

## MULTIPLE POSITIVE SOLUTIONS FOR SEMILINEAR ELLIPTIC EQUATIONS IN ESTEBAN-LIONS DOMAINS WITH HOLES

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**Abstract.** In this paper, we study a Palais-Smale condition in unbounded domains. Furthermore, we apply this result to prove that the semilinear elliptic equation in a Esteban-Lions domain with holes has multiple positive solutions.

### 1. INTRODUCTION

Let  $N \geq 2$  and  $2 < p < 2^*$ , where  $2^* = \frac{2N}{N-2}$  for  $N \geq 3$  and  $2^* = \infty$  for  $N = 2$ . Consider the semilinear elliptic equation

$$(1) \quad \begin{cases} -\Delta u + u = |u|^{p-2}u & \text{in } \Omega \\ u \in H_0^1(\Omega), \end{cases}$$

where  $\Omega$  is a domain in  $\mathbb{R}^N$  and  $H_0^1(\Omega)$  is the Sobolev space in  $\Omega$  with dual space  $H^{-1}(\Omega)$ .

Associated with Equation (1), we consider the energy functionals  $a$ ,  $b$  and  $J$  in  $H_0^1(\Omega)$ ,

$$\begin{aligned} a(u) &= \int_{\Omega} (|\nabla u|^2 + u^2), \\ b(u) &= \int_{\Omega} |u|^p, \\ J(u) &= \frac{1}{2}a(u) - \frac{1}{p}b(u). \end{aligned}$$

It is well-known that the solutions of Equation (1) in  $\Omega$  and the critical points of the energy functional  $J$  in  $H_0^1(\Omega)$  are the same. By the Rellich compactness theorem,

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it is easy to obtain a solution of Equation (1) in a bounded domain. For general unbounded domains  $\Omega$ , because the lack of compactness, the existence of solutions of Equation (1) in  $\Omega$  is very difficult and unclear. The breakthrough was made by Esteban-Lions [8]. They asserted that Equation (1) in Esteban-Lions domain does not admit any nontrivial solution, where the definition of Esteban-Lions domain is: for a proper unbounded domain  $\Omega$  in  $\mathbb{R}^N$ , there exists a  $\chi \in \mathbb{R}^N$ ,  $\|\chi\| = 1$ , such that  $n(z) \cdot \chi \geq 0$  and  $n(z) \cdot \chi \not\equiv 0$  on  $\partial\Omega$ , where  $n(z)$  is the unit outward normal vector to  $\partial\Omega$  at the point  $x$ . Some typical examples are:

- (i) upper half space  $\mathbb{R}_+^N = \{(x, y) \in \mathbb{R}^{N-1} \times \mathbb{R} \mid y > 0\}$ ;
- (ii) upper half strip  $\mathbf{S}^+ = \{(x, y) \in \mathbb{R}^{N-1} \times \mathbb{R} \mid |x| < r_0, y > 0\} \cup B^N(0; r_0)$ .

Thus, perturbing the Esteban-Lions domain to obtain the existence of solutions for Equation (1) is applied in a great deal of research in recent years. First, we consider a perturbation of the upper half strip  $\mathbf{S}^+$  that is the interior flask domain  $\mathbf{F}_r = \mathbf{S}^+ \cup B^N(0; r)$ . Then  $\mathbf{F}_r$  is not a Esteban-Lions domain for all  $r > r_0$ . Moreover, Lien-Tzeng-Wang [9] and Chen-Wang [5] proved that there is a  $r^* > 0$  such that for  $r > r^*$  Equation (1) in  $\mathbf{F}_r$  has a ground state solution. The definition of ground state solution of Equation (1) in  $\Omega$  is as follows: Consider the minimax problem

$$(2) \quad \alpha_\Gamma(\Omega) = \inf_{\gamma \in \Gamma(\Omega)} \max_{t \in [0,1]} J(\gamma(t)),$$

where

$$\Gamma(\Omega) = \{\gamma \in C([0, 1], H_0^1(\Omega)) \mid \gamma(0) = 0, \gamma(1) = e\},$$

$J(e) = 0$  and  $e \neq 0$ . By the well-known mountain pass lemma due to Ambrosetti-Rabinowitz [1], we call the nonzero critical point  $u \in H_0^1(\Omega)$  of  $J$  a ground state solution of Equation (1) in  $\Omega$  if  $J(u) = \alpha_\Gamma(\Omega)$ . We remark that ground state solutions of Equation (1) in  $\Omega$  can also be obtained by the Nehari minimization problem

$$\alpha(\Omega) = \inf_{v \in \mathbf{M}(\Omega)} J(v),$$

where  $\mathbf{M}(\Omega) = \{u \in H_0^1(\Omega) \setminus \{0\} \mid a(u) = b(u)\}$ . Note that  $\alpha_\Gamma(\Omega) = \alpha(\Omega) > 0$  and if there exists a nonzero solution  $v_0$  of Equation (1) such that  $J(v_0) > \alpha(\Omega)$ , then we called the solution  $v_0$  is a higher energy solution. (see Willem [14] and Wang [12]).

Next, we shall consider another perturbation. Let  $\tilde{r} < r_0$  is a positive number, consider the upper half strip with hole

$$\Omega(t) = \mathbf{S}^+ \setminus B((0, t); \tilde{r}).$$

Wang [12] used the Palais-Smale decomposition lemma in the infinite strip  $\mathbf{A} = \{(x, y) \in \mathbb{R}^{N-1} \times \mathbb{R} \mid |x| < r_0\}$  (see Lien-Tzeng-Wang [9]) and the center mass

function. He assumed that the positive solution of Equation (1) in infinite strip  $\mathbf{A}$  is unique, asserting that there exists a  $t_0 > 0$  such that for  $t > t_0$ , Equation (1) in  $\Omega(t)$  has a positive higher energy solution. However, the uniqueness of positive solution of Equation (1) in infinite strip  $\mathbf{A}$  only has been solved in dimension  $N = 2$  (see Dancer [6]). In general, this problem is still open.

