Intermediate disorder limits for multi-layer semi-discrete directed polymers

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Abstract

We show that the partition function of the multi-layer semi-discrete directed polymer converges in the intermediate disorder regime to the partition function for the multi-layer continuum polymer introduced by O’Connell and Warren in [24]. This verifies, modulo a previously hidden constant, an outstanding conjecture proposed by Corwin and Hammond [5]. A consequence is the identification of the KPZ line ensemble as logarithms of ratios of consecutive layers of the continuum partition function. Other properties of the continuum partition function, such as continuity, strict positivity and contour integral formulas to compute mixed moments, are also identified from this convergence result.

Keywords: random polymers; non-intersecting random walks; KPZ.

MSC2020 subject classifications: 82D60.

1 Introduction

1.1 Background and main results

Let \( d \in \mathbb{N} = \{1, 2, 3, \ldots\} \), \( \beta > 0 \), \( t^* > 0 \) and \( z^* \in \mathbb{R} \). In this work, we will use the superscript \( * \) to denote quantities related to the endpoint of bridges; for example \((t^*, z^*)\) will denote the endpoint of \( d \) non-intersecting Brownian bridges. O’Connell and Warren [24] define a continuum partition function which is given by the following white noise chaos series:

\[
Z^\beta_d(t^*, z^*) \triangleq \beta \sum_{k=0}^{\infty} \int_{\Delta_k(0, t^*)} \psi_k(t^*, z^*) \left( (t_1, z_1), \ldots, (t_k, z_k) \right) \xi(dt_1, dz_1) \cdots \xi(dt_k, dz_k),
\]  

(1.1)

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where \( \xi(t, z) \) is 1+1 dimensional Gaussian white noise, \( \Delta_k(a, b) \) denotes the set of ordered \( k \)-tuples of time coordinates, \( \rho(t, z) \) is the heat kernel:

\[
\Delta_k(a, b) \triangleq \{ a < t_1 < \ldots < t_k < b \}, \quad \rho(t, z) \triangleq (2\pi t)^{-1/2} \exp(-z^2/2t),
\]

and \( \psi^{(t^*, z^*)}_k \) is the \( k \)-point correlation function for \( d \) non-intersecting Brownian bridges, each of which starts at 0 at time 0 and ends at \( z^* \) at time \( t^* \) (see Definition 2.2 for a precise definition).

In the case \( d = 1 \), \( Z_1^\beta \) is a solution to the stochastic heat equation with multiplicative white noise

\[
\partial_t Z_1^\beta = \frac{1}{2} \partial_{xx} Z_1^\beta + \beta \xi Z_1^\beta,
\]

with delta initial data \([1]\). Moreover, \( Z_1^\beta \) was shown to be the universal scaling limit of the partition function for discrete directed polymers in the intermediate disorder regime introduced by Alberts, Khanin and Quastel \([1]\). In this scaling limit the strength of the random environment is scaled to zero in a critical way as the size of the discrete system grows to infinity. Similarly, when \( d > 1 \), \( Z_d^\beta \) was shown to be the universal limit in the intermediate disorder regime for discrete directed polymers consisting of \( d \) non-intersecting simple symmetric random walks in \([6]\).

Another random polymer model that has received recent attention is the O’Connell-Yor semi-discrete directed polymer introduced in \([25]\), where the polymers are in continuous time but in discrete space. It was shown in \([23]\) that the multi-layer version of this, which involves several non-intersecting polymer paths, has an algebraic structure related to Whittaker functions and the quantum Toda lattice. This multi-layer semi-discrete partition function is the main object of study in this paper and is defined precisely below.

**Definition 1.1.** An up/right path in \( \mathbb{R} \times \mathbb{N} \) is an increasing path which either proceeds to the right or jumps up by exactly one unit. For any \( \tau^* > 0 \) and any \( x^* \in \mathbb{N} \), each sequence \( 0 < \tau_1 < \ldots < \tau_{x^*} < \tau^* \) is associated to an up/right path \( X^{(\tau^*, x^*)}() \) which travels from the lattice point \( (0, 1) \) to \( (\tau^*, x^* + 1) \), and which jumps between the points \( (\tau_i, i) \) and \( (\tau_i, i + 1) \) for \( 1 \leq i \leq x^* \) and otherwise always travels to the right. The list \( \tau^* \in \Delta_{x^*}(0, \tau^* \in \mathbb{R}^{x^*} \) can be thought of as the “jump times” of the up/right path; the list of jump times is in bijection with the up/right path \( X^{(\tau^*, x^*)}() \) and we therefore conflate the two notions with the convention that the paths are cadlag.

Let \( \{B_i()\}_{i=1}^\infty \) be an infinite family of independent standard Brownian motions on a probability space \( (\Omega, \mathcal{F}, \mathbb{P}) \). Define the energy of the up/right path \( X^{(\tau^*, x^*)}(\cdot) \) to be the following random variable on the probability space \( \Omega \):

\[
H \left( X^{(\tau^*, x^*)} \right) \triangleq B_1(\tau_1) + (B_2(\tau_2) - B_2(\tau_1)) + \cdots + (B_{x^*+1}(\tau^*) - B_{x^*+1}(\tau_{x^*}))
= \sum_{j=1}^{x^*+1} \int_0^{\tau^*} \mathbb{1} \{ j = X^{(\tau^*, x^*)}(s) \} \, dB_j(s) = \int_0^{\tau^*} dB_{X^{(\tau^*, x^*)}(s)}(s). \quad (1.3)
\]

We can think of \( X^{(\tau^*, x^*)}(\cdot) \) as a random up/right path in a natural way by taking the probability measure on the set of jump times \( \tau^* \in \Delta_{x^*}(0, \tau^* \in \mathbb{R}^{x^*} \) which is proportional to the Lebesgue measure on \( \mathbb{R}^{x^*} \). If we denote by \( \mathbb{E} \) the expectation with respect to this measure, we define for any \( \beta > 0 \), the directed polymer partition function \( Z_1^\beta(\tau^*, x^*) \), which is a random variable on the probability space \( \Omega \), by

\[
Z_1^\beta(\tau^*, x^*) \triangleq \mathbb{E} \left[ \exp \left( \beta H(X^{(\tau^*, x^*)}) \right) \right].
\]
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Figure 1: $d$ non-intersecting up/right paths $\vec{X}^{(\tau^*,x^*)}$ started from $X_i(0) = i$ and ended at $X_i(\tau^*) = x^* + i$ for $1 \leq i \leq d$. In this example $d = 3$.

We generalize this for $d > 1$ by taking multiple up/right paths as follows. Let $\vec{X}^{(\tau^*,x^*)} = \left( X_1^{(\tau^*,x^*)}(), \ldots, X_d^{(\tau^*,x^*)}() \right)$ be a collection of $d$ up/right paths with initial points $X_i^{(\tau^*,x^*)}(0) = i$ and final points $X_i^{(\tau^*,x^*)}(\tau^*) = x^* + i$ for $1 \leq i \leq d$ which are non-intersecting. More specifically, the non-intersecting condition that we require is that $X_i^{(\tau^*,x^*)}(\tau) < X_j^{(\tau^*,x^*)}(\tau)$ for all $i < j$ and for all times $\tau \in (0, \tau^*)$.

Notice now that all the jump times for the $d$ up/right paths taken together can be thought of as a vector in $R^{dx^*}$. We can think of $\vec{X}^{(\tau^*,x^*)}()$ as a random process by taking the probability measure on this list of jump times proportional to the Lebesgue measure on the subset of $R^{dx^*}$ of allowed configuration. (The process $\vec{X}^{(\tau^*,x^*)}$ defined in this way also has a natural interpretation as certain Poisson walkers conditioned to be non-intersecting; see Remark 2.6.) Figure 1 shows a typical realization of these paths. Denoting by $E$ the expectation with respect to this measure, we define the partition function:

$$Z_d^\beta (\tau^*, x^*) \equiv E \left[ \exp \left( \beta \sum_{i=1}^{d} H \left( X_i^{(\tau^*,x^*)}() \right) \right) \right].$$

In the case $d = 1$, it is shown in [11] that the semi-discrete partition function $Z_1^\beta$ converges to $Z_d^\beta$ from equation (1.1) in the intermediate disorder regime. An expository presentation of this proof is given in [4]. The main result of this article, Theorem 1.2, is to extend this to $d > 1$: a convergence result for semi-discrete polymers consisting of $d$ non-intersecting up/right paths that start and end grouped together.

**Theorem 1.2.** Fix $d \in \mathbb{N}$, $t^* > 0$, $z^* \in \mathbb{R}$, and $\beta > 0$. Recall for any $\tau^* > 0$, $x^* \in \mathbb{N}$, that $Z_d^\beta (\tau^*, x^*)$ denotes the semi-discrete partition function for $d$ non-intersecting up/right paths as in Definition 1.1. For any sequence $\beta_N$ with $N^{1/2} \beta_N \to \beta$ as $N \to \infty$, we have the following convergence in distribution as $N \to \infty$:

$$Z_d^{\beta_N} \left( t^* N, \left[ t^* N + z^* \sqrt{N} \right] \right) \exp \left( -\frac{d}{2} t^* N \beta_N^2 \right) \Rightarrow \frac{Z_d^\beta (t^*, z^*)}{\rho (t^*, z^*)^d}. \quad (1.4)$$

Moreover, it is possible to find a coupling of the probability space on which $Z_d^{\beta_N}$ is defined to the probability space on which $Z_d^\beta$ is defined, so that the convergence is in $L^p$ for any $p > 1$.

Finally, if one treats the LHS and RHS of equation (1.4) as stochastic processes indexed by $d \in \mathbb{N}, t^* \in (0, \infty), z^* \in \mathbb{R}$, then the convergence also holds for the finite dimensional distributions of these processes.
Remark 1.3. The expected value of $Z^d_\beta(\tau, x)$ is always $\exp(\frac{1}{2} \tau \beta^2)$ irrespective of $x$ (see Lemma 2.13). This explains the scaling on the LHS of equation (1.4), which is exactly needed to normalize to unit expectation.

Remark 1.4. A similar convergence result for non-intersecting ensembles of simple symmetric random walks in discrete time and discrete space was proven in [6]. The interest behind the result for discrete random walks was that the convergence did not depend on the “disordered environment” used to define the partition function: the convergence was universal in this sense.

The interest in the semi-discrete result is different. Instead of a universality-type result, Theorem 1.2 is only about convergence of the specific model in Definition 1.1 where the environment is given by independent Brownian motions. The reason Theorem 1.2 is useful is that many properties of the model in Definition 1.1 are already known, and these properties can be carried over in the limit. Therefore, Theorem 1.2 gives a way to extract information about the limiting partition function $Z^d_\beta$. In particular, this can be used to prove a connection between $Z^d_\beta$ and the KPZ line ensemble defined in [5], which was the original motivation for the convergence result. Section 1.2 details some of these applications of Theorem 1.2.

The main technical tool in the proof of Theorem 1.2 is the $L^2$ convergence of the $k$-point correlation functions of the non-intersecting up/right paths to those of the non-intersecting Brownian bridges under the diffusive scaling $(\tau, x) \approx (Nt, Nt + \sqrt{N}z)$. This is encapsulated in the following convergence result:

**Theorem 1.5.** For any $t > 0$, $z \in \mathbb{R}$, and $k \in \mathbb{N}$, let $\psi_k^{(N),(t,z)} : \Delta_k(0,t) \times \mathbb{R}^k \to \mathbb{R}$ be the $k$-point correlation functions for $d$ non-intersecting up/right paths which start and end grouped together and are rescaled diffusively in space and time; see Definition 2.16 for a precise definition. Let $\psi_k^{(t,z)} : \Delta_k(0,t) \times \mathbb{R}^k \to \mathbb{R}$ be the $k$-point correlation function for $d$ non-intersecting Brownian bridges given in Definition 2.2. Then we have the following convergence as $N \to \infty$:

$$\lim_{N \to \infty} \left\| \psi_k^{(N),(t,z)} - \psi_k^{(t,z)} \right\|_{L^2(\Delta_k(0,t) \times \mathbb{R}^k)} = 0.$$  

(1.5)

The argument which shows that Theorem 1.5 implies Theorem 1.2 is carried out in Section 2 and uses the theory of Gaussian Hilbert spaces to directly connect the semi-discrete polymer and the continuum polymer. This is different than the method of polynomial chaos series developed in [3] which was used as an intermediate step for the convergence of discrete non-intersecting random walks established in [6].

The proof of Theorem 1.5 is carried out in Section 2.7, with technical lemmas deferred to later sections. The proof goes by extending the methods introduced in [6] which were used to prove a similar $L^2$ convergence result for discrete non-intersecting random walks. An additional complication that must be handled here is due to the exponentially rare event that a continuous-time random process takes many steps in a short amount of time. We extend the method of exponential moment control used in [6] in order to handle this type of rare event. Another complication is that the discrete Tanaka formula used in [6] does not apply to the continuous-time random processes studied here. To handle this, it is necessary to first “de-Poissonize” the processes before proving certain bounds, and then “re-Poissonize” to get back to the original model; this is carried out in Section 4.4.

### 1.2 Applications of Theorem 1.2

We connect the notation from Definition 1.1 to other work in the literature and present some applications of Theorem 1.2 in the corollaries below. Many of these corollaries were
conjectured in Sections 2.3.3 and 2.3.4 of [5]. (Note that the numbering of equations in [5] refers to the published version and may differ from the latest arXiv version of that paper.)

**Definition 1.6** (Following Definitions 3.1 and 3.5 of [5]). For each $M > 0$, $t > 0$ define

$$C(M, t, z) \equiv \exp \left\{ M + \frac{\sqrt{tM} + z}{2} + z t^{-\frac{d}{2}} M^\frac{d}{2} \right\} \left( t^2 M^{-\frac{d}{2}} \right)^M.$$

Let $D_d^{(M)}(t) \subset \mathbb{R}^{d(M-d)}$ denote the set of jump times for $d$-tuples of non-intersecting up/right paths with initial points $s(0) = (0, 1, \ldots, (0, d)$ and endpoints $(t, M - d + 1), \ldots, (t, M)$. Identifying up/right paths with their jump times as we did in Definition 1.1, define $Z_d^{(M)}(t)$ as the integral (w.r.t Lebesgue measure) over all such $d$-tuples of non-intersecting up/right paths:

$$Z_d^{(M)}(t) \equiv \int_{D_d^{(M)}(t)} \exp^\sum_{i=1}^d H(\phi_i) d\phi_1 \ldots d\phi_d.$$

Note that $Z_d^{(M)}(t)$ is proportional to $Z_d^\beta(\tau^*, x^*)$ from Definition 1.1 when $\beta = 1$, $\tau^* = t$ and $x^* = M - d$; indeed they are related by the Lebesgue measure of the set $D_d^{(M)}(t)$:

$$Z_d^{(M)}(t) = \mathcal{L}(D_d^{(M)}(t)) Z_d^1(t, M - d). \quad (1.6)$$

The Lebesgue measure of this set is explicitly calculated in Lemma 2.20. For $M \in \mathbb{N}$, $d \in \mathbb{N}$, $z \in \mathbb{R}$ so that $z > -\sqrt{tM}$ define $Z_d^{t,M}(z)$ by:

$$Z_d^{t,M}(z) \equiv \frac{Z_d^{(M)}(\sqrt{tM} + z)}{C(M, t, z)^d}. \quad (1.7)$$

**Corollary 1.7** (Conjecture 2.18 of [5] modulo the constant $c_{d,t}$). For any $d \in \mathbb{N}$, $t > 0$, define the constant $c_{d,t}$ by

$$c_{d,t}^{-1} \equiv t^{\frac{d}{2}(d-1)} \prod_{i=0}^{d-1} i! \quad (1.7)$$

For any fixed $t > 0$ and $z \in \mathbb{R}$, we have the convergence as $M \to \infty$:

$$Z_d^{t,M}(z) \to c_{d,t}^{-1} Z_d^1(t, z). \quad (1.8)$$

Moreover, thinking of the LHS and RHS of equation (1.8) as stochastic process indexed by $d \in \mathbb{N}$, and $z \in \mathbb{R}$, the convergence holds for finite dimensional distributions of these processes and the convergence holds for the $p$-th moment of these processes for any $p \geq 1$.

Corollary 1.7 follows from Theorem 1.2 after recognizing $Z_d^{t,M}$ in terms of $Z_d^\beta$ as in equation (1.6) and applying Stirling’s formula to estimate the Lebesgue measure of the set $D_d^{(M)}(s)$. These calculations are deferred to Section 2.6.

**Remark 1.8.** Note that in the original Conjecture 2.18 of [5], the constant $c_{d,t}$ on the RHS of equation (1.8) was absent. This constant is nontrivial only for $d > 1$, and arises due to the “squeezing” together of the start and end points of the polymer in the diffusive scaling limit. $c_{d,t}^{-1}$ can be related to the constant that appears due to this same squeezing in equation (12) of [19]. The normalization $c_{d,t}^{-1} Z_d^{t,M}(t, z)$ is also the correct normalization so that the time evolution of this object is related to the 2D Toda equations, see [20].
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Note that the omission of this constant in Conjecture 2.18 of [5] does not effect any of the analysis of the KPZ equation carried out there, since these applications are based on studying $\mathcal{H}_n^t$, defined below in Corollary 1.9, for which the constant $c_{1,t} \equiv 1$ has no effect.

**Corollary 1.9.** For each $t > 0$, $n \in \mathbb{N}$, $z \in \mathbb{R}$, set

$$\mathcal{H}_n^t(z) = \ln \left( \frac{c_{n,t}^{-1} \mathcal{Z}_n^t(t,z)}{c_{n-1,t}^{-1} \mathcal{Z}_n^t(t,z)} \right),$$

where we take the convention $\mathcal{Z}_0^t \equiv 1$ and the constant $c_{n,t}$ is as in equation (1.7). Then the line ensemble $(\mathcal{H}_n^t(z))_{n \in \mathbb{N}, z \in \mathbb{R}}$ satisfies the requirements of being a KPZ line ensemble as defined in Theorem 2.15 in [5].

**Proof.** In [5], the KPZ line ensemble was constructed by showing tightness and then extracting a subsequential limit from rescaled versions of the process $\mathcal{Z}_n^t$ (see Theorem 3.9 and Lemma 5.1 in [5]). Corollary 1.7 identifies the finite dimensional distributions of this process, thereby showing that all the subsequential limits are the same, and identifying this unique limit. Following the construction of the KPZ line ensemble in Section 5 of [5] gives $\mathcal{H}_n^t$ as in equation (1.9). □

**Remark 1.10.** The main result, Theorem 2.15, of [5] was to show the existence of a line ensemble which satisfies the requirements of being a KPZ line ensemble. Corollary 1.9 gives an explicit formula for the line ensemble constructed in [5] in terms of the partition functions from [24] by the definition in equation (1.9). It is reasonable to believe that this line ensemble is the unique line ensemble which satisfies the required properties of being a KPZ line ensemble, but this is currently unproven.

**Corollary 1.11.** For fixed $t > 0$ and $d \in \mathbb{N}$, the continuum partition function $\mathcal{Z}_d^t(t,z)$ is almost surely positive and continuous as function of $z \in \mathbb{R}$

**Proof.** This follows from Corollary 1.9 since the KPZ line ensemble $\mathcal{H}_n^t$, from [5] is continuous. □

**Remark 1.12.** The strict positivity and continuity of $\mathcal{Z}_d^t$ was first proven in [19] by different methods. Note that the result in [19] is more powerful since it also proves continuity as $t$ varies.

**Corollary 1.13.** Let $\mathcal{H}_d^t(z)$ be the ensemble from equation (1.9). (which satisfies the requirements of being a KPZ line ensemble as in Theorem 2.15 of [5]). Then, for fixed $d \in \mathbb{N}, t > 0$, the stochastic process $\mathcal{H}_d^t(z) + \frac{z^2}{2t}$ indexed by $z \in \mathbb{R}$ is stationary.

**Proof.** This follows by combining the identification from Corollary 1.9 with the fact that for fixed $t$, $\rho^{-d}(t,z) \mathcal{Z}_d^t(t,z)$ indexed by $z \in \mathbb{R}$ is stationary jointly over $d \in \mathbb{N}$. The latter process is stationary because of the invariance of the white noise environment under the affine shift of coordinates $(t,z) \rightarrow (t,z-z^* \frac{1}{t})$ and because, for all $d \in \mathbb{N}$, this shift maps the non-intersecting Brownian bridges with endpoint $(t^*, z^*)$ to the non-intersecting Brownian bridges with endpoint $(t^*, 0)$ in a measure-preserving way. □

**Remark 1.14.** Conjecture 2.17 of [5] is that the rescaled KPZ line ensemble plus a parabola converges as $t \rightarrow \infty$ to the Airy line ensemble. Corollary 1.13 supports this conjecture since the Airy line ensemble is known to be stationary. In fact, a possible avenue of proof of this conjecture goes by showing that the Airy line ensemble is the unique line ensemble that is stationary and possesses a non-intersecting Brownian Gibbs property. The result Corollary 1.13 is a required first step for this method; see Section 2.3.3 of [5] for a full outline of this argument.
Corollary 1.15. For any \( t > 0 \), \( k \in \mathbb{N} \) and a list of indices \( r_\alpha \in \mathbb{N} \), \( 1 \leq \alpha \leq k \) and list of coordinates \( x_1 < \ldots < x_k \), the joint moments of the continuum random polymer are given by the following explicit contour integrals:

\[
\mathcal{E} \left[ \prod_{\alpha=1}^{k} c_{r_\alpha,t}^{-1} Z_{r_\alpha}(t,x_\alpha) \right] = \prod_{\alpha=1}^{k} \frac{1}{(2\pi i)^{r_\alpha}} \int \cdots \int \prod_{1 \leq \alpha \leq \beta \leq k} \left( \prod_{i=1}^{r_\alpha} \prod_{j=1}^{r_\beta} z_{\alpha,i} - z_{\beta,j} - 1 \right) \times \prod_{\alpha=1}^{k} \left( \prod_{i \neq j} (z_{\alpha,i} - z_{\alpha,j}) \right) \left( \prod_{j=1}^{r_\alpha} e^{\frac{1}{2} \pi i z_{\alpha,j}^2 + x_\alpha z_{\alpha,j} d z_{\alpha,j}} \right) \quad (1.10)
\]

where the constants \( c_{r_\alpha,t} \) are as in equation (1.7), and the \( z_{\alpha,j} \)-contour is along \( C_\alpha + i \mathbb{R} \) for any constants \( C_1 > C_2 + 1 > C_3 + 2 > \ldots > C_k + (k-1) \) for all \( j \in \{1, \ldots, r_\alpha\} \) and \( \mathcal{E} \) denotes expectation with respect to the random environment. (Note that because of the ordering of the contours, this formula only holds when \( x_1 \leq \ldots \leq x_k \) as in the hypothesis.)

Proof. Proposition 5.4.6. in [2] explicitly calculates the contour integral on the RHS of 1.10 as the \( M \to \infty \) limit for the joint moments for the process \( Z_{d,t}^\omega \) defined in Corollary 1.7. Since the convergence in Definition 1.6 holds for finite dimensional distributions and moments, this establishes equation (1.10).

Remark 1.16. The result of Corollary 1.15 was originally conjectured in Remark 5.4.7 of [2]. Note that the constants \( c_{r_\alpha,t}^{-1} \) are absent in the original formulas from Remark 5.4.7 of [2] because, just as in Remark 1.8, these constants were not known to appear in the convergence at the time. Corollary 1.15 also validates the use of these moment formulas in the physics literature, see [7]. (Only the \( r_\alpha = 1 \) formulas were used here, for which the missing constant has no effect since \( c_{1,t} \equiv 1 \).)

1.3 Outline

Subsections 2.1 and 2.2 contain the precise definitions of the stochastic processes used throughout the paper. Subsections 2.3 and 2.4 contain still more definitions and lemmas that reduce the proof of Theorem 1.2 to the convergence of certain chaos series; this proof is given in Subsection 2.5. Subsection 2.7 contains the proof of the main technical result, Theorem 1.5, with important estimates, Propositions 2.24, 2.25, 2.26 and 2.27, deferred to later sections. Subsection 2.6 contains the asymptotic analysis needed to prove Corollary 1.7. Propositions 2.24 and 2.25 are proven in Section 3 using methods involving orthogonal polynomials. Propositions 2.26 and 2.27 are proven in Section 5 using the machinery of overlap times and weak exponential moment control developed in Section 4.

1.4 Notation

Let \( \mathbb{N} = \{1, 2, \ldots\} \). We use the letters \( t \in (0, \infty) \), \( z \in \mathbb{R} \) to denote space-time coordinates for Brownian motions and the letters \( \tau \in (0, \infty) \), \( x \in \mathbb{N} \) to denote space-time for discrete processes in continuous time.

We will use the superscript \( \star \) to denote quantities related to the endpoints of polymers; for example \( (t^\star, z^\star) \) denotes the endpoint of non-intersecting Brownian bridges, \( \tau^\star \) denotes the final time for non-intersecting up/right paths, and \( x^\star \) denotes the vertical displacement of each up/right path.

