## Research Article

# Estimates of Invariant Metrics on Pseudoconvex Domains of Finite Type in $\mathbb{C}^{3}$ 

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Let $\Omega$ be a smoothly bounded pseudoconvex domain in $\mathbb{C}^{3}$ and assume that $z_{0} \in b \Omega$ is a point of finite 1-type in the sense of D'Angelo. Then, there are an admissible curve $\Gamma \subset \Omega \cup\left\{z_{0}\right\}$, connecting points $q_{0} \in \Omega$ and $z_{0} \in b \Omega$, and a quantity $M(z, X)$, along $z \in \Gamma$, which bounds from above and below the Bergman, Caratheodory, and Kobayashi metrics in a small constant and large constant sense.

## 1. Introduction

Let $\Omega$ be a smoothly bounded domain in $\mathbb{C}^{n}$ and let $X$ be a holomorphic tangent vector at a point $z$ in $\Omega$, and let us denote the Bergman, Caratheodory, and Kobayashi metrics at $z$ by $B_{\Omega}(z ; X), C_{\Omega}(z ; X)$, and $K_{\Omega}(z ; X)$, respectively. When $\Omega$ is a strongly pseudoconvex domain in $\mathbb{C}^{n}$, the optimal boundary behavior of the above metrics is well understood. For weakly pseudoconvex domains of finite type in $\mathbb{C}^{n}$, several authors found some results about these metrics. But in each case, the lower bounds are different from the upper bounds [1-5]. In [6], Catlin got optimal estimates in a small constant and large constant sense for pseudoconvex domains of finite type in $\mathbb{C}^{2}$. For pseudoconvex domains of finite type in $\mathbb{C}^{n}$, the first author and Herbort extended Catlin's result to the case that the Levi-form at $z_{0}$ has corank one $[7,8]$ or homogeneous finite diagonal type near $z_{0} \in b \Omega[9,10]$.

To estimate the above invariant metrics, we need a complete geometric analysis near $z_{0} \in b \Omega$ of finite type, and then we construct a family of plurisubharmonic functions with maximal Hessian near $b \Omega$. However, this construction is really technical and known only for special types of domains mentioned above, but not for arbitrary pseudoconvex domains of finite type in $\mathbb{C}^{n}$, even for $n=3$ case. Meanwhile, it is useful to understand the behavior of a holomorphic
function near $z_{0} \in b \Omega$ if we have precise estimates of the invariant metric along some curves.

In the sequel, we let $\Omega$ be a smoothly bounded pseudoconvex domain in $\mathbb{C}^{3}$ with smooth defining function $r$ and let $z_{0} \in b \Omega$. Let $\mathscr{M}\left(z_{0}\right)=\left(1, m, m_{3}\right)$ be Catlin's multitype [11]. Thus, $m=T_{\mathrm{BG}}\left(z_{0}\right)$ is the type in the sense of "BloomGraham." If $m_{3}=\Delta_{1}\left(z_{0}\right)$, then $\Omega$ is an $h$-extensible domain [12] and Herbort [10] got an estimate in this case. Here, $\Delta_{q}\left(z_{0}\right)$ denotes finite $q$-type in the sense of D'Angelo. Thus, we assume that $m \leq m_{3}<\Delta_{1}\left(z_{0}\right)$. Regular finite 1-type at $z_{0} \in b \Omega$ is the maximum order of vanishing of $r \circ \gamma$ for all one complex dimensional regular curves $\gamma, \gamma(0)=z_{0}$ and $\gamma^{\prime}(0) \neq 0$. We denote the regular finite 1-type at $z_{0}$ by $T_{\Omega}^{\mathrm{reg}}\left(z_{0}\right)$. Note that $T_{\Omega}^{\mathrm{reg}}\left(z_{0}\right)$ is a positive integer and $T_{\Omega}^{\mathrm{reg}}\left(z_{0}\right) \leq \Delta_{1}\left(z_{0}\right)$.

Assuming that $T_{\Omega}^{\mathrm{reg}}\left(z_{0}\right)=\eta<\infty$, there exist coordinate functions $z=\left(z_{1}, z_{2}, z_{3}\right)$ defined in a neighborhood $V$ of $z_{0}$ such that $z_{0}=0$ and $\left|\partial r / \partial z_{3}\right| \geq c_{0}$ on $V$ for a uniform constant $c_{0}>0$, and $\left|r\left(z_{1}, 0,0\right)\right|$ vanishes to order $\eta$, and $\left(\partial r / \partial z_{2}\right)(0)=$ 0 (Theorem 2.1 in [13]). With these coordinates at hand, set

$$
\begin{align*}
L_{k} & =\frac{\partial}{\partial z_{k}}-\left(\frac{\partial r}{\partial z_{3}}\right)^{-1} \frac{\partial r}{\partial z_{k}} \frac{\partial}{\partial z_{3}}:=\frac{\partial}{\partial z_{k}}+e_{k}(z) \frac{\partial}{\partial z_{3}} \\
k & =1,2  \tag{1}\\
L_{3} & =\frac{\partial}{\partial z_{3}}
\end{align*}
$$

Then, $e_{k}(0)=0, k=1,2$, and $\left\{L_{1}, L_{2}, L_{3}\right\}$ form a basis of $\mathbb{C} T^{(1,0)}(V)$ provided $V$ is sufficiently small. For any integer $j$, $k>0$, set

$$
\begin{equation*}
\mathscr{L}_{j, k} \partial \bar{\partial} r(z)=\underbrace{L_{2} \cdots L_{2}}_{(j-1) \text { times }} \underbrace{\bar{L}_{2} \cdots \bar{L}_{2}}_{(k-1) \text { times }} \partial \bar{\partial} r(z)\left(L_{2}, \bar{L}_{2}\right)(z) \tag{2}
\end{equation*}
$$

and define

$$
\begin{equation*}
C_{l}(z)=\max \left\{\left|\mathscr{L}_{j, k} \partial \bar{\partial} r(z)\right|: j+k=l\right\} \tag{3}
\end{equation*}
$$

Let $X=a_{1} L_{1}+a_{2} L_{2}+a_{3} L_{3}$ be a holomorphic tangent vector at $z \in \Omega$ and set

$$
\begin{align*}
M(z ; X)= & \left|a_{1}\right||r(z)|^{-1 / \eta}+\left|a_{2}\right| \sum_{l=2}^{m}\left(\frac{C_{l}(z)}{|r(z)|}\right)^{1 / l}  \tag{4}\\
& +\left|a_{3}\right||r(z)|^{-1}
\end{align*}
$$

Let $\Gamma \subset \Omega \cup\left\{z_{0}\right\}$ be the admissible curve defined in (20). Our main result is as follows.

