TAIWANESE JOURNAL OF MATHEMATICS Vol. 26, No. 6, pp. 1219–1234, December 2022 DOI: 10.11650/tjm/220404

Boundedness in Asymmetric Oscillations at Resonance in a Critical Situation

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Abstract. In this article, by using Moser's twist theorem, we prove that all solutions of the equation $x'' + ax^+ - bx^- + \varphi(x) = p(t)$ are bounded in the critical situation, where p is a smooth periodic function, and φ is bounded one.

1. Introduction

In the past few decades, due to its background in applied sciences [7], the boundedness problems for the asymmetric equations

(1.1)
$$x'' + ax^+ - bx^- = f(x,t)$$

have been extensively studied; see for examples [2-5, 8, 11, 12, 15] and references therein, where $x^+ = \max\{x, 0\}, x^- = \max\{-x, 0\}, a$ and b are different positive numbers. The function f(x, t) is periodic in t.

Generally speaking, in the case of resonance, that is,

(1.2)
$$\frac{1}{\sqrt{a}} + \frac{1}{\sqrt{b}} = \frac{2}{n}, \quad n \in \mathbb{N},$$

the boundedness problems for (1.1) are more difficult to study than in non-resonance case.

Liu [8] obtained the boundedness of the solutions for (1.1) when f dependents only on t and satisfies

$$\int_0^{2\pi} f(t)\mathbf{C}(\theta+t) \, dt \neq 0, \quad \theta \in \mathbb{R},$$

where \mathbf{C} is the solution of the initial value problem

(1.3)
$$\begin{cases} x'' + ax^+ - bx^- = 0, \\ x(0) = 1, \quad x'(0) = 0. \end{cases}$$

In [12], Wang proved the boundedness of solutions for the equation

(1.4)
$$x'' + ax^{+} - bx^{-} + \varphi(x) = p(t)$$

Received November 24, 2021; Accepted April 21, 2022.

Communicated by Cheng-Hsiung Hsu.

Key words and phrases. asymmetric oscillations, boundedness, at resonance, critical situation, twist theorem.

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²⁰²⁰ Mathematics Subject Classification. 34C11, 34C27, 37E40.

under the condition

(1.5)
$$\int_{0}^{2\pi} p(t)\mathbf{C}(\theta+t) dt \neq 2n\sqrt{a} \left(\frac{\varphi(+\infty)}{a} - \frac{\varphi(-\infty)}{b}\right), \quad \theta \in \mathbb{R}$$

with $\varphi(\pm \infty) = \lim_{x \to \pm \infty} \varphi(x)$.

Fabry and Mawhin [4] obtained the boundedness result for (1.1) with $f(x,t) = \varphi(x) + g(x) + p(t)$ under the condition (1.5), where g is a sublinear primitive and bounded. If $a = b = n^2$, (1.4) becomes the symmetric equation

(1.6)
$$x'' + n^2 x + \varphi(x) = p(t), \quad n \in \mathbb{N}$$

It is obviously in the resonant case. Lazer and Leach [6] proved that (1.6) has at least one periodic solution under the so-called Lazer–Leach condition

(1.7)
$$\left| \int_{0}^{2\pi} p(t)e^{-int} dt \right| < 2 \left(\liminf_{x \to +\infty} \varphi - \limsup_{x \to -\infty} \varphi \right), \quad \forall \theta \in [0, 2\pi].$$

In 1999, Liu [9] proved that each solution of the equation (1.6) is bounded with $p \in C^7(\mathbb{R}/2\pi\mathbb{Z}), \varphi \in C^6(\mathbb{R})$ under the condition (1.7).

However, Alonso and Ortega [1] proved that if $\lim_{|x|\to\infty} \psi(x)/x = 0$ and φ is bounded, each solution of the semilinear equation

(1.8)
$$x'' + n^2 x + \varphi(x) + \psi'(x) = p(t) = p(t + 2\pi)$$

is unbounded with a large initial condition if

$$\left|\int_0^{2\pi} p(t)e^{-int}\,dt\right| > 2(H-K),$$

where $H = \max \{ \limsup_{x \to -\infty} \varphi, \limsup_{x \to +\infty} \varphi \}$ and $K = \min \{ \liminf_{x \to -\infty} \varphi, \lim_{x \to +\infty} \inf_{x \to +\infty} \varphi \}$.

In 2016, Wang, Wang and Piao [13] showed that if ψ oscillates periodically in x, the Lazer-Leach condition (1.7) is sufficient and necessary for the boundedness of (1.8).

So we can ask a question: if the "<" in (1.6) is changed to "=" (critical situation), can one obtain boundedness results for (1.6)?

Recently, Xing, Wang and Wang [14] succeeded in answer the question. They obtained a certain sufficient and necessary condition for the boundedness for (1.6) in the critical situation, that is,

$$\left|\int_0^{2\pi} p(t)e^{-int} dt\right| = 2(\varphi(+\infty) - \varphi(-\infty)),$$

where $\varphi(\pm \infty)$ exit finitely and p is 2π -periodic in t.

In this article, we are going to study the analogical problem of [14] for the asymmetric equation (1.4). The corresponding critical situation should be

(1.9)
$$\int_{0}^{2\pi} p(t)\mathbf{C}(t-\theta) dt = 2n\sqrt{a} \left(\frac{\varphi(+\infty)}{a} - \frac{\varphi(-\infty)}{b}\right) \quad \text{for some } \theta \in \mathbb{R}.$$

We suppose that there exist two positive constants c_{\pm} such that

(1.10)
$$\lim_{x \to \pm \infty} x^{k-1+d} \Gamma_{\pm}^{(k)}(x) = 0, \quad 0 < k \le 11$$

with 0 < d < 1 and

(1.11)
$$\Gamma_{\pm}(x) = \int_0^x (\varphi(x) - \varphi(\pm \infty)) \, dx - c_{\pm} \cdot (1 + x^2)^{(1-d)/2}.$$

Now we can state our main result as below.