The main purpose of this paper is using a new method to improve a result of Wang [12]. In particular we do this without any assumption on the uniqueness of positive solution of Equation (1) in infinite strip  $\mathbf{A}$ . This paper is organized as follow. In section 2, we describe various preliminaries. In section 3, we describe a Palais-Smale condition in unbounded domains. In section 4, we proved that the semilinear elliptic equation in upper half strip with holes has multiple positive solutions.

## 2. PRELIMINARY

First, we define the (PS)–sequences, (PS)–values, and (PS)–conditions in  $H_0^1(\Omega)$  for  $J$  as follows:

**Definition 1.** We define

- (i) For  $\beta \in \mathbb{R}$ , a sequence  $\{u_n\}$  is a  $(PS)_\beta$ –sequence in  $H_0^1(\Omega)$  for  $J$  if  $J(u_n) = \beta + o(1)$  and  $J'(u_n) = o(1)$  strongly in  $H^{-1}(\Omega)$  as  $n \rightarrow \infty$ ;
- (ii)  $\beta \in \mathbb{R}$  is a (PS)–value in  $H_0^1(\Omega)$  for  $J$  if there exists a  $(PS)_\beta$ –sequence in  $H_0^1(\Omega)$  for  $J$ ;
- (iii)  $J$  satisfies the  $(PS)_\beta$ –condition in  $H_0^1(\Omega)$  if every  $(PS)_\beta$ –sequence in  $H_0^1(\Omega)$  for  $J$  contains a convergent subsequence.

By Willem [14], for any  $\beta \in \mathbb{R}$ , a  $(PS)_\beta$ –sequence in  $X(\Omega)$  for  $J$  is bounded. Moreover, a (PS)–value  $\beta$  should be nonnegative.

**Lemma 2.** Let  $\beta \in \mathbb{R}$  and  $\{u_n\}$  be a  $(PS)_\beta$ –sequence in  $H_0^1(\Omega)$  for  $J$ , then there exists a  $c > 0$  such that  $\|u_n\|_{H^1} \leq c$  for all  $n \in \mathbb{N}$ . Furthermore,

$$a(u_n) = b(u_n) + o(1) = \frac{2p}{p-2}\beta + o(1)$$

and  $\beta \geq 0$ .

Now, we consider the Nehari minimization problem

$$\alpha(\Omega) = \inf_{u \in \mathbf{M}(\Omega)} J(u),$$

where  $\mathbf{M}(\Omega) = \{u \in H_0^1(\Omega) \setminus \{0\} \mid a(u) = b(u)\}$ . Note that  $\mathbf{M}(\Omega)$  contain every nonzero solution of Equation (1) in  $\Omega$  and if  $u_0 \in \mathbf{M}(\Omega)$  achieves  $\alpha(\Omega)$  then

$u_0$  is a ground state solution of Equation (1) in  $\Omega$  (see Wang-Wu [13] or Willem [14]). Moreover, we have the following useful lemmas, whose proof can be found in Chen-Wang [5] and Wang-Wu [13, Lemma 7].

**Lemma 3.** *Let  $\beta > 0$  and  $\{u_n\}$  in  $H_0^1(\Omega) \setminus \{0\}$  be a sequence for  $J$  such that  $J(u_n) = \beta + o(1)$  and  $a(u_n) = b(u_n) + o(1)$ . Then there is a sequence  $\{s_n\} \subset \mathbb{R}^+$  such that  $s_n = 1 + o(1)$ ,  $\{s_n u_n\}$  is in  $\mathbf{M}(\Omega)$  and  $J(s_n u_n) = \beta + o(1)$ .*

**Lemma 4.** *Let  $\{u_n\}$  be in  $H_0^1(\Omega)$ . Then  $\{u_n\}$  is a  $(PS)_{\alpha(\Omega)}$ -sequence in  $H_0^1(\Omega)$  for  $J$  if and only if  $J(u_n) = \alpha(\Omega) + o(1)$  and  $a(u_n) = b(u_n) + o(1)$ .*

Let  $\Omega^1 \not\subseteq \Omega^2$ , clearly  $\alpha(\Omega^2) \leq \alpha(\Omega^1)$ . If  $\alpha(\Omega^2) = \alpha(\Omega^1)$ , then we have the following useful results.

**Lemma 5.** *Let  $\Omega^1 \not\subseteq \Omega^2$  and let  $J : H_0^1(\Omega^2) \rightarrow \mathbb{R}$  be the energy functional. Suppose that  $\alpha(\Omega^2) = \alpha(\Omega^1)$ . We have*

- (i) *Equation (1) in  $\Omega^1$  does not admit any solution  $u^1$  such that  $J(u^1) = \alpha(\Omega^1)$ ;*
- (ii)  *$J$  does not satisfy the  $(PS)_{\alpha(\Omega^2)}$ -condition.*

By the Rellich compact theorem,  $J$  satisfies the  $(PS)_{\alpha_X(\Omega)}$ -condition in  $X(\Omega)$  if  $\Omega$  is a bounded domain.