Theorem 1. Let $\Omega \subset \subset \mathbb{C}^{3}$ be a smoothly bounded pseudocon$v e x$ domain and assume $z_{0} \in b \Omega$ is a point of finite 1-type in the sense of D'Angelo; that is, $\Delta_{1}\left(z_{0}\right)<\infty$. Then, there exist a neighborhood $V$ about $z_{0}$, an admissible curve $\Gamma \subset \Omega \cup\left\{z_{0}\right\}$ connecting $q_{0} \in \Omega$ and $z_{0}$, and positive constants $c$ and $C$ such that, for all $X=a_{1} L_{1}+a_{2} L_{2}+a_{3} L_{3}$ at $z \in V \cap \Gamma \cap \Omega$,

$$
\begin{align*}
& c M(z ; X) \leq B_{\Omega}(z ; X) \leq C M(z ; X) \\
& c M(z ; X) \leq C_{\Omega}(z ; X) \leq C M(z ; X)  \tag{5}\\
& c M(z ; X) \leq K_{\Omega}(z ; X) \leq C M(z ; X)
\end{align*}
$$

To prove Theorem 1, we use special coordinates constructed in Section 2 of [13]. Thus, there is a special direction $d,|d|=1$, so that, for each $\delta>0$, the two-dimensional slice $D_{\delta}:=\left\{\left(z_{2}, z_{3}\right) ; r\left(d \delta^{1 / \eta}, z_{2}, z_{3}\right)<0\right\}$ becomes a pseudoconvex domain of finite type in $\mathbb{C}^{2}$, whose type is less than or equal to $m=T_{\mathrm{BG}}\left(z_{0}\right)$. We then apply the method which holds for the domains of finite type in $\mathbb{C}^{2}$ as in [6]. To avoid the difficulty to push out the domain in $z_{1}$-direction, we use a bumping theorem of Cho [14].

## 2. Special Coordinates

Let $\Omega \subset \mathbb{C}^{3}$ and $z_{0} \in b \Omega$ be as in Section 1 . We may assume that $z_{0}=0$. In this section, we consider special coordinates defined near $z_{0} \in b \Omega$ and then construct "balls" which are of maximal size on which $r(z)$ changes by no more than some prescribed number $\delta>0$. In the following, we let $\alpha=\left(\alpha_{1}, \alpha_{2}\right)$ and $\beta=\left(\beta_{1}, \beta_{2}\right)$ be multi-indices with respect to $z^{\prime}=\left(z_{1}, z_{2}\right)$ variables. In Theorem 2.1 of [13], You constructed special coordinates which represent the local geometry of $b \Omega$ near $z_{0}$.

Theorem 2. Let $\Omega$ be a smoothly bounded pseudoconvex domain in $\mathbb{C}^{3}$ with smooth defining function $r$ and assume
$T_{\Omega}^{r e g}(0)=\eta<\infty, 0 \in b \Omega$. Then, there is a holomorphic coordinate system $z=\left(z_{1}, z_{2}, z_{3}\right)$ about 0 such that
(1) $r(z)=\operatorname{Re} z_{3}+\sum_{\substack{|\alpha|+|\beta|=m \\|\alpha|,|\beta|>0}}^{\eta} a_{\alpha, \beta} z^{\prime \alpha} \bar{z}^{\prime \beta}$

$$
+\mathcal{O}\left(\left|z_{3}\right||z|+\left|z^{\prime}\right|^{\eta+1}\right)
$$

(2) $|r(t, 0,0)| \leqslant|t|^{\eta}$,
where $z^{\prime}=\left(z_{1}, z_{2}\right)$ and where
$a_{\alpha, \beta} \neq 0$ forsome $\alpha, \beta$ with $\alpha_{1}=\beta_{1}=0, \alpha_{2}+\beta_{2}=m$.

Remark 3. (1) The second condition in (6) and the property (7) say that $r(z)$ vanishes to order $\eta$ along $z_{1}$ axis and order $m$ along $z_{2}$ axis. These properties are crucial for the construction of maximal polydiscs $Q_{c \delta}\left(z^{\delta}\right)$ contained in $\Omega$.
(2) There are much more terms (mixed with $z_{1}$ and $z_{2}$ and their conjugates) in the summation part of (6) compared to the $h$-extensible domain cases.

According to Proposition 2.6 and Remark 2.7 of [13], there are pairs of integers $\left(p_{v}, q_{\nu}\right), \nu=1, \ldots, N$, such that the terms satisfying $\alpha_{1}+\beta_{1}=p_{v}$ and $\alpha_{2}+\beta_{2}=q_{v}$ with $\alpha_{2}>0$ and $\beta_{2}>0$ are dominant terms in the summation part of (6). Also, there is a small constant $a_{0}>0$ and a fixed direction $d$, $|d|=1$, in $z_{1}$ direction, such that, for each fixed $\delta>0$ and for all $z_{1}$ satisfying $\left|z_{1}-d \delta^{1 / \eta}\right|<a_{0} \delta^{1 / \eta}$, those major terms in the summation part of (6) satisfy

$$
\begin{equation*}
\left|\frac{\partial^{q_{v}}}{\partial z_{2}^{\alpha_{2}} \bar{\partial} \bar{z}_{2}^{\beta_{2}}} r\left(z_{1}, 0,0\right)\right| \approx\left|z_{1}\right|^{p_{v}} \approx \delta^{p_{v} / \eta} \tag{8}
\end{equation*}
$$

where $\alpha_{2}+\beta_{2}=q_{v}$ and where $\alpha_{2}>0$ and $\beta_{2}>0$.
Now, let us fix $z_{1}$ with $\left|z_{1}-d \delta^{1 / \eta}\right|<a_{0} \delta^{1 / \eta}$ and consider the two-dimensional slice $D_{z_{1}}:=\left\{\left(z_{2}, z_{3}\right): r\left(z_{1}, z_{2}, z_{3}\right)<0\right\}$. For each $z=\left(z_{1}, 0, z_{3}\right)$ near $b \Omega$, set $\pi(z)=\left(z_{1}, 0, e_{\delta}\right):=$ $\widetilde{z}_{1} \in b \Omega$, where $\pi(z)$ is the projection of $z$ onto $b \Omega$ along $z_{3}$ direction. On $D_{z_{1}}$, following the argument in twodimensional case as in the proof of Proposition 1.1 in [6], we construct special coordinates $\zeta=\left(\zeta_{1}, \zeta_{2}, \zeta_{3}\right)=\left(z_{1}, z_{2}, \zeta_{3}\right)$ about $\widetilde{z}_{1}$ so that, in terms of new coordinates, there are no pure terms in $z_{2}$ variable in the expression of $r(z)$ in (6).