Theorem 1.1. Suppose that $p \in C^6(\mathbb{R}/2\pi\mathbb{Z}), \varphi \in C^{10}(\mathbb{R})$ satisfying

$$\varphi(\pm\infty):=\lim_{x\to\pm\infty}\varphi(x)$$

are finite. Assume (1.2), (1.9)-(1.11) hold true, then all solutions of (1.4) are bounded.

Remark 1.2. Theorem 1.1 is applicable to many equations. Here we provide a concrete example.

Let
$$p(t) = 4\cos(nt), \varphi(x) = \arctan x + 2x(1+x^2)^{-2/3}$$
. Then we have

$$\int_0^{2\pi} p(t)\mathbf{C}(t-\theta) dt$$

$$= 4\cos(n\theta) \int_0^{2\pi} \cos(nt)\mathbf{C}(t) dt - 4\sin(n\theta) \int_0^{2\pi} \sin(nt)\mathbf{C}(t) dt$$

$$= 8n\cos(n\theta) \left(\int_0^{\frac{\pi}{2\sqrt{a}}} \cos(nt)\cos(\sqrt{a}t) dt - \sqrt{\frac{a}{b}} \int_0^{\frac{\pi}{2\sqrt{b}}} \cos\left(n\left(t+\frac{\pi}{2\sqrt{a}}\right)\right)\sin\sqrt{b}t dt\right)$$

$$= 8n\sqrt{a}\cos(n\theta)\cos\left(\frac{n\pi}{2\sqrt{a}}\right) \left(\frac{1}{a-n^2} - \frac{1}{b-n^2}\right).$$

Now we choose a = 36, b = 144, n = 8, which satisfy the condition (1.2). Meanwhile

$$\int_{0}^{2\pi} p(t)\mathbf{C}(t-\theta) dt = 8n\sqrt{a}\cos(n\theta)\cos\left(\frac{n\pi}{2\sqrt{a}}\right)\left(\frac{1}{a-n^2} - \frac{1}{b-n^2}\right) = \frac{324}{35}\cos(8\theta),$$
$$2n\sqrt{a}\left(\frac{\varphi(+\infty)}{a} - \frac{\varphi(-\infty)}{b}\right) = \frac{5\pi}{3}.$$

One can take $\theta = \frac{1}{8} \arccos \frac{175\pi}{972} + 2k\pi$ ($k \in \mathbb{Z}$) such that the condition (1.9) holds. Then, according to Theorem 1.1, we obtain the boundedness for the equation with d = 1/3, $c_{\pm} = 3$.

In fact, the conclusion of Theorem 1.1 is also true, if the conditions (1.2) and (1.9) are replaced respectively by

•
$$\frac{1}{\sqrt{a}} + \frac{1}{\sqrt{b}} = \frac{2m}{n}$$
, where *m* and *n* are relatively prime positive integers

and

•
$$\int_{0}^{2\pi} p(mt) \mathbf{C}(mt-\theta) dt = \frac{2n\sqrt{a}}{m} \left(\frac{\varphi(+\infty)}{a} - \frac{\varphi(-\infty)}{b}\right) \text{ for some } \theta \in \mathbb{R}.$$

This paper is organized as follows. In Section 2, we give some technical lemmas. In Section 3, we introduce a rotation transformation and make a series of canonical transformations such that the new Hamiltonian system is closed to a nearly integrable one. In Section 4, we first give a twist condition in some weak way, then prove the boundedness of solutions of (1.4) by Moser's twist theorem.

Throughout this paper, we denote by

$$[I](\cdot) := \frac{1}{2\pi} \int_0^{2\pi} I(\,\cdot\,,\theta) \, d\theta$$

the average value of $I(\cdot, \theta)$ over $\mathbb{R}/2\pi\mathbb{Z}$. We denote by C > 1, c < 1 two positive constants without concerning their quantity.

2. Preliminaries

In this section, some technical lemmas will be given.

Introduce a new variable y as x' = -y, then the equation (1.4) is equivalent to a planar non-autonomous Hamiltonian system

(2.1)
$$x' = -\frac{\partial H}{\partial y}(x, y, t), \quad y' = \frac{\partial H}{\partial x}(x, y, t),$$

where $H(x, y, t) = \frac{1}{2}y^2 + \frac{1}{2}a(x^+)^2 + \frac{1}{2}b(x^-)^2 + \Phi(x) - xp(t), \ \Phi(x) = \int_0^x \varphi(s) \, ds.$ Define $\mathbf{S}(t) = -\mathbf{C}'(t)$. Then $(\mathbf{C}(t), \mathbf{S}(t))$ is the solution of the following system

$$x' = -y, \quad y' = ax^+ - bx^-$$

with the initial condition $(\mathbf{C}(0), \mathbf{S}(0)) = (1, 0)$ from (1.3). Hence

- C(-t) = C(t), S(-t) = -S(t);
- $\mathbf{C}(t)$ and $\mathbf{S}(t)$ are $\frac{2\pi}{n}$ -periodic functions;
- $\mathbf{S}^{2}(t) + a(\mathbf{C}^{+}(t))^{2} + b(\mathbf{C}^{-}(t))^{2} \equiv a;$
- $\mathbf{C}(t)$ can be given by

$$\mathbf{C}(t) = \begin{cases} \cos\sqrt{a}t, & 0 \le |t| \le \frac{\pi}{2\sqrt{a}}, \\ -\sqrt{\frac{a}{b}}\sin\sqrt{b}\left(t - \frac{\pi}{2\sqrt{a}}\right), & \frac{\pi}{2\sqrt{a}} < |t| \le \frac{\pi}{n}, \end{cases}$$

For r > 0, we make the transformation $(r, \theta) \to (x, y)$:

$$x = a^{-1/2} r^{1/2} \mathbf{C}(\theta), \quad y = a^{-1/2} r^{1/2} \mathbf{S}(\theta),$$

then the Hamiltonian system (2.1) is changed into

(2.2)
$$\frac{dr}{dt} = -\frac{\partial h}{\partial \theta}(r,\theta,t), \quad \frac{d\theta}{dt} = \frac{\partial h}{\partial r}(r,\theta,t),$$

where

(2.3)
$$h(r,\theta,t) = r + I_1(r,\theta) + I_2(r,\theta,t)$$

with $I_1(r,\theta) = 2\Phi(a^{-1/2}r^{1/2}\mathbf{C}(\theta)), \ I_2(r,\theta,t) = -2a^{-1/2}r^{1/2}\mathbf{C}(\theta)p(t).$

Similar to [9], we can obtain the following estimates on $I_1(r,\theta)$, $I_2(r,\theta,t)$ by direct calculations. We omit the proof here.

