varepsilon, n+1}-1 \tag{3.33}
\end{equation*}
$$

where $\varphi_{\varepsilon, n}$ is defined by (3.10) with K replaced by $\mathrm{K}_{n}$ and

$$
\begin{equation*}
\chi_{\varepsilon, n}:=\int_{0}^{\infty} \mathrm{e}^{-\varepsilon t}\left[b_{t}(0) \varphi_{\varepsilon, n} \circ \tau_{t, 0}-b_{t}(-1) \varphi_{\varepsilon, n} \circ \tau_{t,-1}\right] \mathrm{d} t \tag{3.34}
\end{equation*}
$$

The monotonicity of $n \mapsto \mathrm{~K}_{n}$ implies $\varphi_{\varepsilon, n} \uparrow \varphi_{\varepsilon}$ as $n \rightarrow \infty$ and the Monotone Convergence Theorem shows $\chi_{\varepsilon, n} \rightarrow \chi_{\varepsilon}$ as $n \rightarrow \infty$. Hence (3.32) follows from (3.33).

Lemma 3.6 now extends the bound from Lemma 3.5 to $\varphi_{\varepsilon}$ as well:
Lemma 3.7. For each $\varepsilon>0$,

$$
\begin{equation*}
\mathbb{E}\left(\varphi_{\varepsilon}^{2}\right) \leq\left(1+\frac{4}{\varepsilon}\right)^{2} \tag{3.35}
\end{equation*}
$$

Proof. The triangle inequality applied to the identity from Lemma 3.6 gives

$$
\begin{equation*}
\left\|\varphi_{\varepsilon}\right\|_{L^{2}(\mathbb{P})} \leq 1+\left\|\chi_{\varepsilon} \circ \tau_{0,1}\right\|_{L^{2}(\mathbb{P})}+\left\|\chi_{\varepsilon}\right\|_{L^{2}(\mathbb{P})}=1+2\left\|\chi_{\varepsilon}\right\|_{L^{2}(\mathbb{P})} \tag{3.36}
\end{equation*}
$$

Lemma 3.5 now bounds the right-hand side by $1+\frac{4}{\varepsilon}$.
With the above lemmas in hand, we are ready to give:
Proof of Proposition 3.4. Our task is to convert the Dirichlet energy with averaged conductance to the Dirichlet energy with instantaneous conductance to which the inequality in Lemma 3.2 can be applied. As observed first in Mourrat and Otto [15] and further exploited in Biskup and Rodriguez [7], this is possible thanks to the fact that $t, x \mapsto \varphi_{\varepsilon}(t, x)$ obeys the (massive) heat equation (3.13). We start with the rewrite

$$
\begin{align*}
c_{0}(0) \varphi_{\varepsilon}(0,0)^{2} & =\int_{0}^{\infty} k_{t} b_{t}(0) \varphi_{\varepsilon}(0,0)^{2} \mathrm{~d} t \\
& =\int_{0}^{\infty} k_{t} b_{t}(0)\left[\varphi_{\varepsilon}(0,0)-\varphi_{\varepsilon}(t, 0)+\varphi_{\varepsilon}(t, 0)\right]^{2} \mathrm{~d} t \\
& \leq 2 \int_{0}^{\infty} k_{t} b_{t}(0) \varphi_{\varepsilon}(t, 0)^{2} \mathrm{~d} t+2 \int_{0}^{\infty} k_{t} b_{t}(0)\left(\varphi_{\varepsilon}(0,0)-\varphi_{\varepsilon}(t, 0)\right)^{2} \mathrm{~d} t  \tag{3.37}\\
& \leq 2 \int_{0}^{\infty} k_{t} b_{t}(0) \varphi_{\varepsilon}(t, 0)^{2} \mathrm{~d} t+2 \int_{0}^{\infty} k_{t}\left(\varphi_{\varepsilon}(0,0)-\varphi_{\varepsilon}(t, 0)\right)^{2} \mathrm{~d} t
\end{align*}
$$