For convenience of notation, we will conflate \( k \)-tuples of space-time coordinates with their list of time and space coordinates, i.e. \( \{(t_1, z_1), \ldots, (t_k, z_k)\} \) with \( (\vec{t}, \vec{z}) \). In the same
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spir, we use the following shorthand for integrals:
\[
\int_{\tilde{r} \in \Delta_k(a,b)} \int_{\tilde{z} \in \Delta_k(c,d)^k} f(\tilde{r}, \tilde{z}) d\tilde{r} d\tilde{z} \triangleq \int_{\tilde{r} \in \Delta_k(a,b)} \int_{\tilde{z} \in \Delta_k(c,d)^k} f\left(t_1, z_1, \ldots, (t_k, z_k)\right) dz_1 \cdots dz_k dt_1 \cdots dt_k.
\]

We also use a similar shorthand for \(k\)-fold stochastic integrals against a \(1 \times 1\) dimensional white noise environment \(\xi(t, z)\), namely
\[
\int_{\tilde{r} \in \Delta_k(a,b)} \int_{\tilde{z} \in \Delta_k(c,d)^k} f(\tilde{r}, \tilde{z}) \xi^{\otimes k}(d\tilde{r}, d\tilde{z}) \triangleq \int_{\tilde{r} \in \Delta_k(a,b)} \int_{\tilde{z} \in \Delta_k(c,d)^k} f\left(t_1, z_1, \ldots, (t_k, z_k)\right) \xi(dt_1, dz_1) \cdots \xi(dt_k, dz_k).
\]

For the semi-discrete coordinates that appear (where time is continuous but space is discrete) we use the following notation:
\[
\sum_{\tilde{r} \in \Delta_k(a,b)} f(\tilde{r}, \tilde{x}) d\tilde{r} \triangleq \int_{\tilde{r} \in \Delta_k(a,b)} \sum_{\tilde{z} \in \{c, \ldots, d\}^k} f\left(\tau_1, x_1, \cdots, (\tau_k, x_k)\right) d\tau_1 \cdots d\tau_k.
\]

For stochastic integrals with respect to i.i.d. Brownian motions \(\{B_1(t), B_2(t), \ldots\}\) we use the notation
\[
\sum_{\tilde{r} \in \Delta_k(a,b)} f(\tilde{r}, \tilde{x}) dB_{x_1}(\tau_1) \cdots dB_{x_k}(\tau_k)
\]
\[
\triangleq \int_{\tilde{r} \in \Delta_k(a,b)} \sum_{\tilde{z} \in \{c, \ldots, d\}^k} f\left(\tau_1, x_1, \cdots, (\tau_k, x_k)\right) dB_{x_1}(\tau_1) \cdots dB_{x_k}(\tau_k).
\]

We use the notation \(P, E\) to refer to the probability measure and its expectation on non-intersecting random walks defined precisely in Definitions 2.4 and 2.5. In contrast, we will use the probability space \((\Omega, \mathcal{F}, P)\) for the disordered environment that our random walks go through and \(E\) for the expectation with respect to this random environment. The \(L^2(P)\) norm for mean-zero random variables on this probability space is
\[
\|Z\|_{L^2(P)} \triangleq E \left(Z^2\right)^{\frac{1}{2}}.
\]

We use \(d \in \mathbb{N}\) to denote the number of Brownian motions or up-right paths in the non-intersecting ensembles.

## 2 Definitions and proof of main results

### 2.1 Non-intersecting Brownian motions and bridges

**Definition 2.1** (Non-intersecting Brownian motions). Define the \(d\)-dimensional Weyl chamber \(W^d = \{z \in \mathbb{R}^d : z_1 \leq \ldots \leq z_d\}\). Let \(\tilde{D}(t) \in W^d, t \in (0, \infty)\) denote an ensemble of \(d\) non-intersecting Brownian motions and let \(E_{\tilde{z}^0}[]\), denote the expectation of this process started from \(\tilde{D}(0) = \tilde{z}^0\). More specifically, \(\tilde{D}(t)\) is the Markov process which is obtained from \(d\) independent Brownian motions by a Doob \(h\)-transform using the Vandermonde determinant
\[
h_d(z) \triangleq \prod_{1 \leq i < j \leq d} (z_j - z_i).
\]
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(See Section 3 of [29] for details on this $h$-transform.) We will use the following fact about this process: for any continuous function $f : \mathbb{W}^d \to \mathbb{R}$ and any $z^0 \in (\mathbb{W}^d)^o$ we have that

$$
\mathbb{E}_{z^0} \left[ f(\bar{B}(t)) \right] \leq \frac{1}{h_d(z^0)} \mathbb{E} \left[ f(\bar{B}(t) + z^0) h_d(\bar{B}(t) + z^0) 1 \{ \tau_{z^0} > t \} \right],
$$

where $\bar{B}(t)$ are $d$ independent standard Brownian motions.

**Definition 2.2** (Non-intersecting Brownian bridges). Fix $t^* > 0$ and $z^* \in \mathbb{R}$. Let $\bar{D}(t^*, z^*) \in \mathbb{W}^d, t \in [0, t^*]$ denote an ensemble of $d$ non-intersecting Brownian bridges, where each bridge starts at $D_i(0, t^*) = z_i^*$, $1 \leq i \leq d$. The process $\bar{D}(t^*, z^*)$ is constructed by starting with the process $\bar{D}(t) \in \mathbb{W}^d$ from Definition 2.1 and applying the Markovian construction of a bridge process. (See Proposition 1 of [10] and Section 2 of [24] for more details.)

Let $\psi_k(t^*, z^*) : ((t_1, z_1), \ldots, (t_k, z_k)) \in (0, t^*)^k \to \mathbb{R}$ denote the $k$-point correlation functions for this process. This is defined by:

$$
\psi_k(t^*, z^*)((t_1, z_1), \ldots, (t_k, z_k)) = \sum_{j \in \{1, \ldots, d\}^k} \rho_{j_1, \ldots, j_k}((t_1, z_1), \ldots, (t_k, z_k)),
$$

where $\rho_{j_1, \ldots, j_k}((t_1, z_1), \ldots, (t_k, z_k))$ is the probability density of the random vector $D_{j_1}(t_1)\ldots D_{j_k}(t_k)$ with respect to Lebesgue measure on $\mathbb{R}^k$ evaluated at the point $(z_1, \ldots, z_k) \in \mathbb{R}^k$.\n
**Proposition 2.3.** (Lemma 4.1 and Proposition 4.2 of [24]) For any $z^* \in \mathbb{R}, t^* > 0, k \in \mathbb{N}$, the function $\psi_k(t^*, z^*) \in L^2(\Delta_k(0, t^*) \times \mathbb{R}^k)$. Moreover for any $\beta > 0$, the following series is absolutely convergent

$$
1 + \sum_{k=1}^\infty \left\| \psi_k(t^*, z^*) \right\|_{L^2(\Delta_k(0, t^*) \times \mathbb{R}^k)}^2 < \infty.
$$

**2.2 Non-intersecting Poisson processes and non-intersecting Poisson bridges**

**Definition 2.4** (Non-intersecting Poisson processes). We denote by $\bar{X}(\tau) \in \mathbb{N}^d$, $\tau \in (0, \infty)$ an ensemble of $d$ non-intersecting Poisson processes and use $\mathbb{E}_{\tau, z^*}$ to denote the expectation over this ensemble started from the initial condition $\bar{X}(0) = \bar{z}^*$. This is the Markov process obtained by conditioning $d$ independent rate one Poisson processes not to intersect by applying a Doob $h$-transform with the Vandermonde determinant $h_d(\bar{x}) \doteq \prod_{1 \leq i < j \leq d} (x_i - x_j)$. The transition probabilities are therefore given by

$$
\mathbb{P} \left( \bar{X}(\tau') = \bar{z}' \mid \bar{X}(\tau) = \bar{z} \right) \doteq q_{\tau', \tau} (\bar{z}, \bar{z}', \bar{z}),
$$

where $q_{\tau, \bar{z}, \bar{y}}$ is the probability for $d$ iid Poisson processes to go from $\bar{z}$ to $\bar{y}$ in time $\tau$ without intersections. By the Karlin-MacGregor theorem, introduced in [15], this is given by

$$
q_{\tau, \bar{z}, \bar{z}} \doteq \det [\mu(\tau, x_i - x_j)]_{i,j=1}^d, \quad \mu(\tau, x) \doteq e^{-\tau \frac{x^2}{2}} \frac{\tau^x}{x!} 1_{x \geq 0}.
$$

**Definition 2.5** (Non-intersecting Poisson bridges). Fix $x^* \in \mathbb{N}$ and $\tau^* \in \mathbb{R}$. For $x \in \mathbb{N} \cup \{0\}$, define $\bar{\delta}_0(x) \doteq (x + 1, x + 2, \ldots, x + d) \in \mathbb{N}^d$. We denote by $\bar{X}(\tau^*, x^*)((\tau, x)) \in \mathbb{N}^d \cap \mathbb{W}^d, \tau \in (0, \tau^*)$ the ensemble of $d$ non-intersecting Poisson bridges that start at
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\[ \vec{X}(\tau, x')(0) = \vec{\delta}_d(0) \] and end at \[ \vec{X}(\tau, x')(\tau^*) = \vec{\delta}_d(x^*) \]. The measure on these processes is the conditional measure one gets by starting \( d \) independent Poisson processes from \( \vec{\delta}_d(0) \) and then conditioning on the positive probability event that there have been no intersections between them for all \( \tau \in (0, \tau^*) \) and that they end exactly at \( \vec{\delta}_d(x^*) \) at time \( \tau^* \). By the Karlin-MacGregor theorem, the transition probabilities for this Markov process are given explicitly by

\[ P \left( \vec{X}(\tau', x') = \vec{x}' \mid \vec{X}(\tau, x') = \vec{x} \right) = \frac{q_{\tau'-\tau}(\vec{x}, \vec{x}') q_{\tau^*'-\tau^*}(\vec{x}', \vec{\delta}_d(x^*))}{q_{\tau^*'-\tau}(\vec{x}, \vec{\delta}_d(x^*))} \quad \forall \tau < \tau', \]

where \( q_{\tau}(\vec{x}, \vec{y}) \) is as in Definition 2.4. Comparing this to Definition 2.4, we see that \( \vec{X}(\tau, x') \) is absolutely continuous with respect \( \vec{X}(\tau) \) started from \( \vec{X}(0) = \vec{\delta}_d(0) \) with Radon-Nikodym derivative given by

\[ \frac{P \left( \vec{X}(\tau', x') = \vec{x}' \right)}{P \left( \vec{X}(\tau) = \vec{x} \right)} = \frac{q_{\tau'-\tau}(\vec{x}, \vec{\delta}_d(x^*))}{q_{\tau}(\vec{x}, \vec{\delta}_d(x^*))} h_d \left( \vec{\delta}_d(0) \right). \]

**Remark 2.6.** Due to Poisson processes conditioned on their final position taking the uniform measure, the measure on Poisson bridges \( \vec{X}(\tau, x') \) in Definition 2.5 is exactly the same as the measure proportional to the Lebesgue measure over non-intersecting up/right paths described in Definition 1.1. It is more convenient to think of this process as a Poisson bridge because the relationship to the non-intersecting Poisson process \( \vec{X}(\cdot) \) from Definition 2.4 is used as an intermediate step in the proof of our results.

### 2.3 Iterated stochastic integrals

In this section we will show how the partition function \( Z^\beta_\kappa(\tau, x^*) \) can be identified as a chaos series of iterated stochastic integrals against Brownian motions.

**Definition 2.7.** Consider an infinite family \( \{B_i(\cdot)\}_{i=1}^{\infty} \) of independent standard Brownian motions on the probability space \((\Omega, \mathcal{F}, \mathbb{P})\). For \( \tau^* > 0 \) and \( x^* \in \mathbb{N} \) and any ensemble of up/right paths \( \vec{X}(\tau) \in \{1, \ldots, x^* + d\}^d, \tau \in [0, \tau^*] \) define the \( k \)-fold stochastic integral \( I_k^\vec{X} \) by:

\[ I_k^\vec{X}(\tau) = \oint_{\vec{X} \in \{1, \ldots, x^* + d\}^k} \prod_{i=1}^k 1 \left\{ x_i \in \vec{X}(\tau_i) \right\} dB_{x_1}(\tau_1) \ldots dB_{x_k}(\tau_k), \]

where we recall the notation for semi-discrete sums from Section 1.4. Let \( \mathbb{P} \) denote the probability w.r.t. non-intersecting Poisson bridges \( \vec{X}(\tau, x') \) described in Definition 2.5. Define the \( k \)-fold stochastic integral \( EI_k^\vec{X}(\tau, x') \) by:

\[ EI_k^\vec{X}(\tau, x') = \oint_{\vec{X} \in \{1, \ldots, x^* + d\}^k} \prod_{i=1}^k \mathbb{P} \left( \bigcap_{i=1}^k \left\{ x_i \in \vec{X}(\tau, x') \right\} \right) dB_{x_1}(\tau_1) \ldots dB_{x_k}(\tau_k). \]

**Remark 2.8.** Note that from the theory of iterated stochastic integrals (see e.g. Chapter 7 of [12]), we have the following Itô isometry between \( L^2(\mathbb{P}) \) and \( L^2(\Delta_k(0, \tau^*) \times \mathbb{N}^k) \) for these stochastic integrals (see e.g. Theorem 7.6 in [12]):

\[ \mathbb{E} \left[ I_k^\vec{X}(\tau) I_j^\vec{X}(\tau) \right] = \delta_{j,k} \oint_{\vec{X} \in \{1, \ldots, x^* + d\}^k} \prod_{i=1}^k 1 \left\{ x_i \in \vec{X}(\tau_i) \right\}^2 d\tau_1 \ldots d\tau_k, \quad (2.1) \]

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The change of order of sum and expectation is justified by the monotone convergence variable which is specified in Definition 4.1:
\[ \sum_{x=1}^{x^*+d} 1 \{ x \in \bar{X}(\tau^*,x^*) (\tau) \} = d \ a.s \text{ for every fixed } \tau \text{ and by an application of the Itô isometry from equation (2.1)}.

Lemma 2.9. For any $\tau^* > 0$ and $x^* \in \mathbb{N}$ we have that
\[ \left\| I_k \left( \bar{X}(\tau^*,x^*) \right) (\tau) \right\|^2_{L^2(\mathcal{P})} = \frac{(d\tau)^k}{k!}. \]

Proof. This holds since $\sum_{x=1}^{x^*+d} 1 \{ x \in \bar{X}(\tau^*,x^*) (\tau) \} = d \ a.s \text{ for every fixed } \tau$ and by an application of the Itô isometry from equation (2.1).

Lemma 2.10. For any $\tau^* > 0$, $x^* \in \mathbb{N}$ and $\beta > 0$ we have that
\[ \sum_{k=0}^{\infty} \beta^k \left\| E I_k(\tau^*,x^*) (\tau) \right\|^2_{L^2(\mathcal{P})} \leq \exp (d\beta \tau). \]

Proof. By using the Itô isometry from equation (2.1), and the inequality from Corollary 5.3, we can now bound the $L^2(\mathcal{P})$ norm by the $k$-th moment of the overlap time random variable which is specified in Definition 4.1:
\[ \sum_{k=0}^{\infty} \beta^k \left\| E I_k(\tau^*,x^*) (\tau) \right\|^2_{L^2(\mathcal{P})} \leq \sum_{k=0}^{\infty} \beta^k \mathbb{E} \left[ \left( O(\tau^*,x^*) (0,\tau) \right)^k \right] = \mathbb{E} \left[ \exp \left( \beta O(\tau^*,x^*) (0,\tau) \right) \right]. \]

The change of order of sum and expectation is justified by the monotone convergence theorem since the overlap time is always non-negative. The result then follows by the simple bound that $O(\tau^*,x^*) (0,\tau) \leq d\tau$ which is immediate from Definition 4.1.

Lemma 2.11. Let $E$ denote the expectation over non-intersecting Poisson bridges $\bar{X}(\tau^*,x^*)$ described in Definition 2.5. Recall the definition of $I_k$ and $EI_k$ from Definition 2.7. We have the following equality (as random variables in $L^2(\mathcal{P})$):
\[ E I_k \left( \bar{X}(\tau^*,x^*) \right) (\tau) = EI_k(\tau^*,x^*) (\tau). \]

Proof. The result amounts to an interchange of the order of the stochastic integration and the expectation $E$. This is justified by a stochastic Fubini theorem for multiple stochastic integrals: see Theorem 5.13.1 in [26]. The required integrability condition is clear in this case since the integrand, $\prod_{i=1}^{\infty} 1 \{ x_i \in \bar{X}(\tau_i) \}$, is non-negative and bounded above by 1.

Lemma 2.12. We have the following equality (as random variables in $L^2(\mathcal{P})$):
\[ E \left[ \sum_{k=0}^{\infty} \beta^k I_k \left( \bar{X}(\tau^*,x^*) \right) (\tau) \right] = \sum_{k=0}^{\infty} \beta^k EI_k(\tau^*,x^*) (\tau). \]

Proof. First notice that the infinite series from (2.2) is guaranteed to converge by the estimate from Lemma 2.10. To see the equality, we will show that given any $\epsilon > 0$, the difference between the LHS and the RHS of equation (2.2) has an $L^2(\mathcal{P})$ norm less than $\epsilon$. Given such an $\epsilon > 0$, we first find an $M \in \mathbb{N}$ so that $\left\| E \left[ \sum_{k=M}^{\infty} \beta^k I_k \left( \bar{X}(\tau^*,x^*) \right) (\tau) \right] \right\|_{L^2(\mathcal{P})} < \epsilon$ and $\left\| \sum_{k=M}^{\infty} \beta^k EI_k(\tau^*,x^*) (\tau) \right\|_{L^2(\mathcal{P})} < \epsilon$. This can be achieved since we have
\[ \left\| E \left[ \sum_{k=M}^{\infty} \beta^k I_k \left( \bar{X}(\tau^*,x^*) \right) (\tau) \right] \right\|^2_{L^2(\mathcal{P})} \leq \sum_{k=M}^{\infty} \mathbb{E} \left[ \left( \beta^k I_k \left( \bar{X}(\tau^*,x^*) \right) (\tau) \right) \right]^2, \]
by an application of Jensen’s inequality, Tonelli’s theorem, and the fact that the individual terms $I_k$ are orthogonal in $L^2(\mathcal{E})$. Thus we can find such an $M \in \mathbb{N}$ to bound this above by $\epsilon$, since we recognize this is as the tail of an absolutely convergent series by an application of Lemma 2.9. A similar result holds for $\left\| \sum_{k=M}^{\infty} \beta^k E I_k^{(\tau^*, x^*)}(\tau) \right\|_{L^2(\mathbb{P})}$ since the stochastic integrals $\{ E I_k^{(\tau^*, x^*)} \}_{k \in \mathbb{N}}$ are orthogonal in $L^2(\mathbb{P})$, and since the sum $\sum_{k=0}^{\infty} \beta^k \left\| E I_k^{(\tau^*, x^*)} \right\|_{L^2(\mathbb{P})}^2$ also is convergent by Lemma 2.10. Once such an $M$ is chosen, we have by the triangle inequality and Lemma 2.11 applied to the first $M$ terms that

$$\left\| \mathbb{E} \left[ \sum_{k=0}^{\infty} \beta^k I_k \left( \mathcal{X}^{(\tau^*, x^*)}_i \right) (\tau) \right] - \sum_{k=0}^{M} \beta^k E I_k^{(\tau^*, x^*)}(\tau) \right\|_{L^2(\mathbb{P})} \leq 0 + \epsilon + \epsilon.$$ 

Since this holds for any $\epsilon > 0$, this completes the proof. \hfill \Box

**Lemma 2.13.** Recall the semi-discrete polymer partition function $Z^\beta_d$ from Definition 1.1. It is possible to realize the partition functions $Z^\beta_d$ as the following infinite chaos series:

$$Z^\beta_d (\tau^*, x^*) \exp \left( -\frac{d}{2} \tau^* \beta^2 \right) = \sum_{k=0}^{\infty} \beta^k E I_k^{(\tau^*, x^*)}.$$ 

**Proof.** Recall the definition of the energy of the $i$-th line $H \left( X_i^{(\tau^*, x^*)} \right)$ from equation (1.3). For any fixed path $X_i$, we notice by the Itô isometry that $H \left( X_i^{(\tau^*, x^*)} \right)$ is a Gaussian random variable of mean 0 and variance $\tau^*$. Moreover, by the non-intersecting condition, the energies $H \left( X_i^{(\tau^*, x^*)} \right)$ and $H \left( X_j^{(\tau^*, x^*)} \right)$ are independent when $i \neq j$, so the sum $\beta \sum_{i=1}^{d} H \left( X_i^{(\tau^*, x^*)} \right)$ is a Gaussian with mean 0 and variance $d\beta^2 \tau^*$. We now apply the relationship between exponential of Gaussians and the Wick exponential, $e^\xi := e^{\xi - E[\xi^2/2]}$ (see Theorem 3.3 and the definition of the Wick exponential in [12]). This gives

$$\mathbb{E} \left[ \exp \left( \beta \sum_{i=1}^{d} H \left( X_i^{(\tau^*, x^*)} \right) \right) \right] \exp \left( -\frac{d}{2} \beta^2 \tau^* \right) = \mathbb{E} \left[ \exp \left( \beta \sum_{i=1}^{d} H \left( X_i^{(\tau^*, x^*)} \right) \right) \right].$$

Since each $H \left( X_i^{(\tau^*, x^*)} \right)$ is a single stochastic integral, the Wick exponential is given by the chaos series (see Theorem 7.3 from [12]):

$$\exp \left( \beta \sum_{i=1}^{d} H \left( X_i^{(\tau^*, x^*)} \right) \right) = \sum_{k=0}^{\infty} \beta^k I_k \left( \mathcal{X}^{(\tau^*, x^*)}_i \right) (\tau).$$

The desired result then follows by application of the interchange of infinite sum and expectation from Lemma 2.12. \hfill \Box

**2.4 1+1 dimensional white noise**

In this section we will couple the semi-discrete partition function $Z^\beta_d$ to the continuum polymer $Z^\beta_c$. This is achieved by constructing the Brownian motions that define $Z^\beta_c$ from integrals of the white noise environment (see [12] for the background on these integrals). This coupling approach is also used in [4] in the proof of convergence of the single-line (i.e. $d = 1$) semi-discrete polymer to the continuum random polymer.
Let Lemma 2.15. By the Itô isometry, since the area of the region in (2.4) defines a Gaussian random variable, that the increments for disjoint

By properties of the 1+1 dimensional white noise, we also observe that the integral on the

\( S \) and denote by \( \varphi \) is constant on cells of the form \( I \) for every

Any function \( f: (S^{(N)})^k \to \mathbb{R} \) can be extended to a function \( f: ((0, \infty) \times \mathbb{R})^k \to \mathbb{R} \) by declaring that \( f \) is constant on cells of the form \( I^{(N)}(t_1, z_1) \times \ldots \times I^{(N)}(t_k, z_k) \) for every \( (t_1, z_1, \ldots, t_k, z_k) \in S^{(N)} \). Note that, since \( f \) is constant on these cells, we have

\[
\int_{\vec{r} \in \Delta_b(a, b)} f(\vec{r}) d\vec{r} = N^{-3/4} \int_{\vec{r} \in B \Delta_b(Na, Nb)} f\left(\frac{\tau_1}{N}, \frac{x_1 - \tau_1}{\sqrt{N}}\right) \ldots \left(\frac{\tau_k}{N}, \frac{x_k - \tau_k}{\sqrt{N}}\right) d\vec{r}. \tag{2.3}
\]

Lemma 2.15. Let \( \xi(t, z) \) be a 1+1 dimensional white noise field. For each \( N \in \mathbb{N} \), we may couple an infinite family of iid standard Brownian motions \( \{B^{(N)}_{x}\}_{x \in \mathbb{N}} \) to the white noise field \( \xi \) by the prescription that:

\[
B^{(N)}_{x}(\tau) \overset{d}{=} N^{3/4} \int_{\varphi^{(N)}((0, \tau) \times [x, x+1])} \xi(dt, dz). \tag{2.4}
\]

Proof. By the Itô isometry, since the area of the region \( \varphi^{(N)}((\tau, \tau') \times [x, x+1]) \) is

\[
\text{Var} \left( B^{(N)}_{x}(\tau') - B^{(N)}_{x}(\tau) \right) = \left( N^{3/4} \right)^2 N^{-3/2} (\tau' - \tau) = \tau' - \tau.
\]

By properties of the 1+1 dimensional white noise, we also observe that the integral on the

Figure 2: The map \( \varphi^{(N)} \) sends non-intersecting paths \( X^{(N)}(\tau, x^*) \) to their rescaled and compensated version \( X^{(N), (\tau', z^*)} \) when \( \tau^* = Nt^* \) and \( x^* = \left[ Nt^* + \sqrt{N}z^* \right] \). The vertical spacing between lines in the image is \( N^{-\frac{1}{2}} \).
time intervals are independent, and that the process $B^{(N)}_x(\cdot)$ admits a modification which has almost surely continuous sample paths. Hence it must be that $B^{(N)}_x$ is a Brownian motion, as desired. The fact that $B^{(N)}_x$ is independent of $B^{(N)}_y$ for $x \neq y$ is clear because the regions $\varphi^{(N)}((0, \tau) \times [x, x + 1])$ and $\varphi^{(N)}((0, \tau) \times [x', x' + 1])$, define disjoint regions in the integration.