Lemma 2.1. For $r \gg 1$, it holds that

$$|I_1(r,\theta)| \le Cr^{1/2}, \quad |\partial_r^i \partial_\theta^j I_1(r,\theta)| \le Cr^{-i+\frac{1}{2}+\frac{1}{2}(\max(1,j)-1)}, \quad i+j \le 11.$$

Lemma 2.2. For $r \gg 1$, it holds that

$$|\partial_r^i \partial_\theta^j \partial_t^k I_2(r,\theta,t)| \le Cr^{-i+1/2}, \quad i+j \le 11, \ k \le 6.$$

Lemma 2.3. Let

$$\alpha(r) = [I_1](r) - \frac{2n}{\pi} r^{1/2} \cdot \left(\frac{\varphi(+\infty)}{a} - \frac{\varphi(-\infty)}{b}\right).$$

Then $\alpha(r)$ satisfies

$$cr^{(1-d)/2-k} \le \alpha^{(k)}(r) \le Cr^{(1-d)/2-k}, \qquad k = 0, 1, \ 0 < d < 1,$$
$$|\alpha^{(2)}(r)| \ge cr^{(1-d)/2-2}, \quad |\alpha^{(k)}(r)| \le cr^{(1-d)/2-k}, \qquad k \le 11, \ 0 < d < 1.$$

Proof. By definition of $[I_1](r)$, one has

$$\alpha(r) = \frac{1}{2\pi} \int_0^{2\pi} 2\Phi(a^{-1/2}r^{1/2}\mathbf{C}(\theta)) \, d\theta - \frac{2n}{\pi}r^{1/2} \cdot \left(\frac{\varphi(+\infty)}{a} - \frac{\varphi(-\infty)}{b}\right).$$

By direct calculations, one has

$$\begin{aligned} \alpha'(r) &= \frac{a^{-1/2}r^{-1/2}}{2\pi} \left(\int_0^{2\pi} \varphi(a^{-1/2}r^{1/2}\mathbf{C}(\theta))\mathbf{C}(\theta) \, d\theta - 2na^{1/2} \cdot \left(\frac{\varphi(+\infty)}{a} - \frac{\varphi(-\infty)}{b}\right) \right) \\ &= \frac{a^{-1/2}r^{-1/2}}{2\pi} \sum_{k=1}^n (\alpha_{k+}(r) + \alpha_{k-}(r)), \end{aligned}$$

where

(2.5)
$$\alpha_{k+}(r) = \int_{\frac{2k\pi}{n} - \frac{\pi}{2\sqrt{a}}}^{\frac{2k\pi}{n} + \frac{\pi}{2\sqrt{a}}} (\varphi(a^{-1/2}r^{1/2}\mathbf{C}(\theta)) - \varphi(+\infty))\mathbf{C}(\theta) d\theta,$$
$$\alpha_{k-}(r) = \int_{\frac{2k\pi}{n} + \frac{\pi}{2\sqrt{a}}}^{\frac{2(k+1)\pi}{n} - \frac{\pi}{2\sqrt{a}}} (\varphi(a^{-1/2}r^{1/2}\mathbf{C}(\theta)) - \varphi(-\infty))\mathbf{C}(\theta) d\theta.$$

By (1.10), as $r \to \infty$, there exists a positive constant $C_1(d)$ such that

$$(a^{-1}r)^{d/2}\alpha_{k+}(r) = \int_{\frac{2k\pi}{n} - \frac{\pi}{2\sqrt{a}}}^{\frac{2k\pi}{n} + \frac{\pi}{2\sqrt{a}}} (\varphi(a^{-1/2}r^{1/2}\mathbf{C}(\theta)) - \varphi(+\infty))(a^{-1/2}r^{1/2}\mathbf{C}(\theta))^{d}\mathbf{C}^{1-d}(\theta) \, d\theta$$

$$\to C_{1}(d)c_{+},$$

$$(a^{-1}r)^{d/2}\alpha_{k-}(r) = \int_{\frac{2k\pi}{n} + \frac{\pi}{2\sqrt{a}}}^{\frac{(2k+1)\pi}{n} - \frac{\pi}{2\sqrt{a}}} (\varphi(a^{-1/2}r^{1/2}\mathbf{C}(\theta)) - \varphi(-\infty))(a^{-1/2}r^{1/2}\mathbf{C}(\theta))^{d}\mathbf{C}^{1-d}(\theta) \, d\theta$$

$$\to C_{1}(d)c_{-}.$$

Then we have, as $r \to \infty$,

$$(a^{-1}r)^{(d+1)/2}\alpha'(r) \to \frac{1}{2\pi a}C_1(d)(c_++c_-),$$

which implies that

(2.6)
$$cr^{(1-d)/2-1} \le \alpha'(r) \le Ch_3^{(1-d)/2-1}.$$

The conclusion

$$cr^{(1-d)/2} \le \alpha(r) \le Cr^{(1-d)/2}$$

is a consequence of (2.6) by the rule of L'Hospital.