**Lemma 6.** *Let  $\Omega$  be a bounded domain in  $\mathbb{R}^N$ . Then the  $(PS)_{\alpha(\Omega)}$ -condition holds in  $H_0^1(\Omega)$  for  $J$ . Furthermore, Equation (1) in  $\Omega$  has a positive solution  $u_0$  such that  $J(u_0) = \alpha(\Omega)$ .*

**Lemma 7.** *Let  $u \in H_0^1(\Omega)$  be a change sign solution of Equation (1) in  $\Omega$ . Then  $J(u) > 2\alpha(\Omega)$ .*

*Proof.* See the proof of Theorem A in Benci-Cerami [3]. ■

### 3. PALAIS-SMALE CONDITIONS

Throughout this section, denote

$$\mathbf{A}_{s,l}(x_0, r) = \{(x, y) \in \mathbb{R}^{N-1} \times \mathbb{R} \mid |x - x_0| < r, s < y < l\}$$

is a finite strip in  $\mathbb{R}^N$ . Let  $\Omega$  be unbounded domain in  $\mathbb{R}^N$  and let

$$M(x_0, r, s, l) = \left\{ u \in \mathbf{M}(\Omega) \mid \int_{[\mathbf{A}_{s,l}(x_0, r)]^c} |u|^p < \frac{p}{(p-2)} \alpha(\Omega) \right\};$$

$$N(x_0, r, s, l) = \left\{ u \in \mathbf{M}(\Omega) \mid \int_{[\mathbf{A}_{s,l}(x_0, r)]^c} |u|^p = \frac{p}{(p-2)} \alpha(\Omega) \right\},$$

be subsets of  $\mathbf{M}(\Omega)$ , where  $\mathbf{A}_{s,l}(x_0, r) \cap \Omega \neq \emptyset$  for some  $x_0 \in \mathbb{R}^{N-1}$ ,  $r > 0$  and  $s, l \in \mathbb{R}$ . It is easy to verify that  $M(x_0, r, s, l)$  is nonempty set for all  $r > 0$ . Define the minimization problem in  $M(x_0, r, s, l)$  and  $N(x_0, r, s, l)$  for  $J$ ,

$$\beta(r) = \inf_{v \in M(x_0, r, s, l)} J(v)$$

and

$$\gamma(r) = \inf_{v \in N(x_0, r, s, l)} J(v).$$

Note that, if  $N(x_0, r, s, l)$  is empty then we define the  $\gamma(r) = \infty$ .

Let  $\xi \in C^\infty([0, \infty))$  such that  $0 \leq \xi \leq 1$  and

$$\xi(t) = \begin{cases} 0, & \text{for } t \in [0, 1] \\ 1, & \text{for } t \in [2, \infty). \end{cases}$$

Let

$$(3) \quad \xi_n(z) = \xi\left(\frac{2|z|}{n}\right).$$

Then we have the following results.

**Lemma 8.** *Let  $\{u_n\}$  be a  $(PS)_\beta$ -sequence in  $H_0^1(\Omega)$  for  $J$  satisfying  $u_n \rightharpoonup 0$  weakly in  $H_0^1(\Omega)$  and let  $v_n = \xi_n u_n$ . Then there exists a subsequence  $\{u_n\}$  such that  $\|u_n - v_n\|_{H^1} = o(1)$  as  $n \rightarrow \infty$ . Furthermore, we have  $a(v_n) = b(v_n) + o(1)$  and  $J(v_n) = \beta + o(1)$ .*

*Proof.* Note that

$$\begin{aligned} a(u_n - v_n) &= \langle u_n - v_n, u_n - v_n \rangle_{H^1} \\ &= a(u_n) + a(v_n) - 2 \langle u_n, v_n \rangle_{H^1}. \end{aligned}$$

Thus, it suffices to show that  $\langle u_n, v_n \rangle_{H^1} = a(u_n) + o(1) = a(v_n) + o(1)$ . Since

$$\begin{aligned} \langle u_n, v_n \rangle_{H^1} &= \int_{\Omega} \nabla u_n \nabla v_n + u_n v_n \\ &= \int_{\Omega} \xi_n \left[ |\nabla u_n|^2 + u_n^2 \right] + \int_{\Omega} u_n \nabla u_n \nabla \xi_n. \end{aligned}$$

Note that  $|\nabla \xi_n| \leq \frac{c}{n}$  and  $\{u_n\}$  is a  $(PS)_\beta$ -sequence in  $H_0^1(\Omega)$  for  $J$ , so

$$(4) \quad \int_{\Omega} \xi_n^q u_n \nabla u_n \nabla \xi_n = o(1) \text{ for } q > 0.$$

Hence,

$$(5) \quad \langle u_n, v_n \rangle_{H^1} = \int_{\Omega} \xi_n \left[ |\nabla u_n|^2 + u_n^2 \right] + o(1).$$

Similarly, we have

$$(6) \quad a(v_n) = \int_{\Omega} \xi_n^2 \left[ |\nabla u_n|^2 + u_n^2 \right] + o(1).$$

For  $r \geq 1$ . Since  $\{\xi_n^r u_n\}$  is bounded in  $H_0^1(\Omega)$ , we have

$$\begin{aligned} o(1) &= \langle J'(u_n), \xi_n^r u_n \rangle \\ &= \int_{\Omega} (\xi_n^r |\nabla u_n|^2 + r \xi_n^{r-1} u_n \nabla \xi_n \nabla u_n + \xi_n^r u_n^2) - \int_{\Omega} \xi_n^r |u_n|^p. \end{aligned}$$

By (4) we conclude that

$$(7) \quad \int_{\Omega} \xi_n^r (|\nabla u_n|^2 + u_n^2) = \int_{\Omega} \xi_n^r |u_n|^p + o(1).$$

Since  $u_n \rightharpoonup 0$  weakly in  $H_0^1(\Omega)$ , there exists a subsequence  $\{u_n\}$  such that  $u_n \rightarrow 0$  strongly in  $L_{loc}^p(\Omega)$ , or there exists a subsequence  $\{u_n\}$  such that

$$\int_{Q(n)} |u_n|^p = o(1),$$

where  $Q(n) = \Omega \cap B^N(0; n)$ . Clearly,

$$(8) \quad \int_{\Omega} \xi_n^r |u_n|^p = \int_{\Omega} |u_n|^p + o(1).$$

By (5-8), we have

$$\langle u_n, v_n \rangle_{H^1} = a(u_n) + o(1) = a(v_n) + o(1).$$

Therefore,  $\|u_n - v_n\|_{H^1} = o(1)$  as  $n \rightarrow \infty$ . ■

Then we have the following Palais-Smale conditions.