where we use the inequality $(a+b)^{2} \leq 2 a^{2}+2 b^{2}$ and the assumption $b_{t}(0) \leq 1$. For the integrand of the second term, the heat equation in Lemma 3.1 along with the Cauchy-Schwarz inequality and the bound $\left(\sum_{i=1}^{4} a_{i}\right)^{2} \leq 4 \sum_{i=1}^{4} a_{i}^{2}$ yields

$$
\begin{align*}
& \left(\varphi_{\varepsilon}(0,0)-\varphi_{\varepsilon}(t, 0)\right)^{2}=\left[\int_{0}^{t} \mathcal{L}_{s}^{+} \varphi_{\varepsilon}(s, 0)-\varepsilon\left(\varphi_{\varepsilon}(t, x)-1\right) \mathrm{d} s\right]^{2} \\
& \quad=\left[\int_{0}^{t} b_{s}(1) \varphi_{\varepsilon}(s, 1)+b_{s}(-1) \varphi_{\varepsilon}(s,-1)-2 b_{s}(0) \varphi_{\varepsilon}(s, 0)-\varepsilon\left(\varphi_{\varepsilon}(s, 0)-1\right) \mathrm{d} s\right]^{2} \\
& \quad \leq t \int_{0}^{t}\left[b_{s}(1) \varphi_{\varepsilon}(s, 1)+b_{s}(-1) \varphi_{\varepsilon}(s,-1)-2 b_{s}(0) \varphi_{\varepsilon}(s, 0)-\varepsilon\left(\varphi_{\varepsilon}(s, 0)-1\right)\right]^{2} \mathrm{~d} s  \tag{3.38}\\
& \quad \leq 4 t \varepsilon^{2} \int_{0}^{t}\left(\varphi_{\varepsilon}(s, 0)-1\right)^{2} \mathrm{~d} s+16 t \sum_{z=-1}^{1} \int_{0}^{t}\left[b_{s}(z) \varphi_{\varepsilon}(s, z)\right]^{2} \mathrm{~d} s
\end{align*}
$$

where the factor 16 results from overcounting that makes the resulting expression simpler to write. Bounding $\left(\varphi_{\varepsilon}(s, 0)-1\right)^{2} \leq 2+2 \varphi_{\varepsilon}(s, 0)^{2}$ and using $b_{s}(z) \leq 1$ to drop one $b_{s}(z)$ from the second integral wraps this into

$$
\begin{equation*}
\left(\varphi_{\varepsilon}(0,0)-\varphi_{\varepsilon}(t, 0)\right)^{2} \leq 8 t^{2} \varepsilon^{2}+8 t \varepsilon^{2} \int_{0}^{t} \varphi_{\varepsilon}(s, 0)^{2} \mathrm{~d} s+16 t \sum_{z=-1}^{1} \int_{0}^{t} b_{s}(z) \varphi_{\varepsilon}(s, z)^{2} \mathrm{~d} s \tag{3.39}
\end{equation*}
$$

Plugging the resulting bound on the right of (3.37) and performing a simple change of order of integration then shows

$$
\begin{align*}
c_{0}(0) \varphi_{\varepsilon}(0,0)^{2} \leq & 2 \int_{0}^{\infty} k_{t} b_{t}(0) \varphi_{\varepsilon}(t, 0)^{2} \mathrm{~d} t+16 \varepsilon^{2} \int_{0}^{\infty} t^{2} k_{t} \mathrm{~d} t \\
& +16 \varepsilon^{2} \int_{0}^{\infty} K_{t} \varphi_{\varepsilon}(t, 0)^{2} \mathrm{~d} t+32 \sum_{z=-1}^{1} \int_{0}^{\infty} K_{t} b_{t}(z) \varphi_{\varepsilon}(t, z)^{2} \mathrm{~d} t \tag{3.40}
\end{align*}
$$

where

$$
\begin{equation*}
K_{t}:=\int_{t}^{\infty} s k_{s} \mathrm{~d} s \tag{3.41}
\end{equation*}
$$