**Definition 2.16.** For $t^* > 0$ and $z^* \in \mathbb{R}$, we will define the rescaled (and compensated) non-intersecting Poisson processes by:

$$\tilde{X}^{(N),(t^*,z^*)}(t) \triangleq \frac{1}{\sqrt{N}} \left( \tilde{X}^{(N^*),(\lfloor N^* + \sqrt{N}z^* \rfloor)}(Nt) - Nt \right).$$

See Figure 2 for an illustration of these processes. Define the rescaled $k$-point correlation function for $\psi^{(N),,(t^*,z^*)}_k : (S^{(N)})^k \to \mathbb{R}$ by defining for $k$-tuples $((t_1, z_1), \ldots, (t_k, z_k)) \in (S^{(N)})^k$ where all the entries $(t_i, z_i)$ are distinct:

$$\psi^{(N),,(t^*,z^*)}_k(t_i, z_i) \triangleq \sqrt{N^k} \sum_{j \in \{1, \ldots, d\}^k} \mathbb{P} \left( \bigcap_{i=1}^k \left\{ z_i = X^{(N),,(t^*,z^*)}(t_i) \right\} \right),$$

and declaring that $\psi^{(N),,(t^*,z^*)}_k \triangleq 0$ if any of the space-time coordinates are duplicated $(t_i, z_i) = (t_j, z_j)$ for $i \neq j$. We extend the domain of $\psi^{(N),,(t^*,z^*)}_k$ to all of $((0, t^*) \times \mathbb{R})^k$ as in Definition 2.14 by declaring it to be constant on the cells $I^{(N)}(t_1, z_1) \times \cdots \times I^{(N)}(t_k, z_k)$ for every $((t_1, z_1), \ldots, (t_k, z_k)) \in S^{(N)}$. Notice that because $\psi^{(N),,(t^*,z^*)}_k$ is constant on these cells, any integral of $\psi^{(N),,(t^*,z^*)}_k$ can be decomposed into a semi-discrete sum as in equation (2.3).

**Lemma 2.17.** Fix $t^* > 0$ and $z^* > 0$. Let $\xi$ be a 1+1 dimensional white noise environment. Recall that for each $N \in \mathbb{N}$, we may couple an infinite collection of iid Brownian motions $B^{(N)}_x$ to this probability space by the prescription from Lemma 2.15. If we use the Brownian motions $B^{(N)}_x$ to define the iterated stochastic integral $EI^{(N^*),(\lfloor N^* + \sqrt{N}z^* \rfloor)}_k$ from Definition 2.7, then we have

$$EI^{(N^*),(\lfloor N^* + \sqrt{N}z^* \rfloor)}_k(Nt) = N^k \int_{\mathbb{R}^2} \phi_{\psi^{(N),,(t^*,z^*)}_k}(t, z) \xi(d\tilde{t}, d\tilde{z}).$$

**Proof.** The identity is immediate from Definition 2.7 and Definition 2.16 using the fact that $\psi^{(N),,(t^*,z^*)}_k$ is constant on intervals of the form $I^{(N)}(t, z)$.

**Remark 2.18.** Note that the power of $N^{k+\frac{1}{2}}$ arises from multiplying the $N^k$ from the definition of the Brownian motion in the coupling Lemma 2.15, and the $N^{-\frac{1}{2}}$ in the rescaling of $\psi^{(N),,(t^*,z^*)}_k$ in Definition 2.16.

### 2.5 Convergence of chaos series – Proof of Theorem 1.2

In addition to the $L^2$ convergence result of Theorem 1.5, and the set up of the coupling from the previous subsection, we will need the following proposition:
With this setup, by combining Lemma 2.13 and Lemma 2.17, and by equation (1.1), we define \( \psi \) and \( \beta \), namely:

\[
Z(\beta, \epsilon) \quad \text{to be as defined as in the coupling from Lemma 2.15, and define for each } k \in \mathbb{N} \text{ the } k\text{-fold stochastic integrals:}
\]

\[
J_k^{(N)} = \sum_{\vec{t} \in \Delta_k(0, t^*)} \sum_{z} \psi_k^{(N)}(\vec{t}^*, z^*) \cdot (d\vec{t}, dz), \\
J_k = \sum_{\vec{t} \in \Delta_k(0, t^*)} \sum_{z} \psi_k(\vec{t}^*, z^*) \cdot (d\vec{t}, dz).
\]

With this setup, by combining Lemma 2.13 and Lemma 2.17, and by equation (1.1), we recognize the quantities of interest as the following infinite series:

\[
Z_d^\beta \left( Nt^*, \frac{Nt^* + \sqrt{N}z^*}{2} \right) = \exp \left( \frac{1}{2} \beta \right) \sum_{k=0}^{\infty} (N^{1/2} \beta N)^k J_k^{(N)} + \frac{Z_d^\beta (t^*, z^*)}{\beta (t^*, z^*)} = \sum_{k=0}^{\infty} \beta^k J_k. \quad (2.6)
\]

The desired result is hence reduced to the convergence as \( N \to \infty \) of the chaos series in equation (2.6). It suffices to show the convergence in the simpler case when \( N^{1/2} \beta N = \beta \), since the hypothesis \( N^{1/2} \beta N \to \beta \) and Proposition 2.19 guarantee the error made by this replacement can be made arbitrarily small.

Notice by the Itô isometry for 1+1 dimensional white noise that these stochastic integrals are naturally related to the \( L^2(\Delta_k(0, t^*) \times \mathbb{R}^k) \) norm of the functions \( \psi_k(\vec{t}^*, z^*) \) and \( \psi_k^{(N)}(\vec{t}^*, z^*) \), namely:

\[
\left\| J_k^{(N)} - J_k \right\|_{L^2(\mathbb{R}^k)} = \left\| \psi_k^{(N)}(\vec{t}^*, z^*) - \psi_k(\vec{t}^*, z^*) \right\|_{L^2(\Delta_k(0, t^*) \times \mathbb{R}^k)}. \quad (2.7)
\]

It is clear then for each fixed \( k \in \mathbb{N} \), that \( J_k^{(N)} \to J_k \) in \( L^2(\mathbb{R}^k) \) by the convergence result from Theorem 1.5. It remains only to justify why the convergence of each individual term in the series in equation (2.6) gives convergence of the full series.

To see this, take any \( \epsilon > 0 \), and use the convergence results of Propositions 2.19 and Proposition 2.3 along with the Itô isometry to find \( N_{\beta, \epsilon} \in \mathbb{N} \) and \( \ell_{\beta, \epsilon} \in \mathbb{N} \) so large so that

\[
\sup_{N > N_{\beta, \epsilon}} \sum_{k=0}^{\ell_{\beta, \epsilon}} \beta^k J_k^{(N)} \to \frac{1}{L^2(\mathbb{R}^k)} \sum_{k=0}^{\ell_{\beta, \epsilon}} \beta^k J_k \epsilon^2 < \epsilon.
\]
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\[
\sum_{k = 1}^{\infty} \left\| \beta k J_k \right\|^2_{L^2(P)} = \sum_{k = 1}^{\infty} \beta^{2k} \left\| \psi_k(t^*, z^*) \right\|^2_{L^2(\Delta(0, t^*) \times \mathbb{R}^k)} < \epsilon.
\]

With this choice, we have finally by the triangle inequality in \(L^2(P)\), and the termwise convergence observed in equation (2.7), that

\[
\lim_{N \to \infty} \left\| \sum_{k = 1}^{\infty} \beta k J_k^{(N)} - \sum_{k = 1}^{\infty} \beta k J_k \right\|_{L^2(P)} < 2\epsilon.
\]

Since this holds for any \(\epsilon > 0\), we have the desired convergence in \(L^2(P)\).

The \(L^2(P)\) convergence proven directly implies \(L^p(P)\) convergence for \(1 \leq p \leq 2\). To see the convergence in \(L^p(P)\) for \(p > 2\), we first use the hypercontractivity of a fixed Wiener chaos to see that there is a constant \(c_p\) so that stochastic integrals \(J_k^{(N)}\) and \(J_k\) have\(^1\):

\[
\left\| J_k^{(N)}(t^*) \right\|^2_{L^p(P)} \leq c_p \left\| \psi_k(t^*) \right\|^2_{L^2(\Delta(0, t^*) \times \mathbb{R}^k)},
\]

\[
\left\| J_k \right\|^2_{L^p(P)} \leq c_p \left\| \psi_k(t^*) \right\|^2_{L^2(\Delta(0, t^*) \times \mathbb{R}^k)}.
\]

Hence, the infinite series \(\sum_{j=1}^{\infty} \beta k J_k\) is seen to have finite \(L^p(P)\) norm by Proposition 2.3, and by Proposition 2.19, we can find \(N_p, \beta \in \mathbb{N}\) large enough so that the infinite series from equation (2.6) has \(L^p\) norm which is uniformly bounded:

\[
\sup_{N > N_p, \beta} \left\| \sum_{k = 1}^{\infty} \beta k J_k^{(N)} \right\|_{L^p(P)} \leq \sup_{N > N_p, \beta} \sum_{k = 1}^{\infty} (\beta c_p)^k \left\| \psi_k(t^*, z^*) \right\|^2_{L^2(\Delta(0, t^*) \times \mathbb{R}^k)} < \infty.
\]

Since these norms are finite for any \(p\), we now apply the Holder inequality in the form

\[
\left\| \sum_{k = 1}^{\infty} \beta k J_k^{(N)} - \sum_{k = 1}^{\infty} \beta k J_k \right\|_{L^p(P)} \leq \left\| \sum_{k = 1}^{\infty} \beta k J_k^{(N)} - \sum_{k = 1}^{\infty} \beta k J_k \right\|^{1/p}_{L^2(P)} \left\| \sum_{k = 1}^{\infty} \beta k J_k^{(N)} - \sum_{k = 1}^{\infty} \beta k J_k \right\|^{(p-1)/p}_{L^{p-1}(P)},
\]

from which the \(L^p(P)\) convergence follows from the \(L^2(P)\) convergence and the uniform bound on the \(L^{2(p-1)}\) norm in equation (2.9).

\[\square\]

2.6 Proof of Corollary 1.7

**Lemma 2.20.** Recall from Definition 1.6 that \(D_d^{(M)}(t) \subset \mathbb{R}^{(M - d)d}\) denotes the set of jump times for \(d\) non-intersecting up/right paths that start at \(X_i(0) = i\) and end at \(X_i(t) = M - d + i\) for \(1 \leq i \leq d\). The Lebesgue measure of this set is:

\[
\mathcal{L} \left( D_d^{(M)}(t) \right) = \frac{d!}{M - d + i}.
\]

**Proof.** The jump times of such a non-intersecting ensemble are in bijection with pairs \((S, \tilde{t})\), where \(\tilde{t} \in \Delta(M - d)d(0, t)\) is the ordered list of all the jump times for the ensemble, and \(S\) is a standard Young tableau of rectangular shape \(d\) by \(M - d\) that indicates

\[\footnote{The same idea is used in a similar setting in Lemma 2.3 in \[19\] and can be proven by applying the Burkholder-Davis-Gundy inequality \(k\) times. See also Theorem 5.10 in \[12\].} \]

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which jump times correspond to which path (i.e. the first row of $S$ indicates the jump times of the top most up/right path and so on; see Section 2 of [22] for more details on this bijection). The Lebesgue measure of $\Delta_{(M-d)d}(0, t)$ is \(t^{(M-d)d}(d(M-d))^{-1}\) and the number of standard tableaux of this shape is \((d(M-d))! \prod_{i=0}^{d-1} \frac{n!}{(M-d+i)!}\) (this is a direct application of the hook-length formula: see Corollary 7.2.14 in [28] or [27]). Combining this gives the desired result. \(\square\)

**Lemma 2.21.** Fix any $d \in \mathbb{N}$, $t > 0$, and $z \in \mathbb{R}$. Let $C(M, t, z)$, $c_d^{−1}$ and $Z_d^M$ be as in Corollary 1.7. Then:

$$\lim_{M \to \infty} \mathcal{E}(Z_d^M) = c_d^{−1} \rho(t, z)^d.$$ (2.11)

**Proof.** Let $\sim$ denote asymptotic equality as $M \to \infty$, i.e. $f(M) \sim g(M)$ if and only if $f(M) = g(M)(1 + o(1))$ as $M \to \infty$. By using the connection from equation (1.6) between $Z_d^M$ and $Z_d^\beta(\tau^*, x^*)$ when $\beta = 1$, $\tau^* = \sqrt{M} + z$ and $x^* = M - d$ we have then:

$$\mathcal{E}(Z_d^M) = \mathcal{E}(\sqrt{M} \sum_{i=0}^{d} d) \cdot \exp \left( \frac{d}{2} \sqrt{M} + z \right) C(M, t, z)^{−d}$$

$$= \left( \sqrt{M} + z \right)^{(M-d)d-1} \prod_{i=0}^{d} \left( \frac{i!}{(M-d+i)!} \right) \exp \left(-dM - dz \sqrt{M} \right) \left( \sqrt{M} + z \right)^{M^d},$$

where the factor of $\exp(\frac{d}{2} \sqrt{M} + z)$ is canceled due to contributions from $C(M, t, z)^{−d}$. We now use $\left( \sqrt{M} + z \right)^{(M-d)d} \sim \sqrt{M}^{(M-d)d} \exp \left( dz \sqrt{M} \right) \exp \left(-\frac{z^2}{2t} \right)^d$ to further simplify:

$$\mathcal{E}(Z_d^M) \sim \sqrt{M}^{(M-d)d} \left( \sqrt{2\pi MM^{d} \exp (-M)} \right)^d \exp \left(-\frac{z^2}{2t} \right)^d \prod_{i=0}^{d} \left( \frac{i!}{(M-d+i)!} \right).$$

We now use Stirling’s formula $\sqrt{2\pi MM^{d} \exp (-M)} \sim M!$ to get:

$$\mathcal{E}(Z_d^M) \sim \frac{1}{\sqrt{2\pi MM^{d}}} \exp \left(-\frac{z^2}{2t} \right)^d \prod_{i=0}^{d} \left( \frac{M+i!}{(M-d+i)!} \right).$$

Since $M!((M-j)!)^{-1} \sim M^j$, we see that the powers of $M$ vanish, and we remain with the desired result of equation (2.11). \(\square\)

**Proof.** (Of Corollary 1.7) Define the scaling parameter $N$, and the parameter $\beta_N$ by

$$N \triangleq \frac{M}{t} - \frac{z}{\sqrt{2\pi}} \sqrt{M}$$

$$\beta_N \triangleq \sqrt{\frac{t}{M}} \left(1 + \frac{t}{N}\right)^{-1/2}$$

With this definition, the limit $N \to \infty$ is the same as the limit $M \to \infty$. Notice also that $\lim_{N \to \infty} N^\frac{1}{2} \beta_N = 1$ by this definition. Define also the shorthands $\tau^* \triangleq \sqrt{M} + z$ and $x^* \triangleq M - d$ and $y \triangleq \frac{\tau^* - tN}{\sqrt{N}}$. Observe the following limit as $M \to \infty$:

$$\lim_{M \to \infty} y = \lim_{M \to \infty} \frac{M - d - tN}{\sqrt{N}} = \lim_{M \to \infty} \frac{-d + \sqrt{M}}{\sqrt{M} + \frac{z}{\sqrt{2\pi}} \sqrt{M}} = \frac{z}{\sqrt{2\pi}}.$$

(2.12)
Now, by the relation from equation (1.6), we have that:
\[
Z^M_{d}(z) = C(M, t, z)^{-d} \mathcal{E} \left( D^{(M)}_{d}(\tau^*) \right) Z_{d}(\tau^*, x^*)
\]
= \mathcal{E} \left( Z^{M}_{d} \right) Z_{d}(\tau^*, x^*) \exp \left( -\frac{d}{2} \tau^* \right).
\]

We now use the following general Gaussian scaling relation for \( Z^2_d \), that \( Z^2_d(s, y) \cong Z^2_d(\beta^{-2} s, y) \). This holds because rescaling both time and the inverse temperature parameter leaves the chaos parameter invariant. We can hence write
\[
Z^{M}_{d}(z) \cong \mathcal{E} \left( Z^{M}_{d} \right) Z^{N\beta}_{d}(\beta^{-2} \tau^*, x^*) \exp \left( -\frac{d}{2} \frac{\tau^*}{tN} tN \right)
\]
= \mathcal{E} \left( Z^{M}_{d} \right) Z^{N\beta}_{d}(tN, [tN + y\sqrt{N}]) \exp \left( -\frac{d}{2} \beta^2 N tN \right),
\]
since \( \beta^{-2} \tau^* = tN \). The desired result then follows by the convergence of equation (2.12), Theorem 1.2 and Lemma 2.21.

### 2.7 \( L^2 \) convergence – Proof of Theorem 1.5

The main technical result that was needed in the proof of Theorem 1.2 was the \( L^2 \) convergence from Theorem 1.5. This is proven by a similar general strategy as the proof of Theorem 1.13 from [6], which was an analogous convergence result for non-intersecting simple random walks rather than non-intersecting Poisson processes. There are several additional complications in this case due to the fact that the processes here evolve in continuous time. The proof goes by dividing the set of space-time coordinates \( \Delta_k(0, t^*) \times \mathbb{R}^k \) into four parts and analyzing contribution to the \( L^2 \) norm on each one separately.

**Definition 2.22.** Fix any \( t^* > 0 \) and \( k \in \mathbb{N} \). For any \( \eta > 0 \), define the set \( S^k_\eta \subseteq \Delta_k(0, t^*) \) by:
\[
S^k_\eta = \left\{ \bar{t} \in \Delta_k(0, t^*) : t_{i+1} - t_i > \eta \forall 1 \leq i \leq k - 1 \right\}
\]
For any parameters \( \delta, \eta, M > 0 \), we subdivide \( \Delta_k(0, t^*) \times \mathbb{R}^k \) into the following four sets:
\[
\begin{align*}
D_1(\delta, \eta, M) &\triangleq \left\{ (\bar{t}, \bar{z}) : \bar{t} \in \Delta_k(0, t^*) - \delta \cap S^k_\eta, \bar{z} \in [-M, M]^k \right\}, \\
D_2(\delta, \eta, M) &\triangleq \left\{ (\bar{t}, \bar{z}) : \bar{t} \in \Delta_k(0, t^*) - \delta \cap S^C_\eta, \bar{z} \in [-M, M]^k \right\}, \\
D_3(\delta) &\triangleq \left\{ (\bar{t}, \bar{z}) : \bar{t} \in \Delta_k(0, t^*) \setminus \Delta_k(0, t^* - \delta), \bar{z} \in \mathbb{R}^k \right\}, \\
D_4(M) &\triangleq \left\{ (\bar{t}, \bar{z}) : \bar{t} \in \Delta_k(0, t^*), \bar{z} \in \mathbb{R}^k \setminus [-M, M]^k \right\}.
\end{align*}
\]
The set \( D_1(\delta, \eta, M) \) can be thought of as the “typical” part of the space \( \Delta_k(0, t^*) \times \mathbb{R}^k \) while the sets \( D_2(\delta, \eta, M), D_3(\delta) \) and \( D_4(M) \) can be thought of as “exceptional” sets. This subdivision is chosen in order to make \( D_1(\delta, \eta, M) \) a compact set on which the function \( \psi^{(N)}_{k}(t^*, z^*) \) has no singularities. This essentially reduces \( L^2 \) convergence on \( D_1(\delta, \eta, M) \) to proving pointwise convergence on \( D_1(\delta, \eta, M) \). All of the singularities/non-compactness issues occur on the exceptional sets \( D_2(\delta, \eta, M), D_3(\delta) \) and \( D_4(M) \) where we will separately argue that they have a negligible contribution to the \( L^2 \) norm in (1.5). With this strategy in mind, the core of the proof of Theorem 1.5 is divided into Propositions 2.24, 2.25, 2.26 and 2.27; each Proposition handles one of these four sets.

**Remark 2.23.** These propositions are very similar to Propositions 2.19, 2.20, 2.21 and 2.22 from [6]. Here \( \psi^{(N)}_{k}(t^*, z^*) \) is the \( k \)-point correlation function for Poisson processes,
while in [6] simple symmetric random walks were studied. Propositions 2.24 and 2.25 are proven in Section 3 using methods involving orthogonal polynomials. Propositions 2.26 and 2.27 are proven in Section 5 using the machinery of overlap times and weak exponential moment control developed in Section 4.

**Proposition 2.24.** Fix $t^*>0, z^* \in \mathbb{R}$. For all $\delta, \eta, M > 0$, we have pointwise convergence
\[
\lim_{N \to \infty} \psi^{(N)}_k(t^*,z^*) (\bar{t}, \bar{z}) = \psi_k^{(t^*,z^*)} (\bar{t}, \bar{z}),
\]
and the convergence is uniform over all $(\bar{t}, \bar{z}) \in D_1 (\delta, \eta, M)$. Moreover, there is a constant $C_{D_1} = C_{D_1} (\delta, \eta, M)$ so that for all $(\bar{t}, \bar{z}) \in D_1 (\delta, \eta, M)$ we have:
\[
\sup_N \psi^{(N)}_k(t^*,z^*) (\bar{t}, \bar{z}) \leq C_{D_1}, \quad \psi^{(t^*,z^*)}_k (\bar{t}, \bar{z}) \leq C_{D_1}.
\]

**Proposition 2.25.** Fix $t^*>0, z^* \in \mathbb{R}$. For all $\epsilon, M > 0$, there exists $\eta > 0$ small enough so that:
\[
\limsup_{N \to \infty} \sup_{D_2 (\delta, \eta, M)} \left| \psi^{(N)}_k(t^*,z^*) (\bar{t}, \bar{z}) \right|^2 d\bar{t} d\bar{z} < \epsilon.
\]

**Proposition 2.26.** Fix $t^*>0, z^* \in \mathbb{R}$. For all $\epsilon > 0$, there exists $\delta > 0$ small enough so that:
\[
\limsup_{N \to \infty} \sup_{D_3 (\delta)} \left| \psi^{(N)}_k(t^*,z^*) (\bar{t}, \bar{z}) \right|^2 d\bar{t} d\bar{z} < \epsilon
\]

**Proposition 2.27.** Fix $t^*>0, z^* \in \mathbb{R}$. For all $\epsilon > 0$, there exists $M > 0$ large enough so that:
\[
\limsup_{N \to \infty} \sup_{D_4 (M)} \left| \psi^{(N)}_k(t^*,z^*) (\bar{t}, \bar{z}) \right|^2 d\bar{t} d\bar{z} < \epsilon
\] (2.13)

**Proof.** (Of Theorem 1.5) Once Propositions 2.24, 2.25, 2.26 and 2.27 are established, the proof is identical to the proof of Theorem 1.13 in [6]. The strategy of the proof goes by first choosing $\delta, \eta, M > 0$ so that the contribution on the exceptional sets $D_2 (\delta, \eta, M)$, $D_3 (\delta)$ and $D_4 (M)$ are less than $\epsilon$, and once $\delta, \eta, M$ are fixed, using Proposition 2.24 to establish $L^2$ convergence on the typical set $D_1 (\delta, \eta, M)$. \(\square\)

3 Determinantal kernels and orthogonal polynomials

In this section we prove Proposition 2.24 and Proposition 2.25 by using the determinantal structure of the non-intersecting processes. The methods used here are similar to those from Section 3 of [6]. In [6], non-intersecting simple symmetric random walk bridges, for which the Hahn orthogonal polynomials arise, were studied. Here we study non-intersecting Poisson bridges, for which the Krawtchouk orthogonal polynomials arise. The limiting object for both are non-intersecting Brownian bridges, which are related to the Hermite polynomials.

3.1 Determinantal kernel for non-intersecting Brownian bridges

We recall some useful definitions and facts about non-intersecting Brownian bridges which were given in detail in Section 3.1. from [6].