Proposition 4. For each fixed $\widetilde{z}_{1}=\left(z_{1}, 0, e_{\delta}\right) \in V \cap b \Omega$, there exists a holomorphic coordinate system $z=\Phi_{\tilde{z}_{1}}(\zeta)=$ $\left(z_{1}, z_{2}, \Phi_{3}(\zeta)\right), \zeta=\left(\zeta_{1}, \zeta_{2}, \zeta_{3}\right)=\left(z_{1}, z_{2}, \zeta_{3}\right)$, where $\Phi_{3}(\zeta)$ is defined by

$$
\begin{align*}
\Phi_{3}(\zeta)= & e_{\delta}+\left(\frac{\partial r}{\partial z_{3}}\left(\widetilde{z}_{1}\right)\right)^{-1} \\
& \times\left(\frac{\zeta_{3}}{2}-\sum_{l=2}^{m} c_{l}\left(\widetilde{z}_{1}\right) \zeta_{2}^{l}-\frac{\partial r}{\partial z_{2}}\left(\widetilde{z}_{1}\right) \zeta_{2}\right)  \tag{9}\\
:= & e_{\delta}+d_{0}\left(\widetilde{z}_{1}\right) \zeta_{3}+\sum_{l=1}^{m} d_{l}\left(\widetilde{z}_{1}\right) \zeta_{2}^{l}
\end{align*}
$$

and the function $\rho$, given by $\rho\left(z_{1}, \zeta^{\prime \prime}\right):=r \circ \Phi_{\tilde{z}_{1}}\left(z_{1}, \zeta^{\prime \prime}\right), \zeta^{\prime \prime}=$ $\left(\zeta_{2}, \zeta_{3}\right)$, satisfies

$$
\begin{equation*}
\rho\left(z_{1}, \zeta^{\prime \prime}\right)=\operatorname{Re}\left(\Phi_{3}(\zeta)\right)+\sum_{\substack{j+k=2 \\ j, k>0}}^{m} a_{j, k}\left(\tilde{z}_{1}\right) \zeta_{2}^{j} \zeta_{2}^{k}+E(\zeta), \tag{10}
\end{equation*}
$$

where

$$
\begin{equation*}
E(\zeta)=\mathcal{O}\left(\left|\Phi_{3}(\zeta)\right||\zeta|+\sum_{v=1}^{N}\left|z_{1}\right|^{1+p_{v}}\left|\zeta_{2}\right|^{q_{v}}+\left|\zeta_{2}\right|^{m+1}\right) \tag{11}
\end{equation*}
$$

In view of (6) and (8), the major terms in (10) are $a_{j, k}\left(\widetilde{z}_{1}\right) \zeta_{2}^{j} \zeta_{2}^{k}$ where $j+k=\alpha_{2}+\beta_{2}=q_{v}$ for some $\alpha_{2}$ and $\beta_{2}$ with $\alpha_{2}>0$ and $\beta_{2}>0$. Also, from (8), it follows that

$$
\begin{equation*}
\left|a_{j, k}\left(\widetilde{z}_{1}\right) \zeta_{2}^{j} \bar{\zeta}_{2}^{k}\right| \approx\left|z_{1}\right|^{p_{v}}\left|z_{2}\right|^{q_{v}} \tag{12}
\end{equation*}
$$

and these terms control the error terms $\left|z_{1}\right|^{1+p_{v}}\left|\zeta_{2}\right|^{q_{v}}$ in $E(\zeta)$. As in Section 1 in [6], set

$$
\begin{equation*}
A_{l}\left(\widetilde{z}_{1}\right)=\max \left\{\left|a_{j, k}\left(\widetilde{z}_{1}\right)\right| ; j+k=l\right\}, \quad l=2, \ldots, m \tag{13}
\end{equation*}
$$

and for each sufficiently small $\delta>0$, we set

$$
\begin{equation*}
\tau\left(\widetilde{z}_{1}, \delta\right)=\min \left\{\left(\frac{\delta}{A_{l}\left(\widetilde{z}_{1}\right)}\right)^{1 / l} ; 2 \leq l \leq m\right\} \tag{14}
\end{equation*}
$$

Thus, for all $z_{1}$ with $\left|z_{1}-d \delta^{1 / \eta}\right|<a_{0} \delta^{1 / \eta}$, it follows from (8) and (14) that

$$
\begin{equation*}
\tau\left(\widetilde{z}_{1}, \delta\right) \lesssim\left(\frac{\delta}{\left|z_{1}\right|^{p_{v}}}\right)^{1 / q_{v}}, \quad v=1, \ldots, N \tag{15}
\end{equation*}
$$

and hence the summation part of (10) is dominated by $C \delta$.
For each $\widetilde{z}=\left(z_{1}, 0, z_{3}\right)$ near $b \Omega$, set $\widetilde{\zeta}=\Phi_{\widetilde{z}_{1}}^{-1}(\widetilde{z})=$ $\left(z_{1}, 0, \widetilde{\zeta}_{3}\right)$, where $\Phi_{\tilde{z}_{1}}$ is the function defined in Proposition 4. For each small $e>0$, set

$$
\begin{align*}
& R_{e \delta}(\widetilde{\zeta})=\left\{\zeta:\left|\zeta_{1}-z_{1}\right|<e \delta^{1 / \eta},\left|\zeta_{2}\right|<e \tau\left(\widetilde{z}_{1}, \delta\right)\right. \\
&\left.\left|\zeta_{3}-\widetilde{\zeta}_{3}\right|<e \delta\right\}  \tag{16}\\
& Q_{e \delta}(\widetilde{z})=\left\{z: z=\Phi_{\tilde{z}_{1}}(\zeta), \zeta \in R_{e \delta}(\widetilde{\zeta})\right\}
\end{align*}
$$

For each $\sigma>0$, let $\Omega_{\sigma}=\{z ; r(z)<\sigma\}$ and define

$$
\begin{align*}
S(\sigma) & =\{z \in V:-\sigma<r(z) \leq \sigma\}  \tag{17}\\
S^{-}(\sigma) & =\{z \in V:-\sigma<r(z) \leq 0\}
\end{align*}
$$

and set $\widetilde{z}^{\delta}=\left(d \delta^{1 / \eta}, 0, e_{\delta}\right) \in b \Omega$, where $z_{1}$ is replaced by $d \delta^{1 / \eta}$ in $\widetilde{z}_{1}=\left(z_{1}, 0, e_{\delta}\right)$. The following theorem is about the existence of plurisubharmonic function with maximal Hessian. In [6], for the domains in $\mathbb{C}^{2}$, Catlin constructed the functions with maximal Hessian on the strip $S(\delta) \cap V$. However, for regular finite type pseudoconvex domains in $\mathbb{C}^{3}$, we show that the functions have maximal Hessian on each ball $Q_{b \delta}\left(\widetilde{z}^{\delta}\right)$ and this will suffice to prove the boundary behavior of the invariant metrics. The proof of the following theorem can be found in Theorem 3.2 in [9].

Theorem 5. There is a small constant $b>0$ such that, for each small $\delta>0$, there is a plurisubharmonic function $g_{\delta} \in$ $C_{0}^{\infty}\left(Q_{2 b \delta}\left(\widetilde{z}^{\delta}\right)\right)$ with the following properties:
(i) $\left|g_{\delta}(\zeta)\right| \leq 1, z \in \Omega_{\delta}$,
(ii) for all $L=b_{1} L_{1}+b_{2} L_{2}+b_{3} L_{3}$ at $z$, where $z \in Q_{b \delta}\left(\widetilde{z}^{\delta}\right) \cap$ $S(b \delta)$,

$$
\begin{equation*}
\partial \bar{\partial} g_{\delta}(L, \bar{L})(z) \gtrsim \delta^{-2 / \eta}\left|b_{1}\right|^{2}+\tau\left(\widetilde{z}^{\delta}, \delta\right)^{-2}\left|b_{2}\right|^{2}+\delta^{-2}\left|b_{3}\right|^{2} \tag{18}
\end{equation*}
$$