By (1.10) and (2.5), as $r \to \infty$, there exists a positive constant $C_2(d)$ such that

$$2(a^{-1}r)^{d/2}r\alpha'_{k+}(r) = \int_{\frac{2k\pi}{n} - \frac{\pi}{2\sqrt{a}}}^{\frac{2k\pi}{n} + \frac{\pi}{2\sqrt{a}}} \varphi'(a^{-1/2}r^{1/2}\mathbf{C}(\theta))(a^{-1/2}r^{1/2}\mathbf{C}(\theta))^{1+d}\mathbf{C}^{1-d}(\theta) d\theta$$

$$\rightarrow -C_2(d)c_+d(1-d),$$

$$2(a^{-1}r)^{d/2}r\alpha'_{k-}(r) = \int_{\frac{2k\pi}{n} + \frac{\pi}{2\sqrt{a}}}^{\frac{(2k+1)\pi}{n} - \frac{\pi}{2\sqrt{a}}} \varphi'(a^{-1/2}r^{1/2}\mathbf{C}(\theta))(a^{-1/2}r^{1/2}\mathbf{C}(\theta))^{1+d}\mathbf{C}^{1-d}(\theta) d\theta$$

$$\rightarrow -C_2(d)c_-d(1-d).$$

Thus

(2.7)
$$(\alpha'_{k+}(r) + \alpha'_{k-}(r)) \to -C_2(d)(c_+ + c_-)d(1-d)\frac{1}{2}a^{d/2}r^{-1-d/2}.$$

By (2.4), one has

$$\alpha''(r) = -\frac{a^{-1/2}r^{-3/2}}{4\pi} \sum_{k=1}^{n} (\alpha_{k+}(r) + \alpha_{k-}(r)) + \frac{a^{-1/2}r^{-1/2}}{2\pi} \sum_{k=1}^{n} (\alpha'_{k+}(r) + \alpha'_{k-}(r)),$$

which together with (2.6) and (2.7) implies $|\alpha''(r)| \ge cr^{(1-d)/2-2}$.

By direct calculations, one has for $m \leq 11$ that

$$r^{m+d/2}\alpha_{k+}^{(m)}(r) = \int_{\frac{2k\pi}{n} - \frac{\pi}{2\sqrt{a}}}^{\frac{2k\pi}{n} + \frac{\pi}{2\sqrt{a}}} \sum_{i=1}^{m} c\varphi^{(i)}(a^{-1/2}r^{1/2}\mathbf{C}(\theta))(a^{-1/2}r^{1/2}\mathbf{C}(\theta))^{i+d}\mathbf{C}^{1-d}(\theta) d\theta,$$

$$r^{m+d/2}\alpha_{k-}^{(m)}(r) = \int_{\frac{2k\pi}{n} + \frac{\pi}{2\sqrt{a}}}^{\frac{2(k+1)\pi}{n} - \frac{\pi}{2\sqrt{a}}} \sum_{i=1}^{m} c\varphi^{(i)}(a^{-1/2}r^{1/2}\mathbf{C}(\theta))(a^{-1/2}r^{1/2}\mathbf{C}(\theta))^{i+d}\mathbf{C}^{1-d}(\theta) d\theta.$$

As $r \to \infty$, we have

(2.8)
$$|\alpha_{k\pm}^{(m)}(r)| \le Cr^{-m-d/2}$$

Thus we can obtain the last estimate from (2.4) and (2.8).

By (2.3), Lemmas 2.1 and 2.2, one has $\partial_r h > 0$ for $r \gg 1$. Then by the implicit function theorem, there exists a function $R(h, t, \theta)$ such that

$$r(h, t, \theta) = h - R(h, t, \theta),$$

where

$$R(h,t,\theta) = I_1(h-R,\theta) + I_2(h-R,\theta,t) = I_1(h,\theta) + I_2(h,\theta,t) - R_0(h,t,\theta)$$

with $R_0(h, t, \theta) = \int_0^1 \partial_r I_1(h - \mu R, \theta) R \, d\mu + \int_0^1 \partial_r I_2(h - \mu R, \theta, t) R \, d\mu.$

Now h, t and θ are the new action, angle and time variables respectively. Moreover $R(h, t, \theta)$ and $R_0(h, t, \theta)$ satisfy the following estimates.

Lemma 2.4. For $h \gg 1$, it holds that

(2.9)
$$\begin{aligned} |\partial_h^i \partial_t^j \partial_\theta^k R| &\leq C h^{-i+\frac{1}{2}+\frac{1}{2}\{\max\{1,k\}-1\}}, \quad i+k \leq 11, \ j \leq 6, \\ |\partial_h^i \partial_t^j \partial_\theta^k R_0| &\leq C h^{-i+k/2}, \quad i+k \leq 10, \ j \leq 6. \end{aligned}$$

The proof can be obtained by direct calculations similar to that of Lemma 3.1 in [14]. Thus we omit it here.

Now the Hamiltonian system (2.2) can be written

$$\frac{dh}{d\theta} = -\frac{\partial r}{\partial t}(h, t, \theta), \quad \frac{dt}{d\theta} = \frac{\partial r}{\partial h}(h, t, \theta)$$

where

(2.10)
$$r(h,t,\theta) = h - I_1(h,\theta) - I_2(h,\theta,t) + R_0(h,t,\theta).$$

3. Canonical transformations

In this section, we will make some canonical transformations such that the perturbation satisfies desirable estimates. First, we eliminate the linear part of the Hamiltonian by a rotation transformation.

Lemma 3.1. There exists a rotation transformation Ψ_1 of the form

 $\Psi_1: \quad h = h_1, \quad t = t_1 + \theta$

such that the system with the Hamiltonian (2.10) is transformed into a sublinear system with the following Hamiltonian

(3.1)
$$r_1(h_1, t_1, \theta) = -I_1(h_1, \theta) - I_2(h_1, \theta, t_1 + \theta) + R_1(h_1, t_1, \theta),$$

where $R_1(h_1, t_1, \theta) = R_0(h, t_1 + \theta, \theta)$ satisfies

(3.2)
$$|\partial_{h_1}^i \partial_{t_1}^j \partial_{\theta}^k R_1(h_1, t_1, \theta)| \le Ch_1^{-i+k/2}, \quad i+k \le 10, \ j \le 6.$$

Proof. It is not difficult to obtain (3.1) and (3.2) from (2.10) and (2.9).