**Definition 3.1.** (Definition 3.2 from [6]) Fix any $t^* > 0$. For $t \in (0, t^*)$, define $\alpha_t \doteq \sqrt{\frac{t^*}{2(t^*-t)}}$. For $z, z' \in \mathbb{R}$ and $t, t' \in (0, t^*)$, define the kernel $K^{(t',0)} ((t, z); (t', z'))$ by:
The first few polynomials are:

\[ K^{(t^*,x)} \left( (t, z); (t', z') \right) \]

\[ \Delta - \frac{1}{\sqrt{2\pi (t' - t)}} \exp \left( -\frac{(z' - z)^2}{2(t' - t)} \right) 1 \{ t < t' \} \]

\[ + \left( \frac{t^*}{2t'(t^* - t)} \right)^{3/2} \sum_{j=0}^{d-1} \left( \frac{t(t^* - t')}{(t' - t)t'} \right)^{j/2} p_j(z\alpha_t) \exp \left( -\frac{z^2}{2(t^* - t)} \right) p_j(z'\alpha_{t'}) \exp \left( -\frac{z'^2}{2t'} \right). \]

(3.1)

where \( p_j(y), j \in \mathbb{N}, y \in \mathbb{R} \) are the normalized Hermite polynomials:

\[ p_j(y) \triangleq \frac{H_j(y)}{\sqrt{\pi} \cdot j! \cdot 2^j}, \quad H_j(y) \triangleq (-1)^j e^{y^2} \frac{d^j}{dy^j} e^{-y^2}. \]

(3.2)

Finally, for any \( z^* \in \mathbb{R} \), we will define:

\[ K^{(t^*,z^*)} \left( (t, z); (t', z') \right) \triangleq K^{(t^{*},0)} \left( \left( t, z - z^* \frac{t}{t'} \right); \left( t', z' - z^* \frac{t'}{t} \right) \right) \frac{\exp \left( z^* \left( \frac{z' - z^* \frac{t'}{t}}{\frac{t}{t'}} \right) \right)}{\exp \left( z^* \left( \frac{z' - z^* \frac{t^*}{t}}{\frac{t^*}{t}} \right) \right)}. \]

(3.3)

**Lemma 3.2** (Lemma 3.3 from [6]). Fix any \( t^* > 0 \) and \( z^* \in \mathbb{R} \). Recall from Definition 2.2 the \( k \)-point correlation functions \( \psi_k^{(t^*,z^*)} \) for non-intersecting Brownian bridges \( D^{(t^*,z^*)} \). We have that \( \psi_k^{(t^*,z^*)} \) is determinantal with kernel \( K^{(t^*,z^*)} \):

\[ \psi_k^{(t^*,z^*)} \left( (t_1, z_1), \ldots, (t_k, z_k) \right) = \det \left[ K^{(t^*,z^*)} \left( (t_i, z_i); (t_j, z_j) \right) \right]_{i,j=1}^k. \]

(3.4)

### 3.2 Determinantal kernel for non-intersecting Poisson bridges

**Definition 3.3.** The Krawtchouk polynomials are a family of orthogonal polynomials parametrized by the two parameters \( N \in \mathbb{N} \) and \( p \in (0,1) \) and given explicitly in terms of the hypergeometric function \( \, _2F_1 \) by

\[ K_j(x;p,N) = \, _2F_1 \left( \begin{array}{c} -j, -x \\ -N \end{array} \right) \left( \frac{1}{p} \right). \]

The first few polynomials are:

\[ K_0(x;p,N) = 1, \]

\[ K_1(x;p,N) = -Np + x, \]

\[ K_2(x;p,N) = \frac{1}{2} \left( N^2p^2 + x(2p + x - 1) - Np(p + 2x) \right). \]

See [16] for more details on the Krawtchouk polynomials. Fix \( \tau^* > 0 \) and \( x^* \in \mathbb{N} \). For any \( \tau > 0, x \in \mathbb{N} \), and any \( 0 \leq j \leq d - 1 \), define \( R_j^\tau(x^*) \) and \( \tilde{R}_j^\tau(x^*) \) which are defined in terms of the Krawtchouk with parameters depending on \( \tau, x, \tau^*, x^* \) by:

\[ R_j^\tau(x^*) \triangleq K_j \left( x, \frac{\tau}{\tau^*}, x^* + d - 1 \right). \]

\[ \tilde{R}_j^\tau(x^*) \triangleq K_j \left( x^* - x + d - 1, 1 - \frac{\tau}{\tau^*}, x^* + d - 1 \right). \]
(We will refer to $R_j$ and $\tilde{R}_j$ without the superscripts for ease of notation whenever there is no ambiguity in this). Finally define the kernel $K_p^{(\tau, x^*)}$ for pairs of space-time coordinates $(\tau, x) \in (0, t^*) \times \mathbb{N}$, $(\tau', x') \in (0, t^*) \times \mathbb{N}$ as follows. (Recall that $\mu(\tau, x) \triangleq e^{-\tau x^*}x^{1-d}1_{x \geq 0}$ is the Poisson probability mass function.)

$$K_p^{(\tau, x^*)}(\tau, x; \tau', x') \triangleq \mu(\tau - \tau', x^* - x) 1\{\tau < \tau'\} + \sum_{j=0}^{d-1} (-1)^j \binom{d-1}{j} \tilde{R}_j(\tau, x) \mu(\tau, x^* - x + d - 1) R_j(\tau', x') \mu(\tau', x'),$$

and define the rescaled version of this, for a pair of space-time coordinates $(t, z) \in (0, t^*) \times \mathbb{R}$, $(t', z') \in (0, t^*) \times \mathbb{R}$:

$$K_p^{(N)N}(t', z') \triangleq \sqrt{\frac{1}{N}} K_p^{(N)}(\sqrt{N}t', \sqrt{N}z').$$

**Lemma 3.4.** Fix any $t^* > 0$ and $z^* \in \mathbb{R}$. Recall from Definition 2.16 the $k$-point correlation functions $\psi_k^{(N)}(t^*, z^*)$ for rescaled non-intersecting Poisson bridges $X_k^{(N)}(t^*, z^*)$. We have that $\psi_k^{(N)}(t^*, z^*)$ is determinantal with kernel $K_k^{(N)N}(t^*, z^*)$:

$$\psi_k^{(N)}(t^*, z^*) \equiv \left\{ (t_1, z_1), \ldots, (t_k, z_k) \right\} = \det \left[ K_p^{(N)}(t^*, z^*) \left( (t_i, z_i); (t_j, z_j) \right) \right]_{i, j=1}^k.$$

**Proof.** It suffices to show that $K_p^{(N)N}(t^*, z^*)$ is the determinantal kernel for non-intersecting Poisson bridges that start at $\delta_0(0)$ and end at $\delta_0(x^*)$, and the result for $K_p^{(N)N}(t^*, z^*)$ follows from the rescaling in the definitions of $\psi_k^{(N)}(t^*, z^*)$ from Definition 2.16. The proof that $K_p^{(N)N}(t^*, z^*)$ is this determinantal kernel is deferred to the appendix, Proposition A.4. \qed

### 3.3 Pointwise convergence on $D_1(\delta, \eta, M)$ – Proof of Proposition 2.24

**Lemma 3.5.** Fix any $0 < \delta < 1$, and $L > 0$. Let $p \in [\delta, 1 - \delta]$, and $y \in [-L, L]$. Suppose that $\{y_M\}_{M=1}^{\infty}$ is a sequence so that $y_M = pM + y\sqrt{2p(1-p)M} + o(\sqrt{M})$ as $M \to \infty$ and moreover suppose that the $O(\sqrt{M})$ error is uniform over all choices of $p, y$ with $p \in [\delta, 1 - \delta]$ and $y \in [-L, L]$. Define for any $M \in \mathbb{N}$:

$$G_j^{(M)}(y) = j! \left( \frac{M}{j} \right) \left( \frac{2p}{M(1-p)} \right)^{j/2} K_j(y_M, p, M).$$

Then, for each $M \in \mathbb{N}$, uniformly over $p \in [\delta, 1 - \delta]$ and $y \in [-L, L]$, we have convergence to the Hermite polynomials:

$$G_j^{(M)}(y) = (-1)^j H_j(y) + O \left( M^{-\frac{1}{2}} \right).$$

where $H_j(y) = (-1)^j e^{y^2} \frac{d^j}{dy^j} e^{-y^2}$ are the standard Hermite polynomials.

**Proof.** The proof is by induction on $j$. The base cases $j = 0$ and $j = 1$ are clear since one can verify $G_0^{(M)} \equiv 1 \equiv H_0$ and $G_1^{(M)}(y) = -2y + O(M^{-\frac{1}{2}}) = -H_1(y) + O(M^{-\frac{1}{2}})$.

Assume that the result holds for $j$ now. To prove the induction step, we compare the three term recurrence for the Krawtchouk polynomials to the three term recurrence for the Hermite polynomials. These are (see [16]):

$$H_{n+1}(x) = 2xH_n(x) - 2nH_{n-1}(x),$$
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\[ K_{n+1}(x, p, N) = \frac{pN + n - 2pm - x}{p(N - n)} K_n(x, p, N) - \frac{n(1 - p)}{p(N - n)} K_{n-1}(x, p, N). \]

This gives the following three term recurrence for \( G^{(M)}_{j+1}(y) \) in terms of \( G^{(M)}_j(y) \) and \( G^{(M)}_{j-1}(y) \):

\[ G^{(M)}_{j+1}(y) = -2yG^{(M)}_j(y) \left( 1 - \frac{j - 2p}{\sqrt{2Mp(1 - p)}} \right) - 2jG^{(M)}_{j-1}(y) \left( \frac{M - j + 1}{M} \right). \] (3.7)

By the inductive hypothesis, the RHS of equation (3.7) is equal to

\[ (-1)^{j+1}(2yH_j(y) - 2jH_{j-1}(y)) + O(M^{-\frac{1}{2}}), \]

and the \( O(M^{-\frac{1}{2}}) \) error is uniform over \( p \in [\delta, 1 - \delta] \) and \( y \in [-L, L] \). By the three term recurrence for the Hermite polynomials, this is \((-1)^j H_{j+1}(y) + O\left(M^{-\frac{1}{2}}\right)\) as desired.

**Corollary 3.6.** Fix \( t^* > 0 \) and \( \tau^* \in \mathbb{R} \). Let \( \tau^* = Nt^* \) and \( x^* = \left| Nt^* + \sqrt{N}z^* \right| \). Recall the definition of \( \alpha_t \) from Definition 3.1. For any choice of \( \delta, L > 0 \), the polynomials \( R_j \) and \( \tilde{R}_j \) from Definition 3.3 have the following limit as \( N \to \infty \), uniformly over the set \((t, z) \in (\delta, t^* - \delta) \times (-L, L)\):

\[ N^2 R_j^{(\tau^*, x^*)}(Nt, \left| Nt + \sqrt{N}z \right|) = \left( \frac{-1}{\sqrt{2}} \right)^j \left( \frac{t^* - t}{t^*t^*} \right)^{j/2} H_j \left( \left| z - z^* \frac{t^*}{t^*} \right| \alpha_t \right) + O\left(N^{-\frac{1}{2}}\right), \]

\[ N^2 \tilde{R}_j^{(\tau^*, x^*)}(Nt, \left| Nt + \sqrt{N}z \right|) = \frac{1}{\sqrt{2}} \left( \frac{t}{t^*t^*} \right)^{j/2} H_j \left( \left| z - z^* \frac{t}{t^*} \right| \alpha_t \right) + O\left(N^{-\frac{1}{2}}\right). \]

**Proof.** This follows by the definitions \( R_j \) and \( \tilde{R}_j \) in terms of Kravtchouk polynomials from Definition 3.3 and the asymptotics from Lemma 3.5. For \( R_j \), the parameters from Lemma 3.5 are to be fixed as \( M = Nt^* + \sqrt{N}z^* + d - 1 \), \( p = \frac{t^*}{t^*} \), \( y = \left| z - z^* \frac{t^*}{t^*} \right| \alpha_t \), \( y_M = Nt + \sqrt{N}z \). \( \tilde{R}_j \) can be done analogously, but it is easier to note that the transformation \((t, z) \to (t^* - t, z - z^*) \) takes \( \tilde{R}_j \) to \( R_j \) in this scaling limit. (The extra factor of \((-1)^j\) that appears in \( \tilde{R} \) comes out by simplifying using \( H_j(-y) = (-1)^j H_j(y) \) and we have also used \( \alpha_{t^* - t} = \alpha_t \).)

**Lemma 3.7.** Fix \( t^* > 0 \) and \( z^* \in \mathbb{R} \). For all \( \delta, \eta, M > 0 \), we have the following pointwise convergence uniformly over all pairs \((t, z), (t', z') \in (0, t^*) \times \mathbb{R} \) that satisfy \( z, z' \in (-M, M), t, t' \in (\delta, t^* - \delta) \) and \(|t - t'| > \eta\):

\[ \lim_{N \to \infty} K^{(N), (t^*, z^*)}(t, z); (t', z') = K^{(t^*, z^*)}(t, z); (t', z'). \]

**Proof.** Define the variables (which depend on \( N \)), \( \tau, \tau', \tau^* > 0 \) and \( x, x', x^* \in \mathbb{Z} \) by \( \tau' , x' \overset{\Delta}{=} Nt', \left| Nt^* + \sqrt{N}z' \right|, \tau, x \overset{\Delta}{=} Nt, \left| Nt + \sqrt{N}z \right|, \tau^*, x^* \overset{\Delta}{=} Nt^*, \left| Nt^* + \sqrt{N}z^* \right| \). By comparing the kernel for non-intersecting Brownian bridges in Definition 3.1 to the kernel for non-intersecting Poisson bridges in equation (3.5), we see that both kernels consist of a sum of \( d + 1 \) terms. We will show the convergence of each term individually with the help of the Poisson CLT: \( \lim_{M \to \infty} \sqrt{M \mu} \left( M, M + \sqrt{Mz} \right) = \frac{1}{\sqrt{2\pi}} \exp \left( -\frac{1}{2} z^2 \right) \). The convergence holds uniformly and is stated precisely in Proposition A.2.

The convergence of the first term of equation (3.5) is a direct application of this Poisson CLT. Notice that uniformly over all \( t', t \) with \(|t' - t| > \eta\) that we have \( n' - n > N\eta \).
By application of Proposition A.2 and the definition of $\tau', \tau, x', x$, we have that uniformly over all such $t', t$ and all $z, z'$

$$\lim_{N \to \infty} \sqrt{N} \mu(\tau' - \tau, x' - x) = \frac{1}{\sqrt{2\pi(t' - t)}} \exp \left( -\frac{(z' - z)^2}{2(t' - t)} \right),$$

and it is clear that $1 \{\tau < \tau'\} = 1 \{t < t'\}$. To see the convergence of the remaining $d$ terms consider as follows. We again apply the local central limit theorem Proposition A.2 to the $j$-th term of the sum in the definition of $K_P^{(t', x')}$ from equation (3.5) to see uniform convergence for the Poisson weights that appear. Combining these asymptotics with the asymptotics for $R_j$ and $\tilde{R}_j$ from Corollary 3.6 we have the following limit for the $j$-th term that appears in our limit, corresponding to the $j$-th term in the sum from equation (3.5):

$$\lim_{N \to \infty} \sqrt{N} (-1)^j \frac{(-1)^j N^{-j} (z^* + d - 1)}{\sqrt{2\pi t}} \exp \left( \frac{z^2}{2t} \right)$$

$$\times \frac{1}{\sqrt{2\pi(t - t')}} \exp \left( \frac{(z' - z)^2}{2(t' - t)} \right)$$

$$\times \frac{1}{\sqrt{2\pi t}} \exp \left( \frac{(z^* - z)^2}{2t} \right) \times \frac{1}{\sqrt{2\pi t'}} \exp \left( \frac{(z^* - z')^2}{2t'} \right).$$

After grouping the terms appropriately, it is verified that this is exactly equal to the corresponding $j$-th term in Definition 3.1 for the kernel $K(t', z')$ for non-intersecting Brownian bridges.

\begin{corollary}
Fix $t^* > 0$ and $z^* \in \mathbb{R}$. For any $\delta, M > 0$, there exist constants $C^C_\delta = C^C_K(\delta, M)$, and $C^C_M = C^C_K(\delta, M)$ so that for pairs $(t, z); (t', z')$ with $t, t' \in (\delta, T - \delta)$, $|t' - t| > \eta$ and $z, z' \in (-M, M)$ we have

$$\sup_N \left| K^{(N)}(t, z); (t', z') \right| \leq C^C_\delta (t' - t)^{-\frac{1}{2}} \quad \text{if } t < t',$$

$$\sup_N \left| K^{(N)}(t, z); (t', z') \right| \leq C^C_M \quad \text{if } t \geq t'.$$

\end{corollary}

\begin{proof}
When $t \geq t'$, the first term in the definition of $K^{(N)}(t, z); (t', z')$ is 0, and the proof of Lemma 3.7 shows that regardless of $\eta$, $K^{(N)}(t, z)$ converges uniformly to $K(t', z')$ for $t, t' \in (\delta, T - \delta)$ and $z, z' \in (-M, M)$. Thus when $t \geq t'$, since $K(t', z')$ is bounded by $C^C_M$ here by Lemma 3.4 from [6], and since the convergence in Lemma 3.7 is uniform, it follows that $K^{(N)}(t, z); (t', z')$ is also bounded. Let $C^C_M$ be a constant large enough to bound both of them.

To see the inequality when $t < t'$ we must consider the first term. By applying the bound from Corollary A.3 to the first term in $K^{(N)}(t, z)$, along with the bound $\sqrt{t' - t} < \sqrt{t}$, we have by the triangle inequality that:

$$\sup_N \sqrt{t' - t} \left| K^{(N)}(t, z); (t', z') \right| \leq \left( C_D + \sqrt{t} C^C_M \right).$$

This bound gives the desired result.
\end{proof}
Corollary 3.9. Fix \( t^* > 0 \) and \( z^* \in \mathbb{R} \). For all \( \delta, \eta, M > 0 \), there exists a constant \( C_{D_1,K} = C_{D_1,K}(\delta, \eta, M) \) such that \( |K^{(N)}(t^*,z^*)((t,z);(t',z'))| \leq C_{D_1,K} \) for all pairs \( (t,z);(t',z') \) that satisfy \( t,t' \in (\delta, t^* - \delta), |t' - t| > \eta \) and \( z,z' \in (-M,M) \).

Proof. It is easily verified by Corollary 3.8 that \( C_{D_1,K} = \max \left( C_{K}^{\geq}, \frac{1}{\sqrt{\eta}} C_{K}^{<} \right) \) will give the desired result since \( \sqrt{t'-t} > \sqrt{\eta} \) when \( t' > t \).

Proof. (Of Proposition 2.24) By Lemma 3.3 from [6] and Lemma 3.4, the \( k \)-point correlation functions \( \psi_k^{(N)}(t^*,z^*) \) and \( \psi_k(N,t^*,z^*) \) are given by \( k \times k \) determinants of the kernels \( K^{(t^*,z^*)} \) and \( K^{(N)}(t^*,z^*) \) respectively. Since determinants are polynomial functions of the matrix entries, the existence of the bound by \( C_{D_1,K} \) follows by the bound for \( |K^{(t^*,z^*)}(\cdot)| \leq C_{D_1,K} \) in Corollary 3.5 from [6] and the bound \( |K^{(N)}(t^*,z^*)(\cdot)| < C_{D_1,K} \) in Corollary 3.9. Now notice that Lemma 3.7 establishes uniform convergence \( K^{(N)}(t^*,z^*)((t_1,z_1);(t_2,z_2)) \to K^{(t^*,z^*)}((t_1,z_1);(t_2,z_2)) \) for any pairs \( (t_1,z_1) \) and \( (t_2,z_2) \) chosen from the list \( (\vec{t}, \vec{z}) \in D_1(\delta, \eta, M) \). Since the entries are bounded, this uniform convergence of the entries implies uniform convergence of the \( k \times k \) determinant.

3.4 Bound on \( D_2(\delta, \eta, M) \) -- Proof of Proposition 2.25

Lemma 3.10. Fix \( t^* > 0 \) and \( z^* \in \mathbb{R} \). For any \( \delta, M > 0 \), there exists a constant \( C_{D_2} = C_{D_2}(\delta, M) \) such that for all \( ((t_1,z_1);\ldots;(t_k,z_k)) \in D_2(\delta, \eta, M) \) we have:

\[
\sup_N \psi_k^{(N)}(t^*,z^*)((t_1,z_1);\ldots;(t_k,z_k)) \leq \frac{C_{D_2}}{\sqrt{t_2-t_1}\sqrt{t_3-t_2}\cdots\sqrt{t_{k-1}-t_{k-2}}}. \tag{3.8}
\]

Proof. This follows by applying Lemma 3.15 in [6] to the bounds on \( K^{(N)}(t^*,z^*) \) from Corollary 3.8 and then finally using the fact that \( K^{(N)}(t^*,z^*) \) is the determinantal kernel for \( \psi_k^{(N)}(t^*,z^*) \) from Lemma 3.4.

Proof. (Of Proposition 2.25) Recall from Definition 2.16 that \( \psi_k^{(N)}(t^*,z^*) \) is constant on intervals of the form \( I^{(N)}(t,z) \). Thus, as in equation (2.3), we may rewrite the integral as a semidiscrte sum. Recalling the definition of the set \( D_2(\delta, \eta) \) in Definition 2.22, we apply the bound from Lemma 3.10 on \( \psi_k^{(N)}(t^*,z^*)((\vec{t}, \vec{z})) \) to see that

\[
\int_{D_2(\delta, \eta)} \left| \psi_k^{(N)}(t^*,z^*)((\vec{t}, \vec{z})) \right|^2 \, d\vec{t} d\vec{z} \leq N^{-\frac{d}{2}} \sum_{\vec{z} \in \mathbb{N}^{d/2}} \sum_{\vec{t} \in \mathbb{N}^{d/2}} C_{D_2} \left| \psi_k^{(N)}(t^*,z^*)((t_1,z_1 - \sqrt{N}t_1),\ldots,(t_k,z_k - \sqrt{N}t_k)) \right|^2.
\]

We notice now from Definition 2.16 that the scaling \( N^{-\frac{d}{2}} \) makes the above exactly the probability of finding a particle occupying each position \( z_1 + t_1, \ldots, z_k + t_k \) at the times \( t_1, \ldots, t_k \) respectively. Summing these probabilities simply counts the \( d \) paths:

\[
\sum_{\vec{z} \in \mathbb{N}^{d/2}} P \left( \bigcap_{j=1}^k \{ z_j - \sqrt{N}t_j \in \mathbb{R}^{(N)}(t^*,z^*)((t_j)) \} \right) = E \left[ |d^k| \right] = |d^k|.
\]
We hence get the bound:

\[
\int_{D_{\delta}^{2} \times \{ t, z \}} \left| \psi_{k}^{(N)}(t^{*}, z^{*})(\bar{t}, \bar{z}) \right|^{2} d\bar{t} \leq d^{k} C_{D_{2}} \int_{t_{1} \in \Delta_{k}(\delta, t^{*} - \delta \cap S_{\eta}^{c})} \frac{dt_{1} dt_{2} \ldots dt_{k}}{\sqrt{t_{2} - t_{1} \sqrt{t_{3} - t_{2}} \ldots \sqrt{t_{k} - t_{k-1}}}}.
\]

(3.9)

Notice that since \((t_{i+1} - t_{i})^{-\frac{1}{2}}\) is integrable around the singularity at \(t_{i+1} = t_{i}\), the integrand in equation (3.9) has finite total integral when integrated over the whole range of times \(\bar{t} \in \Delta_{k}(\delta, t^{*} - \delta)\). Since \(\lim_{\eta \to 0} 1 \{ S_{\eta}^{c} \} = 0 \ a.s., \) we have by the dominated convergence theorem that the RHS of equation (3.9) tends to 0 as \(\eta \to 0\). This gives the desired result. \(\square\)

4 Overlap times

In this section we extend the method of overlap times used for discrete polymers in [6] to be able to apply them to the semi-discrete polymers studied here. This overlap time can also be thought of as the semi-discrete version of the local times between non-intersecting Brownian motions studied in Section 4 of [24]. We prove in this section that the overlap time has a property called “weak exponential moment control”. This property is then used in Section 5 to bound the \(L^{2}\) norm of the \(k\)-point correlation functions.

**Definition 4.1.** Recall from Definition 2.4 the notation \(\bar{X}(\tau), \tau \in (0, \infty)\) for \(d\) non-intersecting Poisson processes started from \(\bar{X}(0) = \delta_{0}(0)\). Let \(\bar{X}'(\tau), \tau \in (0, \infty)\) be an independent copy of the same ensemble. For indices \(1 \leq k, \ell \leq d\) and times \(0 < \tau_{1} < \tau_{2}\), define the overlap time on \([\tau_{1}, \tau_{2}]\) between the \(k\)-th walker of \(\bar{X}\) and the \(\ell\)-th walker of \(X'\) by:

\[
O_{k, \ell}[\tau_{1}, \tau_{2}] \triangleq \int_{\tau_{1}}^{\tau_{2}} 1 \{ \bar{X}_{k}(\tau) = \bar{X}'_{\ell}(\tau) \} \, d\tau.
\]

(4.1)

Define the total overlap time on the interval \([\tau_{1}, \tau_{2}]\) of these processes by

\[
O[\tau_{1}, \tau_{2}] \triangleq \sum_{1 \leq k, \ell \leq d} O_{k, \ell}[\tau_{1}, \tau_{2}] = \int_{\tau_{1}}^{\tau_{2}} \left| \{ \bar{X}(\tau) \cap \bar{X}'(\tau) \} \right| \, d\tau,
\]

where we think of \(\bar{X}(\tau)\) and \(\bar{X}'(\tau)\) as sets and \(\left| \{ \bar{X}(\tau) \cap \bar{X}'(\tau) \} \right|\) is the number of elements in their intersection.

Similarly, for any fixed \(x^{*} \in \mathbb{N}\) and \(\tau^{*} > 0\), recall from Definition 2.5 that \(\bar{X}(\tau^{*}, x^{*})(\tau), \tau \in [0, \tau^{*}]\) denotes an ensemble of \(d\) non-intersecting random walker bridges started from \(\bar{X}(\tau^{*}, x^{*})(0) = \delta_{0}(x^{*})\) and ended at \(\bar{X}(\tau^{*}, x^{*})(\tau^{*}) = \delta_{0}(x^{*})\). Let \(\bar{X}(x^{*}, \tau^{*})(\tau), \tau \in [0, \tau^{*}]\) be an independent copy of the same ensemble. For times \(0 < \tau_{1} < \tau_{2}\), define the total overlap time on the interval \([\tau_{1}, \tau_{2}] \subset [0, \tau^{*}]\) of these processes by

\[
O^{(\tau^{*}, x^{*})}[\tau_{1}, \tau_{2}] \triangleq \int_{\tau_{1}}^{\tau_{2}} \left| \{ \bar{X}(\tau^{*}, x^{*})(\tau) \cap \bar{X}(\tau^{*}, x^{*})(\tau) \} \right| \, d\tau.
\]

For any fixed \(z^{*} \in \mathbb{R}\) and \(t^{*} > 0\), and \(0 < t_{1} < t_{2} < t^{*}\), define the rescaled overlap time by

\[
O^{(N, t^{*}, z^{*})}[t_{1}, t_{2}] \triangleq \frac{1}{\sqrt{N}} O^{(N \tau^{*}, [N \tau^{*} + \sqrt{N} z^{*}])}[\lfloor N \tau_{1} \rfloor, \lfloor N \tau_{2} \rfloor].
\]
4.1 Weak exponential moment control – definition and properties

**Definition 4.2.** We say that a collection of non-negative valued processes

\[ \left\{ Z^{(N)}(t) : t \in [0,t^*] \right\}_{N \in \mathbb{N}}, \]

is “weakly exponential moment controlled as \( t \to 0^+ \)” if the following conditions are met:

i) For any fixed \( t \in [0,t^*], \gamma > 0 \), there exists \( N_\gamma \in \mathbb{N} \) so that:

\[ \sup_{N > N_\gamma} \mathbb{E} \left[ \exp \left( \gamma Z^{(N)}(t) \right) \right] < \infty. \]

ii) For any fixed \( \gamma > 0 \), and \( \epsilon > 0 \), there exists \( N_{\gamma,\epsilon} \in \mathbb{N} \) so that:

\[ \lim_{t \to 0} \sup_{N > N_{\gamma,\epsilon}} \mathbb{E} \left[ \exp \left( \gamma Z^{(N)}(t) \right) \right] \leq 1 + \epsilon. \]

iii) For any fixed \( \gamma > 0 \), \( \epsilon > 0 \) and \( \gamma > 0 \), there exists \( N_{\gamma,\epsilon} \in \mathbb{N} \) so that:

\[ \lim_{t \to \infty} \sup_{N > N_{\gamma,\epsilon}} \mathbb{E} \left[ \sum_{k=\ell}^{\infty} \frac{\gamma^k}{k!} \left( Z^{(N)}(t) \right)^k \right] \leq \epsilon. \]

**Remark 4.3.** The notation of “exponential moment controlled” without the adjective “weak” appears in Definition 4.3 of [6]. Here we weaken the definition by taking the sup over \( N > N_{\gamma,\epsilon} \), rather than sup over all \( N \in \mathbb{N} \), and allowing for an error of size \( \epsilon \) in properties ii) and iii). This extension is necessary because it allows us to handle exponential rare events that arise in the continuous-time processes we study. Note that the exponential moment control defined in [6] always implies weak exponential moment control by setting \( N_{\gamma,\epsilon} = 1 \) everywhere. This relaxation is needed in the semi-discrete setting because the semi-discrete processes under consideration have the potential to be arbitrarily large in a finite amount of time (as opposed to discrete simple symmetric random walks, whose height cannot exceed the number of steps the process takes). This leads to exponential rare “bad” events: the \( \epsilon \) of room created by the weaker definition leaves space for these errors.