(iii) if $\Phi(\zeta)=\left(\zeta_{1}, \zeta_{2}, \Phi_{3}(\zeta)\right)$, where $\Phi_{3}$ is defined in (10) for $\widetilde{z}^{\delta}$, then

$$
\begin{equation*}
\left|\widetilde{D}^{\alpha} g_{\delta} \circ \Phi(\zeta)\right| \leq C_{\alpha} \delta^{-\alpha_{1} / \eta} \tau\left(\widetilde{z}^{\delta}, \delta\right)^{-\alpha_{2}} \delta^{-\alpha_{3}} \tag{19}
\end{equation*}
$$

holds for all $\zeta \in R_{2 b \delta}\left(\widetilde{z}^{\delta}\right)$, where $\widetilde{D}^{\alpha}=\widetilde{D}_{1}^{\alpha_{1}} \widetilde{D}_{2}^{\alpha_{2}} \widetilde{D}_{3}^{\alpha_{3}}$.
Let $\Gamma \subset \Omega$ be a curve defined by

$$
\begin{equation*}
\Gamma:=\left\{z^{\delta}: z^{\delta}=\left(d \delta^{1 / \eta}, 0, e_{\delta}-\frac{b \delta}{2}\right), 0 \leq \delta \leq \delta_{0}\right\} \tag{20}
\end{equation*}
$$

for sufficiently small $\delta_{0}>0$ and $b>0$. In the sequel, for each $z^{\delta}=\left(d \delta^{1 / \eta}, 0, e_{\delta}-b \delta / 2\right) \in \Gamma$, set $\zeta^{\delta}:=\Phi_{\tilde{z}^{\delta}}^{-1}\left(z^{\delta}\right)$ and set $\widetilde{\Omega}=$ $\Phi_{\tilde{z}^{\delta}}^{-1}(\Omega)$. In view of Proposition 3.4 in [9], there is a uniform small constant $c>0$ such that $R_{c \delta}\left(\zeta^{\delta}\right) \subset \subset R_{b \delta}\left(\widetilde{z}^{\delta}\right) \cap \widetilde{\Omega}$, and hence

$$
\begin{equation*}
Q_{c \delta}\left(z^{\delta}\right)=\left\{z: z=\Phi_{\widetilde{z}^{\delta}}(\zeta), \zeta \in R_{c \delta}\left(\zeta^{\delta}\right)\right\} \subset \subset Q_{b \delta}\left(\widetilde{z}^{\delta}\right) \cap \Omega, \tag{21}
\end{equation*}
$$

provided $c>0$ and $\delta_{0}>0$ are sufficiently small. In particular, we have $\Gamma \subset \Omega \cup\left\{z_{0}\right\}$. Note that $\tau\left(z^{\delta}, \delta\right) \approx \tau\left(\widetilde{z}^{\delta}, \delta\right)$, and for $z \in$ $\mathrm{Q}_{c \delta}\left(z^{\delta}\right) \subset \Omega$, we note that $|r(z)| \approx \delta$. Thus, as in Proposition 1.3 and Corollary 1.4 in [6], we obtain that

$$
\begin{equation*}
\tau\left(z^{\delta}, \delta\right)^{-1} \approx \sum_{k=2}^{m}\left(\frac{C_{k}(z)}{|r(z)|}\right)^{1 / k}, \quad z \in Q_{c \delta}\left(z^{\delta}\right) \tag{22}
\end{equation*}
$$

where $C_{k}(z)$ is defined in (3). In the sequel, we set $\tau_{1}=\delta^{1 / \eta}$, $\tau_{2}=\tau\left(\widetilde{z}^{\delta}, \delta\right)$, and $\tau_{3}=\delta$. If we use the plurisubharmonic weight functions constructed in Theorem 5 and follow the method to prove Theorem 6.1 in [6], we get the following estimates of the Bergman kernel along $\Gamma$.

Theorem 6. Let $z_{0} \in b \Omega$ be a point of regular finite 1-type and $T_{\Omega}^{r e g}\left(z_{0}\right)=\eta$. Then, $K_{\Omega}\left(z^{\delta}, z^{\delta}\right)$, the Bergman kernel function of $\Omega$ at $z^{\delta} \in \Gamma, \delta>0$, satisfies

$$
\begin{equation*}
K_{\Omega}\left(z^{\delta}, z^{\delta}\right) \approx \delta^{-2} \tau_{1}^{-2} \tau_{2}^{-2} \tag{23}
\end{equation*}
$$

## 3. Metric Estimates

In this section, we estimate the behavior of the invariant metric along $\Gamma$. In [15], Hahn got the following inequalities:

$$
\begin{equation*}
C_{\Omega}(z ; X) \leq B_{\Omega}(z ; X), \quad C_{\Omega}(z ; X) \leq K_{\Omega}(z ; X) \tag{24}
\end{equation*}
$$

Therefore, the estimates for the lower bounds of $C_{\Omega}(z ; X)$ will suffice for the lower bounds of $B_{\Omega}(z ; X)$ and $K_{\Omega}(z ; X)$. First, we recall the following bumping theorem [14].

Theorem 7 (Theorem 2.3 in [14]). Let $z_{0}$ be a point of finite 1-type in the boundary of a pseudoconvex domain $\Omega \subset \mathbb{C}^{n}$, defined by $\Omega=\{z: r(z)<0\}$. Then, there exist $V \ni z_{0}$ and $a$ smooth 1-parameter family of pseudoconvex domains $\Omega_{t}, 0 \leq$ $t<t_{0}$, each defined by $\Omega_{t}=\{z ; r(z, t)<0\}$, where $r(z, t)$ has the following properties:
(1) $r(z, t)$ is smooth in $z$ for $z$ near $b \Omega$ and in $t$ for $0 \leq t<$ $t_{0}$;
(2) $r(z, t)=r(z)$, for $z \notin V$;
(3) $(\partial r / \partial t)(z, t) \leq 0$;
(4) $r(z, 0)=r(z)$;
(5) for $z$ in $V, \partial r / \partial t<0$.

Proof of Theorem 1. In the sequel, let us fix $\delta>0$ and, for each $z^{\delta} \in \Gamma$, set $\pi\left(z^{\delta}\right)=\widetilde{z}^{\delta}=\left(d \delta^{1 / \eta}, 0, e_{\delta}\right) \in b \Omega$ and consider the special coordinates $\zeta=\left(z_{1}, z_{2}, \zeta_{3}\right)$ and $\Phi_{z^{\delta}}(\zeta)=$ $\left(z_{1}, z_{2}, \Phi_{3}(\zeta)\right)=z$, where $\Phi_{3}$ is defined in Proposition 4. From (9), we see that $\zeta^{\delta}=\left(d \delta^{1 / \eta}, 0,-b \delta / 2 d_{0}\left(\widetilde{z}^{\delta}\right)\right):=$ $\left(\widetilde{\zeta}_{1}, \widetilde{\zeta}_{2}, \widetilde{\zeta}_{3}\right)$. We will estimate the metrics at $\zeta^{\delta}$. For all small $\delta>0$ and for each $\zeta^{\prime \prime}=\left(\zeta_{2}, \zeta_{3}\right)$, define