Taking expectation and invoking stationarity of $\mathbb{P}$ with respect to shifts gives

$$
\begin{align*}
& \mathbb{E}\left(c_{0}(0) \varphi_{\varepsilon}(0,0)^{2}\right) \leq 2 \mathbb{E}\left(b_{0}(0) \varphi_{\varepsilon}^{2}\right)\left(\int_{0}^{\infty} k_{t} \mathrm{~d} t\right)+16 \varepsilon^{2}\left(\int_{0}^{\infty} t^{2} k_{t} \mathrm{~d} t\right) \\
&+\left(\int_{0}^{\infty} K_{t} \mathrm{~d} t\right)\left[16 \varepsilon^{2} \mathbb{E}\left(\varphi_{\varepsilon}^{2}\right)+96 \mathbb{E}\left(b_{0}(0) \varphi_{\varepsilon}^{2}\right)\right] \tag{3.42}
\end{align*}
$$

For our choice (3.16) of $t \mapsto k_{t}$ with $\alpha>3$, the integrals with respect to $t$ converge and the terms involving the expectations are bounded uniformly in $\varepsilon \in(0,1)$ thanks to Lemmas 3.2 and 3.7.

Remark 3.8. Similar to the derivations of [7], the use of the Cauchy-Schwarz inequality while dropping factors of $b_{s}(\cdot)$ is likely a wasteful step that forces the need for higher moments of $T$ than what should be optimal and, in addition, limits us to bounded conductances. Unfortunately, we do not know how to proceed otherwise.

## 4 Random walk on dynamical percolation

We will now apply the conclusions of Theorem 1.3 to random walks on dynamical percolation. Recall that, in our interpretation, a dynamical percolation is any conductance environment with law $\mathbb{P}$ under which $\left\{t \mapsto a_{t}(e)\right\}_{e \in E(\mathbb{Z})}$ are i.i.d. copies of a zero-one valued, non-degenerate (i.e., truly two-valued), stationary process on $\{0,1\}$ with piece-wise constant right-continuous sample paths. A standard argument gives:
Lemma 4.1. Any dynamical percolation law $\mathbb{P}$ obeys Assumption 1.1.
Proof. The required regularity of sample paths follows from the assumed piece-wise constancy. The law $\mathbb{P}$ is also clearly invariant under all space time shifts. In order to show ergodicity, let $A \in \mathcal{F}$ be invariant under the space shifts (invariance under time shifts is not required). The product structure of $A$ ensures that, given $n \geq 1$, there exists $A_{n} \in \sigma\left(a_{t}(x, x+1):-n \leq x<n, t \in \mathbb{R}\right)$ such that $\mathbb{E}\left|1_{A}-1_{A_{n}}\right|<1 / n$. Now define $A_{n}^{\prime}:=\tau_{0, n}\left(A_{n}\right)$ and $A_{n}^{\prime \prime}:=\tau_{0,-n}\left(A_{n}\right)$ and use space-shift invariance of $A$ to check that $\mathbb{E}\left|1_{A}-1_{A_{n}^{\prime}}\right|<1 / n, \mathbb{E}\left|1_{A}-1_{A_{n}^{\prime \prime}}\right|<1 / n$ and so $\mathbb{P}(A)-\mathbb{P}\left(A_{n}^{\prime} \cap A_{n}^{\prime \prime}\right)<2 / n$. Observing that $A_{n}^{\prime}$ and $A_{n}^{\prime \prime}$ are independent under $\mathbb{P}$ and taking $n \rightarrow \infty$ this yields $\mathbb{P}(A) \leq \mathbb{P}(A)^{2}$, thus showing that $A$ is trivial under $\mathbb{P}$.