**Lemma 4.4.** Suppose \( \left\{ Z^{(N)}(t), t \in [0,t^*] \right\}_{N \in \mathbb{N}} \) is a collection of processes so that

\[ \mathbb{P} \left( Z^{(N)}(t) > x \right) \leq C \exp \left( -\frac{x^2}{t} \right). \]

Then \( \left\{ Z^{(N)}(t), t \in [0,t^*] \right\} \) is weakly exponential moment controlled.

**Proof.** In Lemma 4.7 of [6] it is proven that such processes are exponential moment controlled in the sense of Definition 4.3 from that paper. Since exponential moment control implies weak exponential control, the result follows.

**Lemma 4.5.** If \( \left\{ Z^{(N)}(t) : t \in [0,t^*] \right\}_{N \in \mathbb{N}} \) is weakly exponential moment controlled, then for any exponent \( m \in \mathbb{N} \) and \( \gamma > 0 \) we have that \( \forall \epsilon > 0, \exists N_{\gamma,\epsilon,m} > 0 \) s.t.:

\[ \lim_{t \to \infty} \sup_{N > N_{\gamma,\epsilon,m}} \mathbb{E} \left[ \sum_{k=\ell}^{\infty} \frac{\gamma^k}{k!} \left( Z^{(N)}(t) \right)^k \right]^m \leq \epsilon. \]

**Proof.** The proof is very similar to the argument from Lemma 4.4 in [6]. Since each \( Z^{(N)}(t) \) is non-negative, there is no harm in rearranging the order of the terms in the infinite sum to arrive at:

\[ \left( \sum_{k=\ell}^{\infty} \frac{1}{k!} \gamma^k \left( Z^{(N)}(t) \right)^k \right)^m = \sum_{k_1, \ldots, k_m = \ell}^{\infty} \frac{1}{k_1! \ldots k_m!} \gamma^{k_1 + \ldots + k_m} \left( Z^{(N)}(t) \right)^{k_1 + \ldots + k_m}. \]
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\[
\begin{align*}
\sum_{k \geq m \ell} \sum_{k_1 + \cdots + k_m = k} \binom{k}{k_1, \ldots, k_m} \frac{1}{k!} \gamma^k Z^{(N)}(t)^k \\
= \sum_{k \geq m \ell} (m\gamma)^k \frac{1}{k!} Z^{(N)}(t)^k,
\end{align*}
\]

The desired result now holds by property iii) from Definition 4.2 of weak exponential moment control with parameter \( m\gamma \) and choosing \( N_{\gamma, m} = N_{m\gamma, \epsilon} \).

**Lemma 4.6.** Suppose \( \{W^{(N)}(t) : t \in [0, t^*]\} \) and \( \{Y^{(N)}(t) : t \in [0, t^*]\} \) are two collections of processes which are both weakly exponential moment controlled as \( t \to 0 \).

If \( \{Z^{(N)}(t) : t \in [0, t^*]\} \) is a collection of non-negative valued processes so that for all \( t \in [0, t^*] \) and all \( N \in \mathbb{N} \) we have

\[
Z^{(N)}(t) \leq W^{(N)}(t) + Y^{(N)}(t) \text{ a.s.}
\]

then \( \{Z^{(N)}(t) : t \in [0, t^*]\} \) is also weakly exponential moment controlled as \( t \to 0 \).

**Proof.** The proof is very similar to the argument from Lemma 4.5 in [6]. Property i) and ii) of the weak exponential moment control are easily verified by application of the Cauchy-Schwarz inequality:

\[
\mathbb{E} \left[ \exp \left( \gamma Z^{(N)}(t) \right) \right] \leq \sqrt{\mathbb{E} \left[ \exp \left( 2\gamma W^{(N)}(t) \right) \right] \cdot \mathbb{E} \left[ \exp \left( 2\gamma Y^{(N)}(t) \right) \right]}.
\]

To see property iii) for \( W^{(N)}(t) \), we argue as in Lemma 4.5 in [6] by the Cauchy-Schwarz inequality that

\[
\mathbb{E} \left[ \sum_{k=2\ell}^{\infty} \frac{1}{k!} \gamma^k \left( Z^{(N)}(t) \right)^k \right] \leq \sqrt{\mathbb{E} \left[ \exp \left( 2\gamma W^{(N)}(t) \right) \right] \mathbb{E} \left[ \left( \sum_{b=\ell}^{\infty} \left( \frac{1}{b!} \gamma^b \left( Y^{(N)}(t) \right)^b \right) \right)^2 \right]} + \sqrt{\mathbb{E} \left[ \exp \left( 2\gamma Y^{(N)}(t) \right) \right] \mathbb{E} \left[ \left( \sum_{a=\ell}^{\infty} \left( \frac{1}{a!} \gamma^a \left( W^{(N)}(t) \right)^a \right) \right)^2 \right]},
\]

(4.2)

By property i) now, we can find \( N_{\gamma} \in \mathbb{N} \) so for all \( N > N_{\gamma} \) we have a uniform upper bound over \( \mathbb{E} \left[ \exp \left( 2\gamma W^{(N)}(t) \right) \right] \) and \( \mathbb{E} \left[ \exp \left( 2\gamma Y^{(N)}(t) \right) \right] \).

The desired limit as \( \ell \to \infty \) of equation (4.2) follows by an application of Lemma 4.5.

**Lemma 4.7.** Suppose that \( \{W^{(N)}(t) : t \in [0, t^*]\} \) is weakly exponential moment controlled and that the collection of processes \( \{Z^{(N)}(t) : t \in [0, t^*]\} \) have the property that

\[
\mathbb{P} \left( Z^{(N)}(t) > x \right) \leq \mathbb{P} \left( W^{(N)}(t) > x \right) + C \exp \left( -c\sqrt{N}x \right).
\]

Then \( \{Z^{(N)}(t) : t \in [0, t^*]\} \) is weakly exponential moment controlled.

**Proof.** By using integration by parts, we have:

\[
\mathbb{E} \left[ \exp \left( \gamma Z^{(N)}(t) \right) \right] = \int_{0}^{\infty} e^{\gamma x} \mathbb{P} \left( Z^{(N)}(t) > x \right) \, dx
\]

\[
\leq 1 + \gamma \int_{0}^{\infty} e^{\gamma x} \mathbb{P} \left( W^{(N)}(t) > x \right) \, dx + C\gamma \int_{0}^{\infty} \exp \left( -c\sqrt{N}x + \gamma x \right) \, dx
\]

We now notice that for where $P$ and $W$.

Thus for $N > \gamma$.

Denoting by $\vec{Y}$ this coupling, the process $\vec{Y}$

random walkers from Section 2.1 of [30]. We explicitly give the argument for the top

$N$ and for any fixed $\bar{\delta}$ and $\vec{X}$

Recall from Definition 2.4 that $\vec{X}(\tau)$, $\tau > 0$

denotes an ensemble of $d$ non-intersecting Poisson processes started from $\vec{X}(0) = \delta_d(0)$.

Denote by $X_d(\tau) \overset{d}{=} X_d(\tau) - \tau$

and $X_1(\tau) \overset{d}{=} X_1(\tau) - \tau$. Then there are constants $c$, $C$

(which depend on $d$) so that for all $N$ and for any fixed $t > 0$ we have the following inequality:

$$
P \left( \sup_{0 < \tau < t\tau N} |X_d(\tau)| > \alpha \sqrt{N} \right) \leq C \exp \left( -\frac{\alpha^2}{t} \right) + C \exp \left( -c\sqrt{N}\alpha \right).
$$

$$
P \left( \sup_{0 < \tau < t\tau N} |X_1(\tau)| > \alpha \sqrt{N} \right) \leq C \exp \left( -\frac{\alpha^2}{t} \right) + C \exp \left( -c\sqrt{N}\alpha \right).
$$

Proof. The proof is by induction on $d$, using the reflected construction of non-intersecting random walkers from Section 2.1 of [30]. We explicitly give the argument for the top line $X_d$ here; the proof for the bottom line $X_1$ is analogous.

The case $d = 1$ is clear since in this case $X_1(\tau)$ is simply a standard Poisson process

and the needed estimate is a consequence of the stronger general result about Poisson processes proven in Lemma A.1. Now suppose the result holds for $d - 1$. The reflected construction in [30] is a coupling of the process $\vec{X}$ of $d$ non-intersecting walkers started from $\delta_d(0)$ and the process $\vec{Y}$ of $d - 1$ non-intersecting walkers started from $\delta_{d-1}(0)$. In this coupling, the process $\vec{Y}$ is first constructed, and then the top line $X_d$ is realized as a Poisson process which is pushed upward by the top line of the $\vec{Y}$; symbolically this is:

$$
X_d(\tau') - X_d(\tau) = P(\tau') - P(\tau) + \int_{\tau}^{\tau'} \delta \{ X_d(s) - Y_{d-1}(s) = 0 \} \, ds,
$$

where $P(t)$ is a rate 1 Poisson process independent of the process $\vec{Y}$, and $\delta$ is the Dirac delta. Denoting by $\bar{P}(\tau) \overset{d}{=} P(\tau) - \tau$ and $\bar{Y}_{d-1}(\tau) \overset{d}{=} Y_{d-1}(\tau) - \tau$, we see that for any $\gamma > 0$:

$$
\left\{ \sup_{0 < \tau < T} X_d(\tau) > \gamma \right\} \subset \left\{ \sup_{0 < \tau < T} \bar{Y}_{d-1}(\tau) > \frac{\gamma}{2} \right\} \cup \left\{ \sup_{0 < \tau < T} \bar{P}(\tau) - \inf_{0 < \tau < T} \bar{P}(\tau) > \frac{\gamma}{2} \right\}. \quad (4.4)
$$

4.2 Bounds on positions of non-intersecting Poisson processes

The bounds in this subsection are needed as an ingredient to prove weak exponential moment control for the overlap times.

Lemma 4.8. Recall from Definition 2.4 that $\vec{X}(\tau)$, $\tau > 0$

denotes an ensemble of $d$ non-intersecting Poisson processes started from $\vec{X}(0) = \delta_d(0)$. Denote by $X_d(\tau) \overset{d}{=} X_d(\tau) - \tau$

and $X_1(\tau) \overset{d}{=} X_1(\tau) - \tau$. Then there are constants $c$, $C$

(which depend on $d$) so that for all $N$ and for any fixed $t > 0$ we have the following inequality:

$$
P \left( \sup_{0 < \tau < t\tau N} |X_d(\tau)| > \alpha \sqrt{N} \right) \leq C \exp \left( -\frac{\alpha^2}{t} \right) + C \exp \left( -c\sqrt{N}\alpha \right).
$$

$$
P \left( \sup_{0 < \tau < t\tau N} |X_1(\tau)| > \alpha \sqrt{N} \right) \leq C \exp \left( -\frac{\alpha^2}{t} \right) + C \exp \left( -c\sqrt{N}\alpha \right).
$$

Proof. The proof is by induction on $d$, using the reflected construction of non-intersecting random walkers from Section 2.1 of [30]. We explicitly give the argument for the top line $X_d$ here; the proof for the bottom line $X_1$ is analogous.

The case $d = 1$ is clear since in this case $X_1(\tau)$ is simply a standard Poisson process

and the needed estimate is a consequence of the stronger general result about Poisson processes proven in Lemma A.1. Now suppose the result holds for $d - 1$. The reflected construction in [30] is a coupling of the process $\vec{X}$ of $d$ non-intersecting walkers started from $\delta_d(0)$ and the process $\vec{Y}$ of $d - 1$ non-intersecting walkers started from $\delta_{d-1}(0)$. In this coupling, the process $\vec{Y}$ is first constructed, and then the top line $X_d$ is realized as a Poisson process which is pushed upward by the top line of the $\vec{Y}$; symbolically this is:

$$
X_d(\tau') - X_d(\tau) = P(\tau') - P(\tau) + \int_{\tau}^{\tau'} \delta \{ X_d(s) - Y_{d-1}(s) = 0 \} \, ds,
$$

where $P(t)$ is a rate 1 Poisson process independent of the process $\vec{Y}$, and $\delta$ is the Dirac delta. Denoting by $\bar{P}(\tau) \overset{d}{=} P(\tau) - \tau$ and $\bar{Y}_{d-1}(\tau) \overset{d}{=} Y_{d-1}(\tau) - \tau$, we see that for any $\gamma > 0$:

$$
\left\{ \sup_{0 < \tau < T} X_d(\tau) > \gamma \right\} \subset \left\{ \sup_{0 < \tau < T} \bar{Y}_{d-1}(\tau) > \frac{\gamma}{2} \right\} \cup \left\{ \sup_{0 < \tau < T} \bar{P}(\tau) - \inf_{0 < \tau < T} \bar{P}(\tau) > \frac{\gamma}{2} \right\}. \quad (4.4)
$$

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This inclusion follows since if $\sup_{0<\tau<T}\bar{Y}_{d-1}(\tau) \leq \frac{1}{2}$, then in order for the process $\bar{X}_d(\tau)$ to advance from position $\frac{1}{2}$ to $\gamma$, the process $\bar{X}_d(\tau)$ will need a boost of at least $\frac{1}{2}$ which can only come from the process $\bar{P}(\tau)$. We also have by the inductive hypothesis, $\mathbb{P}\left(\sup_{0<\tau<T}\bar{Y}_{d-1}(\tau) > \frac{1}{\sqrt{N}}\right) \leq C_{d-1} \exp\left(-c_{d-1} \frac{\alpha^2}{T}\right) + C_{d-1} \exp\left(-c_{d-1} \sqrt{\frac{\alpha^2}{t}}\right)$ for some constants $C_{d-1}, c_{d-1}$ (which depend on $d-1$). On the other hand, by Lemma A.1 we know that $P\left(\sup_{0<\tau<T} \bar{P}(\tau) - \inf_{0<\tau<T} \bar{P}(\tau) > \frac{1}{2} \sqrt{N}\right)$ also obeys this type of inequality. Setting $T = tN$ and $\gamma = \alpha \sqrt{N}$ in equation (4.4) and applying a union bound then completes the desired bound on $P\left(\sup_{0<\tau<T} \bar{X}_d(\tau) > \alpha \sqrt{N}\right)$. The bound on $P\left(\sup_{0<\tau<T} \left(\bar{X}_d(\tau) - \bar{X}_1(\tau)\right) > \alpha \sqrt{N}\right)$ follows since in this coupling we have $-\bar{X}_d(\tau) \leq -\bar{P}(\tau)$ and the result for $\bar{P}$ is clear by Lemma A.1.

**Corollary 4.9.** For any $1 \leq k \leq d$, there are constants $c, C$ so that for all $N$ and for any fixed $t > 0$, the maximum of absolute value of the compensated $k$-th line process $\bar{X}_k(\tau) - \tau$ obeys the following inequality:

$$
\mathbb{P}\left(\sup_{0<\tau<T} \left|\bar{X}_k(\tau)\right| > \alpha \sqrt{N}\right) \leq C \exp\left(-c \frac{\alpha^2}{t}\right) + C \exp\left(-c \sqrt{\alpha^2 \tau}\right).
$$

**Proof.** The cases $k = d$ and $k = 1$ are exactly Lemma 4.8. Now notice that for $1 < k < d$, because the walkers are always ordered so that $X_1(t) < X_k(t) < X_d(t)$, we have:

$$
\frac{1}{\sqrt{N}} \sup_{0<\tau<T} \left|\bar{X}_k(\tau)\right| \leq \frac{1}{\sqrt{N}} \sup_{0<\tau<T} \left|\bar{X}_d(\tau)\right| + \frac{1}{\sqrt{N}} \sup_{0<\tau<T} \left|\bar{X}_1(\tau)\right|
$$

and the desired inequality then follows by a union bound. \qed

### 4.3 Inverse gaps of non-intersecting Poisson processes

In this subsection, we prove bounds on the inverse gaps, $|X_j(t) - X_i(t)|^{-1}$, $1 \leq i, j \leq d$. The methods here are similar to those used for non-intersecting random walks in [6].

**Definition 4.10.** For fixed $\tau > 0$, $\epsilon > 0$, define $S_{\tau, \epsilon} \subset \mathbb{N}^d$ by

$$
S_{\tau, \epsilon} = \left\{ x \in \mathbb{N}^d : |x_j - x_i| > n^{\frac{1}{2} - \epsilon} \quad \forall 1 \leq i, j \leq d \right\}.
$$

**Lemma 4.11.** Recall from Definition 2.4 that $\bar{X}(\tau)$, $\tau > 0$ denotes $d$ non-intersecting Poisson processes and $E_{P^0}[\cdot]$ denotes the expectation from $\bar{X}(0) = \bar{x}^0$. Recall from Definition 2.3 that $\bar{D}(t)$, $t \in (0, \infty)$ denotes $d$ non-intersecting Brownian motions and $E_{\bar{Q}}[\cdot]$ denotes the expectation from $\bar{D}(0) = \bar{0}$. For any $\epsilon < \frac{1}{4}$, there exists an absolute constant $C$, so that for indices $a, b$ with $1 \leq a < b \leq d$ we have:

$$
\sup_{\tau > 0} \sup_{x^0 \in S_{\tau, \epsilon}} E_{P^0}\left[\frac{1}{\sqrt{\tau}}(X_b(\tau) - X_a(\tau))\right] \leq 3(2) E_{\bar{Q}}\left[\frac{1}{D_b(1) - D_a(1)}\right] + C_{\epsilon}. \quad (4.5)
$$

**Proof.** Let $\bar{P}(\tau) = (P_1(\tau), \ldots, P_d(\tau))$ be $d$ iid ordinary rate $1$ Poisson processes started from $\bar{P}(0) = (0, 0, \ldots, 0)$, and denote their expectation simply by $E$. By Definition 2.4 for $\bar{X}(\tau)$ as a Doob $h$-transform using the Vandermonde determinant $h_d$, the expectation on the LHS of equation (4.5) can be written as

$$
E_{P^0}\left[\frac{1}{\sqrt{\tau}}(X_b(\tau) - X_a(\tau))\right] = \frac{1}{\sqrt{\tau}} E_{P^0}\left[\frac{1}{h_d(X_b(\tau), X_a(\tau))}\right].
$$
Denote by \( \hat{P}(\tau) \triangleq P(\tau) - \tau \). By the KMT coupling [17], we can couple these processes with \( d \) iid Brownian motions, \( \hat{B}(t) = (B_1(t), \ldots, B_d(t)) \) started from \( \hat{B}(0) = (0, 0, \ldots, 0) \) so that for absolute constants \( K_1, K_2, K_3 > 0 \) we have at integer times that:

\[
\Pr\left( \sup_{1 \leq i \leq d} \sup_{1 \leq t \leq \tau} |\hat{P}_j(i) - B_j(i)| > K_3 \ln \tau + x \right) \leq K_1 \exp(-K_2 x),
\]

for all \( x \in \mathbb{R} \). (This can be done because each Poisson variable can be realized as a sum of iid mean zero random variables, \( P(i) \triangleq \sum_{s=1}^{d} (\xi(s) - 1) \) where \( \xi(s) \) are iid Poisson 1 random variables). We do not need the full power of this \( O(\ln \tau) \) coupling, so we will put \( x = \frac{1}{3} \tau^\frac{1}{2} - 2\epsilon \) and use an inclusion to get the weaker inequality:

\[
\Pr\left( \sup_{1 \leq i \leq d} \sup_{1 \leq t \leq \tau} |\hat{P}_j(i) - B_j(i)| \geq \frac{1}{3} \tau^\frac{1}{2} - 2\epsilon \right) \leq K_1 \exp\left(-\frac{K_2}{3} \tau^\frac{1}{2} - 2\epsilon \right). \tag{4.7}
\]

Now define the event \( A_{\epsilon, \tau} = \left\{ \sup_{1 \leq i \leq d} \sup_{t \in [0, \tau]} |\hat{P}_j(t) - B_j(t)| < \frac{1}{3} \tau^\frac{1}{2} - 2\epsilon \right\} \). Notice that if \( A_{\epsilon, \tau} \) does not happen, then either the Brownian motions \( B_j(t) \) are far from the Poisson process \( \hat{P}_j(t) \) at some integer time \( t = i \) or the Brownian motions or else the Poisson processes themselves have a large amount of movement in some interval \( t \in [i, i+1] \) (or in the last interval \( t \in [\tau] \)); in what follows we upper bound this last special exception by looking at \( t \in [[\tau], [\tau] + 1) \). Using this inclusion, we have by a union bound that \( \Pr(A_{\epsilon, \tau}^c) \) is bounded by the sum

\[
\Pr\left( \bigcup_{j=1}^{d} \bigcup_{i=1}^{\tau} \{ |\hat{P}_j(i) - B_j(i)| \geq \frac{\tau^{\frac{1}{2}} - 2\epsilon}{3} \} \right)
\]

\[
+ \Pr\left( \bigcup_{j=1}^{d} \bigcup_{i=1}^{\tau} \left\{ \sup_{0 \leq t \leq 1} |B_j(i + t) - B_j(i)| \geq \frac{\tau^{\frac{1}{2}} - 2\epsilon}{3} \right\} \right)
\]

\[
+ \Pr\left( \bigcup_{j=1}^{d} \bigcup_{i=1}^{\tau} \left\{ \sup_{0 \leq t \leq 1} |\hat{P}_j(i + t) - \hat{P}_j(i)| \geq \frac{\tau^{\frac{1}{2}} - 2\epsilon}{3} \right\} \right) \tag{4.8}
\]

\[
\leq K_1 \exp\left(-\frac{K_2}{3} \tau^{\frac{1}{2}} - 2\epsilon\right) + 2\tau d \Pr\left( \sup_{0 \leq t \leq 1} B(t) \geq \frac{1}{3} \tau^{\frac{1}{2}} - 2\epsilon \right) + 2\tau d \Pr\left( \xi \geq \frac{1}{3} \tau^{\frac{1}{2}} - 2\epsilon \right)
\]

\[
\leq K_1 \exp\left(-\frac{K_2}{3} \tau^{\frac{1}{2}} - 2\epsilon\right) + \frac{4d\tau^{\frac{1}{2}+2\epsilon}}{\sqrt{2\pi}} \exp\left(-\frac{1}{18} \tau^{1-4\epsilon}\right) + 2\tau d E[\exp(\xi)] \exp\left(1 - \frac{1}{3} \tau^{\frac{1}{2}} - 2\epsilon\right),
\]

where \( \xi \) is a Poisson(1) random variable and we have used the exponential Chebyshev inequality to estimate the Poisson probabilities, along with the reflection principle and Mill’s ratio estimate \( \Pr(\sup_{0 \leq t \leq 1} B(t) \geq x) = \frac{2}{\sqrt{2\pi}} \frac{1}{x^2} \exp(-x^2/2) \) to estimate the Brownian motion probabilities. Notice in particular that this probability is \( O(\exp(-\tau^a)) \) for some positive power \( a > 0 \) of \( \tau \).
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We now analyze the expectation on the RHS of equation (4.6) by separately examining the contribution on \( A_{\epsilon, \tau} \) and \( A_{\epsilon, \tau}' \). On the event \( A_{\epsilon, \tau}' \), consider as follows: Let \( E_{\tau} \) be the event

\[
E_{\tau} = \left\{ \sup_{1 \leq i \leq d} P_i(\tau) < 2\tau \right\}.
\]

On the event \( E_{\tau} \cap A_{\epsilon, \tau}' \), we expand the Vandermonde determinant and use the bound \(|P_i(\tau) - P_j(\tau)| < 4n|\) to get the bound:

\[
\frac{\sqrt{\tau}}{h_d(x^0)} E \left[ \prod_{i < j, (i, j) \neq (a, b)} \left( P_j(\tau) + x_j^0 - P_i(\tau) - x_i^0 \right) 1 \{ \tau^{P_j} > \tau \} 1 \{ A_{\epsilon, \tau}' \} 1 \{ E_{\tau} \} \right]
\]

\[
\leq \frac{\sqrt{n}}{x_b^0 - x_a^0} E \left[ \prod_{i < j, (i, j) \neq (a, b)} \left( \frac{4\tau}{x_j^0 - x_i^0} + 1 \right) 1 \{ \tau^{P_j} > \tau \} 1 \{ A_{\epsilon, \tau}' \} 1 \{ E_{\tau} \} \right]
\]

\[
\leq \sqrt{\tau} (4\tau + 1)^{\frac{m}{2}} P \left( A_{\epsilon, \tau}' \right).
\]

Since \( P \left( A_{\epsilon, \tau}' \right) \) is exponentially small by equation (4.8), this contribution tends to zero as \( \tau \to \infty \). The contribution on the event \( E_{\tau}^c \cap A_{\epsilon, \tau}' \) is also seen to be negligible by the following calculation:

\[
\frac{\sqrt{\tau}}{h_d(x^0)} E \left[ \prod_{i < j, (i, j) \neq (a, b)} \left( P_j(\tau) + x_j^0 - P_i(\tau) - x_i^0 \right) 1 \{ \tau^{P_j} > \tau \} 1 \{ A_{\epsilon, \tau}' \} 1 \{ E_{\tau}^c \} \right]
\]

\[
\leq \frac{\sqrt{n}}{x_b^0 - x_a^0} E \left[ \prod_{i < j, (i, j) \neq (a, b)} \left( \frac{P_j(\tau) - P_i(\tau)}{x_j^0 - x_i^0} + 1 \right)^{\frac{m}{2}} \frac{1}{P_{\epsilon, \tau}(1 - \Delta_{\epsilon, \tau}(1))} P \left( E_{\tau}^c \right) \right]
\]

where we have employed the generalized Cauchy-Schwarz/Holder inequality \( E \left[ \prod_{i=1}^n X_i \right] \leq \prod_{i=1}^n E \left[ X_i^m \right]^{\frac{1}{m}} \). Since \( P_i(\tau) \) is mean \( \tau \), the event \( E_{\tau}^c \) is a large deviation event. By an exponential Chebyshev inequality for Poisson random variables, we have that \( P \left( E_{\tau}^c \right) \leq \exp (-\tau (2 \ln 2 - \ln 1)) \) is exponentially small. Hence this too vanishes as \( \tau \to \infty \). Since the total contribution on the event \( A_{\epsilon, \tau}' \) vanishes as \( \tau \to \infty \), it must be bounded for all \( \tau \) by some constant \( C_{\epsilon, \tau} \).