Lemma 3.2. There exists a canonical transformation Ψ_2 given by

(3.3)
$$\Psi_2: \quad h_1 = h_2, \quad t_1 = t_2 - \partial_{h_2} S_2(h_2, \theta)$$

with

(3.4)
$$S_2(h_2, \theta) = \int_0^\theta (I_1(h_2, \theta) - [I_1](h_2)) \, ds$$

such that the Hamiltonian (3.1) is transformed into the following Hamiltonian

(3.5)
$$r_2(h_2, t_2, \theta) = -[I_1](h_2) - I_2(h_2, \theta, t_2 + \theta) + R_2(h_2, t_2, \theta),$$

where $R_2(h_2, t_2, \theta)$ satisfies

(3.6)
$$|\partial_{h_2}^i \partial_{t_2}^j \partial_{\theta}^k R_2(h_2, t_2, \theta)| \le Ch_2^{-i+k/2}, \quad i+k \le 10, \ j \le 5.$$

Proof. Under the transformation Ψ_2 , the transformed Hamiltonian is

$$r_{2}(h_{2}, t_{2}, \theta) = -I_{1}(h_{2}, \theta) - I_{2}(h_{2}, \theta, t_{2} - \partial_{h_{2}}S_{2} + \theta) + R_{1}(h_{2}, t_{2} - \partial_{h_{2}}S_{2}, \theta) + \partial_{\theta}S_{2}$$

= -[I_{1}](h_{2}) - I_{2}(h_{2}, \theta, t_{2} + \theta) + [I_{1}](h_{2}) - I_{1}(h_{2}, \theta) + R_{2}(h_{2}, t_{2}, \theta) + \partial_{\theta}S_{2},

where

$$R_2(h_2, t_2, \theta) = R_1(h_2, t_2 - \partial_{h_2}S_2, \theta) + \int_0^1 \partial_{t_1}I_2(h_2, \theta, t_2 - \mu\partial_{h_2}S_2 + \theta)\partial_{h_2}S_2 d\mu.$$

By (3.4), one has

$$[I_1](h_2) - I_1(h_2, \theta) + \partial_{\theta} S_2 = 0.$$

Thus we obtain the Hamiltonian (3.5). By Lemma 2.1, one has

(3.7)
$$|\partial_{h_2}^i \partial_{\theta}^j S_2(h_2, \theta)| \le C h_2^{-i + \frac{1}{2} + \frac{1}{2}(\max\{1, j\} - 1)}, \quad i + j \le 11.$$

By (3.3), we have

(3.8)
$$|\partial_{h_2}t_1| \le Ch_2^{-3/2}, \quad \frac{1}{2} \le |\partial_{t_2}t_1| \le 2, \quad |\partial_{\theta}t_1| \le Ch_2^{-1/2},$$

(3.9)
$$|\partial_{h_2}^i \partial_{\theta}^j \partial_{t_2}^k t_1| \le Ch_2^{-i-\frac{1}{2}+\frac{1}{2}(\max\{1,j\}-1)}, \quad i+j+k \ge 2, \ i+j \le 10, \ k \le 6.$$

By Leibniz's rule, $\partial_{h_2}^i \partial_{t_2}^j \partial_{\theta}^k R_1(h_2, t_2 - \partial_{h_2}S_2, \theta)$ is the summation of terms

$$\partial_{h_1}^m \partial_{t_1}^s \partial_{\theta}^q R_1 \cdot \prod_{l=1}^s \partial_{h_2}^{i_l} \partial_{t_2}^{j_l} \partial_{\theta}^{k_l} t_1$$

with $1 \le m + s + q \le i + j + k$, $m + \sum_{l=1}^{s} i_l = i$, $\sum_{l=1}^{s} j_l = j$ and $q + \sum_{l=1}^{s} k_l = k$. Combining (3.2), (3.8) with (3.9), we obtain

(3.10)
$$|\partial_{h_2}^i \partial_{t_2}^j \partial_{\theta}^k R_1(h_2, t_2 - \partial_{h_2} S_2, \theta)| \le Ch_2^{-i+k/2}, \quad i+k \le 10, \ j \le 6.$$

Similarly, we obtain

(3.11)
$$\begin{aligned} |\partial_{h_2}^i \partial_{t_2}^j \partial_{\theta}^k (\partial_{t_1} I_2(h_2, \theta, t_2 - \mu \partial_{h_2} S_2 + \theta))| \\ &\leq C h_2^{-i + \frac{1}{2} + \frac{1}{2} (\max\{1, k\} - 1)}, \quad i + k \leq 10, \ j \leq 5. \end{aligned}$$

By (3.7), (3.11) and Leibniz's rule, one has

(3.12)
$$\begin{aligned} |\partial_{h_2}^i \partial_{t_2}^j \partial_{\theta}^k (\partial_{t_1} I_2(h_2, \theta, t_2 - \mu \partial_{h_2} S_2 + \theta) \cdot \partial_{h_2} S_2)| \\ &\leq C h_2^{-i - \frac{1}{2} + \frac{1}{2} (\max\{1, k\} - 1)}, \quad i + k \leq 10, \ j \leq 5. \end{aligned}$$

Then the estimate (3.6) follows from (3.10) and (3.12).