Thanks to the assumed non-degeneracy, each realization of the individual conductance process $t \mapsto a_{t}(e)$ induces a sequence $\left\{\left(T_{i}^{\text {OFF }}, T_{i}^{\text {oN }}\right)\right\}_{i \in \mathbb{Z}}$ of (a.s.) positive and finite random variables (see the discussion before Theorem 1.4). We now observe:
Lemma 4.2. Given a dynamical percolation law $\mathbb{P}$ and an edge $e$, assume that the probability measure $\widetilde{\mathbb{P}}$ on $\sigma\left(\left\{a_{t}(e): t \in \mathbb{R}\right\}\right)$ is well defined by (1.9). Then $\left\{\left(T_{i}^{\text {off }}, T_{i}^{\text {oN }}\right)\right\}_{i \in \mathbb{Z}}$ is stationary (with respect to the shifts of the index set) under $\widetilde{\mathbb{P}}$.

Proof. Recall the notation $\left\{\tau_{i}\right\}_{i \in \mathbb{Z}}$ (from Section 1) for the sequence of successive times that $t \mapsto a_{t}(e)$ switches from 1 to 0 indexed so that $\tau_{0} \leq 0<\tau_{1}$. We will abbreviate $T_{i}:=$ $\tau_{i+1}-\tau_{i}=T_{i}^{\text {OFF }}+T_{i}^{\text {oN }}$. The assumption that $\widetilde{\mathbb{P}}$ is well defined amounts to $T_{0}^{-1} \in L^{1}(\mathbb{P})$. Recall also the definition $U:=-\tau_{0} /\left(\tau_{1}-\tau_{0}\right)$.

In order to prove the desired claim, given any $s>0$ consider the events

$$
\begin{equation*}
A_{0}(s):=\left\{0 \leq s<(1-U) T_{0}\right\} \tag{4.1}
\end{equation*}
$$

and, for $k \geq 1$, also

$$
\begin{equation*}
A_{k}(s):=\left\{(1-U) T_{0}+\sum_{i=1}^{k-1} T_{i} \leq s<(1-U) T_{0}+\sum_{i=1}^{k} T_{i}\right\} \tag{4.2}
\end{equation*}
$$

and note that these define a partition of the whole probability space minus the null set $\left\{(1-U) T_{0}+\sum_{i=1}^{\infty} T_{i} \leq s\right\}$. The reason for introducing these is that, on $A_{0}(s)$, an application of the shift by $s$ to $t \mapsto a_{t}(e)$ changes $U$ to $U+s / T_{0}$ and keeps the sequence $\left\{\left(T_{i}^{\text {off }}, T_{i}^{\mathrm{oN}}\right)\right\}_{i \in \mathbb{Z}}$ intact while, on $A_{k}(s)$ with $k \geq 1$, it changes $U$ to $T_{k}^{-1}\left[s-(1-U) T_{0}-\right.$ $\left.\sum_{i=1}^{k-1} T_{i}\right]$ and shifts the sequence $\left\{\left(T_{i}^{\text {OFF }}, T_{i}^{\mathrm{ON}}\right)\right\}_{i \in \mathbb{Z}}$ by $k$ indices to the left.

Given a bounded measurable function $f: \mathbb{R} \times(\mathbb{R} \times \mathbb{R})^{\mathbb{Z}} \rightarrow[0, \infty)$, the invariance of the law of $t \mapsto a_{t}(e)$ under the shift by $s$ then yields