The contribution to equation (4.6) on the event \( A_{\epsilon, \tau} \) is seen to be bounded above by

\[
3^{\frac{m}{2}} \frac{1}{P_{\epsilon, \tau}(1 - \Delta_{\epsilon, \tau}(1))} E \left[ \frac{1}{h_d(x^0) \left( X_b(\tau) - X_a(\tau) \right)} \right]
\]

by an identical argument employed in the proof of Lemma 4.11 of [6]. A union bound completes the result.

\[\square\]

**Lemma 4.12.** Fix any indices \( 1 \leq a < b \leq d \). There is a universal constant \( C_{a, b}^g \) that bounds the expected inverse gap size uniformly over all initial conditions \( x^0 \in W \) and all times \( n \in \mathbb{N} \). Namely:

\[
\sup_{\tau \geq 0} \sup_{x^0 \in W \cap \mathbb{R}^d} E \left[ \frac{1}{h_d(x^0) \left( X_b(\tau) - X_a(\tau) \right)} \right] \leq C_{a, b}^g.
\]

**Proof.** Using Lemma 4.11, the proof will follow by the same method as the proof of Lemma 4.13 of [6]. The only other ingredient in this method is the following estimate for the hitting time \( \nu_{\tau, \epsilon} = \inf \{ t \geq 0 : x^0 + \hat{P}(t) \in S_{\tau, \epsilon} \} \) (where \( P(\tau) \) are iid ordinary Poisson processes):

\[
E \left[ h_d(x^0 + P(\tau)) \cdot 1 \left\{ \nu_{\tau, \epsilon} > \tau^{1 - \epsilon} \right\} \right] \leq c_1 h_d(x^0) \exp (-c_2 \tau^\epsilon).
\]
In the setting of random walks in discrete time, this follows directly by application of Lemma 7 and/or Lemma 8 from [8]. The same argument applies to random walks in continuous time as we have here. (The proof of Lemma 7 in [8] goes by looking at blocks of steps with \( n' \) steps and applying the central limit theorem to each block when \( n \to \infty \). The argument works equally well with compensated Poisson trajectories over time \( \tau' \) in the limit \( \tau \to \infty \).)

4.4 De-poissonization – non-intersecting multinomial random walks

In this section we will construct “de-Poissonized” versions of the random processes \( \vec{X}(\tau) \) and \( \vec{X}'(\tau) \). This is needed in order to apply the discrete Tanaka theorem in the next subsection.

**Definition 4.13.** Recall from Definition 2.4 that \( \vec{X}(\tau), \tau > 0 \) denotes \( d \) non-intersecting Poisson processes. Let \( \vec{X}'(\tau) \) be an independent copy. We define a pair of stochastic processes in discrete time \( \vec{Y}(n), \vec{Y}'(n), n \in \mathbb{N} \), which are the de-Poissonized version of \( \vec{X}(\tau), \vec{X}'(\tau) \) as follows. First let \( \tau_n \) be the time at which the processes have made their \( n \)-th jump:

\[
\tau_n \triangleq \inf \left\{ \tau : \sum_{i=1}^d X_i(\tau) - X_i(0) + \sum_{i=1}^d X_i'(\tau) - X_i'(0) \geq n \right\},
\]

and then set \( \vec{Y}(n), \vec{Y}'(n) \) to be the position of the processes at this time:

\[
\vec{Y}(n) \triangleq \vec{X}(\tau_n), \quad \vec{Y}'(n) \triangleq \vec{X}'(\tau_n).
\]

We refer to the pair \( \vec{Y}(n), \vec{Y}'(n) \) as the de-Poissonized version of the pair \( \vec{X}(\tau), \vec{X}'(\tau) \).

**Lemma 4.14.** The time between jumps are independent of each other and are each exponentially distributed with mean \( (2d)^{-1} \), i.e. \( \tau_{n+1} - \tau_n \sim \text{Exp}(2d) \) and the processes \( \vec{Y}, \vec{Y}' \) are Markov processes that evolve according to the following rules:

\[
\mathbb{P} \left( \vec{Y}(n+1) - \vec{Y}(n) = \vec{e}, \vec{Y}'(n+1) - \vec{Y}'(n) = 0 \mid \vec{Y}(n) = \vec{y}, \vec{Y}'(n) = \vec{y}' \right) = \frac{1}{2d} \frac{h_d(\vec{y} + \vec{e})}{h_d(\vec{y})},
\]

\[
\mathbb{P} \left( \vec{Y}(n+1) - \vec{Y}(n) = 0, \vec{Y}'(n+1) - \vec{Y}'(n) = \vec{e}, \vec{Y}(n) = \vec{y}, \vec{Y}'(n) = \vec{y}' \right) = \frac{1}{2d} \frac{h_d(\vec{y}' + \vec{e})}{h_d(\vec{y})}.
\]

**Proof.** We observe from Definition 2.4, by explicitly calculating the determinant that appears, that the time until the next jump for the non-intersecting Poisson processes can be calculated by

\[
\mathbb{P} \left( \vec{X}(\tau + \Delta \tau) = \vec{x}, \vec{X}'(\tau + \Delta \tau) = \vec{x}' \mid \vec{X}(\tau) = \vec{x}, \vec{X}'(\tau) = \vec{x}' \right) = \mathbb{P} \left( \vec{X}(\tau + \Delta \tau) = \vec{x} \mid \vec{X}(\tau) = \vec{x} \right)^2 = e^{-2d(\Delta \tau)}.
\]

This shows that the time until the next jump is exponentially distributed with mean \( (2d)^{-1} \). Since by definition the \( \vec{X}, \vec{X}' \) random walk is absolutely continuous with respect to iid Poisson processes, we know that almost surely only one jump occurs at any time. Hence, we have only to consider jumps of size 1 in each individual component. By again computing the determinant that appears in Definition 2.4, we find the jump rates are characterized by:

\[
\mathbb{P} \left( \vec{X}(\tau + \Delta \tau) = \vec{x} + \vec{e}_i, \vec{X}'(\tau + \Delta \tau) = \vec{x}' \mid \vec{X}(\tau) = \vec{x}, \vec{X}'(\tau) = \vec{x}' \right)
\]
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\[ e^{-d(\Delta \tau)} \left( \Delta \tau \right)^{h_d(x + \xi)} h_d(x) + O(\Delta \tau^2), \]

This shows that each walker is individually a Poisson process with jump rate \( h_d(x)^{-1} h_d(x + \xi) \) for the \( \vec{X} \) process, and \( h_d(x')^{-1} h_d(x' + \xi) \) for the \( \vec{X}' \) process when at the position \( (\vec{X}, \vec{X}') = (\vec{x}, \vec{x}') \). (Note that since the function \( h_d \) is harmonic for the simple random walk, the total jump rate of both the \( \vec{X} \) and \( \vec{X}' \) process is always \( d \).) By the definition of the \( \{\vec{Y}, \vec{Y}'\} \) process and the fact that only one jump occurs at a time, we get the desired result. \( \square \)

**Corollary 4.15.** Let \( (\vec{\xi}, \vec{\xi}') \in \mathbb{N}^d \times \mathbb{N}^d \) be the multinomial random vector whose probability distribution is:

\[
\begin{align*}
\mathbb{P} (\vec{\xi} = \vec{\xi}, \vec{\xi}' = \vec{0}) &= \frac{1}{2^d} \forall 1 \leq i \leq d, \\
\mathbb{P} (\vec{\xi} = \vec{0}, \vec{\xi}' = \vec{\xi}) &= \frac{1}{2^d} \forall 1 \leq i \leq d.
\end{align*}
\]

Let \( (\vec{Z}(n), \vec{Z}'(n)) \ n \in \mathbb{N} \) be the stochastic process whose increments are given by an iid sequence of these multinomial random vectors \( \vec{Z}(n) \overset{d}{=} \sum_{j=1}^n \vec{\xi}_j \) and \( \vec{Z}'(n) \overset{d}{=} \sum_{j=1}^n \vec{\xi}_j' \). Then law of the de-Poissonized process \( \{\vec{Y}(n), \vec{Y}'(n)\} \) is identical in distribution to the law of \( \{\vec{Z}(n), \vec{Z}'(n)\} \) conditioned on non-intersection in the sense of the Doob \( h \)-transform for the event

\[
\{Z_i(n) < Z_j(n) \forall 1 \leq i < j \leq d, \forall n \in \mathbb{N}\} \cap \{Z'_i(n) < Z'_j(n) \forall 1 \leq i < j \leq d, \forall n \in \mathbb{N}\}.
\]

**Proof.** We firstly notice that the transition probabilities for each walk individually can be calculated from the transition rates given in Lemma 4.14 and the identity \( \frac{1}{d} \sum_{i=1}^d \frac{h_d(x + \xi)}{h_d(x)} = 1 \) (see e.g. Theorem 2.1 [18] for this identity). This shows that each process \( \vec{Y}(n) \) and \( \vec{Y}'(n) \) taken individually is a Markov process with respect to its own filtration with transition probabilities given by:

\[
\begin{align*}
\mathbb{P} (\vec{Y}(n + 1) = \vec{y}, \vec{Y}'(n) = \vec{y}') &= \frac{1}{2^d} \frac{h_d(y + \xi)}{h_d(y)}. \\
\mathbb{P} (\vec{Y}(n + 1) = \vec{0}, \vec{Y}'(n) = \vec{y}') &= \frac{1}{2}.
\end{align*}
\]

Moreover, we notice that the interaction between the walks \( \vec{Y} \) and \( \vec{Y}' \) is that one jumps precisely when the other does not. The result of the Corollary then follows by noticing that the jump rates for \( \vec{Y}, \vec{Y}' \) exactly match those of the Doob \( h \)-transform by the Vandermonde determinant for the multinomial walks. \( \square \)

**Remark 4.16.** Corollary 4.15 shows that the de-Poissonized process \( \{\vec{Y}(n), \vec{Y}'(n)\} \) constructed in Definition 4.13 has the same law as non-intersecting multinomial random walks. It will also be convenient for us to think of the reverse construction: first constructing the non-intersecting multinomial walks \( \{\vec{Y}(n), \vec{Y}'(n)\} \), and then using this to build the non-intersecting Poisson processes \( \{\vec{X}(\tau), \vec{X}'(\tau)\} \). Corollary 4.17 records this construction.

**Corollary 4.17.** Suppose we are given the non-intersecting multinomial processes \( \{\vec{Y}(n), \vec{Y}'(n)\} \) which are constructed as in Corollary 4.15 and an independent sequence \( \{\xi_i\}_{i=1}^{\infty} \sim \text{Exp}(2d) \) of iid mean \( (2d)^{-1} \) exponential random variables. Let
\[ n_\tau = \inf \{ n : \sum_{i=1}^n \xi_i > \tau \}. \] Then the process \( (\bar{X}(\tau), \bar{X}'(\tau)) = (\bar{Y}(n_\tau), \bar{Y}'(n_\tau)) \) is a realization of the non-intersecting Poisson processes.

**Lemma 4.18.** For any indices \( 1 \leq a < b \leq d \), there exists a constant \( C_{a,b}^\gamma \) so that each of the de-Poissonized random walks \( \bar{Y} \) or \( \bar{Y}' \) have:

\[
\sup_{n \in \mathbb{N}} \sup_{\|x\| \leq \|y\|} E_{\mathbb{R}^d} \left[ \frac{1}{\sqrt{n}} (Y_a(n) - Y_b(n)) \right] \leq C_{a,b}^\gamma.
\]

**Proof.** By the result of Lemma 4.14 of the de-Poissonized random walks \( \bar{Y}, \bar{Y}' \), we know that \( \bar{Y}(n) = \bar{X}(\tau_n) \) where the random times \( \tau_n \leq \sum_{i=1}^n \xi_i \) are distributed as a sum of \( n \) exponential random variables of mean \( (2d)^{-1} \). Thus, denoting by \( \rho_{\tau_n}(\cdot) \) the density of the \( \tau_n \) random variable and applying the bound from Lemma 4.11, we have

\[
\sqrt{n} \frac{1}{\sqrt{n}} E_{\mathbb{R}^d} \left[ \frac{1}{\sqrt{n}} (X_a(n) - X_b(n)) \right] \leq \sqrt{n} \Gamma(n - \frac{1}{2}) \Gamma(n)^{-1} \text{ for } n \geq 2.
\]

**Lemma 4.19.** For any \( t^* > 0 \) and any indices \( 1 \leq a < b \leq d \), the collection of processes

\[
\left\{ \frac{1}{\sqrt{N}} \sum_{i=1}^{\lfloor tN \rfloor} \frac{1}{Y_b(i) - Y_a(i)} : t \in [0, t^*] \right\}_{N \in \mathbb{N}},
\]

is weakly exponential moment controlled as \( t \to 0 \).

**Proof.** Using the bound from Lemma 4.18, the proof follows exactly in the same way as the proof of Lemma 4.14 from [6], which is obtained by estimating the moments of the random process.

**Lemma 4.20.** Recall that \( \bar{Y}_k \) denotes the position of the \( k \)-th line of the de-Poissonized walks. The collection of processes:

\[
\left\{ \frac{1}{\sqrt{N}} \|2dY_k([tN]) - [tN]\| : t \in [0, t^*] \right\}_{N \in \mathbb{N}},
\]

is weakly exponential moment controlled as \( t \to 0 \).

**Proof.** Let \( \{\xi_i\}_{i=1}^\infty \) be the family of mean \( (2d)^{-1} \) exponential random variables that relate \( \bar{Y}, \bar{Y}' \) with \( \bar{X}, \bar{X}' \). Set \( \tau_n = \sum_{i=1}^n \xi_i \). Notice that to prove the lemma it suffices to show that

\[
\left\{ \frac{1}{\sqrt{N}} \|Y_k([tN]) - \tau_{[tN]}\| : t \in [0, t^*] \right\}
\]

is weakly exponential moment controlled, because then the result follows by the inequality:

\[
\frac{1}{\sqrt{N}} \|2dY_k([tN]) - [tN]\| \leq 2d \frac{\|Y_k([tN]) - \tau_{[tN]}\|}{\sqrt{N}} + 2d \frac{\|\tau_{[tN]} - \frac{1}{2} [tN]\|}{\sqrt{N}},
\]

and the fact that a sum of weakly exponential moment controlled random variables is again weakly exponential moment controlled by Lemma 4.6 (it is easily verified that
where we have applied the inequality from Lemma 4.15 of [6], which holds since $s > tN$. But by the definition of the de-Poissonized random walks $\tilde{Y}, \tilde{Y}'$, we know that $\tilde{Y}([tN]) = \hat{X}(\tau_{tN})$. Writing $\rho_{\tau_{tN}}$ for the density of $\tau_{tN}$, and letting $C$ be the constant from Lemma 4.9, make the following estimate for any $\alpha \in \mathbb{R}$:

$$
P \left( |\tilde{Y}_k (\{tN\}) - \tau_{tN}| > \alpha \sqrt{N} \right) = \int_0^\infty P \left( |\tilde{Y}_k (\{tN\}) - \tau_{tN}| > \alpha \sqrt{N} | \tau_{tN} = s \right) \rho_{\tau_{tN}}(s) ds
$$

$$
= \int_0^\infty P \left( |X_k (s) - s| > \alpha \sqrt{N} \right) \rho_{\tau_{tN}}(s) ds
$$

$$
\leq \int \left( C \exp \left( -c \frac{N^2 \alpha^2}{N} \right) + C \exp \left( -c\sqrt{N} \alpha \right) \right) \rho_{\tau_{tN}}(s) ds
$$

$$
\leq C \exp \left( -c \frac{N \alpha^2}{N^2} \right) Nt + C P \left( \tau_{tN} > Nt \right) + C \exp \left( -c\sqrt{N} \alpha \right),
$$

where we have split the integral into the contribution from $s \leq Nt$ and $s > Nt$ to get the last inequality. Notice that typically $\tau_{tN} \sim \frac{tN}{2d}$, so $P \left( \tau_{tN} > tN \right)$ is a large deviation event; an application of the exponential Chebyshev inequality gives $P \left( \tau_{tN} > tN \right) \leq \exp \left( -tN \left( 1 - \ln \left( \frac{2d}{2d-1} \right) \right) \right)$. Finally, the weak exponential control follows from this bound by Lemma 4.7 and Lemma 4.4. \hfill \Box

**Lemma 4.21.** Denote by $\Delta Y_k(i) \overset{\text{d}}{=} Y_k(i+1) - Y_k(i)$. We have that the collection of processes

$$
\left\{ \frac{1}{\sqrt{N}} \sum_{n=1}^{\lfloor tN \rfloor} E \left[ 2d \Delta Y_k(n) - 1 \mid \tilde{Y} (n) \right] : t \in [0, t^*] \right\}_{N \in \mathbb{N}},
$$

is weakly exponential moment controlled.

**Proof.** By expanding the Vandermonde determinants that appear in equation (4.10), we have that:

$$
P \left( \Delta Y_k(n) = +1 \mid \tilde{Y}(n) = \bar{x} \right) = \frac{1}{2d} \prod_{i \neq k} \left( 1 + \frac{1}{x_k - x_i} \right),
$$

and hence we compute

$$
E \left[ 2d \Delta Y_k(n) - 1 \mid \tilde{Y}(n) = \bar{x} \right] \leq \prod_{i \neq k} \left( 1 + \frac{1}{x_k - x_i} \right) - \left( 1 + \sum_{i \neq k} \frac{1}{x_k - x_i} \right) + \sum_{i \neq k} \left| \frac{1}{x_k - x_i} \right|
$$

$$
\leq 2^d \sum_{i \neq k} \left| \frac{1}{x_k - x_i} \right|,
$$

where we have applied the inequality from Lemma 4.15 of [6], which holds since $\frac{1}{x_k - x_i} \leq 1$. Finally then:

$$
\frac{1}{\sqrt{N}} \sum_{n=1}^{\lfloor tN \rfloor} E \left[ 2d \Delta Y_k(n) - 1 \mid \tilde{Y} (n) \right] \leq 2^d \sum_{i \neq k} \frac{1}{\sqrt{N}} \sum_{n=1}^{\lfloor tN \rfloor} \left| Y_k(n) - Y_i(n) \right|,
$$


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and the result follows by the weak exponential moment control established in Lemma 4.19 and since weak exponential moment control is preserved under finite sums by Lemma 4.6.

4.5 Overlap times of non-intersecting multinomial random walks

In this subsection we establish the exponential moment control for overlap times by using a discrete version of Tanaka’s formula. This is like Tanaka’s formula in that it relates the overlap time to increments of the random walk. For our purposes, we only need an upper bound on the overlap time which simplifies the proof somewhat. This inequality will bound the overlap time by a finite sum of quantities, each of which is analyzed to establish exponential moment control. The methods here are similar to those used for non-intersecting random walks in [6].

Lemma 4.22. Let \( u \in \mathbb{N} \) be any positive integer. Suppose that \( A(n) \) is an integer-valued process whose increments are always either +1 or −1, i.e. we have \( \Delta A(n) = A(n+1) - A(n) \in \{u, -1\} \). Then for any \( C \in \mathbb{Z} \) we have the inequality

\[
1 \{ |A(n) - C| = 0 \} \left| \Delta A(n) \right| + (\Delta A(n)) \operatorname{sgn}(A(n) - C) \leq |A(n+1) - C| - |A(n) - C|,
\]

where the \( \operatorname{sgn} \) function uses the convention that \( \operatorname{sgn}(x) = x/|x| \) for \( x \neq 0 \) and \( \operatorname{sgn}(0) = 0 \).

Proof. The proof goes by comparing the LHS and the RHS in several cases.

Case i) \( |A(n) - C| = 0 \).

It is easily verified that both sides of equation (4.11) are equal to \( |\Delta A(n)| \).

Case ii) \( |A(n) - C| \neq 0 \), and \( \operatorname{sgn}(A(n) - C) = \operatorname{sgn}(A(n+1) - C) \) or \( A(n+1) - C = 0 \).

We may write that \( |A(n) - C| = \operatorname{sgn}(A(n) - C) (A(n) - C) = \operatorname{sgn}(A(n+1) - C) (A(n+1) - C) \). Factor \( \operatorname{sgn}(A(n) - C) \) from the RHS of (4.11) to get:

\[
|A(n+1) - C| - |A(n) - C| = \operatorname{sgn}(A(n) - C) ((A(n+1) - C) - (A(n) - C))
= \operatorname{sgn}(A(n) - C) \Delta A(n).
\]

This is exactly equal to the LHS of (4.11) since \( |A(n) - C| \neq 0 \) here.

Case iii) \( A(n) - C < 0 \) and \( A(n+1) - C > 0 \).

This can happen only if \( \Delta A(n) = u \) and \( A(n) - C \in [-u+1, -1] \). In particular \( A(n) - C \geq -u \). In this case, the LHS of (4.11) is \( -u \), while the RHS is

\[
|A(n+1) - C| - |A(n) - C| = \Delta A(n) + 2 (A(n) - C)
= u + 2 (A(n) - C) \geq -u,
\]

which verifies the desired inequality.

Case iv) \( A(n) - C > 0 \) and \( A(n+1) - C < 0 \).

This case is impossible by hypothesis on the process \( A(n) \), since \( \Delta A(n) \geq -1 \) always.

\[\square\]

Lemma 4.23. Let \( u \in \mathbb{N} \) be any positive integer. Suppose that \( A(n) \) and \( B(n) \) are integer valued processes so that the increments are always +1 or −1, i.e. we have that \( \Delta A(n) \in \{u, -1\} \) and \( \Delta B(n) \in \{u, -1\} \). Then

\[
\sum_{i=0}^{n} 1 \{ A(i) = B(i) \} \leq |A(n+1) - B(n+1)| - |A(0) - B(0)|
- \sum_{i=0}^{n} \operatorname{sgn}(A(i) - B(i)) \Delta A(i) + \sum_{i=0}^{n} \operatorname{sgn}(A(i+1) - B(i)) \Delta B(i).
\]


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where we define $S_{\text{weakly exponential moment controlled.}}$. The first two terms on the RHS of equation which have increments of either $2$ will apply the upper bound for the overlap time from Lemma 4.23, to the processes:

The result then follows by applying Lemma 4.22 twice, first to the $B$-process with $C = A(i + 1)$ and then again to the $A$-process with $C = B(i)$, and then summing the resulting inequality from $i = 0$ to $n$. □

**Lemma 4.24.** Define the overlap time for the non-intersecting multinomial random walks between the $k$-th line $Y_k$ and the $\ell$-th line $Y_{\ell}'$ by:

$$Q_{k,\ell}[0,n] = \sum_{i=0}^{n} \mathbb{1}\{Y_k(i) = Y_{\ell}'(i)\}.$$ 

Then, for any fixed $t^* > 0$, and any indices $1 \leq k < \ell \leq d$, the collection:

$$\left\{ \frac{1}{\sqrt{N}}Q_{k,\ell}[0,\lfloor tN \rfloor] : t \in [0,t^*] \right\}_{N \in \mathbb{N}},$$

is weakly exponential moment controlled as $t \to 0$.