$$
\begin{equation*}
J_{\delta}\left(\zeta^{\prime \prime}\right)=\left(\delta^{2}+\left|\zeta_{3}\right|^{2}+\sum_{k=2}^{m}\left(A_{k}\left(\widetilde{z}^{\delta}\right)\right)^{2}\left|\zeta_{2}\right|^{2 k}\right)^{1 / 2} \tag{25}
\end{equation*}
$$

where $A_{k}\left(\widetilde{z}^{\delta}\right)$ is defined in (13) with $\widetilde{z}_{1}$ replaced by $\widetilde{z}^{\delta}$. Let $c>0$ be the fixed constant determined in (21). Note that $\Phi_{\tilde{z}^{\delta}}\left(d \delta^{1 / \eta}, 0,0\right)=\widetilde{z}^{\delta}$. Set

$$
\begin{align*}
\widetilde{\Omega}_{a, \delta}= & \left\{\zeta ;\left|\zeta_{1}-d \delta^{1 / \eta}\right|<c \delta^{1 / \eta},\left|\zeta_{2}\right|<a,\left|\zeta_{3}\right|<a\right.  \tag{26}\\
& \left.\rho\left(\zeta_{1}, \zeta_{2}, \zeta_{3}\right)<0\right\}
\end{align*}
$$

and, for each $\epsilon>0$, define

$$
\begin{gather*}
\widetilde{\Omega}_{a, \delta}^{\epsilon}=\left\{\zeta ;\left|\zeta_{1}-d \delta^{1 / \eta}\right|<c \delta^{1 / \eta},\left|\zeta_{2}\right|<a,\left|\zeta_{3}\right|<a,\right. \\
\left.\rho\left(d \delta^{1 / \eta}, \zeta^{\prime \prime}\right)<\epsilon J_{\delta}\left(\zeta^{\prime \prime}\right)\right\}, \tag{27}
\end{gather*}
$$

and for all small $e>0$ set $B_{e}=R_{e \delta}\left(\zeta^{\delta}\right)$. By (21), we see that $\zeta^{\delta} \in B_{e} \subset \widetilde{\Omega}$ for all $e \leq c$. Note that the domains $\widetilde{\Omega}_{a, \delta}^{\epsilon}$ are pushed out only in $\zeta_{2}$ and $\zeta_{3}$ directions but not in $\zeta_{1}$ direction. To avoid the difficulty to push out $\widetilde{\Omega}$ in $\zeta_{1}$ direction, we use a bumping family of Theorem 7. Consider a bumping family of pseudoconvex domains $\left\{\Omega_{t}\right\}_{0 \leq t \leq t_{0}}$ with front $V$ and set $D=$ $\Omega_{t_{0}}$. For each $r>0$, let $U_{r}(z)$ be a ball of radius $r>0$ with center at $z$ and set $\widetilde{U}_{r}(\zeta)=\Phi_{\widetilde{z}^{\delta}}^{-1}\left(U_{r}\left(\Phi_{\widetilde{z}^{\delta}}(\zeta)\right)\right)$. Then, there is $r_{0}>0$ such that

$$
\begin{equation*}
Q_{c \delta}\left(z^{\delta}\right) \subset \Omega_{a, \delta}^{\epsilon}=\Phi_{\widetilde{z}^{\delta}}\left(\widetilde{\Omega}_{a, \delta}^{\epsilon}\right) \subset U_{r_{0} / 4}(0) \subset U_{r_{0}}(0) \subset \subset D \tag{28}
\end{equation*}
$$

for all sufficiently small $a>0, \epsilon>0$, and $\delta>0$.

In view of the proof in Section 3 of [13], we have $\widetilde{\Omega}_{a, \delta} \subset$ $\widetilde{\Omega}_{a, \delta}^{\epsilon / 2} \subset \widetilde{\Omega}_{a, \delta}^{\epsilon}$ and there is a uniformly (independent of $\delta>$ 0) bounded function $\widetilde{f}=\tilde{f}\left(\zeta_{2}, \zeta_{3}\right)$ which is holomorphic on $\widetilde{\Omega}_{a, \delta}^{\epsilon}$ and satisfies

$$
\begin{equation*}
\left|Y^{\prime \prime} \tilde{f}\left(\zeta^{\delta}\right)\right| \gtrsim\left|b_{2}\right| \tau_{2}^{-1}+\left|b_{3}\right| \tau_{3}^{-1} \tag{29}
\end{equation*}
$$

where $Y^{\prime \prime}=b_{2}\left(\partial / \partial \zeta_{2}\right)+b_{3}\left(\partial / \partial \zeta_{3}\right)$. Here, we may assume that $\widetilde{f}\left(0,-b \delta / d_{0}\left(\widetilde{z}^{\delta}\right)\right)=0$. In the sequel, we let $Y$ be a vector field given by $Y=b_{1}\left(\partial / \partial \zeta_{1}\right)+b_{2}\left(\partial / \partial \zeta_{2}\right)+b_{3}\left(\partial / \partial \zeta_{3}\right)$. If $\left|b_{1}\right| \tau_{1}^{-1} \geq$ $\left|b_{2}\right| \tau_{2}^{-1}+\left|b_{3}\right| \tau_{3}^{-1}$, then set $v_{\delta}=\tau_{1}^{-1}\left(\zeta_{1}-d \delta^{1 / \eta}\right)$. Otherwise, set $v_{\delta}=\tilde{f}\left(\zeta_{2}, \zeta_{3}\right)$. From (29), we note that

$$
\begin{equation*}
\left|Y v_{\delta}\left(\zeta^{\delta}\right)\right| \gtrsim \sum_{i=1}^{3}\left|b_{i}\right| \tau_{i}^{-1} \tag{30}
\end{equation*}
$$

Let $\psi \in C_{0}^{\infty}(U)$, where $U$ is the unit polydisc in $\mathbb{C}^{3}$, such that $\psi(z)=1$ if $\left|z_{i}\right| \leq 1 / 2, i=1,2,3$, and set

$$
\begin{equation*}
\psi_{d}(\zeta)=\psi\left(\frac{\zeta_{1}-\tilde{\zeta}_{1}}{d \tau_{1}}, \frac{\zeta_{2}}{d \tau_{2}}, \frac{\zeta_{3}-\tilde{\zeta}_{3}}{d \tau_{3}}\right) \tag{31}
\end{equation*}
$$

and set $\beta_{\delta}=v_{\delta} \psi_{d}$. Then, $\beta_{\delta}\left(\zeta^{\delta}\right)=0$. Since $\tilde{f}$ is bounded independent of $\delta$ (and hence independent of $\zeta^{\delta}$ ), there exists a constant $C>0$, independent of $\delta$, such that $\left|\beta_{\delta}\right| \leq C$. We want to correct $\beta_{\delta}$ so that the corrected function $f_{\delta}$ becomes a uniformly bounded holomorphic function on $\widetilde{\Omega}$ satisfying the estimate (30) with $\beta_{\delta}$ replaced by $f_{\delta}$. With bumped domain $D=\Omega_{t_{0}}$ at hand, set $\widetilde{D}=\Phi_{\widetilde{z}^{\delta}}^{-1}(D)$. On $\widetilde{D}$, instead of $\widetilde{\Omega}$, we will employ weighted estimates of $\bar{\partial}$ that is essentially a replication of the proof of Theorem 6.1 in [6].