**Theorem 9.** *Let  $\Omega$  be unbounded domain in  $\mathbb{R}^N$  and let  $\mathbf{A}_{s,l}(x_0, r)$  be a finite strip such that  $\mathbf{A}_{s,l}(x_0, r) \cap \Omega \neq \emptyset$  for some  $x_0 \in \mathbb{R}^{N-1}$ ,  $r > 0$  and  $s, l \in \mathbb{R}$ . If  $\{u_n\} \subset M(x_0, r, s, l)$  is a  $(PS)_{\beta(r)}$ -sequence in  $H_0^1(\Omega)$  for  $J$  with  $0 < \beta(r) < \gamma(r)$ . Then there exist a subsequence  $\{u_n\}$  and  $u_0 \in M(x_0, r, s, l)$  such that  $u_n \rightarrow u_0$  strongly in  $H_0^1(\Omega)$  and  $J(u_0) = \beta(r)$ . Furthermore,  $u_0$  is a nonzero solution of Equation (1) in  $\Omega$ .*

*Proof.* Let  $\{u_n\}$  be a  $(PS)_{\beta(r)}$ -sequence in  $H_0^1(\Omega)$  for  $J$ , then by Lemma 2, there exist a subsequence  $\{u_n\}$  and  $u_0$  in  $H_0^1(\Omega)$  such that  $u_n \rightharpoonup u_0$  weakly in  $H_0^1(\Omega)$ . Moreover,  $u_0$  is a solution of Equation (1) in  $\Omega$ . If  $u_0 \equiv 0$ . By Lemma 8, there exists a subsequence  $\{u_n\}$  such that  $J(\xi_n u_n) = \beta(r) + o(1)$  and  $a(\xi_n u_n) = b(\xi_n u_n) + o(1)$ , where  $\xi_n$  is as in (3). Moreover, by Lemma 3 there exists a  $\{s_n\}$  such that

$$\begin{aligned} a(s_n \xi_n u_n) &= b(s_n \xi_n u_n), \\ J(s_n \xi_n u_n) &= \beta(r) + o(1), \\ s_n &= 1 + o(1). \end{aligned}$$

Let  $v_n = s_n \xi_n u_n$ . Then, there exist a  $n_0 \in \mathbb{N}$  such that for  $n > 2n_0$

$$v_n = 0 \text{ in } \mathbf{A}_{s,l}(x_0, r) \cap \Omega.$$

Moreover,

$$\begin{aligned} \left(\frac{2p}{p-2}\right) \alpha(\Omega) &\leq \int_{\Omega} |v_n|^p = \int_{\Omega} |\xi_n u_n|^p + o(1) \\ &= \int_{[\mathbf{A}_{s,l}(x_0,r)]^c} |u_n|^p + o(1) < \frac{p}{(p-2)} \alpha(\Omega), \end{aligned}$$

which is a contradiction. Therefore,  $u_0 \neq 0$ . By the Fatou lemma, we have

$$\int_{[\mathbf{A}_{s,l}(x_0,r)]^c} |u_0|^p \leq \liminf \int_{[\mathbf{A}_{s,l}(x_0,r)]^c} |u_n|^p \leq \frac{p}{(p-2)} \alpha(\Omega)$$

and

$$(9) \quad \int_{\Omega} |u_0|^p \leq \liminf \int_{\Omega} |u_n|^p = \left(\frac{2p}{p-2}\right) \beta(r) < \left(\frac{2p}{p-2}\right) \gamma(r).$$

Thus,  $u_0 \in \mathbf{M}(\Omega)$  and  $\int_{[\mathbf{A}_{s,l}(x_0,r)]^c} |u_0|^p \leq \frac{p}{(p-2)} \alpha(\Omega)$ . If  $\int_{[\mathbf{A}_{s,l}(x_0,r)]^c} |u_0|^p = \frac{p}{(p-2)} \alpha(\Omega)$ . Then  $u_0 \in N(x_0, r, s, l)$  and from (9) that

$$\frac{2p}{p-2} \gamma(r) \leq \int_{\Omega} |u_0|^p < \frac{2p}{(p-2)} \gamma(r),$$

which is a contradiction. Thus,  $\int_{[\mathbf{A}_{s,l}(x_0,r)]^c} |u_0|^p < \frac{p}{(p-2)} \alpha(\Omega)$ . This implies  $u_0 \in M(x_0, r, s, l)$  and  $J(u_0) = \beta(r)$ . Let  $p_n = u_n - u_0$ , by Bahri-Lions [2], we have

$$J(p_n) = J(u_n) - J(u_0) + o(1) = o(1)$$

and

$$\langle J'(p_n), p_n \rangle = o(1).$$

By Lemma 2, we have

$$a(p_n) = \frac{2p}{p-2} J(p_n) + o(1) = o(1).$$

Thus,  $u_n \rightarrow u_0$  strongly in  $H_0^1(\Omega)$ .