$$
\begin{align*}
\mathbb{E}\left(T_{0}^{-1} f(U,\right. & \left.\left.\left\{\left(T_{i}^{\mathrm{OFF}}, T_{i}^{\mathrm{ON}}\right)\right\}_{i \in \mathbb{Z}}\right)\right)=\mathbb{E}\left(1_{A_{0}(s)} T_{0}^{-1} f\left(U+s / T_{0},\left\{\left(T_{i}^{\mathrm{ofF}}, T_{i}^{\mathrm{oN}}\right)\right\}_{i \in \mathbb{Z}}\right)\right) \\
& +\sum_{k \geq 1} \mathbb{E}\left(1_{A_{k}(s)} T_{k}^{-1} f\left(\frac{s-(1-U) T_{0}-\sum_{i=1}^{k-1} T_{i}}{T_{k}},\left\{\left(T_{i+k}^{\mathrm{OFF}}, T_{i+k}^{\mathrm{ON}}\right)\right\}_{i \in \mathbb{Z}}\right)\right) . \tag{4.3}
\end{align*}
$$

Next we pick $n \geq 1$ and average $s$ over $[0, n]$. There are only two terms on the right that "witness" the endpoints of the interval $[0, n]$ - namely, the first term and the term in the sum for which $(1-U) T_{0}+\sum_{i=1}^{k-1} T_{j} \leq n<(1-U) T_{0}+\sum_{i=1}^{k} T_{j}$ - and their contribution is bounded thanks to fact that the integration over $s$ produces a factor that is dominated by $T_{0}$ and $T_{k}$, respectively. A simple change of variables then shows

$$
\begin{align*}
\mathbb{E}\left(T_{0}^{-1} f(U,\right. & \left.\left.\left\{\left(T_{i}^{\mathrm{ofF}}, T_{i}^{\mathrm{oN}}\right)\right\}_{i \in \mathbb{Z}}\right)\right) \\
& =\lim _{n \rightarrow \infty} \frac{1}{n} \sum_{k \geq 1} \mathbb{E}\left(1_{(1-U) T_{0}+\sum_{i=1}^{k} T_{j} \leq n} \int_{0}^{1} f\left(v,\left\{\left(T_{i+k}^{\mathrm{oFF}}, T_{i+k}^{\mathrm{oN}}\right)\right\}_{i \in \mathbb{Z}}\right) \mathrm{d} v\right) \tag{4.4}
\end{align*}
$$

where the limit exists because the left-hand side does not depend on $n$. The expectation on the left is finite by the assumption that $T_{0}^{-1} \in L^{1}(\mathbb{P})$.

Next we observe that the event $(1-U) T_{0}+\sum_{i=1}^{k} T_{j} \leq n$ in the indicator in (4.4) can be changed to $(1-U) T_{0}+\sum_{i=1}^{k-1} T_{j} \leq n$ without changing the limit. (Indeed, this again affects at most two terms in the sum.) Hence, for each $f$ as above we get

$$
\begin{equation*}
\mathbb{E}\left(T_{0}^{-1} f\left(U,\left\{\left(T_{i}^{\text {ofF }}, T_{i}^{\text {oN }}\right)\right\}_{i \in \mathbb{Z}}\right)\right)=\mathbb{E}\left(T_{0}^{-1} f\left(U,\left\{\left(T_{i+1}^{\text {ofF }}, T_{i+1}^{\text {ON }}\right)\right\}_{i \in \mathbb{Z}}\right)\right) \tag{4.5}
\end{equation*}
$$

thus proving that the law of $\left\{\left(T_{i}^{\text {off }}, T_{i}^{\text {ON }}\right)\right\}_{i \in \mathbb{Z}}$ is shift invariant under $\widetilde{\mathbb{P}}$. (Note that (4.4) also allows us to replace $f(U, \cdot)$ by its average over the first coordinate and thus shows that $U$ is independent of $\left\{\left(T_{i}^{\text {off }}, T_{i}^{\text {oN }}\right)\right\}_{i \in \mathbb{Z} .}$. This proves the claim.