Let $g_{\delta}$ be the weight function defined in Theorem 5 and set $\widetilde{g}_{\delta}=\Phi_{\tilde{z}^{\delta}}^{*} g_{\delta}$. By replacing $\widetilde{g}_{\delta}$ by $\widetilde{g}_{\delta}+|\zeta|^{2}:=\phi$, we can obviously assume that $\phi$ is strictly plurisubharmonic on $\widetilde{D}$ and $\phi\left(\zeta^{\delta}\right)=0$. In view of Theorem 5, we also have

$$
\begin{align*}
\partial \bar{\partial} \phi(Y, \bar{Y})(\zeta) \gtrsim \tau_{1}^{-2}\left|b_{1}\right|^{2}+\tau_{2}^{-2}\left|b_{2}\right|^{2} & +\tau_{3}^{-2}\left|b_{3}\right|^{2}  \tag{32}\\
\zeta & \in R_{c \delta}\left(\zeta^{\delta}\right) .
\end{align*}
$$

From property (iii) in Theorem 5, there is a small constant $a$, $0<a \leq c$ (independent of $\tau_{i}, i=1,2,3$ ), so that

$$
\begin{equation*}
\phi(\zeta) \geq 2 \operatorname{Re} h(\zeta)+a \sum_{i=1}^{3} \tau_{i}^{-2}\left|\zeta_{i}-\widetilde{\zeta}_{i}\right|^{2}, \quad \zeta \in R_{c \delta}\left(\zeta^{\delta}\right) \tag{33}
\end{equation*}
$$

where

$$
\begin{align*}
h(\zeta)= & \sum_{i=1}^{3} \frac{\partial \phi}{\partial \zeta_{i}}\left(\zeta^{\delta}\right)\left(\zeta_{i}-\widetilde{\zeta}_{i}\right) \\
& +\frac{1}{2} \sum_{i, j=1}^{3} \frac{\partial^{2} \phi}{\partial \zeta_{i} \partial \zeta_{j}}\left(\zeta^{\delta}\right)\left(\zeta_{i}-\widetilde{\zeta}_{i}\right)\left(\zeta_{j}-\widetilde{\zeta}_{j}\right) \tag{34}
\end{align*}
$$

If we set $\widetilde{a}=a^{3} / 3$, it follows, from (33), that

$$
\begin{equation*}
\operatorname{Re} h(\zeta) \leq-\widetilde{a}, \quad \zeta \in\{\zeta ; \phi(z) \leq \widetilde{a}\} \cap \operatorname{supp} \bar{\partial} \psi_{d} \tag{35}
\end{equation*}
$$

In the sequel, we set $B_{e}=R_{e \delta}\left(\zeta^{\delta}\right)$ for each small $e>0$. For each $s \geq 0$, set

$$
\begin{equation*}
\alpha_{s}=\bar{\partial}\left(\beta_{\delta} e^{s h}\right)=v_{\delta} e^{s h} \bar{\partial} \psi_{d}(\zeta):=\sum_{i=1}^{3} \alpha_{s, i} d \bar{\zeta}_{i} \tag{36}
\end{equation*}
$$

Then, $\alpha_{s}$ is a $\bar{\partial}$-closed smooth ( 0,1 )-form with $\operatorname{supp} \alpha_{s} \subset$ $R_{c \delta}\left(\zeta^{\delta}\right)=B_{c}$. Let $\chi$ be a smooth convex increasing function that satisfies $\chi(t)=0$ for $t \leq \tilde{a} / 2$ and $\chi^{\prime \prime}(t)>0$ for $t>\tilde{a} / 2$. Now, define

$$
\begin{equation*}
\lambda_{s}(\zeta)=\phi(\zeta)+s^{2} \chi(\phi(\zeta)) \tag{37}
\end{equation*}
$$

According to the weighted estimates of $\bar{\partial}$-equation on $\widetilde{D}$ (instead of $\widetilde{\Omega}$ ) and by using estimate (32) for each $s \geq 0$, there is $u_{s}$ which satisfies $\bar{\partial} u_{s}=\alpha_{s}$, and

$$
\begin{equation*}
\left\|u_{s}\right\|_{\lambda_{s}} \lesssim \int_{\widetilde{D}-B_{c}}\left|\alpha_{s}\right|^{2} e^{-\lambda_{s}}+\int_{B_{c}} \sum_{i=1}^{3} \tau_{i}^{2}\left|\alpha_{s, i}\right|^{2} e^{-\lambda_{s}} d V \tag{38}
\end{equation*}
$$

Since $\left|\alpha_{s, i}\right| \leqslant e^{s \operatorname{Reh}} \tau_{i}^{-1}$ and supp $\alpha_{s} \subset B_{c}$, it follows from (38) that

$$
\begin{align*}
\int_{\widetilde{D}}\left|u_{s}\right|^{2} e^{-\lambda_{s}} d V & \lesssim \int_{B_{c}} \sum_{i=1}^{3} \tau_{i}^{2}\left|\alpha_{s, i}\right|^{2} e^{-\lambda_{s}} d V  \tag{39}\\
& \lesssim \int_{\text {supp } \bar{\partial} \psi_{d}} e^{2 s \operatorname{Re} h-\phi-s^{2} \chi(\phi)} d V
\end{align*}
$$

We consider the integrand of the last integral. If $\phi(z) \geq \widetilde{a}$, then $\chi(\phi(z)) \geq \chi(\widetilde{a})>0$, so the $s^{2}$-term in the exponent predominates. On the other hand, if $z \in \operatorname{supp} \bar{\partial} \psi_{d}$ and $\phi(z) \leq$ $\widetilde{a}$, then (35) shows that the integrand tends to zero. Thus, for any $\epsilon_{0}>0$, there exist $s_{0}>0$ and a function $u_{s_{0}}$ so that $\bar{\partial} u_{s_{0}}=$ $\alpha_{s_{0}}$ and

$$
\begin{equation*}
\int_{\widetilde{D}}\left|u_{s_{0}}\right|^{2} e^{-\lambda_{s_{0}}} d V \lesssim \int_{\text {supp } \bar{\partial} \psi_{d}} \epsilon_{0} d V \lesssim \epsilon_{0} \prod_{i=1}^{3} \tau_{i}^{2} \tag{40}
\end{equation*}
$$

Since $\phi\left(\zeta^{\delta}\right)=0$, it follows, from the property (iii) of Theorem 5, that there is $e>0$, independent of $\zeta^{\delta}$, such that $\psi_{d}(z)=1$ and $\phi(z)<\tilde{a} / 2$ for all $z \in B_{e}$. Note that $\lambda_{s}$ is independent of $s$ for $z \in B_{e}$, and $u_{s_{0}}$ is holomorphic in $B_{e}$. By mean value theorem, we have

$$
\begin{align*}
\left|\frac{\partial u_{s_{0}}}{\partial \zeta_{k}}\left(\zeta^{\delta}\right)\right|^{2} \lesssim \tau_{k}^{-2} \prod_{i=1}^{3} \tau_{i}^{-2} \int_{B_{e}}\left|u_{s_{0}}\right|^{2} e^{-\lambda_{s_{0}}} d V & \lesssim \epsilon_{0} \tau_{k}^{-2}  \tag{41}\\
k & =1,2,3
\end{align*}
$$

and hence it follows that

$$
\begin{equation*}
\left|Y u_{s_{0}}\left(\zeta^{\delta}\right)\right| \lesssim \sqrt{\epsilon_{0}} \max \left(\left|b_{k}\right| \tau_{k}^{-1}\right) \tag{42}
\end{equation*}
$$