**Proof.** For notational convenience, we use the shorthand $\Delta F(i) = F(i + 1) - F(i)$. We will apply the upper bound for the overlap time from Lemma 4.23, to the processes:

$$A(i) \triangleq 2dY_k(i) - i, \ A'(i) \triangleq 2dY_{\ell}'(i) - i, \quad (4.12)$$

which have increments of either $2d - 1$ or $-1$. (Notice that the increments of these process are $\Delta A(i) = 2dY_k(i) - 1$ and $\Delta A'(i) = 2dY_{\ell}'(i) - 1$.) By the definition of $Q_{k,\ell}[0,\lfloor tN \rfloor]$ and application of Lemma 4.23 we have:

$$Q_{k,\ell}[0,\lfloor tN \rfloor] \quad (4.13)$$

$$= \sum_{i=0}^{n} \mathbb{1}\{A(i) = A'(i)\} \leq |A(\lfloor tN \rfloor + 1)| + |A'(\lfloor tN \rfloor + 1)| + |S(\lfloor tN \rfloor)| + |S'(\lfloor tN \rfloor)|, \quad (4.14)$$

where we define $S(n)$ and $S'(n)$ by:

$$S(n) \triangleq \sum_{i=0}^{n} \text{sgn}(A(i) - A'(i)) \Delta A(i), \ S'(n) \triangleq \sum_{i=0}^{n} \text{sgn}(A(i + 1) - A'(i)) \Delta A'(i). \quad (4.15)$$

By Lemma 4.6, to see the exponential moment control for $N^{-\frac{1}{2}}Q_{k,\ell}[0,\lfloor tN \rfloor]$, we have only to verify that the four terms that appear on the RHS of equation (4.14) are each weakly exponential moment controlled. The first two terms on the RHS of equation (4.14) are weakly exponential moment controlled by Lemma 4.20. We show that $\left\{N^{-\frac{1}{2}}S(\lfloor tN \rfloor) : t \in [0,t^*]\right\}_{N \in \mathbb{N}}$ and $\left\{N^{-\frac{1}{2}}S'(\lfloor tN \rfloor) : t \in [0,t^*]\right\}_{N \in \mathbb{N}}$ are weakly exponential moment controlled as $t \to 0$ as follows. First notice that by the triangle inequality that

$$\left| \frac{1}{\sqrt{N}}S(\lfloor tN \rfloor) \right| \leq \left| \frac{1}{\sqrt{N}}M(\lfloor tN \rfloor) \right| + \frac{1}{\sqrt{N}}\sum_{i=0}^{\lfloor tN \rfloor} \mathbb{E}\left[\Delta A(i) \big| \check{Y}(i) \right|, \quad (4.16)$$

where we define

$$M(n) \triangleq \sum_{i=0}^{n} \text{sgn}(A(i) - A'(i))(\Delta A(i) - \mathbb{E}\left[\Delta A(i) \big| \check{Y}(i) \right|).$$
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By Lemma 4.6 it suffices to check that both terms that appear on the RHS of equation (4.16) are weakly exponential moment controlled. The second term in equation (4.16) is weakly exponential moment controlled by application of Lemma 4.21. To handle the first term, we notice that \( \{M(n)\}_{n \in \mathbb{N}} \) is a martingale with respect to the filtration \( \mathcal{F}_n \triangleq \sigma \left( \vec{Y}(1), \vec{Y}'(1), \ldots, \vec{Y}(n+1), \vec{Y}'(n+1) \right) \). Its increments are given by

\[
M(n) - M(n-1) = \text{sgn} (A(n) - A'(n)) \left( \Delta A(n) - \mathbb{E} \left[ \Delta A(n) \right] \right),
\]

which have \( \mathbb{E} |M(n) - M(n-1)\|_{\mathcal{F}_{n-1}} = 0 \) as \( \text{sgn} (A(n) - A'(n)) = \text{sgn} (Y_k(n) - Y'_k(n)) \) is \( \mathcal{F}_{n-1} \)-measurable and since \( \vec{Y}() \) is a Markov process. Moreover, since \( \Delta A(n) \in \{-1, +2d - 1\} \), we also notice from equation (4.17) that \( |M(n) - M(n-1)| \leq 2d \). We can therefore apply Azuma’s inequality for martingales with bounded differences (see e.g. Lemma 4.1 of [21]). This gives that for any \( N \in \mathbb{N} \)

\[
P \left( \frac{1}{\sqrt{N}} |M([tN])| > \alpha \right) \leq 2 \exp \left( -\frac{\alpha^2}{2t(2d)^2} \right),
\]

By Lemma 4.4, this shows that \( \left\{ |N^{-\frac{1}{2}} M([tN])| : t \in [0, t^*] \right\}_{N \in \mathbb{N}} \) is exponential moment controlled as desired.

The proof that \( \left\{ |N^{-\frac{1}{2}} S([tN])| : t \in [0, t^*] \right\}_{N \in \mathbb{N}} \) is exponential moment controlled is similar using the martingale

\[
M'(n) \triangleq \sum_{i=0}^{n} \text{sgn} (A(i+1) - A'(i)) \left( \Delta A'(i) - \mathbb{E} \left[ \Delta A'(i) \right] \right),
\]

which is a martingale w.r.t. \( \mathcal{F}_n' \triangleq \sigma \left( \vec{Y}(1), \vec{Y}'(1), \ldots, \vec{Y}(n+1), \vec{Y}'(n+1), \vec{Y}(n+2) \right) \).

### 4.6 Overlap times of non-intersecting Poisson processes and bridges

In this section we prove that the overlap times for non-intersecting Poisson processes are weakly exponential moment controlled by comparison to the overlap time for the de-Poissonized walks.

**Lemma 4.25.** Recall the definition of the overlap time \( O_{k,\ell}[a, b] \) for the Poisson random walks. For any fixed \( t^* > 0 \), and any indices \( 1 \leq k, \ell \leq d \), the collection:

\[
\left\{ \frac{1}{\sqrt{N}} O_{k,\ell}[0, tN] : t \in [0, t^*] \right\}_{N \in \mathbb{N}},
\]

is weakly exponential moment controlled as \( t \to 0 \).

**Proof.** By Lemma 4.14, we know that we can construct a coupling of the non-intersecting Poisson processes \( \left( \vec{X}(t), \vec{X}'(t) \right) \) \( t > 0 \) and the non-intersecting multinomial walks \( \left( \vec{Y}(n), \vec{Y}'(n) \right), n \in \mathbb{N} \) along with a sequence \( \{\xi_i\}_{i=1}^\infty \) of iid mean \( (2d)^{-1} \) exponential random variables so that \( \vec{X}(\tau_n) = \vec{Y}(n) \) and \( \vec{X}'(\tau_n) = \vec{Y}'(n) \) where \( \tau_n \triangleq \sum_{i=1}^n \xi_i \). In this coupling, the overlap time \( O_{k,\ell} \) between \( X \) and \( X' \) can be written in terms of the \( \vec{Y}(n), \vec{Y}'(n), \{\xi_i\}_{i=1}^\infty \) as

\[
O_{k,\ell}[0, tN] \leq \sum_{i=1}^{\eta(tN) + 1} \left\lfloor \frac{\tau_{i+1}}{\tau_{i}} \right\rfloor \{X_k(\tau) = X_{\ell}(\tau)\} \, d\tau = \sum_{i=1}^{\eta(tN)} \xi_{i+1} \{Y_k(i) = Y_{\ell}(i)\},
\]
where \( \eta(t) = \max \{ n : \tau_n \leq t \} \) is the number of steps which have been taken up to time \( t \). Since the \( \xi_i \) are independent of the walk \( Y \), the only thing that is relevant for the distribution of the above is the number of times \( i \) for which \( Y_k(i) = Y_i(i) \). This is exactly counted by the discrete overlap times for the multinomial walkers \( Q_{k,t}[0, \eta(tN)] \). In particular, if we label the indices \( i \) for which \( \{ Y_k(i) = Y_i(i) \} \) as \( i_1, i_2, \ldots \), then we have:

\[
\{ O_{k,t}[0, tN] > x \sqrt{N}\} \subset \{ \eta(tN) > c_1 tN \} \cup \{ Q_{k,t}[0, c_1 tN] > c_2 x \sqrt{N}\} \cup \left\{ \sum_{j=1}^{\lfloor c_2 x \sqrt{N}\rfloor} \xi_{ij} > x \sqrt{N} \right\},
\]

(4.18)

where \( c_1, c_2 \) are some to-be-determined constants that depend on \( d \). Since \( \{ \eta(tN) > \} \subset \{ \sum_{i=1}^{tN} \xi_i < tN \} \), we can use the exponential Chebyshev inequality to estimate

\[
P(\eta(tN) > c_1 tN) \leq E[\exp(-\xi_1)]^{c_1 tN} \exp(tN) = \exp\left( tN \left( c_1 \ln \left( \frac{2d}{2d+1} \right) + 1 \right) \right),
\]

and similarly we have:

\[
P\left( \sum_{i=1}^{c_1 x \sqrt{N}} \xi_{ij} > x \sqrt{N} \right) \leq \exp\left( x \sqrt{N} \left( c_1 \ln \left( \frac{2d}{2d-1} \right) - 1 \right) \right).
\]

If we choose \( c_1 \) and \( c_2 \) to be any constants so that \( c_1 \ln \left( \frac{2d}{2d+1} \right) + 1 < 0 \) and \( c_2 \ln \left( \frac{2d}{2d-1} \right) - 1 < 0 \), then these probabilities are both exponentially small. Thus by the inclusion from equation (4.18) we have:

\[
P \left( \frac{1}{\sqrt{N}} O_{k,t}[0, tN] > x \right) \leq \exp\left( tN \left( c_1 \ln \left( \frac{2d}{2d+1} \right) + 1 \right) \right) + \exp\left( x \sqrt{N} \left( c_2 \ln \left( \frac{2d}{2d-1} \right) - 1 \right) \right).
\]

It is easily verified from Definition 4.2 and the conclusion of Lemma 4.24 that for any fixed positive constants \( c_1, c_2 \) that the process \( \left\{ c_1^{-1} N^{-\frac{1}{2}} Q_{k,t}[0, c_1 tN] : t \in [0, t^*] \right\} \) is weakly exponential moment controlled. Finally the weak exponential moment control for \( O_{k,t} \) follows by Lemma 4.7.

**Proposition 4.26.** Recall from Definition 2.4 the probability function \( q_{\tau}(\vec{x}, \vec{y}) \) which was used in the construction of the non-intersecting Poisson walks. We have the following exact formula:

\[
q_{\tau}(\vec{x}, (0), \vec{x}) = \frac{1}{\tau^{d(d+1)/2}} \prod_{i=1}^{d} \mu(\tau, x_i) \cdot h_d(x_1, x_2, \ldots, x_d).
\]

Proof. The determinant that defines \( q_{\tau} \) in this case is explicitly calculated as part of the proof of Proposition 3.3 in [18].

**Lemma 4.27.** Fix any \( z^* \in \mathbb{R} \) and \( t^* > 0 \). There is a constant \( C_{R}^{(t^*, z^*}, < \infty \) so that the Radon-Nikodym derivative of the rescaled non-intersecting Poisson bridge \( \sqrt{N} X^{(tN), (t^*, z^*)}(t) \) with respect to the rescaled non-intersecting Poisson process \( \frac{1}{\sqrt{N}} X^{(tN)}(t) \) is uniformly bounded by \( C_{R}^{(t^*, z^*}, \) over all possible positions at all times \( t \) that have \( t < \frac{1}{4} t^* \):

\[
\sup_{N \in \mathbb{N}} \sup_{t \leq \frac{1}{4} t^*} \sup_{z \in \mathbb{R}} \frac{P \left( \sqrt{N} X^{(tN), (t^*, z^*)}(t) = z \right)}{P \left( \frac{1}{\sqrt{N}} X^{(tN)}(t) = \bar{z} \right)} \leq C_{R}^{(t^*, z^*)}.
\]
Thus we conclude after plugging these formulas into equation (4.19) and observing that $4.25$, the Radon-Nikodym bound between Poisson processes and Poisson bridges from Definition 4.1. For any $t$ from Definition 4.6, and the fact that weak exponential moment control is closed under addition Proposition 4.28. Recall the definition of the rescaled overlap time $LHS$ of equation (4.21), is finite as desired.

Since this limsup as $N \to \infty$ is finite, we conclude that the sup over all $N \in \mathbb{N}$, as in the LHS of equation (4.21), is finite as desired. 

Proof. By Definition 2.5, we have
\[
\frac{P\left(\bar{X}(\tau, x^*) (\tau) = \bar{x}\right)}{P\left(\bar{X}(\tau) = \bar{x}\right)} = \frac{q_{\tau, \tau} (\bar{x}, \bar{\delta}_d (x^*)) h_d (\bar{\delta}_d (0))}{q_{\tau, \tau} (\bar{\delta}_d (0), \bar{\delta}_d (x^*)) h_d (\bar{x})}.
\] (4.19)

From our exact formula from Proposition 4.26 for $q_{\tau, \tau} (\bar{\delta}_d (0), \bar{x})$ and the time reversal of this formula which yields a similar formula for $q_{\tau, \tau} (\bar{x}, \bar{\delta}_d (x^*))$, we have:
\[
q_{\tau} (\bar{\delta}_d (0), \bar{x}) = \tau^{-d(d+1)/2} \prod_{i=1}^{d} \mu (\tau, x_i) \cdot h_d (x_1, x_2, \ldots, x_d).
\]
\[
q_{\tau} (\bar{x}, \bar{\delta}_d (x^*)) = \tau^{-d(d+1)/2} \prod_{i=1}^{d} \mu (\tau, x^* + i - 1 - x_i) \cdot h_d (x^* + d - x_d, \ldots, x^* + d - x_1)
\]
\[
= \tau^{-d(d+1)/2} \prod_{i=1}^{d} \mu (\tau, x^* + i - 1 - x_i) \cdot h_d (x_1, \ldots, x_d).
\]

Thus we conclude after plugging these formulas into equation (4.19) and observing that the Vandermonde factors $h_d$ cancel out that we remain with
\[
\frac{P\left(\bar{X}(\tau, x^*) (\tau) = \bar{x}\right)}{P\left(\bar{X}(\tau) = \bar{x}\right)} = \left(\frac{\tau^* - \tau}{\tau^*}\right)^{-d(d+1)/2} \prod_{i=1}^{d} \frac{\mu (\tau^* - \tau, x^* + i - 1 - x_i)}{\mu (\tau^*, x^*)}.
\] (4.20)

Putting in now the scaling $\tau = Nt, \tau^* = Nt^*, \bar{x} = Nt + \sqrt{N} \bar{z}, x^* = Nt^* + \sqrt{N} z^*$, we see by the local limit theorem for the Poisson process Proposition A.2, that
\[
\lim_{N \to \infty} \sup_{N \to \infty} \frac{1}{\sqrt{N^* \mu (\tau^*, x^*)}} = \sqrt{2\pi} \exp \left(\frac{z^2}{2t^*}\right),
\]
\[
= \frac{1}{\sqrt{2\pi}} \exp \left(-\frac{(z^* - z)^2}{2(t^* - t)}\right) \leq \frac{1}{\sqrt{2\pi}},
\]

and hence, putting this result back into equation (4.20), we conclude that
\[
\lim_{N \to \infty} \sup_{N \to \infty} \sup_{t \leq \frac{N}{2}, z \leq \frac{N}{2}} \frac{P\left(\bar{X}(\tau) = \bar{z}\right)}{P\left(\bar{X}(t) = \bar{z}\right)} \leq 3^{d(d+1)/2} \exp \left(\frac{z^2}{2t^*}\right).
\] (4.21)

Since this limsup as $N \to \infty$ is finite, we conclude that the sup over all $N \in \mathbb{N}$, as in the LHS of equation (4.21), is finite as desired. 

Proof. The proof is very similar to the proof of Proposition 4.23 from [6] using the exponential moment control for the non-intersecting Poisson processes from Lemma 4.25, the Radon-Nikodym bound between Poisson processes and Poisson bridges from Lemma 4.27, and the fact that weak exponential moment control is closed under addition as in Lemma 4.6.  

Proposition 4.28. Recall the definition of the rescaled overlap time $O(N, t, z^*)[0, t]$ from Definition 4.1. For any $t^* > 0$ and $z^* \in \mathbb{R}$, the collection of rescaled overlap times
\[
\left\{O(N, t, z^*)[0, t], t \in [0, t^*]\right\}_{N \in \mathbb{N}},
\]
is weakly exponential moment controlled as $t \to 0$. 

Proof. The proof is very similar to the proof of Proposition 4.23 from [6] using the exponential moment control for the non-intersecting Poisson processes from Lemma 4.25, the Radon-Nikodym bound between Poisson processes and Poisson bridges from Lemma 4.27, and the fact that weak exponential moment control is closed under addition as in Lemma 4.6.  

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5 $L^2$ bounds – Proof of Propositions 2.19, 2.26, 2.27

This section uses the weak exponential moment control established in Proposition 4.28 to get bounds the $L^2$ norm of the $k$-point correlation function $\psi_k^{(\tau',z')}$. These arguments are a semi-discrete version of those used in Section 5 of [6].

**Lemma 5.1.** If $\{Z(t) : t \in [0,t']\}_{t \in \mathbb{R}}$ is weakly exponential moment controlled as $t \to 0$, then for each $t \in [0,t']$, there exists $N_0$ such that $Z(t)$ has moments of all orders which are uniformly bounded in $N$:

$$\forall k > 0, \forall t \in [0,t'] \sup_{N > N_0} E \left[ \left( Z(t) \right)^k \right] < \infty.$$

Moreover, for any fixed $k$, the $k$-th moment can be made arbitrarily small in the following precise sense: for any $\epsilon > 0$, there exists $N_{\epsilon,k}$ large enough so that:

$$\limsup_{t \to 0} \sup_{N > N_{\epsilon,k}} E \left[ \left( Z(t) \right)^k \right] < \epsilon.$$

**Proof.** Fix any $\gamma > 0$ and then use the inequality $x^k \leq \frac{k! \gamma^k}{\gamma^k}$ for $x \geq 0$ and property i) of the weak exponential moment control to find $N_{\gamma} \in \mathbb{N}$ so large so that we have:

$$\sup_{N > N_{\gamma}} E \left[ \left( Z(t) \right)^k \right] \leq \frac{k!}{\gamma^k} \sup_{N > N_{\gamma}} E \left[ e^{\gamma Z(t)} \right] < \infty,$$

which is finite by property i) of the exponential moment control from Definition 4.2. This establishes the first conclusion of the lemma. To see the second point, for any fixed $k \in \mathbb{N}$ and $\epsilon > 0$, choose $\gamma$ large enough so that $\epsilon \gamma^k > 2k!$, and then apply property ii) of the weak exponential moment control to find $N_{\gamma,1}$ large enough so that we have the following:

$$\limsup_{t \to 0} \sup_{N > N_{\gamma,1}} E \left[ \left( Z(t) \right)^k \right] \leq \frac{k!}{\gamma^k} \limsup_{t \to 0} \sup_{N > N_{\epsilon,k}} E \left[ e^{\gamma Z(t)} \right] \leq \frac{k!}{\gamma^k} (1 + 1) \leq \epsilon.$$

\[ \square \]

**Lemma 5.2.** Recall from Definition 4.1 the overlap time $O^{(\tau',x')}[s,s']$ between the processes $\tilde{X}^{(\tau',x')}$ and $\tilde{X}^{(\tau',x')}$. We have the inequality:

$$\frac{1}{j!} (O^{(\tau',x')}[s,s'])^j \geq \sum_{\varrho \in \Delta_j(s,s')} \sum_{x \in \{1,\ldots,x'\}^k} \prod_{i=1}^j \left\{ x_i \in \tilde{X}^{(\tau',x')}(\tau_i) \right\} \cap \left\{ x_i \in \tilde{X}^{(\tau',x')}(\tau_i) \right\} d\tau_1 \cdots d\tau_j.$$

(5.1)

**Proof.** By Definition 4.1 we have

$$\left( O^{(\tau',x')}[s,s'] \right)^j = \left( \int \sum_{x} 1 \left\{ x \in \tilde{X}^{(\tau',x')}(\tau) \right\} 1 \left\{ x \in \tilde{X}^{(\tau',x')}(\tau) \right\} d\tau \right)^j.$$

(5.2)

The desired inequality follows by expanding the RHS of equation (5.2) as a $j$-fold integral/sum. We then switch from an un-ordered integral over $\varrho \in (s,s')^j$ to an ordered integral over $\varrho \in \Delta_j(s,s')$ at the cost of the factor $j!$, which completes the result. \[ \square \]
Corollary 5.3. For $0 < s < s' < t^*$, we have that:

$$
\int_{\mathcal{D}_j(s,s') \times \mathbb{R}^k} \mathbb{P} \left( \sum_{i=1}^j \{ x_i \in \bar{X}(\tau^*,x^*) (\tau_i) \} \right)^2 \, dt_1 \ldots dt_j \leq \mathbb{E} \left[ \frac{1}{j!} \left( O(\tau^*,x^*) [s,s'] \right)^2 \right].
$$

Proof. Notice that since the processes $\bar{X}(\tau^*,x^*)$ and $\bar{X}(\tau^*,x^*)$ are independent, we have

$$
\mathbb{E} \left[ \mathcal{B} \left( \{ x_i \in \bar{X}(\tau^*,x^*) (\tau_i) \} \cap \{ x_i \in \bar{X}(\tau^*,x^*) (\tau_i) \} \right) \right] = \mathbb{P} \left( \sum_{i=1}^j \{ x_i \in \bar{X}(\tau^*,x^*) (\tau_i) \} \right)^2,
$$

where we have applied the definition of $\psi_j^{(N)}(t^*,x^*)$ from Definition 2.16. The desired results follows by taking $\mathbb{E}$ of both sides of the inequality in equation (5.1). \qed

Corollary 5.4. Recall from Definition 4.1 the rescaled overlap time $O(N,j,t^*,x^*) \mathbb{P} \{ \{ x_i \in \bar{X}(\tau^*,x^*) (\tau_i) \} \cap \{ x_i \in \bar{X}(\tau^*,x^*) (\tau_i) \} \}$ for any $\mathcal{D}_j(s,s') \times \mathbb{R}^k$. We have the inequalities

$$
\frac{1}{j!} \left( \sqrt{N} O(N,j,t^*,x^*) [s,s'] \right)^2 \geq \mathbb{E} \left[ \frac{1}{j!} \left( O(N,t^*,x^*) [s,s'] \right)^2 \right].
$$

Proof. Equation 5.3 follows immediately from Lemma 5.2 and the definition of the rescaled process in Definition 2.16. Equation 5.4 follows immediately from Corollary 5.3 using the definition of $\psi_j^{(N)}(t^*,x^*)$ from equation (2.5) and the fact that the $L^2$ norm of $\psi_j^{(N)}(t^*,x^*)$ can be written as a semi-discrete sum as in equation (2.3). \qed

Proof. (Of Proposition 2.19.) By Corollary 5.4 applied to each term, we have for any $\ell \in \mathbb{N}$ that

$$
\sum_{k=\ell}^\infty \gamma^k \| \psi_k^{(N,t^*,x^*)} \|_{L^2(\mathcal{D}_j(0,t^*) \times \mathbb{R}^k)}^2 \leq \mathbb{E} \left[ \sum_{k=\ell}^\infty \frac{\gamma^k}{k!} \left( O(N,t^*,x^*) [0,t^*] \right)^k \right].
$$

The interchange of expectation with the infinite sum is justified by the monotone convergence theorem since $O(N,t^*,x^*) [0,t^*]$ is non-negative. Finally, since the overlap time $\{ O(N,t^*,x^*) [0,t^*] : t \in [0,t^*] \}_{N \in \mathbb{N}}$ is weakly exponential moment controlled by Proposition 4.28, we apply property i) and property iii) of weak exponential moment control from Definition 4.2 to get the desired conclusions. \qed

Definition 5.5. Recall from Definition 2.22 the subdivision of the space $\mathcal{D}_k(0,t^*) \times \mathbb{R}^k$ into sets $D_1, D_2, D_3, D_4$. Further subdivide $D_3(\delta)$ as follows

$$
D_3^{0,j}(\delta) \triangleq \left( \Delta_j(0,\delta) \times \Delta_k-j(\delta,t^*) \right) \times \mathbb{R}^k, \quad D_3^{j,j}(\delta) \triangleq \left( \Delta_k-j(0,t^*-\delta) \times \Delta_j(t^*-\delta,t^*) \right) \times \mathbb{R}^k,
$$

so that $D_3(\delta) = \bigcup_{j=1}^k D_3^{0,j}(\delta) \cup \bigcup_{j=1}^k D_3^{j,j}(\delta)$.
We now use the weak exponential moment control of The justification of equation (5.6) follows in the same way as the proof of Corollary 5.4 and, for each \( N \) from Proposition 4.28. By Lemma 5.1, we find \( N_2 \) since once this is proven we can use a union bound and \( D_3 = \bigcup_{j=1}^{k} D_{3,j}^{0} \) is a union of these \( 2k \) pieces. We will show only the bound in equation (5.5) for \( D_{3,j}^{0} \) as the result for \( D_{3,j}^{1} \) follows in an analogous way. We first observe that

\[
\limsup_{N \to \infty} \iint_{D_{3,j}^{0} (\delta)} \left| \psi_{k}^{(N)} (t^*, z^*) (\vec{t}, \vec{z}) \right|^2 \, d\vec{t} d\vec{z} < \epsilon, \quad \limsup_{N \to \infty} \iint_{D_{3,j}^{1} (\delta)} \left| \psi_{k}^{(N)} (t^*, z^*) (\vec{t}, \vec{z}) \right|^2 \, d\vec{t} d\vec{z} < \epsilon, \tag{5.5}
\]

since once this is proven we can use a union bound and \( D_3 (\delta) = \bigcup_{j=1}^{k} D_{3,j}^{0} (\delta) \cup \bigcup_{j=1}^{k} D_{3,j}^{1} (\delta) \) is a union of these \( 2k \) pieces. We will show only the bound in equation (5.5) for \( D_{3,j}^{0} \) as the result for \( D_{3,j}^{1} \) follows in an analogous way. We first observe that

\[
\iint_{D_{3,j}^{0} (\delta)} \left| \psi_{k}^{(N)} (t^*, z^*) (\vec{t}, \vec{z}) \right|^2 \, d\vec{t} d\vec{z} \leq E \left[ \frac{1}{j!} \left( \left( \psi^{(N)} (t^*, z^*) [0, \delta] \right)^j \right) \right],
\]

where

\[
\psi_k^{(N)} (t^*, z^*) (\vec{t}, \vec{z}) = \frac{1}{j!} \left( \left( \psi^{(N)} (t^*, z^*) [0, \delta] \right)^j \right).
\]

The justification of equation (5.6) follows in the same way as the proof of Corollary 5.4 by applying the inequality from equation (5.3) and then taking \( E \) of both sides. Applying the Cauchy-Schwarz inequality to the RHS of equation (5.6) and using the fact that \( O^{(N)} (t^*, z^*) [0, \delta] \) is monotone increasing in \( t \) gives us

\[
\text{LHS \ (5.6) } \leq \frac{1}{j! (k-j)!} \left[ E \left( \left( O^{(N)} (t^*, z^*) [0, \delta] \right)^{2j} \right) \right] \left[ E \left( \left( O^{(N)} (t^*, z^*) [0, t^*] \right)^{2(k-j)} \right) \right].
\]

We now use the weak exponential moment control of \( \{ O^{(N)} (t^*, z^*) [0, t] ; t \in [0, t^*] \} \) from Proposition 4.28. By Lemma 5.1, we find \( N_0 \) large enough so that

\[
\sup_{N > N_0} E \left[ \left( O^{(N)} (t^*, z^*) [0, t^*] \right)^{2(k-j)} \right] < \infty, \tag{5.8}
\]

and, for each \( \epsilon > 0 \), an \( N_\epsilon \) large enough so that

\[
\limsup_{\delta \to 0} \sup_{N > N_\epsilon} \left[ E \left( O^{(N)} (t^*, z^*) [0, \delta] \right)^{2j} \right] \leq \left( \frac{j! (k-j)!}{\epsilon^2} \right) \left( \sup_{N > N_0} E \left[ \left( O^{(N)} (t^*, z^*) [0, t^*] \right)^{2(k-j)} \right] \right)^{-1}.
\]

Combining this with the inequality from equation (5.7) we arrive at

\[
\limsup_{\delta \to 0} \sup_{N > N_\epsilon} \iint_{D_{3,j}^{0} (\delta)} \left| \psi_{k}^{(N)} (t^*, z^*) (\vec{t}, \vec{z}) \right|^2 \, d\vec{t} d\vec{z} \leq \frac{\epsilon}{2}.
\]

Since this \( \limsup \) as \( \delta \to 0 \) is less than \( \epsilon/2 \), there exists \( \delta > 0 \) small enough to verify equation (5.5) as desired.