With this in hand, we now give:
Proof of Theorem 1.4. Using the "OFF/ON"-times, the random variable $T$ from (1.6) can be bounded as

$$
\begin{equation*}
T \leq \sum_{i=0}^{N}\left(T_{i}^{\mathrm{ofF}}+T_{i}^{\mathrm{oN}}\right) \tag{4.6}
\end{equation*}
$$

where

$$
\begin{equation*}
N:=\inf \left\{n \geq 1: \sum_{i=1}^{n} T_{i}^{\mathrm{ON}} \geq 1\right\} \tag{4.7}
\end{equation*}
$$

In order to estimate the moments of the sum on the right of (4.6), we recall the following observation from Berger and Biskup [4]:
Lemma 4.3 (Lemma 4.5 of [4]). Given reals $p>1, r \in[1, p)$ and $s$ satisfying

$$
\begin{equation*}
s>r \frac{1-1 / p}{1-r / p} \tag{4.8}
\end{equation*}
$$

if $X_{1}, X_{2}, \ldots$ are random variables such that $\sup _{i \geq 1}\left\|X_{i}\right\|_{p}<\infty$ and $N$ is integer valued such that $N \in L^{s}$, then $\sum_{i=1}^{N} X_{i} \in L^{r}$.

To apply this to our situation, let $p$ and $s$ be reals satisfying the inequalities and the moment bounds in (1.10). Pick any $\tilde{s}$ satisfying

$$
\begin{equation*}
s>\tilde{s}>4 \frac{1-1 / p}{1-4 / p} . \tag{4.9}
\end{equation*}
$$

Continuity then ensures that there is $r \in(4, p)$ such that (4.8) holds with $\tilde{s}$ in place of $s$. In order to apply Lemma 4.3, we need to control the moments of $N$ in (4.7). Here the Markov and Jensen inequalities along with the stationarity proved in Lemma 4.2 yield

$$
\begin{align*}
\widetilde{\mathbb{P}}(N>n) & \leq \widetilde{\mathbb{P}}\left(\sum_{i=1}^{n} T_{i}^{\mathrm{ON}}<1\right) \leq \widetilde{\mathbb{E}}\left(\left(\sum_{i=1}^{n} T_{i}^{\mathrm{ON}}\right)^{-s}\right)  \tag{4.10}\\
& =\frac{1}{n^{s}} \widetilde{\mathbb{E}}\left(\left(\frac{1}{n} \sum_{i=1}^{n} T_{i}^{\mathrm{ON}}\right)^{-s}\right) \leq \frac{1}{n^{s}} \widetilde{\mathbb{E}}\left(\frac{1}{n} \sum_{i=1}^{n}\left(T_{i}^{\mathrm{ON}}\right)^{-s}\right)=\frac{1}{n^{s}} \widetilde{\mathbb{E}}\left(\left(T_{1}^{\mathrm{ON}}\right)^{-s}\right) .
\end{align*}
$$

The formula $\widetilde{\mathbb{E}}\left(N^{\tilde{s}}\right)=\int_{0}^{\infty} \tilde{s} n^{\tilde{s}-1} \widetilde{\mathbb{P}}(N>n) \mathrm{d} n$ then gives $N \in L^{\tilde{s}}$ and Lemma 4.3 (with $\tilde{s}$ in place of $s$ ) shows $\widetilde{\mathbb{E}}\left(T^{r}\right)<\infty$. In order to convert this to a bound under expectation with respect to $\mathbb{P}$, we invoke the Hölder inequality to get

$$
\begin{equation*}
\mathbb{E}\left(T^{\alpha}\right)=\frac{\widetilde{\mathbb{E}}\left(\left(T_{0}^{\mathrm{ofF}}+T_{0}^{\mathrm{oN}}\right) T^{\alpha}\right)}{\widetilde{\mathbb{E}}\left(T_{0}^{\mathrm{ofF}}+T_{0}^{\mathrm{oN}}\right)} \leq \frac{\left[\widetilde{\mathbb{E}}\left(\left(T_{0}^{\mathrm{oFF}}+T_{0}^{\mathrm{oN}}\right)^{4}\right)\right]^{1 / 4}}{\widetilde{\mathbb{E}}\left(T_{0}^{\mathrm{ofF}}+T_{0}^{\mathrm{oN}}\right)}\left[\widetilde{\mathbb{E}}\left(T^{4 \alpha / 3}\right)\right]^{3 / 4} \tag{4.11}
\end{equation*}
$$