Now, set $f_{\delta}=\beta_{\delta} e^{s_{0} h}-u_{s_{0}}$. Then, $f_{\delta}$ is holomorphic on $\widetilde{D}=$ $\Phi_{\tilde{z}^{\delta}}^{-1}(D)$. Since $\beta_{\delta}\left(\zeta^{\delta}\right)=h\left(\zeta^{\delta}\right)=0$, it follows, from (30) and (42), that $f_{\delta}$ satisfies

$$
\begin{equation*}
\left|Y f_{\delta}\left(\zeta^{\delta}\right)\right| \gtrsim \sum_{i=1}^{3}\left|b_{i}\right| \tau_{i}^{-1} \tag{43}
\end{equation*}
$$

provided $\epsilon_{0}$ is sufficiently small.

We want to show that $\sup _{\widetilde{\Omega}}\left|f_{\delta}\right| \leq C$, where $C>0$ is independent of $\delta$. Recall that $s_{0}>0$ is fixed. Thus, from the property (iii) of Theorem 5, there is a uniform constant $C_{0}>$ 0 such that $\left|\beta_{\delta} e^{s_{0} h}\right| \leq C_{0}$. Let $r_{0}>0$ be the constant satisfying (28) and assume that $\zeta \in \widetilde{U}_{r_{0} / 2}(0)=\Phi_{\widetilde{z}^{\delta}}^{-1}\left(U_{r_{0} / 2}(0)\right)$. Since $f_{\delta}$ is holomorphic on $\widetilde{D}$, it follows, by (40) and mean value theorem, that there exists a constant $C_{1}>0$, independent of $\delta>0$, such that

$$
\begin{equation*}
\left|f_{\delta}(\zeta)\right|^{2} \leq r_{0}^{-6} \int_{\widetilde{U}_{r_{0} / 2}(\zeta)}\left|f_{\delta}\right|^{2} d V \leq C_{1} \tag{44}
\end{equation*}
$$

We need to show the boundedness of $f_{\delta}$ outside $\widetilde{U}_{r_{0} / 2}(0)$. Let $\chi_{1}$ and $\chi_{2}$ be smooth cutoff functions with
(i) $\chi_{1}(z)=1 \quad$ if $|z| \geq \frac{r_{0}}{2}, \quad \chi_{2}(z)=1 \quad$ if $z \in \operatorname{supp} \chi_{1}$
(ii) $\chi_{2}(z)=0 \quad$ if $|z| \leq \frac{r_{0}}{4}$,
and set $\widetilde{\chi}_{i}=\Phi_{\tilde{z}^{\delta}}^{*}\left(\chi_{i}\right), i=1,2$. By Kohn's theorem on global regularity for the $\bar{\partial}$-equation, the following estimate for the solution of $\bar{\partial} u=\alpha$,

$$
\begin{equation*}
\left\|\widetilde{\chi}_{1} u_{s_{0}}\right\|_{4}^{2} \lesssim\left\|\tilde{\chi}_{2} \alpha_{s_{0}}\right\|_{4}^{2}+\left\|u_{s_{0}}\right\|^{2} \tag{46}
\end{equation*}
$$

holds on $D$ provided $s_{0}>0$ is sufficiently large. Note that $\widetilde{\chi}_{2} \alpha_{s_{0}}=0$ because supp $\alpha_{s_{0}} \subset R_{c \delta}\left(\zeta^{\delta}\right) \subset \widetilde{U}_{r_{0} / 4}(0)$ for all sufficiently small $\delta>0$. Thus, we conclude from (40), (46), and the Sobolev lemma that

$$
\begin{equation*}
\sup _{\widetilde{D}}\left|\widetilde{\chi}_{1} u_{s_{0}}\right| \lesssim\left\|\widetilde{\chi}_{1} u_{s_{0}}\right\|_{4}^{2} \lesssim\left\|u_{s_{0}}\right\|^{2} \leq C_{2} \tag{47}
\end{equation*}
$$

where $C_{2}$ is independent of $\delta$.
Combining (44) and (47) and by the fact that $\left|\beta_{\delta} e^{s_{0} h}\right| \leq$ $C_{0}$, we conclude that

$$
\begin{equation*}
\sup _{\widetilde{D}}\left|f^{\delta}\right| \leq C \tag{48}
\end{equation*}
$$

where $C$ is independent of $\zeta^{\delta}$ and $\delta$. Therefore, it follows from (43) and (48) that

$$
\begin{equation*}
C_{\widetilde{\Omega}}\left(\zeta^{\delta} ; Y\right) \geq C_{\widetilde{D}}\left(\zeta^{\delta} ; Y\right) \gtrsim \sum_{i=1}^{3}\left|b_{i}\right| \tau_{i}^{-1} \tag{49}
\end{equation*}
$$

On the other hand, the polydisc $B_{c}=R_{c \delta}\left(\zeta^{\delta}\right)$ about $\zeta^{\delta}$ lies in $\widetilde{\Omega}$. So one obtains that

$$
\begin{equation*}
C_{\widetilde{\Omega}}\left(\zeta^{\delta} ; Y\right) \leq C_{B_{c}}\left(\zeta^{\delta} ; Y\right)=\max \left\{\left|b_{k}\right|\left(c \tau_{k}\right)^{-1}: k=1,2,3\right\} . \tag{50}
\end{equation*}
$$

Thus, one concludes from (49) and (50) that

$$
\begin{equation*}
C_{\widetilde{\Omega}}\left(\zeta^{\delta} ; Y\right) \approx \sum_{i=1}^{3}\left|b_{i}\right| \tau_{i}^{-1} \tag{51}
\end{equation*}
$$

Set $L_{k}^{\prime}=\left(d \Phi_{\tilde{z}^{\delta}}^{-1}\right) L_{k}, k=1,2,3$, where $L_{k}$ 's are defined in (1) in terms of $z$-coordinates defined in Theorem 1.