Without causing confusion, denote

$$[I_2](h,t) = \frac{1}{2\pi} \int_0^{2\pi} I_2(h,\theta,t+\theta) \, d\theta.$$

Lemma 3.3. There exists a canonical transformation Ψ_3 given by

$$\Psi_3: \quad h_2 = h_3 + \partial_{t_2} S_3(h_3, t_2, \theta), \quad t_3 = t_2 + \partial_{h_3} S_3(h_3, t_2, \theta)$$

with

(3.13)
$$S_3(h_3, t_2, \theta) = \int_0^\theta (I_2(h_3, s, t_2 + s) - [I_2](h_3, t_2)) \, ds$$

such that the Hamiltonian (3.5) is transformed into the following Hamiltonian

(3.14)
$$r_3(h_3, t_3, \theta) = I(h_3, t_3) + R_3(h_3, t_3, \theta),$$

where $R_3(h_3, t_3, \theta)$ and $I(h_3, t_3)$ satisfy

(3.15)
$$|\partial_{h_3}^i \partial_{t_3}^j \partial_{\theta}^k R_3(h_3, t_3, \theta)| \le Ch_3^{-i+k/2}, \qquad i+k \le 10, \ j \le 5,$$

(3.16)
$$|\partial_{h_3}^k I(h_3, t_3)| \ge ch_3^{(1-d)/2-k}, \quad k = 0, 1, 2,$$

(3.17)
$$|\partial_{h_3}^k \partial_{t_3}^l I(h_3, t_3)| \le C h_3^{-k+1/2}, \qquad k \le 11, \ l \le 6.$$

Proof. Under the transformation Ψ_3 , the transformed Hamiltonian is

$$\begin{aligned} r_3(h_3, t_3, \theta) &= -[I_1](h_3 + \partial_{t_2}S_3) - I_2(h_3 + \partial_{t_2}S_3, \theta, t_2 + \theta) \\ &+ R_2(h_3 + \partial_{t_2}S_3, t_3 - \partial_{h_3}S_3, \theta) + \partial_{\theta}S_3 \\ &= -[I_1](h_3) - [I_2](h_3, t_3) + [I_2](h_3, t_2) - I_2(h_3, \theta, t_2 + \theta) \\ &+ \partial_{\theta}S_3 + R_3(h_3, t_3, \theta), \end{aligned}$$

where

$$R_{3}(h_{3}, t_{3}, \theta) = R_{2}(h_{3} + \partial_{t_{2}}S_{3}, t_{3} - \partial_{h_{3}}S_{3}, \theta) - \int_{0}^{1} \partial_{h_{2}}I_{2}(h_{3} + \mu\partial_{t_{2}}S_{3}, \theta, t_{2} + \theta)\partial_{t_{2}}S_{3} d\mu + \int_{0}^{1} \partial_{t_{2}}[I_{2}](h_{3}, t_{3} - \mu\partial_{h_{3}}S_{3})\partial_{h_{3}}S_{3} d\mu - \int_{0}^{1}[I_{1}]'(h_{3} + \mu\partial_{t_{2}}S_{3})\partial_{t_{2}}S_{3} d\mu.$$

By (3.13), one has

$$[I_2](h_3, t_2) - I_2(h_3, \theta, t_2 + \theta) + \partial_{\theta}S_3 = 0.$$

Denote $I(h_3, t_3) = -[I_1](h_3) - [I_2](h_3, t_3)$, then we obtain the Hamiltonian (3.14). By Lemma 2.2, one has

$$|\partial_{h_3}^i \partial_{t_2}^j \partial_{\theta}^k S_3(h_3, t_2, \theta)| \le C h_2^{-i+1/2}, \quad i+k \le 11, \ j \le 6.$$

From (3.3), we have

$$\begin{aligned} |\partial_{h_3} t_2| &\leq Ch_3^{-3/2}, \quad \frac{1}{2} \leq |\partial_{t_3} t_2| \leq 2, \quad |\partial_{\theta} t_2| \leq Ch_2^{-1/2}, \\ |\partial_{h_3}^i \partial_{\theta}^j \partial_{t_3}^k t_2| &\leq Ch_2^{-i-1/2}, \quad i+j+k \geq 2, \ i+j \leq 10, \ k \leq 6, \\ \frac{1}{2} \leq |\partial_{h_3} h_2| \leq 2, \quad |\partial_{t_3} h_2| \leq Ch_3^{1/2}, \quad |\partial_{\theta} h_2| \leq Ch_3^{1/2}, \\ |\partial_{h_3}^i \partial_{\theta}^j \partial_{t_3}^k h_2| &\leq Ch_3^{-i+1/2}, \quad i+j+k \geq 2, \ i+j \leq 10, \ k \leq 5. \end{aligned}$$

Similar to the proof of (3.6), we can obtain (3.15).

Notice that

$$-I(h_3, t_3) = [I_1](h_3) + [I_2](h_3, t_3)$$

= $\alpha(h_3) + \frac{2h_3^{1/2}}{\pi} \cdot \left(\frac{n\varphi(+\infty)}{a} - \frac{n\varphi(-\infty)}{b} - \frac{1}{2\sqrt{a}}\int_0^{2\pi} \mathbf{C}(t-\theta)p(t)\,dt\right),$

which together with (1.9) and Lemma 2.3 implies (3.16) and (3.17).

Lemma 3.4. [14] Consider the system with Hamiltonian

(3.18)
$$\widetilde{r} = \widetilde{I}(h,t) + \widetilde{R}(h,t,\theta)$$

where $\widetilde{I}(h,t)$ satisfies (3.16) and (3.17) for $k \leq m, l \leq n$, and $R(h,t,\theta)$ satisfies

$$|\partial_h^j \partial_t^k \partial_\theta^l R| \le C h^{-j - i/2 + \max\{0, (l-i)/2\}}$$

for h large enough, $j + l \le m_1$, $k \le n_1$ $(m_1 \le m, n_1 \le n)$. Then there exists a transformation Ψ_+ of the form

$$h = h_{+} + \partial_t S_{+}(h_{+}, t, \theta), \quad t_{+} = t + \partial_{h_{+}} S_{+}(h_{+}, t, \theta)$$

with

$$S_{+}(h_{+},t,\theta) = -\int_{0}^{\theta} \left(\widetilde{R}(h_{+},t,\theta) - [\widetilde{R}](h_{+},t,0)\right) d\theta$$

such that the Hamiltonian (3.18) is transformed to

$$\widetilde{r}_{+}(h_{+}, t_{+}, \theta) = \widetilde{I}_{+}(h_{+}, t_{+}) + \widetilde{R}_{+}(h_{+}, t_{+}, \theta),$$

where $\tilde{I}_{+}(h_{+}, t_{+}) = \tilde{I}(h_{+}, t_{+}) + [\tilde{R}](h_{+}, t_{+})$ satisfies (3.16) and (3.17) for $k \le m_1, l \le n_1$. Moreover for $h_{+} \gg 1$, $l \le n_1 - 1$, $k + j \le m_1 - 1$, it holds that

$$|\partial_{h_+}^j \partial_{t_+}^l \partial_{\theta}^k \widetilde{R}_+| \le C h_+^{-j-(i+1)/2 + \max\{0, (k-i-1)/2\}}.$$