Note that the fourth moment exists by our assumption in (1.10). Setting $\alpha:=3 r / 4$ and noting that then $\alpha>3$, we have verified the moment condition (1.7). Theorem 1.3 shows that a Quenched Invariance Principle holds.

Lemma 4.4. Suppose that the conductance processes $\left\{t \mapsto a_{t}(e)\right\}_{e \in E(\mathbb{Z})}$ are i.i.d. zeroone valued with the underlying sequence $\left\{\left(T_{i}^{\text {off }}, T_{i}^{\text {oN }}\right)\right\}_{i \in \mathbb{Z}}$ of "OFF/ON"-times such that $T_{i}^{\text {on }}:=1$ for all $i \in \mathbb{Z}$ and $\left\{T_{i}^{\text {OFF }}\right\}_{i \in \mathbb{Z}}$ i.i.d. under $\widetilde{\mathbb{P}}$. Assume that $T_{0}^{\text {off }}<\infty \widetilde{\mathbb{P}}$-a.s. yet $T_{0}^{\text {off }} \notin L^{1 / 2}(\widetilde{\mathbb{P}})$. Then $X_{t} / \sqrt{t} \rightarrow 0$ in probability as $t \rightarrow \infty$ for $\mathbb{P}$-a.e. sample of the random environment.

Proof. For each edge $e \in E(\mathbb{Z})$, let

$$
\begin{equation*}
\widetilde{T}(e):=\inf \left\{t \geq 0: a_{t}(e)>0\right\} . \tag{4.12}
\end{equation*}
$$

Under the assumptions of the lemma, and reflecting on the connection between $t \mapsto a_{t}(e)$ and the OFF/ON times for edge $e$, the random variables $\{\widetilde{T}(e)\}_{e \in E(\mathbb{Z})}$ are i.i.d. with the common law determined by

$$
\begin{equation*}
\widetilde{\mathbb{P}}(\widetilde{T}(e)>u)=\widetilde{\mathbb{P}} \otimes P\left(T_{0}^{\mathrm{OFF}}-U\left(1+T_{0}^{\mathrm{OFF}}\right)>u\right) \tag{4.13}
\end{equation*}
$$

where $P$ is the law of a uniform random variable $U$ on $[0,1]$ which (under $\widetilde{\mathbb{P}} \otimes P$ ) is independent of $T_{0}^{\text {off }}$. The assumption $T_{0}^{\text {off }} \notin L^{1 / 2}(\widetilde{\mathbb{P}})$ then forces $\widetilde{\mathbb{E}}\left(\widetilde{T}(e)^{1 / 2}\right)=\infty$ and so, by the standard facts about sequences of i.i.d. random variables,

$$
\begin{equation*}
\forall \varepsilon>0: \quad \frac{1}{n} \max _{0 \leq x \leq \varepsilon \sqrt{n}} \widetilde{T}(x, x+1) \underset{n \rightarrow \infty}{\longrightarrow} \infty \quad \widetilde{\mathbb{P}} \text {-a.s. } \tag{4.14}
\end{equation*}
$$

Since the random walk $X$ cannot cross edge $e$ before time $\widetilde{T}(e)$, on the event that the maximum in (4.14) is larger than $n$ we have $\max _{t \in[0, n]} X_{t} \leq \varepsilon \sqrt{n}$. By symmetry, $X_{t}=o(\sqrt{t})$ a.s. as $t \rightarrow \infty$ thus showing that $X$ is subdiffusive.

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