At $\zeta^{\delta}=\left(d \delta^{1 / \eta}, 0,-b \delta / d_{0}\left(\widetilde{z}^{\delta}\right)\right)$, from the holomorphic coordinate change of $\Phi_{\tilde{z}^{\delta}}$ in Proposition 4, we see that

$$
\begin{align*}
L_{1}^{\prime} & =\frac{\partial}{\partial \zeta_{1}}+e_{1}\left(z^{\delta}\right) d_{0}\left(\tilde{z}^{\delta}\right) \frac{\partial}{\partial \zeta_{3}}:=\frac{\partial}{\partial \zeta_{1}}+\widetilde{e}_{1}\left(z^{\delta}\right) \frac{\partial}{\partial \zeta_{3}} \\
L_{2}^{\prime} & =\frac{\partial}{\partial \zeta_{2}}+\left[d_{1}\left(\tilde{z}^{\delta}\right)+e_{2}\left(z^{\delta}\right)\right] \frac{\partial}{\partial \zeta_{3}} \\
& :=\frac{\partial}{\partial \zeta_{2}}+\tilde{e}_{1}\left(z^{\delta}\right) \frac{\partial}{\partial \zeta_{3}} \tag{52}
\end{align*}
$$

and that

$$
L_{3}^{\prime}=d_{0}\left(\tilde{z}^{\delta}\right) \frac{\partial}{\partial \zeta_{3}}
$$

where $d_{0}\left(\widetilde{z}^{\delta}\right)=(1 / 2)\left(\left(\partial r / \partial z_{3}\right)\left(\widetilde{z}^{\delta}\right)\right)^{-1}$ and $d_{1}\left(\widetilde{z}^{\delta}\right)=-((\partial r /$ $\left.\left.\partial z_{3}\right)\left(\widetilde{z}^{\delta}\right)\right)^{-1}\left(\partial r / \partial z_{2}\right)\left(\widetilde{z}^{\delta}\right)$ and where $e_{i}=-\left(\partial r / \partial z_{3}\right)^{-1}\left(\partial r / \partial z_{i}\right)$, $i=1,2$. Since $\left(\partial r / \partial z_{i}\right)(0)=0, i=1,2$, and $\left|\partial r / \partial z_{3}\right| \approx 1$, independent of $\delta$, it follows that $\left|\widetilde{e}_{i}\right| \leqslant \delta, i=1,2$. Thus, if the vector $Y=\sum_{i=1}^{3} b_{i}\left(\partial / \partial \zeta_{i}\right)$ is written as $Y=\sum_{i=1}^{3} a_{i} L_{i}^{\prime}$, then it follows that

$$
\begin{equation*}
\max \left(\left|b_{i}\right| \tau_{i}^{-1}\right) \approx \sum_{i=1}^{3}\left|a_{i}\right| \tau_{i}^{-1} \tag{53}
\end{equation*}
$$

Let us write $X=\sum_{i=1}^{3} a_{i} L_{i}$, and $Y=\left(\Phi_{\tilde{z}^{\delta}}^{-1}\right)_{*} X=$ $\sum_{i=1}^{3} a_{i} L_{i}^{\prime}=\sum_{i=1}^{3} b_{i}\left(\partial / \partial \zeta_{i}\right)$. From (51), (53), and the invariance property of the metric, it follows that

$$
\begin{equation*}
C_{\Omega}\left(z^{\delta} ; X\right)=C_{\widetilde{\Omega}}\left(\zeta^{\delta} ; Y\right) \approx \sum_{i=1}^{3}\left|a_{i}\right| \tau_{i}^{-1} \tag{54}
\end{equation*}
$$

To obtain an upper bound for the Bergman metric, we note that $R_{c \delta}\left(\zeta^{\delta}\right) \subset \widetilde{\Omega}$. Thus, by elementary estimates, for any $f \in A^{2}(\widetilde{\Omega}):=L^{2}(\widetilde{\Omega}) \cap A(\widetilde{\Omega})$, we obtain that

$$
\begin{equation*}
\left|\frac{\partial f}{\partial \zeta_{k}}\left(\zeta^{\delta}\right)\right|^{2} \lesssim \tau_{k}^{-2} \prod_{j=1}^{3} \tau_{j}^{-2}\|f\|_{L^{2}(\widetilde{\Omega})}^{2} \tag{55}
\end{equation*}
$$

for $k=1,2,3$. Therefore, it follows that

$$
\begin{equation*}
b_{\widetilde{\Omega}}\left(\zeta^{\delta} ; Y\right) \lesssim\left(\sum_{k=1}^{3}\left|b_{k}\right| \tau_{k}^{-1}\right) \prod_{j=1}^{3} \tau_{j}^{-1} \tag{56}
\end{equation*}
$$

where

$$
\begin{align*}
& b_{\widetilde{\Omega}}\left(\zeta^{\delta} ; Y\right) \\
& \quad=\sup \left\{\left|Y f\left(\zeta^{\delta}\right)\right|: f \in A^{2}(\widetilde{\Omega}), f(z)=0,\|f\|_{L^{2}(\widetilde{\Omega})} \leq 1\right\} . \tag{57}
\end{align*}
$$

Combining (23) and (56), one concludes that

$$
\begin{equation*}
B_{\widetilde{\Omega}}\left(\zeta^{\delta} ; Y\right)=\frac{b_{\widetilde{\Omega}}\left(\zeta^{\delta} ; Y\right)}{K_{\widetilde{\Omega}}\left(\zeta^{\delta}, \zeta^{\delta}\right)^{1 / 2}} \lesssim \sum_{k=1}^{3}\left|b_{k}\right| \tau_{k}^{-1} . \tag{58}
\end{equation*}
$$

To estimate the upper bound of the Kobayashi metric, set

$$
\begin{equation*}
R=\min \left\{c \tau_{k}\left|b_{k}\right|^{-1}: k=1,2,3\right\} . \tag{59}
\end{equation*}
$$

Then,

$$
\begin{equation*}
f(t)=\left(b_{1} t, b_{2} t,-\frac{b \delta}{2}+b_{3} t\right) \tag{60}
\end{equation*}
$$

defines a map $f: D_{R} \subset \mathbb{C} \rightarrow B_{c}=R_{c \delta}\left(\zeta^{\delta}\right) \subset \widetilde{\Omega}$ with $f_{*}\left(\left.(\partial / \partial t)\right|_{0}\right)=Y=\sum_{k=1}^{3} b_{k}\left(\partial / \partial \zeta_{k}\right)$. Hence,

$$
\begin{align*}
K_{\widetilde{\Omega}}\left(\zeta^{\delta} ; Y\right) & \leq K_{B_{c}}\left(\zeta^{\delta} ; Y\right) \leq R^{-1} \\
& \leq \max \left\{\left|b_{k}\right|\left(c \tau_{k}\right)^{-1}: k=1,2,3\right\}  \tag{61}\\
& \lesssim \sum_{k=1}^{3}\left|b_{k}\right| \tau_{k}^{-1} .
\end{align*}
$$

Combining (51), (58), and (61), we obtain that

$$
\begin{equation*}
C_{\widetilde{\Omega}}\left(\zeta^{\delta} ; Y\right) \approx B_{\widetilde{\Omega}}\left(\zeta^{\delta} ; Y\right) \approx K_{\widetilde{\Omega}}\left(\zeta^{\delta} ; Y\right) \approx \sum_{i=1}^{3}\left|b_{i}\right| \tau_{i}^{-1}, \tag{62}
\end{equation*}
$$

and hence the invariance property implies that

$$
\begin{equation*}
C_{\Omega}\left(z^{\delta} ; X\right) \approx B_{\Omega}\left(z^{\delta} ; X\right) \approx K_{\Omega}\left(z^{\delta} ; X\right) \approx \sum_{i=1}^{3}\left|a_{i}\right| \tau_{i}^{-1} \tag{63}
\end{equation*}
$$

If we combine (3), (4), (22), and (63), a proof of Theorem 1 is completed.

## Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

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