Lemma 3.5. There exists a canonical transformation Ψ_4 given by

$$\Psi_4: \quad h_3 = h_4 + U(h_4, t_4, \theta), \quad t_3 = t_4 + V(h_4, t_4, \theta)$$

such that the Hamiltonian (3.14) is transformed into the following Hamiltonian

(3.19)
$$r_4(h_4, t_4, \theta) = I(h_4, t_4) + R_4(h_4, t_4, \theta)$$

with $I(h_4, t_4)$ and $R_4(h_4, t_4, \theta)$ satisfying

(3.20)
$$|\partial_{h_4}^k I(h_4, t_4)| \ge ch_4^{(1-d)/2-k}, \qquad k = 0, 1, 2,$$

(3.21)
$$|\partial_{h_4}^k \partial_{t_4}^l I(h_4, t_4)| \le Ch_4^{-k+1/2}, \qquad k \le 5, \ l \le 1,$$

(3.22)
$$|\partial_{h_4}^i \partial_{t_4}^j \partial_{\theta}^k R_4(h_4, t_4, \theta)| \le Ch_4^{-i-5/2}, \qquad i+k \le 5.$$

Proof. We can prove this lemma by Lemma 3.3 and repeated applications of canonical transformations given in Lemma 3.4. \Box

Consider the Hamiltonian (3.19). Noting that $\partial_{h_4}^k I(h_4, t_4) \ge ch_4^{(1-d)/2-1} > 0$ as $h_4 \to \infty$, we can solve (3.19) for large h_4 as follows:

(3.23)
$$h_4(r_4, \theta, t_4) = N(r_4, t_4) + P(r_4, \theta, t_4),$$

where $h_4 = N(r_4, t_4)$ is the inverse function of $r_4 = I(h_4, t_4)$. By (3.19) and (3.23), one has

$$r_4 = I(N+P, t_4) + R_4(N+P, t_4, \theta)$$

= $I(N, t_4) + \int_0^1 \partial_{h_4} I(N+\mu P, t_4) P \, d\mu + R_4(N+P, t_4, \theta).$

Note that $r_4 = I(h_4, t_4)$, thus

(3.24)
$$0 = \int_0^1 \partial_{h_4} I(N + \mu P, t_4) P \, d\mu + R_4(N + P, t_4, \theta),$$

that is,

$$P = -\frac{R_4(N+P, t_4, \theta)}{\int_0^1 \partial_{h_4} I(N+\mu P, t_4) \, d\mu}$$

Lemma 3.6. For r_4 large enough, it holds that

(3.25)
$$cr_4^2 \le |N| \le Cr_4^{2/(1-d)}, \quad cNr_4^{-k} \le |\partial_{r_4}^k N| \le CNr_4^{-k}, \qquad k = 1, 2,$$

(3.26) $|\partial_{r_4}^k N| \le CNr_4^{-k}, \qquad \qquad k \le 6,$

(3.27)
$$|\partial_{r_4}^k \partial_{\theta}^j P| \le Cr_4^{-k-1}N|R_4|, \qquad k+j \le 5.$$

Proof. By $r_4 \equiv I(N(r_4, t_4), t_4)$, one has

$$cr_4^2 \le |N| \le Cr_4^{2/(1-d)}, \quad \partial_{h_4}I \cdot \partial_{r_4}N = 1, \quad \partial_{h_4}I \cdot \partial_{t_4}N + \partial_{t_4}I = 0.$$

Then it follows that

$$\partial_{r_4} h_4 = \partial_{r_4} N = (\partial_{h_4} I)^{-1} \in [chr_4^{-1}, Chr_4^{-1}].$$

From (3.20) and (3.21), one has

(3.28)
$$cr_4^{-1}N \le |\partial_{r_4}N| \le Cr_4^{-1}N.$$

By direct computation, one has

$$\partial_{r_4}^2 N = -\frac{\partial_{h_4}^2 I \cdot \partial_{r_4} h_4}{(\partial_{h_4} I)^2} = -\frac{\partial_{h_4}^2 I \cdot \partial_{r_4} N}{(\partial_{h_4} I)^2}$$

From (3.20), (3.21) and (3.28), one has

$$cr_4^{-2}N \le |\partial_{r_4}^2 N| \le Cr_4^{-2}N.$$

Using Leibniz's rule, for $2 \le k \le 6$, $\partial_{r_4}^k N$ is the summation of terms

$$\partial_{h_4}^m \left(\frac{\partial_{h_4}^2 I}{(\partial_{h_4} I)^2} \right) \prod_{i=1}^m \partial_{r_4}^{k_i} N$$

with $0 \le m \le k$, $\sum_{i=1}^{m} k_i = k-1$, and $k_i \ge 1$, i = 1, 2, ..., m. By induction, we can obtain (3.26) from (3.20), (3.21) and (3.25).

By (3.24), one has

$$|P| \le Cr_4^{-1}N|R_4| \le C\partial_{r_4}N|R_4|$$

Differentiating both sides of (3.24) on r_4 , one has

$$\begin{aligned} |\partial_{r_4}P| &= \left| -\frac{\left(\partial_{h_4}R_4 + P\int_0^1 \partial_{h_4}^2 I(N+\mu P, t_4) \, d\mu\right) \cdot \partial_{r_4}N}{\int_0^1 \partial_{h_4}I(N+\mu P, t_4) \, d\mu + P\int_0^1 \partial_{h_4}^2 I(N+\mu P, t_4)\mu \, d\mu + \partial_{h_4}R_4} \right| \\ &\leq Cr_4^{-1}|R_4| \cdot |\partial_{r_4}N|. \end{aligned}$$

Differentiating both sides of (3.24) on θ , one has

$$\begin{aligned} |\partial_{\theta}P| &= \left| \frac{-\partial_{\theta}R_4}{\int_0^1 \partial_{h_4}I(N+\mu P, t_4) \, d\mu + P \int_0^1 \partial_{h_4}^2I(N+\mu P, t_4)\mu \, d\mu + \partial_{h_4}R_4} \right| \\ &\leq C|R_4| \cdot |\partial_{r_4}N|. \end{aligned}$$

Similar to the proof of (3.26), by induction, we can prove (3.27) for $2 \le k + j \le 5$ using Leibniz's rule.