#### 4. MULTIPLE POSITIVE SOLUTIONS

We need the following definition.

**Definition 10.** A domain  $\Omega$  in  $\mathbf{A}$  is large if for any  $m > 0$  there exist  $s < l$  such that  $l - s = m$  and  $\mathbf{A}_{s,t} \subset \Omega$  where  $\mathbf{A}_{s,t} = \{(x, y) \in \mathbf{A} \mid s < y < l\}$ .

Then we have the following results.

**Lemma 11.** If  $\Omega$  is a large domain in  $\mathbf{A}$ , then  $\alpha(\Omega) = \alpha(\mathbf{A})$ . Furthermore, if  $\Omega$  is a proper large domain in  $\mathbf{A}$ , then Equation (1) in  $\Omega$  does not admit any solution  $u_0$  such that  $J(u_0) = \alpha(\Omega)$ .

*Proof.* By Lien-Tzeng-Wang [9, Lemma 2.5] and Lemma 5. ■

**Corollary 12.** If  $\Omega$  is a proper large domain in  $\mathbf{A}$ , then  $J(v) > \alpha(\Omega)$  for all  $v \in \mathbf{M}(\Omega)$ .

Throughout this section, denote  $\Omega(t) = \mathbf{S}^+ \setminus [\cup_{i=1}^m B^N((0, it); \tilde{r})]$  is an upper half strip with holes and  $\mathbf{A}_{s,l} = \mathbf{A}_{s,l}(0, r_0)$  is a finite strip. Then  $\Omega(t)$  is a proper large domain in  $\mathbf{A}$  and  $\alpha(\Omega(t)) = \alpha(\mathbf{A})$  for all  $t > 0$ . Let  $M_i(t) = M(0, r_0, (i-1)t, it)$  and  $N_i(t) = N(0, r_0, (i-1)t, it)$ , for  $i = 1, 2, \dots, m$ . Define the minimization problem in  $M_i(t)$  and  $N_i(t)$  for  $J$ ,

$$\beta_i(t) = \inf_{v \in M_i(t)} J(v)$$

and

$$\gamma_i(t) = \inf_{v \in N_i(t)} J(v).$$

Clearly,  $\beta_i(t), \gamma_i(t) \geq \alpha(\mathbf{A})$  for each  $t > 0$  and  $i = 1, 2, \dots, m$ . Let  $\overline{M_i(t)}$  be denoting the closure of  $M_i(t)$ , then we have  $\overline{M_i(t)} = M_i(t) \cup N_i(t)$  and  $N_i(t)$  is the boundary of  $\overline{M_i(t)}$ . Then, we have the following results.

**Lemma 13.** For each  $t > 2\tilde{r}$ , we have  $\overline{M_i(t)} \cap \overline{M_j(t)} = \emptyset$  for  $i \neq j$ .



*Proof.* Suppose on the contrary, there exist a  $v_0 \in \mathbf{M}(\Omega(t))$  and  $i \neq j$  such that  $v_0 \in \overline{M_i(t)} \cap \overline{M_j(t)}$ . Then

$$\int_{[\mathbf{A}_{(i-1)t,it}]^c} |v_0|^p \leq \frac{p}{(p-2)} \alpha(\mathbf{A})$$

and

$$\int_{[\mathbf{A}_{(i-1)t,it}]^c} |v_0|^p \leq \frac{p}{(p-2)} \alpha(\mathbf{A}).$$

Since  $\mathbf{A}_{(i-1)t,it} \cap \mathbf{A}_{(j-1)t,jt} = \emptyset$  for all  $t > 2r'$ , we have

$$\begin{aligned} \int_{\Omega(t)} |v_0|^p &\leq \int_{[\mathbf{A}_{(i-1)t,it}]^c} |v_0|^p + \int_{[\mathbf{A}_{(j-1)t,jt}]^c} |v_0|^p \\ &\leq \frac{2p}{(p-2)} \alpha(\mathbf{A}). \end{aligned}$$

Therefore,

$$J(v_0) = \left( \frac{p-2}{2p} \right) \int_{\Omega(t)} |v_0|^p \leq \alpha(\mathbf{A}) = \alpha(\Omega(t)),$$

This contradicts Corollary 12.

**Lemma 14.** For each  $\varepsilon > 0$  there exists a  $t_1 > 0$  such that

$$\beta_i(t) < \alpha(\mathbf{A}) + \varepsilon$$

for all  $i = 1, 2, \dots, m$  and  $t \geq t_1$ .

*Proof.* By the Lien-Tzeng-Wang [9, Lemma 2.2], we have

$$\alpha(\mathbf{A}_{(i-1)t,it}) = \alpha(\mathbf{A}_{0,t}) \searrow \alpha(\mathbf{A}) \text{ as } t \nearrow \infty.$$