**Proof.** (Of Proposition 2.27) Let \( W^{(N)} (t^*, z^*) \) be the largest absolute value achieved by the ensemble at any time \( t \in [0, t^*] \), and let \( W^{(N)} (t^*, z^*) \) be the same for an independent copy \( X^{(N)} (t^*, z^*) \). By the definition of the set \( D_4 \) we have that LHS of (2.13) is bounded above by

\[
N \iint_{\vec{t} \in \Delta_k (0, t^*)} \prod_{i=1}^{k} \left\{ z_i - \sqrt{N} t_i > M \right\} P \left\{ \bigcap_{i=1}^{k} \left\{ z_i - \sqrt{N} t_i \in X^{(N)} (t^*, z^*) (t_i) \right\} \right\}^2 dt_1 \ldots dt_k
\]

\[
\tag{5.9}
\]
Since $\vec{X}^{(t',z')}$ and $\vec{X}^{(t',z')}$ are independent, we write this as:

\[
\text{LHS (2.13)} \leq N^{\frac{3}{2}} \mathbb{E} \left[ \sum_{\vec{t} \in \Delta_2(0,t')} \sum_{z \in \mathbb{N}^{\frac{3}{2}} \mathbb{Z}^3} 1 \left\{ \bigcup_{j=1}^{k} \left\{ z_i - \sqrt{N} t_i > M \right\} \right\} \times 1 \left\{ \bigcap_{i=1}^{k} \left\{ z_i - \sqrt{N} t_i \in \vec{X}^{(N),(t',z')}(t_i) \right\} \bigcap_{j=1}^{k} \left\{ z_i - \sqrt{N} t_i \in \vec{X}^{(N),(t',z')}(t_j) \right\} \right\} \right].
\]

The last inequality follows by inclusion since if $|z_i - \sqrt{N} t_i| > M$ and $z_i - \sqrt{N} t_i \in \vec{X}^{(N),(t',z')}(t_i)$, then the maximum has $W^{(N),(t',z')} > M$. By application of Corollary 5.4, and Cauchy-Schwarz we have that LHS of equation (2.13) is bounded above by:

\[
\mathbb{E} \left[ \sum_{\vec{t} \in \Delta_2(0,t')} \sum_{z \in \mathbb{N}^{\frac{3}{2}} \mathbb{Z}^3} 1 \left\{ W^{(N),(t',z')} > M \right\} \right] \leq \frac{1}{k!} \mathbb{P} \left[ W^{(N),(t',z')} > M \right] \sqrt{\mathbb{E} \left[ |O^{(N)}(t',z')|^{2k} \right]}.
\]

Finally, by the weak exponential moment control from Proposition 4.28 and Lemma 5.1 we know there is an $N_0 \in \mathbb{N}$ so that $\sup_{N>N_0} \mathbb{E} \left[ |O^{(N)}(t',z')|^{2k} \right] < \infty$. Since this is bounded and since $\lim_{M \to \infty} \sup_{N>N_0} \mathbb{P} \left[ W^{(N),(t',z')} > M \right] = 0$, (see e.g. Lemma 4.8) it is possible to choose an $M$ so large so that the RHS of equation (5.10) is less than $\epsilon$. 

\[\square\]

### A Appendix

#### A.1 Facts about Poisson processes

**Lemma A.1.** Let $P(\tau)$ be an ordinary unit rate Poisson process. Let $\tilde{P}(\tau) = \hat{P}(\tau) - \tau$ denote the compensated version of this walk. Then:

\[
P \left( \sup_{0 < \tau < t_N} \tilde{P}(\tau) - \inf_{0 < \tau < t_N} \tilde{P}(\tau) > y\sqrt{N} \right) \leq 2 \exp \left( -\frac{y^2}{4T} \right) + 2 \exp \left( -\frac{1}{4}\sqrt{Ny} \right).
\]

**Proof.** We show that $P \left( \sup_{0 < \tau < t_N} \tilde{P}(\tau) > y\sqrt{N} \right)$ and $P \left( \inf_{0 < \tau < t_N} \tilde{P}(\tau) < -y\sqrt{N} \right)$ both separately obey this type of inequality, and the result will follow by a union bound. Fix any $T > 0$, $x > 0$. Since $\tilde{P}(\tau)$ is a martingale, we have by Doob’s inequality for the running maximum of any sub-martingale that for any $\lambda > 0$:

\[
P \left( \sup_{0 < \tau < T} \tilde{P}(\tau) \geq x \right) \leq \mathbb{E} \left[ \exp \left( \lambda \tilde{P}(T) \right) \right] \leq \exp \left( T \left( \frac{x}{T} - \ln \left( 1 + \frac{x}{T} \right) \right) \right),
\]

where we have used the minimizing value $\lambda = \ln \left( 1 + \frac{x}{T} \right)$ to get the last inequality. We now use the Taylor series inspired bound $z - \ln(1+z)(1+z) = -\frac{1}{2}z^2 + \frac{1}{2} \int_0^z \frac{1}{1+t}^2 dt \leq$
The last inequality follows by considering the cases \( x < T \) and \( x \geq T \) separately. Putting \( T = tN \) and \( x = y\sqrt{N} \) gives the desired result of the Lemma. The same argument works to prove the bound on \( \mathbb{P} \left( - \inf_{0 < \tau < T} \bar{P}(\tau) > y \right) \) using Doob’s inequality again and the fact that \( - \bar{P}(\tau) \) is also a martingale.

**Proposition A.2.** (Local Central Limit Theorem for Poisson probabilities) Recall the Poisson probability mass function \( \mu \) from Definition 2.4. We have that

\[
\lim_{M \to \infty} \sup_{z \in \mathbb{R}} \left| \sqrt{M} \mu \left( M, M + \left| \sqrt{M} z \right| \right) - \frac{1}{\sqrt{2\pi}} \exp \left( - \frac{1}{2} z^2 \right) \right| = 0.
\]

**Proof.** Notice that \( \mu(M, M + y) \) can be realized as a probability:

\[
\mu(M, M + y) = \mathbb{P} \left( \sum_{i=1}^{M} (\xi_i - 1) = y \right),
\]

where \( \xi_i \) are i.i.d. Poisson random variables of rate 1. The result then follows by the local limit theorem for sums of mean zero random variables, see for example Theorem 3.5.2 in [9].

**Corollary A.3.** There exists a constant \( C_P \) so that:

\[
\sup_{M \in \mathbb{N}} \sqrt{M} \mu \left( M, M + \left| \sqrt{M} z \right| \right) \leq C_P.
\]

**Proof.** This follows by applying the triangle inequality to the result from Proposition A.2 and the bound \( \sup_{z \in \mathbb{R}} \exp \left( - \frac{1}{2} z^2 \right) \leq 1. \)

### A.2 Proof of determinantal kernel for non-intersecting Poisson bridges

**Proposition A.4.** For any \( \tau^* > 0 \) and any \( x^* \in \mathbb{N} \), recall from Definition 3.3 the space-time kernel \( K_P^{(\tau^*, x^*)} \). Given any list of times \( \tau_1, \ldots, \tau_k \in (0, \tau^*) \) and coordinates \( x_1, \ldots, x_k \in \{1, \ldots, x^* + d - 1\} \), the \( k \)-point correlation function for non-intersecting Poisson bridges is given by:

\[
\mathbb{P} \left( \bigcap_{i=1}^{k} \left\{ x_i \in X^{(\tau^*, x^*)}(\tau_i) \right\} \right) = \det \left[ K_P^{(\tau^*, x^*)} \left( (\tau_i, x_i); (\tau_j, x_j) \right) \right]_{i,j=1}^{k}. \tag{A.1}
\]

The key ingredient in the proof of this result is the Eynard-Mehta type theorem:

**Proposition A.5.** (Theorem 1.7, from [13], see also Section 1.2 of [14]) Fix \( m \in \mathbb{N} \). Suppose \( X_r, 0 \leq r \leq m + 1 \) are subsets of \( \mathbb{N} \) and that \( \phi_{r,r+1} : X_r \times X_{r+1} \to \mathbb{R}, 0 \leq r \leq m \) are given functions. An element \( \underline{x} = (\underline{x}^{(1)}, \ldots, \underline{x}^{(m)}) \in X_1 \times \cdots \times X_m \) is called a configuration. We think of \( \underline{x}^{(r)} = (x_1^{(r)}, \ldots, x_d^{(r)}) \) as the positions of \( d \) particles in the set \( X_r \). Let \( \underline{x}^{(0)} \in X_0^d \) and \( \underline{x}^{(m)} \in X_d^{m+1} \) be fixed configurations, the initial and final configurations respectively. Define for \( 0 \leq r < s \leq m + 1 \) the function \( \phi_{r,s} : X_r \times X_s \to \mathbb{R} \) by:

\[
\phi_{r,s}(x, y) = \sum_{z_1 \in X_{r+1}} \cdots \sum_{z_{s-r} \in X_{s-1}} \phi_{r,r+1}(x, z_1) \phi_{r+1,r+2}(z_1, z_2) \cdots \phi_{s-1,s}(z_{s-r-1}, y), \tag{A.2}
\]
and define $\phi_{r,s} \equiv 0$ if $r \geq s$. Consider a random configuration $X \in \mathcal{X}$ given by the following prescription:

$$
P(X) = \frac{1}{Z_{d,m}} \prod_{r=0}^{m} \det \left[ \phi_{r,r+1}(x_i^{(r)}, x_j^{(r+1)}) \right]_{i,j=1}^{d}.
$$

Then, for any $k \in \mathbb{N}$, and any list of space-time coordinates $\{(r_i, x_i)\}_{i=1}^{k} \in \{(1, \ldots, m) \times \mathbb{N}\}^{k}$ we have the following determinantal formula for the probability to find these space-time points occupied:

$$
P \left( \bigcap_{i=1}^{k} \{ x_i \in X^{(r_i)} \} \right) = \det \left[ K_{d,m}(r_i, x_i; r_j, x_j) \right]_{i,j=1}^{k},
$$

where the kernel $K$ (which does not depend on $k$) is explicitly given by:

$$
K_{d,m}(r, x; r', x') = -\phi_{r,r}(x, y) + \sum_{i,j=1}^{d} \phi_{r,m+1}(x, x_{i}^{(m)}) (A^{-1})_{i,j} \phi_{0,r'}(x_{j}^{(0)}, x'),
A_{ij} \equiv \phi_{0,m+1}(x_{i}^{(0)}, x_{j}^{(m)}).
$$

(A.3)

**Remark A.6.** Typically this type of measure arises in the context of non-intersecting processes as a consequence of the Lindström-Gessel-Viennot/Karlin-MacGregor formula. The difficulty in practice is inverting the matrix $A$ which appears in the formula for the kernel. The approach we will follow goes by using row and column manipulations to rewrite the functions $\phi$ in terms of orthogonal polynomials. Because these polynomials are orthogonal, the matrix $A$ becomes diagonal and finding $A^{-1}$ is possible.

**Lemma A.7.** Recall the definition of the non-intersecting Poisson bridges from Definition 2.5. For any fixed sequence of times $0 = \tau^{(0)} < \tau^{(1)} < \ldots < \tau^{(m)} < \tau^{(m+1)} = \tau^*$, and any list of vectors $\{\tilde{x}^{(i)}\}_{i=0}^{m+1}$ with $\tilde{x}^{(0)} = \tilde{\delta}(0) \in \mathbb{N}^{d}$ and $\tilde{x}^{(m+1)} = \tilde{\delta}(x^*) \in \mathbb{N}^{d}$ we have:

$$
P \left( \bigcap_{i=1}^{m+1} \left\{ \tilde{X}^{(i*}) \left( \tau^{(i)} \right) = \tilde{x}^{(i)} \right\} \right) = Z_{\tau^*}^{-1} \prod_{r=0}^{m} \det \left[ \mu \left( \tau^{(r+1)} - \tau^{(r)}; x_{i}^{(r+1)} - x_{j}^{(r)} \right) \right]_{i,j=1}^{d},
$$

where $Z_{\tau^*}^{-1}$ is a normalizing constant.

**Proof.** Let $\tilde{F}(\tau) \in \mathbb{N}^{d}$ denote an ordinary Poisson process which consists of $d$ independent Poisson processes. By the Lindström-Gessel-Viennot/Karlin-MacGregor theorem, the probability of $d$ Poisson paths to go from an initial position $\tilde{x} \in \mathbb{N}^{d}$ at an original time $\tau$ to a final position $\tilde{x}' \in \mathbb{N}^{d}$ at a final time $\tau'$ without intersection is given by:

$$
P \left( \text{Non-intersecting in } (\tau, \tau') \cap \left\{ \tilde{F}(\tau') = \tilde{x}' \right\} \right) = \det [\mu (\tau' - \tau; x_{i}^{*} - x_{j}^{*})]_{i,j=1}^{d}.
$$

The result of the Lemma then follows by the definition of $\tilde{X}^{(\tau^*; x^*)}$ as the Markov process of Poisson processes conditioned on non-intersection and with initial and final conditions $\tilde{x}^{(0)}$ and $\tilde{x}^{(m+1)}$ respectively.

**Definition A.8.** Recall the definition of the polynomials $R_j$ and $\tilde{R}_j$ from Definition 3.3, and the Poisson probability mass function $\mu$ from Definition 2.4. Define a family of auxiliary functions $\lambda_{j} : \mathbb{R} \times \mathbb{N} \to \mathbb{R}$ and $\tilde{\lambda}_{j} : \mathbb{R} \times \mathbb{N} \to \mathbb{R}$ for $0 \leq j \leq d - 1$ by:

$$
\lambda_{j}(\tau, x) \equiv R_{j}(\tau, x) \mu(\tau, x).
\tilde{\lambda}_{j}(\tau, x) \equiv \tilde{R}_{j}(\tau, x) \mu(x - x + d - 1, \tau^* - \tau).
$$
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Lemma A.9. For each \( j \), \( \lambda_j(\tau, x) \) and \( \tilde{\lambda}_j(\tau, x) \) can be written as a linear combination of the functions \( \{\mu(\tau, x-i)\}_{i=0}^{j} \) and \( \{\mu(\tau^* - \tau, x^* - x + d - 1 - i)\}_{i=0}^{j} \) respectively:

\[
\lambda_j(\tau, x) = \sum_{i=0}^{j} a_{i,j} \mu(\tau, x-i) \cdot \\
\tilde{\lambda}_j(\tau, x) = \sum_{i=0}^{j} a_{i,j} \mu(\tau^* - \tau, x^* - x + d - 1 - i) \cdot \\
a_{i,j} \doteq (-1)^i \begin{pmatrix} j \\ i \end{pmatrix} \frac{(\tau^*)^i}{(x^* + d - 1)_{-i}} ,
\]

where \( (x)_{-i} \) denotes the falling factorial \( (x)_{-i} = x \cdot (x-1) \cdot \ldots \cdot (x-i+1) \).

Proof. This is verified directly from the definition of \( R_j(\tau, x) \) in terms of the hypergeometric function \( _2F_1 \) from Definition 3.3. From this definition we have that:

\[
R_j(\tau, x) \mu(\tau, x) = \sum_{i=0}^{j} \left(-1\right)^i \begin{pmatrix} j \\ i \end{pmatrix} \frac{(\tau^*)^i}{(x^* + d - 1)_{-i}} \left( \frac{\tau^*}{\tau} \right)^i e^{-\tau \frac{\tau x^*}{x}} . \tag{A.4}
\]

On the other hand, we have:

\[
\sum_{i=0}^{j} a_{i,j} \mu(\tau, x-i) = \sum_{i=0}^{j} (-1)^i \begin{pmatrix} j \\ i \end{pmatrix} \frac{(\tau^*)^i}{(x^* + d - 1)_{-i}} e^{-\tau \frac{\tau x - i}{x-i}} . \tag{A.5}
\]

The RHS of equations (A.4) and (A.5) are seen to be equal by the identity \( x! = (x-i)!(x)_{-i} \). A very similar calculation holds for \( \tilde{\lambda}_j(\tau, x) \).

Corollary A.10. We have the identities:

\[
\sum_{x \in \mathbb{N}} \lambda_j(\tau, x) \mu(\tau', y-x) = \lambda_j(\tau + \tau', y) , \quad \sum_{x \in \mathbb{N}} \mu(\tau, x) \tilde{\lambda}_j(\tau', y-x) = \tilde{\lambda}_j(\tau + \tau', y) .
\]

Proof. First notice that \( \sum_{x \in \mathbb{N}} \mu(\tau, x) \mu(\tau', y-x) = (\tau + \tau', y) \). This is the well-known fact that a sum of two independent Poisson variables is again Poisson (or in other words, the convolution of two Poisson weights is again Poisson). The identities then follow by the observation from Lemma A.9 that \( \lambda_j \) and \( \tilde{\lambda}_j \) are linear combinations of weights \( \mu \).

Lemma A.11. For any sequence of times \( 0 = \tau(0) < \tau(1) < \ldots < \tau(m) < \tau(m+1) = \tau^* \), and any list of vectors \( \{\vec{x}^{(i)}\}_{i=1}^{m} \) with \( \vec{x}^{(0)} = \vec{d}(0) \) and \( \vec{x}^{(m+1)} = \vec{d}(\tau^*) \) we have:

\[
P \left( \bigcap_{i=1}^{m} \{ X(\tau^*, \tau^{(i)}(\tau^{(i)}(0)) = \vec{x}^{(i)} \} \right)
= \frac{Z^{-1}_{\tau^*, \tau^{(r)}}}{\prod_{i=0}^{d-1} a_{i,i}} \det \left[ \lambda_{i-1} \left( \tau^{(1)}(0), x^{(1)}_j \right) \right]_{i,j=1}^{d} \times \prod_{r=1}^{m-1} \det \left[ \mu \left( \tau^{(r+1)}(0) - \tau^{(r)}(0), x^{(r+1)}_j - x^{(r)}_j \right) \right]_{i,j=1}^{d} \det \left[ \tilde{\lambda}_{i-1} \left( \tau^{(m)}(0), x^{(m)}_j \right) \right]_{i,j=1}^{d},
\]

where \( a_{i,i} \) is as defined in Lemma A.9.

Proof. This follows by applying row operations on the determinants that appear in Lemma A.7 to create the linear combinations that appear in Lemma A.9.
Lemma A.12. The polynomials $R_j(\tau, x)$ and $\tilde{R}_j(\tau, x)$ are related by the identity:

$$R_j(\tau, x) = (-1)^j \left( \frac{\tau^*}{\tau} - 1 \right)^j \tilde{R}_j(\tau, x). \tag{A.6}$$

Moreover, for $1 \leq j, k \leq d - 1$, and any $\tau \in (0, \tau^*)$ we have:

$$\sum_{x \in \mathbb{N}} \lambda_j(\tau, x) \tilde{\lambda}_k(\tau, x) = (-1)^j \frac{\mu(\tau^* x^* + d - 1)}{(\tau^* x^* + d - 1)} \delta_{j,k}.$$

Proof. We use the Euler transformation for the hypergeometric function $\binom{a}{b}$,

$$\binom{a}{b}(z) = (1 - z)^{-a} \binom{a}{c}(\frac{z}{z - 1}).$$

This identity applied to the polynomials $R_j$ and $\tilde{R}_j$ from Definition 3.3 verifies equation (A.6). Once this is established, we now compute:

$$\sum_{x \in \mathbb{N}} \lambda_j(\tau, x) \tilde{\lambda}_k(\tau, x) = \frac{\mu(\tau^* x^* + d - 1)}{(\tau^* x^* + d - 1)^2} \sum_{x \in \mathbb{N}} R_j(\tau, x) R_k(\tau, x) \left( \frac{x^* + d - 1}{x^*} \right) \left( \frac{\tau^*}{\tau} \right)^x \left( 1 - \frac{\tau^*}{\tau} \right)^{x^* + d - 1 - x}$$

$$= \frac{\mu(\tau^* x^* + d - 1)}{(\tau^* x^* + d - 1)^2} \left( \frac{\tau^*}{\tau} - 1 \right)^k \delta_{j,k},$$

where we have applied the orthogonality relation for the Krawtchouk polynomials. □

Proof. (Of Proposition A.4) It suffices to verify the result for the process $X^{(\tau^* : x^*)}$ restricted to an arbitrary finite list of times $0 = \tau^{(0)} < \tau^{(1)} < \ldots < \tau^{(m)} < \tau^{(m+1)} = \tau^*$. With such a list fixed, define the initial/final conditions by $x^{(0)} = \delta_d(0)$, $x^{(m)} = \delta_d(x^*)$ and the functions $\phi_{r,s+1}$ for $0 \leq r \leq m$ by:

$$\phi_{r,r+1}(x, x') \triangleq \mu(\tau^{(r+1)} - \tau^{(r)}, x' - x).$$
$$\phi_{0,1}(x_j^{(0)}, x) \triangleq \lambda_j(\tau^{(1)}, x).$$
$$\phi_{m,m+1}(x, x_j^{(m+1)}) \triangleq \tilde{\lambda}_j(\tau^{(m)}, x).$$

By Lemma A.7, the probability of any configuration is explicitly given by equation (A.1), which matches the hypothesis of Proposition A.5. By Corollary A.10, we can explicitly perform the convolutions that appear in equation (A.2), to get

$$\phi_{0,r}(x_j^{(0)}, x) = \lambda_j(\tau^{(r)}, x) \text{ for } 1 \leq r \leq m.$$
$$\phi_{r,m+1}(x, x_j^{(m+1)}) = \tilde{\lambda}_j(\tau^{(r)}, x) \text{ for } 1 \leq r \leq m.$$
$$\phi_{r,s}(x', x) = \mu(\tau^{(s)} - \tau^{(r)}, x' - x) \text{ for } 1 \leq r < s \leq m.$$

It remains only to calculate $\phi_{0,m+1}$. By Lemma A.12 we compute

$$\phi_{0,m+1}(x_j^{(0)}, x_k^{(m)}) = \sum_{x \in \mathbb{N}} \phi_{0,r}(x_j^{(0)}, x) \phi_{r,m+1}(x, x_k^{(m+1)}) = (-1)^j \frac{\mu(\tau^* x^* + d - 1)}{(\tau^* x^* + d - 1)^j} \delta_{j,k}.$$

(Note that the above calculation works for any $0 < r < m$ and that the final result does not depend on $r$ or $m$.) Thus the matrix $A$, defined in equation (A.3) is diagonal! Inverting it and applying the conclusion of Proposition A.5 gives the kernel $K_P$ as desired. □

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