4. Proof of Theorem 1.1

In this section, we will prove Theorem 1.1 by Moser's small twist theorem. Without leading to confusion, we denote (r_4, h_4, t_4) by (ρ, H, τ) in (3.23). The system with Hamiltonian (3.23) is

(4.1)
$$\frac{d\theta}{d\tau} = \partial_{\rho} N(\rho, \tau) + \partial_{\rho} P(\rho, \theta, \tau), \quad \frac{d\rho}{d\tau} = -\partial_{\theta} P(\rho, \theta, \tau).$$

Integrate the system (4.1) by τ from 0 to 2π , the Poincaré map P of system (4.1) is of the form

(4.2)
$$\theta_1 = \theta + \Lambda(\rho) + F_1(\rho, \theta), \quad \rho_1 = \rho + F_2(\rho, \theta)$$

with $(\rho, \theta) = (\rho(0), \theta(0))$, and

$$\begin{split} \Lambda(\rho) &= \int_0^{2\pi} \partial_\rho N(\rho, \tau) \, d\tau, \\ F_1(\rho, \theta) &= \int_0^{2\pi} \partial_\rho P(\rho(\tau), \theta(\tau), \tau) \, d\tau + \int_0^{2\pi} \partial_\rho N(\rho(\tau), \tau) \, d\tau - \int_0^{2\pi} \partial_\rho N(\rho, \tau) \, d\tau, \\ F_2(\rho, \theta) &= -\int_0^{2\pi} \partial_\theta P(\rho(\tau), \theta(\tau), \tau) \, d\tau. \end{split}$$

By Lemma 3.6, for $k + j \leq 4$, $F_1(\rho, \theta)$ and $F_2(\rho, \theta)$ satisfy the following estimates

$$\begin{aligned} |\partial_{\rho}^{k}\partial_{\theta}^{j}F_{1}(\rho,\theta)| &\leq C(N \cdot \rho^{-2} + 1) \cdot \rho^{-k-1}N \cdot |R_{4}|, \\ |\partial_{\rho}^{k}\partial_{\theta}^{j}F_{2}(\rho,\theta)| &\leq C\rho^{-k-1}N \cdot |R_{4}|. \end{aligned}$$

Moreover, the following estimates hold true for $\Lambda(\rho)$:

(4.3)
$$c\rho \leq |\Lambda(\rho)| \leq C\rho^{(1+d)/(1-d)}, \quad c \leq |\Lambda'(\rho)| \leq C\rho^{2d/(1-d)}, \\ |\Lambda^{(k)}(\rho)| \leq C\rho^{(1+d)/(1-d)-k}, \quad k \leq 5.$$

Denote by $\rho(\Lambda)$ the inverse function of $\Lambda(\rho)$. By (4.3), one has

(4.4)
$$c\Lambda^{(1+d)/(1-d)} \le \rho \le C\Lambda, \quad |\rho^{(k)}(\Lambda)| \le C\Lambda^{-k}|\rho|, \quad k \le 5.$$

The Poincaré map (4.2) can be rewritten in the following map

(4.5)
$$\theta_1 = \theta + \Lambda + \widehat{F}_1(\Lambda, \theta), \quad \Lambda_1 = \Lambda + \widehat{F}_2(\Lambda, \theta),$$

where

$$\widehat{F}_1(\Lambda,\theta) = F_1(\rho(r),\theta), \quad \widehat{F}_2(\Lambda,\theta) = \int_0^1 \Lambda'(\rho + \lambda F_2(\rho,\theta)) F_2(\rho,\theta) \, d\lambda.$$

By Leibniz's rule, (3.22) and (4.4), one has

(4.6)
$$\begin{aligned} |\partial_{\Lambda}^{k}\partial_{\theta}^{j}\widehat{F}_{1}| &\leq \sum_{i=1}^{k} |\partial_{\rho}^{i}\partial_{\theta}^{j}F_{1}| \cdot |\rho^{(k_{1})}(r) \cdots \rho^{(k_{i})}(r)| \\ &\leq CN^{2} \cdot \rho^{-i-3}|R_{4}| \cdot \rho^{i} \cdot \Lambda^{-k} \\ &\leq C\rho^{-3} \cdot \Lambda^{-k} \cdot |R_{4}| \cdot N^{2} \\ &\leq C\rho^{-3}, \quad k+j \leq 4 \end{aligned}$$

with $\sum_{l=1}^{i} k_l = k$. Similarly, one has

(4.7)
$$|\partial_{\Lambda}^{k}\partial_{\theta}^{j}\widehat{F}_{2}| \leq C\rho^{-3}, \quad k+j \leq 4$$

By (3.5), we have the estimate

$$|\partial_{h_4}^k \partial_{\theta}^j \partial_{t_4}^l R| \le C h_4^{-\upsilon/2-k}, \quad k \le 5, \ k+j \le 5, \ l \le 4.$$

Since $N = h_4$, thus for $j \le 5$, $k + j \le 4$, (4.6) and (4.7) yield that

$$|\partial^k_\Lambda \partial^j_\theta \widehat{F}_i| \le C \rho^{-3}, \quad i = 1, 2.$$

Proof of Theorem 1.1. The map (4.5) satisfies all the conditions of Moser's small twist theorem [10]. Thus we obtain the boundedness result of Theorem 1.1.

Acknowledgments

This work was supported by the NSFC (grant no. 11801295). The authors are grateful to the referees for their valuable suggestions and comments.

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