Thus, there exists a  $t_1 > 0$  such that

$$(10) \quad \alpha(\mathbf{A}_{(i-1)t,it}) < \alpha(\mathbf{A}) + \varepsilon$$

for each  $i = 1, 2, \dots, m$ . By Lemma 6, Equation (1) in  $\mathbf{A}_{(i-1)t,it}$  has a positive solution  $v_i$  such that  $J(v_i) = \alpha(\mathbf{A}_{(i-1)t,it})$ ,  $v_i \in \mathbf{M}(\mathbf{A}_{(i-1)t,it}) \subset \mathbf{M}(\Omega(t))$  and

$$\int_{[\mathbf{A}_{(i-1)t,it}]^c} |v_i|^p = 0.$$

We obtain  $v_i \in M_i(t)$  and

$$(11) \quad \beta_i(t) \leq \alpha(\mathbf{A}_{(i-1)t,it})$$

for all  $i = 1, 2, \dots, m$  and  $t \geq t_1$ . By (10) and (11), we can conclude that

$$\beta_i(t) < \alpha(\mathbf{A}) + \varepsilon$$

for all  $i = 1, 2, \dots, m$  and  $t \geq t_1$ .  $\blacksquare$

**Lemma 15.** *There exist positive numbers  $\delta, t_2$  such that for each  $i = 1, 2, \dots, m$  we have*

$$\gamma_i(t) > \alpha(\mathbf{A}) + \delta \text{ for all } t \geq t_2.$$

*Proof.* Fix  $i$ . Assume to the contrary that there exist  $t_n \rightarrow \infty$  as  $n \rightarrow \infty$  and  $\{u_n\} \subset N_i(t_n) \subset \mathbf{M}(\Omega(t_n))$  such that

$$J(u_n) = \alpha(\mathbf{A}) + o(1)$$

and

$$(12) \quad \int_{[\mathbf{A}_{(i-1)t_n, it_n}]^c} |u_n|^p = \frac{p}{(p-2)} \alpha(\mathbf{A}).$$

By Lemma 4,  $\{u_n\}$  is a  $(\text{PS})_{\alpha(\mathbf{A})}$ -sequence in  $H_0^1(\mathbf{A})$  for  $J$ . Applying the concentration-compactness principle of Lions [10] there exist  $R > 0$ ,  $d > 0$  and  $\{(0, y_n)\} \in \mathbb{R}^{N-1} \times \mathbb{R}$  such that

$$\int_{B^N((0, y_n); R)} |u_n|^p \geq d \text{ for all } n.$$

Let  $v_n(z) = u_n(x, y + y_n)$ , then  $\{v_n\}$  is a  $(\text{PS})_{\alpha(\mathbf{A})}$ -sequence in  $H_0^1(\mathbf{A})$  for  $J$  and  $\{v_n\} \subset \mathbf{M}(\mathbf{A})$ . Thus, there is a  $u_0 \in H_0^1(\mathbf{A})$  such that

$$\begin{aligned} v_n &\rightarrow u_0 \text{ weakly in } H_0^1(\mathbf{A}) \text{ as } n \rightarrow \infty, \\ v_n &\rightarrow u_0 \text{ a.e. in } \mathbf{A} \text{ as } n \rightarrow \infty \end{aligned}$$

and

$$\int_{B^N(0; R)} |v_n|^p \rightarrow \int_{B^N(0; R)} |u_0|^p \geq d \text{ as } n \rightarrow \infty.$$

Moreover,  $u_0$  is a nonzero solution of Equation (1) in  $\mathbf{A}$  and  $J(u_0) = \alpha(\mathbf{A})$ . By Bahri-Lions [2], Lemma 7 and the maximum principle, we may assume that

$$v_n \rightarrow u_0 \text{ strongly in } H_0^1(\mathbf{A}) \text{ as } n \rightarrow \infty$$

and  $u_0$  is a positive solution. We complete the proof by establishing the contradiction that

$$\int_{[\mathbf{A}_{(i-1)t_n, it_n}]^c} |u_n|^p = \frac{p}{(p-2)} \alpha(\mathbf{A}) \text{ for all } n.$$

Consider the sequence  $\{it_n - y_n\}$ . By passing to a subsequence if necessary, we may assume that one of the following cases occurs:

- (a)  $\{it_n - y_n\}$  is bounded;
- (b)  $it_n - y_n \rightarrow \infty$  as  $n \rightarrow \infty$ ; and
- (c)  $it_n - y_n \rightarrow -\infty$  as  $n \rightarrow \infty$ .

In case (a), we may assume  $it_n - y_n \rightarrow y_0$ . Since

$$v_n \in H_0^1(\mathbf{A} \setminus B^N((0, it_n - y_n), \tilde{r}))$$

we have

$$\Omega(r_n) \rightarrow \mathbf{A} \setminus B^N((0, y_0), \tilde{r}) \text{ as } n \rightarrow \infty.$$

Then  $u_0 \in H_0^1(\mathbf{A} \setminus B^N((0, y_0), \tilde{r}))$ , and this contradicts the fact that  $u_0$  is a positive solution of Equation (1) in  $\mathbf{A}$ .

In case (b), since

$$v_n \rightarrow u_0 \text{ strongly in } H_0^1(\mathbf{A}) \text{ as } n \rightarrow \infty,$$

$u_0$  is a positive solution such that  $J(u_0) = \alpha(\mathbf{A})$ . By the compact imbedding theorem and the Vitali convergence theorem, given  $\varepsilon_0 = \frac{p}{(p-2)} \alpha(\mathbf{A})$  there is a  $R(\varepsilon_0) > 0$  such that

$$(13) \quad \int_{[\mathbf{A}_{-R(\varepsilon_0), R(\varepsilon_0)}]_c} |v_n|^p < \frac{p}{(p-2)} \alpha(\mathbf{A}) \text{ for all } n.$$

Since  $v_n \equiv 0$  in  $[\Omega(t_n)]_c$ ,

$$v_n \rightarrow u_0 \text{ a.e. in } \mathbf{A} \text{ as } n \rightarrow \infty$$

and  $u_0$  is a positive solution of Equation (1) in  $\mathbf{A}$ , we have

$$\lim_{n \rightarrow \infty} \Omega(t_n) = \mathbf{A}.$$

By hypothesis, we have  $(i-1)t_n - y_n \rightarrow -\infty$  as  $n \rightarrow \infty$ . Then there is a  $n_0$  such that

$$\mathbf{A}_{-R(\varepsilon_0), R(\varepsilon_0)} \subset [\mathbf{A}_{(i-1)t_n, it_n} - (0, y_n)] \text{ for all } n \geq n_0.$$

