

## THE JACOBSON DESCENT THEOREM

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**A direct proof of the Jacobson Descent Theorem is given and used to prove the Jacobson-Bourbaki Correspondence Theorem.**

The purpose of this paper is to give a proof of the *Jacobson Descent Theorem*, Theorem 1, which is direct in that it does not assume that  $A = \text{Hom}_{K^A} K$ . This is then used to prove the *Jacobson-Bourbaki Correspondence Theorem*, Theorem 2. The approach simplifies earlier proofs.

A variation of a theme of Hochschild appearing in Jacobson [2] and Winter [3] recurs here in the concentrated form of the dual bases  $x_i, R_j$  which thread their way through both proofs. Thus, this paper underlines the importance of this natural duality.

Throughout the paper,  $K$  denotes a field,  $\text{End } K$  denotes the ring of endomorphisms of  $K$  as additive group,  $A$  denotes a subring of  $\text{End } K$  containing the  $K$ -span  $KI$  of the identity  $I$  of  $\text{End } K$  and  $V$  denotes a vector space over  $K$  of finite or infinite dimension  $V: K$ . Regard  $A$  as left  $K$ -vector space in the obvious way.

**DEFINITION 1.** An  $A$ -product on  $V$  is a mapping  $A \times V \rightarrow V$ , denoted  $(T, v) \rightarrow T(v)$ , such that  $V$  is an  $A$ -module and

$$(xT)(v) = x(T(v)) \quad (x \in K, T \in A, v \in V). \quad \square$$

Clearly  $T(v)$  ( $T \in A, v \in K$ ) is an  $A$ -product for  $K$ .

Suppose henceforth that  $T(v)$  ( $T \in A, v \in V$ ) is an  $A$ -product for  $V$ , and  $V^A = \{v \in V \mid T(xv) = T(x)v \text{ for } T \in A, x \in K\}$ . In particular, we have then defined  $K^A$ .

**DEFINITION 2.** For  $k$  a subfield of  $K$ , a  $k$ -form of  $V$  is a  $k$ -subspace  $V'$  of  $V$  whose  $k$ -bases are  $K$ -bases of  $V$ . □

**THEOREM 1 (Jacobson [1]).** Let  $A: K < \infty$ , then  $V^A$  is a  $K^A$ -form of  $V$ .

*Proof.*  $\hat{K} = \{\hat{x} \mid x \in K\}$  separates  $A$  and therefore contains a basis  $\hat{x}_1, \dots, \hat{x}_n$  for the  $K$ -dual space  $\text{Hom}_K(A, K)$  of  $A$  where  $\hat{x} \in \text{Hom}_K(A, K)$  is defined for  $x \in K$  by  $\hat{x}(T) = T(x)$  ( $T \in A$ ). Letting  $R_1, \dots, R_n$  be a dual basis for  $A$ , so that  $R_i(x_j) = \delta_{ij}$  ( $1 \leq i, j \leq n$ ), we have  $T(xR_i)(x_j) = T(x\delta_{ij}) = T(x)\delta_{ij} = (T(x)R_i)(x_j)$  ( $1 \leq i, j \leq n$ ) so that  $T(xR_i) = T(x)R_i$  ( $1 \leq i \leq n$ ) for all  $T$ , since the  $x_j$  separate  $A$ .

Letting  $v \in V$ , we therefore have  $T(xR_i(v)) = (T(xR_i))(v) = T(x)R_i(v)$  for all  $T \in A, x \in V$ , so that  $R_i(V) \subset V^A$  and, in particular,  $R_i(K) \subset K^A$  ( $1 \leq i \leq n$ ).

It follows that the  $K$ -span  $KV^A$  of  $V^A$  is  $V$ . For we have  $I = \sum_1^n y_i R_i$  for suitable  $y_i \in K$ , so that  $v = \sum_1^n y_i R_i v \in KV^A$  for all  $v \in V$ .

Finally, let  $v_i$  ( $i \in I$ ) be a  $K^A$ -basis for  $V^A$ . Suppose that  $\sum_{i \in I} y_i v_i = 0$  with the  $y_i$  in  $K$ . Then  $0 = \sum_{i \in I} R_j(y_i)v_i$  with the  $R_j(y_i) \in K^A$ , so  $R_j(y_i) = 0$  ( $1 \leq i, j \leq n$ ) and  $y_i = 0$  ( $1 \leq i \leq n$ ). □

**THEOREM 2 (Jacobson [2]).** *Let  $A: K < \infty$ . Then  $A = \text{Hom}_{K^A} K$ .*

*Proof.*  $A$  as left  $A$ -module satisfies  $(xS)T = x(ST)$  ( $x \in K, S, T \in A$ ), so that  $A^A$  is a  $K^A$  form of  $A$  and  $A^A$  contains a basis  $R_1, \dots, R_n$  for  $A$  over  $K$ . Choosing  $x_i \in K$  so that  $I = x_1 R_1 + \dots + x_n R_n$ , we have  $x = \sum_{i=1}^n x_i R_i(x), R_i(x) \in K^A$ , for  $x \in K$ , so that  $K: K^A \leq A: K \leq \text{Hom}_{K^A} K: K \leq K: K^A$  and  $A = \text{Hom}_{K^A} K$ . □

It is clear, in retrospect, that the above  $x_1, \dots, x_n$  form a basis for  $K$  over  $K^A = k$  and that  $A^A$  is the dual space  $\text{Hom}_k(K, k) = K^*$  of  $K$  over  $k$ . The equations  $x_j \stackrel{\text{def}}{=} \sum_{i=1}^n x_i R_i(x_j)$  show that  $R_i(x_j) = \delta_{ij}$ , that is,  $R_1, \dots, R_n$  is a dual basis for  $K^*$ . Finally,  $I = x_1 R_1 + \dots + x_n R_n$  shows that  $T = \sum_1^n x_j R_j T$  and  $T(x_i) = \sum_1^n x_j R_j T(x_i) = \sum_1^n (R_j \hat{x}_i(T))x_j$ . Thus, the  $X_{ij} = R_j \hat{x}_i$  (composite) ( $1 \leq i, j \leq n$ ) are the coordinate functions on the  $T \in A$  relative to the basis  $x_i$ . They form a basis for the  $k$ -dual space  $A^*$  of  $A = \text{Hom}_k K$ . Since we may identify  $\hat{K} = \{\hat{x} \mid x \in K\}$  with  $K$ , it follows that the  $k$ -dual space  $A^*$  of  $A = \text{Hom}_k K = KK^*$  can be identified with  $A$  whereby  $X_{ij}$  corresponds to  $X_i R_j$ —that is, we have a nondegenerate bilinear  $k$ -pairing  $\langle \cdot, \cdot \rangle$  on  $A \times A$  such that  $\langle x_i R_j, T \rangle = R_j T(x_i)$ . This pairing is also characterized by the condition  $\langle xR, yS \rangle = R(y)S(x)$  ( $x, y \in K, R, S \in K^*$ ). Since  $(x_i R_j)(x_r R_s) = x_i (R_j x_r R_s) = x_i R_j(x_r) R_s = x_i \delta_{jr} R_s$ , the  $E_{ij} = x_i R_j$  form a system of matrix units for  $A$ . We have  $\langle E_{ij}, E_{rs} \rangle = \langle x_i R_j, x_r R_s \rangle = R_j(x_r) R_s(x_i) = \delta_{jr} \delta_{is} = \text{Trace}(E_{ij} E_{rs})$ . It follows that  $\langle S, T \rangle = \text{Trace } ST$  ( $S, T \in A$ ).

REFERENCES

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