Thus,

$$(14) \quad \begin{aligned} & \int_{[\mathbf{A}_{(i-1)t_n, it_n} - (0, y_n)]_c} |v_n|^p \\ & \leq \int_{[\mathbf{A}_{-R(\varepsilon_0), R(\varepsilon_0)}]_c} |v_n|^p < \frac{p}{(p-2)} \alpha(\mathbf{A}) \text{ for all } n \geq n_0. \end{aligned}$$

Since  $\{u_n\} \subset \mathbf{M}(\Omega(t_n))$  and  $\Omega(t_n)$  is large domain in  $\mathbf{A}$ , this means

$$(15) \quad \int_{\Omega(t_n)} |u_n|^p \geq \left(\frac{2p}{p-2}\right) \alpha(\Omega(t_n)) = \left(\frac{2p}{p-2}\right) \alpha(\mathbf{A}) \text{ for all } n.$$

From (14) and (15), we have

$$\begin{aligned} \int_{[\mathbf{A}_{(i-1)t_n, it_n}]^c} |u_n|^p &= \int_{\Omega(t_n)} |u_n|^p - \int_{\mathbf{A}_{(i-1)t_n, it_n}} |u_n|^p \\ &= \int_{\Omega(t_n)} |u_n|^p - \int_{[\mathbf{A}_{(i-1)t_n, it_n} - (0, y_n)]^c} |v_n|^p \\ &> \frac{p}{(p-2)} \alpha(\mathbf{A}) \text{ for all } n \geq n_0, \end{aligned}$$

which contradicts (13).

In case (c), the proof is similar to that of case (13). Therefore, we have completed our proof. ■

Here, we will use the idea of Cao-Noussair [4] and Tarantello [11] to get the following results.

**Lemma 16.** *For any  $u^i \in M_i(t)$ , there exist  $\epsilon > 0$  and differentiable function  $t^i : B(0; \epsilon) \subset H_0^1(\Omega(t)) \rightarrow \mathbb{R}^+$  such that  $t^i(0) = 1$ , the function  $z^i = t^i(w) (u^i - w) \in M_i(t)$  and*

$$(16) \quad \begin{aligned} &\langle (t^i)'(0), v \rangle \\ &= \frac{2 \int_{\Omega(t)} \nabla u^i \nabla v + u^i v - p \int_{\Omega(t)} |u^i|^{p-2} u^i v}{\int_{\Omega(t)} |\nabla u^i|^2 + (u^i)^2 - (p-1) \int_{\Omega(t)} |u^i|^p} \text{ for all } v \in H_0^1(\Omega(t)). \end{aligned}$$

*Proof.* Define a function  $F : \mathbb{R} \times H_0^1(\Omega(t)) \rightarrow \mathbb{R}$  given by

$$F(t, w) = t \int_{\Omega(t)} |\nabla(u^i - w)|^2 + (u^i - w)^2 - t^{p-1} \int_{\Omega(t)} |u^i - w|^p.$$

Since  $u^i \in M_i(t)$ , we have  $F(0, 1) = 0$  and

$$\frac{d}{dt} F(1, 0) = \int_{\Omega(t)} |\nabla u^i|^2 + (u^i)^2 - (p-1) \int_{\Omega(t)} |u^i|^p < 0.$$

According to the implicit function theorem, there exists a continuous function  $t^i : B(0; \epsilon) \subset H_0^1(\Omega(t)) \rightarrow \mathbb{R}^+$  such that  $t^i(0) = 1$  and  $F(t^i(w), w) = 0$  for  $w \in B(0; \epsilon)$ . This is equivalent to

$$\langle J'(t^i(w) (u^i - w)), t^i(w) (u^i - w) \rangle = 0.$$

Furthermore, by the continuity of the functionals  $b$  and  $t^i$ , we have

$$\int_{[\mathbf{A}_{(i-1)t, it}]^c} |t^i(w) (u^i - w)|^p < \frac{p}{(p-2)} \alpha(\mathbf{A}),$$

if  $\epsilon$  is sufficiently small. ■

**Proposition 17.** *There exists a  $t_0 > 0$  such that for each  $t \geq t_0$  and  $i = 1, 2, \dots, m$ . We have  $\beta_i(t) < \min \{2\alpha(\Omega(t)), \gamma_i(t)\}$  and  $\beta_i(t)$  has a minimizing sequence  $\{u_n^i\} \subset M_i(t)$  satisfying*

$$\begin{aligned} J(u_n^i) &= \beta_i(t) + o(1), \\ J'(u_n^i) &= o(1) \text{ in } H^{-1}(\Omega(t)). \end{aligned}$$

*Proof.* Using Lemmas 14 and 15, we see that there exists  $t_0 > 0$  such that for  $r \geq t_0$

$$(17) \quad \beta_i(t) < \min \{2\alpha(\Omega(t)), \gamma_i(t)\}.$$

It follows that for  $t \geq t_0$

$$(18) \quad \beta_i(t) = \inf_{v \in \overline{M_i(t)}} J(v).$$

Since  $\overline{M_i(t)}$  is a closure of  $M_i(t)$ . By (18) and the Ekeland variational principle [7], there exists a minimizing sequence  $\{u_n^i\} \subset \overline{M_i(t)}$  such that

$$(19) \quad J(u_n^i) < \beta_i(t) + \frac{1}{n}$$

and

$$(20) \quad J(u_n^i) < J(w) + \frac{1}{n} \|w - u_n^i\|_{H^1} \text{ for any } w \in \overline{M_i(t)}.$$

Using (17) we may assume that  $u_n^i \in M_i(t)$  for  $n$  sufficiently large. Applying Lemma 16 with  $u^i = u_n^i$  to obtain the functions  $t_n^i : B(0; \epsilon_n) \rightarrow \mathbb{R}^+$  for some  $\epsilon_n > 0$ , such that  $t_n^i(w) (u_n^i - w) \in M^i(t)$ . Choose  $0 < \rho < \epsilon_n$ . Let  $u \in H_0^1(\Omega(t))$  with  $u \neq 0$  and let  $w_\rho = \frac{\rho u}{\|u\|_{H^1}}$ . We set  $z_\rho^i = t_n^i(w_\rho) (u_n^i - w_\rho)$ . Since  $z_\rho^i \in M_i(t)$ , we deduce from (19) that

$$J(z_\rho^i) - J(u_n^i) \geq -\frac{1}{n} \|z_\rho^i - u_n^i\|_{H^1}$$

By the mean value theorem, we have

$$\langle J'(u_n^i), z_\rho^i - u_n^i \rangle + o\left(\|z_\rho^i - u_n^i\|_{H^1}\right) \geq -\frac{1}{n} \|z_\rho^i - u_n^i\|_{H^1}.$$

Thus,

$$(21) \quad \begin{aligned} & \langle J'(u_n^i), -w_\rho \rangle + (t_n^i(w_\rho) - 1) \langle J'(u_n^i), (u_n^i - w_\rho) \rangle \\ & \geq -\frac{1}{n} \|z_\rho^i - u_n^i\|_{H^1} + o\left(\|z_\rho^i - u_n^i\|_{H^1}\right). \end{aligned}$$

From  $t_n^i(w_\rho)(u_n^i - w_\rho) \in M^i(\Omega(t))$  and (25), we have

$$\begin{aligned} & -\rho \left\langle J'(u_n^i), \frac{u}{\|u\|_{H^1}} \right\rangle + (t_n^i(w_\rho) - 1) \langle J'(u_n^i) - J'(z_\rho^i), (u_n^i - w_\rho) \rangle \\ & \geq -\frac{1}{n} \|z_\rho^i - u_n^i\|_{H^1} + o\left(\|z_\rho^i - u_n^i\|_{H^1}\right). \end{aligned}$$

Thus,

$$\begin{aligned} \left\langle J'(u_n^i), \frac{u}{\|u\|_{H^1}} \right\rangle & \leq \frac{\|z_\rho^i - u_n^i\|_{H^1}}{n\rho} + \frac{o\left(\|z_\rho^i - u_n^i\|_{H^1}\right)}{\rho} \\ & \quad + \frac{(t_n^i(w_\rho) - 1)}{\rho} \langle J'(u_n^i) - J'(z_\rho^i), (u_n^i - w_\rho) \rangle. \end{aligned}$$

On the other hand, by (16) we can find a constant  $C > 0$ , independent of  $\rho$ , such that

$$\|z_\rho^i - u_n^i\|_{H^1} \leq \rho + |t_n^i(w_\rho) - 1| C$$

and

$$\lim_{\rho \rightarrow 0} \frac{|t_n^i(w_\rho) - 1|}{\rho} \leq \left\| (t_n^i)'(0) \right\| \leq C.$$

If we let  $\rho \rightarrow 0$  in (20) for a fixed  $n$  and use the fact that  $z_\rho^i \rightarrow u_n^i$  in  $H_0^1(\Omega(t))$ , we get

$$\left\langle J'(u_n^i), \frac{u}{\|u\|_{H^1}} \right\rangle \leq \frac{C}{n}.$$

This shows that  $\{u_n^i\}$  is a  $(PS)_{\beta_i(t)}$ -sequence in  $H_0^1(\Omega(t))$  for  $J$ . ■

**Theorem 18.** *There exists  $t_0 > 0$  such that for  $t \geq t_0$ , Equation (1) in  $\Omega(t)$  has  $m$  positive higher energy solutions  $u_0^1, u_0^2, \dots, u_0^m$  with*

$$\int_{[\mathbf{A}^{(i-1)t, it}]^c} |u_0^i|^p < \frac{p}{(p-2)} \alpha(\mathbf{A}) \text{ for each } i = 1, 2, \dots, m.$$

*Proof.* It follows from Proposition 17 that there exists  $t_0 > 0$  such that for each  $t \geq t_0$  and  $i = 1, 2, \dots, m$  we can find minimizing sequence  $\{u_n^i\}$  of  $\beta_i(t)$  with

$$\beta_i(t) < \min \{2\alpha(\Omega(t)), \gamma_i(t)\}.$$

By Lemma 7 and Theorem 9, there exists  $u_0^i \in M_i(t)$  such that

$$u_n^i \rightarrow u_0^i \text{ strongly in } H_0^1(\Omega(t)),$$

$J(u_0^i) = \beta_i(t)$  and  $u_0^i$  is a positive solution of Equation (1) in  $\Omega(t)$ . By Lemma 13, that  $\overline{M_i(t)} \cap \overline{M_j(t)} = \emptyset$  for  $i \neq j$ , we get  $u_0^i \neq u_0^j$  for  $i \neq j$ . Furthermore,  $\Omega(t)$  is a large domain in  $\mathbf{A}$ , we have

$$J(u_0^i) = \beta_i(t) > \alpha(\Omega(t)), \text{ for each } i = 1, 2, \dots, m.$$

This implies,  $u_0^1, u_0^2, \dots, u_0^m$  are higher energy solutions of Equation (1) in  $\Omega(t)$ . ■

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